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General Description

The MAX1211 is a 3.3V, 12-bit analog-to-digital converter (ADC) featuring a fully differential wideband trackand-hold (T/H) input, driving the internal quantizer. The MAX1211 is optimized for low power, small size, and high dynamic performance in intermediate frequency (IF) sampling applications. This ADC operates from a single 3.0V to 3.6V supply, consuming only 340mW while delivering a typical signal-to-noise ratio (SNR) performance of 66.8dB at a 175MHz input frequency. The T/H-driven input stage accepts single-ended or differential inputs. In addition to low operating power, the MAX1211 features a 0.15mW power-down mode to conserve power during idle periods.

A flexible reference structure allows the MAX1211 to use its internal precision bandgap reference or accept an externally applied reference. A common-mode reference is provided to simplify design and reduce external component count in differential analog input circuits.

The MAX1211 supports both a single-ended and differential input clock drive. Wide variations in the clock duty cycle are compensated with the ADC's internal duty-cycle equalizer.

The MAX1211 features parallel, CMOS-compatible outputs. The digital output format is pin selectable to be either two's complement or Gray code. A data-valid indicator eliminates external components that are normally required for reliable digital interfacing. A separate power input for the digital outputs accepts a voltage from 1.7V to 3.6V for flexible interfacing with various logic levels. The MAX1211 is available in a 6mm x 6mm x 0.8mm, 40-pin thin QFN package with exposed paddle (EP), and is specified for the extended industrial (-40°C to +85°C) temperature range.

Applications

IF and Baseband Communication Receivers Cellular, LMDS, Point-to-Point Microwave, MMDS, HFC, WLAN

Ultrasound and Medical Imaging

Portable Instrumentation

Low-Power Data Acquisition

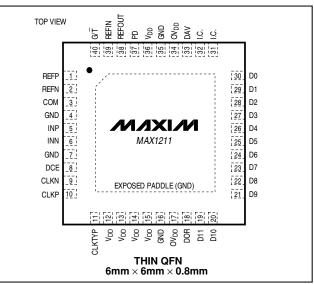
_Features

- Direct IF Sampling Up to 400MHz
- ♦ 700MHz Input Bandwidth
- Excellent Dynamic Performance 66.8dB SNR at f_{IN} = 175MHz 79.7dBc SFDR at f_{IN} = 175MHz
- 3.3V Low-Power Operation 314mW (Single-Ended Clock Mode) 340mW (Differential Clock Mode)
- Differential or Single-Ended Clock
- ♦ Accepts 20% to 80% Clock Duty Cycle
- ♦ Fully Differential or Single-Ended Analog Input
- ♦ Adjustable Full-Scale Analog Input Range
- Common-Mode Reference
- Power-Down Mode
- CMOS-Compatible Outputs in Two's Complement or Gray Code
- Data-Valid Indicator Simplifies Digital Interface
- Out-of-Range Indicator
- Miniature, 40-Pin Thin QFN Package with Exposed Paddle
- Evaluation Kit Available (Order MAX1211EVKIT)
 Ordering Information

 PART
 TEMP RANGE
 PIN-PACKAGE

 MAX1211ETL
 -40°C to +85°C
 40 Thin QFN (6mm x 6mm)

_Pin Configuration



Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

V_{DD} to GND-0.3V to +3.6V OV_{DD} to GND......-0.3V to the lower of (V_{DD} + 0.3V) and +3.6V INP, INN to GND ...-0.3V to the lower of (V_{DD} + 0.3V) and +3.6V REFIN, REFOUT, REFP, REFN,

COM to GND-0.3V to the lower of (V_{DD} + 0.3V) and +3.6V CLKP, CLKN, CLKTYP, G/T, DCE,

PD to GND-0.3V to the lower of (V_{DD} + 0.3V) and +3.6V D11-D0, I.C., DAV, DOR to GND-0.3V to (OV_{DD} + 0.3V)

Continuous Power Dissipation ($T_A = +70^{\circ}C$)

40-Pin Thin QFN 6mm x 6mm x 0.8mm	
(derated 26.3mW/°C above +70°C)	2105.3mW
Operating Temperature Range	40°C to +85°C
Junction Temperature	+150°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT$ (internal reference), $C_{REFOUT} = 0.1\mu$ F, $C_L \approx 5$ pF at digital outputs, $V_{IN} = -1000$ cm s = 0.1 μ F, $C_L \approx 1000$ cm s 0.5dBFS, CLKTYP = high, DCE = high, PD = low, G/T = low, f_{CLK} = 65MHz (50% duty cycle), $C_{REFP} = C_{REFN} = 0.1 \mu$ F, 1 μ F in parallel with 10µF between REFP and REFN, C_{COM} = 0.1µF in parallel with 2.2µF to GND, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
DC ACCURACY						
Resolution			12			Bits
Integral Nonlinearity	INL	f _{IN} = 3MHz (Note 2)		±0.30	±0.75	LSB
Differential Nonlinearity	DNL	f _{IN} = 3MHz, no missing codes over temperature (Note 2)		±0.30	±0.75	LSB
Offset Error		V _{REFIN} = 2.048V		±0.20	±0.91	%FS
Gain Error		V _{REFIN} = 2.048V		±0.3	±4.1	%FS
ANALOG INPUT (INP, INN)						
Differential Input Voltage Range	VDIFF	Differential or single-ended inputs		±1.024		V
Common-Mode Input Voltage				$V_{DD}/2$		V
Input Resistance	R _{IN}	Switched capacitor load		15		kΩ
Input Capacitance	CIN			4		pF
CONVERSION RATE						
Maximum Clock Frequency	fCLK		65			MHz
Minimum Clock Frequency					5	MHz
Data Latency		Figure 5		8.5		Clock cycles
DYNAMIC CHARACTERISTICS (Differential inp	outs, 4096-point FFT)	1			
		f _{IN} = 3MHz at -0.5dBFS (Note 3)	67.0	68.5		
Signal-to-Noise Ratio	SNR	f _{IN} = 70MHz at -0.5dBFS (Note 3)	66.8	68.3		dB
		f _{IN} = 175MHz at -0.5dBFS	64.8	66.8		
		f _{IN} = 3MHz at -0.5dBFS (Note 3)	67.0	68.4		
Signal-to-Noise and Distortion	SINAD	f _{IN} = 70MHz at -0.5dBFS (Note 3)	66.5	68.1		dB
		f _{IN} = 175MHz at -0.5dBFS	64.6	66.5		
		f _{IN} = 3MHz at -0.5dBFS (Note 3)	81.5	90.4		
Spurious-Free Dynamic Range	SFDR	f _{IN} = 70MHz at -0.5dBFS (Note 3)	74.0	82.4		dBc
		f _{IN} = 175MHz at -0.5dBFS	74.0	79.7		

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\muF, C_L \approx 5pF at digital outputs, V_{IN} = -0.5dBFS, CLKTYP = high, DCE = high, PD = low, G/T = low, f_{CLK} = 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\muF, 1\muF in parallel with 10\muF between REFP and REFN, C_{COM} = 0.1\muF in parallel with 2.2\muF to GND, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)$

SYMBOL	CONDITIONS	MIN	ΤΥΡ	MAX	UNITS		
	f _{IN} = 3MHz at -0.5dBFS (Note 3)		-89.3	-80.0			
THD	f _{IN} = 70MHz at -0.5dBFS (Note 3)		-81.3	-73.6	dBc		
	f _{IN} = 175MHz at -5dBFS		-78.7	-73.6			
HD2	f _{IN1} = 70MHz at -5dBFS	f _{IN1} = 70MHz at -5dBFS -82.4 -					
HD3	f _{IN} = 70MHz at -0.5dBFS (Note 3)		-90.9	-84.6	dBc		
IM2	$f_{IN1} = 68.5MHz$ at -7dBFS $f_{IN2} = 71.5MHz$ at -7dBFS		-82.4				
1015	f _{IN1} = 172.5MHz at -7dBFS f _{IN2} = 177.5MHz at -7dBFS		-81.2		dBc		
FPBW	Input at -0.5dBFS, -3dB rolloff		700		MHz		
t _{AD}	Figure 14		0.9		ns		
taj	Figure 14		<0.2		ps _{RMS}		
nout	INP = INN = COM		0.5		LSB _{RMS}		
	±10% beyond full scale		1		Clock cycles		
= REFOUT; V	REFP, VREFN, and VCOM are generated internal	ly)			•		
VREFOUT		1.996	2.048	2.071	V		
Vcom	V _{DD} / 2		1.65		V		
V _{REF}	V _{REF} = V _{REFP} - V _{REFN}	1.024			v		
			35		mV/mA		
TCREF			+100		ppm/°C		
	Short to V _{DD}		0.24				
	Short to GND		2.1		mA		
ICE (REFIN d	riven externally, V _{REFIN} = 2.048V, V _{REFP} , V _{REFN} ,	and V _{CO}	M are gene	erated inte	ernally)		
V _{REFIN}			2.048		V		
VREFP	(V _{DD} / 2) + (V _{REFIN} / 4)		2.162		V		
VREFN	(V _{DD} / 2) - (V _{REFIN} / 4)		1.138		V		
V _{COM}	V _{DD} / 2	1.60	1.65	1.70	V		
VREF	VREF = VREFP - VREFN	0.978	1.024	1.059	v		
			+12.5		ppm/°C		
1	Source		0.4		mA		
IREFP	Sink		1.4				
	THD HD2 HD3 IM3 FPBW taD taJ nout taJ nout taJ nout VREFOUT; V VREFOUT VCOM VREF TCREF TCREF TCREF C C C C C C C C C C C C C C C C C C C	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\muF, C_L \approx 5pF at digital outputs, V_{IN} = -0.5dBFS, CLKTYP = high, DCE = high, PD = low, G/T = low, f_{CLK} = 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\muF, 1\muF in parallel with 10\muF between REFP and REFN, C_{COM} = 0.1\muF in parallel with 2.2\muF to GND, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)$

PARAMETER	SYMBOL	CONDITIONS	MIN TYP MAX	UNITS
		Source	1.0	
Maximum COM Current	ГСОМ	Sink	0.4	mA
EFIN Input Resistance			>50	MΩ
UNBUFFERED EXTERNAL REFE	RENCE (REF	FIN = GND, V_{REFP} , V_{REFN} , and V_{COM} are a	applied externally)	
COM Input Voltage	V _{COM}	V _{DD} / 2	1.65	V
REFP Input Voltage		VREFP - VCOM	0.512	V
REFN Input Voltage		VREFN - VCOM	-0.512	V
Differential Reference Input Voltage	V _{REF}	V _{REF} = V _{REFP} - V _{REFN}	1.024	V
REFP Sink Current	IREFP	V _{REFP} = 2.162V	1.1	mA
REFN Source Current	IREFN	V _{REFN} = 1.138V	1.1	mA
COM Sink Current	Ісом		0.3	mA
REFP, REFN Capacitance			13	pF
COM Capacitance			6	pF
CLOCK INPUTS (CLKP, CLKN)				
Single-Ended Input High Threshold	VIH	CLKTYP = GND, CLKN = GND	0.8 x V _{DD}	V
Single-Ended Input Low Threshold	VIL	CLKTYP = GND, CLKN = GND	0.2 x V _{DD}	V
Differential Input Voltage Swing		CLKTYP = high	1.4	VP-P
Differential Input Common-Mode Voltage		CLKTYP = high	V _{DD} / 2	V
		DCE = OV _{DD}	20	
Minimum Clock Duty Cycle		DCE = GND	45	%
Maximum Clask Duty Cycle		DCE = OV _{DD}	80	
Maximum Clock Duty Cycle		DCE = GND	65	%
Input Resistance	RCLK	Figure 4	5	kΩ
Input Capacitance	CCLK		2	pF
DIGITAL INPUTS (CLKTYP, G/T, F	PD)			-
Input High Threshold	VIH		0.8 x OV _{DD}	v
Input Low Threshold	VIL		0.2 x OV _{DD}	V
Innut Lookogo Qurrent	ſ	V _{IH} = OV _{DD}	±5	
Input Leakage Current		$V_{IL} = 0$	±5	μA
Input Capacitance	CDIN		5	pF

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\muF, C_L \approx 5pF at digital outputs, V_{IN} = -0.5dBFS, CLKTYP = high, DCE = high, PD = low, G/T = low, f_{CLK} = 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\muF, 1\muF in parallel with 10\muF between REFP and REFN, C_{COM} = 0.1\muF in parallel with 2.2\muF to GND, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)$

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	МАХ	UNITS			
DIGITAL OUTPUTS (D0–D11, DAV, DOR)									
Output Voltage Low	Ve	D0–D11, DOR, I _{SINK} = 200μA			0.2	V			
Output-Voltage Low	V _{OL}	DAV, I _{SINK} = 600µA			0.2	v			
	Vон	D0–D11, DOR, I _{SOURCE} = 200µA	OV _{DD} - 0.2			V			
Output-Voltage High	VOH	DAV, I _{SOURCE} = 600µA	OV _{DD} - 0.2			v			
Tri-State Leakage Current	ILEAK	(Note 4)			±5	μA			
D11–D0, DOR Tri-State Output Capacitance	Соит	(Note 4)		3		pF			
DAV Tri-State Output Capacitance	C _{DAV}	(Note 4)		6		pF			
POWER REQUIREMENTS	•	•	•						
Analog Supply Voltage	V _{DD}		3.0	3.3	3.6	V			
Digital Output Supply Voltage	OV _{DD}		1.7	2.0	V _{DD} + 0.3V	V			
	Ivdd	Normal operating mode, f _{IN} = 175MHz at -0.5dBFS, CLKTYP = GND, single-ended clock		95					
Analog Supply Current		Normal operating mode, f _{IN} = 175MHz at -0.5dBFS, CLKTYP = OV _{DD} , differential clock		103	115	mA			
		Power-down mode; clock idle, PD = OV _{DD}		0.045					
		Normal operating mode, f _{IN} = 175MHz at -0.5dBFS, CLKTYP = GND, single-ended clock		314					
Analog Power Dissipation	PDISS	Normal operating mode, f _{IN} = 175MHz at -0.5dBFS, CLKTYP = OV _{DD} , differential clock		340	379	mW			
		Power-down mode, clock idle, $PD = OV_{DD}$		0.15					
Digital Output Supply Current	IOVDD	Normal operating mode, $f_{IN} = 175MHz$ at -0.5dBFS, $OV_{DD} = 2.0V$, $C_L \approx 5pF$		9.2		mA			
		Power-down mode; clock idle, $PD = OV_{DD}$		6		μΑ			

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\muF, C_L \approx 5pF$ at digital outputs, $V_{IN} = -0.5dBFS$, CLKTYP = high, DCE = high, PD = low, $G\overline{T}$ = low, $f_{CLK} = 65MHz$ (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\muF, 1 μ F in parallel with 10 μ F between REFP and REFN, C_{COM} = 0.1 μ F in parallel with 2.2 μ F to GND, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	МАХ	UNITS			
TIMING CHARACTERISTICS (Figure 5)									
Clock Pulse-Width High	tсн			7.7		ns			
Clock Pulse-Width Low	tCL			7.7		ns			
Data Valid Delay	t DAV	$C_L = 5pF$ (Note 5)		6.4		ns			
Data Setup Time Before Rising Edge of DAV	t SETUP	C _L = 5pF (Notes 3, 5)	8.5			ns			
Data Hold Time After Rising Edge of DAV	^t HOLD	C _L = 5pF (Notes 3, 5)	6.3			ns			
Wake-Up Time from Power-Down	t WAKE	V _{REFIN} = 2.048V		10		ms			

Note 1: Specifications ≥+25°C guaranteed by production test, <+25°C guaranteed by design and characterization.

Note 2: Specifications guaranteed by design and characterization. Devices tested for performance during production test.

Note 3: Guaranteed by design and characterization.

Note 4: During power-down, D11–D0, DOR, and DAV are high impedance.

Note 5: Digital outputs settle to VIH or VIL.

Typical Operating Characteristics

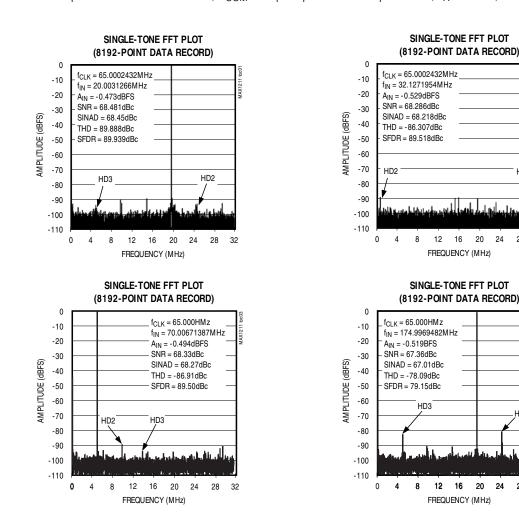
HD3

28 32

HD2

28 32

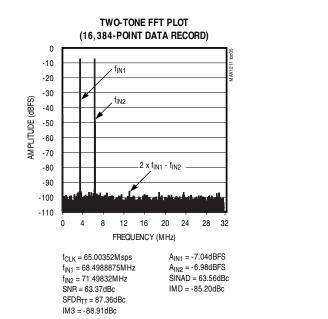
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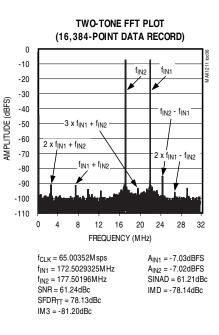


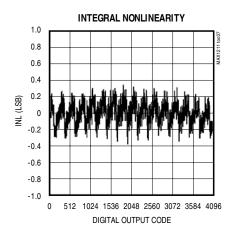
MAX1211

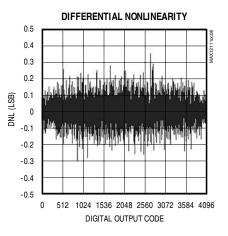
Typical Operating Characteristics (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\mu F, C_L \approx 5pF at digital outputs, differential input at -0.5dBFS, DCE = high, CLKTYP = high, PD = low, G/T = low, f_{CLK} \approx 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\mu F to GND, 1\mu F in parallel with 10\mu F between REFP and REFN, C_{COM} = 0.1\mu F in parallel with 2.2\mu F to GND, T_A = +25°C, unless otherwise noted.)$





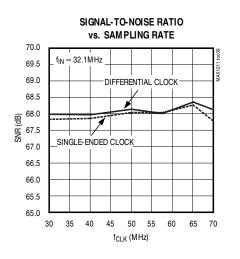


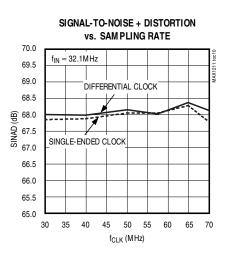




Typical Operating Characteristics (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\mu F, C_L \approx 5pF at digital outputs, differential input at -0.5dBFS, DCE = high, CLKTYP = high, PD = low, G/T = low, f_{CLK} \approx 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\mu F to GND, 1\mu F in parallel with 10\mu F between REFP and REFN, C_{COM} = 0.1\mu F in parallel with 2.2\mu F to GND, T_A = +25°C, unless otherwise noted.)$

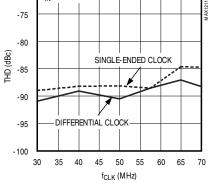




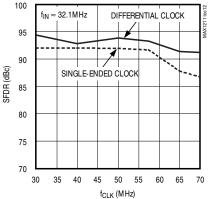
vs. SAMPLING RATE

-70

TOTAL HARM ONIC DISTORTION

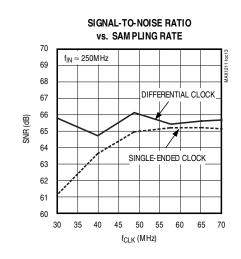


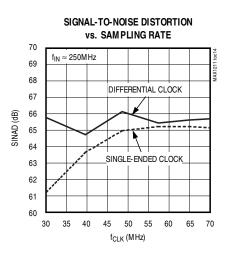
SPURIOUS-FREE DYNAMIC RANGE vs. SAM PLING RATE

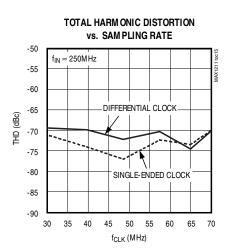


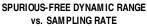
Typical Operating Characteristics (continued)

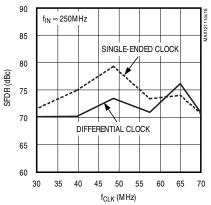
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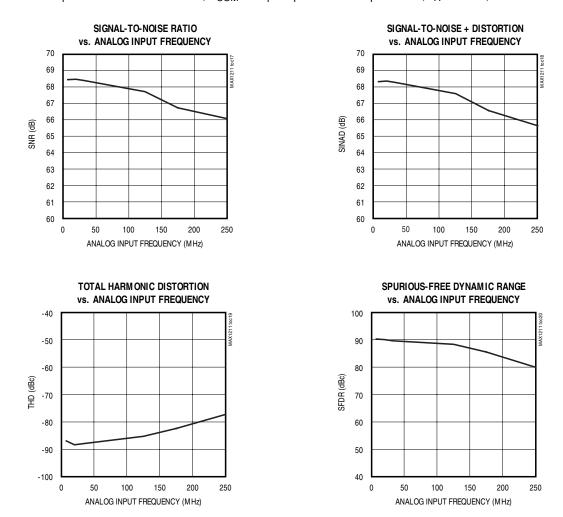






Typical Operating Characteristics (continued)

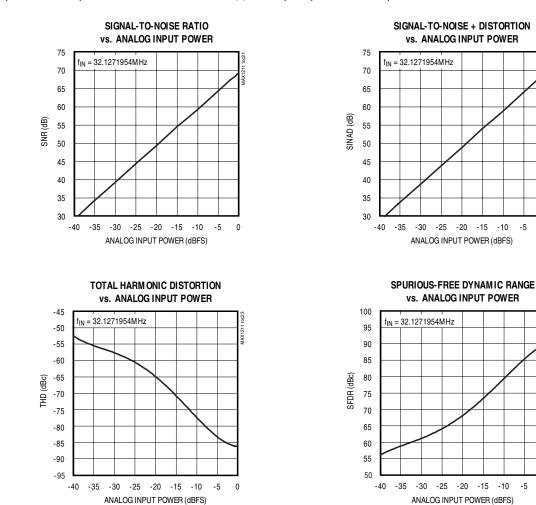
 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\mu F, C_L \approx 5pF at digital outputs, differential input at -0.5dBFS, DCE = high, CLKTYP = high, PD = low, G/T = low, f_{CLK} \approx 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\mu F to GND, 1\mu F in parallel with 10\mu F between REFP and REFN, C_{COM} = 0.1\mu F in parallel with 2.2\mu F to GND, T_A = +25°C, unless otherwise noted.)$



MAX1211

Typical Operating Characteristics (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\mu F, C_L \approx 5pF at digital outputs, differential input at -0.5dBFS, DCE = high, CLKTYP = high, PD = low, G/T = low, f_{CLK} \approx 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\mu F to GND, 1\mu F in parallel with 10\mu F between REFP and REFN, C_{COM} = 0.1\mu F in parallel with 2.2\mu F to GND, T_A = +25°C, unless otherwise noted.)$



MAX1211

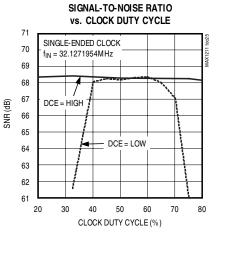
M/XI/M

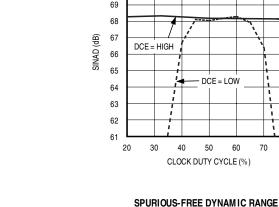
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0

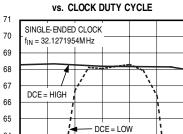
Typical Operating Characteristics (continued)

(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1µF, C_L ≈ 5pF at digital outputs, differential input at -0.5dBFS, DCE = high, CLKTYP = high, PD = low, G/T = low, f_{CLK} ≈ 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1µF to GND, 1µF in parallel with 10µF between REFP and REFN, C_{COM} = 0.1µF in parallel with 2.2µF to GND, T_A = +25°C, unless otherwise noted.)

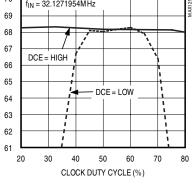


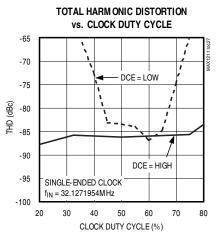


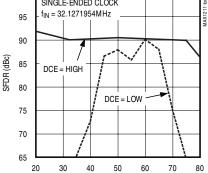
100



SIGNAL-TO-NOISE + DISTORTION





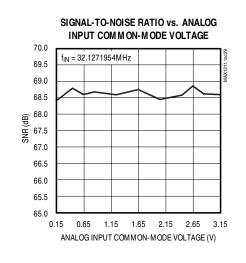


CLOCK DUTY CYCLE (%)

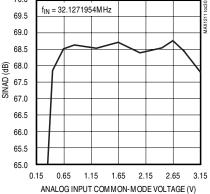
Typical Operating Characteristics (continued)

70.0

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\muF, C_L \approx 5pF at digital outputs, differential input at -0.5dBFS, DCE = high, CLKTYP = high, PD = low, G/T = low, f_{CLK} \approx 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\muF to GND, 1\muF in parallel with 10\muF between REFP and REFN, C_{COM} = 0.1\muF in parallel with 2.2\muF to GND, T_A = +25°C, unless otherwise noted.)$

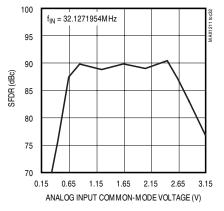


SIGNAL-TO-NOISE RATIO + DISTORTION vs. ANALOG INPUT COM M ON-M ODE VOLTAGE



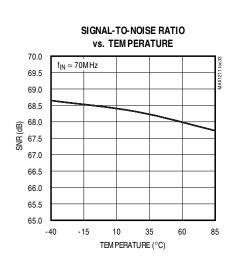
TOTAL HARM ONIC DISTORTION vs. ANALOG INPUT COM MON-MODE VOLTAGE -70 -75 -80 -80 -90 -95 -100 0.15 0.65 1.15 1.65 2.15 2.65 3.15 ANALOG INPUT COMMON-MODE VOLTAGE (V)

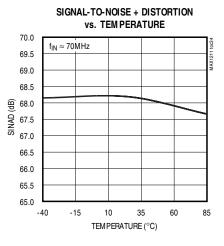
SPURIOUS-FREE DYNAMIC RANGE vs. ANALOG INPUT COMMON-MODE VOLTAGE

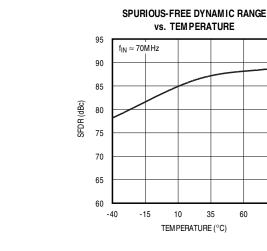


Typical Operating Characteristics (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\mu F, C_L \approx 5pF at digital outputs, differential input at -0.5dBFS, DCE = high, CLKTYP = high, PD = low, G/T = low, f_{CLK} \approx 65MHz (50% duty cycle), C_{REFP} = C_{REFN} = 0.1\mu F to GND, 1\mu F in parallel with 10\mu F between REFP and REFN, C_{COM} = 0.1\mu F in parallel with 2.2\mu F to GND, T_A = +25°C, unless otherwise noted.)$







TOTAL HARM ONIC DISTORTION

THD (dBc)

-95

-100

-40

-15

10

TEMPERATURE (°C)

35

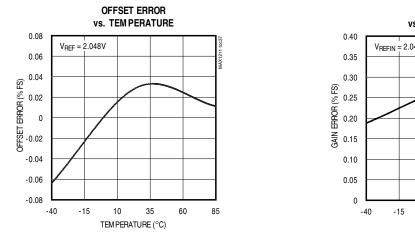
60

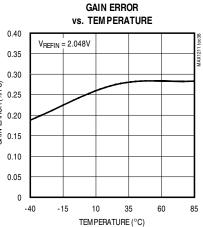
85

85

Typical Operating Characteristics (continued)

 $(V_{DD} = 3.3V, OV_{DD} = 2.0V, GND = 0, REFIN = REFOUT (internal reference), C_{REFOUT} = 0.1\mu F, C_L \approx 5pF at digital outputs, differential input at -0.5dBFS, DCE = high, CLKTYP = high, PD = low, G\overline{/T} = low, f_{CLK} \approx 65MHz$ (50% duty cycle), C_{REFP} = C_{REFN} = 0.1µF to GND, 1µF in parallel with 10µF between REFP and REFN, C_{COM} = 0.1µF in parallel with 2.2µF to GND, T_A = +25°C, unless otherwise noted.)





Pin Description

PIN	NAME	FUNCTION
1	REFP	Positive Reference I/O. Conversion range is \pm (V _{REFP} - V _{REFN}). Bypass REFP to GND with a 0.1µF capacitor. Connect a 1µF capacitor in parallel with a 10µF capacitor between REFP and REFN.
2	REFN	Negative Reference I/O. Conversion range is \pm (V _{REFP} - V _{REFN}). Bypass REFN to GND with a 0.1µF capacitor. Connect a 1µF capacitor in parallel with a 10µF capacitor between REFP and REFN.
3	СОМ	Common-Mode Voltage I/O. Bypass COM to GND with a $\ge 2.2\mu$ F capacitor in parallel with a 0.1μ F capacitor.
4, 7, 16, 35	GND	Ground. Connect all ground pins and the EP together.
5	INP	Positive Analog Input. For single-ended input operation, connect signal source to INP and connect INN to COM. For differential operation, connect the input signal between INP and INN.
6	INN	Negative Analog Input. For single-ended input operation, connect INN to COM. For differential operation, connect the input signal between INP and INN.
8	DCE	Duty-Cycle Equalizer Input. Connect DCE low (GND) to disable the internal duty-cycle equalizer. Connect DCE high (OVDD or VDD) to enable the internal duty-cycle equalizer.
9	CLKN	Negative Clock Input. In differential clock input mode (CLKTYP = OV_{DD} or V_{DD}), connect the clock signal between CLKP and CLKN. In single-ended clock mode (CLKTYP = GND), apply the clock signal to CLKP and tie CLKN to GND.
10	CLKP	Positive Clock Input. In differential clock input mode (CLKTYP = OV_{DD} or V_{DD}), connect the differential clock signal between CLKP and CLKN. In single-ended clock mode (CLKTYP = GND), apply the single-ended clock signal to CLKP and connect CLKN to GND.



_____Pin Description (continued)

PIN	NAME	FUNCTION
11	CLKTYP	Clock Type Definition Input. Connect CLKTYP to GND to define the single-ended clock input. Connect CLKTYP to OV_{DD} or V_{DD} to define the differential clock input.
12–15, 36	V _{DD}	Analog Power Input. Connect V _{DD} to a 3.0V to 3.6V power supply. Bypass V _{DD} to GND with a parallel capacitor combination of \geq 2.2µF and 0.1µF. Connect all V _{DD} pins to the same potential.
17, 34	OV _{DD}	Output Driver Power Input. Connect OV_{DD} to a 1.7V to V_{DD} power supply. Bypass OV_{DD} to GND with a parallel capacitor combination of $\ge 2.2\mu$ F and 0.1μ F.
18	DOR	Data Out-of-Range Indicator. The DOR digital output indicates when the analog input voltage is out of range. When DOR is high, the analog input is beyond its full-scale range. When DOR is low, the analog input is within its full-scale range.
19	D11	CMOS Digital Output, Bit 11 (MSB)
20	D10	CMOS Digital Output, Bit 10
21	D9	CMOS Digital Output, Bit 9
22	D8	CMOS Digital Output, Bit 8
23	D7	CMOS Digital Output, Bit 7
24	D6	CMOS Digital Output, Bit 6
25	D5	CMOS Digital Output, Bit 5
26	D4	CMOS Digital Output, Bit 4
27	D3	CMOS Digital Output, Bit 3
28	D2	CMOS Digital Output, Bit 2
29	D1	CMOS Digital Output, Bit 1
30	D0	CMOS Digital Output, Bit 0 (LSB)
31, 32	I.C.	Internally Connected. Leave I.C. unconnected.
33	DAV	Data Valid Output. The DAV is a single-ended version of the input clock that is compensated to correct for any input clock duty-cycle variations. DAV is typically used to latch the MAX1211 output data into an external back-end digital circuit.
37	PD	Power-Down Input. Force PD high for power-down mode. Force PD low for normal operation.
38	REFOUT	Internal Reference Voltage Output. For internal reference operation, connect REFOUT directly to REFIN or use a resistive divider from REFOUT to set the voltage at REFIN. Bypass REFOUT to GND with a $\geq 0.1 \mu$ F capacitor.
39	REFIN	Reference Input. V _{REFIN} = 2 x (V _{REFP} - V _{REFN}). Bypass REFIN to GND with a $\ge 0.1 \mu$ F capacitor.
40	G/T	Output Format Select Input. Connect G/\overline{T} to GND for the two's complement digital output format. Connect G/\overline{T} to OV_{DD} or V_{DD} for the Gray code digital output format.
_	EP	Exposed Paddle. EP is internally connected to GND. Externally connect EP to GND to achieve specified performance.

_Detailed Description

The MAX1211 uses a 10-stage, fully differential, pipelined architecture (Figure 1) that allows for high-speed conversion while minimizing power consumption. Samples taken at the inputs move progressively through the pipeline stages every half clock cycle. From input to output, the total clock-cycle latency is 8.5 clock cycles.

Each pipeline converter stage converts its input voltage into a digital output code. At every stage, except the last, the error between the input voltage and the digital output code is multiplied and passed along to the next pipeline stage. Digital error correction compensates for ADC comparator offsets in each pipeline stage and ensures no missing codes. Figure 2 shows the MAX1211 functional diagram.

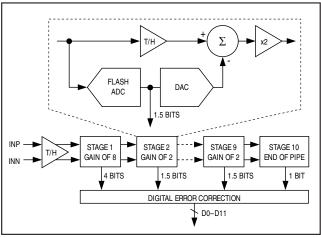


Figure 1. Pipeline Architecture—Stage Blocks

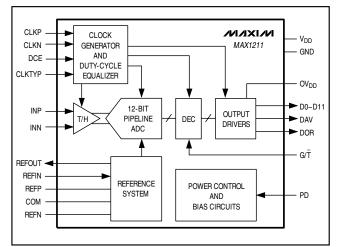


Figure 2. Functional Diagram

Figure 3 displays a simplified functional diagram of the input T/H circuits. In track mode, switches S1, S2a, S2b, S4a, S4b, S5a, and S5b are closed. The fully differential circuits sample the input signals onto the two capacitors (C2a and C2b) through switches S4a and S4b. S2a and S2b set the common mode for the operational transconductance amplifier (OTA), and open simultaneously with S1, sampling the input waveform. Switches S4a, S4b, S5a, and S5b are then opened before switches S3a and S3b connect capacitors C1a and C1b to the output of the amplifier and switch S4c is closed. The resulting differential voltages are held on capacitors C2a and C2b. The amplifiers charge capacitors C1a and C1b to the same values originally held on C2a and C2b. These values are then presented to the first-stage quantizers and isolate the pipelines from the fast-changing inputs. The wide input-bandwidth T/H amplifier allows the MAX1211 to track and sample/hold analog inputs of high frequencies well beyond Nyquist. Analog input INP to INN can be driven either differentially or single ended. For differential inputs, balance the input impedance of INP and INN and set the common-mode voltage to midsupply $(V_{DD}/2)$ for optimum performance.

Reference Output (REFOUT)

An internal bandgap reference is the basis for all the internal voltages and bias currents used in the MAX1211. The power-down logic input (PD) enables and disables the reference circuit. REFOUT has approximately $17k\Omega$ to GND when the MAX1211 is in

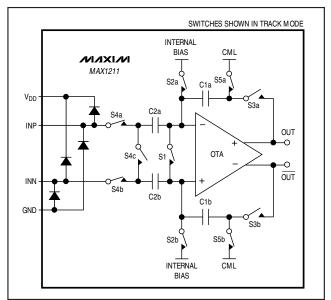


Figure 3. Internal T/H Circuit



power-down. The reference circuit requires 10ms to power up and settle when power is applied to the MAX1211 or when PD transitions from high to low.

The internal bandgap reference and buffer generate REFOUT to be 2.048V with a +100ppm/°C temperature coefficient. Connect an external $\ge 0.1 \mu$ F bypass capacitor from REFOUT to GND for stability. REFOUT sources up to 1.4mA and sinks up to 100 μ A for external circuits with a load regulation of 35mV/mA. Short-circuit protection limits IREFOUT to a 2.1mA source current when shorted to GND and a 240 μ A sink current when shorted to V_{DD}.

Analog Inputs and Reference Configurations

The MAX1211 full-scale analog input range is \pm VREF with a common-mode input range of V_{DD} / 2 \pm 0.8V. VREF is the difference between V_{REFP} and V_{REFN}. The MAX1211 provides three modes of reference operation. The voltage at REFIN (V_{REFIN}) sets the reference operation mode (Table 1).

To operate the MAX1211 with the internal reference, connect REFOUT to REFIN either with a direct short or through a resistive divider. In this mode, COM, REFP, and REFN are low-impedance outputs with V_{COM} = V_{DD} / 2, V_{REFP} = V_{DD} / 2 + V_{REFIN} / 4, and V_{REFN} = V_{DD} / 2 - V_{REFIN} / 4. The REFIN input impedance is very large (>50MΩ). When driving REFIN through a resistive divider, use resistances ≥ 10 kΩ to avoid loading REFOUT.

Buffered external reference mode is virtually identical to internal reference mode except that the reference source is derived from an external reference and not the MAX1211 REFOUT. In buffered external reference mode, apply a stable 0.7V to 2.3V source at REFIN. In this mode, COM, REFP, and REFN are low-impedance outputs with V_{COM} = V_{DD} / 2, V_{REFP} = V_{DD} / 2 + V_{REFIN} / 4, and V_{REFN} = V_{DD} / 2 - V_{REFIN} / 4.

To operate the MAX1211 in the unbuffered external reference mode, connect REFIN to GND. Connecting REFIN to GND deactivates the on-chip reference buffers for COM, REFP, and REFN. With their buffers deactivated, COM, REFP, and REFN become high-impedance inputs and must be driven through separate, external reference sources. Drive V_{COM} to V_{DD} / 2 ±5%, and drive REFP and REFN such that V_{COM} = (V_{REFP} + V_{REFN}) / 2. The analog input range is \pm (V_{REFP} - V_{REFN}).

All three modes of reference operation require the same bypass capacitor combination. Bypass COM with a 0.1 μ F capacitor in parallel with a \geq 2.2 μ F capacitor to GND. Bypass REFP and REFN each with a 0.1 μ F capacitor to GND. Bypass REFP to REFN with a 1 μ F capacitor in parallel with a 10 μ F capacitor. Place the 1 μ F capacitor as close to the device as possible. Bypass REFIN and REFOUT to GND with a 0.1 μ F capacitor.

For detailed circuit suggestions, see Figures 12 and Figures 13.

Clock Input and Clock Control Lines (CLKP, CLKN, CLKTYP)

The MAX1211 accepts both differential and singleended clock inputs. For single-ended clock input operation, connect CLKTYP to GND, CLKN to GND, and drive CLKP with the external single-ended clock signal. For differential clock input operation, connect CLKTYP to OVDD or VDD and drive CLKP and CLKN with the external differential clock signal. To reduce clock jitter, the external single-ended clock must have sharp falling edges. Consider the clock input as an analog input and route it away from any other analog inputs and digital signal lines.

CLKP and CLKN are high impedance when the MAX1211 is powered down (Figure 4).

VREFIN	REFERENCE MODE			
35% VREFOUT to 100% VREFOUT	Internal reference mode . REFIN is driven by REFOUT either through a direct short or a resistive divider. $V_{COM} = V_{DD}/2$, $V_{REFP} = V_{DD}/2 + V_{REFIN}/4$, and $V_{REFN} = V_{DD}/2 - V_{REFIN}/4$.			
0.7V to 2.3V	Buffered external reference mode . An external 0.7V to 2.3V reference voltage is applied to REFIN. $V_{COM} = V_{DD} / 2$, $V_{REFP} = V_{DD} / 2 + V_{REFIN} / 4$, and $V_{REFN} = V_{DD} / 2 - V_{REFIN} / 4$.			
<0.5V	Unbuffered external reference mode . REFP, REFN, and COM are driven by external reference sources. V _{REF} is the difference between the externally applied V _{REFP} and V _{REFN} .			

Table 1. Reference Modes

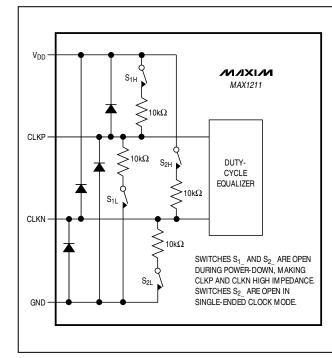


Figure 4. Simplified Clock Input Circuit

Low clock jitter is required for the specified SNR performance of the MAX1211. Analog input sampling occurs on the falling edge of the clock signal, requiring this edge to have the lowest possible jitter. Jitter limits the maximum SNR performance of any ADC according to the following relationship:

$$SNR = 20 \times log \left(\frac{1}{2 \times \pi \times f_{IN} \times t_J}\right)$$

where f_{IN} represents the analog input frequency and t_J is the total system clock jitter. Clock jitter is especially critical for undersampling applications. For example, assuming that clock jitter is the only noise source, to obtain the specified 66.8dB of SNR with an input frequency of 175MHz, the system must have less than 0.42ps of clock jitter. In actuality, there are other noise sources such as thermal noise and quantization noise that contribute to the system noise requiring the clock jitter to be less than 0.24ps to obtain the specified 66.8dB of SNR at 175MHz.

Clock Duty-Cycle Equalizer (DCE)

The MAX1211 clock duty-cycle equalizer allows for a wide 20% to 80% clock duty cycle when enabled (DCE = OV_{DD} or V_{DD}). When disabled (DCE = GND), the MAX1211 accepts a narrow 45% to 65% clock duty cycle. See the *Typical Operating Characteristics* section for dynamic performance vs. clock duty-cycle plots.

The clock duty-cycle equalizer uses a delay-locked loop to create internal timing signals that are duty-cycle independent. Due to this delay-locked loop, the MAX1211 requires approximately 100 clock cycles to acquire and lock to new clock frequencies.

Disabling the clock duty-cycle equalizer reduces the analog supply current by 1.5mA.

System Timing Requirements

Figure 5 shows the relationship between the clock, analog inputs, DAV indicator, DOR indicator, and the resulting output data. The analog input is sampled on the falling edge of the clock signal and the resulting data appears at the digital outputs 8.5 clock cycles later.

The DAV indicator is synchronized with the digital output and optimized for use in latching data into digital back-end circuitry. Alternatively, digital back-end circuitry can be latched with the falling edge of the clock.

Data Valid Output (DAV)

DAV is a single-ended version of the input clock (CLKP). The output data changes on the falling edge of DAV, and DAV rises once the output data is valid.

The state of the duty-cycle equalizer input (DCE) changes the waveform at DAV. With the duty-cycle equalizer disabled (DCE = low), the DAV signal is the inverse of the signal at CLKP delayed by 6.4ns. With the duty-cycle equalizer enabled (DCE = high), the DAV signal has a fixed pulse width that is independent of CLKP. In either case, with DCE high or low, output data at D0–D11 and DOR are valid from 8.5ns before the rising edge of DAV to 6.3ns after the rising edge of DAV, and the rising edge of DAV is synchronized to have a 6.4ns delay from the falling edge of CLKP.

DAV is high impedance when the MAX1211 is in power down (PD = high). DAV is capable of sinking and sourcing 600μ A and has three times the drive strength of D0–D11 and DOR. DAV is typically used to latch the MAX1211 output data into an external backend digital circuit.



MAX121

Table 2. Output Codes vs. Input Voltage

	-	GRAY CODE JTPUT CODE (G/T = 1)			TWO'S COMPLEMENT OUTPUT CODE $(G/\overline{T} = 0)$			
BINARY D11 → D0	DOR	HEXADECIMAL EQUIVALENT OF D11 → D0	DECIMAL EQUIVALENT OF D11 → D0 (CODE ₁₀)	BINARY D11 → D0	DOR	HEXADECIMAL EQUIVALENT OF D11 → D0	DECIMAL EQUIVALENT OF D11 → D0 (CODE ₁₀)	\V _{REFN} = 1.138V/
1000 0000 0000	1	0x800	+4095	0111 1111 1111	1	0x7FF	+2047	>+1.0235V (DATA OUT OF RANGE)
1000 0000 0000	0	0x800	+4095	0111 1111 1111	0	0x7FF	+2047	+1.0235V
1000 0000 0001	0	0x801	+4094	0111 1111 1110	0	0x7FE	+2046	+1.0230V
1100 0000 0011	0	0xC03	+2050	0000 0000 0010	0	0x002	+2	+0.0010V
1100 0000 0001	0	0xC01	+2049	0000 0000 0001	0	0x001	+1	+0.0005V
1100 0000 0000	0	0xC00	+2048	0000 0000 0000	0	0x000	0	+0.0000V
0100 0000 0000	0	0x400	+2047	1111 1111 1111	0	0xFFF	-1	-0.0005V
0100 0000 0001	0	0x401	+2046	1111 1111 1110	0	0xFFE	-2	-0.0010V
0000 0000 0001	0	0x001	+1	1000 0000 0001	0	0x801	-2047	-1.0235V
0000 0000 0000	0	0x000	0	1000 0000 0000	0	0x800	-2048	-1.0240V
0000 0000 0000	1	0x000	0	1000 0000 0000	1	0x800	-2048	<-1.0240V (DATA OUT OF RANGE)

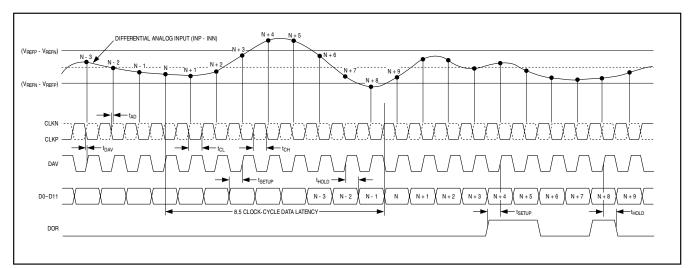


Figure 5. System Timing Diagram

M/X/M

Keep the capacitive load on DAV as low as possible (<25pF) to avoid large digital currents feeding back into the analog portion of the MAX1211 and degrading its dynamic performance. An external buffer on DAV isolates it from heavy capacitive loads. Refer to the MAX1211 evaluation kit schematic for an example of DAV driving back-end digital circuitry through an external buffer.

Data Out-of-Range Indicator (DOR)

The DOR digital output indicates when the analog input voltage is out of range. When DOR is high, the analog input is out of range. When DOR is low, the analog input is within range. The valid differential input range is from (VREFP - VREFN) to (VREFN - VREFP). Signals outside this valid differential range cause DOR to assert high as shown in Table 2.

DOR is synchronized with DAV and transitions along with output data D0–D11. There is an 8.5 clock-cycle latency in the DOR function just as with the output data (Figure 5).

DOR is high impedance when the MAX1211 is in power-down (PD = high). DOR enters a high-impedance state within 10ns of the rising edge of PD and becomes active within 10ns of PD's falling edge.

Digital Output Data (D0–D11), Output Format (G/\overline{T} **)** The MAX1211 provides a 12-bit, parallel, tri-state output bus. D0–D11 and DOR update on the falling edge of DAV and are valid on the rising edge of DAV.

The MAX1211 output data format is either Gray code or two's complement, depending on the logic input G/\overline{T} . With G/\overline{T} high, the output data format is Gray code. With G/\overline{T} low, the output data format is two's complement. See Figure 8 for a binary-to-Gray and Gray-to-binary code-conversion example.

The following equations, Table 2, Figure 6, and Figure 8 define the relationship between the digital output and the analog input:

$$V_{INP} - V_{INN} = (V_{REFP} - V_{REFN}) \times 2 \times \frac{CODE_{10} - 2048}{4096}$$

for Gray code ($G/\overline{T} = 1$).

$$V_{INP} - V_{INN} = (V_{REFP} - V_{REFN}) \times 2 \times \frac{CODE_{10}}{4096}$$

for two's complement $(G/\overline{T} = 0)$.

where $CODE_{10}$ is the decimal equivalent of the digital output code as shown in Table 2.

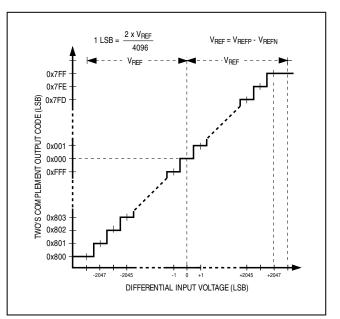


Figure 6. Two's Complement Transfer Function $(G/\overline{T} = 0)$

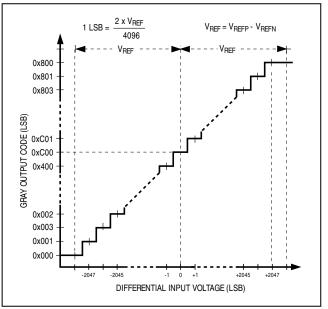


Figure 7. Gray Code Transfer Function $(G/\overline{T} = 1)$

The digital outputs D0–D11 are high impedance when the MAX1211 is in power-down (PD = high). D0–D11 go high impedance within 10ns of the rising edge of PD and become active within 10ns of PD's falling edge.



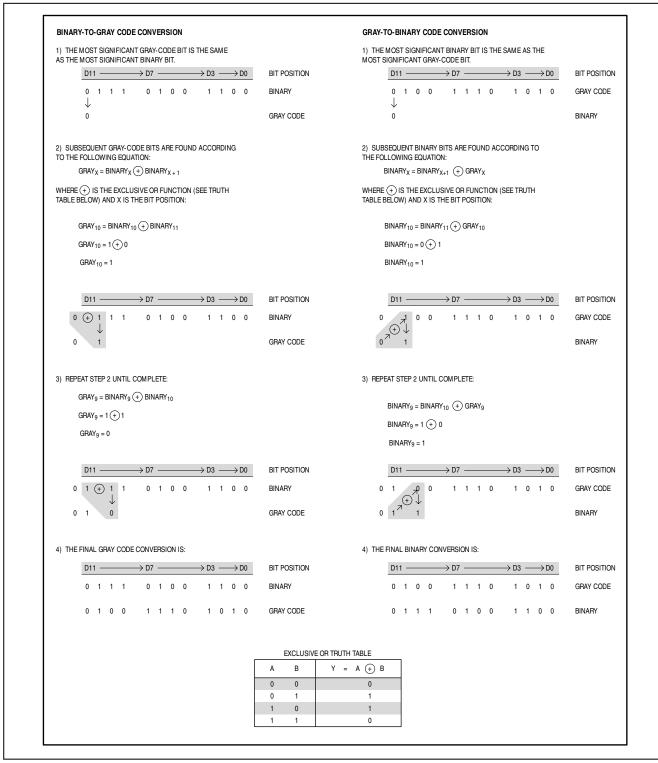


Figure 8. Binary-to-Gray and Gray-to-Binary Code Conversion



Keep the capacitive load on the MAX1211 digital outputs D0–D11 as low as possible (<15pF) to avoid large digital currents feeding back into the analog portion of the MAX1211 and degrading its dynamic performance. The addition of external digital buffers on the digital outputs isolate the MAX1211 from heavy capacitive loads. To improve the dynamic performance of the MAX1211, add 220 Ω resistors in series with the digital outputs close to the MAX1211. Refer to the MAX1211 EV kit schematic for an example of the digital outputs driving a digital buffer through 220 Ω series resistors.

Power-Down Input (PD)

The MAX1211 has two power modes that are controlled with the power-down digital input (PD). With PD low, the MAX1211 is in its normal operating mode. With PD high, the MAX1211 is in power-down mode.

The power-down mode allows the MAX1211 to efficiently use power by transitioning to a low-power state when conversions are not required. Additionally, the MAX1211 parallel output bus goes high impedance in power-down mode, allowing other devices on the bus to be accessed.

In power-down mode, all internal circuits are off, the analog supply current reduces to 0.045mA, and the digital supply current reduces to 6μ A. The following list shows the state of the analog inputs and digital outputs in power-down mode:

- INP, INN analog inputs are disconnected from the internal input amplifier (Figure 3).
- REFOUT has approximately 17kΩ to GND.
- REFP, COM, REFN go high impedance with respect to V_{DD} and GND, but there is an internal $4k\Omega$ resistor between REFP and COM, as well as an internal $4k\Omega$ resistor between REFN and COM.
- D0–D11, DOR, and DAV go high impedance.
- CLKP, CLKN clock inputs go high impedance (Figure 4).

The wake-up time from power-down mode is dominated by the time required to charge the capacitors at REFP, REFN, and COM. In internal reference mode and buffered external reference mode, the wake-up time is typically 10ms. When operating in the unbuffered external reference mode, the wake-up time is dependent on the external reference drivers.

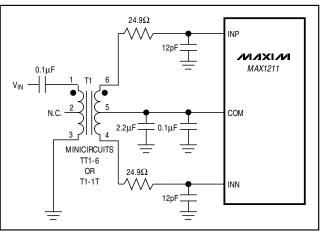


Figure 9. Transformer-Coupled Input Drive for Input Frequencies Up to Nyquist

Applications Information

Using Transformer Coupling

In general, the MAX1211 provides better SFDR and THD with fully differential input signals than singleended input drive. In differential input mode, evenorder harmonics are lower as both inputs are balanced, and each of the ADC inputs only requires half the signal swing compared to single-ended input mode.

An RF transformer (Figure 9) provides an excellent solution to convert a single-ended input source signal to a fully differential signal, required by the MAX1211 for optimum performance. Connecting the center tap of the transformer to COM provides a V_{DD} / 2 DC level shift to the input. Although a 1:1 transformer is shown, a step-up transformer can be selected to reduce the drive requirements. A reduced signal swing from the input driver, such as an op amp, can also improve the overall distortion. The configuration of Figure 9 is good for input frequencies up to Nyquist ($f_{CLK}/2$).

The circuit of Figure 10 converts a single-ended input signal to fully differential just as in Figure 9. However, Figure 10 utilizes an additional transformer to improve the common-mode rejection, allowing high-frequency signals beyond the Nyquist frequency. The two sets of 49.9 Ω termination resistors provide an equivalent 50 Ω termination to the signal source. The second set of termination resistors connects to COM, providing the correct input common-mode voltage. Two 0 Ω resistors in series with the analog inputs allow high IF input frequencies. These 0 Ω resistors can be replaced with low-value resistors to limit the input bandwidth.



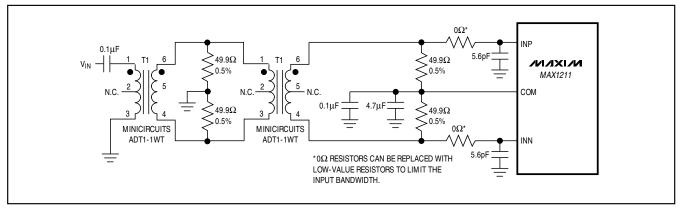


Figure 10. Transformer-Coupled Input Drive for Input Frequencies Beyond Nyquist

Single-Ended AC-Coupled Input Signal

Figure 11 shows an AC-coupled, single-ended input application. The MAX4108 provides high speed, high bandwidth, low noise, and low distortion to maintain the input signal integrity.

Buffered External Reference Drives Multiple ADCs

The buffered external reference mode allows for more control over the MAX1211 reference voltage and allows multiple converters to use a common reference. The REFIN input impedance is $>50M\Omega$.

Figure 12 shows the MAX6062 precision bandgap reference used as a common reference for multiple converters. The 2.048V output of the MAX6062 passes through a one-pole, 10Hz, lowpass filter to the MAX4250. The MAX4250 buffers the 2.048V reference before its output is applied to the REFIN input of the MAX1211. The MAX4250 provides a low offset voltage (for high gain accuracy) and a low noise level.

Unbuffered External Reference Drives Multiple ADCs

The unbuffered external reference mode allows for precise control over the MAX1211 reference and allows multiple converters to use a common reference. Connecting REFIN to GND disables the internal reference, allowing REFP, REFN, and COM to be driven directly by a set of external reference sources.

Figure 13 shows the MAX6066 precision bandgap reference used as a common reference for multiple converters. The 2.500V output of the MAX6066 is followed by a 10Hz lowpass filter and precision voltage-divider. The MAX4254 buffers the taps of this divider to provide

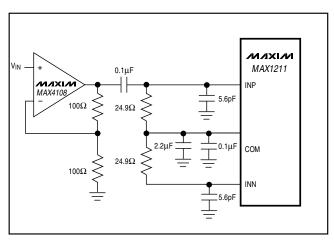


Figure 11. Single-Ended, AC-Coupled Input Drive

the +2.000V, +1.500V, and +1.000V sources to drive REFP, REFN, and COM. The MAX4254 provides a low-offset voltage and low-noise level. The individual voltage followers are connected to 10Hz lowpass filters, which filter both the reference voltage and amplifier noise to a level of $3nV/\sqrt{Hz}$. The 2.000V and 1.000V reference voltages set the differential full-scale range of the associated ADCs at ±1.000V.

The common power supply for all active components removes any concern regarding power-supply sequencing when powering up or down.

With the outputs of the MAX4254 matching better than 0.1%, the buffers and subsequent lowpass support as many as eight ADCs.

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