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LTC2754

FEATURES

- Program or Pin-Strap Six Output Ranges OV to 5V, OV to 10V, -2.5V to 7.5V, ±2.5V, ±5V, ±10V
- Maximum 16-Bit INL Error: ±1 LSB over Temperature
- Guaranteed Monotonic over Temperature
- Low Glitch Impulse 0.26nV•s (3V), 1.25nV•s (5V)
- Serial Readback of All On-Chip Registers
- Low 1µA Maximum Supply Current
- 2.7V to 5.5V Single-Supply Operation
- 16-Bit Settling Time: 2µs
- Voltage-Controlled Offset and Gain Trims
- Clear and Power-On-Reset to 0V Regardless of Output Range
- 52-Pin 7mm × 8mm QFN Package

APPLICATIONS

- High Resolution Offset and Gain Adjustment
- Process Control and Industrial Automation
- Automatic Test Equipment
- Data Acquisition Systems

TYPICAL APPLICATION

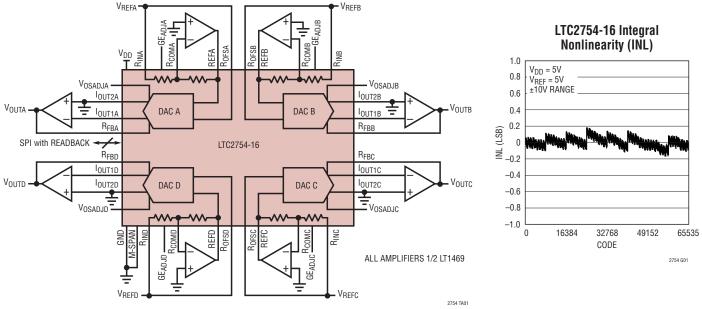
Quad 12-/16-Bit SoftSpan I_{OUT} DACs

DESCRIPTION

The LTC[®]2754 is a family of quad 12- and 16-bit multiplying serial-input, current-output digital-to-analog converters. They operate from a single 3V to 5V supply and are guaranteed monotonic over temperature. The LTC2754A-16 provides full 16-bit performance (±1LSB INL and DNL, max) over temperature without any adjustments. These SoftSpan[™] DACs offer six output ranges (up to ±10V) that can be programmed through the 3-wire SPI serial interface, or pinstrapped for operation in a single range.

The content of any on-chip register (including DAC output-range settings) can be verified in just one instruction cycle; and if you change any register, that register will be automatically read back during the next instruction cycle.

Voltage-controlled offset and gain adjustments are also provided; and the power-on reset circuit and $\overline{\text{CLR}}$ pin both reset the DAC outputs to 0V regardless of output range.





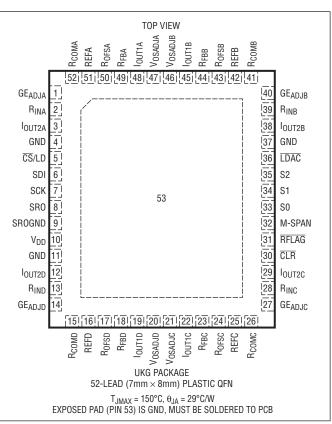
Quad 16-Bit V_{OUT} DAC with Software-Selectable Ranges

ABSOLUTE MAXIMUM RATINGS

(Notes 1, 2)

I _{OUT1X} , I _{OUT2X} to GND±0.3V
R _{INX} , R _{COMX} , REFX, R _{FBX} , R _{OFSX} , V _{OSADJX} ,
GE _{ADJX} to GND±18V
V _{DD} to GND0.3V to 7V
Digital Inputs and
Outputs to GND $-0.3V$ to $V_{DD}+0.3V$ (max 7V)
Operating Temperature Range
LTC2754C
LTC2754I–40°C to 85°C
Maximum Junction Temperature150°C
Storage Temperature Range65°C to 150°C

PIN CONFIGURATION



ORDER INFORMATION

LEAD FREE FINISH	TAPE AND REEL	PART MARKING*	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTC2754CUKG-12#PBF	LTC2754CUKG-12#TRPBF	LTC2754UKG-12	52-Lead (7mm × 8mm) Plastic QFN	0°C to 70°C
LTC2754IUKG-12#PBF	LTC2754IUKG-12#TRPBF	LTC2754UKG-12	52-Lead (7mm × 8mm) Plastic QFN	-40°C to 85°C
LTC2754BCUKG-16#PBF	LTC2754BCUKG-16#TRPBF	LTC2754UKG-16	52-Lead (7mm × 8mm) Plastic QFN	0°C to 70°C
LTC2754BIUKG-16#PBF	LTC2754BIUKG-16#TRPBF	LTC2754UKG-16	52-Lead (7mm × 8mm) Plastic QFN	-40°C to 85°C
LTC2754ACUKG-16#PBF	LTC2754ACUKG-16#TRPBF	LTC2754UKG-16	52-Lead (7mm × 8mm) Plastic QFN	0°C to 70°C
LTC2754AIUKG-16#PBF	LTC2754AIUKG-16#TRPBF	LTC2754UKG-16	52-Lead (7mm × 8mm) Plastic QFN	-40°C to 85°C

Consult LTC Marketing for parts specified with wider operating temperature ranges. *The temperature grade is identified by a label on the shipping container. Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/

For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/



ELECTRICAL CHARACTERISTICS $V_{DD} = 5V$, $V_{REF} = 5V$ unless otherwise specified. The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$.

					LTC2754	-12	LI	C2754B-	16	LT	C2754A-	16	
SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	MIN	ТҮР	MAX	MIN	TYP	MAX	UNITS
Static Per	formance												
	Resolution			12			16			16			Bits
	Monotonicity		•	12			16			16			Bits
DNL	Differential Nonlinearity		•			±1			±1		±0.2	±1	LSB
INL	Integral Nonlinearity		•			±1			±2		±0.4	±1	LSB
GE	Gain Error	All Output Ranges	•		±0.5	±2			±20		±2	±12	LSB
	Gain Error Temp- erature Coefficient	∆Gain/∆Temp			±1			±1			±1		ppm/°C
BZE	Bipolar Zero Error	All Bipolar Ranges	•		±0.2	±1			±12		±1	±8	LSB
	Bipolar Zero Temp- erature Coefficient				±0.5			±0.5			±0.5		ppm/°C
PSR	Power Supply Rejection	V _{DD} = 5V, ±10% V _{DD} = 3V, ±10%	•			±0.025 ±0.06			±0.4 ±1		±0.03 ±0.1	±0.2 ±0.5	LSB/V LSB/V
I _{LKG}	I _{OUT1} Leakage Current	T _A = 25°C T _{MIN} to T _{MAX}	•		±0.05	±2 ±5		±0.05	±2 ±5		±0.05	±2 ±5	nA nA

V_{DD} = 5V, V_{REF} = 5V unless otherwise specified. The \bullet denotes specifications that apply over the full operating temperature range, otherwise specifications are at T_A = 25°C.

SYMBOL	PARAMETER	CONDITIONS				MAX	UNITS
Analog Pins	I	-					·
	Reference Inverting Resistors	(Note 4)		16	20		kΩ
R _{REF}	DAC Input Resistance		٠	8	10		kΩ
R _{FB}	Feedback Resistors	(Note 3)	٠	8	10		kΩ
R _{OFS}	Bipolar Offset Resistors	(Note 3)	٠	16	20		kΩ
R _{VOSADJ}	Offset Adjust Resistors		٠	1024	1280		kΩ
R _{GEADJ}	Gain Adjust Resistors		•	2048	2560		kΩ
C _{IOUT1}	Output Capacitance	Full-Scale Zero-Scale			75 45		pF
Dynamic Perfo	ormance	· ·					<u> </u>
	Output Settling Time	0V to 10V Range, 10V Step. To ±0.0015% FS (Note 5)			2		μs
	Glitch Impulse	V _{DD} = 5V (Note 6) V _{DD} = 3V (Note 6)			1.25 0.26		nV∙s nV•s
	Digital-to-Analog Glitch Impulse	(Note 7)			2		nV∙s
	Reference Multiplying BW	0V to 5V Range, V _{REF} = 3V _{RMS} , Code = Full Scale, –3dB BW			2		MHz
	Multiplying Feedthrough Error	0V to 5V Range, V _{REF} = ±10V, 10kHz Sine Wave			0.5		mV
	Analog Crosstalk	(Note 8)			-109		dB
THD	Total Harmonic Distortion	(Note 9) Multiplying			-110		dB
	Output Noise Voltage Density	(Note 10) at I _{OUT1}			13		nV/√Hz



ELECTRICAL CHARACTERISTICS $V_{DD} = 5V$, $V_{REF} = 5V$ unless otherwise specified. The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$.

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
Power Supply	<u> </u>						
V _{DD}	Supply Voltage		•	2.7		5.5	V
I _{DD}	Supply Current, V _{DD}	Digital Inputs = 0V or V _{DD}	•		0.5	1	μA
Digital Inputs		·					
V _{IH}	Digital Input High Voltage	$\begin{array}{l} 3.3V \leq V_{DD} \leq 5.5V \\ 2.7V \leq V_{DD} < 3.3V \end{array}$	•	2.4 2			V V
V _{IL}	Digital Input Low Voltage	$\begin{array}{l} 4.5V < V_{DD} \leq 5.5V \\ 2.7V \leq V_{DD} \leq 4.5V \end{array}$	•			0.8 0.6	V V
	Hysteresis Voltage				0.1		V
I _{IN}	Digital Input Current	$V_{IN} = GND$ to V_{DD}	•			±1	μA
CIN	Digital Input Capacitance	V _{IN} = 0V (Note 11)	•			6	pF
Digital Outputs	S	·					
V _{OH}	I _{OH} = 200μA	$2.7V \le V_{DD} \le 5.5V$	•	V _{DD} - 0.4			V
V _{OL}	I _{OL} = 200μA	$2.7V \le V_{DD} \le 5.5V$	•			0.4	V

TIMING CHARACTERISTICS The • denotes specifications that apply over the full operating temperature range,

otherwise specifications are at $T_A = 25^{\circ}C$.

SYMBOL	PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS	
$V_{DD} = 4.5V$	to 5.5V						
t ₁	SDI Valid to SCK Set-Up			7			ns
t ₂	SDI Valid to SCK Hold		•	7			ns
t ₃	SCK High Time		•	11			ns
t ₄	SCK Low Time		•	11			ns
t ₅	CS/LD Pulse Width			9			ns
t ₆	LSB SCK High to CS/LD High		•	4			ns
t ₇	CS/LD Low to SCK Positive Edge			4			ns
t ₈	CS/LD High to SCK Positive Edge			4			ns
tg	SRO Propagation Delay	C _{LOAD} = 10pF				18	ns
t ₁₀	CLR Pulse Width Low			36			ns
t ₁₁	LDAC Pulse Width Low			15			ns
t ₁₂	CLR Low to RFLAG Low	C _{LOAD} = 10pF (Note 11)				50	ns
t ₁₃	CS/LD High to RFLAG High	C _{LOAD} = 10pF (Note 11)				40	ns
	SCK Frequency	50% Duty Cycle (Note 12)				40	MHz
$V_{DD} = 2.7V$	to 3.3V						
t ₁	SDI Valid to SCK Set-Up			9			ns
t ₂	SDI Valid to SCK Hold	(Note 11)	•	9			ns
t ₃	SCK High Time	C _L = 10pF	•	15			ns
t ₄	SCK Low Time			15			ns
t ₅	CS/LD Pulse Width			12			ns
t ₆	LSB SCK High to CS/LD High			5			ns



TIMING CHARACTERISTICS

otherwise specifications are at $T_A = 25^{\circ}C$.

The ullet denotes specifications that apply over the full operating temperature range,

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
t ₇	CS/LD Low to SCK Positive Edge		•	5			ns
t ₈	CS/LD High to SCK Positive Edge		•	5			ns
tg	SRO Propagation Delay	C _{LOAD} = 10pF	•			26	ns
t ₁₀	CLR Pulse Width Low		•	60			ns
t ₁₁	LDAC Pulse Width Low		•	20			ns
t ₁₂	CLR Low to RFLAG Low	C _{LOAD} = 10pF (Note 11)	•			70	ns
t ₁₃	CS/LD High to RFLAG high	C _{LOAD} = 10pF (Note 11)	•			60	ns
	SCK Frequency	50% Duty Cycle (Note 12)	•			25	MHz

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: Continuous operation above the specified maximum operating junction temperature may impair device reliability.

Note 3: Because of the proprietary SoftSpan switching architecture, the measured resistance looking into each of the specified pins is constant for all output ranges if the I_{OUT1X} and I_{OUT2X} pins are held at ground.

Note 4: Input resistors measured from R_{INX} to R_{COMX} ; feedback resistors measured from R_{COMX} to REFX.

Note 5: Using LT1469 with C_{FEEDBACK} = 15pF. A \pm 0.0015% settling time of 1.7µs can be achieved by optimizing the time constant on an individual basis. See Application Note 74, <u>Component and Measurement Advances</u> <u>Ensure 16-Bit DAC Settling Time</u>.

Note 6: Measured at the major carry transition, OV to 5V range. Output amplifier: LT1469; $C_{FB} = 27 pF$.

Note 7. Full-scale transition; REF = 0V.

Note 8. Analog Crosstalk is defined as the AC voltage ratio V_{OUTB}/V_{REFA} , expressed in dB. REFB is grounded, and DAC B is set to 0V-5V span and zero-, mid- or full- scale code. V_{REFA} is a $3V_{RMS}$, 1kHz sine wave. Crosstalk between other DAC channels is similar or better.

Note 9. REF = $6V_{RMS}$ at 1kHz. 0V to 5V range. DAC code = FS. Output amplifier = LT1469.

Note 10. Calculation from V_n = $\sqrt{4kTRB}$, where k = 1.38E-23 J/°K (Boltzmann constant), R = resistance (Ω), T = temperature (°K), and B = bandwidth (Hz). OV to 5V Range; zero-, mid-, or full- scale.

Note 11. Guaranteed by design, not subject to test.

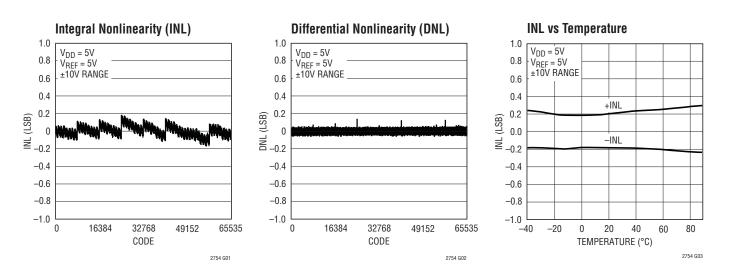
Note 12. When using SRO, maximum SCK frequency f_{MAX} is limited by SRO propagation delay t_9 as follows:

 $f_{MAX} = \left(\frac{1}{2(t_9 + t_S)}\right), \text{ where } t_S \text{ is the setup time of the receiving device.}$

 $T_{\Delta} = 25^{\circ}C$, unless otherwise noted.

TYPICAL PERFORMANCE CHARACTERISTICS

LTC2754-16

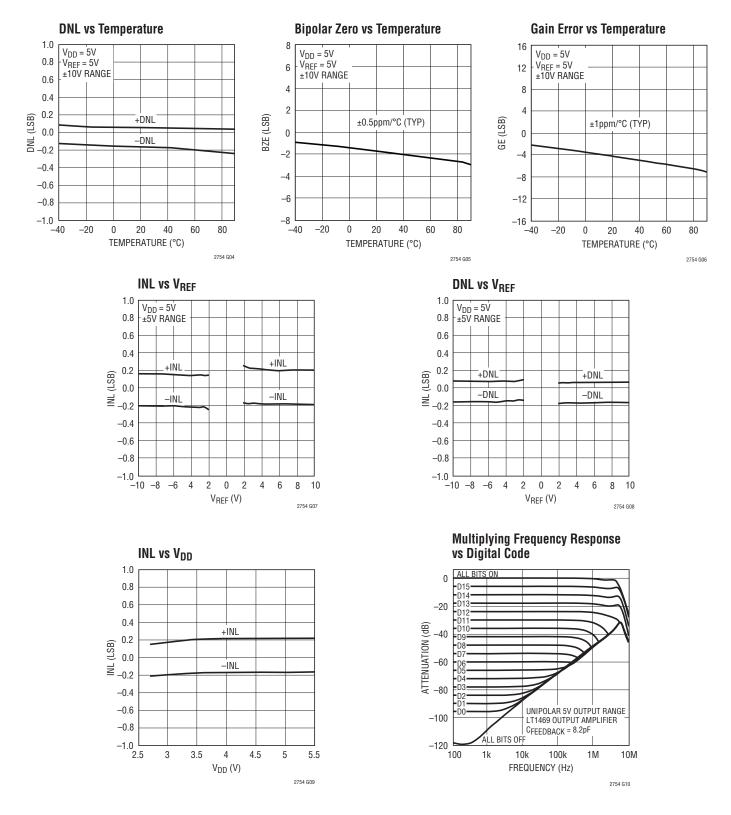




2754

TYPICAL PERFORMANCE CHARACTERISTICS T_A = 25°C, unless otherwise noted.

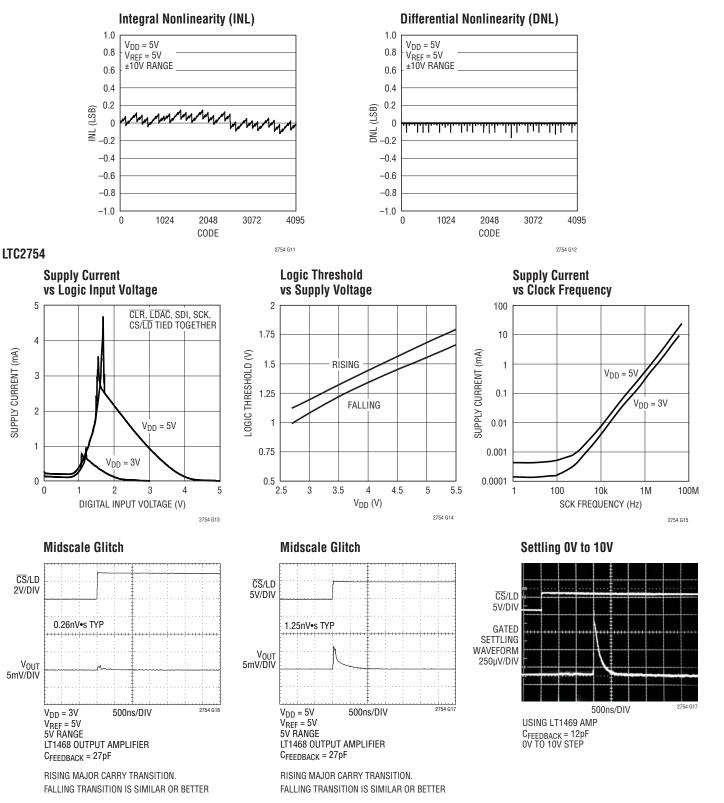
LTC2754-16





TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25$ °C, unless otherwise noted.

LTC2754-12



TECHNOLOGY

GE_{ADJA} (Pin1): Gain Adjust Pin for DAC A. This control pin can be used to null gain error or to compensate for reference errors. Nominal adjustment range is ± 512 LSB (LTC2754-16) for a voltage input range of $\pm V_{RINA}$ (i.e., $\pm 5V$ for a 5V reference input). Tie to ground if not used.

R_{INA} (Pin 2): Input Resistor for Reference Inverting Amplifier. The 20k input resistor is connected internally from R_{INA} to R_{COMA}. For normal operation tie R_{INA} to the external reference voltage V_{REFA} (see Typical Applications). Any or all of these precision-matched resistor sets (Each set comprising R_{INX}, R_{COMX} and REFX) may be used to invert one or more positive reference voltages to the negative voltages needed by the DACs. Typically 5V; accepts up to ±15V.

I_{OUT2A} (**Pin 3**): DAC A Current Output Complement. Tie I_{OUT2A} to ground.

GND (Pin 4): Ground; provides shielding for I_{OUT2A} . Tie to ground.

CS/LD (Pin 5): Synchronous Chip Select and Load Pin.

SDI (Pin 6): Serial Data Input. Data is clocked in on the rising edge of the serial clock (SCK) when CS/LD is low.

SCK (Pin 7): Serial Clock.

SRO (Pin 8): Serial Readback Output. Data is clocked out on the falling edge of SCK. Readback data begins clocking out after the last address bit A0 is clocked in. SRO is an active output only when the chip is selected (i.e., when \overline{CS}/LD is low). Otherwise SRO presents a high-impedance output in order to allow other parts to control the bus.

SROGND (Pin 9): Ground pin for SRO. Tie to ground.

 V_{DD} (Pin 10): Positive Supply Input; 2.7V \leq V_{DD} \leq 5.5V. Bypass with a 0.1µF low-ESR ceramic capacitor to ground.

GND (Pin 11): Ground. Tie to ground.

I_{OUT2D} (**Pin 12**): DAC D Current Output Complement. Tie I_{OUT2D} to ground.

 R_{IND} (Pin 13): Input Resistor for Reference Inverting Amplifier. The 20k input resistor is connected internally from R_{IND} to $R_{COMD}.$ For normal operation tie R_{IND} to the external reference voltage V_{REFD} (see Typical

Applications). Any or all of these precision-matched resistor sets (Each set comprising R_{INX} , R_{COMX} and REFX) may be used to invert one or more positive reference voltages to the negative voltages needed by the DACs. Typically 5V; accepts up to ±15V.

 GE_{ADJD} (Pin 14): Gain Adjust Pin for DAC D. This control pin can be used to null gain error or to compensate for reference errors. Nominal adjustment range is ±512 LSB (LTC2754-16) for a voltage input range of ±V_{RIND} (i.e., ±5V for a 5V reference input). Tie to ground if not used.

R_{COMD} (Pin 15): Center Tap Point for Reference Amplifier Inverting Resistors. The 20k reference inverting resistors are connected internally from R_{IND} to R_{COMD} and from R_{COMD} to REFD, respectively (see Block Diagram). For normal operation tie R_{COMD} to the negative input of external reference inverting amplifier (see Typical Applications).

REFD (Pin 16): Inverted Reference Voltage for DAC D, with internal connection to the reference inverting resistor. The 20k resistor is connected internally from REFD to R_{COMD} . For normal operation tie this pin to the output of reference inverting amplifier (see Typical Applications). Typically–5V; accepts up to ±15V. The impedance looking into this pin is 10k to ground (R_{IND} and R_{COMD} floating).

 R_{OFSD} (Pin 17): Bipolar Offset Network for DAC D. This pin provides the translation of the output voltage range for bipolar spans. Accepts up to ±15V; for normal operation tie to the positive reference voltage at R_{IND} (Pin 13). The impedance looking into this pin is 20k to ground.

 $\mathbf{R_{FBD}}$ (Pin 18): DAC D Feedback Resistor. For normal operation tie to the output of the I/V converter amplifier for DAC D (see Typical Applications). The DAC output current from I_{OUT1D} flows through the feedback resistor to the R_{FBD} pin. The impedance looking into this pin is 10k to ground.

I_{OUT1D} (Pin 19): DAC D Current Output. This pin is a virtual ground when the DAC is operating and should reside at OV. For normal operation tie to the negative input of the I/V converter amplifier for DAC D (see Typical Applications).



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V_{OSADJD} (**Pin 20**): DAC D Offset Adjust Pin. This control pin can be used to null unipolar offset or bipolar zero error. The offset voltage delta is inverted and attenuated such that a 5V control voltage applied to V_{OSADJD} produces $\Delta V_{OS} =$ -512 LSB (LTC2754-16) in any output range (assumes a 5V reference voltage at R_{IND}). Tie to ground if not used.

V_{OSADJC} (**Pin 21**): DAC C Offset Adjust Pin. This control pin can be used to null unipolar offset or bipolar zero error. The offset voltage delta is inverted and attenuated such that a 5V control voltage applied to V_{OSADJC} produces $\Delta V_{OS} =$ -512 LSB (LTC2754-16) in any output range (assumes a 5V reference voltage at R_{INC}). Tie to ground if not used.

I_{OUT1C} (**Pin 22**): DAC C Current Output. This pin is a virtual ground when the DAC is operating and should reside at OV. For normal operation tie to the negative input of the I/V converter amplifier for DAC C (see Typical Applications).

R_{FBC} (**Pin 23**): DAC C Feedback Resistor. For normal operation tie to the output of the I/V converter amplifier for DAC C (see Typical Applications). The DAC output current from I_{OUT1D} flows through the feedback resistor to the R_{FBC} pin. The impedance looking into this pin is 10k to ground.

R_{OFSC} (Pin 24): Bipolar Offset Network for DAC C. This pin provides the translation of the output voltage range for bipolar spans. Accepts up to $\pm 15V$; for normal operation tie to the positive reference voltage at R_{INC} (Pin 28). The impedance looking into this pin is 20k to ground.

REFC (Pin 25): Inverted Reference Voltage for DAC C, with internal connection to the reference inverting resistor. The 20k resistor is connected internally from REFC to R_{COMC} . For normal operation tie this pin to the output of reference inverting amplifier (see Typical Applications). Typically–5V; accepts up to ±15V. The impedance looking into this pin is 10k to ground (R_{INC} and R_{COMC} floating).

R_{COMC} (**Pin 26**): Center Tap Point for Reference Amplifier Inverting Resistors. The 20k reference inverting resistors are connected internally from R_{INC} to R_{COMC} and from R_{COMC} to REFC, respectively (see Block Diagram). For normal operation tie R_{COMC} to the negative input of external reference inverting amplifier (see Typical Applications). **GE_{ADJC} (Pin 27):** Gain Adjust Pin for DAC C. This control pin can be used to null gain error or to compensate for reference errors. Nominal adjustment range is ± 512 LSB (LTC2754-16) for a voltage input range of $\pm V_{RINC}$ (i.e., $\pm 5V$ for a 5V reference input). Tie to ground if not used.

R_{INC} (**Pin 28**): Input Resistor for Reference Inverting Amplifier. The 20k input resistor is connected internally from R_{INC} to R_{COMC}. For normal operation tie R_{INC} to the external reference voltage V_{REFC} (see Typical Applications). Any or all of these precision-matched resistor sets (Each set comprising R_{INX}, R_{COMX} and R_{EFX}) may be used to invert one or more positive reference voltages to the negative voltages needed by the DACs. Typically 5V; accepts up to ±15V.

I_{OUT2C} (**Pin 29**): DAC C Current Output Complement. Tie I_{OUT2C} to ground.

CLR (Pin 30): Asynchronous Clear Pin. When this pin is low, all DAC registers (both code and span) are cleared to zero. All DAC outputs are cleared to zero volts.

RFLAG (Pin 31): Reset Flag Pin. An active low output is asserted when there is a power-on reset or a clear event. Returns high when an Update command is executed.

M-SPAN (Pin 32): Manual Span Control Pin. M-SPAN is used in conjunction with pins S2, S1 and S0 (Pins 33, 34 and 35) to configure all DACs for operation in a single, fixed output range.

To configure the part for manual-span use, tie M-SPAN directly to V_{DD} . The active output range is then set via hardware pin strapping of pins S2, S1 and S0 (rather than through the SPI port); and Write and Update commands have no effect on the active output span.

To configure the part for SoftSpan use, tie M-SPAN directly to GND. The output ranges are then individually and dynamically controllable through the SPI port; and pins S2, S1 and S0 have no effect.

See 'Manual Span Configuration' in the Operation section. M-SPAN must be connected either directly to GND (SoftSpan configuration) or to V_{DD} (manual-span configuration).



S0 (Pin 33): Span Bit 0. In Manual Span mode (M-SPAN tied to V_{DD}), Pins S0, S1 and S2 are pin-strapped to select a single fixed output range for all DACs. These pins should be tied to either GND or V_{DD} even if they are unused.

S1 (Pin 34): Span Bit 1. In Manual Span mode (M-SPAN tied to V_{DD}), Pins SO, S1 and S2 are pin-strapped to select a single fixed output range for all DACs. These pins should be tied to either GND or V_{DD} even if they are unused.

S2 (Pin 35): Span Bit 2. In Manual Span mode (M-SPAN tied to V_{DD}), Pins SO, S1 and S2 are pin-strapped to select a single fixed output range for all DACs. These pins should be tied to either GND or V_{DD} even if they are unused.

LDAC (Pin 36): Asynchronous DAC Load Input. When LDAC is a logic low, all DACs are updated (\overline{CS} /LD must be high).

GND (Pin 37): Ground; provides shielding for I_{OUT2B}. Tie to ground.

I_{OUT2B} (**Pin 38**): DAC B Current Output Complement. Tie I_{OUT2B} to ground.

R_{INB} (Pin 39): Input Resistor for Reference Inverting Amplifier. The 20k input resistor is connected internally from R_{INB} to R_{COMB}. For normal operation tie R_{INB} to the external reference voltage V_{REFB} (see Typical Applications). Any or all of these precision-matched resistor sets (Each set comprising R_{INX}, R_{COMX} and REFX) may be used to invert one or more positive reference voltages to the negative voltages needed by the DACs. Typically 5V; accepts up to ±15V.

 GE_{ADJB} (Pin 40): Gain Adjust Pin for DAC B. This control pin can be used to null gain error or to compensate for reference errors. Nominal adjustment range is ±512 LSB (LTC2754-16) for a voltage input range of ±V_{RINB} (i.e., ±5V for a 5V reference input). Tie to ground if not used.

 R_{COMB} (Pin 41): Center Tap Point for Reference Amplifier Inverting Resistors. The 20k reference inverting resistors are connected internally from R_{INB} to R_{COMB} and from R_{COMB} to REFB, respectively (see Block Diagram). For normal operation tie R_{COMB} to the negative input of external reference inverting amplifier (see Typical Applications).

REFB (Pin 42): Inverted Reference Voltage for DAC B, with internal connection to the reference inverting resistor. The

20k resistor is connected internally from REFB to R_{COMB} . For normal operation tie this pin to the output of reference inverting amplifier (see Typical Applications). Typically–5V; accepts up to ±15V. The impedance looking into this pin is 10k to ground (R_{INB} and R_{COMB} floating).

 R_{OFSB} (Pin 43): Bipolar Offset Network for DAC B. This pin provides the translation of the output voltage range for bipolar spans. Accepts up to ±15V; for normal operation tie to the positive reference voltage at R_{INB} (Pin 39). The impedance looking into this pin is 20k to ground.

 \mathbf{R}_{FBB} (Pin 44): DAC B Feedback Resistor. For normal operation tie to the output of the I/V converter amplifier for DAC B (see Typical Applications). The DAC output current from I_{OUT1B} flows through the feedback resistor to the R_{FBB} pin. The impedance looking into this pin is 10k to ground.

I_{OUT1B} (**Pin 45**): DAC B Current Output. This pin is a virtual ground when the DAC is operating and should reside at OV. For normal operation tie to the negative input of the I/V converter amplifier for DAC B (see Typical Applications).

V_{OSADJB} (Pin 46): DAC B Offset Adjust Pin. This control pin can be used to null unipolar offset or bipolar zero error. The offset-voltage delta is inverted and attenuated such that a 5V control voltage applied to V_{OSADJB} produces $\Delta V_{OS} =$ -512 LSB (LTC2754-16) in any output range (assumes a 5V reference voltage at R_{INB}). Tie to ground if not used.

V_{OSADJA} (Pin 47): DAC A Offset Adjust Pin. This control pin can be used to null unipolar offset or bipolar zero error. The offset-voltage delta is inverted and attenuated such that a 5V control voltage applied to V_{OSADJA} produces $\Delta V_{OS} =$ -512 LSB (LTC2754-16) in any output range (assumes a 5V reference voltage at R_{INA}). Tie to ground if not used.

I_{OUT1A} (**Pin 48**): DAC A Current Output. This pin is a virtual ground when the DAC is operating and should reside at OV. For normal operation tie to the negative input of the I/V converter amplifier for DAC A (see Typical Applications).

 \mathbf{R}_{FBA} (Pin 49): DAC A Feedback Resistor. For normal operation tie to the output of the I/V converter amplifier for DAC A (see Typical Applications). The DAC output current from I_{OUT1A} flows through the feedback resistor to the R_{FBA} pin. The impedance looking into this pin is 10k to ground.



BLOCK DIAGRAM

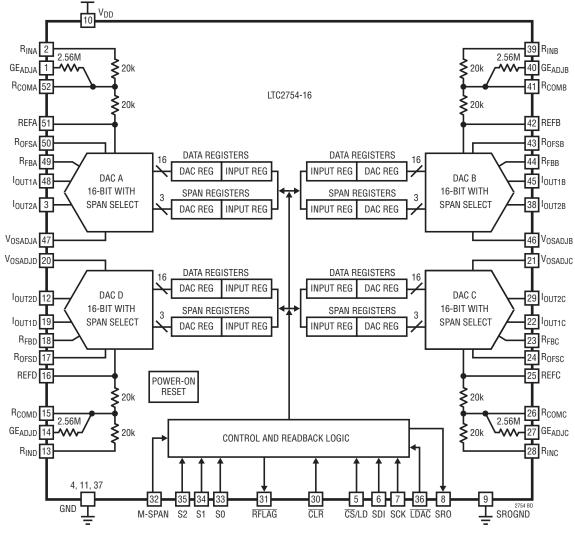
ROFSA (Pin 50): Bipolar Offset Network for DAC A. This pin provides the translation of the output voltage range for bipolar spans. Accepts up to ±15V; for normal operation tie to the positive reference voltage at $\mathsf{R}_{\mathsf{INA}}$ (Pin 2). The impedance looking into this pin is 20k to ground.

REFA (Pin 51): Inverted Reference Voltage for DAC A, with internal connection to the reference inverting resistor. The 20k resistor is connected internally from REFA to R_{COMA}. For normal operation tie this pin to the output of reference inverting amplifier (see Typical Applications). Typically – 5V; accepts up to ±15V. The impedance looking into this pin is 10k to ground (R_{INA} and R_{COMA} floating).

R_{COMA} (Pin 52): Center Tap Point for Reference Amplifier Inverting Resistors. The 20k reference inverting resistors are connected internally from R_{INA} to R_{COMA} and from R_{COMA} to REFA, respectively (see Block Diagram). For normal operation tie R_{COMA} to the negative input of external reference inverting amplifier (see Typical Applications).

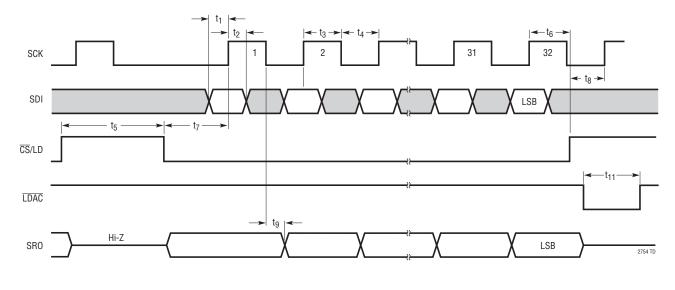
Exposed Pad (Pin 53): Ground. The Exposed Pad must be soldered to the PCB.

V_{DD} R_{INA} 2 2.56M GEADJA **🗲** 20k 1 ᠕᠕᠕ R_{COMA} 20k





TIMING DIAGRAMS



OPERATION

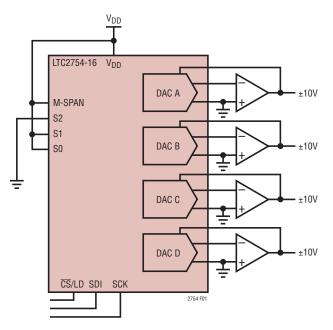
Output Ranges

The LTC2754 is a quad, current-output, serial-input precision multiplying DAC with selectable output ranges. Ranges can either be programmed in software for maximum flexibility—each of the four DACs can be programmed to any one of six output ranges—or hardwired through pin-strapping. Two unipolar ranges are available (OV to 5V and OV to 10V), and four bipolar ranges ($\pm 2.5V, \pm 5V, \pm 10V$ and -2.5V to 7.5V). These ranges are obtained when an external precision 5V reference is used. When a reference voltage of 2V is used, the ranges become: OV to 2V, OV to 4V, $\pm 1V, \pm 2V, \pm 4V$ and -1V to 3V. The output ranges are linearly scaled for other reference voltages.

Manual Span Configuration

Multiple output ranges are not needed in some applications. To configure the LTC2754 to operate in a single span without additional operational overhead, tie the M-SPAN pin directly to V_{DD} . The active output range for all four DACs is then set via hardware pin strapping of pins S2, S1 and S0 (rather than through the SPI port); and Write and Update commands have no effect on the active output span. See Figure 1 and Table 3.

Tie the M-SPAN pin to ground for normal SoftSpan operation.







Input and DAC Registers

The LTC2754 has 5 internal registers for each DAC, a total of 20 registers (see Block Diagram). Each DAC channel has two sets of double-buffered registers—one set for the code data, and one for the output range of the DAC—plus one readback register. Double buffering provides the capability to simultaneously update the span (output range) and code, which allows smooth voltage transitions when changing output ranges. It also permits the simultaneous updating of multiple DACs.

Each set of double-buffered registers comprises an Input register and a DAC register.

Input register: The Write operation shifts data from the SDI pin into a chosen Input register. The Input registers are holding buffers; Write operations do not affect the DAC outputs.

DAC register: The Update operation copies the contents of an Input register to its associated DAC register. The contents of a DAC register directly updates the associated DAC output voltage or output range.

Note that updates always include both Data and Span registers; but the values held in the DAC registers will only change if the associated Input register values have previously been changed via a Write operation.

Serial Interface

When the $\overline{\text{CS}}/\text{LD}$ pin is taken low, the data on the SDI pin is loaded into the shift register on the rising edge of the clock (SCK pin). The minimum (24-bit wide) loading sequence required for the LTC2754 is a 4-bit command word (C3 C2 C1 C0), followed by a 4-bit address word (A3 A2 A1 A0) and 16 data (span or code) bits, MSB first. Figure 2 shows the SDI input word syntax to use when writing code or span. If a 32-bit input sequence is used, the first eight bits must be zeros, followed by the same sequence as for a 24-bit wide input. Figure 3 shows the input and readback sequences for both 24-bit and 32-bit operations.

When $\overline{\text{CS}}/\text{LD}$ is low, the SRO pin (Serial Readback Output) is an active output. The readback data begins after the command (C3-C0) and address (A3-A0) words have been shifted into SDI. SRO outputs a logic low until the readback

data begins. For a 24-bit input sequence, the 16 readback bits are shifted out on the falling edges of clocks 8-23, suitable for shifting into a microprocessor on the rising edges of clocks 9-24. For a 32-bit sequence, the bits are shifted out on clocks 16-31; see Figure 3b.

When \overline{CS}/LD is high, the SRO pin presents a high impedance (three-state) output.

 $\overline{\text{LDAC}}$ is an asynchronous update pin. When $\overline{\text{LDAC}}$ is taken low, all DACs are updated with code and span data (data in the Input buffers is copied into the DAC buffers). $\overline{\text{CS}/\text{LD}}$ must be high during this operation; otherwise $\overline{\text{LDAC}}$ is locked out and will have no effect. The use of $\overline{\text{LDAC}}$ is functionally identical to the "Update All DACs" serial input command.

The codes for the command word (C3-C0) are defined in Table 1; Table 2 defines the codes for the address word (A3-A0).

Readback

In addition to the Input and DAC registers, each DAC has one Readback register associated with it. When a Read command is issued to a DAC, the contents of one of its four buffers (Input and DAC registers for each of Span and Code) is copied into its Readback register and serially shifted out through the SRO pin. Figure 3 shows the loading and readback sequences.

In the data field (D15-D0) of any non-read instruction cycle, SRO shifts out the contents of the buffer that was specified in the preceding command. This "rolling readback" default mode of operation can dramatically reduce the number of instruction cycles needed, since any command can be verified during succeeding commands with no additional overhead. See Figure 4. Table 1 shows the storage location ('readback pointer') of the data which will be output from SRO during the next instruction.

For Read commands, the data is shifted out during the Read instruction itself (on the 16 falling SCK edges immediately after the last address bit is shifted in on SDI). When checking the span of a DAC using SRO, the span bits are the last four bits shifted out, corresponding to their sequence and positions when writing a span. See Figure 3.



Table 1. Command Codes

	CO	DE			READBACK POINTER-	READBACK POINTER-
C3	C2	C1	CO	COMMAND	CURRENT INPUT WORD W ₀	NEXT INPUT WORD W ₊₁
0	0	1	0	Write Span DAC n	Set by Previous Command	Input Span Register DAC n
0	0	1	1	Write Code DAC n	Set by Previous Command	Input Code Register DAC n
0	1	0	0	Update DAC n	Set by Previous Command	DAC Span Register DAC n
0	1	0	1	Update All DACs	Set by Previous Command	DAC Code Register DAC A
0	1	1	0	Write Span DAC n Update DAC n	Set by Previous Command	DAC Span Register DAC n
0	1	1	1	Write Code DAC n Update DAC n	Set by Previous Command	DAC Code Register DAC n
1	0	0	0	Write Span DAC n Update All DACs	Set by Previous Command	DAC Span Register DAC n
1	0	0	1	Write Code DAC n Update All DACs	Set by Previous Command	DAC Code Register DAC n
1	0	1	0	Read Input Span Register DAC n	Input Span Re	gister DAC n
1	0	1	1	Read Input Code Register DAC n	Input Code Re	gister DAC n
1	1	0	0	Read DAC Span Register DAC n	DAC Span Re	gister DAC n
1	1	0	1	Read DAC Code Register DAC n	DAC Code Re	gister DAC n
1	1	1	1	No Operation	Set by Previous Command DAC Code Re	
	-	-		System Clear	_	DAC Span Register DAC A
– Initial Power-Up or Power Interupt				Initial Power-Up or Power Interupt	_	DAC Span Register DAC A

Codes not shown are reserved-do not use

Table 2. Address Codes

A3	A2	A1	AO	n
0	0	0	×	DAC A
0	0	1	×	DAC B
0	1	0	×	DAC C
0	1	1	×	DAC D
1	1	1	×	All DACs (Note 1)

Codes not shown are reserved-do not use. \times = Don't Care. **Note 1.** If readback is taken using the All DACs address, the LTC2754 defaults to DAC A.

Table 3. Span Codes

S 3	S 2	S1	SO	SPAN
×	0	0	0	Unipolar 0V to 5V
×	0	0	1	Unipolar 0V to 10V
×	0	1	0	Bipolar –5V to 5V
×	0	1	1	Bipolar –10V to 10V
×	1	0	0	Bipolar –2.5V to 2.5V
×	1	0	1	Bipolar –2.5V to 7.5V

Codes not shown are reserved-do not use. \times = Don't Care.



Readback in M-Span Configuration

If the part is in M-Span configuration and a DAC Span register is specified for readback, then the data shifted out of SRO will reflect the actual active span. The hardware-configured output range is therefore software detectable and available for use in programming.

Examples

1. Using a 24-bit instruction, load DAC A with the unipolar range of 0V to 10V, output at zero volts and all other DACs with the bipolar range of \pm 10V, outputs at zero volts. Note all DAC outputs should change at the same time.

- b) <u>CS</u>/LD↑

Input register- Range of all DACs set to bipolar ± 10 V.

- d) CS/LD[↑]
 Input register- Range of DAC A set to unipolar OV to 10V.
- f) $\overline{\text{CS}}/\text{LD}^{\uparrow}$ Input register- Code of all DACs set to midscale.
- h) $\overline{\text{CS}}/\text{LD}^{\uparrow}$ Input register- Code of DAC A set to zero code.
- i) $\overline{\text{CS}}/\text{LD}\downarrow$ Clock SDI = 0100 1111 XXXX XXXX XXXX XXXX
- j) $\overline{\text{CS}}/\text{LD}^{\uparrow}$ Update all DACs for both Code and Range.
- k) Alternatively steps i and j could be replaced with $\overline{\text{LDAC}} \supset \Gamma$.

2. Using a 32-bit load sequence, load DAC C with bipolar $\pm 2.5V$ and its output at zero volts. Use readback to check Input register contents before updating the DAC output (i.e., before copying Input register contents into DAC register).

- a) $\overline{\text{CS}}/\text{LD}\downarrow$ (Note that after power-on, the code in Input register is zero) Clock SDI = 0000 0000 0011 0100 1000 0000 0000 0000
- b) $\overline{\text{CS}}/\text{LD}^{\uparrow}$ Input register- Code of DAC C set to midscale setting.
- c) $\overline{\text{CS}/\text{LD}}\downarrow$ Clock SDI = 0000 0000 0010 0100 0000 0000 0000 0100 Data out on SRO = 1000 0000 0000 0000 Verifies that Input register- Code DAC C is at midscale setting.
- d) CS/LD↑
 Input register- Range of DAC C set to Bipolar ±2.5V range.
- e) $\overline{\text{CS}}/\text{LD}\downarrow$

Clock SDI = 0000 0000 1010 0100 xxxx xxxx xxxx xxxx Data Out on SRO = 0000 0000 0000 0100 Verifies that Input register- range of DAC C set to Bipolar $\pm 2.5V$ Range. $\overline{CS}/LD\uparrow$

- g) $\overline{\text{CS}}/\text{LD}^{\uparrow}$ Update DAC C for both Code and Range
- h) Alternatively steps f and g could be replaced with $\overline{\text{LDAC}} \, \mathbb{k}$.



System Offset and Reference Adjustments

The LTC2754 has individual offset- and gain- adjust pins (V_{OSADJX} and GE_{ADJX}, respectively) for each of its four DACs.

Many systems require compensation for overall system offset. This may be an order of magnitude or more greater than the offset of the LTC2754, which is so low as to be dominated by external output amplifier errors even when using the most precise op amps.

The offset adjust pins V_{OSADJX} can be used to null unipolar offset or bipolar zero error. The offset-voltage delta is inverted and attenuated such that a 5V control voltage applied to V_{OSADJX} produces $\Delta V_{OS} = -512$ LSB (LTC2754-16) in any output range (assumes a 5V reference voltage at R_{INX}).

In voltage terms, the offset delta is attenuated by a factor of 32, 64 or 128, depending on the output range. (These functions hold regardless of reference voltage.)

 $\Delta V_{OS} = -(1/128)V_{OSADJX}$ [OV to 5V, ±2.5V spans]

 ΔV_{OS} = –(1/64)V_{OSADJX} [OV to 10V, ±5V, –2.5V to 7.5V spans]

 $\Delta V_{OS} = -(1/32)V_{OSADJX}$ [±10V span]

The gain error adjust pins GE_{ADJX} can be used to null gain error or to compensate for reference errors. Nominal adjustment range is ±512 LSB (LTC2754-16) for a voltage input range of ±V_{RINX} (i.e., ±5V for a 5V reference input). The gain-error delta is non-inverting for positive reference voltages.

Note that these pins compensate the gain by altering the inverted reference voltage V_{REFX} . In voltage terms, the V_{REFX} delta is inverted and attenuated by a factor of 128.

$\Delta V_{\text{REFX}} = -(1/128)\text{GE}_{\text{ADJX}}$

The nominal input range of these pins is $\pm 5V$; other voltages of up to $\pm 15V$ may be used if needed. However, do not use voltages divided down from power supplies; reference-quality, low-noise inputs are required to maintain the performance of which the part is capable.

The V_{OSADJX} pins have an input impedance of 1.28M Ω . These pins should be driven with a Thevenin-equivalent impedance of 10k or less to preserve the settling performance of the LTC2754. They should be shorted to GND if not used.

The GE_{ADJX} pins have an input impedance of 2.56M Ω , and are intended for use with fixed reference voltages only. They should be shorted to GND if not used. If the reference inverting resistors are not used for that channel, then GE_{ADJX}, R_{COMX} and R_{INX} should all be shorted to REFX.

Power-On Reset and Clear

When power is first applied to the LTC2754, all DACs power-up in unipolar 5V mode (S3 S2 S1 S0 = 0000). All internal DAC registers are reset to 0 and the DAC outputs initialize to zero volts.

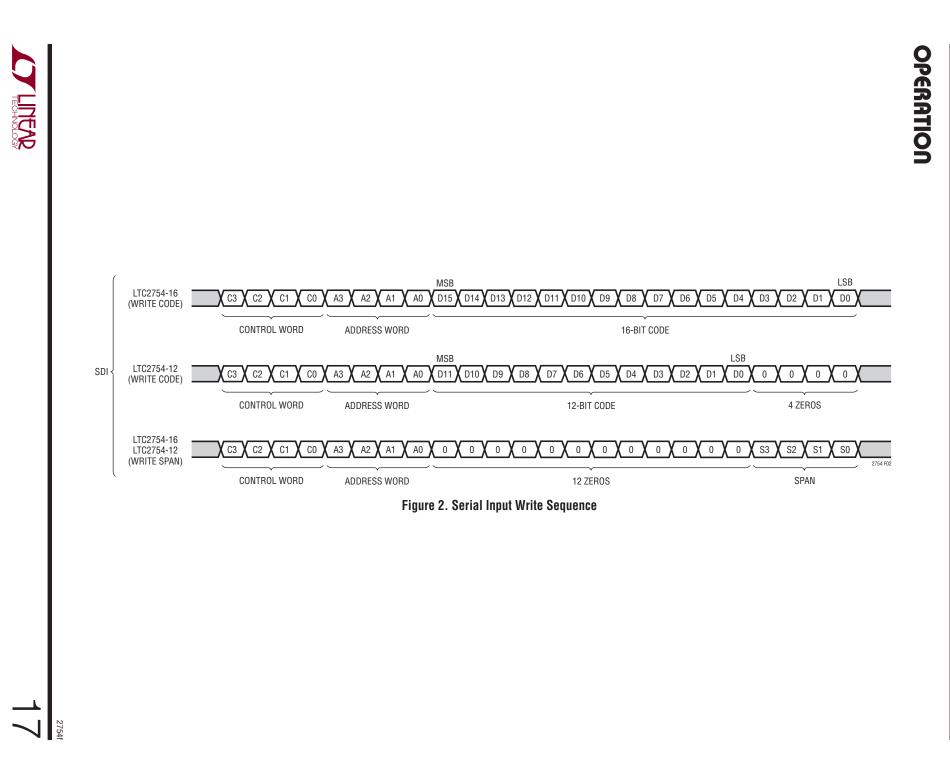
If the part is configured for manual span operation, all four DACs will be set into the pin-strapped range at the first Update command. This allows the user to simultaneously update span and code for a smooth voltage transition into the chosen output range.

When the $\overline{\text{CLR}}$ pin is taken low, a system clear results. The DAC buffers are reset to 0 and the DAC outputs are all reset to zero volts. The Input buffers are left intact, so that any subsequent Update command (including the use of $\overline{\text{LDAC}}$) restores the addressed DACs to their respective previous states.

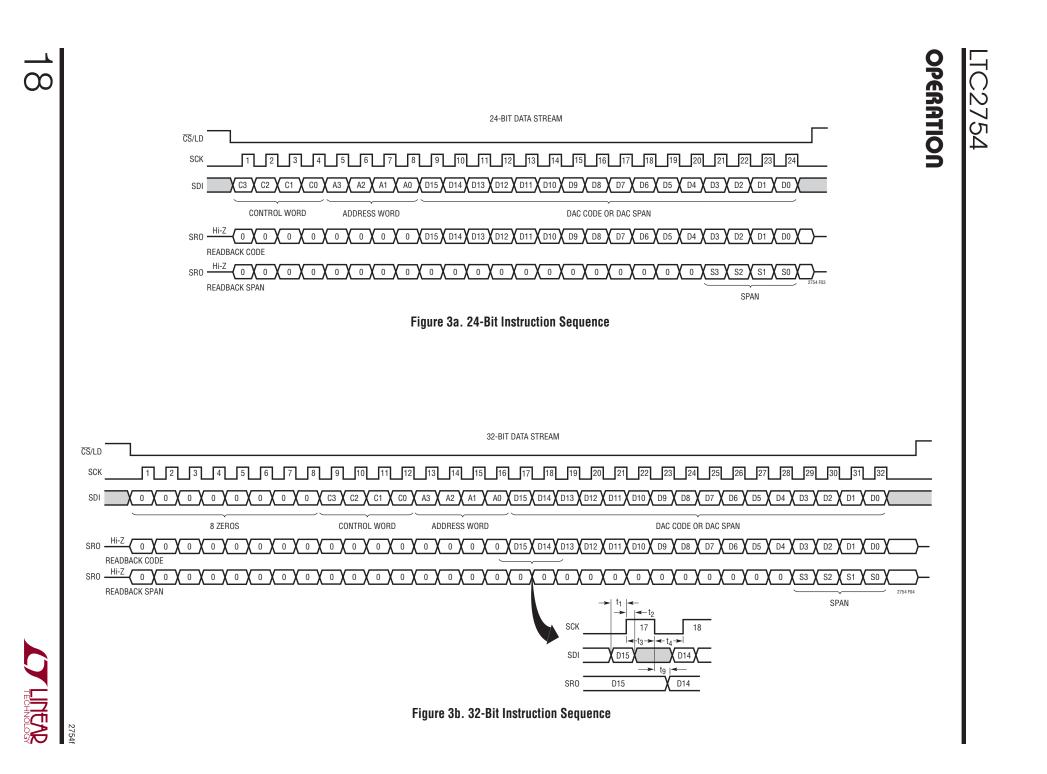
If $\overline{\text{CLR}}$ is asserted during an instruction, i.e., when $\overline{\text{CS}}/\text{LD}$ is low, the instruction is aborted. Integrity of the relevant Input buffers is not guaranteed under these conditions, therefore the contents should be checked using readback or replaced.

The $\overline{\text{RFLAG}}$ pin is used as a flag to notify the system of a loss of data integrity. The $\overline{\text{RFLAG}}$ output is asserted low at power-up, system clear, or if the supply V_{DD} dips below approximately 2V; and stays asserted until any valid Update command is executed.





LTC2754



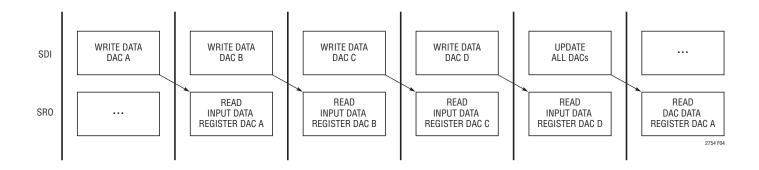


Figure 4. Rolling Readback



Op Amp Selection

Because of the extremely high accuracy of the 16-bit LTC2754-16, careful thought should be given to op amp selection in order to achieve the exceptional performance of which the part is capable. Fortunately, the sensitivity of INL and DNL to op amp offset has been greatly reduced compared to previous generations of multiplying DACs.

Tables 4 and 5 contain equations for evaluating the effects of op amp parameters on the LTC2754's accuracy when programmed in a unipolar or bipolar output range. These are the changes the op amp can cause to the INL, DNL, unipolar offset, unipolar gain error, bipolar zero and bipolar gain error. Tables 4 and 5 can also be used to determine the effects of op amp parameters on the LTC2754-12. However, the results obtained from Tables 4 and 5 are in 16-bit LSBs. Divide these results by 16 to obtain the correct LSB sizing.

Table 6 contains a partial list of LTC precision op amps recommended for use with the LTC2754. The easy-to-use design equations simplify the selection of op amps to meet

Table 4. Coefficients for the Equations in Table 5

OUTPUT RANGE	A1	A2	A3	A4	A5
5V	1.1	2	1		1
10V	2.2	3	0.5		1.5
±5V	2	2	1	1	1.5
±10V	4	4	0.83	1	2.5
±2.5V	1	1	1.4	1	1
–2.5V to 7.5V	1.9	3	0.7	0.5	1.5

Table 5. Easy-to-Use Equations Determine Op Amp Effects on DAC Accuracy in All Output Ranges (Circuit of Page 1). Subscript 1
Refers to Output Amp, Subscript 2 Refers to Reference Inverting Amp.

OP AMP	INL (LSB)	DNL (LSB)	UNIPOLAR OFFSET (LSB)	BIPOLAR ZERO ERROR (LSB)	UNIPOLAR GAIN Error (LSB)	BIPOLAR GAIN Error (LSB)
V _{OS1} (mV)	$V_{OS1} \bullet 3.2 \bullet \left(\frac{5V}{V_{REF}}\right)$	$V_{OS1} \bullet 0.82 \bullet \left(\frac{5V}{V_{REF}}\right)$	A3 • V _{OS1} • 13.2 • $\left(\frac{5V}{V_{REF}}\right)$	$A3 \bullet V_{OS1} \bullet 19.8 \bullet \left(\frac{5V}{V_{REF}}\right)$	$V_{OS1} \bullet 13.2 \bullet \left(\frac{5V}{V_{REF}}\right)$	$V_{OS1} \bullet 13.2 \bullet \left(\frac{5V}{V_{REF}}\right)$
I _{B1} (nA)	$I_{B1} \bullet 0.0003 \bullet \left(\frac{5V}{V_{REF}}\right)$	$I_{B1} \bullet 0.00008 \bullet \left(\frac{5V}{V_{REF}}\right)$	$I_{B1} \bullet 0.13 \bullet \left(\frac{5V}{V_{REF}}\right)$	$I_{B1} \bullet 0.13 \bullet \left(\frac{5V}{V_{REF}}\right)$	$I_{B1} \bullet 0.0018 \bullet \left(\frac{5V}{V_{REF}}\right)$	$I_{B1} \bullet 0.0018 \bullet \left(\frac{5V}{V_{REF}}\right)$
A _{VOL1} (V/V)	A1 • $\left(\frac{16.5k}{A_{VOL1}}\right)$	A2 • $\left(\frac{1.5k}{A_{VOL1}}\right)$	0	0	A5 • $\left(\frac{131k}{AVOL1}\right)$	A5 • $\left(\frac{131k}{AVOL1}\right)$
V _{0S2} (mV)	0	0	0	$A4 \bullet \left(V_{OS2} \bullet 13.1 \bullet \left(\frac{5V}{V_{REF}} \right) \right)$	$V_{OS2} \bullet 26.2 \bullet \left(\frac{5V}{V_{REF}}\right)$	$V_{OS2} \bullet 26.2 \bullet \left(\frac{5V}{V_{REF}}\right)$
I _{B2} (mV)	0	0	0	$A4 \bullet \left(I_{B2} \bullet 0.13 \bullet \left(\frac{5V}{V_{REF}}\right)\right)$	$I_{B2} \bullet 0.26 \bullet \left(\frac{5V}{V_{REF}}\right)$	$I_{B2} \bullet 0.26 \bullet \left(\frac{5V}{V_{REF}}\right)$
Avol2 (V/V)	0	0	0	A4 • $\left(\frac{66k}{A_{VOL2}}\right)$	$\left(\frac{131k}{A_{VOL2}}\right)$	$\left(\frac{131k}{A_{VOL2}}\right)$

	AMPLIFIER SPECIFICATIONS									
AMPLIFIER	V _{OS} µV	I _B nA	A _{VOL} V/mV	VOLTAGE Noise nV/√Hz	CURRENT NOISE p A /√Hz	SLEW RATE V/µs	GAIN BANDWIDTH Product MHz	t _{SETTLING} with LTC2755 μs	POWER DISSIPATION mW	
LT1001	25	2	800	10	0.12	0.25	0.8	120	46	
LT1097	50	0.35	1000	14	0.008	0.2	0.7	120	11	
LT1112 (Dual)	60	0.25	1500	14	0.008	0.16	0.75	115	10.5/Op Amp	
LT1124 (Dual)	70	20	4000	2.7	0.3	4.5	12.5	19	69/Op Amp	
LT1468	75	10	5000	5	0.6	22	90	2	117	
LT1469 (Dual)	125	10	2000	5	0.6	22	90	2	123/Op Amp	



the system's specified error budget. Select the amplifier from Table 6 and insert the specified op amp parameters in Table 5. Add up all the errors for each category to determine the effect the op amp has on the accuracy of the part. Arithmetic summation gives an (unlikely) worst-case effect. A root-sum-square (RMS) summation produces a more realistic estimate.

Op amp offset will contribute mostly to output offset and gain error, and has minimal effect on INL and DNL. For example, for the LTC2754-16 with a 5V reference in 5V unipolar mode, a 250μ V op amp offset will cause a 3.3LSB zero-scale error and a 3.3LSB gain error; but only 0.8LSB of INL degradation and 0.2LSB of DNL degradation.

While not directly addressed by the simple equations in Tables 4 and 5, temperature effects can be handled just as easily for unipolar and bipolar applications. First, consult an op amp's data sheet to find the worst-case V_{OS} and I_B over temperature. Then, plug these numbers into the V_{OS} and I_B equations from Table 5 and calculate the temperature-induced effects.

For applications where fast settling time is important, Application Note 74, "Component and Measurement Advances Ensure 16-Bit DAC Settling Time," offers a thorough discussion of 16-bit DAC settling time and op amp selection.

Precision Voltage Reference Considerations

Much in the same way selecting an operational amplifier for use with the LTC2754 is critical to the performance of the system, selecting a precision voltage reference also requires due diligence. The output voltage of the LTC2754 is directly affected by the voltage reference; thus, any voltage reference error will appear as a DAC output voltage error.

There are three primary error sources to consider when selecting a precision voltage reference for 16-bit applications: output voltage initial tolerance, output voltage temperature coefficient and output voltage noise.

Initial reference output voltage tolerance, if uncorrected, generates a full-scale error term. Choosing a reference with low output voltage initial tolerance, like the LT1236 $(\pm 0.05\%)$, minimizes the gain error caused by the reference; however, a calibration sequence that corrects for system zero- and full-scale error is always recommended.

A reference's output voltage temperature coefficient affects not only the full-scale error, but can also affect the circuit's apparent INL and DNL performance. If a reference is chosen with a loose output voltage temperature coefficient, then the DAC output voltage along its transfer characteristic will be very dependent on ambient conditions. Minimizing the error due to reference temperature coefficient can be achieved by choosing a precision reference with a low output voltage temperature coefficient and/or tightly controlling the ambient temperature of the circuit to minimize temperature gradients.

Table 7. Partial List of LTC Precision References Recommended	
for Use with the LTC2754 with Relevant Specifications	

REFERENCE	INITIAL Tolerance	TEMPERATURE DRIFT	0.1Hz to 10Hz NOISE
LT1019A-5, LT1019A-10	±0.05%	5ppm/°C	12μV _{P-P}
LT1236A-5, LT1236A-10	±0.05%	5ppm/°C	3μV _{P-P}
LT1460A-5, LT1460A-10	±0.075%	10ppm/°C	20µV _{P-P}
LT1790A-2.5	±0.05%	10ppm/°C	12µV _{P-P}
LTC6652A-2.048	±0.05%	5ppm/°C	2.1ppm _{P-P}
LTC6652A-2.5			2.1ppm _{P-P}
LTC6652A-3			2.1ppm _{P-P}
LTC6652A-3.3			2.2ppm _{P-P}
LTC6652A-4.096			2.3ppm _{P-P}
LTC6652A-5			2.8ppm _{P-P}



As precision DAC applications move to 16-bit and higher performance, reference output voltage noise may contribute a dominant share of the system's noise floor. This in turn can degrade system dynamic range and signal-tonoise ratio. Care should be exercised in selecting a voltage reference with as low an output noise voltage as practical for the system resolution desired. Precision voltage references, like the LT1236, produce low output noise in the 0.1Hz to 10Hz region, well below the 16-bit LSB level in 5V or 10V full-scale systems. However, as the circuit bandwidths increase, filtering the output of the reference may be required to minimize output noise.

Grounding

As with any high resolution converter, clean grounding is important. A low impedance analog ground plane and star grounding techniques should be used. I_{OUT2X} must be tied to the star ground with as low a resistance as possible.

When it is not possible to locate star ground close to I_{OUT2} , a low resistance trace should be used to route this pin to star ground. This minimizes the voltage drop from this pin to ground caused by the code-dependent current flowing to ground. When the resistance of this circuit board trace becomes greater than 1 Ω , a force/sense amplifier configuration should be used to drive this pin (see Figure 5). This preserves the excellent accuracy (1LSB INL and DNL) of the LTC2754-16.

Layout

Figures 6, 7, 8, and 9 show the layout for the LTC2754 evaluation board, DC1546. This shows how to route the digital signals around the device without interfering with the reference and output op amps. Complete demo board documentation is available in the DC1546 "Quick Start Guide."



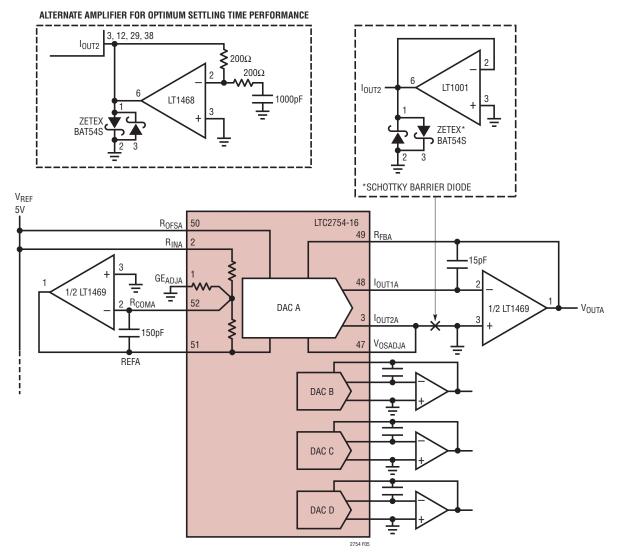


Figure 5. Optional Circuits for Driving I_{OUT2} from GND with a Force/Sense Amplifier.



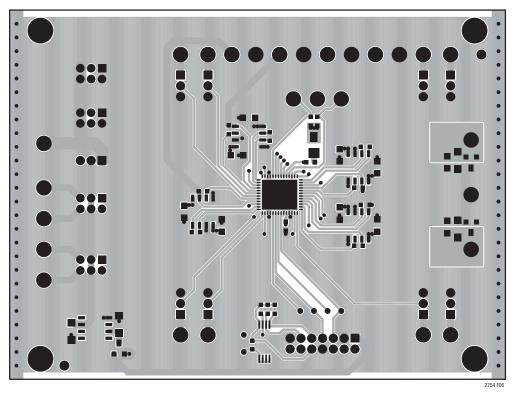


Figure 6. LTC2754 Evaluation Board DC1546. Layer 1, Top Layer (Component Side)

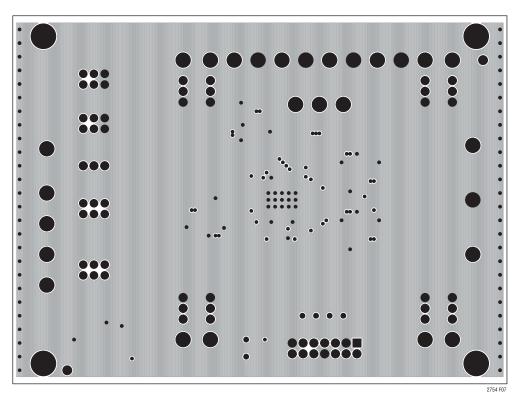


Figure 7. LTC2754 Evaluation Board DC1546. Layer 2, GND Plane



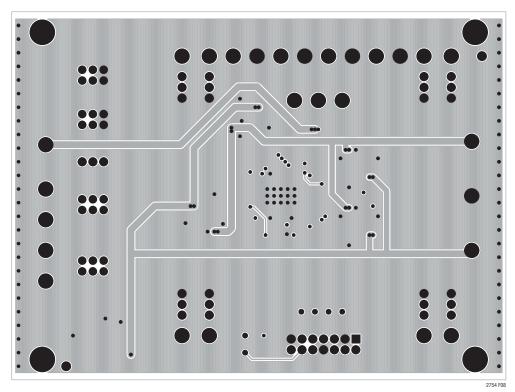


Figure 8. LTC2754 Evaluation Board DC1546. Layer 3, Power Traces

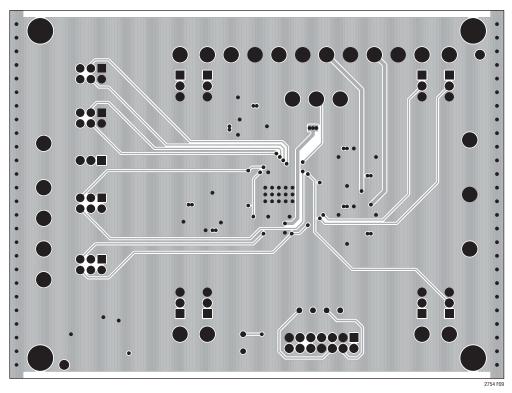


Figure 9. LTC2754 Evaluation Board DC1546. Layer 4, Bottom Layer (Solder Side)

