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## MAX32650–MAX32652

### General Description

DARWIN is a new breed of low-power microcontrollers built to thrive in the rapidly evolving Internet of Things (IoT). They are smart, with the biggest memories in their class and a massively scalable memory architecture. They run forever, thanks to wearable-grade power technology. They are also tough enough to withstand the most advanced cyberattacks. DARWIN microcontrollers are designed to run any application imaginable—in places where you would not dream of sending other microcontrollers.

Generation UP microcontrollers are designed to handle the increasingly complex applications demanded by today's advanced battery-powered devices and wireless sensors. The MAX32650–MAX32652 are ultra-low power memory-scalable microcontrollers designed specifically for high-performance, battery-powered applications. They are based on Arm® Cortex®-M4 with FPU CPU with 3MB flash and 1MB SRAM. Memory scalability is supported with multiple memory-expansion interfaces, including a HyperBus™/Xccela™ DDR interface and two SPI execute in place (SPIX) interfaces. A secure digital interface supports external high-speed memory cards, including SD, SDIO, MMC, SDHC, and microSD™.

Power management features provide five low power modes for clock, peripheral, and voltage control. Individual SRAM banks of 32KB, 96KB, or 1024KB (full retention) can be retained with reduced power consumption. A SmartDMA performs complex background processing while the CPU is off to dramatically reduce overall power consumption.

The MAX32651 is a secure version with a trust protection unit (TPU) that provides a modular arithmetic accelerator (MAA) for fast ECDSA, an AES engine, TRNG, SHA-256 hash, and secure bootloader. A memory decryption integrity unit (MDIU) provides on-the-fly data decryption (plain or executable) stored in external flash.

The MAX32652 is a high-density, 0.35mm pitch, 140-bump WLP package targeted for tiny form factor products that require high I/O counts.

### Applications

- Sports Watches, Fitness Monitors
- Wearable Medical Patches, Portable Medical Devices
- Industrial Sensors, IoT

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## Ultra-Low Power Arm Cortex-M4 with FPU-Based Microcontroller for Battery-Powered Applications

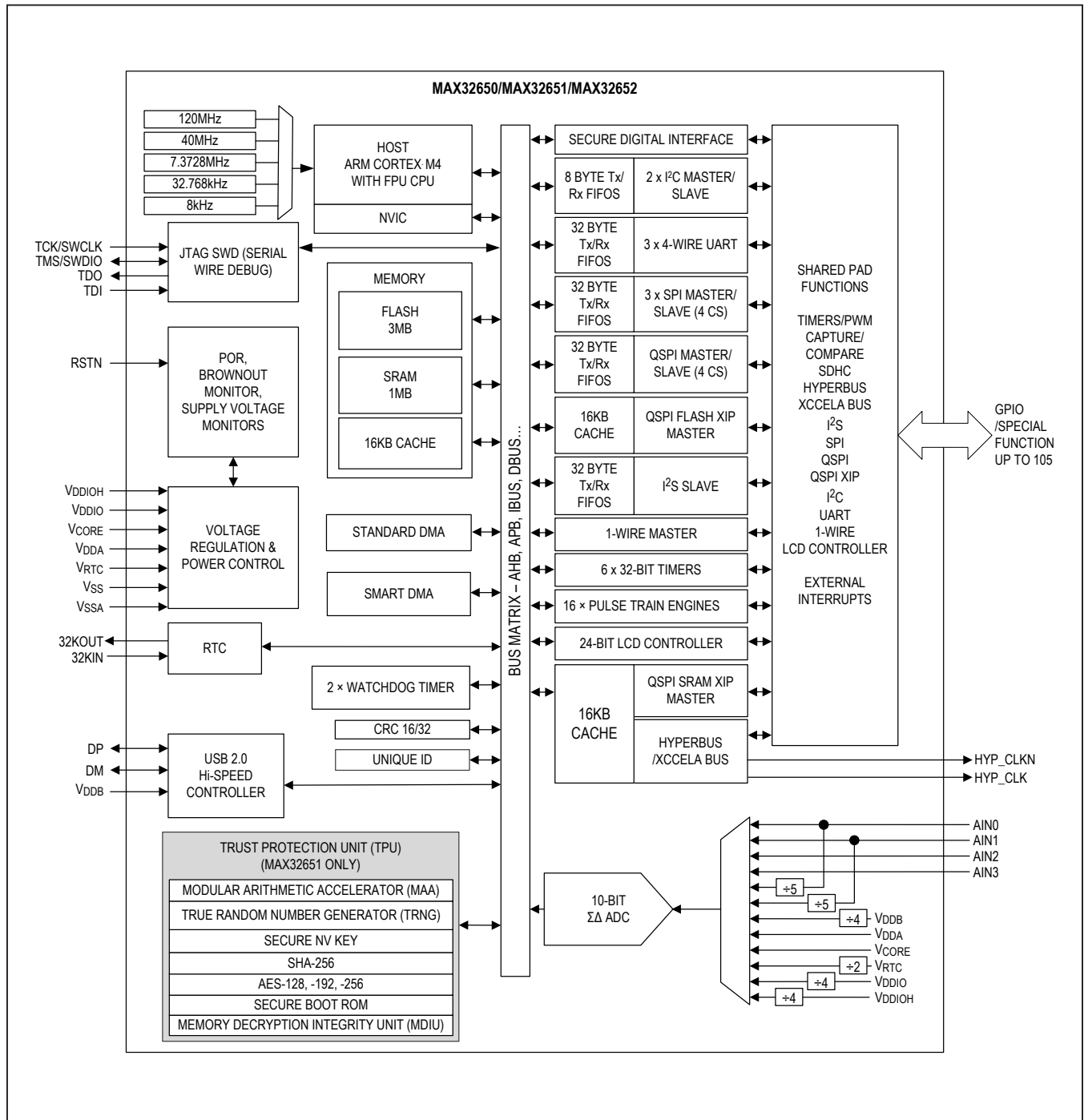
### Benefits and Features

- Ultra-Efficient Microcontroller for Battery-Powered Applications
  - 120MHz Arm Cortex-M4 with FPU
  - SmartDMA Provides Background Memory Transfers with Programmable Data Processing
  - 120MHz High-Speed and 40MHz Low-Power Oscillators
  - 7.3728MHz Low-Power Oscillators
  - 32.768kHz and RTC Clock (Requires External Crystal)
  - 8kHz Always-On Ultra-Low Power Oscillator
  - 3MB Internal Flash, 1MB Internal SRAM
  - 104μW/MHz Executing from Cache at 1.1V
  - Five Low Power Modes: Active, Sleep, Background, Deep-Sleep, and Backup
  - 1.8V and 3.3V I/O with No Level Translators
- Scalable Cached External Memory Interfaces:
  - 120MB/s HyperBus/Xccela DDR Interface
  - SPIXF/SPIXR for External Flash/RAM Expansion
  - 240Mbps SDHC/eMMC/SDIO/microSD Interface
- Optimal Peripheral Mix Provides Platform Scalability
  - 16-Channel DMA
  - Three SPI Master (60MHz)/Slave (48MHz)
  - One QuadSPI Master (60MHz)/Slave (48MHz)
  - Up to Three 4Mbaud UARTs with Flow Control
  - Two 1MHz I<sup>2</sup>C Master/Slave
  - I<sup>2</sup>S Slave
  - Four-Channel 7.8ksps 10-Bit Delta-Sigma ADC
  - USB 2.0 Hi-Speed Device Interface with PHY
  - 16 Pulse Train Generators
  - Six 32-Bit Timers with 8mA High Drive
  - 1-Wire Master
- Trust Protection Unit (TPU) for IP/Data Security
  - Modular Arithmetic Accelerator (MAA), True Random Number Generator (TRNG)
  - Secure Nonvolatile Key Storage, SHA-256, AES-128/192/256
  - Memory Decryption Integrity Unit, Secure Boot ROM

Ordering Information appears at end of data sheet.



Simplified Block Diagram



**Absolute Maximum Ratings**

(All voltages with respect to V<sub>SS</sub>, unless otherwise noted.)

V <sub>CORE</sub> .....	-0.3V to 1.21V	HYP_CLK, HYP_CLKN, P1.[21:18], P1.[16:11], P3.0.....	-0.3V to 1.98V
V <sub>DDA</sub> .....	-0.3V to 1.98V	V <sub>DDIO</sub> pins (sink).....	100mA
V <sub>DDIO</sub> .....	-0.3V to 1.98V	V <sub>DDIOH</sub> pins (sink).....	100mA
V <sub>DDIOH</sub> .....	-0.3V to 3.6V	V <sub>SSA</sub> .....	100mA
V <sub>RTC</sub> .....	-0.3V to 1.98V	V <sub>SS</sub> .....	100mA
RSTN, GPIO (V <sub>DDIO</sub> ).....	-0.3V to V <sub>DDIO</sub> + 0.5V	Output Current (sink) by Any GPIO Pin.....	25mA
GPIO (V <sub>DDIOH</sub> ).....	-0.3V to V <sub>DDIOH</sub> + 0.5V	Output Current (source) by Any GPIO Pin.....	-25mA
32KIN, 32KOUT.....	-0.3V to V <sub>RTC</sub> + 0.2V	Continuous Package Power Dissipation TQFP (multilayer board) T <sub>A</sub> = +70°C (derate 45.5mW/°C above +70°C).....	2857.10mW
AIN[1:0].....	-0.3V to 5.5V	Operating Temperature Range.....	-40°C to +105°C
AIN[3:2].....	-0.3V to V <sub>DDA</sub> + 0.2V	Storage Temperature Range.....	-65°C to +150°C
V <sub>DDB</sub> .....	-0.3V to 3.6V	Soldering Temperature.....	+260°C
DM, DP.....	-0.3V to 3.6V		

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**Package Information**

**140 WLP**

PACKAGE CODE	W1404A4+1
Outline Number	<a href="#">21-100219</a>
Land Pattern Number	Refer to <a href="#">Application Note 1891</a>
<b>Thermal Resistance, Four-Layer Board:</b>	
Junction to Ambient (θ <sub>JA</sub> )	35.13°C/W
Junction to Case (θ <sub>JC</sub> )	N/A

**96 WLP**

PACKAGE CODE	W964A4+1
Outline Number	<a href="#">21-100240</a>
Land Pattern Number	Refer to <a href="#">Application Note 1891</a>
<b>Thermal Resistance, Four-Layer Board:</b>	
Junction to Ambient (θ <sub>JA</sub> )	33.61°C/W
Junction to Case (θ <sub>JC</sub> )	N/A

**144 TQFP**

PACKAGE CODE	C144+1
Outline Number	<a href="#">21-0087</a>
Land Pattern Number	<a href="#">90-0144</a>
<b>Thermal Resistance, Four-Layer Board:</b>	
Junction to Ambient (θ <sub>JA</sub> )	28°C/W
Junction to Case (θ <sub>JC</sub> )	8°C/W

For the latest package outline information and land patterns (footprints), go to [www.maximintegrated.com/packages](http://www.maximintegrated.com/packages). Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to [www.maximintegrated.com/thermal-tutorial](http://www.maximintegrated.com/thermal-tutorial).

## Electrical Characteristics

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested. General Purpose I/O are only tested at  $T_A = +105^\circ\text{C}$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>POWER</b>						
Supply Voltage, Core	$V_{\text{CORE}}$	$f_{\text{SYS\_CLK}} = 120\text{MHz}$	0.99	1.1	1.21	V
Supply Voltage, Analog	$V_{\text{DDA}}$		1.71	1.8	1.89	V
Supply Voltage, RTC	$V_{\text{RTC}}$		1.71	1.8	1.89	V
Supply Voltage, GPIO	$V_{\text{DDIO}}$		1.71	1.8	1.89	V
Supply Voltage, GPIO (High)	$V_{\text{DDIOH}}$		1.71	1.8	3.6	V
Power-Fail Reset Voltage	$V_{\text{RST}}$	Monitors $V_{\text{CORE}}$		0.835		V
		Monitors $V_{\text{DDA}}$		1.67		
		Monitors $V_{\text{RTC}}$		1.67		
		Monitors $V_{\text{DDIO}}$		1.67		
Power-Fail Reset Voltage	$V_{\text{RST}}$	Monitors $V_{\text{DDB}}$		2.95		V
Power-Fail Reset Voltage	$V_{\text{RST}}$	Monitors $V_{\text{DDIOH}}$		1.67		V
Power-On Reset Voltage	$V_{\text{POR}}$	Monitors $V_{\text{CORE}}$		0.594		V
		Monitors $V_{\text{DDA}}$		1.52		
		Monitors $V_{\text{RTC}}$		1.17		
RAM Data Retention Voltage	$V_{\text{DRV}}$			0.81		V
$V_{\text{CORE}}$ Dynamic Current, Active Mode	$I_{\text{CORE\_DACT}}$	Total current into $V_{\text{CORE}}$ pins, $f_{\text{SYS\_CLK}} = 120\text{MHz}$ , $V_{\text{CORE}} = 1.1\text{V}$ , CPU in Active mode, executing from cache, inputs tied to $V_{\text{SS}}$ , $V_{\text{DDIO}}$ , or $V_{\text{DDIOH}}$ , outputs source/sink 0mA		95		$\mu\text{A}/\text{MHz}$
$V_{\text{CORE}}$ Fixed Current, Active Mode	$I_{\text{CORE\_FACT}}$	120MHz oscillator enabled, total current into $V_{\text{CORE}}$ pins, CPU in Active mode 0MHz execution, inputs tied to $V_{\text{SS}}$ , $V_{\text{DDIO}}$ , or $V_{\text{DDIOH}}$ , outputs source/sink 0mA		1020		$\mu\text{A}$
		7.3728MHz oscillator enabled, total current into $V_{\text{CORE}}$ pins, CPU in Active mode 0MHz execution, inputs tied to $V_{\text{SS}}$ , $V_{\text{DDIO}}$ , or $V_{\text{DDIOH}}$ , outputs source/sink 0mA		356		
$V_{\text{DDA}}$ Fixed Current, Active Mode	$I_{\text{DDA\_FACT}}$	120MHz oscillator enabled, total current into $V_{\text{DDA}}$ pins, CPU in Active mode 0MHz execution, inputs tied to $V_{\text{SS}}$ , $V_{\text{DDIO}}$ , or $V_{\text{DDIOH}}$ , outputs source/sink 0mA, $V_{\text{CORE}}$ and $V_{\text{DDA}}$ voltage monitors enabled		348		$\mu\text{A}$
		7.3728MHz oscillator enabled, total current into $V_{\text{DDA}}$ pins, CPU in Active mode 0MHz execution, inputs tied to $V_{\text{SS}}$ , $V_{\text{DDIO}}$ , or $V_{\text{DDIOH}}$ , outputs source/sink 0mA, $V_{\text{CORE}}$ and $V_{\text{DDA}}$ voltage monitors enabled		39		

**Electrical Characteristics (continued)**

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested. General Purpose I/O are only tested at  $T_A = +105^\circ\text{C}$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
$V_{\text{CORE}}$ Dynamic Current, Sleep Mode	$I_{\text{CORE\_DSL P}}$	Total current into $V_{\text{CORE}}$ pins, CPU in Sleep mode, standard DMA with two channels active		114		$\mu\text{A}/\text{MHz}$
$V_{\text{CORE}}$ Fixed Current, Sleep Mode	$I_{\text{CORE\_FSL P}}$	$f_{\text{SYS\_CLK}} = 120\text{MHz}$ , total current into $V_{\text{CORE}}$ pins, CPU in Sleep mode, standard DMA with two channels active		1020		$\mu\text{A}$
		$f_{\text{SYS\_CLK}} = 7.3728\text{MHz}$ , total current into $V_{\text{CORE}}$ pins, CPU in Sleep mode, standard DMA with two channels active		356		
$V_{\text{DDA}}$ Fixed Current, Sleep Mode	$I_{\text{DDA\_FSL P}}$	$f_{\text{SYS\_CLK}} = 120\text{MHz}$ , total current into $V_{\text{DDA}}$ pins, CPU in Sleep mode, Standard DMA with two channels active		348		$\mu\text{A}$
		$f_{\text{SYS\_CLK}} = 7.3728\text{MHz}$ , total current into $V_{\text{DDA}}$ pins, CPU in Sleep mode, standard DMA with two channels active		49		
$V_{\text{CORE}}$ Dynamic Current, Background Mode	$I_{\text{CORE\_DBKG}}$	$f_{\text{SYS\_CLK}} = 7.3728\text{MHz}$ , total current into $V_{\text{CORE}}$ pins, CPU in Deep-sleep mode, SmartDMA active		66		$\mu\text{A}/\text{MHz}$
$V_{\text{CORE}}$ Fixed Current, Background Mode	$I_{\text{CORE\_FBGD}}$	7.3728MHz oscillator enabled, total current into $V_{\text{CORE}}$ pins, CPU in Deep-sleep mode, SmartDMA active		162		$\mu\text{A}$
$V_{\text{CORE}}$ Fixed Current, Deep-Sleep Mode	$I_{\text{CORE\_FDSL}}$	Standby state with full data retention		70		$\mu\text{A}$
$V_{\text{DDA}}$ Fixed Current, Deep-Sleep Mode	$I_{\text{DDA\_FDSL}}$	Standby state with full data retention, $V_{\text{CORE}}$ and $V_{\text{DDA}}$ voltage monitors enabled		132		nA
$V_{\text{RTC}}$ Fixed Current, Deep-Sleep Mode	$I_{\text{DDRTC\_FDSL}}$	Standby state with full data retention, $V_{\text{RTC}} = 1.8\text{V}$ , RTC enabled		540		nA
$V_{\text{CORE}}$ Fixed Current, Backup Mode	$I_{\text{CORE\_FBKU}}$	No SRAM retention (0KB)		30		nA
$V_{\text{DDA}}$ Fixed Current, Backup Mode	$I_{\text{DDA\_FBKU}}$	$V_{\text{DDA}}$ voltage monitor enabled		132		nA
$V_{\text{RTC}}$ Fixed Current, Backup Mode	$I_{\text{DDRTC\_FBKU}}$	RTC enabled, retention regulator off		540		nA
		RTC enabled, 32KB SRAM retained, retention regulator on		720		
		RTC disabled, retention regulator off		156		
Sleep Mode Resume Time	$t_{\text{SLP\_ON}}$			575		ns
Deep-Sleep Mode Resume Time	$t_{\text{DSL\_ON}}$	Wake to 40MHz		9		$\mu\text{s}$
		Wake to 120MHz		18		
Backup Mode Resume Time	$t_{\text{BKU\_ON}}$			5		ms

**Electrical Characteristics (continued)**

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>USB</b>						
USB Supply Voltage	$V_{DDB}$		3.0	3.3	3.6	V
D+, D- Pin Capacitance	$C_{IN\_USB}$	Pin to $V_{SS}$		8		pF
Driver Output Resistance	$R_{DRV}$	Steady state drive		45 ±10%		$\Omega$
<b>USB/FULL SPEED</b>						
Single-Ended Input High Voltage (DP, DM)	$V_{IH\_USB}$		2.0			V
Single-Ended Input Low Voltage (DP, DM)	$V_{IL\_USB}$				0.6	V
Output High Voltage (DP, DM)	$V_{OH\_USB}$	$R_L = 1.5\text{ k}\Omega$ from DP and DM to $V_{SS}$ , $I_{OH} = -4\text{mA}$	$V_{DDB} - 0.4$		$V_{DDB}$	V
Output Low Voltage (DP, DM)	$V_{OL\_USB}$	$R_L = 1.5\text{ k}\Omega$ from DP to $V_{DDB}$ , $I_{OL} = 4\text{mA}$	$V_{SS}$		0.4	V
Differential Input Sensitivity	$V_{DI}$	DP to DM	0.2			V
Common Mode Voltage Range	$V_{CM}$	Includes $V_{DI}$ range	0.8		2.5	V
Transition Time (Rise/Fall) D+, D- (Note 11)	$t_{RF}$	$C_L = 50\text{pF}$	4		20	ns
Pullup Resistor on Upstream Ports	$R_{PU}$		1.05	1.5	1.95	k $\Omega$
<b>USB/HI-SPEED</b>						
Hi-Speed Data Signaling Common-Mode Voltage Range	$V_{HSCM}$		-50		+500	mV
Hi-Speed Squelch Detection Threshold	$V_{HSSQ}$	Squelch detected		100		mV
		No squelch detected		200		
Hi-Speed Idle Level Output Voltage	$V_{HSOI}$		-10		+10	mV
Hi-Speed Low Level Output Voltage	$V_{HSOL}$		-10		+10	mV
Hi-Speed High Level Output Voltage	$V_{HSOH}$			400 ± 40		mV
Chirp-J Output Voltage (Differential)	$V_{CHIRPJ}$			900 ±200		mV
Chirp-K Output Voltage (Differential)	$V_{CHIRPK}$			-700 ±200		mV

**Electrical Characteristics (continued)**

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>CLOCKS</b>						
System Clock Frequency	f <sub>SYS_CLK</sub>		0.256		120,000	kHz
System Clock Period	t <sub>SYS_CLK</sub>			1/f <sub>SYS_CLK</sub>		ns
High-Speed Oscillator Frequency	f <sub>HSCLK</sub>	Measured at +25°C, 120MHz		120 ±1		MHz
Low-Power Oscillator Frequency	f <sub>LPCLK</sub>			40		MHz
7MHz Oscillator Frequency	f <sub>7MCLK</sub>			7.3728		MHz
Nano-Ring Oscillator Frequency	f <sub>NANO</sub>			8		KHz
RTC Input Frequency	f <sub>32KIN</sub>	32kHz watch crystal, C <sub>L</sub> = 6pF, ESR < 70kΩ		32.768		kHz
RTC Operating Current	I <sub>RTC_ACTSLP</sub>	Sleep or Active mode		0.39		µA
RTC Power Up Time	t <sub>RTC_ON</sub>			250		ms
<b>GENERAL-PURPOSE I/O</b>						
Input Low Voltage for All GPIO	V <sub>IL_VDDIO</sub>	V <sub>DDIO</sub> selected as I/O supply			0.3 × V <sub>DDIO</sub>	V
Input Low Voltage for All GPIO except P1.[21:18], P1.[16:11], P3.0	V <sub>IL_VDDIOH</sub>	V <sub>DDIOH</sub> selected as I/O supply			0.3 × V <sub>DDIOH</sub>	V
Input Low Voltage for RSTN	V <sub>IL_RSTN</sub>				0.3 × V <sub>DDIO</sub>	V
Input High Voltage for All GPIO	V <sub>IH_VDDIO</sub>	V <sub>DDIO</sub> selected as I/O supply	0.75 × V <sub>DDIO</sub>			V
Input High Voltage for All GPIO except P1.[21:18], P1.[16:11], P3.0	V <sub>IH_VDDIOH</sub>	V <sub>DDIOH</sub> selected as I/O supply	0.75 × V <sub>DDIOH</sub>			V
Input High Voltage for RSTN	V <sub>IH_RSTN</sub>		0.75 × V <sub>DDIO</sub>			V
Output Low Voltage for All GPIO	V <sub>OL_VDDIO</sub>	V <sub>DDIO</sub> selected as I/O supply, V <sub>DDIO</sub> = 1.71V, DS[1:0] = 00, I <sub>OL</sub> = 1mA		0.2	0.4	V
		V <sub>DDIO</sub> selected as I/O supply, V <sub>DDIO</sub> = 1.71V, DS[1:0] = 01, I <sub>OL</sub> = 2mA		0.2	0.4	
		V <sub>DDIO</sub> selected as I/O supply, V <sub>DDIO</sub> = 1.71V, DS[1:0] = 10, I <sub>OL</sub> = 4mA		0.2	0.4	
		V <sub>DDIO</sub> selected as I/O supply, V <sub>DDIO</sub> = 1.71V, DS[1:0] = 11, I <sub>OL</sub> = 8mA		0.2	0.4	



**Electrical Characteristics (continued)**

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Low Voltage for All GPIO except P1.[21:18], P1.[16:11], P3.0	$V_{OL\_VDDIOH}$	$V_{DDIOH}$ selected as I/O supply, $V_{DDIOH} = 1.71\text{V}$ , $DS[1:0] = 00$ , $I_{OL} = 1\text{mA}$		0.2	0.4	V
		$V_{DDIOH}$ selected as I/O supply, $V_{DDIOH} = 1.71\text{V}$ , $DS[1:0] = 01$ , $I_{OL} = 2\text{mA}$		0.2	0.4	
		$V_{DDIOH}$ selected as I/O supply, $V_{DDIOH} = 1.71\text{V}$ , $DS[1:0] = 10$ , $I_{OL} = 4\text{mA}$		0.2	0.4	
		$V_{DDIOH}$ selected as I/O supply, $V_{DDIOH} = 1.71\text{V}$ , $DS[1:0] = 11$ , $I_{OL} = 8\text{mA}$		0.2	0.4	
Combined $I_{OL}$ , All GPIO	$I_{OL\_TOTAL}$				48	mA
Output High Voltage for All GPIO	$V_{OH\_VDDIO}$	$V_{DDIO}$ selected as I/O supply, $V_{DDIO} = 1.71\text{V}$ , $DS[1:0] = 00$ , $I_{OL} = -1\text{mA}$	$V_{DDIO}$ - 0.4			V
		$V_{DDIO}$ selected as I/O supply, $V_{DDIO} = 1.71\text{V}$ , $DS[1:0] = 01$ , $I_{OL} = -2\text{mA}$	$V_{DDIO}$ - 0.4			
		$V_{DDIO}$ selected as I/O supply, $V_{DDIO} = 1.71\text{V}$ , $DS[1:0] = 10$ , $I_{OL} = -4\text{mA}$	$V_{DDIO}$ - 0.4			
		$V_{DDIO}$ selected as I/O supply, $V_{DDIO} = 1.71\text{V}$ , $DS[1:0] = 00$ , $I_{OL} = -8\text{mA}$	$V_{DDIO}$ - 0.4			
Output High Voltage for All GPIO except P1.[21:18], P1.[16:11], P3.0	$V_{OH\_VDDIOH}$	$V_{DDIOH}$ selected as I/O supply, $V_{DDIOH} = 1.71\text{V}$ , $DS[1:0] = 00$ , $I_{OL} = -1\text{mA}$	$V_{DDIOH}$ - 0.4			V
		$V_{DDIOH}$ selected as I/O supply, $V_{DDIOH} = 1.71\text{V}$ , $DS[1:0] = 01$ , $I_{OL} = -2\text{mA}$	$V_{DDIOH}$ - 0.4			
		$V_{DDIOH}$ selected as I/O supply, $V_{DDIOH} = 1.71\text{V}$ , $DS[1:0] = 10$ , $I_{OL} = -8\text{mA}$	$V_{DDIOH}$ - 0.4			
		$V_{DDIOH}$ selected as I/O supply, $V_{DDIOH} = 1.71\text{V}$ , $DS[1:0] = 11$ , $I_{OL} = -8\text{mA}$	$V_{DDIOH}$ - 0.4			
Combined $I_{OH}$ , All GPIO	$I_{OH\_TOTAL}$				-48	mA
Input Hysteresis (Schmitt)	$V_{IHYS}$			300		mV
Input Leakage Current Low	$I_{IL}$	$V_{DDIO} = 1.89\text{V}$ , $V_{DDIOH} = 3.6\text{V}$ , $V_{DDIOH}$ selected as I/O supply, $V_{IN} = 0\text{V}$ , internal pullup disabled	-1000		+1000	nA
Input Leakage Current High	$I_{IH}$	$V_{DDIO} = 1.89\text{V}$ , $V_{DDIOH} = 3.6\text{V}$ , $V_{DDIOH}$ selected as I/O supply, $V_{IN} = 3.6\text{V}$ , internal pulldown disabled	-1000		+1000	nA
	$I_{OFF}$	$V_{DDIO} = 0\text{V}$ , $V_{DDIOH} = 0\text{V}$ , $V_{DDIO}$ selected as I/O supply, $V_{IN} < 1.89\text{V}$	-1		+1	$\mu\text{A}$
	$I_{IH3V}$	$V_{DDIO} = V_{DDIOH} = 1.71\text{V}$ , $V_{DDIO}$ selected as I/O supply, $V_{IN} = 3.6\text{V}$	-2		+2	
Input Pullup Resistor TMS, TCK, TDI	$R_{PU\_T}$			25		k $\Omega$
Input Pullup Resistor RSTN	$R_{PU\_R}$			1		M $\Omega$

**Electrical Characteristics (continued)**

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested. General-purpose I/O are only tested at  $T_A = +105^\circ\text{C}$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Pullup/Pulldown Resistor for All GPIO	$R_{PU1}$	Normal resistance		25		k $\Omega$
	$R_{PU2}$	Highest resistance		1		M $\Omega$
<b>FLASH MEMORY</b>						
Flash Erase Time	$t_{M\_ERASE}$	Mass erase		30		ms
	$t_{P\_ERASE}$	Page erase		30		
Flash Programming Time Per Word	$t_{PROG}$			60		$\mu\text{s}$
Flash Endurance			10			kcycles
Data Retention	$t_{RET}$	$T_A = +85^\circ\text{C}$	10			years
<b>ADC (DELTA-SIGMA)</b>						
Resolution				10		Bits
ADC Clock Rate	$f_{ACLK}$		0.1		8	MHz
ADC Clock Period	$t_{ACLK}$			$1/f_{ACLK}$		$\mu\text{s}$
Input Voltage Range	$V_{AIN}$	AIN[3:0], ADC_CHSEL = 0-3, ADC_REFSEL = 1	$V_{SSA} + 0.05$		$V_{BG}/2$	V
		AIN[3:0], ADC_CHSEL = 0-3, ADC_REFSEL = 0	$V_{SSA} + 0.05$		$V_{BG}$	
		AIN[1:0], ADC_CHSEL = 4-5, ADC_REFSEL = 0	$V_{SSA} + 0.05$		5.5	
Input Impedance	$R_{AIN}$	AIN[1:0], ADC_CHSEL = 4-5, ADC active		40		k $\Omega$
Analog Input Capacitance	$C_{AIN}$	Fixed capacitance to $V_{SSA}$		1		pF
		Dynamically switched capacitance		250		fF
Integral Nonlinearity	INL		-2		+2	LSb
Differential Nonlinearity	DNL		-1		+2	LSb
Offset Error	$V_{OS}$			$\pm 1$		LSb
Gain Error	GE			$\pm 2$		LSb
ADC Active Current	$I_{ADC}$	ADC active, reference buffer enabled, input buffer disabled		210		$\mu\text{A}$
ADC Setup Time	$t_{ADC\_SU}$	Any powerup of: ADC clock or ADC bias to CpuAdcStart			10	$\mu\text{s}$
ADC Output Latency	$t_{ADC}$			1025		$t_{ACLK}$
ADC Sample Rate	$f_{ADC}$				7.8	ksps
ADC Input Leakage	$I_{ADC\_LEAK}$	AIN0 or AIN1, ADC inactive or channel not selected		0.01		nA
		AIN2 or AIN3, ADC inactive or channel not selected		0.01		

**Electrical Characteristics (continued)**

(Limits are 100% tested at  $T_A = +25^\circ\text{C}$  and  $T_A = +105^\circ\text{C}$ . Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested. General-purpose I/O are only tested at  $T_A = +105^\circ\text{C}$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
AIN0/AIN1 Resistor Divider Error		ADC_CHSEL = 4 or 5, not including ADC offset/gain error.		±2		LSb
Full-Scale Voltage	$V_{FS}$	ADC code = 0x3FF		1.2		V
Bandgap Temperature Coefficient	$V_{TEMPCO}$	From $+25^\circ\text{C}$ to $+105^\circ\text{C}$		15		ppm

**Electrical Characteristics—SPI**

(Timing specifications are guaranteed by design and not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>MASTER MODE</b>						
SPI Master Operating Frequency	$f_{MCK}$	$f_{MCK(MAX)} = f_{SYS\_CLK}/2$			60	MHz
SPI Master SCK Period	$t_{MCK}$			$1/f_{MCK}$		ns
SCK Output Pulse-Width High/Low	$t_{MCH}, t_{MCL}$		$t_{MCK}/2$			ns
MOSI Output Hold Time After SCK Sample Edge	$t_{MOH}$		$t_{MCK}/2$			ns
MOSI Output Valid to Sample Edge	$t_{MOV}$		$t_{MCK}/2$			ns
MISO Input Valid to SCK Sample Edge Setup	$t_{MIS}$			5		ns
MISO Input to SCK Sample Edge Hold	$t_{MIH}$			$t_{MCK}/2$		ns
<b>SLAVE MODE</b>						
SPI Slave Operating Frequency	$f_{SCK}$				48	MHz
SPI Slave SCK Period	$t_{SCK}$			$1/f_{SCK}$		ns
SCK Input Pulse-Width High/Low	$t_{SCH}, t_{SCL}$			$t_{SCK}/2$		
SSx Active to First Shift Edge	$t_{SSE}$			10		ns
MOSI Input to SCK Sample Edge Rise/Fall Setup	$t_{SIS}$			5		ns
MOSI Input from SCK Sample Edge Transition Hold	$t_{SIH}$			1		ns
MISO Output Valid After SCLK Shift Edge Transition	$t_{SOV}$			5		ns
SCK Inactive to SSx Inactive	$t_{SSD}$			10		ns
SSx Inactive Time	$t_{SSH}$			$1/f_{SCK}$		µs

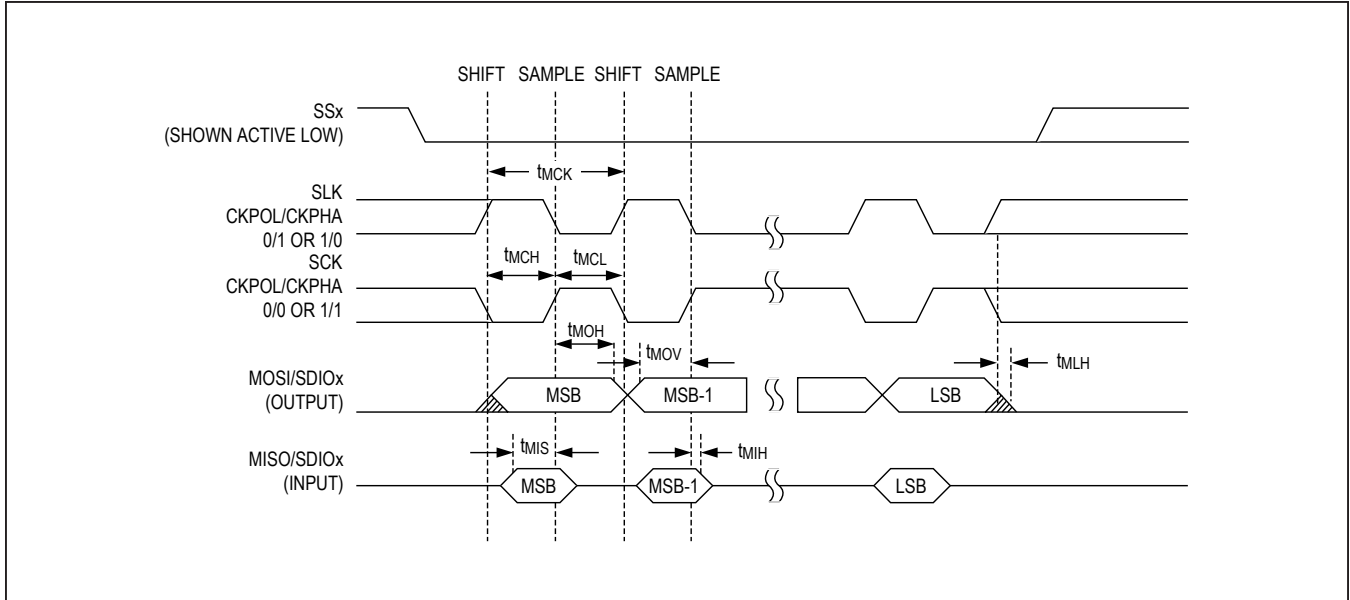


Figure 1. SPI Master Mode Timing Diagram

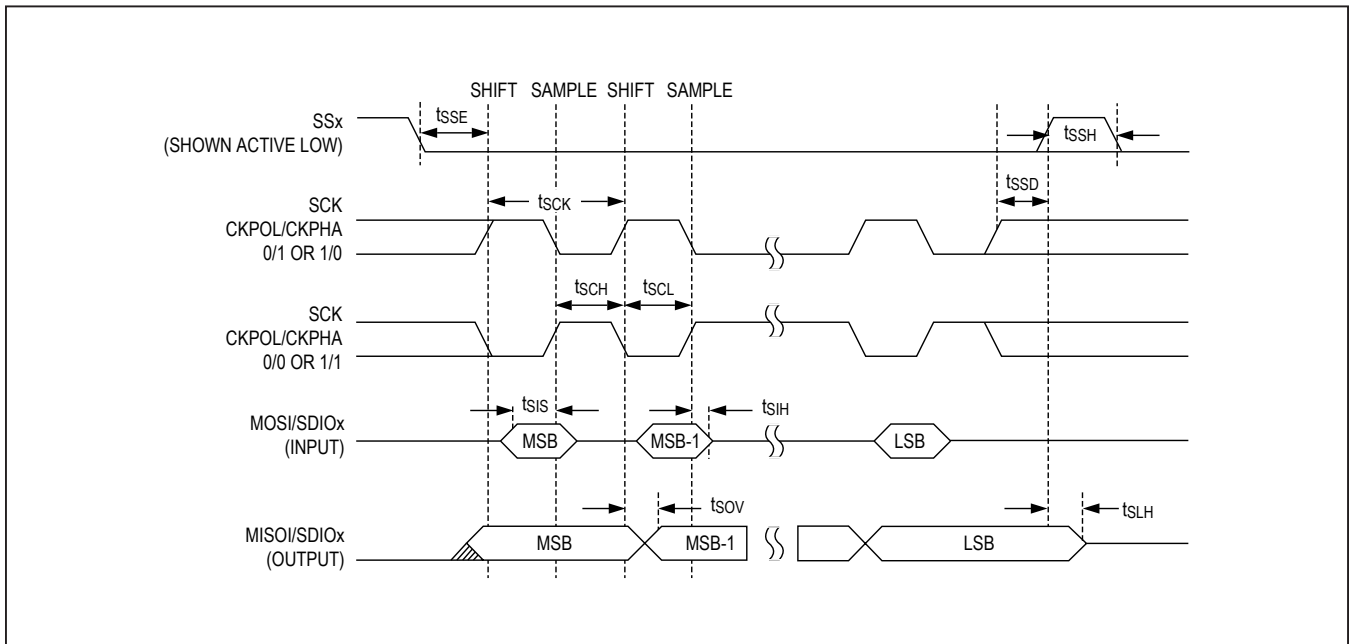


Figure 2. SPI Slave Mode Timing Diagram

**Electrical Characteristics—I<sup>2</sup>C**

(Timing specifications are guaranteed by design and not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>STANDARD MODE</b>						
Output Fall Time	$t_{OF}$	Standard mode, from $V_{IH(MIN)}$ to $V_{IL(MAX)}$		150		ns
SCL Clock Frequency	$f_{SCL}$		0		100	kHz
Low Period SCL Clock	$t_{LOW}$		4.7			$\mu$ s
High Time SCL Clock	$t_{HIGH}$		4.0			$\mu$ s
Setup Time for Repeated Start Condition	$t_{SU;STA}$		4.7			$\mu$ s
Hold Time for Repeated Start Condition	$t_{HD;STA}$		4.0			$\mu$ s
Data Setup Time	$t_{SU;DAT}$			300		ns
Data Hold Time	$t_{HD;DAT}$			10		ns
Rise Time for SDA and SCL	$t_R$			800		ns
Fall Time for SDA and SCL	$t_F$			200		ns
Setup Time for a Stop Condition	$t_{SU;STO}$		4.0			$\mu$ s
Bus Free Time Between a Stop and Start Condition	$t_{BUS}$		4.7			$\mu$ s
Data Valid Time	$t_{VD;DAT}$		3.45			$\mu$ s
Data Valid Acknowledge Time	$t_{VD;ACK}$		3.45			$\mu$ s
<b>FAST MODE</b>						
Output Fall Time	$t_{OF}$	From $V_{IH(MIN)}$ to $V_{IL(MAX)}$		150		ns
Pulse Width Suppressed by Input Filter	$t_{SP}$			75		ns
SCL Clock Frequency	$f_{SCL}$		0		400	kHz
Low Period SCL Clock	$t_{LOW}$		1.3			$\mu$ s
High Time SCL Clock	$t_{HIGH}$		0.6			$\mu$ s
Setup Time for Repeated Start Condition	$t_{SU;STA}$		0.6			$\mu$ s
Hold Time for Repeated Start Condition	$t_{HD;STA}$		0.6			$\mu$ s
Data Setup Time	$t_{SU;DAT}$			125		ns
Data Hold Time	$t_{HD;DAT}$			10		ns
Rise Time for SDA and SCL	$t_R$			30		ns
Fall Time for SDA and SCL	$t_F$			30		ns
Setup Time for a Stop Condition	$t_{SU;STO}$		0.6			$\mu$ s
Bus Free Time Between a Stop and Start Condition	$t_{BUS}$		1.3			$\mu$ s
Data Valid Time	$t_{VD;DAT}$		0.9			$\mu$ s
Data Valid Acknowledge Time	$t_{VD;ACK}$		0.9			$\mu$ s

**Electrical Characteristics—I<sup>2</sup>C (continued)**

(Timing specifications are guaranteed by design and not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>FAST MODE PLUS</b>						
Output Fall Time	t <sub>OF</sub>	From V <sub>IH(MIN)</sub> to V <sub>IL(MAX)</sub>		80		ns
Pulse Width Suppressed by Input Filter	t <sub>SP</sub>			75		ns
SCL Clock Frequency	f <sub>SCL</sub>		0		1000	kHz
Low Period SCL Clock	t <sub>LOW</sub>		0.5			μs
High Time SCL clock	t <sub>HIGH</sub>		0.26			μs
Setup Time for Repeated Start Condition	t <sub>SU;STA</sub>		0.26			μs
Hold Time for Repeated Start Condition	t <sub>HD;STA</sub>		0.26			μs
Data Setup Time	t <sub>SU;DAT</sub>			50		ns
Data Hold Time	t <sub>HD;DAT</sub>			10		ns
Rise Time for SDA and SCL	t <sub>R</sub>			50		ns
Fall Time for SDA and SCL	t <sub>F</sub>			30		ns
Setup Time for a Stop Condition	t <sub>SU;STO</sub>		0.26			μs
Bus Free Time Between a Stop and Start Condition	t <sub>BUS</sub>		0.5			μs
Data Valid Time	t <sub>VD;DAT</sub>		0.45			μs
Data Valid Acknowledge Time	t <sub>VD;ACK</sub>		0.45			μs

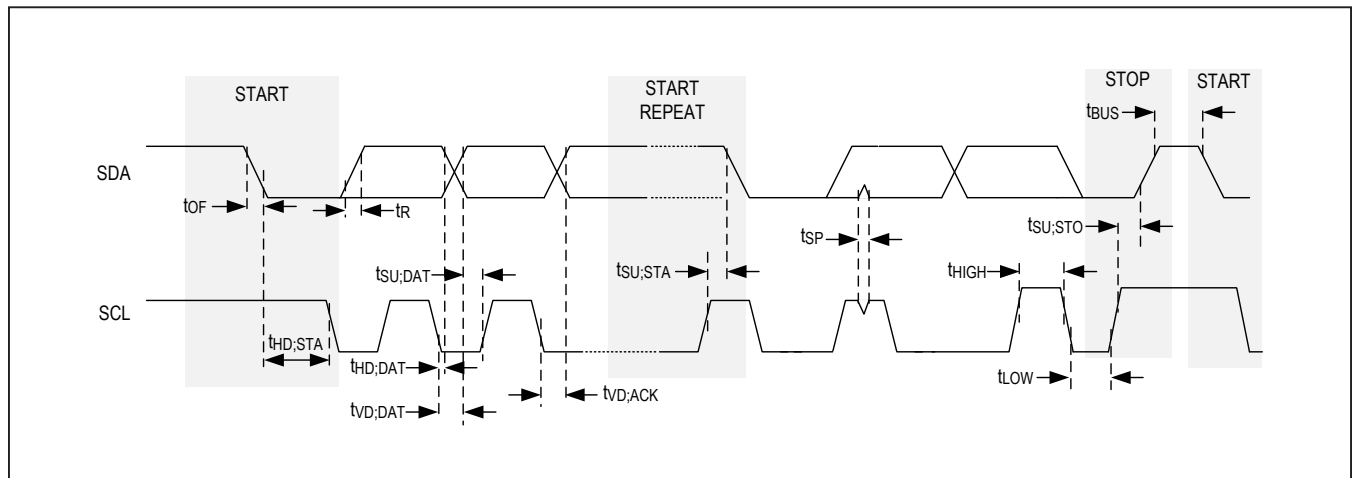


Figure 3. I<sup>2</sup>C Timing Diagram

**Electrical Characteristics—I<sup>2</sup>C Slave**

(Timing specifications are guaranteed by design and not production tested, T<sub>A</sub> = -40°C to +105°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Bit Clock Frequency	f <sub>BCLK</sub>	96kHz LRCLK frequency			3.072	MHz
BCLK High Time	t <sub>WBCLKH</sub>			0.5		1/f <sub>BCLK</sub>
BCLK Low Time				0.5		1/f <sub>BCLK</sub>
LRCLK Setup Time	t <sub>LRCLK_BCLK</sub>			25		ns
Delay Time, BCLK to SD (Output) Valid	t <sub>BCLK_SDO</sub>			12		ns
Setup Time for SD (Input)	t <sub>SU_SDI</sub>			6		ns
Hold Time SD (Input)	t <sub>HD_SDI</sub>			3		ns

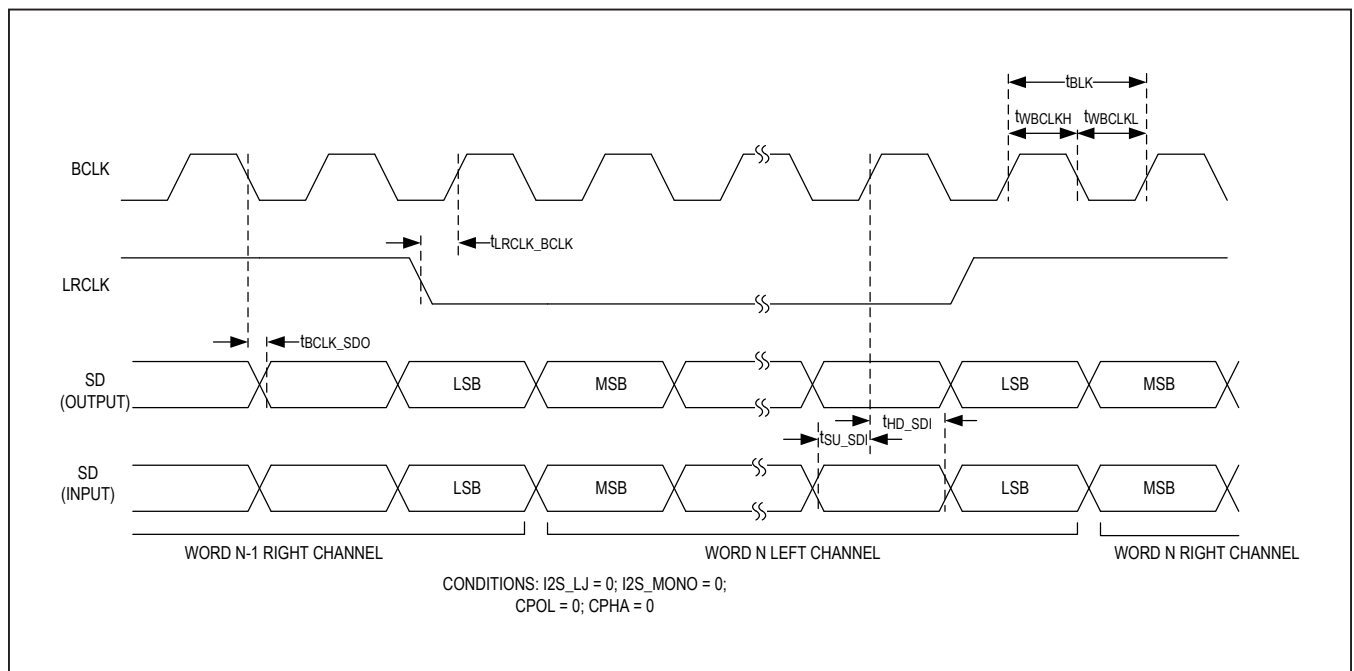


Figure 4. I<sup>2</sup>S Timing Diagram

**Electrical Characteristics—SD/SDIO/SDHC/MMC**

(T<sub>A</sub> = -40°C to +105°C )

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Clock Frequency in Data Transfer Mode	f <sub>SDHC_CLK</sub>		0		f <sub>HSCLK</sub> /2	MHz
Clock Period	t <sub>CLK</sub>			1/f <sub>SDHC_CLK</sub>		ns
Clock Low Time	t <sub>WCL</sub>			7		ns
Clock High Time	t <sub>WCH</sub>			7		ns
Input Setup Time	t <sub>ISU</sub>			5		ns
Input Hold Time	t <sub>IHL</sub>			1		ns
Output Valid Time	t <sub>OVL</sub>			5		ns
Output Hold Time	t <sub>OHL</sub>			6		ns

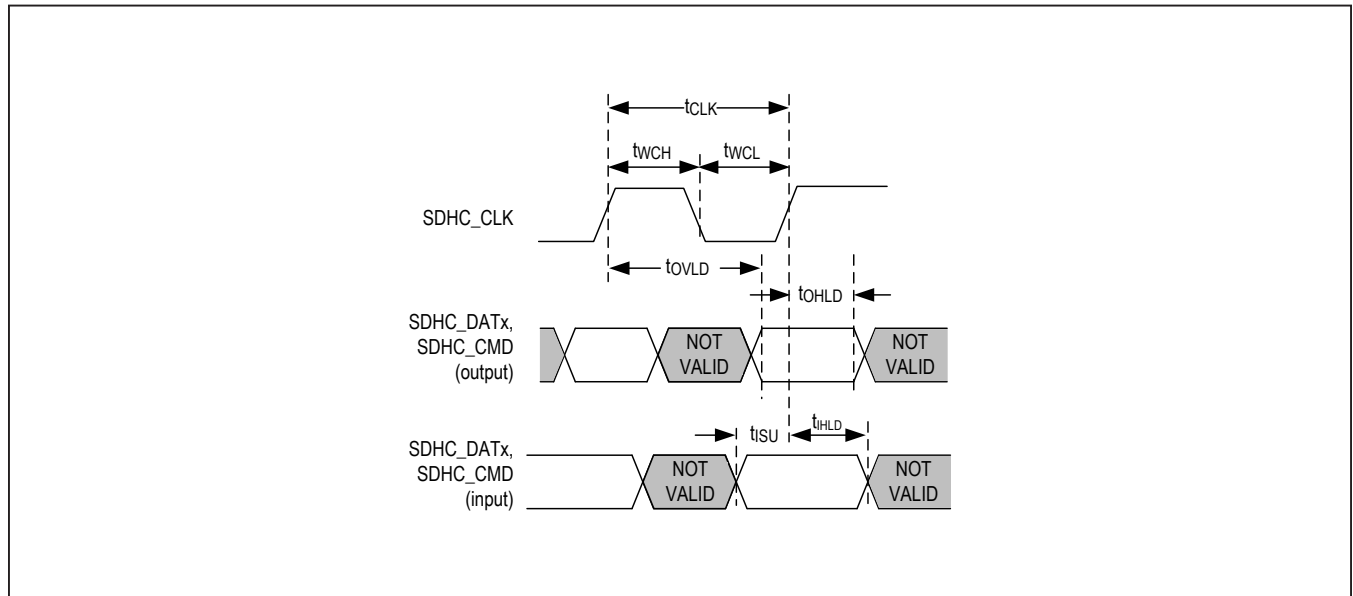


Figure 5. SD/SDIO/SDHC/MMC Timing Diagram



**Electrical Characteristics—HyperBus**

(Timing specifications are guaranteed by design and not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
HYP_CLK, HYP_CLKN Frequency	$f_{HYP\_CLK}$				60	MHz
HYP_CLK, HYP_CLKN Period	$t_{HYP\_CLK}$		$1/f_{HYP\_CLK}$			ns
HYP_CLK, HYP_CLKN High Time	$t_{WHCKH}$			7		ns
HYP_CLK, HYP_CLKN Low Time	$t_{WHCKL}$			7		ns
CS Setup to RWDS	$t_{CSSU}$			6		ns
RWDS Setup to CK	$t_{RWDS\_CK}$			10		ns
Dx Output Setup	$t_{OSU}$			5		ns
Dx Output Hold	$t_{OH}$			3		ns
CS Hold After CK Falling Edge	$t_{CSH}$			5		ns
CS High Between Transactions	$t_{CHSI}$			15		ns
Dx Input Setup to RWDS	$t_{ISU}$			4		ns
Dx Input Hold	$t_{IHD}$			2		ns

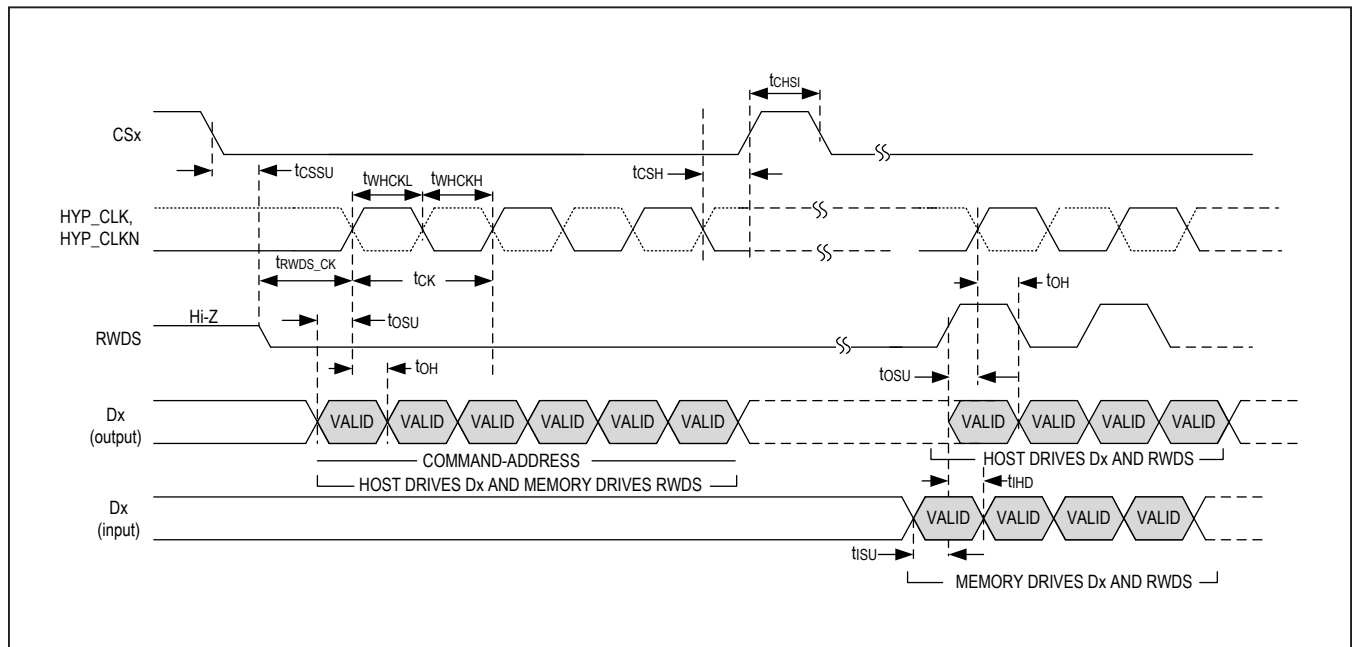


Figure 6. HyperBus/Xccela Bus Timing Diagram

**Electrical Characteristics—One Wire Master**

(Timing specifications are guaranteed by design and not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Write 0 Low Time	$t_{W0L}$	Standard		60		$\mu\text{s}$
		Overdrive		8		
Write 1 Low Time	$t_{W1L}$	Standard		6		$\mu\text{s}$
		Standard, Long Line mode		8		
		Overdrive		1		
Presence Detect Sample	$t_{MSP}$	Standard		70		$\mu\text{s}$
		Standard, Long Line mode		85		
		Overdrive		9		
Read Data Value	$t_{MSR}$	Standard		15		$\mu\text{s}$
		Standard, Long Line mode		24		
		Overdrive		3		
Recovery Time	$t_{REC0}$	Standard		10		$\mu\text{s}$
		Standard, Long Line mode		20		
		Overdrive		4		
Reset Time High	$t_{RSTH}$	Standard		480		$\mu\text{s}$
		Overdrive		58		
Reset Time Low	$t_{RSTL}$	Standard		600		$\mu\text{s}$
		Overdrive		70		
Time Slot	$t_{SLOT}$	Standard		70		$\mu\text{s}$
		Overdrive		12		

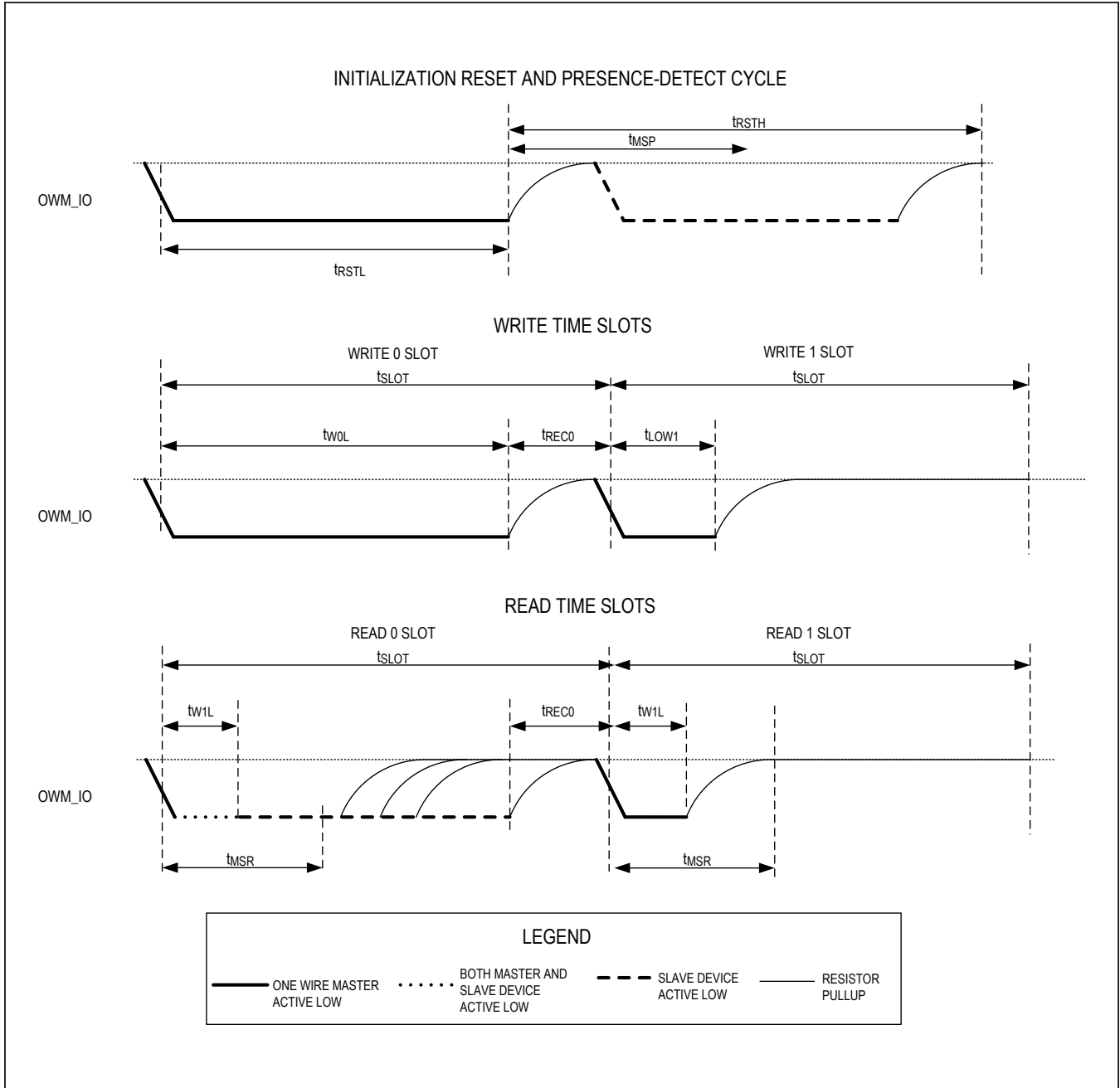
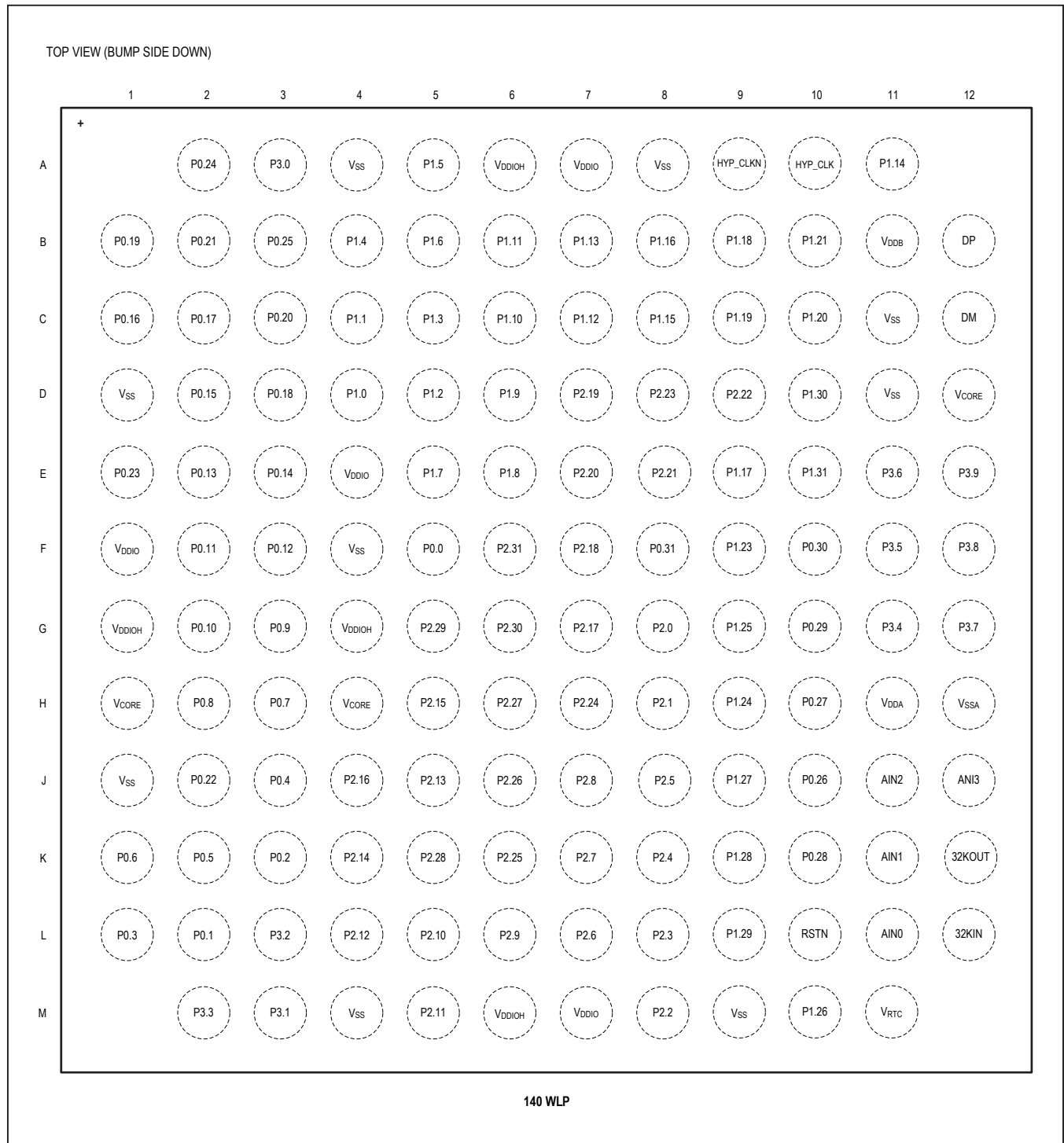
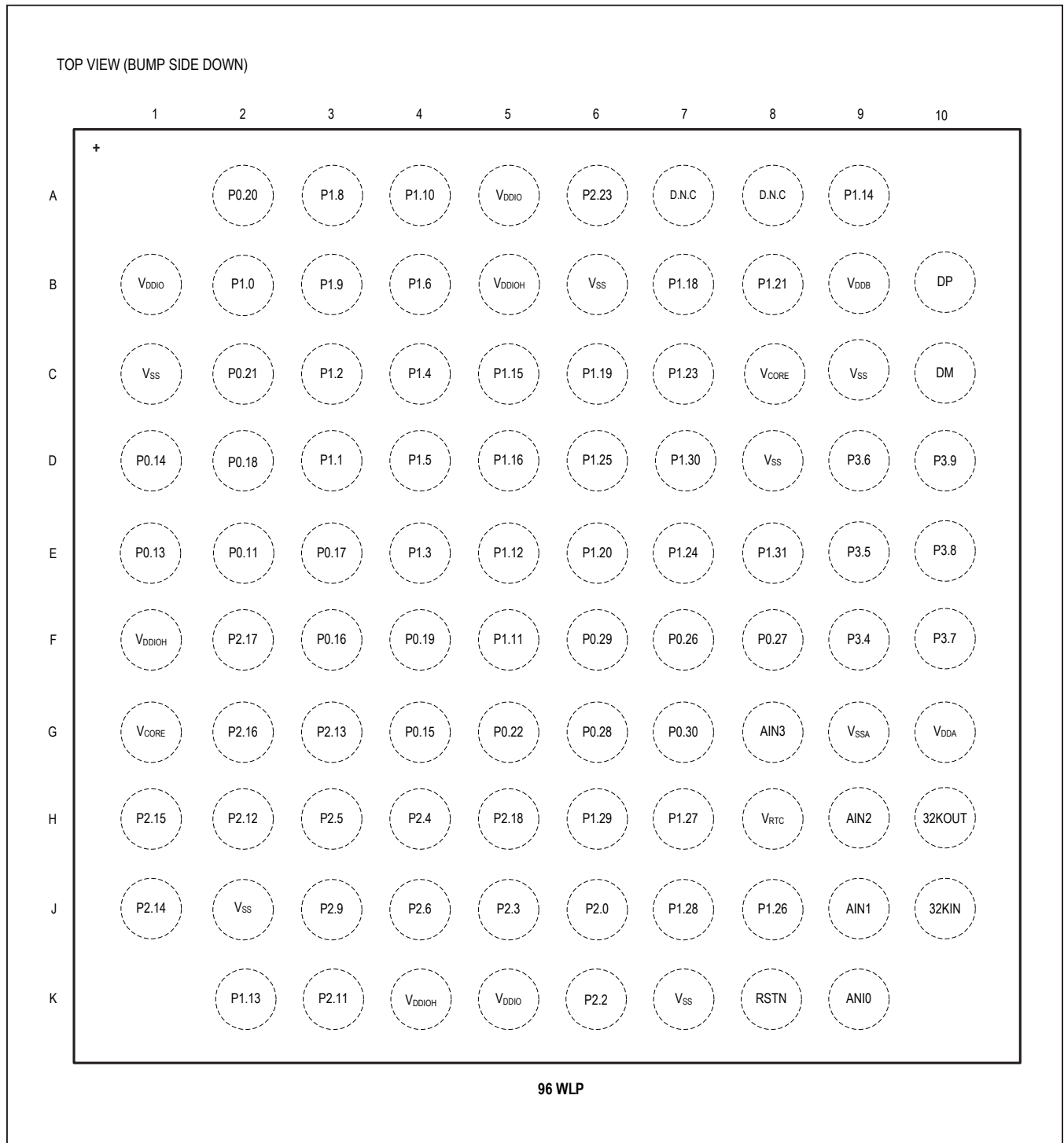


Figure 7. One-Wire Master Data Timing Diagram

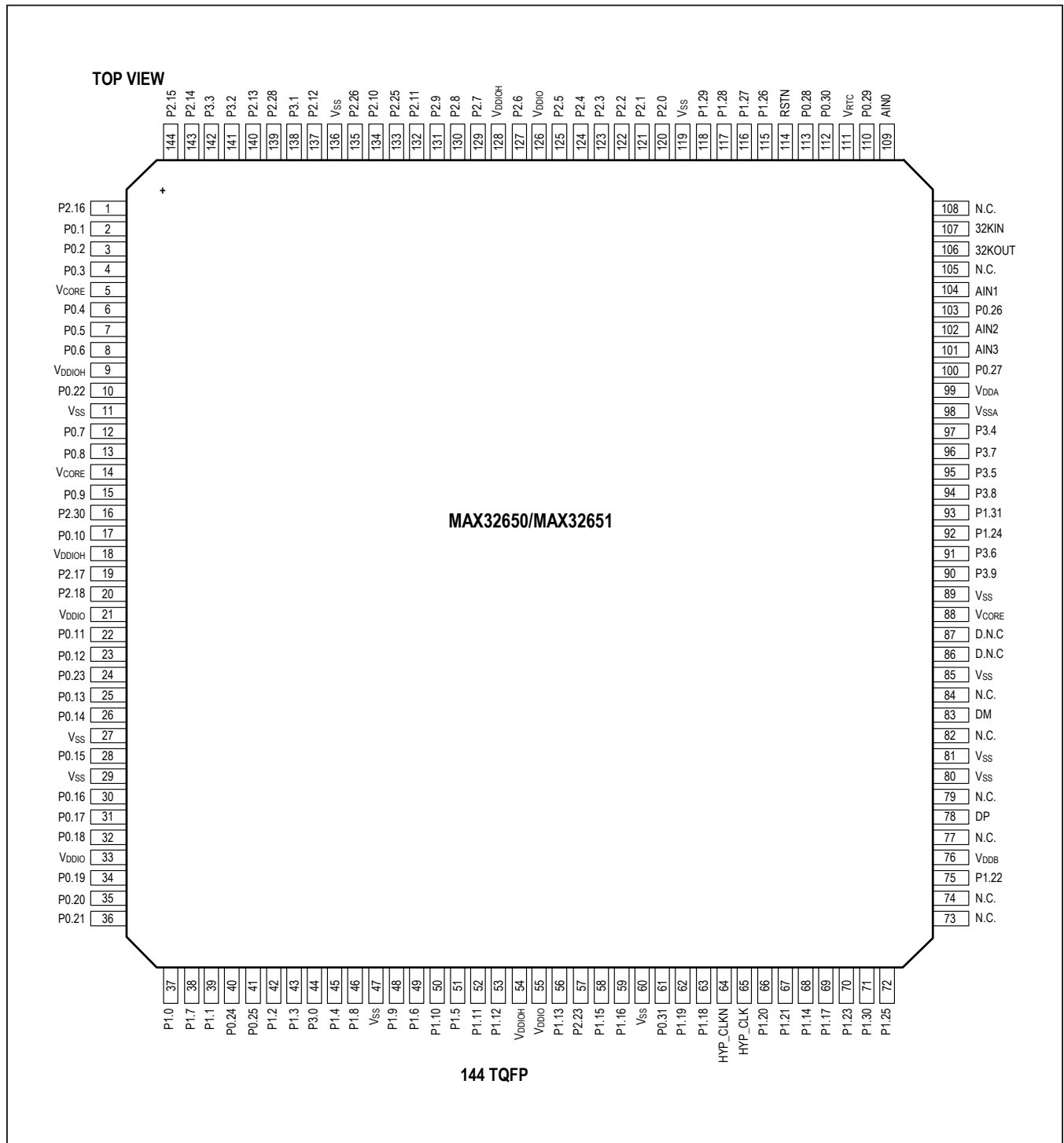
Pin Configurations



Pin Configurations (continued)



Pin Configurations (continued)



Pin Description

PIN			NAME	FUNCTION
140 WLP	96 WLP	144 TQFP		
<b>POWER</b>				
H1, H4, D12	G1, C8	5, 14, 88	V <sub>CORE</sub>	Core Supply Voltage. This pin must be bypassed to V <sub>SS</sub> with a 1.0µF capacitor as close as possible to the package.
H11	G10	99	V <sub>DDA</sub>	1.8V Analog Supply Voltage. This pin must be bypassed to V <sub>SSA</sub> with 1.0µF and 0.01µF capacitors as close as possible to the package.
B11	B9	76	V <sub>DDB</sub>	USB Transceiver Supply Voltage. This pin must be bypassed to V <sub>SS</sub> with a 1.0µF capacitor as close as possible to the package.
A7	A5	21	V <sub>DDIO</sub>	GPIO Supply Voltage. This pin must be bypassed to V <sub>SS</sub> with 1.0µF and 0.01µF capacitors as close as possible to the package.
E4, F1	B1, K5	33, 55		GPIO Supply Voltage. This pin must be bypassed to V <sub>SS</sub> with a 1.0µF and a 0.01µF capacitor as close as possible to the package.
M7	—	126		GPIO Supply Voltage. This pin must be bypassed to V <sub>SS</sub> with 1.0µF and 0.01µF capacitors as close as possible to the package.
A6	B5	9	V <sub>DDIOH</sub>	GPIO Supply Voltage, High. V <sub>DDIOH</sub> ≥ V <sub>DDIO</sub> . This pin must be bypassed to V <sub>SS</sub> with 1.0µF and 0.01µF capacitors as close as possible to the package.
G1, G4, M6	F1, K4	18, 54, 128		GPIO Supply Voltage, High. V <sub>DDIOH</sub> ≥ V <sub>DDIO</sub> . This pin must be bypassed to V <sub>SS</sub> with 1.0µF and 0.01µF capacitors as close as possible to the package.
M11	H8	111	V <sub>RTC</sub>	RTC Supply Voltage. This pin must be bypassed to V <sub>SS</sub> with a 1.0µF capacitor as close as possible to the package.
A4, A8, C11, D1, D11, F4, J1, M4, M9	B6, C1, C9, D8, K7, J2	11, 27, 29, 47, 60, 80, 81, 85, 89, 119, 136	V <sub>SS</sub>	Digital Ground
H12	G9	98	V <sub>SSA</sub>	Analog Ground
<b>RESET</b>				
L10	K8	114	RSTN	Hardware Power Reset (Active-Low) Input. The device remains in reset while this pin is in its active state. When the pin transitions to its inactive state, the device performs a POR reset (resetting all logic on all supplies except for real-time clock circuitry) and begins execution. This pin has an internal pullup to the V <sub>DDIO</sub> supply.
<b>CLOCK</b>				
L12	J10	107	32KIN	32kHz Crystal Oscillator Input. Connect a 32kHz crystal between 32KIN and 32KOUT for RTC operation. Optionally, an external clock source can be driven on 32KIN if the 32KOUT pin is left unconnected.
K12	H10	106	32KOUT	32kHz Crystal Oscillator Output
<b>GPIO AND ALTERNATE FUNCTIONS</b>				
F5	—	—	P0.0	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
L2	—	2	P0.1	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.

## Pin Description (continued)

PIN			NAME	FUNCTION
140 WLP	96 WLP	144 TQFP		
K3	—	3	P0.2	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
L1	—	4	P0.3	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
J3	—	6	P0.4	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
K2	—	7	P0.5	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
K1	—	8	P0.6	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
H3	—	12	P0.7	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
H2	—	13	P0.8	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
G3	—	15	P0.9	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
G2	—	17	P0.10	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
F2	E2	22	P0.11	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
F3	—	23	P0.12	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
E2	E1	25	P0.13	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
E3	D1	26	P0.14	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
D2	G4	28	P0.15	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
C1	F3	30	P0.16	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.



## Pin Description (continued)

PIN			NAME	FUNCTION
140 WLP	96 WLP	144 TQFP		
C2	E3	31	P0.17	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
D3	D2	32	P0.18	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
B1	F4	34	P0.19	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
C3	A2	35	P0.20	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
B2	C2	36	P0.21	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
J2	G5	10	P0.22	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
E1	—	24	P0.23	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
A2	—	40	P0.24	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
B3	—	41	P0.25	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
J10	F7	103	P0.26	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
H10	F8	100	P0.27	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
K10	G6	113	P0.28	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
G10	F6	110	P0.29	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
F10	G7	112	P0.30	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
F8	—	61	P0.31	General-Purpose I/O, Port 0. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.

## Pin Description (continued)

PIN			NAME	FUNCTION
140 WLP	96 WLP	144 TQFP		
D4	B2	37	P1.0	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
C4	D3	39	P1.1	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
D5	C3	42	P1.2	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
C5	E4	43	P1.3	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
B4	C4	45	P1.4	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
A5	D4	51	P1.5	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
B5	B4	49	P1.6	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
E5	—	38	P1.7	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
E6	A3	46	P1.8	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
D6	B3	48	P1.9	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
C6	A4	50	P1.10	General-Purpose I/O, Port 1. Most port pins have multiple special functions. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
B6	F5	52	P1.11	General-Purpose I/O, Port 1. Most port pins have multiple special functions. This pin is connected to V <sub>DDIO</sub> only. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
C7	E5	53	P1.12	General-Purpose I/O, Port 1. Most port pins have multiple special functions. This pin is connected to V <sub>DDIO</sub> only. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
B7	K2	56	P1.13	General-Purpose I/O, Port 1. Most port pins have multiple special functions. This pin is connected to V <sub>DDIO</sub> only. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.
A11	A9	68	P1.14	General-Purpose I/O, Port 1. Most port pins have multiple special functions. This pin is connected to V <sub>DDIO</sub> only. See <a href="#">Table 3</a> , <a href="#">Table 4</a> and <a href="#">Table 5</a> GPIO and Alternate Function Matrix tables for details.