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# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

### **General Description**

The *Himalaya* series of voltage regulator ICs and power modules enable cooler, smaller, and simpler powersupply solutions. The MAXM17574 is an easy-to-use power module that combines a synchronous step-down DC-DC converter, fully shielded inductor, and compensation components in a low-profile, thermally-efficient, system-in-package (SiP). The device operates over a wide input-voltage range of 4.5V to 60V, delivers up to 3A continuous output current, and has excellent line and load regulation over an output-voltage range of 0.9V to 15V. The device only requires five external components to complete the total power solution. The high level of integration significantly reduces design complexity, manufacturing risks, and offers a true plug-and-play power-supply solution, reducing time-to-market.

The device can be operated in pulse-width modulation (PWM) or discontinuous conduction mode (DCM).

The MAXM17574 is available in a low-profile, highly thermal-emissive, compact, 33-pin, 9mm x 15mm x 2.92mm SiP package that reduces power dissipation in the package and enhances efficiency. The feedback voltageregulation accuracy over -40°C to +125°C is  $\pm 0.9\%$ . The package is easily soldered onto a printed circuit board and suitable for automated circuit board assembly.

### **Applications**

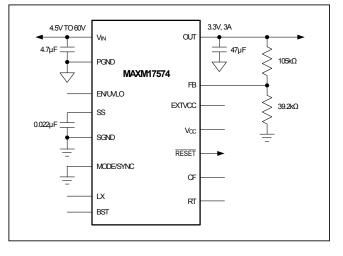
- Industrial Power Supplies
- Distributed Supply Regulation
- FPGA and DSP Point-of-Load Regulator
- Base Station Point-of-Load Regulator
- HVAC and Building Control

Ordering Information appears at end of data sheet.

#### **Benefits and Features**

- Reduces Design Complexity, Manufacturing Risks, and Time-to-Market
  - Integrated Synchronous Step-Down DC-DC converter
  - Integrated Inductor
  - Integrated Compensation Components
- Saves Board Space in Space-Constrained Applications
  - Complete Integrated Step-Down Power Supply in a Single Package
  - Small Profile 9mm x 15mm x 2.92mm SiP Package
  - Simplified PCB Design with Minimal External BOM Components
- Offers Flexibility for Power-Design Optimization
  - Wide Input-Voltage Range from 4.5V to 60V
  - Output-Voltage Adjustable Range from 0.9V to 15V
  - Adjustable Frequency with External Frequency Synchronization (100kHz to 2.2MHz)
  - Soft-Start Programmable
  - Auxiliary bootstrap LDO for improved EfficiencyOptional Programmable EN/UVLO
- Operates Reliably in Adverse Industrial Environments
  - Integrated Thermal Protection
  - Hiccup Mode Overload Protection
  - RESET Output-Voltage Monitoring
  - High Industrial Ambient Operating Temperature Range (-40°C to +125°C) / Junction Temperature Range (-40°C to +150°C)

## **Typical Application Circuit**





# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

### **Absolute Maximum Ratings**

V <sub>IN</sub> to PGND	0.3V to +65V
EN/UVLO to SGND	0.3V to +65V
EXTVCC to SGND	0.3V to +26V
BST to PGND	0.3V to +70V
BST to LX	0.3V to +6.5V
BST to V <sub>CC</sub>	0.3V to +65V
OUT to PGND (V <sub>IN</sub> < 25V)	0.3V to V <sub>IN</sub> + 0.3V
OUT to PGND (V <sub>IN</sub> > 25V)	0.3V to +25V
LX to PGND	0.3V to V <sub>IN</sub> + 0.3V
FB to SGND	0.3V to +1.5V

RESET, SS to SGND	0.3V to +6.5V
MODE/SYNC, V <sub>CC</sub> , RT, CF to SGND	0.3V to +6.5V
PGND to SGND	0.3V to +0.3V
Output Short-circuit duration	Continuous
Operating Temperature Range (Note 1)	40°C to +125°C
Junction Temperature	+150°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10s)	+300°C
Soldering Temperature (reflow)	+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **Package Information**

PACKAGE TYPE: 33-PIN SIP				
Package Code	L33915#3			
Outline Number	21-100175			
Land Pattern Number	<u>90-100057</u>			
THERMAL RESISTANCE, FOUR-LAYER BOARD (	Note 2)			
Junction to Ambient Thermal Resistance $(\theta_{JA})$	22.6°C/W			

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

**Note 1:** Junction temperature greater than +125°C degrades operating lifetimes.

Note 2: Package thermal resistance is measured on evaluation board with natural convection.

## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Electrical Characteristics**

 $(V_{IN} = V_{EN/UVLO} = 24V, R_{RT} = 40.2k\Omega$  (f<sub>SW</sub> = 500kHz), V<sub>SGND</sub> = V<sub>PGND</sub> = V<sub>MODE/SYNC</sub> = V<sub>EXTVCC</sub> = 0V, V<sub>FB</sub> = 1V, SS = CF = RESET = LX = OUT = BST = V<sub>CC</sub> = OPEN, T<sub>A</sub> = -40°C to 125°C, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C. All voltages are referenced to SGND, unless otherwise noted.) (Note 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
INPUT SUPPLY (VIN)							
Input Voltage Range	V <sub>IN</sub>		4.5		60	V	
Input Shutdown Current	I <sub>IN-SH</sub>	V <sub>EN/UVLO</sub> = 0V, shutdown mode		10	15	μA	
	IQ_DCM	DCM Mode, V <sub>LX</sub> = 0.1V		1.2	1.8		
Input Quiescent Current	I <sub>Q_PWM</sub>	Normal Switching Mode, f <sub>SW</sub> = 650kHz, V <sub>OUT</sub> = EXTVCC = 5V		12.5		mA	
ENABLE/UVLO (EN)							
	V <sub>ENR</sub>	V <sub>EN/UVLO</sub> rising	1.19	1.215	1.26		
EN/UVLO Threshold	V <sub>ENF</sub>	V <sub>EN/UVLO</sub> falling	1.068	1.09	1.131	V	
	V <sub>EN-TRUESD</sub>	V <sub>EN/UVLO</sub> falling, true shutdown		0.8			
Enable Pullup resistor	R <sub>ENP</sub>	Pullup resistor between IN and EN/UVLO pins	3.15	3.3	3.45	MΩ	
LDO (V <sub>CC</sub> )							
V <sub>CC</sub> Output-Voltage		1mA < I <sub>VCC</sub> < 25mA	4.75	5	5.25		
Range	V <sub>CC</sub>	$6V \le V_{IN} \le 60V; I_{VCC}=1mA$	4.75	5	5.25	V	
V <sub>CC</sub> Current Limit	I <sub>VCC(MAX)</sub>	V <sub>CC</sub> = 4.3V, V <sub>IN</sub> = 7V	40	65	130	mA	
V <sub>CC</sub> Dropout	V <sub>CC(DO)</sub>	V <sub>IN</sub> = 4.5V, I <sub>VCC</sub> = 20mA			0.3	V	
	V <sub>CC(UVR)</sub>	Rising	4.05	4.2	4.3		
V <sub>CC</sub> UVLO	V <sub>CC(UVF)</sub>	Falling	3.65	3.8	3.9	- V	
EXT LDO (EXTVCC)							
EXTVCC Operating Voltage Range			4.84		24	V	
EXTVCC Switchover		EXTVCC rising	4.55	4.7	4.84		
Threshold		EXTVCC falling	4.3	4.48	4.6	V	
EXTVCC Dropout	EXTVCC(DO)	EXTVCC = 4.85V, I <sub>VCC</sub> = 20mA			0.4	V	
EXTVCC Current Limit	I <sub>VCC(MAX)</sub>	V <sub>CC</sub> = 4.5V, EXTVCC = 8V	40	80	150	mA	
SOFT-START (SS)						1	
Charging Current	I <sub>SS</sub>	V <sub>SS</sub> = 0.5V	4.7	5	5.3	μA	
OUTPUT SPECIFICATION							
Line-Regulation Accuracy		V <sub>IN</sub> = 10V to 60V, V <sub>OUT</sub> = 5V		0.1		mV/V	
Load-Regulation Accuracy		$I_{OUT} = 0A \text{ to } 1.5A$		1		mV/A	
FB Regulation Voltage	V <sub>FB_REG</sub>	MODE/SYNC = SGND or V <sub>CC</sub>	0.892	0.9	0.908	V	
FB Input Leakage Current	I <sub>FB</sub>	V <sub>FB</sub> = 1V, T <sub>A</sub> = 25°C	-50		50	nA	
V <sub>FB</sub> Undervoltage Trip Level to Cause HICCUP	V <sub>OUT(HICF)</sub>		0.56	0.58	0.65	V	
HICCUP Timeout				32768		Cycles	

## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

### **Electrical Characteristics (continued)**

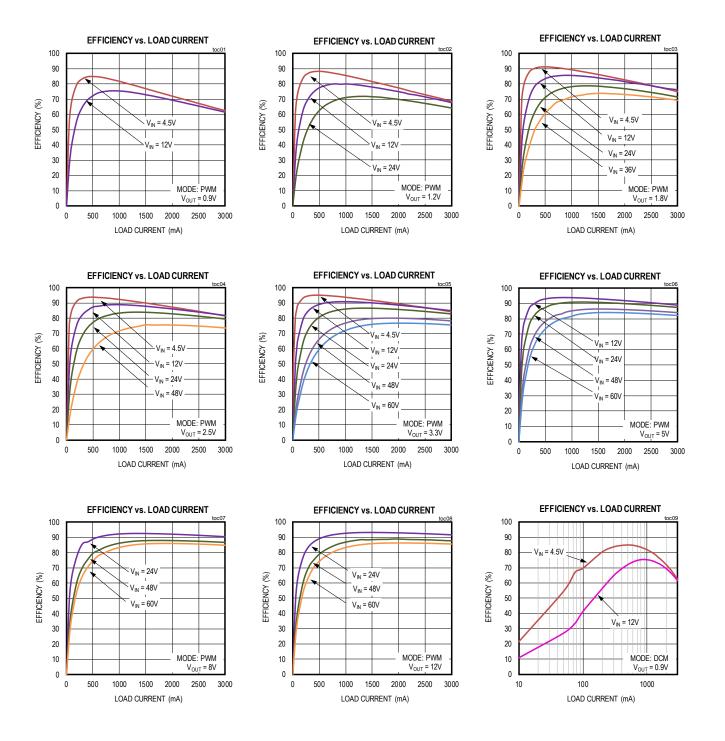
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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
MODE/SYNC			·				
MODE Threshold	V <sub>M(DCM)</sub>	MODE/SYNC = V <sub>CC</sub> (DCM Mode)	V <sub>CC</sub> - 0.65			V	
	V <sub>M(PWM</sub> )	MODE/SYNC = SGND (PWM Mode)			0.75		
SYNC Frequency Capture Range			1.1 x f <sub>SW</sub>		1.4 x f <sub>SW</sub>	kHz	
SYNC Pulse Width			50			ns	
CVNC Threehold	V <sub>IH</sub>		2.1			N	
SYNC Threshold	VIL				0.8	- V	
CURRENT LIMIT		-	· · ·				
Average Current-Limit Threshold	I <sub>AVG-LIMIT</sub>	V <sub>OUT</sub> = 5V, f <sub>SW</sub> = 650kHz		4.6		A	
RT			· ·				
		R <sub>RT</sub> = OPEN	460	500	540		
Switching Frequency	f <sub>SW</sub>	R <sub>RT</sub> = 40.2k	475	500	525	- kHz	
Switching Frequency		R <sub>RT</sub> = 8.06K	1950	2200	2450		
		R <sub>RT</sub> = 210K	90	100	110		
Minimum On-Time	t <sub>ON(MIN)</sub>			60	80	ns	
Minimum Off-Time	t <sub>OFF(MIN)</sub>		140		160	ns	
RESET							
RESET Output Level Low		IRESET = 10mA			0.4	V	
RESET Output leakage Current		$T_A = T_J = +25^{\circ}C, V_{\overline{RESET}} = 5.5V$	-0.1		0.1	μA	
FB Threshold for RESET Deassertion	V <sub>FB-OKR</sub>	V <sub>FB</sub> rising	93.8	95	97.8	%	
FB Threshold for RESET Assertion	V <sub>FB-OKF</sub>	V <sub>FB</sub> falling	90.5	92	94.6	%	
RESET Deassertion Delay After FB Reaches 95% Regulation				1024		Cycles	
THERMAL SHUTDOWN (1	EMP)						
Thermal Shutdown Threshold		Temperature rising		165		°C	
Thermal Shutdown Hysteresis				10		°C	

**Note 3:** Electrical specifications are production tested at  $T_A = +25^{\circ}C$ . Specifications over the entire operating temperature range are guaranteed by design and characterization.

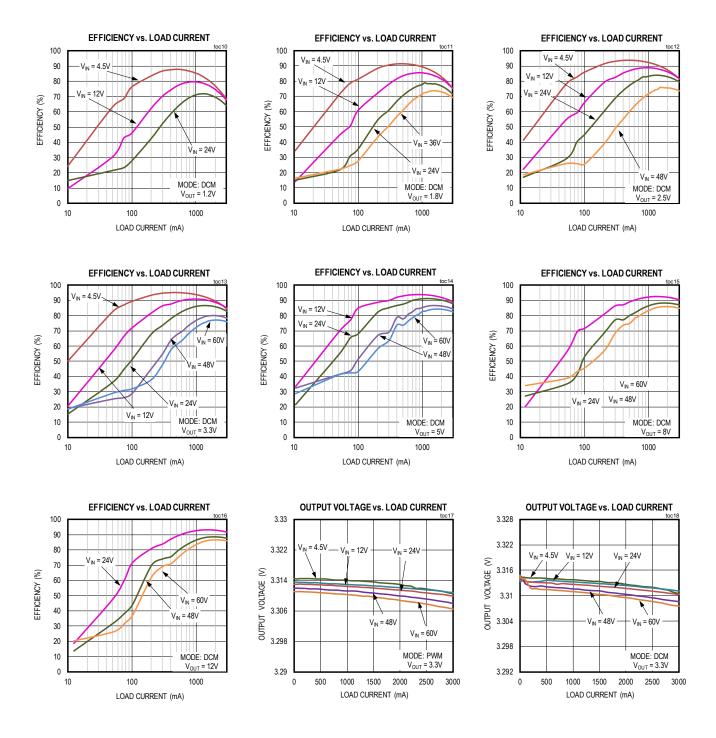
# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

### **Typical Operating Characteristics**



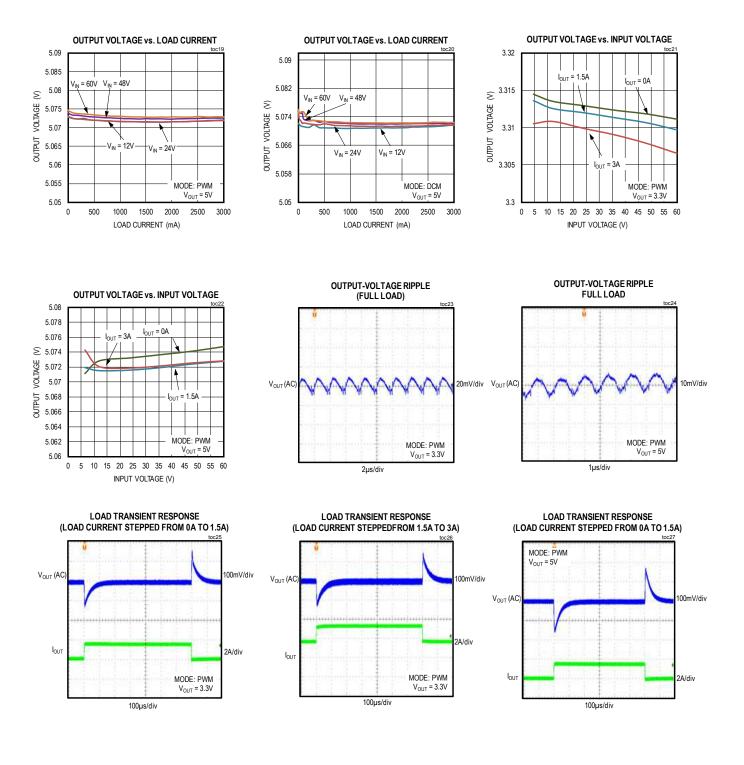
# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

### **Typical Operating Characteristics (continued)**



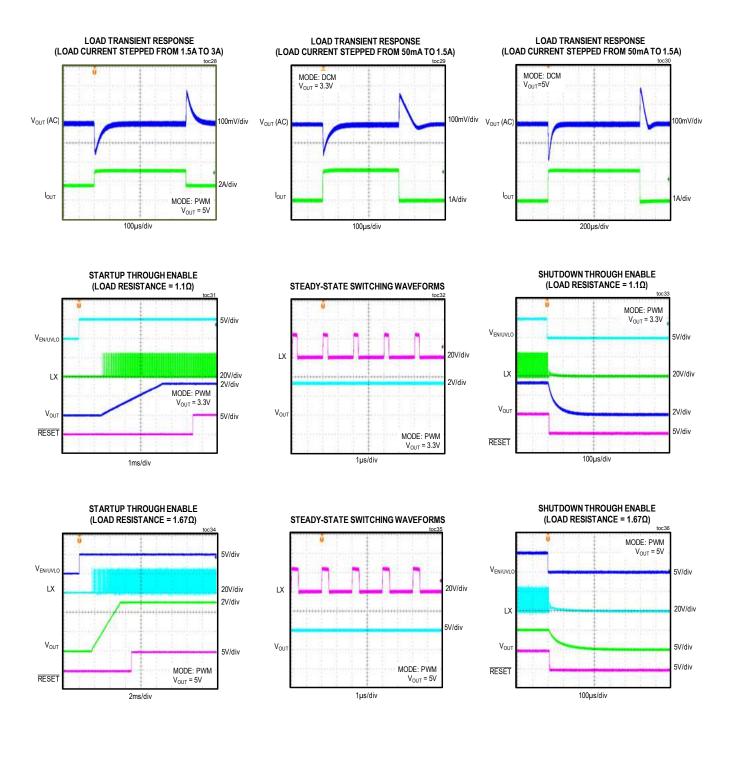
# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Typical Operating Characteristics (continued)**



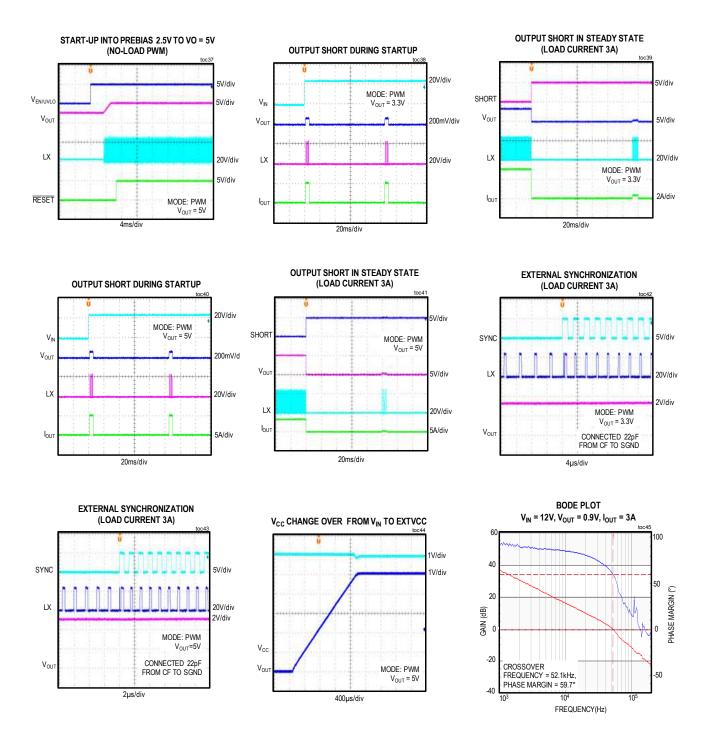
# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Typical Operating Characteristics (continued)**



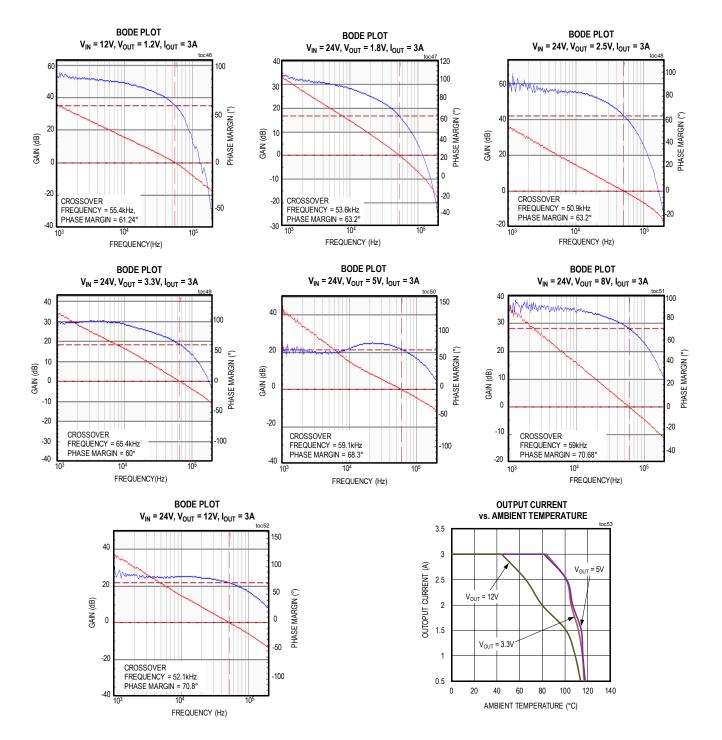
# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Typical Operating Characteristics (continued)**



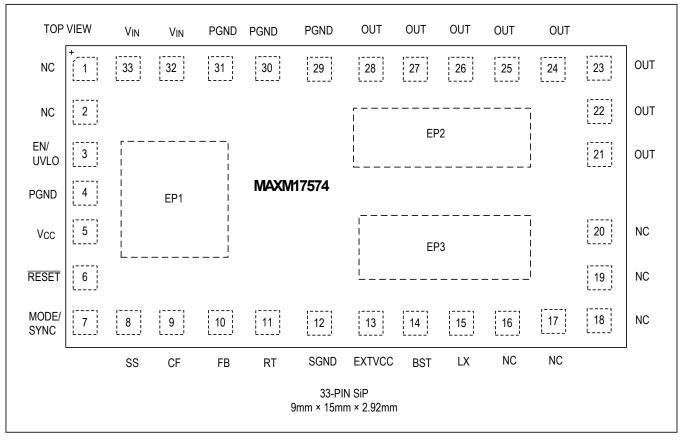
# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

### **Typical Operating Characteristics (continued)**



## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Pin Configuration**



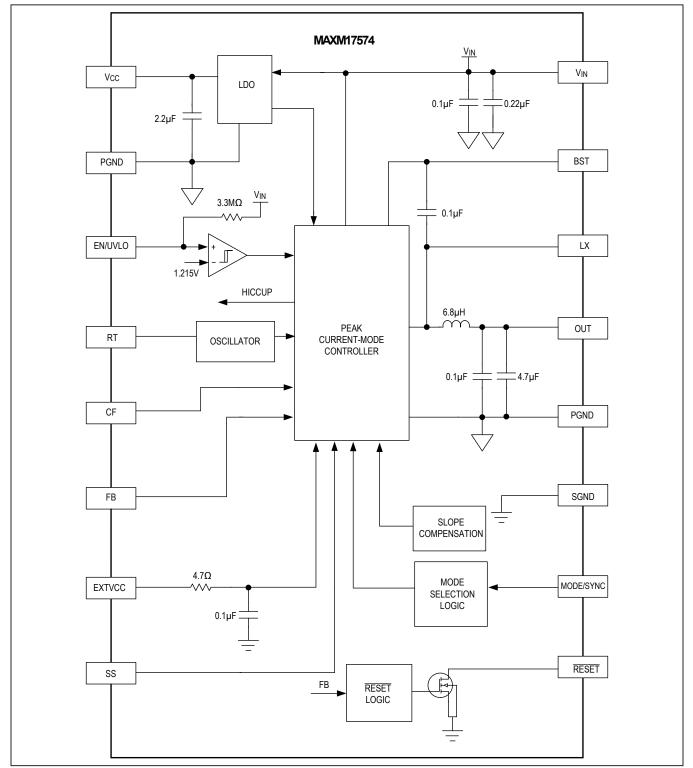
## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Pin Description**

PIN	NAME	FUNCTION	
1, 2, 16-20, EP3	NC	Not connected	
3 EN/UVLO		Enable/Undervoltage-Lockout Input. Connect a resistor from EN/UVLO to SGND to set the UVLO threshold. See the <i>Input Undervoltage-Lockout Level</i> section for more details.	
4, 29-31	PGND	Power Ground. Connect the PGND pins to the power ground plane.	
5	V <sub>CC</sub>	5V LDO Output. The V <sub>CC</sub> is bypassed to PGND internally through a 2.2µF capacitor. Do not connect any external components to the V <sub>CC</sub> pin.	
6	RESET	Open-Drain $\overline{\text{RESET}}$ Output. The $\overline{\text{RESET}}$ output is driven low if FB drops below 92% of its set value. RESET goes high 1024 clock cycles after FB rises above 95% of its set value.	
7 MODE/SYNC Configures Device Mode of Operation. MODE pin configures the device to operate either in P at all loads. Connect MODE to V <sub>CC</sub> for DCM operation. The device can be synchronized to an external clock using this pin. See the <i>Mode Selection (MODE)</i> section and the <i>External Frequ</i> <i>Synchronization</i> section for more details.			
8	SS	Soft-Start Input. Connect a capacitor from SS to SGND to set the soft-start time.	
9 CF 500kH		Compensation Pin. Connect a capacitor from CF to FB when the switching frequency is below 500kHz. Leave CF open for switching frequency greater than 500kHz. See the <i>Loop Compensation</i> section for more details.	
10	FB	Feedback Input. Connect FB to the center tap of an external resistor-divider from the output to SGND to set the output voltage. See the <i>Adjusting Output Voltage</i> section for more details	
11 RT regulator's switching frequency between 100kHz and 2.2MHz. Leave RT open f		Pin for Programming Switching Frequency. Connect a resistor from RT to SGND to set the regulator's switching frequency between 100kHz and 2.2MHz. Leave RT open for the default 500kHz frequency. See the <i>Setting the Switching Frequency</i> section for more details.	
12	SGND	Analog Ground pin.	
		External Power Supply Input for the Internal LDO. Applying a voltage between 4.84V and 24V at EXTVCC pin bypasses the internal LDO and improves the efficiency.	
14	BST	Boost Flying Capacitor. Internally a 0.1µF is connected from BST to LX. Do not connect any external components to BST pin.	
15	LX	Switching Node. Do not connect any external components to the LX pin.	
21-28     OUT     Regulator Output Pin. Connect required capacitor from OUT to PGND.       32-33     V <sub>IN</sub> Power-Supply Input. Connect the V <sub>IN</sub> pins together. Decouple to PGND with a capacitor. Place the capacitor close to the V <sub>IN</sub> and PGND pins.		Regulator Output Pin. Connect required capacitor from OUT to PGND.	
EP1         SGND         Exposed Pad. Connect to the SGND of the Module. Connect to a large copper plane below to IC to improve heat dissipation capability.		Exposed Pad. Connect to the SGND of the Module. Connect to a large copper plane below the IC to improve heat dissipation capability.	
EP2 OUT		Exposed Pad. Connect this pad to the OUT pin of the Module. Connect to a large copper plane below the Module to improve heat dissipation capability.	

4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Functional Diagram**



## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

#### **Detailed Description**

The MAXM17574 is a high-efficiency, high-voltage stepdown power module with dual-integrated MOSFETs that operates over a 4.5V to 60V input and supports a programmable output voltage from 0.9V to 15V, delivering up to 3A current. The module integrates all the necessary components required for the switching converter. Built-in compensation for the entire output-voltage range eliminates the need for external components.

The device features a peak-current-mode control architecture with a MODE feature that can be used to operate the device in pulse-width modulation (PWM) or discontinuousconduction mode (DCM) control schemes. PWM operation provides constant frequency operation at all loads, and is useful in applications sensitive to switching frequency. DCM features constant frequency operation and disables negative inductor currents at light loads. DCM operation offers higher efficiency at light loads than PWM mode.

A programmable soft-start feature allows users to reduce input inrush current. The device also incorporates an output enable/undervoltage-lockout pin (EN/UVLO) that allows the user to turn on the part at the desired inputvoltage level. An open-drain RESET pin provides a delayed power-good signal to the system upon achieving successful regulation of the output voltage.

#### Mode Selection (MODE)

The logic state of the MODE pin is latched when V<sub>CC</sub> and EN/UVLO voltages exceed the respective UVLO rising thresholds and all internal voltages are ready to allow LX switching. If the MODE pin is grounded during power-up, the device operates in constant frequency PWM mode at all loads. If the MODE pin is connected to V<sub>CC</sub> during power-up, the device operates in constant frequency DCM mode at light loads. State changes on the MODE pin are ignored during normal operation.

#### **Modes of Operation**

PWM operation provides constant frequency operation at all loads, and is useful in applications sensitive to variable switching frequency. In PWM mode, the inductor current is allowed to go negative. DCM mode of operation doesn't allow the inductor current to go negative. Because of this, the PWM mode of operation gives lower efficiency at light loads compared to DCM mode of operation.

#### **Setting the Switching Frequency**

The switching frequency of the device can be programmed from 100kHz to 2.2MHz by using a resistor connected from the RT pin to SGND. The switching frequency ( $f_{SW}$ ) is related to the resistor( $R_{RT}$ ) connected between RT and SGND pins by the following equation:

$$R_{RT} = \frac{21 \times 10^3}{f_{SW}} - 1.7$$

where  $R_{RT}$  is in k $\Omega$  and  $f_{SW}$  is in kHz. Leaving the RT pin open causes the device to operate at the default switching frequency of 500kHz.

#### **External Frequency Synchronization**

The internal oscillator of the MAXM17574 can be synchronized to an external clock signal on the MODE/ SYNC pin. The external synchronization clock frequency must be between 1.1 ×  $f_{SW}$  and 1.4 ×  $f_{SW}$ , where  $f_{SW}$ is the frequency programmed by the R<sub>RT</sub> resistor. When an external clock is applied to MODE/SYNC pin, the internal oscillator frequency changes to external clock frequency (from original frequency based on RT setting) after detecting 16 external clock edges. The converter operates in PWM mode during synchronization operation. When the external clock is applied on-fly then the mode of operation changes to PWM from the initial state of DCM/ PWM. When the external clock is removed on-fly then the internal oscillator frequency changes to the RT set frequency and the converter still continues to operate in PWM mode until either power cycling or enable cycling. For applications that need external clock synchronization, a 22pF capacitor should be connected from the CF to the SGND pin for robust operation. The minimum external clock pulse-width high should be greater than 50ns. See the MODE/SYNC section in the Electrical Characteristics table for details.

#### Linear Regulator (V<sub>CC</sub> and EXTVCC)

The MAXM17574 has two internal low-dropout (LDO) regulators that powers V<sub>CC</sub>. During power-up, when the EN/UVLO pin voltage is above the true shutdown voltage, then the V<sub>CC</sub> is powered from INLDO. When V<sub>CC</sub> voltage is above the V<sub>CC</sub> UVLO threshold and EXTVCC voltage is greater than 4.7V the V<sub>CC</sub> is powered from EXTVCC LDO. Only one of the two LDOs is in operation at a time, depending on the voltage levels present at EXTVCC. Powering V<sub>CC</sub> from EXTVCC voltage should not exceed 24V.

Typical V<sub>CC</sub> output voltage is 5V. Internally, V<sub>CC</sub> is bypassed with a 2.2 $\mu$ F ceramic capacitor to PGND. See the <u>Electrical Characteristics</u> table for the current limit details for both the regulators. In applications where the buck converter output is connected to the EXTVCC pin, if the output is shorted to ground, then the transfer from EXTVCC LDO to INLDO happens seamlessly without any impact on the normal functionality.

## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

#### Input-Voltage Range

The minimum and maximum operating input voltages for a given output voltage should be calculated as follows:

$$V_{IN(MIN)} = \frac{V_{OUT} + (I_{OUT} \times 0.195)}{1 - (f_{SW(MAX)} \times t_{OFF(MAX)})} + (I_{OUT} \times 0.075)$$

$$V_{IN(MAX)} = \frac{V_{OUT}}{f_{SW(MAX)} \times t_{ON(MIN)}}$$

where,

V<sub>OUT</sub> = Steady-state output voltage,

I<sub>OUT</sub> = Maximum load current

f<sub>sw(MAX)</sub> = Maximum switching frequency,

t<sub>OFF(MAX)</sub> = Worst-case minimum switch off-time (160ns),

t<sub>ON(MIN)</sub> = Worst-case minimum switch on-time (80ns).

<u>Table 1</u> provides operating input-voltage range and the optimum switching frequency for different selected output voltages.

#### **RESET** Output

The device includes a RESET comparator to monitor the output voltage. The open-drain RESET output requires an external pullup resistor. RESET goes high (high impedance) 1024 switching cycles after the regulator output increases above 95% of the designed nominal regulated voltage. RESET goes low when the regulator output voltage drops to below 92% of the nominal regulated voltage. RESET also goes low during thermal shutdown.

#### **Thermal Shutdown Protection**

Thermal shutdown protection limits total power dissipation in the device. When the junction temperature of the device exceeds +165°C (typ), a thermal sensor shuts down the device, allowing the device to cool. The thermal sensor turns the device on again after the junction temperature cools by 10°C. Soft-start resets during thermal shutdown. Carefully evaluate the total power dissipation (see the <u>Power Dissipation and</u> <u>Output-Current Derating</u> section) to avoid unwanted triggering of the thermal shutdown protection in normal operation.

#### **Overcurrent Protection (OCP) / Hiccup Mode**

The device is provided with a robust overcurrent protection (OCP) scheme that protects the device under overload and output short-circuit conditions. When the overcurrent occurs, the module enters hiccup mode of operation. In hiccup mode, the converter is protected by suspending switching for a hiccup timeout period of 32,768 clock cycles. Once the hiccup timeout period expires, soft-start is attempted again. Hiccup mode of operation ensures low power dissipation under output short-circuit conditions.

#### **Applications Information**

#### **Input-Capacitor Selection**

The input capacitor serves to reduce the current peaks drawn from the input power supply and reduces switching noise to the IC. The input capacitor values in <u>Table 1</u> are the minimum recommended values for desired input and output voltages. Applying capacitor values larger than those indicated in <u>Table 1</u> are acceptable to improve the dynamic response. For other operating conditions, the total input capacitance must be greater than or equal to the value given by the following equation in order to keep the input-voltage ripple within specifications and minimize the high-frequency ripple current being fed back to the input source:

$$C_{IN} = \frac{I_{OUT(MAX)} \times D \times (1-D)}{\eta \times f_{SW} \times \Delta V_{IN}}$$

where,

D = The duty ratio of the controller ( $V_{OUT}/V_{IN}$ ),

 $f_{SW}$  = The switching frequency,

 $\Delta V_{IN}$  = The allowable input voltage ripple,

I<sub>OUT(MAX)</sub> = The maximum load current,

 $\eta$  = The efficiency.

In applications, where the source is located distant from the device input, an electrolytic capacitor should be added in parallel to the ceramic capacitor to provide necessary damping for potential oscillations caused by the inductance of the longer input power path and input ceramic capacitor.

## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

#### **Soft-Start Capacitor Selection**

The device implements adjustable soft-start operation to reduce inrush current. A capacitor connected from the SS pin to SGND programs the soft-start time. The selected output capacitance ( $C_{SEL}$ ) and the output voltage ( $V_{OUT}$ ) determine the minimum required soft-start capacitor as follows:

$$C_{SS} \ge 28 \times 10^{-6} \times C_{SEL} \times V_{OUT}$$

The soft-start time  $(t_{SS})$  is related to the capacitor connected at SS  $(C_{SS})$  by the following equation:

$$t_{SS} = \frac{C_{SS}}{5.55 \times 10^{-6}}$$

For example, to program a 1ms soft-start time, a 5.6nF capacitor should be connected from the SS pin to SGND.

#### Input Undervoltage-Lockout Level

The MAXM17574 contains an internal pullup resistor ( $3.3M\Omega$ ) from EN/UVLO to V<sub>IN</sub> to have a default startup voltage. The device offers an adjustable input undervoltage-lockout level to set the voltage at which the device is turned on by a single resistor connecting from EN/UVLO to SGND. Calculate the resistor using the following equation:

$$R_{ENU} = \frac{3.3 \times 1215}{V_{INU} - 1.215}$$

where R<sub>ENU</sub> is in k $\Omega$  and V<sub>INU</sub> is the voltage required to turn on the device. Ensure that V<sub>INU</sub> is high enough to support the V<sub>OUT</sub>. See <u>Table 1</u> to set the proper V<sub>INU</sub> voltage greater than or equal to the minimum input voltage for each desired output voltage.

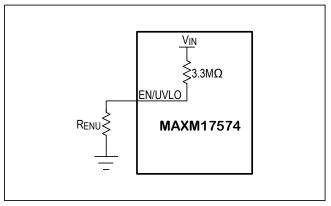


Figure 1. Setting the Input Undervoltage-Lockout Level

#### **Output Capacitor Selection**

The X7R ceramic output capacitors are preferred due to their stability over temperature in industrial applications. The minimum recommended output capacitor values are listed in <u>Table 1</u> for desired output voltages to support a dynamic step load of 50% of the maximum output current and to contain the output-voltage deviation to 3% of the output voltage. For additional adjustable output voltages, the output capacitance value is derived from the following equation:

$$C_{OUT} = \frac{1}{2} \times \frac{I_{STEP} \times I_{RESPONSE}}{\Delta V_{OUT}}$$
$$t_{RESPONSE} \cong \left(\frac{0.33}{f_C}\right) + \left(\frac{1}{f_{SW}}\right)$$

where,

ISTEP = Load current step,

tRESPONSE = Response time of the controller,

 $\Delta V_{OUT}$  = Allowable output-voltage deviation,

f<sub>C</sub> = Target closed-loop crossover frequency,

f<sub>SW</sub> = Switching frequency.

Typically, select  $f_C$  to be 1/9th of  $f_{SW}$  if the switching frequency is less than or equal to 500kHz. If the switching frequency is more than 500kHz, select  $f_C$  to be 55kHz.

#### Adjusting Output Voltage

The MAXM17574 supports an adjustable output-voltage range of 0.9V to 15V by using a resistive feedback divider from OUT to FB. <u>Table 1</u> provides the feedback dividers for desired input and output voltages. Other adjustable output voltages programmed using the following procedure.

Calculate resistor RU from the output to FB as follows:

$$R_{U} = \frac{216 \times 10^{3}}{f_{C} \times C_{OUT}}$$

where,

 $R_U$  is in  $k\Omega$ ,

 $f_C$  = Crossover frequency (kHz),

 $C_{OUT}$  = Actual derated value of output capacitance (µF). Calculate the R<sub>B</sub> resistor as

$$R_B = \frac{R_U \times 0.9}{V_{OUT} - 0.9}$$

where  $R_B$  and  $R_U$  are in k $\Omega$ .

## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

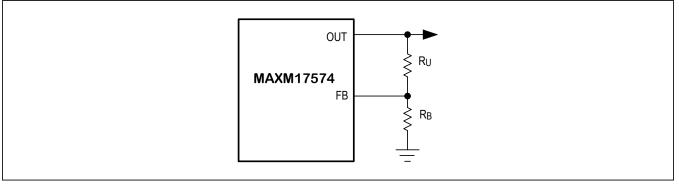


Figure 2. Setting the Output Voltage

## **Table 1. Selection of Components**

V <sub>IN(MIN)</sub> (V)	V <sub>IN(MAX)</sub> (V)	V <sub>OUT</sub> (V)	C <sub>IN</sub>	С <sub>ОИТ</sub>	R <sub>U</sub> (kΩ)	R <sub>B</sub> (kΩ)	fsw (kHZ)	R <sub>RT</sub> (kΩ)	C <sub>SS</sub> (pF)		
4.5	18	0.9	3 × 2.2µF 25V 1206	4 × 47µF 6.3V 1210	23.2	OPEN	500	OPEN	22000		
4.5	18	1	3 × 2.2µF 25V1206	4 × 47µF 6.3V 1210	23.2	200	500	OPEN	22000		
4.5	15	1.2	3 × 2.2µF 25V1206		33.2	100	450	44.2	22000		
4.5	30	1.2	3 × 2.2µF 50V1206	3 × 47µF 6.3V 1210	33.Z	100	450	44.2	22000		
4.5	15	1.5	3 × 2.2µF 25V1206	3 × 47µF 6.3V 1210				40.0	500		22000
4.5	30	1.5	3 × 2.2µF 50V1206	3 × 47µr 6.3V 1210	33.2	49.9	500	OPEN	22000		
4.5	15	4.0	2 × 2.2µF 25V1206	0 47	07.4	07.4	500	ODEN	22000		
4.5	40	1.8	2 × 2.2µF 50V1206	2 × 47µF 6.3V 1210	37.4	37.4	500	OPEN	22000		
	15	2.5	2 × 2.2µF 25V 1206			34.8			22000		
4.5	40		2 × 2.2µF 50V 1206	2 × 47µF 6.3V 1210	61.9		500	OPEN	22000		
	54		2 × 2.2µF 100V 1210						22000		
	15		1 × 4.7µF 25V 1206						22000		
4.5	40	3.3	3.3 1 × 4.7μF 50V 1206 1 × 47μF 6.3V 121	1 × 47µF 6.3V 1210	105	39.2	500	OPEN	22000		
	60		1 × 4.7µF 80V 1210						22000		
	15		1 × 4.7µF 25V 1206		140	30.1	650	30.1	22000		
10	40	5	1 × 4.7µF 50V 1206	1 × 47µF 6.3V 1210					22000		
	60		1 × 4.7µF 80V 1210						22000		
18	40	8	1 × 2.2µF 50V 1206	1 × 220E 10V 1210	200	24.0	1000	19.6	22000		
10	60	0	1 × 2.2µF 100V 1206	1 × 22µF 10V 1210	200	24.9	1000	19.0	22000		
24	40	12	1 × 1µF 50V 1206	2 × 10UE 25V 1210	255	20 F	1500	10.4	22000		
24	60		1 × 1µF 100V 1206	2 × 10µF 25V 1210	200	20.5	1500	12.4	22000		
20	40	15	1 × 1µF 50V 1206	2 × 10UE 25V 1210	200	10.1	2000	0.07	22000		
28	60 15	15	1 × 1µF 100V 1206	2 × 10µF 25V 1210	300	19.1	2000	8.87	22000		

## 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

#### **Loop Compensation**

The device is internally loop compensated. However, if the switching frequency is less than 500kHz, connect a 0402 capacitor ( $C_{CF}$ ) between the CF and FB pins. Use Table 2 to select the value of capacitor ( $C_{CF}$ ).

#### Power Dissipation and Output-Current Derating

The MAXM17574 output current needs to be derated if the device needs to be operated in a high ambient-temperature environment. The amount of current-derating depends upon the input voltage, output voltage, and ambient temperature. The derating curves in TOC 53 from the *Typical Operating Characteristics* section can be used as a guideline for different output voltages generated from 24V input. The curves are based on the actual power-loss measurements on bench to limit the maximum junction temperature (T<sub>J(MAX)</sub>) to +125°C. The maximum allowable power losses can be calculated using the following equation:

$$\mathsf{P}_{\mathsf{D}(\mathsf{MAX})} = \frac{\mathsf{T}_{\mathsf{J}(\mathsf{MAX})} - \mathsf{T}_{\mathsf{A}}}{\theta_{\mathsf{J}\mathsf{A}}}$$

where:

 $P_{D(MAX)}$  = Maximum allowed power losses with maximum allowed junction temperature.

 $T_{JMAX}$  = Maximum allowed junction temperature.

 $T_A$  = Operating ambient temperature.

 $\theta_{JA}$  = Junction to ambient thermal resistance.

#### Table 2. Loop Compensation

SWITCHING FREQUENCY RANGE (kHZ)	C <sub>CF</sub> (PF)
200 to 300	2.2
300 to 400	1.2
400 to 500	0.75

#### **PCB Layout Guidelines**

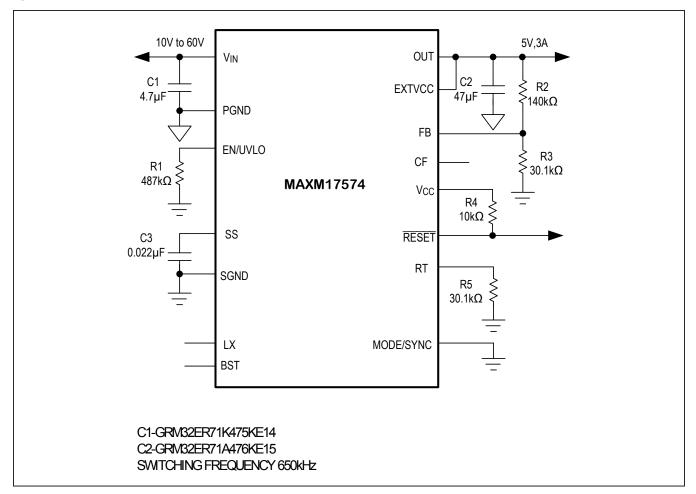
Careful PCB layout is critical to achieve clean, stable operation and to minimize EMI. Use the following guidelines for good PCB layout. Refer to *MAXM17574 EVKIT data sheet* for a good sample layout.

- 1) Place R<sub>RT</sub>, C<sub>SS</sub>, R<sub>U</sub>,R<sub>B</sub> components as close as possible to MAXM17574 respective pins.
- 2) Place the input capacitor as close as possible to the  $V_{\mbox{\rm IN}}$  and PGND of the MAXM17574.
- 3) Place the output capacitor as close as possible to the OUT and PGND of the MAXM17574.
- Connect both PGND and SGND to a large common copper pour or plane area (GND) on the top layer. Avoid breaking the ground connection between the external components and the MAXM17574.
- 5) Use multiple vias to connect internal GND planes to the top layer GND plane.
- Do not keep any solder mask on EP1 and EP2 on the bottom layer. Keeping a solder mask on exposed pads decreases the heat-dissipating capability.

# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Typical Application Circuits**

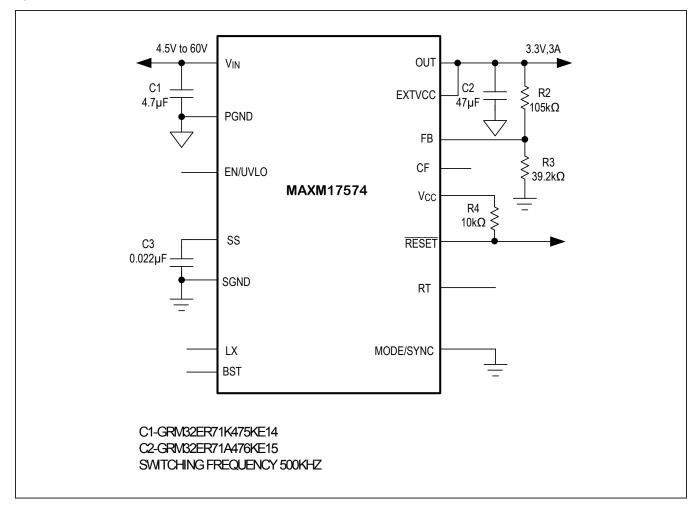
#### **Typical Application Circuit-5V Output Application**



# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

### **Typical Application Circuits (continued)**

#### **Typical Application Circuit-3.3V Output Application**



## **Ordering Information**

PART NUMBER	TEMP RANGE	PIN-PACKAGE
MAXM17574ALC#T -	40°C to +125°C	33 SiP

# Denotes a RoHS-compliant device that may include lead(Pb) that is exampt under the RoHS requirements.

T = Tape and reel.

# 4.5V to 60V, 3A High-Efficiency, DC-DC Step-Down Power Module with Integrated Inductor

## **Revision History**

	REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
ĺ	0	6/17	Initial release	—
	1	9/17	Updated Package Information table, Ordering Information table, and Table 1. Updated Linear Regulator ( $V_{CC}$ and EXTVCC) section.	1, 14, 17, 20

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at www.maximintegrated.com.

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