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# Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



19-2741; Rev 0; 4/03

**EVALUATION KIT AVAILABLE**

## **MAXM** TFT LCD DC-to-DC Converter with Operational Amplifiers

### General Description

The MAX1542/MAX1543 include a high-performance boost regulator and two high-current operational amplifiers for active matrix, thin-film transistor (TFT), liquidcrystal displays (LCDs). Also included is a logiccontrolled, high-voltage switch with adjustable delay. The MAX1543 includes an additional high-voltage load switch and features pin-selectable boost regulator switching frequency.

The step-up DC-to-DC converter is a high-frequency 640kHz (MAX1543)/1.2MHz (MAX1542/MAX1543) current-mode regulator with a built-in power MOSFET that allows the use of ultra-small inductors and ceramic capacitors. It provides fast transient response to pulsed loads while producing efficiencies over 85%.

The two easy-to-use, high-performance operational amplifiers can drive the LCD backplane (V<sub>COM</sub>) and/or the gamma correction divider string. The devices feature high short-circuit current (150mA), fast slew rate  $(7.5V/\mu s)$ , wide bandwidth (12MHz), and Rail-to-Rail<sup>®</sup> inputs and outputs.

The MAX1542/MAX1543 are available in 20-pin thin QFN packages with a maximum thickness of 0.8mm for ultra-thin LCD panel design.

Applications

Notebook Computer Displays LCD Monitor Panels PDAs Car Navigation Displays



### $MNIM$

Features

♦ **Ultra-High-Performance Step-Up Regulator Fast Transient Response to Pulsed Load Using Current-Mode Control Architecture High-Accuracy Output Voltage (1.3%) Built-In 14V, 1.2A, 0.2**Ω **N-Channel Power MOSFET with Lossless Current-Sensing High Efficiency (85%) 8-Step Current-Controlled Digital Soft-Start**

♦ **Two High-Performance Operational Amplifiers 150mA Output Short-Circuit Current 7.5V/µs Slew Rate 12MHz -3dB Bandwidth Rail-to-Rail Inputs/Outputs Unity Gain Stable**

- ♦ **Logic-Controlled High-Voltage Switch with Adjustable Delay**
- ♦ **Timer Delay Latch FB Fault Protection**
- ♦ **Thermal Protection**
- ♦ **2.6V to 5.5V Input Operating Voltage Range**
- ♦ **3.6mA (Switching), 0.45mA (Not Switching) Quiescent Current**
- ♦ **Ultra-Thin 20-Pin Thin QFN Package (5mm x 5mm x 0.8mm)**

### **Pin Configurations Concretivity Contracts** Ordering Information



**For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.**

### **ABSOLUTE MAXIMUM RATINGS**

IN, CTL, COMP, FB, DEL, FREQ (MAX1543)





Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **ELECTRICAL CHARACTERISTICS**

(V<sub>IN</sub> = 3V, V<sub>SUP</sub> = 8V, V<sub>SRC</sub> = 28V, FREQ = IN (MAX1543), PGND = AGND = 0,  $T_A = 0^\circ \text{C}$  to  $+85^\circ \text{C}$ , typical values at  $T_A = +25^\circ \text{C}$ , unless otherwise noted.)





### **ELECTRICAL CHARACTERISTICS (continued)**

(V<sub>IN</sub> = 3V, V<sub>SUP</sub> = 8V, V<sub>SRC</sub> = 28V, FREQ = IN (MAX1543), PGND = AGND = 0,  $T_A = 0^\circ \text{C}$  to +85°C, typical values at  $T_A = +25^\circ \text{C}$ , unless otherwise noted.)





### **ELECTRICAL CHARACTERISTICS (continued)**

(V<sub>IN</sub> = 3V, V<sub>SUP</sub> = 8V, V<sub>SRC</sub> = 28V, FREQ = IN (MAX1543), PGND = AGND = 0,  $T_A = 0^\circ \text{C}$  to +85°C, typical values at  $T_A = +25^\circ \text{C}$ , unless otherwise noted.)



### **ELECTRICAL CHARACTERISTICS**

(VIN = 3V, VSUP = 8V, VSRC = 28V, FREQ = IN (MAX1543), PGND = AGND = 0, **TA = -40°C to +85°C,** unless otherwise noted.)



**MAXIM** 

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{IN} = 3V, V_{SUP} = 8V, V_{SRC} = 28V, FREQ = IN (MAX1543), PGND = AGND = 0, **T_A = -40°C** to **+85°C**, unless otherwise noted.)$ 



 $(V_{IN} = 3.3V, V_{MAIN} = 8V, f_{OSC} = 1.2MHz, T_A = +25°C, unless otherwise noted.)$ STEP-UP REGULATOR OUTPUT VOLTAGE STEP-UP REGULATOR EFFICIENCY STEP-UP REGULATOR EFFICIENCY vs. LOAD CURRENT (V<sub>MAIN</sub> = 8V) vs. LOAD CURRENT (V<sub>MAIN</sub> = 8V) vs. LOAD CURRENT (V<sub>MAIN</sub> = 8V) 95 95 8.1  $\overline{1111111}$ MAX1542 toc03 MAX1542 toc02 MAX1542 toc01  $V_{IN} = 5V$ MAX1543 MAX1543 90 90  $f<sub>OSC</sub> = 1.2MHz$  $f<sub>OSC</sub> = 640kHz$ 8.0 85  $L = 4.7$ uH 85  $L = 10uH$  $||||||||$  $V_{IN} = 5V$ OUTPUT VOLTAGE (V) OUTPUT VOLTAGE (V) 80 80 7.9 EFFICIENCY (%) EFFICIENCY (%) Ш 加Ⅲ  $($ % $)$ TTIIIT. EFFICIENCY (% 75  $V_{IN} = 3.3$ 75  $3.3V$ EFFICIENCY 7.8  $V_{IN} = 5V$ 70 70 Ш  $\frac{1}{2}$  V<sub>IN</sub><br> $\frac{1}{2}$ 65 7.7 65 Vini M 60 60 7.6  $V_{IN} = 3.3V$ 55 55  $f<sub>OSC</sub> = 1.2MHz$ 50 50 7.5 10 100 10 1 10 100 1000 1 10 100 1000 1 10 100 1000 LOAD CURRENT (mA) LOAD CURRENT (mA) LOAD CURRENT (mA) STEP-UP REGULATOR SUPPLY CURRENT STEP-UP REGULATOR SUPPLY CURRENT SWITCHING FREQUENCY vs. SUPPLY VOLTAGE vs. TEMPERATURE vs. INPUT VOLTAGE 0.7 2.0 1400 MAX1542 toc04 NO LOAD MAX1542 toc05 MAX1542 toc06 MAX1543  $V_{IN} = 3.3V$  $I_{MAIN} = 200mA$ 0.6 f<sub>OSC</sub> = 1.2MHz<br>R<sub>1</sub> = 75kΩ 1.6 SWITCHING FREQUENCY (kHz) 1200 CURRENT INTO INDUCTOR SUPPLY CURRENT (mA) SUPPLY CURRENT (mA) 0.5 SUPPLY CURRENT (mA) SUPPLY CURRENT (mA)  $R_2 = 13.7k\Omega$ SUP DISCONNECTED 1.2  $FREQ = IN$ CURRENT INTO IN PIN 1000 0.4 CURRENT INTO INDUCTOR 0.3  $FREQ = AGND$ 0.8 800 CURRENT INTO IN PIN NO LOAD  $0.2$  $f<sub>OSC</sub> = 1.2MHz$  $0.4$ 600  $R_1 = 75k\Omega$ 0.1  $R_2 = 13.7k\Omega$ SUP DISCONNECTED  $\boldsymbol{0}$  $\boldsymbol{0}$ 400 3.0 3.5 4.0 4.5 5.0 -15 10 35 60 3.0 3.5 4.0 4.5 5.0 2.5 3.0 3.5 4.0 4.5 5.0 5.5 -40 -15 10 35 60 85 2.5 3.0 3.5 4.0 4.5 5.0 5.5  $V_{IN}$  (V) TEMPERATURE (°C)  $V_{IN}$  (V) SUP SUPPLY CURRENT SUP SUPPLY CURRENT vs. TEMPERATURE vs. SUP VOLTAGE 2.0 1.75 MAX1542 toc07 MAX1542 toc08 NO LOAD  $V_{SUP} = 13V$ BUFFER CONFIGURATION  $POS$  =  $V_{SUP}/2$ 1.50 1.6 ISUP (mA) ISUP (mA)  $V_{SUP} = 8V$ 1.25 1.2 1.00 NO LOAD BUFFER CONFIGURATION  $V_{SUP} = 5V$  $V<sub>POS</sub> = V<sub>SUP</sub>/2$ 0.8 0.75 6.0 7.5 9.0 10.5 12.0 -40 -15 10 35 60 85 -15 10 35 60 4.5 6.0 7.5 9.0 10.5 12.0 13.5 TEMPERATURE (°C) V<sub>SUP</sub> (V)

### Typical Operating Characteristics

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MAX1542/MAX1543

**MAX1542/MAX1543** 

### Typical Operating Characteristics (continued)

( $V_{IN}$  = 3.3V,  $V_{MAIN}$  = 8V, f<sub>OSC</sub> = 1.2MHz,  $T_A$  = +25°C, unless otherwise noted.)









#### OPERATIONAL AMPLIFIER OUTPUT LOW VOLTAGE vs. LOAD



**MAX1542/MAX1543** MAX1542/MAX1543





**MAXIM** 

### Typical Operating Characteristics (continued)

( $V_{IN}$  = 3.3V,  $V_{MAIN}$  = 8V, f<sub>OSC</sub> = 1.2MHz,  $T_A$  = +25°C, unless otherwise noted.)



MAX1542 toc18



HEAVY-LOAD SOFT-START WAVEFORMS



2ms/div

TIMER DELAY LATCH RESPONSE TO OVERLOAD



OPERATIONAL AMPLIFIER RAIL-TO-RAIL I/O PERFORMANCE





**8 \_**

**MAXIM** 

200ns/div

 $V_{SUP} = 8V$ ,  $Av = 1$ 



POS\_ 50mV/div AC-COUPLED

OUT\_ 50mV/div AC-COUPLED



### Pin Description

CH2 + OVER 6.234% CH2 - OVER 2.352%







### Typical Application Circuits

The MAX1542 typical application circuit (Figure 1) and the MAX1543 typical application circuit (Figure 2) generate an +8V source driver supply and approximately +22V and -7V gate driver supplies for TFT displays. The input voltage is from +2.6V to +5.5V. Table 1 lists recommended components and Table 2 lists contact information for component suppliers.

### Detailed Description

The MAX1542/MAX1543 include a high-performance step-up regulator, two high-current operational amplifiers, and startup timing and level-shifting functionality useful for active matrix TFT LCDs. Figure 3 shows the MAX1542/MAX1543 functional diagram.

### Main Step-Up Converter

The MAX1542/MAX1543 main step-up converter switches at 1.2MHz or 640kHz (MAX1543 only) (see the Oscillator Frequency (FREQ) section). The devices employ a current-mode, fixed-frequency, pulse-width modulation (PWM) architecture to maximize loop bandwidth providing fast transient response to pulsed loads found in source drivers for TFT LCD panels. The highswitching frequency also allows the use of low-profile inductors and capacitors to minimize the thickness of LCD panel designs. The integrated high-efficiency MOSFET and the IC's built-in digital soft-start function reduce the number of external components required while controlling inrush current. The output voltage of the main step-up converter ( $V_{\text{MAIN}}$ ) can be set from  $V_{\text{IN}}$ to 13V with an external resistive voltage-divider at FB.



### **Table 1. Component List**



#### **Table 2. Component Suppliers**



The regulator controls the output voltage and the power delivered to the outputs by modulating the duty cycle (D) of the power MOSFET in each switching cycle. The duty cycle of the MOSFET is approximated by:

$$
D \approx \frac{V_{MAIN} - V_{IN}}{V_{MAIN}}
$$

The device regulates the output voltage through a combination of an error amplifier, two comparators, and several signal generators (Figure 3). The error amplifier compares the signal at FB to 1.24V and varies the COMP output. The voltage at COMP determines the current trip point each time the internal MOSFET turns on. As the load varies, the error amplifier sources or sinks current to the COMP output accordingly to produce the inductor peak current necessary to service the load. To maintain stability at high duty cycles, a slope compensation signal is summed with the currentsense signal.

#### Operational Amplifiers

The MAX1542/MAX1543 include two operational amplifiers that are typically used to drive the LCD backplane VCOM and/or the gamma correction divider string. The operational amplifiers feature ±150mA output short-circuit current, 7.5V/µs slew rate, and 12MHz bandwidth. The rail-to-rail inputs and outputs maximize flexibility.

### **MAXM**

#### **Short-Circuit Current Limit**

The MAX1542/MAX1543 operational amplifiers limit short-circuit current to  $\pm 150$ mA if the output is directly shorted to SUP or AGND. In such a condition, the junction temperature of the IC rises until it reaches the thermal shutdown threshold, typically +160°C. Once it reaches this threshold, the IC shuts down and remains inactive until IN falls below VUVLO.

#### **Driving Pure Capacitive Loads**

The operational amplifiers are typically used to drive the LCD backplane (VCOM) or the gamma correction divider string. The LCD backplane consists of a distributed series capacitance and resistance, a load easily driven by the operational amplifiers. However, if the operational amplifiers are used in an application with a pure capacitive load, steps must be taken to ensure stable operation.

As the operational amplifier's capacitive load increases, the amplifier bandwidth decreases and gain peaking increases. A small 5Ω to 50Ω resistance placed between OUT\_ and the capacitive load reduces peaking but reduces the amplifier gain. An alternative method of reducing peaking is the use of a snubber circuit. A  $150\Omega$ and 10nF (typ) shunt load, or snubber, does not continuously load the output or reduce amplifier gain.





Figure 1. MAX1542 Typical Application Circuit

#### Delay Control Circuit

A capacitor from DEL to AGND selects the switch control block supply startup delay. After the input voltage exceeds  $V_{UV}$   $\cap$ , a 5µA current source charges C<sub>DFL</sub>. Once the capacitor voltage exceeds the turn-on threshold (1.24V) COM can be connected to SRC, depending on the state of CTL. Before startup and when IN is less than VUVLO, DEL is internally connected to AGND to discharge CDEL. Select CDEL using the following equation:

$$
C_{DEL} = (DELAY TIME) \times \frac{5\mu A}{1.24V}
$$

#### **MAX1542 Control Block Switch**

The switch control input (CTL) is not activated until VDEL exceeds the turn-on voltage (1.24V) and the input voltage (VIN) exceeds VUVLO (2.5V). Once activated, CTL controls the P-channel MOSFET, between COM and SRC. A high at CTL turns on Q1 between SRC and COM, and a low at CTL turns Q1 off (Figure 4).

#### **MAX1543 Control Block Switch**

The switch control input (CTL) is not activated until the input voltage  $(V_{IN})$  exceeds  $V_{UVLO}$  (2.5V) and  $V_{DEL}$ exceeds the turn-on voltage (1.24V). During UVLO or when DEL is below the turn-on threshold, COM is pulled low to PGND through Q3 and a 1kΩ resistance. Once activated, CTL controls the COM MOSFETs, switching COM between SRC and DRN. A high at CTL turns on Q1 and disables Q2. A low at CTL turns on Q2 and turns off Q1 (Figure 4).

#### Undervoltage Lockout (UVLO)

The UVLO comparator of the MAX1542/MAX1543 compares the input voltage at IN with the UVLO threshold



Figure 2. MAX1543 Typical Application Circuit

(2.5V rising, 2.35V falling, typ) to ensure that the input voltage is high enough for reliable operation. The 150mV (typ) hysteresis prevents supply transients from causing a restart. Once the input voltage exceeds the UVLO threshold, startup begins. When the input voltage falls below the UVLO threshold, the controller turns off the N-channel MOSFET, the switch control block turns off Q1, and the operational amplifier outputs float. For the MAX1543, the switch control block also turns off Q2 and turns on Q3 when the input voltage falls below the UVLO threshold (Figure 4).

#### Oscillator Frequency (FREQ)

The MAX1542 internal oscillator is preset to 1.2MHz. The internal oscillator frequency is pin programmable for the MAX1543. Connect FREQ to ground or leave it unconnected for 640kHz operation and connect it to V<sub>IN</sub> for 1.2MHz operation. FREQ has a 5µA (typ) pulldown current.

#### Fault Protection

MAX1542/MAX1543

**MAX1542/MAX1543** 

Once the soft-start routine is complete, if the output of the main regulator is below the fault detection threshold, the MAX1542/MAX1543 activate the fault timer. If the fault condition continuously exists throughout the fault timer duration, the MAX1542/MAX1543 set the fault latch, which shuts down the device. After removing the fault condition, cycle the input voltage (IN) below VUVLO to clear the fault latch and reactivate the device.

#### Digital Soft-Start

The MAX1542/MAX1543 digital soft-start period duration is 14ms (typ). During this time, the MAX1542/ MAX1543 directly limit the peak inductor current, allowing from zero up to the full current-limit value in eight equal current steps (ILIM/8). The maximum load current is available after output voltage reaches the full regulation threshold (which terminates soft-start), or after the soft-start timer expires.



**\_ 13**





Figure 3. Functional Diagram

#### Thermal-Overload Protection

Thermal-overload protection prevents excessive power dissipation from overheating the MAX1542/MAX1543. When the junction temperature exceeds  $T_J = +160^{\circ}C$ , a thermal sensor immediately activates the fault protection, which shuts down the device, allowing the IC to cool. The input voltage must fall (below  $V_{U}$ <sub>VLO</sub>) to clear the fault latch and reactivate the controller.

Thermal-overload protection protects the controller in the event of fault conditions. For continuous operation, do not exceed the absolute maximum junction-temperature rating of  $T_J = +150^{\circ}C$ .

### Applications Information

#### Inductor Selection

The primary considerations in inductor selection are inductor physical shape, circuit efficiency, and cost. The factors that determine the inductance value are input voltage, output voltage, switching frequency, and maximum output current. Final inductor selection includes ensuring the chosen inductor meets the application's peak current and RMS current requirements.

Very high inductance values minimize the current ripple and therefore reduce the peak current, which decreases core losses in the inductor and I2R losses in the circuit's entire power path. However, large inductance



Figure 4. Switch Control

values also require more energy storage and more turns of wire, which increase physical size and can increase I2R losses in the inductor. Low inductance values decrease the physical size but increase the current ripple and peak current. Finding the best inductor involves choosing the best compromise between circuit efficiency, inductor size, and cost.

The equations used here include a constant, LIR, which is the ratio of the inductor peak-to-peak ripple current to the average DC inductor current at the full output current. The best trade-off between inductor size and circuit efficiency for step-up converters generally has an LIR between 0.3 and 0.5. However, depending on the AC characteristics of the inductor core material and ratio of inductor resistance to other power path resistances, the best LIR can shift up or down. If the inductor resistance is relatively high, more ripple can be accepted to reduce the number of turns required and increase the wire diameter. If the inductor resistance is relatively low, increasing inductance to lower the peak current can decrease losses throughout the power path. If extremely thin, high-resistance inductors are used, as is common for LCD panel applications, the best LIR can increase to between 0.5 and 1.0.

Once a physical inductor is chosen, higher and lower values of that inductor should be evaluated for efficiency improvements in typical operating regions.

Calculate the approximate inductor value using the typical input voltage  $(V_{\text{IN}})$ , the maximum output current  $(N_{\text{MAIN}(MAX)})$ , the expected efficiency  $(\eta_{\text{TVP}})$  taken from an appropriate curve in the Typical Operating Characteristics, and an estimate for LIR based on the above paragraphs:

$$
L \cong V_{IN}^2 \times \eta_{TYP} \times (V_{MAIN} - V_{IN})/
$$
  
(V<sub>MAIN</sub><sup>2</sup> x LIR x I<sub>MAIN(MAX)</sub> x f<sub>OSC</sub>)

Choose an available inductor value from an appropriate inductor family. Calculate the maximum DC input current at the minimum input voltage VIN(MIN) using conservation of energy and the expected efficiency at that



operating point  $(\eta_{MIN})$  taken from an appropriate curve in the Typical Operating Characteristics:

 $I_{IN(DC,MAX)} = I_{MAN(MAX)} \times V_{MAIN} / (V_{IN(MIN)} \times \eta_{MIN})$ 

Calculate the ripple current at that operating point and the peak current required for the inductor:

 $I$ RIPPLE = VIN(MIN)  $\times$  (VMAIN -VIN(MIN)) / (L  $\times$  fosc  $\times$ VMAIN)

 $IPEAK = IIN(DC, MAX) + (IRIPPLE) / 2$ 

The inductor's saturation current rating and the MAX1542/MAX1543s' LX current limit (ILIM) should exceed IPEAK and the inductor's DC current rating should exceed  $I_{IN(DC,MAX)}$ . For reasonable efficiency, choose an inductor with less than 0.5Ω series resistance.

Considering the Typical Application Circuits, the maximum load current (IMAIN(MAX)) is 200mA with an 8V output and a typical input voltage of 3.3V.

Choosing an LIR of 0.6 and estimating efficiency of 85% at this operating point:

 $L = (3.3V)^2 \times 0.85 \times (8V - 3.3V) / ((8V)^2 \times 0.6 \times 0.2A \times$  $1.2$ MHz) =  $4.7$ µH

Using the circuit's minimum input voltage (2.7V) and estimating efficiency of 80% at that operating point,

 $I_{IN(DC,MAX)} = (0.2A \times 8V / (2.7V \times 0.8)) = 741mA$ 

The ripple current and the peak current are:

$$
I_{RIPPLE} = 2.7V \times (8V - 2.7V) / (4.7\mu H \times 1.2MHz \times 8V)
$$
  
= 317mA

 $IPFAK = 741mA + (317mA / 2) = 900mA$ 

#### Output Capacitor Selection

The total output voltage ripple has two components: the capacitive ripple caused by the charging and discharging of the output capacitance, and the ohmic ripple due to the capacitor's equivalent series resistance (ESR):

$$
V_{RIPPLE} = V_{RIPPLE(ESR)} + V_{RIPPLE(C)}
$$

$$
V_{RIPPLE(ESR)} \cong I_{PEAK} \times R_{ESR(COUT)}
$$
, and

$$
V_{RIPPLE(C)} \cong \frac{I_{MAIN}}{C_{OUT}} \left( \frac{V_{MAIN} - V_{IN}}{V_{MAIN} \times f_{OSC}} \right)
$$

where IPEAK is the peak inductor current (see the Inductor Selection section). For ceramic capacitors, the output voltage ripple is typically dominated by VRIP- $PIF(C)$ . The voltage rating and temperature characteristics of the output capacitor must also be considered.

#### Input Capacitor Selection

The input capacitor  $(C_{1N})$  reduces the current peaks drawn from the input supply and reduces noise injection into the device. A 10µF ceramic capacitor is used in the Typical Application Circuits (Figures 1 and 2) because of the high source impedance seen in typical lab setups. Actual applications usually have much lower source impedance since the step-up regulator often runs directly from the output of another regulated supply. Typically, C<sub>IN</sub> can be reduced below the values used in the Typical Application Circuits. Ensure a lownoise supply at IN by using adequate CIN.

#### Output Voltage

The MAX1542/MAX1543 operate with an adjustable output from V<sub>IN</sub> to 13V. Connect a resistive voltage-divider to FB (Typical Application Circuits) from the output (VMAIN) to AGND. Select the resistor values as follows:

$$
R_1 = R_2 \left( \frac{V_{MAIN}}{V_{FB}} - 1 \right)
$$

where V<sub>FB</sub>, the step-up converter feedback set point, is 1.24V. Since the input bias current into FB is typically zero,  $R_2$  can have a value up to 100k $\Omega$  without sacrificing accuracy, although lower values provide better noise immunity. Connect the resistor-divider as close to the IC as possible.

#### Loop Compensation

Choose RCOMP to set the high-frequency integrator gain for fast transient response. Choose CCOMP to set the integrator zero to maintain loop stability.

For low-ESR output capacitors, use the following equations to obtain stable performance and good transient response:

$$
R_{COMP} \cong \frac{500 \times V_{IN} \times V_{OUT} \times C_{OUT}}{L \times I_{MAIN(MAX)}}
$$

$$
C_{COMP} \cong \frac{V_{OUT} \times C_{OUT}}{10 \times I_{MAIN(MAX)} \times R_{COMP}}
$$

To further optimize transient response, vary RCOMP in 20% steps and C<sub>COMP</sub> in 50% steps while observing transient response waveforms.

#### Charge Pumps

**MAXM** 

#### **Selecting the Number of Charge-Pump Stages**

For highest efficiency, always choose the lowest number of charge-pump stages that meet the output requirements. Figures 5 and 6 show the positive and

**MAX1542/MAX1543** 



Figure 5. Positive Charge-Pump Output Voltage vs. VMAIN

negative charge-pump output voltages for a given VMAIN for one-, two-, and three-stage charge pumps, based on the following equations:

$$
G\_ON = V_{MAN} + n(V_{MAIN} - V_D)
$$

$$
G\_OFF = -n(V_{MAIN} - V_D)
$$

where G ON is the positive charge-pump output voltage, G OFF is the negative charge-pump output voltage, n is the number of charge-pump stages, and  $V_D$  is the voltage drop across each diode.

 $V<sub>D</sub>$  is the forward voltage drop of the charge-pump diodes.

#### **Flying Capacitors**

Increasing the flying capacitor (C3, C4, and C5) value increases the output current capability. Increasing the capacitance indefinitely has a negligible effect on output current capability because the internal switch resistance and the diode impedance limit the source impedance. A 0.1µF ceramic capacitor works well in most low-current applications. The flying capacitor's voltage rating must exceed the following:

#### $V_{CX}$  > n  $\times$   $V_{MAIN}$

Where n is the stage number in which the flying capacitor appears, and V<sub>MAIN</sub> is the main output voltage. For example, the two-stage positive charge pump in the Typical Application Circuits (Figures 1 and 2) where VMAIN = 8V contains two flying capacitors. The flying capacitor in the first stage (C5) requires a voltage rat-



Figure 6. Negative Charge-Pump Output Voltage vs. VMAIN

ing greater than 8V. The flying capacitor in the second stage (C4) requires a voltage rating greater than 16V.

#### **Charge-Pump Output Capacitor**

Increasing the output capacitance or decreasing the ESR reduces the output ripple voltage and the peak-topeak transient voltage. With ceramic capacitors, the output voltage ripple is dominated by the capacitance value. Use the following equation to approximate the required capacitor value:

$$
C_{\text{OUT}} \ge \frac{I_{\text{LOAD}}}{2 \times F_{\text{OSC}} \times V_{\text{RIPPLE}}}
$$

where VRIPPLE is the acceptable peak-to-peak outputvoltage ripple.

#### **Charge-Pump Rectifier Diodes**

To maximize the available output voltage, use Schottky diodes with a current rating equal to or greater than two times the average charge-pump input current. If the loaded charge-pump output voltage is greater than required, some or all of the Schottky diodes can be replaced with low-cost silicon switching diodes with an equivalent current rating. The charge-pump input current is:

$$
I_{CP\_IN} = I_{CP\_OUT} \times n
$$

where n is the number of charge-pump stages.

### **MAXM**

#### Power Dissipation

The MAX1542/MAX1543s' maximum power dissipation depends on the thermal resistance from the IC die to the ambient environment and the ambient temperature. The thermal resistance depends on the IC package, PC board copper area, other thermal mass, and airflow. The MAX1542/MAX1543, with their exposed backside pad soldered to 1in2 of PC board copper, can dissipate about 1.7W into +70°C still air. More PC board copper, cooler ambient air, and more airflow increase the possible dissipation while less copper or warmer air decreases the IC's dissipation capability. The major components of power dissipation are the power dissipated in the step-up converter and the power dissipated by the operational amplifiers.

#### **Step-Up Converter**

The largest portions of power dissipation in the step-up converter are the internal MOSFET, inductor, and the output diode. If the step-up converter has 90% efficiency, about 3% to 5% of the power is lost in the internal MOSFET, about 3% to 4% in the inductor, and about 1% in the output diode. The rest of the 1% to 3% is distributed among the input and output capacitors and the PC board traces. If the input power is about 3W, the power lost in the internal MOSFET is about 90mW to 150mW.

#### **Operational Amplifiers**

The power dissipated in the operational amplifiers depends on their output current, the output voltage, and the supply voltage:

$$
PD_{\text{SOURCE}} = I_{\text{OUT\_ (SOURCE)}} \times (V_{\text{SUP}} - V_{\text{OUT}})
$$
  
\n
$$
PD_{\text{SINK}} = I_{\text{OUT\_(SINK)}} \times V_{\text{OUT\_}}
$$

where  $I_{\text{OUT}}$  (SOURCE) is the output current sourced by the operational amplifier, and  $I_{\text{OUT}}$  (SINK) is the output current that the operational amplifier sinks.

In a typical case where the supply voltage is 8V and the output voltage is 4V with an output source current of 30mA, the power dissipated is 120mW.

#### Layout Procedure

Careful PC board layout and routing are required for high-frequency switching power supplies to achieve good regulation, high efficiency, and stability. Use the following guidelines for good PC board layout:

1) Place the input capacitors close enough to the IC to provide adequate bypassing (within 1.5cm). Connect the input capacitors to IN with a wide trace.

Minimize the area of high-current loops by placing the inductor, output diode, and output capacitors near the input capacitors and near LX and PGND. The high-current input loop goes from the positive terminal of the input capacitor to the inductor, to the IC's LX pin, out PGND, and to the input capacitor negative terminal. The high-current output loop is from the positive terminal of the input capacitor to the inductor, to the catch diode (D1), to the positive terminal of the output capacitors, reconnecting between the output capacitor and input capacitor ground terminals. Connect these loop components together with short, wide connections. Avoid using vias in the high-current paths. If vias are unavoidable, use many vias in parallel to reduce resistance and inductance.

2) Create a power ground island (PGND) consisting of the input and output capacitor grounds, PGND pin, and the SRC bypass capacitor and other chargepump components. Connect all of these together with short, wide traces or a small ground plane. Maximizing the width of the power ground traces improves efficiency and reduces output voltage ripple and noise spikes.

Create an analog ground island (AGND) consisting of the AGND pin, FB divider, the operation amplifier dividers, the COMP and DEL capacitor ground connections, and the device's exposed backside pad.

Connect the AGND and PGND islands by connecting the PGND pin directly to the exposed backside pad. Make no other connections between these separate ground planes.

- 3) Place the feedback voltage-divider resistors close to FB. The divider's center trace should be kept short. Placing the resistors far away causes their FB traces to become antennas that can pick up switching noise. Avoid running the feedback trace near LX or the switching nodes in the charge pumps.
- 4) Minimize the length and maximize the width of the traces between the output capacitors and the load for best transient response.
- 5) Minimize the size of the LX node while keeping it wide and short. Keep the LX node away from the feedback node (FB) and analog ground. Use DC traces as shields if necessary.

Refer to the MAX1543 Evaluation Kit for an example of proper board layout.





TRANSISTOR COUNT: 2508 PROCESS: BiCMOS

### Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



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