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# High-Performance, Single-Ended, Current-Mode PWM Controllers

MAX5070/MAX5071

## General Description

The MAX5070/MAX5071 BiCMOS, high-performance, current-mode PWM controllers have all the features required for wide input voltage range isolated/nonisolated power supplies. These controllers are used for low- and high-power universal input voltage and telecom power supplies.

The MAX5070/MAX5071 contain a fast comparator with only 60ns typical delay from current sense to the output for overcurrent protection. The MAX5070A/MAX5070B have an integrated error amplifier with the output at COMP. Soft-start is achieved by controlling the COMP voltage rise using external components.

The frequency is adjustable from 20kHz to 1MHz with an external resistor and capacitor. The timing capacitor discharge current is trimmed allowing for programmable dead time and maximum duty cycle for a given frequency. The available saw-toothed waveform at RT/CT can be used for slope compensation when needed.

The MAX5071A/MAX5071B include a bidirectional synchronization circuit allowing for multiple controllers to run at the same frequency to avoid beat frequencies. Synchronization is accomplished by simply connecting the SYNC pins of all devices together. When synchronizing with other devices, the MAX5071A/MAX5071B with the highest frequency synchronizes the other devices. Alternatively, the MAX5071A/MAX5071B can be synchronized to an external clock with an open-drain output stage running at a higher frequency.

The MAX5071C provides a clock output pulse (ADV\_CLK) that leads the driver output (OUT) by 110ns. The advanced clock signal is used to drive the secondary-side synchronous rectifiers.

The MAX5070/MAX5071 are available in 8-pin  $\mu$ MAX<sup>®</sup> and SO packages and operate over the automotive temperature range of -40°C to +125°C.

## Applications

- Universal Input AC/DC Power Supplies
- Isolated Telecom Power Supplies
- Isolated Power-Supply Modules
- Networking Systems
- Computer Systems/Servers
- Industrial Power Conversion
- Isolated Keep-Alive Circuits

$\mu$ MAX is a registered trademark of Maxim Integrated Products, Inc.

## Features

- ◆ Pin-for-Pin Replacement for UC2842 (MAX5070A) and UC2844 (MAX5070B)
- ◆ 2A Drive Source and 1A Sink Capability
- ◆ Up to 1MHz Switching Frequency Operation
- ◆ Bidirectional Synchronization (MAX5071A/MAX5071B)
- ◆ Advanced Output Drive for Secondary-Side Synchronous Rectification (MAX5071C)
- ◆ Fast 60ns Cycle-by-Cycle Current Limit
- ◆ Trimmed Oscillator Capacitor Discharge Current Sets Maximum Duty Cycle Accurately
- ◆ Accurate 5% Start and Stop Voltage with 6V Hysteresis
- ◆ Low 32 $\mu$ A Startup Current
- ◆ 5V Regulator Output (VREF) with 20mA Capability
- ◆ Overtemperature Shutdown

## Ordering Information

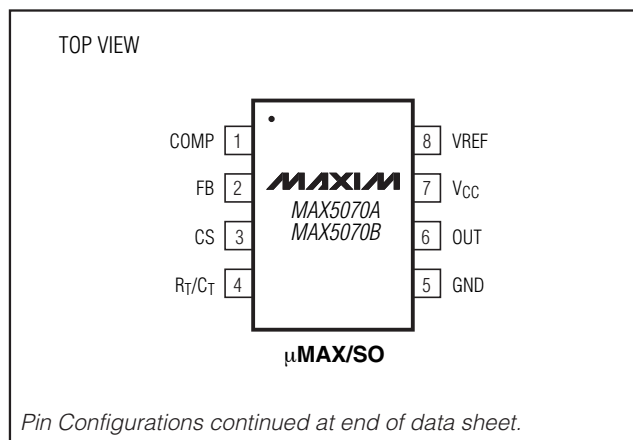
PART	TEMP RANGE	PIN-PACKAGE
MAX5070AASA	-40°C to +125°C	8 SO
MAX5070AAUA	-40°C to +125°C	8 $\mu$ MAX
MAX5070BASA	-40°C to +125°C	8 SO
MAX5070BAUA	-40°C to +125°C	8 $\mu$ MAX

Specify lead-free by adding the + symbol at the end of the part number when ordering.

Ordering Information continued at end of data sheet.

Selector Guide appears at end of data sheet.

## Pin Configurations



# High-Performance, Single-Ended, Current-Mode PWM Controllers

## ABSOLUTE MAXIMUM RATINGS

V<sub>CC</sub> (Low-Impedance Source) to GND .....-0.3V to +30V  
 V<sub>CC</sub> (I<sub>CC</sub> < 30mA).....Self Limiting  
 OUT to GND .....-0.3V to (V<sub>CC</sub> + 0.3V)  
 OUT Current.....±1A for 10μs  
 FB, SYNC, COMP, CS, R<sub>T</sub>/C<sub>T</sub>, VREF to GND .....-0.3V to +6V  
 COMP Sink Current (MAX5070).....10mA

Continuous Power Dissipation (T<sub>A</sub> = +70°C)  
 8-Pin μMAX (derate 4.5mW/°C above +70°C) .....362mW  
 8-Pin SO (derate 5.9mW/°C above +70°C).....470.6mW  
 Operating Temperature Range (Automotive) ....-40°C to +125°C  
 Maximum Junction Temperature .....+150°C  
 Storage Temperature Range .....-65°C to +150°C  
 Lead Temperature (soldering, 10s) .....+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub> = +15V, R<sub>T</sub> = 10kΩ, C<sub>T</sub> = 3.3nF, V<sub>VREF</sub> = OPEN, C<sub>VREF</sub> = 0.1μF, COMP = OPEN, V<sub>FB</sub> = 2V, CS = GND, T<sub>A</sub> = -40°C to +85°C, unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>REFERENCE</b>						
Output Voltage	V <sub>VREF</sub>	T <sub>A</sub> = +25°C, I <sub>VREF</sub> = 1mA	4.950	5.000	5.050	V
Line Regulation	ΔV <sub>LINE</sub>	12V < V <sub>CC</sub> < 25V, I <sub>VREF</sub> = 1mA		0.4	4	mV
Load Regulation	ΔV <sub>LOAD</sub>	1mA < I <sub>VREF</sub> < 20mA		6	25	mV
Total Output Variation	V <sub>REFT</sub>	1mA < I <sub>VREF</sub> < 20mA, 12V < V <sub>CC</sub> < 25V	4.9		5.1	V
Reference Output-Noise Voltage	V <sub>NOISE</sub>	10Hz < f < 10kHz, T <sub>A</sub> = +25°C		50		μV
Reference Output Short Circuit	I <sub>S_SC</sub>	V <sub>VREF</sub> = 0V	-30	-100	-180	mA
<b>OSCILLATOR</b>						
Initial Accuracy		T <sub>A</sub> = +25°C	51	54	57	kHz
Voltage Stability		12V < V <sub>CC</sub> < 25V		0.2	0.5	%
Temp Stability		-40°C < T <sub>A</sub> < +85°C		0.5		%
R <sub>T</sub> /C <sub>T</sub> Voltage Ramp (P-P)	V <sub>RAMP</sub>			1.7		V
R <sub>T</sub> /C <sub>T</sub> Voltage Ramp Valley	V <sub>RAMP_VALLEY</sub>			1.1		V
Discharge Current	I <sub>DIS</sub>	V <sub>RT/CT</sub> = 2V, T <sub>A</sub> = +25°C	7.9	8.3	8.7	mA
Frequency Range	f <sub>OSC</sub>		20		1000	kHz
<b>ERROR AMPLIFIER (MAX5070A/MAX5070B)</b>						
FB Input Voltage	V <sub>FB</sub>	FB shorted to COMP	2.465	2.5	2.535	V
FB Input Bias Current	I <sub>B(FB)</sub>			-0.01	-0.1	μA
Open-Loop Voltage Gain	A <sub>VOL</sub>	2V ≤ V <sub>COMP</sub> ≤ 4V		100		dB
Unity-Gain Bandwidth	f <sub>GBW</sub>			1		MHz
Power-Supply Rejection Ratio	PSRR	12V ≤ V <sub>CC</sub> ≤ 25V (Note 2)	60	80		dB
COMP Sink Current	I <sub>SINK</sub>	V <sub>FB</sub> = 2.7V, V <sub>COMP</sub> = 1.1V	2	6		mA
COMP Source Current	I <sub>SOURCE</sub>	V <sub>FB</sub> = 2.3V, V <sub>COMP</sub> = 5V	-0.5	-1.2	-1.8	mA
COMP Output High Voltage	V <sub>COMPH</sub>	V <sub>FB</sub> = 2.3V, R <sub>COMP</sub> = 15kΩ to GND	5	5.8		V
COMP Output Low Voltage	V <sub>COMPL</sub>	V <sub>FB</sub> = 2.7V, R <sub>COMP</sub> = 15kΩ to VREF		0.1	0.5	V
<b>CURRENT-SENSE AMPLIFIER</b>						
Gain	A <sub>CS</sub>	(Notes 3, 4)	2.85	3	3.26	V/V
Maximum Current-Sense Signal	V <sub>CS_MAX</sub>	MAX5070A/B (Note 3)	0.95	1	1.05	V
		V <sub>COMP</sub> = 5V, MAX5071_	0.95	1	1.05	



# High-Performance, Single-Ended, Current-Mode PWM Controllers

## ELECTRICAL CHARACTERISTICS (continued)

( $V_{CC} = +15V$ ,  $R_T = 10k\Omega$ ,  $C_T = 3.3nF$ ,  $V_{REF} = OPEN$ ,  $C_{VREF} = 0.1\mu F$ ,  $COMP = OPEN$ ,  $V_{FB} = 2V$ ,  $CS = GND$ ,  $T_A = -40^\circ C$  to  $+85^\circ C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Power-Supply Rejection Ratio	PSRR	$12V \leq V_{CC} \leq 25V$		70		dB
Input Bias Current	$I_{CS}$	$V_{COMP} = 0V$		-1	-2.5	$\mu A$
Delay From CS to OUT	$t_{CS\_DELAY}$	50mV overdrive		60		ns
<b>MOSFET DRIVER</b>						
OUT Low-Side On-Resistance	$V_{RDS\_ONL}$	$I_{SINK} = 200mA$		4.5	10	$\Omega$
OUT High-Side On-Resistance	$V_{RDS\_ONH}$	$I_{SOURCE} = 100mA$		3.5	7	$\Omega$
$I_{SOURCE}$ (Peak)	$I_{SOURCE}$	$C_{OUT} = 10nF$		2		A
$I_{SINK}$ (Peak)	$I_{SINK}$	$C_{OUT} = 10nF$		1		A
Rise Time	$t_r$	$C_{OUT} = 1nF$		15		ns
Fall Time	$t_f$	$C_{OUT} = 1nF$		22		ns
<b>UNDERVOLTAGE LOCKOUT/STARTUP</b>						
Startup Voltage Threshold	$V_{CC\_START}$		15.2	16	16.8	V
Minimum Operating Voltage After Turn-On	$V_{CC\_MIN}$		9.2	10	10.8	V
Undervoltage-Lockout Hysteresis	$UVLO_{HYST}$			6		V
<b>PWM</b>						
Maximum Duty Cycle	$D_{MAX}$	MAX5070A/MAX5071A	94.5	96	97.5	%
		MAX5070B/MAX5071B/MAX5071C	48	49.8	50	
Minimum Duty Cycle	$D_{MIN}$				0	%
<b>SUPPLY CURRENT</b>						
Startup Supply Current	$I_{START}$			32	65	$\mu A$
Operating Supply Current	$I_{CC}$	$V_{FB} = V_{CS} = 0V$		3	5	mA
Zener Bias Voltage at $V_{CC}$	$V_Z$	$I_{CC} = 25mA$	24	26.5		V
<b>THERMAL SHUTDOWN</b>						
Thermal Shutdown	$T_{SHDN}$			+150		$^\circ C$
Thermal-Shutdown Hysteresis	$T_{HYST}$			4		$^\circ C$
<b>SYNCHRONIZATION (MAX5071A/MAX5071B only) (Note 5)</b>						
SYNC Frequency Range	$f_{SYNC}$		20		1000	kHz
SYNC Clock Input High Threshold	$V_{SYNCINH}$		3.5			V
SYNC Clock Input Low Threshold	$V_{SYNCINL}$				0.8	V
SYNC Clock Input Minimum Pulse Width	$t_{PW\_SYNCIN}$		200			ns
SYNC Clock Output High Level	$V_{SYNCOH}$	1mA external pulldown	4.0	4.7		V
SYNC Clock Output Low Level	$V_{SYNCOL}$	$R_{SYNC} = 5k\Omega$		0	0.1	V
SYNC Leakage Current	$I_{SYNC}$	$V_{SYNC} = 0V$		0.01	0.1	$\mu A$

# High-Performance, Single-Ended, Current-Mode PWM Controllers

## ELECTRICAL CHARACTERISTICS (continued)

( $V_{CC} = +15V$ ,  $R_T = 10k\Omega$ ,  $C_T = 3.3nF$ ,  $V_{VREF} = OPEN$ ,  $C_{VREF} = 0.1\mu F$ ,  $COMP = OPEN$ ,  $V_{FB} = 2V$ ,  $CS = GND$ ,  $T_A = -40^\circ C$  to  $+85^\circ C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>ADV_CLK (MAX5071C only)</b>						
ADV_CLK High Voltage	$V_{ADV\_CLKH}$	$I_{ADV\_CLK} = 10mA$ source	2.4	3		V
ADV_CLK Low Voltage	$V_{ADV\_CLKL}$	$I_{ADV\_CLK} = 10mA$ sink			0.4	V
ADV_CLK Output Pulse Width	$t_{PULSE}$			85		ns
ADV_CLK Rising Edge to OUT Rising Edge	$t_{ADV\_CLK}$			110		ns
ADV_CLK Source and Sink Current	$I_{ADV\_CLK}$		10			mA

## ELECTRICAL CHARACTERISTICS

( $V_{CC} = +15V$ ,  $R_T = 10k\Omega$ ,  $C_T = 3.3nF$ ,  $V_{VREF} = OPEN$ ,  $C_{VREF} = 0.1\mu F$ ,  $COMP = OPEN$ ,  $V_{FB} = 2V$ ,  $CS = GND$ ,  $T_A = -40^\circ C$  to  $+125^\circ C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>REFERENCE</b>						
Output Voltage	$V_{VREF}$	$T_A = +25^\circ C$ , $I_{VREF} = 1mA$	4.950	5.000	5.050	V
Line Regulation	$\Delta V_{LINE}$	$12V < V_{CC} < 25V$ , $I_{VREF} = 1mA$		0.4	4	mV
Load Regulation	$\Delta V_{LOAD}$	$1mA < I_{VREF} < 20mA$		6	25	mV
Total Output Variation	$V_{REFT}$	$1mA < I_{VREF} < 20mA$ , $12V < V_{CC} < 25V$	4.9		5.1	V
Reference Output Noise Voltage	$V_{NOISE}$	$10Hz < f < 10kHz$ , $T_A = +25^\circ C$		50		$\mu V$
Reference Output Short Circuit	$I_{S\_SC}$	$V_{VREF} = 0V$	-30	-100	-180	mA
<b>OSCILLATOR</b>						
Initial Accuracy		$T_A = +25^\circ C$	51	54	57	kHz
Voltage Stability		$12V < V_{CC} < 25V$		0.2	0.5	%
Temp Stability		$-40^\circ C < T_A < +125^\circ C$		1		%
$R_T/C_T$ Voltage Ramp (P-P)	$V_{RAMP}$			1.7		V
$R_T/C_T$ Voltage Ramp Valley	$V_{RAMP\_VALLEY}$			1.1		V
Discharge Current	$I_{DIS}$	$V_{RT/CT} = 2V$ , $T_A = +25^\circ C$	7.9	8.3	8.7	mA
Frequency Range	$f_{OSC}$		20		1000	kHz
<b>ERROR AMPLIFIER (MAX5070A/MAX5070B)</b>						
FB Input Voltage	$V_{FB}$	FB shorted to COMP	2.465	2.5	2.535	V
FB Input Bias Current	$I_{B(FB)}$			-0.01	-0.1	$\mu A$
Open-Loop Voltage Gain	$A_{VOL}$	$2V \leq V_{COMP} \leq 4V$		100		dB
Unity-Gain Bandwidth	$f_{GBW}$			1		MHz
Power-Supply Rejection Ratio	PSRR	$12V \leq V_{CC} \leq 25V$ (Note 2)	60	80		dB
COMP Sink Current	$I_{SINK}$	$V_{FB} = 2.7V$ , $V_{COMP} = 1.1V$	2	6		mA
COMP Source Current	$I_{SOURCE}$	$V_{FB} = 2.3V$ , $V_{COMP} = 5V$	-0.5	-1.2	-1.8	mA
COMP Output High Voltage	$V_{COMPH}$	$V_{FB} = 2.3V$ , $R_{COMP} = 15k\Omega$ to GND	5	5.8		V
COMP Output Low Voltage	$V_{COMPL}$	$V_{FB} = 2.7V$ , $R_{COMP} = 15k\Omega$ to VREF		0.1	0.5	V

# High-Performance, Single-Ended, Current-Mode PWM Controllers

## ELECTRICAL CHARACTERISTICS (continued)

( $V_{CC} = +15V$ ,  $R_T = 10k\Omega$ ,  $C_T = 3.3nF$ ,  $V_{VREF} = OPEN$ ,  $C_{VREF} = 0.1\mu F$ ,  $COMP = OPEN$ ,  $V_{FB} = 2V$ ,  $CS = GND$ ,  $T_A = -40^\circ C$  to  $+125^\circ C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>CURRENT-SENSE AMPLIFIER</b>						
Gain	ACS	(Notes 3, 4)	2.85	3	3.26	V/V
Maximum Current-Sense Signal	VCS_MAX	MAX5070A/B (Note 3)	0.95	1	1.05	V
		VCOMP = 5V, MAX5071_	0.95	1	1.05	
Power-Supply Rejection Ratio	PSRR	$12V \leq V_{CC} \leq 25V$		70		dB
Input Bias Current	I <sub>CS</sub>			-1	-2.5	$\mu A$
Delay From CS to OUT	t <sub>CS_DELAY</sub>	50mV overdrive		60		ns
<b>MOSFET DRIVER</b>						
OUT Low-Side On-Resistance	V <sub>RDS_ONL</sub>	I <sub>SINK</sub> = 200mA		4.5	12	$\Omega$
OUT High-Side On-Resistance	V <sub>RDS_ONH</sub>	I <sub>SOURCE</sub> = 100mA		3.5	9	$\Omega$
I <sub>SOURCE</sub> (Peak)	I <sub>SOURCE</sub>	C <sub>OUT</sub> = 10nF		2		A
I <sub>SINK</sub> (Peak)	I <sub>SINK</sub>	C <sub>OUT</sub> = 10nF		1		A
Rise Time	t <sub>r</sub>	C <sub>OUT</sub> = 1nF		15		ns
Fall Time	t <sub>f</sub>	C <sub>OUT</sub> = 1nF		22		ns
<b>UNDERVOLTAGE LOCKOUT/STARTUP</b>						
Startup Voltage Threshold	V <sub>CC_START</sub>		15.2	16	16.8	V
Minimum Operating Voltage After Turn-On	V <sub>CC_MIN</sub>		9.2	10	10.8	V
Undervoltage-Lockout Hysteresis	UVLO <sub>HYST</sub>			6		V
<b>PWM</b>						
Maximum Duty Cycle	D <sub>MAX</sub>	MAX5070A/MAX5071A	94.5	96	97.5	%
		MAX5070B/MAX5071B/MAX5071C	48	49.8	50	
Minimum Duty Cycle	D <sub>MIN</sub>				0	%
<b>SUPPLY CURRENT</b>						
Startup Supply Current	I <sub>START</sub>			32	65	$\mu A$
Operating Supply Current	I <sub>CC</sub>	V <sub>FB</sub> = V <sub>CS</sub> = 0V		3	5	mA
Zener Bias Voltage at V <sub>CC</sub>	V <sub>Z</sub>	I <sub>CC</sub> = 25mA	24	26.5		V
<b>THERMAL SHUTDOWN</b>						
Thermal Shutdown	T <sub>SHDN</sub>			+150		$^\circ C$
Thermal-Shutdown Hysteresis	T <sub>HYST</sub>			4		$^\circ C$
<b>SYNCHRONIZATION (MAX5071A/MAX5071B only, Note 5)</b>						
SYNC Frequency Range	f <sub>SYNC</sub>		20		1000	kHz
SYNC Clock Input High Threshold	V <sub>SYNCINH</sub>		3.5			V
SYNC Clock Input Low Threshold	V <sub>SYNCINL</sub>				0.8	V
SYNC Clock Input Minimum Pulse Width	t <sub>PW_SYNCIN</sub>		200			ns
SYNC Clock Output High Level	V <sub>SYNCOH</sub>	1mA external pulldown	4.0	4.7		V
SYNC Clock Output Low Level	V <sub>SYNCOL</sub>	R <sub>SYNC</sub> = 5k $\Omega$		0	0.1	V

# High-Performance, Single-Ended, Current-Mode PWM Controllers

## ELECTRICAL CHARACTERISTICS (continued)

( $V_{CC} = +15V$ ,  $R_T = 10k\Omega$ ,  $C_T = 3.3nF$ ,  $V_{REF} = OPEN$ ,  $C_{VREF} = 0.1\mu F$ ,  $COMP = OPEN$ ,  $V_{FB} = 2V$ ,  $CS = GND$ ,  $T_A = -40^\circ C$  to  $+125^\circ C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SYNC Leakage Current	$I_{SYNC}$	$V_{SYNC} = 0V$		0.01	0.1	$\mu A$
<b>ADV_CLK (MAX5071C only)</b>						
ADV_CLK High Voltage	$V_{ADV\_CLKH}$	$I_{ADV\_CLK} = 10mA$ source	2.4	3		V
ADV_CLK Low Voltage	$V_{ADV\_CLKL}$	$I_{ADV\_CLK} = 10mA$ sink			0.4	V
ADV_CLK Output Pulse Width	$t_{PULSE}$			85		ns
ADV_CLK Rising Edge to OUT Rising Edge	$t_{ADV\_CLK}$			110		ns
ADV_CLK Source and Sink Current	$I_{ADV\_CLK}$		10			mA

**Note 1:** All devices are 100% tested at  $+25^\circ C$ . All limits over temperature are guaranteed by design, not production tested.

**Note 2:** Guaranteed by design, not production tested.

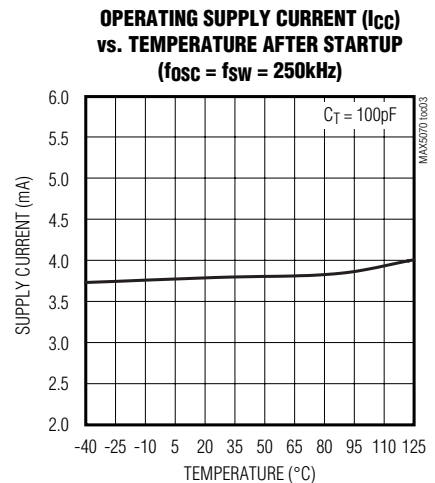
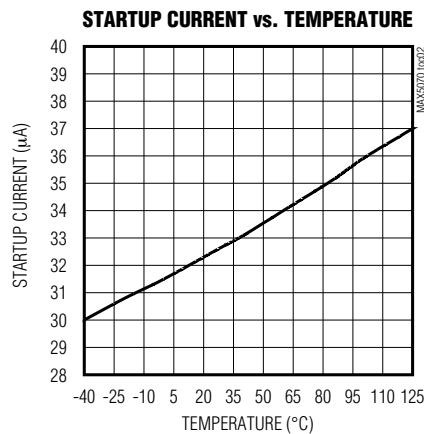
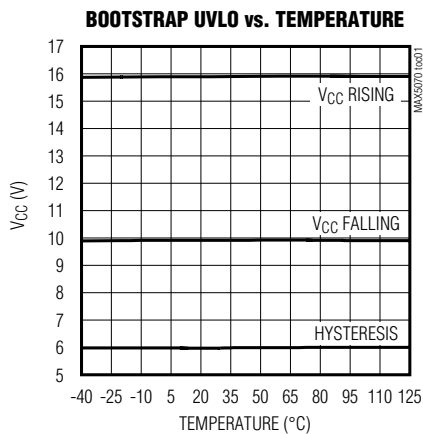
**Note 3:** Parameter measured at trip point of latch with  $V_{FB} = 0V$  (MAX5070A/MAX5070B only).

**Note 4:** Gain is defined as  $A = \Delta V_{COMP}/\Delta V_{CS}$ ,  $0 \leq V_{CS} \leq 0.8V$ .

**Note 5:** Output Frequency equals oscillator frequency for MAX5070A/MAX5071A. Output frequency is one-half oscillator frequency for MAX5070B/MAX5071B/MAX5071C.

## Typical Operating Characteristics

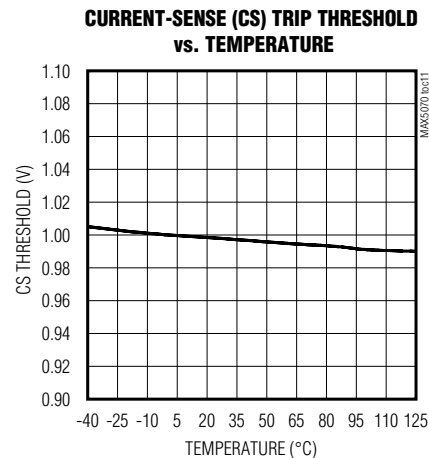
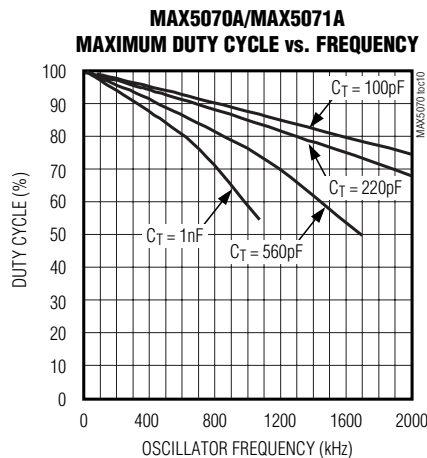
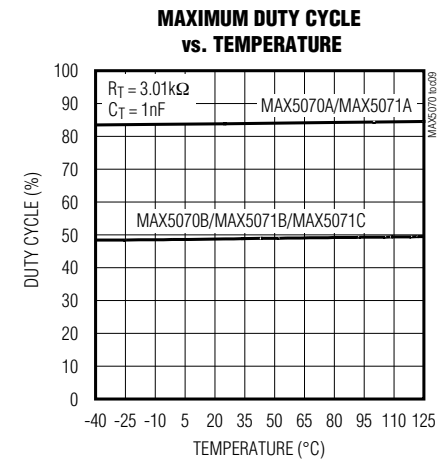
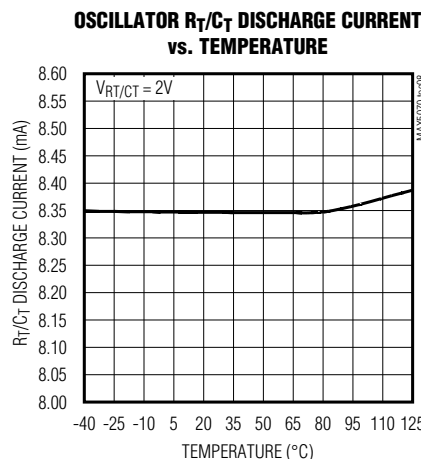
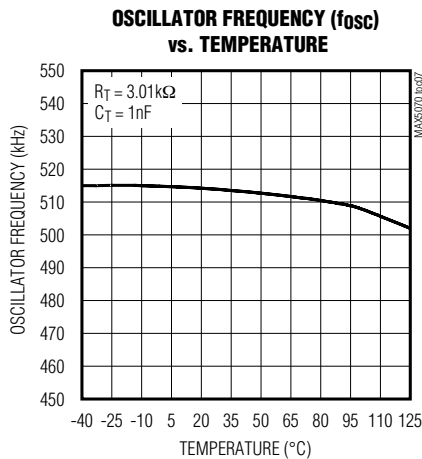
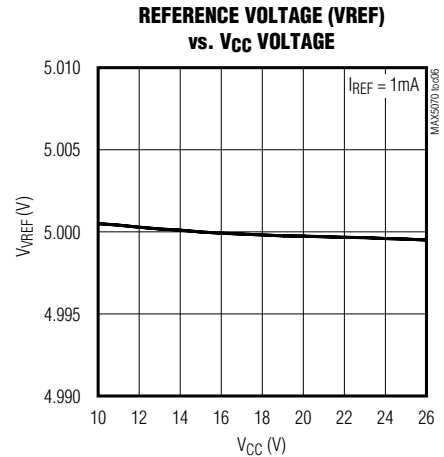
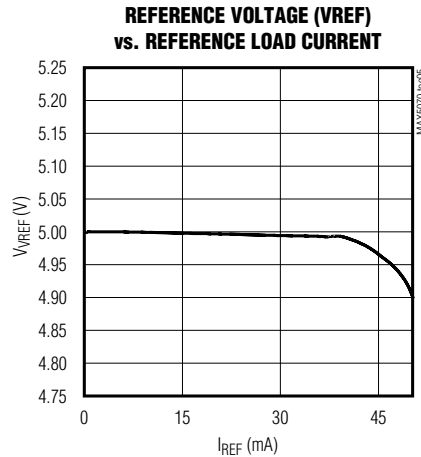
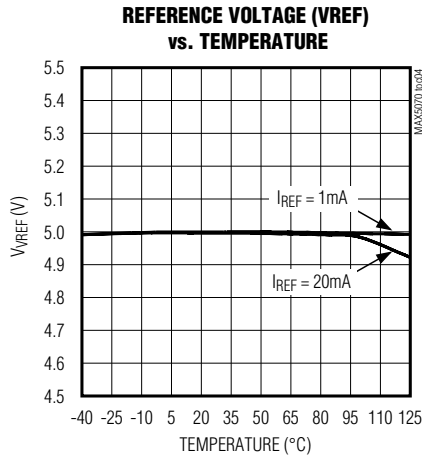
( $V_{CC} = 15V$ ,  $T_A = +25^\circ C$ , unless otherwise noted.)



# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Typical Operating Characteristics (continued)

( $V_{CC} = 15V$ ,  $T_A = +25^\circ C$ , unless otherwise noted.)

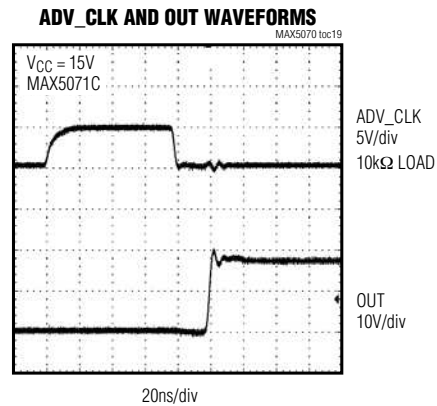
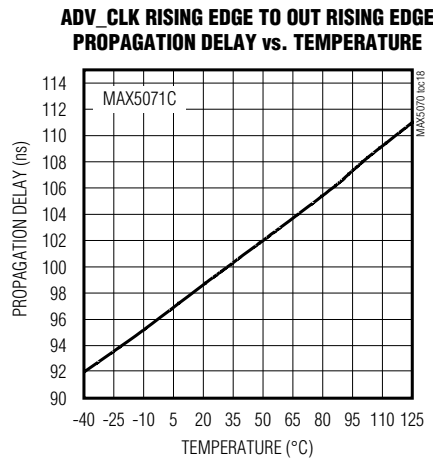
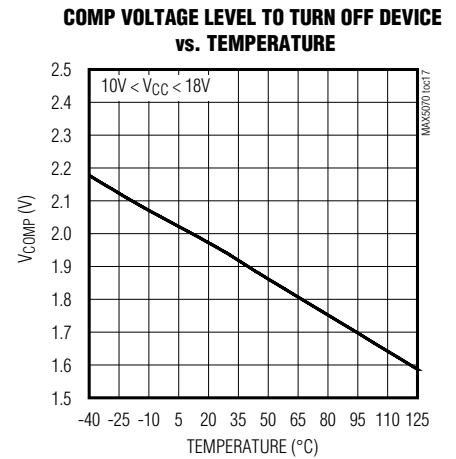
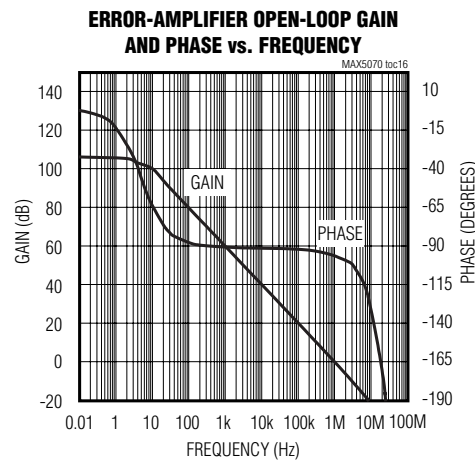
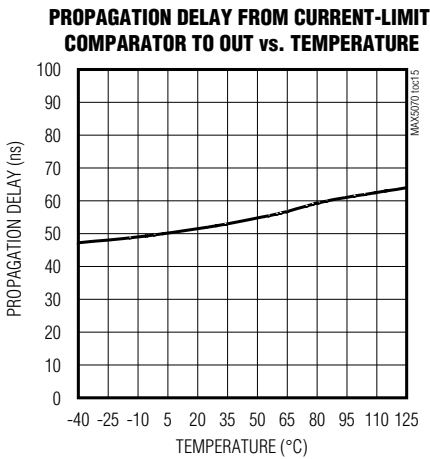
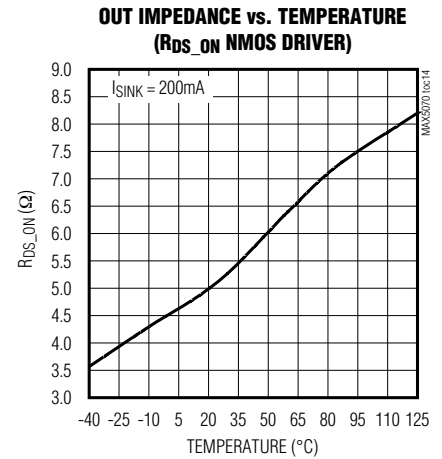
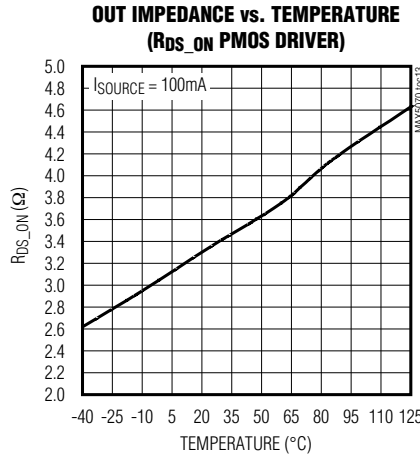
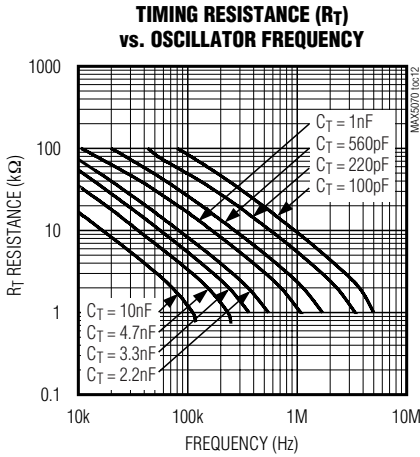




# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Typical Operating Characteristics (continued)

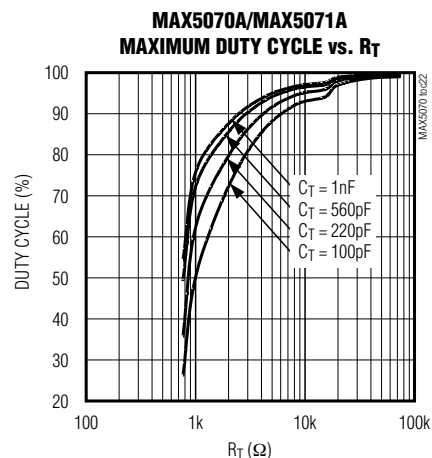
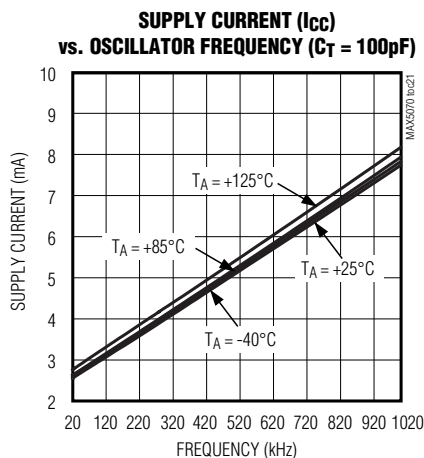
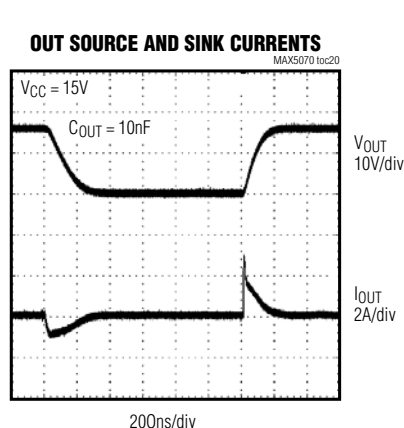
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# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Typical Operating Characteristics (continued)

( $V_{CC} = 15V$ ,  $T_A = +25^\circ C$ , unless otherwise noted.)



## Pin Descriptions

### MAX5070A/MAX5070B

PIN	NAME	FUNCTION
1	COMP	Error-Amplifier Output. COMP can be used for soft-start.
2	FB	Error-Amplifier Inverting Input
3	CS	Input to the PWM Comparator and Overcurrent Protection Comparator. The current-sense signal is compared to a signal proportional to the error-amplifier output voltage.
4	$R_T/C_T$	Timing Resistor and Capacitor Connection. A resistor $R_T$ from $R_T/C_T$ to $V_{REF}$ and capacitor $C_T$ from $R_T/C_T$ to GND set the oscillator frequency.
5	GND	Power-Supply Ground. Place the $V_{CC}$ and $V_{REF}$ bypass capacitors close to the IC to minimize ground loops.
6	OUT	MOSFET Driver Output. OUT connects to the gate of the external n-channel MOSFET.
7	$V_{CC}$	Power-Supply Input for MAX5070. Bypass $V_{CC}$ to GND with a $0.1\mu F$ ceramic capacitor or a parallel combination of a $0.1\mu F$ and a higher value ceramic capacitor.
8	$V_{REF}$	5V Reference Output. Bypass $V_{REF}$ to GND with a $0.1\mu F$ ceramic capacitor or a parallel combination of a $0.1\mu F$ and a higher value ceramic capacitor.

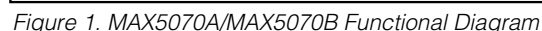
# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Pin Descriptions (continued)

### MAX5071A/MAX5071B/MAX5071C

PIN		NAME	FUNCTION
MAX5071A/ MAX5071B	MAX5071C		
1	1	COMP	COMP is level-shifted and connected to the inverting input of the PWM comparator. Pull up COMP to VREF through a resistor and connect an optocoupler from COMP to GND for proper operation.
2	—	SYNC	Bidirectional Synchronization Input. When synchronizing with other MAX5071A/MAX5071Bs, the higher frequency part synchronizes all other devices.
—	2	ADV_CLK	ADV_CLK is an 85ns clock output pulse preceding the rising edge of OUT (see Figure 4). Use the pulse to drive the secondary-side synchronous rectifiers through a pulse transformer or an optocoupler (see Figure 8).
3	3	CS	Input to the PWM Comparator and Overcurrent Protection Comparator. The current-sense signal is compared to the voltage at COMP.
4	4	R <sub>T</sub> /C <sub>T</sub>	Timing Resistor and Capacitor Connection. A resistor R <sub>T</sub> from R <sub>T</sub> /C <sub>T</sub> to VREF and capacitor C <sub>T</sub> from R <sub>T</sub> /C <sub>T</sub> to GND set the oscillator frequency.
5	5	GND	Power-Supply Ground. Place the V <sub>CC</sub> and VREF bypass capacitors close to the IC to minimize ground loops.
6	6	OUT	MOSFET Driver Output. OUT connects to the gate of the external n-channel MOSFET.
7	7	V <sub>CC</sub>	Power-Supply Input for MAX5071. Bypass V <sub>CC</sub> to GND with a 0.1μF ceramic capacitor or a parallel combination of a 0.1μF and a higher value ceramic capacitor.
8	8	VREF	5V Reference Output. Bypass VREF to GND with a 0.1μF ceramic capacitor or a parallel combination of a 0.1μF and a higher value ceramic capacitor.

**MAX5070/MAX5071**



The MAX5070/MAX5071 current-mode PWM controllers are designed for use as the control and regulation core of flyback or forward topology switching power supplies. These devices incorporate an integrated low-side driver, adjustable oscillator, error amplifier (MAX5070A/MAX5070B only), current-sense amplifier, 5V reference, and external synchronization capability (MAX5071A/MAX5071B only). An internal +26.5V current-limited V<sub>CC</sub> clamp prevents overvoltage during startup.

versions with a feedback input (FB) and internal error amplifier. The MAX5071A/MAX5071B include bidirectional synchronization (SYNC). This enables multiple MAX5071A/MAX5071Bs to be connected and synchronized to the device with the highest frequency. The MAX5071C includes an ADV\_CLK output, which precedes the MAX5071C's drive output (OUT) by 110ns. Figures 1, 2, and 3 show the internal functional diagrams of the MAX5070A/MAX5070B, MAX5071A/MAX5071B, and MAX5071C, respectively. The MAX5070A/MAX5071A are capable of 100% maximum duty cycle. The MAX5070B/MAX5071B/MAX5071C are designed to limit the maximum duty cycle to 50%.

# High-Performance, Single-Ended, Current-Mode PWM Controllers

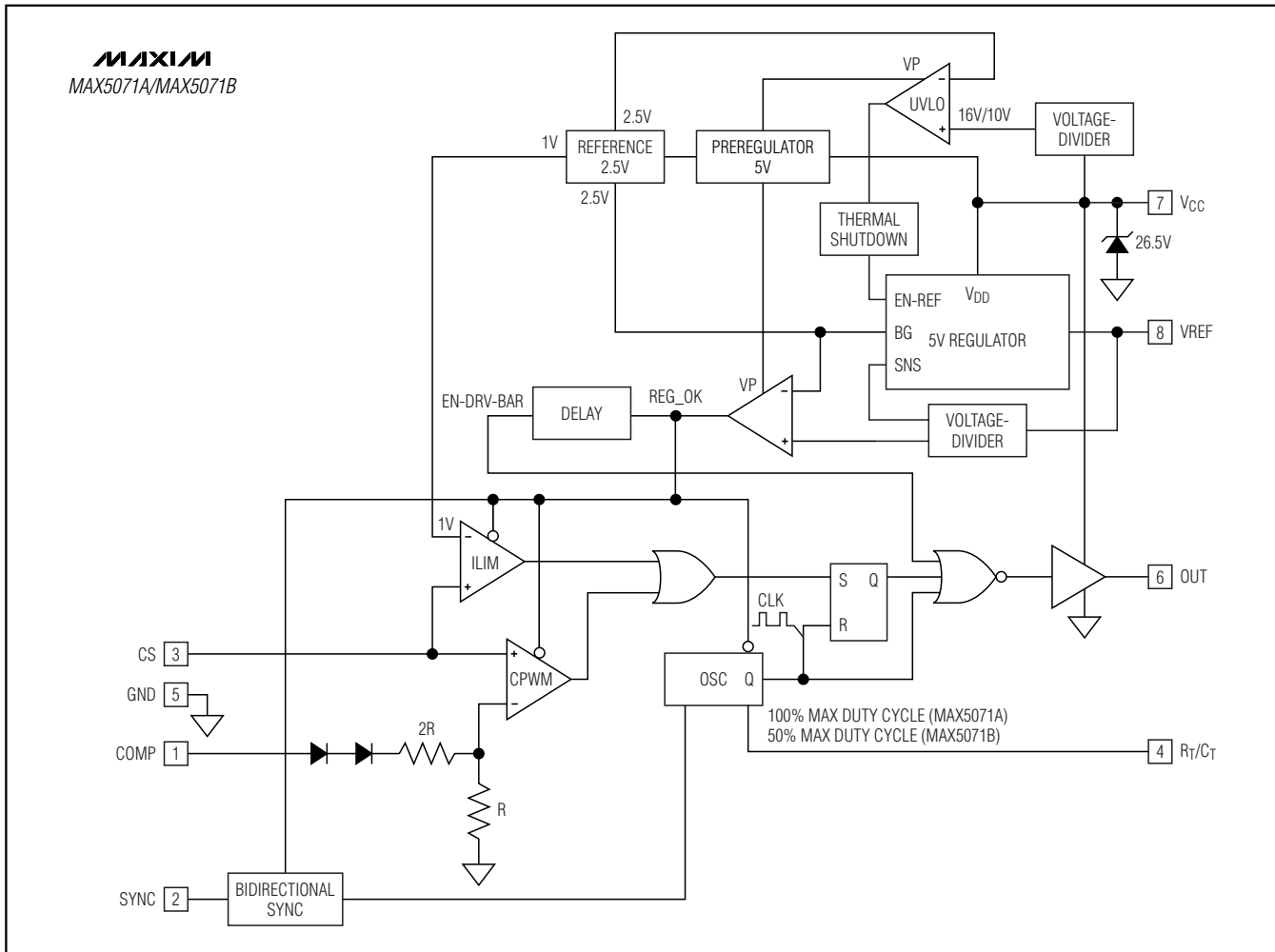


Figure 2. MAX5071A/MAX5071B Functional Diagram

## Current-Mode Control Loop

The advantages of current-mode control over voltage-mode control are twofold. First, there is the feed-forward characteristic brought on by the controller's ability to adjust for variations in the input voltage on a cycle-by-cycle basis. Secondly, the stability requirements of the current-mode controller are reduced to that of a single-pole system unlike the double pole in the voltage-mode control scheme.

The MAX5070/MAX5071 use a current-mode control loop where the output of the error amplifier is compared to the current-sense voltage ( $V_{CS}$ ). When the current-sense signal is lower than the noninverting input of the PWM comparator, the output of the CPWM comparator is low and the switch is turned on at each clock pulse. When the current-sense signal is higher than the inverting input of the CPWM, the output of the CPWM comparator is high and the switch is turned off.

# High-Performance, Single-Ended, Current-Mode PWM Controllers

MAX5070/MAX5071

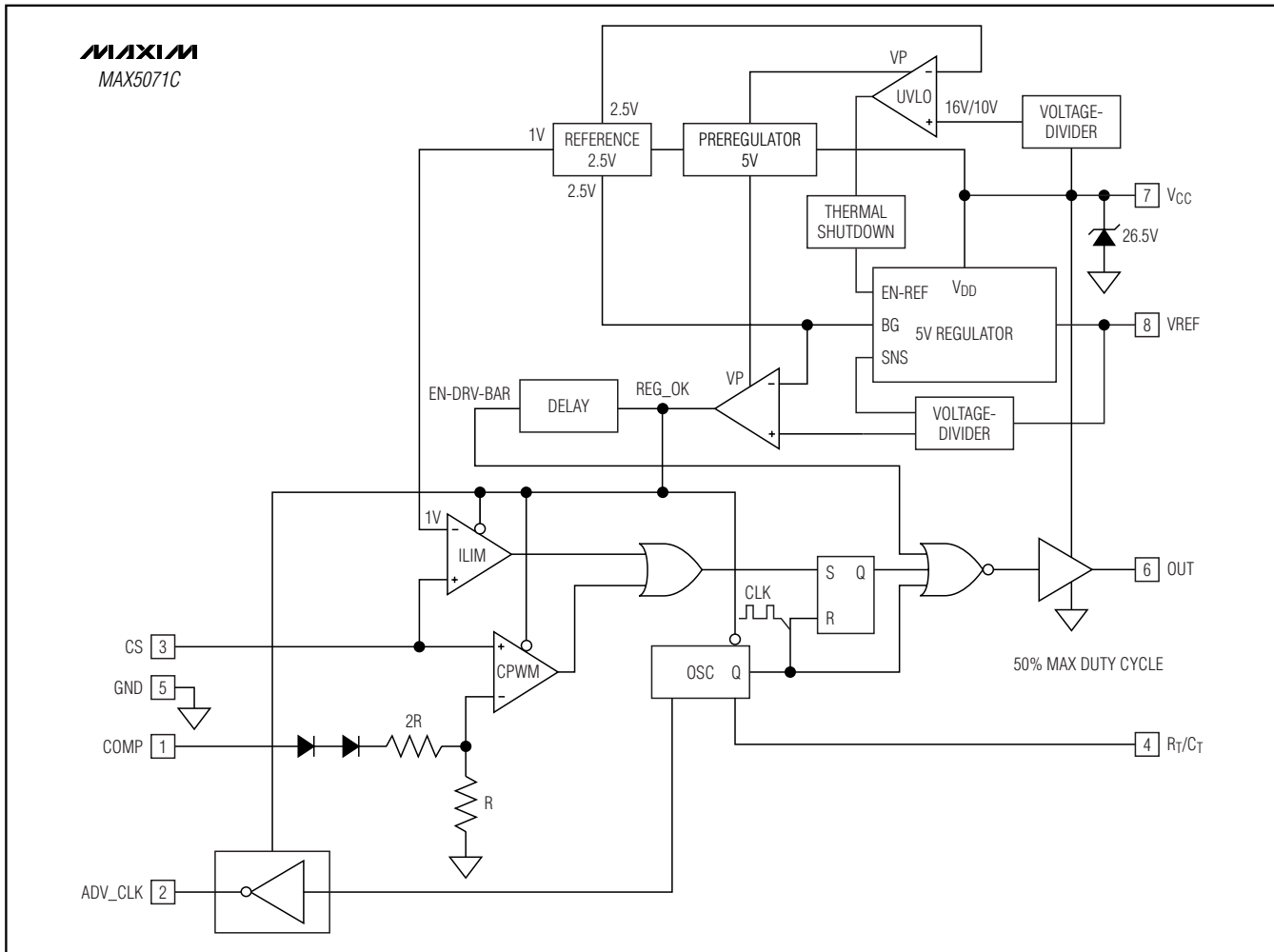


Figure 3. MAX5071C Functional Diagram

## V<sub>CC</sub> and Startup

In normal operation, V<sub>CC</sub> is derived from a tertiary winding of the transformer. However, at startup there is no energy delivered through the transformer, thus a resistor must be connected from V<sub>CC</sub> to the input power source (see R<sub>ST</sub> and C<sub>ST</sub> in Figures 5 to 8). During startup, C<sub>ST</sub> charges up through R<sub>ST</sub>. The 5V reference generator, comparator, error amplifier, oscillator, and drive circuit remain off during UVLO to reduce startup current below 65μA. When V<sub>CC</sub> reaches the undervoltage-lockout threshold of 16V, the output driver begins to switch and the tertiary winding will supply power to V<sub>CC</sub>. V<sub>CC</sub> has an internal 26.5V current-limited clamp at its input to protect the device from overvoltage during startup.

Size the startup resistor, R<sub>ST</sub>, to supply both the maximum startup bias (I<sub>START</sub>) of the device (65μA max) and the charging current for C<sub>ST</sub>. The startup capacitor C<sub>ST</sub> must charge to 16V within the desired time period t<sub>ST</sub> (for example, 500ms). The size of the startup capacitor depends on:

- 1) IC operating supply current at a programmed oscillator frequency (f<sub>OSC</sub>).
- 2) The time required for the bias voltage, derived from a bias winding, to go from 0 to 11V.
- 3) The MOSFET total gate charge.
- 4) The operating frequency of the converter (f<sub>SW</sub>).



# High-Performance, Single-Ended, Current-Mode PWM Controllers

To calculate the capacitance required, use the following formula:

$$C_{ST} = \frac{\left[ I_{CC} + I_G - \left( \frac{V_{INMIN} - 13V}{R_{ST}} \right) \right] (t_{SS})}{V_{HYST}}$$

where:

$$I_G = Q_G f_{SW}$$

$I_{CC}$  is the MAX5070/MAX5071s' maximum internal supply current after startup (see the *Typical Operating Characteristics* to find the  $I_{IN}$  at a given  $f_{OSC}$ ).  $Q_G$  is the total gate charge for the MOSFET,  $f_{SW}$  is the converter switching frequency,  $V_{HYST}$  is the bootstrap UVLO hysteresis (6V), and  $t_{SS}$  is the soft-start time, which is set by external circuitry.

Size the resistor  $R_{ST}$  according to the desired startup time period,  $t_{ST}$ , for the calculated  $C_{ST}$ . Use the following equations to calculate the average charging current ( $I_{CST}$ ) and the startup resistor ( $R_{ST}$ ).

$$I_{CST} = \frac{V_{SUVR} \times C_{ST}}{t_{ST}}$$

$$R_{ST} = \frac{\left( V_{INMIN} - \frac{V_{SUVR}}{2} \right)}{I_{CST} + I_{START}}$$

Where  $V_{INMIN}$  is the minimum input supply voltage for the application (36V for telecom),  $V_{SUVR}$  is the bootstrap UVLO wake-up level (16V), and  $I_{START}$  is the  $V_{IN}$  supply current at startup (65 $\mu$ A, max). Choose a higher value for  $R_{ST}$  than the one calculated above if longer startup times can be tolerated in order to minimize power loss in  $R_{ST}$ .

The above startup method is applicable to circuits where the tertiary winding has the same phase as the output windings. Thus, the voltage on the tertiary winding at any given time is proportional to the output voltage and goes through the same soft-start period as the output voltage. The minimum discharge time of  $C_{ST}$  from 16V to 10V must be greater than the soft-start time ( $t_{SS}$ ).

## Undervoltage Lockout (UVLO)

The minimum turn-on supply voltage for the MAX5070/MAX5071 is 16V. Once  $V_{CC}$  reaches 16V, the reference powers up. There is 6V of hysteresis from the minimum turn-on voltage to the UVLO threshold. Once  $V_{CC}$  reaches 16V, the MAX5070/MAX5071 will operate with  $V_{CC}$  down to 10V. Once  $V_{CC}$  goes below 10V the device is in UVLO. When in UVLO, the quiescent supply current into  $V_{CC}$  falls back to 37 $\mu$ A (typ), and OUT and VREF are pulled low.

## MOSFET Driver

OUT drives an external n-channel MOSFET and swings from GND to  $V_{CC}$ . Ensure that  $V_{CC}$  remains below the absolute maximum  $V_{GS}$  rating of the external MOSFET. OUT is a push-pull output with the on-resistance of the PMOS typically 3.5 $\Omega$  and the on-resistance of the NMOS typically 4.5 $\Omega$ . The driver can source 2A typically and sink 1A typically. This allows for the MAX5070/MAX5071 to quickly turn on and off high gate-charge MOSFETs.

Bypass  $V_{CC}$  with one or more 0.1 $\mu$ F ceramic capacitors to GND, placed close to the MAX5070/MAX5071. The average current sourced to drive the external MOSFET depends on the total gate charge ( $Q_G$ ) and operating frequency of the converter. The power dissipation in the MAX5070/MAX5071 is a function of the average output drive current ( $I_{DRIVE}$ ). Use the following equation to calculate the power dissipation in the device due to  $I_{DRIVE}$ :

$$I_{DRIVE} = Q_G \times f_{SW}$$

$$PD = (I_{DRIVE} + I_{CC}) \times V_{CC}$$

where  $I_{CC}$  is the operating supply current. See the *Typical Operating Characteristics* for the operating supply current at a given frequency.

## Error Amplifier (MAX5070A/MAX5070B)

The MAX5070 includes an internal error amplifier. The inverting input is at FB and the noninverting input is internally connected to a 2.5V reference. The internal error amplifier is useful for nonisolated converter design (see Figure 6) and isolated design with primary-side regulation through a bias winding (see Figure 5). In the case of a nonisolated power supply, the output voltage will be:

$$V_{OUT} = \left( 1 + \frac{R1}{R2} \right) \times 2.5V$$

where R1 and R2 are from Figure 6.

# High-Performance, Single-Ended, Current-Mode PWM Controllers

## MAX5071A/MAX5071B/MAX5071C Feedback

The MAX5071A/MAX5071B/MAX5071C are designed to be used with either an external error amplifier when designed into a nonisolated converter or an error amplifier and optocoupler when designed into an isolated power supply. The COMP input is level-shifted and connected to the inverting terminal of the PWM comparator (CPWM). Connect the COMP pin to the output of the external error amplifier for nonisolated design. Pull COMP high externally to at least 5V (or VREF) and connect the optocoupler transistor as shown in Figures 7 and 8. COMP can be used for soft-start and also as a shutdown. See the *Typical Operating Characteristics* to find the turn-off COMP voltage at different temperatures. If the maximum external COMP voltage is below 4.9V, it may reduce the PWM current-limit threshold below 1V. Use the following equation to calculate minimum COMP voltage (VCOMP) required for a guaranteed peak primary current (IP-P):

$$V_{COMP} = (3 \times I_{P-P} \times R_{CS}) + 1.95V$$

where  $R_{CS}$  is a current-sense resistor.

## Oscillator

The oscillator frequency is adjusted by adding an external capacitor and resistor at  $R_T/C_T$  (see  $R_T$  and  $C_T$  in the *Typical Application Circuits*).  $R_T$  is connected from  $R_T/C_T$  to the 5V reference (VREF) and  $C_T$  is connected from  $R_T/C_T$  to GND. VREF charges  $C_T$  through  $R_T$  until its voltage reaches 2.8V.  $C_T$  then discharges through an 8.3mA internal current sink until  $C_T$ 's voltage reaches 1.1V, at which time  $C_T$  is allowed to charge through  $R_T$  again. The oscillator's period will be the sum of the charge and discharge times of  $C_T$ . Calculate the charge time as:

$$t_C = 0.57 \times R_T \times C_T$$

The discharge time is then:

$$t_D = \frac{R_T \times C_T \times 10^3}{4.88 \times R_T - 1.8 \times 10^3}$$

The oscillator frequency will then be:

$$f_{OSC} = \frac{1}{t_C + t_D}$$

For the MAX5070A/MAX5071A, the converter output switching frequency ( $f_{SW}$ ) is the same as the oscillator frequency ( $f_{OSC}$ ). For the MAX5070B/MAX5071B/MAX5071C, the output switching frequency is 1/2 the oscillator frequency.

## Reference Output

VREF is a 5V reference output that can source 20mA. Bypass VREF to GND with a 0.1μF capacitor.

## Current Limit

The MAX5070/MAX5071 include a fast current-limit comparator to terminate the ON cycle during an overload or a fault condition. The current-sense resistor ( $R_{CS}$ ), connected between the source of the MOSFET and GND, sets the current limit. The CS input has a voltage trip level ( $V_{CS}$ ) of 1V. Use the following equation to calculate  $R_{CS}$ :

$$R_{CS} = \frac{V_{CS}}{I_{P-P}}$$

$I_{P-P}$  is the peak current in the primary that flows through the MOSFET. When the voltage produced by this current (through the current-sense resistor) exceeds the current-limit comparator threshold, the MOSFET driver (OUT) will turn the switch off within 60ns. In most cases, a small RC filter is required to filter out the leading-edge spike on the sense waveform. Set the time constant of the RC filter at 50ns. Use a current transformer to limit the losses in the current-sense resistor and achieve higher efficiency especially at low input-voltage operation.

## Synchronization (MAX5071A/MAX5071B)

### SYNC

SYNC is a bidirectional input/output that outputs a synchronizing pulse and accepts a synchronizing pulse from other MAX5071A/MAX5071Bs (see Figures 7 and 9). As an output, SYNC is an open-drain p-channel MOSFET driven from the internal oscillator and requires an external pulldown resistor ( $R_{SYNC}$ ) from between 500Ω and 5kΩ. As an input, SYNC accepts the output pulses from other MAX5071A/MAX5071Bs.

Synchronize multiple MAX5071A/MAX5071Bs by connecting their SYNC pins together. All devices connected together will synchronize to the one operating at the highest frequency. The rising edge of SYNC will precede the rising edge of OUT by approximately the discharge time ( $t_D$ ) of the oscillator (see the *Oscillator* section). The pulse width of the SYNC output is equal to the time required to discharge the stray capacitance at SYNC through  $R_{SYNC}$  plus the  $C_T$  discharge time  $t_D$ . Adjust  $R_T/C_T$  such that the minimum discharge time  $t_D$  is 200ns.

# High-Performance, Single-Ended, Current-Mode PWM Controllers

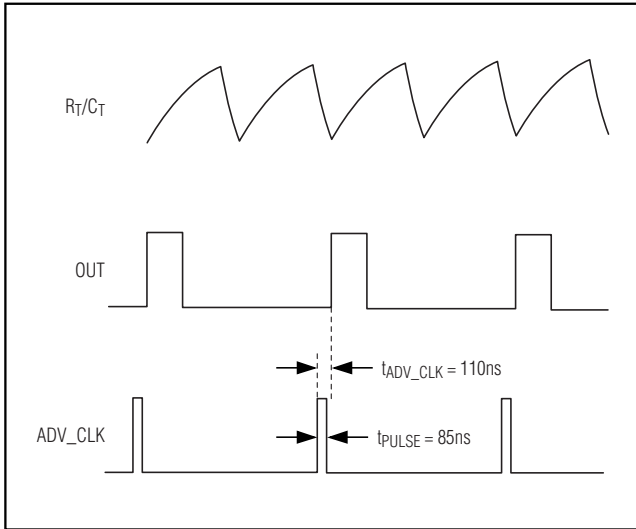


Figure 4. ADV\_CLK

## Advance Clock Output (ADV\_CLK) (MAX5071C)

ADV\_CLK is an advanced pulse output provided to facilitate the easy implementation of secondary-side synchronous rectification using the MAX5071C. The ADV\_CLK pulse width is 85ns (typically) with its rising edge leading the rising edge of OUT by 110ns. Use this leading pulse to turn off the secondary-side synchronous-rectifier MOSFET (QS) before the voltage appears on the secondary (see Figure 8). Turning off the secondary-side synchronous MOSFET earlier avoids the shorting of the secondary in the forward converter. The ADV\_CLK pulse can be propagated to the secondary side using a pulse transformer or high-speed optocoupler. The 85ns pulse, with 3V drive voltage (10mA source), significantly reduces the volt-second requirement of the pulse transformer and the advanced pulse alleviates the need for a high-speed optocoupler.

## Thermal Shutdown

When the MAX5070/MAX5071s' die temperature goes above  $+150^{\circ}\text{C}$ , the thermal-shutdown circuitry will shut down the 5V reference and pull OUT low.

## Typical Application Circuits

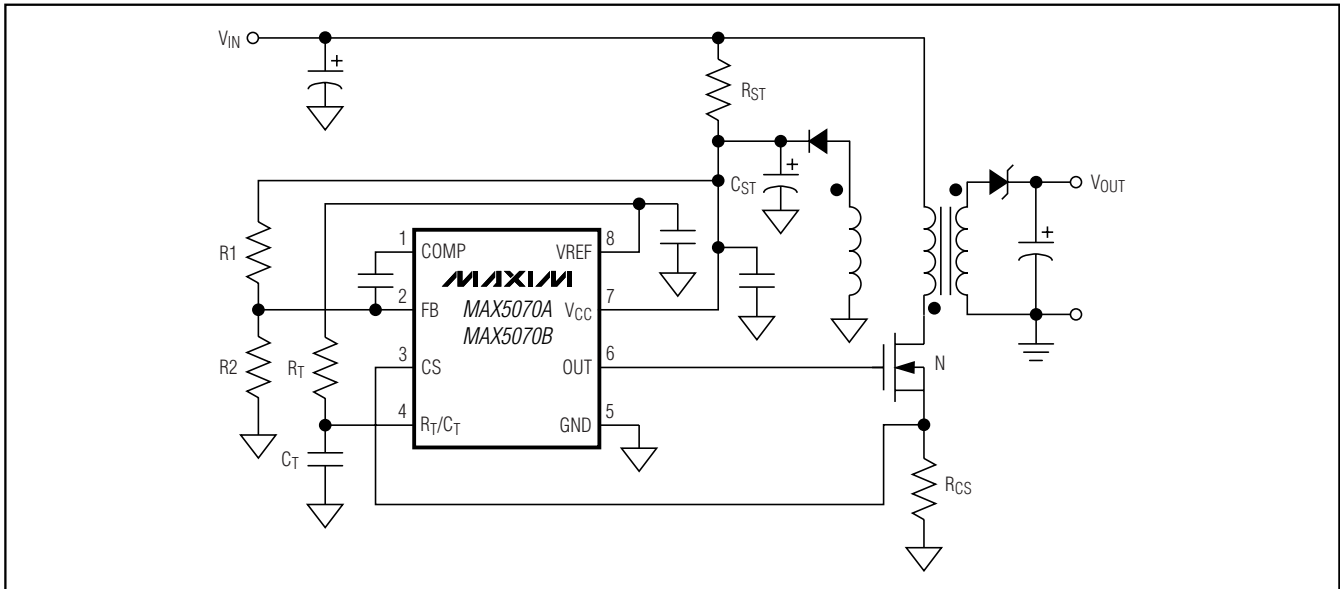


Figure 5. MAX5070A/MAX5070B Typical Application Circuit (Isolated Flyback with Primary-Side Regulation)

# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Typical Application Circuits (continued)

MAX5070/MAX5071

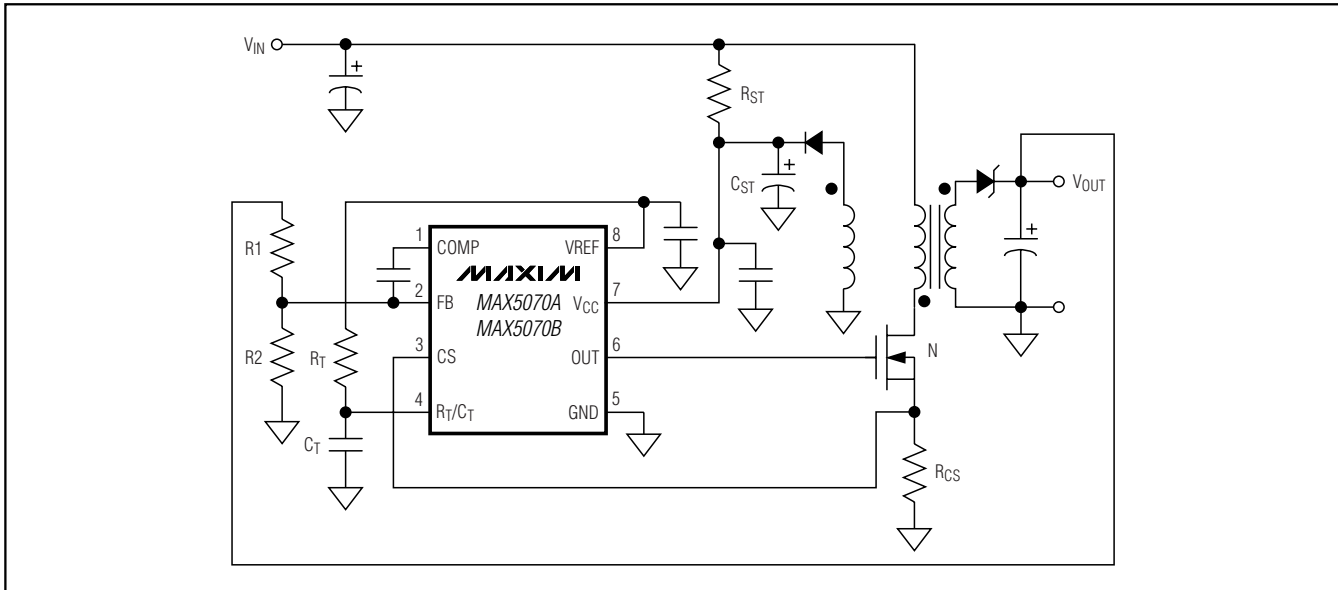


Figure 6. MAX5070A/MAX5070B Typical Application Circuit (Non-Isolated Flyback)

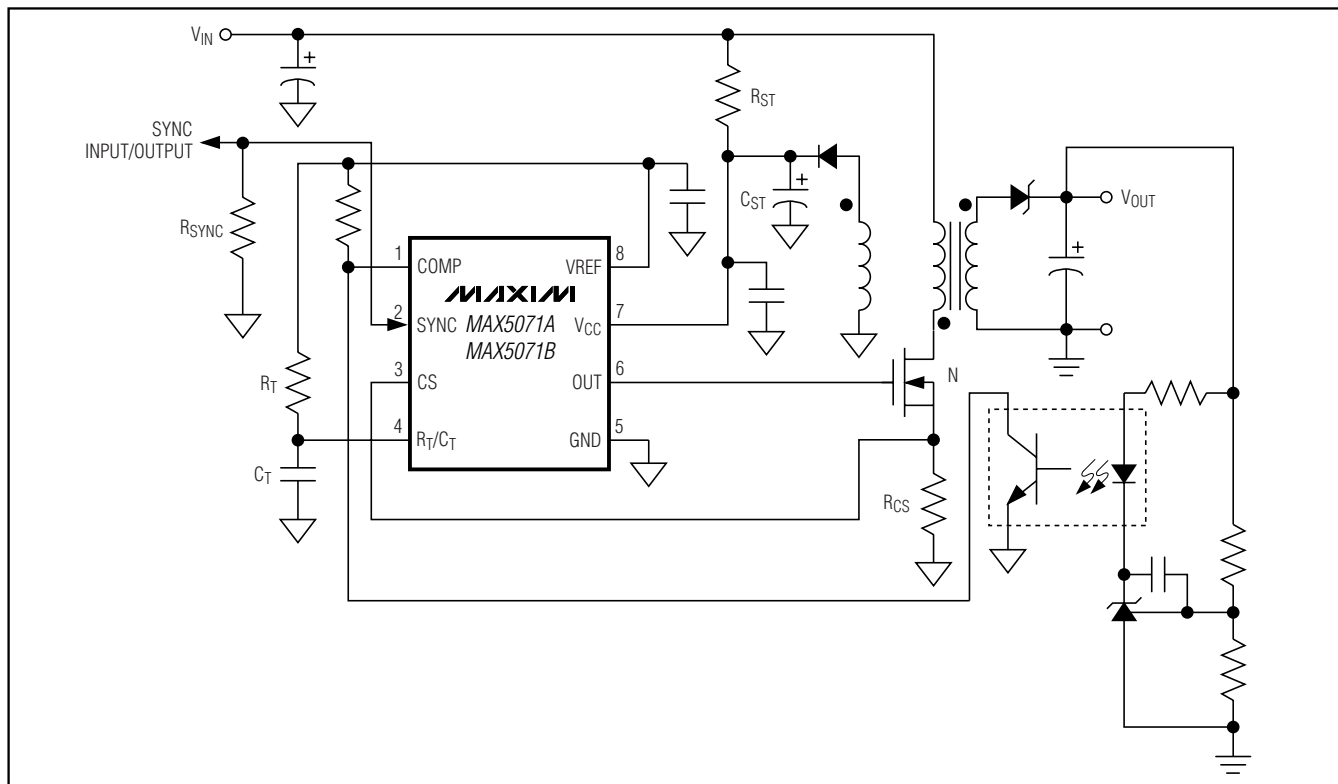


Figure 7. MAX5071A/MAX5071B Typical Application Circuit (Isolated Flyback)

# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Typical Application Circuits (continued)

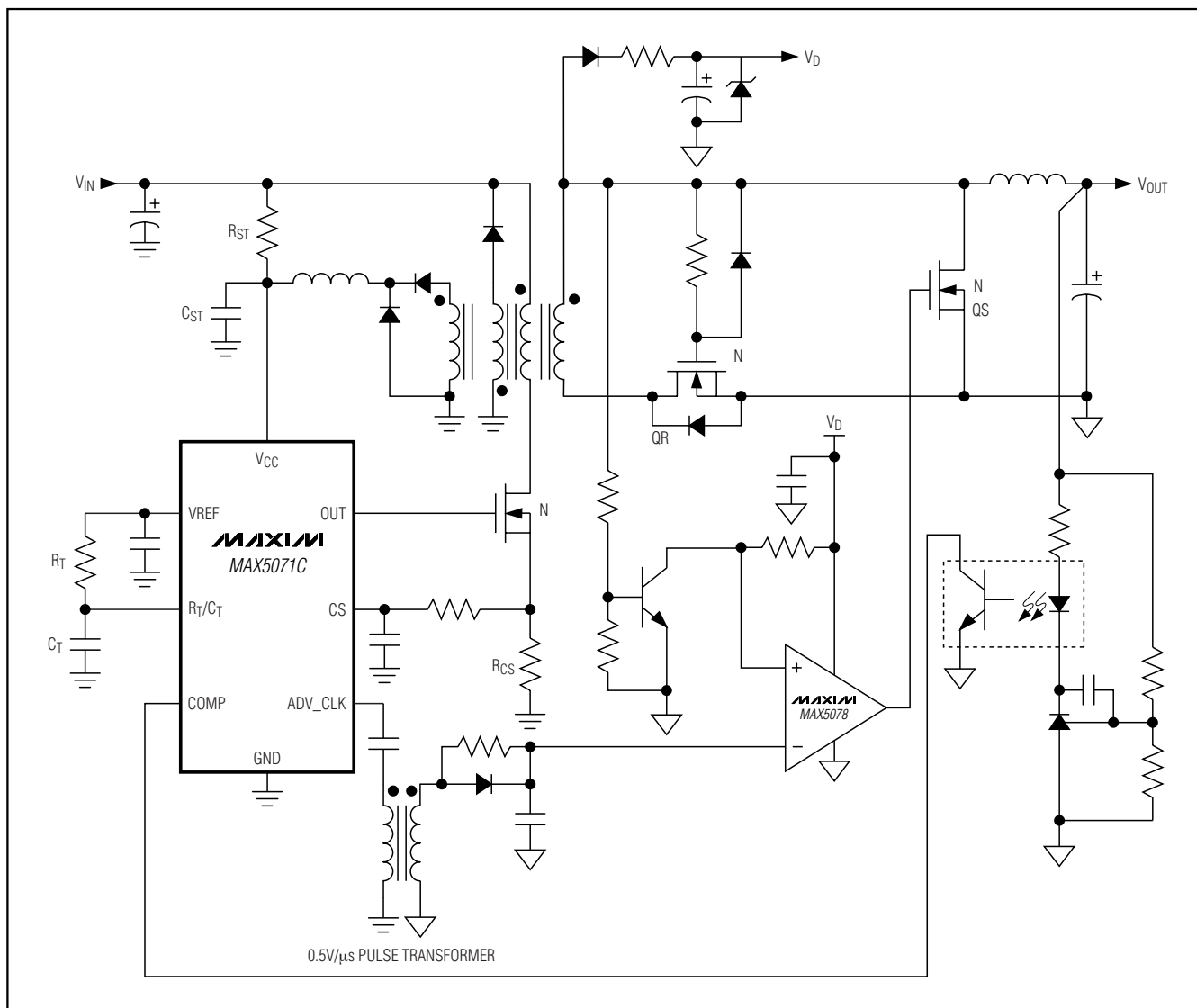


Figure 8. MAX5071C Typical Application Circuit (Isolated Forward with Secondary-Side Synchronous Rectification)

# High-Performance, Single-Ended, Current-Mode PWM Controllers

MAX5070/MAX5071

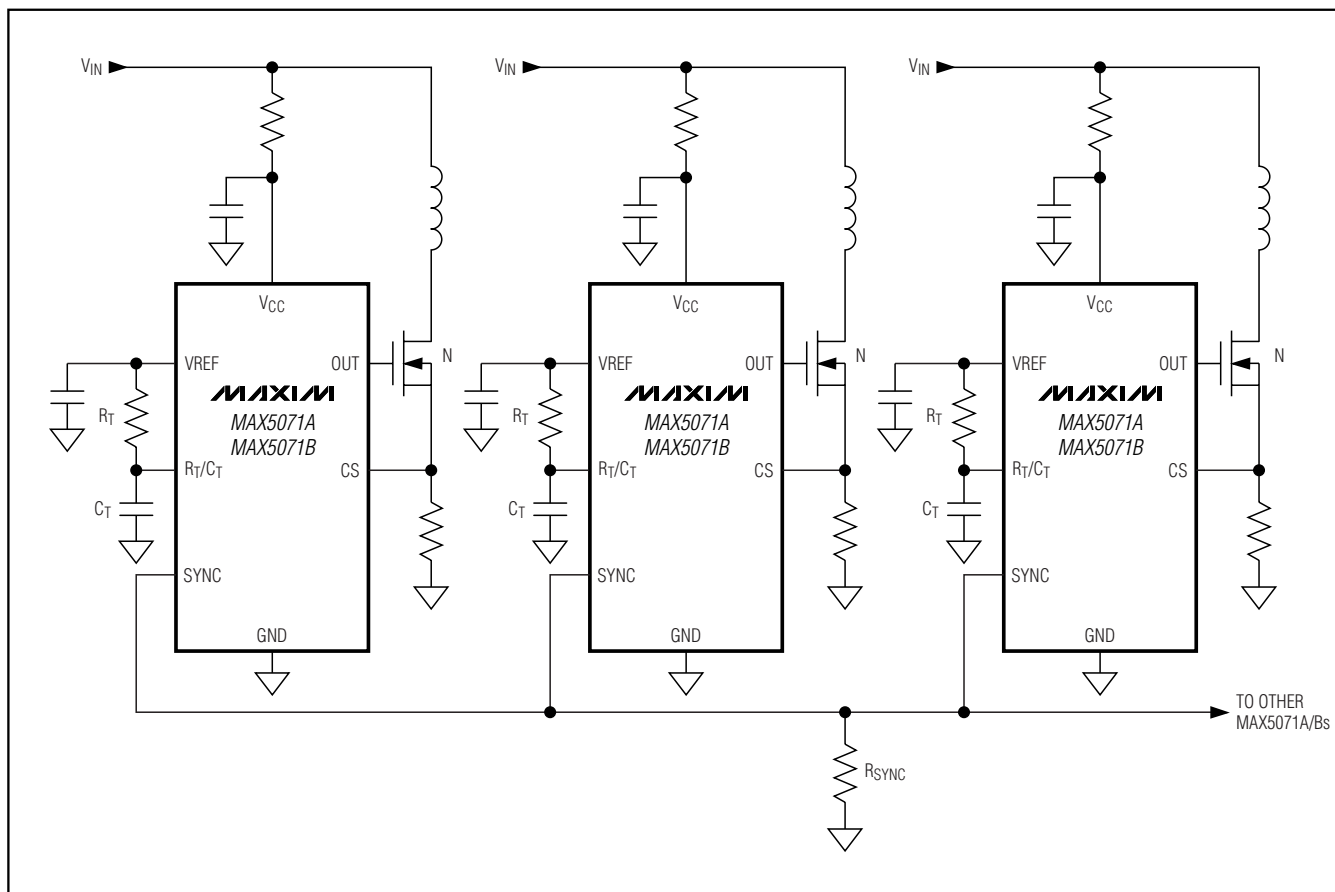


Figure 9. Synchronization of MAX5071s

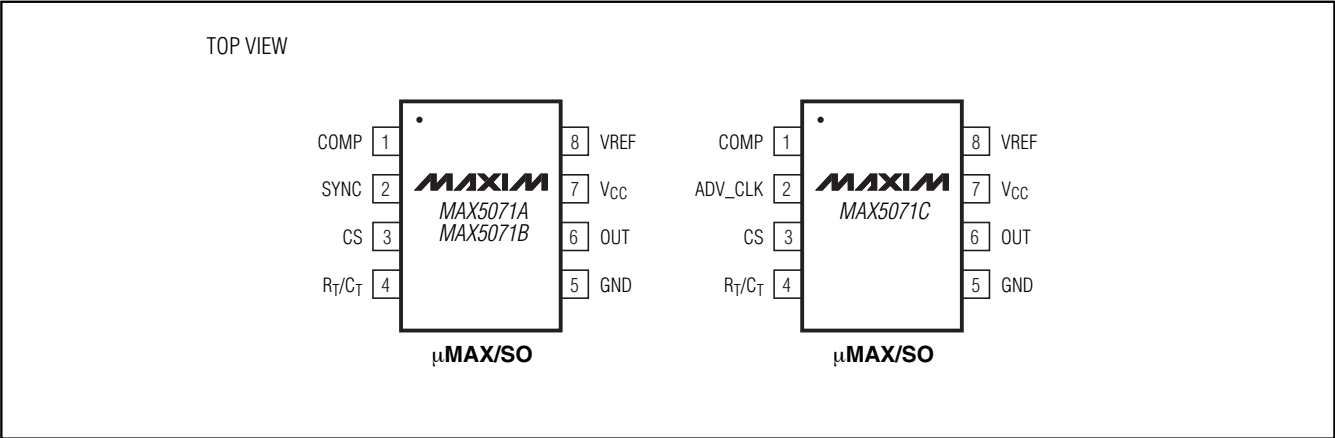


# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Selector Guide

PART	FEEDBACK/ ADVANCED CLOCK	MAXIMUM DUTY CYCLE (%)	PIN-PACKAGE	PIN COMPATIBLE
MAX5070AASA	Feedback	100	8 SO	UC2842/UCC2842
MAX5070AAUA	Feedback	100	8 $\mu$ MAX	UC2842/UCC2842
MAX5070BASA	Feedback	50	8 SO	UC2844/UCC2844
MAX5070BAUA	Feedback	50	8 $\mu$ MAX	UC2844/UCC2844
MAX5071AASA	Sync.	100	8 SO	—
MAX5071AAUA	Sync.	100	8 $\mu$ MAX	—
MAX5071BASA	Sync.	50	8 SO	—
MAX5071BAUA	Sync.	50	8 $\mu$ MAX	—
MAX5071CASA	ADV_CLK	50	8 SO	—
MAX5071CAUA	ADV_CLK	50	8 $\mu$ MAX	—

## Pin Configurations (continued)



## Ordering Information (continued)

PART	TEMP RANGE	PIN-PACKAGE
MAX5071AASA	-40°C to +125°C	8 SO
MAX5071AAUA	-40°C to +125°C	8 $\mu$ MAX
MAX5071BASA	-40°C to +125°C	8 SO
MAX5071BAUA	-40°C to +125°C	8 $\mu$ MAX
MAX5071CASA	-40°C to +125°C	8 SO
MAX5071CAUA	-40°C to +125°C	8 $\mu$ MAX

Specify lead-free by adding the + symbol at the end of the part number when ordering.

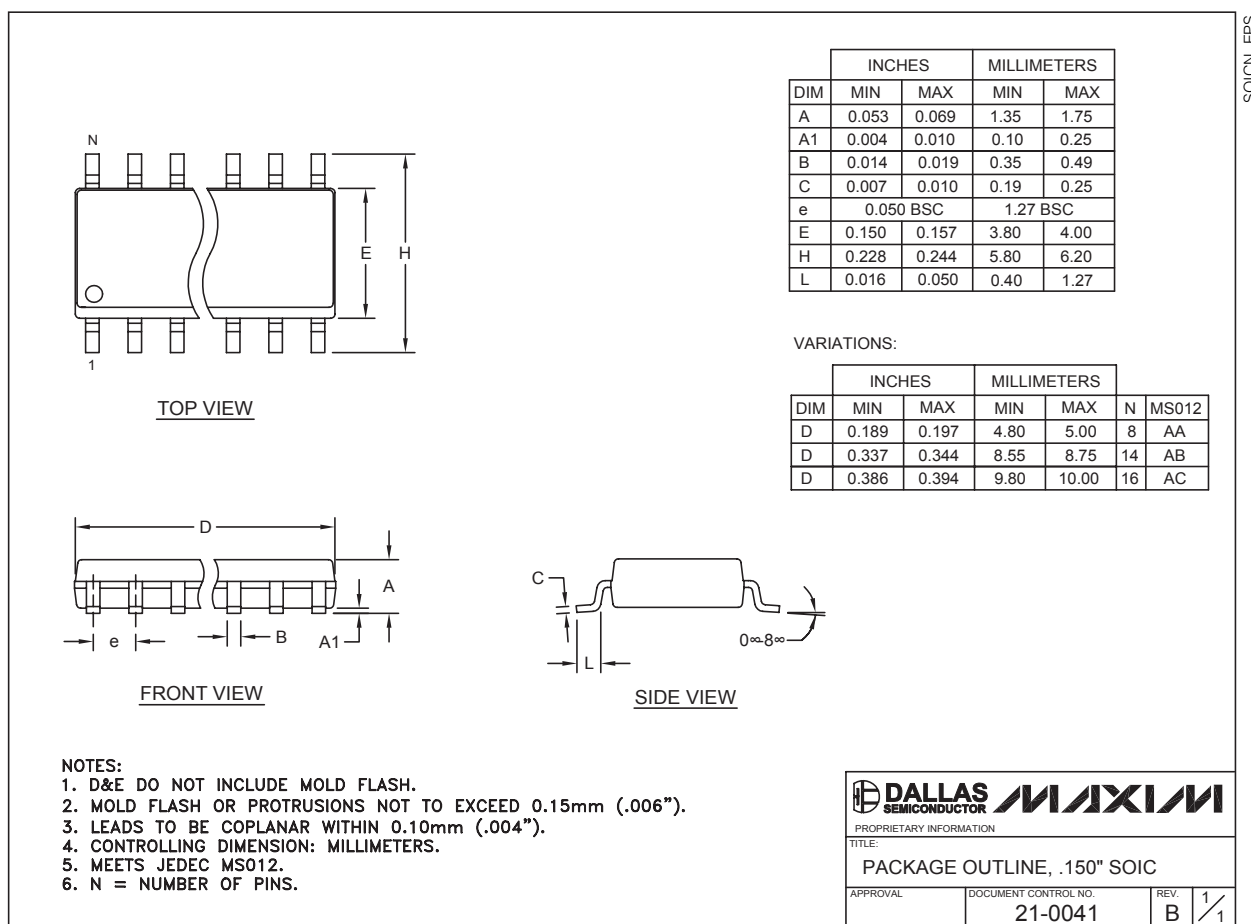
## Chip Information

TRANSISTOR COUNT: 1987  
PROCESS: BiCMOS

# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Package Information

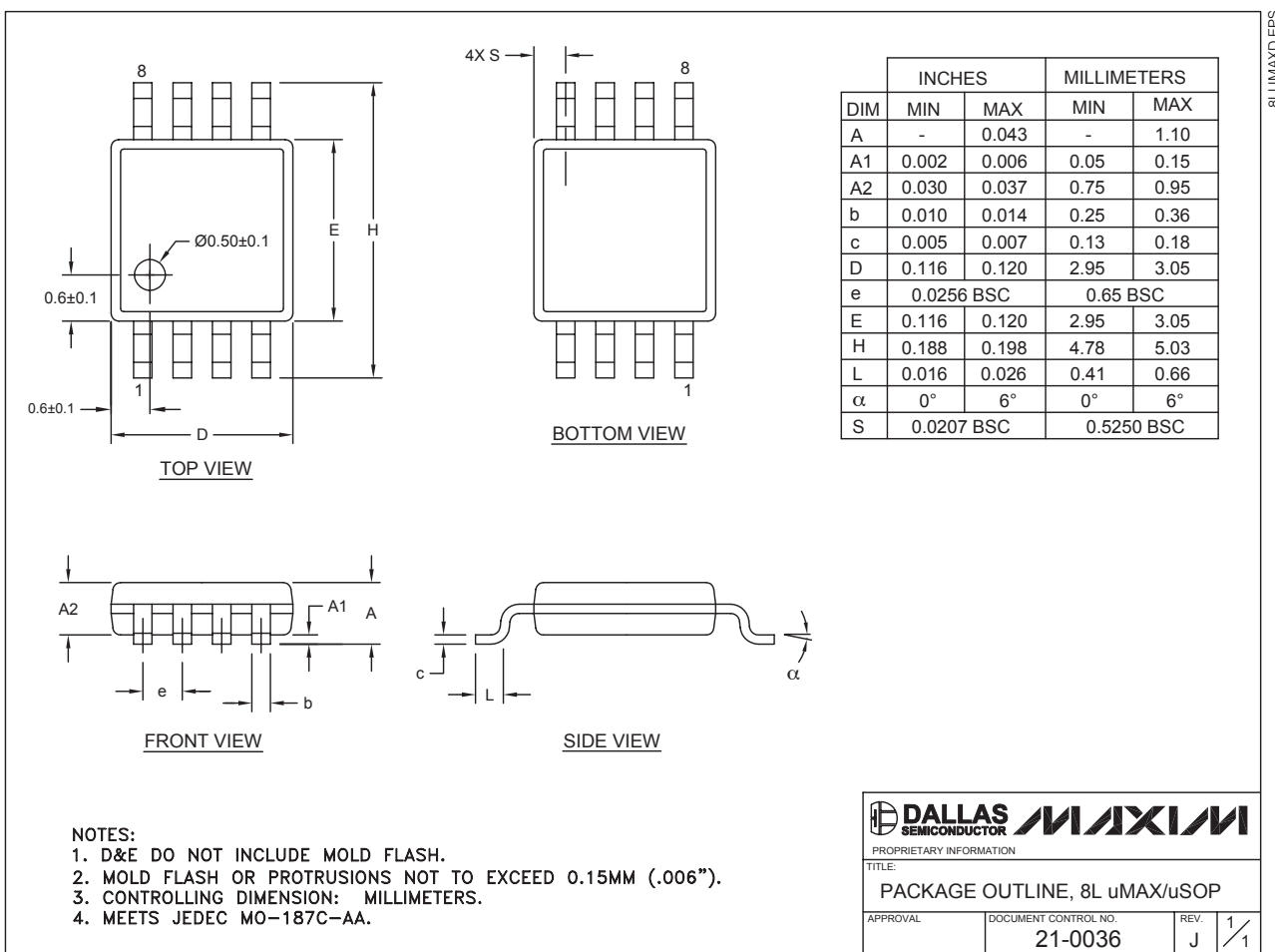
(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).)



# High-Performance, Single-Ended, Current-Mode PWM Controllers

## Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).)



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