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8-Input Priority Encoder

Description

The MC10H165 is an 8–Input Priority Encoder. This 10H part is a functional/pinout duplication of the standard MECL $10K^{TM}$ family part, with 100% improvement in propagation delay, and no increases in power–supply current.

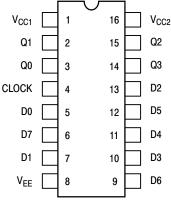
Features

- Propagation Delay, Data-to-Output, 2.2 ns Typical
- Improved Noise Margin 150 mV (Over Operating Voltage and Temperature Range)
- Voltage Compensated
- MECL 10K Compatible
- Pb-Free Packages are Available*

TRUTH TABLE

DATA INPUTS								ουτι	PUTS	;	
D0	D1	D2	D3	D4	D5	D6	D7	Q3	Q2	Q1	Q0
$H \sqcup \sqcup \sqcup \sqcup \sqcup$	X H L L L L	XXHLLL	XXXHLL	XXXXHL	XXXXXH	× × × × × × × × ×	× × × × × × × ×	нтнтт			
L L	L	L	L L	L	L	H L	X H	H H	H H	H H I	L H I





Pin assignment is for Dual-in-Line Package. For PLCC pin assignment, see the Pin Conversion Tables on page 18 of the ON Semiconductor MECL Data Book (DL122/D).

*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

*For additional marking information, refer to Application Note AND8002/D.

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 5 of this data sheet.



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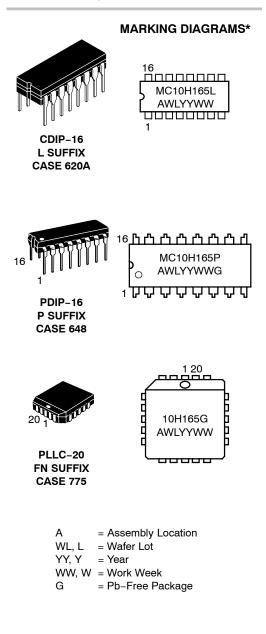


Table 1. MAXIMUM RATINGS

Symbol	Characteristic	Rating	Unit
V_{EE}	Power Supply (V _{CC} = 0)	-8.0 to 0	Vdc
VI	Input Voltage (V _{CC} = 0)	0 to V _{EE}	Vdc
l _{out}	Output Current – Continuous – Surge	50 100	mA
T _A	Operating Temperature Range	0 to +75	°C
T _{stg}	Storage Temperature Range – Plastic – Ceramic	−55 to +150 −55 to +165	°C

Maximum ratings are those values beyond which device damage can occur. Maximum ratings applied to the device are individual stress limit values (not normal operating conditions) and are not valid simultaneously. If these limits are exceeded, device functional operation is not implied, damage may occur and reliability may be affected.

		0 °		25 °		75 °		
Symbol	Characteristic	Min	Max	Min	Max	Min	Мах	Unit
١ _E	Power Supply Current	-	144	-	131	-	144	mA
I _{inH}	Input Current High							μ Adc
	Pin 4	-	510	-	320	-	320	
	Data Inputs	-	600	-	370	-	370	
I _{inL}	Input Current Low	0.5	-	0.5	-	0.3	-	μΑ
V _{OH}	High Output Voltage	-1.02	-0.84	-0.98	-0.81	-0.92	-0.735	Vdc
V _{OL}	Low Output Voltage	-1.95	-1.63	-1.95	-1.63	-1.95	-1.60	Vdc
V _{IH}	High Input Voltage	-1.17	-0.84	-1.13	-0.81	-1.07	-0.735	Vdc
V _{IL}	Low Input Voltage	-1.95	-1.48	-1.95	-1.48	-1.95	-1.45	Vdc

1. Each MECL 10H[™] series circuit has been designed to meet the dc specifications shown in the test table, after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse air flow greater than 500 lfpm is maintained. Outputs are terminated through a 50 Ω resistor to −2.0 V.

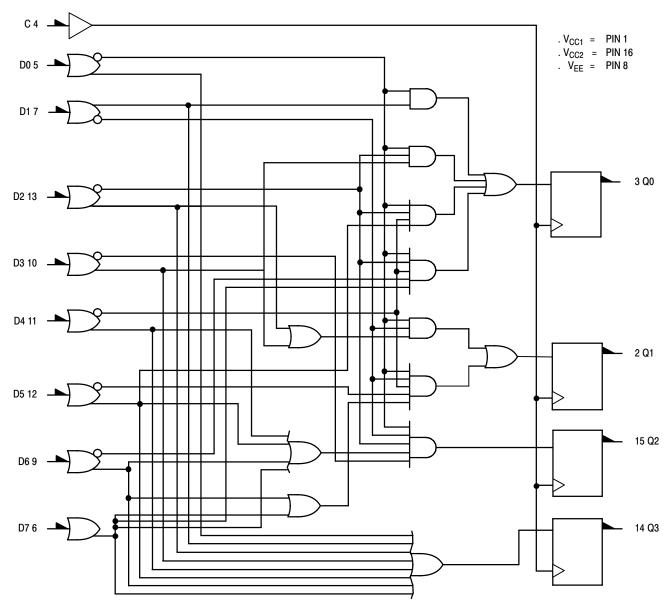
Table 3. AC PARAMETERS

		0 °		25 °		75 °		
Symbol	Characteristic	Min	Max	Min	Max	Min	Max	Unit
t _{pd}	t _{od} Propagation Delay							ns
	Data Input \rightarrow Output	0.7	3.4	0.7	3.4	0.7	3.4	
	Clock Input \rightarrow Output	0.7	2.2	0.7	2.2	0.7	2.2	
t _{set}	Set–up Time	3.0	-	3.0	-	3.0	-	ns
t _{hold}	Hold Time	0.5	-	0.5	-	0.5	-	ns
t _r	Rise Time	0.5	2.4	0.5	2.4	0.5	2.4	ns
t _f	Fall Time	0.5	2.4	0.5	2.4	0.5	2.4	ns

NOTE: Device will meet the specifications after thermal equilibrium has been established when mounted in a test socket or printed circuit board with maintained transverse airflow greater than 500 lfpm. Electrical parameters are guaranteed only over the declared operating temperature range. Functional operation of the device exceeding these conditions is not implied. Device specification limit values are applied individually under normal operating conditions and not valid simultaneously.

8-INPUT PRIORITY ENCODER

The MC10H165 is a device designed to encode eight inputs to a binary coded output. The output code is that of the highest order input. Any input of lower priority is ignored. Each output incorporates a latch allowing synchronous operation. When the clock is low the outputs follow the inputs and latch when the clock goes high. This device is very useful for a variety of applications in checking system status in control processors, peripheral controllers, and testing systems. The input is active when high, (e.g., the three binary outputs are low when input D0 is high). The Q3 output is high when any input is high. This allows direct extension into another priority encoder when more than eight inputs are necessary. The MC10H165 can also be used to develop binary codes from random logic inputs, for addressing ROMs, RAMs, or for multiplexing data.

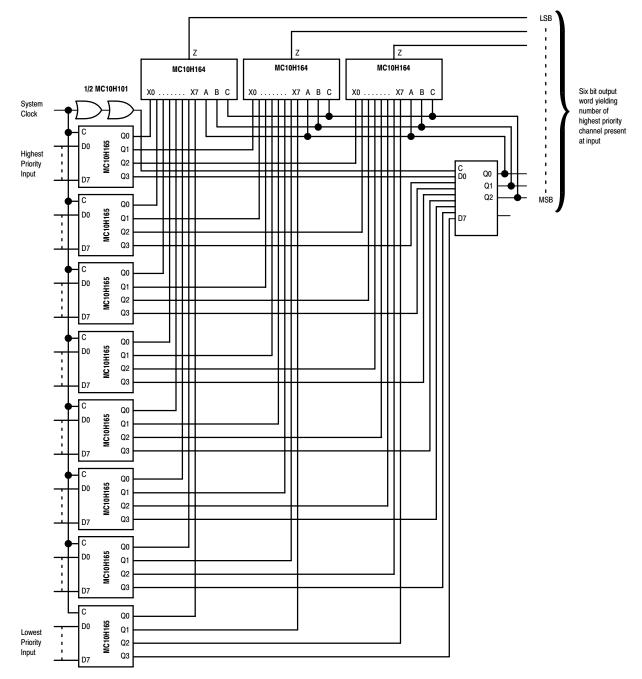


LOGIC DIAGRAM

Numbers at ends of terminals denote pin numbers for L and P packages.

APPLICATION INFORMATION

A typical application of the MC10H165 is the decoding of system status on a priority basis. A 64–line priority encoder is shown in the figure below. System status lines are connected to this encoder such that, when a given condition exists, the respective input will be at a logic high level. This scheme will select the one of 64 different system conditions, as represented at the encoder inputs, which has priority in determining the next system operation to be performed. The binary code showing the address of the highest priority input present will appear at the encoder outputs to control other system logic functions.



64-LINE PRIORITY ENCODER

ORDERING INFORMATION

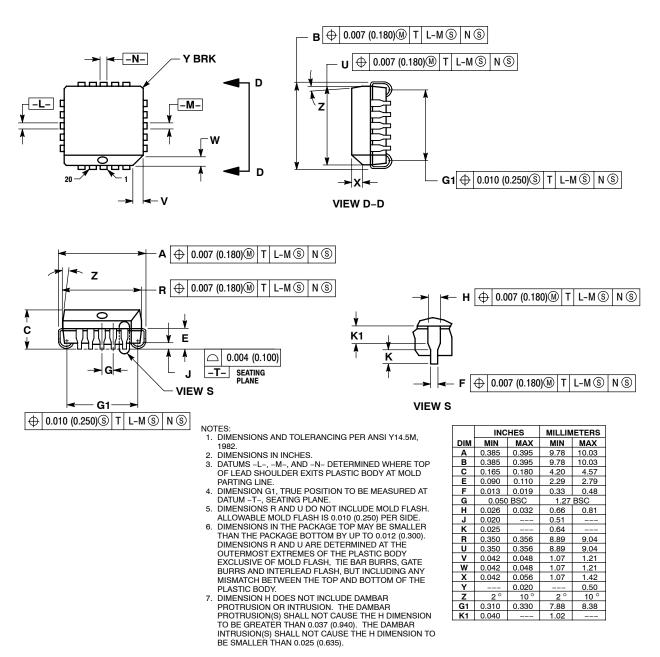
Device	Package	Shipping [†]	
MC10H165FN	PLLC-20	46 Units / Rail	
MC10H165FNG	PLLC-20 (Pb-Free)	46 Units / Rail	
MC10H165FNR2	PLLC-20	500 / Tape & Reel	
MC10H165FNR2G	PLLC-20 (Pb-Free)	500 / Tape & Reel	
MC10H165L	CDIP-16	25 Unit / Rail	
MC10H165P	PDIP-16	25 Unit / Rail	
MC10H165PG	PDIP-16 (Pb-Free)	25 Unit / Rail	

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

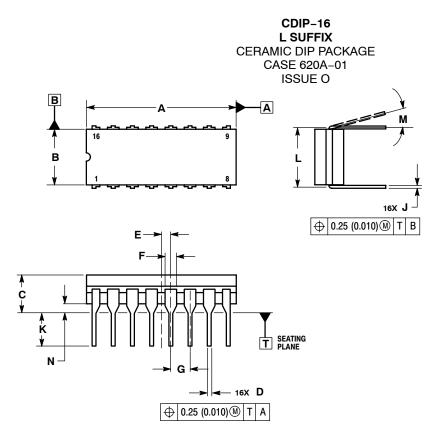
PACKAGE DIMENSIONS



CASE 775-02 ISSUE E



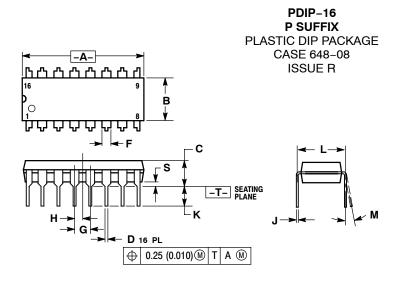
PACKAGE DIMENSIONS



NOTES: 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994. 2. CONTROLLING DIMENSION: INCH. 3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL. 4. DIMENSION F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC BODY. 5. THIS DRAWING REPLACES OBSOLETE CASE OUTLINE 620-10.

	INC	HES	MILLIN	IETERS	
DIM	MIN	MAX	MIN	MAX	
Α	0.750	0.785	19.05	19.93	
В	0.240	0.295	6.10	7.49	
С		0.200		5.08	
D	D 0.015 0.0		0.39	0.50	
Ε	0.050	BSC	1.27	BSC	
F	0.055	0.065	1.40	1.65	
G	0.100	BSC	2.54	BSC	
Н	0.008	0.015	0.21	0.38	
K	0.125 0.1		3.18	4.31	
L	0.300	BSC	7.62	BSC	
М	M 0° 15		0 °	15°	
N	0.020	0.040	0.51	1.01	

PACKAGE DIMENSIONS



NOTES:

DIMENSIONING AND TOLERANCING PER ANSI Y14.5M. 1982.

CONTROLLING DIMENSION: INCH.

DIMENSION L TO CENTER OF LEADS WHEN 3

FORMED PARALLEL DIMENSION B DOES NOT INCLUDE MOLD FLASH. ROUNDED CORNERS OPTIONAL. 5.

	INC	HES	MILLIN	IETERS	
DIM	MIN MAX		MIN	MAX	
Α	A 0.740 (18.80	19.55	
В	3 0.250 0.270		6.35	6.85	
С	0.145	0.175	3.69	4.44	
D	0.015	0.021	0.39	0.53	
F	0.040	0.70	1.02	1.77	
G	0.100	BSC	2.54 BSC		
н	0.050	BSC	1.27 BSC		
J	0.008	0.015	0.21	0.38	
К	0.110	0.130	2.80	3.30	
L	0.295	0.305	7.50	7.74	
Μ	0°	10 °	0 °	10 °	
S	0.020	0.040	0.51	1.01	

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