# mail

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## LTC2859/LTC2861

## 20Mbps RS485 Transceivers with Integrated Switchable Termination **DESCRIPTION**

The LTC<sup>®</sup>2859 and LTC2861 are low power, 20Mbps

RS485/422 transceivers operating on 5V supplies. The receiver includes a logic-selectable  $120\Omega$  termination,

one-eighth unit load supporting up to 256 nodes per bus

(C-, I-grades), and a failsafe feature that guarantees a high output state under conditions of floating or shorted inputs.

The driver features a logic-selectable low-EMI 250kbps

operating mode, and maintains a high output impedance

over the entire common mode range when disabled or

when the supply is removed. Excessive power dissipation

caused by bus contention or a fault is prevented by current

Enhanced ESD protection allows the LTC2859 and LTC2861

to withstand ±15kV (human body model) on the transceiver

DUPLEX

Half

Full

limiting all outputs and by a thermal shutdown.

**PRODUCT SELECTION GUIDE** 

interface pins without latchup or damage.

PART NUMBER

LTC2859

I TC2861

## FEATURES

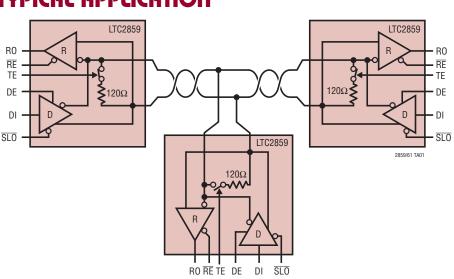
- Integrated, Logic-Selectable 120Ω Termination Resistor
- 20Mbps Max Data Rate
- No Damage or Latchup to ESD: ±15kV HBM
- High Input Impedance Supports 256 Nodes (C-, I-Grades)
- Operation Up to 105°C (LTC2859H)
- 250kbps Low-EMI Mode
- Guaranteed Failsafe Receiver Operation Over the Entire Common Mode Range
- Current Limited Drivers and Thermal Shutdown
- Delayed Micropower Shutdown (5µA Max)
- Power Up/Down Glitch-Free Driver Outputs
- Low Operating Current (900µA Max in Receive Mode)
- Meets All TIA/EIA-485-A Specifications
- Available in 10-Pin 3mm × 3mm DFN, 12-Pin 4mm × 3mm DFN and 16-Pin SSOP Packages

## **APPLICATIONS**

- Low Power RS485/RS422 Transceiver
- Level Translator
- Backplane Transceiver

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## TYPICAL APPLICATION

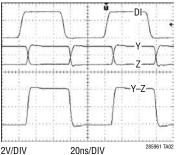


#### LTC2859 at 20Mbps

PACKAGE

DFN-10

SSOP-16. DFN-12





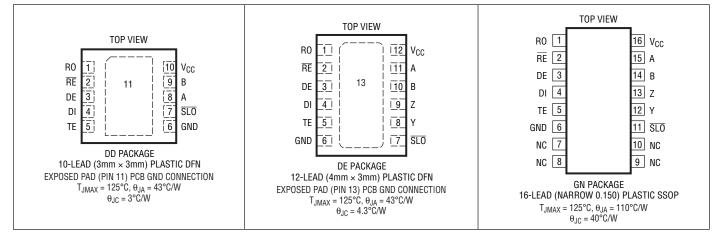
## ABSOLUTE MAXIMUM RATINGS (Note 1)

Supply Voltage (V<sub>CC</sub>) .....-0.3V to 7V Logic Input Voltages ( $\overline{RE}$ , DE, DI, TE,  $\overline{SLO}$ )....-0.3V to 7V Interface I/O:

(A-B) or (B-A) with Terminator Enabled .......6V Receiver Output Voltage (RO) ......-0.3V to (V<sub>CC</sub> +0.3V)

Operating Temperature (Note 4)	
LTC2859C, LTC2861C	0°C to 70°C
LTC2859I, LTC2861I	–40°C to 85°C
LTC2859H	–40°C to 105°C
Storage Temperature Range	–65°C to 125°C
Lead Temperature (Soldering, 10 sec)	
GN Package	

## PIN CONFIGURATION



## ORDER INFORMATION

LEAD FREE FINISH	TAPE AND REEL	PART MARKING*	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTC2861CDE#PBF	LTC2861CDE#TRPBF	2861	12-Lead (4mm × 3mm) Plastic DFN	0°C to 70°C
LTC2861IDE#PBF	LTC2861IDE#TRPBF	2861	12-Lead (4mm × 3mm) Plastic DFN	–40°C to 85°C
LTC2861CGN#PBF	LTC2861CGN#TRPBF	2861	16-Lead Plastic SSOP	0°C to 70°C
LTC2861IGN#PBF	LTC2861IGN#TRPBF	28611	16-Lead Plastic SSOP	-40°C to 85°C
LTC2859CDD#PBF	LTC2859CDD#TRPBF	LBNX	10-Lead (3mm × 3mm) Plastic DFN	0°C to 70°C
LTC2859IDD#PBF	LTC2859IDD#TRPBF	LBNX	10-Lead (3mm × 3mm) Plastic DFN	-40°C to 85°C
LTC2859HDD#PBF	LTC2859HDD#TRPBF	LBNX	10-Lead (3mm × 3mm) Plastic DFN	-40°C to 105°C

Consult LTC Marketing for parts specified with wider operating temperature ranges. \*The temperature grade is identified by a label on the shipping container. Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/

For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/



285961fc

# **ELECTRICAL CHARACTERISTICS** The $\bullet$ denotes the specifications which apply over the full operating temperature range, otherwise specifications are at T<sub>A</sub> = 25°C, V<sub>CC</sub> = 5V unless otherwise noted (Note 2).

SYMBOL	PARAMETER	PARAMETER CONDITIONS		MIN	ТҮР	MAX	UNITS
Driver							·
V <sub>OD</sub>	Differential Driver Output Voltage	$ \begin{array}{l} R = \infty, \ I_0 = 0 m A, \ V_{CC} = 4.5 V \ (Figure 1) \\ R = 27 \Omega \ (RS485), \ V_{CC} = 4.5 V \ (Figure 1) \\ R = 50 \Omega \ (RS422), \ V_{CC} = 4.5 V \ (Figure 1) \end{array} $	•	1.5 2.0		V <sub>CC</sub> V <sub>CC</sub> V <sub>CC</sub>	V V V
$\Delta  V_{OD} $	Change in Magnitude of Driver Differential Output Voltage for Complementary Output States	R = $27\Omega$ or R = $50\Omega$ (Figure 1)	•			0.2	V
V <sub>OC</sub>	Driver Common Mode Output Voltage	$R = 27\Omega$ or $R = 50\Omega$ (Figure 1)				3.0	V
$\Delta  V_{0C} $	Change in Magnitude of Driver Common Mode Output Voltage for Complementary Output States	$R$ = 27 $\Omega$ or $R$ = 50 $\Omega$ (Figure 1)	•			0.2	V
I <sub>OZD</sub>	Driver Three-State (High Impedance) Output Current on Y and Z	DE = 0V, V <sub>0</sub> = -7V, +12V (LTC2861 Only)	•			±10	μA
I <sub>OSD</sub>	Maximum Driver Short-Circuit Current	$-7V \le (Y \text{ or } Z) \le 12 \text{ (Figure 2)}$			±120	±250	mA
Receiver							<u>.</u>
I <sub>IN2</sub>	Receiver Input Current (A, B)	$ \begin{array}{ c c c c c c c c } \hline DE = TE = 0V, V_{CC} = 0V \text{ or } 5V, V_A \text{ or } V_B = 12V, \\ \hline Other at 0V \\ (H-Grade) \end{array} $				125 250	μA μA
		$DE = TE = 0V$ , $V_{CC} = 0V$ or 5V, $V_A$ or $V_B = -7V$ , Other at 0V	•	-100		200	μA
V <sub>TH</sub>	Receiver Differential Input Threshold	$(\text{H-Grade})$ $-7\text{V} \le \text{V}_{\text{CM}} \le 12$		-145		±0.2	μA V
VIH	Voltage	$-7.0 \ge 0.0 M \ge 1.5$				±0.2	v
$\Delta V_{TH}$	Receiver Input Hysteresis	$V_{CM} = 0V$			25		mV
V <sub>OH</sub>	Receiver Output HIGH Voltage	$I_0 = -4mA$ , $V_{ID} = 200mV$ , $V_{CC} = 4.5V$		2.4			V
V <sub>OL</sub>	Receiver Output LOW Voltage	$I_0 = 4mA$ , $V_{ID} = -200mV$ , $V_{CC} = 4.5V$				0.4	V
I <sub>OZR</sub>	Receiver Three-State (High Impedance) Output Current on RO	$\overline{\text{RE}}$ = 5V, 0V $\leq$ V <sub>0</sub> $\leq$ V <sub>CC</sub>	•			±1	μA
R <sub>IN</sub>	Receiver Input Resistance	$\overline{\text{RE}}$ = 5V or 0V, DE = TE = 0V		96	125		kΩ
		$-7V \le V_A = V_B \le 12V$ (H-Grade)	•	48	125		kΩ
R <sub>TERM</sub>	Receiver Input Terminating Resistor	TE = 5V, $V_{AB}$ = 2V, $V_B$ = -7, 0, 10V (Figure 7)	•	108	120	156	Ω
Logic							
V <sub>IH</sub>	Logic Input High Voltage	DE, DI, $\overline{\text{RE}}$ , TE, $\overline{\text{SLO}}$ , $V_{\text{CC}}$ = 4.5V		2			V
VIL	Logic Input Low Voltage	DE, DI, $\overline{\text{RE}}$ , TE, $\overline{\text{SLO}}$ , V <sub>CC</sub> = 4.5V				0.8	V
I <sub>IN1</sub>	Logic Input Current	DE, DI, RE, TE, SLO			0	±10	μA
Supplies							
I <sub>SHDN</sub>	Supply Current in Shutdown Mode	$DE = 0V, \overline{RE} = V_{CC}, TE = 0V$			0	5	μA
I <sub>CCR</sub>	Supply Current in Receive Mode	No Load, $DE = 0V$ , $\overline{RE} = 0V$ , $TE = 0V$			540	900	μA
I <sub>CCT</sub>	Supply Current in Transmit Mode	No Load, DE = V <sub>CC</sub> , $\overline{RE}$ = V <sub>CC</sub> , $\overline{SLO}$ = V <sub>CC</sub> , TE = 0V			630	1000	μA
I <sub>CCTS</sub>	Supply Current in Transmit SLO Mode	No Load, $DE = V_{CC}$ , $\overline{RE} = V_{CC}$ , $\overline{SLO} = 0V$ , $TE = 0V$			670	1100	μA
I <sub>CCL</sub>	Supply Current in Loopback Mode (Both Driver and Receiver Enabled)	No Load, DE = $V_{CC}$ , $\overline{RE}$ = 0V, $\overline{SLO}$ = $V_{CC}$ , TE = 0V	•		660	1100	μA
I <sub>CCRT</sub>	Supply Current in Termination Mode	$DE = OV, \ \overline{RE} = V_{CC}, \ TE = V_{CC}, \ \overline{SLO} = V_{CC}$			640	1180	μA



**SWITCHING CHARACTERISTICS** The  $\bullet$  denotes the specifications which apply over the full operating temperature range, otherwise specifications are at T<sub>A</sub> = 25°C, V<sub>CC</sub> = 5V, T<sub>E</sub> = 0 unless otherwise noted (Note 2).

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
Driver in Norma	al Mode ( <mark>SLO</mark> HIGH)	-					
f <sub>MAX</sub>	Maximum Data Rate	Note 3		20		-	Mbps
t <sub>PLHD</sub> , t <sub>PHLD</sub>	Driver Input to Output	$R_{DIFF} = 54\Omega, C_L = 100 pF$ (Figure 3)			10	50	ns
Δt <sub>PD</sub>	Driver Input to Output Difference  t <sub>PLHD</sub> -t <sub>PHLD</sub>	$R_{DIFF} = 54\Omega, C_L = 100pF$ (Figure 3)			1	6	ns
t <sub>SKEWD</sub>	Driver Output Y to Output Z	$R_{DIFF} = 54\Omega, C_L = 100pF$ (Figure 3)			1	±6	ns
t <sub>RD</sub> , t <sub>FD</sub>	Driver Rise or Fall Time	$R_{DIFF} = 54\Omega, C_{L} = 100 pF$ (Figure 3)			4	12.5	ns
$t_{ZLD}, t_{ZHD}, t_{LZD}, t_{HZD}$	Driver Enable or Disable Time	$R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = 0$ (Figure 4)	•			70	ns
t <sub>ZHSD</sub> , t <sub>ZLSD</sub>	Driver Enable from Shutdown	$R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = V_{CC}$ (Figure 4)				8	μs
t <sub>SHDN</sub>	Time to Shutdown	(DE = $\downarrow$ , $\overline{RE}$ = V <sub>CC</sub> ) or (DE = 0, $\overline{RE}$ $\uparrow$ ) (Figure 4)	•			100	ns
Driver in SLO N	lode ( <mark>SLO</mark> LOW)						
f <sub>MAXS</sub>	Maximum Data Rate	Note 3		250			kbps
t <sub>PLHDS,</sub> t <sub>PHLDS</sub>	Driver Input to Output	$R_{DIFF} = 54\Omega, C_L = 100pF$ (Figure 3)	•		0.95	1.5	μs
$\Delta t_{PDS}$	Driver Input to Output Difference  tpLHR <sup>-t</sup> PHLR	$R_{DIFF} = 54\Omega, C_L = 100pF$ (Figure 3)	•		50	500	ns
t <sub>SKEWDS</sub>	Driver Output A to Output B	$R_{DIFF} = 54\Omega$ , $C_{L} = 100$ pF (Figure 3) (H-Grade)	•		200 200	±500 ±750	ns ns
t <sub>RDS,</sub> t <sub>FDS</sub>	Driver Rise or Fall Time	$R_{DIFF} = 54\Omega, C_{L} = 100 pF$ (Figure 3)	•		0.9	1.5	μs
t <sub>ZHDS,</sub> t <sub>ZLDS</sub>	Driver Enable Time	$R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = 0$ (Figure 4)				300	ns
t <sub>LZDS,</sub> t <sub>HZDS</sub>	Driver Disable Time	$R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = 0$ (Figure 4)	•			70	ns
t <sub>ZHSDS</sub> , t <sub>ZLSDS</sub>	Driver Enable from Shutdown	$R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = V_{CC}$ (Figure 4)	•			8	μs
t <sub>SHDNS</sub>	Time to Shutdown	$(DE = 0, \overline{RE} = \uparrow) \text{ or } (DE = \downarrow, \overline{RE} = V_{CC}) \text{ (Figure 4)}$				500	ns
Receiver		·					
t <sub>PLHR</sub> , t <sub>PHLR</sub>	Receiver Input to Output	$C_L$ = 15pF, $V_{CM}$ = 1.5V, $\left V_{AB}\right $ = 1.5V, $t_R$ and $t_F$ < 4ns (Figure 5)			50	70	ns
t <sub>SKEWR</sub>	Differential Receiver Skew  tpLHR <sup>-t</sup> PHLR	C <sub>L</sub> = 15pF (Figure 5)	•		1	6	ns
t <sub>RR</sub> , t <sub>FR</sub>	Receiver Output Rise or Fall Time	C <sub>L</sub> = 15pF (Figure 5)			3	12.5	ns
t <sub>ZLR</sub> , t <sub>ZHR</sub> , t <sub>LZR</sub> , t <sub>HZR</sub>	Receiver Enable/Disable	$ \begin{array}{l} R_L = 1 k \Omega,  C_L = 15 p F,  DE = V_{CC} \; (Figure 6) \\ DI = 0 \; or \; V_{CC} \end{array} $				50	ns
t <sub>ZHSR</sub> , t <sub>ZLSR</sub>	Receiver Enable from Shutdown	$R_L = 1k\Omega$ , $C_L = 15pF$ , DE = 0V (Figure 6) DI = 0 or V <sub>CC</sub>	•			8	μs
t <sub>RTEN</sub> , t <sub>RTZ</sub>	Termination Enable or Disable Time	$V_B = 0V, V_{AB} = 2V, \overline{RE} = V_{CC}, DE = 0V$ (Figure 7)				100	μs

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime ..

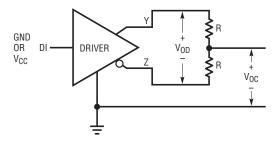
Note 2: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.

Note 3: Maximum data rate is guaranteed by other measured parameters and is not tested directly.

Note 4: This IC includes overtemperature protection that is intended to protect the device during momentary overload conditions. Junction temperature will exceed 125°C when overtemperature protection is active. Continuous operation above the specified maximum operating junction temperature may result in device degradation or failure.



## **TEST CIRCUITS**



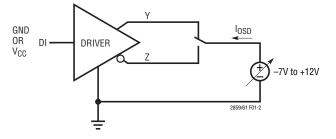


Figure 1. Driver DC Characteristics

Figure 2. Driver Output Short-Circuit Current

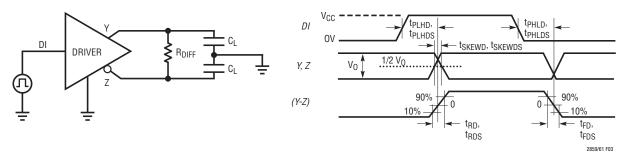


Figure 3. Driver Timing Measurement

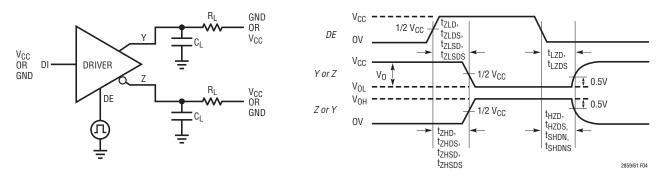


Figure 4. Driver Enable and Disable Timing Measurement



## LTC2859/LTC2861

## **TEST CIRCUITS**

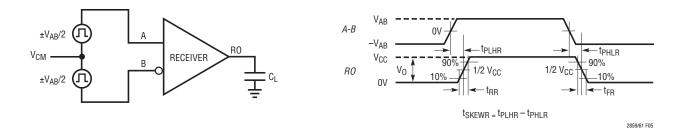


Figure 5. Receiver Propagation Delay Measurements

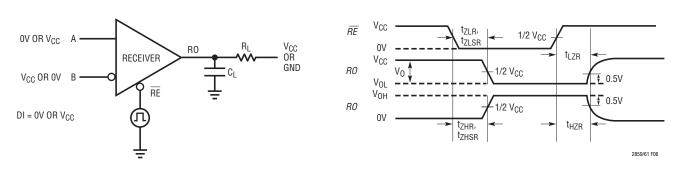


Figure 6. Receiver Enable/Disable Time Measurements

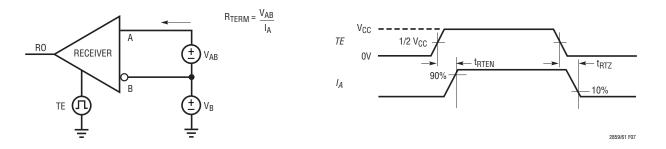
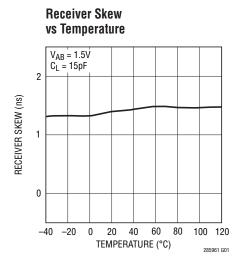
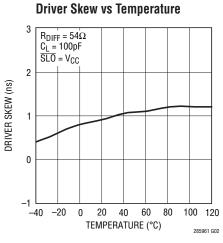


Figure 7. Termination Resistance and Timing Measurements

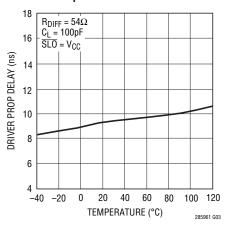


## **TYPICAL PERFORMANCE CHARACTERISTICS** $T_A = 25^{\circ}C$ , $V_{CC} = 5V$ , unless otherwise noted.

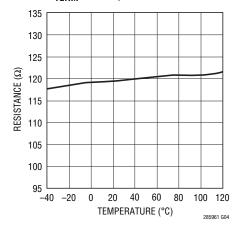




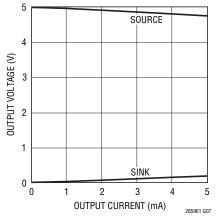
#### Driver Propagation Delay vs Temperature



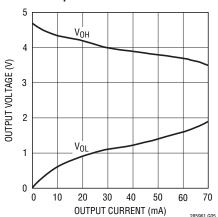
**R<sub>TERM</sub> vs Temperature** 



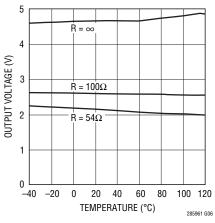




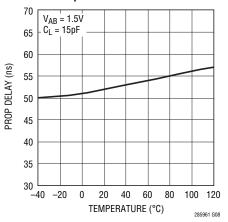
Driver Output Low/High Voltage vs Output Current



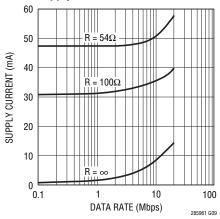
Driver Differential Output Voltage vs Temperature



Receiver Propagation Delay vs Temperature



Supply Current vs Data Rate



285961fc



## PIN FUNCTIONS (DD/DE/GN)

**RO** (Pin 1): Receiver Output. If the receiver output is enabled ( $\overline{RE}$  low) and A > B by 200mV, then RO will be high. If A < B by 200mV, then RO will be low. If the receiver inputs are open, shorted, or terminated without a valid signal, RO will be high.

**RE** (Pin 2): Receiver Enable. A low enables the receiver. A high input forces the receiver output into a high impedance state.

**DE (Pin 3):** Driver Enable. A high on DE enables the driver. A low input will force the driver outputs into a high impedance. If RE is high with DE and TE LOW, the part will enter a low power shutdown state.

**DI (Pin 4):** Driver Input. If the driver outputs are enabled (DE HIGH), then a low on DI forces the driver positive output LOW and negative output HIGH. A high on DI, with the driver outputs enabled, forces the driver positive output HIGH and negative output LOW.

**TE (Pin 5):** Internal Termination Resistance Enable. A high input will connect a termination resistor ( $120\Omega$  typical) between pins A and B.

**GND (Pins 6,11/6,13/6):** Ground. Pins 11 and 13 are backside thermal pad, connected to Ground.

**SLO** (Pins 7/7/11): Driver Slew Rate Control. A low input will force the driver into a reduced slew rate mode.

Y (Pins -/8/12): Positive Driver Output for LTC2861.

Z (Pins -/9/13): Negative Driver Output for LTC2861.

**B (Pins 9/10/14):** Negative Receiver Input (and Negative Driver Output for LTC2859).

**A (Pins 8/11/15):** Positive Receiver Input (and Positive Driver Output for LTC2859).

 $V_{CC}$  (Pins 10/12/16): Positive Supply. 4.5V <  $V_{CC}$  < 5.5V. Bypass with 0.1µF ceramic capacitor.





## FUNCTION TABLES

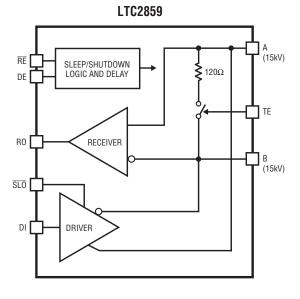
#### LTC2859

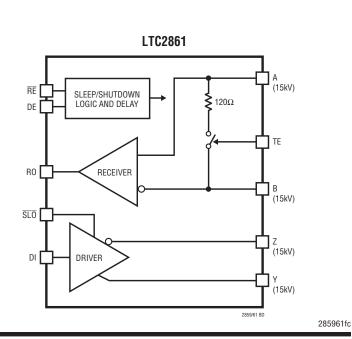
I	LOGIC INPUTS					
DE	RE	TE	MODE	A, B	RO	TERMINATOR
0	0	0	Receive	R <sub>IN</sub>	Enabled	Off
0	0	1	Receive with Term	R <sub>IN</sub>	Enabled	On
0	1	0	Shutdown	R <sub>IN</sub>	Hi-Z	Off
0	1	1	Term Only	R <sub>IN</sub>	Hi-Z	On
1	0	0	Transmit with Receive	Driven	Enabled	Off
1	0	1	Transmit with Receive and Term	Driven	Enabled	On
1	1	0	Transmit	Driven	Hi-Z	Off
1	1	1	Transmit with Term	Driven	Hi-Z	On

#### LTC2861

LOGIC INPUTS		LOGIC INPUTS					
DE	RE	TE	MODE	A, B	Y, Z	RO	TERMINATOR
0	0	0	Receive	R <sub>IN</sub>	Hi-Z	Enabled	Off
0	0	1	Receive with Term	R <sub>IN</sub>	Hi-Z	Enabled	On
0	1	0	Shutdown	R <sub>IN</sub>	Hi-Z	Hi-Z	Off
0	1	1	Term Only	R <sub>IN</sub>	Hi-Z	Hi-Z	On
1	0	0	Transmit with Receive	R <sub>IN</sub>	Driven	Enabled	Off
1	0	1	Transmit with Receive and Term	R <sub>IN</sub>	Driven	Enabled	On
1	1	0	Transmit	R <sub>IN</sub>	Driven	Hi-Z	Off
1	1	1	Transmit with Term	R <sub>IN</sub>	Driven	Hi-Z	On

## **BLOCK DIAGRAMS**







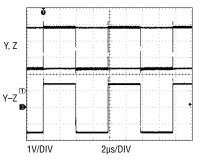
#### Driver

The driver provides full RS485 and RS422 compatibility. When enabled, if DI is high, Y-Z is positive for the full duplex device (LTC2861) and A-B is positive for the halfduplex device (LTC2859).

When the driver is disabled, both outputs are highimpedance. For the full duplex LTC2861, the leakage on the driver output pins is guaranteed to be less than 10µA over the entire common mode range of -7V to +12V. On the half-duplex LTC2859, the impedance is dominated by the receiver input resistance, R<sub>IN</sub>.

#### **Driver Overvoltage and Overcurrent Protection**

The driver outputs are protected from short circuits to any voltage within the Absolute Maximum range of ( $V_{CC}$ -15V) to +15V. The maximum current in this condition is 250mA. If the pin voltage exceeds about ±10V, current limit folds back to about half of the peak value to reduce overall power dissipation and avoid damaging the part.



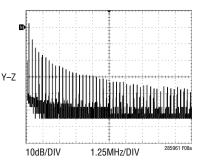
Driver Output at 125kHz into 100 $\Omega$  Resistor

The LTC2859/LTC2861 also feature thermal shutdown protection that disables the driver, terminator, and receiver in case of excessive power dissipation.

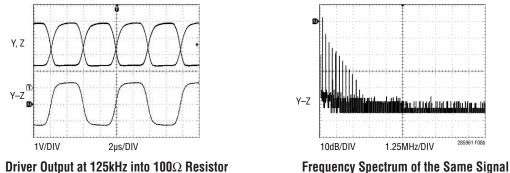
#### **SLO** Mode: Slew Limiting for EMI Emissions Control

The LTC2859/LTC2861 feature a logic-selectable reducedslew mode (SLO mode) that softens the driver output edges to control the high frequency EMI emissions from equipment and data cables. The reduced slew rate mode is entered by taking the SLO pin low, where the data rate is limited to about 250kbps. Slew limiting also mitigates the adverse effects of imperfect transmission line termination caused by stubs or mismatched cables.

Figures 8a and 8b show the LTC2861 driver outputs in normal and <u>SLO</u> mode with their corresponding frequency spectrums operating at 250kbps. SLO mode significantly reduces the high frequency harmonics.

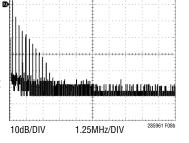


Frequency Spectrum of the Same Signal









285961fc



#### **Receiver and Failsafe**

With the receiver enabled, when the absolute value of the differential voltage between the A and B pins is greater than 200mV, the state of RO will reflect the polarity of (A-B).

The LTC2859/LTC2861 have a failsafe feature that guarantees the receiver output to be in a logic HIGH state when the inputs are either shorted, left open, or terminated (externally or internally), but not driven for more than about  $3\mu$ s. The delay prevents signal zero crossings from being interpreted as shorted inputs and causing RO to go high inadvertently. This failsafe feature is guaranteed to work for inputs spanning the entire common mode range of -7V to +12V.

The receiver output is internally driven high (to  $V_{CC}$ ) or low (to ground) with no external pull-up needed. When the receiver is disabled the RO pin becomes Hi-Z with leakage of less than  $\pm 1\mu$ A for voltages within the supply range.

#### **Receiver Input Resistance**

The receiver input resistance from A or B to ground is greater than 96k permitting up to a total of 256 receivers per system without exceeding the RS485 receiver load-

ing specification. High temperature H-Grade operation reduces the minimum input resistance to 48k permitting 128 receivers on the bus. The input resistance of the receiver is unaffected by enabling/disabling the receiver or by powering/unpowering the part. The equivalent input resistance looking into A and B is shown in Figure 9.

#### **Switchable Termination**

Proper cable termination is very important for good signal fidelity. If the cable is not terminated with its characteristic impedance, reflections will result in distorted waveforms.

The LTC2859/LTC2861 are the first RS485 transceivers to offer integrated switchable termination resistors on the receiver input pins. This provides the tremendous advantage of being able to easily change, through logic control, the proper line termination for optimal performance when configuring transceiver networks.

When the TE pin is high, the termination resistor is enabled and the differential resistance from A to B is  $120\Omega$ . Figure 10 shows the I/V characteristics between pins A and B with the termination resistor enabled and disabled. The resistance is maintained over the entire RS485 common mode range of -7V to +12V as shown in Figure 11.

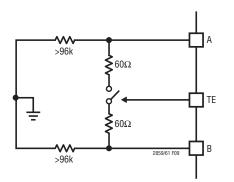


Figure 9. Equivalent Input Resistance into A and B (on the LTC2859, Valid if Driver is Disabled)

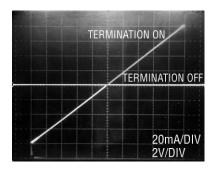


Figure 10. Curve Trace Between A and B with Termination Enabled and Disabled



The integrated termination resistor has a high frequency response which does not limit performance at the maximum specified data rate. Figure 12 shows the magnitude and phase of the termination impedance vs frequency. The termination resistor cannot be enabled by TE if the device is unpowered or in thermal shutdown mode.

### Supply Current

The unloaded static supply currents in the LTC2859/ LTC2861 are very low —typically under 700 $\mu$ A for all modes of operation without the internal terminator enabled. In applications with resistively terminated cables, the supply current is dominated by the driver load. For example, when using two 120 $\Omega$  terminators with a differential driver output voltage of 2V, the DC current is 33mA, which is sourced by the positive voltage supply. This is true whether the terminators are external or internal such as in the LTC2859/ LTC2861. Power supply current increases with toggling data due to capacitive loading and this term can increase significantly at high data rates. Figure 13 shows supply current vs data rate for two different capacitive loads (for the circuit configuration of Figure 3).

#### **High Speed Considerations**

A ground plane layout is recommended for the LTC2859/ LTC2861. A 0.1 $\mu$ F bypass capacitor less than one quarter inch away from the V<sub>CC</sub> pin is also recommended. The PC board traces connected to signals A/B and Z/Y (LTC2861) should be symmetrical and as short as possible to maintain good differential signal integrity. To minimize capacitive effects, the differential signals should be separated by more than the width of a trace and should not be routed on top of each other if they are on different signal planes.

Care should be taken to route outputs away from any sensitive inputs to reduce feedback effects that might cause noise, jitter, or even oscillations. For example, in the full duplex LTC2861, DI and A/B should not be routed near the driver or receiver outputs.

The logic inputs of the LTC2859/LTC2861 have 50mV of hysteresis to provide noise immunity. Fast edges on the outputs can cause glitches in the ground and power supplies which are exacerbated by capacitive loading. If a logic input is held near its threshold (typically 1.5V), a noise glitch

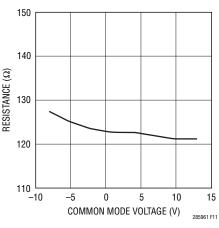


Figure 11. Termination Resistance vs Common Mode Voltage

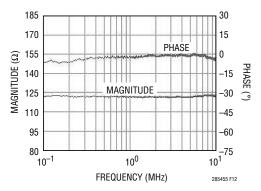


Figure 12. Termination Magnitude and Phase vs Frequency

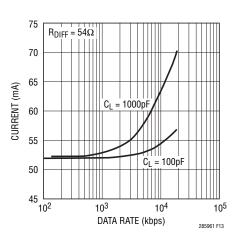


Figure 13. Supply Current vs Data Rate





from a driver transition may exceed the hysteresis levels on the logic and data inputs pins causing an unintended state change. This can be avoided by maintaining normal logic levels on the pins and by slewing inputs through their thresholds by faster than  $1V/\mu s$  when transitioning. Good supply decoupling and proper line termination also reduces glitches caused by driver transitions.

#### Cable Length vs Data Rate

For a given data rate, the maximum transmission distance is bounded by the cable properties. A typical curve of cable length vs data rate compliant with the RS485 standard is shown in Figure 14. Three regions of this curve reflect different performance limiting factors in data transmission. In the flat region of the curve, maximum distance is determined by resistive losses in the cable. The downward sloping region represents limits in distance and data rate due to AC losses in the cable. The solid vertical line represents the specified maximum data rate in the RS485 standard. The dashed lines at 250kbps and 20Mbps show the maximum data rates of the LTC2859/LTC2861 in Low-EMI and normal modes, respectively.

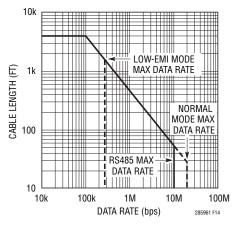
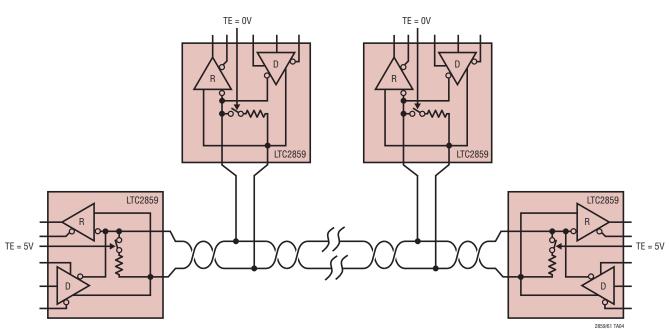


Figure 14. Cable Length vs Data Rate (RS485 Standard Shown in Solid Lines)

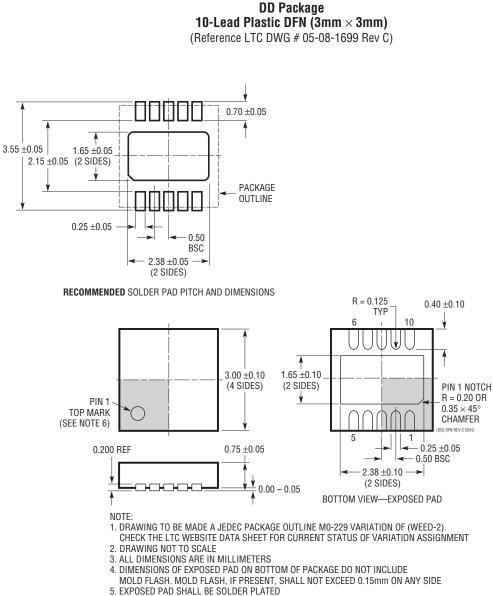
## TYPICAL APPLICATIONS



#### Multi-Node Network with End Termination Using LTC2859

## PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.



6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION ON THE

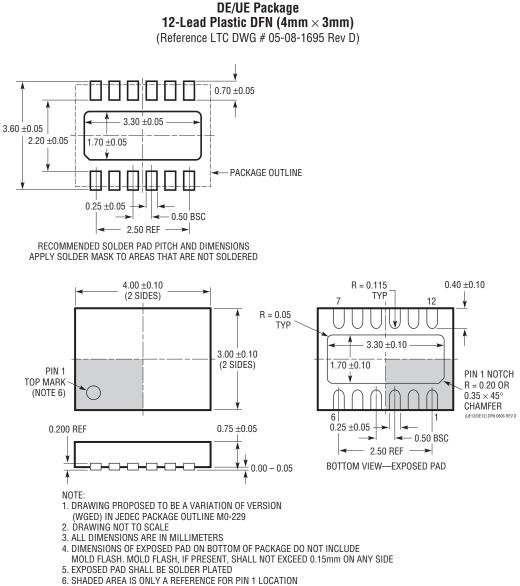
TOP AND BOTTOM OF PACKAGE





## PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.



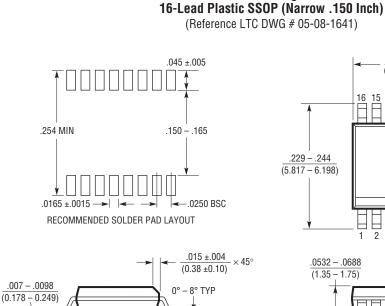
ON THE TOP AND BOTTOM OF PACKAGE

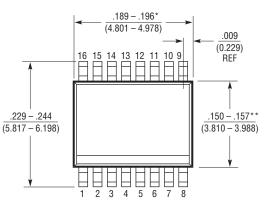


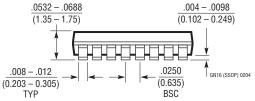
## PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.

**GN Package** 







NOTE:

- 1. CONTROLLING DIMENSION: INCHES
- 2. DIMENSIONS ARE IN  $\frac{\text{INUMES}}{(\text{MILLIMETERS})}$ INCHES

.016 – .050

(0.406 - 1.270)

- 3. DRAWING NOT TO SCALE
- \*DIMENSION DOES NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED 0.006" (0.152mm) PER SIDE
- \*\*DIMENSION DOES NOT INCLUDE INTERLEAD FLASH. INTERLEAD FLASH SHALL NOT EXCEED 0.010" (0.254mm) PER SIDE





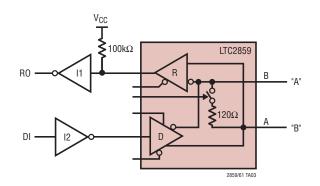
## **REVISION HISTORY** (Revision history begins at Rev C)

REV	DATE	DESCRIPTION	PAGE NUMBER
С	3/12	Added H-grade Order Information and Electrical Characteristics parameters	2, 3, 4
		Revised Receiver Input Resistance section	11
		Replaced Figure 12	12
		Added Termination Resistor restriction information	12



## TYPICAL APPLICATION





## **RELATED PARTS**

PART NUMBER	DESCRIPTION	COMMENTS
LTC2854/LTC2855	3.3V 20Mbps RS485/RS422 Transceivers with Integrated Switchable Termination	Up to ±25kV HBM ESD, 125°C Operation
LTC2856/LTC2857/ LTC2858	5V 20Mbps and Slew Rate Limited 15kV RS485/RS422 Transceivers	±15kV ESD, 125°C Operation
LTC2850/LTC2851/ LTC2852	3.3V 20Mbps RS485/RS422 Transceivers	±15kV ESD, 125°C Operation
LTC2862/LTC2863/ LTC2864/LTC2865	±60V Fault Protected 3V to 5.5V RS485/RS422 Transceivers	20Mbps or 250kbps, ±15kV HBM ESD, ±25V Common Mode Range
LTM2881	Complete 3.3V Isolated RS485/RS422 µModule® Transceiver + Power	$2500V_{RMS}$ Isolation with Integrated Isolated DC/DC Converter and Switchable Termination
LTC485	Low Power RS485 Interface Transceiver	I <sub>CC</sub> = 300μA (Typ)
LTC491	Differential Driver and Receiver Pair	I <sub>CC</sub> = 300μA
LTC1480	3.3V Ultralow Power RS485 Transceiver	3.3V Operation
LTC1483	Ultralow Power RS485 Low EMI Transceiver	Controlled Driver Slew Rate
LTC1485	Differential Bus Transceiver	10Mbaud Operation
LTC1487	Ultralow Power RS485 with Low EMI, Shutdown and High Input Impedance	Up to 256 Transceivers on the Bus
LTC1520	50Mbps Precision Quad Line Receiver	Channel-to-Channel Skew 400ps (Typ)
LTC1535	Isolated RS485 Full-Duplex Transceiver	2500V <sub>RMS</sub> Isolation in Surface Mount Package
LTC1685	52Mbps RS485 Transceiver with Precision Delay	Propagation Delay Skew 500ps (Typ)
LT1785	±60V Fault Protected RS485 Transceiver	60V Tolerant, 15kV ESD

