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LatticeECP/EC Family Data Sheet

DS1000 Version 02.8, September 2012



LatticeECP/EC Family Data Sheet Introduction

September 2012

Features

- Extensive Density and Package Options
 - 1.5K to 32.8K LUT4s
 - 65 to 496 I/Os
 - Density migration supported
- sysDSP[™] Block (LatticeECP[™] Versions)
 - High performance multiply and accumulate
 - 4 to 8 blocks
 - 4 to 8 36x36 multipliers or
 - 16 to 32 18x18 multipliers or
 - 32 to 64 9x9 multipliers

Embedded and Distributed Memory

- 18 Kbits to 498 Kbits sysMEM[™] Embedded Block RAM (EBR)
- Up to 131 Kbits distributed RAM
- Flexible memory resources:
 - Distributed and block memory

■ Flexible I/O Buffer

 Programmable sysl/O[™] buffer supports wide range of interfaces:

Table 1-1. LatticeECP/EC Family Selection Guide

- LVCMOS 3.3/2.5/1.8/1.5/1.2
- LVTTL
- SSTL 3/2 Class I, II, SSTL18 Class I
- HSTL 18 Class I, II, III, HSTL15 Class I, III
- PCI
- LVDS, Bus-LVDS, LVPECL, RSDS
- Dedicated DDR Memory Support
 - Implements interface up to DDR400 (200MHz)

■ sysCLOCK[™] PLLs

- Up to four analog PLLs per device
- · Clock multiply, divide and phase shifting

System Level Support

- IEEE Standard 1149.1 Boundary Scan, plus ispTRACY™ internal logic analyzer capability
- SPI boot flash interface
- 1.2V power supply

Low Cost FPGA

- · Features optimized for mainstream applications
- Low cost TQFP and PQFP packaging

LFEC1	LFEC3	LFEC6/ LFECP6	LFEC10/ LFECP10	LFEC15/ LFECP15	LFEC20/ LFECP20	LFEC33/ LFECP33
12	16	24	32	40	44	64
16	24	32	40	48	56	64
192	384	768	1280	1920	2464	4096
1.5	3.1	6.1	10.2	15.4	19.7	32.8
6	12	25	41	61	79	131
18	55	92	276	350	424	498
2	6	10	30	38	46	54
	—	4	5	6	7	8
	—	16	20	24	28	32
1.2	1.2	1.2	1.2	1.2	1.2	1.2
2	2	2	4	4	4	4
ons:		•				
67	67					
97	97	97				
112	145	147	147			
	160	195	195	195		
		224	288	352	360	360
					400	496
	LFEC1 12 16 192 1.5 6 18 2 1.2 2 ons: 67 97 112	LFEC1 LFEC3 12 16 16 24 192 384 1.5 3.1 6 12 18 55 2 6 1.2 1.2 2 2 0 1.2 1.2 2 2 0 1.2 1.2 2 9 112 1.45 160	LFEC1 LFEC3 LFEC6/ LFECP6 12 16 24 16 24 32 192 384 768 1.5 3.1 6.1 6 12 25 18 55 92 2 6 10 - 4 - 4 - 16 1.2 1.2 1.2 2 2 2 97 97 97 97 97 97 112 145 147 160 195 224 224	LFEC1LFEC3LFEC6/ LFECP6LFEC10/ LFECP10121624321624324019238476812801.53.16.110.261225411855922762610304516201.21.21.21.22224oms:147112145147147160195195224288	LFEC1LFEC3LFEC6/ LFECP6LFEC10/ LFECP10LFEC15/ LFECP1512162432401624324048192384768128019201.53.16.110.215.4612254161185592276350261030384561620241.21.21.21.21.222244ons:147147112145147147195160195195195195244288352146147	LFEC1LFEC3LFEC6/ LFECP6LFEC10/ LFECP10LFEC15/ LFECP15LFEC20/

1. LatticeECP devices only.

Data Sheet

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Introduction

The LatticeECP/EC family of FPGA devices is optimized to deliver mainstream FPGA features at low cost. For maximum performance and value, the LatticeECP[™] (<u>EC</u>onomy <u>P</u>lus) FPGA concept combines an efficient FPGA fabric with high-speed dedicated functions. Lattice's first family to implement this approach is the LatticeECP[™] (<u>EC</u>onomy <u>P</u>lus <u>DSP</u>) family, providing dedicated high-performance DSP blocks on-chip. The LatticeEC[™] (<u>EC</u>onomy) family supports all the general purpose features of LatticeECP devices without dedicated function blocks to achieve lower cost solutions.

The LatticeECP/EC FPGA fabric, which was designed from the outset with low cost in mind, contains all the critical FPGA elements: LUT-based logic, distributed and embedded memory, PLLs and support for mainstream I/Os. Dedicated DDR memory interface logic is also included to support this memory that is becoming increasingly prevalent in cost-sensitive applications.

The ispLEVER[®] design tool suite from Lattice allows large complex designs to be efficiently implemented using the LatticeECP/EC FPGA family. Synthesis library support for LatticeECP/EC is available for popular logic synthesis tools. The ispLEVER tool uses the synthesis tool output along with the constraints from its floor planning tools to place and route the design in the LatticeECP/EC device. The ispLEVER tool extracts the timing from the routing and back-annotates it into the design for timing verification.

Lattice provides many pre-designed IP (Intellectual Property) ispLeverCORE[™] modules for the LatticeECP/EC family. By using these IPs as standardized blocks, designers are free to concentrate on the unique aspects of their design, increasing their productivity.



LatticeECP/EC Family Data Sheet Architecture

September 2012

Data Sheet

Architecture Overview

The LatticeECP-DSP and LatticeEC architectures contain an array of logic blocks surrounded by Programmable I/ O Cells (PIC). Interspersed between the rows of logic blocks are rows of sysMEM Embedded Block RAM (EBR), as shown in Figures 2-1 and 2-2. In addition, LatticeECP-DSP supports an additional row of DSP blocks, as shown in Figure 2-2.

There are two kinds of logic blocks, the Programmable Functional Unit (PFU) and Programmable Functional unit without RAM/ROM (PFF). The PFU contains the building blocks for logic, arithmetic, RAM, ROM and register functions. The PFF block contains building blocks for logic, arithmetic and ROM functions. Both PFU and PFF blocks are optimized for flexibility, allowing complex designs to be implemented quickly and efficiently. Logic Blocks are arranged in a two-dimensional array. Only one type of block is used per row. The PFU blocks are used on the outside rows. The rest of the core consists of rows of PFF blocks interspersed with rows of PFU blocks. For every three rows of PFF blocks there is a row of PFU blocks.

Each PIC block encompasses two PIOs (PIO pairs) with their respective sysI/O interfaces. PIO pairs on the left and right edges of the device can be configured as LVDS transmit/receive pairs. sysMEM EBRs are large dedicated fast memory blocks. They can be configured as RAM or ROM.

The PFU, PFF, PIC and EBR Blocks are arranged in a two-dimensional grid with rows and columns as shown in Figure 2-1. The blocks are connected with many vertical and horizontal routing channel resources. The place and route software tool automatically allocates these routing resources.

At the end of the rows containing the sysMEM Blocks are the sysCLOCK Phase Locked Loop (PLL) Blocks. These PLLs have multiply, divide and phase shifting capability; they are used to manage the phase relationship of the clocks. The LatticeECP/EC architecture provides up to four PLLs per device.

Every device in the family has a JTAG Port with internal Logic Analyzer (ispTRACY) capability. The sysCONFIG[™] port which allows for serial or parallel device configuration. The LatticeECP/EC devices use 1.2V as their core voltage.

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Figure 2-1. Simplified Block Diagram, LatticeEC Device (Top Level)

Figure 2-2. Simplified Block Diagram, LatticeECP-DSP Device (Top Level)





PFU and PFF Blocks

The core of the LatticeECP/EC devices consists of PFU and PFF blocks. The PFUs can be programmed to perform Logic, Arithmetic, Distributed RAM and Distributed ROM functions. PFF blocks can be programmed to perform Logic, Arithmetic and ROM functions. Except where necessary, the remainder of the data sheet will use the term PFU to refer to both PFU and PFF blocks.

Each PFU block consists of four interconnected slices, numbered 0-3 as shown in Figure 2-3. All the interconnections to and from PFU blocks are from routing. There are 53 inputs and 25 outputs associated with each PFU block.

Figure 2-3. PFU Diagram



Slice

Each slice contains two LUT4 lookup tables feeding two registers (programmed to be in FF or Latch mode), and some associated logic that allows the LUTs to be combined to perform functions such as LUT5, LUT6, LUT7 and LUT8. There is control logic to perform set/reset functions (programmable as synchronous/asynchronous), clock select, chip-select and wider RAM/ROM functions. Figure 2-4 shows an overview of the internal logic of the slice. The registers in the slice can be configured for positive/negative and edge/level clocks.

There are 14 input signals: 13 signals from routing and one from the carry-chain (from adjacent slice or PFU). There are 7 outputs: 6 to routing and one to carry-chain (to adjacent PFU). Table 2-1 lists the signals associated with each slice.



Figure 2-4. Slice Diagram



Table 2-1. Slice Signal Descriptions

Function	Туре	Signal Names	Description
Input	Data signal	A0, B0, C0, D0	Inputs to LUT4
Input	Data signal	A1, B1, C1, D1	Inputs to LUT4
Input	Multi-purpose	MO	Multipurpose Input
Input	Multi-purpose	M1	Multipurpose Input
Input	Control signal	CE	Clock Enable
Input	Control signal	LSR	Local Set/Reset
Input	Control signal	CLK	System Clock
Input	Inter-PFU signal	FCIN	Fast Carry In ¹
Output	Data signals	F0, F1	LUT4 output register bypass signals
Output	Data signals	Q0, Q1	Register Outputs
Output	Data signals	OFX0	Output of a LUT5 MUX
Output	Data signals	OFX1	Output of a LUT6, LUT7, LUT8 ² MUX depending on the slice
Output	Inter-PFU signal	FCO	For the right most PFU the fast carry chain output ¹

1. See Figure 2-3 for connection details.

2. Requires two PFUs.



Modes of Operation

Each Slice is capable of four modes of operation: Logic, Ripple, RAM and ROM. The Slice in the PFF is capable of all modes except RAM. Table 2-2 lists the modes and the capability of the Slice blocks.

Table 2-2. Slice Modes

	Logic	Ripple	RAM	ROM
PFU Slice	LUT 4x2 or LUT 5x1	2-bit Arithmetic Unit	SPR16x2	ROM16x1 x 2
PFF Slice	LUT 4x2 or LUT 5x1	2-bit Arithmetic Unit	N/A	ROM16x1 x 2

Logic Mode: In this mode, the LUTs in each Slice are configured as 4-input combinatorial lookup tables. A LUT4 can have 16 possible input combinations. Any logic function with four inputs can be generated by programming this lookup table. Since there are two LUT4s per Slice, a LUT5 can be constructed within one Slice. Larger lookup tables such as LUT6, LUT7 and LUT8 can be constructed by concatenating other Slices.

Ripple Mode: Ripple mode allows the efficient implementation of small arithmetic functions. In ripple mode, the following functions can be implemented by each Slice:

- Addition 2-bit
- Subtraction 2-bit
- Add/Subtract 2-bit using dynamic control
- Up counter 2-bit
- Down counter 2-bit
- Ripple mode multiplier building block
- Comparator functions of A and B inputs
- A greater-than-or-equal-to B
- A not-equal-to B
- A less-than-or-equal-to B

Ripple Mode includes an optional configuration that performs arithmetic using fast carry chain methods. In this configuration (also referred to as CCU2 mode) two additional signals, Carry Generate and Carry Propagate, are generated on a per slice basis to allow fast arithmetic functions to be constructed by concatenating Slices.

RAM Mode: In this mode, distributed RAM can be constructed using each LUT block as a 16x1-bit memory. Through the combination of LUTs and Slices, a variety of different memories can be constructed.

The Lattice design tools support the creation of a variety of different size memories. Where appropriate, the software will construct these using distributed memory primitives that represent the capabilities of the PFU. Table 2-3 shows the number of Slices required to implement different distributed RAM primitives. Figure 2-5 shows the distributed memory primitive block diagrams. Dual port memories involve the pairing of two Slices, one Slice functions as the read-write port. The other companion Slice supports the read-only port. For more information about using RAM in LatticeECP/EC devices, please see the list of technical documentation at the end of this data sheet.

Table 2-3. Number of Slices Required For Implementing Distributed RAM

	SPR16x2	DPR16x2
Number of slices	1	2

Note: SPR = Single Port RAM, DPR = Dual Port RAM



Figure 2-5. Distributed Memory Primitives



ROM Mode: The ROM mode uses the same principal as the RAM modes, but without the Write port. Pre-loading is accomplished through the programming interface during configuration.

PFU Modes of Operation

Slices can be combined within a PFU to form larger functions. Table 2-4 tabulates these modes and documents the functionality possible at the PFU level.

Table 2-4	I. PFU	Modes	of O	peration
-----------	--------	-------	------	----------

Logic	Ripple	RAM ¹	ROM
LUT 4x8 or MUX 2x1 x 8	2-bit Add x 4	SPR16x2 x 4 DPR16x2 x 2	ROM16x1 x 8
LUT 5x4 or MUX 4x1 x 4	2-bit Sub x 4	SPR16x4 x 2 DPR16x4 x 1	ROM16x2 x 4
LUT 6x 2 or MUX 8x1 x 2	2-bit Counter x 4	SPR16x8 x 1	ROM16x4 x 2
LUT 7x1 or MUX 16x1 x 1	2-bit Comp x 4		ROM16x8 x 1

1. These modes are not available in PFF blocks



Routing

There are many resources provided in the LatticeECP/EC devices to route signals individually or as busses with related control signals. The routing resources consist of switching circuitry, buffers and metal interconnect (routing) segments.

The inter-PFU connections are made with x1 (spans two PFU), x2 (spans three PFU) and x6 (spans seven PFU). The x1 and x2 connections provide fast and efficient connections in horizontal and vertical directions. The x2 and x6 resources are buffered, the routing of both short and long connections between PFUs.

The ispLEVER design tool suite takes the output of the synthesis tool and places and routes the design. Generally, the place and route tool is completely automatic, although an interactive routing editor is available to optimize the design.

Clock Distribution Network

The clock inputs are selected from external I/O, the sysCLOCK[™] PLLs or routing. These clock inputs are fed through the chip via a clock distribution system.

Primary Clock Sources

LatticeECP/EC devices derive clocks from three primary sources: PLL outputs, dedicated clock inputs and routing. LatticeECP/EC devices have two to four sysCLOCK PLLs, located on the left and right sides of the device. There are four dedicated clock inputs, one on each side of the device. Figure 2-6 shows the 20 primary clock sources.

Figure 2-6. Primary Clock Sources





Secondary Clock Sources

LatticeECP/EC devices have four secondary clock resources per quadrant. The secondary clock branches are tapped at every PFU. These secondary clock networks can also be used for controls and high fanout data. These secondary clocks are derived from four clock input pads and 16 routing signals as shown in Figure 2-7.

Figure 2-7. Secondary Clock Sources



Clock Routing

The clock routing structure in LatticeECP/EC devices consists of four Primary Clock lines and a Secondary Clock network per quadrant. The primary clocks are generated from MUXs located in each quadrant. Figure 2-8 shows this clock routing. The four secondary clocks are generated from MUXs located in each quadrant as shown in Figure 2-9. Each slice derives its clock from the primary clock lines, secondary clock lines and routing as shown in Figure 2-10.



Figure 2-8. Per Quadrant Primary Clock Selection



Figure 2-9. Per Quadrant Secondary Clock Selection



Figure 2-10. Slice Clock Selection



sysCLOCK Phase Locked Loops (PLLs)

The PLL clock input, from pin or routing, feeds into an input clock divider. There are three sources of feedback signal to the feedback divider: from CLKOP (PLL Internal), from clock net (CLKOP) or from a user clock (PIN or logic). There is a PLL_LOCK signal to indicate that VCO has locked on to the input clock signal. Figure 2-11 shows the sysCLOCK PLL diagram.

The setup and hold times of the device can be improved by programming a delay in the feedback or input path of the PLL which will advance or delay the output clock with reference to the input clock. This delay can be either pro-



grammed during configuration or can be adjusted dynamically. In dynamic mode, the PLL may lose lock after adjustment and not relock until the t_{LOCK} parameter has been satisfied. Additionally, the phase and duty cycle block allows the user to adjust the phase and duty cycle of the CLKOS output.

The sysCLOCK PLLs provide the ability to synthesize clock frequencies. Each PLL has four dividers associated with it: input clock divider, feedback divider, post scalar divider and secondary clock divider. The input clock divider is used to divide the input clock signal, while the feedback divider is used to multiply the input clock signal. The post scalar divider allows the VCO to operate at higher frequencies than the clock output, thereby increasing the frequency range. The secondary divider is used to derive lower frequency outputs.

Figure 2-11. PLL Diagram



Figure 2-12 shows the available macros for the PLL. Table 2-5 provides signal description of the PLL Block.

Figure 2-12. PLL Primitive





Table 2-5. PLL Signal Descriptions

Signal	I/O	Description
CLKI	I	Clock input from external pin or routing
CLKFB	I	PLL feedback input from CLKOP (PLL internal), from clock net (CLKOP) or from a user clock (PIN or logic)
RST	I	"1" to reset PLL
CLKOS	0	PLL output clock to clock tree (phase shifted/duty cycle changed)
CLKOP	0	PLL output clock to clock tree (No phase shift)
CLKOK	0	PLL output to clock tree through secondary clock divider
LOCK	0	"1" indicates PLL LOCK to CLKI
DDAMODE	Ι	Dynamic Delay Enable. "1": Pin control (dynamic), "0": Fuse Control (static)
DDAIZR	I	Dynamic Delay Zero. "1": delay = 0, "0": delay = on
DDAILAG	Ι	Dynamic Delay Lag/Lead. "1": Lead, "0": Lag
DDAIDEL[2:0]	I	Dynamic Delay Input
DDAOZR	0	Dynamic Delay Zero Output
DDAOLAG	0	Dynamic Delay Lag/Lead Output
DDAODEL[2:0]	0	Dynamic Delay Output

For more information about the PLL, please see the list of technical documentation at the end of this data sheet.

Dynamic Clock Select (DCS)

The DCS is a global clock buffer with smart multiplexer functions. It takes two independent input clock sources and outputs a clock signal without any glitches or runt pulses. This is achieved regardless of where the select signal is toggled. There are eight DCS blocks per device, located in pairs at the center of each side. Figure 2-13 illustrates the DCS Block Macro.

Figure 2-13. DCS Block Primitive



Figure 2-14 shows timing waveforms of the default DCS operating mode. The DCS block can be programmed to other modes. For more information about the DCS, please see the list of technical documentation at the end of this data sheet.



Figure 2-14. DCS Waveforms



sysMEM Memory

The LatticeECP/EC devices contain a number of sysMEM Embedded Block RAM (EBR). The EBR consists of a 9-Kbit RAM, with dedicated input and output registers.

sysMEM Memory Block

The sysMEM block can implement single port, dual port or pseudo dual port memories. Each block can be used in a variety of depths and widths as shown in Table 2-6.

Table 2-6. sysMEM Block Configurations

Memory Mode	Configurations
Single Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9 512 x 18 256 x 36
True Dual Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9 512 x 18
Pseudo Dual Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9 512 x 18 256 x 36

Bus Size Matching

All of the multi-port memory modes support different widths on each of the ports. The RAM bits are mapped LSB word 0 to MSB word 0, LSB word 1 to MSB word 1 and so on. Although the word size and number of words for each port varies, this mapping scheme applies to each port.

RAM Initialization and ROM Operation

If desired, the contents of the RAM can be pre-loaded during device configuration. By preloading the RAM block during the chip configuration cycle and disabling the write controls, the sysMEM block can also be utilized as a ROM.



Memory Cascading

Larger and deeper blocks of RAM can be created using EBR sysMEM Blocks. Typically, the Lattice design tools cascade memory transparently, based on specific design inputs.

Single, Dual and Pseudo-Dual Port Modes

Figure 2-15 shows the four basic memory configurations and their input/output names. In all the sysMEM RAM modes the input data and address for the ports are registered at the input of the memory array. The output data of the memory is optionally registered at the output.

Figure 2-15. sysMEM EBR Primitives



The EBR memory supports three forms of write behavior for single port or dual port operation:

- 1. **Normal** data on the output appears only during read cycle. During a write cycle, the data (at the current address) does not appear on the output. This mode is supported for all data widths.
- 2. Write Through a copy of the input data appears at the output of the same port during a write cycle. This mode is supported for all data widths.
- 3. **Read-Before-Write** when new data is being written, the old content of the address appears at the output. This mode is supported for x9, x18 and x36 data widths.

Memory Core Reset

The memory array in the EBR utilizes latches at the A and B output ports. These latches can be reset asynchronously or synchronously. RSTA and RSTB are local signals, which reset the output latches associated with Port A and Port B, respectively. The Global Reset (GSRN) signal resets both ports. The output data latches and associated resets for both ports are as shown in Figure 2-16.



Figure 2-16. Memory Core Reset



For further information about sysMEM EBR block, please see the the list of technical documentation at the end of this data sheet.

EBR Asynchronous Reset

EBR asynchronous reset or GSR (if used) can only be applied if all clock enables are low for a clock cycle before the reset is applied and released a clock cycle after the reset is released, as shown in Figure 2-17. The GSR input to the EBR is always asynchronous.

Figure 2-17. EBR Asynchronous Reset (Including GSR) Timing Diagram

Reset	
Clock	
Clock ———— Enable	

If all clock enables remain enabled, the EBR asynchronous reset or GSR may only be applied and released after the EBR read and write clock inputs are in a steady state condition for a minimum of $1/f_{MAX}$ (EBR clock). The reset release must adhere to the EBR synchronous reset setup time before the next active read or write clock edge.

If an EBR is pre-loaded during configuration, the GSR input must be disabled or the release of the GSR during device Wake Up must occur before the release of the device I/Os becomes active.

These instructions apply to all EBR RAM and ROM implementations.

Note that there are no reset restrictions if the EBR synchronous reset is used and the EBR GSR input is disabled.

sysDSP Block

The LatticeECP-DSP family provides a sysDSP block, making it ideally suited for low cost, high performance Digital Signal Processing (DSP) applications. Typical functions used in these applications are Finite Impulse Response (FIR) filters; Fast Fourier Transforms (FFT) functions, correlators, Reed-Solomon/Turbo/Convolution encoders and



decoders. These complex signal processing functions use similar building blocks such as multiply-adders and multiply-accumulators.

sysDSP Block Approach Compared to General DSP

Conventional general-purpose DSP chips typically contain one to four (Multiply and Accumulate) MAC units with fixed data-width multipliers; this leads to limited parallelism and limited throughput. Their throughput is increased by higher clock speeds. The LatticeECP, on the other hand, has many DSP blocks that support different data-widths. This allows the designer to use highly parallel implementations of DSP functions. The designer can optimize the DSP performance vs. area by choosing an appropriate level of parallelism. Figure 2-18 compares the serial and the parallel implementations.



Figure 2-18. Comparison of General DSP and LatticeECP-DSP Approaches

sysDSP Block Capabilities

The sysDSP block in the LatticeECP-DSP family supports four functional elements in three 9, 18 and 36 data path widths. The user selects a function element for a DSP block and then selects the width and type (signed/unsigned) of its operands. The operands in the LatticeECP-DSP family sysDSP Blocks can be either signed or unsigned but not mixed within a function element. Similarly, the operand widths cannot be mixed within a block.

The resources in each sysDSP block can be configured to support the following four elements:

 MULT 	(Multiply)
--------------------------	------------

- MAC (Multiply, Accumulate)
- MULTADD (Multiply, Addition/Subtraction)
- MULTADDSUM (Multiply, Addition/Subtraction, Accumulate)

The number of elements available in each block depends on the width selected from the three available options x9, x18, and x36. A number of these elements are concatenated for highly parallel implementations of DSP functions. Table 2-1 shows the capabilities of the block.



Width of Multiply	x9	x18	x36
MULT	8	4	1
MAC	2	2	_
MULTADD	4	2	_
MULTADDSUM	2	1	_

Some options are available in four elements. The input register in all the elements can be directly loaded or can be loaded as shift registers from previous operand registers. In addition by selecting "dynamic operation" in the 'Signed/Unsigned' options the operands can be switched between signed and unsigned on every cycle. Similarly by selecting 'Dynamic operation' in the 'Add/Sub' option the Accumulator can be switched between addition and subtraction on every cycle.

MULT sysDSP Element

This multiplier element implements a multiply with no addition or accumulator nodes. The two operands, A and B, are multiplied and the result is available at the output. The user can enable the input/output and pipeline registers. Figure 2-19 shows the MULT sysDSP element.

Figure 2-19. MULT sysDSP Element



MAC sysDSP Element

In this case the two operands, A and B, are multiplied and the result is added with the previous accumulated value. This accumulated value is available at the output. The user can enable the input and pipeline registers but the output register is always enabled. The output register is used to store the accumulated value. A registered overflow signal is also available. The overflow conditions are provided later in this document. Figure 2-20 shows the MAC sysDSP element.



Figure 2-20. MAC sysDSP Element



MULTADD sysDSP Element

In this case, the operands A0 and B0 are multiplied and the result is added/subtracted with the result of the multiplier operation of operands A1 and A2. The user can enable the input, output and pipeline registers. Figure 2-21 shows the MULTADD sysDSP element.

Figure 2-21. MULTADD





MULTADDSUM sysDSP Element

In this case, the operands A0 and B0 are multiplied and the result is added/subtracted with the result of the multiplier operation of operands A1 and B1. Additionally the operands A2 and B2 are multiplied and the result is added/ subtracted with the result of the multiplier operation of operands A3 and B3. The result of both addition/subtraction are added in a summation block. The user can enable the input, output and pipeline registers. Figure 2-22 shows the MULTADDSUM sysDSP element.

Figure 2-22. MULTADDSUM



Clock, Clock Enable and Reset Resources

Global Clock, Clock Enable and Reset signals from routing are available to every DSP block. Four Clock, Reset and Clock Enable signals are selected for the sysDSP block. From four clock sources (CLK0, CLK1, CLK2, CLK3) one clock is selected for each input register, pipeline register and output register. Similarly Clock enable (CE) and Reset (RST) are selected from their four respective sources (CE0, CE1, CE2, CE3 and RST0, RST1, RST2, RST3) at each input register, pipeline register and output register.



Signed and Unsigned with Different Widths

The DSP block supports different widths of signed and unsigned multipliers besides x9, x18 and x36 widths. For unsigned operands, unused upper data bits should be filled to create a valid x9, x18 or x36 operand. For signed two's complement operands, sign extension of the most significant bit should be performed until x9, x18 or x36 width is reached. Table 2-8 provides an example of this.

Table 2-8.	An	Exampl	e of	Sign	Extension
Table 2-0.	~	∟∧аттрі	e 01	Sign	LALENSION

Number	Unsigned	Unsigned 9-bit	Unsigned 18-bit	Signed	Two's Complement Signed 9-Bits	Two's Complement Signed 18-bits
+5	0101	000000101	00000000000000101	0101	00000101	00000000000000101
-6	0110	000000110	00000000000000110	1010	111111010	1111111111111111010

OVERFLOW Flag from MAC

The sysDSP block provides an overflow output to indicate that the accumulator has overflowed. When two unsigned numbers are added and the result is a smaller number then accumulator roll over is said to occur and overflow signal is indicated. When two positive numbers are added with a negative sum and when two negative numbers are added with a positive sum, then the accumulator "roll-over" is said to have occurred and an overflow signal is indicated. Note when overflow occurs the overflow flag is present for only one cycle. By counting these overflow pulses in FPGA logic, larger accumulators can be constructed. The conditions overflow signals for signed and unsigned operands are listed in Figure 2-23.

Figure 2-23. Accumulator Overflow/Underflow Conditions





IPexpress[™]

The user can access the sysDSP block via the IPexpress configuration tool, included with the ispLEVER design tool suite. IPexpress has options to configure each DSP module (or group of modules) or through direct HDL instantiation. Additionally Lattice has partnered Mathworks to support instantiation in the Simulink tool, which is a Graphical Simulation Environment. Simulink works with ispLEVER and dramatically shortens the DSP design cycle in Lattice FPGAs.

Optimized DSP Functions

Lattice provides a library of optimized DSP IP functions. Some of the IPs planned for LatticeECP DSP are: Bit Correlators, Fast Fourier Transform, Finite Impulse Response (FIR) Filter, Reed-Solomon Encoder/ Decoder, Turbo Encoder/Decoders and Convolutional Encoder/Decoder. Please contact Lattice to obtain the latest list of available DSP IPs.

Resources Available in the LatticeECP Family

Table 2-9 shows the maximum number of multipliers for each member of the LatticeECP family. Table 2-10 shows the maximum available EBR RAM Blocks in each of the LatticeECP family. EBR blocks, together with Distributed RAM can be used to store variables locally for the fast DSP operations.

Device	DSP Block	9x9 Multiplier	18x18 Multiplier	36x36 Multiplier
LFECP6	4	32	16	4
LFECP10	5	40	20	5
LFECP15	6	48	24	6
LFECP20	7	56	28	7
LFECP33	8	64	32	8

Table 2-9. Number of DSP Blocks in LatticeECP Family

Table 2-10. Embedded SRAM in LatticeECP Family

Device	EBR SRAM Block	Total EBR SRAM (Kbits)
LFECP6	10	92
LFECP10	30	276
LFECP15	38	350
LFECP20	46	424
LFECP33	54	498

DSP Performance of the LatticeECP Family

Table 2-11 lists the maximum performance in millions of MAC operations per second (MMAC) for each member of the LatticeECP family.

 Table 2-11. DSP Block Performance of LatticeECP Family

Device	DSP Block	DSP Performance MMAC
LFECP6	4	3680
LFECP10	5	4600
LFECP15	6	5520
LFECP20	7	6440
LFECP33	8	7360



For further information about the sysDSP block, please see the list of technical information at the end of this data sheet.

Programmable I/O Cells (PIC)

Each PIC contains two PIOs connected to their respective sysl/O Buffers which are then connected to the PADs as shown in Figure 2-24. The PIO Block supplies the output data (DO) and the Tri-state control signal (TO) to sysl/O buffer, and receives input from the buffer.

Figure 2-24. PIC Diagram



Two adjacent PIOs can be joined to provide a differential I/O pair (labeled as "T" and "C") as shown in Figure 2-25. The PAD Labels "T" and "C" distinguish the two PIOs. Only the PIO pairs on the left and right edges of the device can be configured as LVDS transmit/receive pairs.

One of every 16 PIOs contains a delay element to facilitate the generation of DQS signals. The DQS signal feeds the DQS bus which spans the set of 16 PIOs. Figure 2-25 shows the assignment of DQS pins in each set of 16 PIOs. The exact DQS pins are shown in a dual function in the Logic Signal Connections table at the end of this data sheet. Additional detail is provided in the Signal Descriptions table at the end of this data sheet. The DQS signal from the bus is used to strobe the DDR data from the memory into input register blocks. This interface is designed for memories that support one DQS strobe per eight bits of data.



Table 2-12. PIO Signal List

Name	Туре	Description
CE0, CE1	Control from the core	Clock enables for input and output block FFs.
CLK0, CLK1	Control from the core	System clocks for input and output blocks.
LSR	Control from the core	Local Set/Reset.
GSRN	Control from routing	Global Set/Reset (active low).
INCK	Input to the core	Input to Primary Clock Network or PLL reference inputs.
DQS	Input to PIO	DQS signal from logic (routing) to PIO.
INDD	Input to the core	Unregistered data input to core.
INFF	Input to the core	Registered input on positive edge of the clock (CLK0).
IPOS0, IPOS1	Input to the core	DDRX registered inputs to the core.
ONEG0	Control from the core	Output signals from the core for SDR and DDR operation.
OPOS0,	Control from the core	Output signals from the core for DDR operation
OPOS1 ONEG1	Tristate control from the core	Signals to Tristate Register block for DDR operation.
TD	Tristate control from the core	Tristate signal from the core used in SDR operation.
DDRCLKPOL	Control from clock polarity bus	Controls the polarity of the clock (CLK0) that feed the DDR input block.

Figure 2-25. DQS Routing

	→	PIO A		Pair
	→	PIO B	PADB "C	; ,
	→	PIO A	PADA "T"	
				-an)"
		PIO B		<u>i _ i</u>
		PIO A	PADA "T'	<u>-</u> - ۲
			LVDS F	Pair
	→	PIO B		ן "C
		PIO A	PADA "T"	<u></u>
	-		LVDS F	air i
		PIO B	PADB "C	" I
				<u> </u>
			A SUSIO	Ju I
			Buffer DQS Pin	י י
DQS		PIO A	Buffer PADA "	י ד"
		PIO A	Buffer DQS Pin PADA " Delay LVDS F	n T" Pair
DQS		PIO A PIO B	Buffer DQS Pin PADA " Delay LVDS P	n T" Pair C"
DQS	→	PIO A PIO B	Buffer PADA " Pada " LvDs F	Pair
DQS		PIO A PIO B PIO A	Buffer PADA " PADA " PADA " PADA " PADA " PADA "T"	Pair Pair C"
↓ DQS		PIO A PIO B PIO A	Buffer PADA " Pelay LVDS F PADA "T" PADA "T" LVDS P	Pair Pair C" Pair Pair
DQS		PIO A PIO B PIO A PIO B	Buffer PADA " PADA " PADB " PADB " PADB " PADB "C	Pair Pair C" C" Pair Pair C"
DQS	\rightarrow	PIO A PIO B PIO A PIO B PIO A	Buffer PADA " PADA " PADA " PADA "T" PADA "T" UVDS P PADB "C PADA "T"	Pair Pair C" C" Pair Pair Pair Pair Pair Pair
DQS	\rightarrow	PIO A PIO B PIO A PIO B PIO A	Buffer PADA " PADA " PADA " PADA "T" PADA "T" VDS P PADA "T" VDS P	Pair Pair C" Pair Pair Pair Pair Pair
	\rightarrow	PIO A PIO B PIO A PIO B PIO A PIO B	Buffer PADA " PADA " PADA " PADA " PADA " PADA "T" LVDS P PADA "T" LVDS P PADA "T" LVDS P PADA "T" LVDS P	Pair Pair C" C" Pair Pair Pair C" Pair
		PIO A PIO B PIO A PIO B PIO A PIO B	Buffer PADA " LVDS F PADA " PADB "C PADB "C PADB "C PADB "C PADB "C PADB "C	Pair C" C" Pair Pair Pair Pair Pair Pair Pair Pair
	$ \begin{array}{c} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\$	PIO A PIO B PIO A PIO B PIO A PIO B PIO A	Buffer PADA " PADA " PADA " PADA " PADA " PADA " PADA "T" LVDS F PADA "T" LVDS F PADA "T" LVDS F PADA "T" LVDS F	n
	$ \rightarrow $	PIO A PIO B PIO A PIO B PIO A PIO B PIO A PIO B	DOS PIR PADA "" LVDS F PADA "T" LVDS P PADB "C PADB "C PADB "C PADB "C PADB "C PADB "C PADB "C PADB "C PADB "C PADB "C	n

PIO

The PIO contains four blocks: an input register block, output register block, tristate register block and a control logic block. These blocks contain registers for both single data rate (SDR) and double data rate (DDR) operation along with the necessary clock and selection logic. Programmable delay lines used to shift incoming clock and data signals are also included in these blocks.