Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from,Europe,America and south Asia,supplying obsolete and hard-to-find components to meet their specific needs.

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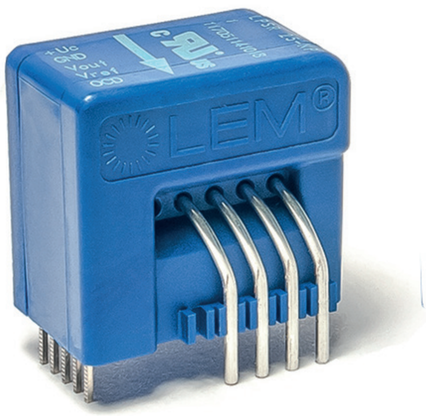
Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China

Current Transducer LPSR series I_{PN} = 6, 15, 25, 50 A

Ref: LPSR 6-NP, LPSR 15-NP, LPSR 25-NP, LPSR 50-NP

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



Features

- Closed loop multi-range current transducer
- Voltage output
- Unipolar supply voltage
- Compact design for PCB mounting
- Overcurrent detect at 4.1 × I_{PN}.

Advantages

- Very low offset drift
- Very good dv/dt immunity
- Reference pin with two modes: Ref IN and Ref OUT
- Extended measuring range for unipolar measurement.

Applications

- AC variable speed and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications
- Solar inverters.

Standards

- IEC 61800-1: 1997
- IEC 61800-2: 2015
- IEC 61800-3: 2004
- IEC 61800-5-1: 2007
- IEC 62109-1: 2010
- IEC 62477-1: 2012
- UL 508:2013.

Application Domain

- Industrial.

Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage	$U_{C\ max}$	V	7
Maximum primary conductor temperature	$T_{B\ max}$	°C	110
Maximum primary current	$I_{P\ max}$	A	20 × $I_{P\ N}$
Maximum electrostatic discharge voltage	$U_{ESD\ max}$	kV	4

Stresses above these ratings may cause permanent damage. Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 11

Standards

- CSA C22.2 NO. 14-10 INDUSTRIAL CONTROL EQUIPMENT - Date 2011/08/01
- UL 508 STANDARD FOR INDUSTRIAL CONTROL EQUIPMENT - Date 2013

Ratings

Parameter	Symbol	Unit	Value
Primary involved potential		V AC/DC	1000
Max surrounding air temperature	T_A	°C	105
Primary current	I_P	A	According to series primary currents
Secondary supply voltage	U_C	V DC	7
Output voltage	V_{out}	V	0 to 5

Conditions of acceptability

When installed in the end-use equipment, consideration shall be given to the following:

1 - These devices must be mounted in a suitable end-use enclosure.

2 - The terminals have not been evaluated for field wiring.

3 - The LES, LESR, LKSR, LPSR, LXS and LXSR Series shall be used in a pollution degree 2 environment or better.

4 - Low voltage circuits are intended to be powered by a circuit derived from an isolating source (such as a transformer, optical isolator, limiting impedance or electro-mechanical relay) and having no direct connection back to the primary circuit (other than through the grounding means).

5 - These devices are intended to be mounted on the printed wiring board of the end-use equipment (with a minimum CTI of 100).

6 - LES, LESR, LKSR and LPSR Series: based on results of temperature tests, in the end-use application, a maximum of 110°C cannot be exceeded on the primary jumper.

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	U_d	kV	4.3	
Impulse withstand voltage 1.2/50 µs	$\hat{U}_W$	kV	8	
Insulation resistance	R_{INS}	GΩ	18	measured at 500 V DC
Partial discharge RMS test voltage (q_m < 10 pC)	U_t	kV	1.65	
Clearance (pri. - sec.)	d_{Cl}	mm		See dimensions drawing on page 19
Creepage distance (pri. - sec.)	d_{Cp}			
Case material	-	-	V0 according to UL 94	
Comparative tracking index	*CTI*		600	
Application example		V	600 V CAT III, PD2	Reinforced insulation, non uniform field according to IEC 61800-5-1
Application example		V	1000 V CAT III, PD2	Basic insulation, non uniform field according to IEC 61800-5-1

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Ambient operating temperature	T_A	°C	−40		105	
Ambient storage temperature	T_S	°C	−55		125	
Mass	m	g		10		

Electrical data LPSR 6-NP

At T_A = 25 °C, U_C = +5 V, N_P = 1 turn, R_L = 10 kΩ internal reference, unless otherwise noted (see Definition of typical, minimum and maximum values paragraph in page 18).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal RMS current	I_{PN}	A		6		Apply derating according to fig. 21
Primary current, measuring range	I_{PM}	A	−20		20	
Number of primary turns	N_P			1, 2, 3, 4		
Supply voltage	U_C	V	4.75	5	5.25	
Current consumption	I_C	mA		$17+\frac{I_P(\text{mA})}{N_S}$	$20+\frac{I_P(\text{mA})}{N_S}$	N_S = 2000 turns
Reference voltage @ I_P = 0 A	V_{ref}	V	2.485	2.5	2.515	Internal reference
External reference voltage	V_{ref}	V	0.5		2.75	
Output voltage	V_{out}	V	0.25		4.75	with U_C = +5 V
Output voltage @ I_P = 0 A	V_{out}	V		V_{ref}		
Electrical offset voltage	V_{OE}	mV	−5		5	100 % tested $V_{out} - V_{ref}$
Electrical offset current referred to primary	I_{OE}	mA	−48		48	100 % tested
Temperature coefficient of V_{ref} @ I_P = 0 A	TCV_{ref}	ppm/K			±70	Internal reference
Temperature coefficient of V_{out} @ I_P = 0 A	TCV_{out}	ppm/K			±14	ppm/K of 2.5 V −40 °C … 105 °C
Theoretical sensitivity	G_{th}	mV/A		104.2		625 mV/I_{PN}
Sensitivity error	ε_G	%	−0.2		0.2	100 % tested
Temperature coefficient of G	TCG	ppm/K			±40	−40 °C … 105 °C
Linearity error	ε_L	% of I_{PN}	−0.1		0.1	
Magnetic offset current (10 × I_{PN}) referred to primary	I_{OM}	mA	−25		25	
Output RMS voltage noise spectral density 100 … 100 kHz referred to primary	e_{no}	µV/Hz½		7		
Output voltage noise DC … 10 kHz DC … 100 kHz DC … 1 MHz	V_{no}	mVpp		 10.5 13.4 13.6		
Primary current, detection threshold	I_{PTh}	A	4.02 × I_{PN}	4.1 × I_{PN}	4.17 × I_{PN}	
Overcurrent detection response time	t_{rTh}	µs		1.4	2.2	Overcurrent detection measured over temperature −40 °C … 105 °C with a I_P step of 5 × I_{PN} and di/dt = 50 A/µs
Overcurrent detection hold time	$t_{hold\,Th}$	ms			1	
Reaction time @ 10 % of I_{PN}	t_{ra}	µs			0.3	R_L = 1 kΩ, di/dt = 50 A/µs
Step response time to 90 % of I_{PN}	t_r	µs			0.4	R_L = 1 kΩ, di/dt = 50 A/µs
Frequency bandwidth (±1 dB)	BW	kHz	300			R_L = 1 kΩ
Overall accuracy	X_G	% of I_{PN}			1.25	
Overall accuracy @ T_A = 85 °C (105 °C)	X_G	% of I_{PN}			1.25 (1.5)	
Accuracy	X	% of I_{PN}			0.5	
Accuracy @ T_A = 85 °C (105 °C)	X	% of I_{PN}			0.75 (1)	

Electrical data LPSR 15-NP

At T_A = 25 °C, U_C = +5 V, N_P = 1 turn, R_L = 10 kΩ internal reference, unless otherwise noted (see Definition of typical, minimum and maximum values paragraph in page 18).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal RMS current	I_{PN}	A		15		Apply derating according to fig. 22
Primary current, measuring range	I_{PM}	A	−51		51	
Number of primary turns	N_P			1, 2, 3, 4		
Supply voltage	U_C	V	4.75	5	5.25	
Current consumption	I_C	mA		$17 + \frac{I_P(\text{mA})}{N_S}$	$20 + \frac{I_P(\text{mA})}{N_S}$	N_S = 2000 turns
Reference voltage @ I_P = 0 A	V_{ref}	V	2.485	2.5	2.515	Internal reference
External reference voltage	V_{ref}	V	0.5		2.75	
Output voltage	V_{out}	V	0.25		4.75	with U_C = +5 V
Output voltage @ I_P = 0 A	V_{out}	V		V_{ref}		
Electrical offset voltage	V_{OE}	mV	−1.75		1.75	100 % tested $V_{out} - V_{ref}$
Electrical offset current referred to primary	I_{OE}	mA	−42		42	100 % tested
Temperature coefficient of V_{ref} @ I_P = 0 A	TCV_{ref}	ppm/K			±70	Internal reference
Temperature coefficient of V_{out} @ I_P = 0 A	TCV_{out}	ppm/K			±6	ppm/K of 2.5 V −40 °C … 105 °C
Theoretical sensitivity	G_{th}	mV/A		41.67		625 mV/I_{PN}
Sensitivity error	ε_G	%	−0.2		0.2	100 % tested
Temperature coefficient of G	TCG	ppm/K			±40	−40 °C … 105 °C
Linearity error	ε_L	% of I_{PN}	−0.1		0.1	
Magnetic offset current (10 × I_{PN}) referred to primary	I_{OM}		−45		45	
Output RMS voltage noise spectral density 100 … 100 kHz referred to primary	e_{no}	µV/Hz½		3.5		
Output voltage noise DC … 10 kHz DC … 100 kHz DC … 1 MHz	V_{no}	mVpp		 4.5 5.7 6.3		
Primary current, detection threshold	I_{PTh}	A	4.02 × I_{PN}	4.1 × I_{PN}	4.17 × I_{PN}	
Overcurrent detection response time	t_{rTh}	µs		1.4	2.2	Overcurrent detection measured over temperature −40 °C … 105 °C with a I_P step of 5 × I_{PN} and di/dt = 50 A/µs
Overcurrent detection hold time	$t_{hold\,Th}$	ms			1	
Reaction time @ 10 % of I_{PN}	t_{ra}	µs			0.3	R_L = 1 kΩ, di/dt = 50 A/µs
Step response time to 90 % of I_{PN}	t_r	µs			0.4	R_L = 1 kΩ, di/dt = 50 A/µs
Frequency bandwidth (±3 dB)	BW	kHz	300			R_L = 1 kΩ
Overall accuracy	X_G	% of I_{PN}			0.75	
Overall accuracy @ T_A = 85 °C (105 °C)	X_G	% of I_{PN}			0.75 (1)	
Accuracy	X	% of I_{PN}			0.5	
Accuracy @ T_A = 85 °C (105 °C)	X	% of I_{PN}			0.65 (0.75)	

Electrical data LPSR 25-NP

At T_A = 25 °C, U_C = +5 V, N_P = 1 turn, R_L = 10 kΩ internal reference, unless otherwise noted (see Definition of typical, minimum and maximum values paragraph in page 18).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal RMS current	I_{PN}	A		25		Apply derating according to fig. 23
Primary current, measuring range	I_{PM}	A	−85		85	
Number of primary turns	N_P			1, 2, 3, 4		
Supply voltage	U_C	V	4.75	5	5.25	
Current consumption	I_C	mA		$17 + \frac{I_P(mA)}{N_S}$	$20 + \frac{I_P(mA)}{N_S}$	N_S = 2000 turns
Reference voltage @ I_P = 0 A	V_{ref}	V	2.485	2.5	2.515	Internal reference
External reference voltage	V_{ref}	V	0.5		2.75	
Output voltage	V_{out}	V	0.25		4.75	with U_C = +5 V
Output voltage @ I_P = 0 A	V_{out}	V		V_{ref}		
Electrical offset voltage	V_{OE}	mV	−1		1	100 % tested $V_{out} - V_{ref}$
Electrical offset current referred to primary	I_{OE}	mA	−40		40	100 % tested
Temperature coefficient of V_{ref} @ I_P = 0 A	TCV_{ref}	ppm/K			±70	Internal reference
Temperature coefficient of V_{out} @ I_P = 0 A	TCV_{out}	ppm/K			±4	ppm/K of 2.5 V −40 °C … 105 °C
Theoretical sensitivity	G_{th}	mV/A		25		625 mV/I_{PN}
Sensitivity error	ε_G	%	−0.2		0.2	100 % tested
Temperature coefficient of G	TCG	ppm/K			±40	−40 °C … 105 °C
Linearity error	ε_L	% of I_{PN}	−0.1		0.1	
Magnetic offset current (10 × I_{PN}) referred to primary	I_{OM}	mA	−60		60	
Output RMS voltage noise spectral density 100 … 100 kHz referred to primary	e_{no}	µV/Hz½		1.8		
Output voltage noise DC … 10 kHz DC … 100 kHz DC … 1 MHz	V_{no}	mVpp		 2.6 3.9 5.1		
Primary current, detection threshold	$I_{P\,Th}$	A	4.02 × I_{PN}	4.1 × I_{PN}	4.17 × I_{PN}	
Overcurrent detection response time	$t_{r\,Th}$	µs		1.4	2.2	Overcurrent detection measured over temperature −40 °C … 105 °C with a I_P step of 5 × I_{PN} and di/dt = 50 A/µs
Overcurrent detection hold time	$t_{hold\,Th}$	ms			1	
Reaction time @ 10 % of I_{PN}	t_{ra}	µs			0.3	R_L = 1 kΩ, di/dt = 50 A/µs
Step response time to 90 %of I_{PN}	t_r	µs			0.4	R_L = 1 kΩ, di/dt = 50 A/µs
Frequency bandwidth (±3 dB)	BW	kHz	300			R_L = 1 kΩ
Overall accuracy	X_G	% of I_{PN}			0.8	
Overall accuracy @ T_A = 85 °C (105 °C)	X_G	% of I_{PN}			0.85 (0.9)	
Accuracy	X	% of I_{PN}			0.5	
Accuracy @ T_A = 85 °C (105 °C)	X	% of I_{PN}			0.65 (0.75)	

Electrical data LPSR 50-NP

At T_A = 25 °C, U_C = +5 V, N_P = 1 turn, R_L = 10 kΩ internal reference, unless otherwise noted (see Definition of typical, minimum and maximum values paragraph in page 18).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal RMS current	I_{PN}	A		50		Apply derating according to fig. 24
Primary current, measuring range	I_{PM}	A	−150		150	
Number of primary turns	N_P			1, 2, 3, 4		
Supply voltage	U_C	V	4.75	5	5.25	
Current consumption	I_C	mA		$17 + \frac{I_P(\text{mA})}{N_S}$	$20 + \frac{I_P(\text{mA})}{N_S}$	N_S = 1600 turns
Reference voltage @ I_P = 0 A	V_{ref}	V	2.485	2.5	2.515	Internal reference
External reference voltage	V_{ref}	V	0.5		2.75	
Output voltage	V_{out}	V	0.25		4.75	with U_C = +5 V
Output voltage @ I_P = 0 A	V_{out}	V		V_{ref}		
Electrical offset voltage	V_{OE}	mV	−0.7		0.7	100 % tested $V_{out} - V_{ref}$
Electrical offset current referred to primary	I_{OE}	mA	−56		56	100 % tested
Temperature coefficient of V_{ref} @ I_P = 0 A	TCV_{ref}	ppm/K			±70	Internal reference
Temperature coefficient of V_{out} @ I_P = 0 A	TCV_{out}	ppm/K			±3	ppm/K of 2.5 V −40 °C … 105 °C
Theoretical sensitivity	G_{th}	mV/A		12.5		625 mV/I_{PN}
Sensitivity error	ε_G	%	−0.2		0.2	100 % tested
Temperature coefficient of G	TCG	ppm/K			±40	−40 °C … 105 °C
Linearity error	ε_L	% of I_{PN}	−0.1		0.1	
Magnetic offset current (10 × I_{PN}) referred to primary	I_{OM}	mA	−60		60	
Output RMS voltage noise spectral density 100 … 100 kHz referred to primary	e_{no}	µV/Hz½		1.7		
Output voltage noise DC … 10 kHz DC … 100 kHz DC … 1 MHz	V_{no}	mVpp		 2.4 3.2 4.8		
Primary current, detection threshold	I_{PTh}	A	4.02 × I_{PN}	4.1 × I_{PN}	4.17 × I_{PN}	
Overcurrent detection response time	t_{rTh}	µs		1.4	2.2	Overcurrent detection measured over temperature −40 °C … 105 °C with a I_P step of 5 × I_{PN} and di/dt = 50 A/µs
Overcurrent detection hold time	$t_{hold\,Th}$	ms			1	
Reaction time @ 10 % of I_{PN}	t_{ra}	µs			0.3	R_L = 1 kΩ, di/dt = 50 A/µs
Step response time to 90 % of I_{PN}	t_r	µs			0.4	R_L = 1 kΩ, di/dtt = 50 A/µs
Frequency bandwidth (±3 dB)	BW	kHz	300			R_L = 1 kΩ
Overall accuracy	X_G	% of I_{PN}			0.7	
Overall accuracy @ T_A = 85 °C (105 °C)	X_G	% of I_{PN}			0.7 (0.8)	
Accuracy	X	% of I_{PN}			0.5	
Accuracy @ T_A = 85 °C (105 °C)	X	% of I_{PN}			0.65 (0.75)	

Typical performance characteristics LPSR 6-NP

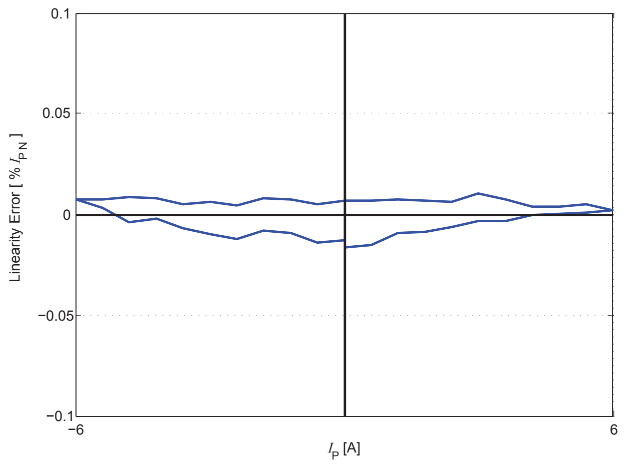


Figure 1: Linearity error

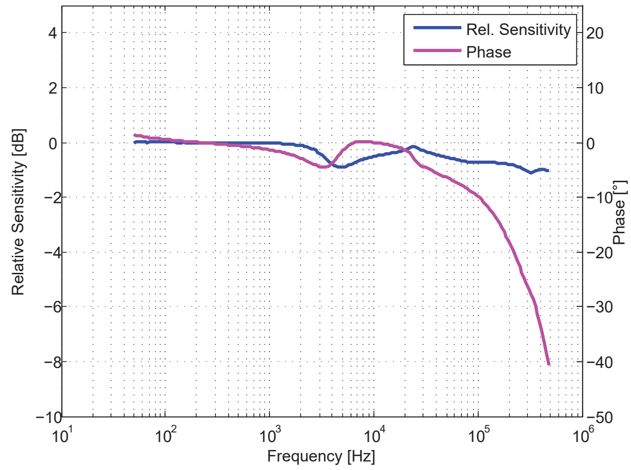


Figure 2: Frequency response

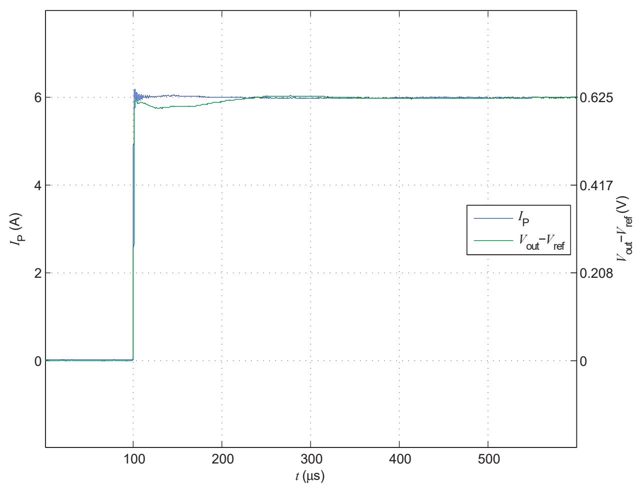


Figure 3: Step response

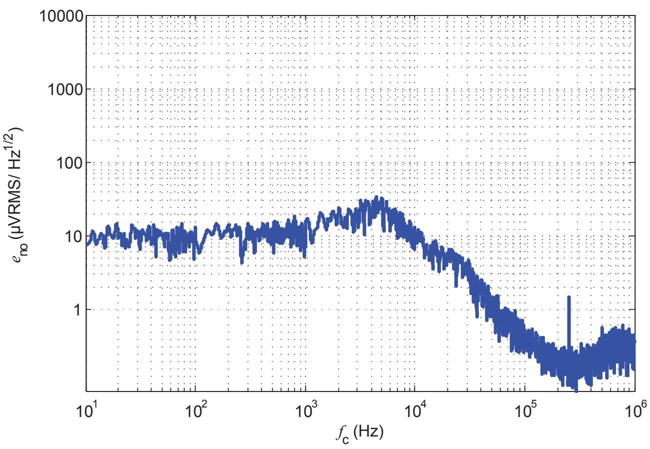


Figure 4: Output noise voltage spectral density

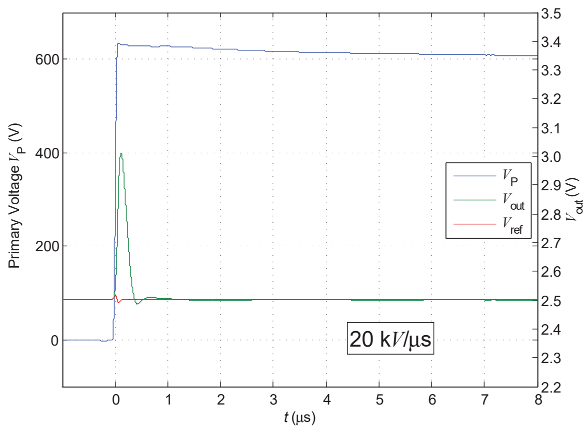


Figure 5: dv/dt

Typical performance characteristics LPSR 15-NP

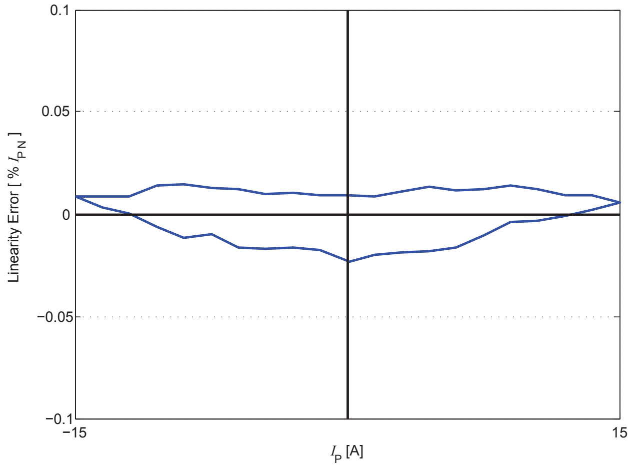


Figure 6: Linearity error

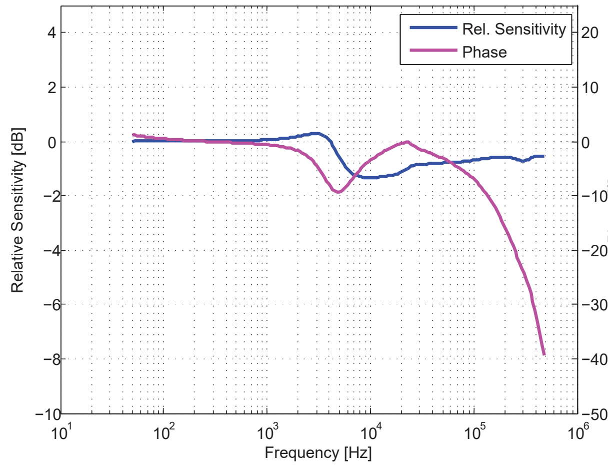


Figure 7: Frequency response

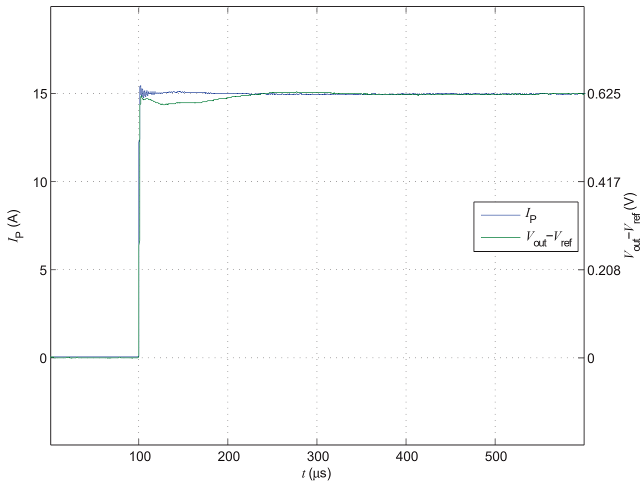


Figure 8: Step response

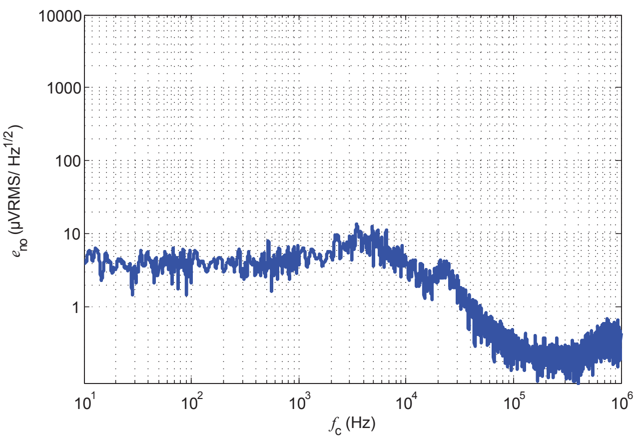


Figure 9: Output noise voltage spectral density

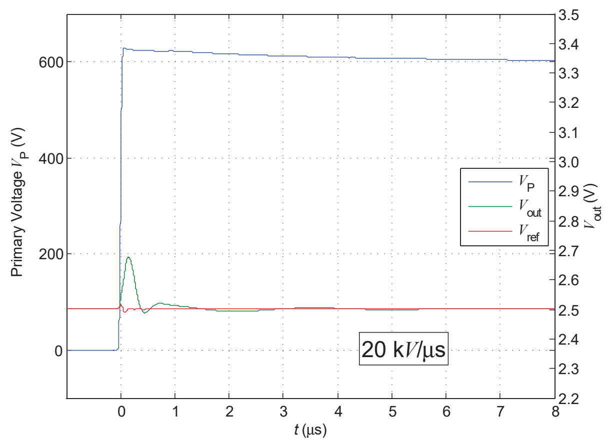


Figure 10: dv/dt

Typical performance characteristics LPSR 25-NP

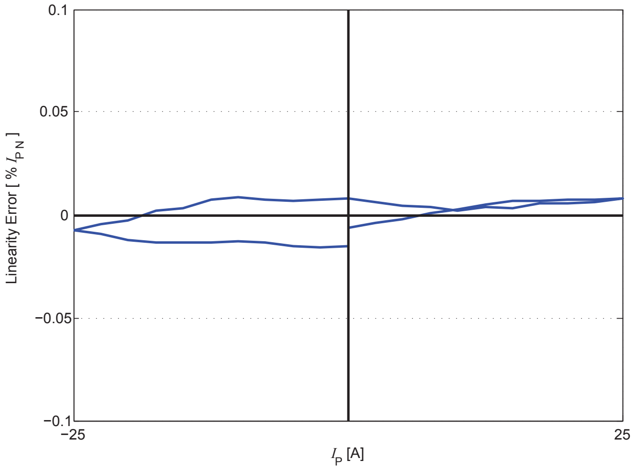


Figure 11: Linearity error

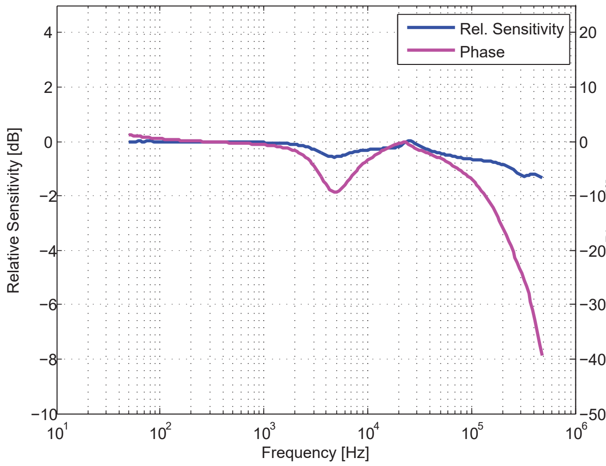


Figure 12: Frequency response

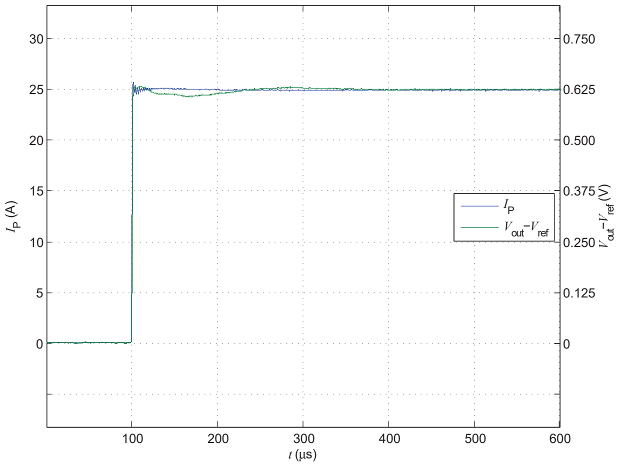


Figure 13: Step response

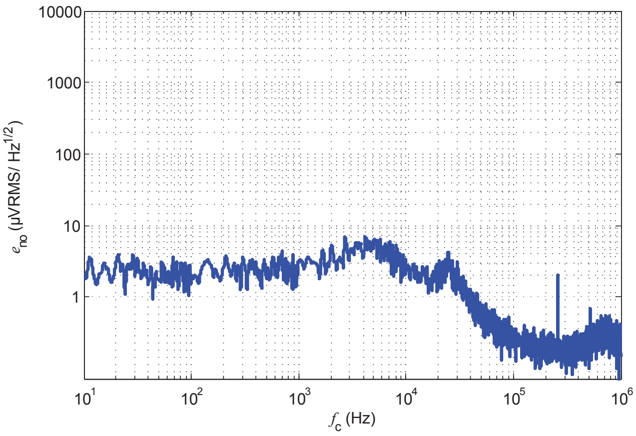


Figure 14: Output noise voltage spectral density

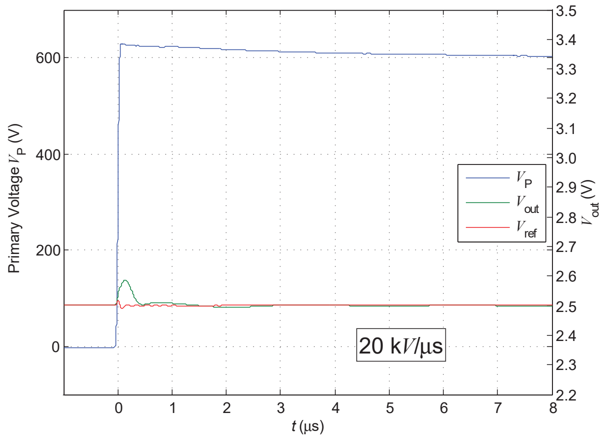


Figure 15: dv/dt

Typical performance characteristics LPSR 50-NP

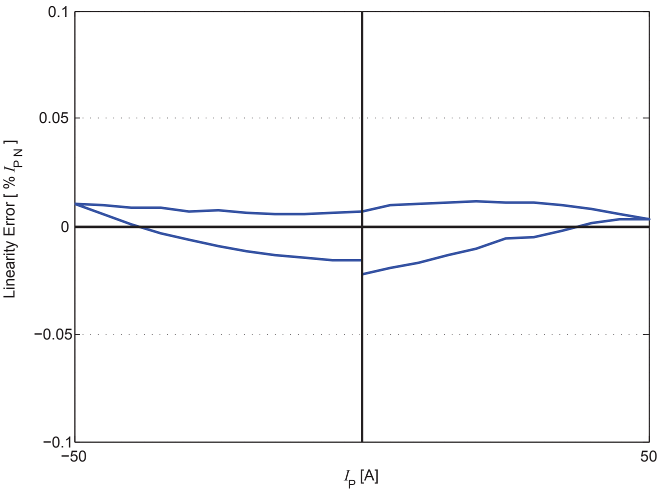


Figure 16: Linearity error

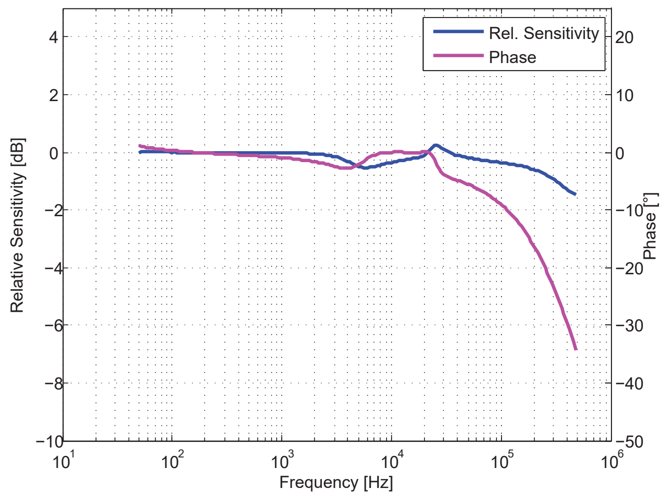


Figure 17: Frequency response

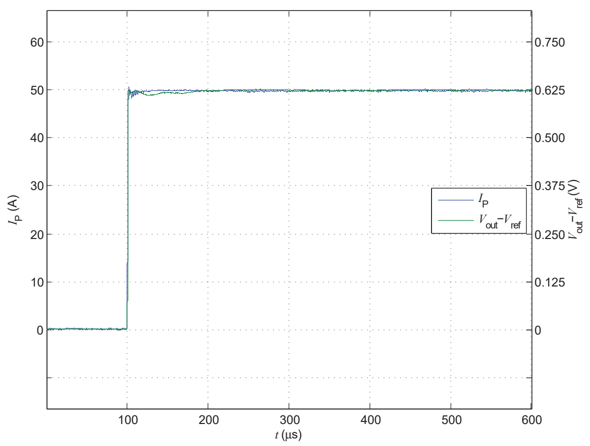


Figure 18: Step response

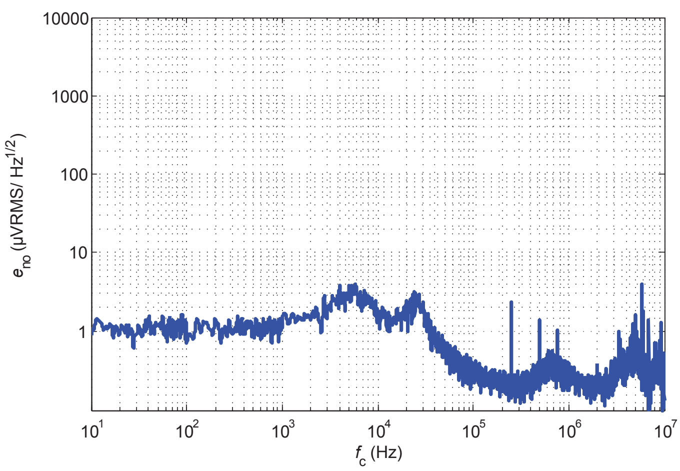


Figure 19: Output noise voltage spectral density

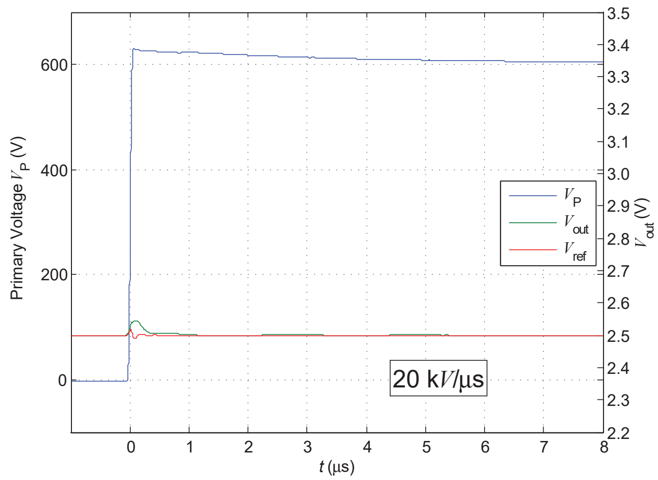


Figure 20: dv/dt

Maximum continuous DC primary current

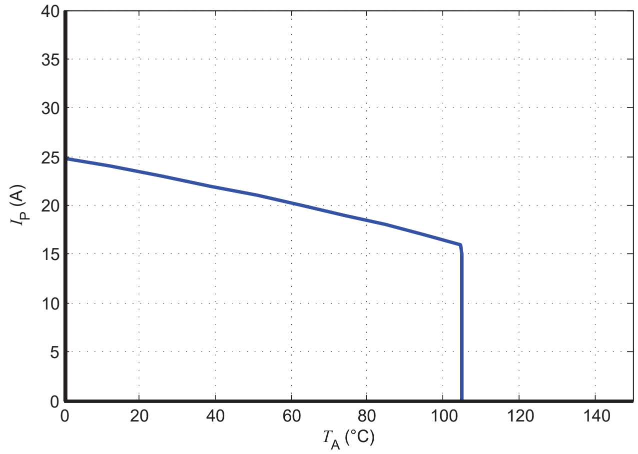


Figure 21: I_P vs T_A for LPSR 6-NP

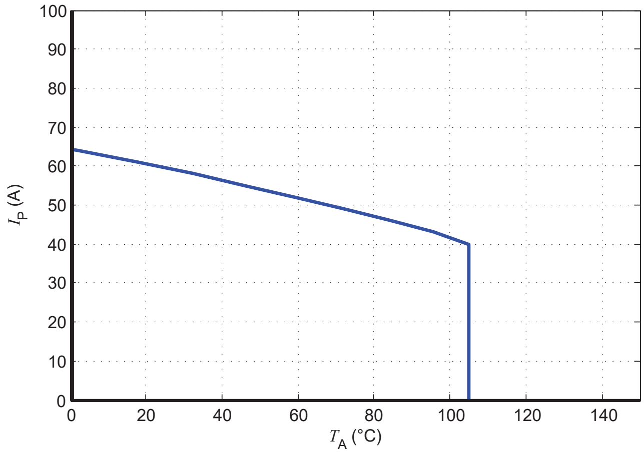


Figure 22: I_P vs T_A for LPSR 15-NP

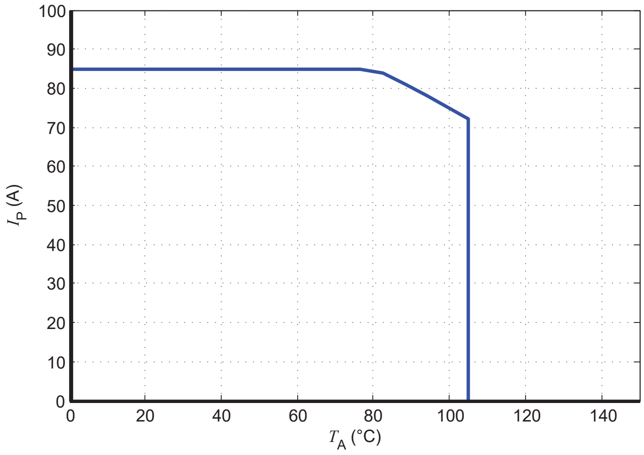


Figure 23: I_P vs T_A for LPSR 25-NP

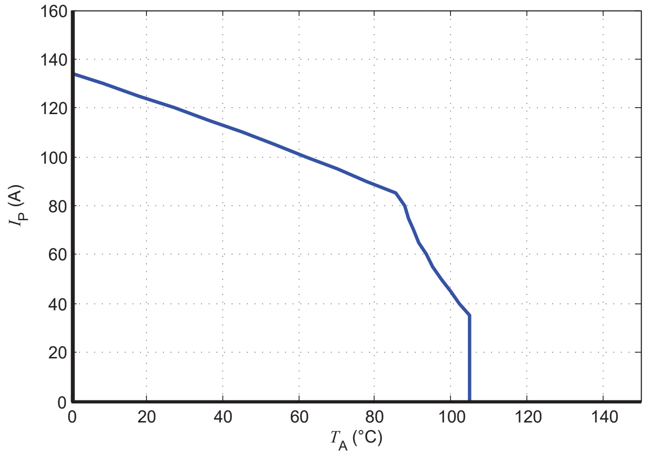


Figure 24: I_P vs T_A for LPSR 50-NP

The maximum continuous DC primary current plot shows the boundary of the area for which all the following conditions are true:

- $I_P < I_{P M}$
- Junction temperature T_J < 125 °C
- Primary conductor temperature < 110 °C
- Max power dissipation of internal resistors < 0.5 × resistors nominal power

Frequency derating

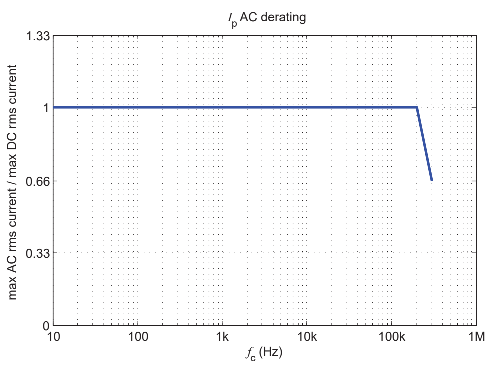


Figure 25: Maximum RMS AC primary current / maximum DC primary current vs frequency

Performance parameters definition

Ampere-turns and amperes

The transducer is sensitive to the primary current linkage Θ_P (also called ampere-turns).

$\Theta_P = N_P \cdot I_P$ (At)
Where N_P is the number of primary turn (depending on the connection of the primary jumpers)

Caution: As most applications will use the transducer with only one single primary turn (N_P = 1), much of this datasheet is written in terms of primary current instead of current linkages. However, the ampere-turns (At) unit is used to emphasis that current linkages are intended and applicable.

Transducer simplified model

The static model of the transducer at temperature T_A is:

$V_{out} = G \cdot \Theta_P + \varepsilon$
In which ε =

$$V_{O E} + V_{O T}(T_A) + \varepsilon_G \cdot \Theta_P \cdot G + \varepsilon_L (\Theta_{P\,max}) \cdot \Theta_{P\,max} \cdot G + TCG \cdot (T_A - 25) \cdot \Theta_P \cdot G$$

With:
- $\Theta_P = N_P \cdot I_P$: primary current linkage (At)
- $\Theta_{P\,max}$: max primary current linkage applied to the transducer
- I_S : secondary current (A)
- T_A : ambient operating temperature (°C)
- $I_{O E}$: electrical offset current (A)
- $I_{O T}(T_A)$: temperature variation of I_O at temperature T_A (°C)
- G : sensitivity of the transducer (V/At)
- TCG : temperature coefficient of G
- ε_G : sensitivity error
- $\varepsilon_L(\Theta_{P\,max})$: linearity error for $\Theta_{P\,max}$

This model is valid for primary ampere-turns Θ_P between $-\Theta_{P\,max}$ and $+\Theta_{P\,max}$ only.

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to I_P, then to $-I_P$ and back to 0 (equally spaced I_P/10 steps). The sensitivity G is defined as the slope of the linear regression line for a cycle between $\pm I_{P N}$.
The linearity error ε_L is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of $I_{P N}$.

Magnetic offset

The magnetic offset current $I_{O M}$ is the consequence of a current on the primary side ("memory effect" of the transducer's ferro-magnetic parts). It is measured using the following primary current cycle. $I_{O M}$ depends on the current value I_{P1} ($I_{P1} > I_{P M}$).

$$I_{O M} = \frac{V_{out}(t_1) - V_{out}(t_2)}{2} \cdot \frac{1}{G_{th}}$$

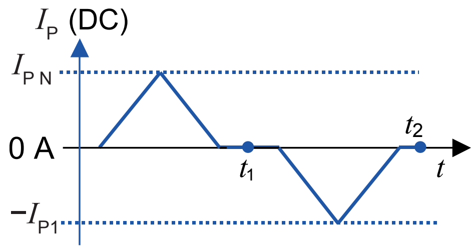


Figure 26: Current cycle used to measure magnetic and electrical offset (transducer supplied)

Performance parameters definition

Electrical offset

The electrical offset voltage V_{OE} can either be measured when the ferro-magnetic parts of the transducer are:

- Completely demagnetized, which is difficult to realize,
- or in a known magnetization state, like in the current cycle shown in figure 26.

Using the current cycle shown in figure 26, the electrical offset is:

$$V_{OE} = \frac{V_{out}(t_1) + V_{out}(t_2)}{2}$$

The temperature variation V_{OT} of the electrical offset voltage V_{OE} is the variation of the electrical offset from 25 °C to the considered temperature:

$$V_{OT}(T) = V_{OE}(T) - V_{OE}(25°C)$$

Note: the transducer has to be demagnetized prior to the application of the current cycle (for example with a demagnetization tunnel).

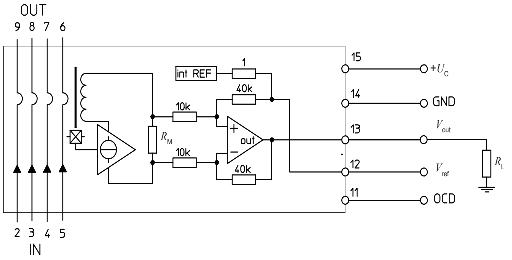


Figure 27: Test connection

Overall accuracy

The overall accuracy at 25 °C X_G is the error in the $-I_{PN} \dots +I_{PN}$ range, relative to the rated value I_{PN}.
It includes:

- the electrical offset V_{OE}
- the sensitivity error ε_G
- the linearity error ε_L (to I_{PN})

Response and reaction times

The response time t_r and the reaction time t_{ra} are shown in figure 28.

Both depend on the primary current di/dt. They are measured at nominal ampere-turns.

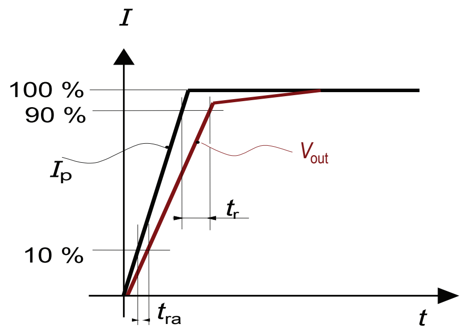


Figure 28: Response time t_r and reaction time t_{ra}

Application information

Filtering and decoupling

Supply voltage U_C

The transducer has internal decoupling capacitors, but in the case of a power supply with high impedance, it is highly recommended to provide local decoupling (100 nF or more, located close to the transducer) as it may reduce disturbance on transducer output V_{out} and reference V_{ref} due to high varying primary current. The transducer power supply rejection ratio is low at high frequency.

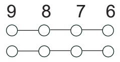
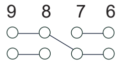
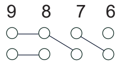
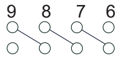
Output V_{out}

The output V_{out} has a very low output impedance of typically 1 Ohm; it can drive capacitive loads of up to 100 nF directly. Adding series resistance Rf of several tenths of Ohms allows much larger capacitive loads Cf (higher than 1 μF). Empirical evaluation may be necessary to obtain optimum results. The minimum load resistance on V_{out} is 1 kOhm.

Total Primary Resistance

The primary resistance is 0.72 mΩ per conductor.

In the following table, examples of primary resistance according to the number of primary turns.

Number of primary turns	Primary Nominal RMS current	Output voltage V_{out}	Primary resistance R_P [mΩ]	Recommended connections
1	$\pm I_{PN}$	V_{ref} ±0.625	0.18	9 8 7 6 OUT  IN 2 3 4 5
2	$\pm I_{PN}/2$	V_{ref} ±0.625	0.72	9 8 7 6 OUT  IN 2 3 4 5
3	$\pm I_{PN}/3$	V_{ref} ±0.625	1.8	9 8 7 6 OUT  IN 2 3 4 5
4	$\pm I_{PN}/4$	V_{ref} ±0.625	2.88	9 8 7 6 OUT  IN 2 3 4 5

Reference V_{ref}

Likewise output V_{out}, the V_{ref} has a very low output impedance of typically 1 Ohm; it can drive capacitive loads of up to 100 nF directly. Adding series resistance Rf of several tenths of Ohms allows much larger capacitive loads Cf (higher than 1 μF). Empirical evaluation may be necessary to obtain optimum results. The minimum load resistance on V_{ref} is 10 kOhms.

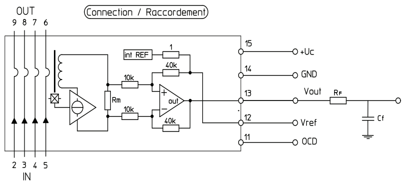


Figure 29: filtered V_{out} connection

External reference voltage

The REF pin can be used either as a reference voltage output or as a reference voltage input.
When used in reference voltage output, the internal reference voltage V_{ref} is used by the transducer as the reference point for bipolar measurements.
The internal reference voltage output accuracy is defined in the electrical parameter data.
When used in reference voltage input, an external reference voltage is connected to the REF pin.
In this case, the maximun allowable reference voltage range is 0.5 V - 2.75 V.
The REF pin must be able to source or sink an input current of maximun 1.5 mA.
If the reference voltage is not used, the REF pin should be left unconnected.

The following graphs show how the measuring range of each transducer version depends on the external reference voltage value V_{ref}.

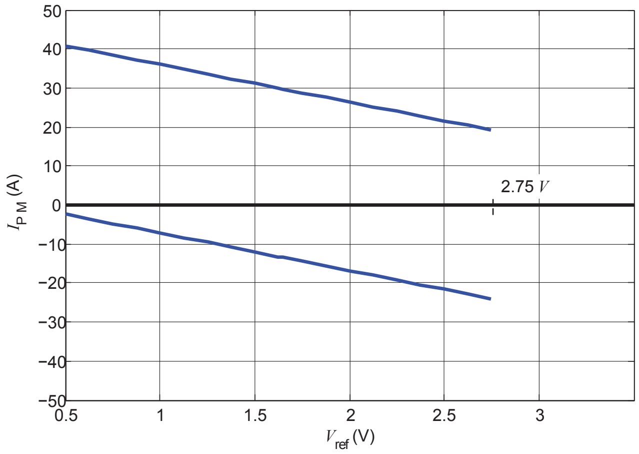


Figure 30: Measuring range versus external V_{ref} LPSR 6 A

Upper limit: $I_P = -9.6 * V_{ref} + 45.6$ (V_{ref} = 0.5 … 2.75 V)

Lower limit: $I_P = -9.6 * V_{ref} + 2.4$ (V_{ref} = 0.5 … 2.75 V)

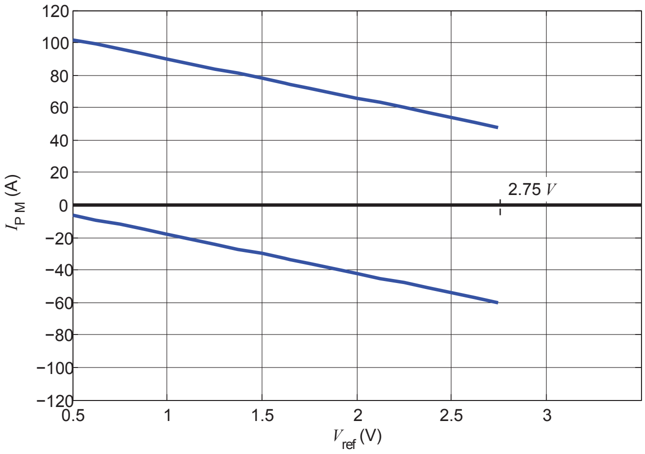


Figure 31: Measuring range versus external V_{ref} LPSR 15 A

Upper limit: $I_P = -24 * V_{ref} + 114$ (V_{ref} = 0.5 … 2.75 V)

Lower limit: $I_P = -24 * V_{ref} + 6$ (V_{ref} = 0 … 2.75 V)

External reference voltage

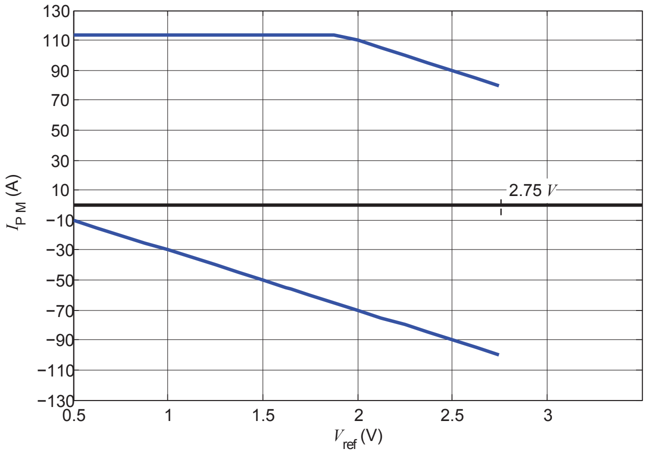


Figure 32: Measuring range versus external V_{ref} LPSR 25 A

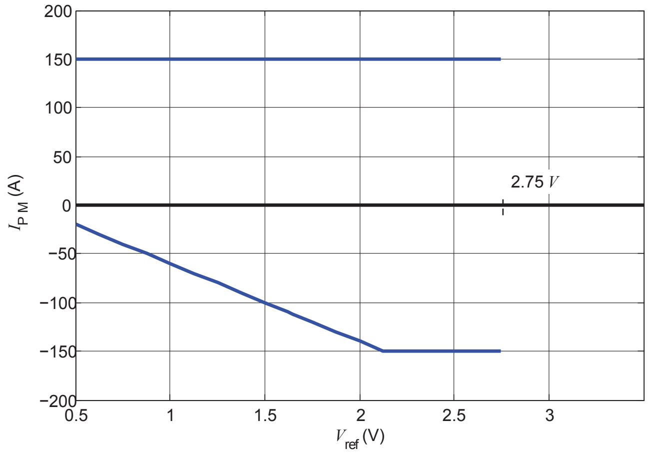


Figure 33: Measuring range versus external V_{ref} LPSR 50 A

Upper limit: $I_P = -40 * V_{ref} + 190$ (V_{ref} = 1.85 … 2.75 V)
Upper limit: I_P = 113 (V_{ref} = 0 …1.85 V)
Lower limit: $I_P = -40 * V_{ref} + 10$ (V_{ref} = 0 … 2.75 V)

Upper limit: I_P = 150 (V_{ref} = 0 … 2.75 V)
Lower limit: $I_P = -80 * V_{ref} + 20$ (V_{ref} = 0 … 2.125 V)
Lower limit: I_P = −150 (V_{ref} = 2.125 … 2.75 V)

Example with V_{ref} = 1.65 V:

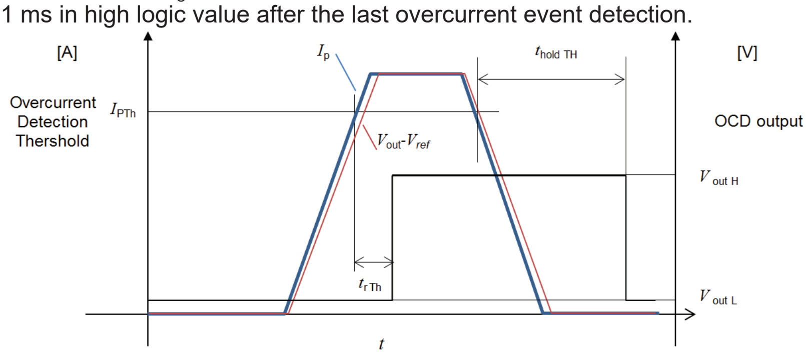
- The 6 A version has a measuring range from −13.44 A to +29.76 A
- The 15 A version has a measuring range from −33.6 A to +74.4 A
- The 25 A version has a measuring range from −56 A to +113 A
- The 50 A version has a measuring range from −112 A to +150 A

Example with V_{ref} = 0.5 V:

- The 6 A version has a measuring range from −2.4 A to +40.8 A
- The 15 A version has a measuring range from −6 A to +102 A
- The 25 A version has a measuring range from −10 A to +113 A
- The 50 A version has a measuring range from −20 A to +150 A

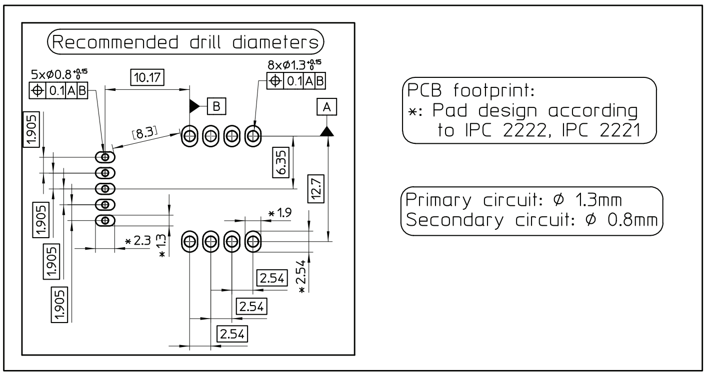
Overcurrent detection definition

The overcurrent detection function generates an output signal to the OCD pin whenever the primary current exceeds a pre-programmed threshold value. Once the overcurrent event is detected, the CMOS-type OCD signal changes from low logic (< 30 % U_C) to high logic value(> 70 % U_C). In order to avoid undesirable glitches, the OCD signal is digitally filtered and the OCD signal output is held for 1 ms in high logic value after the last overcurrent event detection.



Parameter	Symbol	Unit	Min	Typ	Max	Comment
High-level output voltage	$V_{out\ H}$	V	3.5			With U_C = +5 V and source current of 3 mA
Low-level output voltage	$V_{out\ L}$	V			1.5	With U_C = +5 V and sink current of 3 mA

PCB footprint



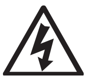
Assembly on PCB

- Recommended PCB hole diameter — 1.3 mm for primary pin; 0.8 mm for secondary pin
- Maximum PCB thickness — 2.4 mm
- Wave soldering profile — maximum 260 °C for 10 s
  No clean process only

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.

This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.
Caution, risk of electrical shock



When operating the transducer, certain parts of the module can carry hazardous voltage (e.g. primary busbar, power supply). Ignoring this warning can lead to injury and/or cause serious damage.
This transducer is a build-in device, whose conducting parts must be inaccessible after installation.
A protective housing or additional shield could be used. Main supply must be able to be disconnected.

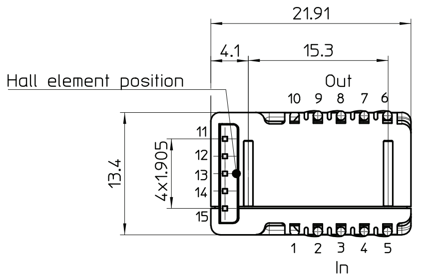
Remark

Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: **Products/Product Documentation.**

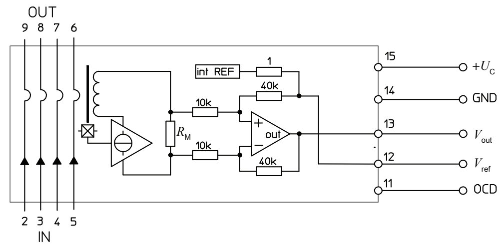
Definition of typical, minimum and maximum values

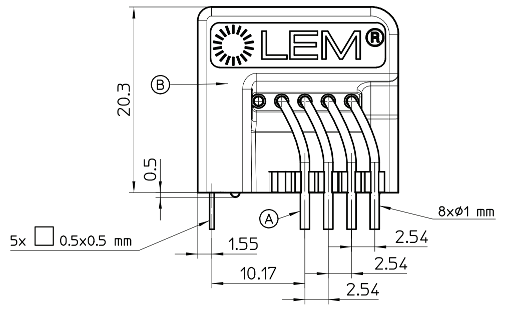
Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.
On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.
Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.
For a normal (Gaussian) distribution, this corresponds to an interval between −3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between −sigma and +sigma for a normal distribution.
Typical, maximal and minimal values are determined during the initial characterization of the product.

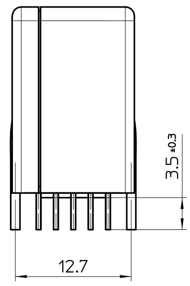
Dimensions (in mm)



Connection



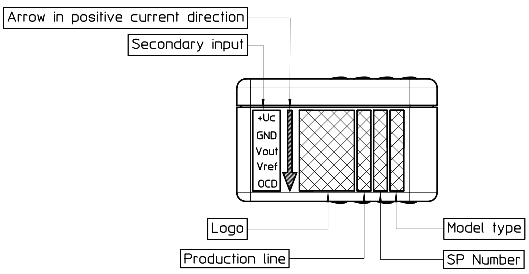




	dCl (mm)	dCp (mm)
A-B	8.26	8.26

Clearance between pads on PCB: 8.3mm

A and B correspond to internal points used for the creepage and clearance distance calculation



Packaging information

Standard delivery in cardboard: L × W × H: 315 × 200 × 120 mm
Each carboard contains 200 parts, placed into 4 Polystyrene-made trays of 50 parts each one.
Both trays and carboard are ESD-compliant.
The typical weight of the cardboard is 2.5 Kg.