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EVALUATION KIT
AVAILABLE

MAXIM

7.5Msps, Ultra-Low-Power Analog Front-End

MAX19700

General Description

The MAX19700 is an ultra-low-power, mixed-signal analog front-end (AFE) designed for TD-SCDMA handsets and data cards. Optimized for high dynamic performance at ultra-low power, the MAX19700 integrates a dual 10-bit, 7.5Msps receive (Rx) ADC, dual 10-bit, 7.5Msps transmit (Tx) DAC with TD-SCDMA baseband filters, and three fast-settling 12-bit aux-DAC channels for ancillary RF front-end control. The typical operating power in Tx-Rx FAST mode is 36.3mW at a 5.12Msps clock frequency.

The Rx ADCs feature 54.9dB SINAD and 78dBc SFDR at a 1.87MHz input frequency with a 7.5Msps sample frequency. The analog I/Q input amplifiers are fully differential and accept 1.024V_{P-P} full-scale signals. Typical I/Q channel matching is $\pm 0.22^\circ$ phase and ± 0.02 dB gain.

The Tx DACs with TD-SCDMA lowpass filters feature -3dB cutoff frequency of 1.27MHz and >55dB stopband rejection at $f_{\text{IMAGE}} = 4.32$ MHz. The analog I/Q full-scale output voltage range is selectable at ± 410 mV or ± 500 mV. The output common-mode voltage is selectable from 0.9V to 1.4V and the I/Q channel offset is adjustable. The typical I/Q channel matching is ± 0.05 dB gain and $\pm 0.16^\circ$ phase.

The Rx ADC and Tx DAC share a single, 10-bit parallel, high-speed digital bus allowing half-duplex operation for time-division duplex (TDD) applications. A 3-wire serial interface controls power-management modes and the aux-DAC channels.

The MAX19700 operates on a single +2.7V to +3.3V analog supply and +1.8V to +3.3V digital I/O supply. The MAX19700 is specified for the extended (-40°C to +85°C) temperature range and is available in a 48-pin, thin QFN package.

Applications

TD-SCDMA Handsets
TD-SCDMA Data Cards
Portable Communication Equipment

Ordering Information

| PART* | PIN-PACKAGE | PKG CODE |
|--------------|------------------|----------|
| MAX19700ETM | 48 Thin QFN-EP** | T4877-4 |
| MAX19700ETM+ | 48 Thin QFN-EP** | T4877-4 |

*All devices are specified over the -40°C to +85°C operating range.

**EP = Exposed paddle.

+Denotes lead-free package.

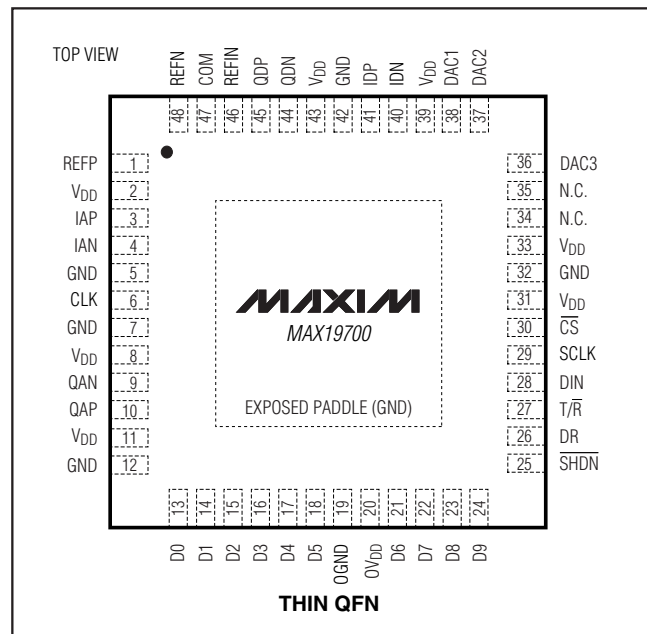
Functional Diagram appears at end of data sheet.

MAXIM

Features

- ◆ Dual 10-Bit Rx ADC and Dual 10-Bit Tx DAC
- ◆ Ultra-Low Power
 - 36.3mW at $f_{\text{CLK}} = 5.12$ Msps, Fast Mode
 - 19.8mW at $f_{\text{CLK}} = 5.12$ Msps, Slow Mode
 - Low Standby and Shutdown Current
- ◆ Integrated TD-SCDMA Filters with >55dB Stopband Rejection
- ◆ Excellent Dynamic Performance
 - SINAD = 54.9dB at $f_{\text{IN}} = 1.87$ MHz (Rx ADC)
 - SFDR = 76.5dBc at $f_{\text{OUT}} = 620$ kHz (Tx DAC)
- ◆ Excellent Gain/Phase Match
 - $\pm 0.22^\circ$ Phase, ± 0.02 dB Gain (Rx ADC) at $f_{\text{IN}} = 1.87$ MHz at -0.5dBFS
- ◆ Three 12-Bit, 1 μ s Aux-DACs
- ◆ Single-Supply Operation
- ◆ Multiplexed Parallel Digital I/O
- ◆ Serial-Interface Control
- ◆ Versatile Power-Control Circuits
 - Shutdown, Standby, Idle, Tx-Rx Disable
- ◆ Miniature 48-Pin Thin QFN Package (7mm x 7mm x 0.8mm)

Pin Configuration



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ABSOLUTE MAXIMUM RATINGS

| | |
|---|------------------------------------|
| V _{DD} to GND, OV _{DD} to OGND | -0.3V to +3.4V |
| GND to OGND | -0.3V to +0.3V |
| IAP, IAN, QAP, QAN, IDP, IDN, QDP, QDN, REFP, REFN, REFIN, COM, DAC1, DAC2, DAC3 to GND | -0.3V to (V _{DD} + 0.3V) |
| D0–D9, DR, T/R, SHDN, SCLK, DIN, CS, CLK to OGND | -0.3V to (OV _{DD} + 0.3V) |

| | | |
|---|--|-----------------|
| Continuous Power Dissipation (T _A = +70°C) | 48-Pin Thin QFN (derate 26.3mW/°C above +70°C) | 2.1W |
| Thermal Resistance θ_{JA} | | 38°C/W |
| Operating Temperature Range | | -40°C to +85°C |
| Junction Temperature | | +150°C |
| Storage Temperature Range | | -60°C to +150°C |
| Lead Temperature (soldering, 10s) | | +300°C |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(V_{DD} = 3V, OV_{DD} = 1.8V, internal reference (1.024V), C_L ≈ 10pF on all digital outputs, f_{CLK} = 7.5MHz (50% duty cycle), ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, C_{REFP} = C_{REFN} = C_{COM} = 0.33μF. Typical values are at T_A = +25°C, unless otherwise noted. C_L < 5pF on all aux-DAC outputs.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------|------------------|---|-----|------|-----------------|-------|
| POWER REQUIREMENTS | | | | | | |
| Analog Supply Voltage | V _{DD} | | 2.7 | 3.0 | 3.3 | V |
| Output Supply Voltage | OV _{DD} | | 1.8 | | V _{DD} | V |
| V _{DD} Supply Current | | Ext1-Tx, Ext3-Tx, and SPI2-Tx states; transmit DAC operating mode (Tx), f _{CLK} = 5.12MHz, f _{OUT} = 620kHz on both channels; aux-DACs ON and at midscale | | 10.3 | | mA |
| | | Ext2-Tx, Ext4-Tx, and SPI4-Tx states; transmit DAC operating mode (Tx), f _{CLK} = 5.12MHz, f _{OUT} = 620kHz on both channels; aux-DACs ON and at midscale | | 12.4 | | |
| | | Ext1-Rx, Ext4-Rx, and SPI3-Rx states; receive ADC operating mode (Rx), f _{CLK} = 5.12MHz, f _{IN} = 1.87MHz on both channels; aux-DACs ON and at midscale | | 12.1 | | |
| | | Ext2-Rx, Ext3-Rx, and SPI1-Rx modes; receive ADC operating mode (Rx), f _{CLK} = 5.12MHz, f _{IN} = 1.87MHz on both channels; aux-DACs ON and at midscale | | 6.6 | | |
| | | Ext2-Tx, Ext4-Tx, and SPI4-Tx modes; transmit DAC operating mode (Tx), f _{CLK} = 7.5MHz, f _{OUT} = 620kHz on both channels; aux-DACs ON and at midscale | | 13.1 | 16 | |
| | | Ext1-Tx, Ext3-Tx, and SPI2-Tx modes; transmit DAC operating mode (Tx), f _{CLK} = 7.5MHz, f _{OUT} = 620kHz on both channels; aux-DACs ON and at midscale | | 10.4 | | |

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ELECTRICAL CHARACTERISTICS (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ (50% duty cycle), ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$. Typical values are at $T_A = +25^\circ C$, unless otherwise noted. $C_L < 5pF$ on all aux-DAC outputs.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------|--------|--|-----|-------|-------|---------|
| V _{DD} Supply Current | | Ext1-Rx, Ext4-Rx, and SPI3-Rx modes; receive ADC operating mode (Rx), $f_{CLK} = 7.5MHz$, $f_{IN} = 1.87MHz$ on both channels; aux-DACs ON and at midscale | | 12.8 | 16 | mA |
| | | Ext2-Rx, Ext3-Rx, and SPI1-Rx modes; receive ADC operating mode (Rx), $f_{CLK} = 7.5MHz$, $f_{IN} = 1.87MHz$ on both channels; aux-DACs ON and at midscale | | 7 | | |
| | | Standby mode, CLK = 0 or OV _{DD} ; aux-DACs ON and at midscale | | 2.7 | 4 | |
| | | Idle mode, $f_{CLK} = 7.5MHz$; aux-DACs ON and at midscale | | 4.7 | 6 | |
| | | Shutdown mode, CLK = 0 or OV _{DD} | | 0.7 | | μA |
| OV _{DD} Supply Current | | Ext1-Rx, Ext2-Rx, Ext3-Rx, Ext4-Rx, SPI1-Rx, SPI3-Rx modes; receive ADC operating mode (Rx), $f_{CLK} = 7.5MHz$, $f_{IN} = 1.87MHz$ on both channels; aux-DACs ON and at midscale | | 1.38 | | mA |
| | | Ext1-Tx, Ext2-Tx, Ext3-Tx, Ext4-Tx, SPI2-Tx, SPI4-Tx modes; transmit DAC operating mode (Tx), $f_{CLK} = 7.5MHz$, $f_{OUT} = 620kHz$; aux-DACs ON and at midscale | | 72.9 | | |
| | | Idle mode, $f_{CLK} = 7.5MHz$; aux-DACs ON and at midscale | | 10.9 | | μA |
| | | Shutdown mode, CLK = 0 or OV _{DD} | | 0.01 | | |
| | | Standby mode, CLK = 0 or OV _{DD} ; aux-DACs ON and at midscale | | 0.03 | | |
| Rx ADC DC ACCURACY | | | | | | |
| Resolution | | | 10 | | | Bits |
| Integral Nonlinearity | INL | | | ±0.85 | | LSB |
| Differential Nonlinearity | DNL | | | ±0.55 | | LSB |
| Offset Error | | Residual DC offset error | | ±0.5 | ±5 | %FS |
| Gain Error | | Include reference error | | ±1.1 | ±5 | %FS |
| DC Gain Matching | | | | ±0.01 | ±0.25 | dB |
| Offset Matching | | | | ±4.5 | | LSB |
| Gain Temperature Coefficient | | | | ±15.7 | | ppm/°C |
| Power-Supply Rejection | PSRR | Offset error ($V_{DD} \pm 5\%$) | | ±0.2 | | LSB |
| | | Gain error ($V_{DD} \pm 5\%$) | | ±0.04 | | %FS |

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ELECTRICAL CHARACTERISTICS (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ (50% duty cycle), ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$. Typical values are at $T_A = +25^\circ C$, unless otherwise noted. $C_L < 5pF$ on all aux-DAC outputs.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|-----------|---|--------------|------|-------|--------------|
| Rx ADC ANALOG INPUT | | | | | | |
| Input Differential Range | V_{ID} | Differential or single-ended inputs | ±0.512 | | | V |
| Input Common-Mode Voltage Range | V_{CM} | | $V_{DD} / 2$ | | | V |
| Input Impedance | R_{IN} | Switched capacitor load | 720 | | | k Ω |
| | C_{IN} | | 5 | | | pF |
| Rx ADC CONVERSION RATE | | | | | | |
| Maximum Clock Frequency | f_{CLK} | (Note 2) | | | 7.5 | MHz |
| Data Latency (Figure 3) | | Channel I | | | 5 | Clock Cycles |
| | | Channel Q | | | 5.5 | |
| Rx ADC DYNAMIC CHARACTERISTICS (Note 3) | | | | | | |
| Signal-to-Noise Ratio | SNR | $f_{IN} = 1.875MHz$, $f_{CLK} = 7.5MHz$ | 53.7 | 55 | | dB |
| | | $f_{IN} = 3.5MHz$, $f_{CLK} = 7.5MHz$ | 54.8 | | | |
| Signal-to-Noise Plus Distortion | SINAD | $f_{IN} = 1.875MHz$, $f_{CLK} = 7.5MHz$ | 53.6 | 54.9 | | dB |
| | | $f_{IN} = 3.5MHz$, $f_{CLK} = 7.5MHz$ | 54.7 | | | |
| Spurious-Free Dynamic Range | SFDR | $f_{IN} = 1.875MHz$, $f_{CLK} = 7.5MHz$ | 66 | 78 | | dBc |
| | | $f_{IN} = 3.5MHz$, $f_{CLK} = 7.5MHz$ | 70.1 | | | |
| Third-Harmonic Distortion | HD3 | $f_{IN} = 1.875MHz$, $f_{CLK} = 7.5MHz$ | | | -84 | dBc |
| | | $f_{IN} = 3.5MHz$, $f_{CLK} = 7.5MHz$ | | | -72.1 | |
| Intermodulation Distortion | IMD | $f_1 = 1.8MHz$, -7dBFS; $f_2 = 1MHz$, -7dBFS | | | -75.6 | dBc |
| Third-Order Intermodulation Distortion | IM3 | $f_1 = 1.8MHz$, -7dBFS; $f_2 = 1MHz$, -7dBFS | | | -78 | dBc |
| Total Harmonic Distortion | THD | $f_{IN} = 1.875MHz$, $f_{CLK} = 7.5MHz$ | -77.9 | -64 | | dBc |
| | | $f_{IN} = 3.5MHz$, $f_{CLK} = 7.5MHz$ | -71 | | | |
| Aperture Delay | | | 3.5 | | | ns |
| Overdrive Recovery Time | | 1.5x full-scale input | 2 | | | ns |
| Rx ADC INTERCHANNEL CHARACTERISTICS | | | | | | |
| Crosstalk Rejection | | $f_{INX,Y} = 1.875MHz$ at -0.5dBFS, $f_{INX,Y} = 1MHz$ at -0.5dBFS (Note 4) | | | -85 | dB |
| Amplitude Matching | | $f_{IN} = 1.875MHz$ at -0.5dBFS (Note 5) | | | ±0.02 | dB |
| Phase Matching | | $f_{IN} = 1.875MHz$ at -0.5dBFS (Note 5) | | | ±0.22 | Degrees |

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ELECTRICAL CHARACTERISTICS (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ (50% duty cycle), ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$. Typical values are at $T_A = +25^\circ C$, unless otherwise noted. $C_L < 5pF$ on all aux-DAC outputs.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|-----------|---|-------|------------|------|-------------------|
| Tx DAC DC ACCURACY | | | | | | |
| Resolution | N | | 10 | | | Bits |
| Integral Nonlinearity | INL | | | ± 0.45 | | LSB |
| Differential Nonlinearity | DNL | Guaranteed monotonic (Note 6) | | ± 0.26 | | LSB |
| Residual DC Offset | VOS | $T_A > +25^\circ C$ | -4 | ± 1 | +4 | mV |
| | | $T_A < +25^\circ C$ | -6.5 | ± 1 | +6.5 | |
| Full-Scale Gain Error | | Include reference error (peak-to-peak error) | -50 | | +50 | mV |
| TRANSMIT-PATH DYNAMIC PERFORMANCE | | | | | | |
| Corner Frequency | | 3dB corner | 1.1 | 1.27 | 1.5 | MHz |
| Passband Ripple | | DC to 640kHz (Note 6) | | 0.28 | 0.5 | dB _{P-P} |
| Group Delay Variation in Passband | | DC to 640kHz, guaranteed by design | | 50 | 100 | ns |
| Error-Vector Magnitude | EVM | DC to 700kHz | | 2 | | % |
| Stopband Rejection | | $f_{IMAGE} = 4.32MHz$, $f_{OUT} = 800kHz$, $f_{CLK} = 5.12MHz$ | 55 | | | dBc |
| Baseband Attenuation | | Spot relative to 100kHz | 2MHz | 20 | | dB |
| | | | 4MHz | 46.5 | | |
| | | | 5MHz | 54.7 | | |
| | | | 10MHz | 81 | | |
| | | | 20MHz | 88 | | |
| DAC Conversion Rate | f_{CLK} | (Note 2) | | | 7.5 | MHz |
| In-Band Noise Density | N_D | $f_{OUT} = 620kHz$, $f_{CLK} = 5.12MHz$, offset = 500kHz | | -121.7 | | dBc/Hz |
| Third-Order Intermodulation Distortion | IM3 | $f_1 = 620kHz$, $f_2 = 640kHz$ | | 76 | | dBc |
| Glitch Impulse | | | | 10 | | pV•s |
| Spurious-Free Dynamic Range to Nyquist | SFDR | $f_{CLK} = 7.5MHz$, $f_{OUT} = 620kHz$ | 60 | 76.5 | | dBc |
| Total Harmonic Distortion to Nyquist | THD | $f_{CLK} = 7.5MHz$, $f_{OUT} = 620kHz$ | | -74.8 | -59 | dB |
| Signal-to-Noise Ratio to Nyquist | SNR | $f_{CLK} = 7.5MHz$, $f_{OUT} = 620kHz$ | | 57.1 | | dB |

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ELECTRICAL CHARACTERISTICS (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ (50% duty cycle), ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$. Typical values are at $T_A = +25^\circ C$, unless otherwise noted. $C_L < 5pF$ on all aux-DAC outputs.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|-----------|--|------|------------|------|----------|
| TRANSMIT-PATH INTERCHANNEL CHARACTERISTICS | | | | | | |
| I-to-Q Output Isolation | | $f_{OUTX,Y} = 500kHz$, $f_{OUTX,Y} = 620kHz$ | | 85 | | dB |
| Gain Mismatch Between DAC Outputs | | Measured at DC | -0.3 | ± 0.05 | +0.3 | dB |
| Phase Mismatch Between DAC Outputs | | $f_{OUT} = 620kHz$, $f_{CLK} = 7.5MHz$ | | ± 0.16 | | Degrees |
| Differential Output Impedance | | | | 800 | | Ω |
| TRANSMIT-PATH ANALOG OUTPUT | | | | | | |
| Full-Scale Output Voltage (Table 6) | V_{FS} | Bit E7 = 0 (default) | | ± 410 | | mV |
| | | Bit E7 = 1 | | ± 500 | | |
| Output Common-Mode Voltage (Table 8) | | Bits CM1 = 0, CM0 = 0 (default) | 1.32 | 1.4 | 1.48 | V |
| | | Bits CM1 = 0, CM0 = 1 | | 1.25 | | |
| | | Bits CM1 = 1, CM0 = 0 | | 1.1 | | |
| | | Bits CM1 = 1, CM0 = 1 | | 0.9 | | |
| RECEIVE TRANSMIT-PATH INTERCHANNEL CHARACTERISTICS | | | | | | |
| Receive Transmit Isolation | | ADC $f_{INI} = f_{INQ} = 1.875MHz$, DAC $f_{OUTI} = f_{OUTQ} = 620kHz$, $f_{CLK} = 7.5MHz$ | | 85 | | dB |
| AUXILIARY DACs (DAC1, DAC2, DAC3) | | | | | | |
| Resolution | | (Note 6) | 12 | | | Bits |
| Integral Nonlinearity | INL | | | ± 1.25 | | LSB |
| Differential Nonlinearity | DNL | Guaranteed monotonic over codes 100 to 4000 (Note 6) | | ± 0.65 | | LSB |
| Gain Error | GE | $R_L > 200k\Omega$ | | ± 0.7 | | %FS |
| Zero-Code Error | | | | ± 0.6 | | %FS |
| Output-Voltage Low | V_{OL} | $R_L > 200k\Omega$ | | | 0.1 | V |
| Output-Voltage High | V_{OH} | $R_L > 200k\Omega$ | 2.56 | | | V |
| DC Output Impedance | | DC output at midscale | | 4 | | Ω |
| Settling Time | | From 1/4 FS to 3/4 FS | | 1 | | μs |
| Glitch Impulse | | From 0 to FS transition | | 24 | | nV•s |
| Rx ADC-Tx DAC TIMING CHARACTERISTICS | | | | | | |
| CLK Rise to Channel-I Output Data Valid | t_{DOI} | Figure 3 (Note 6) | | 6.9 | 10 | ns |
| CLK Fall to Channel-Q Output Data Valid | t_{DOQ} | Figure 3 (Note 6) | | 9.3 | 13 | ns |
| CLK Rise/Fall to DR Rise/Fall Time | t_{DR} | Figure 3 (Note 6) | | 8.5 | 12 | ns |
| I-DAC DATA to CLK Fall Setup Time | t_{DSI} | Figure 5 (Note 6) | 10 | | | ns |

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ELECTRICAL CHARACTERISTICS (continued)

(V_{DD} = 3V, OV_{DD} = 1.8V, internal reference (1.024V), C_L ≈ 10pF on all digital outputs, f_{CLK} = 7.5MHz (50% duty cycle), ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, C_{REFP} = C_{REFN} = C_{COM} = 0.33μF. Typical values are at T_A = +25°C, unless otherwise noted. C_L < 5pF on all aux-DAC outputs.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|-------------------------|--|-----|-----|-----|-------|
| Q-DAC DATA to CLK Rise Setup Time | t _{DSQ} | Figure 5 (Note 6) | 10 | | | ns |
| CLK Fall to I-DAC Data Hold Time | t _{DHI} | Figure 5 (Note 6) | 0 | | | ns |
| CLK Rise to Q-DAC Data Hold Time | t _{DHQ} | Figure 5 (Note 6) | 0 | | | ns |
| CLK Duty Cycle | | | | 50 | | % |
| CLK Duty-Cycle Variation | | | | ±15 | | % |
| Digital Output Rise/Fall Time | | 20% to 80% | | 2.3 | | ns |
| SERIAL-INTERFACE TIMING CHARACTERISTICS (Figure 6, Note 6) | | | | | | |
| Falling Edge of \overline{CS} to Rising Edge of First SCLK Time | t _{CSS} | | 10 | | | ns |
| DIN to SCLK Setup Time | t _{DS} | | 10 | | | ns |
| DIN to SCLK Hold Time | t _{DH} | | 0 | | | ns |
| SCLK Pulse-Width High | t _{CH} | | 25 | | | ns |
| SCLK Pulse-Width Low | t _{CL} | | 25 | | | ns |
| SCLK Period | t _{CP} | | 50 | | | ns |
| SCLK to \overline{CS} Setup Time | t _{CS} | | 10 | | | ns |
| \overline{CS} High Pulse Width | t _{CSW} | | 80 | | | ns |
| MODE-RECOVERY TIMING CHARACTERISTICS (Figure 7) | | | | | | |
| Shutdown Wake-Up Time | t _{WAKE,SD} | From shutdown to Rx mode, ADC settles to within 1dB SINAD | 75 | | | μs |
| | | From shutdown to Tx mode, DAC settles to within 10 LSB error | 25 | | | |
| Idle Wake-Up Time (With CLK) | t _{WAKE,ST0} | From idle to Rx mode with CLK present during idle, ADC settles to within 1dB SINAD | 7.3 | | | μs |
| | | From idle to Tx mode with CLK present during idle, DAC settles to 10 LSB error | 5 | | | |
| Standby Wake-Up Time | t _{WAKE,ST1} | From standby to Rx mode, ADC settles to within 1dB SINAD | 7.3 | | | μs |
| | | From standby to Tx mode, DAC settles to 10 LSB error | 25 | | | |
| Enable Time from Tx to Rx, (Ext2-Tx to Ext2-Rx, Ext4-Tx to Ext4-Rx, and SPI4-Tx to SPI3-Rx Modes) | t _{ENABLE, RX} | ADC settles to within 1dB SINAD | | 500 | | ns |
| Enable Time from Rx to Tx, (Ext1-Rx to Ext1-Tx, Ext4-Rx to Ext4-Tx, and SPI3-Rx to SPI4-Tx Modes) | t _{ENABLE, TX} | DAC settles to within 10 LSB error | | 1 | | μs |

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ELECTRICAL CHARACTERISTICS (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ (50% duty cycle), ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$. Typical values are at $T_A = +25^\circ C$, unless otherwise noted. $C_L < 5pF$ on all aux-DAC outputs.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|------------------|---|---------------------|----------------------|----------------------|-----------------|
| Enable Time from Tx to Rx, (Ext1-Tx to Ext1-Rx, Ext3-Tx to Ext3-Rx, and SPI2-Tx to SPI1-Rx Modes) | $t_{ENABLE, RX}$ | ADC settles to within 1dB SINAD | | 7.3 | | μs |
| Enable Time from Rx to Tx, (Ext2-Rx to Ext2-Tx, Ext3-Rx to Ext3-Tx, and SPI1-Rx to SPI2-Tx Modes) | $t_{ENABLE, TX}$ | DAC settles to within 10 LSB error | | 5 | | μs |
| INTERNAL REFERENCE (REFIN = VDD; VREFP, VREFN, VCOM levels are generated internally) | | | | | | |
| Positive Reference | | $V_{REFP} - V_{COM}$ | | 0.256 | | V |
| Negative Reference | | $V_{REFN} - V_{COM}$ | | -0.256 | | V |
| Common-Mode Output Voltage | V_{COM} | | $V_{DD} / 2 - 0.15$ | $V_{DD} / 2$ | $V_{DD} / 2 + 0.15$ | V |
| Maximum REFP/REFN/COM Source Current | I_{SOURCE} | | | 2 | | mA |
| Maximum REFP/REFN/COM Sink Current | I_{SINK} | | | 2 | | mA |
| Differential Reference Output | V_{REF} | $V_{REFP} - V_{REFN}$ | +0.490 | +0.512 | +0.534 | V |
| Differential Reference Temperature Coefficient | $REFTC$ | | | ± 10 | | ppm/ $^\circ C$ |
| BUFFERED EXTERNAL REFERENCE (external REFIN = 1.024V applied; VREFP, VREFN, VCOM levels are generated internally) | | | | | | |
| Reference Input Voltage | V_{REFIN} | | | 1.024 | | V |
| Differential Reference Output | V_{DIFF} | $V_{REFP} - V_{REFN}$ | | 0.512 | | V |
| Common-Mode Output Voltage | V_{COM} | | | $V_{DD} / 2$ | | V |
| Maximum REFP/REFN/COM Source Current | I_{SOURCE} | | | 2 | | mA |
| Maximum REFP/REFN/COM Sink Current | I_{SINK} | | | 2 | | mA |
| REFIN Input Current | | | | -0.7 | | μA |
| REFIN Input Resistance | | | | 500 | | k Ω |
| DIGITAL INPUTS (CLK, SCLK, DIN, \overline{CS}, D0–D9, T/R, \overline{SHDN}) | | | | | | |
| Input High Threshold | V_{INH} | D0–D9, CLK, SCLK, DIN, \overline{CS} , T/R, \overline{SHDN} | | $0.7 \times OV_{DD}$ | | V |
| Input Low Threshold | V_{INL} | D0–D9, CLK, SCLK, DIN, \overline{CS} , T/R, \overline{SHDN} | | | $0.3 \times OV_{DD}$ | V |
| Input Leakage | D_{IN} | D0–D9, CLK, SCLK, DIN, \overline{CS} , T/R, $\overline{SHDN} = OGND$ or OV_{DD} | | -1 | +1 | μA |
| Input Capacitance | DC_{IN} | | | 5 | | pF |

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ELECTRICAL CHARACTERISTICS (continued)

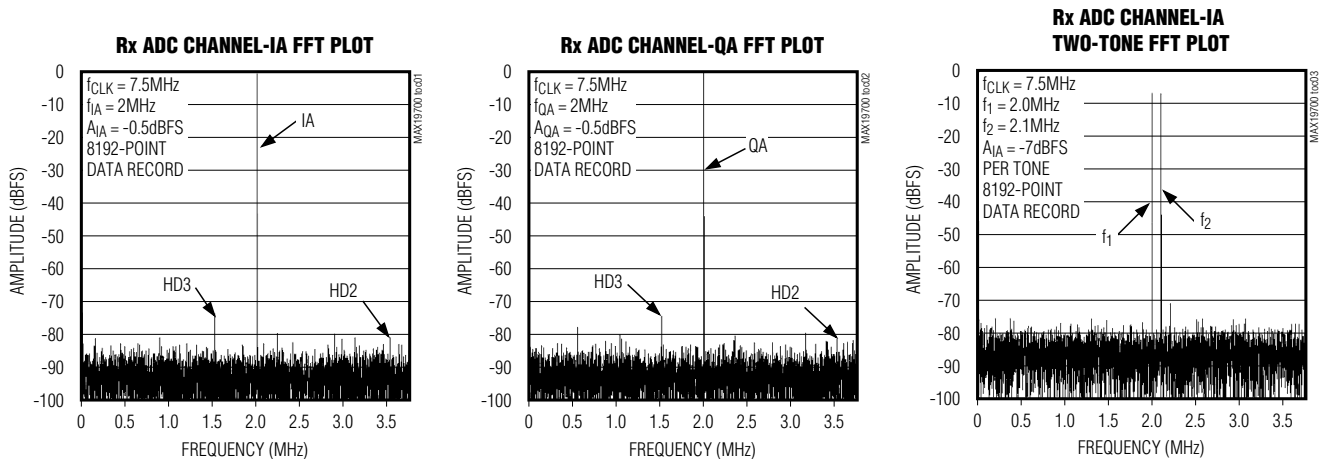
($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ (50% duty cycle), ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$. Typical values are at $T_A = +25^\circ C$, unless otherwise noted. $C_L < 5pF$ on all aux-DAC outputs.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------------|------------|-------------------------|----------------------|-----|----------------------|---------|
| DIGITAL OUTPUTS (D0–D9, DR) | | | | | | |
| Output-Voltage Low | V_{OL} | $I_{SINK} = 200\mu A$ | | | $0.2 \times OV_{DD}$ | V |
| Output-Voltage High | V_{OH} | $I_{SOURCE} = 200\mu A$ | $0.8 \times OV_{DD}$ | | | V |
| Tri-State Leakage Current | I_{LEAK} | | -1 | | +1 | μA |
| Tri-State Output Capacitance | C_{OUT} | | | 5 | | pF |

- Note 1:** Specifications from $T_A = +25^\circ C$ to $+85^\circ C$ are guaranteed by production tests. Specifications from $T_A = +25^\circ C$ to $-40^\circ C$ are guaranteed by design and characterization.
- Note 2:** The minimum clock frequency for the MAX19700 is 2MHz.
- Note 3:** SNR, SINAD, SFDR, HD3, and THD are based on a differential analog input voltage of -0.5dBFS referenced to the amplitude of the digital outputs. SINAD and THD are calculated using HD2 through HD6.
- Note 4:** Crosstalk rejection is measured by applying a high-frequency test tone to one channel and a low-frequency tone to the second channel. FFTs are performed on each channel. The parameter is specified as the power ratio of the first and second channel FFT test tone.
- Note 5:** Amplitude and phase matching is measured by applying the same signal to each channel, and comparing the two output signals using a sine-wave fit.
- Note 6:** Guaranteed by design and characterization.

Typical Operating Characteristics

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ 50% duty cycle, ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$, $T_A = +25^\circ C$, unless otherwise noted.)

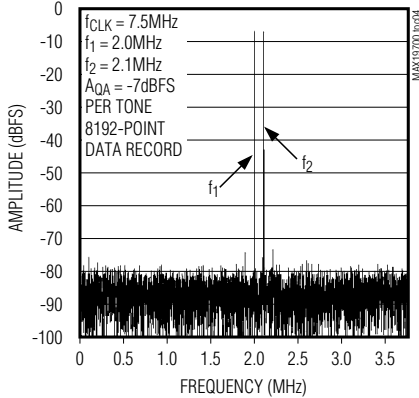


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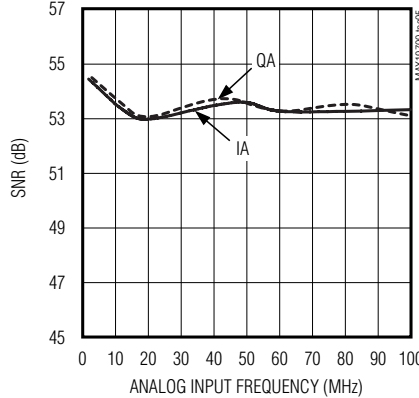
Typical Operating Characteristics (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ 50% duty cycle, ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$, $T_A = +25^\circ C$, unless otherwise noted.)

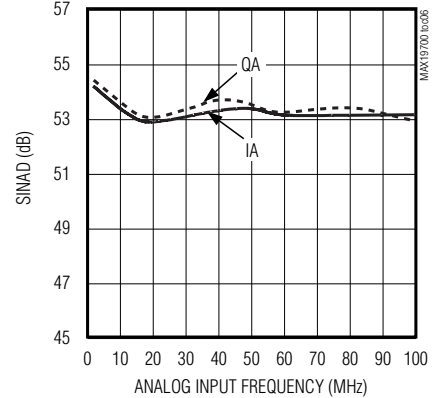
Rx ADC CHANNEL-QA TWO-TONE FFT PLOT



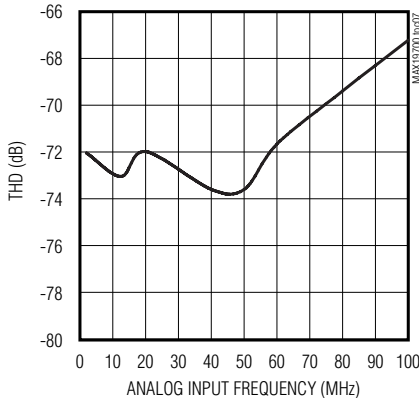
Rx ADC SIGNAL-TO-NOISE RATIO vs. ANALOG INPUT FREQUENCY



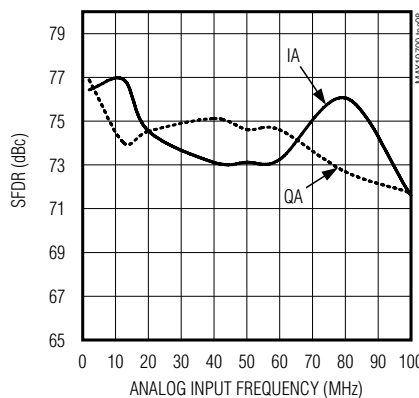
Rx ADC SIGNAL-TO-NOISE AND DISTORTION RATIO vs. ANALOG INPUT FREQUENCY



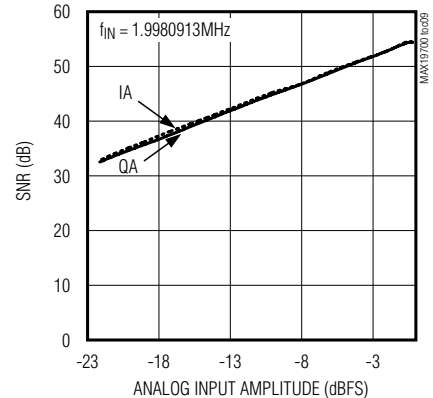
Rx ADC TOTAL HARMONIC DISTORTION vs. ANALOG INPUT FREQUENCY



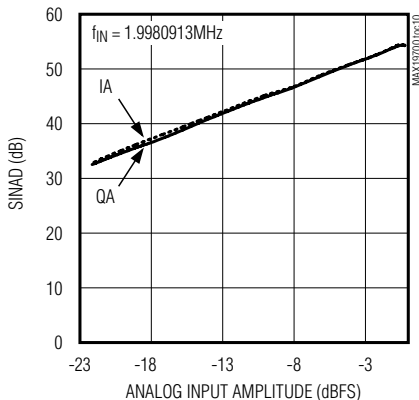
Rx ADC SPURIOUS-FREE DYNAMIC RANGE vs. ANALOG INPUT FREQUENCY



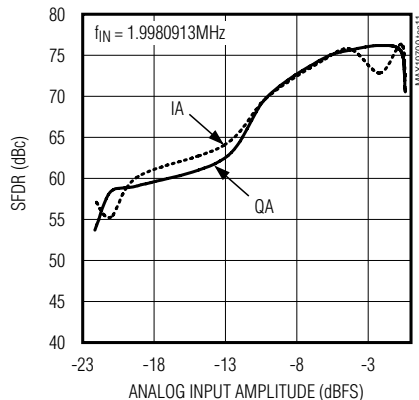
Rx ADC SIGNAL-TO-NOISE RATIO vs. ANALOG INPUT AMPLITUDE



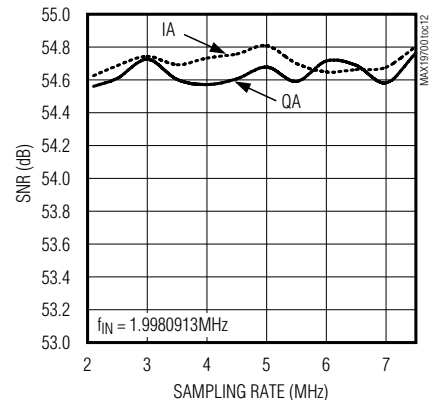
Rx ADC SIGNAL-TO-NOISE AND DISTORTION RATIO vs. ANALOG INPUT AMPLITUDE



Rx ADC SPURIOUS-FREE DYNAMIC RANGE vs. ANALOG INPUT AMPLITUDE



Rx ADC SIGNAL-TO-NOISE RATIO vs. SAMPLING RATE



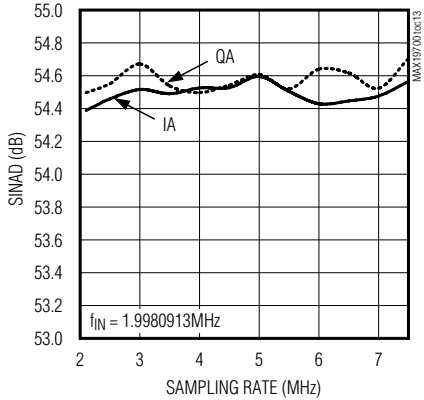
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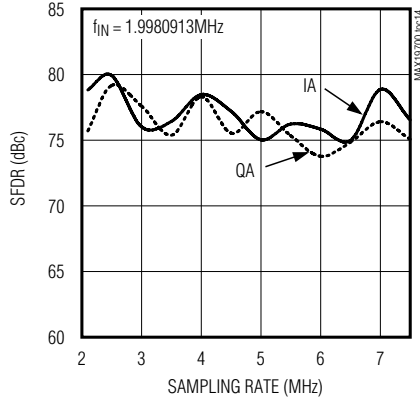
Typical Operating Characteristics (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ 50% duty cycle, ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$, $T_A = +25^\circ C$, unless otherwise noted.)

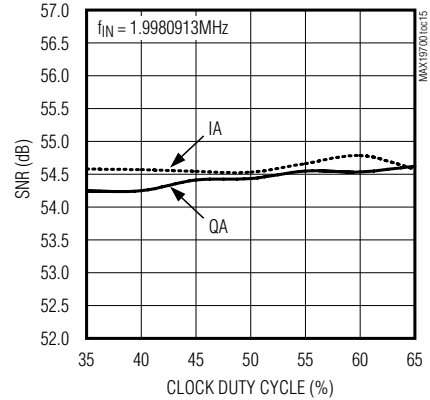
Rx ADC SIGNAL-TO-NOISE AND DISTORTION RATIO vs. SAMPLING RATE



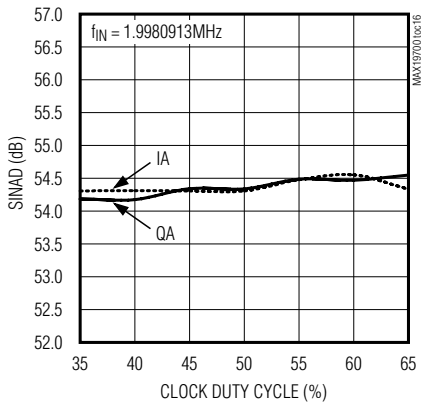
Rx ADC SPURIOUS-FREE DYNAMIC RANGE vs. SAMPLING RATE



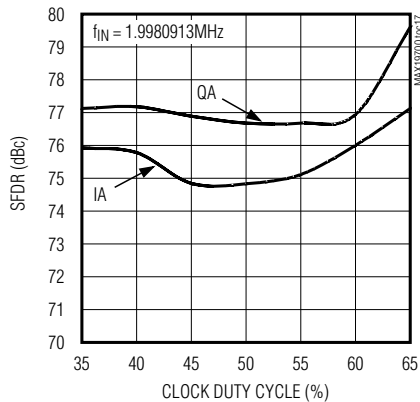
Rx ADC SIGNAL-TO-NOISE RATIO vs. CLOCK DUTY CYCLE



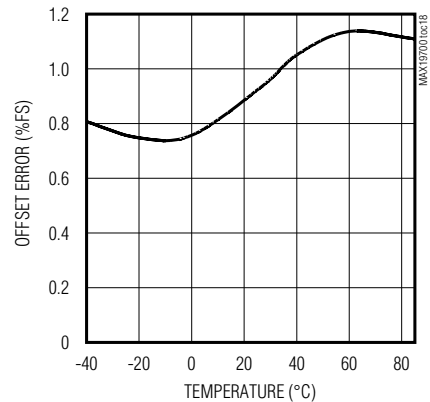
Rx ADC SIGNAL-TO-NOISE AND DISTORTION RATIO vs. CLOCK DUTY CYCLE



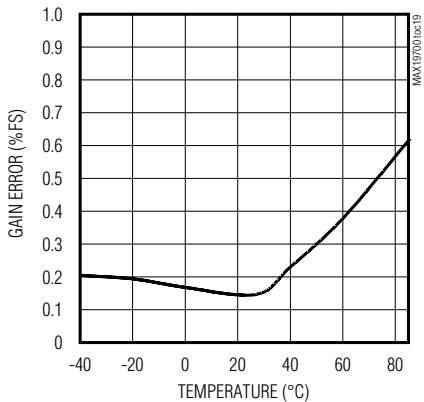
Rx ADC SPURIOUS-FREE DYNAMIC RANGE vs. CLOCK DUTY CYCLE



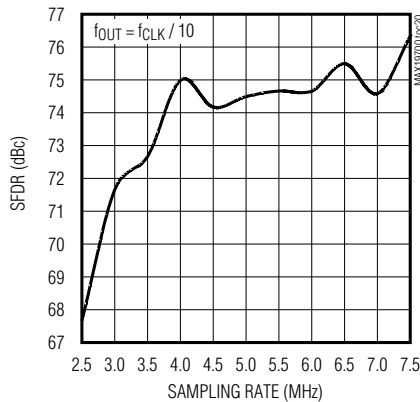
Rx ADC OFFSET ERROR vs. TEMPERATURE



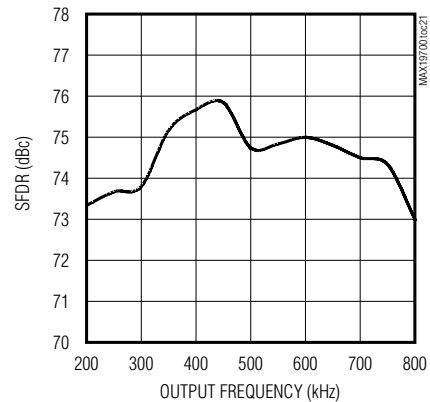
Rx ADC GAIN ERROR vs. TEMPERATURE



Tx PATH SPURIOUS-FREE DYNAMIC RANGE vs. SAMPLING RATE



Tx PATH SPURIOUS-FREE DYNAMIC RANGE vs. OUTPUT FREQUENCY

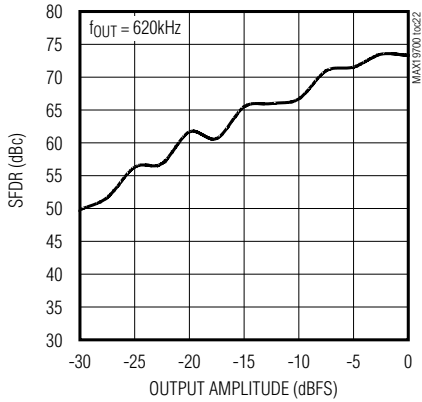


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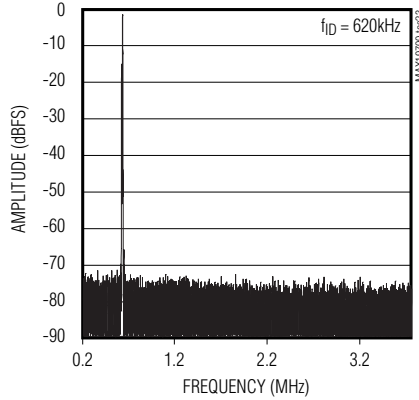
Typical Operating Characteristics (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ 50% duty cycle, ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$, $T_A = +25^\circ C$, unless otherwise noted.)

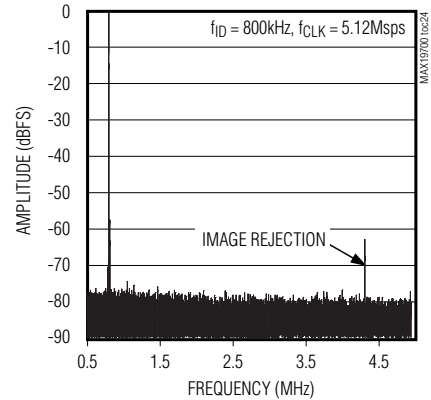
Tx PATH SPURIOUS-FREE DYNAMIC RANGE vs. OUTPUT AMPLITUDE



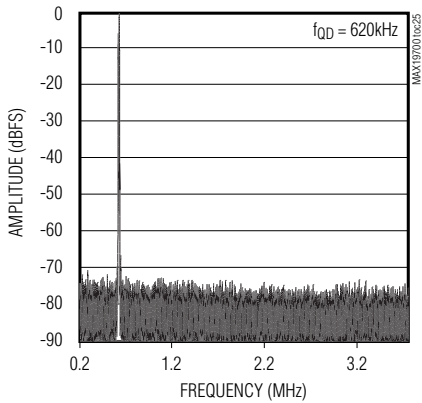
Tx PATH CHANNEL-ID SPECTRAL PLOT



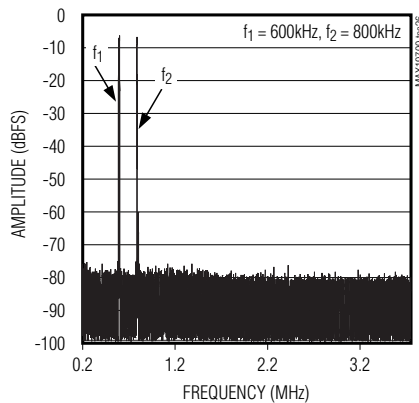
Tx PATH CHANNEL-ID SPECTRAL PLOT WITH IMAGE REJECTION



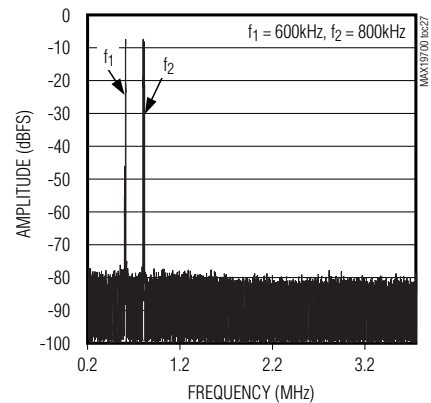
Tx PATH CHANNEL-QD SPECTRAL PLOT



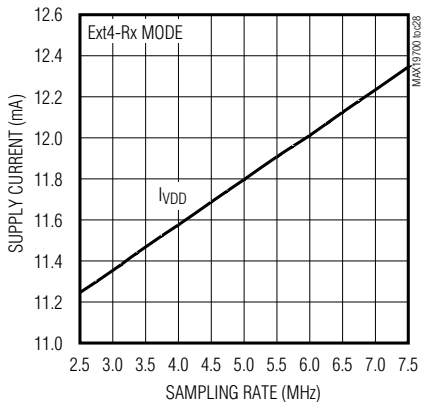
Tx PATH CHANNEL-ID TWO-TONE SPECTRAL PLOT



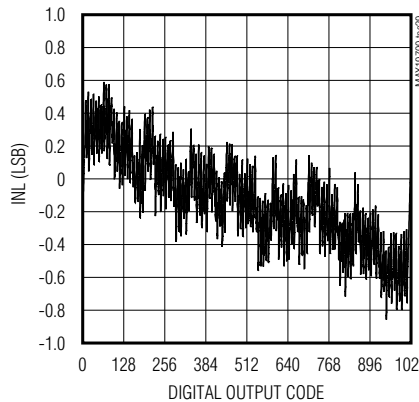
Tx PATH CHANNEL-QD TWO-TONE SPECTRAL PLOT



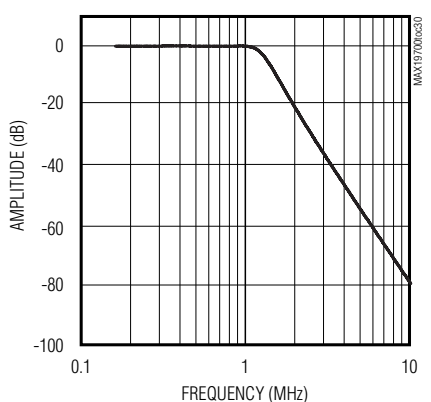
SUPPLY CURRENT vs. SAMPLING RATE



Rx ADC INTEGRAL NONLINEARITY



TRANSMIT FILTER FREQUENCY RESPONSE

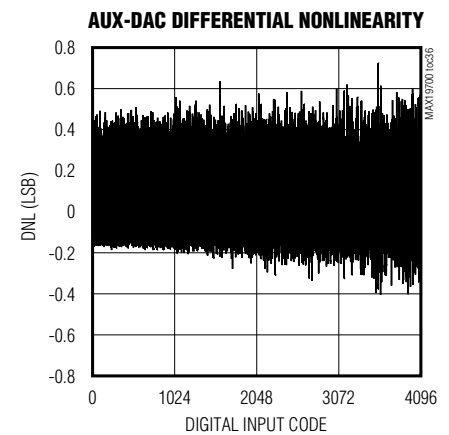
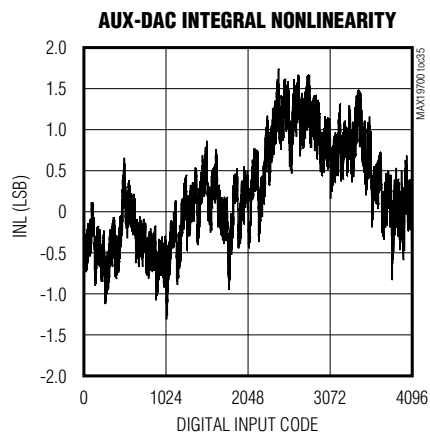
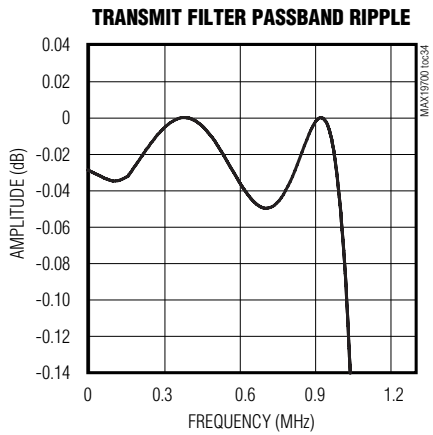
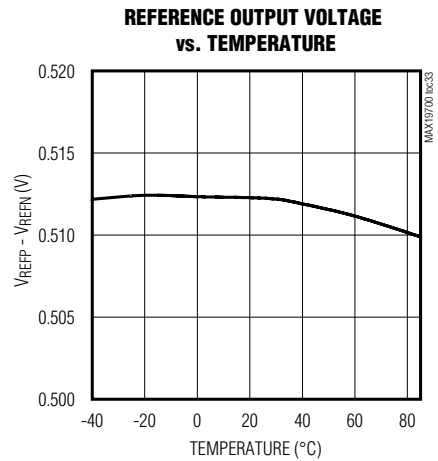
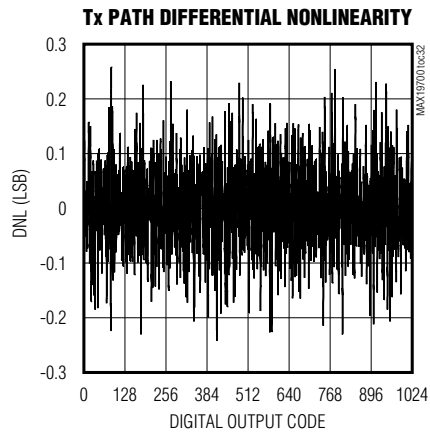
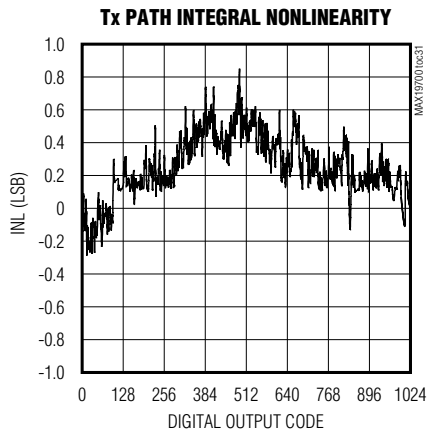


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Typical Operating Characteristics (continued)

($V_{DD} = 3V$, $OV_{DD} = 1.8V$, internal reference (1.024V), $C_L \approx 10pF$ on all digital outputs, $f_{CLK} = 7.5MHz$ 50% duty cycle, ADC input amplitude = -0.5dBFS, DAC output amplitude = 0dBFS, differential ADC input, differential DAC output, $C_{REFP} = C_{REFN} = C_{COM} = 0.33\mu F$, $T_A = +25^\circ C$, unless otherwise noted.)



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Pin Description

| PIN | NAME | FUNCTION |
|-------------------------|--------------------------|--|
| 1 | REFP | Upper Reference Voltage. Bypass with a 0.33 μ F capacitor to GND as close to REFP as possible. |
| 2, 8, 11, 31, 33, 39 43 | V _{DD} | Analog Supply Voltage. Bypass V _{DD} to GND with a combination of a 2.2 μ F capacitor in parallel with a 0.1 μ F capacitor. |
| 3 | IAP | Channel IA Positive Analog Input. For single-ended operation, connect signal source to IAP. |
| 4 | IAN | Channel IA Negative Analog Input. For single-ended operation, connect IAN to COM. |
| 5, 7, 12, 32, 42 | GND | Analog Ground. Connect all GND pins to ground plane. |
| 6 | CLK | Conversion Clock Input. Clock signal for both receive ADCs and transmit DACs. |
| 9 | QAN | Channel QA Negative Analog Input. For single-ended operation, connect QAN to COM. |
| 10 | QAP | Channel QA Positive Analog Input. For single-ended operation, connect signal source to QAP. |
| 13–18, 21–24 | D0–D9 | Digital I/O. Outputs for receive ADC in Rx mode. Inputs for transmit DAC in Tx mode. D9 is the most significant bit (MSB) and D0 is the least significant bit (LSB). |
| 19 | OGND | Output-Driver Ground |
| 20 | OV _{DD} | Output-Driver Power Supply. Supply range from +1.8V to V _{DD} to accommodate most logic levels. Bypass OV _{DD} to OGND with a combination of a 2.2 μ F capacitor in parallel with a 0.1 μ F capacitor. |
| 25 | $\overline{\text{SHDN}}$ | Active-Low Shutdown Input. Apply logic-low to place the MAX19700 in shutdown. |
| 26 | DR | Data-Ready Indicator. This digital output indicates channel I data (DR = 1) or channel Q data (DR = 0) is present on the output. |
| 27 | T/ $\overline{\text{R}}$ | Transmit- or Receive-Mode Select Input. T/ $\overline{\text{R}}$ logic-low input sets the device in receive mode. A logic-high input sets the device in transmit mode. |
| 28 | DIN | 3-Wire Serial-Interface Data Input. Data is latched on the rising edge of the SCLK. |
| 29 | SCLK | 3-Wire Serial-Interface Clock Input |
| 30 | $\overline{\text{CS}}$ | 3-Wire Serial-Interface Chip-Select Input. Logic-low enables the serial interface. |
| 34, 35 | N.C. | No Connection |
| 36 | DAC3 | Analog Output for Auxiliary DAC3 |
| 37 | DAC2 | Analog Output for Auxiliary DAC2 |
| 38 | DAC1 | Analog Output for Auxiliary DAC1 (AFC DAC, V _{OUT} = 1.1V During Power-Up) |
| 40, 41 | IDN, IDP | DAC Channel-ID Differential Voltage Output |
| 44, 45 | QDN, QDP | DAC Channel-QD Differential Voltage Output |
| 46 | REFIN | Reference Input. Connect to V _{DD} for internal reference. |
| 47 | COM | Common-Mode Voltage I/O. Bypass COM to GND with a 0.33 μ F capacitor. |
| 48 | REFN | Negative Reference I/O. Conversion range is $\pm(V_{\text{REFP}} - V_{\text{REFN}})$. Bypass REFN to GND with a 0.33 μ F capacitor. |
| — | EP | Exposed Paddle. Exposed paddle is internally connected to GND. Connect EP to the GND plane. |

Detailed Description

The MAX19700 integrates a dual 10-bit Rx ADC and a dual 10-bit Tx DAC with TD-SCDMA baseband filters while providing ultra-low power and high dynamic performance at a 7.5Msps conversion rate. The Rx ADC analog input amplifiers are fully differential and accept 1V_{p-p} full-scale signals. The Tx DAC analog outputs are fully differential with ± 410 mV full-scale output, selectable common-mode range and offset adjust.

The MAX19700 includes a 3-wire serial interface to control operating modes and power management. The serial interface is SPI™ and MICROWIRE™ compatible. The MAX19700 serial interface selects shutdown, idle, standby, transmit (Tx), and receive (Rx) modes.

SPI is a trademark of Motorola, Inc.

MICROWIRE is a trademark of National Semiconductor Corp.

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Table 1. Output Codes vs. Input Voltage

| DIFFERENTIAL INPUT VOLTAGE | DIFFERENTIAL INPUT (LSB) | OFFSET BINARY (D0–D9) | OUTPUT DECIMAL CODE |
|----------------------------|----------------------------|-----------------------|---------------------|
| $V_{REF} \times 512/512$ | 511 (+Full Scale – 1 LSB) | 11 1111 1111 | 1023 |
| $V_{REF} \times 511/512$ | 510 (+Full Scale – 2 LSB) | 11 1111 1110 | 1022 |
| $V_{REF} \times 1/512$ | +1 | 10 0000 0001 | 513 |
| $V_{REF} \times 0/512$ | 0 (Bipolar Zero) | 10 0000 0000 | 512 |
| $-V_{REF} \times 1/512$ | -1 | 01 1111 1111 | 511 |
| $-V_{REF} \times 511/512$ | -511 (-Full Scale + 1 LSB) | 00 0000 0001 | 1 |
| $-V_{REF} \times 512/512$ | -512 (-Full Scale) | 00 0000 0000 | 0 |

and IAN, as well as QAP and QAN, and set the input signal common-mode voltage within the ADC range of $V_{DD}/2$ ($\pm 200\text{mV}$) for optimum performance.

ADC System Timing Requirements

Figure 3 shows the relationship between the clock, analog inputs, DR indicator, and the resulting output data. Channel I (CHI) and channel Q (CHQ) are sampled on the rising edge of the clock signal (CLK) and the resulting data is multiplexed at the D0–D9 outputs. CHI data is updated on the rising edge and CHQ data is updated on the falling edge of the CLK. The DR indicator follows CLK with a typical delay time of 8.5ns and remains high when CHI data is updated and low when CHQ data is updated. Including the delay through the output

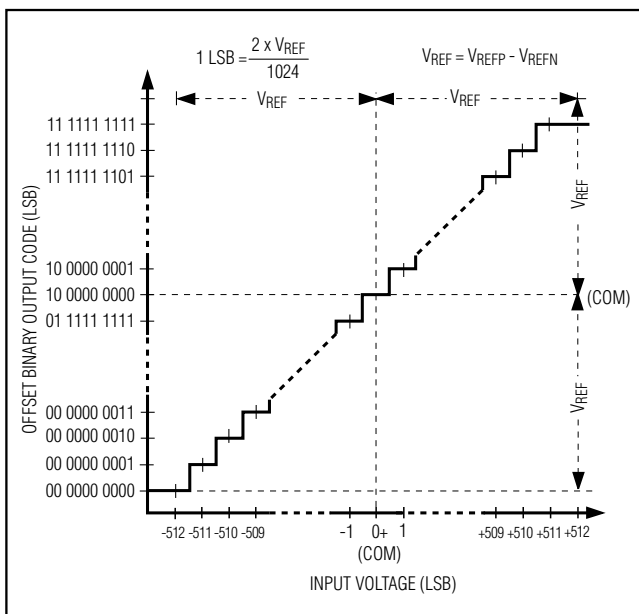


Figure 2. ADC Transfer Function

latch, the total clock-cycle latency is 5 clock cycles for CHI and 5.5 clock cycles for CHQ.

Digital Input/Output Data (D0–D9)

D0–D9 are the Rx ADC digital logic outputs when the MAX19700 is in receive mode. This bus is shared with the Tx DAC digital logic inputs and operates in half-duplex mode. D0–D9 are the Tx DAC digital logic inputs when the MAX19700 is in transmit mode. The logic level is set by OV_{DD} from 1.8V to V_{DD} . The digital output coding is offset binary (Table 1). Keep the capacitive load on the digital outputs D0–D9 as low as possible ($< 15\text{pF}$) to avoid large digital currents feeding back into the analog portion of the MAX19700 and degrading its dynamic performance. Buffers on the digital outputs isolate the outputs from heavy capacitive loads. Adding 100Ω resistors in series with the digital outputs close to the MAX19700 will help improve ADC performance. See the MAX19700EVKIT schematic for an example of the digital outputs driving a digital buffer through 100Ω series resistors.

During SHDN, IDLE, and STBY states, the pins D0–D9 are internally pulled up to prevent floating digital inputs. To ensure no current flows through D0–D9 I/O, the external bus needs to be either tri-stated or pulled up to OV_{DD} and should not be pulled to ground.

Dual 10-Bit Tx DAC and Transmit Path

The dual 10-bit digital-to-analog converters (Tx DAC) operate with clock speeds up to 7.5MHz. The Tx DAC digital inputs, D0–D9, are multiplexed on a single 10-bit bus. The voltage reference determines the Tx path full-scale output voltage. See the *Reference Configurations* section for details on setting the reference voltage. Each Tx path channel integrates a lowpass filter tuned to meet the TD-SCDMA spectral mask requirements. The TD-SCDMA filters are tuned for 1.27MHz cutoff frequency and $> 55\text{dB}$ image rejection at $f_{IMAGE} = 4.32\text{MHz}$, $f_{OUT} = 800\text{kHz}$, and $f_{CLK} = 5.12\text{MHz}$. See Figure 4 for an illustration of the filter frequency response.

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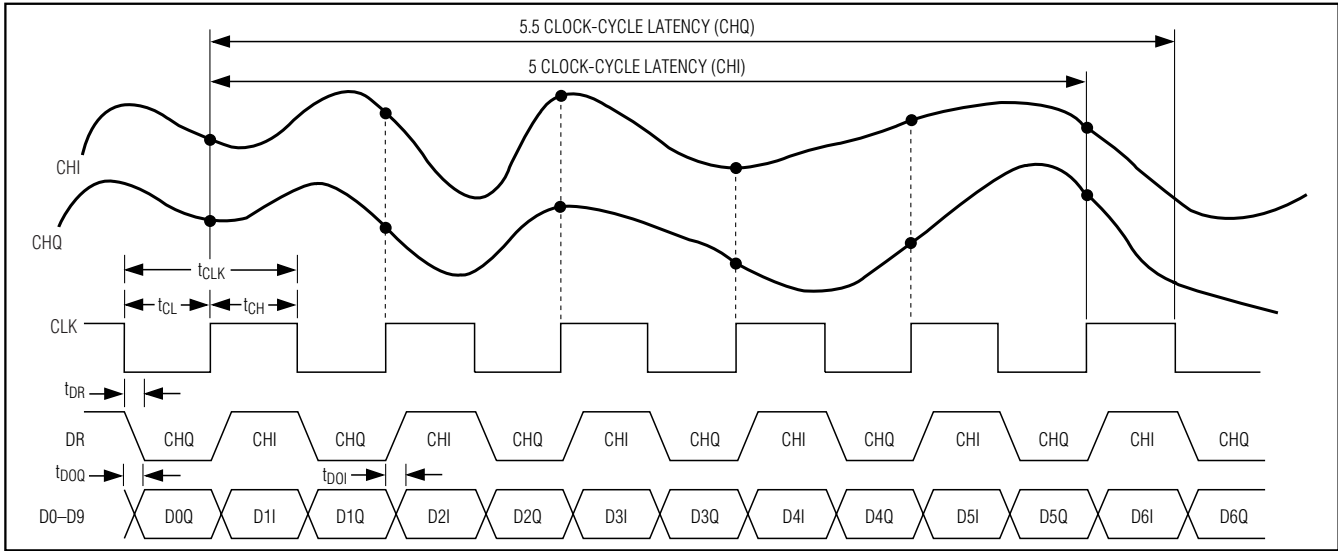


Figure 3. Rx ADC System Timing Diagram

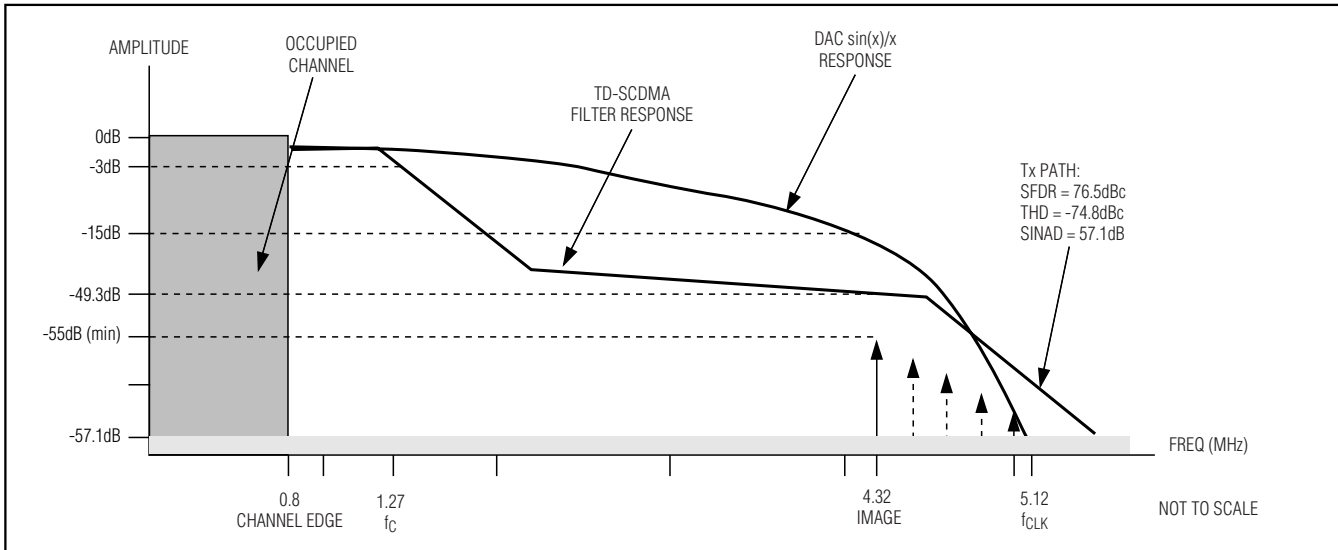


Figure 4. TD-SCDMA Filter Frequency Response

Buffer amplifiers follow the TD-SCDMA filters. The amplifier outputs are biased at an adjustable common-mode DC level and designed to drive a differential input stage with input impedance $\geq 70k\Omega$. This simplifies the analog interface between RF quadrature upconverters and the MAX19700. Many RF upconverters require a 0.9V to 1.5V common-mode bias. The SPI-controlled DC common-mode bias eliminates discrete level-setting resistors and code-generated level shifting while preserving the full dynamic range of each Tx DAC. Table 2

shows the Tx path output voltage vs. input codes. Table 10 shows the selection of DC common-mode levels.

The buffer amplifiers also feature a programmable full-scale output level of $\pm 410mV$ or $\pm 500mV$ and independent DC offset correction of each I/Q channel. Both features are configured through the SPI interface. The DC offset correction is used to optimize sideband and carrier suppression in the Tx signal path (see Tables 8 and 9).

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Table 2. Tx Path Output Voltage vs. Input Codes

(Internal Reference Mode $V_{REFDAC} = 1.024V$, External Reference Mode $V_{REFDAC} = V_{REFIN}$; $V_{FS} = 410mV$ for 820mVp-p Full Scale and $V_{FS} = 500mV$ for 1Vp-p Full Scale)

| DIFFERENTIAL OUTPUT VOLTAGE (V) | OFFSET BINARY (D0–D9) | INPUT DECIMAL CODE |
|--|-----------------------|--------------------|
| $(V_{FS}) \frac{V_{REFDAC}}{1024} \times \frac{1023}{1023}$ | 11 1111 1111 | 1023 |
| $(V_{FS}) \frac{V_{REFDAC}}{1024} \times \frac{1021}{1023}$ | 11 1111 1110 | 1022 |
| $(V_{FS}) \frac{V_{REFDAC}}{1024} \times \frac{3}{1023}$ | 10 0000 0001 | 513 |
| $(V_{FS}) \frac{V_{REFDAC}}{1024} \times \frac{1}{1023}$ | 10 0000 0000 | 512 |
| $(V_{FS}) \frac{-V_{REFDAC}}{1024} \times \frac{1}{1023}$ | 01 1111 1111 | 511 |
| $(V_{FS}) \frac{-V_{REFDAC}}{1024} \times \frac{1021}{1023}$ | 00 0000 0001 | 1 |
| $(V_{FS}) \frac{-V_{REFDAC}}{1024} \times \frac{1023}{1023}$ | 00 0000 0000 | 0 |

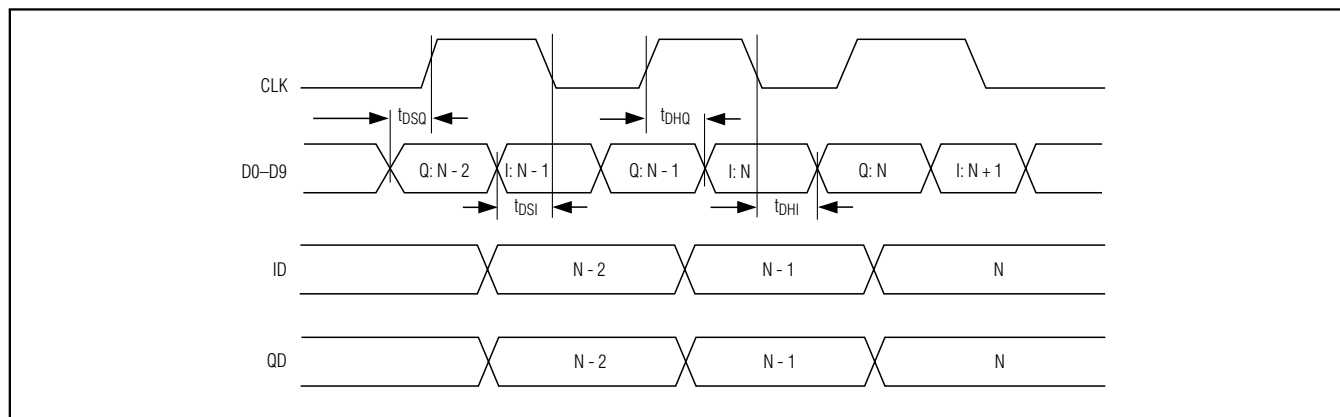


Figure 5. Tx DAC System Timing Diagram

Tx DAC Timing

Figure 5 shows the relationship between the clock, input data, and analog outputs. Data for the I-channel (ID) is latched on the falling edge of the clock signal, and Q-channel (QD) data is latched on the rising edge of the clock signal. Both I and Q outputs are simultaneously updated on the next rising edge of the clock signal.

3-Wire Serial Interface and Operation Modes

The 3-wire serial interface controls the MAX19700 operation modes as well as the three 12-bit aux-DACs. Upon power-up, program the MAX19700 to operate in the desired mode. Use the 3-wire serial interface to program the device for shutdown, idle, standby, Rx, Tx, or aux-DAC modes. A 16-bit data register sets the mode control. The 16-bit word is comprised of A3–A0 control bits and D11–D0 data bits. Tables 4, 5, and 6 show the MAX19700 operating modes and SPI commands. The serial interface remains active in all modes.

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SPI Register Description

The operating modes can be selected by programming the control bits, A3–A0, in the register as shown in Table 3. Modifying A3–A0 bits will select from ENABLE-16, Aux-DAC1, Aux-DAC2, Aux-DAC3, IOFFSET, QOFFSET, and COMSEL modes. ENABLE-16 is the default operating mode. This mode allows for shutdown, idle, and standby states as well as switching between FAST, SLOW, Rx, and Tx modes. Table 4 shows the MAX19700 power-management modes. Table 5 shows the T/R pin-controlled external Tx-Rx switching modes. Table 6 shows the SPI-controlled Tx-Rx switching modes.

In ENABLE-16 mode, the aux-DACs have independent control bits E6, E5, and E4, and the Tx-path full-scale output can be set with bit E7. Table 7 shows the auxiliary DAC enable codes and Table 8 shows the full-scale output selection. Bits E11 and E10 are reserved and need to be programmed to logic-low. Bits E9 and E8 are not used.

Modes Aux-DAC1, Aux-DAC2, and Aux-DAC3 select the aux-DAC channels named DAC1, DAC2, and DAC3 and hold the data inputs for each DAC. Bits $_D11\text{--}_D0$ are the data inputs for each aux-DAC and can be programmed through SPI. The MAX19700 also includes two 6-bit registers that can be programmed to correct the offsets for the Tx-path I and Q channels independently (see Table 9). Use the COMSEL mode to select the output common-mode voltage with bits CM1 and CM0 (see Table 10).

Shutdown mode offers the most dramatic power savings by shutting down all the analog sections of the MAX19700 and placing the Rx ADC digital outputs in tri-state mode. When the Rx ADC outputs transition from tri-state to active, the last converted word is placed on the digital outputs. The Tx DAC previously stored data is lost when coming out of shutdown mode. The wake-up time from shutdown mode is dominated by the time required to charge the capacitors at REFP, REFN, and COM. In internal reference mode and buffered external reference mode, the wake-up time is typically 75 μ s to enter Rx mode and 25 μ s to enter Tx mode.

In idle mode, the reference and clock distribution circuits are powered, but all other functions are off. The Rx ADC outputs are forced to tri-state. The wake-up time is 7.3 μ s to enter Rx mode and 5 μ s to enter Tx mode. When the Rx ADC outputs transition from tri-state to active, the last converted word is placed on the digital outputs.

In standby mode, the reference is powered, but the rest of the device functions are off. The wake-up time from standby mode is 7.3 μ s to enter Rx mode and 25 μ s to enter Tx mode. When the Rx ADC outputs transition from tri-state to active, the last converted word is placed on the digital outputs.

FAST and SLOW Rx and Tx Modes

In addition to the external Tx-Rx control, the MAX19700 also features SLOW and FAST modes for switching between Rx and Tx operation. In FAST Tx mode, the Rx ADC core is powered on but the ADC core digital outputs are tri-stated on the D0–D9 bus; likewise, in FAST Rx mode the transmit path (DAC core and Tx filter) is powered on but the DAC core digital inputs are tri-stated on the D0–D9 bus. The switching time between Tx to Rx or Rx to Tx is FAST because the converters are on and do not have to recover from a power-down state. In FAST mode, the switching time between Rx to Tx and Tx to Rx is 1 μ s. However, power consumption is higher in this mode because both the Tx and Rx cores are always on. To prevent bus contention in these states, the Rx ADC output buffers are tri-stated during Tx and the Tx DAC input bus is tri-stated during Rx.

In SLOW mode, the Rx ADC core is off during Tx; likewise the Tx DAC and filters are turned off during Rx to yield lower power consumption in these modes. For example, the power in SLOW Tx mode is 31.2mW. The power consumption during Rx is 21mW compared to power consumption in FAST mode of 38.4mW. However, the recovery time between states is increased. The switching time in SLOW mode between Rx to Tx is 5 μ s and Tx to Rx is 7.3 μ s.

External T/R Switching Control vs. Serial-Interface Control

Bit E3 in the ENABLE-16 register determines whether the device Tx-Rx mode is controlled externally through the T/R input (E3 = low) or through the SPI command (E3 = high). By default, the MAX19700 is in the external Tx-Rx control mode. In the external control mode, use the T/R input (pin 27) to switch between Rx and Tx modes. Using the T/R pin provides faster switching between Rx and Tx modes. To override the external Tx-Rx control, program the MAX19700 through the serial interface. During SHDN, IDLE, or STBY modes, the T/R input is overridden. To restore external Tx-Rx control, program bit E3 low and exit the SHDN, IDLE, or STBY modes through the serial interface.

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SPI Timing

The serial digital interface is a standard 3-wire connection compatible with SPI/QSPI™/MICROWIRE/DSP interfaces. Set \overline{CS} low to enable the serial data loading at DIN. Following a \overline{CS} high-to-low transition, data is shifted synchronously, most significant bit first, on the rising edge of the serial clock (SCLK). After 16 bits are loaded into the serial input register, data is transferred to the latch when \overline{CS} transitions high. \overline{CS} must transition high for a minimum of 80ns before the next write sequence. The SCLK can idle either high or low between transitions. Figure 6 shows the detailed timing diagram of the 3-wire serial interface.

QSPI is a trademark of Motorola, Inc.

Mode-Recovery Timing

Figure 7 shows the mode-recovery timing diagram. t_{WAKE} is the wakeup time when exiting shutdown, idle, or standby mode and entering Rx or Tx mode. t_{ENABLE} is the recovery time when switching between either Rx or Tx mode. t_{WAKE} or t_{ENABLE} is the time for the Rx ADC to settle within 1dB of specified SINAD performance and Tx DAC settling to 10 LSB error. t_{WAKE} and t_{ENABLE} times are measured after either the 16-bit serial command is latched into the MAX19700 by a \overline{CS} transition high (SPI controlled) or a T/\overline{R} logic transition (external Tx-Rx control). In FAST mode, the recovery time is 1 μ s to switch between Tx or Rx modes.

Table 3. MAX19700 Mode Control

| REGISTER NAME | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | A3 | A2 | A1 | A0 |
|---------------|---------------------|---------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|----|
| | (MSB) | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
| ENABLE-16 | E11 = 0 Reserved | E10 = 0 Reserved | — | — | E7 | E6 | E5 | E4 | E3 | E2 | E1 | E0 | 0 | 0 | 0 | 0 |
| Aux-DAC1 | 1D11 | 1D10 | 1D9 | 1D8 | 1D7 | 1D6 | 1D5 | 1D4 | 1D3 | 1D2 | 1D1 | 1D0 | 0 | 0 | 0 | 1 |
| Aux-DAC2 | 2D11 | 2D10 | 2D9 | 2D8 | 2D7 | 2D6 | 2D5 | 2D4 | 2D3 | 2D2 | 2D1 | 2D0 | 0 | 0 | 1 | 0 |
| Aux-DAC3 | 3D11 | 3D10 | 3D9 | 3D8 | 3D7 | 3D6 | 3D5 | 3D4 | 3D3 | 3D2 | 3D1 | 3D0 | 0 | 0 | 1 | 1 |
| IOFFSET | — | — | — | — | — | — | IO5 | IO4 | IO3 | IO2 | IO1 | IO0 | 0 | 1 | 0 | 0 |
| QOFFSET | — | — | — | — | — | — | QO5 | QO4 | QO3 | QO2 | QO1 | QO0 | 0 | 1 | 0 | 1 |
| COMSEL | — | — | — | — | — | — | — | — | — | — | CM1 | CM0 | 0 | 1 | 1 | 0 |

Table 4. Power-Management Modes

| ADDRESS | | | | DATA BITS | | | | T/ \overline{R} | MODE | FUNCTION (POWER MANAGEMENT) | DESCRIPTION | COMMENT |
|---------|----|----|----|-----------|----|----|----|-------------------|------|-----------------------------|---|---|
| A3 | A2 | A1 | A0 | E3 | E2 | E1 | E0 | PIN 27 | | | | |
| 0000 | | | | X000 | | | | X | SHDN | SHUTDOWN | Rx ADC = OFF Tx DAC = OFF Aux-DAC = OFF REF = OFF | Device is in complete shutdown Overrides T/ \overline{R} pin |
| | | | | X001 | | | | X | IDLE | IDLE | Rx ADC = OFF Tx DAC = OFF Aux-DAC = Last State CLK = ON REF = ON | Fast turn-on time Moderate idle power Overrides T/ \overline{R} pin |
| | | | | X010 | | | | X | STBY | STANDBY | Rx ADC = OFF Tx DAC = OFF Aux-DAC = Last State CLK = OFF REF = ON | Slow turn-on time Low standby power Overrides T/ \overline{R} pin |

X = Don't care.

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Table 5. External Tx-Rx Control Using T/R Pin (T/R = 0 = Rx Mode, T/R = 1 = Tx Mode)

| ADDRESS | | | | DATA BITS | | | | T/R | STATE | FUNCTION Rx TO Tx-Tx TO Rx SWITCHING SPEED | DESCRIPTION | COMMENT | | | | |
|---------|----|----|----|-----------|----|----|----|--------|---------|--|-------------|---|--|-----------|---------|---|
| A3 | A2 | A1 | A0 | E3 | E2 | E1 | E0 | PIN 27 | | | | | | | | |
| 0000 | | | | 0011 | | | | 0 | Ext1-Rx | FAST-SLOW | Rx Mode | Moderate Power Fast Rx to Tx when T/R transitions 0 to 1 | | | | |
| | | | | | | | | 1 | Ext1-Tx | | Tx Mode | | Low Power Slow Tx to Rx when T/R transitions 1 to 0 | | | |
| | | | | 0100 | | | | 0100 | | | | 0 | Ext2-Rx (Default) | SLOW-FAST | Rx Mode | Low Power Slow Rx to Tx when T/R transitions 0 to 1 |
| | | | | | | | | | | | | 1 | Ext2-Tx | | Tx Mode | |
| | | | | 0101 | | | | 0101 | | | | 0 | Ext3-Rx | SLOW-SLOW | Rx Mode | Low Power Slow Rx to Tx when T/R transitions 0 to 1 |
| | | | | | | | | | | | | 1 | Ext3-Tx | | Tx Mode | |
| | | | | 0110 | | | | 0110 | | | | 0 | Ext4-Rx | FAST-FAST | Rx Mode | Moderate Power Fast Rx to Tx when T/R transitions 0 to 1 |
| | | | | | | | | | | | | 1 | Ext4-Tx | | Tx Mode | |

System Clock Input (CLK)

Both the Rx ADC and Tx DAC share the CLK input. The CLK input accepts a CMOS-compatible signal level set by OV_{DD} from 1.8V to V_{DD} . Since the interstage conversion of the device depends on the repeatability of

the rising and falling edges of the external clock, use a clock with low jitter and fast rise and fall times (<2ns). Specifically, sampling occurs on the rising edge of the clock signal, requiring this edge to provide the lowest

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Table 6. Tx-Rx Control Using SPI Commands

| ADDRESS | | | | DATA BITS | | | | T/R | MODE | FUNCTION (Tx-Rx SWITCHING SPEED) | DESCRIPTION | COMMENTS |
|---------|----|----|----|-----------|----|----|----|--------|---------|-------------------------------------|---|---|
| A3 | A2 | A1 | A0 | E3 | E2 | E1 | E0 | PIN 27 | | | | |
| 0000 | | | | 1 | 0 | 1 | 1 | X | SPI1-Rx | SLOW | Rx Mode Rx ADC = ON Tx DAC = OFF Rx Bus = Enable | Low Power Slow Rx to Tx through SPI command |
| | | | | 1 | 1 | 0 | 0 | X | SPI2-Tx | SLOW | Tx Mode Rx ADC = OFF Tx DAC = ON Tx Bus = Enable | Low Power Slow Tx to Rx through SPI command |
| | | | | 1 | 0 | 1 | 0 | X | SPI3-Rx | FAST | Rx Mode Rx ADC = ON Tx DAC = ON Rx Bus = Enabled | Moderate Power Fast Rx to Tx through SPI command |
| | | | | 1 | 1 | 0 | 1 | X | SPI4-Tx | FAST | Tx Mode Rx ADC = ON Tx DAC = ON Tx Bus = Enabled | Moderate Power Fast Tx to Rx through SPI command |

X = Don't care.

Table 7. Aux-DAC Enable Table (ENABLE-16 Mode)

| E6 | E5 | E4 | Aux-DAC3 | Aux-DAC2 | Aux-DAC1 |
|----|----|----|----------|----------|----------|
| 0 | 0 | 0 | ON | ON | ON |
| 0 | 0 | 1 | ON | ON | OFF |
| 0 | 1 | 0 | ON | OFF | ON |
| 0 | 1 | 1 | ON | OFF | OFF |
| 1 | 0 | 0 | OFF | ON | ON |
| 1 | 0 | 1 | OFF | ON | OFF |
| 1 | 1 | 0 | OFF | OFF | ON |
| 1 | 1 | 1 | OFF | OFF | OFF |

Table 8. Tx-Path Full-Scale Select (ENABLE-16 Mode)

| E7 | Tx-PATH OUTPUT FULL SCALE |
|-------------|---------------------------|
| 0 (Default) | 820mV _{p-p} |
| 1 | 1V _{p-p} |

possible jitter. Any significant clock jitter limits the SNR performance of the on-chip Rx ADC as follows:

$$\text{SNR} = 20 \times \log \left(\frac{1}{2 \times \pi \times f_{\text{IN}} \times t_{\text{AJ}}} \right)$$

where f_{IN} represents the analog input frequency and t_{AJ} is the time of the clock jitter.

Clock jitter is especially critical for undersampling applications. Consider the clock input as an analog input and route away from any analog input or other digital signal lines. The MAX19700 clock input operates with a $\text{OV}_{\text{DD}} / 2$ voltage threshold and accepts a 50% $\pm 15\%$ duty cycle.

12-Bit, Auxiliary Control DACs

The MAX19700 includes three 12-bit aux-DACs (DAC1, DAC2, DAC3) with 1 μ s settling time for controlling variable-gain amplifier (VGA), automatic gain-control (AGC), and automatic frequency-control (AFC) functions. The aux-DAC output range is 0.1V to 2.56V. During power-up, the VGA and AGC outputs (DAC2 and DAC3) are at zero. The AFC DAC (DAC1) is at 1.1V during power-up. The aux-DACs can be independently

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Table 9. Offset Control Bits for I and Q Channels (IOFFSET or QOFFSET Mode)

| BITS IO5–IO0 WHEN IN IOFFSET MODE, BITS QO5–QO0 WHEN IN QOFFSET MODE | | | | | | OFFSET 1 LSB = (VFS _{p-p} /1023) |
|--|---------|---------|---------|---------|---------|---|
| IO5/QO5 | IO4/QO4 | IO3/QO3 | IO2/QO2 | IO1/QO1 | IO0/QO0 | |
| 1 | 1 | 1 | 1 | 1 | 1 | -31 LSB |
| 1 | 1 | 1 | 1 | 1 | 0 | -30 LSB |
| 1 | 1 | 1 | 1 | 0 | 1 | -29 LSB |
| • | • | • | • | • | • | • |
| • | • | • | • | • | • | • |
| • | • | • | • | • | • | • |
| 1 | 0 | 0 | 0 | 1 | 0 | -2 LSB |
| 1 | 0 | 0 | 0 | 0 | 1 | -1 LSB |
| 1 | 0 | 0 | 0 | 0 | 0 | 0mV |
| 0 | 0 | 0 | 0 | 0 | 0 | 0mV (Default) |
| 0 | 0 | 0 | 0 | 0 | 1 | 1 LSB |
| 0 | 0 | 0 | 0 | 1 | 0 | 2 LSB |
| • | • | • | • | • | • | • |
| • | • | • | • | • | • | • |
| • | • | • | • | • | • | • |
| 0 | 1 | 1 | 1 | 0 | 1 | 29 LSB |
| 0 | 1 | 1 | 1 | 1 | 0 | 30 LSB |
| 0 | 1 | 1 | 1 | 1 | 1 | 31 LSB |

Note: For transmit full-scale select of 820mV_{p-p}: 1 LSB = (820mV_{p-p}/1023) = 0.8016mV. For transmit full-scale select of 1V_{p-p}: 1 LSB = (1V_{p-p}/1023) = 0.9775mV.

Table 10. Common-Mode Select (COMSEL Mode)

| CM1 | CM0 | Tx-PATH OUTPUT COMMON MODE (V) |
|-----|-----|--------------------------------|
| 0 | 0 | 1.4 (Default) |
| 0 | 1 | 1.25 |
| 1 | 0 | 1.1 |
| 1 | 1 | 0.9 |

controlled through the SPI bus, except during SHDN mode where the aux-DACs are turned off completely and the output voltage is set to zero. In STBY and IDLE modes the aux-DACs maintain the last value. On wakeup from SHDN, the aux-DACs resume the last values.

Loading on the aux-DAC outputs should be carefully observed to achieve specified settling time and stability. The capacitive load must be kept to a maximum of 5pF including package and trace capacitance. The resistive load must be greater than 200kΩ. If capacitive loading exceeds 5pF, then add a 10kΩ resistor in series with the output. Adding the series resistor helps

drive larger load capacitance (<15pF) at the expense of slower settling time.

Reference Configurations

The MAX19700 features an internal precision 1.024V bandgap reference that is stable over the entire power-supply and temperature ranges. The REFIN input provides two modes of reference operation. The voltage at REFIN (V_{REFIN}) sets the reference operation mode (Table 11).

In internal reference mode, connect REFIN to V_{DD}. V_{REF} is an internally generated 0.512V ±4%. COM, REFP, and REFN are low-impedance outputs with V_{COM} = V_{DD} / 2, V_{REFP} = V_{DD} / 2 + V_{REF} / 2, and V_{REFN} = V_{DD} / 2 - V_{REF} / 2. Bypass REFP, REFN, and COM each with a 0.33μF capacitor. Bypass REFIN to GND with a 0.1μF capacitor.

In buffered external reference mode, apply 1.024V ±10% at REFIN. In this mode, COM, REFP, and REFN are low-impedance outputs with V_{COM} = V_{DD} / 2, V_{REFP} = V_{DD} / 2 + V_{REFIN} / 4, and V_{REFN} = V_{DD} / 2 - V_{REFIN} / 4. Bypass REFP, REFN, and COM each with a 0.33μF capacitor. Bypass REFIN to GND with a 0.1μF

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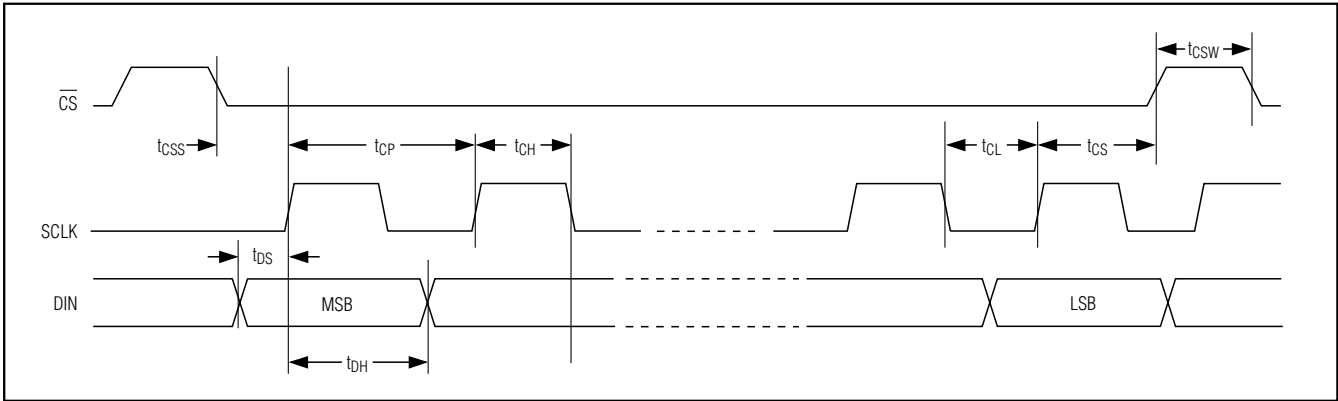


Figure 6. 3-Wire Serial-Interface Timing Diagram

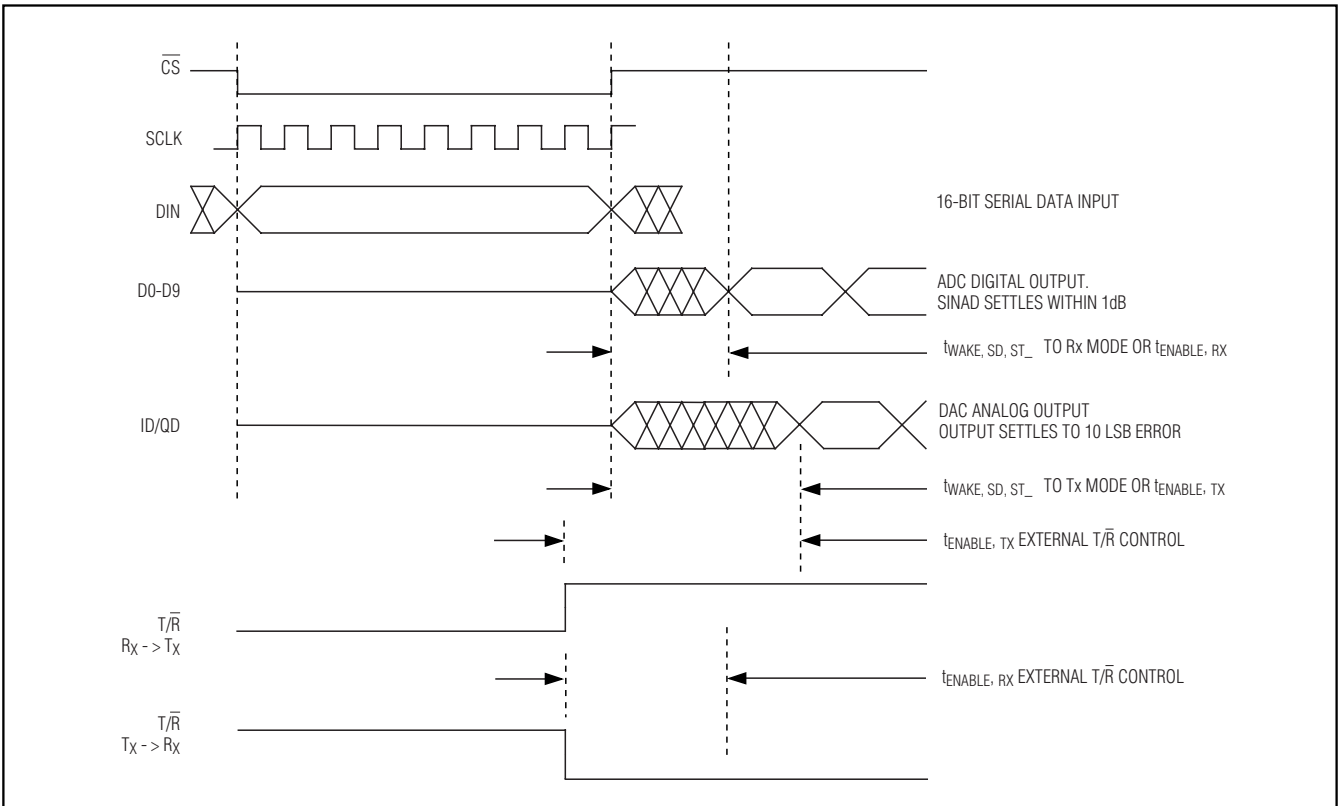


Figure 7. MAX19700 Mode-Recovery Timing Diagram

capacitor. In this mode, the Tx-path full-scale output is proportional to the external reference. For example, if the V_{REFIN} is increased by 10% (max), the Tx-path full-scale output is also increased by 10% or $\pm 451\text{mV}$.

Power-On Reset

The MAX19700 features a power-on-reset (POR) function that sets the device in a known state upon power-up. The default state is Ext2-Rx. The POR circuit is designed to accommodate power supplies that ramp

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Table 11. Reference Modes

| V _{REFIN} | REFERENCE MODE |
|-------------------------|--|
| >0.8V × V _{DD} | Internal Reference Mode. V _{REF} is internally generated to be 0.512V. Bypass REFP, REFN, and COM each with a 0.33μF capacitor. |
| 1.024V ±10% | Buffered External Reference Mode. An external 1.024V ±10% reference voltage is applied to REFIN. V _{REF} is internally generated to be V _{REFIN} / 2. Bypass REFP, REFN, and COM each with a 0.33μF capacitor. Bypass REFIN to GND with a 0.1μF capacitor. |

from 0V to V_{DD} in less than or equal to 1ms. For power supplies that ramp from 0V to V_{DD} in greater than 1ms, program the MAX19700 to enter the desired state using the SPI interface.

Applications Information

Using Balun Transformer AC-Coupling

An RF transformer (Figure 8) provides an excellent solution to convert a single-ended signal source to a fully differential signal for optimum ADC performance. Connecting the center tap of the transformer to COM provides a V_{DD} / 2 DC level shift to the input. A 1:1 transformer can be used, or a step-up transformer can be selected to reduce the drive requirements. In general, the MAX19700 provides better SFDR and THD with fully differential input signals than single-ended signals, especially for high input frequencies. In differential mode, even-order harmonics are lower as both inputs (IAP, IAN, QAP, QAN) are balanced, and each of the Rx ADC inputs only requires half the signal swing compared to single-ended mode. Figure 9 shows an RF transformer converting the MAX19700 Tx DAC differential analog outputs to single-ended.

Using Op-Amp Coupling

Drive the MAX19700 Rx ADC with op amps when a balun transformer is not available. Figures 10 and 11 show the Rx ADC being driven by op amps for AC-coupled single-ended and DC-coupled differential applications. Amplifiers such as the MAX4454 and MAX4354 provide high speed, high bandwidth, low noise, and low distortion to maintain the input signal integrity. The op-amp circuit shown in Figure 11 can also be used to interface with the Tx DAC differential analog outputs to provide gain or buffering. The Tx DAC differential analog outputs cannot be used in single-ended mode because of the internally generated common-mode level. Also, the Tx DAC analog outputs are designed to drive a differential input stage with input impedance ≥70kΩ. If single-ended outputs are desired, use an amplifier to provide differential-to-single-ended conversion and select an amplifier with proper input common-mode voltage range.

TDD Mode

The MAX19700 is optimized to operate in TD-SCDMA applications. When FAST mode is selected, the MAX19700 can switch between Tx and Rx modes through the T/R pin in typically 1μs. The Rx ADC and Tx DAC operate independently. The Rx ADC and Tx DAC digital bus are shared forming a single 10-bit parallel bus. Using the 3-wire serial interface or external T/R pin, select between Rx mode to enable the Rx ADC or Tx mode to enable the Tx DAC. When operating in Rx mode, the Tx DAC bus is not enabled and in Tx mode the Rx ADC bus is tri-stated eliminating any unwanted

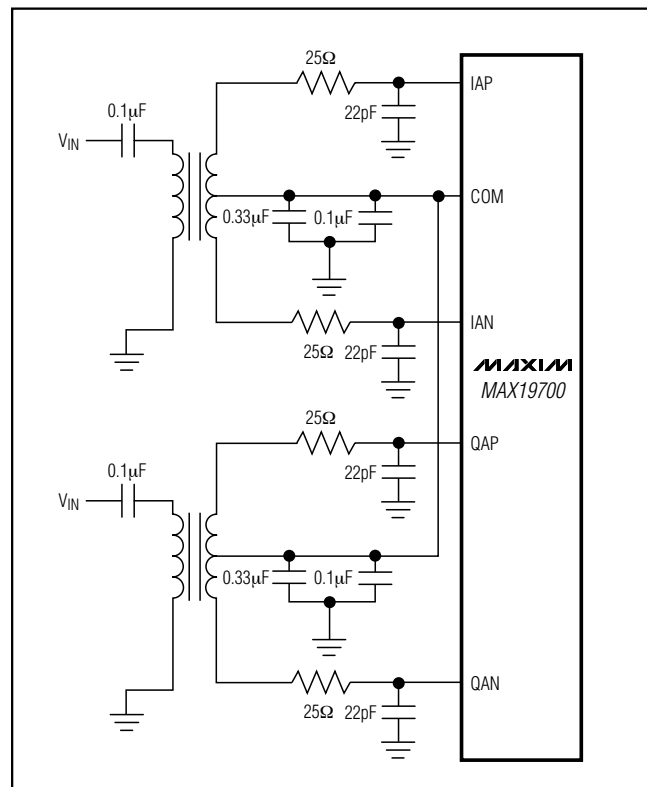


Figure 8. Balun Transformer-Coupled Single-Ended-to-Differential Input Drive for Rx ADC