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Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



EVALUATION KIT
AVAILABLE



±15kV ESD-Protected Touch-Screen Controllers Include DAC and Keypad Controller

MAX1233/MAX1234

General Description

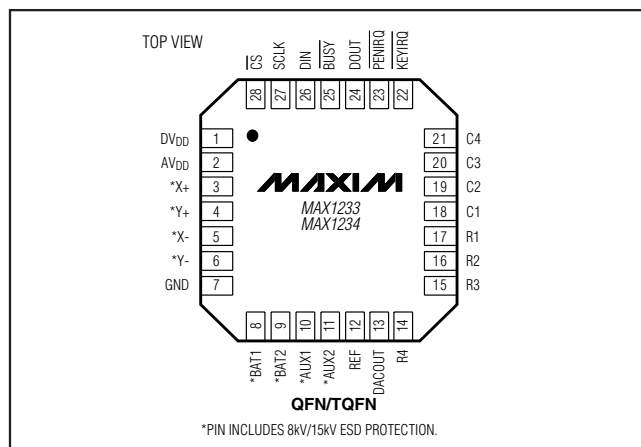
The MAX1233/MAX1234 are complete PDA controllers in 5mm × 5mm, 28-pin QFN and TQFN packages. They feature a 12-bit analog-to-digital converter (ADC), low on-resistance switches for driving resistive touch screens, an internal +1.0V/+2.5V or external reference, ±2°C accuracy, on-chip temperature sensor, direct +6V battery monitor, keypad controller, 8-bit digital-to-analog converter (DAC), and a synchronous serial interface. Each of the keypad controllers' eight row and column inputs can be reconfigured as general-purpose parallel I/O pins (GPIO). All analog inputs are fully ESD protected, eliminating the need for external TransZorb™ devices.

The MAX1233/MAX1234 offer programmable resolution and sampling rates. Interrupts from the devices alert the host processor when data is ready, when the screen is touched, or a key press is detected. Software-configurable scan control and internal timers give the user flexibility without burdening the host processor. These devices consume only 260µA at the maximum sampling rate of 50ksps. Supply current falls to below 50µA for sampling rates of 10ksps. The MAX1233/MAX1234 are guaranteed over the -40°C to +85°C temperature range.

Applications

Personal Digital Assistants
Pagers
Touch-Screen Monitors
Cellular Phones
MP3 Players
Portable Instruments
Point-of-Sale Terminals

Pin Configuration



Features

- ◆ ESD-Protected Analog Inputs
 - ±15kV IEC 1000-4-2 Air-Gap Discharge
 - ±8kV IEC 1000-4-2 Contact Discharge
- ◆ Single-Supply Operation
 - +2.7V to +3.6V (MAX1233)
 - +4.75V to +5.25V (MAX1234)
- ◆ 4-Wire Touch-Screen Interface
- ◆ Internal +1.0V/+2.5V Reference or External Reference (+1.0V to AVDD)
- ◆ SPI™/QSPI™/MICROWIRE™-Compatible 10MHz Serial Interface
- ◆ 12-Bit, 50ksps ADC Measures
 - Resistive Touch-Screen Position and Pressure
 - Two Auxiliary Analog Inputs
 - Two Battery Voltages (0.5V to 6V)
 - On-Chip Temperature
- ◆ 8-Bit DAC for LCD Bias Control
- ◆ 4 × 4 Keypad Programmable Controller Offers Up to Eight GPIO Pins
- ◆ Automatic Detection of Screen Touch, Key Press, and End of Conversion
- ◆ Programmable 8-, 10-, 12-Bit Resolution
- ◆ Programmable Conversion Rates
- ◆ AutoShutdown™ Between Conversions
- ◆ Low Power
 - 260µA at 50ksps
 - 50µA at 10ksps
 - 6µA at 1ksps
 - 0.3µA Shutdown Current
- ◆ 28-Pin 5mm × 5mm QFN and TQFN Packages

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX1233EGI	-40°C to +85°C	28 QFN (5mm × 5mm)
MAX1233ETI	-40°C to +85°C	28 TQFN (5mm × 5mm)
MAX1234EGI	-40°C to +85°C	28 QFN (5mm × 5mm)
MAX1234ETI	-40°C to +85°C	28 TQFN (5mm × 5mm)

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SPI and QSPI are trademarks of Motorola, Inc.

MICROWIRE is a trademark of National Semiconductor Corp.

AutoShutdown is a trademark of Maxim Integrated Products, Inc.



Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

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ABSOLUTE MAXIMUM RATINGS

AV_{DD} to GND.....-0.3V to +6V
 DV_{DD} to AV_{DD}.....-0.3V to +0.3V
 Digital Inputs/Outputs to GND.....-0.3V to (DV_{DD} + 0.3V)
 X+, Y+, X-, Y-, AUX1, AUX2,
 and REF to GND.....-0.3V to (AV_{DD} + 0.3V)
 BAT1, BAT2 to GND.....-0.3V to +6V
 Maximum ESD per IEC 1000-4-2 (per MIL STD-883 HBM)
 X+, X-, Y+, Y-, AUX1, AUX2, BAT1, BAT2.....±15kV

All Other Pins.....±2.5kV
 Maximum Current into Any Pin.....50mA
 Continuous Power Dissipation (T_A = +70°C)
 28-Pin QFN (derate 28.5mW/°C above +70°C).....2W
 28-Pin TQFN (derate 28.5mW/°C above +70°C).....2W
 Operating Temperature Range.....-40°C to +85°C
 Storage Temperature Range.....-60°C to +150°C
 Lead Temperature (soldering, 10s).....+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(DV_{DD} = AV_{DD} = +2.7V to +3.6V (MAX1233), DV_{DD} = AV_{DD} = +4.75V to +5.25V (MAX1234), external reference V_{REF} = 2.5V (MAX1233), V_{REF} = 4.096V (MAX1234); f_{SCLK} = 10MHz, f_{SAMPLE} = 50ksps, 12-bit mode, 0.1µF capacitor at REF, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
ANALOG-TO-DIGITAL CONVERTER							
DC ACCURACY (Note 1)							
Resolution		Software-programmable 8/10/12 bit				12	Bits
No Missing Codes				11			Bits
Relative Accuracy (Note 2)	INL	12-bit mode			±0.8	±2	LSB
		10-bit and 8-bit modes			±0.5		
Differential Nonlinearity	DNL	12-bit mode			±0.8	±2	LSB
		10-bit and 8-bit modes			±0.5		
Offset Error		12-bit mode			±0.5	±4	LSB
		10-bit and 8-bit modes			±0.5		
Gain Error (Note 3)		12-bit mode			±0.5	±4	LSB
		10-bit mode			±0.5		
		8-bit mode			±0.5		
Total Unadjusted Error	TUE	12-bit mode			±2		LSB
		10-bit and 8-bit modes			±1		
Offset Temperature Coefficient					±0.4		ppm/°C
Gain Temperature Coefficient					±0.4		ppm/°C
Channel-to-Channel Offset					±0.1		LSB
Channel-to-Channel Gain Matching					±0.1		LSB
Noise		Including internal V _{REF}			50		µV _{RMS}
Power-Supply Rejection	PSR	Full-scale input	MAX1233 AV _{DD} = DV _{DD} = +2.7V to +3.6V		±0.4		mV
			MAX1234 AV _{DD} = DV _{DD} = +5V ±5%		±0.3		
DYNAMIC SPECIFICATIONS (1kHz SINE WAVE, V_{IN} = 2.5V_{p-p} FOR MAX1233, V_{IN} = 4.096V_{p-p} FOR MAX1234, 50ksps, f_{SCLK} = 10MHz)							
Signal-to-Noise Plus Distortion	SINAD				69		dB

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ELECTRICAL CHARACTERISTICS (continued)

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Total Harmonic Distortion	THD			-84		dB
Spurious-Free Dynamic Range	SFDR			84		dB
Full-Power Bandwidth		-3dB point		0.5		MHz
Full-Linear Bandwidth		SINAD > 67dB		50		kHz
CONVERSION RATE						
Internal Oscillator Frequency			8		11.5	MHz
Aperture Delay				30		ns
Aperture Jitter				<50		ps
Maximum Serial Clock Frequency	f _{SCLK}		10			MHz
Duty Cycle			30		70	%
AUXILIARY ANALOG INPUTS (AUX1, AUX2)						
Input Voltage Range			0		V _{REF}	V
Input Leakage Current		Channel not selected or conversion stopped		±0.1	±1	μA
Input Capacitance				34		pF
BATTERY MONITOR INPUTS (BAT1, BAT2)						
Input Voltage Range			0.5		6.0	V
Input Impedance		Sampling battery		10		kΩ
		Battery monitor OFF		1		GΩ
Accuracy		Internal reference	-3		+3	%
TEMPERATURE MEASUREMENT						
Temperature Range			-40		+85	°C
Resolution		Differential method (Note 4)		1.6		°C
		Single measurement method (Note 5)		0.3		
Accuracy		Differential method (Note 4)		±3		°C
		Single measurement method (Note 5)		±2		
INTERNAL ADC REFERENCE						
Reference Output Voltage	V _{REF}	2.5V mode, T _A = +25°C	2.470	2.500	2.530	V
		1.0V mode, T _A = +25°C	0.980	1.000	1.020	
Output Tempco	TCV _{REF}			60		ppm/°C
Reference Output Impedance		Normal operation		250		Ω
Reference Short-Circuit Current				18		mA
EXTERNAL ADC REFERENCE (INTERNAL REFERENCE DISABLED, REFERENCE APPLIED TO REF)						
Reference Input Voltage Range		(Note 6)	1.0		V _{DD}	V
Input Impedance		\overline{CS} = GND or V _{DD}		1		GΩ
Input Current		V _{REF} = +2.5V at 50ksps (MAX1233)		5	10	μA
		V _{REF} = +4.096V at 50ksps (MAX1234)		8	15	
		Shutdown/between conversions		±0.1		

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ELECTRICAL CHARACTERISTICS (continued)

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DIGITAL-TO-ANALOG CONVERTER						
DC ACCURACY						
Resolution					8	Bits
Integral Linearity Error	INL	(Note 7)			±1.0	LSB
Differential Linearity Error	DNL	No missing codes			±1.0	LSB
Offset Error	V _{OS}	(Note 8)		±1	±25	mV
Offset Error Temperature Coefficient				1		ppm/°C
Full-Scale Error		Code = 255, no load			5	%
Full-Scale Error Temperature Coefficient		Code = 255, no load		±10		ppm/°C
DYNAMIC PERFORMANCE						
Voltage Output Slew Rate		Positive and negative		0.4		V/μs
Output Settling Time		0.5LSB; 50kΩ and 50pF load (Note 9)		20		μs
Glitch Impulse		Code 127 to 128		40		nV/s
Wake-Up Time		From shutdown		50		μs
DAC OUTPUT						
Internal DAC Reference	V _{REFDAC}	(Note 10)	0.85 × AV _{DD}	0.9 × AV _{DD}	0.95 × AV _{DD}	V
Output Load Regulation		Code = 255; 0 to 100μA	0.5			LSB
		Code = 0; 0 to 100μA	0.5			
Output Resistance		Power-down mode		1.0		MΩ
TOUCH-SCREEN CONTROLLER						
On-Resistance		Y+, X+	7			Ω
		Y-, X-	9			
Touch-Detection Internal Pullup Resistance		X+ to AV _{DD}		1		MΩ
KEYPAD CONTROLLER						
Pullup Resistance		C4, C3, C2, C1 (Note 11)		0.5		kΩ
Pulldown Resistance		R4, R3, R2, R1 (Note 11)		16		kΩ
DIGITAL INTERFACE						
DIGITAL INPUTS (SCLK, $\overline{\text{CS}}$, DIN, R₋, C₋)						
Input Voltage Low	V _{IL}				0.3 × DV _{DD}	V
Input Voltage High	V _{IH}		0.7 × DV _{DD}			V
Input Leakage Current	I _L			±0.1	±1	μA

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MAX1233/MAX1234

ELECTRICAL CHARACTERISTICS (continued)

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Capacitance	C _{IN}			15		pF
DIGITAL OUTPUT (DOUT)						
Output Voltage Low	V _{OL}	I _{SINK} = 2mA			0.4	V
		I _{SINK} = 4mA			0.8	
Output Voltage High	V _{OH}	I _{SOURCE} = 1.5mA	DV _{DD} - 0.5			V
DIGITAL OUTPUT (<u>BUSY</u>, <u>PENIRQ</u>, <u>KEYIRQ</u>, <u>R_</u>, <u>C_</u>)						
Output Voltage Low	V _{OL}	I _{SINK} = 0.2mA			0.4	V
Output Voltage High	V _{OH}	I _{SOURCE} = 0.2mA	DV _{DD} - 0.5			V
POWER REQUIREMENTS						
Supply Voltage (Note 12)	AV _{DD} / DV _{DD}	MAX1233	2.7	3	3.6	V
		MAX1234	4.75	5	5.25	
Analog and Digital Supply Current	I _{AVDD} + I _{DVDD}	Idle; all blocks shut down		0.5	5	μA
		Only ADC on; f _{SAMPLE} = 20ksps		150	500	
		Only DAC on; no load		150	230	
		Only internal reference on		670	900	
TIMING CHARACTERISTICS						
SCLK Clock Period	t _{CP}		100			ns
SCLK Pulse Width High	t _{CH}		40			ns
SCLK Pulse Width Low	t _{CL}		40			ns
DIN to SCLK Rise Setup	t _{DS}		40			ns
SCLK Rise to DIN Hold	t _{DH}		0			ns
SCLK Fall to DOUT Valid	t _{DOV}	C _{LOAD} = 50pF			40	ns
\overline{CS} Fall to DOUT Enabled	t _{DV}	C _{LOAD} = 50pF			45	ns
\overline{CS} Rise to DOUT Disabled	t _{DOD}	C _{LOAD} = 50pF			40	ns
\overline{CS} Fall to SCLK Rise	t _{CSS}		40			ns
\overline{CS} Fall to SCLK Ignored	t _{CSH}		0			ns
SCLK Rise to R _J /C _J Data Valid	t _{GPO}	C _{LOAD} = 50pF (Note 13)			230	ns
\overline{CS} Pulse Width High	t _{CSW}		40			ns

Note 1: Tested at DV_{DD} = AV_{DD} = +2.7V (MAX1233), DV_{DD} = AV_{DD} = +5V (MAX1234).

Note 2: Relative accuracy is the deviation of the analog value at any code from its theoretical value after the offset and gain errors have been removed.

Note 3: Offset nulled.

Note 4: Difference between TEMP1 and TEMP2; temperature in °K = (V_{TEMP2} - V_{TEMP1}) × 2680°K/V. No calibration is necessary.

Note 5: Temperature coefficient is -2.1mV/°C. Determine absolute temperature by extrapolating from a calibrated value.

Note 6: ADC performance is limited by the conversion noise floor, typically 300μV_{P-P}. An external reference below 2.5V can compromise the ADC performance.

Note 7: Guaranteed from code 5 to 255.

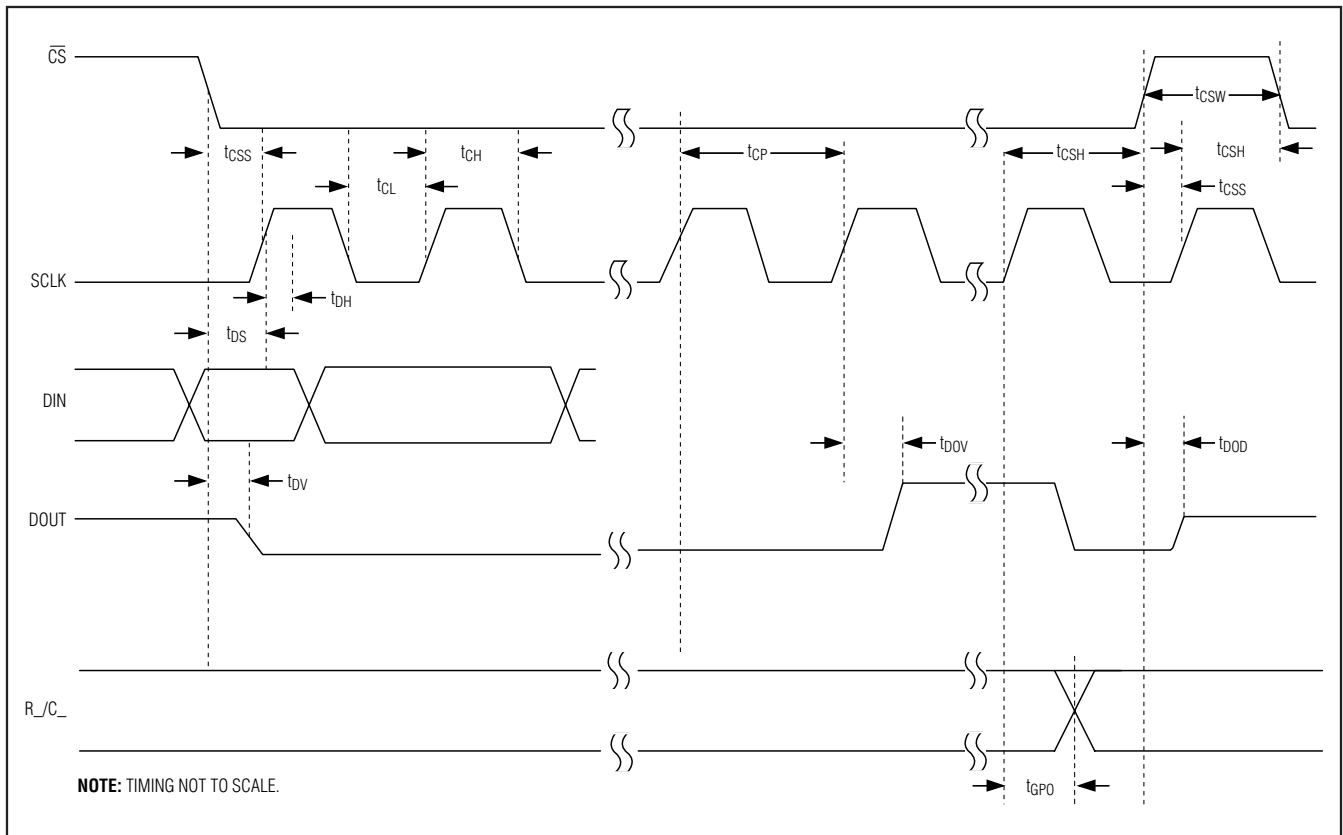
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- Note 8:** The offset value extrapolated from the range over which the INL is guaranteed.
- Note 9:** Output settling time is measured by stepping from code 5 to 255, and from code 255 to 5.
- Note 10:** Actual output voltage at full scale is 255/256 × V_{REFDAC}.
- Note 11:** Resistance is open when configured as GPIO or in shutdown.
- Note 12:** AV_{DD} and DV_{DD} should not differ by more than 300mV.
- Note 13:** When configured as GPIO.

Timing Diagram

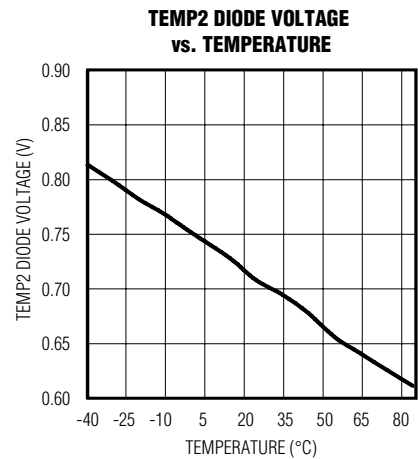
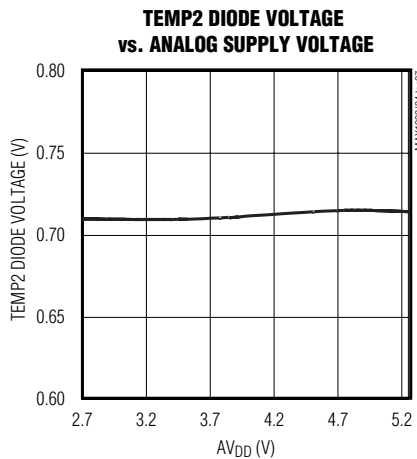
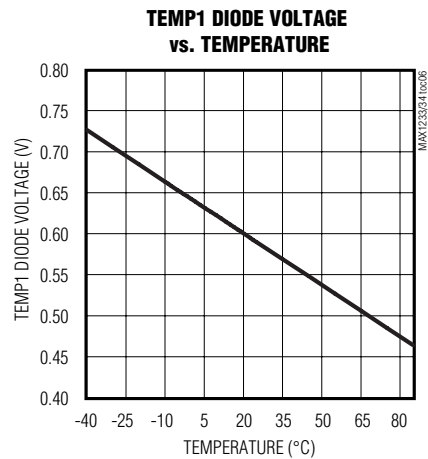
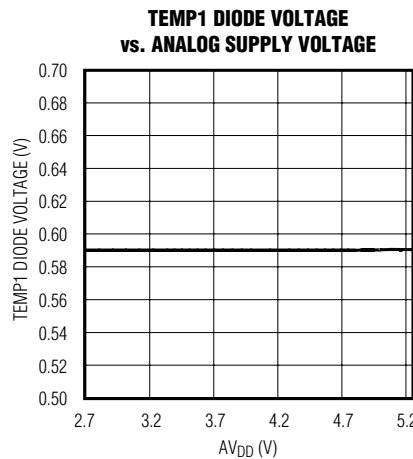
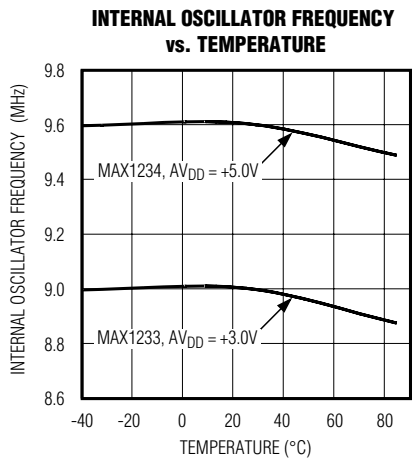
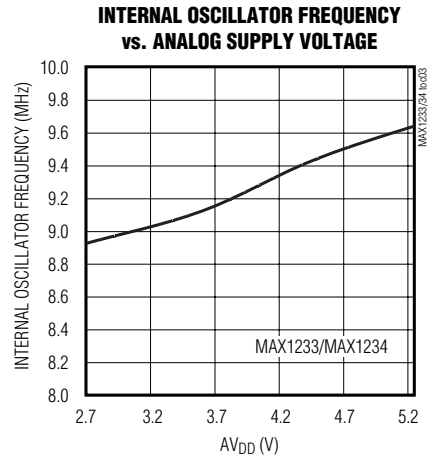
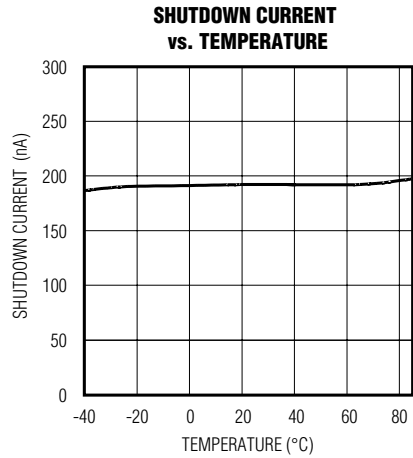
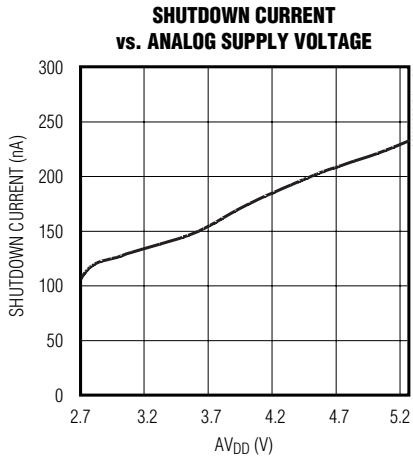


±15kV ESD-Protected Touch-Screen Controllers Include DAC and Keypad Controller

Typical Operating Characteristics

($AV_{DD} = DV_{DD} = 3V$ (MAX1233) or $5V$ (MAX1234), external $V_{REF} = +2.5V$ (MAX1233), external $V_{REF} = +4.096V$ (MAX1234), $f_{SCLK} = 10MHz$ (50% duty cycle), $f_{SAMPLE} = 20ksps$, $C_{LOAD} = 50pF$, $0.1\mu F$ capacitor at REF, $T_A = +25^\circ C$, unless otherwise noted.)

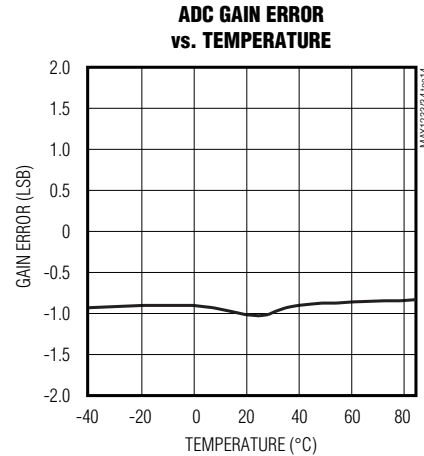
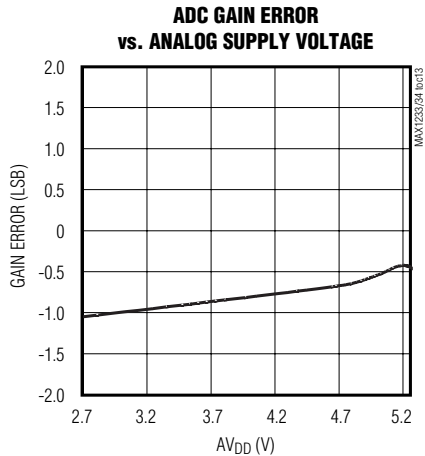
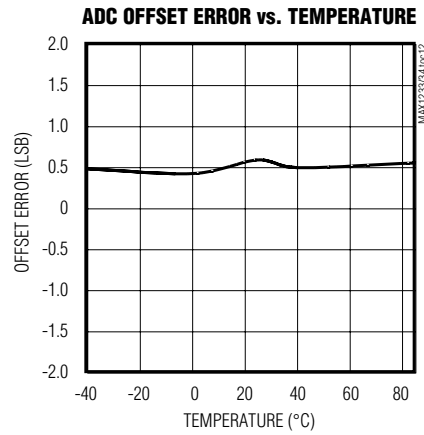
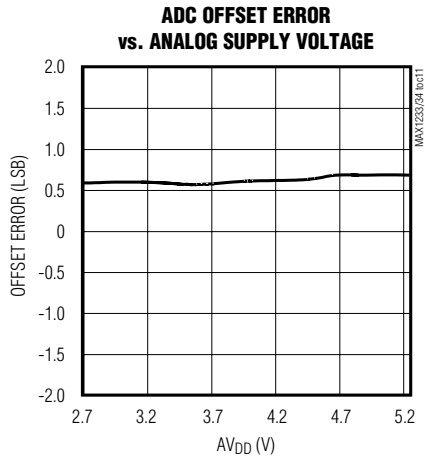
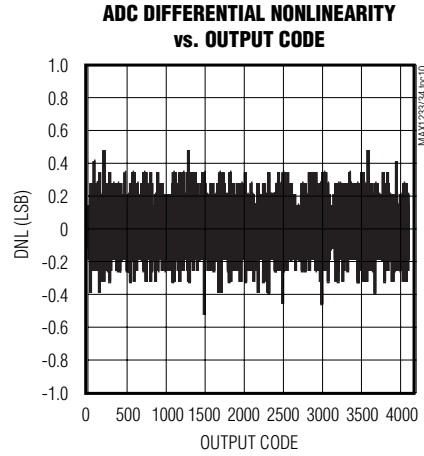
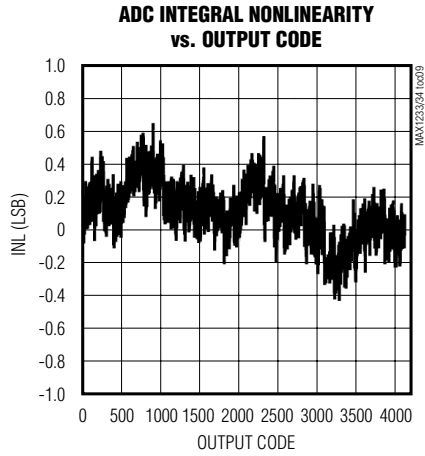
MAX1233/MAX1234



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Typical Operating Characteristics (continued)

(AV_{DD} = DV_{DD} = 3V (MAX1233) or 5V (MAX1234), external V_{REF} = +2.5V (MAX1233), external V_{REF} = +4.096V (MAX1234), f_{SCLK} = 10MHz (50% duty cycle), f_{SAMPLE} = 20ksps, C_{LOAD} = 50pF, 0.1μF capacitor at REF, T_A = +25°C, unless otherwise noted.)

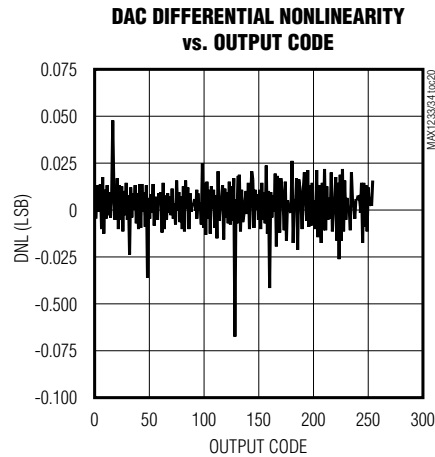
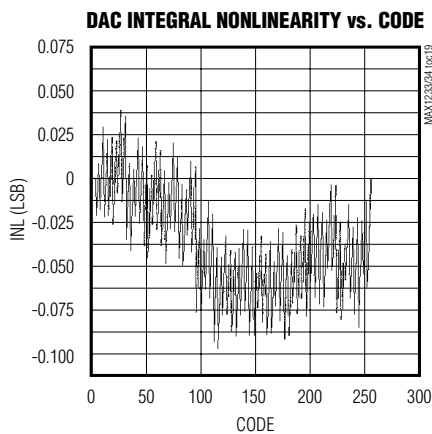
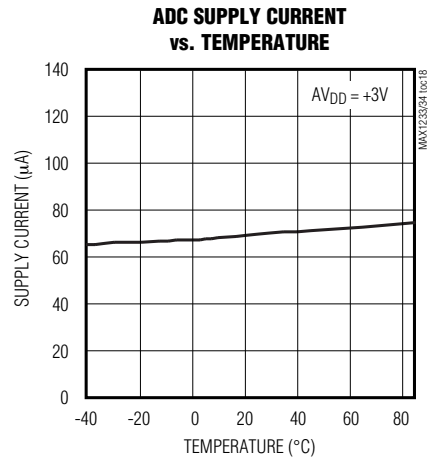
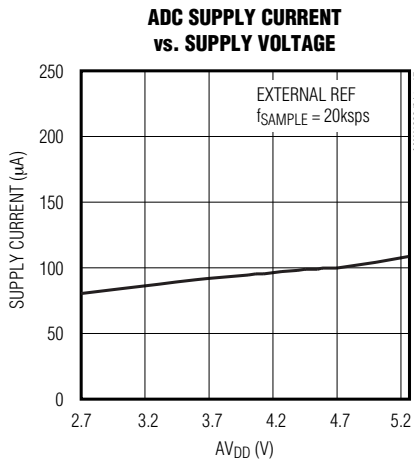
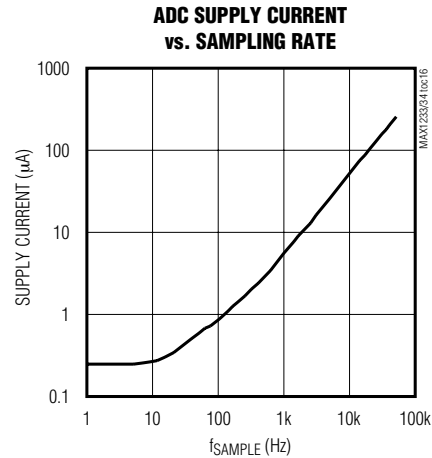
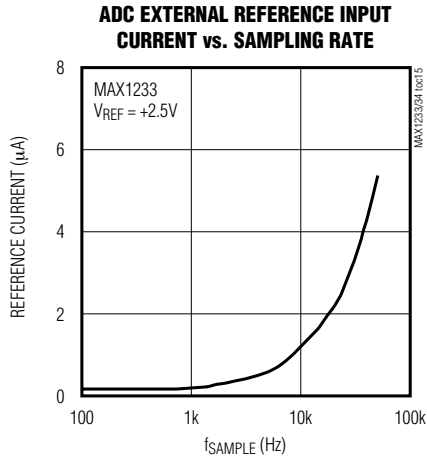


±15kV ESD-Protected Touch-Screen Controllers Include DAC and Keypad Controller

Typical Operating Characteristics (continued)

(AVDD = DVDD = 3V (MAX1233) or 5V (MAX1234), external VREF = +2.5V (MAX1233), external VREF = +4.096V (MAX1234), fSCLK = 10MHz (50% duty cycle), fSAMPLE = 20ksps, CLOAD = 50pF, 0.1μF capacitor at REF, TA = +25°C, unless otherwise noted.)

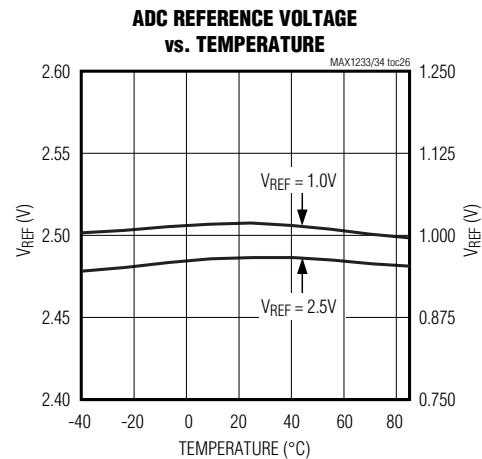
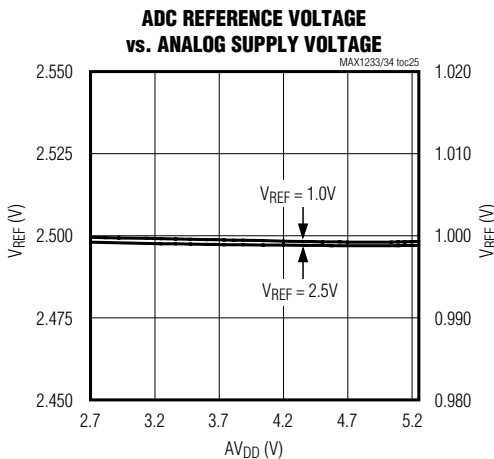
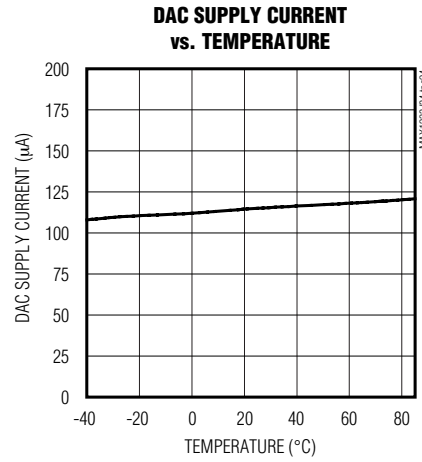
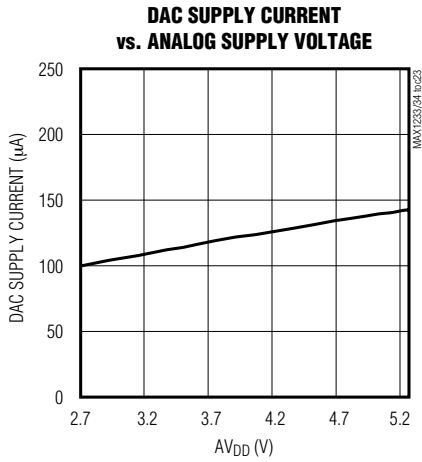
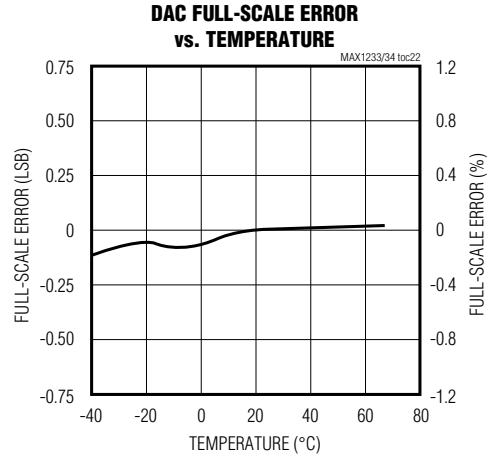
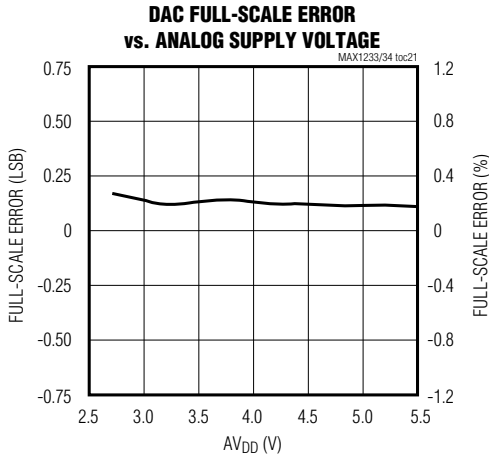
MAX1233/MAX1234



±15kV ESD-Protected Touch-Screen Controllers Include DAC and Keypad Controller

Typical Operating Characteristics (continued)

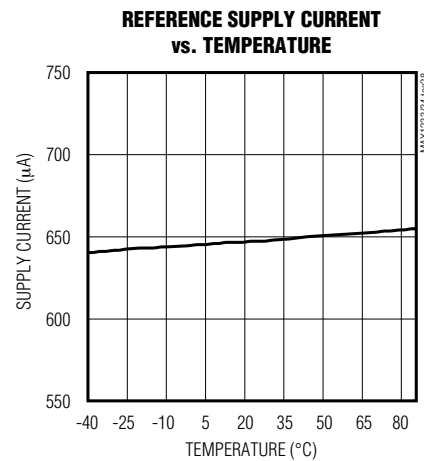
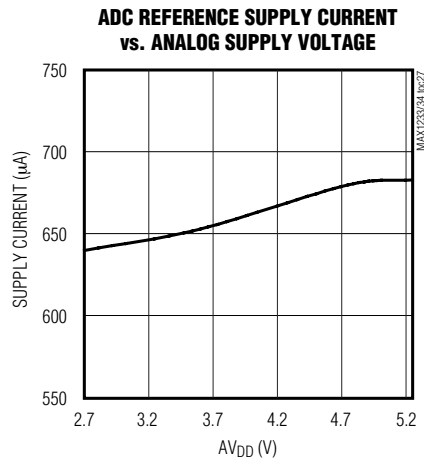
(AVDD = DVDD = 3V (MAX1233) or 5V (MAX1234), external VREF = +2.5V (MAX1233), external VREF = +4.096V (MAX1234), fsCLK = 10MHz (50% duty cycle), fsAMPLE = 20ksps, CLOAD = 50pF, 0.1μF capacitor at REF, TA = +25°C, unless otherwise noted.)



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Typical Operating Characteristics (continued)

(AV_{DD} = DV_{DD} = 3V (MAX1233) or 5V (MAX1234), external V_{REF} = +2.5V (MAX1233), external V_{REF} = +4.096V (MAX1234), f_{SCLK} = 10MHz (50% duty cycle), f_{SAMPLE} = 20ksps, C_{LOAD} = 50pF, 0.1μF capacitor at REF, T_A = +25°C, unless otherwise noted.)



MAX1233/MAX1234

Pin Description

PIN	NAME	FUNCTION
1	DV _{DD}	Positive Digital Supply Voltage, +2.7V to +3.6V for MAX1233, +4.75V to +5.25V for MAX1234. Bypass with a 0.1μF capacitor. Must be within 300mV of AV _{DD} .
2	AV _{DD}	Positive Analog Supply Voltage, +2.7V to +3.6V for MAX1233, +4.75V to +5.25V for MAX1234. Bypass with a 0.1μF capacitor. Must be within 300mV of DV _{DD} .
3*	X+	X+ Position Input
4*	Y+	Y+ Position Input
5*	X-	X- Position Input
6*	Y-	Y- Position Input
7	GND	Analog and Digital Ground
8*	BAT1	Battery Monitoring Input 1. Measures battery voltages up to 6V.
9*	BAT2	Battery Monitoring Input 2. Measures battery voltages up to 6V.
10*	AUX1	Auxiliary Analog Input 1 to ADC. Measures analog voltages from zero to V _{REF} .
11*	AUX2	Auxiliary Analog Input 2 to ADC. Measures analog voltages from zero to V _{REF} .
12	REF	Voltage Reference Output/Input. Reference voltage for analog-to-digital conversion. In internal reference mode, the reference buffer provides a 2.5V or 1.0V nominal output. In external reference mode, apply a reference voltage between 1.0V and AV _{DD} . Bypass REF to GND with a 0.1μF capacitor in the external reference mode only.
13	DACOUT	DAC Voltage Output; 0.9 × AV _{DD} Full Scale
14	R4	Keypad Row 4. Can be reconfigured as GPIO3.
15	R3	Keypad Row 3. Can be reconfigured as GPIO2.
16	R2	Keypad Row 2. Can be reconfigured as GPIO1.
17	R1	Keypad Row 1. Can be reconfigured as GPIO0.
18	C1	Keypad Column 1. Can be reconfigured as GPIO4.

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Pin Description (continued)

PIN	NAME	FUNCTION
19	C2	Keypad Column 2. Can be reconfigured as GPIO5.
20	C3	Keypad Column 3. Can be reconfigured as GPIO6.
21	C4	Keypad Column 4. Can be reconfigured as GPIO7.
22	$\overline{\text{KEYIRQ}}$	Active-Low Keypad Interrupt. $\overline{\text{KEYIRQ}}$ is low when a key press is detected.
23	$\overline{\text{PENIRQ}}$	Active-Low Pen Touch Interrupt. $\overline{\text{PENIRQ}}$ is low when a screen touch is detected.
24	DOUT	Serial Data Output. Data is clocked out at SCLK falling edge. High impedance when $\overline{\text{CS}}$ is high.
25	$\overline{\text{BUSY}}$	Active-Low Busy Output. $\overline{\text{BUSY}}$ goes low and stays low during each functional operation. The host controller should wait until $\overline{\text{BUSY}}$ is high again before using the serial interface.
26	DIN	Serial Data Input. Data is clocked in on the rising edge of SCLK.
27	SCLK	Serial Clock Input. Clocks data in and out of the serial interface and sets the conversion speed (duty cycle must be 30% to 70%).
28	$\overline{\text{CS}}$	Active-Low Chip Select. Data is not clocked into DIN unless $\overline{\text{CS}}$ is low. When $\overline{\text{CS}}$ is high, DOUT is high impedance.
—	EP	Exposed Pad. Internally connected to GND. Connect to a large ground plane to maximize thermal performance. Not intended as an electrical connection point.

*ESD protected: ±8kV Contact, ±15kV Air.

Detailed Description

The MAX1233/MAX1234 are 4-wire touch-screen controllers. Figure 1 shows the functional diagram of the MAX1233/MAX1234. Each device includes a 12-bit sampling ADC, 8-bit voltage output DAC, keypad scanner that can also be configured as a GPIO, internal clock, reference, temperature sensor, two battery monitor inputs, two auxiliary analog inputs, SPI/QSPI/MICROWIRE-compatible serial interface, and low on-resistance switches for driving touch screens.

The 16-bit register inside the MAX1233/MAX1234 allows for easy control and stores results that can be read at any time. The $\overline{\text{BUSY}}$ output indicates that a functional operation is in progress. The $\overline{\text{PENIRQ}}$ and $\overline{\text{KEYIRQ}}$ outputs, respectively, indicate that a screen touch or a key press has occurred.

Touch-Screen Operation

The 4-wire touch-screen controller works by creating a voltage gradient across the vertical or horizontal resistive touch screen connected to the analog inputs of the MAX1233/MAX1234, as shown in Figure 2. The voltage across the touch-screen panels is applied through internal MOSFET switches that connect each resistive layer to AVDD and ground. For example, to measure the Y position when a pointing device presses on the touch screen, the Y+ and Y- drivers are turned on, connecting one side of the vertical resistive layer to AVDD and the other side to ground. The horizontal resistive layer functions as a sense line. One side of this resistive layer gets connected to the X+ input, while the other side is left

open or floating. The point where the touch screen is pressed brings the two resistive layers in contact and creates a voltage-divider at that point. The data converter senses the voltage at the point of contact through the X+ input and digitizes it.

12-Bit ADC

Analog Inputs

Figure 3 shows a block diagram of the ADC's analog input section including the input multiplexer, the differential input, and the differential reference. The input multiplexer switches between X+, X-, Y+, Y-, AUX1, AUX2, BAT1, BAT2, and the internal temperature sensor.

The time required for the T/H to acquire an input signal is a function of how quickly its input capacitance is charged. If the input signal's source impedance is high, the acquisition time lengthens, and more time must be allowed. The acquisition time (t_{ACQ}) is the maximum time the device takes to acquire the input signal to 12-bit accuracy. Configure t_{ACQ} by writing to the ADC control register. See Table 1 for the maximum input signal source impedance (R_{SOURCE}) for complete settling during acquisition.

Accommodate higher source impedances by placing a 0.1µF capacitor between the analog input and GND.

Input Bandwidth

The ADC's input-tracking circuitry has a 0.5MHz small-signal bandwidth. To avoid high-frequency signals being aliased into the frequency band of interest, anti-alias filtering is recommended.

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MAX1233/MAX1234

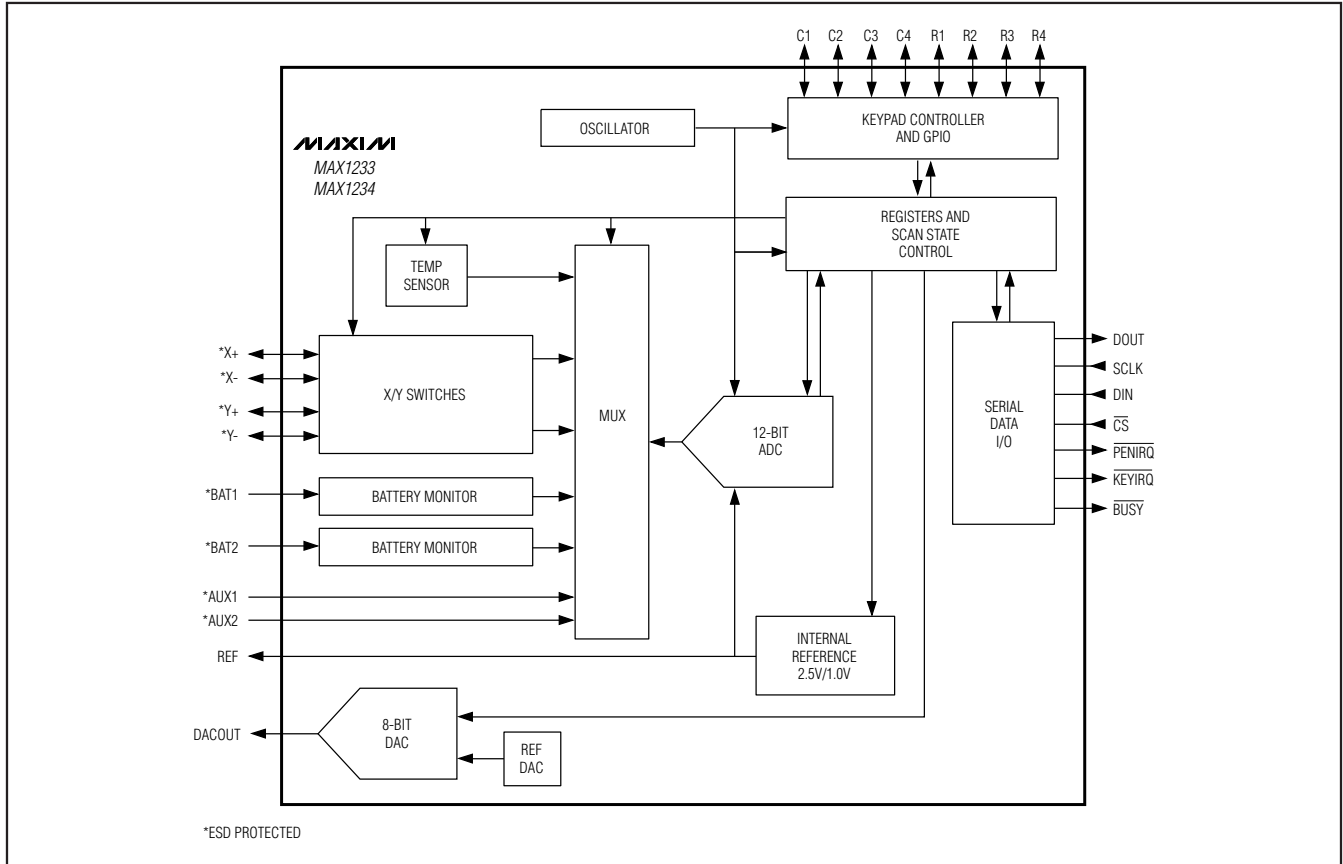


Figure 1. Block Diagram

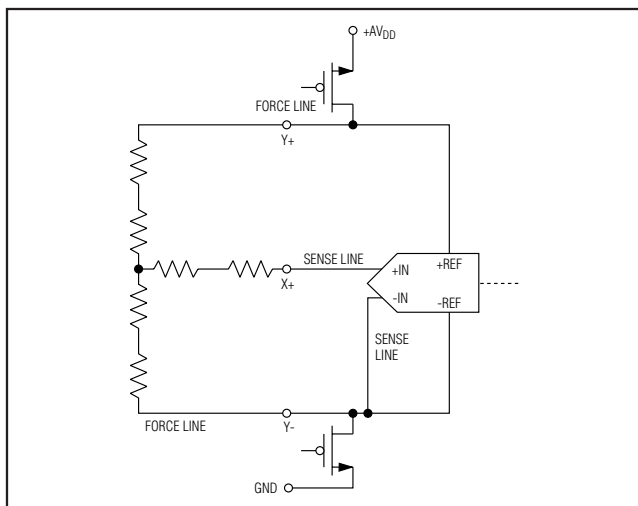


Figure 2. Touch-Screen Measurement

Table 1. Maximum Input Source Impedance

ACQUISITION TIME (μs)	RESOLUTION (BITS)	MAXIMUM R _{SOURCE} FOR COMPLETE SETTLING DURING ACQUISITION (kΩ)
1.5	8	2.6
1.5	10	2.0
1.5	12	1.5
5.0	8	23
5.0	10	19
5.0	12	15
95	8	560
95	10	470
95	12	400

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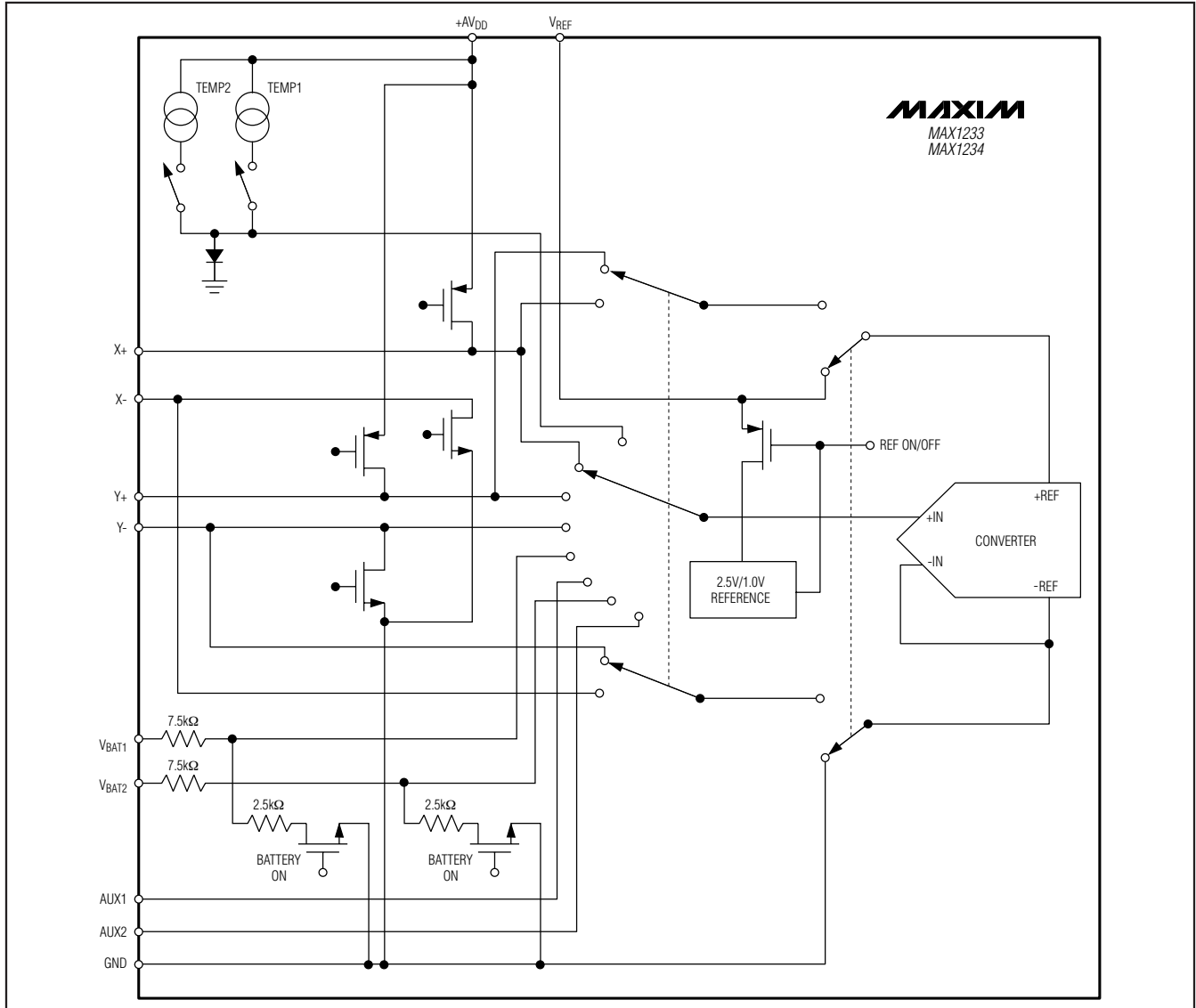


Figure 3. Simplified Diagram of Analog Input Section

Analog Input Protection

Internal protection diodes that clamp the analog input to AV_{DD} and GND allow the analog input pins to swing from GND - 0.3V to AV_{DD} + 0.3V without damage. Analog inputs must not exceed AV_{DD} by more than 50mV or be lower than GND by more than 50mV for accurate conversions. If an off-channel analog input voltage exceeds the supplies, limit the input current to 50mA. **All analog inputs are also fully ESD protected**

to ±8kV, using the Contact-Discharge method and ±15kV using the Air-Gap method specified in IEC-1000-4-2.

Reference for ADC Internal Reference

The MAX1233/MAX1234 offer an internal voltage reference for the ADC that can be set to +1.0V or +2.5V. The MAX1233/MAX1234 typically use the internal reference for battery monitoring, temperature measurement, and for

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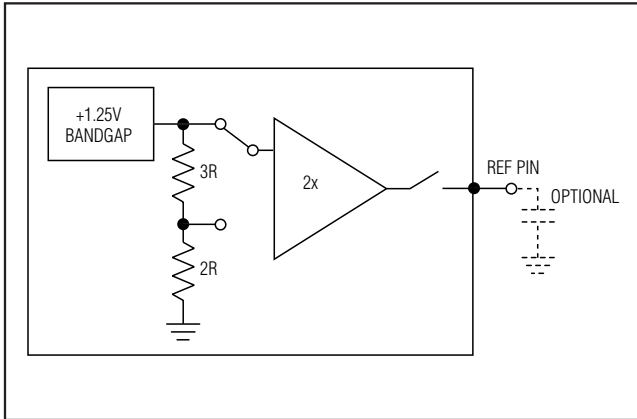


Figure 4. Block Diagram of the Internal Reference

measurement of the auxiliary inputs. Figure 4 shows the on-chip reference circuitry of the MAX1233/MAX1234.

Set the internal reference voltage by writing to the RFV bits in the ADC control register (see Tables 4, 5, and 12). The MAX1233/MAX1234 can accept an external reference connected to REF for ADC conversion.

External Reference

The MAX1233/MAX1234 can accept an external reference connected to the REF pin for ADC conversions. The internal reference should be disabled ($RES1 = 1$) when using an external reference. At a conversion rate of 50ksps, an external reference at REF must deliver up to 15 μ A of load current and have 50 Ω or less output impedance. If the external reference has high output impedance or is noisy, bypass it close to the REF pin with a 0.1 μ F capacitor.

Selecting Internal or External Reference

Set the type of reference being used by programming the ADC control register. To select the internal reference, clock zeros into bits [A/D3:A/D0] and a zero to bit RES1, as shown in the *Control Registers* section. To change to external reference mode, clock zeros into bits [A/D3:A/D0] and a one to bit RES1. See Table 13 for more information about selecting an internal or external reference for the ADC.

Reference Power Modes

Auto Power-Down Mode ($RES1 = RES0 = 0$)

The MAX1233/MAX1234 are in auto power-down mode at initial power-up. Set the RES1 and RES0 bits to zero to use the MAX1233/MAX1234 in the auto power-down mode. In this mode, the internal reference is normally off. When a command to perform a battery measure-

ment, temperature measurement, or auxiliary input measurement is written to the ADC control register, the device powers on the internal reference, waits for the internal reference to settle, completes the requested scan, and powers down the internal reference. The reference power delay depends upon the ADC resolution selected (see Table 8). Do not bypass REF with an external capacitor when performing scans in auto power-down mode.

Full-Power Mode ($RES1 = 0, RES0 = 1$)

In the full-power mode, the RES1 bit is set LOW and RES0 bit is set HIGH. In this mode, the device is powered up and the internal ADC reference is always ON. The MAX1233/MAX1234 internal reference remains fully powered after completing a scan.

Internal Clock

The MAX1233/MAX1234 operate from an internal oscillator, which is accurate to within 20% of the 10MHz specified clock rate. The internal oscillator controls the timing of the acquisition, conversion, touch-screen settling, reference power-up, and keypad debounce times.

8-Bit DAC

The MAX1233/MAX1234 have a voltage-output, true 8-bit monotonic DAC with less than 1LSB integral nonlinearity error and less than 1LSB differential nonlinearity error. It requires a supply current of only 150 μ A (typ) and provides a buffered voltage output. The DAC is at midscale code at power-up and remains there until a new code is written to the DAC register. During shutdown, the DAC's output is pulled to ground with a 1M Ω load.

The internal DAC can be used in various system applications such as LCD/TFT-bias control, automatic tuning (VCO), power amplifier bias control, programmable threshold levels, and automatic gain control (AGC).

The 8-bit DAC in the MAX1233/MAX1234 employs a current-steering topology as shown in Figure 5. At the core of this DAC is a reference voltage-to-current converter (V/I) that generates a reference current. This current is mirrored to 255 equally weighted current sources. DAC switches control the outputs of these current mirrors so that only the desired fraction of the total current-mirror currents is steered to the DAC output. The current is then converted to a voltage across a resistor, and the output amplifier buffers this voltage.

DAC Output Voltage

The 8-bit DAC code is binary unipolar with 1LSB = ($V_{REF}/256$). The DAC has a full-scale output voltage of ($0.9 \times AV_{DD} - 1LSB$).

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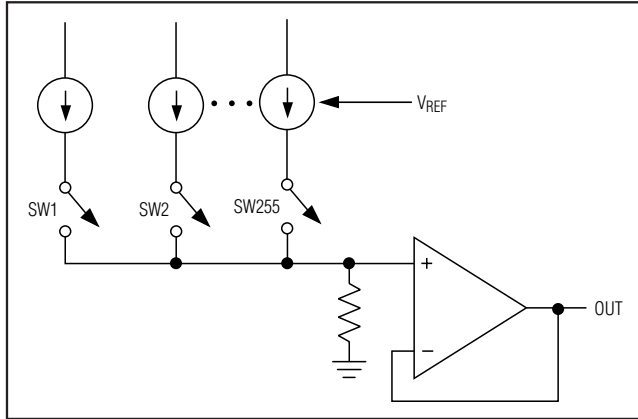


Figure 5. DAC Current-Steering Topology

Output Buffer

The DAC voltage output is an internally buffered unity-gain follower that slews at up to $\pm 0.4\text{V}/\mu\text{s}$. The output can swing from zero to full scale. With a 1/4FS to 3/4FS output transition, the amplifier output typically settles to 1/2LSB in less than $5\mu\text{s}$ when loaded with $10\text{k}\Omega$ in parallel with 50pF . The buffer amplifier is stable with any combination of resistive loads $>10\text{k}\Omega$ and capacitive loads $<50\text{pF}$.

Power-On Reset

All registers of the MAX1233/MAX1234 power up at a default zero state, except the DAC data register, which is set to 10000000, so the output is at midscale.

Keypad Controller and GPIO

The keypad controller is designed to interface a matrix-type 4 rows \times 4 columns (16 keys or fewer) keypad to a host controller. The KEY control register controls keypad interrupt, keypad scan, and keypad debounce times. The KeyMask and ColumnMask registers enable masking of a particular key or an entire column of the keypad when they are not in use. The MAX1233/MAX1234 offer two keypad data registers. KPData1 is the pending register. KPData2 holds keypad scan results of only the unmasked keys. If 12 or fewer keys are being monitored, one or more of the row/column pins of the MAX1233/MAX1234 can be software programmed as GPIO pins.

Touch-Screen Detection

Touch-screen detection can be enabled or disabled by writing to the ADC control register as shown in Table 4. Touch-screen detection is disabled at initial power-up. Once touch-screen detection is enabled, the Y- driver is on and the Y- pin is connected to GND. The X+ pin is internally pulled to AVDD through a $1\text{M}\Omega$ resistor as

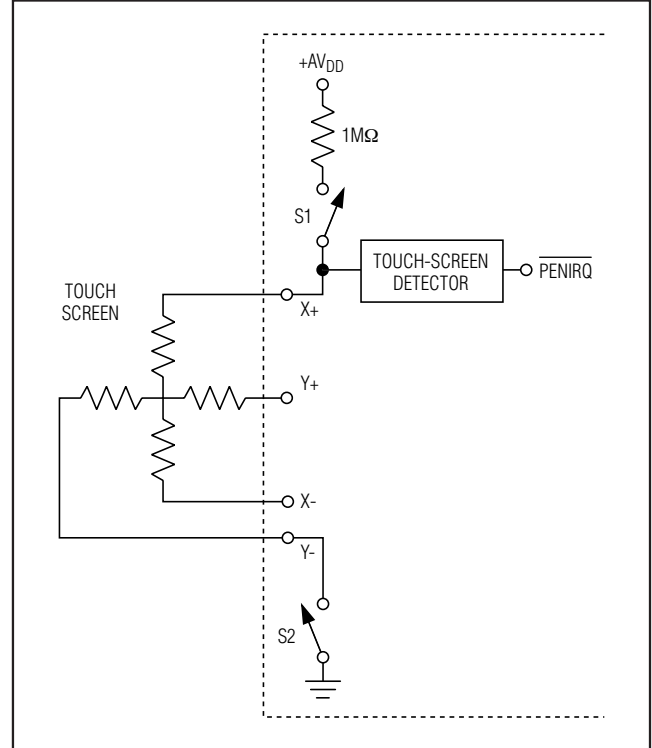


Figure 6. Touch-Screen Detection Block Diagram

shown in Figure 6. When the screen is touched, the X+ pin is pulled to GND through the touch screen and a touch is detected.

When the $1\text{M}\Omega$ pullup resistor is first connected, the X+ pin can be floating near ground. To prevent false touch detection in this case, the X+ pin is precharged high for $0.1\mu\text{s}$ using the 7Ω PMOS driver before touch detection begins.

Key-Press Detection

Key-press detection can be enabled or disabled by writing to the keypad control register as shown in Table 17. Key-press detection is disabled at initial power-up. Once key-press detection is enabled, the C_ pins are internally connected to DVDD and the R_ pins are internally pulled to GND through a $16\text{k}\Omega$ resistor. When a key is pressed, the associated row pin is pulled to DVDD and the key press is detected. Figure 7 shows the key-press detection circuitry.

Interrupts

PEN Interrupt Request (PENIRQ)

The $\overline{\text{PENIRQ}}$ output can be used to alert the host controller of a screen touch. The $\overline{\text{PENIRQ}}$ output is normally high and goes low after a screen touch is detected.

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MAX1233/MAX1234

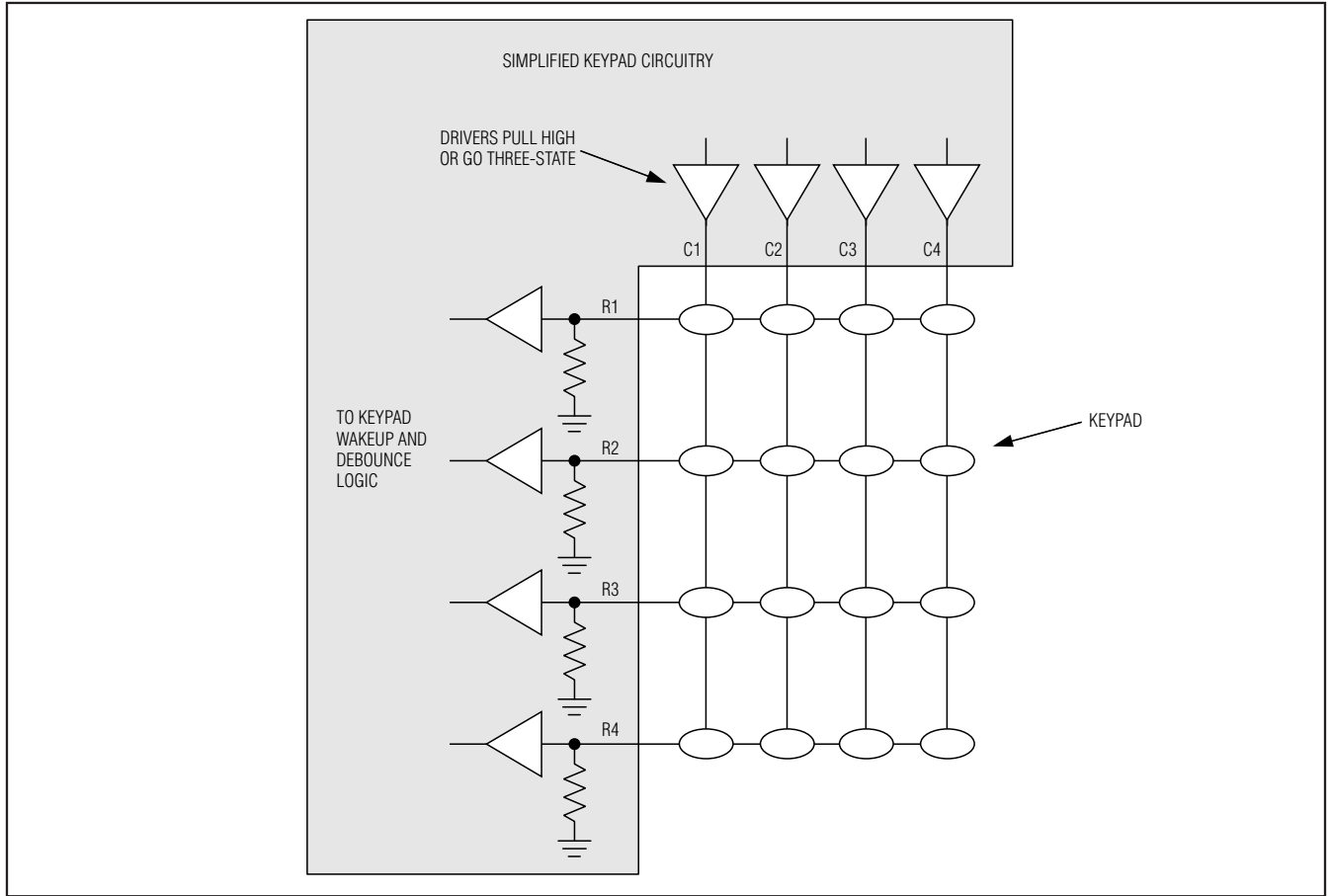


Figure 7. Key-Press Detection Circuitry

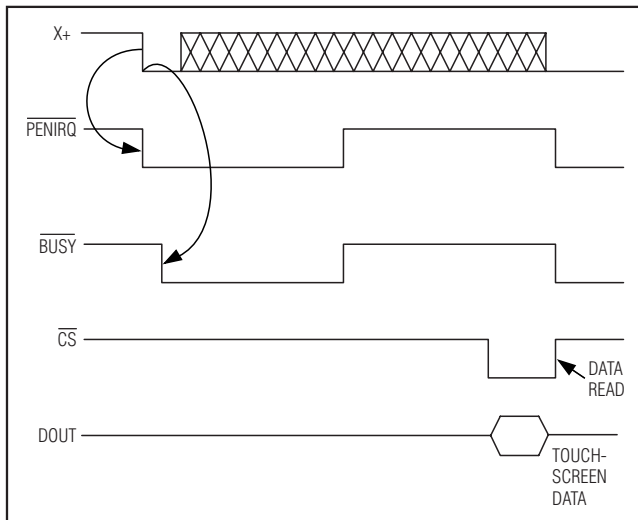


Figure 8a. Timing Diagram for Touch-Initiated Screen Scan

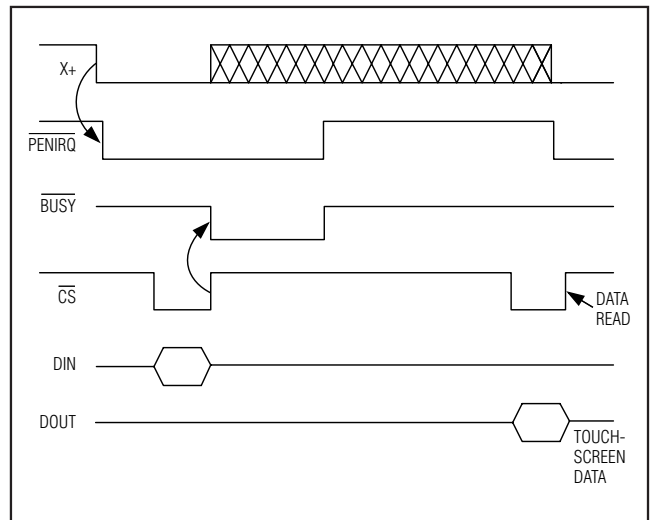


Figure 8b. Timing Diagram for Host-Initiated Screen Scan

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$\overline{\text{PENIRQ}}$ returns high only after a touch-screen scan is completed. $\overline{\text{PENIRQ}}$ does not go low again until one of the touch-screen data registers is read. Figures 8a and 8b show the timing diagrams for the $\overline{\text{PENIRQ}}$ pin.

Keypad Interrupt Request ($\overline{\text{KEYIRQ}}$)

The $\overline{\text{KEYIRQ}}$ output can be used to alert the host controller of a key press. The $\overline{\text{KEYIRQ}}$ output is normally high and goes low after a key press is detected. $\overline{\text{KEYIRQ}}$ returns high only after a key-press scan is completed. $\overline{\text{KEYIRQ}}$ does not go low again until one of the key-press data registers is read. Figures 9a and 9b show the timing diagrams for the $\overline{\text{KEYIRQ}}$ pin.

Busy Indicator ($\overline{\text{BUSY}}$)

$\overline{\text{BUSY}}$ informs the host processor that a scan is in progress. $\overline{\text{BUSY}}$ is normally high and goes low and stays low during each functional operation. The host controller should wait until $\overline{\text{BUSY}}$ is high again before using the serial interface.

Digital Interface

The MAX1233/MAX1234 interface to the host controller through a standard 3-wire serial interface at up to 10MHz. $\overline{\text{DIN}}$ and $\overline{\text{CS}}$ are the digital inputs to the MAX1233/MAX1234. $\overline{\text{DOUT}}$ is the serial data output. Data is clocked out at the SCLK falling edge and is high impedance when $\overline{\text{CS}}$ is high. When performing an ADC scan, $\overline{\text{CS}}$ must de-assert high before the end of the first conversion, otherwise the conversion results will not be stored. $\overline{\text{PENIRQ}}$ and $\overline{\text{KEYIRQ}}$ communicate interrupts from the touch-screen and keypad controllers to the host processor when a screen touch or a key press is detected. $\overline{\text{BUSY}}$ informs the host processor that a scan is in progress. In addition to these digital I/Os, the row and column pins of the keypad controller can be programmed as GPIO pins.

Communications Protocol

The MAX1233/MAX1234 are controlled by reading from and writing to registers through the 3-wire serial interface. These registers are addressed through a 16-bit command that is sent prior to the data. The command is shown in Table 2.

The first 16 bits after the falling edge of $\overline{\text{CS}}$ contain the command word. The command word begins with an $\overline{\text{R/W}}$ bit, which specifies the direction of data flow on the serial bus. Bits 14 through 7 are reserved for future use. Bit 6 specifies the page of memory in which the

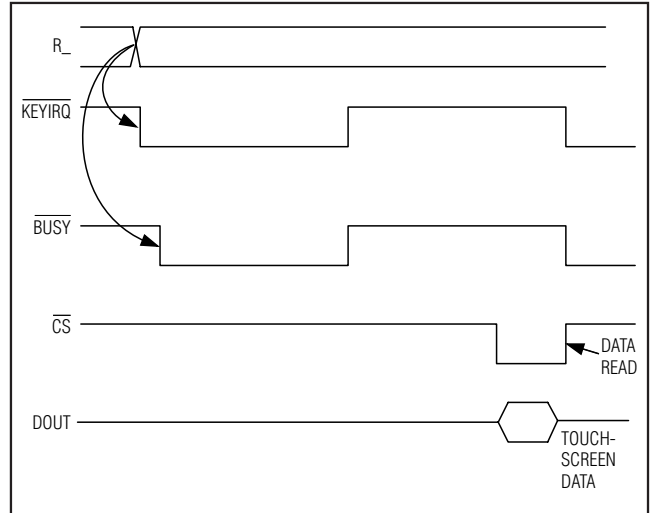


Figure 9a. Timing Diagram for Key-Press-Initiated Debounce Scan

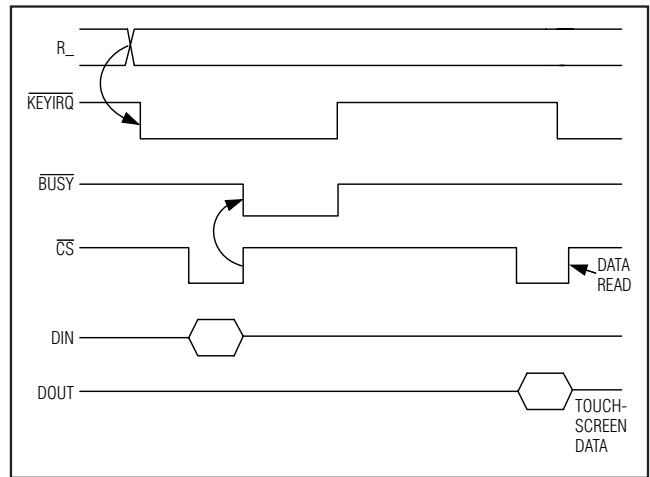


Figure 9b. Timing Diagram for Host-Initiated Keypad Debounce Scan

desired register is located. The last 6 bits specify the address of the desired register. The next 16 bits of data are read from or written to the address specified in the command word. After 32 clock cycles, the interface automatically increments its address pointer and continues reading or writing until the rising edge of $\overline{\text{CS}}$, or until it reaches the end of the page.

Table 2. Command Word Format

BIT15 MSB	BIT14	BIT13	BIT12	BIT11	BIT10	BIT9	BIT8	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0 LSB
R/W	RES	RES	RES	RES	RES	RES	RES	RES	PAGE	ADD5	ADD4	ADD3	ADD2	ADD1	ADD0

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MAX1233/MAX1234

Table 3. Register Summary

WRITE COMMAND (HEX)	READ COMMAND (HEX)	REGISTER NAME	BIT15	BIT14	BIT13	BIT12	BIT11	BIT10	BIT9	BIT8	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0
—	0x8000	X	0	0	0	0	X11	X10	X9	X8	X7	X6	X5	X4	X3	X2	X1	X0
—	0x8001	Y	0	0	0	0	Y11	Y10	Y9	Y8	Y7	Y6	Y5	Y4	Y3	Y2	Y1	Y0
—	0x8002	Z1	0	0	0	0	Z1_11	Z1_10	Z1_9	Z1_8	Z1_7	Z1_6	Z1_5	Z1_4	Z1_3	Z1_2	Z1_1	Z1_0
—	0x8003	Z2	0	0	0	0	Z2_11	Z2_10	Z2_9	Z2_8	Z2_7	Z2_6	Z2_5	Z2_4	Z2_3	Z2_2	Z2_1	Z2_0
—	0x8004	KPD	K15	K14	K13	K12	K11	K10	K9	K8	K7	K6	K5	K4	K3	K2	K1	K0
—	0x8005	BAT1	0	0	0	0	B1_11	B1_10	B1_9	B1_8	B1_7	B1_6	B1_5	B1_4	B1_3	B1_2	B1_1	B1_0
—	0x8006	BAT2	0	0	0	0	B2_11	B2_10	B2_9	B2_8	B2_7	B2_6	B2_5	B2_4	B2_3	B2_2	B2_1	B2_0
—	0x8007	AUX1	0	0	0	0	A1_11	A1_10	A1_9	A1_8	A1_7	A1_6	A1_5	A1_4	A1_3	A1_2	A1_1	A1_0
—	0x8008	AUX2	0	0	0	0	A2_11	A2_10	A2_9	A2_8	A2_7	A2_6	A2_5	A2_4	A2_3	A2_2	A2_1	A2_0
—	0x8009	TEMP1	0	0	0	0	T1_11	T1_10	T1_9	T1_8	T1_7	T1_6	T1_5	T1_4	T1_3	T1_2	T1_1	T1_0
—	0x800A	TEMP2	0	0	0	0	T2_11	T2_10	T2_9	T2_8	T2_7	T2_6	T2_5	T2_4	T2_3	T2_2	T2_1	T2_0
0x000B	0x800B	DAC data	0	0	0	0	0	0	0	0	DA7	DA6	DA5	DA4	DA3	DA2	DA1	DA0
0x000F	0x800F	GPIO data	GPD7	GPD6	GPD5	GPD4	GPD3	GPD2	GPD1	GPD0	0	0	0	0	0	0	0	0
—	0x8010	KPData1	K1_15	K1_14	K1_13	K1_12	K1_11	K1_10	K1_9	K1_8	K1_7	K1_6	K1_5	K1_4	K1_3	K1_2	K1_1	K1_0
—	0x8011	KPData2	K2_15	K2_14	K2_13	K2_12	K2_11	K2_10	K2_9	K2_8	K2_7	K2_6	K2_5	K2_4	K2_3	K2_2	K2_1	K2_0
0x0040	0x8040	ADC control	PENSTS	ADSTS	A/D3	A/D2	A/D1	A/D0	RES1	RES0	AVG1	AVG0	CNR1	CNR0	ST2	ST1	ST0	RFV
0x0041	0x8041	KEY control	KEYSTS1	KEYSTS0	DBN2	DBN1	DBN0	HLD2	HLD1	HLD0	0	0	0	0	0	0	0	0
0x0042	0x8042	DAC control	DAPD	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0x004E	0x804E	GPIO pullup	PU7	PU6	PU5	PU4	PU3	PU2	PU1	PU0	0	0	0	0	0	0	0	0
0x004F	0x804F	GPIO control	GP7	GP6	GP5	GP4	GP3	GP2	GP1	GP0	OE7	OE6	OE5	OE4	OE3	OE2	OE1	OE0
0x0050	0x8050	KPKeyMask	KM15	KM14	KM13	KM12	KM11	KM10	KM9	KM8	KM7	KM6	KM5	KM4	KM3	KM2	KM1	KM0
0x0051	0x8051	KPColumnMask	CM4	CM3	CM2	CM1	0	0	0	0	0	0	0	0	0	0	0	0

Note: All other registers are reserved and should always be 0. Power-on reset state is DAC data at midscale (0x0080), all other registers are 0.

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In order to read the entire first page of memory, for example, the host processor must send the MAX1233/MAX1234 the command 0x8000H. The MAX1233/MAX1234 then begin clocking out 16-bit data starting with the X-data register. In order to write to the second page of memory, the host processor sends the MAX1233/MAX1234 the command 0x0040H. The succeeding data is then written in 16-bit words beginning with the ADC control register. Figures 10a and 10b show a complete write and read operation, respectively, between the processor and the MAX1233/MAX1234.

Memory Map

The MAX1233/MAX1234s' internal memory is divided into two pages—one for data and one for control, each of which contains thirty-two 16-bit registers.

Control Registers

Table 3 provides a summary of all registers and bit locations of the MAX1233/MAX1234.

ADC Control Register

The ADC measures touch position, touch pressure, battery voltage, auxiliary analog inputs, and temperature. The ADC control register determines which input is selected and converted. Tables 4 and 5 show the format and bit descriptions for the ADC control register.

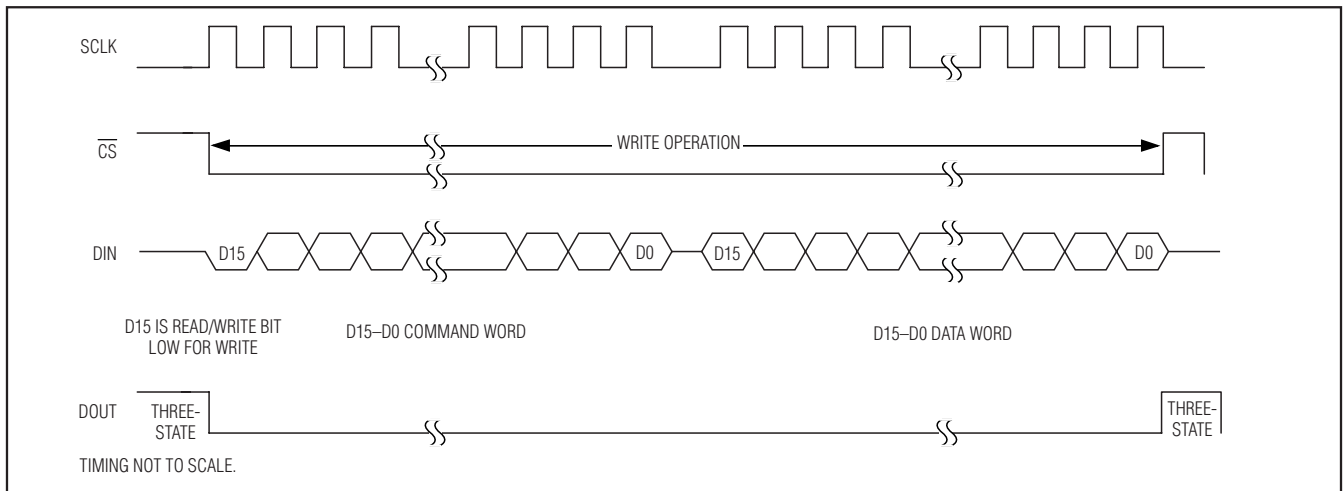


Figure 10a. Timing Diagram of Write Operation

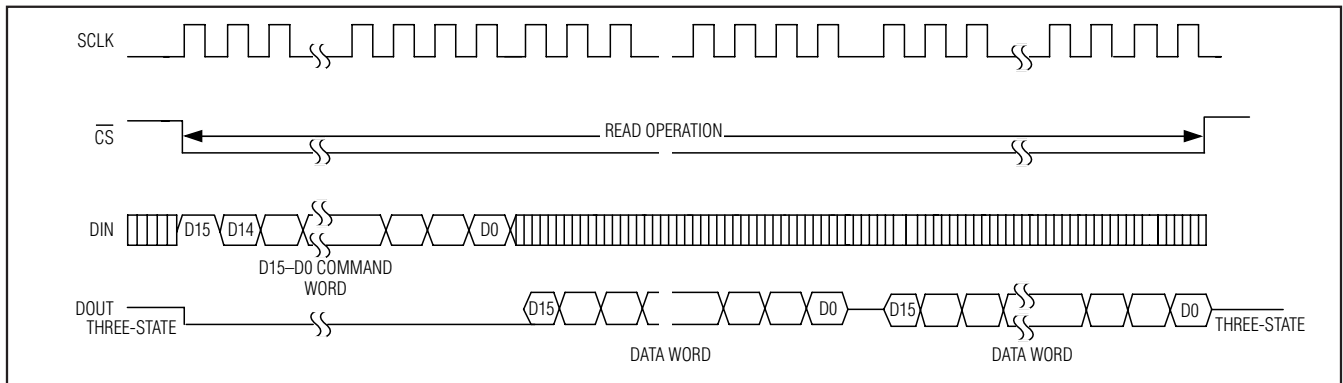


Figure 10b. Timing Diagram of Read Operation

Table 4. ADC Control Register (Write 0x0040/Read 0x8040)

BIT15	BIT14	BIT13	BIT12	BIT11	BIT10	BIT9	BIT8	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0
PENSTS	ADSTS	A/D3	A/D2	A/D1	A/D0	RES1	RES0	AVG1	AVG0	CNR1	CNR0	ST2	ST1	ST0	RFV

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Bits 14-15: Pen Interrupt Status and ADC Status Bits

These bits are used to control or monitor ADC scans.

Bits 10-13: ADC Scan Select

These bits control which input to convert and which converter mode is used. The bits are identical regardless of a read or write. See Table 7 for details about using these bits.

Bits 8-9: ADC Resolution Control

These bits specify the ADC resolution and are identical regardless of read or write. Table 8 shows how to use these bits to set the resolution.

Bits 6-7: Converter Averaging Control

These bits specify the number of data averages the converter performs. Table 9 shows how to program for the desired number of averages. When averaging is used, ADSTS and BUSY indicate the converter is busy until all conversions needed for the averaging finish. These bits are identical, regardless of read or write.

Bits 4-5: ADC Conversion Rate Control

These bits specify the internal conversion rate, which the ADC uses to perform a single conversion, as shown in Table 10. Lowering the conversion rate also reduces power consumption. These bits are identical, regardless of read or write.

Table 5. ADC Control Register Bit Descriptions (Write 0x0040/Read 0x8040)

BIT	NAME	DESCRIPTION
15 (MSB)	PENSTS	Read: pen interrupt status; Write: sets interrupt initiated touch-screen scans
14	ADSTS	Read: ADC status; Write: stops ADC
13	A/D3	Selects ADC scan functions
12	A/D2	Selects ADC scan functions
11	A/D1	Selects ADC scan functions
10	A/D0	Selects ADC scan functions
9	RES1	Controls ADC resolution
8	RES0	Controls ADC resolution
7	AVG1	Controls ADC result averaging
6	AVG0	Controls ADC result averaging
5	CNR1	Controls ADC conversion rate
4	CNR0	Controls ADC conversion rate
3	ST2	Controls touch-screen settling wait time
2	ST1	Controls touch-screen settling wait time
1	ST0	Controls touch-screen settling wait time
0 (LSB)	RFV	Chooses 1.0V or 2.5V reference

Table 6. ADSTS Bit Operation

PENSTS	ADSTS	READ FUNCTION	WRITE FUNCTION
0	0	No screen touch detected; scan or conversion in progress	Performs one scan and waits to detect a screen touch. Upon detection, issues an interrupt and waits until told to scan by the host controller.
1	0	Screen touch detected; scan or conversion in progress	Stops any ongoing scan and waits to detect a screen touch. Upon detection, issues an interrupt and performs a scan.
0	1	No screen touch detected; data available	Stops any ongoing scan and waits to detect a screen touch. Upon detection, issues an interrupt and waits until told to scan by the host controller.
1	1	Screen touch detected; data available	Stops any ongoing scan and powers down the screen touch detection circuit. No screen touches are detected in this mode.

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Table 7. ADC Scan Select (Touch Screen, Battery, Auxiliary Channels, and Temperature)

A/D3	A/D2	A/D1	A/D0	FUNCTION
0	0	0	0	Configures the ADC reference as selected by RES [1:0] bits as shown in Table 13. No measurement is performed.
0	0	0	1	Measures X/Y touch position and returns results to the X and Y data registers.
0	0	1	0	Measures X/Y touch position and Z1/ Z2 touch pressure and returns results to the X, Y, Z1, and Z2 data registers.
0	0	1	1	Measures X touch position and returns results to the X data register.
0	1	0	0	Measures Y touch position and returns results to the Y data register.
0	1	0	1	Measures Z1/Z2 touch pressure and returns results to the Z1 and Z2 data register.
0	1	1	0	Measures Battery Input 1 through a 4:1 divider and returns results to the BAT1 data register.
0	1	1	1	Measures Battery Input 2 through a 4:1 divider and returns results to the BAT2 data register.
1	0	0	0	Measures Auxiliary Input 1 and returns results to the AUX1 data register.
1	0	0	1	Measures Auxiliary Input 2 and returns results to the AUX2 data register.
1	0	1	0	Measures temperature (single ended) and returns results to the TEMP1 data register.
1	0	1	1	Measures Battery Input 1, Battery Input 2, Auxiliary Input 1, Auxiliary Input 2, and temperature (differential), and returns results to the appropriate data registers.
1	1	0	0	Measures temperature (differential) and returns results to the TEMP1 and TEMP2 data registers.
1	1	0	1	Turns on Y+, Y- drivers. No measurement is performed.
1	1	1	0	Turns on X+, X- drivers. No measurement is performed.
1	1	1	1	Turns on Y+, X- drivers. No measurement is performed.

Table 8. ADC Resolution Control

RES1	RES0	ADC RESOLUTION	INTERNALLY TIMED REFERENCE POWER-UP DELAY* (μs)
0	0	8 bit	31
0	1	8 bit	31
1	0	10 bit	37
1	1	12 bit	44

*Applicable only for temperature, battery, or auxiliary measurements in auto power-up reference mode.

Table 10. ADC Conversion Rate Control

CNR1	CNR0	FUNCTION
0	0	3.5μs/sample (1.5μs acquisition, 2μs conversion)
0	1	3.5μs/sample (1.5μs acquisition, 2μs conversion)
1	0	10μs/sample (5μs acquisition, 5μs conversion)
1	1	100μs/sample (95μs acquisition, 5μs conversion)

Table 9. ADC Averaging Control

AVG1	AVG0	FUNCTION
0	0	No data averages (default)
0	1	4 data averages
1	0	8 data averages
1	1	16 data averages

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Bits 1-3: Touch-Screen Settling Time Control

These bits specify the time delay from pen-touch detection to a conversion start. This allows the selection of the appropriate settling time for the touch screen being used. Table 11 shows how to set the settling time. These bits are identical, regardless of read or write.

Bit 0: ADC Internal Reference Voltage Control

This bit selects the ADC internal reference voltage, either +1.0V or +2.5V. This bit is identical, regardless of read or write. The reference control bit is shown in Table 12.

Table 11. Touch-Screen Settling Time Control*

ST2	ST1	ST0	SETTLING TIME
0	0	0	Settling time: 0μs
0	0	1	Settling time: 100μs
0	1	0	Settling time: 500μs
0	1	1	Settling time: 1ms
1	0	0	Settling time: 5ms
1	0	1	Settling time: 10ms
1	1	0	Settling time: 50ms
1	1	1	Settling time: 100ms

*Applicable only for X, Y, Z1, and Z2 measurements.

Table 12. ADC Reference Control Bit

RFV	FUNCTION
0	+1.0V reference
1	+2.5V reference

Table 13. Internal ADC Reference Auto Power-Up Control

[A/D3:A/D0]	RES1	RES0	ADC REFERENCE SOURCE	ADC REFERENCE POWER MODE
0000	0	0	Internal	Power up, wait for reference to settle, and power down again for each temperature, battery, or auxiliary scan (auto power-up mode)
0000	0	1	Internal	Always powered up
0000	1	0	External	Always powered down
0000	1	1	External	Always powered down

Table 14. DAC Control Register (Write 0x0042/Read 0x8042)

BIT15	BIT14	BIT13	BIT12	BIT11	BIT10	BIT9	BIT8	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0
DAPD	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Internal ADC Reference Power-Down Control

The ADC control register controls the power setting of the internal ADC reference. Zeros must be written to bits A/D3–A/D0 to control internal reference power-up followed by the appropriate logic at the RES1 and RES0 bits. Table 13 shows the internal ADC reference power-down control.

DAC Control Register

The MSB in this control register determines the power-down control of the on-board DAC. Table 14 shows the DAC control register. Writing a zero to bit 15 (DAPD) powers up the DAC, while writing a 1 powers down the DAC. Table 15 describes the DAC control register contents, while Table 16 shows the DAC power-down bit.

Keypad Control Registers

The keypad control register, keypad mask register, and keypad column mask control register control the keypad scanner in the MAX1233/MAX1234. The keypad control register (Table 17) controls scanning and debouncing, while the keypad mask register (Table 22) and the keypad column mask control register (Table 24),

Table 15. DAC Control Register Descriptions

BIT	NAME	DESCRIPTION
15 (MSB)	DAPD	DAC powered down
[14:0]	0	Reserved

Table 16. DAC Power-Down Bit

DAPC	FUNCTION
0	DAC powered up
1	DAC powered down

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Table 17. Keypad Control Register (Write 0x0041/Read 0x8041)

BIT15	BIT14	BIT13	BIT12	BIT11	BIT10	BIT9	BIT8	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0
KEYSTS1	KEYSTS0	DBN2	DBN1	DBN0	HLD2	HLD	HLD	0	0	0	0	0	0	0	0

Table 18. Keypad Control Register Bit Descriptions (Write 0x0041/Read 0x8041)

BIT	NAME	DESCRIPTION
15 (MSB)	KEYSTS1	Read: keypad interrupt status; Write: set interrupt initiated keypad scans
14	KEYSTS0	Read: keypad scan status; Write: stop keypad scan
13	DBN2	Keypad debounce time control
12	DBN1	Keypad debounce time control
11	DBN0	Keypad debounce time control
10	HLD2	Keypad hold time control
9	HLD1	Keypad hold time control
8	HLD0	Keypad hold time control
[7:0]	0	Reserved

Table 19. KEYSTS1/KEYSTS0 Functions

KEYSTS1	KEYSTS0	READ FUNCTION	WRITE FUNCTION
0	0	No button press detected; scan or debounce in progress	Scans keypad once and waits to detect a button press. Upon detection, issues an interrupt and waits for the host's instruction before scanning.
1	0	Button press detected; scan or debounce in progress	Stops any ongoing scan and waits to detect a button press. Upon detection, issues an interrupt and scans the keypad.
0	1	No button press detected; data available	Stops any ongoing scan and waits to detect a button press. Upon detection, issues an interrupt and waits for the host's instruction before scanning.
1	1	Button press detected; data available	Stops any ongoing scan and powers down the button press detection circuit. No button presses are detected in this mode.

Table 20. Keypad Debounce Time Control

DBN2	DBN1	DBN0	FUNCTION (ms)
0	0	0	Debounce time: 2
0	0	1	Debounce time: 10
0	1	0	Debounce time: 20
0	1	1	Debounce time: 50
1	0	0	Debounce time: 60
1	0	1	Debounce time: 80
1	1	0	Debounce time: 100
1	1	1	Debounce time: 120

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allowing certain keys to be masked from detection. Tables 18–21 show the programmable bits of the keypad control register. Tables 23, 24, and 25 show the programmable bits of the keypad mask registers. The *Keypad Controller and GPIO* section provides more details.

GPIO Control Register

The GPIO control register and the GPIO pullup register allow the keypad controller's row and column inputs to be configured as up to eight parallel I/O pins. Tables 26 and 27 show the GPIO control register layout and control register descriptions. Tables 28 and 29 show the GPIO pullup disable register and associated descriptions. For more information, see the *Applications Information* section.

Table 21. Keypad Hold Time Control

HLD2	HLD1	HLD0	FUNCTION
0	0	0	If a button is held, wait 100µs before beginning next debounce scan
0	0	1	If a button is held, wait 1 debounce time before beginning the next debounce scan
0	1	0	If a button is held, wait 2 debounce times before beginning the next debounce scan
0	1	1	If a button is held, wait 3 debounce times before beginning the next debounce scan
1	0	0	If a button is held, wait 4 debounce times before beginning the next debounce scan
1	0	1	If a button is held, wait 5 debounce times before beginning the next debounce scan
1	1	0	If a button is held, wait 6 debounce times before beginning the next debounce scan
1	1	1	If a button is held, wait 7 debounce times before beginning the next debounce scan

Table 22. Keypad Key Mask Register Bit Descriptions (Write 0x0050/Read 0x8050)

BIT15	BIT14	BIT13	BIT12	BIT11	BIT10	BIT9	BIT8	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0
KM15	KM14	KM13	KM12	KM11	KM10	KM9	KM8	KM7	KM6	KM5	KM4	KM3	KM2	KM1	KM0

Table 23. Keypad Key Mask Register Bit Descriptions (Write 0x0050/Read 0x8050)

BIT	NAME	DESCRIPTION
15	KM15	Mask status register data update on individual key for row 4, column 4
14	KM14	Mask status register data update on individual key for row 3, column 4
13	KM13	Mask status register data update on individual key for row 2, column 4
12	KM12	Mask status register data update on individual key for row 1, column 4
11	KM11	Mask status register data update on individual key for row 4, column 3
10	KM10	Mask status register data update on individual key for row 3, column 3
9	KM9	Mask status register data update on individual key for row 2, column 3
8	KM8	Mask status register data update on individual key for row 1, column 3
7	KM7	Mask status register data update on individual key for row 4, column 2
6	KM6	Mask status register data update on individual key for row 3, column 2
5	KM5	Mask status register data update on individual key for row 2, column 2
4	KM4	Mask status register data update on individual key for row 1, column 2
3	KM3	Mask status register data update on individual key for row 4, column 1
2	KM2	Mask status register data update on individual key for row 3, column 1
1	KM1	Mask status register data update on individual key for row 2, column 1
0	KM0	Mask status register data update on individual key for row 1, column 1

Table 24. Keypad Column Mask Register (Write 0x0051/Read 0x8051)

BIT15	BIT14	BIT13	BIT12	BIT11	BIT10	BIT9	BIT8	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0
CM4	CM3	CM2	CM1	0	0	0	0	0	0	0	0	0	0	0	0