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MAXM

Low-Cost, 230MHz, Single/Quad Op Amps with Rail-to-Rail Outputs and ±15kV ESD Protection

General Description

The MAX4385E/MAX4386E op amps are unity-gain stable devices that combine high-speed performance, rail-to-rail outputs, and ±15kV ESD protection. Targeted for applications where an input or an output is exposed to the outside world, such as video and communications, these devices are compliant with International ESD Standards: ±15kV IEC 1000-4-2 Air-Gap Discharge, ±8kV IEC 1000-4-2 Contact Discharge, and the ±15kV Human Body Model.

The MAX4385E/MAX4386E operate from a single 5V supply with a common-mode input voltage range that extends beyond VEE. The MAX4385E/MAX4386E consume only 5.5mA of quiescent supply current per amplifier while achieving a 230MHz -3dB bandwidth, 30MHz 0.1dB gain flatness and a 450V/us slew rate.

Applications

Set-Top Boxes Surveillance Video Systems Battery-Powered **Instruments** Analog-to-Digital Converter Interface CCD Imaging Systems Video Routing and Switching Systems Digital Cameras Video-on-Demand Video Line Driver

Features

- ♦ **ESD-Protected Inputs and Outputs ±15kV—Human Body Model ±8kV—IEC 1000-4-2 Contact Discharge ±15kV—IEC 1000-4-2 Air-Gap Discharge**
- ♦ **Low Cost and High Speed 230MHz -3dB Bandwidth 30MHz 0.1dB Gain Flatness 450V/µs Slew Rate**
- ♦ **Rail-to-Rail Outputs**
- ♦ **Input Common-Mode Range Extends Beyond VEE**
- ♦ **Low Differential Gain/Phase: 0.02%/0.01°**
- ♦ **Low Distortion at 5MHz -60dBc SFDR -58dB Total Harmonic Distortion**
- ♦ **Ultra-Small 5-Pin SOT23 and 14-Pin TSSOP Packages**

Ordering Information

Pin Configurations

/VI A XI*/V*I

__ Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

Typical Operating Circuit

ABSOLUTE MAXIMUM RATINGS

Power-Supply Voltage (VCC to VEE).........................-0.3V to +6V IN_+, IN_-, OUT_,.............................(VEE - 0.3V) to (VCC + 0.3V) Output Short-Circuit Duration to VCC or VEE...Continuous

Continuous Power Dissipation $(T_A = +70^{\circ}C)$ 5-Pin SOT23 (derate 8.7mW/°C above +70°C)...........696mW

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or at any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

(V_{CC} = 5V, V_{EE} = 0, V_{CM} = V_{CC}/2, V_{OUT} = V_{CC}/2, R_L = ∞ to V_{CC}/2, C_{BYPASS} = 2.2µF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.) (Note 1)

DC ELECTRICAL CHARACTERISTICS (continued)

(V_{CC} = 5V, V_{EE} = 0, V_{CM} = V_{CC}/2, V_{OUT} = V_{CC}/2, R_L = ∞ to V_{CC}/2, C_{BYPASS} = 2.2µF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.) (Note 1)

AC ELECTRICAL CHARACTERISTICS

(V_{CC} = 5V, V_{EE} = 0, V_{CM} = 1.5V, R_L = 100 Ω to V_{CC}/2, V_{OUT} = V_{CC}/2, A_{VCL} = 1V/V, T_A = +25°C, unless otherwise noted.)

Note 1: All devices are 100% production tested at T_A = +25°C. Specifications over temperature limits are guaranteed by design. **Note 2**: ESD protection is specified for test point A and test point B only (Figure 6).

Typical Operating Characteristics (V_{CC} = 5V, V_{EE} = 0, V_{CM} = 1.5V, A_{VCL} = 1V/V, R_L = 100 Ω to V_{CC}/2, T_A = +25°C, unless otherwise noted.)

MAX4385E/MAX4386E

Typical Operating Characteristics (continued)

(V_{CC} = 5V, V_{EE} = 0, V_{CM} = 1.5V, A_{VCL} = 1V/V, R_L = 100 Ω to V_{CC}/2, T_A = +25°C, unless otherwise noted.)

MAXM

MAX4385E/MAX4386E

MAX4385E/MAX4386E

Typical Operating Characteristics (continued)

(V_{CC} = 5V, V_{EE} = 0, V_{CM} = 1.5V, A_{VCL} = 1V/V, R_L = 100 Ω to V_{CC}/2, T_A = +25°C, unless otherwise noted.) LARGE-SIGNAL PULSE RESPONSE LARGE-SIGNAL PULSE RESPONSE VOLTAGE NOISE vs. FREQUENCY 1000 MAX4385E/86E toc19 MAX4385E/86E toc20 $A_{VCL} = 5 \dot{V} / V$ A_{VCL} = 2V/V
R_F = 200Ω $= 100Q$ $R_F = 250\Omega$ INPUT INPUT 500mV/div VOLTAGE NOISE (nV/√Hz) 200mV/div **VOLTAGE NOISE (nV/VHZ** 100 10 OUTPUT OUTPUT 1V/div 1V/div 1 20ns/div 20ns/div 10 100 1k 10k 1 10 100 1k 10k 100k FREQUENCY (Hz) ISOLATION RESISTANCE SMALL-SIGNAL BANDWIDTH vs. CAPACITIVE LOAD CURRENT NOISE vs. FREQUENCY vs. LOAD RESISTANCE 100 16 300 MAX4385E/86E toc22 MAX4385E/86E toc23 100 14 250 TT CURRENT NOISE (pA/VFZ) CURRENT NOISE (pA/√Hz) 12 \perp Ш BANDWIDTH (MHZ) BANDWIDTH (MHz) 200 10 RISO (Ω) 10 150 8 6 100 4 50 2 $\boldsymbol{0}$ 1 0 10 100 1k 10k 1 10 100 1k 10k 100k 0 200 100 300 400 500 FREQUENCY (Hz) CLOAD (pF) $R_{\text{LOAD}}(\Omega)$ OPEN-LOOP GAIN vs. RESISTIVE LOAD CROSSTALK vs. FREQUENCY 80 0 MAX4385E/86E toc26 $V_{CC} = 5V$ -10 70 -20 60

6 ___

 Ω

20 10

50

OPEN-LOOP GAIN (dB) 40 30

OPEN-LOOP GAIN (dB)

MAX4385E/86E toc25 -30 CROSSTALK (dB) CROSSTALK (dB) Ш -40 -50 -60 -70 -80 -90 -100 100k 100k 1M 10M 100M 1G 100 1k 10k FREQUENCY (Hz) R _{LOAD} (Ω)

MAX4385E/86E toc21

Typical Operating Characteristics (continued)

(V_{CC} = 5V, V_{EE} = 0, V_{CM} = 1.5V, A_{VCL} = 1V/V, R_L = 100 Ω to V_{CC}/2, T_A = +25°C, unless otherwise noted.)

Pin Description

Detailed Description

The MAX4385E/MAX4386E are single/quad, 5V, rail-torail, voltage-feedback amplifiers that employ currentfeedback techniques to achieve 450V/µs slew rates and 230MHz bandwidths. High ±15kV ESD protection guards against unexpected discharge. Excellent harmonic distortion and differential gain/phase performance make these amplifiers an ideal choice for a wide variety of video and RF signal-processing applications.

Applications Information

The output voltage swings to within 50mV of each supply rail. Local feedback around the output stage ensures low open-loop output impedance to reduce gain sensitivity to load variations. The input stage permits common-mode voltages beyond V_{EE} and to within 2.25V of the positive supply rail.

Choosing Resistor Values *Unity-Gain Configuration*

The MAX4385E/MAX4386E are internally compensated for unity gain. When configured for unity gain, a 24 Ω resistor (RF) in series with the feedback path optimizes AC performance. This resistor improves AC response by reducing the Q of the parallel LC circuit formed by the parasitic feedback capacitance and inductance.

Video Line Driver

The MAX4385E/MAX4386E are low-power, voltagefeedback amplifiers featuring bandwidths up to 230MHz, 0.1dB gain flatness to 30MHz. They are designed to minimize differential-gain error and differential-phase error to 0.02% and 0.01°, respectively. They have a 14ns settling time to 0.1%, 450V/us slew rates, and output-current-drive capability of up to 50mA, making them ideal for driving video loads.

Inverting and Noninverting Configurations

Select the gain-setting feedback (R_F) and input (R_G) resistor values to fit your application. Large resistor values increase voltage noise and interact with the amplifier's input and PC board capacitance. This can generate undesirable poles and zeros and decrease bandwidth or cause oscillations. For example, a noninverting gain-of-two configuration (RF = RG) using $1k\Omega$ resistors, combined with 8pF of amplifier input capacitance and 1pF of PC board capacitance, causes a pole at 35.4MHz. Since this pole is within the amplifier bandwidth, it jeopardizes stability. Reducing the $1k\Omega$ resistors to 100Ω extends the pole frequency to 353.8MHz, but could limit output swing by adding 200Ω in parallel with the amplifier's load resistor (Figures 1a and 1b).

Figure 1a. Noninverting Gain Configuration

Figure 1b. Inverting Gain Configuration

Layout and Power-Supply Bypassing

These amplifiers operate from a single 5V power supply. Bypass V_{CC} to ground with 0.1µF and 2.2µF capacitors as close to the pin as possible.

Maxim recommends using microstrip and stripline techniques to obtain full bandwidth. To ensure that the PC board does not degrade the amplifier's performance, design it for a frequency greater than 1GHz. Pay careful attention to inputs and outputs to avoid large parasitic capacitance. Regardless of whether you use a constant-impedance board, observe the following design guidelines:

- Do not use wire-wrap boards; they are too inductive.
- Do not use IC sockets; they increase parasitic capacitance and inductance.
- Use surface mount instead of through-hole components for better high-frequency performance.
- Use a PC board with at least two layers; it should be as free from voids as possible.
- Keep signal lines as short and as straight as possible. Do not make 90° turns; round all corners.

Figure 2. Driving a Capacitive Load Through an Isolation Resistor

Rail-to-Rail Outputs, Ground-Sensing Inputs

The input common-mode range extends from (VEE -200mV) to (V_{CC} - 2.25V) with excellent common-mode rejection. Beyond this range, the amplifier output is a nonlinear function of the input, but does not undergo phase reversal or latchup.

The output swings to within 50mV of either power-supply rail with a 2k Ω load. The input ground sensing and the rail-to-rail output substantially increase the dynamic range. The input can swing 2.95VP-P and the output can swing 4.9VP-P with minimal distortion.

Output Capacitive Loading and Stability The MAX4385E/MAX4386E are optimized for AC performance and do not drive highly reactive loads, which decreases phase margin and may produce excessive ringing and oscillation. Figure 2 shows a circuit that eliminates this problem. Figure 3 is a graph of the Optimal Isolation Resistor (RS) vs. Capacitive Load. Figure 4 shows how a capacitive load causes excessive peaking of the amplifier's frequency response if the capacitor is not isolated from the amplifier by a resistor. A small isolation resistor (usually 10Ω to 15Ω) placed before the reactive load prevents ringing and oscillation. At higher capacitive loads, the interaction of the load capacitance and the isolation resistor controls the AC performance. Figure 5 shows the effect of a 15Ω isolation resistor on closed-loop response.

Figure 4. Small-Signal Gain vs. Frequency with Load Capacitance and No Isolation Resistor

Figure 5. Small-Signal Gain vs. Frequency with Load Capacitance and 27Ω Isolation Resistor

ESD Protection

As with all Maxim devices, ESD protection structures are incorporated on all pins to protect against ESD encountered during handling and assembly. Input and output pins of the MAX4385E/MAX4386E have extra protection against static electricity. Maxim's engineers have developed state-of-the-art structures enabling these pins to withstand ESD up to \pm 15kV without damage when placed in the test circuit (Figure 6). The MAX4385E/MAX4386E are characterized for protection to the following limits:

- ±15kV using the Human Body Model
- ±8kV using the Contact Discharge method specified in IEC 1000-4-2
- ±15kV using the Air-Gap Discharge method specified in IEC 1000-4-2

Human Body Model

Figure 7 shows the Human Body Model, and Figure 8 shows the current waveform it generates when discharged into a low impedance. This model consists of a 150pF capacitor charged to the ESD voltage of interest, and then discharged into the test device through a 1.5kΩ resistor.

IEC 1000-4-2

The IEC 1000-4-2 standard covers ESD testing and performance of finished equipment; it does not specifically refer to ICs. The MAX4385E/MAX4386E enable the design of equipment that meets the highest level (Level 4) of IEC 1000-4-2 without the need for additional ESD protection components. The major difference between tests done using the Human Body Model and IEC 1000- 4-2 is higher peak current in IEC 1000-4-2. Because series resistance is lower in the IEC 1000-4-2 model, the ESD-withstand voltage measured to this standard is generally lower than that measured using the Human Body. Figure 10 shows the IEC 1000-4-2 model and Figure 9 shows the current waveform for the \pm 8kV IEC 1000-4-2 Level 4 ESD Contact Discharge test. The Air-Gap test involves approaching the device with a charged probe. The Contact Discharge method connects the probe to the device before the probe is energized.

Figure 6. ESD Test Circuit

Figure 8. Human Body Current Waveform

Figure 9. IEC 1000-4-2 ESD Test Model

Pin Configurations (continued)

Figure 10. IEC 1000-4-2 ESD Generator Current Waveform

Chip Information

MAX4385E TRANSISTOR COUNT: 124 MAX4386E TRANSISTOR COUNT: 264

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)

Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)

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