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**Benefits and Features** 



### **MAX9272**

### 28-Bit GMSL Deserializer for Coax or STP Cable

#### **General Description**

# ♦ Ideal for Camera Applications

The MAX9272 compact deserializer is designed to interface with a GMSL serializer over  $50\Omega$  coax or  $100\Omega$  shielded twisted-pair (STP) cable. The device pairs with the MAX9271 or MAX9273 serializers.

The parallel output is programmable for single or double output. Double output strobes out half of a parallel word on each pixel clock cycle. Double output can be used with GMSL serializers that have the double-input feature.

The device features an embedded control channel that operates at 9.6kbps to 1Mbps in UART and mixed UART/ I²C modes, and up to 400kbps in I²C mode. Using the control channel, a microcontroller ( $\mu$ C) is capable of programming serializer/deserializer and peripheral device registers at any time, independent of video timing. Two GPIO ports are included, allowing power-up and switching of the backlight in display applications and similar uses. A continuously sampled GPI input supports touch-screen controller interrupt requests.

For use with longer cables, the device has a programmable equalizer. Programmable spread spectrum is available on the parallel output. The serial input meets ISO 10605 and IEC 61000-4-2 ESD standards. The core supply range is 1.7V to 1.9V and the I/O supply range is 1.7V to 3.6V. The device is available in a 48-pin (7mm x 7mm) TQFN-EP package with 0.5mm lead pitch and operates over the -40°C to +105°C temperature range.

### **Applications**

Automotive Camera Systems

Ordering Information appears at end of data sheet.

Typical Application Circuit appears at end of data sheet.

For related parts and recommended products to use with this part, refer to <a href="https://www.maximintegrated.com/MAX9272.related">www.maximintegrated.com/MAX9272.related</a>.

- ♦ Works with Low-Cost 50Ω Coax Cable and FAKRA Connectors or 100Ω STP
- ♦ Error Detection/Correction
- ♦ 9.6kbps to 1Mbps Control Channel in I<sup>2</sup>C-to-I<sup>2</sup>C Mode with Clock Stretch Capability
- ♦ Best-in-Class Supply Current: 90mA (max)
- **♦ Double-Rate Clock for Megapixel Cameras**
- ♦ Cable Equalization Allows 15m Cable at Full Speed
- 48-Pin (7mm x 7mm) TQFN-EP Package with 0.5mm Lead Pitch
- High-Speed Data Deserialization for Megapixel Cameras
  - Up to 1.5Gbps Serial-Bit Rate with Single or Double Output: 6.25MHz to 100MHz Clock
- Multiple Control-Channel Modes for System Flexibility
  - ♦ 9.6kbps to 1Mbps Control Channel in UART-to-UART or UART-to-I<sup>2</sup>C Modes
- **♦** Reduces EMI and Shielding Requirements
  - ♦ Input Programmable for 100mV to 500mV Single-Ended or 50mV to 400mV Differential
  - ♦ Programmable Spread Spectrum on the Parallel Output Reduces EMI
  - ♦ Tracks Spread Spectrum on Serial Input
- Peripheral Features for Camera Power-Up and Verification
  - Built-In PRBS Checker for BER Testing of the Serial Link
  - **♦ Two GPIO Ports**
  - ♦ Dedicated "Up/Down" GPI for Camera Frame Sync Trigger and Other Uses
  - ♦ Remote/Local Wake-Up from Sleep Mode
- ♦ Meets Rigorous Automotive and Industrial Requirements
  - → -40°C to +105°C Operating Temperature

# 28-Bit GMSL Deserializer for Coax or STP Cable

#### **TABLE OF CONTENTS**

General Description	1
Applications	1
Benefits and Features	1
Absolute Maximum Ratings*	6
Package Thermal Characteristics	6
DC Electrical Characteristics	6
AC Electrical Characteristics	8
Typical Operating Characteristics	10
Pin Configuration	12
Pin Description	12
Functional Diagram	14
Detailed Description	18
Register Mapping	18
Bit Map	18
Serial Link Signaling and Data Format	24
Reverse Control Channel	24
Data-Rate Selection	24
Control Channel and Register Programming	25
UART Interface	25
Interfacing Command-Byte-Only I <sup>2</sup> C Devices with UART	26
UART Bypass Mode	26
I <sup>2</sup> C Interface	26
START and STOP Conditions	28
Bit Transfer	28
Acknowledge	28
Slave Address	29
Bus Reset	29
Format for Writing	29
Format for Reading	29
I <sup>2</sup> C Communication with Remote-Side Devices	30
I <sup>2</sup> C Address Translation	30
Control-Channel Broadcast Mode	30
GPO/GPI Control	30
DDDC T4	0.4

# 28-Bit GMSL Deserializer for Coax or STP Cable

TABLE OF CONTENTS (continued)	
Line Equalizer	
Spread Spectrum	
Manual Programming of the Spread-Spectrum Divider	
Additional Error Detection and Correction	
Cyclic Redundancy Check (CRC)	
Hamming Code	
HV/VS Encoding and/or Tracking	
Serial Input	
Coax-Mode Splitter	
Cable Type Configuration Input (CX/TP)	
Sleep Mode	
Power-Down Mode	
Configuration Link	
Link Startup Procedure	34
Applications Information	36
Error Checking	
ERR Output	
Autoerror Reset	
Dual μC Control	
Changing the Clock Frequency	
Fast Detection of Loss-of-Synchronization	
Providing a Frame Sync (Camera Applications)	
Software Programming of the Device Addresses	
Three-Level Configuration Inputs	
Configuration Blocking	
Compatibility with other GMSL Devices	
GPIOs	
Staggered Parallel Outputs	
Local Control-Channel Enable (LCCEN)	
Internal Input Pulldowns	
Choosing I <sup>2</sup> C/UART Pullup Resistors	
AC-Coupling	
Selection of AC-Coupling Capacitors	
Power-Supply Circuits and Bypassing	

# 28-Bit GMSL Deserializer for Coax or STP Cable

TABLE OF CONTENTS (continued)	
Power-Supply Table	39
Cables and Connectors	39
Board Layout	39
ESD Protection	39
Typical Application Circuit	46
Ordering Information	46
Chip Information	46
Package Information	46
Revision History	47
LIST OF FIGURES	
Figure 1. Reverse Control-Channel Output Parameters	15
Figure 2. Test Circuit for Differential Input Measurement	16
Figure 4. Parallel Clock Output High and Low Times	16
Figure 5. I <sup>2</sup> C Timing Parameters	16
Figure 3. Worst-Case Pattern Output	16
Figure 6. Output Rise-and-Fall Times	17
Figure 7. Deserializer Delay	17
Figure 8. GPI-to-GPO Delay	17
Figure 9. Lock Time	18
Figure 10. Power-Up Delay	18
Figure 11. Single-Output Waveform (Serializer Using Single Input)	20
Figure 12. Single-Output Waveform (Serializer Using Double Input)	20
Figure 13. Double-Output Waveform (Serializer Using Single Input)	21
Figure 14. Double-Output Waveform (Serializer Using Double Input)	21
Figure 15. Serial-Data Format	24
Figure 16. GMSL UART Protocol for Base Mode	25
Figure 17. GMSL UART Data Format for Base Mode	26
Figure 18. SYNC Byte (0x79)	26
Figure 19. ACK Byte (0xC3)	26
Figure 20. Format Conversion Between GMSL UART and I $^2$ C with Register Address (I2CMETHOD = 0)	27
Figure 21. Format Conversion Between GMSL UART and I <sup>2</sup> C with Register Address (I2CMETHOD = 1)	27

# 28-Bit GMSL Deserializer for Coax or STP Cable

LIST OF FIGURES (continued)
Figure 22. START and STOP Conditions
Figure 23. Bit Transfer
Figure 24. Acknowledge
Figure 25. Slave Address
Figure 26. Format for I <sup>2</sup> C Write
Figure 27. Format for Write to Multiple Registers
Figure 28. Format for I <sup>2</sup> C Read
Figure 29. 2:1 Coax-Mode Splitter Connection Diagram
Figure 30. Coax-Mode Connection Diagram
Figure 31. State Diagram, Remote Microcontroller Application
Figure 32. Human Body Model ESD Test Circuit
Figure 33. IEC 61000-4-2 Contact Discharge ESD Test Circuit
Figure 34. ISO 10605 Contact Discharge ESD Test Circuit
LIST OF TABLES
Table 1. Power-Up Default Register Map (see <u>Table 16</u> )
Table 2. Output Map
Table 3. Data-Rate Selection Table
Table 4. I <sup>2</sup> C Bit-Rate Ranges
Table 5. MAX9262 Cable Equalizer Boost Levels
Table 6. Parallel Output Spread
Table 7. Modulation Coefficients and Maximum SDIV Settings
Table 8. Configuration Input Map
Table 9. Startup Procedure for Video-Display Applications
Table 10. Startup Procedure for Image-Sensing Applications
Table 11. MAX9272 Feature Compatibility
Table 12. Staggered Output Delay
Table 13. Double-Function Configuration.    38
Table 14. Typical Power-Supply Currents (Using Worst-Case Input Pattern)
Table 15. Suggested Connectors and Cables for GMSL
Table 16. Register Table (see <u>Table 1</u> )

#### **ABSOLUTE MAXIMUM RATINGS\***

AVDD to EP0.5V to +1.9V	Junction Temperature+150°C
DVDD to EP0.5V to +1.9V	Operating Temperature Range40°C to +105°C
IOVDD to EP0.5V to +3.9V	Storage Temperature Range65°C to +150°C
IN+, IN- to EP0.5V to +1.9V	Lead Temperature (soldering, 10s)+300°C
All other pins to EP0.5V to (VIOVDD + 0.5V)	Soldering Temperature (reflow)+260°C
IN+, IN- short circuit to ground or supplyContinuous	
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	
TQFN (derate 40mW/°C above +70°C)3200mW	*EP is connected to PCB ground.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **PACKAGE THERMAL CHARACTERISTICS (Note 1)**

TQFN

 $\label{eq:continuous} \mbox{Junction-to-Ambient Thermal Resistance } (\theta_{\mbox{\scriptsize JA}})......1°\mbox{C/W} \qquad \mbox{Junction-to-Case Thermal Resistance } (\theta_{\mbox{\scriptsize JC}})......1°\mbox{C/W}$ 

**Note 1:** Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to <a href="https://www.maximintegrated.com/thermal-tutorial">www.maximintegrated.com/thermal-tutorial</a>.

#### DC ELECTRICAL CHARACTERISTICS

 $(V_{AVDD} = V_{DVDD} = 1.7V \text{ to } 1.9V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\% \text{ (differential)}, EP connected to PCB ground, T_A = -40°C to +105°C, unless otherwise noted. Typical values are at <math>V_{AVDD} = V_{DVDD} = V_{IOVDD} = 1.8V, T_A = +25°C.)$ 

PARAMETER	SYMBOL	СО	NDITIONS	MIN TY	P MAX	UNITS
SINGLE-ENDED INPUTS (I2C	SEL, LCCEN,	GPI, PWDN, MS/HVI	EN)			
High-Level Input Voltage	V <sub>IH1</sub>			0.65 x V <sub>IOVDD</sub>		V
Low-Level Input Voltage	V <sub>IL1</sub>				0.35 x V <sub>IOVDD</sub>	V
Input Current	I <sub>IN1</sub>	$V_{IN} = 0V \text{ to } V_{IOVDE}$	)	-10	+20	μΑ
THREE-LEVEL LOGIC INPUTS	S (CX/TP)					
High-Level Input Voltage	V <sub>IH</sub>			0.7 x V <sub>IOVDD</sub>		V
Low-Level Input Voltage	V <sub>IL</sub>				0.3 x V <sub>IOVDD</sub>	V
Mid-Level Input Current	I <sub>INM</sub>	(Note 2)		-10	+10	μΑ
Input Current	I <sub>IN</sub>			-150	+150	μΑ
SINGLE-ENDED OUTPUTS (D	OUT_, PCLKO	OUT)				
Llight Lovel Output Voltage		) - Oma A	DCS = 0	V <sub>IOVDD</sub> - 0.3		V
High-Level Output Voltage V <sub>OH1</sub>	$I_{OUT} = -2mA$	DCS = 1	V <sub>IOVDD</sub> - 0.2		V	
Low Lovel Output Voltage	Vou	)/           D	DCS = 0		0.3	V
Low-Level Output Voltage V <sub>OL1</sub> I <sub>OUT</sub> = 2mA		1001 = 21114	DCS = 1		0.2	\ \ \

### **DC ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{AVDD} = V_{DVDD} = 1.7V \text{ to } 1.9V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\% \text{ (differential)}, EP connected to PCB ground, T_A = -40°C to +105°C, unless otherwise noted. Typical values are at <math>V_{AVDD} = V_{DVDD} = V_{IOVDD} = 1.8V, T_A = +25°C.)$ 

PARAMETER	SYMBOL		CON	DITIONS	MIN	TYP	MAX	UNITS	
			$V_O = 0V$ ,	$V_{IOVDD} = 3.0V \text{ to } 3.6V$	15	25	39		
		DOLLT	DCS = 0	$V_{IOVDD} = 1.7V \text{ to } 1.9V$	3	7	13		
		DOUT_	$V_O = 0V$ ,	$V_{IOVDD} = 3.0V \text{ to } 3.6V$	20	35	63		
Output Chart Circuit Current	,		DCS = 1		5	10	21		
Output Short-Circuit Current	los		$V_O = 0V$ ,	$V_{IOVDD} = 3.0V \text{ to } 3.6V$	15	33	50	mA	
		PCLKOUT	DCS = 0	$V_{IOVDD} = 1.7V \text{ to } 1.9V$	5	10	17		
		FULKUUT	$V_{O} = 0V$		30	54	97		
			DCS = 1	$V_{IOVDD} = 1.7V \text{ to } 1.9V$	9	16	32		
OPEN-DRAIN INPUTS/OUTPUTS	(GPIO0/DE	BL, GPIO1/E	BWS, RX/S	DA/EDC, TX/SCL/ES, ER	R, LOCK)				
High-Level Input Voltage	V <sub>IH2</sub>				0.7 x V <sub>IOVDD</sub>			V	
Low-Level Input Voltage	V <sub>IL2</sub>						0.3 x V <sub>IOVDD</sub>	V	
	I <sub>IN2</sub> (	(Note 3)		RX/SDA, TX/SCL	-110		+1		
Input Current				LOCK, ERR, GPIO_	-80		+1	μΑ	
				DBL, BWS, EDC, ES	-10		+20		
Low-Level Output Voltage	V	V <sub>OL2</sub> I <sub>OUT</sub> = 3mA		$V_{IOVDD} = 1.7V \text{ to } 1.9V$			0.4	V	
Low-Level Output voltage	VOL2			$V_{IOVDD} = 3.0V \text{ to } 3.6V$			0.3		
OUTPUT FOR REVERSE CONTR	OL CHAN	NEL (IN+, IN	l <b>-</b> )						
Differential High Output Peak Voltage, (V <sub>IN</sub> +) - (V <sub>IN</sub> -)	V <sub>ROH</sub>	No high-sp	No high-speed data transmission (Figure 1)				60	mV	
Differential Low Output Peak Voltage, (V <sub>IN</sub> +) - (V <sub>IN</sub> -)	V <sub>ROL</sub>	No high-sp	eed data	transmission (Figure 1)	-60		-30	mV	
DIFFERENTIAL INPUTS (IN+, IN-	-)								
Differential High Input Threshold		(Figure 0)		detector, medium ld (0x22 D[6:5] = 01)			60	>/	
(Peak) Voltage, (V <sub>IN</sub> +) - (V <sub>IN</sub> -)	V <sub>IDH(P)</sub>	(Figure 2)	Figure 2) Activity detector, low threshold (0x22 D[6:5] = 00)				45	- mV	
Differential Low Input Threshold				detector, medium ld (0x22 D[6:5] = 01)	-60				
(Peak) Voltage, (V <sub>IN</sub> +) - (V <sub>IN</sub> -)	V <sub>IDL(P)</sub> (F	(Figure 2)		detector, medium ld (0x22 D[6:5] = 00)	-45			mV	
Input Common-Mode Voltage ((V <sub>IN</sub> +) + (V <sub>IN</sub> -))/2	V <sub>CMR</sub>				1	1.3	1.6	V	
Differential Input Resistance (Internal)	R <sub>I</sub>				80	105	130	Ω	

#### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = 1.7V \text{ to } 1.9V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\% \text{ (differential)}, EP connected to PCB ground, T_A = -40°C to +105°C, unless otherwise noted. Typical values are at <math>V_{AVDD} = V_{DVDD} = V_{IOVDD} = 1.8V, T_A = +25°C.)$ 

PARAMETER	SYMBOL	CONE	DITIONS	MIN	TYP	MAX	UNITS
SINGLE-ENDED INPUTS (IN+,	IN-)						
Single-Ended High Input	V	Activity detector, med (0x22 D[6:5] = 01)			43	m\/	
Threshold (Peak) Voltage, (V <sub>IN</sub> +) - (V <sub>IN</sub> -)	V <sub>IDH(P)</sub>	Activity detector, low to (0x22 D[6:5] = 00)	threshold			33	33 mV
Single-Ended Low Input	\ \/	Activity detector, med (0x22 D[6:5] = 01)	ium threshold	-43			, no.\/
Threshold (Peak) Voltage, (V <sub>IN</sub> +) - (V <sub>IN</sub> -)	V <sub>IDL(P)</sub>	Activity detector, med (0x22 D[6:5] = 00)	ium threshold	-33			mV
Input Resistance (Internal)	R <sub>I</sub>			40	52.5	65	Ω
POWER SUPPLY							
Worst-Case Supply Current (Figure 3)		BWS = 0, single outpu	ut, f <sub>PCLKOUT</sub> = 25MHz		42	65	
		EQ off	f <sub>PCLKOUT</sub> = 50MHz		61	90	mA
	lwcs	BWS = 0, double outp	out, fPCLKOUT = 50MHz		42	70	
		EQ off $f_{PCLKOUT} = 100MHz$		-	62	90	]
Sleep Mode Supply Current	Iccs				40	100	μA
Power-Down Current	I <sub>CCZ</sub>	PWDN = EP			5	70	μA
ESD PROTECTION							
		Human Body Model, $R_D = 1.5k\Omega$ , $C_S = 100pF$			±8		
			Contact discharge		±10		
IN+, IN- (Note 4)	V <sub>ESD</sub>	$R_D = 330\Omega$ , $C_S = 150pF$	Air discharge		±15		kV
		ISO 10605, $R_D = 2k\Omega$ ,	Contact discharge		±10		
		$C_{S} = 330pF$	Air discharge		±30		
All Other Pins (Note 5)	V <sub>ESD</sub>	Human Body Model, F	Human Body Model, $R_D = 1.5k\Omega$ , $C_S = 100pF$				kV

#### **AC ELECTRICAL CHARACTERISTICS**

 $(V_{AVDD} = V_{DVDD} = 1.7V \text{ to } 1.9V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\% \text{ (differential)}, EP connected to PCB ground, T_A = -40°C to +105°C, unless otherwise noted. Typical values are at <math>V_{AVDD} = V_{DVDD} = V_{IOVDD} = 1.8V, T_A = +25°C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS			
PARALLEL CLOCK OUTPUT (PCLKOUT)									
		BWS = 0, DRS = 1	8.33		16.66				
		BWS = 0, DRS = 0	16.66		50				
Clock Frequency	f	BWS = 1, DRS = 1	6.25		12.5 MHz				
	†PCLKOUT	BWS = 1, DRS = 0	12.5		37.5	IVITZ			
		BWS = 1, DRS = 0, 15-bit double input	25		75	]			
		BWS = 0, DRS = 0, 11-bit double input	33.33		100				
Clock Duty Cycle	DC	t <sub>HIGH</sub> /t <sub>T</sub> or t <sub>LOW</sub> /t <sub>T</sub> (Figure 4, Note 6)	40	50	60	%			
Clock Jitter	tu	Period jitter, RMS, spread off, 1.5Gbps, PRBS pattern, UI = 1/f <sub>PCLKOUT</sub> (Note 6)		0.05		UI			

#### AC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = 1.7V \text{ to } 1.9V, V_{IOVDD} = 1.7V \text{ to } 3.6V, R_L = 100\Omega \pm 1\% \text{ (differential)}, EP connected to PCB ground, T_A = -40°C to +105°C, unless otherwise noted. Typical values are at <math>V_{AVDD} = V_{DVDD} = V_{IOVDD} = 1.8V, T_A = +25°C.)$ 

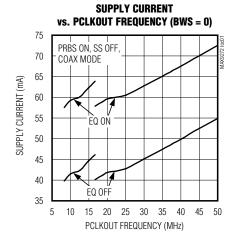
PARAMETER	SYMBOL		COI	NDITIONS	MIN	TYP	MAX	UNITS
I <sup>2</sup> C/UART PORT TIMING	•	•						
I <sup>2</sup> C/UART Bit Rate					9.6		1000	kbps
Output Rise Time	t <sub>R</sub>	30% to 70% 1kΩ pullup t		10pF to 100pF,	20		120	ns
Output Fall Time	t <sub>F</sub>	70% to 30% 1k <b>Ω</b> pullup t	_	10pF to 100pF,	20		120	ns
Input Setup Time	t <sub>SET</sub>	I <sup>2</sup> C only (Fig	jure 5, 1	Note 6)	100			ns
Input Hold Time	tHOLD	I <sup>2</sup> C only (Fig	jure 5, 1	Note 6)	0			ns
SWITCHING CHARACTERISTIC	S							
	t <sub>R</sub> , t <sub>F</sub>	20% to 80%		DCS = 1, C <sub>L</sub> = 10pf	0.4		2.2	
PCLKOUT Rise-and-Fall Time		V <sub>IOVDD</sub> = 1. 1.9V (Note 6		DCS = 0, C <sub>L</sub> = 5pF	0.5		2.8	
		20% to 80%, V <sub>IOVDD</sub> = 3.0V to 3.6V (Note 6)		DCS = 1, C <sub>L</sub> = 10pF	0.25		1.7	ns -
				DCS = 0, C <sub>L</sub> = 5pF	0.3		2.0	
Parallel Data Rise-and-Fall Time	t <sub>R</sub> , t <sub>F</sub>	20% to 80%, V <sub>IOVDD</sub> = 1.7V to 1.9V (Note 6)		DCS = 1, C <sub>L</sub> = 10pf	0.5		3.1	- ns
				DCS = 0, C <sub>L</sub> = 5pF	0.6		3.8	
(Figure 6)		20% to 80%,		DCS = 1, C <sub>L</sub> = 10pF	0.3		2.2	
		V <sub>IOVDD</sub> = 3. 3.6V (Note 6		DCS = 0, C <sub>L</sub> = 5pF	0.4		2.4	
		(Figure 7,		Spread spectrum enabled			6960	- Bits
Deserializer Delay	t <sub>SD</sub> N	Notes 6, 7)		Spread spectrum disabled			2160	DIIS
Reverse Control-Channel Output Rise Time	t <sub>R</sub>	No forward-channel data transmission (Figure 1, Note 6)		I data transmission	180		400	ns
Reverse Control-Channel Output Fall Time	t <sub>F</sub>	No forward-channel data transmission (Figure 1, Note 6)		180		400	ns	
GPI-to-GPO Delay	t <sub>GPIO</sub>	Deserializer GPI to serializer GPO (cable delay not included) (Figure 8)				350	μs	
Lock Thomas		(Figure 9,	Spread	d spectrum enabled			1.5	
Lock Time	t <sub>LOCK</sub>	Note 6)	Spread	d spectrum disabled			1	ms
Power-Up Time	t <sub>PU</sub>	(Figure 10)				6	ms	

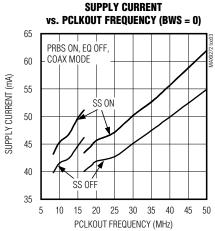
- Note 2: To provide a midlevel, leave the input open, or, if driven, put driver in high impedance. High-impedance leakage current must be less than ±10µA.
- **Note 3:**  $I_{IN}$  min due to voltage drop across the internal pullup resistor.
- Note 4: Specified pin to ground.
- Note 5: Specified pin to all supply/ground.
- Note 6: Guaranteed by design and not production tested.
- Note 7: Measured in serial link bit times. Bit time = 1/(30 x f<sub>PCI KOLIT</sub>) for BWS = GND. Bit time = 1/(40 x f<sub>PCI KOLIT</sub>) for BWS = 1.

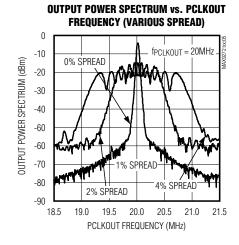
# 28-Bit GMSL Deserializer for Coax or STP Cable

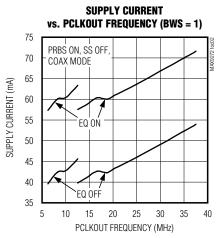
### **Typical Operating Characteristics**

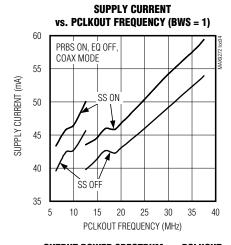
 $(V_{AVDD} = V_{DVDD} = V_{IOVDD} = 1.8V, DBL = low, T_A = +25$ °C, unless otherwise noted.)

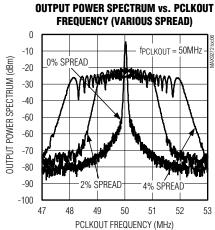










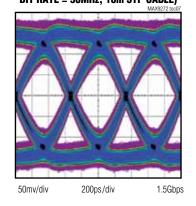


## 28-Bit GMSL Deserializer for Coax or STP Cable

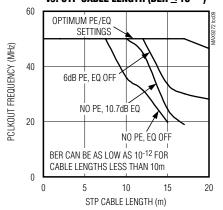
#### **Typical Operating Characteristics (continued)**

 $(V_{AVDD} = V_{DVDD} = V_{IOVDD} = 1.8V$ , DBL = low,  $T_A = +25$ °C, unless otherwise noted.)

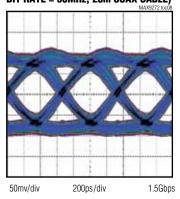
#### SERIAL LINK SWITCHING PATTERN WITH 6dB PREEMPHASIS (PARALELL BIT RATE = 50MHz, 10m STP CABLE)



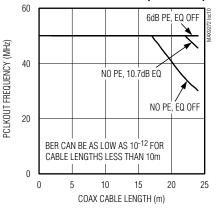
# MAXIMUM PCLKOUT FREQUENCY vs. STP CABLE LENGTH (BER $\leq 10^{-10}$ )



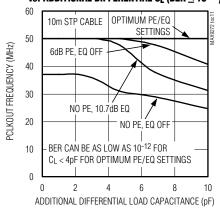
#### SERIAL LINK SWITCHING PATTERN WITH 6dB PREEMPHASIS (PARALELL BIT RATE = 50MHz, 20m COAX CABLE)



# MAXIMUM PCLKOUT FREQUENCY vs. COAX CABLE LENGTH (BER $\leq 10^{-10}$ )

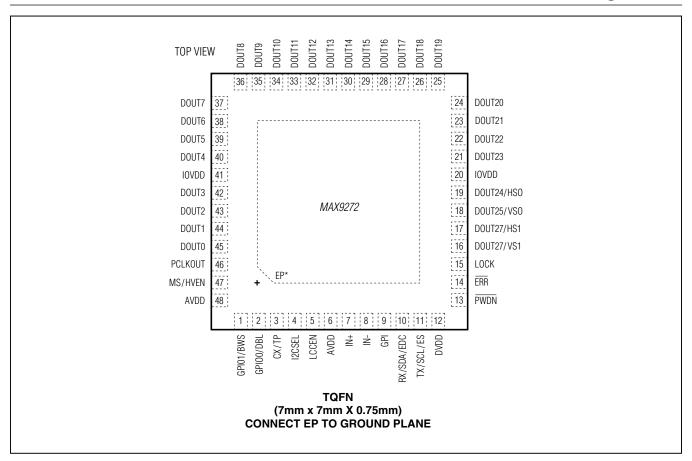


# MAXIMUM PCLKOUT FREQUENCY vs. Additional differential $c_L$ (Ber $\leq$ 10- $^{10}$ )



## 28-Bit GMSL Deserializer for Coax or STP Cable

### **Pin Configuration**



### **Pin Description**

PIN	NAME	FUNCTION
1	GPIO1/BWS	GPIO/Bus Width Select Input. Function is determined by the state of LCCEN (Table 13). GPIO1 (LCCEN = high): Open-drain, general-purpose input/output with internal $60k\Omega$ pullup to IOVDD. BWS (LCCEN = low): Input with internal pulldown to EP. Set BWS = low for 22-bit input latch. Set BWS = high for 30-bit input latch.
2	GPIO0/DBL	GPIO/Double-Mode Input. Function is determined by the state of LCCEN (Table 13). GPIO0 (LCCEN = high): Open-drain, general-purpose input/output with internal $60k\Omega$ pullup to IOVDD. DBL (LCCEN = low): Input with internal pulldown to EP. Set DBL = high to use double-input mode. Set DBL = low to use single-input mode.
3	CX/TP	Coax/Twisted-Pair Three-Level Configuration Input (Table 8)
4	I2CSEL	I <sup>2</sup> C Select. Control-channel interface protocol select input with internal pulldown to EP. Set I <sup>2</sup> CSEL = high to select I <sup>2</sup> C slave interface. Set I <sup>2</sup> CSEL = low to select UART interface.

# 28-Bit GMSL Deserializer for Coax or STP Cable

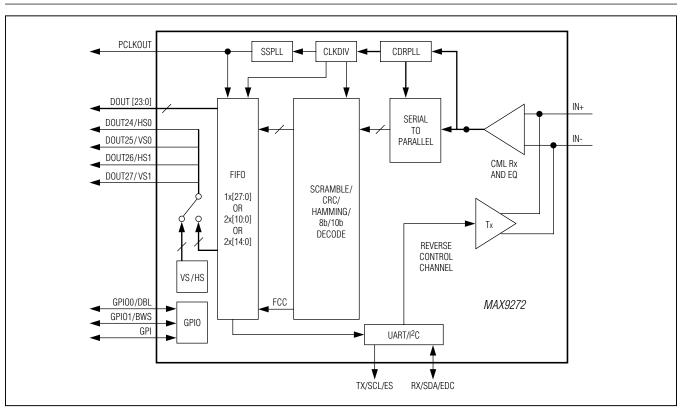
## Pin Description (continued)

PIN	NAME	FUNCTION
5	LCCEN	Local Control-Channel Enable Input with Internal Pulldown to EP. LCCEN = high enables the control-channel interface pins. LCCEN = low disables the control-channel interface pins and selects an alternate function on the indicated pins (Table 13).
6, 48	AVDD	1.8V Analog Power Supply. Bypass AVDD to EP with 0.1µF and 0.001µF capacitors as close as possible to the device with the smaller capacitor closest to AVDD.
7	IN+	Noninverting Coax/Twisted-Pair Serial Input
8	IN-	Inverting Coax/Twisted-Pair Serial Input
9	GPI	General-Purpose Input. The GMSL deserializer GPI (or INT) input follows GPI.
10	RX/SDA/EDC	Receive/Serial Data/Error Detection Correction. Function is determined by the state of LCCEN (Table 13). RX/SDA (LCCEN = high): Input/output with internal $30k\Omega$ pullup to IOVDD. In UART mode, RX/SDA is the Rx input of the MAX9272's UART. In the I²C mode, RX/SDA is the SDA input/output of the MAX9272's I²C master/slave. RX/SDA has an open-drain driver and requires a pullup resistor. EDC (LCCEN = low): Input with internal pulldown to EP. Set EDC = high to enable error detection correction. Set EDC = low to disable error detection correction.
11	TX/SCL/ES	Transmit/Serial Clock/Edge Select. Function is determined by the state of LCCEN (Table 13). TX/SCL (LCCEN = high). Input/output with internal 30kΩ pullup to IOVDD. In UART mode, TX/SCL is the Tx output of the MAX9272's UART. In the I²C mode, TX/SCL is the SCL input/output of the MAX9272's I²C master/slave. TX/SCL has an open-drain driver and requires a pullup resistor. ES (LCCEN = low): Input with internal pulldown to EP. When ES is high, PCLKOUT indicates valid data on the falling edge of PCLKOUT. When ES is low, PCLKOUT indicates valid data on the rising edge of PCLKOUT. Do not change the ES input while the pixel clock is running.
12	DVDD	1.8V Digital Power Supply. Bypass DVDD to EP with 0.1µF and 0.001µF capacitors as close as possible to the device with the smaller value capacitor closest to DVDD.
13	PWDN	Active-Low Power-Down Input with Internal Pulldown to EP. Set PWDN low to enter power-down mode to reduce power consumption.
14	ERR	Error Output. Open-drain data error detection and/or correction indication output with internal $60k\Omega$ pullup to IOVDD. $\overline{\text{ERR}}$ is an open-drain driver and requires a pullup resistor.
15	LOCK	Open-Drain Lock Output with Internal $60k\Omega$ Pullup to IOVDD. LOCK = high indicates that PLLs are locked with correct serial-word-boundary alignment. LOCK = low indicates that PLLs are not locked or an incorrect serial-word-boundary alignment. LOCK remains low when the configuration link is active or during PRBS test. LOCK is high impedance when $\overline{PWDN}$ = low. LOCK is an open-drain driver and requires a pullup resistor.
16	DOUT27/VS1	Parallel Data/Vertical Sync 1 Output. Defaults to parallel data input on power-up. Parallel data output when VS/HS encoding is disabled. Decoded vertical sync for upper half of single output when VS/HS encoding is enabled (Table 2).
17	DOUT26/HS1	Parallel Data/Horizontal Sync 1 Output. Defaults to parallel data input on power-up. Parallel data output when VS/HS encoding is disabled. Decoded horizontal sync for upper half of single-output when VS/HS encoding is enabled (Table 2).
18	DOUT25/VS0	Parallel Data/Vertical Sync 0 Output. Defaults to parallel data input on power-up. Parallel data output when VS/HS encoding is disabled. Decoded vertical sync for lower half of single-output when VS/HS encoding is enabled (Table 2).

### **Pin Description (continued)**

PIN	NAME	FUNCTION			
19	DOUT24/HS0	Parallel Data/Horizontal Sync 0 Output. Defaults to parallel data input on power-up. Parallel data output when VS/HS encoding is disabled. Decoded horizontal sync for lower half of single-output when VS/HS encoding is enabled (Table 2).			
20, 41	IOVDD	I/O Supply Voltage. 1.8V to 3.3V logic I/O power supply. Bypass IOVDD to EP with 0.1µF and 0.001µF capacitors as close as possible to the device with the smallest value capacitor closest to IOVDD.			
21–40, 42–45	DOUT23- DOUT0	Parallel Data Outputs			
46	PCLKOUT	Parallel Clock Output. Latches parallel data into the input of another device.			
47	MS/HVEN	Mode Select/HS and VS Encoding Enable with Internal Pulldown to EP. Function is determined by the state of LCCEN (Table 13).  MS (LCCEN = high). Set MS = low to select base mode. Set MS = high to select the bypass mode. HVEN (LCCEN = low): Set HVEN = high to enable HS/VS encoding on DOUT_/HS_ and DOUT_/VS Set HVEN = low to use DOUT_/HS_ and DOUT_/VS_ as parallel data outputs.			
_	EP	Exposed Pad. EP is internally connected to device ground. <b>MUST</b> connect EP to the PCB ground plane through an array of vias for proper thermal and electrical performance.			

### **Functional Diagram**



# 28-Bit GMSL Deserializer for Coax or STP Cable

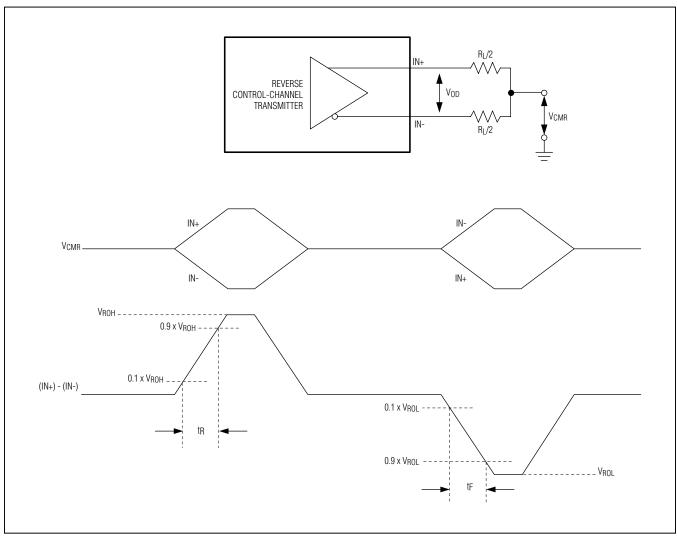
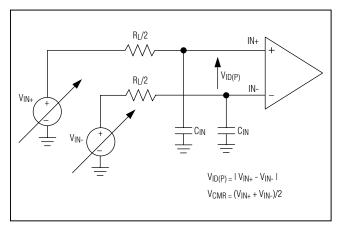


Figure 1. Reverse Control-Channel Output Parameters



PCLKOUT

DOUT\_

NOTE: PCLKOUT PROGRAMMED FOR RISING LATCH EDGE.

Figure 2. Test Circuit for Differential Input Measurement

Figure 3. Worst-Case Pattern Output

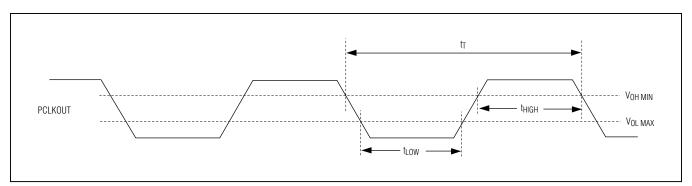


Figure 4. Parallel Clock Output High and Low Times

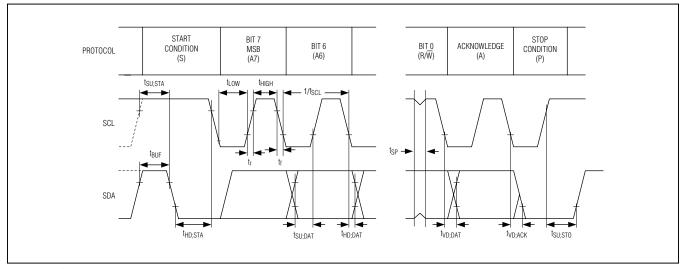


Figure 5. I2C Timing Parameters

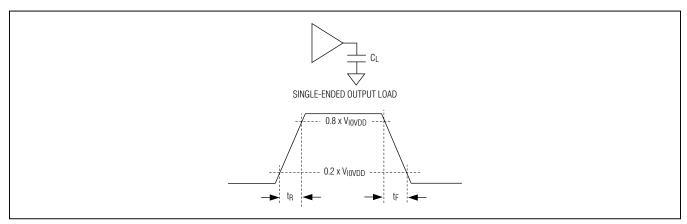


Figure 6. Output Rise-and-Fall Times

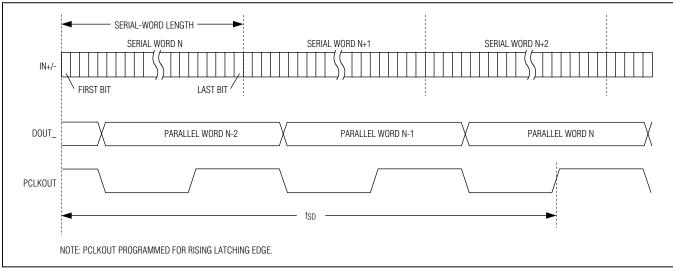


Figure 7. Deserializer Delay

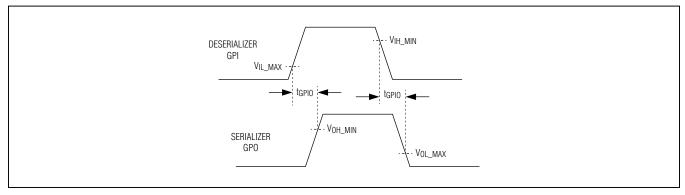


Figure 8. GPI-to-GPO Delay

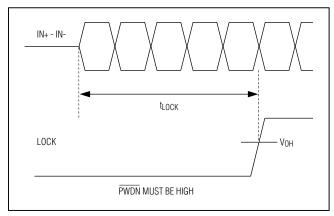


Figure 9. Lock Time

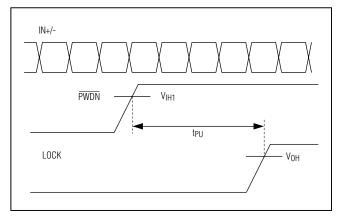


Figure 10. Power-Up Delay

#### **Detailed Description**

The MAX9272 deserializer, when paired with the MAX9271 or MAX9273 serializer, provides the full set of operating features, but offers basic functionality when paired with any GMSL serializer.

The deserializer has a maximum serial-bit rate of 1.5Gbps for 15m or more of cable and operates up to a maximum output clock of 50MHz in 28-bit, single-output mode, or 75MHz to 100MHz in 15-bit/11-bit, double-output mode, respectively. This bit rate and output flexibility support a wide range of displays, from QVGA (320 x 240) to WVGA (800 x 480) and higher with 18-bit color, as well as megapixel image sensors. Input equalization, combined with GMSL serializer pre/deemphasis, extends the cable length and enhances link reliability

The control channel enables a  $\mu C$  to program the serializer and deserializer registers and program registers on peripherals. The control channel is also used to configure and access the GPIO. The  $\mu C$  can be located at either end of the link, or when using two  $\mu Cs$ , at both ends. Two modes of control-channel operation are available. Base mode uses either I<sup>2</sup>C or GMSL UART protocol, while bypass mode uses a user-defined UART protocol. UART protocol allows full-duplex communication, while I<sup>2</sup>C allows half-duplex communication.

Spread spectrum is available to reduce EMI on the parallel output. The serial input complies with ISO 10605 and IEC 61000-4-2 ESD protection standards.

#### Register Mapping

Registers set the operating conditions of the deserializer and are programmed using the control channel in base mode. The deserializer holds its device address and the device address of the serializer it is paired with. Similarly, the serializer holds its device address and the address of the deserializer. Whenever a device address is changed, the new address should be written to both devices. The default device address of the deserializer is set by the CX/TP input and the default device address of any GMSL serializer is 0x80 (see <u>Table 1</u> and <u>Table 8</u>). Registers 0x00 and 0x01 in both devices hold the device addresses.

#### Bit Map

The parallel output functioning and width depend on settings of the double-/single-output mode (DBL), HS/VS encoding (HVEN), error correction used (EDC), and bus width (BWS) pins. Table 2 lists the bit map for the control pin settings. Unused output bits are pulled low.

The parallel output has two output modes: single and double output. In single-output mode, the deserialized parallel data is clocked out every PCLKOUT cycle. The device accepts pixel clocks from 6.25MHz to 50MHz (Figures 11 and 12).

In double-output mode, the device splits deserialized data into two half-sized words that are output at twice the serial-word rate (Figures 13 and 14). The serializer/deserializer use pixel clock rates from  $33.3 \mathrm{MHz}$  to  $100 \mathrm{MHz}$  for 11-bit, double-output mode and  $25 \mathrm{MHz}$  to  $75 \mathrm{MHz}$  for 15-bit, double-output mode.

### 28-Bit GMSL Deserializer for Coax or STP Cable

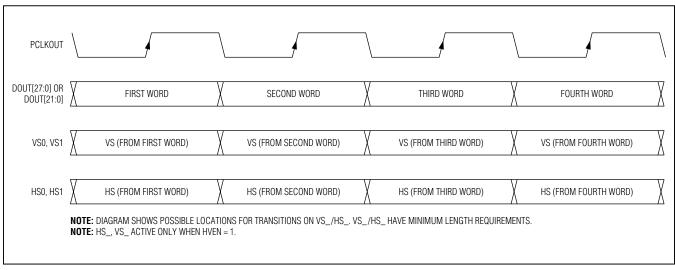


Figure 11. Single-Output Waveform (Serializer Using Single Input)

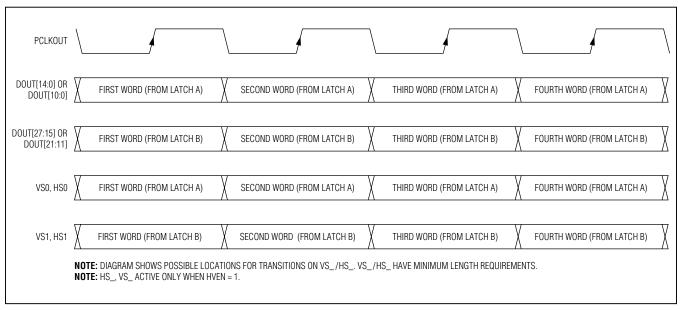


Figure 12. Single-Output Waveform (Serializer Using Double Input)

# 28-Bit GMSL Deserializer for Coax or STP Cable

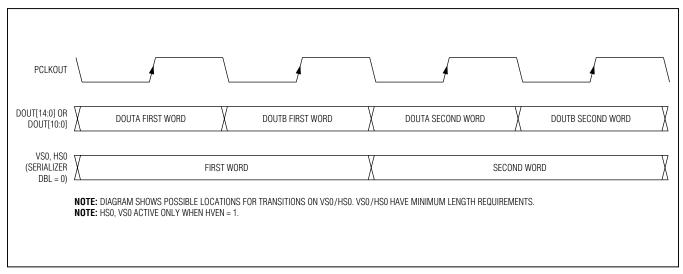


Figure 13. Double-Output Waveform (Serializer Using Single Input)

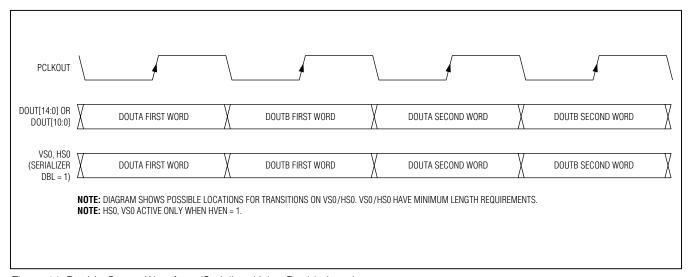


Figure 14. Double-Output Waveform (Serializer Using Double Input)

Table 1. Power-Up Default Register Map (see Table 16)

REGISTER ADDRESS (hex)	POWER-UP DEFAULT (hex)	POWER-UP DEFAULT SETTINGS (MSB FIRST)		
0x00	0x80	SERID = 1000000, serializer device address RESERVED = 0		
0x01	0x90 or 0x92	DESID = 1001000 (CX/TP = high or low), DESID = 1001001 (CX/TP = midlevel), deserializer device address is determined by the state of the CX/TP input at power-up CFGBLOCK = 0, registers 0x00 to 0x1F are read/write		
0x02	0x1F	SS = 00, spread spectrum disabled RESERVED = 01 PRNG = 11, automatically detect the pixel clock range SRNG = 11, automatically detect serial-data rate		
0x03	0x00	AUTOFM = 00, calibrate spread-modulation rate only once after locking RESERVED = 0 SDIV = 00000, autocalibrate sawtooth divider		
0x04	0x07	LOCKED = 0, LOCK output is low (read only)  OUTENB = 0, output enabled  PRBSEN = 0, PRBS test disabled  SLEEP = 0, sleep mode deactivated (see the <i>Link Startup Procedure</i> section)  INTTYPE = 01, base mode uses UART  REVCCEN = 1, reverse control channel active (sending)  FWDCCEN = 1, forward control channel active (receiving)		
0x05	0x24	I2CMETHOD = 0, I <sup>2</sup> C master sends the register address DCS = 0, normal parallel output driver current HVTRMODE = 1, full periodic HS/VS tracking ENEQ = 0, equalizer disabled EQTUNE = 1001, 10.7dB equalization		
0x06	0x02 or 0x22	RESERVED = 00X00010		
0x07	0xXX	DBL = 0 or 1, single-/double-input mode setting determined by the state of LCCEN and GPIO0/DBL at startup DRS = 0, high data-rate mode BWS = 0 or 1, bit width setting determined by the state of LCCEN and GPIO1/BWS at startup ES = 0 or 1, edge-select input setting determined by the state of LCCEN and TX/SCL/ES at start: HVTRACK = 0 or 1, HS/VS tracking setting determined by the state of LCCEN and MS/HVEN at startup HVEN = 0 or 1, HS/VS tracking encoding setting determined by the state of LCCEN and MS/HVE at startup EDC = 00 or 10, error-detection/correction setting determined by the state of LCCEN and RX/SDA/EDC at startup		

Table 1. Power-Up Default Register Map (see <u>Table 16</u>) (continued)

REGISTER ADDRESS (hex)	POWER-UP DEFAULT (hex)	POWER-UP DEFAULT SETTINGS (MSB FIRST)			
0x08	0x00	INVVS = 0, deserializer does not invert VSYNC INVHS = 0, deserializer does not invert HSYNC RESERVED = 0 UNEQDBL = 0, serializer DBL is not the same as deserializer DISSTAG = 0, outputs are staggered AUTORST = 0, error registers/output autoreset disabled ERRSEL = 00, detected errors trigger ERR			
0x09	0x00	I2CSCRA = 0000000, I2C address translator source A is 0x00 RESERVED = 0			
0x0A	0x00	I2CDSTA = 0000000, I <sup>2</sup> C address translator destination A is 0x00 RESERVED = 0			
0x0B	0x00	I2CSCRB = 0000000, I2C address translator source B is 0x00 RESERVED = 0			
0x0C	0x00	I2CDSTB = 0000000, I <sup>2</sup> C address translator destination B is 0x00 RESERVED = 0			
0x0D	0x36	I2CLOCACK = 0, acknowledge not generated when forward channel is not available I2CSLVSH = 01, 469ns/234ns I <sup>2</sup> C setup/hold time I2CMSTBT = 101, 339kbps (typ) I <sup>2</sup> C-to-I <sup>2</sup> C master bit-rate setting I2CSLVTO = 10, 1024µs (typ) I <sup>2</sup> C-to-I <sup>2</sup> C slave remote timeout			
0x0E	0x6A	RESERVED = 01  GPIEN = 1, enable GPI-to-GPO signal transmission to serializer  GPIIN = 0, GPI input is low (read only)  GPIO10UT = 1, set GPIO1 to high  GPIO1IN = 0, GPIO1 input is low (read only)  GPIO00UT = 1, set GPIO0 to high  GPIO0IN = 0, GPIO0 input is low (read only)			
0x0F	0x00	DETTHR = 00000000, error threshold set to zero for detected errors			
0x10	0x00 (read only)	DETERR = 00000000, zero errors detected			
0x11	0x00	CORRTHR = 00000000, error threshold set to zero for corrected errors			
0x12	0x00 (read only)	CORRERR = 00000000, zero errors corrected			
0x13	0x00 (read only)	PRBSERR = 00000000, zero PRBS errors detected			
0x14	0x00 (read only)	PRBSOK = 0, PRBS test not completed RESERVED = 0000000			
0x15	0x2X	RESERVED = 00100XXX			
0x16	0x30	RESERVED = 00110000			
0x17	0x54	RESERVED = 01010100			
0x18	0x30	RESERVED = 00110000			

Table 1. Power-Up Default Register Map (see Table 16) (continued)

REGISTER ADDRESS (hex)	POWER-UP DEFAULT (hex)	POWER-UP DEFAULT SETTINGS (MSB FIRST)	
0x19	0xC8	RESERVED = 11001000	
0x1A	0xXX (read only)	RESERVED = XXXXXXXX	
0x1B	0xXX (read only)	RESERVED = XXXXXXXX	
0x1C	0xXX (read only)	RESERVED = XXXXXXXX	
0x1D	OxOX (read only)  CXTP = 0, twisted-pair input CXSEL = 0, noninverting input I2CSEL = 0, UART input LCCEN = 0, local control channel disabled RESERVED = XXXX		
0x1E	0x0A (read only)	() ID = 00001010, device ID is 0x0A	
0x1F	0x0X (read only)	RESERVED = 000 CAPS = 0, not HDCP capable REVISION = XXXX	

X = Indeterminate.

**Table 2. Output Map** 

EDC	BWS	DBL	HVEN	DOUTA	DOUTB*	SERIAL LINK WORD BITS
0	0	0	0	0:21	_	0:21
0	0	0	1	0:17, 20:21, HS, VS	_	0:17, 20:21
0	0	1	0	0:10	0:10	0:21
0	0	1	1	0:10, HS, VS	0:10, HS, VS	0:21
0	1	0	0	0:21	_	0:21
0	1	0	1	0:17, 20:21, HS, VS	_	0:17, 20:21
0	1	1	0	0:14	0:14	0:29
0	1	1	1	0:14, HS, VS	0:14, HS, VS	0:29
1	0	0	0	0:15	_	0:15
1	0	0	1	0:15, HS, VS	_	0:15
1	0	1	0	0:7	0:7	0:15
1	0	1	1	0:7, HS, VS	0:7, HS, VS	0:15
1	1	0	0	0:21	_	0:21
1	1	0	1	0:17, 20:21, HS, VS	_	0:17, 20:21
1	1	1	0	0:11	0:11, HS, VS	0:23
1	1	1	1	0:11, HS, VS	0:11, HS, VS	0:23

<sup>\*</sup>In double-output mode (DBL = 1), DOUTA output on the first cycle of PCLKOUT and DOUTB output on the second cycle of PCLKOUT.

#### **Serial Link Signaling and Data Format**

The serializer uses differential CML signaling to drive twisted-pair cable and single-ended CML to drive coax cable with programmable pre/deemphasis and AC-coupling. The deserializer uses AC-coupling and programmable channel equalization.

Input data is scrambled and then 8b/10b coded. The deserializer recovers the embedded serial clock, then samples, decodes, and descrambles the data. In 24-bit or 32-bit mode, 22 or 30 bits contain the video data and/or error-correction bits, if used. The 23rd or 31st bit carries the forward control-channel data. The last bit is the parity bit of the previous 23 or 31 bits (Figure 15).

#### **Reverse Control Channel**

The serializer uses the reverse control channel to receive  $I^2C/UART$  and GPO signals from the deserializer in the

opposite direction of the video stream. The reverse control channel and forward video data coexist on the same serial cable, forming a bidirectional link. The reverse control channel operates independently from the forward control channel. The reverse control channel is available 2ms after power-up. The serializer temporarily disables the reverse control channel for 350µs after starting/stopping the forward serial link.

#### **Data-Rate Selection**

The serializer/deserializer use DRS, DBL, and BWS to set the PCLKOUT frequency range (Table 3). Set DRS = 1 for a PCLKOUT frequency range of 6.25MHz to 12.5MHz (32-bit, single-output mode) or 8.33MHz to 16.66MHz (24-bit, single-output mode). Set DRS = 0 for normal operation. It is not recommended to use double-output mode when DRS = 1.

Table	3	Data-Ra	te Sel	ection	Table
Iable		Dala-ina		-CHOIL	Iavic

DRS SETTING	DBL SETTING	BWS SETTING	PCLKOUT RANGE (MHz)
0	0 (single input)	0 (24-bit mode)	16.66 to 50
0	0	1 (32-bit mode)	12.5 to 35
0	1 (double input)	0	33.3 to 100
0	1	1	25 to 75
1	0	0	8.33 to 16.66
1	0	1	6.25 to 12.5
1	1	0	Do Not Use
1	1	1	Do Not Use

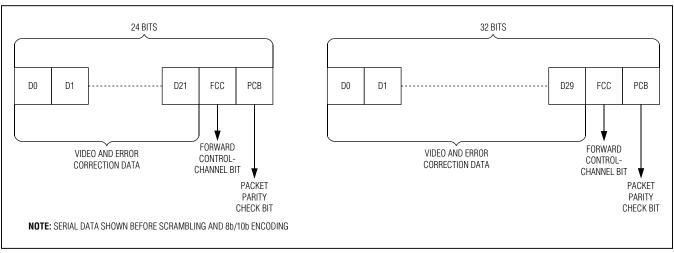


Figure 15. Serial-Data Format

#### Control Channel and Register Programming

The control channel is available for the  $\mu C$  to send and receive control data over the serial link simultaneously with the high-speed data. The  $\mu C$  controls the link from either the serializer or the deserializer side to support video-display or image-sensing applications. The control channel between the  $\mu C$  and serializer or deserializer runs in base mode or bypass mode, according to the mode selection (MS/HVEN) input of the device connected to the  $\mu C$ . Base mode is a half-duplex control channel and bypass mode is a full-duplex control channel.

#### **UART Interface**

In base mode, the  $\mu$ C is the host and can access the registers of both the serializer and deserializer from either side of the link using the GMSL UART protocol. The  $\mu$ C can also program the peripherals on the remote side by sending the UART packets to the serializer or deserializer, with the UART packets converted to I<sup>2</sup>C by the device on the remote side of the link. The  $\mu$ C communicates with a UART peripheral in base mode (through INTTYPE register settings), using the half-duplex default GMSL UART protocol of the serializer/deserializer. The device addresses of the serializer/deserializer in base mode are programmable. The default value is 0x80 for the serializer and is determined by the CX/TP input for the deserializer (Table 8).

When the peripheral interface is I<sup>2</sup>C, the serializer/deserializer convert UART packets to I<sup>2</sup>C that have device addresses different from those of the serializer or deserializer. The converted I<sup>2</sup>C bit rate is the same as the original UART bit rate.

The deserializer uses differential line coding to send signals over the reverse channel to the serializer. The bit rate of the control channel is 9.6kbps to 1Mbps in both directions. The serializer/deserializer automatically detect the control-channel bit rate in base mode. Packet bit-rate changes can be made in steps of up to 3.5 times higher or lower than the previous bit rate. See the *Changing the Clock Frequency* section for more information on changing the control-channel bit rate.

Figure 16 shows the UART protocol for writing and reading in base mode between the  $\mu C$  and the serializer/deserializer.

Figure 17 shows the UART data format. Figure 18 and Figure 19 detail the formats of the SYNC byte (0x79) and the ACK byte (0xC3). The µC and the connected slave chip generate the SYNC byte and ACK byte, respectively. Events such as device wake-up and GPI generate transitions on the control channel that can be ignored by the µC. Data written to the serializer/deserializer registers do not take effect until after the ACK byte is sent. This allows the µC to verify that write commands are received without error, even if the result of the write command directly affects the serial link. The slave uses the SYNC byte to synchronize with the host UART's data rate. If the GPI or MS/HVEN inputs of the deserializer toggle while there is control-channel communication, or if a line fault occurs, the control-channel communication is corrupted. In the event of a missed or delayed acknowledge (~1ms due to control-channel timeout), the µC should assume there was an error in the packet when the slave device received it, or that an error occurred during the response from the slave device. In base mode, the μC must keep the UART Tx/Rx lines high for 16 bit times before starting to send a new packet.

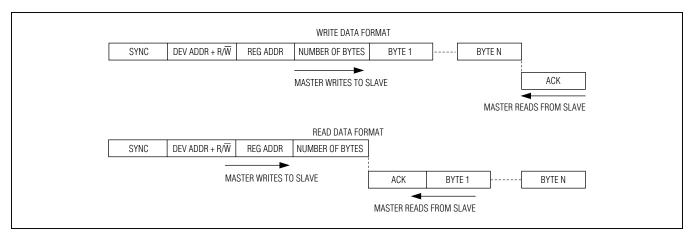


Figure 16. GMSL UART Protocol for Base Mode