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Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

General Description

The MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T are dual-output, step-down, constant on-time Quick-PWM™ controllers for VR12/IMVP-7 CPU core supplies. The controllers consist of two high-current switching power supplies for CPU and GFX cores. The CPU regulator (regulator A) is a three-phase constant on-time architecture. The GFX regulator (regulator B) is also constant on-time architecture. The MAX17411 supports 2-phase operation and the MAX17511/MAX17511C/MAX17511N/MAX17511T support 1-phase operation. The MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T include two internal drivers on regulator A and one internal driver on regulator B. External drivers such as the MAX17491 enable the additional phases.

Both regulator A and regulator B include output voltage sensing and accurate load-line gain. Switching frequencies are programmable from 200kHz to 600kHz per phase. Output overvoltage protection (OVP, MAX17411/MAX17511/MAX17511C/MAX17511N), undervoltage protection (UVP), and thermal protection ensure effective and reliable operation. When any of these protection features detect a fault, the controller shuts down both outputs.

The multiphase regulators include transient-phase overlap and active overshoot suppression, which speed up the response time and reduce the total output capacitance. The CPU and GFX outputs are controlled independently by writing the appropriate data into a function-mapped register file. VID code transitions and soft-start are enabled with a precision slew-rate control circuit. The SVID interface also allows each regulator to be individually set into a low-power, single-phase, pulse-skipping state to optimize efficiency. The MAX17411 is available in a 48-pin, 6mm x 6mm, TQFN package. The MAX17511/MAX17511C/MAX17511N/MAX17511T are available in a 40-pin, 5mm x 5mm, TQFN lead-free package.

Applications

VR12/IMVP-7 CPU Core Power Supplies
Notebooks/Desktops/Servers

Features

- ◆ Intel VR12/IMVP-7-Compliant Serial Interface
- ◆ 3-/2-/1-Phase Quick-PWM CPU Core Regulator
 - Two Internal Drivers and One External Driver
 - Transient-Phase Overlap Mode
 - Dynamic Phase Selection
- ◆ 2-/1-Phase Quick-PWM GFX Regulator
 - One Internal and One External Driver
- ◆ Active Overshoot Suppression
- ◆ 8-Bit VR12/IMVP-7 DAC
- ◆ ±0.5% VOUT Accuracy Over Line, Load, and Temperature
- ◆ Active Voltage Positioning with Programmable Gain
- ◆ Accurate Lossless Current Balance
- ◆ Accurate Droop and Current Limit
- ◆ Remote Output and Ground Sense
- ◆ Power-Good Window Comparators (POKA and POKB)
- ◆ 4.5V to 24V Battery-Input Voltage Range
- ◆ Programmable 200kHz to 600kHz Switching Frequency
- ◆ External Thermal-Fault Detection Output (VR_HOT#)
- ◆ Overvoltage (MAX17411/MAX17511/MAX17511C/MAX17511N), Undervoltage, and Thermal-Fault Protection
- ◆ Slew-Rate Controlled Soft-Start
- ◆ Passive Soft-Shutdown (20Ω Discharge Switches)
- ◆ Integrated Boost Switches
- ◆ Low-Profile, 48-Lead/40-Lead TQFN Packages

Quick PWM is a trademark of Maxim Integrated Products, Inc.

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	FEATURE
MAX17411GTM+	-40°C to +105°C	48 TQFN-EP*	3-/2-/1-Phase + 2-/1-Phase
MAX17511GTL+	-40°C to +105°C	40 TQFN-EP*	3-/2-/1-Phase + 1-Phase

Ordering Information continued on last page.

+Denotes a lead(Pb)-free/RoHS-compliant package.

*EP = Exposed pad.

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ABSOLUTE MAXIMUM RATINGS

VCC, VDDA, VDDB to GND (AGND).....	-0.3V to +6V	BSTA_ to VDDA.....	-0.3V to +26V
VDIO, CLK, ALERT# to GND (AGND).....	-0.3V to +6V	BSTB to VDDB	-0.3V to +26V
CSPAIVE, CSPBAIVE, CSP_		LXA_ to BSTA_	-6V to +0.3V
CSN_ to GND (AGND)	-0.3V to +6V	LXB to BSTB.....	-6V to +0.3V
FBA, FBB to GND (AGND).....	-0.3V to (VCC + 0.3V)	LX_ to GND (AGND)	-6V to +26V
SR, IMAX_ to GND (AGND)	-0.3V to (VCC + 0.3V)	DHA_ to LXA_.....	-0.3V to (VBSTA_ + 0.3V)
POKA, POKB, EN to GND (AGND).....	-0.3V to +6V	DHB to LXB	-0.3V to (VBSTB + 0.3V)
VR_HOT# to GND (AGND).....	-0.3V to +6V	Continuous Power Dissipation (TA = +70°C)	
THERMA, THERMB to GND (AGND)	-0.3V to (VCC + 0.3V)	40-Pin TQFN (derate 35.7mW/°C above +70°C) ...	2857.1mW
GNDSA, GNDSB to GND (AGND)	-0.3V to +0.3V	48-Pin TQFN (derate 37mW/°C above +70°C)	2963mW
TON to GND	-0.3V to +26V	Operating Temperature Range	-40°C to +105°C
DRVPMMA to GND (AGND)	-0.3V to (VDDA + 0.3V)	Junction Temperature	+150°C
DRVPMWB to GND (AGND)	-0.3V to (VDDB + 0.3V)	Storage Temperature Range.....	-65°C to +165°C
DLA_ to GND (PGND).....	-0.3V to (VDDA + 0.3V)	Lead Temperature (soldering, 10s)	+300°C
DLB to GND (PGND).....	-0.3V to (VDDB + 0.3V)	Soldering Temperature (reflow)	+260°C

PACKAGE THERMAL CHARACTERISTICS (Note 1)

40 TQFN	Junction-to-Ambient Thermal Resistance (θ_{JA})	28°C/W	48 TQFN	Junction-to-Ambient Thermal Resistance (θ_{JA})	27°C/W
	Junction-to-Case Thermal Resistance (θ_{JC})	1.6°C/W		Junction-to-Case Thermal Resistance (θ_{JC})	1.3°C/W

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maxim-ic.com/thermal-tutorial.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(Circuits of Figures 1 and 2. VIN = 10V, VCC = VDDA = VDDB = 5V, EN = VCC, VGND_S = 0V, VFB₋ = VCSP_AVE = VCSP₋ = VCSN₋ = 1V; [SerialVID = 1.00, FPWM MODE]; TA = 0°C to +85°C, unless otherwise noted. Typical values are at TA = +25°C. All devices 100% tested at TA = +25°C. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
PWM CONTROLLER							
Input Voltage Range		VCC, VDDA, VDDB	4.5		5.5	V	
DC Output Voltage Accuracy		Measured at FB ₋ with respect to GNDS ₋ ; includes load regulation error (Note 2)	DAC codes from 1.000V to 1.520V	-0.5		+0.5	%
			DAC codes from 0.800V to 0.995V	-5		+5	mV
			DAC codes from 0.250V to 0.795V	-8		+8	
Line Regulation Error		VCC = 4.5V to 5.5V, VIN = 4.5V to 24V		0.1		mV	
VSETTLED Bit Accuracy		Upward transitions	-15	-10	-5	mV	
		Downward transitions	5	10	15		
GNDS ₋ Input Range			-200		+200	mV	
GNDS ₋ Gain	AGNDS	$\Delta V_{OUT}/\Delta V_{GNDS_}$	0.97	1.00	1.03	V/V	
GNDS ₋ Input Bias Current		TA = +25°C	-0.5		+0.5	µA	
TON Shutdown Current		EN = GND, VIN = 24V, VCC = 0V, TA = +25°C		0.01	0.1	µA	
Boot Voltage	VBOOT	MAX17511N only, Reg A and Reg B	1.094	1.100	1.106	V	
		MAX17511C only, Reg B only	0.895	0.900	0.905		

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GND_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = 0^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All devices 100% tested at $T_A = +25^{\circ}C$. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DHA_ On-Time (Note 3)	t _{ONA}	Measured at DHA_ (600kHz - 10%), R _{TON} = 96.7k Ω (MAX17411 only), R _{TON} = 48.35k Ω (MAX17511/MAX17511C/ MAX17511N/MAX17511T)	157	185	213	ns
		Measured at DHA_, $V_{IN} = 12V$ (300kHz - 10%), R _{TON} = 200k Ω (MAX17411 only), R _{TON} = 100k Ω (MAX17511/MAX17511C/MAX17511N/ MAX17511T)	276	307	338	
		Measured at DHA_ (200kHz - 10%), R _{TON} = 303.3k Ω (MAX17411 only), R _{TON} = 151.65k Ω (MAX17511/MAX17511C/ MAX17511N/MAX17511T)	470	554	638	
DHB On-Time (Note 3)	t _{ONB}	Measured at DHB (600kHz + 10%), R _{TON} = 96.7k Ω (MAX17411 only), R _{TON} = 48.35k Ω (MAX17511/MAX17511C/ MAX17511N/MAX17511T)	128	151	174	ns
		Measured at DHB, $V_{IN} = 12V$ (300kHz + 10%), R _{TON} = 200k Ω (MAX17411 only), R _{TON} = 100k Ω (MAX17511/MAX17511C/MAX17511N/ MAX17511T)	226	251	277	
		Measured at DHB (200kHz + 10%), R _{TON} = 303.3k Ω (MAX17411 only), R _{TON} = 151.65k Ω (MAX17511/MAX17511C/ MAX17511N/MAX17511T)	385	453	521	
Minimum Off-Time (Note 3)	t _{OFF(MIN)}	Measured at DH_	150	200	250	ns
Minimum DRVPWM_ Pulse Width				40		ns
BIAS CURRENTS						
Quiescent Supply Current (V _{CC})	I _{BIAS}	Measured at V _{CC} , SKIP mode, FB_ forced above the regulation point		5	10	mA
Quiescent Supply Current (V _{DD_})	I _{DRV}	$T_A = +25^{\circ}C$, measured at V _{DD_} , FPWM mode, FB_ forced above the regulation point		0.02	1	μA
Shutdown Supply Current (V _{CC})		Measured at V _{CC} , EN = GND		16	30	μA
Shutdown Supply Current (V _{DD_})		$T_A = +25^{\circ}C$, measured at V _{DD} , EN = GND		0.01	1	μA
SLEW-RATE CONTROL						
Slew-Rate Accuracy		V _{SR} = 0V or V _{SR} = 5V	SetVID - fast slew rate = 10mV/ μs (min)	10		mV/ μs
			SetVID - slow slew rate = 2.5mV/ μs (min)	2.5		
		V _{SR} = 3V or V _{SR} = 1.5V	SetVID - fast slew rate = 20mV/ μs (min)	20		
			SetVID - slow slew rate = 5mV/ μs (min)	5		

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuit of Figure 1. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = 0^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All devices 100% tested at $T_A = +25^{\circ}C$. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Soft-Start Slew Rate		Non-zero V_{BOOT}	2.5			mV/ μ s
Discharge Switch Resistance		CSNA, CSNB		20		Ω
SR Four-Level Logic Thresholds		Low			0.4	V
		Mid-low	1.2		1.8	
		Mid-high	2.2		$V_{CC} - 1.2V$	
		High	$V_{CC} - 0.4V$			
FAULT PROTECTION						
Upper POK_ (MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T) and Output Overvoltage Protection Trip Threshold(MAX17411/MAX17511/MAX17511C/MAX17511N)	V_{OVP}	SKIP mode after output reaches the regulation voltage or PWM mode; measured at FB_{-} with respect to the voltage target set by the VID code (see Table 3)	200	250	300	mV
		Soft-start, SKIP mode, and output has not reached the regulation voltage; measured at FB_{-}	1.72	1.77	1.82	V
		Minimum OVP threshold, measured at FB_{-}		0.8		
Upper POK_ and Output Overvoltage Propagation Delay	t_{OVP}	FB_{-} forced 25mV above trip threshold (MAX17411/MAX17511/MAX17511C/MAX17511N)		5		μ s
Lower POK_ and Output Undervoltage Protection Trip Threshold	V_{UVP}	Measured at FB_{-} with respect to unloaded output voltage	-300	-250	-200	mV
Lower POK_ Propagation Delay		FB_{-} forced 25mV below trip threshold		5		μ s
Output Undervoltage Propagation Delay	t_{UVP}	FB_{-} forced 25mV below trip threshold	100	200	350	μ s
POK_ Output Low Voltage		$I_{SINK} = 4mA$			0.3	V
POK_ Leakage Current		High state, POK_ forced to 5V, $T_A = +25^{\circ}C$			1	μ A
POK_ Startup Delay and Transitions Blanking Time	$t_{POK_}$	Measured from the time when FB_{-} reaches the target voltage		20		μ s
V_{CC} Undervoltage-Lockout Threshold	V_{UVLO}	Rising edge, 50mV typical hysteresis, controller disabled below this level	4.05	4.25	4.45	V

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = 0^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All devices 100% tested at $T_A = +25^{\circ}C$. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
THERMAL PROTECTION							
VR_HOT# Trip Threshold		Measured at THERM_ with respect to VCC falling edge; specify as % error for all TEMP MAX DAC code settings, typical hysteresis = 100mV	49.5		50.5	%	
Thermal Zone Registers Trip Points		Thermal zone comparator trip points, measured with respect to VCC; voltage threshold corresponding to $T_{MAX} \times (1 - N\%)$, N = 0, 3, 6, 9, 12, 15, 18, 25	49 + 24 x N/31	50 + 24 x N/31	51 + 24 x N/31	%	
THERM_ Input Leakage	ITHRM	$V_{THERM_} = 2.5V$, $T_A = +25^{\circ}C$	-100		+100	nA	
VR_HOT# Leakage Current		High-Z state ($THERM_ > 0.505 \times V_{CC}$), VR_HOT# forced to 5V, $T_A = +25^{\circ}C$			1	μA	
Internal Thermal Fault Shutdown Threshold	TTSHDN	Typical hysteresis = $15^{\circ}C$		160		$^{\circ}C$	
VALLEY CURRENT LIMIT AND DROOP							
Valley Current-Limit Threshold Voltage (Positive)	VILIMA	$V_{CSP_} - V_{CSN_}$, $V_{SR} = 0V$, $V_{SR} = 1.5V$, or one-phase operation	$R_{SENSE} = 0.65m\Omega$, $I_{MAXA} = 39A$	22.5	25.5	28.5	mV
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXA} = 36A$	21.5	24.5	27.5	
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXA} = 30A$	17.0	20.0	23.0	
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXA} = 26A$	15.0	18.0	21.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXA} = 39A$	27.0	30.0	33.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXA} = 36A$	25.0	28.0	31.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXA} = 30A$	20.0	23.0	26.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXA} = 26A$	17.0	20.0	23.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXA} = 39A$	30.0	33.0	36.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXA} = 36A$	28.0	31.0	34.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXA} = 30A$	22.5	25.5	28.5	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXA} = 26A$	20.0	23.0	26.0	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXA} = 39A$	33.5	36.5	39.5	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXA} = 36A$	31.0	34.0	37.0	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXA} = 30A$	25.0	28.0	31.0	
$R_{SENSE} = 0.95m\Omega$, $I_{MAXA} = 26A$	21.5	24.5	27.5				

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = 0^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All devices 100% tested at $T_A = +25^{\circ}C$. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Valley Current-Limit Threshold Voltage (Positive)	V _{ILIMA}	V _{CSP_} - V _{CSN_} , V _{SR} = 3V or V _{SR} = 5V, exclude one-phase operaton	R _{SENSE} = 0.65mΩ, I _{MAXA} = 39A	29.0	33.0	37.0	mV
			R _{SENSE} = 0.65mΩ, I _{MAXA} = 36A	28.0	32.0	36.0	
			R _{SENSE} = 0.65mΩ, I _{MAXA} = 30A	22.0	26.0	30.0	
			R _{SENSE} = 0.65mΩ, I _{MAXA} = 26A	19.5	23.5	27.5	
			R _{SENSE} = 0.75mΩ, I _{MAXA} = 39A	35.0	39.0	43.0	
			R _{SENSE} = 0.75mΩ, I _{MAXA} = 36A	32.5	36.5	40.5	
			R _{SENSE} = 0.75mΩ, I _{MAXA} = 30A	26.0	29.9	33.8	
			R _{SENSE} = 0.75mΩ, I _{MAXA} = 26A	22.0	26.0	30.0	
			R _{SENSE} = 0.85mΩ, I _{MAXA} = 39A	39.0	43.0	47.0	
			R _{SENSE} = 0.85mΩ, I _{MAXA} = 36A	36.5	40.5	44.5	
			R _{SENSE} = 0.85mΩ, I _{MAXA} = 30A	29.0	33.0	37.0	
			R _{SENSE} = 0.85mΩ, I _{MAXA} = 26A	26.0	30.0	34.0	
			R _{SENSE} = 0.95mΩ, I _{MAXA} = 39A	43.5	47.5	51.5	
			R _{SENSE} = 0.95mΩ, I _{MAXA} = 36A	40.0	44.0	48.0	
R _{SENSE} = 0.95mΩ, I _{MAXA} = 30A	32.5	36.5	40.5				
R _{SENSE} = 0.95mΩ, I _{MAXA} = 26A	28.0	32.0	36.0				
Valley Current-Limit Threshold Voltage (Positive)	V _{ILIMB}	V _{CSP_} - V _{CSN_} , V _{SR} = 0V, V _{SR} = 1.5V, or one-phase operation	R _{SENSE} = 0.65mΩ, I _{MAXB} = 39A	22.5	25.5	28.5	mV
			R _{SENSE} = 0.65mΩ, I _{MAXB} = 36A	21.5	24.5	27.5	
			R _{SENSE} = 0.65mΩ, I _{MAXB} = 23A	13.0	16.0	19.0	
			R _{SENSE} = 0.65mΩ, I _{MAXB} = 20A	11.0	14.0	17.0	
			R _{SENSE} = 0.75mΩ, I _{MAXB} = 39A	27.0	30.0	33.0	
			R _{SENSE} = 0.75mΩ, I _{MAXB} = 36A	25.0	28.0	31.0	
			R _{SENSE} = 0.75mΩ, I _{MAXB} = 23A	15.0	18.0	21.0	
			R _{SENSE} = 0.75mΩ, I _{MAXB} = 20A	13.0	16.0	19.0	
			R _{SENSE} = 0.85mΩ, I _{MAXB} = 39A	30.0	33.0	36.0	
			R _{SENSE} = 0.85mΩ, I _{MAXB} = 36A	28.0	31.0	34.0	
			R _{SENSE} = 0.85mΩ, I _{MAXB} = 23A	17.0	20.0	23.0	
			R _{SENSE} = 0.85mΩ, I _{MAXB} = 20A	15.0	18.0	21.0	
			R _{SENSE} = 0.95mΩ, I _{MAXB} = 39A	33.5	36.5	39.5	
			R _{SENSE} = 0.95mΩ, I _{MAXB} = 36A	31.0	34.0	37.0	
R _{SENSE} = 0.95mΩ, I _{MAXB} = 23A	20.0	23.0	26.0				
R _{SENSE} = 0.95mΩ, I _{MAXB} = 20A	17.0	20.0	23.0				

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GND_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = 0^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All devices 100% tested at $T_A = +25^{\circ}C$. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Valley Current-Limit Threshold Voltage (Positive)	VILIMB	$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 39A$	29.0	33.0	37.0	mV
		$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 36A$	28.0	32.0	36.0	
		$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 23A$	17.0	21.0	25.0	
		$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 20A$	14.0	18.0	22.0	
		$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 39A$	35.0	39.0	43.0	
		$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 36A$	32.5	36.5	40.5	
		$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 23A$	19.5	23.5	27.5	
		$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 20A$	17.0	21.0	25.0	
		$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 39A$	39.0	43.0	47.0	
		$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 36A$	36.5	40.5	44.5	
		$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 23A$	22.0	26.0	30.0	
		$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 20A$	19.5	23.5	27.5	
		$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 39A$	43.5	47.5	51.5	
		$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 36A$	40.0	44.0	48.0	
$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 23A$	26.0	30.0	34.0			
$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 20A$	22.0	26.0	30.0			
Current-Limit Threshold Voltage (Zero Crossing)	VZERO	$V_{GND} - V_{LX_}$		1		mV
Current-Balance Offset Voltage			-1.5		+1.5	mV
CSPAAVE, CSPBAVE, CSP_ ₋ , Input Current		$T_A = +25^{\circ}C$	-0.12		+0.12	μA
CSN_ ₋ Pulldown Current			7		14	μA
Phase Disable Threshold		CSPB2, CSPB1, CSPA3, CSPA2, CSPA1	3	$V_{CC} - 1$	$V_{CC} - 0.4$	V
FB_ ₋ Droop Amplifier (GMD) Offset		$(V_{CSP_AVE} - V_{CSN_})$ at $I_{FB_} = 0mA$	-1.0		+1.0	mV
FB_ ₋ Droop Amplifier (GMD) Transconductance		$\Delta I_{FB_} / \Delta (V_{CSP_AVE} - V_{CSN_})$, $V_{CSP_AVE} - V_{CSN_} = -15mV$ to $+15mV$	591	600	609	μS

MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GND_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = 0^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All devices 100% tested at $T_A = +25^{\circ}C$. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
IMAX_LOGIC						
IMAX_Detection Thresholds		Threshold 0, fault			13.65 x $V_{CC}/50$	V
		Threshold 1, $R_{SENSE} = 0.65m\Omega$, $I_{MAX} = 39A$	14.20 x $V_{CC}/50$		14.65 x $V_{CC}/50$	
		Threshold 2, $R_{SENSE} = 0.65m\Omega$, $I_{MAX} = 36A$	15.20 x $V_{CC}/50$		15.65 x $V_{CC}/50$	
		Threshold 3, $R_{SENSE} = 0.65m\Omega$, $I_{MAXA/B} = 30A/23A$	16.20 x $V_{CC}/50$		16.65 x $V_{CC}/50$	
		Threshold 4, $R_{SENSE} = 0.65m\Omega$, $I_{MAXA/B} = 26A/20A$	17.20 x $V_{CC}/50$		17.65 x $V_{CC}/50$	
		Threshold 5, $R_{SENSE} = 0.75m\Omega$, $I_{MAX} = 39A$	18.20 x $V_{CC}/50$		18.65 x $V_{CC}/50$	
		Threshold 6, $R_{SENSE} = 0.75m\Omega$, $I_{MAX} = 36A$	19.20 x $V_{CC}/50$		19.65 x $V_{CC}/50$	
		Threshold 7, $R_{SENSE} = 0.75m\Omega$, $I_{MAX} = 30A/23A$	20.20 x $V_{CC}/50$		20.65 x $V_{CC}/50$	
		Threshold 8, $R_{SENSE} = 0.75m\Omega$, $I_{MAX} = 26A/20A$	21.20 x $V_{CC}/50$		21.65 x $V_{CC}/50$	
		Threshold 9, $R_{SENSE} = 0.85m\Omega$, $I_{MAX} = 39A$	22.20 x $V_{CC}/50$		22.65 x $V_{CC}/50$	
		Threshold 10, $R_{SENSE} = 0.85m\Omega$, $I_{MAX} = 36A$	23.20 x $V_{CC}/50$		23.65 x $V_{CC}/50$	
		Threshold 11, $R_{SENSE} = 0.85m\Omega$, $I_{MAXA/B} = 30A/23A$	24.20 x $V_{CC}/50$		24.65 x $V_{CC}/50$	
		Threshold 12, $R_{SENSE} = 0.85m\Omega$, $I_{MAXA/B} = 26A/20A$	25.20 x $V_{CC}/50$		25.65 x $V_{CC}/50$	
		Threshold 13, $R_{SENSE} = 0.95m\Omega$, $I_{MAX} = 39A$	26.20 x $V_{CC}/50$		26.65 x $V_{CC}/50$	
		Threshold 14, $R_{SENSE} = 0.95m\Omega$, $I_{MAX} = 36A$	27.20 x $V_{CC}/50$		27.65 x $V_{CC}/50$	
		Threshold 15, $R_{SENSE} = 0.95m\Omega$, $I_{MAXA/B} = 30A/23A$	28.20 x $V_{CC}/50$		28.65 x $V_{CC}/50$	
		Threshold 16, $R_{SENSE} = 0.95m\Omega$, $I_{MAXA/B} = 26A/20A$	29.20 x $V_{CC}/50$		29.65 x $V_{CC}/50$	
	Threshold 17, fault	30.20 x $V_{CC}/50$				

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GND S_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = 0^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All devices 100% tested at $T_A = +25^{\circ}C$. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
GATE DRIVERS						
DH_ Gate-Driver On-Resistance	RON(DH)	BST_ - LX_ forced to 5V	High state (pullup)	0.9	2.5	Ω
			Low state (pulldown)	0.7	2.0	
DL_ Gate-Driver On-Resistance	RON(DL)	High state (pullup)		0.7	2.0	Ω
		Low state (pulldown)		0.25	0.7	
Internal BST_ Switch On-Resistance	R _{BST}	BSTA1 to V _{DDA} , BSTA2 to V _{DDA} , BSTB to V _{DDB} , V _{DD_} = 5V		10	20	Ω
DH_ Gate-Driver Source Current	I _{DH(SRC)}	DH_ forced to 2.5V, BST_ - LX_ forced to 5V		2.2		A
DH_ Gate-Driver Sink Current	I _{DH(SINK)}	DH_ forced to 2.5V, BST_ - LX_ forced to 5V		2.7		A
DL_ Gate-Driver Source Current	I _{DL(SRC)}	DL_ forced to 2.5V		2.7		A
DL_ Gate-Driver Sink Current	I _{DL(SINK)}	DL_ forced to 2.5V		8		A
Driver Propagation Delay		DH_ low to DL_ high		30		ns
		DL_ low to DH_ high		30		
DL_ Transition Time		DL_ falling, C _{DL} = 3nF		20		ns
		DL_ rising, C _{DL} = 3nF		20		
DH_ Transition Time		DH_ falling, C _{DH} = 3nF		20		ns
		DH_ rising, C _{DH} = 3nF		20		
DRVWMA, DRVWMB Logic-High Voltage		I _{SOURCE} = 3mA		V _{DD_} - 0.4		V
DRVWMA, DRVWMB Logic-Low Voltage		I _{SINK} = 3mA			0.4	V
LOGIC AND I/O						
Enable Input High Voltage	V _{EN_IH}		0.67			V
Enable Input Low Voltage	V _{EN_IL}				0.33	V
Enable Input Current		T _A = +25°C	-1		+1	μ A
SERIALVID INTERFACE (per Intel SerialVID Specification—see the Detailed Description)						
SerialVID Input Low Voltage (CLK, VDIO)	V _{IL}		-0.1		+0.45	V
SerialVID Input High Voltage (CLK, VDIO)	V _{IH}		0.65		V _{TT} + 1V	V
SerialVID Output High Voltage (VDIO, ALERT#)	V _{OH}	Open-drain pullup to V _{TT}		V _{TT}		V
SerialVID Output Low Level (VDIO, ALERT#)	V _{OL}	Open-drain pullup to V _{TT} , R _{PU} = 50 Ω			0.36	V

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = 0^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All devices 100% tested at $T_A = +25^{\circ}C$. Limits over temperature guaranteed by design.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SerialVID Open-Drain Output On-Resistance (VDIO, ALERT#, VRHOT#)	RON	ISINK = 30mA	4		13	Ω
SerialVID Logic-Input Leakage Current (CLK, VDIO)		$T_A = +25^{\circ}C$	-1		+1	μA
ALERT# Deasserted Leakage Current		$T_A = +25^{\circ}C$, VALERT# = 3.3V			1	μA
SerialVID Logic Slew Rate (CLK, VDIO, ALERT#)			0.5		2.0	V/ns
SerialVID Input Capacitance	CPAD				4	pF
CLK Frequency	fCLK		13	25	33.3	MHz
CLK Absolute Min/Max Period		Specified as a percentage of fCLK	-5		+5	%
CLK High Time	tHIGH	Specified as a percentage of tCLK period	45			%
CLK Low Time	tLOW	Specified as a percentage of tCLK period	45			%
Rise Time	tRISE		0.25		2.5	ns
Fall Time	tFALL		0.25		2.5	ns
Duty Cycle			45		55	%
SerialVID Inactivity Timeout	tRSTNA		0.14		0.40	μs

ELECTRICAL CHARACTERISTICS

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = -40^{\circ}C$ to $+105^{\circ}C$, unless otherwise noted. Specifications to $-40^{\circ}C$ and $+105^{\circ}C$ are guaranteed by design, not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
PWM CONTROLLER						
Input Voltage Range		V_{CC} , V_{DDA} , V_{DDB}	4.5		5.5	V
DC Output Voltage Accuracy		Measured at FB_ with respect to GNDS_ ₋ ; includes load regulation error (Note 2)	DAC codes from 1.000V to 1.520V	-0.8	+0.8	%
			DAC codes from 0.800V to 0.995V	-8	+8	
			DAC codes from 0.250 to 0.795V	-8	+8	
VSETTLED BIT Accuracy		Upward transitions	-15		-5	mV
		Downward transitions	5		15	
GNDS_ Input Range			-200		+200	mV
GNDS_ Gain	AGNDS	$\Delta V_{OUT}/\Delta V_{GNDS_}$	0.97		1.03	V/V
Boot Voltage	VBOOT	MAX17511N only, Reg A and Reg B	1.091		1.109	V
		MAX17511C only, Reg B only	0.892		0.908	

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = -40^{\circ}C$ to $+105^{\circ}C$, unless otherwise noted. Specifications to $-40^{\circ}C$ and $+105^{\circ}C$ are guaranteed by design, not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DHA_ On-Time (Note 3)	t _{ONA}	Measured at DHA_ (600kHz - 10%), R _{TON} = 96.7k Ω (MAX17411 only), R _{TON} = 48.35k Ω (MAX17511/MAX17511C/MAX17511N/MAX17511T)	157		213	ns
		Measured at DHA_, $V_{IN} = 12V$ (300kHz - 10%), R _{TON} = 200k Ω (MAX17411 only), R _{TON} = 100k Ω (MAX17511/MAX17511C/MAX17511N/MAX17511T)	276		338	
		Measured at DHA_ (200kHz - 10%), R _{TON} = 303.3k Ω (MAX17411 only), R _{TON} = 151.65k Ω (MAX17511/MAX17511C/MAX17511N/MAX17511T)	470		638	
DHB On-Time (Note 3)	t _{ONB}	Measured at DHB (600kHz + 10%), R _{TON} = 96.7k Ω (MAX17411 only), R _{TON} = 48.35k Ω (MAX17511/MAX17511C/MAX17511N/MAX17511T)	128		174	ns
		Measured at DHB, $V_{IN} = 12V$ (300kHz + 10%), R _{TON} = 200k Ω (MAX17411 only), R _{TON} = 100k Ω (MAX17511/MAX17511C/MAX17511N/MAX17511T)	226		277	
		Measured at DHB (200kHz + 10%), R _{TON} = 303.3k Ω (MAX17411 only), R _{TON} = 151.65k Ω (MAX17511/MAX17511C/MAX17511N/MAX17511T)	385		521	
Minimum Off-Time (Note 3)	t _{OFF(MIN)}	Measured at DH_	150		250	ns
BIAS CURRENTS						
Quiescent Supply Current (V _{CC})	I _{BIAS}	Measured at V _{CC} , SKIP mode, FB_ forced above the regulation point			10	mA
Shutdown Supply Current (V _{CC})		Measured at V _{CC} , EN = GND			30	μ A
SLEW-RATE CONTROL						
Slew-Rate Accuracy		V _{SR} = 0V or V _{SR} = 5V	SetVID - fast slew rate = 10mV/ μ s (min)	10		mV/ μ s
			SetVID - slow slew rate = 2.5mV/ μ s (min)	2.5		
		V _{SR} = 3V or V _{SR} = 1.5V	SetVID - fast slew rate = 20mV/ μ s (min)	20		
			SetVID - slow slew rate = 5mV/ μ s (min)	5		
Soft-Start Slew Rate		Non-zero V _{BOOT}	2.5		mV/ μ s	
SR Four-Level Logic Thresholds		Low			0.4	V
		Mid-low		1.2	1.8	
		Mid-high		2.2	V _{CC} - 1.2V	
		High		V _{CC} - 0.4V		

MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = -40^{\circ}C$ to $+105^{\circ}C$, unless otherwise noted. Specifications to $-40^{\circ}C$ and $+105^{\circ}C$ are guaranteed by design, not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
FAULT PROTECTION							
Upper POK_ (MAX17411/ MAX17511/MAX17511N/ MAX17511T) and Output Overvoltage Protection Trip Threshold (MAX17411/ MAX17511/MAX17511C/ MAX17511N)	VOVP	SKIP mode after output reaches the regulation voltage or PWM mode; measured at FB_ with respect to the voltage target set by the VID code (see Table 3)	200		300	mV	
		Soft-start, SKIP mode, and output has not reached the regulation voltage, measured at FB_	1.72		1.82	V	
Lower POK_ and Output Undervoltage Protection Trip Threshold	VUVP	Measured at FB_ with respect to unloaded output voltage	-300		-200	mV	
Output Undervoltage Propagation Delay	tUVP	FB_ forced 25mV below trip threshold	100		350	μs	
POK_ Output Low Voltage		ISINK = 4mA			0.3	V	
VCC Undervoltage Lockout Threshold	VUVLO	Rising edge, 50mV typical hysteresis, controller disabled below this level	4.05		4.45	V	
THERMAL PROTECTION							
VR_HOT# Trip Threshold		Measured at THERM_ with respect to VCC falling edge; specify as % error for all TEMP MAX DAC code settings; typical hysteresis = 100mV	49.5		50.5	%	
Thermal Zone Registers Trip Points		Thermal zone comparator trip points, measured with respect to VCC, voltage threshold corresponding to $T_{MAX} \times (1 - N\%)$, $N = 0, 3, 6, 9, 12, 15, 18, 25$	49 + 24 x N/31		51 + 24 x N/31	%	
VALLEY CURRENT LIMIT AND DROOP							
Valley Current-Limit Threshold Voltage (Positive)	VILIMA	VCSP_ - VCSN_ VSR = 0V, VSR = 1.5V, or one-phase operation	RSENSE = 0.65mΩ, I _{MAXA} = 39A	22.5		28.5	mV
			RSENSE = 0.65mΩ, I _{MAXA} = 36A	21.5		27.5	
			RSENSE = 0.65mΩ, I _{MAXA} = 30A	17.0		23.0	
			RSENSE = 0.65mΩ, I _{MAXA} = 26A	15.0		21.0	
			RSENSE = 0.75mΩ, I _{MAXA} = 39A	27.0		33.0	
			RSENSE = 0.75mΩ, I _{MAXA} = 36A	25.0		31.0	
			RSENSE = 0.75mΩ, I _{MAXA} = 30A	20.0		26.0	
			RSENSE = 0.75mΩ, I _{MAXA} = 26A	17.0		23.0	
			RSENSE = 0.85mΩ, I _{MAXA} = 39A	30.0		36.0	
			RSENSE = 0.85mΩ, I _{MAXA} = 36A	28.0		34.0	
			RSENSE = 0.85mΩ, I _{MAXA} = 30A	22.5		28.5	
			RSENSE = 0.85mΩ, I _{MAXA} = 26A	20.0		26.0	
			RSENSE = 0.95mΩ, I _{MAXA} = 39A	33.5		39.5	
			RSENSE = 0.95mΩ, I _{MAXA} = 36A	31.0		37.0	
			RSENSE = 0.95mΩ, I _{MAXA} = 30A	25.0		31.0	
RSENSE = 0.95mΩ, I _{MAXA} = 26A	21.5		27.5				

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = -40^{\circ}C$ to $+105^{\circ}C$, unless otherwise noted. Specifications to $-40^{\circ}C$ and $+105^{\circ}C$ are guaranteed by design, not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Valley Current-Limit Threshold Voltage (Positive)	V_{ILIMA}	$V_{CSP_} - V_{CSN_}$, $V_{SR} = 3V$ or $V_{SR} = 5V$, exclude one-phase operation	$R_{SENSE} = 0.65m\Omega$, $I_{MAXA} = 39A$	29.0		37.0	mV
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXA} = 36A$	28.0		36.0	
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXA} = 30A$	22.0		30.0	
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXA} = 26A$	19.5		27.5	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXA} = 39A$	35.0		43.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXA} = 36A$	32.5		40.5	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXA} = 30A$	26.0		33.8	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXA} = 26A$	22.0		30.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXA} = 39A$	39.0		47.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXA} = 36A$	36.5		44.5	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXA} = 30A$	29.0		37.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXA} = 26A$	26.0		34.0	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXA} = 39A$	43.5		51.5	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXA} = 36A$	40.0		48.0	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXA} = 30A$	32.5		40.5	
$R_{SENSE} = 0.95m\Omega$, $I_{MAXA} = 26A$	28.0		36.0				
Valley Current-Limit Threshold Voltage (Positive)	V_{ILIMB}	$V_{CSP_} - V_{CSN_}$, $V_{SR} = 0V$, $V_{SR} = 1.5V$, or one-phase operation	$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 39A$	22.5		28.5	mV
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 36A$	21.5		27.5	
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 23A$	13.0		19.0	
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 20A$	11.0		17.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 39A$	27.0		33.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 36A$	25.0		31.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 23A$	15.0		21.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 20A$	13.0		19.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 39A$	30.0		36.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 36A$	28.0		34.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 23A$	17.0		23.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 20A$	15.0		21.0	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 39A$	33.5		39.5	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 36A$	31.0		37.0	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 23A$	20.0		26.0	
$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 20A$	17.0		23.0				

MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = -40^{\circ}C$ to $+105^{\circ}C$, unless otherwise noted. Specifications to $-40^{\circ}C$ and $+105^{\circ}C$ are guaranteed by design, not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Valley Current-Limit Threshold Voltage (Positive)	V_{ILIMB}	$V_{CSP_} - V_{CSN_}$, $V_{SR} = 3V$ or $V_{SR} = 5V$, exclude one-phase operation	$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 39A$	29.0		37.0	mV
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 36A$	28.0		36.0	
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 23A$	17.0		25.0	
			$R_{SENSE} = 0.65m\Omega$, $I_{MAXB} = 20A$	14.0		22.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 39A$	35.0		43.0	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 36A$	32.5		40.5	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 23A$	19.5		27.5	
			$R_{SENSE} = 0.75m\Omega$, $I_{MAXB} = 20A$	17.0		25.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 39A$	39.0		47.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 36A$	36.5		44.5	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 23A$	22.0		30.0	
			$R_{SENSE} = 0.85m\Omega$, $I_{MAXB} = 20A$	19.5		27.5	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 39A$	43.5		51.5	
			$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 36A$	40.0		48.0	
$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 23A$	26.0		34.0				
$R_{SENSE} = 0.95m\Omega$, $I_{MAXB} = 20A$	22.0		30.0				
Current-Balance Offset Voltage			-1.5		+1.5	mV	
Phase Disable Threshold		CSPB2, CSPB1, CSPA3, CSPA2, CSPA1	3		$V_{CC} - 0.4$	V	
FB_ Droop Amplifier (GMD) Offset		$V_{CSP_AVE} - V_{CSN_}$ at $I_{FB_} = 0mA$	-1.0		+1.0	mV	
FB_ Droop Amplifier (GMD) Transconductance		$\Delta I_{FB_} / \Delta (V_{CSP_AVE} - V_{CSN_})$, $V_{CSP_AVE} - V_{CSN_} = -15mV$ to $+15mV$	588		612	μS	

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = -40^{\circ}C$ to $+105^{\circ}C$, unless otherwise noted. Specifications to $-40^{\circ}C$ and $+105^{\circ}C$ are guaranteed by design, not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
IMAX_LOGIC						
IMAX_Detection Thresholds		Threshold 0, fault			13.65 x $V_{CC}/50$	V
		Threshold 1, $R_{SENSE} = 0.65m\Omega$, $I_{MAX} = 39A$	14.20 x $V_{CC}/50$		14.65 x $V_{CC}/50$	
		Threshold 2, $R_{SENSE} = 0.65m\Omega$, $I_{MAX} = 36A$	15.20 x $V_{CC}/50$		15.65 x $V_{CC}/50$	
		Threshold 3, $R_{SENSE} = 0.65m\Omega$, $I_{MAXA/B} = 30A/23A$	16.20 x $V_{CC}/50$		16.65 x $V_{CC}/50$	
		Threshold 4, $R_{SENSE} = 0.65m\Omega$, $I_{MAXA/B} = 26A/20A$	17.20 x $V_{CC}/50$		17.65 x $V_{CC}/50$	
		Threshold 5, $R_{SENSE} = 0.75m\Omega$, $I_{MAX} = 39A$	18.20 x $V_{CC}/50$		18.65 x $V_{CC}/50$	
		Threshold 6, $R_{SENSE} = 0.75m\Omega$, $I_{MAX} = 36A$	19.20 x $V_{CC}/50$		19.65 x $V_{CC}/50$	
		Threshold 7, $R_{SENSE} = 0.75m\Omega$, $I_{MAX} = 30A/23A$	20.20 x $V_{CC}/50$		20.65 x $V_{CC}/50$	
		Threshold 8, $R_{SENSE} = 0.75m\Omega$, $I_{MAX} = 26A/20A$	21.20 x $V_{CC}/50$		21.65 x $V_{CC}/50$	
		Threshold 9, $R_{SENSE} = 0.85m\Omega$, $I_{MAX} = 39A$	22.20 x $V_{CC}/50$		22.65 x $V_{CC}/50$	
		Threshold 10, $R_{SENSE} = 0.85m\Omega$, $I_{MAX} = 36A$	23.20 x $V_{CC}/50$		23.65 x $V_{CC}/50$	
		Threshold 11, $R_{SENSE} = 0.85m\Omega$, $I_{MAXA/B} = 30A/23A$	24.20 x $V_{CC}/50$		24.65 x $V_{CC}/50$	
		Threshold 12, $R_{SENSE} = 0.85m\Omega$, $I_{MAXA/B} = 26A/20A$	25.20 x $V_{CC}/50$		25.65 x $V_{CC}/50$	
		Threshold 13, $R_{SENSE} = 0.95m\Omega$, $I_{MAX} = 39A$	26.20 x $V_{CC}/50$		26.65 x $V_{CC}/50$	
		Threshold 14, $R_{SENSE} = 0.95m\Omega$, $I_{MAX} = 36A$	27.20 x $V_{CC}/50$		27.65 x $V_{CC}/50$	
		Threshold 15, $R_{SENSE} = 0.95m\Omega$, $I_{MAXA/B} = 30A/23A$	28.20 x $V_{CC}/50$		28.65 x $V_{CC}/50$	
		Threshold 16, $R_{SENSE} = 0.95m\Omega$, $I_{MAXA/B} = 26A/20A$	29.20 x $V_{CC}/50$		29.65 x $V_{CC}/50$	
	Threshold 17, fault	30.20 x $V_{CC}/50$				
GATE DRIVERS						
DH_Gate-Driver On-Resistance	RON(DH)	BST_ - LX_ forced to 5V	High state (pullup)		2.5	Ω
			Low state (pulldown)		2.0	
DL_Gate-Driver On-Resistance	RON(DL)	High state (pullup)			2.0	Ω
		Low state (pulldown)			0.7	

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

ELECTRICAL CHARACTERISTICS (continued)

(Circuits of Figures 1 and 2. $V_{IN} = 10V$, $V_{CC} = V_{DDA} = V_{DDB} = 5V$, $EN = V_{CC}$, $V_{GNDS_} = 0V$, $V_{FB_} = V_{CSP_AVE} = V_{CSP_} = V_{CSN_} = 1V$; [SerialVID = 1.00, FPWM MODE]; $T_A = -40^{\circ}C$ to $+105^{\circ}C$, unless otherwise noted. Specifications to $-40^{\circ}C$ and $+105^{\circ}C$ are guaranteed by design, not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Internal BST_ Switch On-Resistance	R_{BST}	BSTA1 to V_{DDA} , BSTA2 to V_{DDA} , BSTB to V_{DDB} $V_{DD_} = 5V$			20	Ω
DRVWMA, DRVPWMB Logic-High Voltage		$I_{SOURCE} = 3mA$	$V_{DD_}$ -0.4			V
DRVWMA, DRVPWMB Logic-Low Voltage		$I_{SINK} = 3mA$			0.4	V
LOGIC AND I/O						
Enable Input High Voltage	V_{EN_IH}		0.67			V
Enable Input Low Voltage	V_{EN_IL}				0.33	V
SERIALVID INTERFACE (per Intel SerialVID specification—see the Detailed Description)						
SerialVID Input Low Voltage (CLK, VDIO)	V_{IL}		-0.1		+0.45	V
SerialVID Input High Voltage (CLK, VDIO)	V_{IH}		0.65		$V_{TT} + 1V$	V
SerialVID Output Low Level (VDIO, ALERT#)	V_{OL}	Open-drain pullup to V_{TT} , $R_{PU} = 50\Omega$			0.36	V
SerialVID Open-Drain Output On-Resistance (VDIO, ALERT#, VRHOT#)	R_{ON}	$I_{SINK} = 30mA$, $T_A = 0^{\circ}C$ to $+105^{\circ}C$	4		13	Ω
SerialVID Logic Slew Rate (CLK, VDIO, ALERT#)			0.5		2.0	V/ns
SerialVID Input Capacitance	C_{PAD}				4	pF
CLK Frequency	f_{CLK}		13		33.3	MHz
CLK Absolute Min/Max Period		Specified as a percentage of f_{CLK}	-5		+5	%
CLK High Time	t_{HIGH}	Specified as a percentage of t_{CLK} period	45			%
CLK Low Time	t_{LOW}	Specified as a percentage of t_{CLK} period	45			%
Rise Time	t_{RISE}		0.25		2.5	ns
Fall Time	t_{FALL}		0.25		2.5	ns
Duty Cycle			45		55	%
SerialVID Inactivity Timeout	t_{RSTNA}		0.14		0.40	μs

Note 2: The equation for the target voltage V_{TARGET} is:

$$V_{TARGET} = \text{the slew-rate-controlled version of either } V_{DAC}$$

where $V_{DAC} = 0V$ for shutdown, $V_{DAC} = V_{BOOT}$ during startup, otherwise $V_{DAC} = V_{ID}$ (the V_{ID} voltages for all possible VID codes are given in Table 3 and V_{OFFSET} = the negative or positive offset to the output voltage based on the voltage set from the offset register and the mode of operation (startup, shutdown, deeper sleep, or normal operation), as defined elsewhere in this document.

Note 3: On-time and minimum off-time specifications are measured from 50% to 50% at the $DH_$ pin, with $LX_$ forced to 0V, $BST_$ forced to 5V, and a 500pF capacitor from $DH_$ to $LX_$ to simulate external MOSFET gate capacitance. Actual in-circuit times may be different due to MOSFET switching speeds.

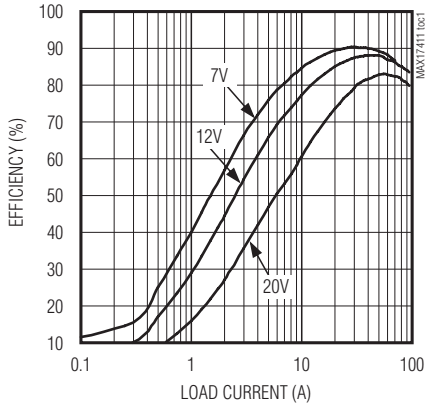
Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Typical Operating Characteristics

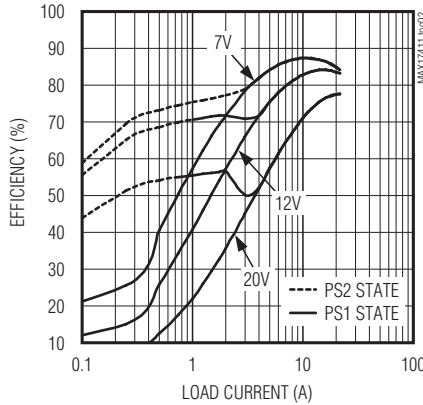
($T_A = +25^\circ\text{C}$, unless otherwise noted.)

MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T

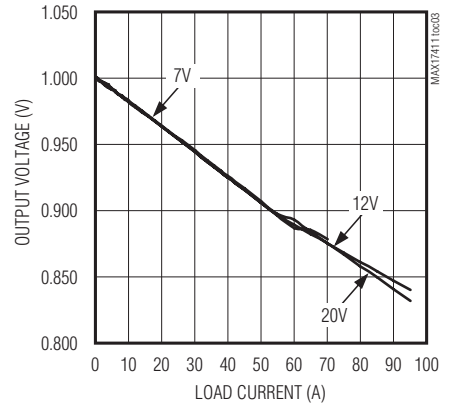
REG A EFFICIENCY vs. LOAD CURRENT IN PSO STATE (SVID = 1V)



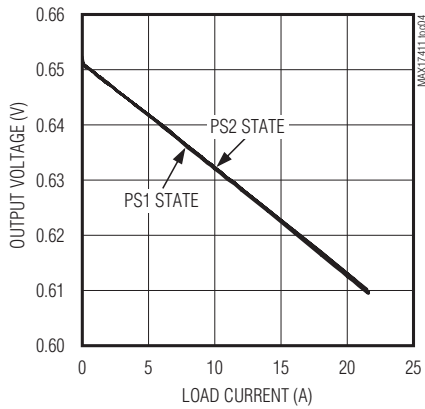
REG A EFFICIENCY vs. LOAD CURRENT IN PS1 AND PS2 STATES (SVID = 0.65V)



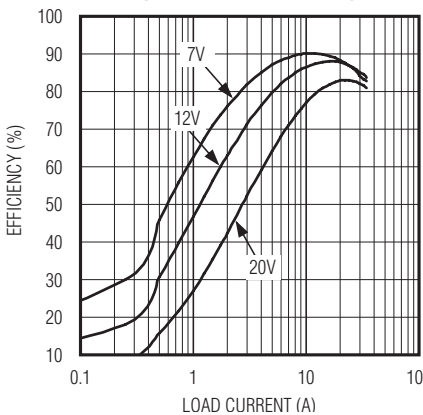
REG A OUTPUT VOLTAGE vs. LOAD CURRENT IN PSO STATE (SVID = 1V)



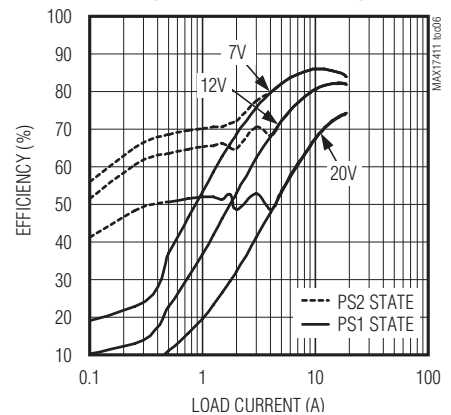
REG A OUTPUT VOLTAGE vs. LOAD CURRENT IN PS1 AND PS2 STATES (SVID = 0.65V)



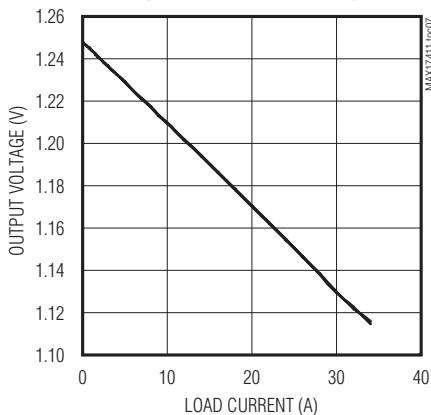
REG B EFFICIENCY vs. LOAD CURRENT IN PSO STATE (SVID = 1.25V) (MAX17511/C/N/T ONLY)



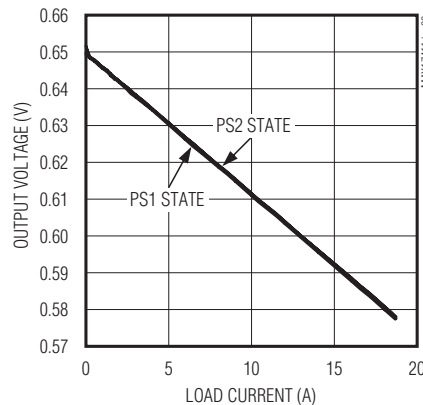
REG B EFFICIENCY vs. LOAD CURRENT IN PS1 AND PS2 STATES (SVID = 0.65V) (MAX17511/C/N/T ONLY)



REG B OUTPUT VOLTAGE vs. LOAD CURRENT IN PSO STATE (SVID = 1.25V) (MAX17511/C/N/T ONLY)



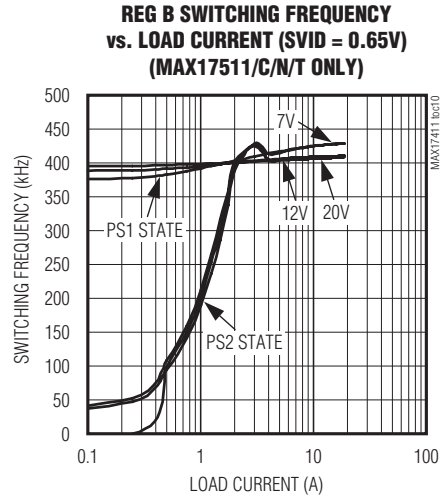
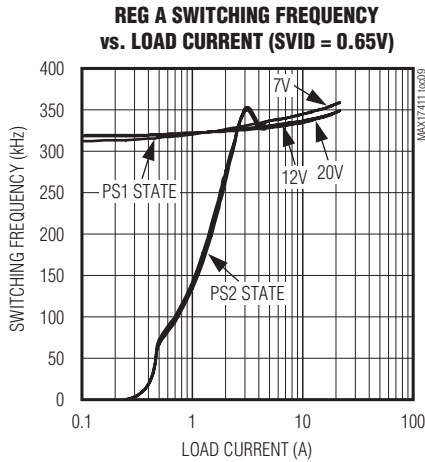
REG B OUTPUT VOLTAGE vs. LOAD CURRENT IN PS1 AND PS2 STATES (SVID = 0.65V) (MAX17511/C/N/T ONLY)



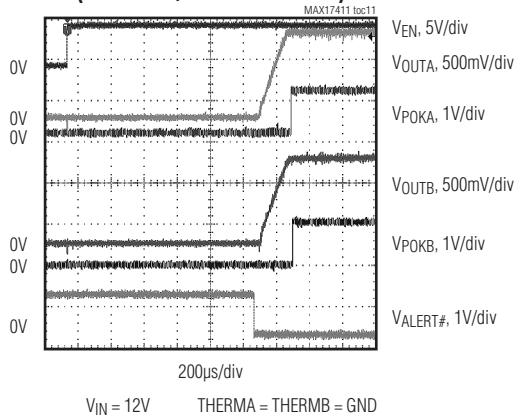
Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Typical Operating Characteristics (continued)

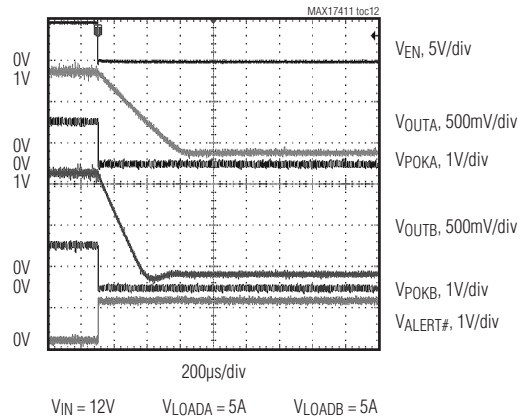
(T_A = +25°C, unless otherwise noted.)



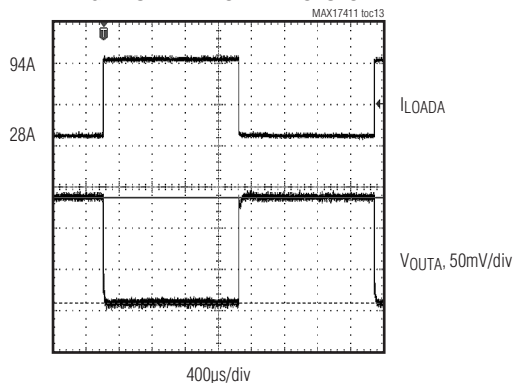
NON-ZERO V_{BOOT} STARTUP WAVEFORMS (V_{BOOT}, 1.05V) (MAX17511/MAX17511T ONLY)



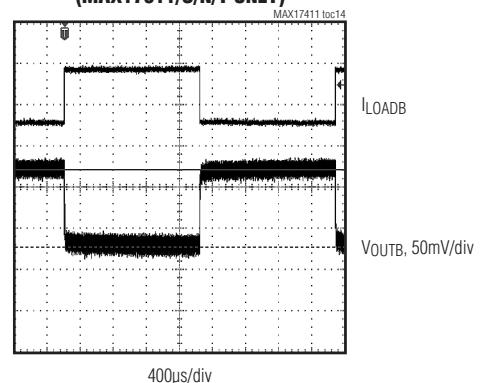
SHUTDOWN WAVEFORMS



REG A LOAD-TRANSIENT RESPONSE

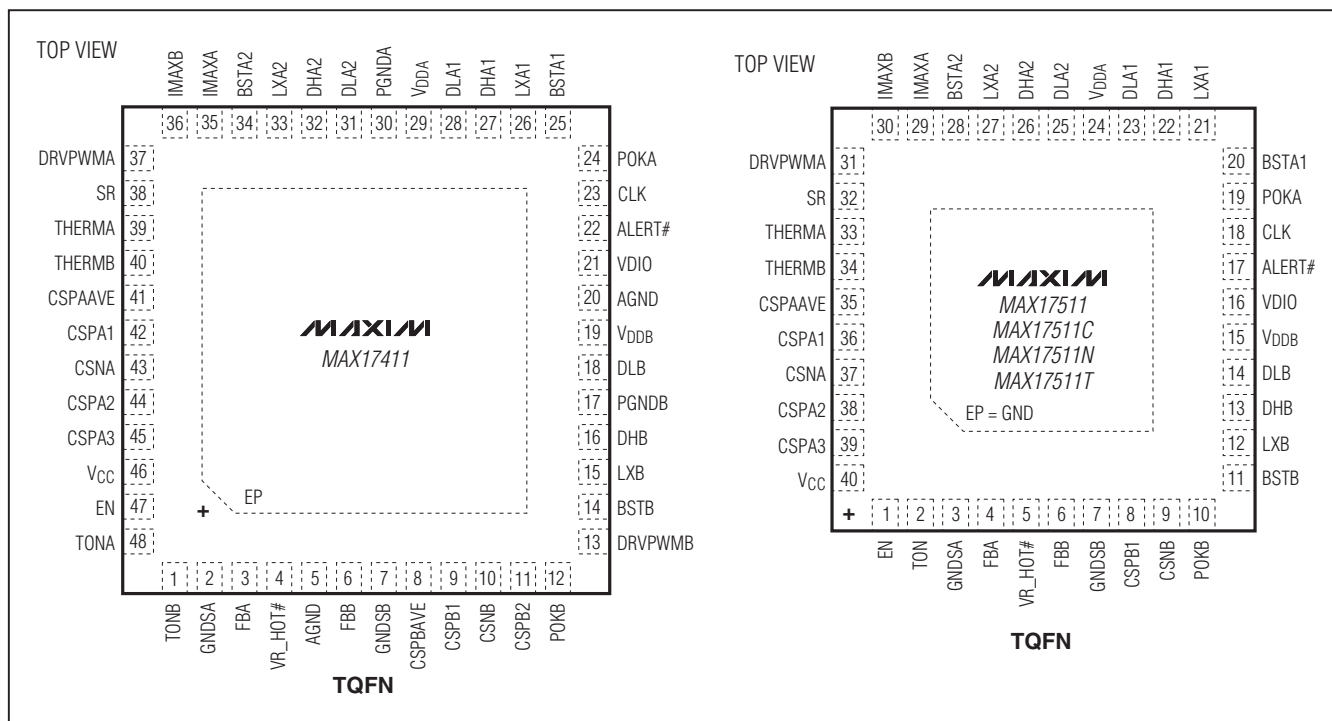


REG B LOAD-TRANSIENT RESPONSE (MAX17511/C/N/T ONLY)



Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Pin Configurations



Pin Description

PIN		NAME	FUNCTION
MAX17411	MAX17511/ MAX17511C/ MAX17511N/ MAX17511T		
1	—	TONB	Switching Frequency Adjustment Input for Regulator B. An external resistor between the input power source and TONB sets the switching period (per phase) for regulator B according to the following equation: $t_{SWB} = (R_{TONB} + 6.5k\Omega) \times 14.6pF$ where $f_{SWB} = 1/t_{SWB}$ is the nominal switching frequency. TONB is high-impedance in shutdown. If REG B is disabled, connect TONB to GND or Vcc.
—	2	TON	Switching Frequency Adjustment Input for Both Regulators. An external resistor between the input power source and TON sets the switching period (per phase) according to the following equations: $t_{SWA} = (2 \times R_{TON} + 6.5k\Omega) \times 17.9pF$ $t_{SWB} = (2 \times R_{TON} + 6.5k\Omega) \times 14.6pF$ where $f_{SW} = 1/t_{SW}$ is the nominal switching frequency. If REG B is disabled: $t_{SWA} = (R_{TON} + 6.5k\Omega) \times 17.9pF$ TON is high-impedance in shutdown.

MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Pin Description (continued)

PIN		NAME	FUNCTION
MAX17411	MAX17511/ MAX17511C/ MAX17511N/ MAX17511T		
2	3	GNDSA	Ground Remote-Sense Input for Regulator A. Connect GNDSA to the ground-sense pin of the CPU located directly at the point of load. GNDSA internally connects to an internal transconductance amplifier that adjusts the output voltage to compensate for voltage drops between the controller analog ground and the load ground.
3	4	FBA	<p>Feedback Remote-Sense Input and Voltage Positioning Transconductance (VPS) Amplifier Output for Regulator A. Connect a resistor (R_{FBA}) between FBA and the positive side of the feedback remote sense (the CPU output remote sense (V_{CC_SENSE})) to set the DC steady-state droop based on the voltage-positioning gain requirement.</p> $R_{FBA} = (NPH \times RDROOP) / (R_{SENSE} \times GMD)$ <p>where $RDROOP$ is the desired voltage-positioning slope, $GMD = 600\mu S$ (typ), and R_{SENSE} is the current-sense resistance with respect to the CSPAAVE to CSNA current-sense inputs. See the <i>CSP_AVE - CSN_Inputs</i> section. FBA is internally connected to the input of an error comparator and an integrator that corrects for output ripple, error comparator offsets, and the ground-sense offset of regulator A as shown in Figure 5.</p> <p>Shorting FBA directly to the output disables voltage positioning, but impacts the stability requirements. Designs that disable voltage positioning require a higher minimum output capacitance ESR to maintain stability (see the <i>Output Capacitor Selection</i> section). FBA enters a high-impedance state in shutdown.</p>
4	5	VR_HOT#	Open-Drain Output of the Thermal Comparators that monitor THERMA and THERMB. These comparators are wire-ORed with output at VR_HOT#. This output is required as backup to the temperature zone register in the event of an SVID bus failure. The comparator responds to the temperature threshold voltage of 2.5V at THERMA OR THERMB. This threshold is equivalent to the 100% threshold defined in the Temperature-Zone register (12h).
5, 20	—	AGND	Analog Ground

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Pin Description (continued)

PIN		NAME	FUNCTION
MAX17411	MAX17511/ MAX17511C/ MAX17511N/ MAX17511T		
6	6	FBB	<p>Feedback Remote-Sense Input and Voltage Positioning Transconductance (VPS) Amplifier Output for Regulator B. Connect a resistor (RFBB) between FBB and the positive side of the feedback remote sense to set the DC steady-state droop based on the voltage-positioning gain requirement.</p> $R_{FBB} = (NPH \times RDROOP) / (R_{SENSEB} \times GMD)$ <p>where RDROOP is the desired voltage-positioning slope, GMD = 600μS (typ), and RSENSEB is the current-sense resistance with respect to the CSPBAVE to CSNB (MAX17411) or CSPB1 - CSNB (MAX17511/MAX17511C/MAX17511N/MAX17511T) current-sense inputs. See the <i>CSP_AVE – CSN_ Inputs</i> section. FBB is internally connected to the input of an error comparator and an integrator that corrects for output ripple, error comparator offsets, and the ground-sense offset of regulator B as shown in Figures 6 and 7.</p> <p>Shorting FBB directly to the output disables voltage positioning, but impacts the stability requirements. Designs that disable voltage positioning require a higher minimum output capacitance ESR to maintain stability (see the <i>Output Capacitor Selection</i> section).</p> <p>FBB enters a high-impedance state in shutdown.</p>
7	7	GNDSB	<p>Ground Remote-Sense Input for Regulator B. Connect GNDSB to the ground-sense pin of the GFX located directly at the point of load. GNDSB internally connects to an internal transconductance amplifier that adjusts the output voltage to compensate for voltage drops between the controller analog ground and the load ground.</p>
8	—	CSPBAVE	<p>Positive Current-Sense Average Input for Regulator B. Connect CSPBAVE to the positive side of the differential output of external current-sense averaging network. The averaging is achieved by using a resistive summation and current-sense resistors, or by using a parallel DCR sense network with a single NTC thermistor for thermal compensation (see Figure 9). The average current-sense input is used for the load-line and current monitor.</p>
9	8	CSPB1	<p>Positive Current-Sense Input for Regulator B. Connect CSPB1 to the positive side of the current-sense resistor or the DCR sense filter capacitor of regulator B as shown in Figure 8.</p> <p>To <i>completely</i> disable Regulator B, Connect CSPB1 and CSPB2 to VCC. Also leave BSTB, DHB, LXB, DLB, CSPBAVE, and CSNB unconnected. Address 1 is disabled from the SVID bus.</p>
10	9	CSNB	<p>Negative Current-Sense Input of Regulator B. Connect CSNB to the negative side of the current-sense element as shown in Figure 8. An internal 20Ω discharge MOSFET between CSNB and ground is enabled under an input UVLO or shutdown condition. A bypass capacitor between CSNB and GND in the range of 1nF to 0.1μF is recommended.</p>

MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Pin Description (continued)

PIN		NAME	FUNCTION
MAX17411	MAX17511/ MAX17511C/ MAX17511N/ MAX17511T		
11	—	CSPB2	Positive Current-Sense Input for Second Phase of Regulator B. Connect CSPB2 to the positive side of the current-sense element of the second phase of regulator B as shown in Figure 8. Connect CSPB2 to V _{CC} and leave DRVPWMB unconnected to disable the second phase of Regulator B.
12	10	POKB	Open-Drain Power-Good Output for Regulator B. During soft-start and shutdown, POKB stays low. At the end of soft-start, approximately 20μs (typ) after FBB reaches the output voltage set by the VID code, POKB becomes high-impedance and remains high-impedance as long as FBB is in regulation. POKB is blanked high-impedance when the slew-rate controller for regulator B is active (VID transition occurs). In pulse-skipping mode, the upper POKB threshold is blanked during downward transitions until the output voltage reaches its regulation value. POKB is forced low in shutdown (EN = GND) and after any fault condition is detected on either regulator. To obtain a logic signal, pull up POKB with an external resistor connected to a positive logic supply of +5V and lower.
13	—	DRVPWMB	Direct-Drive PWM Output for Controlling the External Second Phase Driver for Regulator B. DRVPWMB is three-stated in shutdown when the controller detects an output overvoltage fault condition on regulator B.
14	11	BSTB	Boost Flying Capacitor Connection for High-Side Gate Voltage for the First Phase of Regulator B. Connect a ceramic capacitor between BSTB and LXB. See the <i>Boost Capacitors</i> section.
15	12	LXB	Inductor Connection for the First Phase of Regulator B. LXB serves as the lower supply rail for the DHB high-side gate driver. LXB is also used as an input to the zero-crossing comparator for regulator B.
16	13	DHB	High-Side Gate-Driver Output for Regulator B. DHB output voltage swings from V _{BSTB} to V _{LXB} . DHB is pulled low in shutdown.
17	—	PGNDB	Power Ground of the Low-Side Driver of Regulator B
18	14	DLB	Low-Side Gate-Driver Output for the First Phase of Regulator B. DLB output voltage swings from V _{DDB} to GND. DLB is forced high when the controller detects an output overvoltage fault condition on regulator B. DLB is forced low in shutdown and in pulse-skipping mode when an inductor current zero crossing (LXB - GND) is detected.
19	15	V _{DDB}	Driver-Supply Voltage Input for Regulator B. V _{DDB} provides power for the low-side driver of regulator B and is used to recharge the BSTB flying capacitor during the on-time of DLB. Connect V _{DDB} to the 4.5V to 5.5V system supply voltage. Bypass V _{DDB} to power ground with a 1μF or greater ceramic capacitor.
21	16	VDIO	Serial VID Input/Output
22	17	ALERT#	Serial VID Alert Output. ALERT# is in the high state in shutdown.
23	18	CLK	Serial VID Clock Input

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Pin Description (continued)

PIN		NAME	FUNCTION
MAX17411	MAX17511/ MAX17511C/ MAX17511N/ MAX17511T		
24	19	POKA	Open-Drain Power-Good Output for Regulator A. During soft-start and shutdown, POKA stays low. At the end of soft-start, approximately 20 μ s (typ) after FBA reaches the output voltage set by the VID code, POKA becomes high-impedance and remains high-impedance as long as FBA is in regulation. POKA is blanked high-impedance when the slew-rate controller for regulator A is active (VID transition occurs). In pulse-skipping mode, the upper POKA threshold is blanked during downward transitions until the output voltage reaches its regulation value. POKA is forced low in shutdown (EN = GND) and after any fault condition is detected on either regulator. To obtain a logic signal, pull up POKA with an external resistor connected to a positive logic supply of +5V and lower.
25	20	BSTA1	Boost Flying Capacitor Connection for High-Side Gate Voltage for the First Phase of Regulator A. Connect a ceramic capacitor between BSTA1 and LXA1. See the <i>Boost Capacitors</i> section.
26	21	LXA1	Inductor Connection for the First Phase of Regulator A. LXA1 serves as the lower supply rail for the DHA1 high-side gate driver. LXA1 is also used as an input to the zero-crossing comparator for regulator A.
27	22	DHA1	High-Side Gate-Driver Output for the First Phase of Regulator A. DHA1 output voltage swings from VBSTA1 to VLXA1. DHA1 is pulled low in shutdown.
28	23	DLA1	Low-Side Gate-Driver Output for the First Phase of Regulator A. DLA1 output voltage swings from VDDA to VGND. DLA1 is forced high when the controller detects an output overvoltage fault condition on regulator A. DLA1 is forced low in shutdown and in pulse-skipping mode when an inductor current zero crossing (LXA1 - GND) is detected.
29	24	VDDA	Driver Supply Voltage Input for Regulator A. VDDA is the driver supply voltage used for the DLA_ low-side drivers, and to recharge the BSTA_ flying capacitors when the corresponding DLA_s are high. Connect VDDA to the 4.5V to 5.5V system supply voltage. Bypass VDDA to power ground with a 1 μ F or greater ceramic capacitor.
30	—	PGNDA	Power Ground of the Low-Side Drivers of Regulator A.
31	25	DLA2	Low-Side Gate-Driver Output for the Second Phase of Regulator A. DLA2 Output Voltage swings from VDDA to VGND. DLA2 is forced high when the controller detects an output overvoltage fault condition on regulator A. DLA2 is forced low in shutdown and in pulse-skipping mode when an inductor current zero crossing (LXA2 - GND) is detected.
32	26	DHA2	High-Side Gate-Driver Output for the Second Phase of Regulator A. DHA2 Output Voltage swings from VBSTA2 to VLXA2. DHA2 is pulled low in shutdown.
33	27	LXA2	Inductor Connection for the Second Phase of Regulator A. LXA2 serves as the lower supply rail for the DHA2 high-side gate driver. LXA2 is also used as an input to the zero crossing comparator for Regulator A.

MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Pin Description (continued)

PIN		NAME	FUNCTION		
MAX17411	MAX17511/ MAX17511C/ MAX17511N/ MAX17511T				
34	28	BSTA2	Boost Flying Capacitor Connection for High-Side Gate Voltage for the Second Phase of Regulator A. Connect a ceramic capacitor between BSTA2 and LXA2. See the <i>Boost Capacitors</i> section.		
35	29	IMAXA	Maximum Current Threshold for Regulator A. This multivalued logic input sets the valley current limit and compensates for inductor DCR. The maximum output current value in register 21h is determined by the number of phases times the maximum output current per phase set by IMAXA. If the voltage applied to IMAXA is not within the defined threshold, the MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T detect a fault and latch off. See Table 6 for more details.		
36	30	IMAXB	Maximum Current Threshold for Regulator B. This multivalued logic input sets the valley current limit and compensates for inductor DCR. The maximum output current value in register 21h is determined by the number of phases times the maximum output current per phase set by IMAXB. If the voltage applied to IMAXB is not within the defined threshold, the MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T detect a fault and latch off. See Table 6 for more details.		
37	31	DRVPWMA	Direct-Drive PWM Output for Controlling the External Third Phase Driver for Regulator A. DRVPWMA is three-stated in shutdown when the controller detects an output overvoltage fault condition on regulator A.		
38	32	SR	Fast Slew-Rate Adjustment for Both Regulators. The SR setting determines the value stored in the Slew Rate Fast (24h) and Slew Rate Slow (25h) registers. The input uses a four-level voltage sense to determine the slew rate setting upon power-up and if NTC are used for the CSP_ signals. The SR values in the registers (24h and 25h) change accordingly.		
			SR THRESHOLD (V)	SR (min) (mV/μs)	NTC
			0	10	Yes
			1.5	20	Yes
			3	20	No
VCC	10	No			
39	33	THERMA	Thermal-Sense Input for Regulator A. Connect THERMA to a resistor/thermistor-divider network between VCC and THERMA to analog ground. The VR_HOT# is pulled low when the voltage at THERMA or THERMB drops below 0.5 x VCC. If THERMA is held low at startup, REG A is forced in to non-zero VBOOT mode with an output voltage of 1.05V (MAX17411/MAX17511/MAX17511T).		
40	34	THERMB	Thermal-Sense Input for Regulator B. Connect THERMB to a resistor/thermistor-divider network between VCC and THERMB to analog ground. The VR_HOT# is pulled low when the voltage at THERMA or THERMB drops below 0.5 x VCC. If THERMB is held low at startup, REG B is forced in to non-zero VBOOT mode with a output voltage of 1.05V (MAX17411/MAX17511/MAX17511T).		
41	35	CSPAAVE	Positive Current-Sense Average Input for Regulator A. Connect CSPAAVE to the positive side of the differential output of external current-sense averaging network. The averaging is achieved by using a resistive summation and current-sense resistors, or by using a parallel DCR sense network with a single NTC thermistor for thermal compensation (see Figures 1, 2, and 3). The average current-sense input is used for the load-line and current monitor.		

Dual-Output, 3-/2-/1-Phase + 2-/1-Phase Quick-PWM Controllers for VR12/IMVP7

Pin Description (continued)

PIN		NAME	FUNCTION
MAX17411	MAX17511/ MAX17511C/ MAX17511N/ MAX17511T		
42	36	CSPA1	Positive Current-Sense Input for the First Phase of Regulator A. Connect CSPA1 to the positive side of the current-sense resistor or the DCR sense filter capacitor of regulator A as shown in Figure 8. To <i>completely</i> disable Regulator A, connect CSPA1, CSPA2, and CSPA3 to VCC and leave BSTA1, DHA1, LXA1, DLA1, CSPAAVE, and CSNA unconnected. Address 0 is also disabled from the SVID bus.
43	37	CSNA	Negative Current-Sense Input of Regulator A. Connect CSNA to the negative side of the current-sense element as shown in Figure 8. An internal 20Ω discharge MOSFET between CSNA and ground is enabled under an input UVLO or shutdown condition. A bypass capacitor between CSNA and GND in the range of 1nF to 0.1μF is recommended.
44	38	CSPA2	Positive Current-Sense Input for the Second Phase of Regulator A. Connect CSPA2 to the positive side of the current-sense resistor or the DCR sense filter capacitor of regulator A as shown in Figure 8. To <i>completely</i> disable Regulator A, connect CSPA1, CSPA2, and CSPA3 to VCC. Address 0 is also disabled from the SVID bus. When Phase 2 is disabled, leave BSTA2, DHA2, LXA2, and DLA2 unconnected. If phase 2 is disabled, phase 3 must be disabled as well.
45	39	CSPA3	Positive Current-Sense Input for Third Phase of Regulator A. Connect CSPA3 to the positive side of the current-sense element of the third phase of regulator A as shown in Figure 8. Connect CSPA3 to VCC and leave DRVPWMA unconnected to disable the third phase of Regulator A.
46	40	VCC	Analog Supply Voltage. Connect to a filtered 4.5V to 5.5V source. Bypass VCC to AGND with a 1μF or greater ceramic capacitor.
47	1	EN	Controller Enable Input. Pull EN high or connect EN to VCC for normal operation. Connect to ground to put the controller into its 30μA (max) shutdown state. During soft-start, the controller slowly ramps the output voltage up to the boot voltage with a 2.5mV/μs (min) slew rate. During the transition from normal operation to shutdown, the output is discharged through a 20Ω internal CSN_FET. Toggling EN resets the fault latches. EN cannot withstand the battery voltage.
48	—	TONA	Switching Frequency Adjustment Input for Regulator A. An external resistor between the input power source and TONA sets the switching period (per phase) for regulator A according to the following equation: $t_{SWA} = (R_{TONA} + 6.5k\Omega) \times 17.9pF$ where $f_{SWA} = 1/t_{SWA}$ is the nominal switching frequency. TONA is high-impedance in shutdown. If REG A is disabled, connect TONA to GND.
EP	—	PAD (AGND)	Exposed Pad. Connect EP to the ground plane with thermally enhanced vias.
—	EP	PAD (GND)	Exposed Pad. Connect EP to the ground plane with thermally enhanced vias. Power ground pads and analog ground pads are all internally connected to the exposed pad.

MAX17411/MAX17511/MAX17511C/MAX17511N/MAX17511T