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## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China









### **General Description**

The MAX5214/MAX5216 are pin-compatible, 14-bit and 16-bit digital-to-analog converters (DACs). The MAX5214/MAX5216 are single-channel, low-power, buffered voltage-output DACs. The devices use a precision external reference applied through the high resistance input for rail-to-rail operation and low system power consumption. The MAX5214/MAX5216 accept a wide 2.7V to 5.25V supply voltage range. Power consumption is extremely low to accommodate most low-power and low-voltage applications. These devices feature a 3-wire SPI™-/QSPI™-/MICROWIRE™-/DSP-compatible serial interface to save board space and to reduce the complexity in isolated applications. The MAX5214/ MAX5216 minimize the digital noise feedthrough from input to output with SCLK and DIN input buffers powered down after completion of each serial input frame. On power-up, the MAX5214/MAX5216 reset the DAC output to zero, providing additional safety for applications that drive valves or other transducers that need to be off on power-up. The DAC output is buffered resulting in a low supply current of 80µA (max) and a low offset error of ±0.25mV. A zero level applied to the CLR pin asynchronously clears the contents of the input and DAC registers and sets the DAC output to zero independent of the serial interface. The MAX5214/ MAX5216 are available in an ultra-small (3mm x 3mm), 8-pin µMAX® package and are specified over the -40°C to +105°C extended industrial temperature range.

#### **Applications**

2-Wire Sensors

Communication Systems

**Automatic Tuning** 

Gain and Offset Adjustment

Power Amplifier Control

Process Control and Servo Loops

Portable Instrumentation

Programmable Voltage and Current Sources

Automatic Test Equipment

SPI/QSPI are trademarks of Motorola, Inc. MICROWIRE is a trademark of National Semiconductor Corp. µMAX is a registered trademark of Maxim Integrated Products, Inc.

#### **Features**

- ♦ Low-Power Consumption (80µA max)
- ♦ 14-/16-Bit Resolution in a 3mm x 3mm, 8-Pin µMAX Package
- **♦** Relative Accuracy ±0.25 LSB INL (MAX5214, 14-Bit) ±1.0 LSB INL (MAX5216, 16-Bit)
- **♦** Guaranteed Monotonic Over All Operating Ranges
- ♦ Low Gain and Offset Error
- ♦ Wide 2.7V to 5.25V Supply Range
- ♦ Rail-to-Rail Buffered Output Operation
- ♦ Safe Power-On Reset (POR) to Zero DAC Output
- ♦ Fast 50MHz. 3-Wire. SPI/QSPI/MICROWIRE-**Compatible Serial Interface**
- **♦** Schmitt-Trigger Inputs for Direct Optocoupler Interface
- ♦ Asynchronous CLR Clears DAC Output to Code 0
- ♦ High Reference Input Resistance for Power Reduction
- ♦ Buffered Voltage Output Directly Drives 10kΩ Loads

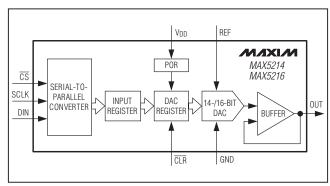
### **Ordering Information**

PART	PIN-PACKAGE	RESOLUTION (BITS)
MAX5214GUA+	8 µMAX	14
MAX5216GUA+	8 µMAX	16

**Note:** All devices are specified over the -40°C to +105°C operating temperature range.

+Denotes a lead(Pb)-free/RoHS-compliant package.

### **Functional Diagram**



/U/IXI/U

Maxim Integrated Products 1

#### **ABSOLUTE MAXIMUM RATINGS**

Vpp to GND0.3V to +6\	/ Maximum Cui
REF, OUT, CLR to GND0.3V to the lower o	f Operating Ter
$(V_{DD} + 0.3V)$ and +6\	
SCLK, DIN, CS to GND0.3V to +6V	Lead Temper
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	Soldering Ter
μMAX (derate at 4.8mW/°C above +70°C)387mW	1

Maximum Current into Any Input or Output	. ±50mA
Operating Temperature Range40°C to	+105°C
Storage Temperature Range65°C to	+150°C
Lead Temperature (soldering, 10s)	.+300°C
Soldering Temperature (reflow)	.+260°C

### PACKAGE THERMAL CHARACTERISTICS (Note 1)

XAML

**Note 1:** Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to **www.maxim-ic.com/thermal-tutorial**.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{DD} = 5V, V_{REF} = 5V, C_L = 100pF, R_L = 10k\Omega, T_A = -40^{\circ}C$  to  $+105^{\circ}C$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
STATIC ACCURACY (Note 2)						
Danalukian	N.	MAX5214	14			D:1-
Resolution	N	MAX5216	16			Bits
Interval Nanlina vity	INL	MAX5214 (14-bit) (Note 3)	-1	±0.25	+1	LSB
Integral Nonlinearity	IINL	MAX5216 (16-bit) (Note 3)	-3	±1	+3	LSB
Differential Menlinearity	DNL	MAX5214 (14-bit) (Note 3)	-1	±0.1	+1	LSB
Differential Nonlinearity	DINL	MAX5216 (16-bit) (Note 3)	-1	±0.1	+1	LSD
Offset Error	OE	(Note 4)	-1.25	±0.25	+1.25	mV
Offset-Error Drift				±0.5		μV/°C
Gain Error	GE	(Note 4)	-0.06	-0.04	0	%FS
Gain Temperature Coefficient				±2		ppmFS/ °C
REFERENCE INPUT			1			
Reference-Input Voltage Range	VREF		2		V <sub>DD</sub>	V
Reference-Input Impedance	RREF		200	256		kΩ
DAC OUTPUT						
		No load (typical)			VDD	.,,
Output Voltage Range		10kΩ load	0.2		V <sub>DD</sub> - 0.2	V
DC Output Impedance				0.1		Ω
Capacitive Load (Note 5)	C	Series resistance = $0\Omega$			0.1	nF
Capacitive Load (Note 5)	CL	Series resistance = 1kΩ			15	μF
Resistive Load (Note 5)	RL		5			kΩ
Short-Circuit Current		V <sub>DD</sub> = 5.25V	-10	±5	+10	mA
Power-Up Time		From power-down mode		25		μs

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = 5V, V_{REF} = 5V, C_L = 100pF, R_L = 10k\Omega, T_A = -40^{\circ}C$  to  $+105^{\circ}C$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DIGITAL INPUTS (SCLK, DIN, CS	S, CLR)					
Input High Voltage	VIH		0.7 x V <sub>DD</sub>			V
Input Low Voltage	VIL				0.3 x V <sub>DD</sub>	V
Input Leakage Current	I <sub>IN</sub>	$V_{IN} = 0V$ or $V_{DD}$		±0.1	±1	μΑ
Input Capacitance	CIN				10	рF
Hysteresis Voltage	VHYS			0.15		V
<b>DYNAMIC PERFORMANCE (Not</b>	e 5)					
Voltage-Output Slew Rate	SR	Positive and negative		0.5		V/µs
Voltage-Output Settling Time		1/4 scale to 3/4 scale, to ≤ 0.5 LSB, 14-bit		14		μs
Reference -3dB Bandwidth	BW	Hex code = 2000 (MAX5214), Hex code = 8000 (MAX5216)		100		kHz
Digital Feedthrough		Code = 0, all digital inputs from 0V to V <sub>DD</sub> , SCLK < 50MHz		0.5		nV·s
DAC Glitch Impulse		Major code transition		2		nV⋅s
Output Noise		10kHz		70		nV/√Hz
Integrated Output Noise		0.1Hz to 10Hz		1.5		μV <sub>P-P</sub>
POWER REQUIREMENTS	•					
Supply Voltage	V <sub>DD</sub>		2.7		5.25	V
Supply Current	I <sub>DD</sub>	No load; all digital inputs at 0V or V <sub>DD</sub> , supply current only; excludes reference input current, midscale		70	80	μΑ
Power-Down Supply Current		No load, all digital inputs at 0V or VDD		0.4	2	μΑ
TIMING CHARACTERISTICS (No	tes 5 and 6)	(Figures 1 and 2)				
Serial Clock Frequency	fsclk		0		50	MHz
SCLK Pulse-Width High	tcH		8			ns
SCLK Pulse-Width Low	tCL		8			ns
CS Fall to SCLK Fall Setup Time	tcsso		8			ns
CS Fall to SCLK Fall Hold Time	tCSH0		0			ns
CS Rise to SCLK Fall Hold Time	tCSH1		0			ns
CS Rise to SCLK Fall	tCSA				12	ns
SCLK Fall to CS Fall	tCSF		100			ns
DIN to SCLK Fall Setup Time	tDS		5			ns
DIN to SCLK Fall Hold Time	tDH		4.5			ns
CS Pulse-Width High	tcspw		20	,		ns
CLR Pulse-Width Low	tCLPW		20			ns
CLR Rise to CS Fall	tcsc		20			ns

Note 2: Static accuracy tested without load.

Note 3: Linearity is tested within 20mV of GND and VDD.

Note 4: Gain and offset is tested within 100mV of GND and VDD.

Note 5: Guaranteed by design; not production tested.

Note 6: All timing specifications measured with  $V_{IL} = V_{GND}$ ,  $V_{IH} = V_{DD}$ .

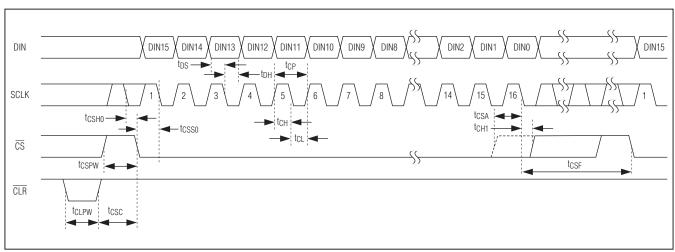


Figure 1. 16-Bit Serial-Interface Timing Diagram (MAX5214)

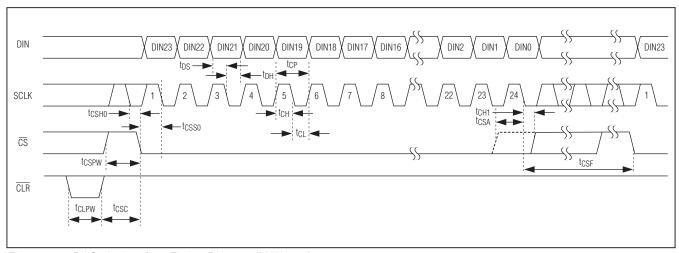
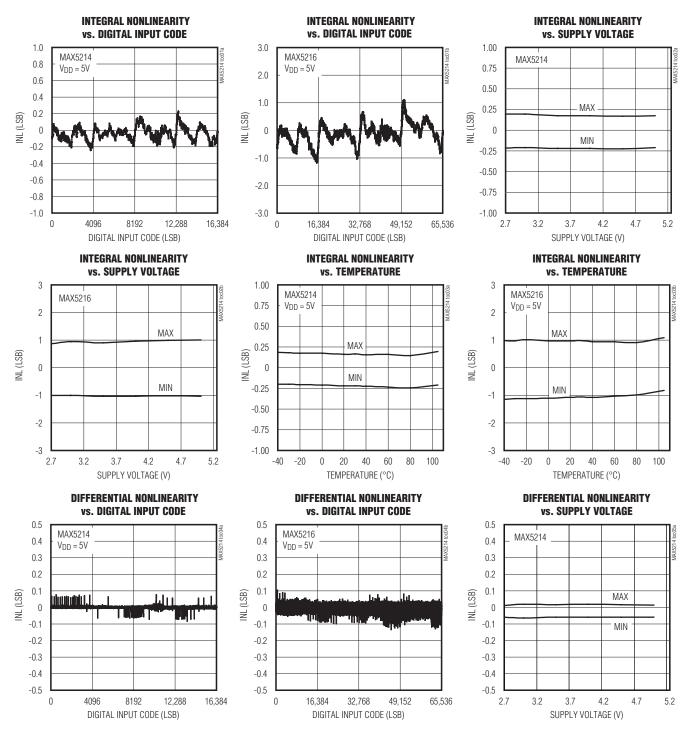
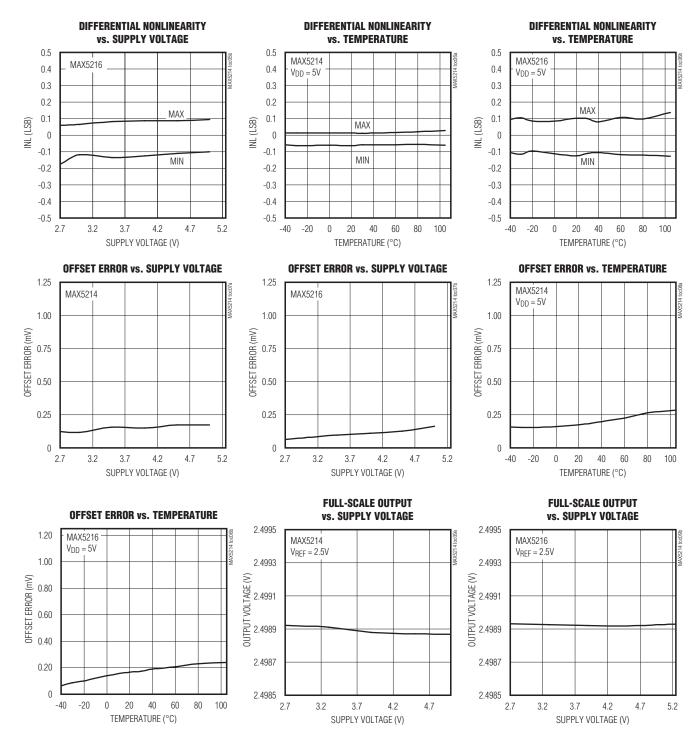


Figure 2. 24-Bit Serial-Interface Timing Diagram (MAX5216)

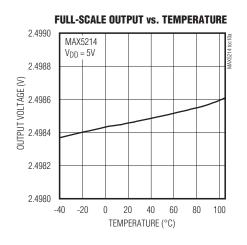
## **Typical Operating Characteristics**

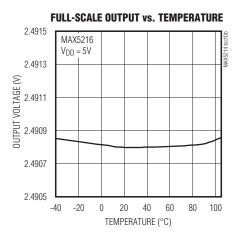


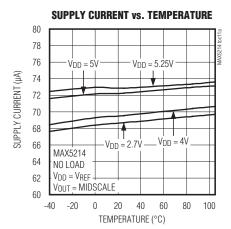
Typical Operating Characteristics (continued)

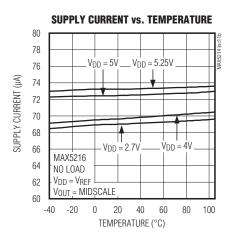


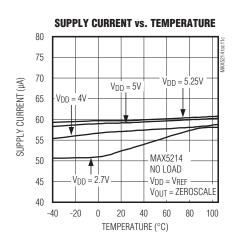
## Typical Operating Characteristics (continued)

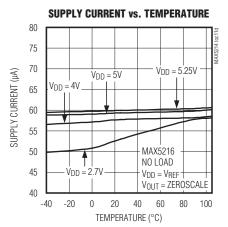




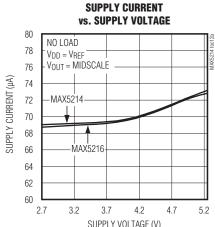


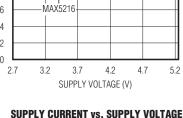


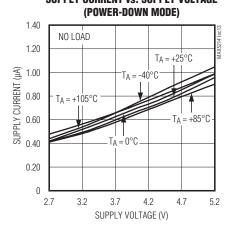


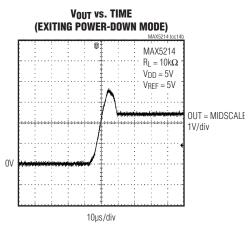


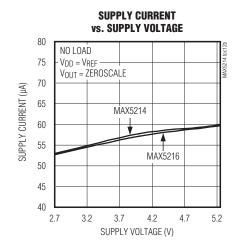
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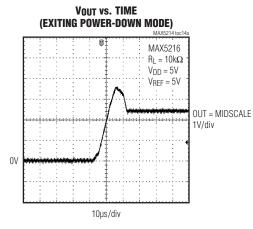


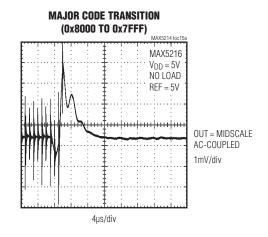




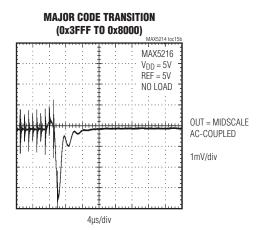


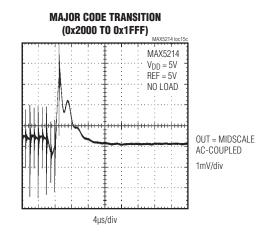


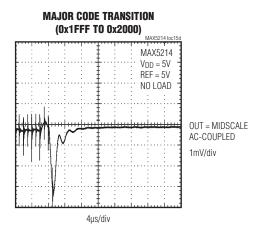


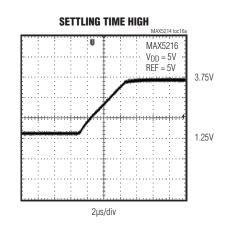


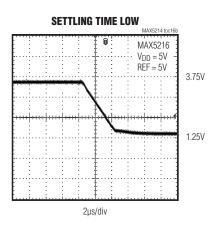
## **Typical Operating Characteristics (continued)**

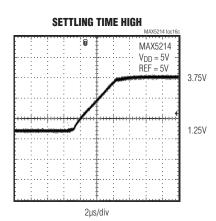






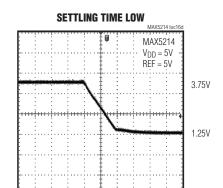




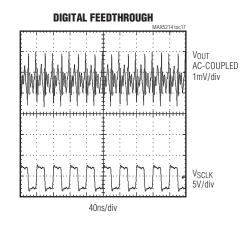


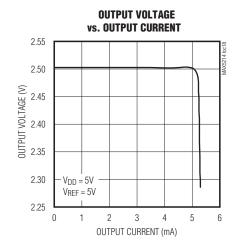
## Typical Operating Characteristics (continued)

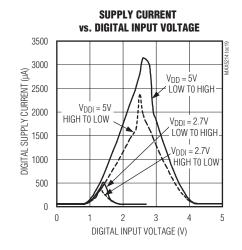
 $(T_A = +25^{\circ}C, \text{ unless otherwise noted.})$ 

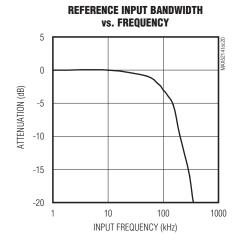


2µs/div

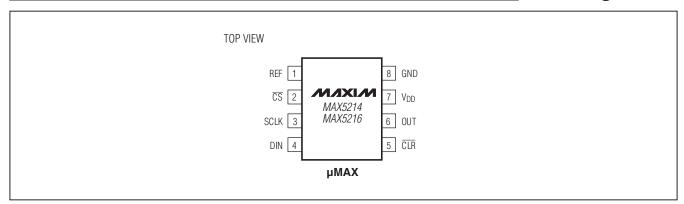








### **Pin Configuration**



### **Pin Description**

PIN	NAME	FUNCTION
1	REF	Reference Voltage Input. Bypass REF with a 0.1µF capacitor to GND.
2	CS	Active-Low Chip-Select Input
3	SCLK	Serial-Clock Input
4	DIN	Data In
5	CLR	Active-Low Asynchronous Digital-Clear Input. Drive CLR low to clear the contents of the input and DAC registers and set the DAC output to zero.
6	OUT	Buffered DAC Output
7	VDD	Supply Voltage. Bypass V <sub>DD</sub> with a 0.1µF capacitor to GND.
8	GND	Ground

### **Detailed Description**

The MAX5214/MAX5216 are pin-compatible and software-compatible 14-bit and 16-bit DACs. The MAX5214/ MAX5216 are single-channel, low-power, high-reference input resistance, and buffered voltage-output DACs. The MAX5214/MAX5216 minimize the digital noise feedthrough from their inputs to their outputs by powering down the SCLK and DIN input buffers after completion of each data frame. The data frames are 16-bit for the MAX5214 and 24-bit for the MAX5216. On power-up, the MAX5214/MAX5216 reset the DAC output to zero, providing additional safety for applications that drive valves or other transducers which need to be off on power-up. The MAX5214/MAX5216 contain a segmented resistor string-type DAC, a serial-in/parallel-out shift register, a DAC register, power-on-reset (POR) circuit, CLR to asynchronously clear the device independent of the serial interface, and control logic. On the falling edge

of the clock (SCLK) pulse, the serial input (DIN) data is shifted into the device, MSB first.

#### Output Amplifier (OUT)

The MAX5214/MAX5216 include an internal buffer on the DAC output. The internal buffer provides improved load regulation and transition glitch suppression for the DAC output. The output buffer slews at 0.5V/µs and drives up to  $10k\Omega$  in parallel with 100pF. The analog supply voltage (VDD) determines the maximum output voltage range of the device as VDD powers the output buffer.

#### **DAC Reference (REF)**

The external reference input features a typical input impedance of  $256k\Omega$  and accepts an input voltage from +2V to VDD. Connect an external voltage supply between REF and GND to apply an external reference.

Visit <u>www.maxim-ic.com/products/references</u> for a list of available voltage-reference devices.

#### **Serial Interface**

The MAX5214/MAX5216 3-wire serial interface is compatible with MICROWIRE, SPI, QSPI, and DSP. The interface provides three inputs: SCLK,  $\overline{CS}$ , and DIN. The chip-select input ( $\overline{CS}$ ) frames the serial data loading at DIN. Following a chip-select input high-to-low transition, the data is shifted synchronously and latched into the input register on each falling edge of the serial-clock input (SCLK). Each serial word is 16-bit for the MAX5214 and 24-bit for the MAX5216. The first 2 bits are the control bits followed by 14 data bits (MSB first) for the MAX5214 and 22 data bits (MSB first) for the MAX5216 as shown in Tables 1 and 2. The serial input register

transfers its contents to the input registers after loading 16/24 bits of data and updates the DAC output immediately after the data is received on the 16-/24-bit falling edge of the clock. To initiate a new data transfer, drive  $\overline{CS}$  high and keep  $\overline{CS}$  high for a minimum of 20ns before the next write sequence. The SCLK can be either high or low between  $\overline{CS}$  write pulses. Figures 1 and 2 show the timing diagram for the complete 3-wire serial interface transmission. The MAX5216 DAC code is unipolar binary with VOUT = (code/65,535) x VREF. The MAX5214 DAC code is unipolar binary with VOUT = (code/16,383) x VREF. See Tables 1 and 2.

Table 1. Operating Mode Truth Table (MAX5214)

16-BIT WORD																
	CONTROL DATA BITS													FUNCTION		
MS	MSB LSB															
D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	
0	0	Χ	Χ	Х	Χ	Χ	Х	Х	Х	Х	Χ	Χ	Χ	Х	Х	No operation
1	0	0	X	A1	A0	X	X	X	X	X	X	X	X	X	×	Power-down (see Table 3)
0	1	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	ВЗ	B2	B1	В0	Write through
1	1 Reserved, Do Not Use															

Table 2. Operating Mode Truth Table (MAX5216)

24-BIT WORD																			
CONTROL DATA BITS													FUNCTION						
MSB LSB													FUNCTION						
D23	D22	D21	D20	D19	D18	D17	D16	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5- D0	
0	0	X	Х	Х	Х	Х	Χ	Χ	Χ	Х	Χ	Х	Х	Χ	Χ	Х	Х	Х	No operation
1	0	0	Х	A1	A0	Х	X	X	Х	Х	Х	Х	Х	Χ	Х	X	X	Х	Power-down (see Table 3)
0	1	B15	B14	B13	B12	B11	B10	В9	B8	B7	B6	B5	B4	В3	B2	B1	В0	Х	Write through
1	1 1 Reserved, Do Not Use																		

#### Writing to the Devices

- 1) Drive  $\overline{\text{CS}}$  low, enabling the shift register.
- 2) Clock 16/24 bits of data into DIN (MSB first and LSB last), observing the specified setup and hold times.
- 3) After clocking in the last data bit, drive  $\overline{\text{CS}}$  high.  $\overline{\text{CS}}$  must remain high for 20ns before the next transmission is started.

Figure 1 shows a write operation for the transmission of 16 bits. If  $\overline{\text{CS}}$  is driven high at any point prior to receiving 16 bits, the transmission is discarded.

Figure 2 shows a write operation for the transmission of 24 bits. If  $\overline{CS}$  is driven high at any point prior to receiving 24 bits, the transmission is discarded.

#### Clear (CLR)

The MAX5214/MAX5216 feature an asynchronous active-low  $\overline{\text{CLR}}$  logic input that sets the DAC output to zero. Driving  $\overline{\text{CLR}}$  low clears the contents of both the input and DAC registers and also aborts the on-going SPI command. To allow a new SPI command, drive  $\overline{\text{CLR}}$  high.

#### Power-Down Mode

The MAX5214/MAX5216 feature a software-controlled power-down mode. In power-down, the output disconnects from the buffer and is grounded with one of the three selectable internal resistors. See Table 3 for the selectable internal resistor values in power-down mode. The selected mode takes effect on the 16th SCLK falling edge of the MAX5214 and 24th SCLK falling edge of the MAX5216. The serial interface remains active in powerdown mode. In order to abort the power-down mode selection, pull CS high prior to the 16th (MAX5214) or 24th (MAX5216) SCLK falling edge. The contents of the DAC register remain valid while in power-down mode, allowing for the DAC to return to previous code by writing 0x8000 for the MAX5214 or 0x800000 for the MAX5216 (Table 3). A write to the write-through register causes the device to immediately exit power-down mode and transition to the requested code (see Tables 1 and 2).

#### Table 3. Power-Down Modes

<b>A</b> 1	Α0	DESCRIPTION	DAC OPERATION CONDITION
0	0	DAC powers up and returns to its previous code setting.	Normal operation
0	1	DAC powers down; OUT is high impedance.	
1	0	DAC powers down; OUT connects to ground through an internal 100k $\Omega$ resistor.	Power-down
1	1	DAC powers down; OUT connects to ground through an internal $1k\Omega$ resistor.	

#### Table 4. MAX5216 Input Code vs. Output Voltage

DAC LATCH CONTENTS	ANALOG OUTPUT (VOUT)
MSB → LSB	ANALOG COTPOT (VOUT)
1111 1111 1111	V <sub>REF</sub> x (65,535/65,535)
1000 0000 0000 0000	VREF x (32,768/65,535) = 1/2 VREF
0000 0000 0000 0001	V <sub>REF</sub> x (1/65,535)
0000 0000 0000 0000	OV

### Table 5. MAX5214 Input Code vs. Output Voltage

DAC LATCH CONTENTS	ANALOG OUTPUT (VOUT)
MSB → LSB	ANALOG OUTFOT (VOUT)
1111 1111 111XX	V <sub>REF</sub> x (16,383/16,383)
1000 0000 000XX	VREF x (8,192/16,383) = 1/2 VREF
0000 0000 0000 01XX	V <sub>REF</sub> x (1/16,383)
0000 0000 000XX	OV

### **Applications Information**

#### **Power-On Reset (POR)**

When first power is applied to V<sub>DD</sub>, the input registers are set to zero so the DAC output is set to code zero. To optimize DAC linearity, wait until the supplies have settled. The MAX5214/MAX5216 output voltage range is 0 to V<sub>REF</sub>.

#### Power Supplies and Bypassing Considerations

Bypass V<sub>DD</sub> with high-quality  $0.1\mu F$  ceramic capacitors to a low-impedance ground as close as possible to the device.

Minimize lead lengths to reduce lead inductance. Connect the GND to the analog ground plane.

#### **Layout Considerations**

Digital and AC transient signals on GND can create noise at the output. Connect GND to the star ground for the DAC system. Refer the remote DAC loads to this system ground for the best possible performance. Use proper grounding techniques, such as a multilayer board with a low-inductance ground plane, or star connect all ground return paths back to the MAX5214/MAX5216 GND. Carefully lay out the traces between channels to reduce AC cross-coupling. Do not use wire-wrapped boards and sockets. Use shielding to improve noise immunity. Do not run analog and digital signals parallel to one another, especially clock signals. Avoid routing digital lines underneath the MAX5214/MAX5216 package.

#### **Definitions**

#### Integral Nonlinearity (INL)

INL is the deviation of the measured transfer function from a straight line drawn between two codes once offset and gain errors have been nullified.

#### **Differential Nonlinearity (DNL)**

DNL is the difference between an actual step height and the ideal value of 1 LSB. If the magnitude of the DNL is greater than -1 LSB, the DAC guarantees no missing codes and is monotonic.

#### Offset Error

Offset error indicates how well the actual transfer function matches the ideal transfer function at a single point.

Typically, the point at which the offset error is specified is at or near the zero-scale point of the transfer function.

#### **Gain Error**

Gain error is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

#### **Settling Time**

The settling time is the amount of time required from the start of a transition, until the DAC output settles to the new output value within the converter's specified accuracy.

#### **Digital Feedthrough**

Digital feedthrough is the amount of noise that appears on the DAC output when the DAC digital control lines are toggled.

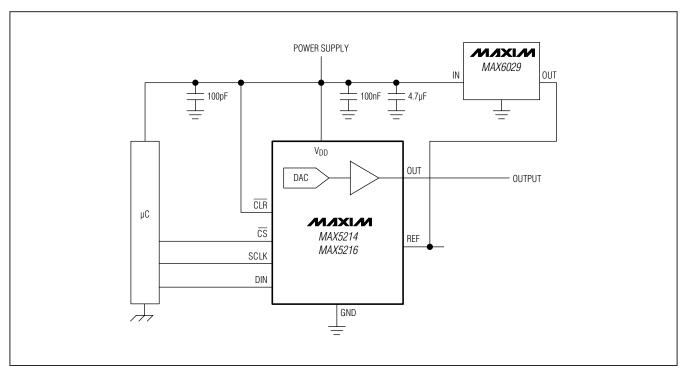
#### Digital-to-Analog Glitch Impulse

A major carry transition occurs at the midscale point where the MSB changes from low to high and all other bits change from high to low, or where the MSB changes from high to low and all other bits change from low to high. The duration of the magnitude of the switching glitch during a major carry transition is referred to as the digital-to-analog glitch impulse.

#### Digital-to-Analog Power-Up Glitch Impulse

The digital-to-analog power-up glitch is the duration of the magnitude of the switching glitch that occurs as the device exits power-down mode.

### **Typical Operating Circuit**



### **Chip Information**

## **Package Information**

pertains to the package regardless of RoHS status.

For the latest package outline information and land patterns, go to www.maxim-ic.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing

> **PACKAGE PACKAGE OUTLINE LAND TYPE** CODE NO. PATTERN NO. 8 μΜΑΧ U8+3 90-0092 21-0036

PROCESS: BICMOS

**Revision History** 

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	12/10	Initial release	_

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