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IEEE 802.3at PD with Synchronous No-Opto Flyback Controller

FEATURES

- **25.5W IEEE 802.3at Compliant (Type 2) PD**
- **Integrated State-of-the-Art Synchronous Flyback Controller**
 - **Isolated Power Supply Efficiency >92%**
 - **88% Efficiency Including Diode Bridge and Hot Swap™ FET**
- **Flexible Integrated Auxiliary Power Support**
- **Superior EMI Performance**
- **Robust 100V 0.7Ω (Typ) Integrated Hot Swap MOSFET**
- **IEEE 802.3at High Power Available Indicator**
- **Integrated Signature Resistor and Programmable Class Current**
- **Undervoltage, Overvoltage and Thermal Protection**
- **Short-Circuit Protection with Auto-Restart**
- **Programmable Soft-Start and Switching Frequency**
- **Complementary Power Good Indicators**
- **Thermally Enhanced 7mm × 4mm DFN Package**

APPLICATIONS

- VoIP Phones with Advanced Display Options
- Dual-Radio Wireless Access Points
- PTZ Security Cameras
- RFID Readers
- Industrial Controls

DESCRIPTION

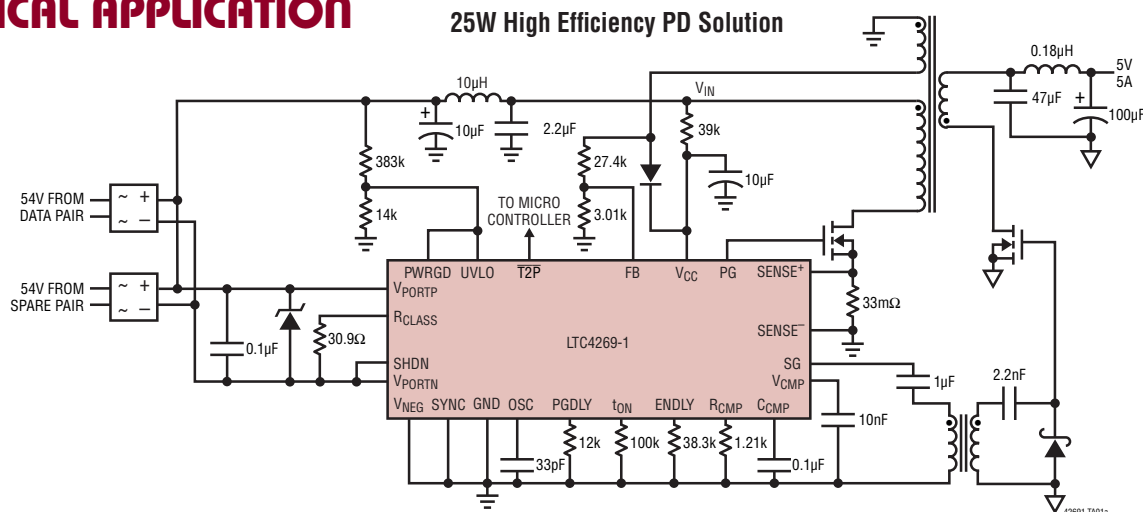
The LTC®4269-1 is an integrated Powered Device (PD) controller and switching regulator intended for high power IEEE 802.3at and 802.3af applications. The LTC4269-1 is targeted for high efficiency, single and multioutput applications from 10W to 25W. By supporting both 1-event and 2-event classifications, as defined by the IEEE, the LTC4269-1 can be used in a wide range of product configurations.

The LTC4269-1 synchronous, current mode, flyback controller generates multiple supply rails in a single conversion step providing for the highest system efficiency while maintaining tight regulation across all outputs. The LTC4269-1 includes Linear Technology's patented No-Opto feedback topology to provide full IEEE 802.3 isolation without the need of an opto-isolator circuit. A true soft-start function allows graceful ramp-up of all output voltages.

All Linear Technology PD solutions include a shutdown pin to provide flexible auxiliary power options. The LTC4269-1 can accommodate adaptor voltages from 18V to 60V and supports both PoE or aux dominance options. The LTC4269-1 is available in a space saving 32-pin DFN package.

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TYPICAL APPLICATION



LTC4269-1

ABSOLUTE MAXIMUM RATINGS

(Notes 1, 2)

Pins with Respect to V_{PORTN}

V_{PORTP} Voltage..... $-0.3V$ to $100V$

V_{NEG} Voltage..... $-0.3V$ to V_{PORTP}

V_{NEG} Pull-Up Current $1A$

SHDN..... $-0.3V$ to $100V$

R_{CLASS} , Voltage..... $-0.3V$ to $7V$

R_{CLASS} Source Current..... $50mA$

PWRGD Voltage (Note 3)

Low Impedance Source $V_{NEG} -0.3V$ to $V_{NEG} +11V$

Sink Current..... $5mA$

\overline{PWRGD} , $\overline{T2P}$ Voltage..... $-0.3V$ to $100V$

\overline{PWRGD} , $\overline{T2P}$ Sink Current..... $10mA$

Pins with Respect to GND

V_{CC} (Note 3)

Low Impedance Source $-0.3V$ to $+18V$

Sink Current..... $30mA$

$SENSE^-$, $SENSE^+$ Voltage..... $-0.5V$ to $+0.5V$

UVLO, SYNC Voltage..... $-0.3V$ to V_{CC}

FB Current..... $\pm 2mA$

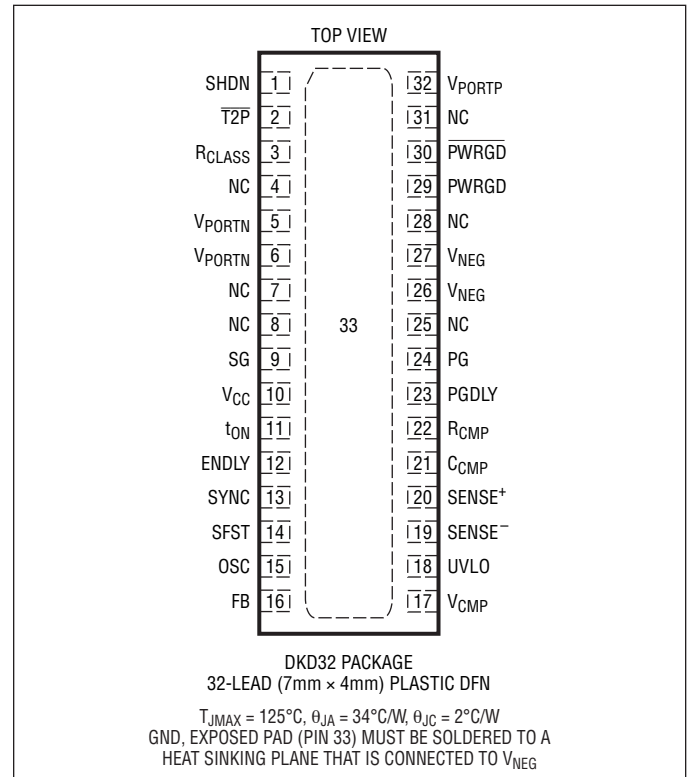
V_{CMP} Current $\pm 1mA$

Operating Ambient Temperature Range

LTC4269C-1 $0^\circ C$ to $70^\circ C$

LTC4269I-1 $-40^\circ C$ to $85^\circ C$

PIN CONFIGURATION



ORDER INFORMATION

| LEAD FREE FINISH | TAPE AND REEL | PART MARKING* | PACKAGE DESCRIPTION | TEMPERATURE RANGE |
|-------------------|---------------------|---------------|---------------------------------|-------------------------------|
| LTC4269CDKD-1#PBF | LTC4269CDKD-1#TRPBF | 42691 | 32-Lead (7mm × 4mm) Plastic DFN | $0^\circ C$ to $70^\circ C$ |
| LTC4269IDKD-1#PBF | LTC4269IDKD-1#TRPBF | 42691 | 32-Lead (7mm × 4mm) Plastic DFN | $-40^\circ C$ to $85^\circ C$ |

Consult LTC Marketing for parts specified with wider operating temperature ranges. *The temperature grade is identified by a label on the shipping container.

For more information on lead free part marking, go to: <http://www.linear.com/leadfree/>

For more information on tape and reel specifications, go to: <http://www.linear.com/tapeandreeel/>

ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$.

| PARAMETER | CONDITIONS | | MIN | TYP | MAX | UNITS |
|------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------|---|-------|-----|-----------|---------------|
| Interface Controller (Note 4) | | | | | | |
| Operating Input Voltage | At V_{PORTP} (Note 5) | | | | 60 | V |
| Signature Range | | ● | 1.5 | | 9.8 | V |
| Classification Range | | ● | 12.5 | | 21 | V |
| ON Voltage | | ● | | | 37.2 | V |
| OFF Voltage | | ● | 30.0 | | | V |
| Overvoltage Lockout | | | | 71 | | V |
| ON/OFF Hysteresis Window | | ● | 4.1 | | | V |
| Signature/Class Hysteresis Window | | ● | 1.4 | | | V |
| Reset Threshold | State Machine Reset for 2-Event Classification | ● | 2.57 | | 5.40 | V |
| Supply Current | | | | | | |
| Supply Current at 57V | Measured at V_{PORTP} Pin | ● | | | 1.35 | mA |
| Class 0 Current | $V_{PORTP} = 17.5\text{V}$, No R_{CLASS} Resistor | ● | | | 0.40 | mA |
| Signature | | | | | | |
| Signature Resistance | $1.5\text{V} \leq V_{PORTP} \leq 9.8\text{V}$ (Note 6) | ● | 23.25 | | 26 | k Ω |
| Invalid Signature Resistance, SHDN Invoked | $1.5\text{V} \leq V_{PORTP} \leq 9.8\text{V}$, $V_{SHDN} = 3\text{V}$ (Note 6) | ● | | | 11 | k Ω |
| Invalid Signature Resistance During Mark Event | (Notes 6, 7) | ● | | | 11 | k Ω |
| Classification | | | | | | |
| Class Accuracy | $10\text{mA} < I_{CLASS} < 40\text{mA}$, $12.5\text{V} < V_{PORTP} < 21\text{V}$ (Notes 8, 9) | ● | | | ± 3.5 | % |
| Classification Stability Time | V_{PORTP} Pin Step to 17.5V, $R_{CLASS} = 30.9$, I_{CLASS} Within 3.5% of Ideal Value (Notes 8, 9) | ● | | | 1 | ms |
| Normal Operation | | | | | | |
| Inrush Current | $V_{PORTP} = 54\text{V}$, $V_{NEG} = 3\text{V}$ | ● | 60 | 100 | 180 | mA |
| Power FET On-Resistance | Tested at 600mA into V_{NEG} , $V_{PORTP} = 54\text{V}$ | ● | | 0.7 | 1.0 | Ω |
| Power FET Leakage Current at V_{NEG} | $V_{PORTP} = \text{SHDN} = V_{NEG} = 57\text{V}$ | ● | | | 1 | μA |
| Digital Interface | | | | | | |
| SHDN Input High Level Voltage | | ● | 3 | | | V |
| SHDN Input Low Level Voltage | | ● | | | 0.45 | V |
| SHDN Input Resistance | $V_{PORTP} = 9.8\text{V}$, $\text{SHDN} = 9.65\text{V}$ | ● | 100 | | | k Ω |
| $\overline{\text{PWRGD}}$, $\overline{\text{T2P}}$ Output Low Voltage | Tested at 1mA, $V_{PORTP} = 54\text{V}$. For $\overline{\text{T2P}}$, Must Complete 2-Event Classification to See Active Low | ● | | | 0.15 | V |
| $\overline{\text{PWRGD}}$, $\overline{\text{T2P}}$ Leakage Current | Pin Voltage Pulled 57V, $V_{PORTP} = V_{PORTN} = 0\text{V}$ | ● | | | 1 | μA |
| $\overline{\text{PWRGD}}$ Output Low Voltage | Tested at 0.5mA, $V_{PORTP} = 52\text{V}$, $V_{NEG} = 48\text{V}$, Output Voltage Is with Respect to V_{NEG} | ● | | | 0.4 | V |
| $\overline{\text{PWRGD}}$ Clamp Voltage | Tested at 2mA, $V_{NEG} = 0\text{V}$, Voltage with Respect to V_{NEG} | ● | 12 | | 16.5 | V |
| $\overline{\text{PWRGD}}$ Leakage Current | $V_{\overline{\text{PWRGD}}} = 11\text{V}$, $V_{NEG} = 0\text{V}$, Voltage with Respect to V_{NEG} | ● | | | 1 | μA |

ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS | |
|-------------------------------------------|----------------------------------------|-----|-------|--------------|-------|-----------------|
| PWM Controller (Note 10) | | | | | | |
| Power Supply | | | | | | |
| V_{CC} Turn-On Voltage, $V_{CC(ON)}$ | | ● | 14 | 15.3 | 16 | V |
| V_{CC} Turn-Off Voltage, $V_{CC(OFF)}$ | | ● | 8 | 9.7 | 11 | V |
| V_{CC} Hysteresis | $V_{CC(ON)} - V_{CC(OFF)}$ | ● | 4 | 5.6 | 6.5 | V |
| V_{CC} Shunt Clamp | $V_{UVLO} = 0V, I_{VCC} = 15mA$ | ● | 19.5 | 20.5 | | V |
| V_{CC} Supply Current (I_{CC}) | $V_{CMP} = \text{Open}$ (Note 11) | ● | 4 | 6.4 | 10 | mA |
| V_{CC} Start-Up Current | $V_{CC} = 10V$ | ● | | 180 | 400 | μA |
| Feedback Amplifier | | | | | | |
| Feedback Regulation Voltage (V_{FB}) | | ● | 1.220 | 1.237 | 1.251 | V |
| Feedback Pin Input Bias Current | R_{CMP} Open | | | 200 | | nA |
| Feedback Amplifier Transconductance | $\Delta I_C = \pm 10\mu\text{A}$ | ● | 700 | 1000 | 1400 | μmho |
| Feedback Amplifier Source or Sink Current | | ● | 25 | 55 | 90 | μA |
| Feedback Amplifier Clamp Voltage | $V_{FB} = 0.9V$ $V_{FB} = 1.4V$ | | | 2.56 0.84 | | V V |
| Reference Voltage Line Regulation | $12V \leq V_{CC} \leq 18V$ | ● | | 0.005 | 0.02 | %/V |
| Feedback Amplifier Voltage Gain | $V_{CMP} = 1.2V$ to $1.7V$ | | | 1400 | | V/V |
| Soft-Start Charging Current | $V_{SFST} = 1.5V$ | | 16 | 20 | 25 | μA |
| Soft-Start Discharge Current | $V_{SFST} = 1.5V, V_{UVLO} = 0V$ | | 0.8 | 1.3 | | mA |
| Control Pin Threshold (V_{CMP}) | Duty Cycle = Min | | | 1 | | V |
| Gate Outputs | | | | | | |
| PG, SG Output High Level | | ● | 6.6 | 7.4 | 8 | V |
| PG, SG Output Low Level | | ● | | 0.01 | 0.05 | V |
| PG, SG Output Shutdown Strength | $V_{UVLO} = 0V; I_{PG}, I_{SG} = 20mA$ | ● | | 1.6 | 2.3 | V |
| PG Rise Time | $C_{PG} = 1nF$ | | | 11 | | ns |
| SG Rise Time | $C_{SG} = 1nF$ | | | 15 | | ns |
| PG, SG Fall Time | $C_{PG}, C_{SG} = 1nF$ | | | 10 | | ns |
| Current Amplifier | | | | | | |
| Switch Current Limit at Maximum V_{CMP} | V_{SENSE}^+ | ● | 88 | 98 | 110 | mV |
| $\Delta V_{SENSE} / \Delta V_{CMP}$ | | | | 0.07 | | V/V |
| Sense Voltage Overcurrent Fault Voltage | $V_{SENSE}^+, V_{SFST} < 1V$ | ● | | 206 | 230 | mV |
| Timing | | | | | | |
| Switching Frequency (f_{OSC}) | $C_{OSC} = 100pF$ | ● | 84 | 100 | 110 | kHz |
| Oscillator Capacitor Value (C_{OSC}) | (Note 12) | | 33 | | 200 | pF |
| Minimum Switch On Time ($t_{ON(MIN)}$) | | | | 200 | | ns |
| Flyback Enable Delay Time (t_{ENDLY}) | | | | 265 | | ns |
| PG Turn-On Delay Time (t_{PGDLY}) | | | | 200 | | ns |
| Maximum Switch Duty Cycle | | ● | 85 | 88 | | % |
| SYNC Pin Threshold | | ● | | 1.53 | 2.1 | V |
| SYNC Pin Input Resistance | | | | 40 | | k Ω |

ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$.

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------------------------------|----------------------------------------------------------------------|----------------|-----------|---------------|--------------------------------|
| Load Compensation | | | | | |
| Load Compensation to V_{SENSE} Offset Voltage | V_{RCMP} with $V_{\text{SENSE}^+} = 0\text{V}$ | | 1 | | mV |
| Feedback Pin Load Compensation Current | $V_{\text{SENSE}^+} = 20\text{mV}$, $V_{\text{FB}} = 1.230\text{V}$ | | 20 | | μA |
| UVLO Function | | | | | |
| UVLO Pin Threshold (V_{UVLO}) | | ● 1.215 | 1.240 | 1.265 | V |
| UVLO Pin Bias Current | $V_{\text{UVLO}} = 1.2\text{V}$ $V_{\text{UVLO}} = 1.3\text{V}$ | -0.25 -4.50 | 0 -3.4 | 0.25 -2.50 | μA μA |

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: Pins with 100V absolute maximum guaranteed for $T \geq 0^\circ\text{C}$, otherwise 90V.

Note 3: Active high PWRGD internal clamp self-regulates to 14V with respect to V_{NEG} . V_{CC} has internal 19.5V clamp with respect to GND.

Note 4: All voltages are with respect to V_{PORTN} pin unless otherwise noted.

Note 5: Input voltage specifications are defined with respect to LTC4269-1 pins and meet IEEE 802.3af/at specifications when the input diode bridge is included.

Note 6: Signature resistance is measured via the $\Delta V/\Delta I$ method with the minimum ΔV of 1V. The LTC4269-1 signature resistance accounts for the additional series resistance in the input diode bridge.

Note 7: An invalid signature after the 1st classification event is mandated by the IEEE802.3at standard. See the Applications Information section.

Note 8: Class accuracy is with respect to the ideal current defined as $1.237/R_{\text{CLASS}}$ and does not include variations in R_{CLASS} resistance.

Note 9: This parameter is assured by design and wafer level testing.

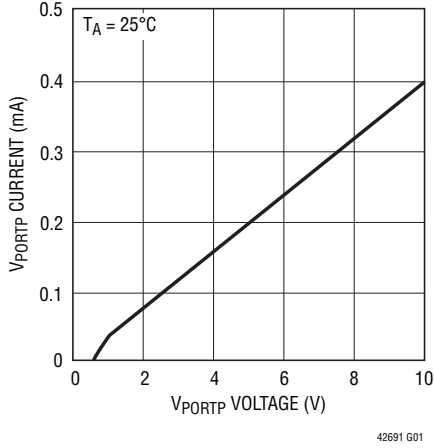
Note 10: $V_{\text{CC}} = 14\text{V}$; PG, SG Open; $V_{\text{CMP}} = 1.5\text{V}$, $V_{\text{SENSE}^-} = 0\text{V}$, $R_{\text{CMP}} = 1\text{k}$, $R_{\text{TON}} = 90\text{k}$, $R_{\text{PGDLY}} = 27.4\text{k}$, $R_{\text{ENDLY}} = 90\text{k}$, unless otherwise specified. All voltages are with respect to GND.

Note 11: Supply current does not include gate charge current to the MOSFETs. See the Applications Information section.

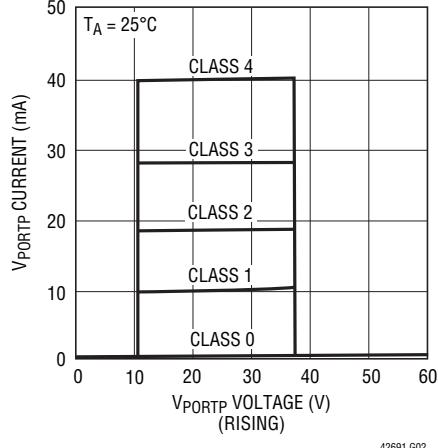
Note 12: Component value range guaranteed by design.

TYPICAL PERFORMANCE CHARACTERISTICS

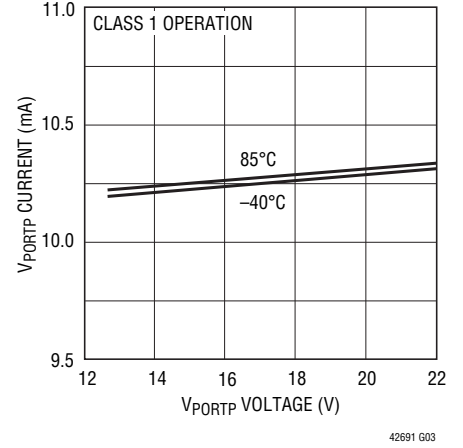
Input Current vs Input Voltage
25k Detection Range



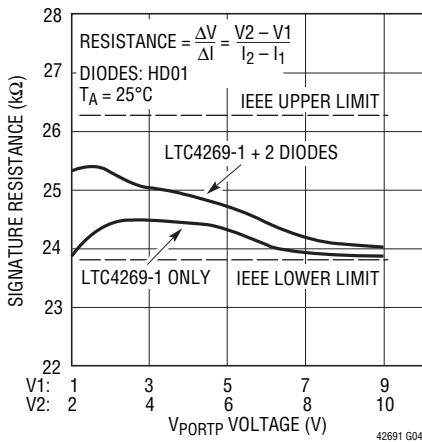
Input Current vs Input Voltage



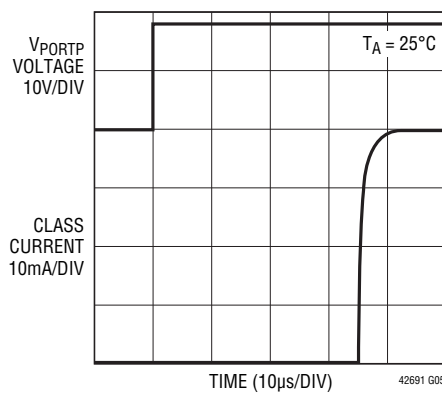
Input Current vs Input Voltage



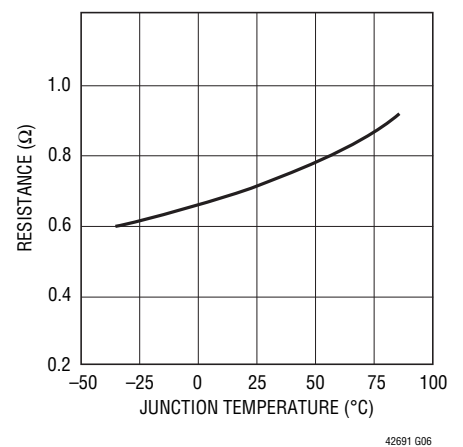
Signature Resistance vs Input Voltage



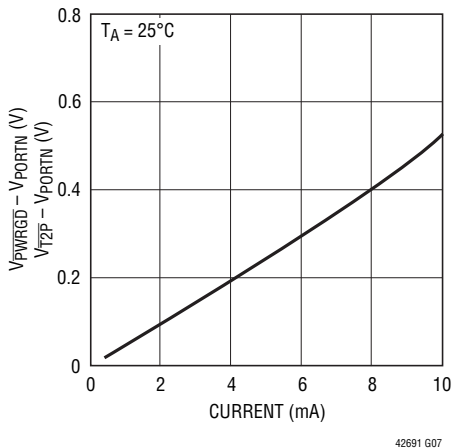
Class Operation vs Time



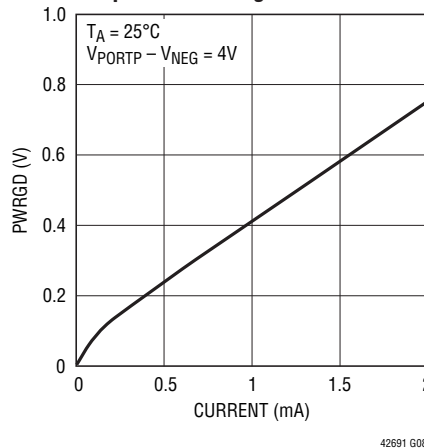
On-Resistance vs Temperature



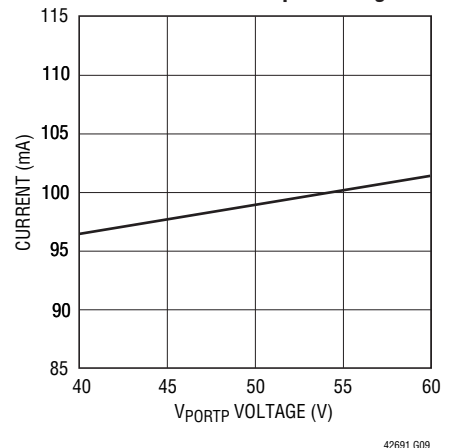
PWRGD, T2P Output Low Voltage vs Current



Active High PWRGD Output Low Voltage vs Current

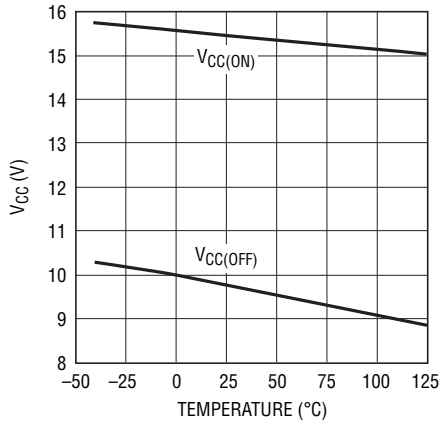


Inrush Current vs Input Voltage



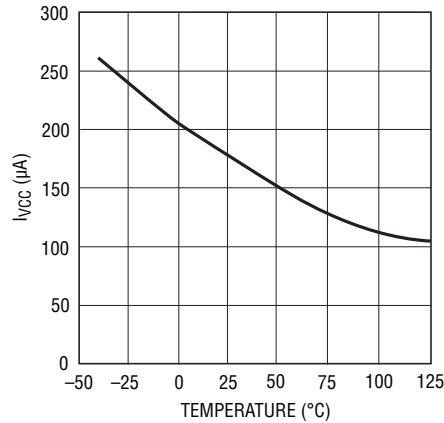
TYPICAL PERFORMANCE CHARACTERISTICS

V_{CC(ON)} and V_{CC(OFF)} vs Temperature



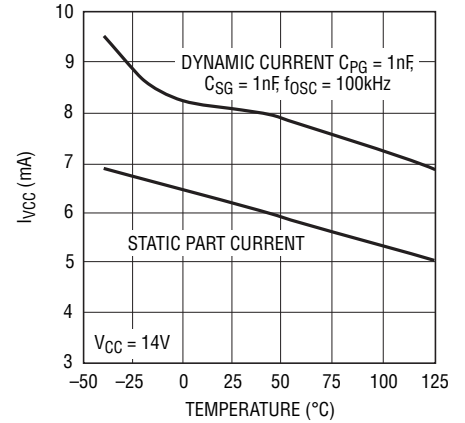
42691 G10

V_{CC} Start-Up Current vs Temperature



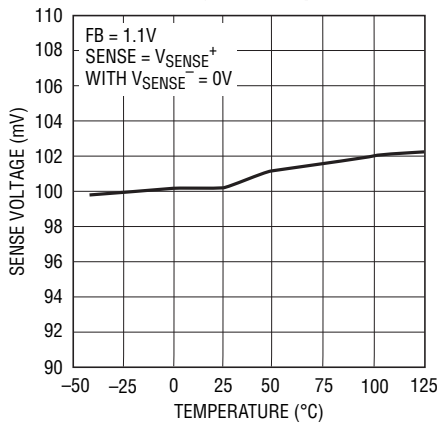
42691 G11

V_{CC} Current vs Temperature



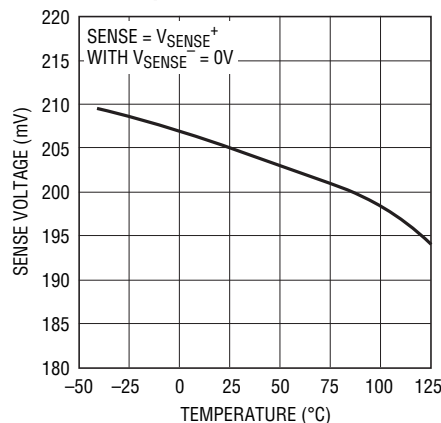
42691 G12

SENSE Voltage vs Temperature



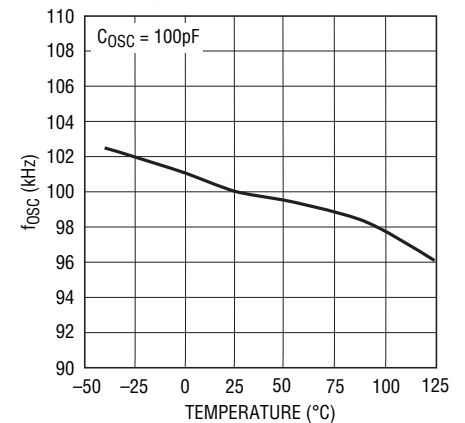
42691 G13

SENSE Fault Voltage vs Temperature



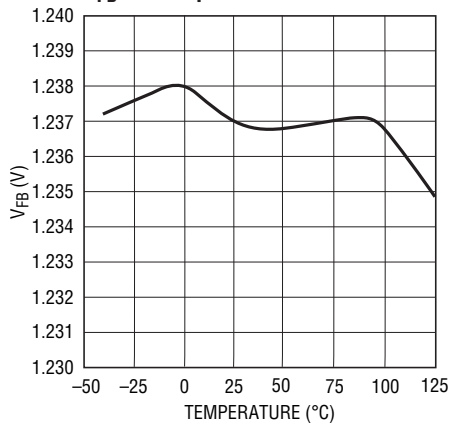
42691 G14

Oscillator Frequency vs Temperature



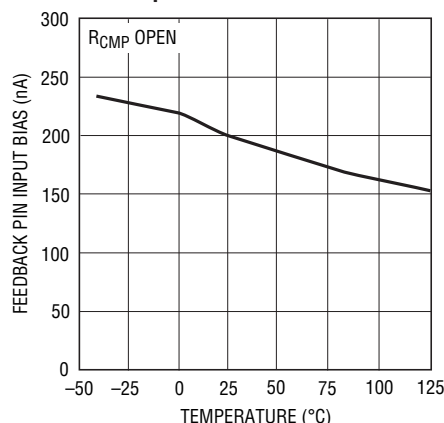
42691 G15

V_{FB} vs Temperature



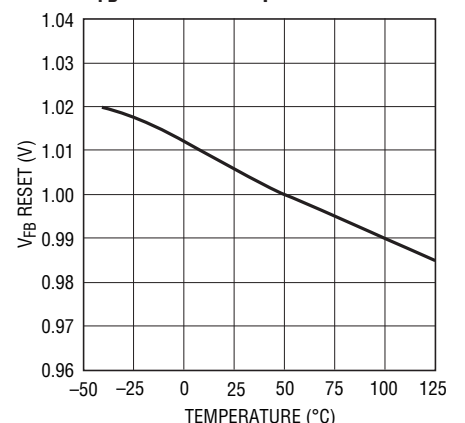
42691 G16

Feedback Pin Input Bias vs Temperature



42691 G17

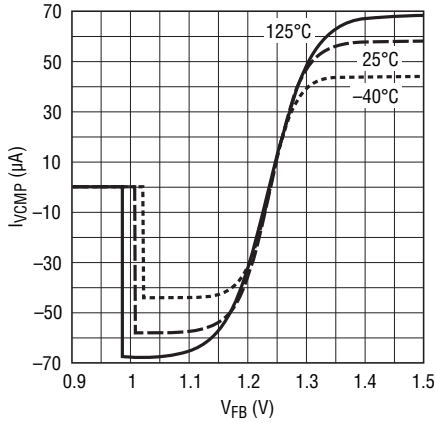
V_{FB} Reset vs Temperature



42691 G18

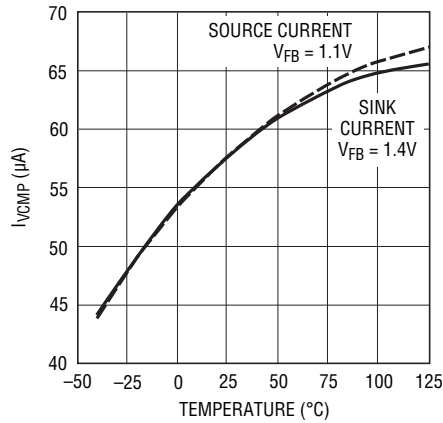
TYPICAL PERFORMANCE CHARACTERISTICS

Feedback Amplifier Output Current vs V_{FB}



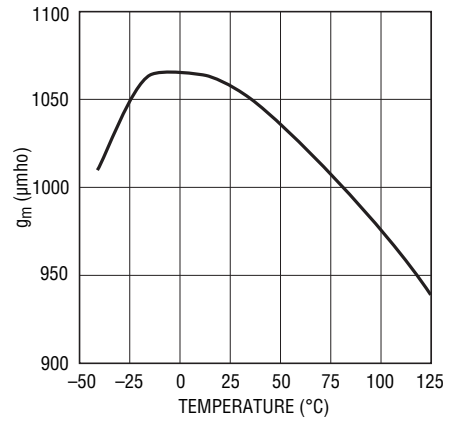
42691 G19

Feedback Amplifier Source and Sink Current vs Temperature



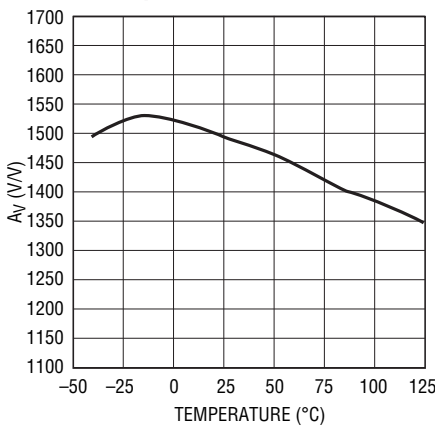
42691 G20

Feedback Amplifier g_m vs Temperature



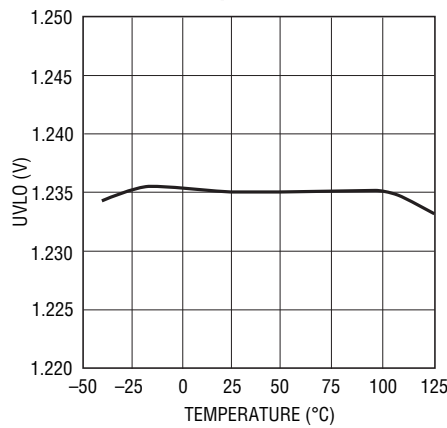
42691 G21

Feedback Amplifier Voltage Gain vs Temperature



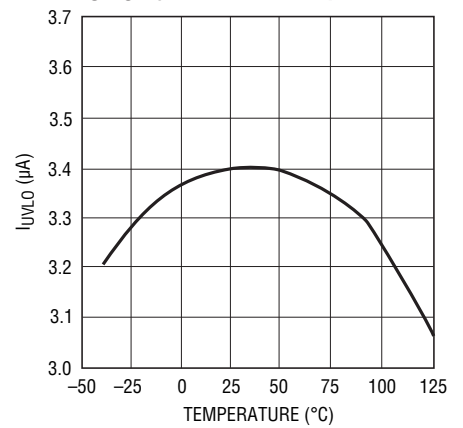
42691 G22

UVLO vs Temperature



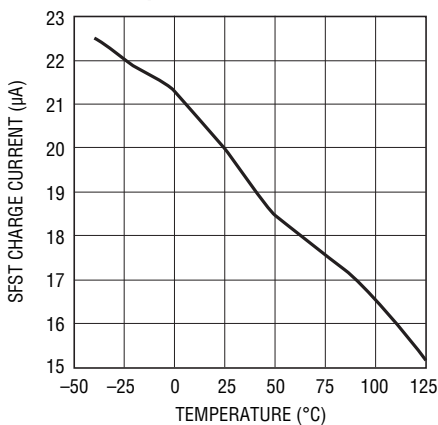
42691 G23

I_{UVLO} Hysteresis vs Temperature



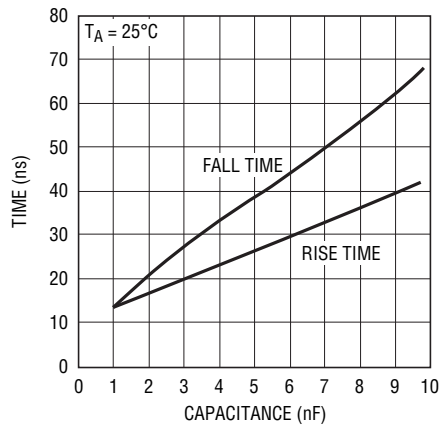
42691 G24

Soft-Start Charge Current vs Temperature



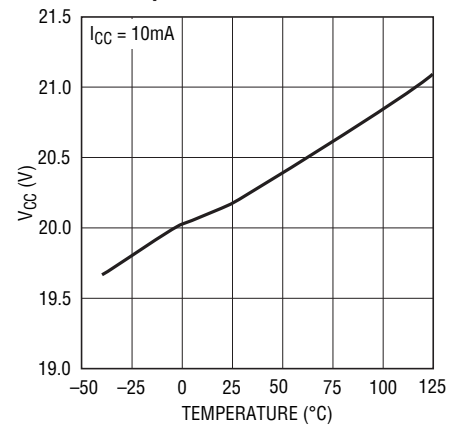
42691 G25

PG, SG Rise and Fall Times vs Load Capacitance



42691 G26

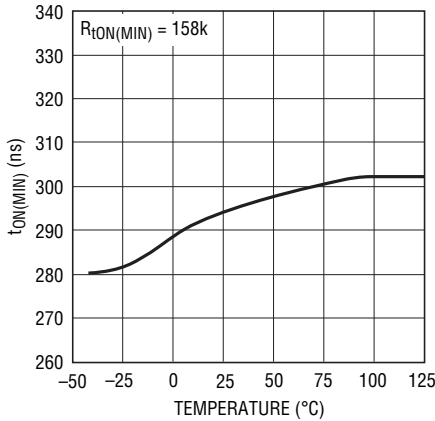
V_{CC} Clamp Voltage vs Temperature



42691 G27

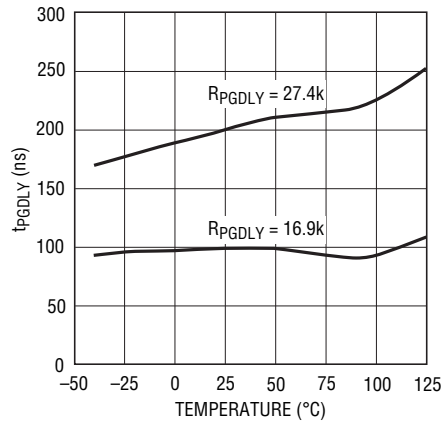
TYPICAL PERFORMANCE CHARACTERISTICS

Minimum PG On-Time vs Temperature



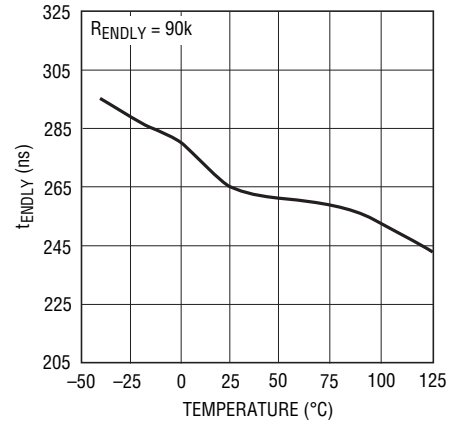
42691 G28

PG Delay Time vs Temperature



42691 G29

Enable Delay Time vs Temperature



42691 G30

PIN FUNCTIONS

SHDN (Pin 1): Shutdown Input. Use this pin for auxiliary power application. Drive SHDN high to disable the PD interface operation and corrupt the signature resistance. If unused, tie SHDN to V_{PORTN}.

T2P (Pin 2): Type 2 PSE Indicator, Open-Drain. Low impedance indicates the presence of a Type 2 PSE.

R_{CLASS} (Pin 3): Class Select Input. Connect a resistor between R_{CLASS} and V_{PORTN} to set the classification load current (see Table 2).

NC (Pins 4, 7, 8, 25, 28, 31): No Connect.

V_{PORTN} (Pins 5, 6): Input Voltage, Negative Rail. Pin 5 and Pin 6 must be electrically tied together at the package.

SG (Pin 9): Synchronous Gate Drive Output. This pin provides an output signal for a secondary-side synchronous rectifier. Large dynamic currents may flow during voltage transitions. See the Applications Information section for details.

V_{CC} (Pin 10): Supply Voltage Pin. Bypass this pin to GND with a 4.7μF, or more, capacitor. This pin has a 19.5V clamp to ground. V_{CC} has an undervoltage lockout function that turns the part on when V_{CC} is approximately 15.3V and off at 9.7V. In a conventional trickle-charge bootstrapped configuration, the V_{CC} supply current

increases significantly during turn-on causing a benign relaxation oscillation action on the V_{CC} pin if the part does not start normally.

t_{ON} (Pin 11): Pin for external programming resistor to set the minimum time that the primary switch is on for each cycle. Minimum turn-on facilitates the isolated feedback method. See the Applications Information section for details.

ENDLY (Pin 12): Pin for external programming resistor to set enable delay time. The enable delay time disables the feedback amplifier for a fixed time after the turn-off of the primary-side MOSFET. This allows the leakage inductance voltage spike to be ignored for flyback voltage sensing. See the Applications Information section for details.

SYNC (Pin 13): External Sync Input. This pin is used to synchronize the internal oscillator with an external clock. The positive edge of the clock causes the oscillator to discharge causing PG to go low (off) and SG high (on). The sync threshold is typically 1.5V. Tie to ground if unused. See the Applications Information section for details.

SFST (Pin 14): Soft-Start. This pin, in conjunction with a capacitor (C_{SFST}) to GND, controls the ramp-up of peak primary current through the sense resistor. It is also used to control converter inrush at start-up. The SFST clamps

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PIN FUNCTIONS

the V_{CMP} voltage and thus limits peak current until soft-start is complete. The ramp time is approximately 70ms per μF of capacitance. Leave SFST open if not using the soft-start function.

OSC (Pin 15): Oscillator. This pin, in conjunction with an external capacitor (C_{OSC}) to GND, defines the controller oscillator frequency. The frequency is approximately $100\text{kHz} \cdot 100/C_{OSC}$ (pF).

FB (Pin 16): Feedback Amplifier Input. Feedback is usually sensed via a third winding and enabled during the flyback period. This pin also sinks additional current to compensate for load current variation as set by the R_{CMP} pin. Keep the Thevenin equivalent resistance of the feedback divider at roughly 3k.

V_{CMP} (Pin 17): Frequency Compensation Control. V_{CMP} is used for frequency compensation of the switcher control loop. It is the output of the feedback amplifier and the input to the current comparator. Switcher frequency compensation components are placed on this pin to GND. The voltage on this pin is proportional to the peak primary switch current. The feedback amplifier output is enabled during the synchronous switch on time.

UVLO (Pin 18): Undervoltage Lockout. A resistive divider from V_{PORTP} to this pin sets an undervoltage lockout based upon V_{PORTP} level (not V_{CC}). When the UVLO pin is below its threshold, the gate drives are disabled, but the part draws its normal quiescent current from V_{CC} . The V_{CC} undervoltage lockout supersedes this function, so V_{CC} must be great enough to start the part.

The bias current on this pin has hysteresis such that the bias current is sourced when UVLO threshold is exceeded. This introduces a hysteresis at the pin equivalent to the bias current change times the impedance of the upper divider resistor. The user can control the amount of hysteresis by adjusting the impedance of the divider. Tie the UVLO pin to V_{CC} if not using this function. See the Applications Information section for details. This pin is used for the UVLO function of the switching regulator. The PD interface section has an internal UVLO.

SENSE⁻, SENSE⁺ (Pins 19, 20): Current Sense Inputs. These pins are used to measure primary-side switch current through an external sense resistor. Peak primary-side

current is used in the converter control loop. Make Kelvin connections to the sense resistor R_{SENSE} to reduce noise problems. SENSE⁻ connects to the GND side. At maximum current (V_{CMP} at its maximum voltage) SENSE pins have 100mV threshold. The signal is blanked (ignored) during the minimum turn-on time.

C_{CMP} (Pin 21): Load Compensation Capacitive Control. Connect a capacitor from C_{CMP} to GND in order to reduce the effects of parasitic resistances in the feedback sensing path. A 0.1 μF ceramic capacitor suffices for most applications. Short this pin to GND when load compensation is not needed.

R_{CMP} (Pin 22): Load Compensation Resistive Control. Connect a resistor from R_{CMP} to GND in order to compensate for parasitic resistances in the feedback sensing path. In less demanding applications, this resistor is not needed and this pin can be left open. See the Applications Information section for details.

PGDLY (Pin 23): Primary Gate Delay Control. Connect an external programming resistor (R_{PGDLY}) to set delay from synchronous gate turn-off to primary gate turn-on. See the Applications Information section for details.

PG (Pin 24): Primary Gate Drive. PG is the gate drive pin for the primary-side MOSFET switch. Large dynamic currents flow during voltage transitions. See the Applications Information section for details.

V_{NEG} (Pins 26, 27): System Negative Rail. Connects V_{NEG} to V_{PORTN} through an internal power MOSFET. Pin 26 and Pin 27 must be electrically tied together at the package.

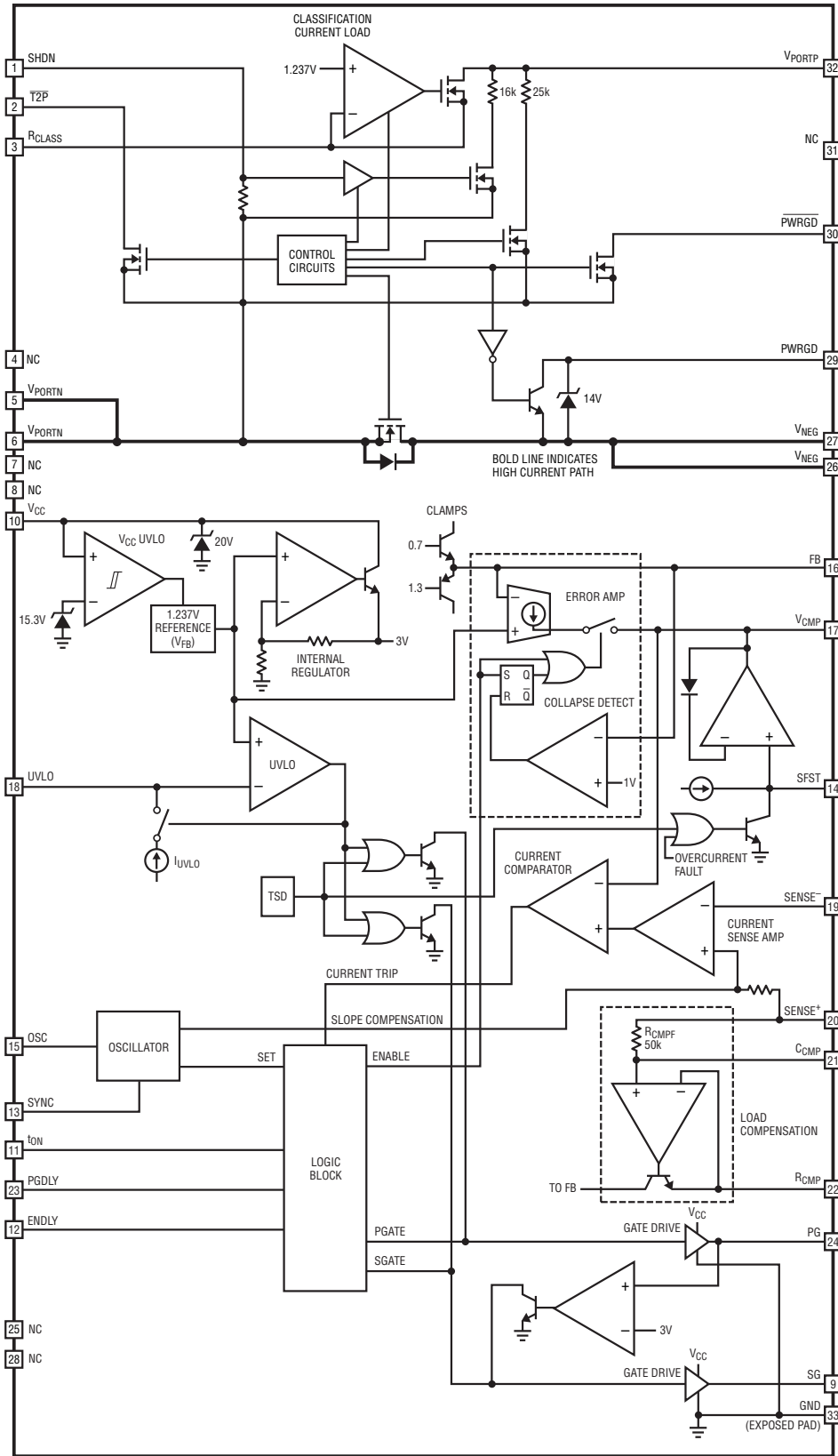
PWRGD (Pin 29): Power Good Output, Open-Collector. High impedance signals power-up completion. PWRGD is referenced to V_{NEG} and features a 14V clamp.

$\overline{\text{PWRGD}}$ (Pin 30): Complementary Power Good Output, Open-Drain. Low impedance signals power-up completion. $\overline{\text{PWRGD}}$ is referenced to V_{PORTN} .

V_{PORTP} (Pin 32): Positive Power Input. Tie to the input port power through the input diode bridge.

Exposed Pad (Pin 33): Ground. This is the negative rail connection for both signal ground and gate driver grounds of the flyback controller. This pin should be connected to V_{NEG} .

BLOCK DIAGRAM



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APPLICATIONS INFORMATION

OVERVIEW

Power over Ethernet (PoE) continues to gain popularity as more products are taking advantage of having DC power and high speed data available from a single RJ45 connector. As PoE continues to grow in the marketplace, Powered Device (PD) equipment vendors are running into the 13.0W power limit established by the IEEE 802.3af standard.

The IEEE 802.3at standard establishes a higher power allocation for Power over Ethernet while maintaining backwards compatibility with the existing IEEE 802.3af systems. Power sourcing equipment (PSE) and powered devices are distinguished as Type 1 complying with the IEEE 802.3af power levels, or Type 2 complying with the IEEE 802.3at power levels. The maximum available power of a Type 2 PD is 25.5W.

The IEEE 802.3at standard also establishes a new method of acquiring power classification from a PD and communicating the presence of a Type 2 PSE. A Type 2 PSE has the option of acquiring PD power classification by performing 2-event classification (layer 1) or by communicating with the PD over the data line (layer 2). In turn, a Type 2 PD must be able to recognize both layers of communications and identify a Type 2 PSE.

The LTC4269-1 is specifically designed to support the front end of a PD that must operate under the IEEE 802.3at standard. In particular, the LTC4269-1 provides the $\overline{T2P}$ indicator bit which recognizes 2-event classification. This indicator bit may be used to alert the LTC4269-1 output load that a Type 2 PSE is present. With an internal signature resistor, classification circuitry, inrush control, and thermal shutdown, the LTC4269-1 is a complete PD Interface solution capable of supporting in the next generation PD applications.

MODES OF OPERATION

The LTC4269-1 has several modes of operation depending on the input voltage applied between the V_{PORTP} and V_{PORTN} pins. Figure 1 presents an illustration of voltage and current waveforms the LTC4269-1 may encounter with the various modes of operation summarized in Table 1.

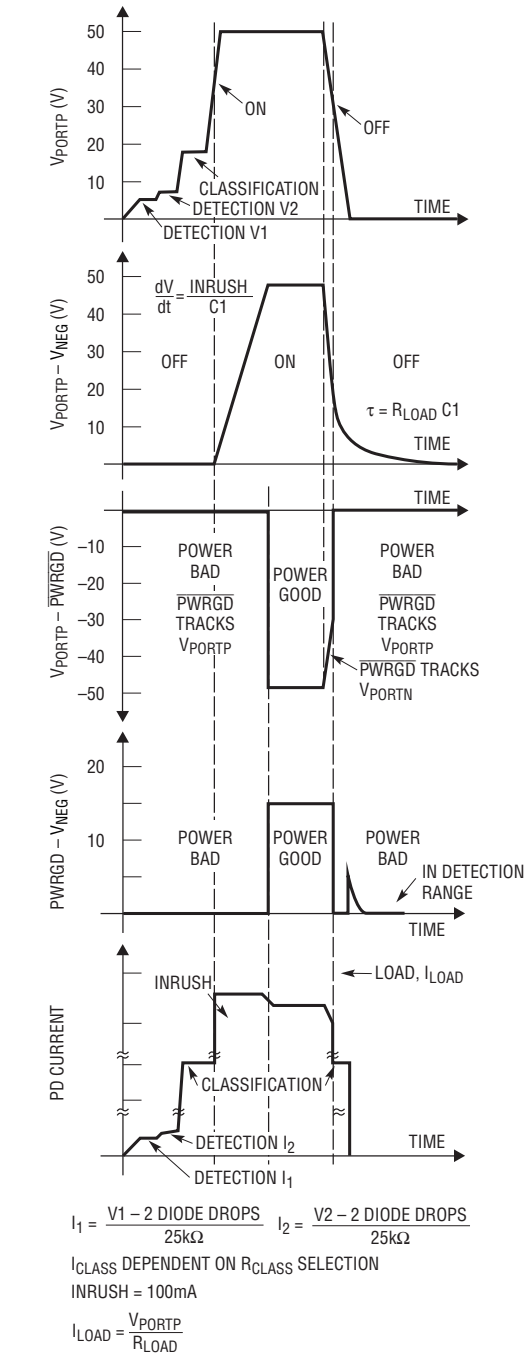


Figure 1. V_{NEG} , \overline{PWRGD} , \overline{PWRGD} and PD Current as a Function of Input Voltage

APPLICATIONS INFORMATION

Table 1. LTC4269-1 Modes of Operation as a Function of Input Voltage

| $V_{PORTP}-V_{PORTN}$ (V) | LTC4269-1 MODES OF OPERATION |
|--------------------------------|-------------------------------------------------------------------------------------------------------------------------------|
| 0V to 1.4V | Inactive (Reset After 1st Classification Event) |
| 1.5V to 9.8V (5.4V to 9.8V) | 25k Signature Resistor Detection Before 1st Classification Event (Mark, 11k Signature Corrupt After 1st Classification Event) |
| 12.5V to ON/OFF* | Classification Load Current Active |
| ON/OFF* to 60V | Inrush and Power Applied To PD Load |
| >71V | Overtoltage Lockout, Classification and Hot Swap Are Disabled |

*ON/OFF includes hysteresis. Rising input threshold, 37.2V Max. Falling input threshold, 30V Min.

These modes satisfy the requirements defined in the IEEE 802.3af/IEEE 802.3at specification.

INPUT DIODE BRIDGE

In the IEEE 802.3af/IEEE 802.3at standard, the modes of operation reference the input voltage at the PD's RJ45 connector. Since the PD must handle power received in either polarity from either the data or the spare pair, input diode bridges BR1 and BR2 are connected between the RJ45 connector and the LTC4269-1 (Figure 2).

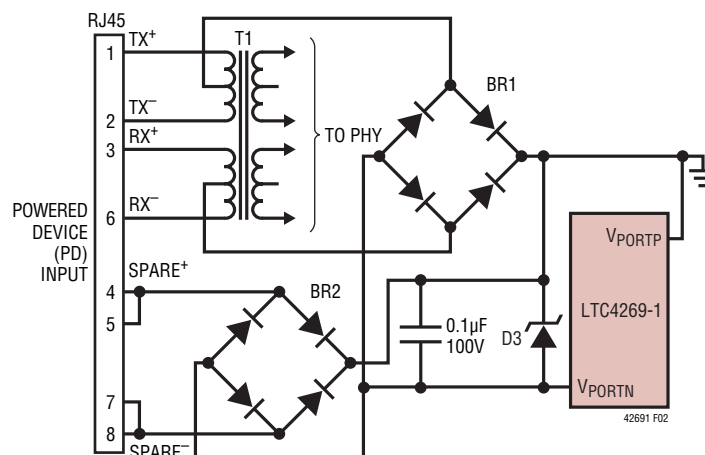


Figure 2. PD Front End Using Diode Bridges on Main and Spare Inputs

The input diode bridge introduces a voltage drop that affects the range for each mode of operation. The LTC4269-1 compensates for these voltage drops so that a PD built with the LTC4269-1 meets the IEEE 802.3af/IEEE 802.3at-established voltage ranges. Note the Electrical Characteristics are referenced with respect to the LTC4269-1 package pins.

DETECTION

During detection, the PSE looks for a 25k signature resistor which identifies the device as a PD. The PSE will apply two voltages in the range of 2.8V to 10V and measures the corresponding currents. Figure 1 shows the detection voltages V1 and V2 and the corresponding PD current. The PSE calculates the signature resistance using the $\Delta V/\Delta I$ measurement technique.

The LTC4269-1 presents its precision, temperature-compensated 25k resistor between the V_{PORTP} and V_{PORTN} pins, alerting the PSE that a PD is present and requests power to be applied. The LTC4269-1 signature resistor also compensates for the additional series resistance introduced by the input diode bridge. Thus a PD built with the LTC4269-1 conforms to the IEEE 802.3af/IEEE 802.3at specifications.

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SIGNATURE CORRUPT OPTION

In some designs that include an auxiliary power option, it is necessary to prevent a PD from being detected by a PSE. The LTC4269-1 signature resistance can be corrupted with the SHDN pin (Figure 3). Taking the SHDN pin high will reduce the signature resistor below 11k which is an invalid signature per the IEEE 802.3af/IEEE 802.3at specification, and alerts the PSE not to apply power. Invoking the SHDN pin also ceases operation for classification and disconnects the LTC4269-1 load from the PD input. If this feature is not used, connect SHDN to V_{PORTN} .

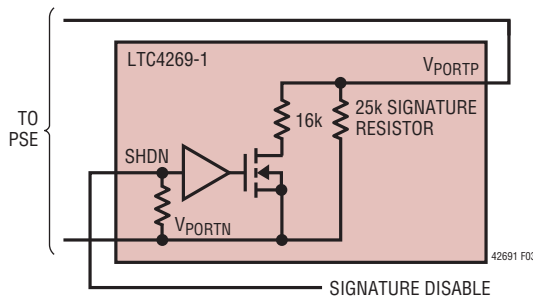


Figure 3. 25k Signature Resistor with Disable

CLASSIFICATION

Classification provides a method for more efficient power allocation by allowing the PSE to identify a PD power classification. Class 0 is included in the IEEE specification for PDs that do not support classification. Class 1-3 partitions PDs into three distinct power ranges. Class 4 includes the new power range under IEEE802.3at (see Table 2).

During classification probing, the PSE presents a fixed voltage between 15.5V and 20.5V to the PD (Figure 1). The LTC4269-1 asserts a load current representing the PD power classification. The classification load current is programmed with a resistor R_{CLASS} that is chosen from Table 2.

Table 2. Summary of Power Classifications and LTC4269-1 R_{CLASS} Resistor Selection

| CLASS | USAGE | MAXIMUM AVERAGE POWER LEVELS AT INPUT OF PD (W) | NOMINAL CLASSIFICATION LOAD CURRENT (mA) | LTC4269-1 R_{CLASS} RESISTOR (Ω , 1%) |
|-------|--------|-------------------------------------------------|------------------------------------------|-------------------------------------------------|
| 0 | Type 1 | 0.44 to 13.0 | < 0.4 | Open |
| 1 | Type 1 | 0.44 to 3.84 | 10.5 | 124 |
| 2 | Type 1 | 3.84 to 6.49 | 18.5 | 69.8 |
| 3 | Type 1 | 6.49 to 13.0 | 28 | 45.3 |
| 4 | Type 2 | 13.0 to 25.5 | 40 | 30.9 |

2-EVENT CLASSIFICATION AND THE $\overline{T2P}$ PIN

A Type 2 PSE may declare the availability of high power by performing a 2-event classification (layer 1) or by communicating over the high speed data line (layer 2). A Type 2 PD must recognize both layers of communication. Since layer 2 communication takes place directly between the PSE and the LTC4269-1 load, the LTC4269-1 concerns itself only with recognizing 2-event classification.

In 2-event classification, a Type 2 PSE probes for power classification twice. Figure 4 presents an example of a 2-event classification. The 1st classification event occurs when the PSE presents an input voltage between 15.5V to 20.5V and the LTC4269-1 presents a class 4 load current. The PSE then drops the input voltage into the mark voltage range of 7V to 10V, signaling the 1st mark event. The PD in the mark voltage range presents a load current between 0.25mA to 4mA.

The PSE repeats this sequence, signaling the 2nd Classification and 2nd mark event occurrence. This alerts the LTC4269-1 that a Type 2 PSE is present. The Type 2 PSE then applies power to the PD and the LTC4269-1 charges up the reservoir capacitor C1 with a controlled inrush current. When C1 is fully charged, and the LTC4269-1 declares power good, the $\overline{T2P}$ pin presents an active low signal, or low impedance output with respect to V_{PORTN} . The $\overline{T2P}$ output becomes inactive when the LTC4269-1 input voltage falls below undervoltage lockout threshold.

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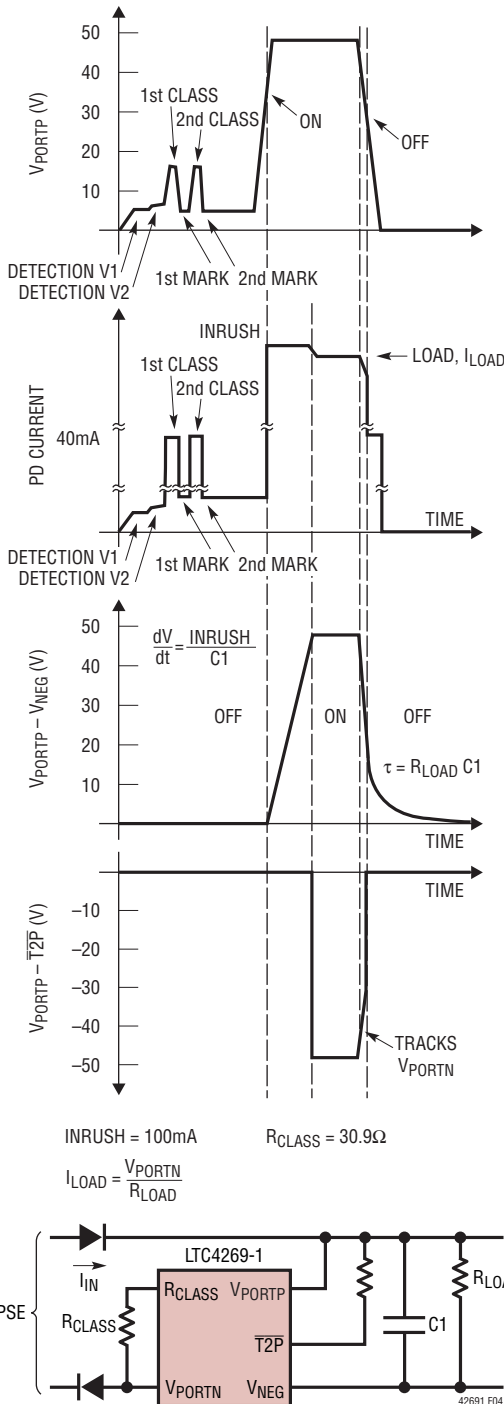


Figure 4. V_{NEG} , $T2P$ and PD Current as a Result of 2-Event Classification

SIGNATURE CORRUPT DURING MARK

As a member of the IEEE 802.3at working group, Linear Technology noted that it is possible for a Type 2 PD to receive a false indication of a 2-event classification if a PSE port is pre-charged to a voltage above the detection voltage range before the first detection cycle. The IEEE working group modified the standard to prevent this possibility by requiring a Type 2 PD to corrupt the signature resistance during the mark event, alerting the PSE not to apply power. The LTC4269-1 conforms to this standard by corrupting the signature resistance. This also discharges the port before the PSE begins the next detection cycle.

PD STABILITY DURING CLASSIFICATION

Classification presents a challenging stability problem due to the wide range of possible classification load current. The onset of the classification load current introduces a voltage drop across the cable and increases the forward voltage of the input diode bridge. This may cause the PD to oscillate between detection and classification with the onset and removal of the classification load current.

The LTC4269-1 prevents this oscillation by introducing a voltage hysteresis window between the detection and classification ranges. The hysteresis window accommodates the voltage changes a PD encounters at the onset of the classification load current, thus providing a trouble-free transition between detection and classification modes.

The LTC4269-1 also maintains a positive I-V slope throughout the classification range up to the on-voltage. In the event a PSE overshoots beyond the classification voltage range, the available load current aids in returning the PD back into the classification voltage range. (The PD input may otherwise be “trapped” by a reverse-biased diode bridge and the voltage held by the 0.1µF capacitor).

INRUSH CURRENT

Once the PSE detects and optionally classifies the PD, the PSE then applies powers on the PD. When the LTC4269-1 input voltage rises above the on-voltage threshold, LTC4269-1 connects V_{NEG} to V_{PORTN} through the internal power MOSFET.

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To control the power-on surge currents in the system, the LTC4269-1 provides a fixed inrush current, allowing C1 to ramp up to the line voltage in a controlled manner.

The LTC4269-1 keeps the PD inrush current below the PSE current limit to provide a well controlled power-up characteristic that is independent of the PSE behavior. This ensures a PD using the LTC4269-1 interoperability with any PSE.

TURN-ON/TURN-OFF THRESHOLD

The IEEE 802.3af/at specification for the PD dictates a maximum turn-on voltage of 42V and a minimum turn-off voltage of 30V. This specification provides an adequate voltage to begin PD operation, and to discontinue PD operation when the input voltage is too low. In addition, this specification allows PD designs to incorporate an ON/OFF hysteresis window to prevent start-up oscillations.

The LTC4269-1 features an ON/OFF hysteresis window (see Figure 5) that conforms with the IEEE 802.3af/at specification and accommodates the voltage drop in the cable and input diode bridge at the onset of the inrush current.

Once C1 is fully charged, the LTC4269-1 turns on its internal MOSFET and passes power to the PD load. The LTC4269-1 continues to power the PD load as long as the input voltage

does not fall below the OFF threshold. When the LTC4269-1 input voltage falls below the OFF threshold, the PD load is disconnected, and classification mode resumes. C1 discharges through the LTC4269-1 circuitry.

COMPLEMENTARY POWER GOOD

When LTC4269-1 fully charges the load capacitor (C1), power good is declared and the LTC4269-1 load can safely begin operation. The LTC4269-1 provides complementary power good signals that remain active during normal operation and are de-asserted when the input voltage falls below the OFF threshold, when the input voltage exceeds the overvoltage lockout (OVLO) threshold, or in the event of a thermal shutdown (see Figure 6).

The PWRGD pin features an open collector output referenced to V_{NEG} which can interface directly with the UVLO pin. When power good is declared and active, the PWRGD pin is high impedance with respect to V_{NEG} . An internal 14V clamp limits the PWRGD pin voltage. Connecting the PWRGD pin to the UVLO prevents the DC/DC converter

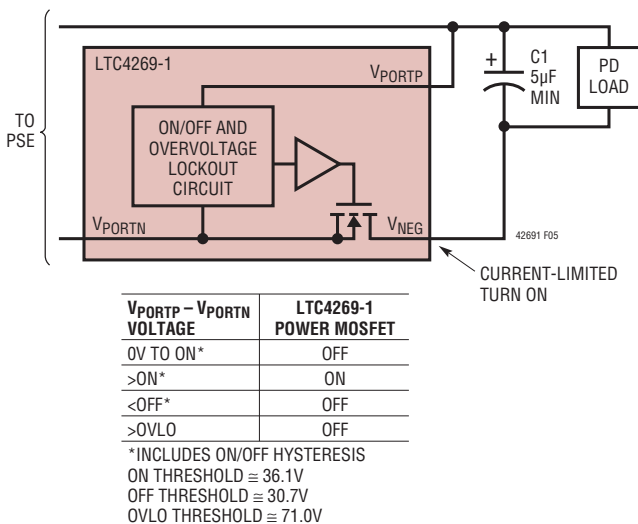


Figure 5. LTC4269-1 ON/OFF and Overvoltage Lockout

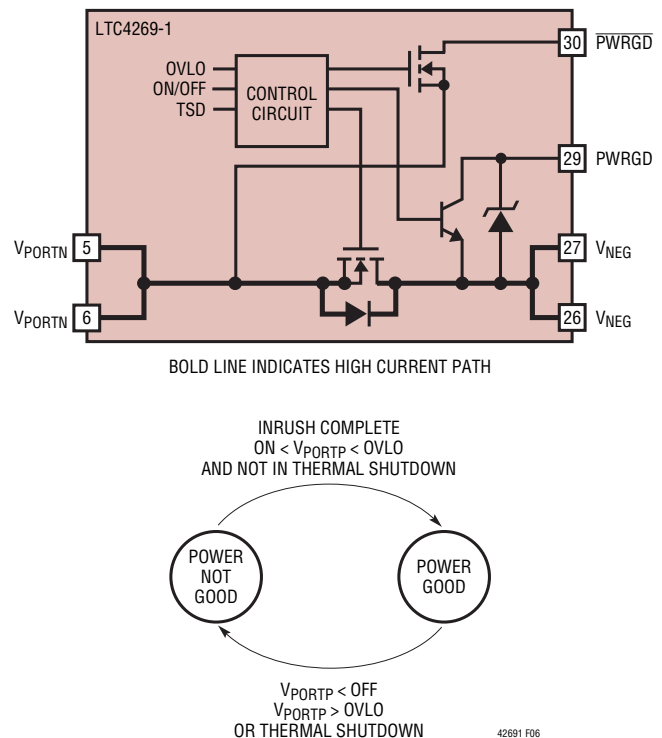


Figure 6. LTC4269-1 Power Good Functional and State Diagram

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from commencing operation before the PD interface completely charges the reservoir capacitor, C1.

The active low $\overline{\text{PWRGD}}$ pin connects to an internal, open-drain MOSFET referenced to V_{PORTN} and may be used as an indicator bit when power good is declared and active. The $\overline{\text{PWRGD}}$ pin is low impedance with respect to V_{PORTN} .

PWRGD PIN WHEN SHDN IS INVOKED

In PD applications where an auxiliary power supply invokes the SHDN feature, the PWRGD pin becomes high impedance. This prevents the PWRGD pin that is connected to the UVLO pin from interfering with the DC/DC converter operations when powered by an auxiliary power supply.

OVERVOLTAGE LOCKOUT

The LTC4269-1 includes an overvoltage lockout (OVLO) feature (Figure 6) which protects the LTC4269-1 and its load from an overvoltage event. If the input voltage exceeds the OVLO threshold, the LTC4269-1 discontinues PD operation. Normal operations resume when the input voltage falls below the OVLO threshold and when C1 is charged up.

THERMAL PROTECTION

The IEEE 802.3af/at specification requires a PD to withstand any applied voltage from 0V to 57V indefinitely. However, there are several possible scenarios where a PD may encounter excessive heating.

During classification, excessive heating may occur if the PSE exceeds the 75ms probing time limit. At turn-on, when the load capacitor begins to charge, the instantaneous power dissipated by the PD interface can be large before it reaches the line voltage. And if the PD experiences a fast input positive voltage step in its operational mode (for example, from 37V to 57V), the instantaneous power dissipated by the PD Interface can be large.

The LTC4269-1 includes a thermal protection feature which protects the LTC4269-1 from excessive heating. If the LTC4269-1 junction temperature exceeds the over-temperature threshold, the LTC4269-1 discontinues PD

operations and power good becomes inactive. Normal operation resumes when the junction temperature falls below the overtemperature threshold and when C1 is charged up.

EXTERNAL INTERFACE AND COMPONENT SELECTION

Transformer

Nodes on an Ethernet network commonly interface to the outside world via an isolation transformer. For PDs, the isolation transformer must also include a center tap on the RJ45 connector side (see Figure 7).

The increased current levels in a Type 2 PD over a Type 1 increase the current imbalance in the magnetics which can interfere with data transmission. In addition, proper termination is also required around the transformer to provide correct impedance matching and to avoid radiated and conducted emissions. Transformer vendors such as Bel Fuse, Coilcraft, Halo, Pulse, and Tyco (Table 4) can assist in selecting an appropriate isolation transformer and proper termination methods.

Table 4. Power over Ethernet Transformer Vendors

| VENDOR | CONTACT INFORMATION |
|-------------------|-------------------------------------------------------------------------------------------------------|
| Bel Fuse Inc. | 206 Van Vorst Street Jersey City, NJ 07302 Tel: 201-432-0463 www.belfuse.com |
| Coilcraft Inc. | 1102 Silver Lake Road Gary, IL 60013 Tel: 847-639-6400 www.coilcraft.com |
| Halo Electronics | 1861 Landings Drive Mountain View, CA 94043 Tel: 650-903-3800 www.haloelectronics.com |
| PCA Electronics | 16799 Schoenborn Street North Hills, CA 91343 Tel: 818-892-0761 www.pca.com |
| Pulse Engineering | 12220 World Trade Drive San Diego, CA 92128 Tel: 858-674-8100 www.pulseeng.com |
| Tyco Electronics | 308 Constitution Drive Menlo Park, CA 94025-1164 Tel: 800-227-7040 www.circuitprotection.com |

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Input Diode Bridge

Figure 2 shows how two diode bridges are typically connected in a PD application. One bridge is dedicated to the data pair while the other bridge is dedicated to the spare pair. The LTC4269-1 supports the use of either silicon or Schottky input diode bridges. However, there are trade-offs in the choice of diode bridges.

An input diode bridge must be rated above the maximum current the PD application will encounter at the temperature the PD will operate. Diode bridge vendors typically call out the operating current at room temperature, but derate the maximum current with increasing temperature. Consult the diode bridge vendors for the operating current derating curve.

A silicon diode bridge can consume over 4% of the available power in some PD applications. Using Schottky diodes can help reduce the power loss with a lower forward voltage.

A Schottky bridge may not be suitable for some high temperature PD application. The leakage current has a voltage dependency that can reduce the perceived signature resistance. In addition, the IEEE 802.3af/at specification mandates the leakage back-feeding through the unused bridge cannot generate more than 2.8V across a 100k resistor when a PD is powered with 57V.

Sharing Input Diode Bridges

At higher temperatures, a PD design may be forced to consider larger bridges in a bigger package because the maximum operating current for the input diode bridge is drastically derated. The larger package may not be acceptable in some space-limited environments.

One solution to consider is to reconnect the diode bridges so that only one of the four diodes conducts current in each package. This configuration extends the maximum operating current while maintaining a smaller package profile. Figure 7 shows how to reconnect the two diode bridges. Consult the diode bridge vendors for the derating curve when only one of four diodes is in operation.

Input Capacitor

The IEEE 802.3af/at standard includes an impedance requirement in order to implement the AC disconnect function. A 0.1 μ F capacitor (C14 in Figure 7) is used to meet this AC impedance requirement.

Input Series Resistance

Linear Technology has seen the customer community cable discharge requirements increase by nearly 500,000 times the original test levels. The PD must survive and operate

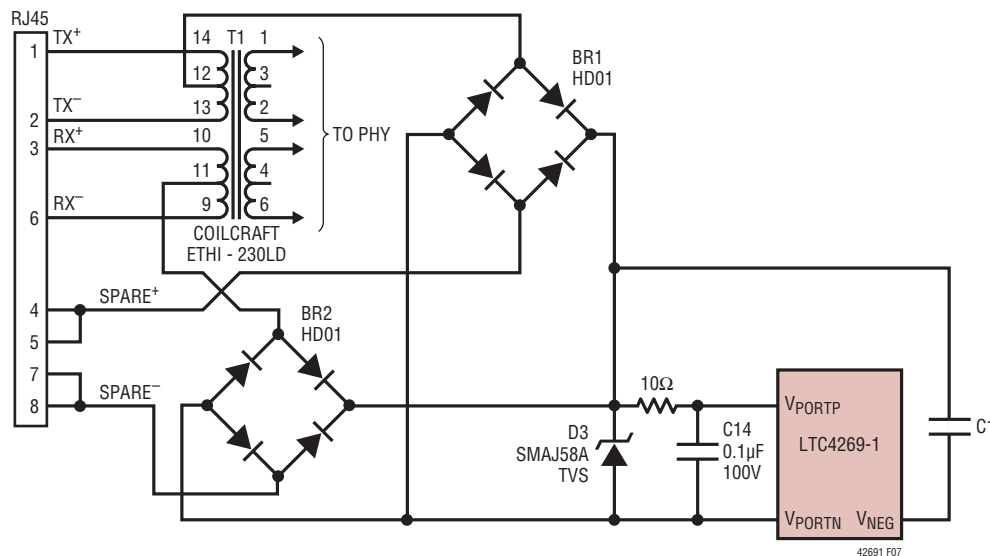


Figure 7. PD Front-End with Isolation Transformer, Diode Bridges, Capacitors, and a Transient Voltage Suppressor (TVS).

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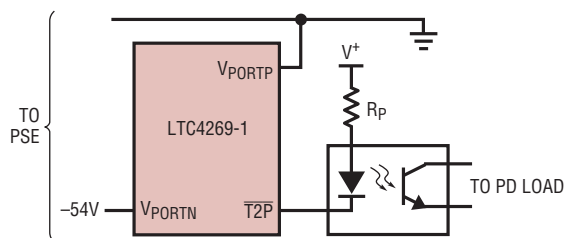
reliably not only when an initially charged cable connects and dissipates the energy through the PD front end, but also when the electrical power system grounds are subject to very high energy events (e.g. lightning strikes).

In these high energy events, adding 10Ω series resistance into the V_{PORTP} pin greatly improves the robustness of the LTC4269-1 based PD. (See Figure 7) The TVS limits the voltage across the port while the 10Ω and $0.1\mu\text{F}$ capacitance reduces the edge rate the LTC4269-1 encounters across its pin. The added 10Ω series resistance does not operationally affect the LTC4269-1 PD interface nor does it affect its compliance with the IEEE802.3 standard.

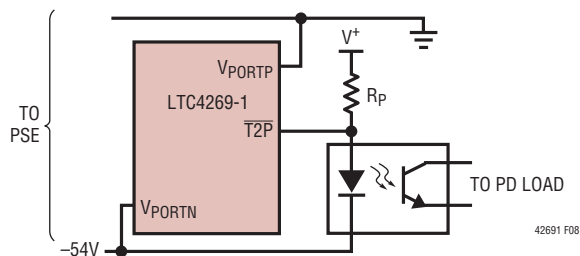
Transient Voltage Suppressor

The LTC4269-1 specifies an absolute maximum voltage of 100V and is designed to tolerate brief overvoltage events. However, the pins that interface to the outside world can routinely see excessive peak voltages. To protect the LTC4269-1, install a transient voltage suppressor (D3) between the input diode bridge and the LTC4269-1 as shown in Figure 7.

A SMAJ58A is recommended for typical PD applications. However, a SMBJ58A may be preferred in applications where the PD front end must absorb higher energy discharge events.



OPTION 1: SERIES CONFIGURATION FOR ACTIVE LOW/LOW IMPEDANCE OUTPUT



OPTION 2: SHUNT CONFIGURATION FOR ACTIVE HIGH/OPEN COLLECTOR OUTPUT

Figure 8. $\overline{\text{T2P}}$ Interface Examples

Classification Resistor (R_{CLASS})

The R_{CLASS} resistor sets the classification load current, corresponding to the PD power classification. Select the value of R_{CLASS} from Table 2 and connect the resistor between the R_{CLASS} and V_{PORTN} pins as shown in Figure 4, or float the R_{CLASS} pin if the classification load current is not required. The resistor tolerance must be 1% or better to avoid degrading the overall accuracy of the classification circuit.

Load Capacitor

The IEEE 802.3af/at specification requires that the PD maintains a minimum load capacitance of $5\mu\text{F}$ and does not specify a maximum load capacitor. However, if the load capacitor is too large, there may be a problem with inadvertent power shutdown by the PSE.

This occurs when the PSE voltage drops quickly. The input diode bridge reverses bias, and the PD load momentarily powers off the load capacitor. If the PD does not draw power within the PSE's 300ms disconnection delay, the PSE may remove power from the PD. Thus, it is necessary to evaluate the load current and capacitance to ensure that an inadvertent shutdown cannot occur.

The load capacitor can store significant energy when fully charged. The PD design must ensure that this energy is not inadvertently dissipated in the LTC4269-1. For example, if the V_{PORTP} pin shorts to V_{PORTN} while the capacitor is charged, current will flow through the parasitic body diode of the internal MOSFET and may cause permanent damage to the LTC4269-1.

$\overline{\text{T2P}}$ Interface

When a 2-event classification sequence successfully completes, the LTC4269-1 recognizes this sequence, and provides an indicator bit, declaring the presence of a Type 2 PSE. The open-drain output provides the option to use this signal to communicate to the LTC4269-1 load, or to leave the pin unconnected.

Figure 8 shows two interface options using the $\overline{\text{T2P}}$ pin and the opto-isolator. The $\overline{\text{T2P}}$ pin is active low and connects to an opto-isolator to communicate across the DC/DC converter isolation barrier. The pull-up resistor R_p is sized according to the requirements of the opto-isolator

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operating current, the pull-down capability of the $\overline{T2P}$ pin, and the choice of V^+ . V^+ for example can come from the PoE supply rail (which the LTC4269-1 V_{PORTP} is tied to), or from the voltage source that supplies power to the DC/DC converter. Option 1 has the advantage of not drawing power unless $\overline{T2P}$ is declared active.

Shutdown Interface

To corrupt the signature resistance, the SHDN pin can be driven high with respect to V_{PORTN} . If unused, connect SHDN directly to V_{PORTN} .

Auxiliary Power Source

In some applications, it is desirable to power the PD from an auxiliary power source such as a wall adapter.

Auxiliary power can be injected into an LTC4269-1-based PD at the input of the LTC4269-1 V_{PORTN} , at V_{NEG} , or even the power supply output. In addition, some PD application may desire auxiliary supply dominance or may be configured for PoE dominance. Furthermore, PD applications may also opt for a seamless transition — that is, without power disruption — between PoE and auxiliary power.

The most common auxiliary power option injects power at V_{NEG} . Figure 9 presents an example of this application. In this example, the auxiliary port injects 48V onto the line via diode D1. The components surrounding the SHDN pin are selected so that the LTC4269-1 does not disconnect power to the output until the auxiliary supply exceeds 36V.

This configuration is an auxiliary-dominant configuration. That is, the auxiliary power source supplies the power even if PoE power is already present. This configuration also provides a seamless transition from PoE to auxiliary power when auxiliary power is applied, however, the removal of auxiliary power to PoE power is not seamless.

Contact Linear Technology applications support for detail information on implementing a custom auxiliary power supply.

IEEE 802.3at SYSTEM POWER-UP REQUIREMENT

Under the IEEE 802.3at standard, a PD must operate under 13.0W as a Type 1 PD until it recognizes a Type 2 PSE. Initializing PD operation in 13.0W mode eliminates interoperability issue in case a Type 2 PD connects to a Type 1 PSE. Once the PD recognizes a Type 2 PSE, the IEEE 802.3at standard requires the PD to wait 80ms in 13.0W operation before 25.5W operation can commence.

MAINTAIN POWER SIGNATURE

In an IEEE 802.3af/at system, the PSE uses the maintain power signature (MPS) to determine if a PD continues to require power. The MPS requires the PD to periodically draw at least 10mA and also have an AC impedance less than 26.25k in parallel with 0.05 μ F. If one of these conditions is not met, the PSE may disconnect power to the PD.

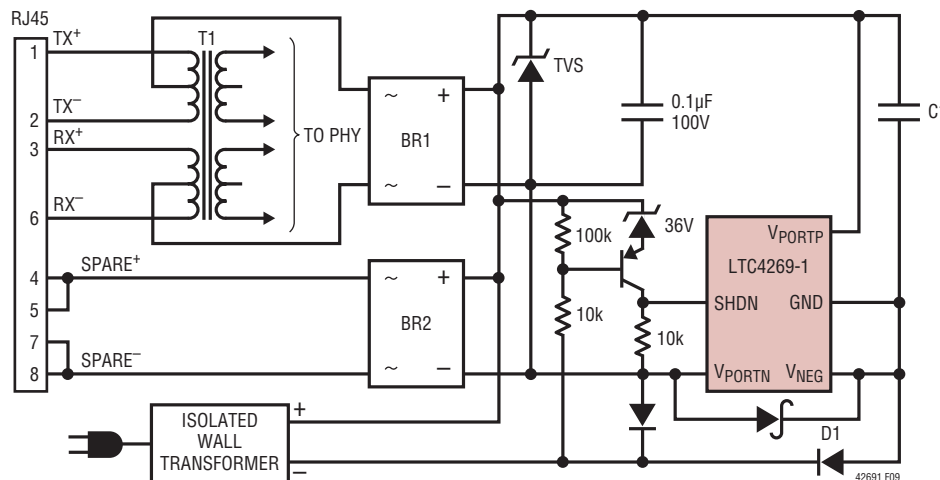


Figure 9. Auxiliary Power Dominant PD Interface Example

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SWITCHING REGULATOR OVERVIEW

The LTC4269-1 includes a current mode converter designed specifically for use in an isolated flyback topology employing synchronous rectification. The LTC4269-1 operation is similar to traditional current mode switchers. The major difference is that output voltage feedback is derived via sensing the output voltage through the transformer. This precludes the need of an opto-isolator in isolated designs, thus greatly improving dynamic response and reliability. The LTC4269-1 has a unique feedback amplifier that samples a transformer winding voltage during the flyback period and uses that voltage to control output voltage. The internal blocks are similar to many current mode controllers. The differences lie in the feedback amplifier and load compensation circuitry. The logic block also contains circuitry to control the special dynamic requirements of flyback control. For more information on the basics of current mode switcher/controllers and isolated flyback converters see Application Note 19.

Feedback Amplifier—Pseudo DC Theory

For the following discussion, refer to the simplified Switching Regulator Feedback Amplifier diagram (Figure 10A). When the primary-side MOSFET switch MP turns off, its drain voltage rises above the V_{PORTP} rail. Flyback occurs when the primary MOSFET is off and the synchronous secondary MOSFET is on. During flyback the voltage on nondriven transformer pins is determined by the secondary voltage. The amplitude of this flyback pulse, as seen on the third winding, is given as:

$$V_{FLBK} = \frac{V_{OUT} + I_{SEC} \cdot (ESR + R_{DS(ON)})}{N_{SF}}$$

$R_{DS(ON)}$ = on-resistance of the synchronous MOSFET MS

I_{SEC} = transformer secondary current

ESR = impedance of secondary circuit capacitor, winding and traces

N_{SF} = transformer effective secondary-to-flyback winding turns ratio (i.e., N_S/N_{FLBK})

The flyback voltage is scaled by an external resistive divider R1/R2 and presented at the FB pin. The feedback amplifier compares the voltage to the internal bandgap reference. The feedback amp is actually a transconductance

amplifier whose output is connected to V_{CMP} only during a period in the flyback time. An external capacitor on the V_{CMP} pin integrates the net feedback amp current to provide the control voltage to set the current mode trip point. The regulation voltage at the FB pin is nearly equal to the bandgap reference V_{FB} because of the high gain in the overall loop. The relationship between V_{FLBK} and V_{FB} is expressed as:

$$V_{FLBK} = \frac{R1+R2}{R2} \cdot V_{FB}$$

Combining this with the previous V_{FLBK} expression yields an expression for V_{OUT} in terms of the internal reference, programming resistors and secondary resistances:

$$V_{OUT} = \left(\frac{R1+R2}{R2} \cdot V_{FB} \cdot N_{SF} \right) - I_{SEC} \cdot (ESR + R_{DS(ON)})$$

The effect of nonzero secondary output impedance is discussed in further detail (see Load Compensation Theory). The practical aspects of applying this equation for V_{OUT} are found in subsequent sections of the Applications Information.

Feedback Amplifier Dynamic Theory

So far, this has been a pseudo-DC treatment of flyback feedback amplifier operation. But the flyback signal is a pulse, not a DC level. Provision is made to turn on the flyback amplifier only when the flyback pulse is present, using the enable signal as shown in the timing diagram (Figure 10b).

Minimum Output Switch On Time ($t_{ON(MIN)}$)

The LTC4269-1 affects output voltage regulation via flyback pulse action. If the output switch is not turned on, there is no flyback pulse and output voltage information is not available. This causes irregular loop response and start-up/latchup problems. The solution is to require the primary switch to be on for an absolute minimum time per each oscillator cycle. To accomplish this the current limit feedback is blanked each cycle for $t_{ON(MIN)}$. If the output load is less than that developed under these conditions, forced continuous operation normally occurs. See subsequent discussions in the Applications Information section for further details.

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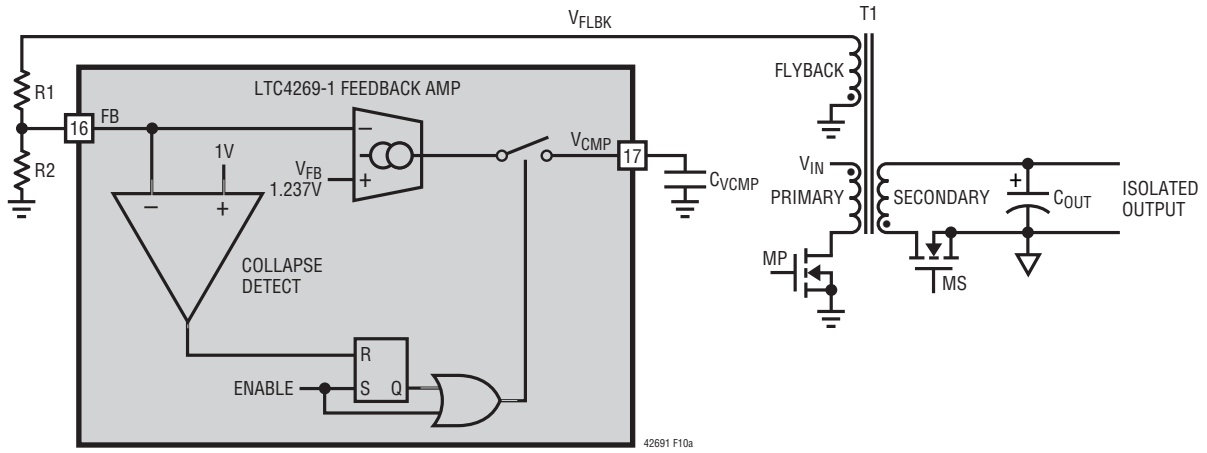


Figure 10a. LTC4269-1 Switching Regulator Feedback Amplifier

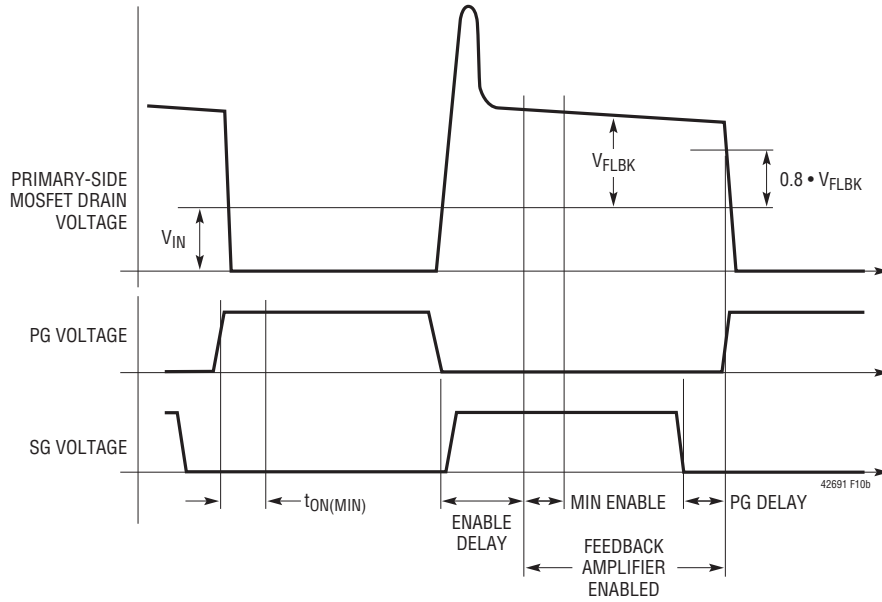


Figure 10b. LTC4269-1 Switching Regulator Timing Diagram

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Enable Delay Time (ENDLY)

The flyback pulse appears when the primary-side switch shuts off. However, it takes a finite time until the transformer primary-side voltage waveform represents the output voltage. This is partly due to rise time on the primary-side MOSFET drain node, but, more importantly, is due to transformer leakage inductance. The latter causes a voltage spike on the primary side, not directly related to output voltage. Some time is also required for internal settling of the feedback amplifier circuitry. In order to maintain immunity to these phenomena, a fixed delay is introduced between the switch turn-off command and the enabling of the feedback amplifier. This is termed “enable delay.” In certain cases where the leakage spike is not sufficiently settled by the end of the enable delay period, regulation error may result. See the subsequent sections for further details.

Collapse Detect

Once the feedback amplifier is enabled, some mechanism is then required to disable it. This is accomplished by a collapse detect comparator, which compares the flyback voltage (FB) to a fixed reference, nominally 80% of V_{FB} . When the flyback waveform drops below this level, the feedback amplifier is disabled.

Minimum Enable Time

The feedback amplifier, once enabled, stays on for a fixed minimum time period, termed “minimum enable time.” This prevents lockup, especially when the output voltage is abnormally low, e.g., during start-up. The minimum enable time period ensures that the V_{CMP} node is able to “pump up” and increase the current mode trip point to the level where the collapse detect system exhibits proper operation. This time is set internally.

Effects of Variable Enable Period

The feedback amplifier is enabled during only a portion of the cycle time. This can vary from the fixed minimum enable time described to a maximum of roughly the off switch time minus the enable delay time. Certain parameters of feedback amp behavior are directly affected by the variable enable period. These include effective transconductance and V_{CMP} node slew rate.

Load Compensation Theory

The LTC4269-1 uses the flyback pulse to obtain information about the isolated output voltage. An error source is caused by transformer secondary current flow through the synchronous MOSFET $R_{DS(ON)}$ and real life nonzero impedances of the transformer secondary and output capacitor. This was represented previously by the expression, $I_{SEC} \cdot (ESR + R_{DS(ON)})$. However, it is generally more useful to convert this expression to effective output impedance. Because the secondary current only flows during the off portion of the duty cycle (DC), the effective output impedance equals the lumped secondary impedance divided by off time DC.

Since the off-time duty cycle is equal to $1 - DC$, then:

$$R_{S(OUT)} = \frac{ESR + R_{DS(ON)}}{1 - DC}$$

where:

$R_{S(OUT)}$ = effective supply output impedance

DC = duty cycle

$R_{DS(ON)}$ and ESR are as defined previously

This impedance error may be judged acceptable in less critical applications, or if the output load current remains relatively constant. In these cases, the external FB resistive divider is adjusted to compensate for nominal expected error. In more demanding applications, output impedance error is minimized by the use of the load compensation function. Figure 11 shows the block diagram of the load compensation function. Switch current is converted to a voltage by the external sense resistor, averaged and lowpass filtered by the internal 50k resistor R_{CMPF} and the external capacitor on C_{CMP} . This voltage is impressed across the external R_{CMP} resistor by op amp A1 and transistor Q3 producing a current at the collector of Q3 that is subtracted from the FB node. This effectively increases the voltage required at the top of the R1/R2 feedback divider to achieve equilibrium.

The average primary-side switch current increases to maintain output voltage regulation as output loading increases. The increase in average current increases R_{CMP} resistor current which affects a corresponding increase

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in sensed output voltage, compensating for the IR drops. Assuming relatively fixed power supply efficiency, Eff, power balance gives:

$$P_{OUT} = \text{Eff} \cdot P_{IN}$$

$$V_{OUT} \cdot I_{OUT} = \text{Eff} \cdot V_{IN} \cdot I_{IN}$$

Average primary-side current is expressed in terms of output current as follows:

$$I_{IN} = K1 \cdot I_{OUT}$$

where:

$$K1 = \frac{V_{OUT}}{V_{IN} \cdot \text{Eff}}$$

So, the effective change in V_{OUT} target is:

$$\Delta V_{OUT} = K1 \cdot \frac{R_{SENSE}}{R_{CMP}} \cdot R1 \cdot N_{SF} \cdot \Delta I_{OUT}$$

thus:

$$\frac{\Delta V_{OUT}}{\Delta I_{OUT}} = K1 \cdot \frac{R_{SENSE}}{R_{CMP}} \cdot R1 \cdot N_{SF}$$

where:

$K1$ = dimensionless variable related to V_{IN} , V_{OUT} and efficiency, as previously explained

R_{SENSE} = external sense resistor

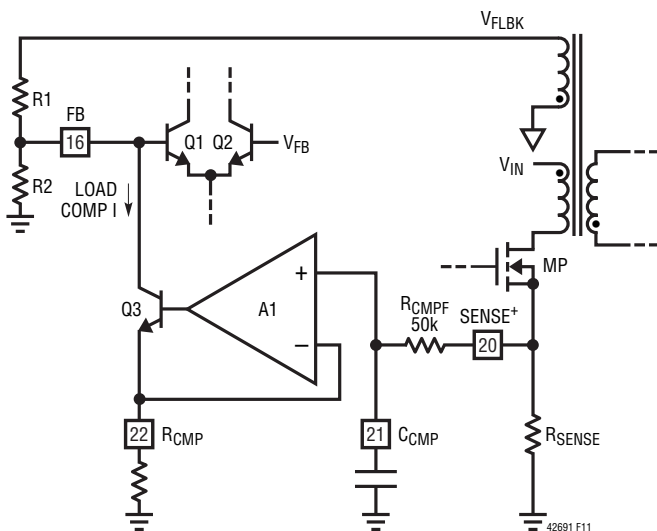


Figure 11. Load Compensation Diagram

Nominal output impedance cancellation is obtained by equating this expression with $R_{S(OUT)}$:

$$K1 \cdot \frac{R_{SENSE}}{R_{CMP}} \cdot R1 \cdot N_{SF} = \frac{ESR + R_{DS(ON)}}{1 - DC}$$

Solving for R_{CMP} gives:

$$R_{CMP} = K1 \cdot \frac{R_{SENSE} \cdot (1 - DC)}{ESR + R_{DS(ON)}} \cdot R1 \cdot N_{SF}$$

The practical aspects of applying this equation to determine an appropriate value for the R_{CMP} resistor are discussed subsequently in the Applications Information section.

Transformer Design

Transformer design/specification is the most critical part of a successful application of the LTC4269-1. The following sections provide basic information about designing the transformer and potential trade-offs. If you need help, the LTC Applications group is available to assist in the choice and/or design of the transformer.

Turns Ratios

The design of the transformer starts with determining duty cycle (DC). DC impacts the current and voltage stress on the power switches, input and output capacitor RMS currents and transformer utilization (size vs power). The ideal turns ratio is:

$$N_{IDEAL} = \frac{V_{OUT}}{V_{IN}} \cdot \frac{1 - DC}{DC}$$

Avoid extreme duty cycles, as they generally increase current stresses. A reasonable target for duty cycle is 50% at nominal input voltage.

For instance, if we wanted a 48V to 5V converter at 50% DC then:

$$N_{IDEAL} = \frac{5}{48} \cdot \frac{1 - 0.5}{0.5} = \frac{1}{9.6}$$

In general, better performance is obtained with a lower turns ratio. A DC of 45.5% yields a 1:8 ratio.

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Note the use of the external feedback resistive divider ratio to set output voltage provides the user additional freedom in selecting a suitable transformer turns ratio. Turns ratios that are the simple ratios of small integers; e.g., 1:1, 2:1, 3:2 help facilitate transformer construction and improve performance.

When building a supply with multiple outputs derived through a multiple winding transformer, lower duty cycle can improve cross regulation by keeping the synchronous rectifier on longer, and thus, keep secondary windings coupled longer. For a multiple output transformer, the turns ratio between output windings is critical and affects the accuracy of the voltages. The ratio between two output voltages is set with the formula $V_{OUT2} = V_{OUT1} \cdot N21$ where $N21$ is the turns ratio between the two windings. Also keep the secondary MOSFET $R_{DS(ON)}$ small to improve cross regulation.

The feedback winding usually provides both the feedback voltage and power for the LTC4269-1. Set the turns ratio between the output and feedback winding to provide a rectified voltage that under worst-case conditions is greater than the 11V maximum V_{CC} turn-off voltage.

$$N_{SF} > \frac{V_{OUT}}{11 + V_F}$$

where:

V_F = Diode Forward Voltage

$$\text{For our example: } N_{SF} > \frac{5}{11 + 0.7} = \frac{1}{2.34}$$

We will choose $\frac{1}{3}$

Leakage Inductance

Transformer leakage inductance (on either the primary or secondary) causes a spike after the primary-side switch turn-off. This is increasingly prominent at higher load currents, where more stored energy is dissipated. Higher flyback voltage may break down the MOSFET switch if it has too low a BV_{DSS} rating.

One solution to reducing this spike is to use a clamp circuit to suppress the voltage excursion. However, suppressing the voltage extends the flyback pulse width. If the flyback

pulse extends beyond the enable delay time, output voltage regulation is affected. The feedback system has a deliberately limited input range, roughly $\pm 50\text{mV}$ referred to the FB node. This rejects higher voltage leakage spikes because once a leakage spike is several volts in amplitude, a further increase in amplitude has little effect on the feedback system. Therefore, it is advisable to arrange the clamp circuit to clamp at as high a voltage as possible, observing MOSFET breakdown, such that leakage spike duration is as short as possible. Application Note 19 provides a good reference on clamp design.

As a rough guide, leakage inductance of several percent (of mutual inductance) or less may require a clamp, but exhibit little to no regulation error due to leakage spike behavior. Inductances from several percent up to, perhaps, ten percent, cause increasing regulation error.

Avoid double digit percentage leakage inductances. There is a potential for abrupt loss of control at high load current. This curious condition potentially occurs when the leakage spike becomes such a large portion of the flyback waveform that the processing circuitry is fooled into thinking that the leakage spike itself is the real flyback signal!

It then reverts to a potentially stable state whereby the top of the leakage spike is the control point, and the trailing edge of the leakage spike triggers the collapse detect circuitry. This typically reduces the output voltage abruptly to a fraction, roughly one-third to two-thirds of its correct value.

Once load current is reduced sufficiently, the system snaps back to normal operation. When using transformers with considerable leakage inductance, exercise this worst-case check for potential bistability:

1. Operate the prototype supply at maximum expected load current.
2. Temporarily short-circuit the output.
3. Observe that normal operation is restored.

If the output voltage is found to hang up at an abnormally low value, the system has a problem. This is usually evident by simultaneously viewing the primary-side MOSFET drain voltage to observe firsthand the leakage spike behavior.