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General Description

The MAX1300/MAX1301 multirange, low-power, 16-bit, successive-approximation, analog-to-digital converters (ADCs) operate from a single +5V supply and achieve throughput rates up to 115ksps. A separate digital supply allows digital interfacing with 2.7V to 5.25V systems using the SPI-/QSPITM-/MICROWIRE®-compatible serial interface. Partial power-down mode reduces the supply current to 1.3mA (typ). Full power-down mode reduces the power-supply current to 1µA (typ).

The MAX1300 provides eight (single-ended) or four (true differential) analog input channels. The MAX1301 provides four (single-ended) or two (true differential) analog input channels. Each analog input channel is independently software programmable for seven single-ended input ranges [0 to (3 x VREF)/2, (-3 x VREF)/2 to 0, 0 to 3 x VREF, -3 x VREF to 0, (±3 x VREF)/4, (±3 x VREF)/2, ±3 x VREF] and three differential input ranges [(±3 x VREF)/2, ±3 x VREF, ±6 x VREF].

An on-chip +4.096V reference offers a small convenient ADC solution. The MAX1300/MAX1301 also accept an external reference voltage between 3.800V and 4.136V.

The MAX1300 is available in a 24-pin TSSOP package and the MAX1301 is available in a 20-pin TSSOP package. Each device is specified for operation from -40°C to +85°C.

Applications

Industrial Control Systems **Data-Acquisition Systems Avionics** Robotics

Features

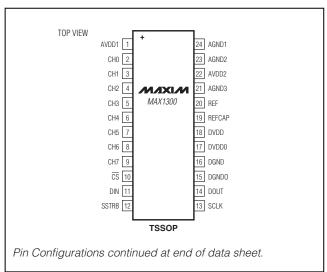
- ♦ Software-Programmable Input Range for Each Channel
- ♦ Single-Ended Input Ranges (VREF = 4.096V) 0 to (3 x VREF)/2, (-3 x VREF)/2 to 0, 0 to 3 x VREF, -3 x VREF to 0, (±3 x VREF)/4, (±3 x VREF)/2, ±3 x VREF
- ♦ Differential Input Ranges (±3 x V_{REF})/2, ±3 x V_{REF}, ±6 x V_{REF}
- ♦ Eight Single-Ended or Four Differential Analog Inputs (MAX1300)
- **♦** Four Single-Ended or Two Differential Analog Inputs (MAX1301)
- ♦ ±16.5V Overvoltage Tolerant Inputs
- ♦ Internal or External Reference
- ♦ 115ksps Maximum Sample Rate
- ♦ Single +5V Power Supply
- **♦** 20-/24-Pin TSSOP Package

Ordering Information

PART	TEMP RANGE	PIN- PACKAGE	CHANNELS
MAX1300AEUG+	-40°C to +85°C	24 TSSOP	8
MAX1300BEUG+	-40°C to +85°C	24 TSSOP	8
MAX1301AEUP+	-40°C to +85°C	20 TSSOP	4
MAX1301BEUP+	-40°C to +85°C	20 TSSOP	4

⁺Denotes a lead(Pb)-free/RoHS-compliant package.

Pin Configurations



OSPI is a trademark of Motorola, Inc. MICROWIRE is a registered trademark of National Semiconductor Corp.

Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{AVDD1} = V_{AVDD2} = V_{DVDD} = V_{DVDD0} = 5V$, $V_{AGND1} = V_{DGND} = V_{DGND0} = V_{AGND2} = V_{AGND3} = 0V$, $f_{CLK} = 3.5$ MHz (50% duty cycle), external clock mode, $V_{REF} = 4.096V$ (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range ($\pm 3 \times V_{REF}$), $C_{DOUT} = 50$ pF, $C_{SSTRB} = 50$ pF, $C_{AGND2} = 40$ °C to +85°C, unless otherwise noted. Typical values are at $C_{AGND2} = 40$ °C.

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
DC ACCURACY (Notes 1, 2)	•							
Resolution				16			Bits	
Integral Naplinearity	INL	MAX130_A			±1.0	±2	LSB	
Integral Nonlinearity	IINL	MAX130_B			±1.0	±4	LOD	
Differential Nonlinearity	DNL	No missing codes		-1		+2	LSB	
Transition Noise		External or internal reference	ce		1		LSB _{RMS}	
		Single-ended inputs	Unipolar		0	±20		
Offset Error		Single-ended inputs	Bipolar		-1.0	±12	mV	
		Differential inputs (Note 3)	Bipolar		-2.0	±20		
Channel-to-Channel Gain Matching		Unipolar or bipolar			0.025		%FSR	
Channel-to-Channel Offset Error Matching		Unipolar or bipolar			1.0		mV	
		Unipolar			3			
Offset Temperature Coefficient		Bipolar		1		μV/°C		
		Fully differential		2				
		Unipolar				±0.5		
Gain Error		Bipolar				±0.8	%FSR	
		Fully differential				±1		
		Unipolar			2			
Gain Temperature Coefficient		Bipolar			1		ppm/°C	
		Fully differential			2]	
DYNAMIC SPECIFICATIONS fin(SINE-WAVE) =	$5kHz$, $V_{IN} = FSR - 0.05dB$ (I	Notes 1, 2)					
		Differential inputs, FSR = ±6 x V _{REF}			91		- dB	
Signal-to-Noise Plus Distortion	SINAD	Single-ended inputs, FSR = ±3 x V _{REF}			89			
Signal-to-Noise lus Distortion	SINAD	Single-ended inputs, FSR =	= (±3 x V _{REF})/2		86		UD	
		Single-ended inputs, FSR =	= (±3 x V _{REF})/4	80	83			

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ELECTRICAL CHARACTERISTICS (continued)

(VAVDD1 = VAVDD2 = VDVDD0 = 5V, VAGND1 = VDGND0 = VAGND2 = VAGND3 = 0V, fCLK = 3.5MHz (50% duty cycle), external clock mode, VREF = 4.096V (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range (±3 x VREF), CDOUT = 50pF, CSSTRB = 50pF, TA = -40°C to +85°C, unless otherwise noted. Typical values are at TA = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP MAX	UNITS
		Differential inputs, FSR = ±6 x V _{REF}		91	
Circulta Naia - Datia	ONID	Single-ended inputs, FSR = ±3 x V _{REF}		89	ı.D
Signal-to-Noise Ratio	SNR	Single-ended inputs, FSR = (±3 x V _{REF})/2		86	dB
		Single-ended inputs, FSR = (±3 x V _{REF})/4		83	
Total Harmonic Distortion (Up to the 5th Harmonic)	THD			-97	dB
Spurious-Free Dynamic Range	SFDR		92	99	dB
Aperture Delay	t _{AD}	Figure 21		15	ns
Aperture Jitter	taj	Figure 21		100	ps
Channel-to-Channel Isolation				105	dB
CONVERSION RATE					
		External clock mode, Figure 2		114	
Byte-Wide Throughput Rate	fSAMPLE	External acquisition mode, Figure 3		84	ksps
		Internal clock mode, Figure 4		106	
ANALOG INPUTS (CH0-CH3 MA	X1301, CH0-	CH7 MAX1300, AGND1)			
Small-Signal Bandwidth		All input ranges, V _{IN} = 100mV _{P-P} (Note 2)		2	MHz
Full-Power Bandwidth		All input ranges, V _{IN} = 4V _{P-P} (Note 2)		700	kHz
		R[2:1] = 001	(-3 x V _{REF})/	(+3 x V _{REF})/ 4	
	e 6) V _{CH} _	R[2:1] = 010	(-3 x V _{REF})/	0	
Input Voltage Range (Table 6)		R[2:1] = 011	0	(+3 x V _{REF})/ 2	V
		R[2:1] = 100	(-3 x V _{REF})/	(+3 x V _{REF})/ 2	
		R[2:1] = 101	-3 x V _{REF}	0	
		R[2:1] = 110	0	+3 x V _{REF}	
		R[2:1] = 111	-3 x V _{REF}	+3 x V _{REF}	
True-Differential Analog Common- Mode Voltage Range	VCMDR	DIF/SGL = 1 (Note 4)	-14	+9	V
Common-Mode Rejection Ratio	CMRR	DIF/SGL = 1, input voltage range = (±3 x V _{REF})/4		75	dB
Input Current	ICH_	-3 x V _{REF} < V _{CH} < +3 x V _{REF}	-1250	+900	μΑ
Input Capacitance	C _{CH} _			5	рF
Input Resistance	R _{CH} _			17	kΩ

ELECTRICAL CHARACTERISTICS (continued)

(VAVDD1 = VAVDD2 = VDVDD0 = 5V, VAGND1 = VDGND0 = VDGND0 = VAGND2 = VAGND3 = 0V, fCLK = 3.5MHz (50% duty cycle), external clock mode, VREF = 4.096V (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range (±3 x VREF), CDOUT = 50pF, CSSTRB = 50pF, TA = -40°C to +85°C, unless otherwise noted. Typical values are at TA = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
INTERNAL REFERENCE (Bypass	REFCAP wi	th 0.1μF to AGND1 and REF with 1.0μF to	AGND1)			
Reference Output Voltage	V _{REF}		4.056	4.096	4.136	V
Reference Temperature Coefficient	TC _{REF}			±30		ppm/°C
Deference Chart Circuit Current	1	REF shorted to AGND1		10		Л
Reference Short-Circuit Current	IREFSC	REF shorted to AVDD		-1		mA
Reference Load Regulation		I _{REF} = 0 to 0.5mA		0.1	10	mV
EXTERNAL REFERENCE (REFC	AP = AVDD)					
Reference Input Voltage Range	V _{REF}		3.800		4.136	V
REFCAP Buffer Disable Threshold	V _{RCTH}	(Note 5)	V _{AVDD1} - 0.4		V _{AVDD1} - 0.1	٧
Reference Input Current	I _{REF}	V _{REF} = +4.096V, external clock mode, external acquisition mode, internal clock mode, or partial power-down mode		90	200	μΑ
		V _{REF} = +4.096V, full power-down mode		±0.1	±10	
Reference Input Resistance	R _{REF}	External clock mode, external acquisition mode, internal clock mode, or partial power-down mode	20	45		kΩ
		Full power-down mode		40		МΩ
DIGITAL INPUTS (DIN, SCLK, CS	<u>.</u>					
Input High Voltage	VIH		0.7 x V _{DVDDO}			V
Input Low Voltage	VIL				0.3 x V _{DVDDO}	V
Input Hysteresis	V _{HYST}			0.2		V
Input Leakage Current	I _{IN}	V _{IN} = 0 to V _{DVDDO}	-10		+10	μΑ
Input Capacitance	C _{IN}			10		рF
DIGITAL OUTPUTS (DOUT, SSTE	RB)					
Output Low Voltage	Vol	$V_{DVDDO} = 4.75V$, $I_{SINK} = 10$ mA			0.4	V
Culput Low Voltage	VOL	V _{DVDDO} = 2.7V, I _{SINK} = 5mA			0.4	, i
Output High Voltage	Voн	ISOURCE = 0.5mA	V _{DVDDO} - 0.4			V
DOUT Tri-State Leakage Current	I _{DDO}	CS = DVDDO	-10		+10	μΑ
POWER REQUIREMENTS (AVDD	1 and AGND	1, AVDD2 and AGND2, DVDD and DGND,	DVDDO and	d DGND	O)	
Analog Supply Voltage	AVDD1		4.75		5.25	V
Digital Supply Voltage	DVDD		4.75		5.25	V

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ELECTRICAL CHARACTERISTICS (continued)

(VAVDD1 = VAVDD2 = VDVDD0 = 5V, VAGND1 = VDGND0 = VDGND0 = VAGND2 = VAGND3 = 0V, fCLK = 3.5MHz (50% duty cycle), external clock mode, VREF = 4.096V (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range (±3 x VREF), CDOUT = 50pF, CSSTRB = 50pF, TA = -40°C to +85°C, unless otherwise noted. Typical values are at TA = +25°C.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Preamplifier Supply Voltage	AVDD2			4.75		5.25	V
Digital I/O Supply Voltage	DVDDO			2.70		5.25	V
AVes Cupply Current	luma	External clock mode, external acquisition	Internal reference		3	3.5	mA
AV _{DD1} Supply Current	lavdd1	mode, or internal clock mode	External reference		2.3	3	IIIA
DV _{DD} Supply Current	IDVDD	External clock mode, or internal cloc	· ·		0.8	2	mA
AV _{DD2} Supply Current	I _{AVDD2}	External clock mode, or internal cloc	· ·		13.5	20	mA
DV _{DDO} Supply Current	IDVDDO	External clock mode, mode, or internal cloc			0.01	1	mA
Total Cuspilis Current		Partial power-down mode			1.3		mA
Total Supply Current		Full power-down mode			0.5		μΑ
Power-Supply Rejection Ratio	PSRR	All analog input range		±0.5		LSB	
TIMING CHARACTERISTICS (Fig	ures 15 and	16)					
		External clock mode		0.272		62	
SCLK Period	t _{CP}	External acquisition m	0.228		62	μs	
		Internal clock mode		0.1			
		External clock mode		109			
SCLK High Pulse Width (Note 6)	tcH	External acquisition mode		92			ns
		Internal clock mode		40			
		External clock mode		109			
SCLK Low Pulse Width (Note 6)	t _{CL}	External acquisition mode		92			ns
		Internal clock mode		40			
DIN to SCLK Setup	tDS			40			ns
DIN to SCLK Hold	tDH			0			ns
SCLK Fall to DOUT Valid	tDO					40	ns
CS Fall to DOUT Enable	t _{DV}					40	ns

ELECTRICAL CHARACTERISTICS (continued)

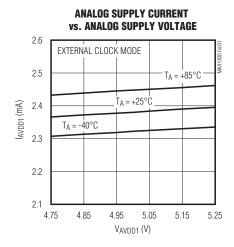
(VAVDD1 = VAVDD2 = VDVDD0 = 5V, VAGND1 = VDGND0 = VDGND0 = VAGND2 = VAGND3 = 0V, fclk = 3.5MHz (50% duty cycle), external clock mode, VREF = 4.096V (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range (±3 x VREF), CDOUT = 50pF, CSSTRB = 50pF, TA = -40°C to +85°C, unless otherwise noted. Typical values are at TA = +25°C.)

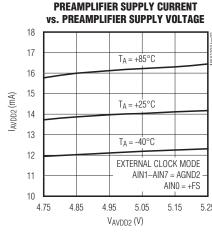
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CS Rise to DOUT Disable	t _{TR}				40	ns
CS Fall to SCLK Rise Setup	tcss		40			ns
CS High Minimum Pulse Width	tcspw		40			ns
SCLK Fall to CS Rise Hold	tcsh		0			ns
SSTRB Rise to CS Fall Setup		(Note 4)	40			ns
DOUT Rise/Fall Time		$C_L = 50pF$		10		ns
SSTRB Rise/Fall Time		$C_L = 50pF$		10		ns

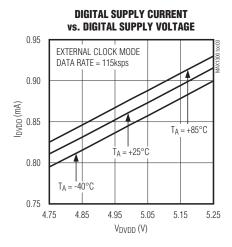
- **Note 1:** Parameter tested at $V_{AVDD1} = V_{AVDD2} = V_{DVDD} = V_{DVDD0} = 5V$.
- **Note 2:** See definitions in the *Parameter Definitions* section at the end of the data sheet.
- Note 3: Guaranteed by correlation with single-ended measurements.
- Note 4: Not production tested. Guaranteed by design.
- Note 5: To ensure external reference operation, V_{REFCAP} must exceed (V_{AVDD1} 0.1V). To ensure internal reference operation, V_{REFCAP} must be below (V_{AVDD1} 0.4V). Bypassing REFCAP with a 0.1µF or larger capacitor to AGND1 sets V_{REFCAP} ≈ 4.096V. The transition point between internal reference mode and external reference mode lies between the REFCAP buffer disable threshold minimum and maximum values (Figures 17 and 18).
- Note 6: The SCLK duty cycle can vary between 40% and 60%, as long as the t_{CL} and t_{CH} timing requirements are met.

Typical Operating Characteristics

(VAVDD1 = VAVDD2 = VDVDD = VDVDD0 = 5V, VAGND1 = VDGND = VDGND0 = VAGND2 = VAGND3 = 0V, fCLK = 3.5MHz (50% duty cycle), external clock mode, VREF = 4.096V (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range, CDOUT = 50pF, CSSTRB = 50pF; unless otherwise noted.)



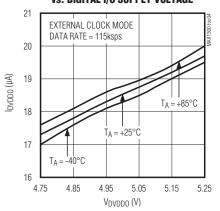




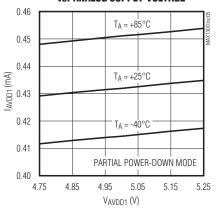
Typical Operating Characteristics (continued)

(VAVDD1 = VAVDD2 = VDVDD = VDVDD0 = 5V, VAGND1 = VDGND = VDGND0 = VAGND2 = VAGND3 = 0V, fCLK = 3.5MHz (50% duty cycle), external clock mode, VREF = 4.096V (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range, CDOUT = 50pF, CSSTRB = 50pF; unless otherwise noted.)

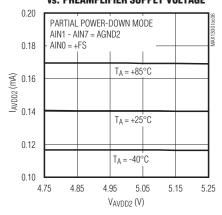
DIGITAL I/O SUPPLY CURRENT vs. DIGITAL I/O SUPPLY VOLTAGE



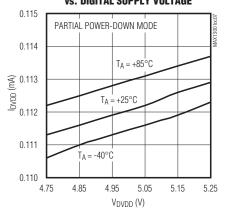
ANALOG SUPPLY CURRENT vs. Analog Supply Voltage



PREAMPLIFIER SUPPLY CURRENT vs. Preamplifier Supply Voltage

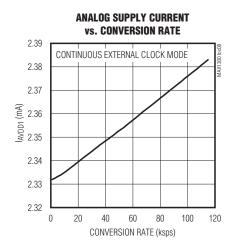


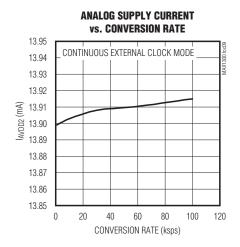
DIGITAL SUPPLY CURRENT vs. DIGITAL SUPPLY VOLTAGE

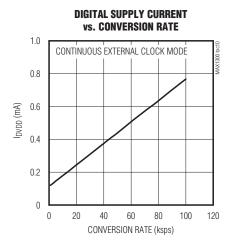


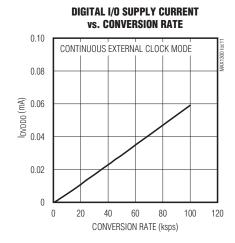
Typical Operating Characteristics (continued)

 $(V_{AVDD1} = V_{AVDD2} = V_{DVDD} = V_{DVDD0} = 5V$, $V_{AGND1} = V_{DGND} = V_{DGND0} = V_{AGND2} = V_{AGND3} = 0V$, $f_{CLK} = 3.5$ MHz (50% duty cycle), external clock mode, $V_{REF} = 4.096V$ (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range, $C_{DOUT} = 50$ pF, $C_{SSTRB} = 50$ pF; unless otherwise noted.)





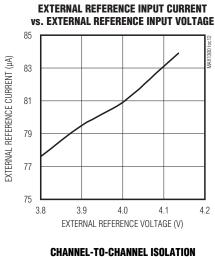


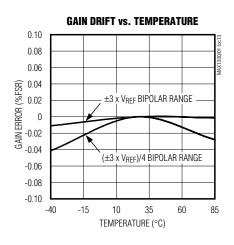


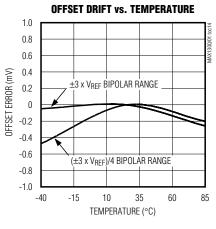
Note 7: For partial power-down and full power-down modes, external clock mode was used for a burst of continuous samples. Partial power-down or full power-down modes were entered thereafter. By using this method, the conversion rate was found by averaging the number of conversions over the time starting from the first conversion to the end of the partial power-down or full power-down modes.

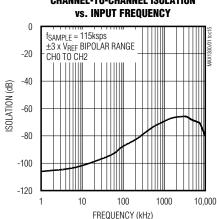
Typical Operating Characteristics (continued)

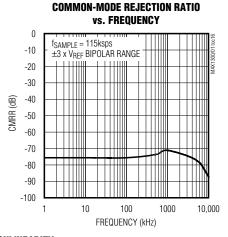
 $(V_{AVDD1} = V_{AVDD2} = V_{DVDD} = V_{DVDD0} = 5V$, $V_{AGND1} = V_{DGND} = V_{DGND0} = V_{AGND2} = V_{AGND3} = 0V$, $f_{CLK} = 3.5MHz$ (50% duty cycle), external clock mode, $V_{REF} = 4.096V$ (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range, $C_{DOUT} = 50pF$, $C_{SSTRB} = 50pF$; unless otherwise noted.)

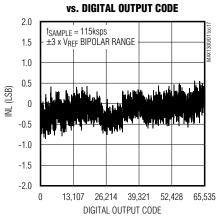




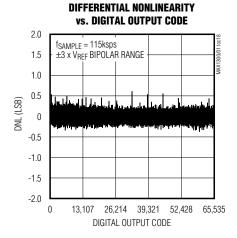


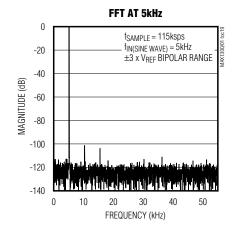






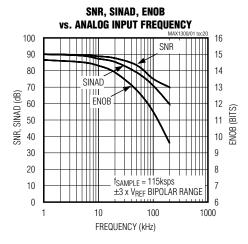
INTEGRAL NONLINEARITY

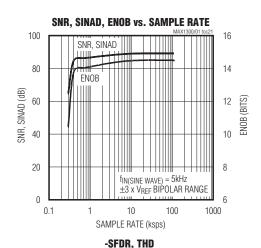


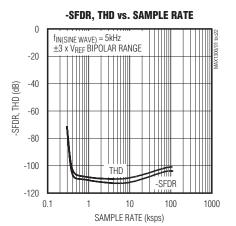


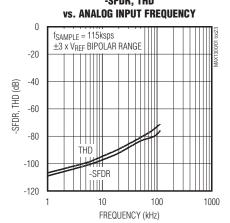
Typical Operating Characteristics (continued)

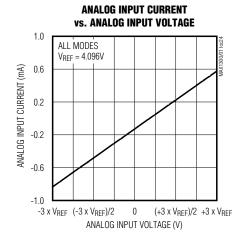
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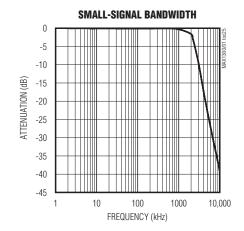








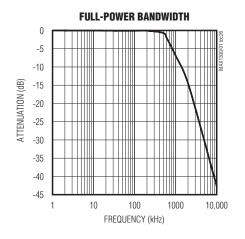


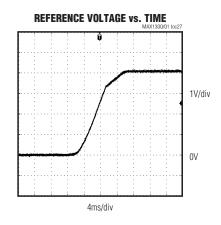


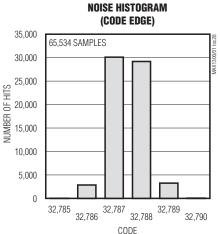
10 ______ /I/XI/M

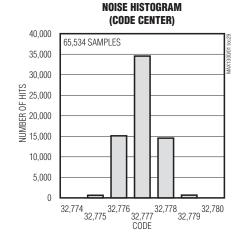
Typical Operating Characteristics (continued)

(VAVDD1 = VAVDD2 = VDVDD = VDVDD0 = 5V, VAGND1 = VDGND = VDGND0 = VAGND2 = VAGND3 = 0V, fCLK = 3.5MHz (50% duty cycle), external clock mode, VREF = 4.096V (external reference operation), REFCAP = AVDD1, maximum single-ended bipolar input range, CDOUT = 50pF, CSSTRB = 50pF; unless otherwise noted.)









Pin Description

PIN			FUNCTION
MAX1300	MAX1301	NAME	FUNCTION
1	2	AVDD1	Analog Supply Voltage 1. Connect AVDD1 to a +4.75V to +5.25V power-supply voltage. Bypass AVDD1 to AGND1 with a 0.1µF capacitor.
2	3	CH0	Analog Input Channel 0
3	4	CH1	Analog Input Channel 1
4	5	CH2	Analog Input Channel 2
5	6	CH3	Analog Input Channel 3
6	_	CH4	Analog Input Channel 4
7	_	CH5	Analog Input Channel 5
8	_	CH6	Analog Input Channel 6
9	_	CH7	Analog Input Channel 7
10	7	CS	Active-Low Chip-Select Input. When \overline{CS} is low, data is clocked into the device from DIN on the rising edge of SCLK. With \overline{CS} low, data is clocked out of DOUT on the falling edge of SCLK. When \overline{CS} is high, activity on SCLK and DIN is ignored and DOUT is high impedance.
11	8	DIN	Serial Data Input. When \overline{CS} is low, data is clocked in on the rising edge of SCLK. When \overline{CS} is high, transitions on DIN are ignored.
12	9	SSTRB	Serial-Strobe Output. When using the internal clock, SSTRB rising edge transitions indicate that data is ready to be read from the device. When operating in external clock mode, SSTRB is always low. SSTRB does not tri-state, regardless of the state of \overline{CS} , and therefore requires a dedicated I/O line.
13	10	SCLK	Serial Clock Input. When $\overline{\text{CS}}$ is low, transitions on SCLK clock data into DIN and out of DOUT. When $\overline{\text{CS}}$ is high, transitions on SCLK are ignored.
14	11	DOUT	Serial Data Output. When $\overline{\text{CS}}$ is low, data is clocked out of DOUT with each falling SCLK transition. When $\overline{\text{CS}}$ is high, DOUT is high impedance.
15	12	DGNDO	Digital I/O Ground. DGND, DGNDO, AGND3, AGND2, and AGND1 must be connected together.
16	13	DGND	Digital Ground. DGND, DGNDO, AGND3, AGND2, and AGND1 must be connected together.
17	14	DVDDO	Digital I/O Supply Voltage Input. Connect DVDDO to a +2.7V to +5.25V power-supply voltage. Bypass DVDDO to DGNDO with a 0.1µF capacitor.
18	15	DVDD	Digital-Supply Voltage Input. Connect DVDD to a +4.75V to +5.25V power-supply voltage. Bypass DVDD to DGND with a 0.1µF capacitor.
19	16	REFCAP	Bandgap-Voltage Bypass Node. For external reference operation, connect REFCAP to AVDD. For internal reference operation, bypass REFCAP with a 0.01µF capacitor to AGND1 (VREFCAP ≈ 4.096V).
20	17	REF	Reference-Buffer Output/ADC Reference Input. For external reference operation, apply an external reference voltage from 3.800V to 4.136V to REF. For internal reference operation, bypassing REF with a 1µF capacitor to AGND1 sets V _{REF} = 4.096V ±1%.

Pin Description (continued)

P	IN	NAME	FUNCTION
MAX1300	MAX1301	NAIVIE	FUNCTION
21	18	AGND3	Analog Signal Ground 3. AGND3 is the ADC negative reference potential. Connect AGND3 to AGND1. DGND, DGNDO, AGND3, AGND2, and AGND1 must be connected together.
22	19	AVDD2	Analog Supply Voltage 2. Connect AVDD2 to a +4.75V to +5.25V power-supply voltage. Bypass AVDD2 to AGND2 with a 0.1µF capacitor.
23	20	AGND2	Analog Ground 2. This ground carries approximately five times more current than AGND1. DGND, DGNDO, AGND3, AGND2, and AGND1 must be connected together.
24	1	AGND1	Analog Ground 1. DGND, DGNDO, AGND3, AGND2, and AGND1 must be connected together.

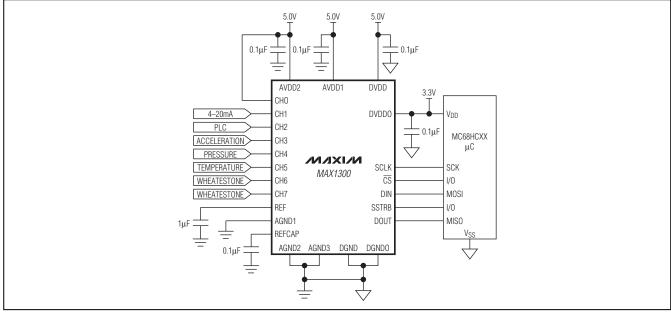


Figure 1. Typical Application Circuit

Detailed Description

The MAX1300/MAX1301 multirange, low-power, 16-bit successive-approximation ADCs operate from a single +5V supply and have a separate digital supply allowing digital interface with 2.7V to 5.25V systems. These 16-bit ADCs have internal track-and-hold (T/H) circuitry that supports single-ended and fully differential inputs. For single-ended conversions, the valid analog input voltage range spans from -3 x VREF below ground to +3 x VREF above ground. The maximum allowable differential input voltage spans from -6 x VREF to +6 x VREF. Data can be converted in a variety of software-programmable channel and data-acquisition configurations. Microprocessor (µP) control is made easy through an SPI-/QSPI-/MICROWIRE-compatible serial interface.

The MAX1300 has eight single-ended analog input channels or four differential channels (see the *Block Diagram* at the end of the data sheet). The MAX1301 has four single-ended analog input channels or two differential channels. Each analog input channel is independently software programmable for seven single-ended input ranges [0 to (+3 x VREF)/2, (-3 x VREF)/2 to 0, 0 to +3 x VREF, -3 x VREF to 0, (±3 x VREF)/4, (±3 x VREF)/2, ±3 x VREF] and three differential input ranges [(±3 x VREF)/2, ±3 x VREF, ±6 x VREF]. Additionally, all analog input channels are fault tolerant to ±16.5V. A fault condition on an idle channel does not affect the conversion result of other channels.

Power Supplies

To maintain a low-noise environment, the MAX1300 and MAX1301 provide separate power supplies for each section of circuitry. Table 1 shows the four separate power supplies. Achieve optimal performance using separate AVDD1, AVDD2, DVDD, and DVDDO supplies. Alternatively, connect AVDD1, AVDD2, and DVDD together as close to the device as possible for a convenient power connection. Connect AGND1, AGND2, AGND3, DGND, and DGNDO together as close to the device as possible. Bypass each supply to the corresponding ground using a 0.1μF capacitor (Table 1). If significant low-frequency noise is present, add a 10μF capacitor in parallel with the 0.1μF bypass capacitor.

Converter Operation

The MAX1300/MAX1301 ADCs feature a fully differential, successive-approximation register (SAR) conversion technique and an on-chip T/H block to convert voltage signals into a 16-bit digital result. Both single-ended and differential configurations are supported with programmable unipolar and bipolar signal ranges.

Track-and-Hold Circuitry

The MAX1300/MAX1301 feature a switched-capacitor T/H architecture that allows the analog input signal to be stored as charge on sampling capacitors. See Figures 2, 3, and 4 for T/H timing and the sampling instants for each operating mode. The MAX1300/MAX1301 analog input circuitry buffers the input signal from the sampling capacitors, resulting in a constant input impedance with varying input voltage (Figure 5).

Analog Input Circuitry

Select differential or single-ended conversions using the associated analog input configuration byte (Table 2). The analog input signal source must be capable of driving the ADC's $17k\Omega$ input resistance (Figure 6).

Figure 6 shows the simplified analog input circuit. The analog inputs are $\pm 16.5 \text{V}$ fault tolerant and are protected by back-to-back diodes. The summing junction voltage, V_{SJ}, is a function of the channel's input common-mode voltage:

$$V_{SJ} = \left(\frac{R1}{R1 + R2}\right) \times 2.375V + \left(1 + \left(\frac{R1}{R1 + R2}\right)\right) \times V_{CM}$$

As a result, the analog input impedance is relatively constant over input voltage as shown in Figure 5.

Table 1. MAX1300/MAX1301 Power Supplies and Bypassing

POWER SUPPLY/GROUND	SUPPLY VOLTAGE RANGE (V)	TYPICAL SUPPLY CURRENT (mA)	CIRCUIT SECTION	BYPASSING
DVDDO/DGNDO	2.7 to 5.25	0.03	Digital I/O	0.1µF to DGNDO
AVDD2/AGND2	4.75 to 5.25	135	Analog Circuitry	0.1µF to AGND2
AVDD1/AGND1	4.75 to 5.25	3.0	Analog Circuitry	0.1µF to AGND1
DVDD/DGND	4.75 to 5.25	0.8	Digital Control Logic and Memory	0.1µF to DGND

Table 2. Analog Input Configuration Byte

BIT NUMBER	NAME	DESCRIPTION			
7	START	Start Bit. The first logic 1 after $\overline{\text{CS}}$ goes low defines the beginning of the analog input configuration byte.			
6	C2				
5	C1	Channel-Select Bits. SEL[2:0] select the analog input channel to be configured (Tables 4 and 5).			
4	C0				
3	DIF/SGL	Differential or Single-Ended Configuration Bit. DIF/SGL = 0 configures the selected analog input channel for single-ended operation. DIF/SGL = 1 configures the channel for differential operation. In single-ended mode, input voltages are measured between the selected input channel and AGND1, as shown in Table 4. In differential mode, the input voltages are measured between two input channels, as shown in Table 5. Be aware that changing DIF/SGL adjusts the FSR, as shown in Table 6.			
2	R2				
1	R1	Input-Range-Select Bits. R[2:0] select the input voltage range, as shown in Table 6 and Figure 7.			
0 R0					

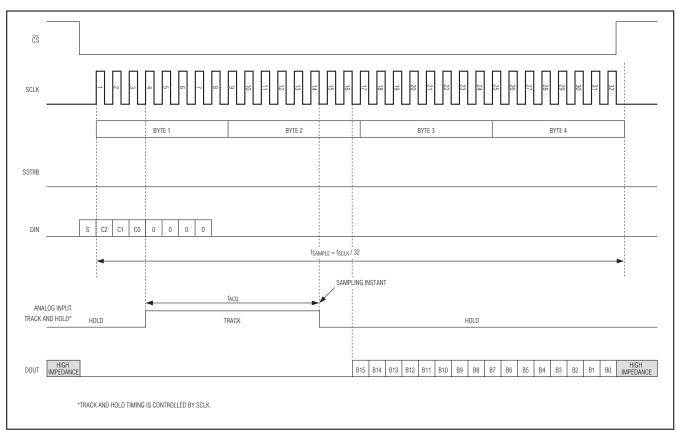


Figure 2. External Clock-Mode Conversion (Mode 0)

Single-ended conversions are internally referenced to AGND1 (Tables 3 and 4). In differential mode, IN+ and IN- are selected according to Tables 3 and 5. When configuring differential channels, the differential pair follows the analog configuration byte for the positive channel. For example, to configure CH2 and CH3 for a ±3 x VREF differential conversion, set the CH2 analog configuration byte for a differential conversion with the ±3 x VREF range (1010 1100). To initiate a conversion for the CH2 and CH3 differential pair, issue the command 1010 0000.

Analog Input Bandwidth

The MAX1300/MAX1301 input-tracking circuitry has a 2MHz small-signal bandwidth. The 2MHz input bandwidth makes it possible to digitize high-speed transient events. Harmonic distortion increases when digitizing signal frequencies above 15kHz as shown in the THD and -SFDR vs. Input Frequency plot in the *Typical Operating Characteristics*.

Analog Input Range and Fault Tolerance

Figure 7 illustrates the software-selectable single-ended analog input voltage range that produces a valid digital output. Each analog input channel can be independently programmed to one of seven single-ended input ranges by setting the R[2:0] control bits with DIF/SGL = 0.

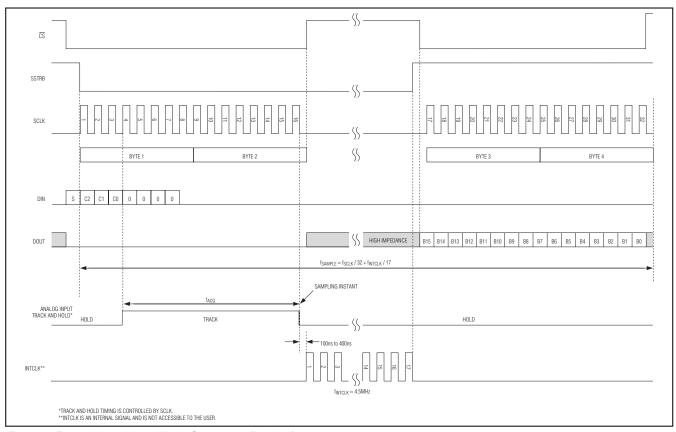


Figure 3. External Acquisition-Mode Conversion (Mode 1)

Figure 8 illustrates the software-selectable differential analog input voltage range that produces a valid digital output. Each analog input differential pair can be independently programmed to one of three differential input ranges by setting the R[2:0] control bits with DIF/SGL = 1.

Regardless of the specified input voltage range and whether the channel is selected, each analog input is ±16.5V fault tolerant. The analog input fault protection is active whether the device is unpowered or powered.

Any voltage beyond FSR, but within the ± 16.5 V fault-tolerant range, applied to an analog input results in a full-scale output voltage for that channel.

Clamping diodes with breakdown thresholds in excess of 16.5V protect the MAX1300/MAX1301 analog inputs during ESD and other transient events (Figure 6). The clamping diodes do not conduct during normal device operation, nor do they limit the current during such transients. When operating in an environment with the potential for high-energy voltage and/or current transients, protect the MAX1300/MAX1301 externally.

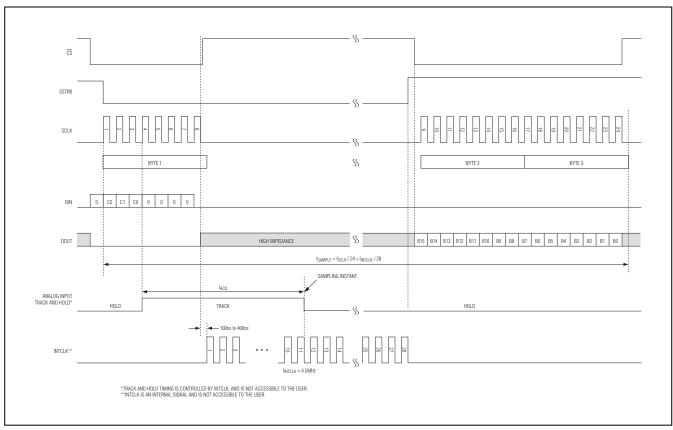


Figure 4. Internal Clock-Mode Conversion (Mode 2)

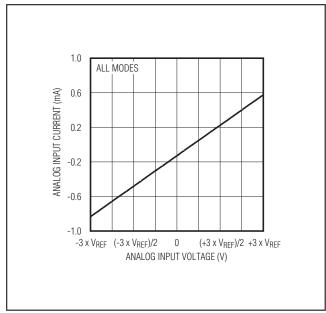


Figure 5. Analog Input Current vs. Input Voltage

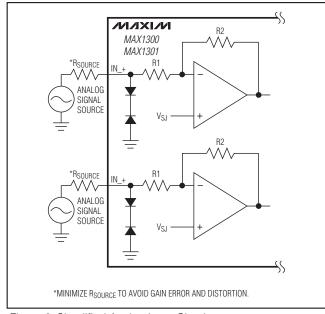


Figure 6. Simplified Analog Input Circuit

Table 3. Input Data Word Formats

	DATA BIT							
OPERATION	D7 (START)	D6	D5	D4	D3	D2	D1	D0
Conversion-Start Byte (Tables 4 and 5)	1	C2	C1	C0	0	0	0	0
Analog-Input Configuration Byte (Table 2)	1	C2	C1	C0	DIF/SGL	R2	R1	R0
Mode-Control Byte (Table 7)	1	M2	M1	MO	1	0	0	0

Table 4. Channel Selection in Single-Ended Mode (DIF/ $\overline{SGL} = 0$)

CHANNEL-SELECT BIT			CHANNEL								
C2	C1	C0	CH0	CH1	CH2	CH3	CH4	CH5	CH6	CH7	AGND1
0	0	0	+								-
0	0	1		+							-
0	1	0			+						-
0	1	1				+					-
1	0	0					+				-
1	0	1						+			-
1	1	0							+		-
1	1	1								+	-

Table 5. Channel Selection in True-Differential Mode (DIF/SGL = 1)

CHANNEL-SELECT BIT			CHANNEL								
C2	C1	C0	CH0	CH1	CH2	CH3	CH4	CH5	CH6	CH7	AGND1
0	0	0	+	-							
0	0	1	RESERVED								
0	1	0			+	-					
0	1	1	RESERVED								
1	0	0					+	-			
1	0	1	RESERVED								
1	1	0							+	-	
1	1	1	RESERVED								

Differential Common-Mode Range

The MAX1300/MAX1301 differential common-mode range (V_{CMDR}) must remain within -14V to +10V to obtain valid conversion results. The differential common-mode range is defined as:

$$V_{CMDR} = \frac{(CH_+) + (CH_-)}{2}$$

In addition to the common-mode input voltage limitations, each individual analog input must be limited to $\pm 16.5V$ with respect to AGND1.

The range-select bits R[2:0] in the analog input configuration bytes determine the full-scale range for the corresponding channel (Tables 2 and 6). Figures 9, 10, and 11 show the valid analog input voltage ranges for the MAX1300/MAX1301 when operating with FSR = $(\pm 3 \times V_{REF})/2$, FSR = $\pm 3 \times V_{REF}$, and FSR = $\pm 6 \times V_{REF}$, respectively. The shaded area contains the valid common-mode voltage ranges that support the entire FSR.

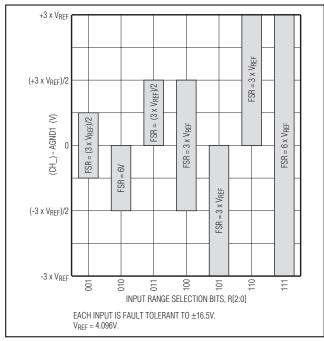


Figure 7. Single-Ended Input Voltage Ranges

Digital Interface

The MAX1300/MAX1301 feature a serial interface that is compatible with SPI/QSPI and MICROWIRE devices. DIN, DOUT, SCLK, \overline{CS} , and SSTRB facilitate bidirectional communication between the MAX1300/MAX1301 and the master at SCLK rates up to 10MHz (internal clock mode, mode 2), 3.67MHz (external clock mode, mode 0), or 4.39MHz (external acquisition mode, mode 1). The master, typically a microcontroller, should use the CPOL = 0, CPHA = 0, SPI transfer format, as shown in the timing diagrams of Figures 2, 3, and 4.

The digital interface is used to:

- Select single-ended or true-differential input channel configurations
- Select the unipolar or bipolar input range
- Select the mode of operation:
 External clock (mode 0)
 External acquisition (mode 1)
 Internal clock (mode 2)
 Reset (mode 4)
 Partial power-down (mode 6)

Full power-down (mode 7)

• Initiate conversions and read results

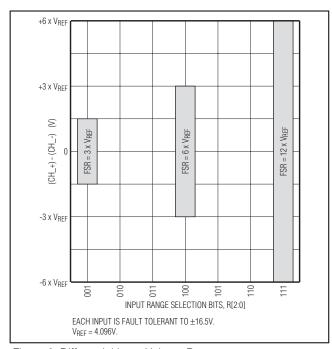


Figure 8. Differential Input Voltage Ranges

Chip Select (CS)

CS enables communication with the MAX1300/MAX1301. When CS is low, data is clocked into the device from DIN on the rising edge of SCLK and data is clocked out of DOUT on the falling edge of SCLK. When CS is high, activity on SCLK and DIN is ignored and DOUT is high impedance allowing DOUT to be shared with other peripherals. SSTRB is never high impedance and therefore cannot be shared with other peripherals.

Serial Strobe Output (SSTRB)

As shown in Figures 3 and 4, the SSTRB transitions high to indicate that the ADC has completed a conversion and results are ready to be read by the master. SSTRB remains low in the external clock mode (Figure 2) and consequently may be left unconnected. SSTRB is driven high or low regardless of the state of \overline{CS} , therefore SSTRB cannot be shared with other peripherals.

Table 6. Range-Select Bits

DIF/SGL	R2	R1	R0	MODE	TRANSFER FUNCTION	
0	0	0	0	No Range Change*	_	
0	0	0	1	Single-Ended Bipolar (-3 x V _{REF})/4 to (+3 x V _{REF})/4 Full-Scale Range (FSR) = (3 x V _{REF})/2	Figure 12	
0	0	1	0	Single-Ended Unipolar (-3 x V _{REF})/2 to 0 FSR = (3 x V _{REF})/2	Figure 13	
0	0	1	1	Single-Ended Unipolar 0 to (+3 x V _{REF})/2 FSR = (+3 x V _{REF})/2	Figure 14	
0	1	0	0	Single-Ended Bipolar (-3 x V _{REF})/2 to (+3 x V _{REF})/2 FSR = 3 x V _{REF}	Figure 12	
0	1	0	1	Single-Ended Unipolar -3 x V _{REF} to 0 FSR = 3 x V _{REF}	Figure 13	
0	1	1	0	Single-Ended Unipolar 0 to +3 x V _{REF} FSR = 3 x V _{REF}	Figure 14	
0	1	1	1	DEFAULT SETTING Single-Ended Bipolar -3 x V _{REF} to +3 x V _{REF} FSR = 6 x V _{REF}	Figure 12	
1	0	0	0	No Range Change**	_	
1	0	0	1	Differential Bipolar (-3 x V _{REF})/2 to (+3 x V _{REF})/2 FSR = 3 x V _{REF}	Figure 12	
1	0	1	0	Reserved	_	
1	0	1	1	Reserved	_	
1	1	0	0	Differential Bipolar -3 x V _{REF} to +3 x V _{REF} FSR = 6 x V _{REF}	Figure 12	
1	1	0	1	Reserved		
1	1	1	0	Reserved	_	
1	1	1	1	Differential Bipolar -6 x V _{REF} to +6 x V _{REF} FSR = 12 x V _{REF}	Figure 12	

^{*}Conversion-Start Byte (see Table 3).

^{**}Mode-Control Byte (see Table 3).

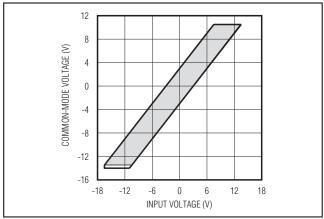


Figure 9. Common-Mode Voltage vs. Input Voltage (FSR = 3 x V_{REF})

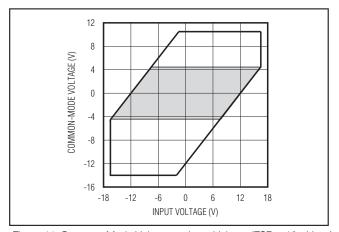


Figure 11. Common-Mode Voltage vs. Input Voltage (FSR = $12 \times V_{REF}$)

Start Bit

Communication with the MAX1300/MAX1301 is accomplished using the three input data word formats shown in Table 3. Each input data word begins with a start bit. The start bit is defined as the first high bit clocked into DIN with $\overline{\text{CS}}$ low when any of the following are true:

- Data conversion is not in process and all data from the previous conversion has clocked out of DOUT.
- The device is configured for operation in external clock mode (mode 0) and previous conversion-result bits B15–B3 have clocked out of DOUT.
- The device is configured for operation in external acquisition mode (mode 1) and previous conversionresult bits B15–B7 have clocked out of DOUT.
- The device is configured for operation in internal clock mode, (mode 2) and previous conversionresult bits B15–B4 have clocked out of DOUT.

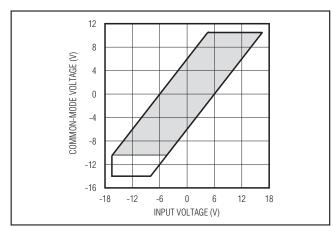


Figure 10. Common-Mode Voltage vs. Input Voltage (FSR = 6 x V_{REF})

Output Data Format

Output data is clocked out of DOUT in offset binary format on the falling edge of SCLK, MSB first (B15). For output binary codes, see the *Transfer Function* section and Figures 12, 13, and 14.

Configuring Analog Inputs

Each analog input has two configurable parameters:

- Single-ended or true-differential input
- Input voltage range

These parameters are configured using the analog input configuration byte as shown in Table 2. Each analog input has a dedicated register to store its input configuration information. The timing diagram of Figure 15 shows how to write to the analog input configuration registers. Figure 16 shows DOUT and SSTRB timing.

Transfer Function

An ADC's transfer function defines the relationship between the analog input voltage and the digital output code. Figures 12, 13, and 14 show the MAX1300/MAX1301 transfer functions. The transfer function is determined by the following characteristics:

- Analog input voltage range
- Single-ended or differential configuration
- Reference voltage

The axes of an ADC transfer function are typically in least significant bits (LSBs). For the MAX1300/MAX1301, an LSB is calculated using the following equation:

$$1 LSB = \frac{FSR \times V_{REF}}{2^{N} \times 4.096V}$$

where N is the number of bits (N = 16) and FSR is the full-scale range (see Figures 7 and 8).

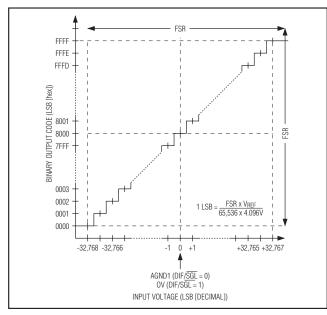


Figure 12. Ideal Bipolar Transfer Function, Single-Ended or Differential Input

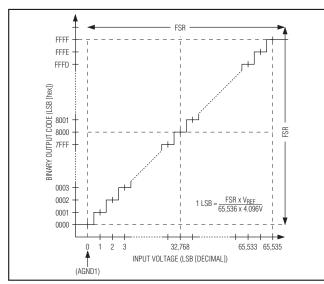


Figure 14. Ideal Unipolar Transfer Function, Single-Ended Input, 0 to +FSR

Mode Control

The MAX1300/MAX1301 contain one byte-wide mode-control register. The timing diagram of Figure 15 shows how to use the mode-control byte, and the mode-control byte format is shown in Table 7. The mode-control byte is used to select the conversion method and to control the power modes of the MAX1300/MAX1301.

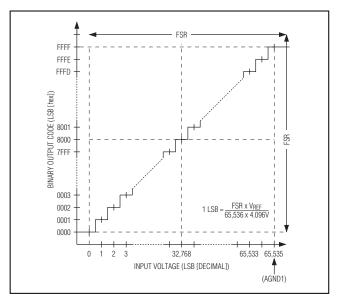


Figure 13. Ideal Unipolar Transfer Function, Single-Ended Input, -FSR to 0

Selecting the Conversion Method

The conversion method is selected using the mode-control byte (see the *Mode Control* section), and the conversion is initiated using a conversion-start command (Table 3, and Figures 2, 3, and 4). The MAX1300/MAX1301 convert analog signals to digital data using one of three methods:

- External Clock Mode, Mode 0 (Figure 2)
 - Highest maximum throughput (see the *Electrical Characteristics* table)
 - User controls the sample instant
 - $\overline{\text{CS}}$ remains low during the conversion
 - User supplies SCLK throughout the ADC conversion and reads data at DOUT
- External Acquisition Mode, Mode 1 (Figure 3)
 - Lowest maximum throughput (see the *Electrical Characteristics* table)
 - User controls the sample instant

 - After SSTRB transitions high, the user supplies two bytes of SCLK and reads data at DOUT
- Internal Clock Mode, Mode 2 (Figure 4)
 - High maximum throughput (see the *Electrical Characteristics* table)

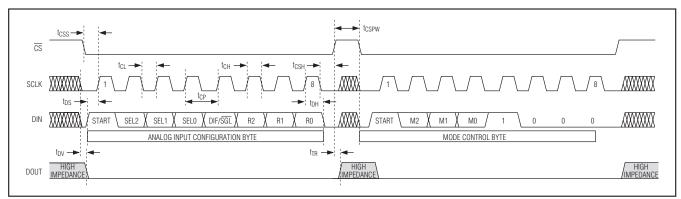


Figure 15. Analog Input Configuration Byte and Mode-Control Byte Timing

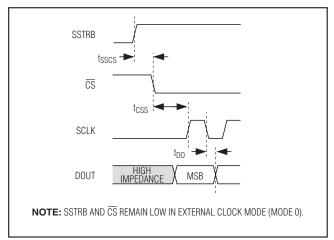


Figure 16. DOUT and SSTRB Timing

- The internal clock controls the sampling instant
- User supplies one byte of SCLK, then drives CS high to relieve processor load while the ADC converts

 After SSTRB transitions high, the user supplies two bytes of SCLK and reads data at DOUT

External Clock Mode (Mode 0)

The MAX1300/MAX1301's fastest maximum throughput rate is achieved operating in external clock mode. SCLK controls both the acquisition and conversion of the analog signal, facilitating precise control over when the analog signal is captured. The analog input sampling instant is at the falling edge of the 14th SCLK (Figure 2).

Since SCLK drives the conversion in external clock mode, the SCLK frequency should remain constant while the conversion is clocked. The minimum SCLK frequency prevents droop in the internal sampling capacitor voltages during conversion.

SSTRB remains low in the external clock mode, and as a result may be left unconnected if the MAX1300/MAX1301 will always be used in the external clock mode.

Table 7. Mode-Control Byte

BIT NUMBER	BIT NAME	DESCRIPTION					
7	START	Start Bit. The first logic 1 after $\overline{\text{CS}}$ goes low defines the beginning of the mode-control byte.					
6	M2						
5	M1	Mode-Control Bits. M[2:0] select the mode of operation as shown in Table 8.					
4	MO						
3	1	Bit 3 must be a logic 1 for the mode-control byte.					
2	0	Bit 2 must be a logic 0 for the mode-control byte.					
1	0	Bit 1 must be a logic 0 for the mode-control byte.					
0	0	Bit 0 must be a logic 0 for the mode-control byte.					

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8- and 4-Channel, ±3 x VREF Multirange Inputs, Serial 16-Bit ADCs

Table 8. Mode-Control Bits M[2:0]

M2	M1	МО	MODE			
0	0	0	External Clock (DEFAULT)			
0	0	1	External Acquisition			
0	1	0	Internal Clock			
0	1	1	Reserved			
1	0	0	Reset			
1	0	1	Reserved			
1	1	0	Partial Power-Down			
1	1	1	Full Power-Down			

External Acquisition Mode (Mode 1)

The slowest maximum throughput rate is achieved with the external acquisition method. SCLK controls the acquisition of the analog signal in external acquisition mode, facilitating precise control over when the analog signal is captured. The internal clock controls the conversion of the analog input voltage. The analog input sampling instant is at the falling edge of the 16th SCLK (Figure 3).

For the external acquisition mode, $\overline{\text{CS}}$ must remain low for the first 15 clock cycles and the rise on or after the falling edge of the 16th SCLK cycle as shown in Figure 3. For optimal performance, idle DIN and SCLK during the conversion. With careful board layout, transitions at DIN and SCLK during the conversion have a minimal impact on the conversion result.

After the conversion is complete, SSTRB asserts high and $\overline{\text{CS}}$ can be brought low to read the conversion result. SSTRB returns low on the rising SCLK edge of the subsequent start bit.

Internal Clock Mode (Mode 2)

In internal clock mode, the internal clock controls both acquisition and conversion of the analog signal. The internal clock starts approximately 100ns to 400ns after the falling edge of the eighth SCLK and has a rate of about 4.5MHz. The analog input sampling instant occurs at the falling edge of the 11th internal clock signal (Figure 4).

For the internal clock mode, $\overline{\text{CS}}$ must remain low for the first seven SCLK cycles and then rise on or after the falling edge of the eighth SCLK cycle. After the conversion is complete, SSTRB asserts high and $\overline{\text{CS}}$ can be brought low to read the conversion result. SSTRB returns low on the rising SCLK edge of the subsequent start bit.

Reset (Mode 4)

As shown in Table 8, set M[2:0] = 100 to reset the MAX1300/MAX1301 to its default conditions. The default conditions are full power operation with each channel configured for $\pm 3 \times V_{REF}$, bipolar, single-ended conversions using external clock mode (mode 0).

Partial Power-Down Mode (Mode 6)

As shown in Table 8, when M[2:0] = 110, the device enters partial power-down mode. In partial power-down, all analog portions of the device are powered down except for the reference voltage generator and bias supplies.

To exit partial power-down, change the mode by issuing one of the following mode-control bytes (see the *Mode Control* section):

- External-Clock-Mode Control Byte
- External-Acquisition-Mode Control Byte
- Internal-Clock-Mode Control Byte
- Reset Byte
- Full Power-Down-Mode Control Byte

This prevents the MAX1300/MAX1301 from inadvertently exiting partial power-down mode because of a $\overline{\text{CS}}$ glitch in a noisy digital environment.

Full Power-Down Mode (Mode 7)

When M[2:0] = 111, the device enters full power-down mode and the total supply current falls to $1\mu A$ (typ). In full power-down, all analog portions of the device are powered down. When using the internal reference, upon exiting full power-down mode, allow 10ms for the internal reference voltage to stabilize prior to initiating a conversion.

To exit full power-down, change the mode by issuing one of the following mode-control bytes (see the *Mode Control* section):

• External-Clock-Mode Control Byte

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- External-Acquisition-Mode Control Byte
- Internal-Clock-Mode Control Byte
- Reset Byte
- Partial Power-Down-Mode Control Byte

This prevents the MAX1300/MAX1301 from inadvertently exiting full power-down mode because of a $\overline{\text{CS}}$ glitch in a noisy digital environment.

Power-On Reset

The MAX1300/MAX1301 power up in normal operation configured for external clock mode with all circuitry active (Tables 7 and 8). Each analog input channel (CH0-CH7) is set for single-ended conversions with a ±3 x VREF bipolar input range (Table 6).

Allow the power supplies to stabilize after power-up. Do not initiate any conversions until the power supplies have stabilized. Additionally, allow 10ms for the internal reference to stabilize when $C_{REF} = 1.0 \mu F$ and $C_{REF} = 0.1 \mu F$. Larger reference capacitors require longer stabilization times.

Internal or External Reference

The MAX1300/MAX1301 operate with either an internal or external reference. The reference voltage impacts the ADC's FSR (Figures 12, 13, and 14). An external reference is recommended if more accuracy is required than the internal reference provides, and/or multiple converters require the same reference voltage.

Internal Reference

The MAX1300/MAX1301 contain an internal 4.096V bandgap reference. This bandgap reference is connected to REFCAP through a nominal $5k\Omega$ resistor (Figure 17). The voltage at REFCAP is buffered creating 4.096V at REF. When using the internal reference, bypass

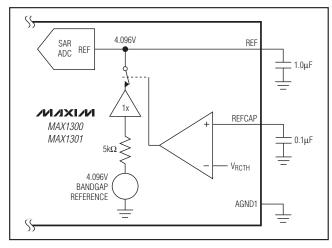


Figure 17. Internal Reference Operation

REFCAP with a 0.1µF or greater capacitor to AGND1 and bypass REF with a 1.0µF or greater capacitor to AGND1.

External Reference

For external reference operation, disable the internal reference and reference buffer by connecting REFCAP to AVDD1. With AVDD1 connected to REFCAP, REF becomes a high-impedance input and accepts an external reference voltage. The MAX1300/MAX1301 can accept an external reference voltage of 4.096V or less. However, to meet all of the electrical characteristic specifications, V_{REF} must be > 38V. The MAX1300/MAX1301 external reference current varies depending on the applied reference voltage and the operating mode (see the External Reference Input Current vs. External Reference Input Voltage in the *Typical Operating Characteristics*).

_Applications Information

Noise Reduction

Additional samples can be taken and averaged (oversampling) to remove the effect of transition noise on conversion results. The square root of the number of samples determines the improvement in performance. For example, with $2/3LSB_{RMS}$ ($4LSB_{P-P}$) transition noise, 16 ($4^2 = 16$) samples must be taken to reduce the noise to $1LSB_{P-P}$.

Interface with 0 to 10V Signals

In industrial control applications, 0 to 10V signaling is common. For 0 to 10V applications, configure the selected MAX1300/MAX1301 input channel for the single-ended 0 to 3 x V_{REF} input range (R[2:0] = 110, Table 6). The 0 to 3 x V_{REF} range accommodates 0 to 10V where the signals saturate at approximately $3 \times V_{REF}$ if out of range.

Interface with 4-20mA Signals

Figure 19 illustrates a simple interface between the MAX1300/MAX1301 and a 4-20mA signal. 4-20mA signaling can be used as a binary switch (4mA represents a logic-low signal, 20mA represents a logic-high signal), or for precision communication where currents between 4mA and 20mA represent intermediate analog data. For binary switch applications, connect the 4-20mA signal to the MAX1300/MAX1301 with a resistor to ground. For example, a 250 Ω resistor converts the 4-20mA signal to a 1V to 5V signal. Adjust the resistor value so the parallel combination of the resistor and the MAX1300/MAX1301 source impedance is 250Ω . In this application, select the single-ended 0 to $(3 \times V_{REF})/2$ range (R[2:0] = 011, Table 6). For applications that require precision measurements of continuous analog currents between 4mA and 20mA, use a buffer to prevent the MAX1300/MAX1301 input from diverting current from the 4-20mA signal.