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High Efficiency USB Power Manager + Triple Step-Down DC/DC

FEATURES

Power Manager

- High Efficiency Switching PowerPath[™] Controller with Bat-Track[™] Adaptive Output Control
- Programmable USB or Wall Current Limit (100mA/500mA/1A)
- Full Featured Li-Ion/Polymer Battery Charger
- 1.5A Maximum Charge Current
- Internal 180mΩ Ideal Diode + External Ideal Diode Controller Powers Load in Battery Mode
- Low No-Load Quiescent Current when Powered from BAT (<32μA)

DC/DCs

- Triple High Efficiency Step-Down DC/DCs (1A/400mA/400mA I_{OUT})
- All Regulators Operate at 2.25MHz
- Dynamic Voltage Scaling on Two Outputs
- I²C or Independent Enable, V_{OLIT} Controls
- Low No-Load Quiescent Current: 20µA
- 28-Pin (4mm \times 5mm \times 0.75mm) QFN Package

APPLICATIONS

- HDD-Based MP3 Players, PDAs, GPS, PMPs
- Portable Medical Products
- Handheld Instrumentation
- Other USB-Based Handheld Products

DESCRIPTION

The LTC®3555 family are highly integrated USB compatible power management and battery charger ICs for Li-Ion/Polymer battery applications. They include a high efficiency current limited switching PowerPath manager with automatic load prioritization, a battery charger, an ideal diode and three general purpose synchronous step-down switching regulators.

The LTC3555 family limits input current to either 100mA or 500mA for USB applications or 1A for adapter-powered applications. Unlike linear chargers, the LTC3555 family's switching architecture transmits nearly all of the power available from the USB port to the load with minimal loss and heat which eases thermal constraints in small spaces.

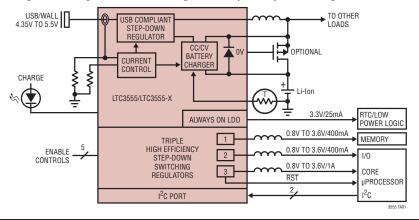
Two of the three general purpose switching regulators can provide up to 400mA and the third can deliver 1A. The entire product can be controlled via I^2C or simple I/O. The LTC3555-1/LTC3555-3 versions offer "instant-on" power delivery to the portable product even with a very low battery voltage. The LTC3555-3 version also has a reduced charger float voltage of 4.100V for battery safety and longevity.

The LTC3555 family is available in the low profile 28-pin $(4mm \times 5mm \times 0.75mm)$ QFN surface mount package.

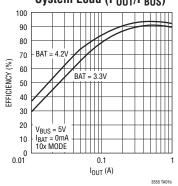
(C), LT, LTC, LTM Linear Technology, the Linear logo and Burst Mode are registered trademarks and PowerPath and Bat-Track are trademarks of Linear Technology Corporation. All other trademarks are the property of their respective owners. Protected by U.S. Patents, including 6522118 and 6404251.

TYPICAL APPLICATION

High Efficiency PowerPath Manager and Triple Step-Down Regulator



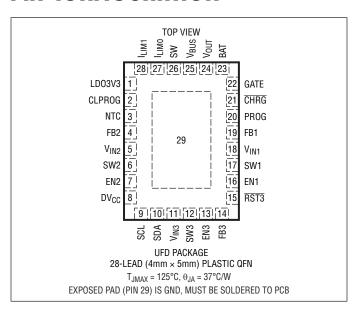
Switching Regulator Efficiency to System Load (P_{OUT}/P_{BUS})



ABSOLUTE MAXIMUM RATINGS

(Notes 1, 2, 3) V_{BLIS} (Transient) t < 1ms, Duty Cycle < 1%-0.3V to 7V V_{IN1}, V_{IN2}, V_{IN3}, V_{BLIS} (Static), DV_{CC}, FB1, FB2, FB3, NTC, BAT, SCL, SDA, RST3, CHRG......–0.3V to 6V EN1, EN2, EN3...... -0.3V to V_{OUT} +0.3V I_{LIMO} , I_{LIM1}-0.3V to MAX (V_{BUS} , V_{OUT} BAT) I_{BST3}, I_{CHBG}......50mA I_{PROG}......2mA I_{LD03V3}......30mA I_{SW1}, I_{SW2} 600mA ISW, ISW3, IRAT, IVOLIT2A Junction Temperature 125°C Operating Temperature Range (Note 2)....-40°C to 85°C Storage Temperature Range-65°C to 125°C

PIN CONFIGURATION



ORDER INFORMATION http://www.linear.com/product/LTC3555#orderinfo

LEAD FREE FINISH	TAPE AND REEL	PART MARKING*	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTC3555EUFD#PBF	LTC3555EUFD#TRPBF	3555	28-Lead (4mm x 5mm) Plastic QFN	-40°C to 85°C
LTC3555IUFD#PBF	LTC3555IUFD#TRPBF	3555	28-Lead (4mm x 5mm) Plastic QFN	-40°C to 85°C
LTC3555EUFD-1#PBF	LTC3555EUFD-1#TRPBF	35551	28-Lead (4mm x 5mm) Plastic QFN	-40°C to 85°C
LTC3555IUFD-1#PBF	LTC3555IUFD-1#TRPBF	35551	28-Lead (4mm x 5mm) Plastic QFN	-40°C to 85°C
LTC3555EUFD-3#PBF	LTC3555EUFD-3#TRPBF	35553	28-Lead (4mm x 5mm) Plastic QFN	-40°C to 85°C
LTC3555IUFD-3#PBF	LTC3555IUFD-3#TRPBF	35553	28-Lead (4mm x 5mm) Plastic QFN	-40°C to 85°C

Consult LTC Marketing for parts specified with wider operating temperature ranges. *The temperature grade is identified by a label on the shipping container.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/

For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/. Some packages are available in 500 unit reels through designated sales channels with #TRMPBF suffix.

ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$. $V_{BUS} = 5V$, BAT = 3.8V, $DV_{CC} = 3.3V$, $R_{PROG} = 1k$, $R_{CLPROG} = 3k$, unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
PowerPath Sv	vitching Regulator	,					
$\overline{V_{BUS}}$	Input Supply Voltage			4.35		5.5	V
IBUSLIM	Total Input Current	1x Mode, V _{OUT} = BAT 5x Mode, V _{OUT} = BAT 10x Mode, V _{OUT} = BAT Suspend Mode, V _{OUT} = BAT	•	87 436 800 0.31	95 460 860 0.38	100 500 1000 0.50	mA mA mA
I _{VBUSQ}	V _{BUS} Quiescent Current	1x Mode, I _{OUT} = 0mA 5x Mode, I _{OUT} = 0mA 10x Mode, I _{OUT} = 0mA Suspend Mode, I _{OUT} = 0mA			7 15 15 0.044		mA mA mA



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SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
h _{CLPROG} (Note 4)	Ratio of Measured V _{BUS} Current to CLPROG Program Current	1x Mode 5x Mode 10x Mode Suspend Mode			224 1133 2140 11.3		mA/mA mA/mA mA/mA mA/mA
I _{OUT(POWERPATH)}	V _{OUT} Current Available Before Loading BAT	1x Mode, BAT = 3.3V 5x Mode, BAT = 3.3V 10x Mode, BAT = 3.3V Suspend Mode			135 672 1251 0.32		mA mA mA
V _{CLPROG}	CLPROG Servo Voltage in Current Limit	1x, 5x, 10x Modes Suspend Mode			1.188 100		V mV
V _{UVLO_VBUS}	V _{BUS} Undervoltage Lockout	Rising Threshold Falling Threshold		3.95	4.30 4.00	4.35	V
V _{UVLO_VBUS-BAT}	V _{BUS} to BAT Differential Undervoltage Lockout	Rising Threshold Falling Threshold			200 50		mV mV
V _{OUT}	V _{OUT} Voltage	1x, 5x, 10x Modes, 0V < BAT < 4.2V, I _{OUT} = 0mA, Battery Charger Off		3.4	BAT + 0.3	4.7	V
		USB Suspend Mode, I _{VOUT} = 250μA		4.5	4.6	4.7	V
fosc	Switching Frequency			1.8	2.25	2.7	MHz
R _{PMOS_POWERPATH}	PMOS On Resistance				0.18		Ω
$\frac{R_{\text{NMOS_POWERPATH}}}{}$	NMOS On Resistance				0.30		Ω
IPEAK_POWERPATH	Peak Switch Current Limit	1x, 5x Modes 10x			2		A A
Battery Charger							
V _{FLOAT}	BAT Regulated Output Voltage	LTC3555/LTC3555-1 LTC3555/LTC3555-1 LTC3555-3 LTC3555-3	•	4.179 4.165 4.079 4.065	4.200 4.200 4.100 4.100	4.221 4.235 4.121 4.135	V V V
I _{CHG}	Constant Current Mode Charge Current	R _{PROG} = 1k R _{PROG} = 5k		980 185	1022 204	1065 223	mA mA
I _{BAT}	Battery Drain Current	V _{BUS} > V _{UVLO} , Battery Charger Off, I _{VOUT} = 0μA V _{BUS} = 0V, I _{VOUT} = 0μA (Ideal Diode Mode) LTC3555 LTC3555-1/LTC3555-3		2	3.5 27 32	5 38 44	μΑ μΑ Αμ
$\overline{V_{PROG}}$	PROG Pin Servo Voltage				1.000		V
V _{PROG_TRKL}	PROG Pin Servo Voltage in Trickle Charge	BAT < V _{TRKL}			0.100		V
V _{C/10}	C/10 Threshold Voltage at PROG				100		m۷
h _{PROG}	Ratio of I _{BAT} to PROG Pin Current				1022		mA/mA
I _{TRKL}	Trickle Charge Current	BAT < V _{TRKL}			100		mA
$\overline{V_{TRKL}}$	Trickle Charge Threshold Voltage	BAT Rising		2.7	2.85	3.0	V
ΔV_{TRKL}	Trickle Charge Hysteresis Voltage				135		m۷
ΔV_{RECHRG}	Recharge Battery Threshold Voltage	Threshold Voltage Relative to V _{FLOAT}		-75	-100	-125	mV
t _{TERM}	Safety Timer Termination	Timer Starts when BAT = V _{FLOAT}		3.3	4	5	Hour
t _{BADBAT}	Bad Battery Termination Time	BAT < V _{TRKL}		0.42	0.5	0.63	Hour
h _{C/10}	End of Charge Indication Current Ratio	(Note 5)	+	0.088	0.1	0.112	mA/mA



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SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
V _{CHRG}	CHRG Pin Output Low Voltage	I _{CHRG} = 5mA		65	100	mV
I _{CHRG}	CHRG Pin Leakage Current	V _{CHRG} = 5V			1	μА
R _{ON_CHG}	Battery Charger Power FET On Resistance (Between V _{OUT} and BAT)			0.18		Ω
T _{LIM}	Junction Temperature in Constant Temperature Mode			110		°C
NTC						
V _{COLD}	Cold Temperature Fault Threshold Voltage	Rising Threshold Hysteresis	75.0	76.5 1.5	78.0	%V _{BUS} %V _{BUS}
V _{HOT}	Hot Temperature Fault Threshold Voltage	Falling Threshold Hysteresis	33.4	34.9 1.5	36.4	%V _{BUS} %V _{BUS}
V _{DIS}	NTC Disable Threshold Voltage	Falling Threshold Hysteresis	0.7	1.7 50	2.7	%V _{BUS} mV
I _{NTC}	NTC Leakage Current	$V_{NTC} = V_{BUS} = 5V$	-50		50	nA
Ideal Diode						
V_{FWD}	Forward Voltage	$V_{BUS} = 0V$, $I_{VOUT} = 10$ mA $I_{VOUT} = 10$ mA		2 15		mV mV
R _{DROPOUT}	Internal Diode On Resistance, Dropout	V _{BUS} = 0V		0.18		Ω
I _{MAX_DIODE}	Internal Diode Current Limit		1.6			А
Always On 3.3V	LDO Supply					
$\overline{V_{LD03V3}}$	Regulated Output Voltage	0mA < I _{LD03V3} < 25mA	3.1	3.3	3.5	V
R _{CL_LD03V3}	Closed-Loop Output Resistance			4		Ω
R _{0L_LD03V3}	Dropout Output Resistance			23		Ω
Logic (I _{LIMO} , I _{LIM}	1, EN1, EN2, EN3)					·
$\overline{V_{IL}}$	Logic Low Input Voltage				0.4	V
V _{IH}	Logic High Input Voltage		1.2			V
I _{PD1}	I _{LIM0} , I _{LIM1} , EN1, EN2, EN3 Pull-Down Currents			2		μА
I ² C Port						
DV _{CC}	Input Supply Voltage		1.6		5.5	V
I _{DVCC}	DV _{CC} Current	SCL/SDA = 0kHz		0.5		μА
V _{DVCC_UVLO}	DV _{CC} UVLO			1.0		V
ADDRESS	I ² C Address			0001 001[0]	
V _{IH} , SDA, SCL	Input High Threshold		70			%DV _{CC}
V _{IL} , SDA, SCL	Input Low Threshold				30	%DV _{CC}
I _{PD2} SDA, SCL	Pull-Down Current			2		μA
V _{OL}	Digital Output Low (SDA)	I _{PULLUP} = 3mA			0.4	V
f _{SCL}	Clock Operating Frequency				400	kHz
t _{BUF}	Bus Free Time Between Stop and Start Condition		1.3			μs
t _{HD_STA}	Hold Time After (Repeated) Start Condition		0.6			μs
t _{SU_STA}	Repeated Start Condition Setup Time		0.6			μs

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SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
t _{SU_STD}	Stop Condition Time			0.6			μs
t _{HD_DAT(OUT)}	Data Hold Time			225			ns
t _{HD_DAT(IN)}	Input Data Hold Time			0		900	ns
t _{SU_DAT}	Data Setup Time			100			ns
t_{LOW}	Clock Low Period			1.3			μs
t _{HIGH}	Clock High Period			0.6			μs
t _f	Clock Data Fall Time			20		300	ns
t _r	Clock Data Rise Time			20		300	ns
t _{SP}	Spike Suppression Time					50	ns
General Purpos	se Switching Regulators 1, 2 and 3						
V _{IN1,2,3}	Input Supply Voltage			2.7		5.5	V
V _{OUTUVLO}	V _{OUT} UVLO—V _{OUT} Falling V _{OUT} UVLO—V _{OUT} Rising	V _{IN1,2,3} Connected to V _{OUT} Through Low Impedance. Switching Regulators are Disabled in UVLO		2.5	2.6 2.8	2.9	V
f _{OSC}	Oscillator Frequency			1.8	2.25	2.7	MHz
I _{FB1,2,3}	FBx Input Current	V _{FB1,2,3} = 0.85V		-50		50	nA
D _{1,2,3}	Maximum Duty Cycle			100			%
R _{SW1,2,3_PD}	SWx Pull-Down in Shutdown				10		kΩ
General Purpos	se Switching Regulator 1		•				
I _{VIN1}	Pulse Skip Mode Input Current Burst Mode Input Current Forced Burst Mode® Input Current LDO Mode Input Current Shutdown Input Current	I _{OUT1} = 0μA (Note 6) I _{OUT1} = 0μA, FB1 = 0V			225 35 20 20	60 35 35 1	Αμ Αμ Αμ Αμ
I _{LIMSW1}	PMOS Switch Current Limit	Pulse Skip/Burst Mode Operation		600	800	1100	mA
I _{OUT1}	Available Output Current	Pulse Skip/Burst Mode Operation (Note 7) Forced Burst Mode Operation (Note 7) LDO Mode (Note 7)		400 60 50			mA mA mA
V _{FB1}	V _{FB1} Servo Voltage	(Note 8)	•	0.78	0.80	0.82	V
R _{P1}	PMOS R _{DS(ON)}				0.6		Ω
R _{N1}	NMOS R _{DS(ON)}				0.7		Ω
R _{LDO_CL1}	LDO Mode Closed-Loop R _{OUT}				0.25		Ω
R _{LD0_0L1}	LDO Mode Open-Loop R _{OUT}	(Note 9)			2.5		Ω
General Purpos	se Switching Regulator 2						
I _{VIN2}	Pulse Skip Mode Input Current Burst Mode Input Current Forced Burst Mode Input Current LDO Mode Input Current Shutdown Input Current	I _{OUT2} = 0μA (Note 6) I _{OUT2} = 0μA, FB2 = 0V			225 35 20 20	60 35 35 1	Ац Ац Ац Ац Ац
I _{LIMSW2}	PMOS Switch Current Limit	Pulse Skip/Burst Mode Operation		600	800	1100	mA
I _{OUT2}	Available Output Current	Pulse Skip/Burst Mode Operation (Note 7) Forced Burst Mode Operation (Note 7) LDO Mode (Note 7)		400 60 50			mA mA mA



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SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
V _{FBHIGH2}	Maximum Servo Voltage	Full Scale (1, 1, 1, 1) (Note 8)	•	0.78	0.80	0.82	V
$V_{\rm FBLOW2}$	Minimum Servo Voltage	Zero Scale (0, 0, 0, 0) (Note 8)		0.405	0.425	0.445	V
V_{LSB2}	V _{FB2} Servo Voltage Step Size				25		mV
R _{P2}	PMOS R _{DS(ON)}				0.6		Ω
R _{N2}	NMOS R _{DS(ON)}				0.7		Ω
R _{LDO_CL2}	LDO Mode Closed-Loop R _{OUT}				0.25		Ω
R _{LDO_OL2}	LDO Mode Open-Loop R _{OUT}	(Note 9)			2.5		Ω
General Purpo	se Switching Regulator 3		'				
I _{VIN3}	Pulse Skip Mode Input Current Burst Mode Input Current Forced Burst Mode Input Current LDO Mode Input Current Shutdown Input Current	I _{OUT3} = 0μA (Note 6) I _{OUT3} = 0μA, FB3 = 0V			225 35 20 20	60 35 35 1	Ац Ац Ац Ац Ац
I _{LIMSW3}	PMOS Switch Current Limit	Pulse Skip/Burst Mode Operation		1500	2000	2800	mA
I _{OUT3}	Available Output Current	Pulse Skip/Burst Mode Operation (Note 7) Forced Burst Mode Operation (Note 7) LDO Mode (Note 7)		1000 150 50			mA mA mA
V _{FBHIGH3}	Maximum Servo Voltage	Full Scale (1, 1, 1, 1) (Note 8)	•	0.78	0.80	0.82	V
V _{FBLOW3}	Minimum Servo Voltage	Zero Scale (0, 0, 0, 0) (Note 8)		0.405	0.425	0.445	V
V_{LSB3}	V _{FB} Servo Voltage Step Size				25		mV
R _{P3}	PMOS R _{DS(ON)}				0.18		Ω
R _{N3}	NMOS R _{DS(ON)}				0.30		Ω
R _{LDOCL3}	LDO Mode Closed Loop R _{OUT}				0.25		Ω
R _{LD00L3}	LDO Mode Open Loop R _{OUT}	(Note 9)			2.5		Ω
t _{RST3}	Power On Reset Time for Switching Regulator	V _{FB3} Within 92% of Final Value to RST3 Hi-Z	230		ms		

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: The LTC3555E/LTC3555E-X are guaranteed to meet performance specifications from 0°C to 85°C. Specifications over the -40°C to 85°C operating temperature range are assured by design, characterization and correlation with statistical process controls. The LTC3555I/LTC3555I-X are guaranteed to meet performance specifications over the full -40°C to 85°C operating temperature range.

Note 3: The LTC3555/LTC3555-X include overtemperature protection that is intended to protect the device during momentary overload conditions. Junction temperature will exceed 125°C when overtemperature protection is active. Continuous operation above the specified maximum operating junction temperature may impair device reliability.

Note 4: Total input current is the sum of quiescent current, I_{VBUSQ} , and measured current given by:

V_{CLPROG}/R_{CLPROG} • (h_{CLPROG} +1)

Note 5: $h_{\text{C}/10}$ is expressed as a fraction of measured full charge current with indicated PROG resistor.

Note 6: FBx above regulation such that regulator is in sleep. Specification does not include resistive divider current reflected back to V_{INx} .

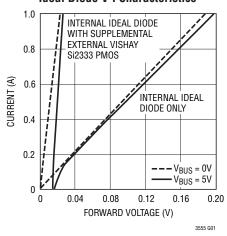
Note 7: Guaranteed by design but not explicitly tested.

Note 8: Applies to pulse skip, Burst Mode operation and forced Burst Mode operation only.

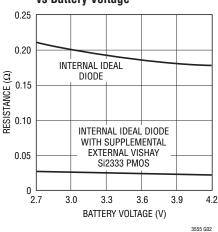
Note 9: Inductor series resistance adds to open-loop R_{OUT} .

LINEAR TECHNOLOGY

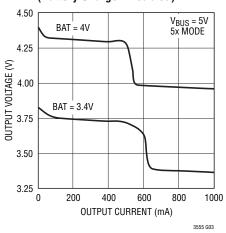
Ideal Diode V-I Characteristics



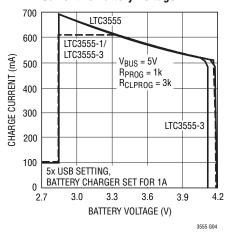
Ideal Diode Resistance vs Battery Voltage



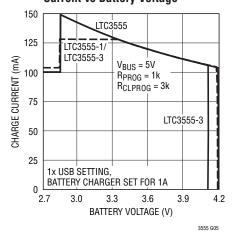
Output Voltage vs Output Current (Battery Charger Disabled)



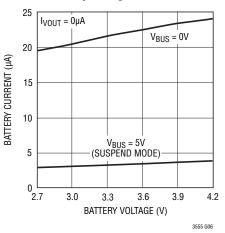
USB Limited Battery Charge Current vs Battery Voltage



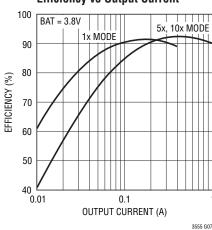
USB Limited Battery Charge Current vs Battery Voltage



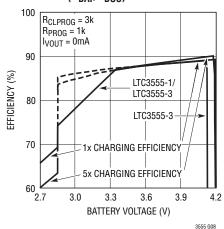
Battery Drain Current vs Battery Voltage



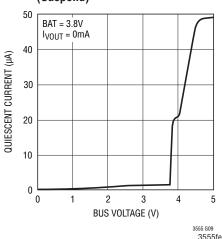
PowerPath Switching Regulator Efficiency vs Output Current

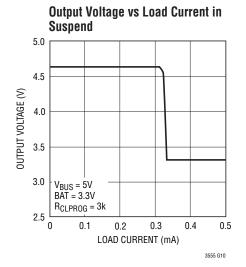


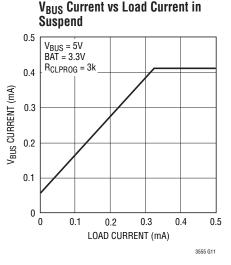
Battery Charging Efficiency vs Battery Voltage with No External Load (P_{BAT}/P_{BUS})

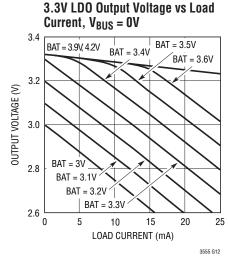


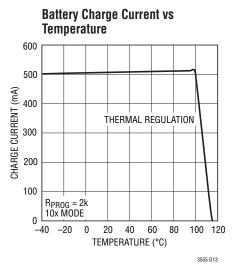
V_{BUS} Current vs V_{BUS} Voltage (Suspend)

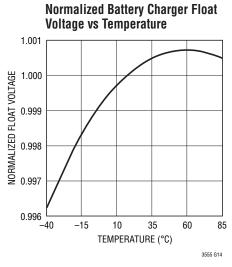


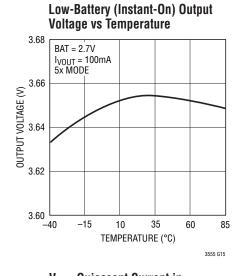


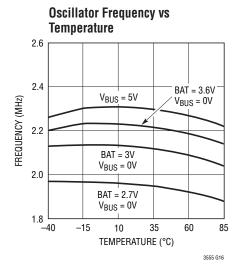


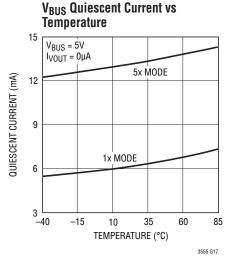


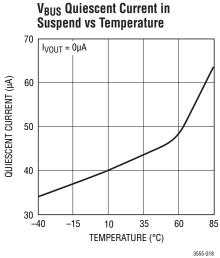


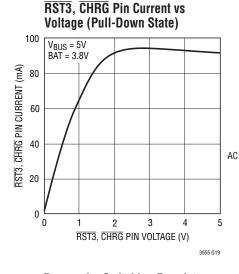




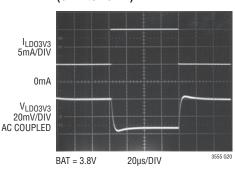




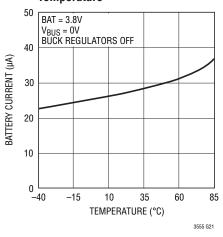




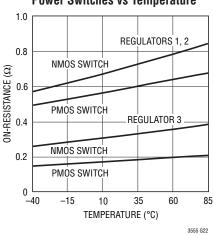
3.3V LDO Step Response (5mA to 15mA)



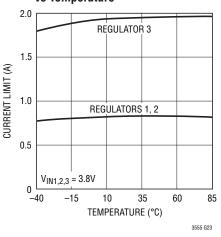
Battery Drain Current vs Temperature



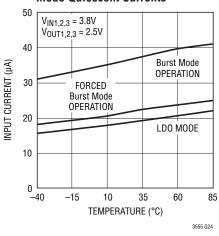
R_{DS(ON)} for Switching Regulator Power Switches vs Temperature



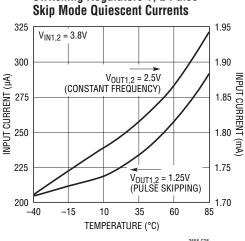
Switching Regulator Current Limit vs Temperature



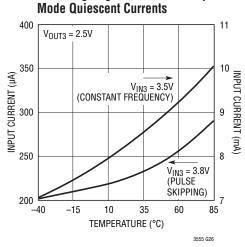
Switching Regulator Low Power Mode Quiescent Currents



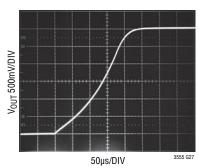
Switching Regulators 1, 2 Pulse Skin Mode Quiescent Currents



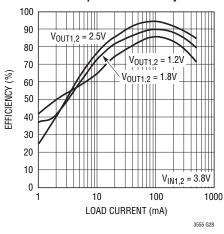
Switching Regulator 3 Pulse Skip



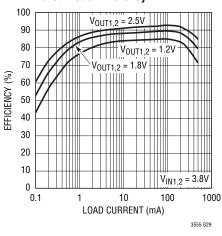
Switching Regulator Soft-Start Waveform



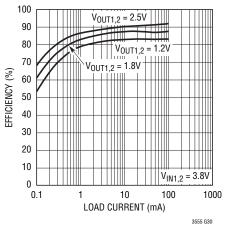




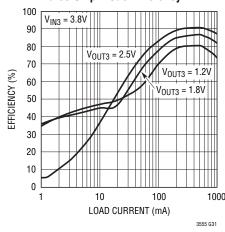
Switching Regulators 1, 2 Burst Mode Efficiency



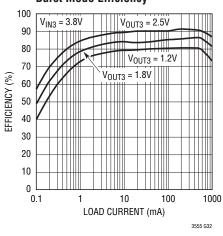
Switching Regulators 1, 2 Forced Burst Mode Efficiency



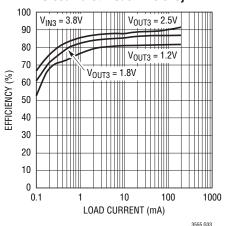
Switching Regulator 3
Pulse Skip Mode Efficiency



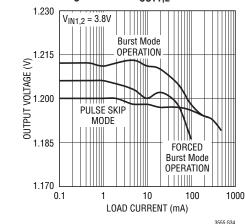
Switching Regulator 3 Burst Mode Efficiency



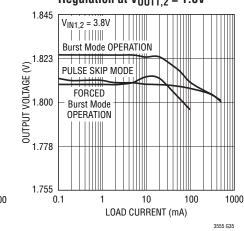
Switching Regulator 3
Forced Burst Mode Efficiency



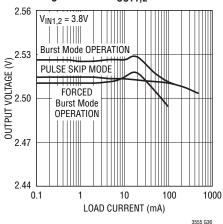
Switching Regulators 1, 2 Load Regulation at V_{OUT1.2} = 1.2V



Switching Regulators 1, 2 Load Regulation at $V_{OUT1,2} = 1.8V$



Switching Regulators 1, 2 Load Regulation at $V_{OUT1.2} = 2.5V$





PIN FUNCTIONS

LD03V3 (Pin 1): 3.3V LD0 Output Pin. This pin provides a regulated always-on 3.3V supply voltage. LD03V3 gets its power from V_{OUT} . It may be used for light loads such as a watchdog microprocessor or real time clock. A 1 μ F capacitor is required from LD03V3 to ground. If the LD03V3 output is not used it should be disabled by connecting it to V_{OUT} .

CLPROG (Pin 2): USB Current Limit Program and Monitor Pin. A resistor from CLPROG to ground determines the upper limit of the current drawn from the V_{BUS} pin. A fraction of the V_{BUS} current is sent to the CLPROG pin when the synchronous switch of the PowerPath switching regulator is on. The switching regulator delivers power until the CLPROG pin reaches 1.188V. Several V_{BUS} current limit settings are available via user input which will typically correspond to the 500mA and 100mA USB specifications. A multi-layer ceramic averaging capacitor or R-C network is required at CLPROG for filtering.

NTC (Pin 3): Input to the Thermistor Monitoring Circuits. The NTC pin connects to a battery's thermistor to determine if the battery is too hot or too cold to charge. If the battery's temperature is out of range, charging is paused until it re-enters the valid range. A low drift bias resistor is required from V_{BUS} to NTC and a thermistor is required from NTC to ground. If the NTC function is not desired, the NTC pin should be grounded.

FB2 (**Pin 4**): Feedback Input for Switching Regulator 2. When regulator 2's control loop is complete, this pin servos to 1 of 16 possible set-points based on the commanded value from the I²C serial port. See Table 4.

 V_{IN2} (Pin 5): Power Input for Switching Regulator 2. This pin will generally be connected to V_{OUT} . A 1 μ F MLCC capacitor is recommended on this pin.

SW2 (**Pin 6**): Power Transmission Pin for Switching Regulator 2.

EN2 (Pin 7): Logic Input. This logic input pin independently enables switching regulator 2. This pin is logically OR-ed with its corresponding bit in the I²C serial port. See Table 2.

 DV_{CC} (Pin 8): Logic Supply for the I^2C Serial Port. If the serial port is not needed it can be disabled by grounding DV_{CC} . When DV_{CC} is grounded, chip control is automatically passed to the individual logic input pins.

SCL (**Pin 9**): Clock Input Pin for the I 2 C Serial Port. The I 2 C logic levels are scaled with respect to DV $_{CC}$. If DV $_{CC}$ is grounded, the SCL pin is equivalent to the B5 bit in the I 2 C serial port. SCL in conjunction with SDA determine the operating modes of switching regulators 1, 2 and 3 when DV $_{CC}$ is grounded. See Tables 2 and 5.

SDA (Pin 10): Data Input Pin for the I^2C Serial Port. The I^2C logic levels are scaled with respect to DV_{CC} . If DV_{CC} is grounded, the SDA pin is equivalent to the B6 bit in the I^2C serial port. SDA in conjunction with SCL determine the operating modes of switching regulators 1, 2 and 3 when DV_{CC} is grounded. See Tables 2 and 5.

 V_{IN3} (Pin 11): Power Input for Switching Regulator 3. This pin will generally be connected to V_{OUT} . A 1 μ F MLCC capacitor is recommended on this pin.

SW3 (Pin 12): Power Transmission Pin for Switching Regulator 3.

EN3 (Pin 13): Logic Input. This logic input pin independently enables switching regulator 3. This pin is logically OR-ed with its corresponding bit in the I²C serial port. See Table 2.

FB3 (Pin 14): Feedback Input for Switching Regulator 3. When regulator 3's control loop is complete, this pin servos to 1 of 16 possible set-points based on the commanded value from the I²C serial port. See Table 4.

RST3 (**Pin 15**): Logic Output. This in an open-drain output which indicates that switching regulator 3 has settled to its final value. It can be used as a power-on reset for the primary microprocessor or to enable the other switching regulators for supply sequencing.

EN1 (Pin 16): Logic Input. This logic input pin independently enables switching regulator 1. This pin is logically OR-ed with its corresponding bit in the I²C serial port. See Table 2.



PIN FUNCTIONS

SW1 (Pin 17): Power Transmission Pin for Switching Regulator 1.

 V_{IN1} (Pin 18): Power Input for Switching Regulator 1. This pin will generally be connected to V_{OUT} . A 1 μ F MLCC capacitor is recommended on this pin.

FB1 (Pin 19): Feedback Input for Switching Regulator 1. When regulator 1's control loop is complete, this pin servos to a fixed voltage of 0.8V.

PROG (Pin 20): Charge Current Program and Charge Current Monitor Pin. Connecting a resistor from PROG to ground programs the charge current. If sufficient input power is available in constant-current mode, this pin servos to 1V. The voltage on this pin always represents the actual charge current.

CHRG (Pin 21): Open-Drain Charge Status Output. The CHRG pin indicates the status of the battery charger. Four possible states are represented by CHRG: charging, not charging, unresponsive battery and battery temperature out of range. CHRG is modulated at 35kHz and switches between a low and a high duty cycle for easy recognition by either humans or microprocessors. See Table 1. CHRG requires a pull-up resistor and/or LED to provide indication.

GATE (Pin 22): Analog Output. This pin controls the gate of an optional external P-channel MOSFET transistor used to supplement the ideal diode between V_{OUT} and BAT. The external ideal diode operates in parallel with the internal ideal diode. The source of the P-channel MOSFET should be connected to V_{OUT} and the drain should be connected to BAT. If the external ideal diode FET is not used, GATE should be left floating.

BAT (Pin 23): Single Cell Li-Ion Battery Pin. Depending on available V_{BUS} power, a Li-Ion battery on BAT will either deliver power to V_{OUT} through the ideal diode or be charged from V_{OUT} via the battery charger.

 V_{OUT} (Pin 24): Output voltage of the Switching PowerPath Controller and Input Voltage of the Battery Charger. The majority of the portable product should be powered from V_{OUT} . The LTC3555 family will partition the available power between the external load on V_{OUT} and the internal battery charger. Priority is given to the external load and any extra power is used to charge the battery. An ideal diode from BAT to V_{OUT} ensures that V_{OUT} is powered even if the load exceeds the allotted power from V_{BUS} or if the V_{BUS} power source is removed. V_{OUT} should be bypassed with a low impedance ceramic capacitor.

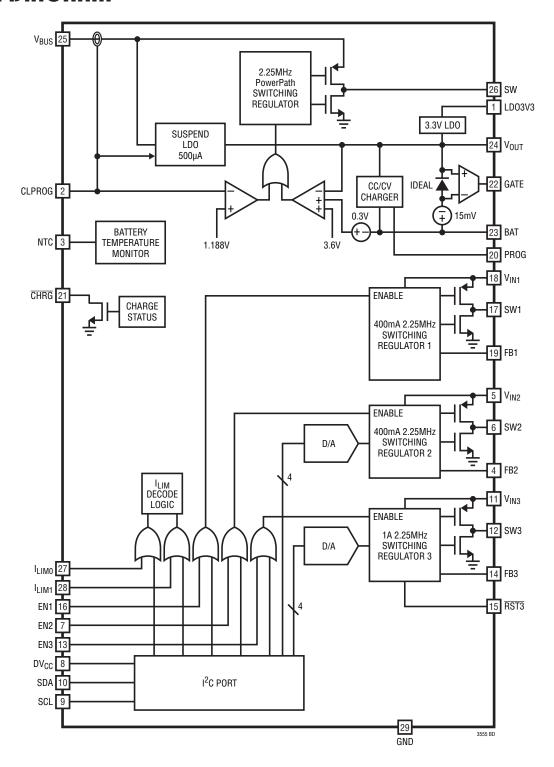
V_{BUS} (**Pin 25**): Primary Input Power Pin. This pin delivers power to V_{OUT} via the SW pin by drawing controlled current from a DC source such as a USB port or wall adapter.

SW (**Pin 26**): Power Transmission Pin for the USB Power Path. The SW pin delivers power from V_{BUS} to V_{OUT} via the step-down switching regulator. A 3.3µH inductor should be connected from SW to V_{OUT} .

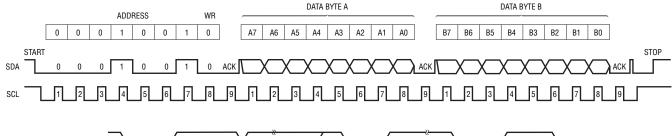
 I_{LIM0} , I_{LIM1} (Pins 27, 28): Logic Inputs. I_{LIM0} and I_{LIM1} control the current limit of the PowerPath switching regulator. See Table 3. Both of the I_{LIM0} and I_{LIM1} pins are logically OR-ed with their corresponding bits in the I^2C serial port. See Table 2.

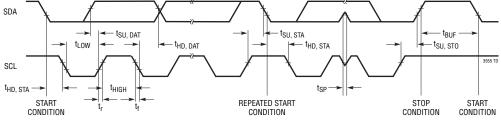
Exposed Pad (Pin 29): Ground. The Exposed Pad should be connected to a continuous ground plane on the second layer of the printed circuit board by several vias directly under the part.

BLOCK DIAGRAM



TIMING DIAGRAM





Introduction

The LTC3555 family are highly integrated power management ICs which include a high efficiency switch mode PowerPath controller, a battery charger, an ideal diode, an always-on LDO and three general purpose step-down switching regulators. The entire chip is controlled by either direct digital control, by an I²C serial port or both.

Designed specifically for USB applications, the PowerPath controller incorporates a precision average input current step-down switching regulator to make maximum use of the allowable USB power. Because power is conserved, the LTC3555 family allows the load current on V_{OUT} to exceed the current drawn by the USB port without exceeding the USB load specifications.

The PowerPath switching regulator and battery charger communicate to ensure that the input current never violates the USB specifications.

The ideal diode from BAT to V_{OUT} guarantees that ample power is always available to V_{OUT} even if there is insufficient or absent power at V_{BUS} .

An "always on" LDO provides a regulated 3.3V from available power at V_{OUT} . Drawing very little quiescent current, this LDO will be on at all times and can be used to supply up to 25mA.

The three general purpose switching regulators can be independently enabled via either direct digital control or by operating the I²C serial port. Under I²C control, two of the three switching regulators have adjustable set-points so that voltages can be reduced when high processor performance is not needed. Along with constant frequency PWM mode, all three switching regulators have a low power burst-only mode setting as well as automatic Burst Mode operation and LDO modes for significantly reduced quiescent current under light load conditions.

High Efficiency Switching PowerPath Controller

Whenever V_{BUS} is available and the PowerPath switching regulator is enabled, power is delivered from V_{BUS} to V_{OUT} via SW. V_{OUT} drives the combination of the external load (switching regulators 1, 2 and 3) and the battery charger.

If the combined load does not exceed the PowerPath switching regulator's programmed input current limit, V_{OUT} will track 0.3V above the battery. By keeping the voltage across the battery charger low, efficiency is optimized because power lost to the linear battery charger is minimized. Power available to the external load is therefore optimized.



If the combined load at V_{OUT} is large enough to cause the switching power supply to reach the programmed input current limit, the battery charger will reduce its charge current by that amount necessary to enable the external load to be satisfied. Even if the battery charge current is set to exceed the allowable USB current, the USB specification will not be violated. The switching regulator will limit the average input current so that the USB specification is never violated. Furthermore, load current at V_{OUT} will always be prioritized and only excess available power will be used to charge the battery.

If the voltage at BAT is below 3.3V, or the battery is not present, and the load requirement does not cause the switching regulator to exceed the USB specification, V_{OUT} will regulate at 3.6V. If the load exceeds the available power, V_{OUT} will drop to a voltage between 3.6V and the battery voltage. If there is no battery present when the load exceeds the available USB power, V_{OUT} can drop toward ground.

The power delivered from V_{BUS} to V_{OUT} is controlled by a 2.25MHz constant-frequency step-down switching regulator. To meet the USB maximum load specification, the switching regulator includes a control loop which ensures that the average input current is below the level programmed at CLPROG.

The current at CLPROG is a fraction (h_{CLPROG}^{-1}) of the V_{BUS} current. When a programming resistor and an averaging capacitor are connected from CLPROG to GND, the voltage on CLPROG represents the average input current of the switching regulator. When the input current approaches the programmed limit, CLPROG reaches V_{CLPROG} , 1.188V, and power out is held constant. The input current limit is programmed by the I_{LIMO} and I_{LIM1} pins or by the I^2C serial port. It can be configured to limit average input current to one of several possible settings as well as be deactivated (USB suspend). The input current limit will be set by the V_{CLPROG} servo voltage and the resistor on CLPROG according to the following expression:

$$I_{VBUS} = I_{VBUSQ} + \frac{V_{CLPROG}}{R_{CLPROG}} \bullet (h_{CLPROG} + 1)$$

Figure 1 shows the range of possible voltages at V_{OUT} as a function of battery voltage.

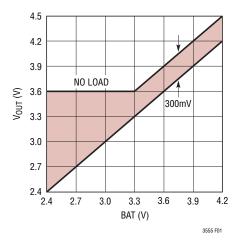


Figure 1. Vollt vs BAT

The LTC3555 vs the LTC3555-1 and LTC3555-3

For very low battery voltages, the battery charger acts like a load and, due to limited input power, its current will tend to pull V_{OUT} below the 3.6V "instant-on" voltage. To prevent V_{OUT} from falling below this level, the LTC3555-1 and LTC3555-3 include an undervoltage circuit that automatic detects that V_{OUT} is falling and reduces the battery charge current as needed. This reduction ensures that load current and output voltage are always prioritized and yet delivers as much battery charge current as possible. The standard LTC3555 does not include this circuit and thus favors maximum charge current at all times over output voltage preservation.

If instant-on operation under low battery conditions is a requirement then the LTC3555-1 or LTC3555-3 should be used. If maximum charge efficiency at low battery voltages is preferred, and instant-on operation is not a requirement, then the standard LTC3555 should be selected. All versions of the LTC3555 family will start up with a removed battery.

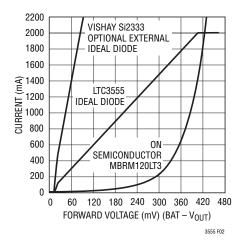
The LTC3555-3 has a battery charger float voltage of 4.100V rather than the 4.200V float voltage of the LTC3555 and LTC3555-1.

Ideal Diode from BAT to V_{OUT}

The LTC3555 family has an internal ideal diode as well as a controller for an optional external ideal diode. The ideal diode controller is always on and will respond quickly whenever V_{OUT} drops below BAT.

LINEAR TECHNOLOGY

If the load current increases beyond the power allowed from the switching regulator, additional power will be pulled from the battery via the ideal diode. Furthermore, if power to V_{BUS} (USB or wall power) is removed, then all of the application power will be provided by the battery via the ideal diode. The transition from input power to battery power at V_{OUT} will be quick enough to allow only the $10\mu F$ capacitor to keep V_{OUT} from drooping. The ideal diode consists of a precision amplifier that enables a large on-chip P-channel MOSFET transistor whenever the voltage at V_{OUT} is approximately 15mV (V_{FWD}) below the voltage



at BAT. The resistance of the internal ideal diode is approximately $180m\Omega$. If this is sufficient for the application, then no external components are necessary. However, if more conductance is needed, an external P-channel MOSFET transistor can be added from BAT to V_{OUT} .

When an external P-channel MOSFET transistor is present, the GATE pin of the LTC3555 family drives its gate for automatic ideal diode control. The source of the external P-channel MOSFET should be connected to V_{OUT} and the drain should be connected to BAT. Capable of driving a 1nF load, the GATE pin can control an external P-channel MOSFET transistor having an on-resistance of $40m\Omega$ or lower.

Suspend LDO

If the LTC3555 family is configured for USB suspend mode, the switching regulator is disabled and the suspend LDO provides power to the V_{OUT} pin (presuming there is power available to V_{BUS}). This LDO will prevent the battery from running down when the portable product has access to a suspended USB port. Regulating at 4.6V, this LDO only becomes active when the switching converter is disabled (suspended). To remain compliant with the USB specification, the input to the LDO is current limited so that it will not exceed the 500 μ A low power suspend

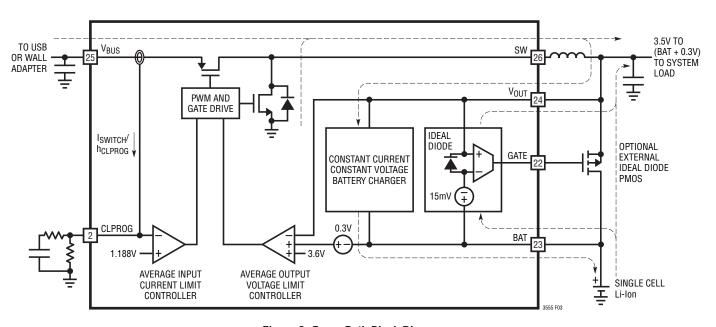


Figure 3. PowerPath Block Diagram





specification. If the load on V_{OUT} exceeds the suspend current limit, the additional current will come from the battery via the ideal diode.

3.3V Always-On LDO Supply

The LTC3555 family includes a low quiescent current low dropout regulator that is always powered. This LDO can be used to provide power to a system pushbutton controller, standby microcontroller or real time clock. Designed to deliver up to 25mA, the always-on LDO requires at least a 1 μ F low impedance ceramic bypass capacitor for compensation. The LDO is powered from V_{OUT}, and therefore will enter dropout at loads less than 25mA as V_{OUT} falls near 3.3V. If the LDO3V3 output is not used, it should be disabled by connecting it to V_{OUT}.

V_{BUS} Undervoltage Lockout (UVLO)

An internal undervoltage lockout circuit monitors V_{BUS} and keeps the PowerPath switching regulator off until V_{BUS} rises above 4.30V and is about 200mV above the battery voltage. Hysteresis on the UVLO turns off the regulator if V_{BUS} drops below 4.00V or to within 50mV of BAT. When this happens, system power at V_{OUT} will be drawn from the battery via the ideal diode.

Battery Charger

The LTC3555 family includes a constant-current/constant-voltage battery charger with automatic recharge, automatic termination by safety timer, low voltage trickle charging, bad cell detection and thermistor sensor input for out-of-temperature charge pausing.

Battery Preconditioning

When a battery charge cycle begins, the battery charger first determines if the battery is deeply discharged. If the battery voltage is below V_{TRKL} , typically 2.85V, an automatic trickle charge feature sets the battery charge current to 10% of the programmed value. If the low voltage persists for more than 1/2 hour, the battery charger automatically terminates and indicates via the \overline{CHRG} pin that the battery was unresponsive.

Once the battery voltage is above 2.85V, the battery charger begins charging in full power constant-current mode. The

current delivered to the battery will try to reach 1022V/ R_{PROG}. Depending on available input power and external load conditions, the battery charger may or may not be able to charge at the full programmed rate. The external load will always be prioritized over the battery charge current. The USB current limit programming will always be observed and only additional power will be available to charge the battery. When system loads are light, battery charge current will be maximized.

Charge Termination

The battery charger has a built-in safety timer. When the voltage on the battery reaches the pre-programmed float voltage, the battery charger will regulate the battery voltage and the charge current will decrease naturally. Once the battery charger detects that the battery has reached the float voltage, the four hour safety timer is started. After the safety timer expires, charging of the battery will discontinue and no more current will be delivered.

Automatic Recharge

After the battery charger terminates, it will remain off drawing only microamperes of current from the battery. If the portable product remains in this state long enough, the battery will eventually self discharge. To ensure that the battery is always topped off, a charge cycle will automatically begin when the battery voltage falls below the recharge threshold which is typically 100mV less than the charger's float voltage. In the event that the safety timer is running when the battery voltage falls below the recharge threshold, it will reset back to zero. To prevent brief excursions below the recharge threshold from resetting the safety timer, the battery voltage must be below the recharge threshold for more than 1.3ms. The charge cycle and safety timer will also restart if the V_{BUS} UVLO cycles low and then high (e.g., V_{BLIS} is removed and then replaced), or if the battery charger is cycled on and off by the I²C port.

Charge Current

The charge current is programmed using a single resistor from PROG to ground. 1/1022th of the battery charge current is sent to PROG which will attempt to servo to 1.000V. Thus, the battery charge current will try to reach



1022 times the current in the PROG pin. The program resistor and the charge current are calculated using the following equations:

$$R_{PROG} = \frac{1022V}{I_{CHG}}, I_{CHG} = \frac{1022V}{R_{PROG}}$$

In either the constant-current or constant-voltage charging modes, the voltage at the PROG pin will be proportional to the actual charge current delivered to the battery. Therefore, the actual charge current can be determined at any time by monitoring the PROG pin voltage and using the following equation:

$$I_{BAT} = \frac{V_{PROG}}{R_{PROG}} \bullet 1022$$

In many cases, the actual battery charge current, I_{BAT} , will be lower than I_{CHG} due to limited input power available and prioritization with the system load drawn from V_{OUT} .

Charge Status Indication

The CHRG pin indicates the status of the battery charger. Four possible states are represented by CHRG which include charging, not charging, unresponsive battery, and battery temperature out of range.

The signal at the $\overline{\text{CHRG}}$ pin can be easily recognized as one of the above four states by either a human or a microprocessor. An open-drain output, the $\overline{\text{CHRG}}$ pin can drive an indicator LED through a current limiting resistor for human interfacing or simply a pull-up resistor for microprocessor interfacing.

To make the CHRG pin easily recognized by both humans and microprocessors, the pin is either low for charging, high for not charging, or it is switched at high frequency (35kHz) to indicate the two possible faults, unresponsive battery and battery temperature out of range.

When charging begins, CHRG is pulled low and remains low for the duration of a normal charge cycle. When charging is complete, i.e., the BAT pin reaches the float voltage and the charge current has dropped to one tenth of the programmed value, the CHRG pin is released (Hi-Z). If a fault occurs, the pin is switched at 35kHz. While switching, its duty cycle is modulated between a low and high value at a very low frequency. The low and high

duty cycles are disparate enough to make an LED appear to be on or off thus giving the appearance of "blinking". Each of the two faults has its own unique "blink" rate for human recognition as well as two unique duty cycles for machine recognition.

The $\overline{\text{CHRG}}$ pin does not respond to the C/10 threshold if the LTC3555 family is in V_{BUS} current limit. This prevents false end-of-charge indications due to insufficient power available to the battery charger.

Table 1 illustrates the four possible states of the CHRG pin when the battery charger is active.

Table 1. CHRG Signal

STATUS	FREQUENCY	MODULATION (BLINK) FREQUENCY	DUTY CYCLES
Charging	0Hz	0Hz (Lo-Z)	100%
Not Charging	0Hz	0Hz (Hi-Z)	0%
NTC Fault	35kHz	1.5Hz at 50%	6.25% to 93.75%
Bad Battery	35kHz	6.1Hz at 50%	12.5% to 87.5%

An NTC fault is represented by a 35kHz pulse train whose duty cycle varies between 6.25% and 93.75% at a 1.5Hz rate. A human will easily recognize the 1.5Hz rate as a "slow" blinking which indicates the out-of-range battery temperature while a microprocessor will be able to decode either the 6.25% or 93.75% duty cycles as an NTC fault.

If a battery is found to be unresponsive to charging (i.e., its voltage remains below 2.85V for 1/2 hour), the $\overline{\text{CHRG}}$ pin gives the battery fault indication. For this fault, a human would easily recognize the frantic 6.1Hz "fast" blink of the LED while a microprocessor would be able to decode either the 12.5% or 87.5% duty cycles as a bad battery fault.

Note that the LTC3555 family is a three terminal PowerPath product where system load is always prioritized over battery charging. Due to excessive system load, there may not be sufficient power to charge the battery beyond the trickle charge threshold voltage within the bad battery timeout period. In this case, the battery charger will falsely indicate a bad battery. System software may then reduce the load and reset the battery charger to try again.

Although very improbable, it is possible that a duty cycle reading could be taken at the bright-dim transition (low duty cycle to high duty cycle). When this happens the



duty cycle reading will be precisely 50%. If the duty cycle reading is 50%, system software should disqualify it and take a new duty cycle reading.

NTC Thermistor

The battery temperature is measured by placing a negative temperature coefficient (NTC) thermistor close to the battery pack.

To use this feature, connect the NTC thermistor, R_{NTC} , between the NTC pin and ground and a resistor, R_{NOM} , from V_{BUS} to the NTC pin. R_{NOM} should be a 1% resistor with a value equal to the value of the chosen NTC thermistor at 25°C (R25). For applications requiring greater than 750mA of charging current, a 10k NTC thermistor is recommended due to increased interference.

The LTC3555 family will pause charging when the resistance of the NTC thermistor drops to 0.54 times the value of R25 or approximately 5.4k. For a Vishay "Curve 1" thermistor, this corresponds to approximately 40°C. If the battery charger is in constant voltage (float) mode, the safety timer also pauses until the thermistor indicates a return to a valid temperature. As the temperature drops, the resistance of the NTC thermistor rises. The LTC3555 family is also designed to pause charging when the value of the NTC thermistor increases to 3.25 times the value of R25. For Vishay "Curve 1" this resistance, 32.5k, corresponds to approximately 0°C. The hot and cold comparators each have approximately 3°C of hysteresis to prevent oscillation about the trip point. Grounding the NTC pin disables the NTC charge pausing function.

Thermal Regulation

To optimize charging time, an internal thermal feedback loop may automatically decrease the programmed charge current. This will occur if the die temperature rises to approximately 110°C. Thermal regulation protects the LTC3555 family from excessive temperature due to high power operation or high ambient thermal conditions and allows the user to push the limits of the power handling capability with a given circuit board design without risk of damaging the part or external components. The benefit of the LTC3555 family thermal regulation loop is that charge current can be set according to actual conditions rather

than worst-case conditions with the assurance that the battery charger will automatically reduce the current in worst-case conditions.

I²C Interface

The LTC3555 family may receive commands from a host (master) using the standard I 2 C2-wire interface. The Timing Diagram shows the timing relationship of the signals on the bus. The two bus lines, SDA and SCL, must be high when the bus is not in use. External pull-up resistors or current sources, such as the LTC1694 I 2 C accelerator, are required on these lines. The LTC3555 family is a receive-only slave device. The I 2 C control signals, SDA and SCL are scaled internally to the DV $_{CC}$ supply. DV $_{CC}$ should be connected to the same power supply as the microcontroller generating the I 2 C signals.

The I 2 C port has an undervoltage lockout on the DV $_{CC}$ pin. When DV $_{CC}$ is below approximately 1V, the I 2 C serial port is cleared and switching regulators 2 and 3 are set to full scale.

Bus Speed

The I^2C port is designed to be operated at speeds of up to 400kHz. It has built-in timing delays to ensure correct operation when addressed from an I^2C compliant master device. It also contains input filters designed to suppress glitches should the bus become corrupted.

Start and Stop Conditions

A bus-master signals the beginning of a communication to a slave device by transmitting a START condition. A START condition is generated by transitioning SDA from high to low while SCL is high. When the master has finished communicating with the slave, it issues a STOP condition by transitioning SDA from low to high while SCL is high.

Byte Format

Each byte sent to the LTC3555 family must be eight bits long followed by an extra clock cycle for the acknowledge bit to be returned by the LTC3555 family. The data should be sent to the LTC3555 family most significant bit (MSB) first.

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Table 2. I²C Serial Port Mapping

A7	A6	A5	A4	A3	A2	A1	A0	B7	В6	B5	B4	В3	B2	B1	B0
	vitching I oltage (S				vitching I oltage (S	0		Disable Battery Charger	Switc Regul Mod (See Ta	ator les	Enable Regulator 1	Enable Regulator 2	Enable Regulator 3	Lir	Current nit able 3)

Table 3. USB Current Limit Settings

B1 (I _{LIM1})	BO (I _{LIMO})	USB SETTING
0	0	1x Mode (USB 100mA Limit)
0	1	10x Mode (Wall 1A Limit)
1	0	Suspend
1	1	5x Mode (USB 500mA Limit)

Table 4. Switching Regulator Servo Voltage

ר טועטו	. Owito	iiiiig iit	guiuto	i ocivo voltago
A 7	A6	A5	A4	Switching Regulator 2 Servo Voltage
А3	A2	A1	A0	Switching Regulator 3 Servo Voltage
0	0	0	0	0.425V
0	0	0	1	0.450V
0	0	1	0	0.475V
0	0	1	1	0.500V
0	1	0	0	0.525V
0	1	0	1	0.550V
0	1	1	0	0.575V
0	1	1	1	0.600V
1	0	0	0	0.625V
1	0	0	1	0.650V
1	0	1	0	0.675V
1	0	1	1	0.700V
1	1	0	0	0.725V
1	1	0	1	0.750V
1	1	1	0	0.775V
1	1	1	1	0.800V
	_			

Table 5. General Purpose Switching Regulator Modes

B6 (SDA)*	B5 (SCL)*	Switching Regulator Mode
0	0	Pulse Skip
0	1	Forced Burst Mode Operation
1	0	LDO Mode
1	1	Burst Mode Operation

^{*}SDA and SCL take on this context only when $DV_{CC} = 0V$.

Acknowledge

The acknowledge signal is used for handshaking between the master and the slave. An acknowledge (active low) generated by the slave (LTC3555 family) lets the master know that the latest byte of information was received. The acknowledge related clock pulse is generated by the master. The master releases the SDA line (high) during the acknowledge clock cycle. The slave-receiver must pull down the SDA line during the acknowledge clock pulse so that it remains a stable low during the high period of this clock pulse.

Slave Address

The LTC3555 family responds to only one 7-bit address which has been factory programmed to 0001001. The eighth bit of the address byte (R/W) must be 0 for the LTC3555 family to recognize the address since it is a write only device. This effectively forces the address to be eight bits long where the least significant bit of the address is 0. If the correct seven bit address is given but the R/W bit is 1, the LTC3555 family will not respond.

Bus Write Operation

The master initiates communication with the LTC3555 family with a START condition and a 7-bit address followed by the write bit R/W = 0. If the address matches that of the LTC3555 family, the LTC3555 family returns an acknowledge. The master should then deliver the most significant data byte. Again the LTC3555 family acknowledges and the cycle is repeated for a total of one address byte and two data bytes. Each data byte is transferred to an internal holding latch upon the return of an acknowledge. After both data bytes have been transferred to the LTC3555 family, the master may terminate the communication with a STOP condition. Alternatively, a REPEAT-START condition can be initiated by the master and another chip on the $\rm I^2C$ bus can be addressed. This cycle can continue indefinitely and

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the LTC3555 family will remember the last input of valid data that it received. Once all chips on the bus have been addressed and sent valid data, a global STOP condition can be sent and the LTC3555 family will update its command latch with the data that it had received.

In certain circumstances the data on the I²C bus may become corrupted. In these cases the LTC3555 family responds appropriately by preserving only the last set of complete data that it has received. For example, assume the LTC3555 family has been successfully addressed and is receiving data when a STOP condition mistakenly occurs. The LTC3555 family will ignore this STOP condition and will not respond until a new START condition, correct address, new set of data and STOP condition are transmitted.

Likewise, with only one exception, if the LTC3555 family was previously addressed and sent valid data but not updated with a STOP, it will respond to any STOP that appears on the bus, independent of the number of REPEAT-STARTS that have occurred. If a REPEAT-START is given and the LTC3555 family successfully acknowledges its address and first byte, it will not respond to a STOP until both bytes of the new data have been received and acknowledged.

Disabling the I²C Port

The I^2C serial port can be disabled by grounding the DV_{CC} pin. In this mode, control automatically passes to the individual logic input pins EN1, EN2, EN3, I_{LIM0} , I_{LIM1} , SDA and SCL. Some functionality is not available in this mode such as the programmability of switching regulators 2 and 3's output voltage and the battery charger disable feature. In this mode, both of the programmable switching regulators have a fixed servo voltage of 0.8V.

Because the SDA and SCL pins have no other context when DV_CC is grounded, these pins are re-mapped to control the switching regulator mode bits B5 and B6. SCL maps to B5 and SDA maps to B6.

RST3 Pin

The $\overline{\text{RST3}}$ pin is an open-drain output used to indicate that switching regulator 3 has reached its final voltage. $\overline{\text{RST3}}$

remains low impedance until regulator 3 reaches 92% of its regulation value. A 230ms delay is included to allow a system microcontroller ample time to reset itself. RST3 may be used as a power-on reset to the microprocessor powered by regulator 3 or may be used to enable regulators 1 and/or 2 for supply sequencing. RST3 is an open-drain output and requires a pull-up resistor to the output voltage of regulator 3 or another appropriate power source.

General Purpose Step-Down Switching Regulators

The LTC3555 family contains three general purpose 2.25MHz step-down constant-frequency current mode switching regulators. Two regulators provide up to 400mA and a third switching regulator can produce up to 1A. All three switching regulators can be programmed for a minimum output voltage of 0.8V and can be used to power a microcontroller core, microcontroller I/O, memory, disk drive or other logic circuitry. Two of the switching regulators have I²C programmable set-points for on-the-fly power savings. All three converters support 100% duty cycle operation (low dropout mode) when their input voltage drops very close to their output voltage. To suit a variety of applications, selectable mode functions can be used to trade-off noise for efficiency. Four modes are available to control the operation of the LTC3555 family's general purpose switching regulators. At moderate to heavy loads, the pulse skip mode provides the least noise switching solution. At lighter loads, either Burst Mode operation, forced Burst Mode operation or LDO mode may be selected. The switching regulators include soft-start to limit inrush current when powering on, short-circuit current protection and switch node slew limiting circuitry to reduce radiated EMI. No external compensation components are required. The operating mode of the regulators may be set by either I²C control or by manual control of the SDA and SCL pins if the I^2C port is not used. Each converter may be individually enabled by either their external control pins EN1, EN2, EN3 or by the I²C port. Switching regulators 2 and 3 have individual programmable feedback servo voltages via I²C control. The switching regulator input supplies V_{IN1} , V_{IN2} and V_{IN3} will generally be connected to the system load pin V_{OUT} .



Step-Down Switching Regulator Output Voltage Programming

All three switching regulators can be programmed for output voltages greater than 0.8V. Switching regulators 2 and 3 have I²C programmable set-points while regulator 1 has a single fixed set-point. The full-scale output voltage for each switching regulator is programmed using a resistor divider from the switching regulator output connected to the feedback pins (FB1, FB2 and FB3) such that:

$$V_{OUTX} = V_{FBX} \left(\frac{R1}{R2} + 1 \right)$$

where V_{FBX} ranges from 0.425V to 0.8V for switching regulators 2 and 3 and V_{FBX} is fixed at 0.8V for switching regulator 1. See Figure 4

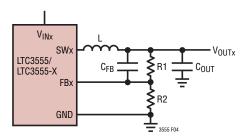


Figure 4. Buck Converter Application Circuit

Typical values for R1 are in the range of 40k to 1M. The capacitor C_{FB} cancels the pole created by feedback resistors and the input capacitance of the FB pin and also helps to improve transient response for output voltages much greater than 0.8V. A variety of capacitor sizes can be used for C_{FB} but a value of 10pF is recommended for most applications. Experimentation with capacitor sizes between 2pF and 22pF may yield improved transient response.

Step-Down Switching Regulator Operating Modes

The LTC3555 family's general purpose switching regulators include four possible operating modes to meet the noise/power needs of a variety of applications.

In pulse skip mode, an internal latch is set at the start of every cycle which turns on the main P-channel MOSFET switch. During each cycle, a current comparator compares the peak inductor current to the output of an error amplifier. The output of the current comparator resets the internal

latch which causes the main P-channel MOSFET switch to turn off and the N-channel MOSFET synchronous rectifier to turn on. The N-channel MOSFET synchronous rectifier turns off at the end of the 2.25MHz cycle or if the current through the N-channel MOSFET synchronous rectifier drops to zero. Using this method of operation, the error amplifier adjusts the peak inductor current to deliver the required output power. All necessary compensation is internal to the switching regulator requiring only a single ceramic output capacitor for stability. At light loads in PWM mode, the inductor current may reach zero on each pulse which will turn off the N-channel MOSFET synchronous rectifier. In this case, the switch node (SW) goes high impedance and the switch node voltage will "ring". This is discontinuous mode operation, and is normal behavior for a switching regulator. At very light loads in pulse skip mode, the switching regulators will automatically skip pulses as needed to maintain output regulation.

At high duty cycles ($V_{OUTx} > V_{INx}/2$) it is possible for the inductor current to reverse, causing the regulator to operate continuously at light loads. This is normal and regulation is maintained, but the supply current will increase to several milliamperes due to continuous switching.

In forced Burst Mode operation, the switching regulators use a constant current algorithm to control the inductor current. By controlling the inductor current directly and using a hysteretic control loop, both noise and switching losses are minimized. In this mode output power is limited. While in forced Burst Mode operation, the output capacitor is charged to a voltage slightly higher than the regulation point. The step-down converter then goes into sleep mode. during which the output capacitor provides the load current. In sleep mode, most of the regulator's circuitry is powered down, helping conserve battery power. When the output voltage drops below a pre-determined value, the switching regulator circuitry is powered on and another burst cycle begins. The duration for which the regulator operates in sleep mode depends on the load current. The sleep time decreases as the load current increases. The maximum output current in forced Burst Mode operation is about 100mA for switching regulators 1 and 2, and about 250mA for switching regulator 3. The step-down switching regulators will not enter sleep mode if the maximum output current is exceeded in forced Burst Mode operation and



the output will drop out of regulation. Forced Burst Mode operation provides a significant improvement in efficiency at light loads at the expense of higher output ripple when compared to pulse skip mode. For many noise-sensitive systems, forced Burst Mode operation might be undesirable at certain times (i.e., during a transmit or receive cycle of a wireless device), but highly desirable at others (i.e., when the device is in low power standby mode). The I²C port can be used to enable or disable forced Burst Mode operation at any time, offering both low noise and low power operation when they are needed.

In Burst Mode operation, the switching regulator automatically switches between fixed frequency PWM operation and hysteretic control as a function of the load current. At light loads, the regulators operate in hysteretic mode in much the same way as described for the forced Burst Mode operation. Burst Mode operation provides slightly less output ripple at the expense of slightly lower efficiency than forced Burst Mode operation. At heavy loads the switching regulator operates in the same manner as pulse skip operation at high loads. For applications that can tolerate some output ripple at low output currents, Burst Mode operation provides better efficiency than pulse skip at light loads while still providing the full specified output current of the switching regulator.

Finally, the switching regulators have an LDO mode that gives a DC option for regulating their output voltages. In LDO mode, the switching regulators are converted to linear regulators and deliver continuous power from their SWx pins through their respective inductors. This mode gives the lowest possible output noise as well as low quiescent current at light loads.

The step-down switching regulators allow mode transition on the fly, providing seamless transition between modes even under load. This allows the user to switch back and forth between modes to reduce output ripple or increase low current efficiency as needed.

Step-Down Switching Regulator in Shutdown

The step-down switching regulators are in shutdown when not enabled for operation. In shutdown, all circuitry in the step-down switching regulator is disconnected from the switching regulator input supply leaving only a few nanoamperes of leakage current. The step-down switching regulator outputs are individually pulled to ground through a 10k resistor on the switch pins (SW1-SW3) when in shutdown.

General Purpose Switching Regulator Dropout Operation

It is possible for a switching regulator's input voltage, V_{INx} , to approach its programmed output voltage (e.g., a battery voltage of 3.4V with a programmed output voltage of 3.3V). When this happens, the PMOS switch duty cycle increases until it is turned on continuously at 100%. In this dropout condition, the respective output voltage equals the regulator's input voltage minus the voltage drops across the internal P-channel MOSFET and the inductor.

Step-Down Switching Regulator Soft-Start Operation

Soft-start is accomplished by gradually increasing the peak inductor current for each switching regulator over a 500µs period. This allows each output to rise slowly, helping minimize the battery surge current. A soft-start cycle occurs whenever a given switching regulator is enabled, or after a fault condition has occurred (thermal shutdown or UVLO). A soft-start cycle is not triggered by changing operating modes. This allows seamless output operation when transitioning between forced Burst Mode, Burst Mode, pulse skip mode or LDO operation.

Step-Down Switching Regulator Switching Slew Rate Control

The step-down switching regulators contain new patent pending circuitry to limit the slew rate of the switch nodes (SWx). This new circuitry is designed to transition the switch nodes over a period of a couple of nanoseconds, significantly reducing radiated EMI and conducted supply noise.

Low Supply Operation

The LTC3555 family incorporates an undervoltage lockout circuit on V_{OUT} which shuts down the general purpose switching regulators when V_{OUT} drops below $V_{OUTUVLO}$. This UVLO prevents unstable operation.

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APPLICATIONS INFORMATION

CLPROG Resistor and Capacitor

As described in the High Efficiency Switching PowerPath Controller section, the resistor on the CLPROG pin determines the average input current limit when the switching regulator is set to either the 1x mode (USB 100mA), the 5x mode (USB 500mA) or the 10x mode. The input current will be comprised of two components, the current that is used to drive V_{OUT} and the quiescent current of the switching regulator. To ensure that the USB specification is strictly met, both components of input current should be considered. The Electrical Characteristics table gives values for quiescent currents in either setting as well as current limit programming accuracy. To get as close to the 500mA or 100mA specifications as possible, a 1% resistor should be used. Recall that

An averaging capacitor or an R-C combination is required in parallel with the CLPROG resistor so that the switching regulator can determine the average input current. This network also provides the dominant pole for the feedback loop when current limit is reached. To ensure stability, the capacitor on CLPROG should be $0.47\mu F$ or larger. Alternatively, faster transient response may be achieved with $0.1\mu F$ in series with 8.2Ω .

Choosing the PowerPath Inductor

Because the average input current circuit does not measure reverse current (i.e., current from SW to V_{BUS}), current reversal in the inductor at light loads will contribute an error to the average V_{BUS} current measurement. The error is conservative in that if the current reverses, the voltage at CLPROG will be higher than what would represent the actual average input current drawn. The current available for battery charging plus system load is thus reduced but the USB specification will not be violated.

This reduction in available V_{BUS} current will happen when the peak-peak inductor ripple is greater than twice the average current limit setting. For example, if the average current limit is set to 100mA, the peak-peak ripple should not exceed 200mA. If the input current is less than 100mA, the measurement accuracy may be reduced. However, this will not affect the average current loop since it will not be in regulation.

The LTC3555 family includes a current-reversal comparator which monitors inductor current and disables the synchronous rectifier as current approaches zero. This comparator will minimize the effect of current reversal on the average input current measurement. For some low inductance values, however, the inductor current may still reverse slightly. This value depends on the speed of the comparator in relation to the slope of the current waveform, given by V_L/L . V_L is the voltage across the inductor (approximately $-V_{OLIT}$) and L is the inductance value.

An inductance value of 3.3µH is a good starting value. The ripple will be small enough for the regulator to remain in continuous conduction at 100mA average V_{BUS} current. At lighter loads the current-reversal comparator will disable the synchronous rectifier for currents slightly above 0mA. As the inductance is reduced from this value, the LTC3555 family will enter discontinuous conduction mode at progressively higher loads. Ripple at V_{OUT} will increase directly proportionally to the magnitude of inductor ripple. Transient response, however, will improve. The current mode controller controls inductor current to exactly the amount required by the load to keep V_{OLIT} in regulation. A transient load step requires the inductor current to change to a new level. Since inductor current cannot change instantaneously, the capacitance on V_{OUT} delivers or absorbs the difference in current until the inductor current can change to meet the new load demand. A smaller inductor changes its current more quickly for a given voltage drive than a larger inductor, resulting in faster transient response. A larger inductor will reduce output ripple and current ripple. but at the expense of reduced transient performance and a physically larger inductor package size. For this reason a larger C_{VOLIT} will be required for larger inductor sizes.

The input regulator has an instantaneous peak current clamp to prevent the inductor from saturating during transient load or start-up conditions. The clamp is designed so that it does not interfere with normal operation at high loads and reasonable inductor ripple. It is intended to prevent inductor current runaway in case of a shorted output.

The DC winding resistance and AC core losses of the inductor will affect efficiency, and therefore available output power. These effects are difficult to characterize and vary

