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## Gigabit Multimedia Serial Link Deserializer with LVDS System Interface

### **General Description**

The MAX9268 deserializer utilizes Maxim's gigabit multimedia serial link (GMSL) technology. The MAX9268 deserializer features an LVDS system interface for reduced pin count and a smaller package, and pairs with any GMSL serializer to form a complete digital serial link for joint transmission of high-speed video, audio, and bidirectional control data.

The MAX9268 allows a maximum serial payload data rate of 2.5Gbps for a 15m shielded twisted-pair (STP) cable. The deserializer operates up to a maximum output clock rate of 104MHz (3-channel LVDS) or 78MHz (4-channel LVDS). This serial link supports display panels from QVGA (320 x 240) to WXGA (1280 x 800) and higher with 24-bit color.

The 3-channel mode outputs an LVDS clock, three lanes of LVDS data (21 bits), UART control signals, and one I2S audio channel consisting of three signals. The 4-channel mode outputs an LVDS clock, four lanes of LVDS data (28 bits), UART control signals, an I<sup>2</sup>S audio channel, and auxiliary control outputs. The three audio outputs form a standard I<sup>2</sup>S interface, supporting sample rates from 8kHz to 192kHz and audio word lengths of 4 to 32 bits. The embedded control channel forms a full-duplex, differential, 100kbps to 1Mbps UART link between the serializer and deserializer. An electronic control unit (ECU), or microcontroller (µC), can be located on the serializer side of the link (typical for video display), on the MAX9268 side of the link (typical for image sensing), or on both sides. In addition, the control channel enables ECU/µC control of peripherals on the remote side, such as backlight control, grayscale gamma correction, camera module, and touch screen. Base-mode communication with peripherals uses either I<sup>2</sup>C or the GMSL UART format. In addition, the MAX9268 features a bypass mode that enables full-duplex communication using custom UART formats.

The GMSL serializer driver preemphasis, along with the MAX9268 channel equalizer, extends the link length and enhances the link reliability. Spread spectrum is available to reduce EMI on the LVDS and control outputs of the MAX9268. The serial line inputs comply with ISO 10605 and IEC 61000-4-2 ESD protection standards.

The core supply for the MAX9268 is 3.3V. The I/O supply ranges from 1.8V to 3.3V. The MAX9268 is available in a 48-pin TQFP package (7mm x 7mm) with an exposed pad, and is specified over the -40°C to +105°C automotive temperature range.

### \_Features

- Pairs with Any GMSL Serializer
- 2.5Gbps Payload-Rate AC-Coupled Serial Link
- Scrambled 8b/10b Line Coding
- Supports WXGA (1280 x 800) with 24-Bit Color
- 8.33MHz to 104MHz (3-Channel LVDS) or 6.25MHz to 78MHz (4-Channel LVDS) Output Clock
- 4-Bit to 32-Bit Word Length, 8kHz to 192kHz l<sup>2</sup>S Audio Channel Supports High-Definition Audio
- Embedded Half-/Full-Duplex Bidirectional Control Channel (100kbps to 1Mbps)
- Two 3-Level Inputs Support 9 Device Addresses
- Interrupt Supports Touch-Screen Functions for Display Panels
- I<sup>2</sup>C Master for Peripherals
- Equalizer for Serial Link Input
- Programmable Spread Spectrum on the LVDS and Control Outputs for Reduced EMI
- Serial-Data Clock Recovery Eliminates an External Clock
- Automatic Data-Rate Detection Allows On-the-Fly Data-Rate Change
- Built-In PRBS Generator for BER Testing of the Serial Link
- ISO 10605 and IEC 61000-4-2 ESD Protection
- ♦ -40°C to +105°C Operating Temperature Range
- + 1.8V to 3.3V I/O and 3.3V Core Supplies
- Patent Pending

#### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX9268GCM/V+	-40°C to +105°C	48 TQFP-EP*
MAX9268GCM/V+T	-40°C to +105°C	48 TQFP-EP*

/V denotes an automotive qualified product.

+Denotes a lead(Pb)-free/RoHS-compliant package.

\*EP = Exposed pad.

T = Tape and reel.

#### Applications

High-Resolution Automotive Navigation Rear-Seat Infotainment Megapixel Camera Systems

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Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

### **ABSOLUTE MAXIMUM RATINGS**

AVDD to AGND DVDD, IOVDD to AGND	0.5V to +3.9V
GND to AGND IN+, IN- to AGND	
TXOUT_, TXCLKOUT_ to AGND	
All Other Pins to GND	
TXOUT_, TXCLKOUT_ Short Circuit to	Ground
or Supply	Continuous
Continuous Power Dissipation ( $T_A = +70$	,
48-Pin TQFP (derate 36.2mW/°C abov	/
Human Body Model ( $R_D = 1.5 k\Omega$ , $C_S =$	1 /
(IN+, IN-) to AGND	
(TXOUT_, TXCLKOUT_) to AGND All Other Pins to GND	
IEC 61000-4-2 ( $R_D = 330\Omega$ , $C_S = 150pF$	
Contact Discharge	/
(IN+, IN-) to AGND	±10kV
DAOKAGE THEDRAAL OHA	

(TXOUT_, TXCLKOUT_) to AGND Air Discharge	±8kV
(IN+, IN-) to AGND	±12kV
(TXOUT_, TXCLKOUT_) to AGND	±20kV
ISO 10605 (R <sub>D</sub> = $2k\Omega$ , C <sub>S</sub> = $330pF$ )	
Contact Discharge	
(IN+, IN-) to AGND	±8kV
(TXOUT_, TXCLKOUT_) to AGND	±8kV
Air Discharge	
(IN+, IN-) to AGND	±15kV
(TXOUT_, TXCLKOUT_) to AGND	±30kV
Operating Temperature Range	40°C to +105°C
Junction Temperature	
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10s)	+300°C
Soldering Temperature (reflow)	+260°C

### PACKAGE THERMAL CHARACTERISTICS (Note 1)

48 TQFP

Junction-to-Ambient Thermal Resistance ( $\theta_{JA}$ )......27.6°C/W Junction-to-Case Thermal Resistance ( $\theta_{JC}$ ).......2°C/W

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a fourlayer board. For detailed information on package thermal considerations, refer to www.maxim-ic.com/thermal-tutorial.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### DC ELECTRICAL CHARACTERISTICS

 $(V_{AVDD} = V_{DVDD} = 3.0V \text{ to } 3.6V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\%$  (differential),  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ , unless otherwise noted. Typical values are at  $V_{AVDD} = V_{DVDD} = V_{IOVDD} = 3.3V$ ,  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CON	DITIONS	MIN	TYP	MAX	UNITS	
SINGLE-ENDED INPUTS (BWS,	INT, CDS, E	QS, MS, PWDN, SSE	EN, DRS)					
High-Level Input Voltage	VIH1			0.65 x V <sub>IOVDD</sub>			V	
Low-Level Input Voltage	VIL1					0.35 x Viovdd	V	
Input Current	lin1	VIN = 0V to VIOVDD	)	-10		+10	μΑ	
Input Clamp Voltage	VCL	$I_{CL} = -18 \text{mA}$				-1.5	V	
SINGLE-ENDED OUTPUTS (WS	SINGLE-ENDED OUTPUTS (WS, SCK, SD/CNTL0, CNTL1, CNTL2/MCLK)							
	VOH1	I <sub>OUT</sub> = -2mA	DCS = 0	Viovdd - 0.3			V	
High-Level Output Voltage			DCS = 1	VIOVDD - 0.2				
	Vou		DCS = 0			0.3	V	
Low-Level Output Voltage	VOL1	$I_{OUT} = 2mA$	DCS = 1			0.2	V	
		Vout = Vgnd,	$V_{IOVDD} = 3.0V$ to $3.6V$	15	25	39		
Output Short-Circuit Current		DCS = 0	$V_{IOVDD} = 1.7V$ to $1.9V$	3	7	13	mΛ	
	los	Vout = Vgnd,	$V_{IOVDD} = 3.0V$ to $3.6V$	20	35	63	mA	
		DCS = 1	$V_{IOVDD} = 1.7V$ to 1.9V	5	10	21		

### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = 3.0V \text{ to } 3.6V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\%$  (differential),  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ , unless otherwise noted. Typical values are at  $V_{AVDD} = V_{DVDD} = V_{IOVDD} = 3.3V$ ,  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CO	MIN	TYP	MAX	UNITS	
I <sup>2</sup> C AND UART I/O, OPEN-DRAI	OUTPUTS	(RX/SDA, TX/SCL,	LOCK, ERR, GPIO_)				
High-Level Input Voltage	VIH2			0.7 x Viovdd			V
Low-Level Input Voltage	VIL2					0.3 x Viovdd	V
Input Current	I <sub>IN2</sub>	VIN = 0V to VIOVDD (Note 2)	RX/SDA, TX/SCL LOCK, ERR, GPIO_	-110 -80		+1 +1	μA
Low-Level Output Voltage	V <sub>OL2</sub>	I <sub>OUT</sub> = 3mA	VIOVDD = 1.7V to 1.9V VIOVDD = 3.0V to 3.6V			0.4 0.3	V
DIFFERENTIAL OUTPUT FOR R	EVERSE CO	NTROL CHANNEL	(IN+, IN-)				
Differential High Output Peak Voltage, (VIN+) - (VIN-)	Vroh	No high-speed dat (Figure 1)	ta transmission	30		60	mV
Differential Low Output Peak Voltage, (VIN+) - (VIN-)	VROL	No high-speed da (Figure 1)	ta transmission	-60		-30	mV
DIFFERENTIAL INPUTS (IN+, IN-	-)						
Differential High Input Threshold (Peak) Voltage, (V <sub>IN+</sub> ) - (V <sub>IN-</sub> )	VIDH(P)	Figure 2			40	90	mV
Differential Low Input Threshold (Peak) Voltage, (VIN+) - (VIN-)	VIDL(P)	Figure 2		-90	-40		mV
Input Common-Mode Voltage ((V <sub>IN+</sub> ) + (V <sub>IN-</sub> ))/2	VCMR			1	1.3	1.6	V
Differential Input Resistance (Internal)	Rı			80	100	130	Ω
THREE-LEVEL LOGIC INPUTS (	ADD0, ADD1	)					
High-Level Input Voltage	VIH			0.7 x Viovdd			V
Low-Level Input Voltage	VIL					0.3 x Viovdd	V
Mid-Level Input Current	linm	ADD0 and ADD1 c to a driver with out (Note 3)	open or connected put in high impedance	-10		+10	μA
Input Current	lin	$\frac{\text{ADD0}}{\text{PWDN}} = \text{high or loc}$		-150		+150	μΑ
Input Clamp Voltage	VCL	I <sub>CL</sub> = -18mA				-1.5	V
LVDS OUTPUTS (TXOUT_, TXO	CLKOUT_)						
Differential Output Voltage	Vod	Figure 3		250		450	mV
Change in V <sub>OD</sub> Between Complementary Output States	ΔV <sub>OD</sub>	Figure 3				25	mV
Output Offset Voltage	Vos	Figure 3		1.125		1.375	V
Change in VOS Between Complementary Output States	ΔVos	Figure 3				25	mV

### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = 3.0V \text{ to } 3.6V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\%$  (differential),  $T_A = -40^{\circ}C$  to  $\pm 105^{\circ}C$ , unless otherwise noted. Typical values are at  $V_{AVDD} = V_{DVDD} = V_{IOVDD} = 3.3V$ ,  $T_A = \pm 25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Output Chart Circuit Current	laa	V <sub>OUT</sub> = 0V or 3.6V	3.5mA LVDS output	-7.5		+7.5	
Output Short-Circuit Current	los	V(0) = 0 V  or  3.6 V	7mA LVDS output	-15		+15	mA
Magnitude of Differential Output	laar	3.5mA LVDS outpu	it			7.5	
Short-Circuit Current	IOSD	7mA LVDS output				15	mA
Output High-Impedance Current	I <sub>OZ</sub>	ADD0 and ADD1 = high or low, $\overline{PWDN}$ = high or low		-0.5		+0.5	μA
POWER SUPPLY							
		BWS = low, fTXCLK	OUT_ = 16.6MHz		142	180	
Worst-Case Supply Current	Iwcs	BWS = low, fTXCLKOUT_ = 33.3MHz			153	200	]
(Figure 4)		BWS = low, fTXCLKOUT_ = 66.6MHz			179	240	mA
		BWS = low, fTXCLK	COUT_ = 104MHz		212	280	]
Sleep-Mode Supply Current	Iccs				80	130	μA
Power-Down Current	ICCZ	PWDN = GND			19	70	μA

### **AC ELECTRICAL CHARACTERISTICS**

 $(V_{AVDD} = V_{DVDD} = 3.0V \text{ to } 3.6V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\%$  (differential), T<sub>A</sub> = -40°C to +105°C, unless otherwise noted. Typical values are at V<sub>AVDD</sub> = V<sub>DVDD</sub> = V<sub>IOVDD</sub> = 3.3V, T<sub>A</sub> = +25°C.)

PARAMETER	SYMBOL	CO	NDITIONS	MIN	TYP	MAX	UNITS		
LVDS CLOCK OUTPUTS (TXCLKOUT+, TXCLKOUT-)									
		BWS = GND, VDR	s = Viovdd	8.33		16.66			
	favoricour	BWS = GND, DRS	S = GND	16.66		104	MHz		
Clock Frequency	ftxclkout_	VBWS = VIOVDD, \	/drs = Viovdd	6.25		12.5			
		VBWS = VIOVDD, [	DRS = GND	12.5		78			
I <sup>2</sup> C/UART PORT TIMING									
Output Rise Time	tR	30% to 70%, C <sub>L</sub> = 1k $\Omega$ pullup to IOV		20		150	ns		
Output Fall Time	tF	70% to 30%, $C_L = 10$ pF to 100pF, 1k $\Omega$ pullup to IOVDD (Figure 5)		20		150	ns		
Input Setup Time	tSET	I <sup>2</sup> C only (Figure 5)	)	100			ns		
Input Hold Time	thold	I <sup>2</sup> C only (Figure 5)	)	0			ns		
SWITCHING CHARACTERISTICS	5	· · · · · · · · · · · · · · · · · · ·							
		20% to 80%, CL = 10pF, DCS = 1	$V_{IOVDD} = 1.7V$ to $1.9V$	0.5		3.1			
CNTL_ Output Rise-and-Fall Time		(Figure 6)	$V_{IOVDD} = 3.0V$ to $3.6V$	0.3		2.2	ns		
	t <sub>R</sub> , t <sub>F</sub>	20% to 80%, CL = 5pF, DCS = 0	$V_{IOVDD} = 1.7V$ to $1.9V$	0.6		3.8	113		
		= 5pF, DCS = 0 (Figure 6)	$V_{IOVDD} = 3.0V$ to $3.6V$	0.4		2.4			
LVDS Output Rise Time	t <sub>R</sub>	20% to 80%, $R_L = 100\Omega$ (Figure 3)			200	350	ps		
LVDS Output Fall Time	tF	80% to 20%, RL =	100 $\Omega$ (Figure 3)		200	350	ps		



**MAX9268** 

### AC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = 3.0V \text{ to } 3.6V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\%$  (differential),  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ , unless otherwise noted. Typical values are at  $V_{AVDD} = V_{DVDD} = V_{IOVDD} = 3.3V$ ,  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	C	ONDITIONS	MIN	TYP	MAX	UNITS
			ftxclkout_ = 12.5MHz	N/7 x t <sub>CLK</sub> - 250	N/7 x t <sub>CLK</sub>	N/7 x t <sub>CLK</sub> + 250	
LVDS Output Pulse Position	tapoor	$N = 0$ to 6, tCLK = 1/fTXCLKOUT_,	= ftxclkout_ = 33MHz	N/7 x t <sub>CLK</sub> - 200	N/7 x tCLK	N/7 x t <sub>CLK</sub> + 200	
LVD3 Output Pulse Position	tpposn	fTXCLKOUT_ = 104MHz (Figure 7)	fTXCLKOUT_ = 78MHz	N/7 x t <sub>CLK</sub> - 125	N/7 x tCLK	N/7 x t <sub>CLK</sub> + 125	ps
			ftxclkout_ = 104MHz	N/7 x t <sub>CLK</sub> - 100	N/7 x tCLK	N/7 x t <sub>CLK</sub> + 100	
LVDS Output Enable Time	<sup>t</sup> LVEN	From the last bit packet to V <sub>OS</sub> =	of the enable UART 1125mV			100	μs
LVDS Output Disable Time	tlvds	From the last bit packet to V <sub>OS</sub> =	of the enable UART 0V			100	μs
Deserializer Delay	tsd	Figure 8 (Note 4)	)			3540	Bits
Reverse Control-Channel Output Rise Time	t <sub>R</sub>	No forward-chan (Figure 1)	nel data transmission	180		400	ns
Reverse Control-Channel Output Fall Time	tF	No forward-channel data transmission (Figure 1)		180		400	ns
Lock Time	<b>t</b> LOCK	Figure 9				3.6	ms
Power-Up Time	tpu	Figure 10				4.1	ms
I <sup>2</sup> S OUTPUT TIMING							
	taj-ws	1/1/03 - 1/1/03,	f <sub>WS</sub> = 48kHz or 44.1kHz		0.4e <sup>-3</sup> x tws	0.5e <sup>-3</sup> x tws	
WS Jitter		° °	f <sub>WS</sub> = 96kHz		0.8e <sup>-3</sup> x tws	1e <sup>-3</sup> x tws	ns
		(rising) edge (Note 5)	fws = 192kHz		1.6e <sup>-3</sup> x tws		
			nws = 16 bits, fws = 48kHz or 44.1kHz		13е <sup>-3</sup> x tscк		
SCK Jitter	taj-sck	tSCK = 1/tSCK, - rising edge to	nws = 24 bits, fws = 96kHz		39e <sup>-3</sup> x tsck	48e <sup>-3</sup>	ns
			n <sub>WS</sub> = 32 bits, f <sub>WS</sub> = 192kHz		0.1 х tscк	0.13	
Audio Skew Relative to Video	task	Video and audio	synchronized		3 x tws		μs
SCK, SD, WS Rise-and-Fall Time	tR, tF	1 20% to 80%	$C_L = 10pF, DCS = 1$ $C_L = 5pF, DCS = 0$	0.3		3.1 3.8	ns
SD, WS Valid Time Before SCK	tDVB	tSCK = 1/fSCK (F	· ·	0.35 x tsck	0.5 x tsck	-	ns
SD, WS Valid Time After SCK	tdva	tSCK = 1/fSCK (F	igure 11)	0.35 x tsck	0.5 x tsck		ns

Note 2: Minimum  $I_{IN}$  due to voltage drop across the internal pullup resistor.

Note 3: Measured in serial link bit times. Bit time = 1/(30 x fTXCLKOUT\_) for BWS = GND. Bit time = 1/(40 x fTXCLKOUT\_) for VBWS = VIOVDD.

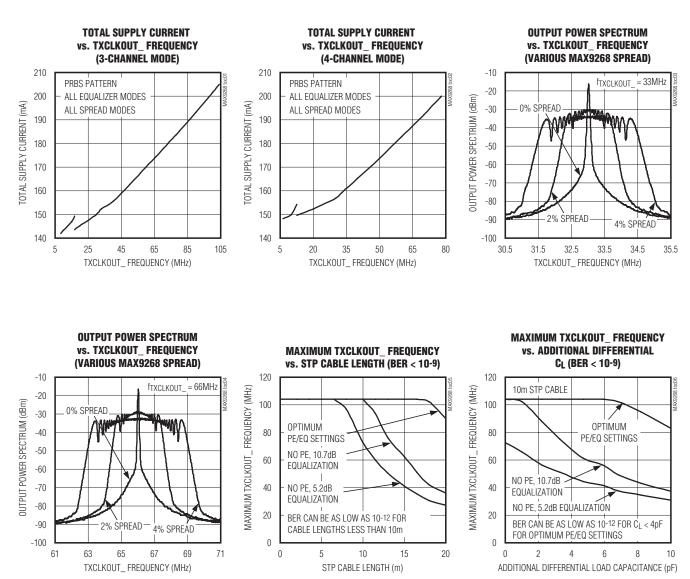
**Note 4:** Rising to rising-edge jitter can be twice as large.

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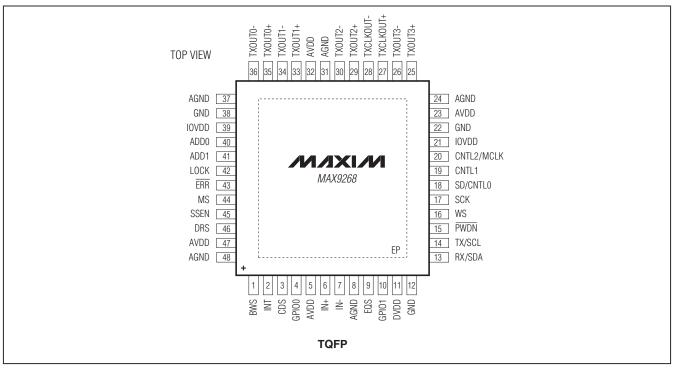
**MAX9268** 

\_Typical Operating Characteristics

(VAVDD = VDVDD = VIOVDD = 3.3V, TA = +25°C, unless otherwise noted.)



### **\_Pin Configuration**



### Pin Description

PIN	NAME	FUNCTION
1	BWS	Bus-Width Select. Output width selection requires external pulldown or pullup resistor. Set BWS = low for 3-channel mode. Set BWS = high for 4-channel mode.
2	INT	Interrupt Input. Requires external pulldown or pullup resistor. A transition on the MAX9268's INT input toggles the GMSL serializer's INT output.
3	CDS	Control Direction Selection. Control link direction selection input requires external pulldown or pullup resistor. Set CDS = low for $\mu$ C on the GMSL serializer side of the serial link. Set CDS = high for $\mu$ C on the MAX9268 side of the serial link.
4	GPI00	General-Purpose I/O 0. Open-drain, general-purpose input/output with internal $60k\Omega$ (typ) pullup resistor to IOVDD. GPIO0 is high impedance during power-up and when $\overline{PWDN}$ = low.
5, 23, 32, 47	AVDD	3.3V Analog Power Supply. Bypass AVDD to AGND with 0.1 $\mu$ F and 0.001 $\mu$ F capacitors as close as possible to the device with the smaller capacitor closest to AVDD.
6, 7	IN+, IN-	Differential CML Input. Differential input of the serial link.
8, 24, 31, 37, 48	AGND	Analog Ground
9	EQS	Equalizer Select Input. EQS requires external pulldown or pullup resistor. The state of EQS latches upon power-up or when resuming from power-down mode ( $\overline{PWDN} = Iow$ ). Set EQS = Iow for 10.7dB equalizer boost (EQTUNE = 1001). Set EQS = high for 5.2dB equalizer boost (EQTUNE = 0100).

### Pin Description (continued)

PIN	NAME	FUNCTION
10	GPIO1	General-Purpose I/O 1. Open-drain general-purpose input/output with internal $60k\Omega$ (typ) pullup resistor to IOVDD. GPIO1 is high impedance during power-up and when $\overline{PWDN}$ = low.
11	DVDD	3.3V Digital Power Supply. Bypass DVDD to GND with 0.1µF and 0.001µF capacitors as close as possible to the device with the smaller capacitor closest to DVDD.
12, 22, 38	GND	Digital and I/O Ground
13	RX/SDA	Receive/Serial Data. UART receive or I <sup>2</sup> C serial-data input/output with internal 30k $\Omega$ (typ) pullup to IOVDD. In UART mode, RX/SDA is the Rx input of the MAX9268's UART. In I <sup>2</sup> C mode, RX/SDA is the SDA input/output of the MAX9268's I <sup>2</sup> C master.
14	TX/SCL	Transmit/Serial Clock. UART transmit or I <sup>2</sup> C serial-clock output with internal 30k $\Omega$ (typ) pullup to IOVDD. In UART mode, TX/SCL is the Tx output of the MAX9268's UART. In I <sup>2</sup> C mode, TX/SCL is the SCL output of the MAX9268's I <sup>2</sup> C master.
15	PWDN	Power-Down. Active-low power-down input requires external pulldown or pullup resistor.
16	WS	I <sup>2</sup> S Word-Select Output
17	SCK	I <sup>2</sup> S Serial-Clock Output
18	SD/CNTL0	I <sup>2</sup> S Serial-Data/Control Output. Disable I <sup>2</sup> S to use SD/CNTL0 as an additional control output.
19	CNTL1	Control Output 1. CNTL1 is not active in 3-channel mode and remains low. To use CNTL1, drive BWS high (4-channel mode) and set DISCNTL = 0. CNTL1 is mapped from DOUT27.
20	CNTL2/MCLK	Control 2/MCLK Output. CNTL2/MCLK is not active in 3-channel mode and remains low. To use CNTL2/MCLK, drive BWS high (4-channel mode). CNTL2/MCLK is mapped from DOUT28. CNTL/MCLK can also be used to output MCLK (see the <i>Additional MCLK Output for</i> <i>Audio Applications</i> section).
21, 39	IOVDD	I/O Supply Voltage. 1.8V to 3.3V logic I/O power supply. Bypass IOVDD to GND with $0.1\mu$ F and $0.001\mu$ F capacitors as close as possible to the device with the smaller capacitor closest to IOVDD.
25, 26, 29, 30, 33–36	TXOUT_+, TXOUT	Differential LVDS Data Outputs. Set BWS = low (3-channel mode) to use TXOUT0_ to TXOUT2 Set BWS = high (4-channel mode) to use TXOUT0_ to TXOUT3
27, 28	TXCLKOUT+, TXCLKOUT-	Differential LVDS Output for the LVDS Clock
40	ADD0	Address Selection Input 0. Three-level input to select the MAX9268's device address (see Table 2). The state of ADD0 latches upon power-up or when resuming from power-down mode (PWDN = low).
41	ADD1	Address Selection Input 1. Three-level input to select the MAX9268's device address (see Table 2). The state of ADD1 latches upon power-up or when resuming from power-down mode (PWDN = low).
42	LOCK	Open-Drain Lock Output with Internal 60k $\Omega$ (typ) Pullup to IOVDD. LOCK = high indicates PLLs are locked with correct serial-word-boundary alignment. LOCK = low indicates PLLs are not locked or incorrect serial-word-boundary alignment. LOCK remains low when the configuration link is active. LOCK is high impedance when $\overline{PWDN}$ = low.
43	ERR	Active-Low, Open-Drain Video Data Error Output with Internal $60k\Omega$ (typ) Pullup to IOVDD. ERR goes low when the number of decoding errors during normal operation exceeds a pro- grammed error threshold, or when at least one PRBS error is detected during PRBS test. ERR is high impendence when $\overline{PWDN} = Iow$ .

### Pin Description (continued)

PIN	NAME	FUNCTION
44	MS	Mode Select. Control link mode-selection input requires an external pulldown or pullup resistor. Set MS = low to select base mode. Set MS = high to select bypass mode.
45	SSEN	Spread-Spectrum Enable. Serial link spread-spectrum enable input requires an external pull- down or pullup resistor. The state of SSEN latches upon power-up or when resuming from power-down mode ( $\overline{PWDN}$ = low). Set SSEN = high for ±2% spread spectrum on the LVDS and control outputs. Set SSEN = low to use the LVDS and control outputs without spread spectrum.
46	DRS	Data-Rate Select. Data-rate range-selection input requires an external pulldown or pullup resistor. The state of DRS latches upon power-up or when resuming from power-down mode (PWDN = low). Set DRS = high for TXCLKOUT_ frequencies of 8.33MHz to 16.66MHz (3-channel mode), or 6.25MHz to 12.5MHz (4-channel mode). Set DRS = low for TXCLKOUT_ frequencies of 16.66MHz to 104MHz (3-channel mode), or 12.5MHz to 78MHz to 78MHz (4-channel mode).
	EP	Exposed Pad. EP internally connected to AGND. <b>MUST</b> externally connect EP to the plane supplying AGND for proper thermal and electrical performance.

#### IN+ CLK CDR TXCLKOUT+/-SSPLL Rx/EQ IN-DIV PLL 7x PLL RGB[17:0] RGB TXOUT0+/-HS HS SERIAL VS VS TO TXOUT1+/-VIDEO DE DE PARALLEL PARALLEL TO LVDS RGB[23:18] (4-CH) TXOUT2+/-8b/10b DECODE/ RES/CNTL1 UNSCRAMBLE TXOUT3+/-CNTL1/RES FIFO (4-CH) Тх CNTL2 **REVERSE CONTROL** CNTL1 (4-CH) CHANNEL ACB AUDIO FCC CNTL2/MCLK (4-CH) MAX9268 UART/I2C ¥ SD/CNTL0 SCK WS TX/SCL RX/SDA

### Functional Diagram

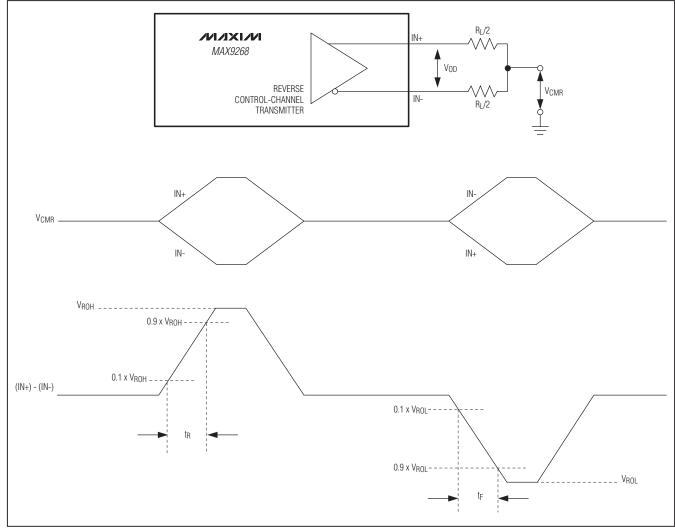


Figure 1. Reverse Control-Channel Output Parameters

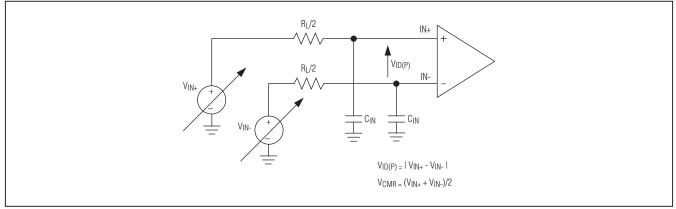


Figure 2. Test Circuit for Differential Input Measurement

**MAX9268** 

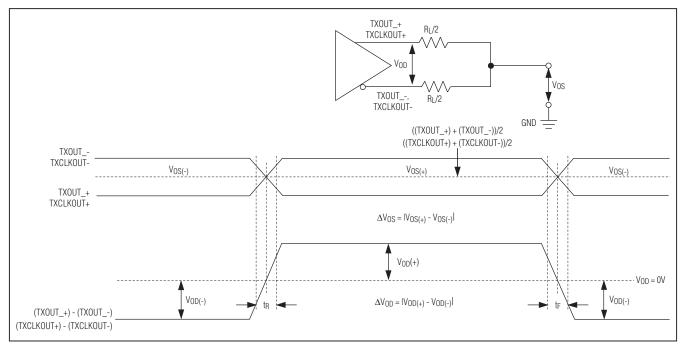


Figure 3. LVDS Output Parameters

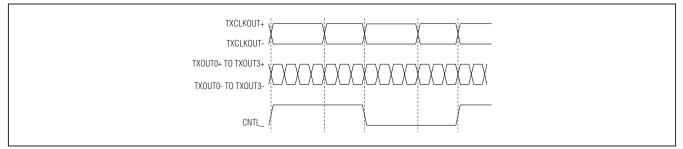


Figure 4. Worst-Case Pattern Output

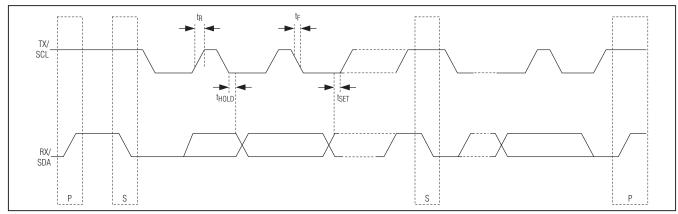


Figure 5. I<sup>2</sup>C Timing Parameters

**MAX9268** 

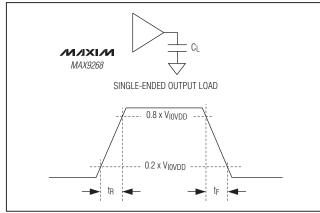


Figure 6. Single-Ended Output Rise-and-Fall Times

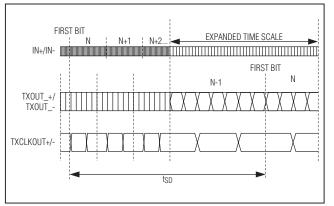


Figure 8. Deserializer Delay

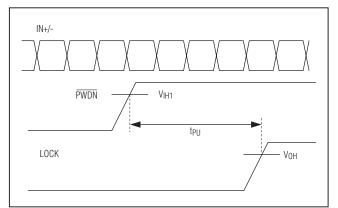


Figure 10. Power-Up Delay

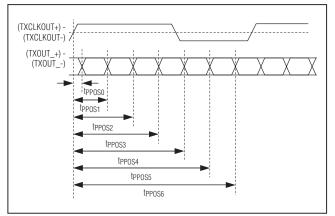
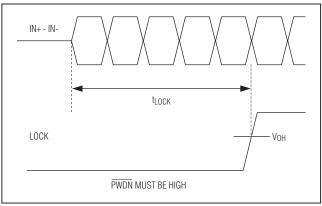


Figure 7. LVDS Output Pulse Position Measurement





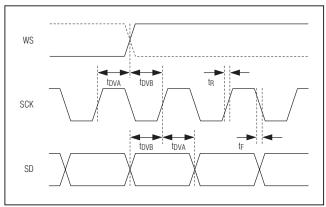


Figure 11. Output I<sup>2</sup>S Timing Parameters



### **Detailed Description**

The MAX9268 deserializer with LVDS system interface utilizes Maxim's GMSL technology. The MAX9268 deserializer pairs with any GMSL serializer to form a complete digital serial link for joint transmission of highspeed video, audio, and bidirectional control data.

The MAX9268 allows a maximum serial payload data rate of 2.5Gbps for greater than 15m of STP cable. The deserializer operates up to 104MHz for 3-channel LVDS or 78MHz for 4-channel LVDS. The operating frequency range supports display panels from QVGA (320 x 240) up to WXGA (1280 x 800) and higher with 24-bit color.

The 3-channel mode outputs an LVDS clock, three lanes of LVDS data (21 bits), UART control signals, and one I<sup>2</sup>S audio channel (consisting of three signals). The 4-channel mode outputs an LVDS clock, four lanes of LVDS data (28 bits), UART control signals, one I<sup>2</sup>S audio channel, and control signals. The I<sup>2</sup>S interface supports sample rates from 8kHz to 192kHz and audio word lengths of 4 to 32 bits. The embedded control channel forms a full-duplex, differential, 100kbps to 1Mbps UART link between the serializer and deserializer. An ECU or  $\mu$ C can be located on the

serializer side of the link (typical for video display), on the MAX9268 side of the link (typical for image sensing), or on both sides. In addition, the control channel enables ECU/µC control of peripherals in the remote side, such as backlight control, grayscale Gamma correction, camera module, and touch screen. Base-mode communication with peripherals uses either I<sup>2</sup>C or the GMSL UART format. A bypass mode enables full-duplex communication using custom UART formats.

The MAX9268 channel equalizer, along with the serializer preemphasis, extends the link length and enhances the link reliability. Spread spectrum is available to reduce EMI on the LVDS and control outputs of the MAX9268. The serial input complies with ISO 10605 and IEC 61000-4-2 ESD protection standards.

#### **Register Mapping**

The  $\mu$ C configures various operating conditions of the GMSL serializer and the MAX9268 through internal registers. The default device addresses are stored in registers 0x00 and 0x01 of both the GMSL serializer and the MAX9268 (Table 1). Write to the 0x00 and 0x01 registers in both devices to change the device address of the GMSL serializer or the MAX9268.

REGISTER ADDRESS (hex)	POWER-UP DEFAULT (hex)	POWER-UP DEFAULT SETTINGS (MSB FIRST)
0x00	0x40, 0x44, 0x48 0x80, 0x84, 0x88, 0xC0, 0xC4, 0xC8	SERID = XX00XX0, serializer device address is determined by ADD1 and ADD0 (Table 2) RESERVED = 0
0x01	0x50, 0x54, 0x58, 0x90, 0x94, 0x98, 0xD0, 0xD4, 0xD8	DESID =XX01XX0, deserializer device address is determined by ADD1 and ADD0 (Table 2) RESERVED = 0
0x02	0x1F or 0x5F	SS = 00 (SSEN = low), SS = 01 (SSEN = high), spread-spectrum settings depend on SSEN pin state at power-up RESERVED = 0 AUDIOEN = 1, I <sup>2</sup> S channel enabled PRNG = 11, automatically detect the pixel clock range SRNG = 11, automatically detect serial-data rate
0x03	0x00	AUTOFM = 00, calibrate spread-modulation rate only once after locking RESERVED = 0 SDIV = 00000, autocalibrate sawtooth divider

#### Table 1. Power-Up Default Register Map (see Table 12)

 Table 1. Power-Up Default Register Map (see Table 12) (continued)

REGISTER ADDRESS (hex)	POWER-UP DEFAULT (hex)	POWER-UP DEFAULT SETTINGS (MSB FIRST)
0x04	0x03 or 0x13	LOCKED = 0, LOCK output is low (read only) OUTENB = 0, outputs enabled PRBSEN = 0, PRBS test disabled SLEEP = 0 or 1, SLEEP setting default depends on CDS and MS pin state at power-up (see the <i>Link Startup Procedure</i> section) INTTYPE = 00, base mode uses I <sup>2</sup> C REVCCEN = 1, reverse control channel active (sending) FWDCCEN = 1, forward control channel active (receiving)
0x05	0x24 or 0x29	I2CMETHOD = 0, I <sup>2</sup> C master sends the register address HPFTUNE = 01, 3.75MHz equalizer highpass cutoff frequency PDHF = 0, high-frequency boosting disabled EQTUNE = 0100 (EQS = high, 5.2dB), EQTUNE = 1001 (EQS = low, 10.7dB), EQTUNE default setting depends on EQS pin state at power-up
0x06	0x0F	RESERVED = 0 AUTORST = 0, error registers/output autoreset disabled DISINT = 0, INT transmission enabled INT = 0, INT output is low (read only) GPIO1OUT = 1, GPIO1 output set to high GPIO1 = 1, GPIO1 input = high (read only) GPIO0OUT = 1, GPIO0 output set to high GPIO0 = 1, GPIO0 input = high (read only)
0x07	0x54	RESERVED = 01010100
0x08	0x30	RESERVED = 00110000
0x09	0xC8	RESERVED = 11001000
0x0A	0x12	RESERVED = 00010010
0x0B	0x20	RESERVED = 00100000
0x0C	0x00	ERRTHR = 00000000, error threshold set to zero for decoding errors
0x0D	0x00 (read only)	DECERR = 00000000, zero decoding errors detected
0x0E	0x00 (read only)	PRBSERR = 00000000, zero PRBS errors detected
0x12	0x00	MCLKSRC = 0, MCLK is derived from PCLK (see Table 5) MCLKDIV = 0000000, MCLK output is disabled
0x13	0xX0	RESERVED = XXX RESERVED = 10000
0x14	0x01	RESERVED = 00 FORCELVDS = 0, normal LVDS operation DCS = 0, normal CMOS driver current strength DISCNTL1 = 0, serial-data bit 27 is mapped to CNTL1 DISRES = 0, serial-data bit 27 is mapped to RES ILVDS = 01, 3.5mA LVDS output current

### Table 1. Power-Up Default Register Map (see Table 12) (continued)

REGISTER ADDRESS (hex)	POWER-UP DEFAULT (hex)	POWER-UP DEFAULT SETTINGS (MSB FIRST)
0x1E	0x04 (read only)	ID = 00000100, device ID is 0x04
0x1F	0x0X (read only)	RESERVED = 000 CAPS = 0, not HDCP capable REVISION = XXXX

X = Don't care.

### Table 2. Deserializer Device Address Defaults (Register 0x01)

PII	N	DEVICE ADDRESS* (bin)						SERIALIZER DEVICE ADDRESS*	DESERIALIZER DEVICE ADDRESS*		
ADD1	ADD0	D7	D6	D5	D4	D3	D2	D1	D0	(hex)	(hex)
Low	Low	1	0	0	X**	0	0	0	R/W	80	90
Low	High	1	0	0	X**	0	1	0	R/W	84	94
Low	Open	1	0	0	X**	1	0	0	R/W	88	98
High	Low	1	1	0	X**	0	0	0	R/W	CO	D0
High	High	1	1	0	X**	0	1	0	R/W	C4	D4
High	Open	1	1	0	X**	1	0	0	R/W	C8	D8
Open	Low	0	1	0	X**	0	0	0	R/W	40	50
Open	High	0	1	0	X**	0	1	0	R/W	44	54
Open	Open	0	1	0	X**	1	0	0	R/W	48	58

\*ADD0 and ADD1 affect the default device address values stored in the MAX9268 only. The default device address values stored in the GMSL serializer may differ (see the 3-Level Inputs for Default Device Address section).

\*X = 0 for the serializer address, X = 1 for the deserializer address.

#### Typical Bitmapping and Bus-Width Selection

The LVDS output has two selectable widths: 3-channel and 4-channel. The MAX9268 outputs 3- or 4-channel LVDS (Table 3). Serial data is mapped to outputs on the MAX9268 according to Figures 12 and 13. In 3-channel mode, TXOUT3\_ and CNTL1, CNTL2/MCLK are not available. For both modes, the SD/CNTL0, SCK, and WS pins are for I<sup>2</sup>S audio when audio is enabled. With audio disabled, SD/CNTL0 becomes control signal CNTL0. The MAX9268 outputs clock rates from 8.33MHz to 104MHz for 3-channel mode and 6.25MHz to 78MHz for 4-channel mode.

Serial Link Signaling and Data Format

The GMSL high-speed serial link uses CML signaling with programmable preemphasis and AC-coupling. The GMSL deserializer uses AC-coupling and programmable channel equalization. When using both the preemphasis and equalization, including internally generated overhead bits, the GMSL link operates up to 3.125Gbps over STP cable lengths of 15m or greater. The payload data rate, which is the data rate available to the user or the data rate after subtracting overhead, is 2.5Gbps.

The GMSL serializer scrambles and encodes the input data and sends the 8b/10b coded signal through the serial link. The MAX9268 deserializer recovers the embedded serial clock and then samples, decodes, and descrambles before outputting the data. Figures 14 and 15 show the serial-data packet format after unscrambling and 8b/10b decoding. In 3-channel or 4-channel mode, 21 or 28 bits map to the TXOUT\_\_LVDS outputs. Serial-data bits 27 and 28 map to control outputs in 4-channel mode. The audio channel bit (ACB) contains an encoded audio signal derived from the three I<sup>2</sup>S signals (SD/CNTL0, SCK, and WS). The forward control-channel (FCC) bit carries the forward control data. The last bit (PCB) is the parity bit of the previous 23 or 31 bits.

	3-CHANN (BWS =	EL MODE = LOW)	4-CHANNEL MODE (BWS = HIGH)		
OUTPUT BITS	TYPICAL BITMAPPING AUXILIARY SIGNALS MAPPING		TYPICAL BITMAPPING	AUXILIARY SIGNALS MAPPING	
DOUT[0:5]	R[0:5]	—	R[0:5]	—	
DOUT[6:11]	G[0:5]	—	G[0:5]	_	
DOUT[12:17]	B[0:5]	—	B[0:5]	—	
DOUT[18:20]	HS, VS, DE	_	HS, VS, DE	_	
DOUT[21:22]	Not used	Not used	R6, R7	—	
DOUT[23:24]	Not used	Not used	G6, G7	_	
DOUT[25:26]	Not used	Not used	B6, B7	_	
DOUT27	Not used	Not used	RES*	CNTL1*	
DOUT28	Not used	Not used	_	CNTL2/MCLK	
SD		SD/CNTL0	_	SD/CNTL0	

### Table 3. Bus-Width Selection Using BWS

\*See the Reserved Bit (RES)/CNTL1 section for details.

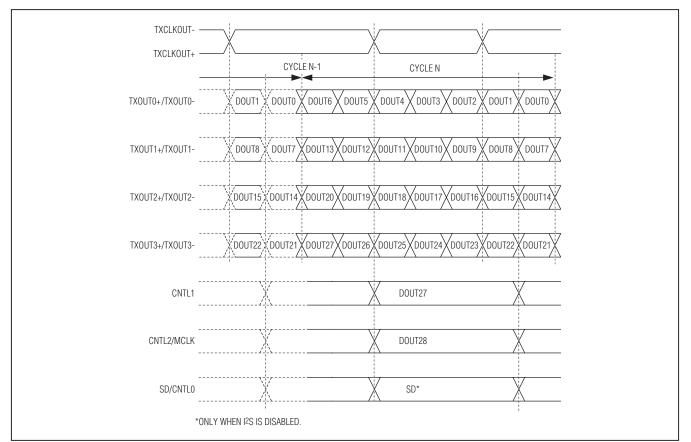


Figure 12. LVDS Output Timing

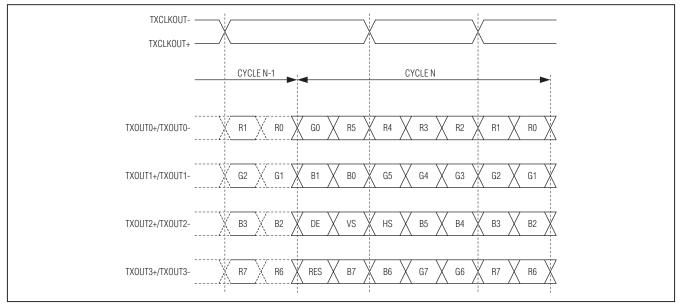
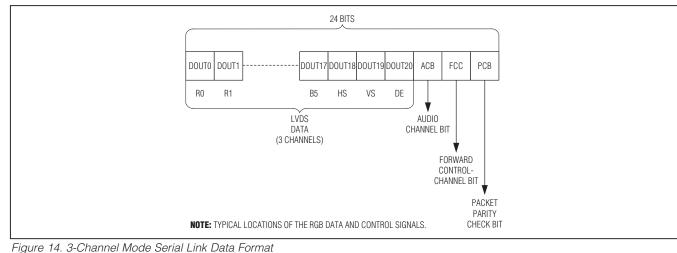
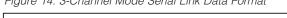


Figure 13. Typical Panel Clock and Bit Assignment

**MAX9268** 





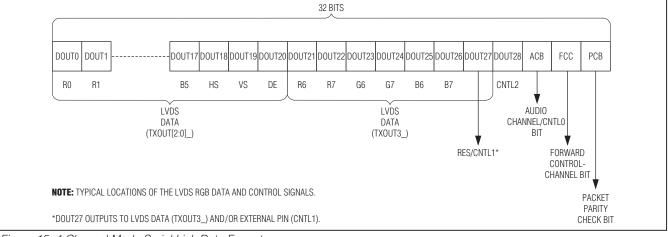


Figure 15. 4-Channel Mode Serial Link Data Format

#### **Reserved Bit (RES)/CNTL1**

In 4-channel mode, the MAX9268 deserializes serialdata bit 27 to both RES and CNTL1 by default (both DISCNTL and DISRES = 0). Setting DISRES (D2 of register 0x14) = 1 forces RES low. Setting DISCNTL1 (D3 of register 0x14) = 1 forces CNTL1 low.

#### **Reverse Control Channel**

The GMSL serializer uses the reverse control channel to receive I<sup>2</sup>C/UART and interrupt signals from the MAX9268 in the opposite direction of the video stream. The reverse control channel and forward video data coexist on the same twisted pair forming a bidirectional link. The reverse control channel operates independently from the forward control channel. The reverse control channel is available 500µs after power-up. The GMSL serializer temporarily disables the reverse control

channel for 350 $\!\mu s$  after starting/stopping the forward serial link.

#### **Data-Rate Selection**

The MAX9268 uses the DRS input to set the TXCLKOUT\_ frequency. Set DRS high for a TXCLKOUT\_ frequency of 6.25MHz to 12.5MHz (4-channel mode), or 8.33MHz to 16.66MHz (3-channel mode). Set DRS low for normal operation with a TXCLKOUT\_ frequency of 12.5MHz to 78MHz (4-channel mode), or 16.66MHz to 104MHz (3-channel mode).

#### **Audio Channel**

The I<sup>2</sup>S audio channel supports audio sampling rates from 8kHz to 192kHz and audio word lengths from 4 bits to 32 bits. The audio bit clock (SCK) does not have to be synchronized with TXCLKOUT\_. The GMSL serializer automatically encodes audio data into a single bit stream



where:

synchronous with TXCLKOUT\_. The MAX9268 deserializer decodes the audio stream and stores audio words in a FIFO. Audio rate detection uses an internal oscillator to continuously determine the audio data rate and output the audio in I<sup>2</sup>S format. The audio channel is enabled by default. When the audio channel is disabled, the audio data input (SD) on the serializer becomes a control input (CNTL0) and SD/CNTL0 becomes a control output on the deserializer.

Low TXCLKOUT\_ frequencies limit the maximum audio sampling rate. Table 4 lists the maximum audio sampling rate for various TXCLKOUT\_ frequencies. Spread-spectrum settings do not affect the I<sup>2</sup>S data rate or WS clock frequency.

#### Additional MCLK Output for Audio Applications

Some audio DACs such as the MAX9850 do not require a synchronous main clock (MCLK), while other DACs require MCLK to be a specific multiple of WS. If the audio DAC chip needs the MCLK to be a multiple of WS, use an external PLL to regenerate the required MCLK from WS or SCK.

For audio applications that have WS synchronous to TXCLKOUT\_, the MAX9268 provides a divided clock

output on CNTL2/MCLK at the expense of one less control line in 4-channel mode (3-channel mode is not affected). By default, CNTL2/MCLK operates as a control data output, and MCLK is turned off. Set MCLKDIV (MAX9268 register 0x12, D[6:0]) to a nonzero value to enable the MCLK output. Set MCLKDIV to 0x00 to disable MCLK and set CNTL2/MCLK as a control data output.

The output MCLK frequency is:

 $f_{MCLK} = \frac{f_{SRC}}{MCLKDIV}$ 

fsRc = the MCLK source frequency (Table 5)

MCLKDIV = the divider ratio from 1 to 127

Choose MCLKDIV values such that f<sub>MCLK</sub> is not greater than 60MHz. MCLK frequencies derived from TXCLKOUT\_ (MSCLKSRC = 0) are not affected by spread-spectrum settings in the MAX9268. However, enabling spread spectrum into MCLK. Spread-spectrum settings of either device do not affect MCLK frequencies derived from the internal oscillator. The internal oscillator frequency ranges from 100MHz to 150MHz over all process corners and operating conditions.

WORD LENGTH (BITS)		•	FREQUENCY = LOW) Hz)		TXCLKOUT_ FREQUENCY (DRS = HIGH) (MHz)			
(BI13)	12.5	15	16.6	> 20	6.25	7.5	8.33	> 10
8	> 192	> 192	> 192	> 192	> 192	> 192	> 192	> 192
16	> 192	> 192	> 192	> 192	> 192	> 192	> 192	> 192
18	185.5	> 192	> 192	> 192	185.5	> 192	> 192	> 192
20	174.6	> 192	> 192	> 192	174.6	> 192	> 192	> 192
24	152.2	182.7	> 192	> 192	152.2	182.7	> 192	> 192
32	123.7	148.4	164.3	> 192	123.7	148.4	164.3	> 192

### Table 4. Maximum Audio WS Frequency (kHz) for Various TXCLKOUT\_ Frequencies

### Table 5. fSRC Settings

MCLKSRC SETTING (REGISTER 0x12, D7)	DATA-RATE SETTING	BUS-WIDTH SETTING	MCLK SOURCE FREQUENCY (f <sub>SRC</sub> )	
	High speed	3-channel mode	3 x ftxclkout_	
0	r light speed	4-channel mode	4 x ftxclkout_	
0	Low apood	3-channel mode	6 x ftxclkout_	
	Low speed	4-channel mode	8 x ftxclkout_	
1			Internal oscillator (120MHz, typ)	

**Control Channel and Register Programming** The control channel is available for the  $\mu$ C to send and receive control data over the serial link simultaneously with the high-speed data, to program registers on the link serializer/deserializer or to program peripherals. Configuring the CDS pin allows a  $\mu$ C to control the link from the side of the serializer or deserializer, or with dual  $\mu$ Cs from both sides, to support a wide variety of applications.

The control channel runs in base mode or bypass mode according to the mode-selection (MS) input of the device connected to the  $\mu$ C. In base mode, the control-channel transactions are half-duplex and in bypass mode they are full-duplex.

#### Base Mode

In base mode the  $\mu$ C is the host, and in order to access the registers of the serializer or deserializer it must use the GMSL UART format and protocol. The  $\mu$ C accesses peripherals with an I<sup>2</sup>C interface by sending GMSL UART packets, which are converted to I<sup>2</sup>C by the serializer or deserializer on the remote side of the link. The  $\mu$ C communicates with a UART peripheral in base mode (through INTTYPE register settings) using the GMSL UART protocol. The device addresses of the GMSL serializer and MAX9268 in base mode are programmable. The default MAX9268 device address is determined by ADD0 and ADD1 upon power-up, or after returning from a power-down state (Table 2).

When the peripheral interface uses I<sup>2</sup>C (default), the GMSL serializer/MAX9268 convert packets to I<sup>2</sup>C that have device addresses different from those of the GMSL serializer or MAX9268. The converted I<sup>2</sup>C bit rate is the same as the original UART bit rate.

The GMSL serializer embeds control signals going to the MAX9268 in the high-speed forward link. The MAX9268 uses a proprietary differential line coding to send signals

back towards the serializer. The speed of the control channel ranges from 100kbps to 1Mbps in both directions. The GMSL serializer and MAX9268 deserializer automatically detect the control-channel bit rate in base mode. Packet bit rates can vary up to 3.5x from the previous bit rate (see the *Changing the Clock Frequency section*). Figure 16 shows the UART protocol for writing and reading in base mode between the  $\mu$ C and the GMSL serializer/MAX9268.

Figure 17 shows the UART data format. Figures 18 and 19 detail the formats of the SYNC byte (0x79) and the ACK byte (0xC3). The µC and the connected slave chip generate the SYNC byte and ACK byte, respectively. Events such as device wake-up and interrupt generate transitions on the control channel that should be ignored by the  $\mu$ C. Data written to the GMSL serializer/MAX9268 registers do not take effect until after the acknowledge byte is sent. This allows the µC to verify write commands received without error, even if the result of the write command directly affects the serial link. The slave uses the SYNC byte to synchronize with the host UART data rate automatically. If the INT or MS inputs of the MAX9268 toggle while there is control-channel communication, the control-channel communication can be corrupted since INT has priority on the control channel. In the event of a missed acknowledge, the µC should assume there was an error in the packet when the slave device receives it, or that an error occurred during the response from the slave device. In base mode, the µC must keep the UART Tx/Rx lines high for 16 bit times before sending a new packet.

As shown in Figure 20, the remote-side device converts the packets going to or coming from the peripherals from the UART format to the I<sup>2</sup>C format and vice versa. The remote device removes the byte number count and adds or receives the ACK between the data bytes of I<sup>2</sup>C. The I<sup>2</sup>C's data rate is the same as the UART data rate.

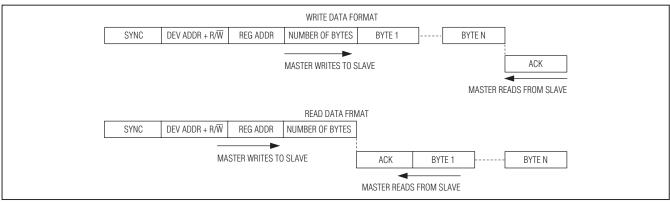


Figure 16. GMSL UART Protocol for Base Mode

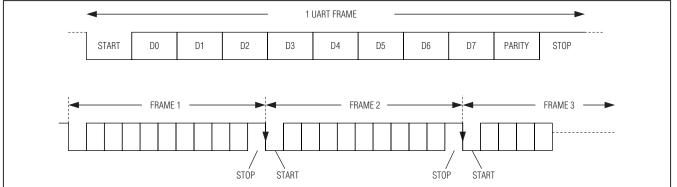
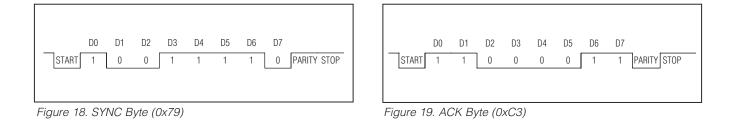


Figure 17. GMSL UART Data Format for Base Mode



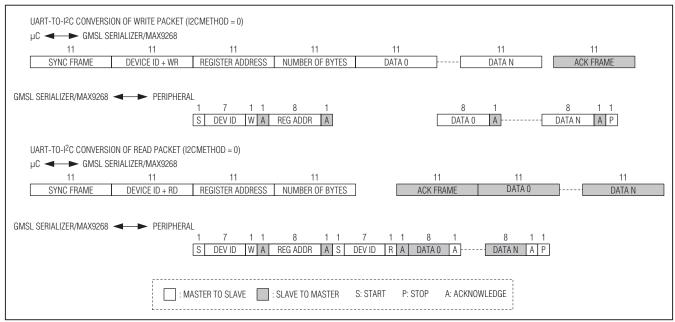


Figure 20. Format Conversion between GMSL UART and  $I^2C$  with Register Address (I2CMETHOD = 0)

#### Interfacing Command-Byte-Only I<sup>2</sup>C Devices

The GMSL serializer and MAX9268 UART-to-I<sup>2</sup>C conversion interfaces with devices that do not require register addresses, such as the MAX7324 GPIO expander. In this mode, the I<sup>2</sup>C master ignores the register address byte and directly reads/writes the subsequent data bytes (Figure 21). Change the communication method of the I<sup>2</sup>C master using the I2CMETHOD bit. I2CMETHOD = 1 sets command-byte-only mode, while I2CMETHOD = 0 sets normal mode where the first byte in the data stream is the register address.

#### Bypass Mode

In bypass mode, the GMSL serializer/MAX9268 ignore UART communications. The  $\mu$ C is thereby free to communicate with the peripherals using its own UART protocol without concern that communication traffic inadvertently misprograms the GMSL serializer or MAX9268. The  $\mu$ C cannot access the GMSL serializer/MAX9268 registers in this mode. Peripherals accessed through the forward control channel using the UART interface need to handle at least one TXCLKOUT\_ period of jitter due to the asynchronous sampling of the UART signal by TXCLKOUT\_.

Set MS = high to put the control channel into bypass mode. For applications with the  $\mu$ C connected to the deserializer (CDS is high), there is a 1ms wait time between setting MS high and the bypass control channel being active. There is no delay time when switching to bypass mode when the  $\mu$ C is connected to the serializer

(CDS = low). Bypass mode accepts bit rates down to 28kbps in the forward direction (serializer to deserializer), and 7.7kbps in the reverse direction (deserializer to serializer). See the *Interrupt Control* section for interrupt functionality limitations. The control-channel data pattern should not be held low longer than 100µs if interrupt control is used.

#### **Interrupt Control**

///XI//

The INT pin of the GMSL serializer is the interrupt output and the INT pin of the MAX9268 is the interrupt input. The interrupt output on the GMSL serializer follows the transitions at the interrupt input, even during reversechannel communication or loss of lock. This interrupt function supports remote-side functions such as touchscreen peripherals, remote power-up, or remote monitoring. Interrupts that occur during periods where the reverse control channel is disabled, such as link startup/ shutdown, are automatically resent once the reverse control channel becomes available again. Bit D4 of register 0x06 in the MAX9268 also stores the interrupt input state. The INT output of the GMSL serializer is low after power-up. In addition, the µC can set the INT output of the serializer by writing to the SETINT register bit. In normal operation, the state of the interrupt output changes when the interrupt input on the MAX9268 toggles. Do not send a logic-low value longer than 100µs in either base or bypass mode to ensure proper interrupt functionality.

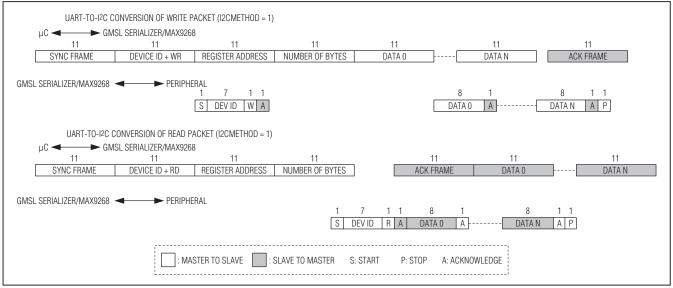


Figure 21. Format Conversion Between GMSL UART and I<sup>2</sup>C with Register Address (I2CMETHOD = 1)

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#### Line Equalizer

The MAX9268 includes an adjustable line equalizer to further compensate cable attenuation at high frequencies. The cable equalizer has 12 selectable levels of compensation, from 2.1dB to 13dB (Table 6). The EQS input selects the default equalization level at power-up. The state of EQS is latched upon power-up or when resuming from power-down mode. To select other equalization levels, set the corresponding register bits in the MAX9268 (0x05 D[3:0]). Use equalization in the MAX9268, together with preemphasis in the GMSL serializer, to create the most reliable link for a given cable.

#### Spread Spectrum

To reduce the EMI generated by the transitions on the serial link and outputs of the MAX9268, both the GMSL serializer and MAX9268 support spread spectrum. Turning on spread spectrum on the GMSL serializer spreads the serial data and the MAX9268 outputs. Do not enable spread for both the GMSL serializer and the MAX9268. The two selectable spread-spectrum rates at the MAX9268 outputs are  $\pm 2\%$  and  $\pm 4\%$  (Table 7).

Set the MAX9268 SSEN input high to select 2% spread at power-up, and SSEN input low to select no spread at power-up. The state of SSEN is latched upon power-up or when resuming from power-down mode.

Turning on spread spectrum on the GMSL serializer or the MAX9268 does not affect the audio data stream. Changes

#### Table 6. Cable Equalizer Boost Levels

BOOST SETTING (0x05 D[3:0])	TYPICAL BOOST GAIN (dB)		
0000	2.1		
0001	2.8		
0010	3.4		
0011	4.2		
	5.2		
0100	Power-up default (EQS = high)		
0101	6.2		
0110	7		
0111	8.2		
1000	9.4		
1001	10.7 Power-up default (EQS = low)		
1010	11.7		
1011	13		

in the GMSL serializer spread settings only affect the MAX9268 MCLK output if it is derived from TXCLKOUT\_ (MCLKSRC = 0).

The MAX9268 includes a sawtooth divider to control the spread-modulation rate. Autodetection or manual programming of the TXCLKOUT\_ operation range guarantees a spread-spectrum modulation frequency within 20kHz to 40kHz. Additionally, manual configuration of the sawtooth divider (SDIV, 0x03 D[4:0]) allows the user to set a modulation frequency according to the TXCLKOUT\_ frequency. Always keep the modulation frequency between 20kHz to 40kHz to ensure proper operation.

#### Manual Programming of the Spread-Spectrum Divider

The modulation rate for the MAX9268 relates to the TXCLKOUT\_ frequency as follows:

$$f_{M} = (1 + DRS) \frac{f_{TXCLKOUT}}{MOD \times SDIV}$$

 $f_{M} = Modulation frequency$ 

where:

DRS = DRS input value (0 or 1)

fTXCLKOUT\_ = LVDS clock frequency

MOD = Modulation coefficient given in Table 8

SDIV = 5-bit SDIV setting, manually programmed by the  $\mu$ C

To program the SDIV setting, first look up the modulation coefficient according to the spread-spectrum settings.

## Table 7. LVDS and Control Output SpreadRates

SS	SPREAD (%)				
00	No spread spectrum. <b>Power-up default when SSEN = low.</b>				
01	±2% spread spectrum. <b>Power-up default when SSEN = high.</b>				
10	No spread spectrum				
11	±4% spread spectrum				

## Table 8. Modulation Coefficients andMaximum SDIV Settings

SPREAD- SPECTRUM SETTING (%)	MODULATION COEFFICIENT (dec)	SDIV UPPER LIMIT (dec)	
4	208	15	
2	208	30	

Solve the above equation for SDIV using the desired pixel clock and modulation frequencies. If the calculated SDIV value is larger than the maximum allowed SDIV value in Table 8, set SDIV to the maximum value.

#### Sleep Mode

The GMSL serializer/MAX9268 include low-power sleep mode to reduce power consumption on the device not attached to the  $\mu$ C (the MAX9268 in LCD applications and the GMSL serializer in camera applications). Set the corresponding remote IC's SLEEP bit to 1 to initiate sleep mode. The GMSL serializer sleeps immediately after setting its SLEEP = 1. The MAX9268 sleeps after serial link inactivity or 8ms (whichever arrives first) after setting its SLEEP = 1. See the *Link Startup Procedure* section for details on waking up the device for different  $\mu$ C and starting conditions.

The  $\mu$ C side device cannot enter into sleep mode. If an attempt is made to program the  $\mu$ C side device for sleep, the SLEEP bit remains 0. Use the power-down mode to bring the  $\mu$ C side device into a low-power state.

#### **Power-Down Mode**

The MAX9268 includes a power-down mode to further reduce power consumption. Set PWDN low to enter power-down mode. While in power-down mode, the outputs of the device remain high impedance. Entering power-down mode resets the internal registers of the device. In addition, upon exiting power-down mode, the MAX9268 relatches the state of SSEN, EQS, DRS, and ADD\_.

#### **Configuration Link Mode**

The GMSL includes a low-speed configuration link to allow control-data connection between the two devices in the absence of a valid clock input. In either display or camera applications, the configuration link can be used to program equalizer/preemphasis or other registers before establishing the video link. An internal oscillator provides a clock for establishing the serial configuration link between the GMSL serializer and the MAX9268. Set CLINKEN = 1 on the GMSL serializer to turn on the configuration link. The configuration link remains active as long as the video link has not been enabled. The video link overrides the configuration link and attempts to lock when SEREN = 1.

### Link Startup Procedure

Table 9 lists four startup cases for video-display applications. Table 10 lists two startup cases for image-sensing applications. In either video-display or image-sensing applications, the control link is always available after the high-speed data link or the configuration link is established and the GMSL serializer/MAX9268 registers or peripherals are ready for programming.

#### **Video-Display Applications**

For a video-display application with a remote display unit, connect the  $\mu$ C to the GMSL serializer and set CDS = low for both the GMSL serializer and the MAX9268. Table 9 summarizes the four startup cases based on the settings of  $\overline{\text{AUTOS}}$  and MS.

#### Case 1: Autostart Mode

After power-up or when PWDN transitions from low to high for both the serializer and deserializer, the serial link establishes whether a stable clock is present. The GMSL serializer locks to the clock and sends the serial data to the MAX9268. The MAX9268 then detects activity on the serial link and locks to the input serial data.

#### Case 2: Standby Start Mode

After power-up or when  $\overline{PWDN}$  transitions from low to high for both the serializer and deserializer, the MAX9268 starts up in sleep mode, and the GMSL serializer stays in standby mode (does not send serial data). Use the  $\mu$ C and program the serializer to set SEREN = 1 to establish a video link or CLINKEN = 1 to establish the configuration link. After locking to a stable clock (for SEREN = 1) or the internal oscillator (for CLINKEN = 1), the serializer sends a wakeup signal to the MAX9268. The MAX9268 exits sleep mode after locking to the serial data and sets SLEEP = 0. If after 8ms the MAX9268 does not lock to the input serial data, the deserializer goes back to sleep and the internal sleep bit remains set (SLEEP = 1).

#### Case 3: Remote Side Autostart Mode

After power-up or when  $\overline{PWDN}$  transitions from low to high, the remote device (MAX9268) starts up and tries to lock to an incoming serial signal with sufficient power. The host side (GMSL serializer) is in standby mode and does not try to establish a link. Use the  $\mu$ C and program the serializer to set SEREN = 1 (and apply a stable clock signal) to establish a video link, or CLINKEN = 1 to establish the configuration link. In this case, the MAX9268 ignores the short wake-up signal sent from the GMSL serializer.

#### Case 4: Remote Side in Sleep Mode

After power-up or when PWDN transitions from low to high, the remote device (MAX9268) starts up in sleep mode. The high-speed link establishes automatically after the GMSL serializer powers up with a stable clock signal and sends a wake-up signal to the MAX9268. Use this mode in applications where the MAX9268 powers up before the GMSL serializer.

### Table 9. Startup Selection for Display Applications (CDS = Low)

CASE	AUTOS (GMSL SERIALIZER)	GMSL SERIALIZER POWER-UP STATE	MS (MAX9268)	MAX9268 POWER-UP STATE	LINK STARTUP MODE
1	Low	Serialization enabled	Low	Normal (SLEEP = 0)	Both devices power up with serial link active (autostart).
2	High	Serialization disabled	High	Sleep mode (SLEEP = 1)	Serial link is disabled and the MAX9268 powers up in sleep mode. Set SEREN = 1 or CLINKEN = 1 in the GMSL serializer to start the serial link and wake up the MAX9268.
3	High	Serialization disabled	Low	Normal (SLEEP = 0)	Both devices power up in normal mode with the serial link disabled. Set SEREN = 1 or CLINKEN = 1 in the GMSL serializer to start the serial link.
4	Low	Serialization enabled	High	In sleep mode (SLEEP = 1)	MAX9268 starts in sleep mode. Link autostarts upon GMSL serializer power-up. Use this case when the MAX9268 powers up before the serializer.

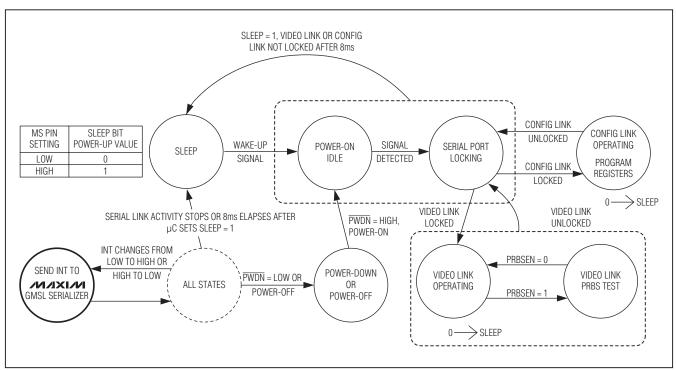


Figure 22. State Diagram, CDS = Low (LCD Application)