



Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from,Europe,America and south Asia,supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of “Quality Parts,Customers Priority,Honest Operation,and Considerate Service”,our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip,ALPS,ROHM,Xilinx,Pulse,ON,Everlight and Freescale. Main products comprise IC,Modules,Potentiometer,IC Socket,Relay,Connector.Our parts cover such applications as commercial,industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



# Quad Network Power Controller with I<sup>2</sup>C Compatible Interface

## FEATURES

- Controls Four Independent –48V Power Channels
- Each Channel has Separate Relay Drivers, ON/OFF Control, Short-Circuit Protection with Current Foldback, Open-Circuit Detection, and Power Good Indication
- Programmed via I<sup>2</sup>C™ Compatible Interface
- Five Bit Programmable Digital Address Allows Control of up to 32 LTC4255s (128 Channels)
- Interrupt on FAULT Output can be used to Eliminate Software Polling
- Programmable Current Limit and Open-Circuit Duration Periods
- Programmable Latchoff or Autoretry after Short-Circuit Faults
- Programmable Autoretry Duty Cycle

## APPLICATIONS

- IP Phone Systems
- DTE Power Distribution

## DESCRIPTION

The LTC<sup>®</sup>4255 is a quad –48V network power controller with independent relay drivers and I<sup>2</sup>C compatible interface. Each channel can be turned on and off via software control, while providing short-circuit protection, open-circuit detection, and power good indication. The short-circuit protection includes a current foldback feature to reduce power dissipation in the switch during shorts and start-up.

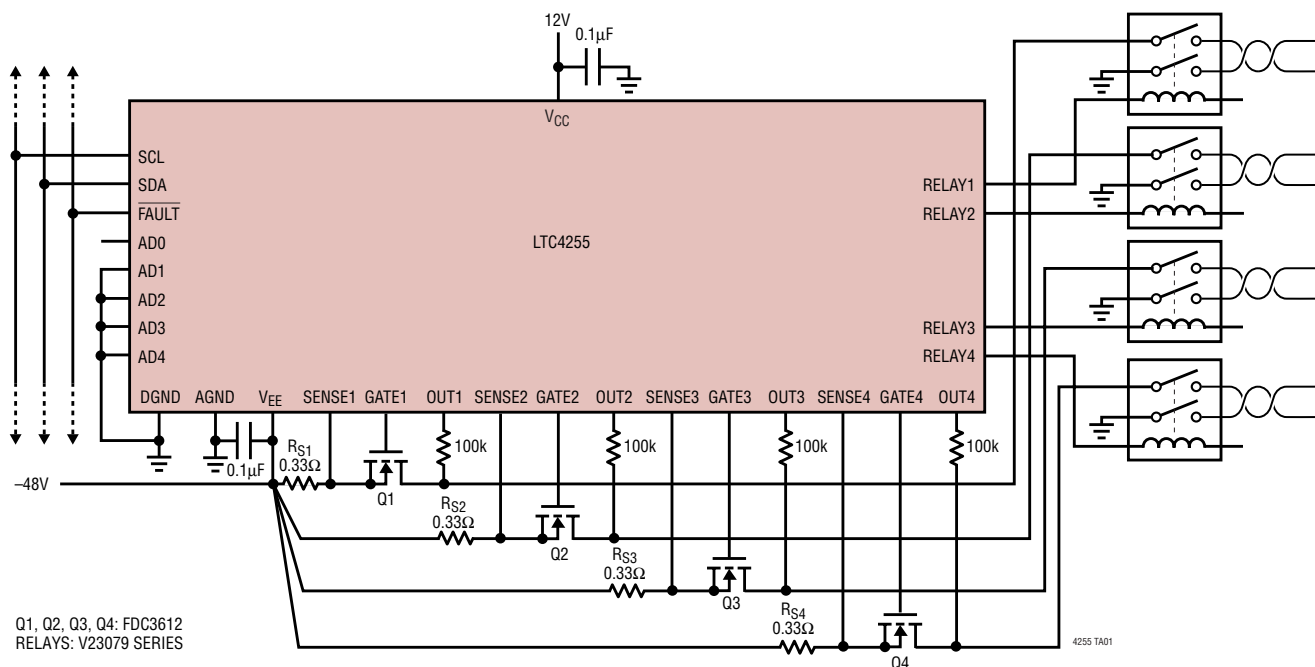
The serial interface allows up to 128 channels to be controlled with only two digital lines. A FAULT output can be used as an interrupt line to eliminate fault detection by software polling.

External switches and current sense resistors allow easy scaling of current and power dissipation levels and provide the maximum protection against voltage and current spikes.

The LTC4255 is available in the 28-pin SSOP package.

LTC, LTC and LT are registered trademarks of Linear Technology Corporation. I<sup>2</sup>C is a trademark of Philips Electronics N.V.

## TYPICAL APPLICATION



## ABSOLUTE MAXIMUM RATINGS

(Note 1)

### Supply Voltages

$V_{CC}$ to DGND	18V
$V_{EE}$ to AGND	-80V
DGND to AGND	$\pm 5V$

### Digital Pin Voltages

SCL, SDA, FAULT	DGND - 0.3V to 6V
AD0-4	DGND - 0.3V to 5.5V

### Relay Driver Output Voltage

RELAY1-4 (Note 5)	DGND - 0.3V to DGND + 15V
-------------------	---------------------------

### Analog Voltages

SENSE1-4	$V_{EE} - 0.3V$ to $V_{EE} + 1V$
OUT1-4	$V_{EE} - 80V$ to $V_{EE} + 80V$

### Operating Temperature Range

LTC4255C	0°C to 70°C
----------	-------------

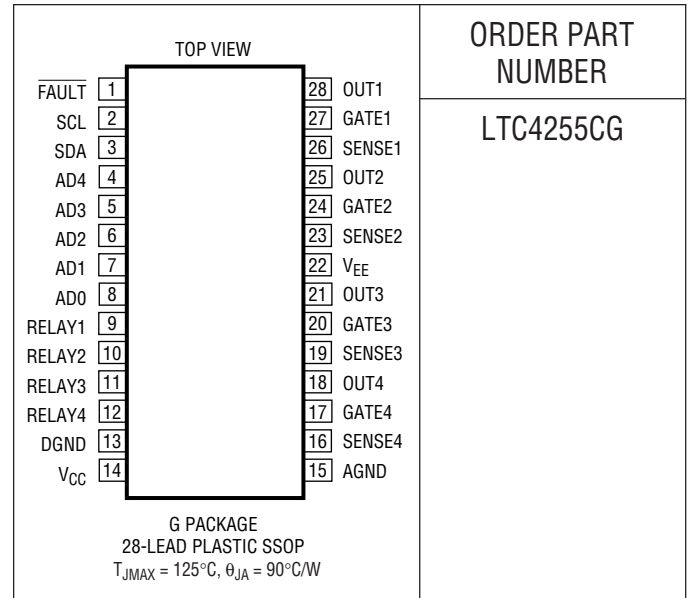
### Storage Temperature Range

	-65°C to 150°C
--	----------------

### Lead Temperature (Soldering, 10 sec)

	300°C
--	-------

## PACKAGE/ORDER INFORMATION



ORDER PART NUMBER

LTC4255CG

Consult LTC Marketing for parts specified with wider operating temperature ranges.

## ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ C$ .  $V_{CC} = 12V$ ,  $V_{EE} = -48V$ ,  $AGND = DGND = 0V$  (Note 2)

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
<b>DC Characteristics</b>						
$V_{CC}$	Positive Supply Voltage	$V_{CC}$ Referenced to DGND	10.8	12	13.2	V
$I_{CC}$	Positive Supply Current	Relays Off All Relays On		2.1 10	3 15	mA mA
$V_{EE}$	Negative Supply Voltage	$V_{EE}$ Referenced to AGND		-48	-72	V
$I_{EE}$	Negative Supply Current			-1.9	-3	mA
$\Delta V_{GND}$	DC Ground Difference	AGND - DGND (Note 3)	-5		5	V
$V_{LKO}$	$V_{EE}$ Undervoltage Lockout			-27		V
$\Delta V_{GATE}$	External Gate Voltage ( $V_{GATE} - V_{EE}$ )	$I_{GATE} = -1\mu A$	10	13	15	V
$I_{GATE}$	GATE Pin Output Current	GATE On, $V_{GATE} = V_{EE}$ GATE Off, $V_{GATE} = V_{EE} + 5V$	-30 30	-50 50	-70 80	$\mu A$ $\mu A$
$V_{SC}$	Short-Circuit Sense Voltage	$(V_{SENSE} - V_{EE})$ , $V_{OUT} - V_{EE} = 0V$	● 125	150	170	mV
$V_{OC}$	Open-Circuit Sense Voltage	$(V_{SENSE} - V_{EE})$	● 1	3	4.5	mV
$V_{PG}$	Power_OK Threshold Voltage	$(V_{OUT} - V_{EE})$	● 1	2	3	V
$I_{OUT}$	OUT Pin Current	$V_{OUT} = V_{EE}$		-1.4		$\mu A$
$V_{OLR}$	Relay Driver Output Low Voltage	$(V_{RELAY} - DGND)$ , $I_{RELAY} = 50mA$ , RELAY On			0.3	V
$V_{CLAMPR}$	Relay Driver Clamp Voltage	$(V_{RELAY} - DGND)$ , $I_{RELAY} = 50mA$ , RELAY Off (Note 5)		18	24	V
$V_{OLD}$	Digital Output Low Voltage	SDA, FAULT, $I = 3mA$	●		0.4	V



## ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ .  $V_{CC} = 12\text{V}$ ,  $V_{EE} = -48\text{V}$ ,  $\text{AGND} = \text{DGND} = 0\text{V}$

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
$V_{ILD}$	Digital Input Low Voltage	SCL, SDA	●		0.8	V
$V_{IHD}$	Digital Input High Voltage	SCL, SDA	●	2.4		V
$R_{PU}$	AD0 to AD4 Pullup Resistors to 5V		30	50	90	k $\Omega$

### AC Characteristics

$t_{CL}$	Current Limit Filter Time	B5 = 0, B4 = 0, Figure 2	●	4.8	6	7.2	ms
		B5 = 0, B4 = 1	●	9.6	12	14.4	ms
		B5 = 1, B4 = 0	●	19.2	24	28.8	ms
		B5 = 1, B4 = 1	●	76.8	96	115.2	ms
$t_{OCD}$	Open-Circuit Enable Delay After Power_OK	B7 = 0, B6 = 0	●	50	62	74	ms
		B7 = 0, B6 = 1	●	104	130	156	ms
		B7 = 1, B6 = 0	●	213	267	320	ms
		B7 = 1, B6 = 1	●	433	541	649	ms
$t_{OCF}$	Open-Circuit Filter Time	Figure 3	●	9.6	18	28.8	ms
$t_{OD}$	Turn-On Delay Time	Figure 4	●	9.6	18	28.8	ms
$DC_R$	Retry Duty Cycle	B3 = 0	●	0.78	0.83	0.89	%
		B3 = 1	●	5.5	6	6.7	%
$t_{SCLK}$	Clock Frequency	(Note 3)	●		400	kHz	
$t_1$	Bus Free Time	Figure 1 (Notes 3, 4)	●	1.3		$\mu\text{s}$	
$t_2$	Start Hold Time	Figure 1 (Notes 3, 4)	●	600		ns	
$t_3$	SCL Low Time	Figure 1 (Notes 3, 4)	●	1.3		$\mu\text{s}$	
$t_4$	SCL High Time	Figure 1 (Notes 3, 4)	●	600		ns	
$t_5$	Data Hold Time	Figure 1 (Notes 3, 4)	●	150		ns	
$t_6$	Data Setup Time	Figure 1 (Notes 3, 4)	●	200		ns	
$t_7$	Start Setup Time	Figure 1 (Notes 3, 4)	●	600		ns	
$t_8$	Stop Setup Time	Figure 1 (Notes 3, 4)	●	600		ns	
$t_9$	Stop to Fault Clear	Figure 1 (Notes 3, 4)	●		300	ns	
$t_r$	SCL, SDA Rise Time	Figure 1 (Notes 3, 4)	●	20	300	ns	
$t_f$	SCL, SDA Fall Time	Figure 1 (Notes 3, 4)	●	20	150	ns	

**Note 1:** Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

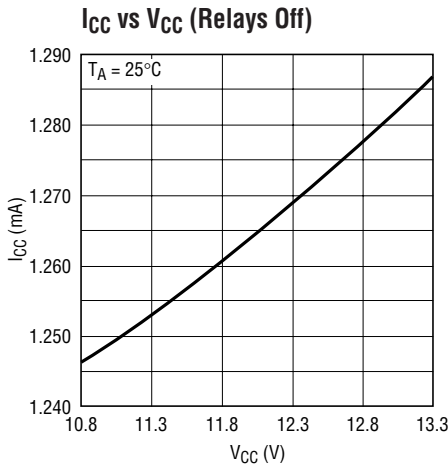
**Note 2:** All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to ground unless otherwise specified.

**Note 3:** Guaranteed by design, not subject to test.

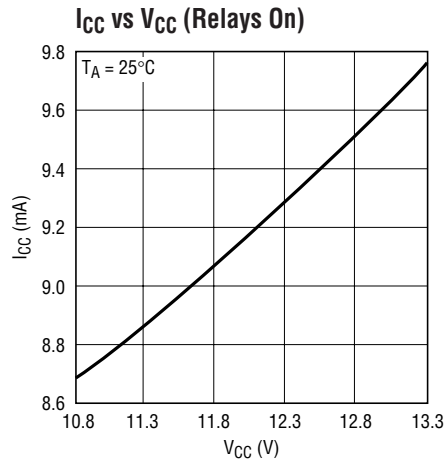
**Note 4:** Values referred to  $V_{ILD}$  and  $V_{IHD}$ .

**Note 5:** A Zener diode clamps the relay drivers at 18V (RELAY 1-4).

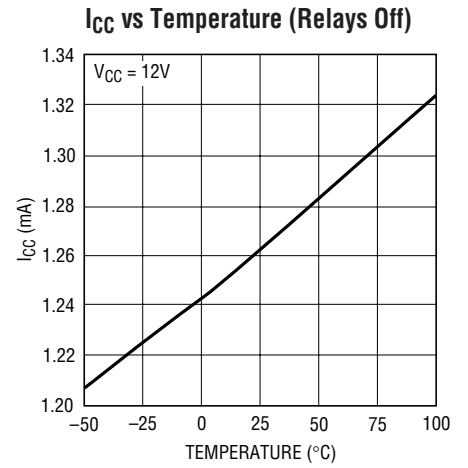
## TYPICAL PERFORMANCE CHARACTERISTICS



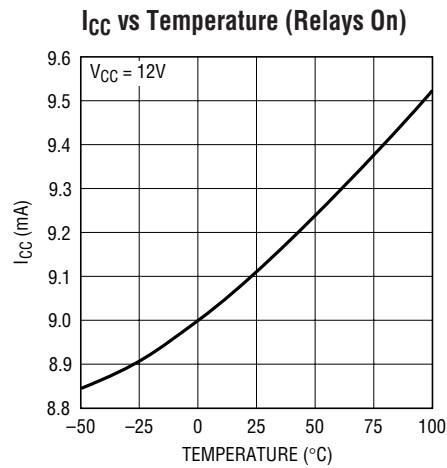
4255 G01



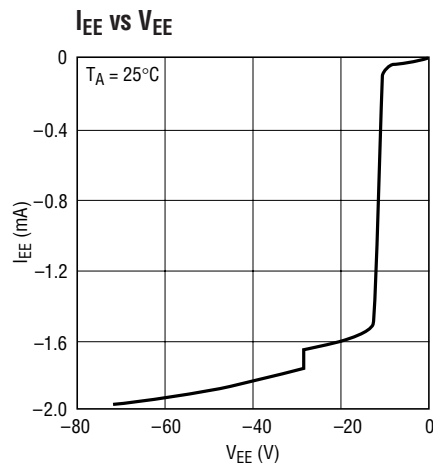
4255 G02



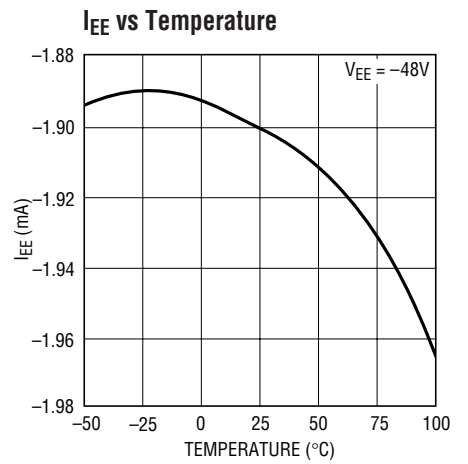
4255 G03



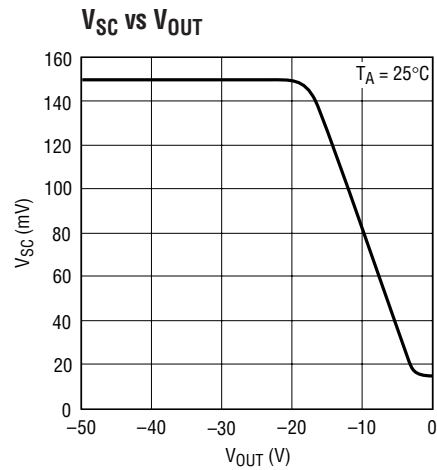
4255 G04



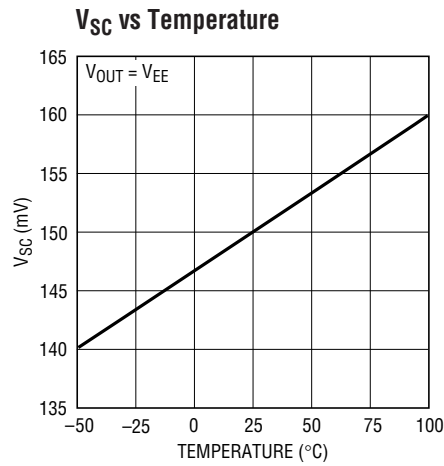
4255 G05



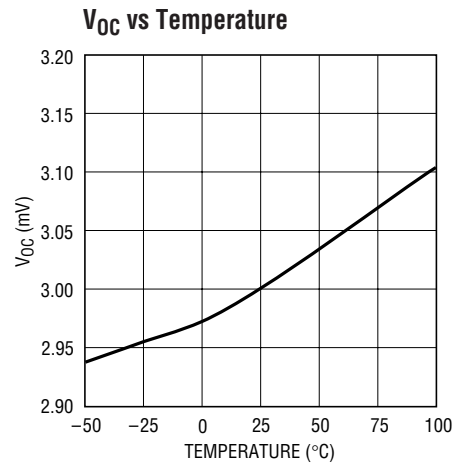
4255 G06



4255 G07

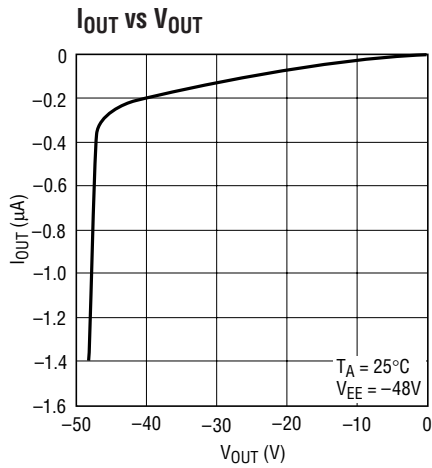


4255 G08

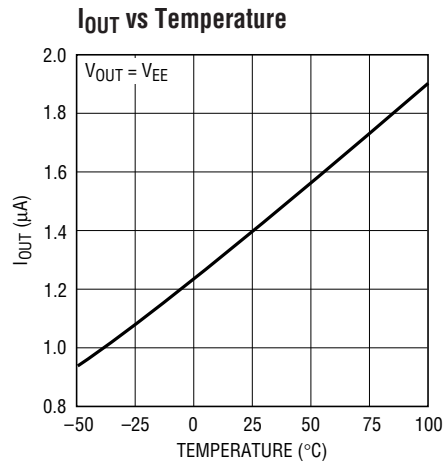


4255 G09

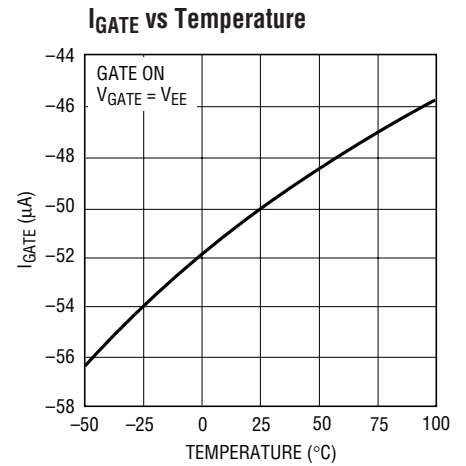
# TYPICAL PERFORMANCE CHARACTERISTICS



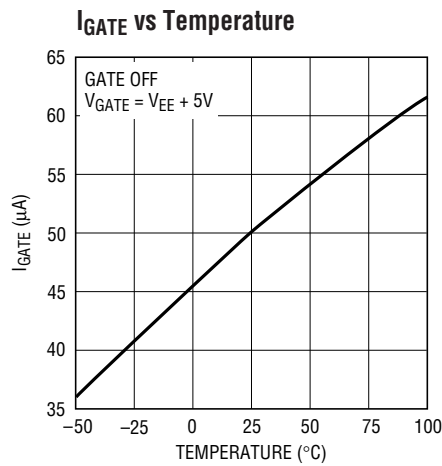
4255 G10



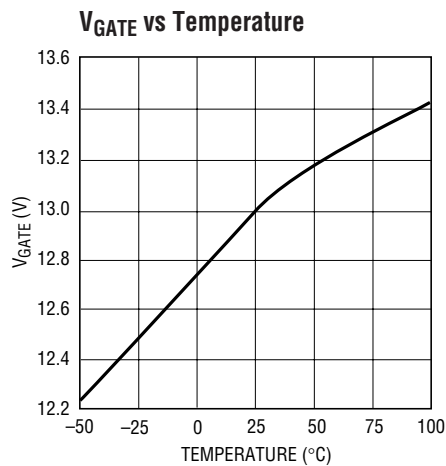
4255 G11



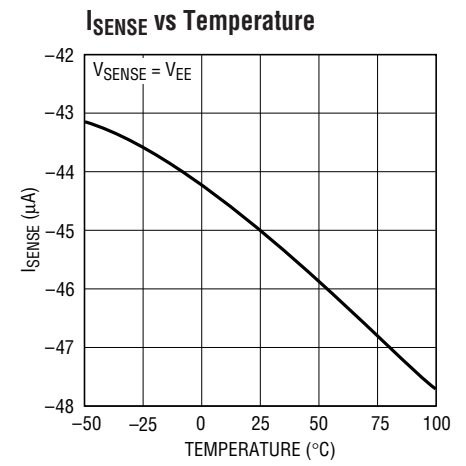
4255 G12



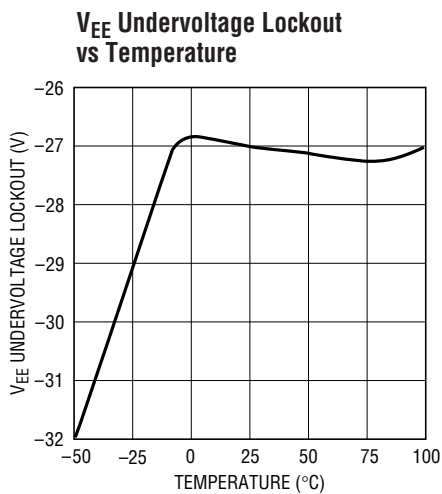
4255 G13



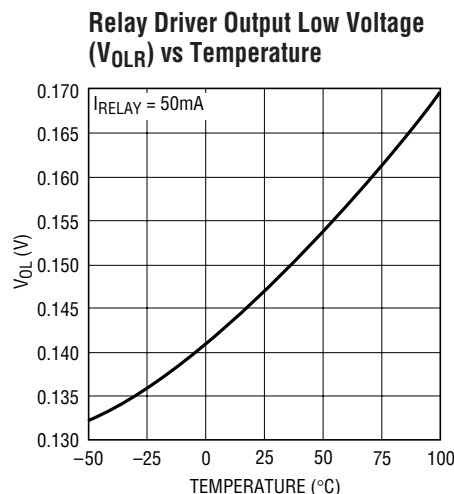
4255 G14



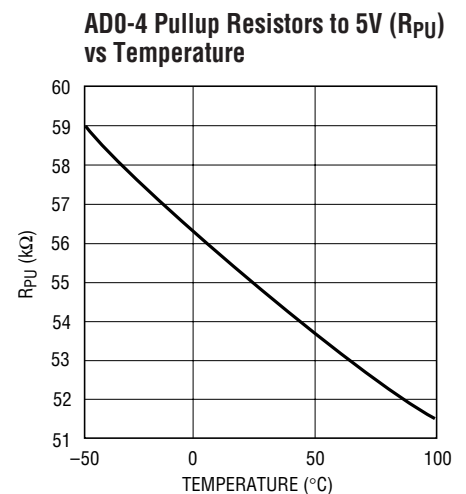
4255 G15



4255 G16



4255 G17



4255 G18

## PIN FUNCTIONS

**FAULT (Pin 1):** Open-Drain  $\overline{\text{FAULT}}$  Output. Pulls low when a short-circuit or open circuit fault occurs. The signal can be used to generate a fault condition interrupt to the host controller eliminating the need for continuous software polling.

**SCL (Pin 2):** Serial Interface Clock Input. It requires a resistor or current source that pulls up to a supply that is less than 6V.

**SDA (Pin 3):** Serial Interface Data Input and Output. It requires a resistor or current source that pulls up to a supply that is less than 6V.

**AD0-4 (Pins 4,5,6,7,8):** Serial Interface Address Inputs. Connect to DGND for a low, float or connect to 3.3V or 5V supply for a high.

**RELAY1-4 (Pins 9,10,11,12):** Relay Driver Outputs. Open collector capable of sinking 50mA to within 0.3V of DGND. An internal 18V clamp to DGND will protect the part when the relay is turned off.

**DGND (Pin 13):** Digital Ground. Return for digital logic and relay drivers. Must be within  $\pm 5V$  of AGND.

**V<sub>CC</sub> (Pin 14):** 12V Supply Input. Powers the digital section and relay drivers. Bypass with a 0.1 $\mu$ F capacitor to DGND.

**AGND (Pin 15):** Analog Ground.

**SENSE1-4 (Pins 16,19,23,26):** Current Sense Inputs. Monitors the FET current with a sense resistor placed

between SENSE and  $V_{EE}$ . When the voltage across the sense resistor reaches the short-circuit sense voltage, the GATE pin voltage will be lowered to maintain a constant current in the FET. At the same time, the current limit timer will be started. If the short-circuit condition persists for the duration of the current limit timer period, the FET will be turned off. The short-circuit sense voltage is lowered to reduce the FET power dissipation when the voltage at the associated OUT pin is within 18V of AGND.

If the open-circuit enable bit is set and the voltage across the sense resistor remains below the open-circuit sense voltage for longer than  $t_{OCF}$ , the open-circuit filter time, then the FET will be turned off.

**GATE1-4 (Pins 17,20,24,27):** Gate Drive Outputs. When the FET is turned on, a 50 $\mu$ A pull-up current source is connected to the pin. The gate voltage is clamped to 13V(typ) above  $V_{EE}$ . During a short-circuit condition, the GATE pin voltage will be driven to a lower voltage to maintain a constant current in the FET.

**OUT1-4 (Pins 18,21,25,28):** Output Voltage Monitor Inputs. A current limit foldback feature limits the power dissipation in the FET by reducing the short-circuit current when the voltage at the OUT pin is between AGND and AGND – 18V. The Power\_OK bit is set when the voltage from OUT to  $V_{EE}$  is less than about 2V.

**V<sub>EE</sub> (Pin 22):** –48V Supply Input.

## REGISTER DEFINITIONS

### Register 1: Control Register (Write Only)

**A0:** Switch 1 Enable. Logic high turns on Port 1 switch, logic low turns off the Port 1 switch.

**A1:** Switch 2 Enable. Logic high turns on Port 2 switch, logic low turns off Port 2 switch.

**A2:** Switch 3 Enable. Logic high turns on Port 3 switch, logic low turns off Port 3 switch.

**A3:** Switch 4 Enable. Logic high turns on Port 4 switch, logic low turns off Port 4 switch.

**A4:** Relay 1 Enable. Logic high turns on Port 1 relay, logic low turns off Port 1 relay.

**A5:** Relay 2 Enable. Logic high turns on Port 2 relay, logic low turns off Port 2 relay.

**A6:** Relay 3 Enable. Logic high turns on Port 3 relay, logic low turns off Port 3 relay.

**A7:** Relay 4 Enable. Logic high turns on Port 4 relay, logic low turns off Port 4 relay.

The default setting is all bits set low.

### Register 2: Setup Register (Write Only)

**B0:** Fault Clear Bit. Logic high clears any fault bits that are set.

**B1:** Autoretry Enable Bit. Logic high enables autoretry following short-circuit faults. Logic low disables autoretry.

**B2:** Open-Circuit Detect Enable Bit. Logic high enables and logic low disables open-circuit fault detection.

**B3:** Retry Duty Cycle Select Bit. Logic high sets the autoretry duty cycle to 6%. Logic low sets the autoretry duty cycle to 0.83%. When autoretry is not enabled (B1 = low), the switch turn-on after A0 to A3 are set to high will be delayed to enforce the selected retry duty cycle.

**B4:** Current Limit Timer Select Bit 0. The current limit timer select bits configure  $t_{CL}$ , the time a current limit must be sustained before a short-circuit fault occurs. (See  $t_{CL}$  in AC Characteristics.)

**B5:** Current Limit Timer Select Bit 1. The current limit timer select bits configure  $t_{CL}$ , the time a current limit must be sustained before a short-circuit fault occurs. (See  $t_{CL}$  in AC Characteristics.)

**B6:** Open-Circuit Enable Delay Timer Select Bit 0. The open-circuit enable delay timer select bits configure  $t_{OCD}$ , the time following a Power\_OK condition when no open-circuit faults will be generated. (See  $t_{OCD}$ , in AC Characteristics.)

**B7:** Open-Circuit Enable Delay Timer Select Bit 1. The open-circuit enable delay timer select bits configure  $t_{OCD}$ , the time following a Power\_OK condition when no open-circuit faults will be generated. (See  $t_{OCD}$ , in AC Characteristics.)

The default setting is all bits set low.

### Register 3: Status Register 1 (Read Only)

**C0:** Power\_OK for Port 1. Logic high indicates switch 1 is on.

**C1:** Power\_OK for Port 2. Logic high indicates switch 2 is on.

**C2:** Power\_OK for Port 3. Logic high indicates switch 3 is on.

**C3:** Power\_OK for Port 4. Logic high indicates switch 4 is on.

**C4:** Reserved. Logic high.

**C5:** Reserved. Logic low.

**C6:** Reserved. Logic low.

**C7:** Reserved. Logic low.



## REGISTER DEFINITIONS

### Register 4: Status Register 2 (Read Only)

**D0:** Current Limit Fault Status for Port 1. Logic high indicates a short-circuit has been detected on Port 1.

**D1:** Current Limit Fault Status for Port 2. Logic high indicates a short-circuit has been detected on Port 2.

**D2:** Current Limit Fault Status for Port 3. Logic high indicates a short-circuit has been detected on Port 3.

**D3:** Current Limit Fault Status for Port 4. Logic high indicates a short-circuit has been detected on Port 4.

**D4:** Open-Circuit Fault Status for Port 1. Logic high indicates an open-circuit has been detected on Port 1.

**D5:** Open-Circuit Fault Status for Port 2. Logic high indicates an open-circuit has been detected on Port 2.

**D6:** Open-Circuit Fault Status for Port 3. Logic high indicates an open-circuit has been detected on Port 3.

**D7:** Open-Circuit Fault Status for Port 4. Logic high indicates an open-circuit has been detected on Port 4.

## TEST TIMING

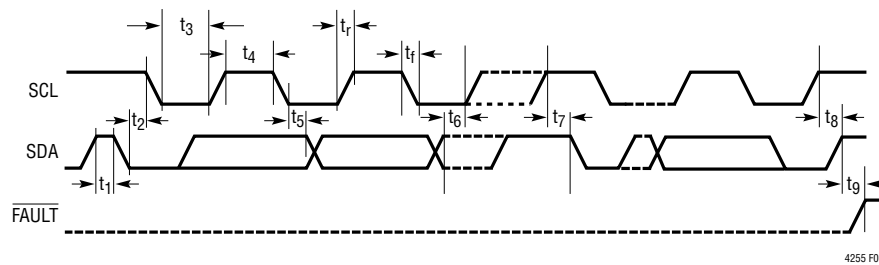


Figure 1. 2-Wire Interface Timing

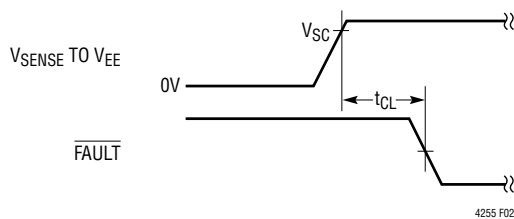


Figure 2. Current Limit Timing

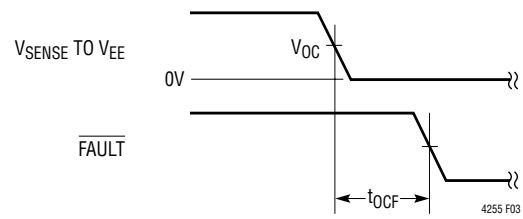


Figure 3. Open-Circuit Filter Timing

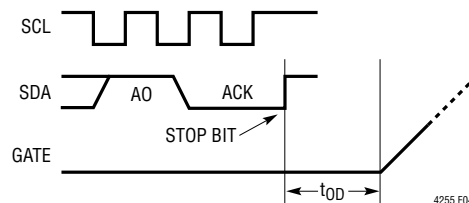


Figure 4. Turn-On Delay

# TIMING DIAGRAMS

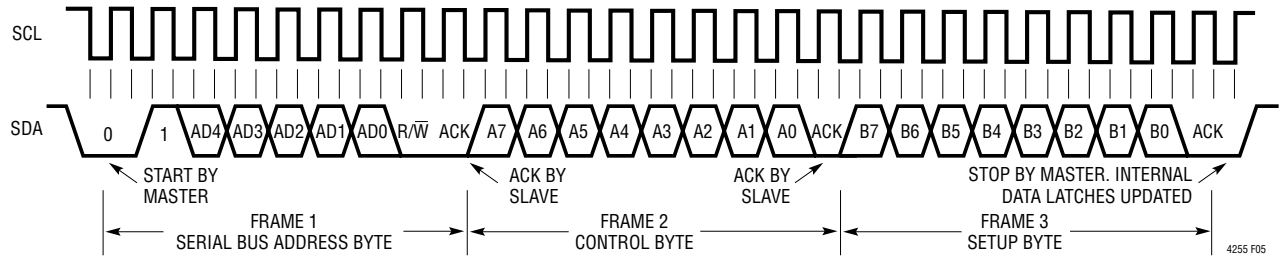


Figure 5. Writing to the Control and Setup Registers

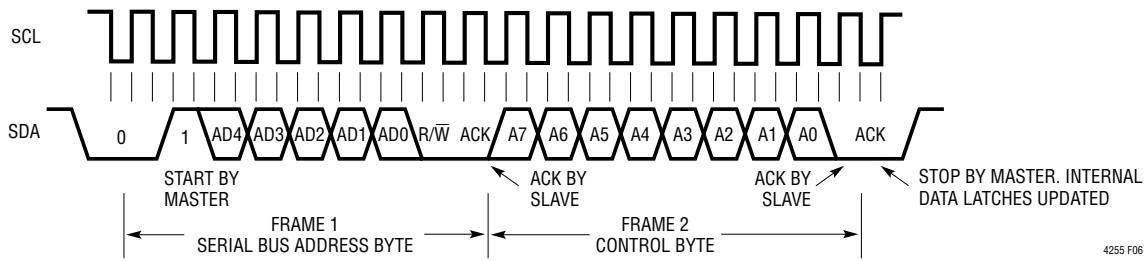


Figure 6. Writing to the Control Register Only

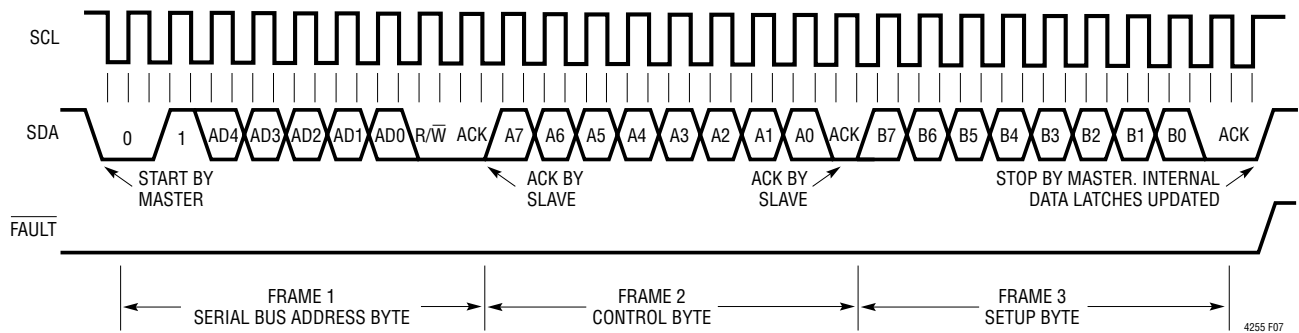


Figure 7. Clearing the FAULT Signal

## TIMING DIAGRAMS

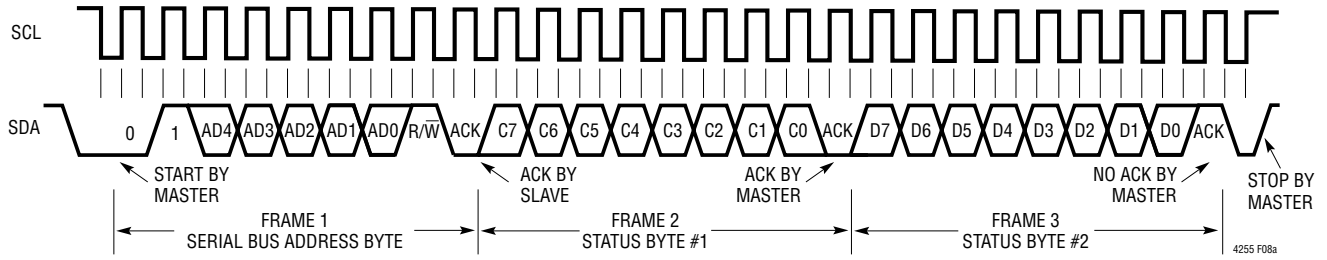


Figure 8a. Reading Both Status Registers

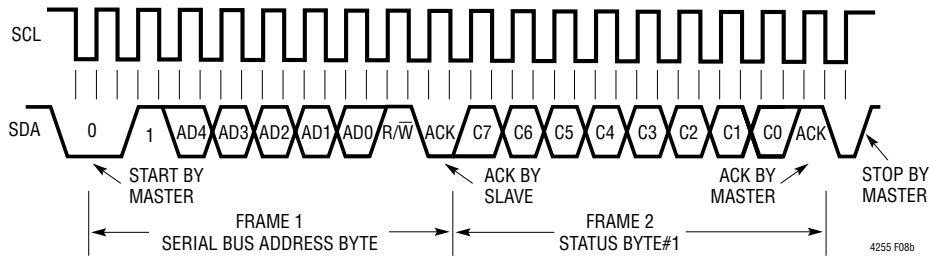


Figure 8b. Reading Status Register #1 Only

## APPLICATIONS INFORMATION

### Normal Power-Up

Using channel 1 as an example, a normal power-up cycle begins when the switch 1 enable bit (A0) and relay 1 enable bit (A4) are set high and then latched into the chip by a STOP bit on the serial interface (point A, Figure 9).

The RELAY1 output turns on immediately and energizes an optional relay connecting the AGND and OUT1 pins to the cable. After a fixed delay of approximately 18ms ( $t_{OD}$ ), the GATE1 pin will start to pull high (point B). When the threshold voltage of the FET is reached, current will begin flowing in the external FET (point C). The voltage at the OUT1 pin will then fall at a rate determined by the current limit and the output load capacitance. Because the current limit is lower when the OUT1 pin is near AGND due to the foldback circuit, the voltage will fall slowly at first, then get faster. At the same time, the current limit timer will start. The OUT1 voltage must reach its final value and the analog current limit circuit must turn off before the current limit timer expires, or a current limit fault will be detected and the  $\overline{\text{FAULT}}$  pin will be pulled low.

When the voltage at OUT1 is within 2V of  $V_{EE}$ , the Power\_OK (C0) bit will be set (point D) and the open-circuit enable delay timer started. As long as the load current turns on before the open-circuit enable delay timer expires, the FAULT pin will remain in a high impedance state and the current limit fault status bit (D0) and open-circuit fault status bit (D4) bits will remain low, thus completing a normal power-up sequence. The Power\_OK bit will remain high until the switch is turned off by setting the switch enable bit (A0) low or a short-circuit or open-circuit condition turns off the switch.

A normal power-down sequence begins when the switch enable bit (A0) and relay enable bit (A4) are cleared and then latched into the chip by a STOP bit on the serial interface (point E). The RELAY1 pin will go into a high impedance state and the inductive voltage spike from the primary coil will be clamped at about 18V. The relay will typically disengage several milliseconds later. At the same time, the GATE1 pin will be pulled low by a 50 $\mu$ A current source, the FET will turn off, and the Power\_OK bit will be cleared.

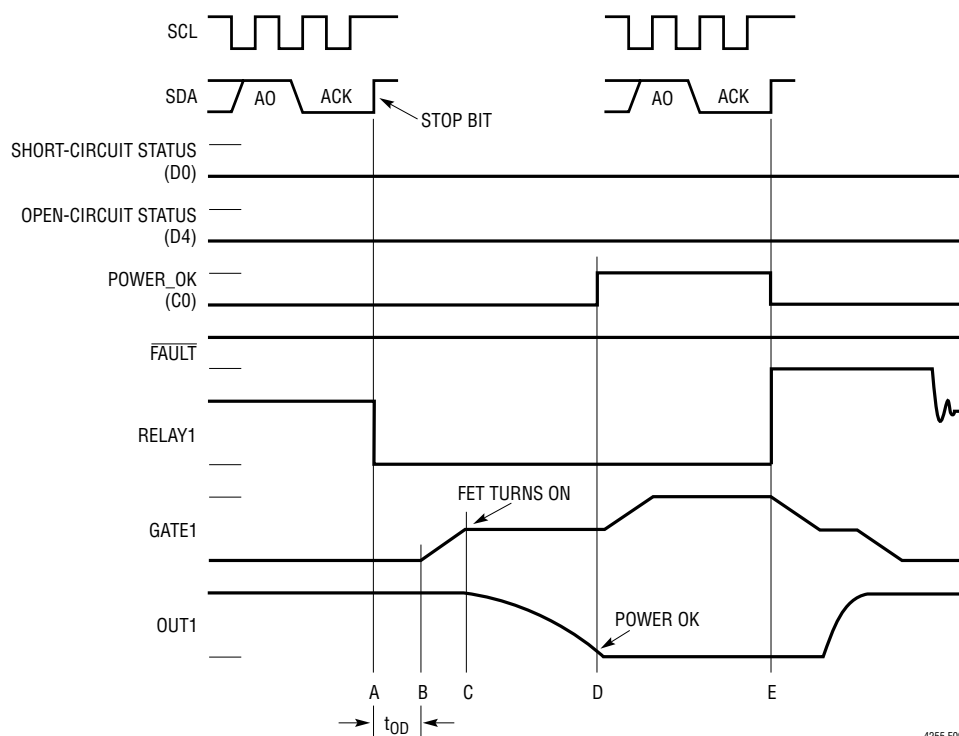


Figure 9. Normal Power-Up and Power-Down Sequence on Channel 1

## APPLICATIONS INFORMATION

### Power-Up with No Load

When a channel powers-up with no load, the initial sequence is the same as the normal case. When the  $V_{OUT1}$  voltage is within the power good threshold, the Power\_OK bit is set (point D, Figure 10) and the open-circuit enable delay timer started. The duration of the timer can be programmed via bits B6-B7.

When the open-circuit enable timer expires ( $t_{OCD}$ , point E), the open-circuit detector is enabled if the global open-circuit detect enable bit (B2) has been set. When the voltage across the sense resistor is less than 3mV(typ) for at least 18ms ( $t_{OCF}$ ), the FET will be turned off, and the

open-circuit fault status bit (D4) will be set (point E). The  $\overline{\text{FAULT}}$  pin will pull low to generate an interrupt to the processor which can then read the status register to determine which channel faulted.

When the fault clear bit (B0) is set during a write cycle via the 2-wire interface (point F), the  $\overline{\text{FAULT}}$  pin goes into a high impedance state, the open-circuit fault status bit (D4) is cleared, and the channel is allowed to turn back on if the relay 1 enable (A4) and switch 1 (A0) enable bits are set (point G.)

The channel is always turned off after an open-circuit fault detection and not allowed to automatically restart.

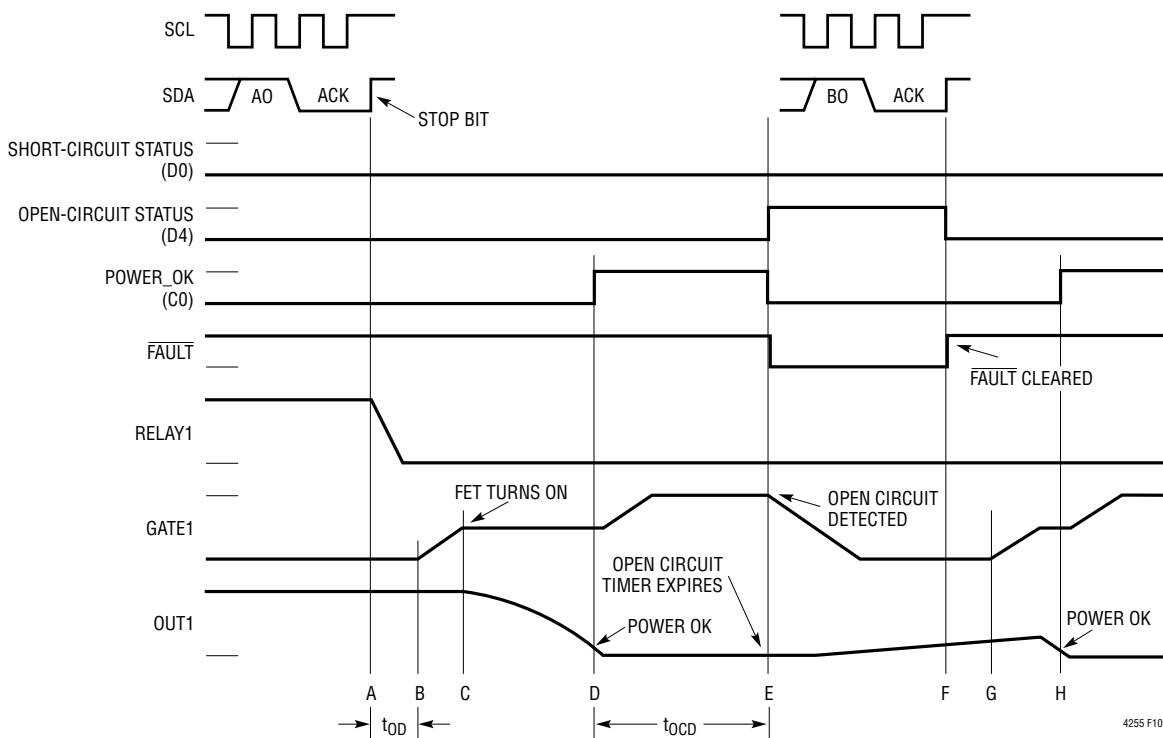


Figure 10. Power-Up Sequence with No Load on Channel 1



## APPLICATIONS INFORMATION

### Power-Up into a Short-Circuit

When a channel powers-up with a shorted load, the RELAY1 pin will pull low immediately and the GATE1 pin will start to pull high (point B Figure 11) after a turn-on delay ( $t_{OD}$ ). When the FET turns on at point C, the current will reach a constant value and the programmable current limit timer ( $t_{CL}$ ) will start. The current limit timer is programmed via bits B4 to B5. When the current limit timer expires, the GATE1 and FAULT pins will pull low, the current limit fault status bit (D0) will be set, and the retry timer ( $t_R$ ) started (point D).

If the autoretry enable bit (B1) is not set, the channel will remain off until the fault is cleared by setting the fault clear bit (B0) and the channel is turned back on by setting the switch enable bit (A0) and the relay enable bit (A4) (point F). If the fault clear bit (B0) is set before the retry timer expires (point E) the channel turn-on will be delayed until the timer expires to enforce the maximum retry duty cycle ( $DC_R$ ). This duty cycle is programmable via bit B3 and sets the maximum ratio of the FET on-time to off-time under a short-circuit condition.

$$DC_R = \frac{t_{CL}}{t_{CL} + t_R}$$

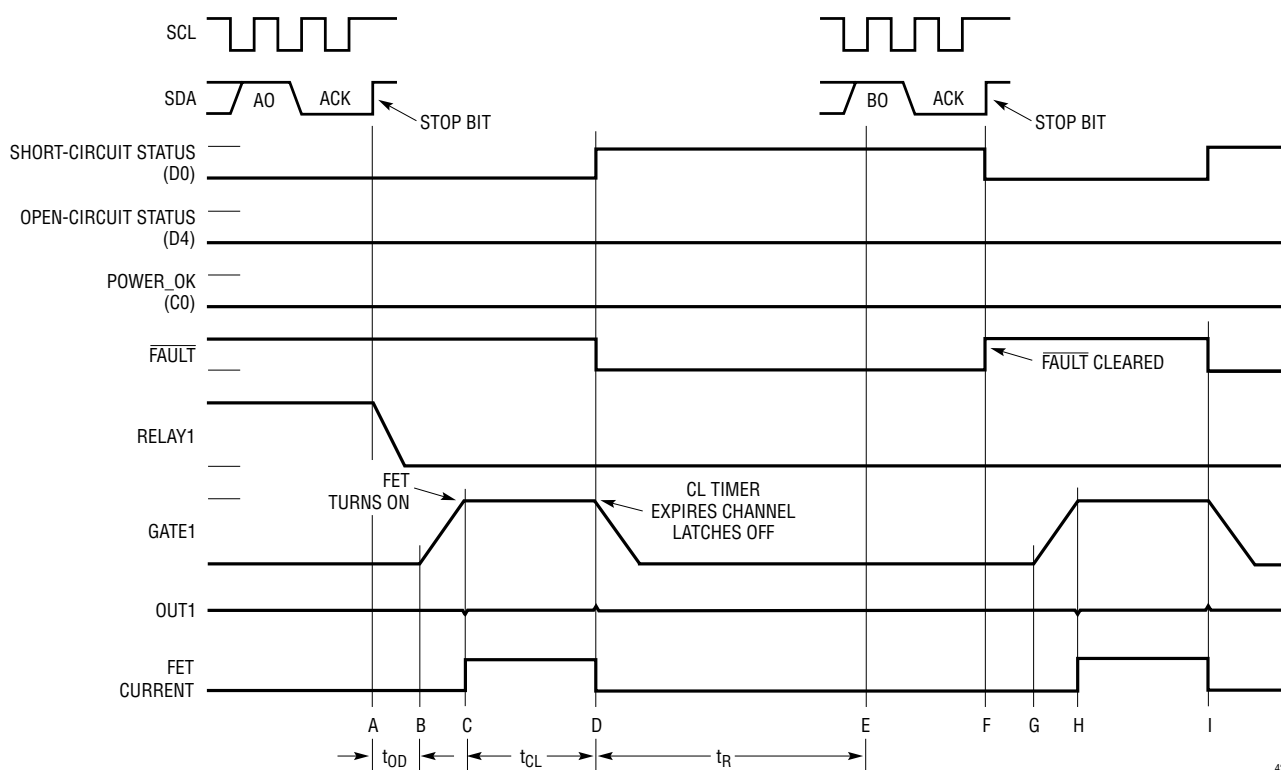


Figure 11. Power-Up Sequence with Shorted Load on Channel 1 with Autoretry Disabled

4255 F11

## APPLICATIONS INFORMATION

If the autoretry enable bit (B1) is set, then the channel will automatically restart after the retry delay timer expires (Figure 12, point E). If the channel successfully powers up after an autoretry, the Power\_OK bit (C0) will be set. However,  $\overline{\text{FAULT}}$  will continue to pull down and the short-circuit bit (D0) will remain high until the fault is cleared by setting the  $\overline{\text{FAULT}}$  clear bit (B0).

In the case of a short-circuit occurring after a normal power-up, high rates of change of current (high di/dt) through the inductance of the cable or even the traces on the PCB can cause the voltages at OUT1-4 to overshoot. A 100k $\Omega$  resistor should be placed between the drains of the FETs and the OUT1-4 pins to limit the energy absorbed by the LTC4255 if the drains of the FETs exceed OUT1-4's absolute maximum voltage rating. Also, if the FETs are not capable of safely absorbing this energy, high-speed

Schottky diodes should be added between the drains of the FETs and AGND using a layout that minimizes the trace lengths between the parts.

### Address Selection

The lower 5 bits of the serial interface address can be set by the address selection pins AD0 to AD4 with AD0 being the least significant bit. The upper two bits are preset to AD5 = high and AD6 = low. To force an address bit to low, the address selection pin should be connected to DGND. To force an address bit to high, the address selection pin can be left floating and an internal pull-up resistor will pull the pin up to the internal digital supply voltage (typically 5V). If more noise immunity is needed, the pin can be connected directly to a 5V or 3.3V external supply.

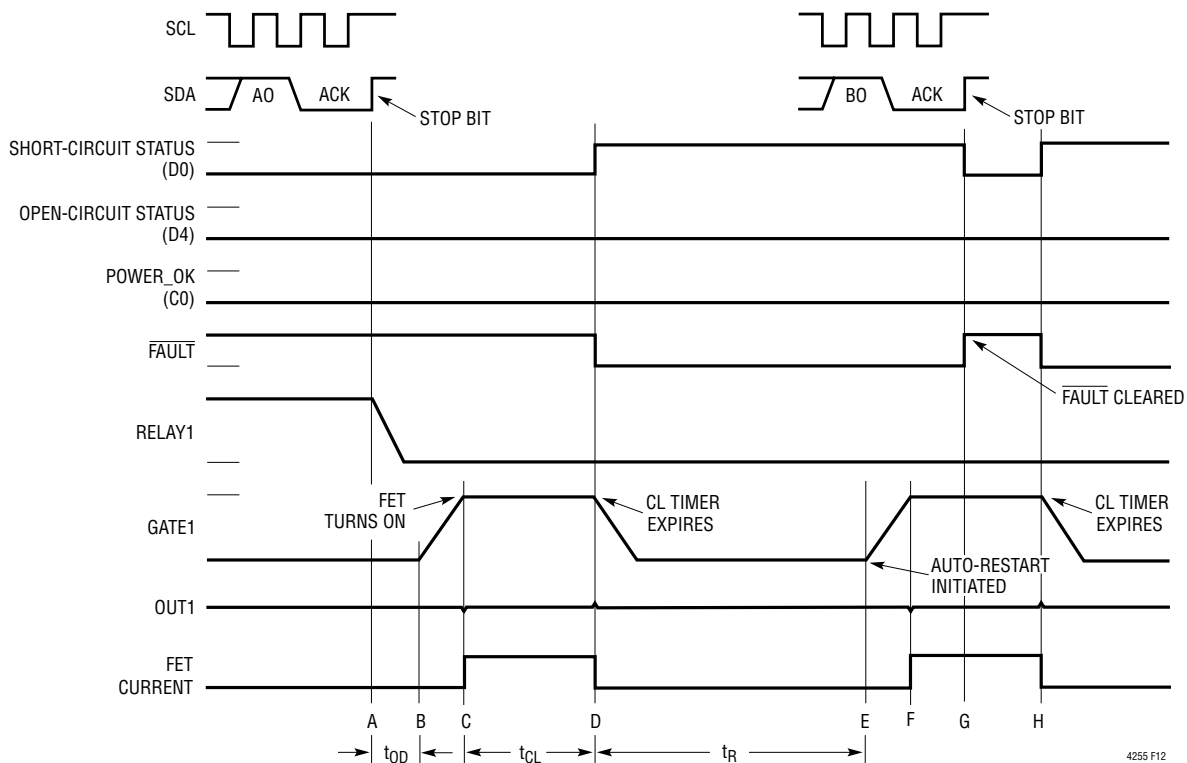


Figure 12. Power-Up Sequence with Shorted Load on Channel 1 with Autoretry Enabled

## APPLICATIONS INFORMATION

### Relay Drivers

The four relay drivers have an open collector NPN transistor with the ability to sink 50mA to within 0.3V of DGND (Figure 13).

An 18V Zener diode connected to DGND is provided to protect against the inductive kickback of the coil when the NPN transistor is turned off.

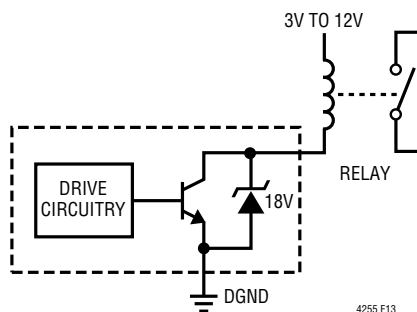
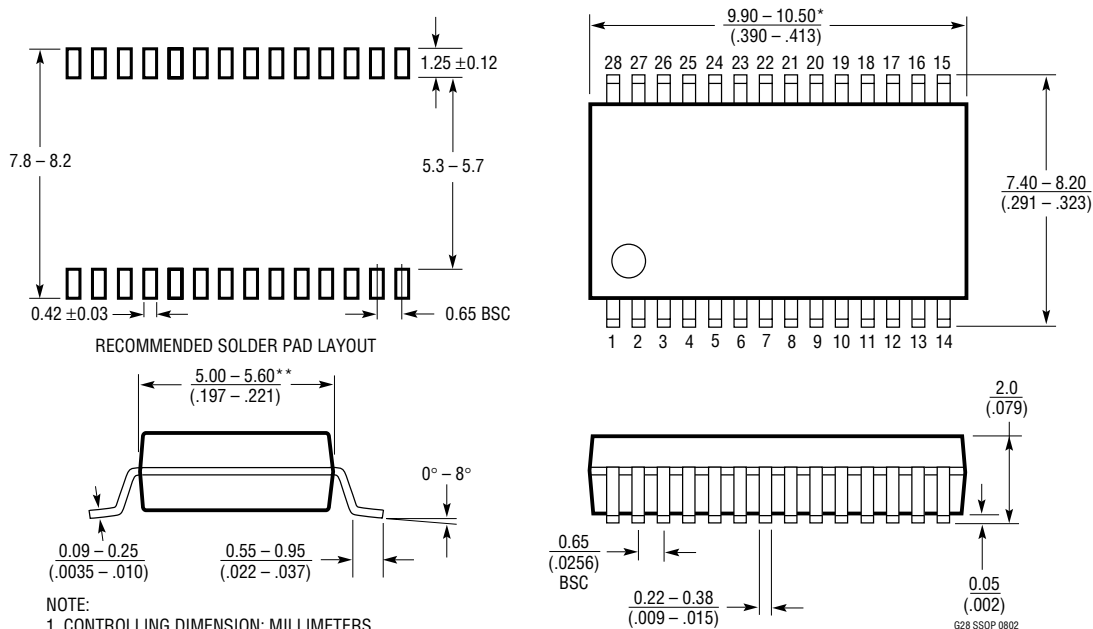


Figure 13. Relay Driver Output

## PACKAGE DESCRIPTION

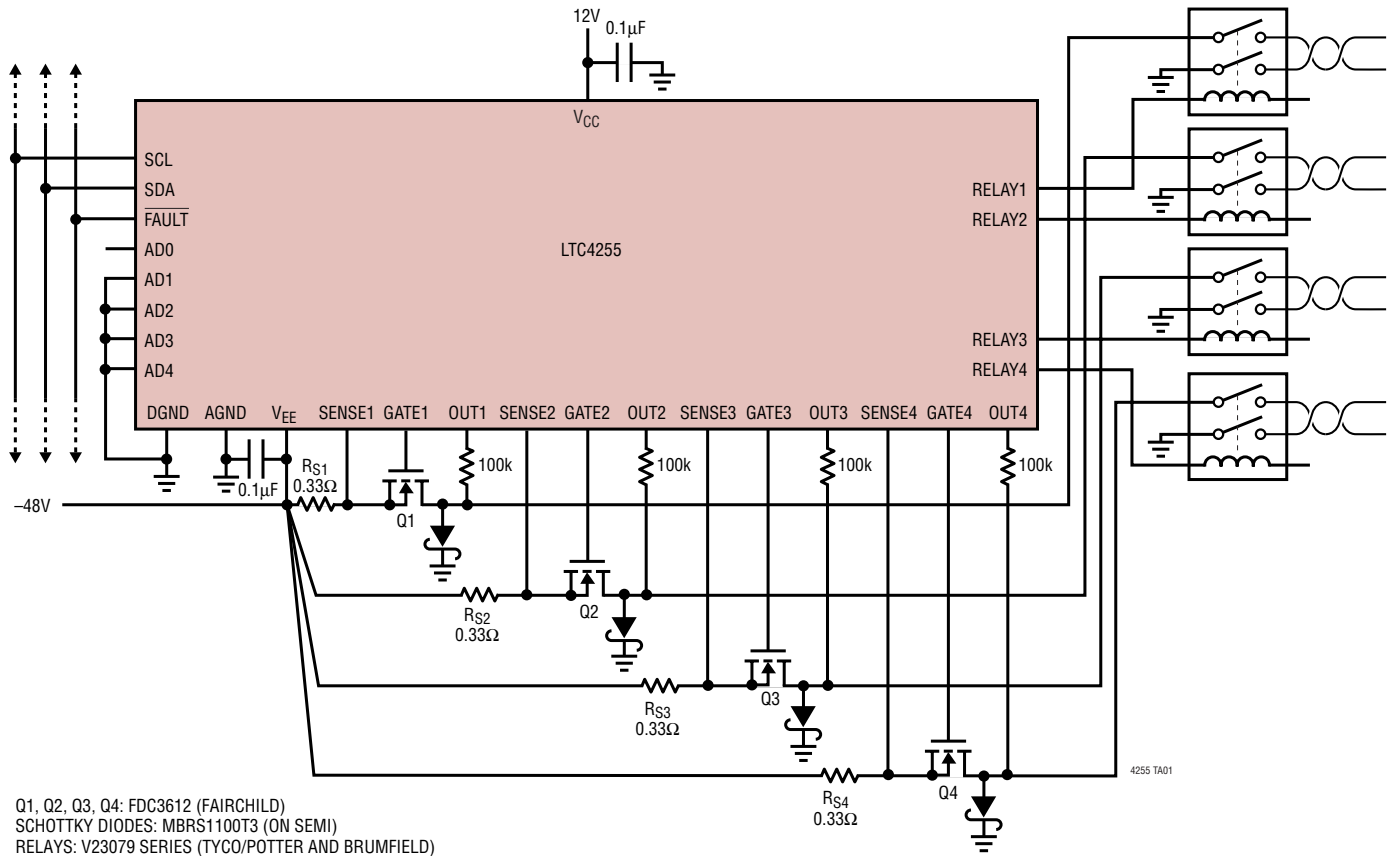
### G Package 28-Lead Plastic SSOP (5.3mm) (Reference LTC DWG # 05-08-1640)



- NOTE:
1. CONTROLLING DIMENSION: MILLIMETERS
  2. DIMENSIONS ARE IN  $\frac{\text{MILLIMETERS}}{\text{(INCHES)}}$
  3. DRAWING NOT TO SCALE
- \*DIMENSIONS DO NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED .152mm (.006") PER SIDE
- \*\*DIMENSIONS DO NOT INCLUDE INTERLEAD FLASH. INTERLEAD FLASH SHALL NOT EXCEED .254mm (.010") PER SIDE

## TYPICAL APPLICATION

Typical Application Using Schottky Diodes to Protect FETs



## RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LTC1694	I <sup>2</sup> C/SMBus Accelerator	Active Pull-Up Improves Rise Time, Ensures Data Integrity
LT4250	Negative Voltage Hot Swap Controller in SO-8	Active Current Limiting, Supplies from -20V to -80V
LTC4251	Negative Voltage Hot Swap Controller in SOT-23	Active Current Limiting, Floating Supplies from -15V
LTC4300-1/LTC4300-2	Hot Swappable 2-Wire Bus Buffer	Isolates SDA, SCL Lines from Output/Allows 3.3V to 5V Level Translation