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# Smart Front Corner Light Switch (Triple 10 mOhm and Dual 35 mOhm)

The 10XS3535 is designed for low voltage automotive and industrial lighting applications. Its five low  $R_{DS(ON)}$  MOSFETs (three 10 m $\Omega$ , two 35 m $\Omega$ ) can control the high sides of five separate resistive loads (bulbs, Xenon-HID modules and LEDs). This device is powered by SMARTMOS technology.

Programming, control and diagnostics are accomplished using a 16-bit SPI interface (3.3 V or 5.0 V). Each output has its own pulse-width modulation (PWM) control via the SPI. The 10XS3535 has highly sophisticated failure mode handling to provide high availability of the outputs. Its multiphase control and output edge shaping improves electromagnetic compatibility (EMC) behavior.

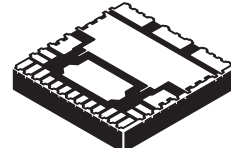
The 10XS3535 is packaged in a power-enhanced 12 x 12 mm nonleadless PQFN package with exposed tabs.

## Features

- Triple 10 m $\Omega$  and dual 35 m $\Omega$  high side switches
- 16-bit SPI communication interface with daisy chain capability
- Current sense output with SPI-programmable multiplex switch and board temperature feedback
- Digital diagnosis feature
- PWM module with multiphase feature including prescaler
- LEDs control including accurate current sensing and low duty-cycle capability
- Fully protected switches
- Over-current shutdown detection
- Power net and reverse polarity protection
- Low-power mode
- Fail mode functions including autorestart feature
- External smart power switch control including current recopy

10XS3535

HIGH SIDE SWITCH



**Bottom View**

<b>FK SUFFIX (Pb FREE)</b> 98ART10511D 24-PIN PQFN	<b>FK SUFFIX (Pb FREE)</b> 98ASA00426D 24-PIN PQFN
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ORDERING INFORMATION		
Device (For Tape and Reel, add R2 Suffix)	Temperature Range (T <sub>A</sub> )	Package
MC10XS3535HFK	-40 to 125 °C	24 PQFN
MC10XS3535DHFK		
* MC10XS3535JHFK		

\* Recommended for all new designs

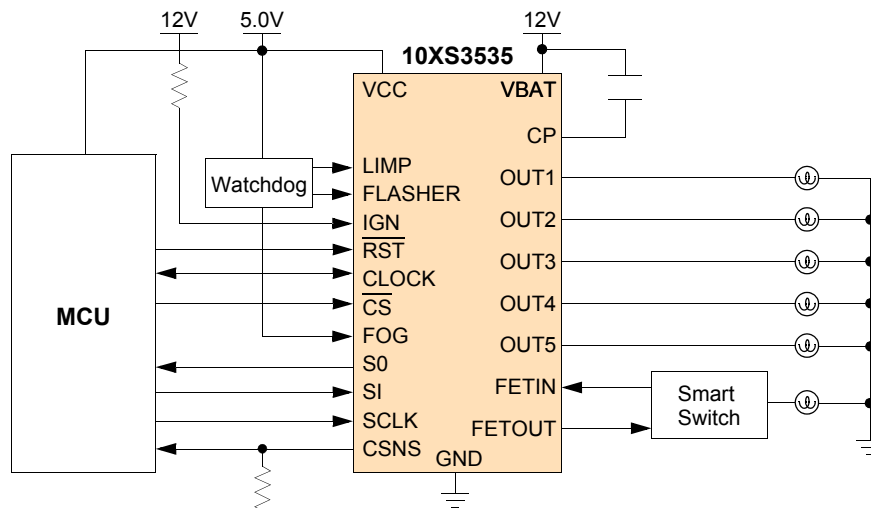


Figure 1. 10XS3535 Simplified Application Diagram

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## DEVICE VARIATIONS

**Table 1. MC10XS3535 Device Variations**

Part Number	Package	Temp.	Comment
MC10XS3535HFK	24 PQFN	-40 to 125 °C	Initial release
MC10XS3535DHFk	98ART10511D		D version is more robust against $V_{BAT}$ interrupt
MC10XS3535JHFK	24 PQFN 98ASA00426D		D version with enhancement MSL3 performance

### INTERNAL BLOCK DIAGRAM

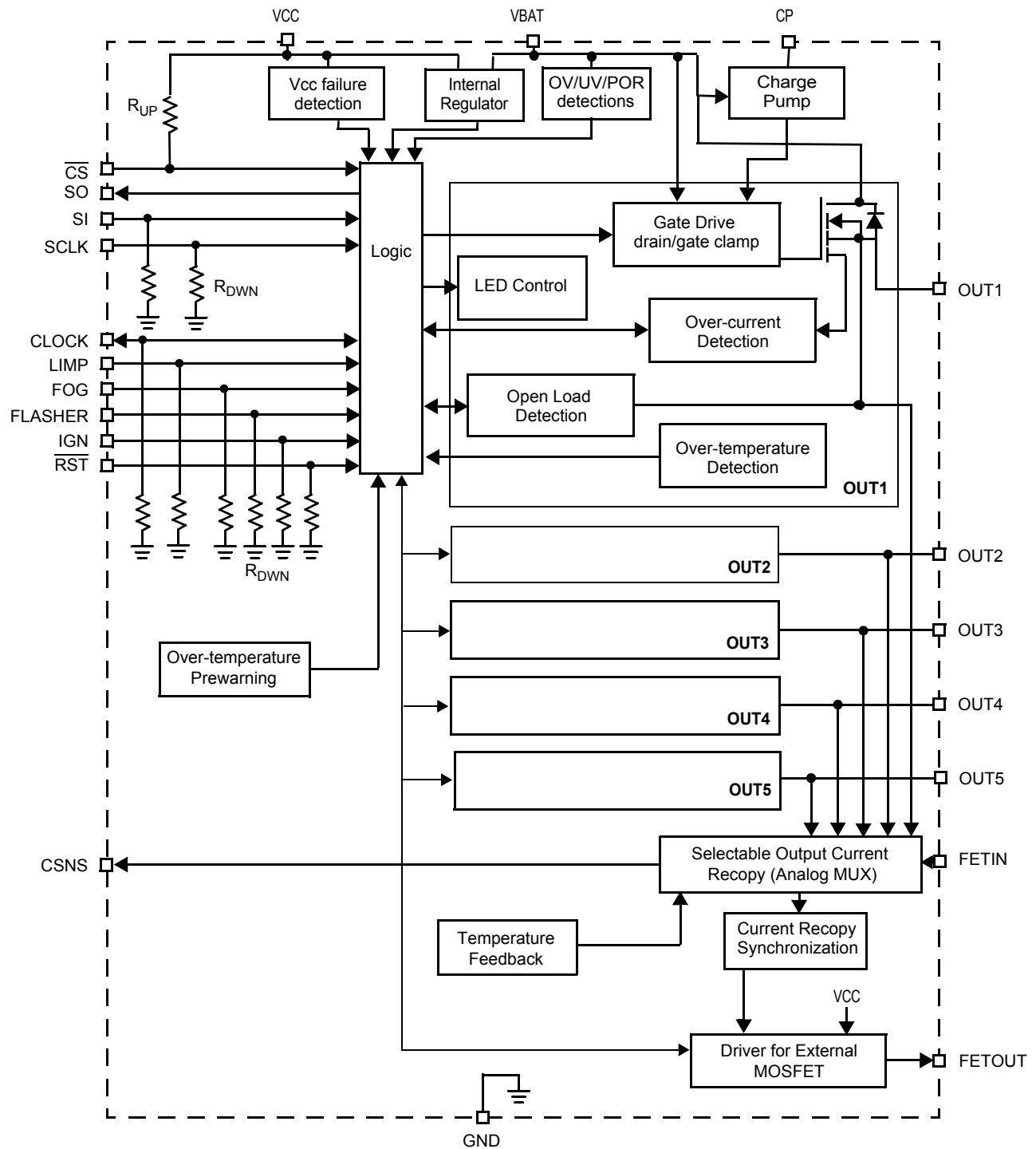


Figure 2. 10XS3535 Simplified Internal Block Diagram

### PIN CONNECTIONS

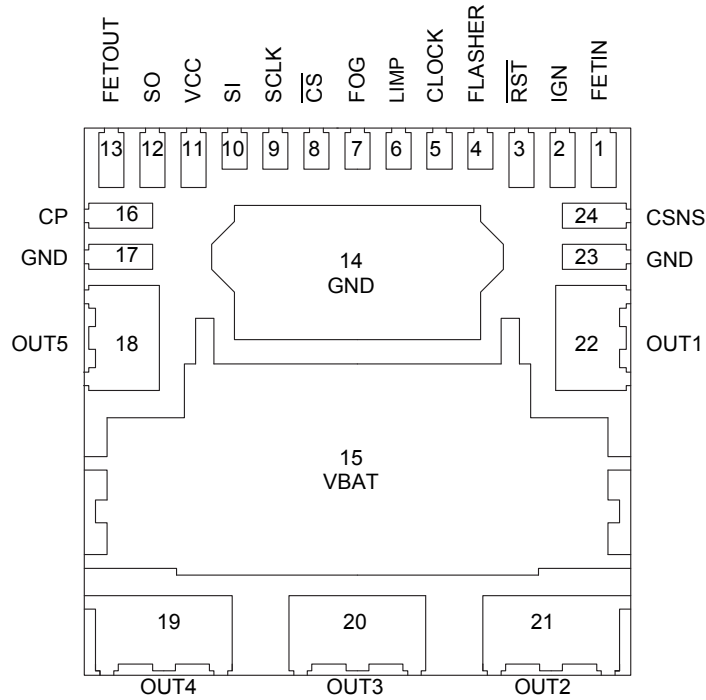


Figure 3. 10XS3535 Pin Connections (Transparent Top View Of Package)

Table 2. 10XS3535 Pin Definitions

A functional description of each pin can be found in the Functional Pin Description section beginning on [Page 20](#).

Pin Number	Pin Name	Pin Function	Formal Name	Definition
1	FETIN	Input	External FET Input	This pin is the current sense recopy of the external SMART MOSFET.
2	IGN	Input	Ignition Input (Active High)	This input wakes the device. It also controls the Outputs 1 and 2 in case of Fail mode activation. This pin has a passive internal pull-down.
3	$\overline{\text{RST}}$	Input	Reset	This input wakes the device. It is also used to initialize the device configuration and fault registers through SPI. This digital pin has a passive internal pull-down.
4	FLASHER	Input	Flasher Input (Active High)	This input wakes the device. This pin has a passive internal pull-down.
5	CLOCK	Input/Output	Clock Input	This pin state depends on $\overline{\text{RST}}$ logic level. As long as $\overline{\text{RST}}$ input pin is set to logic [0], this pin is pulled up in order to report wake event. Otherwise, the PWM frequency and timing are generated from this digital clock input by the PWM module. This pin has a passive internal pull-down.
6	LIMP	Input	Limp Home Input (Active High)	The Fail mode can be activated by this digital input. This pin has a passive internal pull-down.
7	FOG	Input	FOG Input (Active high)	This input wakes the device. This pin has a passive internal pull-down.
8	$\overline{\text{CS}}$	Input	Chip Select (Active Low)	When this digital signal is high, SPI signals are ignored. Asserting this pin low starts a SPI transaction. The transaction is signaled as completed when this signal returns high. This pin has a passive internal pull-up resistance.
9	SCLK	Input	SPI Clock Input	This digital input pin is connected to the master microcontroller providing the required bit shift clock for SPI communication. This pin has a passive internal pull-down resistance.



**Table 2. 10XS3535 Pin Definitions (continued)**

A functional description of each pin can be found in the Functional Pin Description section beginning on [Page 20](#).

Pin Number	Pin Name	Pin Function	Formal Name	Definition
10	SI	Input	Master-Out Slave-In	This data input is sampled on the positive edge of the SCLK. This pin has a passive internal pull-down resistance.
11	VCC	Power	Logic Supply	SPI Logic power supply.
12	SO	Output	Master-In Slave-Out	SPI data is sent to the MCU by this pin. This data output changes on the negative edge of SCLK and when CS is high, this pin is high-impedance.
13	FETOUT	Output	External FET Gate	This pin controls an external SMART MOSFET by logic level. This output is also called OUT6. If OUT6 is not used in the application, this output pin is set to logic high when the current sense output becomes valid when CSNS sync SPI bit is set to logic [1].
14,17,23	GND	Ground	Ground	This pin is the ground for the logic and analog circuitry of the device. <sup>(1)</sup>
15	VBAT	Power	Battery Input	Power supply pin.
16	CP	Output	Charge Pump	This pin is the connection for an external tank capacitor (for internal use only).
22 18	OUT1 OUT5	Output	Output 1 Output 5	Protected 35 mΩ high side power output to the load.
21 20 19	OUT2 OUT3 OUT4	Output	Output 2 Output 3 Output 4	Protected 10 mΩ high side power output to the load.
24	CSNS	Output	Current Sense Output	This pin is used to output a current proportional to OUT1:OUT5, FETin current, and it is used externally to generate a ground-referenced voltage for the microcontroller to monitor output current. Moreover, this pin can report a voltage proportional to the temperature on the GND flag. OUT1:OUT5, FETin current sensing and Temperature feedback choice is SPI programmable.

## Notes

1. The pins 14, 17 and 23 must be shorted on the board.

## ELECTRICAL CHARACTERISTICS

### **MAXIMUM RATINGS**

**Table 3. Maximum Ratings**

All voltages are with respect to ground unless otherwise noted. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Ratings	Symbol	Value	Unit
<b>ELECTRICAL RATINGS</b>			
Over-voltage Test Range (all OUT[1:5] ON with nominal DC current) Maximum Operating Voltage Load Dump (400 ms) @ 25 °C	$V_{BAT}$	28 40	V
Reverse Polarity Voltage Range (all OUT[1:5] ON with nominal DC current) 2.0 Min @ 25 °C	$V_{BAT}$	-18	V
VCC Supply Voltage	$V_{CC}$	-0.3 to 5.5	V
OUT[1:5] Voltage Positive Negative (ground disconnected)	$V_{OUT}$	40 -16	V
Digital Current in Clamping Mode (SI, SCLK, $\overline{CS}$ , $\overline{RST}$ , IGN, FLASHER, LIMP and FOG)	$I_{IN}$	$\pm 1.0$	mA
FETIN Input Current	$I_{FETIN}$	+10 -1.0	mA
SO, FETOUT, CLOCK and CSNS Outputs Voltage	$V_{SO}$	-0.3 to $V_{CC}+0.3$	V
Outputs clamp energy using single pulse method (L = 2 mH; R = 0 $\Omega$ ; $V_{BAT} = 14$ V @150°C initial) OUT[1,5] OUT[2:4]	$E_{1,5}$ $E_{2,3,4}$	30 100	mJ
ESD Voltage <sup>(2)</sup> Human Body Model (HBM) Human Body Model (HBM) OUT [1:5], VPWR, and GND Charge Device Model (CDM) Corner Pins (1, 13, 19, 21) All Other Pins (2-12, 14-18, 20, 22-24)	$V_{ESD}$	$\pm 2000$ $\pm 8000$ $\pm 750$ $\pm 500$	V

**Notes**

- ESD testing is performed in accordance with the Human Body Model (HBM) ( $C_{ZAP} = 100$  pF,  $R_{ZAP} = 1500$   $\Omega$ ) and the Charge Device Model.

**Table 3. Maximum Ratings (continued)**

All voltages are with respect to ground unless otherwise noted. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Ratings	Symbol	Value	Unit
<b>THERMAL RATINGS</b>			
Operating Temperature			°C
Ambient	$T_A$	-40 to 125	
Junction	$T_J$	-40 to 150	
Peak Package Reflow Temperature During Reflow <sup>(3), (4)</sup>	$T_{PPRT}$	Note 4	°C
Storage Temperature	$T_{STG}$	-55 to 150	°C
<b>THERMAL RESISTANCE</b>			
Thermal Resistance, Junction to Case <sup>(5)</sup>	$R_{\theta JC}$	1.0	°K/W

## Notes

- Pin soldering temperature limit is for 40 seconds maximum duration. Not designed for immersion soldering. Exceeding these limits may cause malfunction or permanent damage to the device.
- Freescle's Package Reflow capability meets Pb-free requirements for JEDEC standard J-STD-020C. For Peak Package Reflow Temperature and Moisture Sensitivity Levels (MSL), Go to [www.freescale.com](http://www.freescale.com), search by part number [e.g. remove prefixes/suffixes and enter the core ID to view all orderable parts. (i.e. MC33xxxD enter 33xxx), and review parametrics.
- Typical value guaranteed per design.



**STATIC ELECTRICAL CHARACTERISTICS**

**Table 4. Static Electrical Characteristics**

Characteristics noted under conditions  $3.0\text{ V} \leq V_{CC} \leq 5.5\text{ V}$ ,  $7.0\text{ V} \leq V_{BAT} \leq 20\text{ V}$ ,  $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$ ,  $\text{GND} = 0\text{ V}$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25\text{ }^\circ\text{C}$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>POWER INPUTS (VBAT, VCC)</b>					
Battery Supply Voltage Range Full Performance & Short Circuit Extended Voltage Range <sup>(6)</sup>	$V_{BAT}$	7.0 6.0	– –	20.0 28.0	V
Battery Supply Under-voltage (UV flag is set ON)	$V_{BATUV}$	5.0	5.5	6.0	V
Battery Supply Over-voltage (OV flag is set ON)	$V_{BATOV}$	27.5	30	32.5	V
Battery Voltage Clamp <sup>(9)</sup>	$V_{BATCLAMP}$	40	–	48	V
Battery Supply Power on Reset <sup>(10)</sup> If $V_{BAT} < 5.5\text{ V}$ , $V_{BAT} = V_{CC}$ If $V_{BAT} < 5.5\text{ V}$ , $V_{CC} = 0$	$V_{BATPOR1}$ $V_{BATPOR2}$	2.0 2.0	– –	3.0 4.0	V
VBAT Supply Current @ $25\text{ }^\circ\text{C}$ and $V_{BAT} = 12\text{ V}$ and $V_{CC} = 5\text{ V}$ Sleep State Current, Outputs Opened Sleep State Current, Outputs Grounded Normal Mode, $\text{IGN} = 5\text{ V}$ , $\text{RST} = 5\text{ V}$ , Outputs Open	$I_{BATSLEEP1}$ $I_{BATSLEEP2}$ $I_{BAT}$	– – –	0.5 0.5 10.0	5.0 5.0 20.0	$\mu\text{A}$ $\mu\text{A}$ mA
Digital Supply Voltage Range, Full Performance	$V_{CC}$	3.0	–	5.5	V
Digital Supply Undervoltage (VCC Failure)	$V_{CCUV}$	2.2	2.5	2.8	V
Sleep Current Consumption on $V_{CC}$ @ $25\text{ }^\circ\text{C}$ and $V_{BAT} = 12\text{ V}$ Output OFF	$I_{CCSLEEP}$	–	0.2	5.0	$\mu\text{A}$
Supply Current Consumption on $V_{CC}$ and $V_{BAT} = 12\text{ V}$ No SPI 3.0 MHz SPI Communication	$I_{CC}$	– –	– –	2.6 5.0	mA
<b>LOGIC INPUT/OUTPUT (IGN, CS, CSNS, SI, SCLK, CLOCK, SO, FLASHER, RST, LIMP, FOG)</b>					
Input High Logic Level <sup>(7)</sup>	$V_{IH}$	2.0	–	–	V
Input Low Logic Level <sup>(7)</sup>	$V_{IL}$	–	–	0.8	V
Voltage Threshold for wake-up (IGN, FLASHER, FOG and RST)	$V_{IGNTH}$	1.0	–	2.2	V
Input Clamp Voltage (IGN, FLASHER, LIMP, FOG, CS, SCLK, SI, RST) $I = 1.0\text{ mA}$	$V_{CL\_POS}$	7.5	–	13	V
Input Forward Voltage (IGN, FLASHER, LIMP, FOG, CS, SCLK, SI, RST) $I = -1.0\text{ mA}$	$V_{CL\_NEG}$	-2.0	–	-0.3	V
Input Passive Pull-up Resistance on CS input <sup>(8)</sup>	$R_{UP}$	100	200	400	$\text{k}\Omega$
Input Passive Pull-down Resistance on SI, SCLK, FLASHER, IGN, FOG, CLOCK, LIMP and RST pins <sup>(8)</sup>	$R_{DWN}$	100	200	500	$\text{k}\Omega$
SO High-state Output Voltage $I_{OH} = 1.0\text{ mA}$	$V_{SOH}$	0.8	0.95	–	$V_{CC}$
SO Low-state Output Voltage $I_{OL} = -1.6\text{ mA}$	$V_{SOL}$	–	0.2	0.4	V
CLOCK Output Voltage reporting wake-up event ( $I_{CLOCK} = 1.0\text{ mA}$ )	$V_{CLOCKH}$	0.8	0.95	–	$V_{CC}$

Notes

- In extended mode, the functionality is guaranteed but not the electrical parameters.
- Valid for RST, SI, SCLK, CS, CLOCK, IGN, FLASHER, FOG, and LIMP pins.
- Valid for the following input voltage range: -0.3 V to  $V_{CC} + 0.3\text{ V}$ .
- Outputs shorted to ground,  $I_{OUT} = +500\text{ mA}$  and  $I_{OUT} = \text{OCHI}$  (guaranteed by design).
- Please refer to [Loss of Supply Lines](#) section for more details.

**Table 4. Static Electrical Characteristics (continued)**

Characteristics noted under conditions  $3.0\text{ V} \leq V_{CC} \leq 5.5\text{ V}$ ,  $7.0\text{ V} \leq V_{BAT} \leq 20\text{ V}$ ,  $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$ ,  $GND = 0\text{ V}$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25\text{ }^\circ\text{C}$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>LOGIC INPUT/OUTPUT (IGN, CS, CSNS) (CONTINUED)</b>					
CSNS Tri-state Leakage Current VCC = 5.5 V, CSNS = 5.5 V VCC = 5.0 V, CSNS = 5.5 V VCC = 5.0 V, CSNS = 4.5 V	$I_{CSNSLEAK}$	-5.0 -10 -1.0	0 0 0	1.0 1.0 1.0	$\mu\text{A}$
Current Sense Output Clamp Voltage CSNS open and $I_{OUT[1:5]} = I_{FSR}$	$V_{CSNS}$	5.0	6.0	7.0	V
<b>OUTPUTS (OUT 1-5)</b>					
Output Leakage Current in OFF state Sleep mode, Outputs Grounded Normal mode, Outputs Grounded	$I_{OUTLEAK}$	- -	0 20	2.0 25	$\mu\text{A}$
Output Negative Clamp Voltage $I_{OUT} = -500\text{ mA}$ , Outputs OFF	$V_{OUT}$	-22.0	-	-16.0	V
Current Sense Output Precision <sup>(11)</sup> Full-Scale Range (FSR) for LED Control bit = 0 0.75 FSR 0.50 FSR 0.25 FSR 0.10 FSR Full-Scale Range for LED Control bit = 1 (OUT1 and OUT5 only) 0.187 FSR = $0.75\text{ FSR}_{LED}$ 0.125 FSR = $0.50\text{ FSR}_{LED}$ 0.062 FSR = $0.25\text{ FSR}_{LED}$ 0.025 FSR = $0.10\text{ FSR}_{LED}$	$\delta I_{CS}/I_{CS}$	-14 -15 -17 -22 -13 -13 -20 -30	- - - - - - - -	14 15 17 22 13 13 20 30	%

Notes

11.  $10\text{ V} < V_{BAT} < 16\text{ V}$ .  $\delta I_{CS}/I_{CS} = (\text{measured } I_{CS} - \text{targeted } I_{CS}) / \text{targeted } I_{CS}$  with targeted  $I_{CS} = 5\text{ mA}$

**Table 4. Static Electrical Characteristics (continued)**

Characteristics noted under conditions  $3.0\text{ V} \leq V_{CC} \leq 5.5\text{ V}$ ,  $7.0\text{ V} \leq V_{BAT} \leq 20\text{ V}$ ,  $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$ ,  $GND = 0\text{ V}$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25\text{ }^\circ\text{C}$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
Current Sense Output Precision with one calibration point (50% FSR, $V_{BAT} = 13.5\text{ V}$ at $25\text{ }^\circ\text{C}$ ) <sup>(13)</sup>		-6.0	–	6.0	%
Current Sense Output Precision with one calibration point (50% FSR <sub>LED</sub> , $V_{BAT} = 13.5\text{ V}$ at $25\text{ }^\circ\text{C}$ ) <sup>(13)</sup>		-6.0	–	6.0	%
Temperature Drift of Current Sense Output <sup>(12)</sup> $V_{BAT} = 13.5\text{ V}$ , $I_{OUT1,5} = 2.8\text{ A}$ , $I_{OUT2-4} = 5.5\text{ A}$ , reference taken at $T_A = 25\text{ }^\circ\text{C}$	$\Delta I_{CS}/\Delta T$	–	±280	±400	ppm/°C
Minimum Output Current Reported in CSNS for OUT[2-4] <sup>(15)</sup> $10\text{ V} \leq V_{BAT} \leq 16\text{ V}$	$I_{10MIN}(CSNS)$	250	–	–	mA
Minimum Output Current Reported in CSNS for OUT[1,5] <sup>(15)</sup> $10\text{ V} \leq V_{BAT} \leq 16\text{ V}$	$I_{35MIN}(CSNS)$	65	–	–	mA
Minimum Output Current Reported in CSNS for OUT[2-4] in LED Mode <sup>(15)</sup> $10\text{ V} \leq V_{BAT} \leq 16\text{ V}$	$I_{10MIN}(CSNS)_{LED}$	140	–	–	mA
Minimum Output Current Reported in CSNS for OUT[1,5] in LED Mode <sup>(15)</sup> $10\text{ V} \leq V_{BAT} \leq 16\text{ V}$	$I_{35MIN}(CSNS)_{LED}$	40	–	–	mA
Over-temperature Shutdown	$T_{OTS}$	155	175	195	°C
Thermal Prewarning <sup>(14)</sup>	$T_{OTSWARN}$	110	125	140	°C
Output Voltage Threshold	$V_{OUT\_TH}$	0.475	0.5	0.525	VBAT

Notes

12. Based on statistical data. Not production tested.  $\Delta I_{CS}/\Delta T = [( \text{measured } I_{CS} \text{ at } T_1 - \text{measured } I_{CS} \text{ at } T_2 ) / \text{measured } I_{CS} \text{ at room}] / (T_1 - T_2)$ .
13. Based on statistical analysis covering 99.74% of parts, except 10% of FSR. Please refer to [Current Sense](#) section for more details.
14. Parameter guaranteed by design; however, it is not production tested.
15. Output current value computed after leakage current removal (open load condition)

**Table 4. Static Electrical Characteristics (continued)**

Characteristics noted under conditions  $3.0\text{ V} \leq V_{CC} \leq 5.5\text{ V}$ ,  $7.0\text{ V} \leq V_{BAT} \leq 20\text{ V}$ ,  $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$ ,  $\text{GND} = 0\text{ V}$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25\text{ }^\circ\text{C}$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>PARKING LIGHT OUT1</b>					
Output Drain-to-Source ON Resistance ( $I_{OUT} = 2.8\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) $V_{BAT} = 13.5\text{ V}$ $V_{BAT} = 7.0\text{ V}$	$R_{DS(ON)25}$	–	–	35 55	$\text{m}\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 2.8\text{ A}$ , $V_{BAT} = 13.5\text{ V}$ , $T_A = 150\text{ }^\circ\text{C}$ ) <sup>(14)</sup>	$R_{DS(ON)150}$	–	–	59.5	$\text{m}\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 1.5\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) for LED Control = 1 $V_{BAT} = 13.5\text{ V}$ $V_{BAT} = 7.0\text{ V}$	$R_{DS(ON)25\_LED}$	–	–	70 110	$\text{m}\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 1.5\text{ A}$ , $V_{BAT} = 13.5\text{ V}$ , $T_A = 150\text{ }^\circ\text{C}$ ) for LED Control = 1 <sup>(14)</sup>	$R_{DS(ON)150\_LED}$	–	–	119	$\text{m}\Omega$
Reverse Output ON Resistance ( $I_{OUT} = -2.8\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) <sup>(16)</sup> $V_{BAT} = -12\text{ V}$	$R_{SD(ON)}$	–	–	70	$\text{m}\Omega$
High Over-current Shutdown Threshold 1 $V_{BAT} = 16\text{ V}$ , $T_A = -40\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 25\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 125\text{ }^\circ\text{C}$	$I_{OCH11}$	28.0 30.2 29.4 28.3	35.0 36.0 35.0 33.8	43.5 41.8 40.6 39.3	A

Notes

16. Source-to-Drain ON Resistance (Reverse Drain-to-Source ON Resistance) with negative polarity  $V_{BAT}$ .

**Table 4. Static Electrical Characteristics (continued)**

Characteristics noted under conditions  $3.0\text{ V} \leq V_{CC} \leq 5.5\text{ V}$ ,  $7.0\text{ V} \leq V_{BAT} \leq 20\text{ V}$ ,  $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$ ,  $GND = 0\text{ V}$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25\text{ }^\circ\text{C}$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>PARKING LIGHT OUT1 (CONTINUED)</b>					
High Over-current Shutdown Threshold 2	$I_{OCHI2}$	12.3	15.4	18.5	A
Low Over-current Shutdown Threshold	$I_{OCLO}$	5.7	7.2	8.9	A
Open Load-current Threshold in ON State <sup>(17)</sup>	$I_{OL}$	0.05	0.2	0.5	A
Open Load-current Threshold in ON State with LED <sup>(18)</sup> $V_{OUT} = V_{BAT} - 0.8\text{ V}$	$I_{OLLED}$	4.0	10.0	20.0	mA
Current Sense Full-Scale Range <sup>(19)</sup>	$I_{CS\ FSR}$	–	5.7	–	A
Current Sense Full-Scale Range <sup>(19)</sup> depending on LED Control = 1	$I_{CS\ FSR\_LED}$	–	1.6	–	A
Severe short-circuit impedance range <sup>(20)</sup>	$R_{SC1(OUT1)}$	350	–	–	m $\Omega$

**LOW BEAM OUT2**

Output Drain-to-Source ON Resistance ( $I_{OUT} = 5.5\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) $V_{BAT} = 13.5\text{ V}$ $V_{BAT} = 7.0\text{ V}$	$R_{DS(ON)}$	– –	– –	10 15	m $\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 5.5\text{ A}$ , $V_{BAT} = 13.5\text{ V}$ , $T_A = 150\text{ }^\circ\text{C}$ ) <sup>(20)</sup>	$R_{DS(ON)}$	–	–	17.0	m $\Omega$
Reverse Source-to-Drain ON Resistance ( $I_{OUT} = -5.5\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) <sup>(21)</sup> $V_{BAT} = -12\text{ V}$	$R_{SD(ON)}$	–	–	20	m $\Omega$
High Over-current Shutdown Threshold 1 $V_{BAT} = 16\text{ V}$ , $T_A = -40\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 25\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 125\text{ }^\circ\text{C}$	$I_{OCHI1}$	63.2 67.2 66.3 62.5	79.0 80.0 79.0 74.5	94.8 92.8 91.7 86.5	A
High Over-current Shutdown Threshold 2	$I_{OCHI2}$	26.2	32.8	39.4	A
Low Over-current Shutdown Threshold Optional Xenon Bulb Optional H7 Bulb	$I_{OCLO}$	17.6 12.1	22.0 15.2	26.4 18.3	A
Open Load Current Threshold in ON State <sup>(22)</sup>	$I_{OL}$	0.1	0.4	1.0	A
Open Load Current Threshold in ON State with LED <sup>(23)</sup> $V_{OL} = V_{BAT} - 0.8\text{ V}$	$I_{OLLED}$	4.0	10.0	20.0	mA
Current Sense Full-scale Range <sup>(24)</sup> Optional Xenon Bulb Optional H7 Bulb	$I_{CS\ FSR}$	– –	21.9 12.5	– –	A
Severe short-circuit impedance range <sup>(20)</sup>	$R_{SC1(OUT2)}$	100	–	–	m $\Omega$

Notes

17. OLLED1, bit D0 in SI data is set to [0].
18. OLLED1, bit D0 in SI data is set to [1].
19. For typical value of  $I_{CS\ FSR}$ ,  $I_{CSNS} = 5.0\text{ mA}$ . If the range is exceeded, no current clamp and the precision is no more guaranteed.
20. Parameter guaranteed by design; however, it is not production tested.
21. Source-to-Drain ON Resistance (Reverse Drain-to-Source ON Resistance) with negative polarity  $V_{BAT}$ .
22. OLLED2, bit D1 in SI data is set to [0].
23. OLLED2, bit D1 in SI data is set to [1].
24. For typical value of  $I_{CS\ FSR}$ ,  $I_{CSNS} = 5.0\text{ mA}$ . If the range is exceeded, no current clamp and the precision is no more guaranteed.

**Table 4. Static Electrical Characteristics (continued)**

Characteristics noted under conditions  $3.0\text{ V} \leq V_{CC} \leq 5.5\text{ V}$ ,  $7.0\text{ V} \leq V_{BAT} \leq 20\text{ V}$ ,  $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$ ,  $\text{GND} = 0\text{ V}$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25\text{ }^\circ\text{C}$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>HIGH BEAM OUT3</b>					
Output Drain-to-Source ON Resistance ( $I_{OUT} = 5.5\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) $V_{BAT} = 13.5\text{ V}$ $V_{BAT} = 7.0\text{ V}$	$R_{DS(ON)25}$	– –	– –	10 15	$\text{m}\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 5.5\text{ A}$ , $V_{BAT} = 13.5\text{ V}$ , $T_A = 150\text{ }^\circ\text{C}$ ) <sup>(25)</sup>	$R_{DS(ON)150}$	–	–	17.0	$\text{m}\Omega$
Reverse Source-to-Drain ON Resistance ( $I_{OUT} = -5.5\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) <sup>(26)</sup> $V_{BAT} = -12\text{ V}$	$R_{SD(ON)25}$	–	–	20	$\text{m}\Omega$
High Over-current Shutdown Threshold 1 $V_{BAT} = 16\text{ V}$ , $T_A = -40\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 25\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 125\text{ }^\circ\text{C}$	$I_{OCHI1}$	65.6 70.1 68.8 65.5	82.0 83.5 82.0 78.0	98.4 96.9 95.2 90.5	A
High Over-current Shutdown Threshold 2	$I_{OCHI2}$	27.5	34.4	41.3	A
Low Over-current Shutdown Threshold	$I_{OCLO}$	12.5	15.7	18.9	A
Open Load Current Threshold in ON State <sup>(27)</sup>	$I_{OL}$	0.1	0.4	1.0	A
Open Load Current Threshold in ON State with LED <sup>(28)</sup> $V_{OL} = V_{BAT} - 0.8\text{ V}$	$I_{OLLED}$	4.0	10.0	20.0	mA
Current Sense Full-scale Range <sup>(29)</sup>	$I_{CS\text{ FSR}}$	–	12.7	–	A
Severe short-circuit impedance range <sup>(25)</sup>	$R_{SC1(OUT3)}$	100	–	–	$\text{m}\Omega$

Notes

25. Parameter guaranteed by design; however, it is not production tested.
26. Source-to-Drain ON Resistance (Reverse Drain-to-Source ON Resistance) with negative polarity  $V_{BAT}$ .
27. OLLED3, bit D2 in SI data is set to [0].
28. OLLED3, bit D2 in SI data is set to [1].
29. For typical value of  $I_{CS\text{ FSR}}$ ,  $I_{CSNS} = 5.0\text{ mA}$ . If the range is exceeded, no current clamp and the precision is no more guaranteed.



**Table 4. Static Electrical Characteristics (continued)**

Characteristics noted under conditions  $3.0\text{ V} \leq V_{CC} \leq 5.5\text{ V}$ ,  $7.0\text{ V} \leq V_{BAT} \leq 20\text{ V}$ ,  $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$ ,  $\text{GND} = 0\text{ V}$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25\text{ }^\circ\text{C}$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>FOG LIGHT OUT4</b>					
Output Drain-to-Source ON Resistance ( $I_{OUT} = 5.5\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) $V_{BAT} = 13.5\text{ V}$ $V_{BAT} = 7.0\text{ V}$	$R_{DS(ON)25}$	–	–	10 15	$\text{m}\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 5.5\text{ A}$ , $V_{BAT} = 13.5\text{ V}$ , $T_A = 150\text{ }^\circ\text{C}$ ) <sup>(30)</sup>	$R_{DS(ON)150}$	–	–	17.0	$\text{m}\Omega$
Reverse Source-to-Drain ON Resistance ( $I_{OUT} = -5.5\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) <sup>(31)</sup> $V_{BAT} = -12\text{ V}$	$R_{SD(ON)25}$	–	–	20	$\text{m}\Omega$
High Over-current Shutdown Threshold 1 $V_{BAT} = 16\text{ V}$ , $T_A = -40\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 25\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 125\text{ }^\circ\text{C}$	$I_{OCHI1}$	63.2 67.2 66.3 62.5	79.0 80.0 79.0 74.5	94.8 92.8 91.7 86.5	A
High Over-current Shutdown Threshold 2	$I_{OCHI2}$	26.2	32.8	39.4	A
Low Over-current Shutdown Threshold	$I_{OCLO}$	12.1	15.2	18.3	A
Open Load Current Threshold in ON State <sup>(32)</sup>	$I_{OL}$	0.1	0.4	1.0	A
Open Load Current Threshold in ON State with LED <sup>(33)</sup> $V_{OL} = V_{BAT} - 0.8\text{ V}$	$I_{OLLED}$	4.0	10.0	20.0	mA
Current Sense Full-scale Range <sup>(34)</sup>	$I_{CS\text{ FSR}}$	–	12.5	–	A
Severe short-circuit impedance range <sup>(30)</sup>	$R_{SC1(OUT4)}$	100	–	–	$\text{m}\Omega$

**FLASHER OUTS**

Output Drain-to-Source ON Resistance ( $I_{OUT} = 2.8\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) $V_{BAT} = 13.5\text{ V}$ $V_{BAT} = 7.0\text{ V}$	$R_{DS(ON)25}$	–	–	35 55	$\text{m}\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 2.8\text{ A}$ , $V_{BAT} = 13.5\text{ V}$ , $T_A = 150\text{ }^\circ\text{C}$ ) <sup>(35)</sup>	$R_{DS(ON)150}$	–	–	59.5	$\text{m}\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 1.5\text{ A}$ , $T_A = 25\text{ }^\circ\text{C}$ ) for LED Control = 1 $V_{BAT} = 13.5\text{ V}$ $V_{BAT} = 7.0\text{ V}$	$R_{DS(ON)25\_LED}$	–	–	70 110	$\text{m}\Omega$
Output Drain-to-Source ON Resistance ( $I_{OUT} = 1.5\text{ A}$ , $V_{BAT} = 13.5\text{ V}$ , $T_A = 150\text{ }^\circ\text{C}$ ) for LED Control = 1 <sup>(35)</sup>	$R_{DS(ON)150\_LED}$	–	–	119	$\text{m}\Omega$
Reverse Source-to-Drain ON Resistance ( $I_{OUT} = -2.8\text{ A}$ , $T_J = 25\text{ }^\circ\text{C}$ ) <sup>(36)</sup> $V_{BAT} = -12\text{ V}$	$R_{SD(ON)25}$	–	–	70	$\text{m}\Omega$

Notes

30. Parameter guaranteed by design; however, it is not production tested.
31. Source-to-Drain ON Resistance (Reverse Drain-to-Source ON Resistance) with negative polarity  $V_{BAT}$ .
32. OLLED4, bit D3 in SI data is set to [0].
33. OLLED4, bit D3 in SI data is set to [1].
34. For typical value of  $I_{CS\text{ FSR}}$ ,  $I_{CSNS} = 5.0\text{ mA}$ . If the range is exceeded, no current clamp and the precision is no more guaranteed.

**Table 4. Static Electrical Characteristics (continued)**

Characteristics noted under conditions  $3.0\text{ V} \leq V_{CC} \leq 5.5\text{ V}$ ,  $7.0\text{ V} \leq V_{BAT} \leq 20\text{ V}$ ,  $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$ ,  $GND = 0\text{ V}$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25\text{ }^\circ\text{C}$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>FLASHER OUT5 (CONTINUED)</b>					
High Over-current Shutdown Threshold 1 $V_{BAT} = 16\text{ V}$ , $T_A = -40\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 25\text{ }^\circ\text{C}$ $V_{BAT} = 16\text{ V}$ , $T_A = 125\text{ }^\circ\text{C}$	$I_{OCHI1}$	28.0 30.2 29.4 28.3	35.0 36.0 35.0 33.8	43.5 41.8 40.6 39.3	A
High Over-current Shutdown Threshold 2	$I_{OCHI2}$	12.3	15.4	18.5	A
Low Over-current Shutdown Threshold	$I_{OCLO}$	5.7	7.2	8.9	A
Open Load Current Threshold in ON State <sup>(38)</sup>	$I_{OL}$	0.05	0.2	0.5	A
Open Load Current Threshold in ON State with LED <sup>(38)</sup> $V_{OL} = V_{BAT} - 0.8\text{ V}$	$I_{OLLED}$	4.0	10.0	20.0	mA
Current Sense Full-Scale Range <sup>(39)</sup>	$I_{CS\text{ FSR}}$	–	5.7	–	A
Current Sense Full-Scale Range <sup>(19)</sup> depending on LED Control = 1	$I_{CS\text{ FSR\_LED}}$	–	1.6	–	A
Severe short-circuit impedance range <sup>(35)</sup>	$R_{SC1(OUT5)}$	350	–	–	m $\Omega$
<b>SPARE FETOUT / FETIN</b>					
FETOUT Output High Level @ $I = 1.0\text{ mA}$	$V_{H\text{ MAX}}$	0.8	–	–	$V_{CC}$
FETOUT Output Low Level @ $I = -1.0\text{ mA}$	$V_{H\text{ MIN}}$	–	0.2	0.4	V
FETIN Input Full Scale Range Current	$I_{FETIN}$	–	5.0	–	mA
FETIN Input Clamp Voltage $I_{FET\text{ IN}} = 5\text{ mA}$ , CSNS open	$V_{CLIN}$	5.3	–	13	V
Drop Voltage between FETIN and CSNS for MUX[2:0]=110 $I_{FETIN} = 5\text{ mA}$ , $5.5\text{ V} > CSNS > 0.0\text{ V}$	$V_{DRIN}$	0.0	–	0.4	V
FETIN Leakage Current when external current switch sense is enabled $V_{CC} > V_{FETIN} > 0\text{ V}$ , $5.5\text{ V} > V_{CC} > 4.5\text{ V}$ , CSNS open $V_{CC} > V_{FETIN} > 0\text{ V}$ , $4.5\text{ V} > V_{CC} > 0$ , CSNS open	$I_{FETINLEAK}$	-1.0 -1.0	– –	5.0 1.0	$\mu\text{A}$
<b>TEMPERATURE OF GND FLAG</b>					
Analog Temperature Feedback Range	$T_{FEED\_RANGE}$	-40		150	$^\circ\text{C}$
Analog Temperature Feedback at $T_A = 25\text{ }^\circ\text{C}$ with $5.0\text{ k}\Omega > R_{CSNS} > 500\text{ }\Omega$	$V_{T\_FEED}$	920	1025	1140	mV
Analog Temperature Feedback Derating with $5.0\text{ k}\Omega > R_{CSNS} > 500\text{ }\Omega$ <sup>(35)</sup>	$V_{DT\_FEED}$	10.9	11.3	11.7	mV/ $^\circ\text{C}$
Analog Temperature Feedback Precision <sup>(35)</sup>	$V_{DT\_ACC}$	-15	–	15	$^\circ\text{C}$
Analog Temperature Feedback Precision with calibration point at $25\text{ }^\circ\text{C}$ <sup>(35)</sup>	$V_{DT\_ACC\_CAL}$	-5.0	–	5.0	$^\circ\text{C}$

Notes

- 35. Parameter guaranteed by design; however, it is not production tested.
- 36. Source-to-Drain ON Resistance (Reverse Drain-to-Source ON Resistance) with negative polarity  $V_{BAT}$ .
- 37. OLLED5, bit D4 in SI data is set to [0].
- 38. OLLED5, bit D4 in SI data is set to [1].
- 39. For typical value of  $I_{CS\text{ FSR}}$ ,  $I_{CSNS} = 5.0\text{ mA}$ . If the range is exceeded, no current clamp and the precision is no more guaranteed.

**DYNAMIC ELECTRICAL CHARACTERISTICS**

**Table 5. Dynamic Electrical Characteristics**

Characteristics noted under conditions  $3.0V \leq V_{CC} \leq 5.5V$ ,  $7.0V \leq V_{BAT} \leq 20V$ ,  $-40^{\circ}C \leq T_A \leq 125^{\circ}C$ ,  $GND = 0V$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25^{\circ}C$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>POWER OUTPUTS TIMING (OUT1 TO OUT5)</b>					
Current Sense Valid Time on resistive load only <sup>(40)</sup> SR bit = 0 SR bit = 1	$t_{CSNS(VAL)}$	– –	90 45	150 75	$\mu s$
Current Sense Synchronization Time on FETOUT SR bit = 0 SR bit = 1	$t_{CSNS(SYNC)}$	– –	130 70	185 110	$\mu s$
Current Sense Settling Time on resistive load only <sup>(40)</sup>	$t_{CSNS(SET)}$	–	10	30	$\mu s$
Driver Output Positive Slew Rate (30% to 70% @ $V_{BAT} = 14 V$ ) SR bit = 0 $I_{OUT} = 2.8 A$ for OUT1 and OUT5 $I_{OUT} = 5.5 A$ for OUT2, OUT3, and OUT4 SR bit = 1 $I_{OUT} = 0.7 A$ for OUT1 and OUT5 $I_{OUT} = 1.4 A$ for OUT2, OUT3, and OUT4	$SR_R$	0.10 0.14 0.20 0.30	0.25 0.30 0.40 0.55	0.56 0.56 0.80 1.05	$V/\mu s$
Driver Output Negative Slew Rate (70% to 30% @ $V_{BAT} = 14 V$ ) SR bit = 0 $I_{OUT} = 2.8 A$ for OUT1 and OUT5 $I_{OUT} = 5.5 A$ for OUT2, OUT3, and OUT4 SR bit = 1 $I_{OUT} = 0.7 A$ for OUT1 and OUT5 $I_{OUT} = 1.4 A$ for OUT2, OUT3, and OUT4	$SR_F$	0.10 0.14 0.20 0.30	0.25 0.30 0.40 0.55	0.56 0.56 0.80 1.05	$V/\mu s$
Driver Output Matching Slew Rate ( $SR_R / SR_F$ ) (70% to 30% @ $V_{BAT} = 14 V$ @ $25^{\circ}C$ ) SR bit = 0: $I_{OUT} = 2.8 A$ for OUT1 and OUT5 and $I_{OUT} = 5.5 A$ for OUT2/3/4 SR bit = 1: $I_{OUT} = 0.7 A$ for OUT1 and OUT5 and $I_{OUT} = 1.4 A$ for OUT2/3/4	$\Delta SR$	0.8 0.8	1.0 1.0	1.2 1.2	
Driver Output Turn-ON Delay (SPI ON Command [No PWM, $\overline{CS}$ Positive Edge] to Output = 50% $V_{BAT}$ @ $V_{BAT} = 14 V$ ) (see Figure 6) SR bit = 0: $I_{OUT} = 2.8 A$ for OUT1 and OUT5 and $I_{OUT} = 5.5 A$ for OUT2/3/4 SR bit = 1: $I_{OUT} = 0.7 A$ for OUT1 and OUT5 and $I_{OUT} = 1.4 A$ for OUT2/3/4	$t_{DLYON}$	50 25	– –	120 65	$\mu s$
Driver Output Turn-OFF Delay (SPI OFF command [ $\overline{CS}$ Positive Edge] to Output = 50% $V_{BAT}$ @ $V_{BAT} = 14 V$ ) (see Figure 6) SR bit = 0: $I_{OUT} = 2.8 A$ for OUT1 and OUT5 and $I_{OUT} = 5.5 A$ for OUT2/3/4 SR bit = 1: $I_{OUT} = 0.7 A$ for OUT1 and OUT5 and $I_{OUT} = 1.4 A$ for OUT2/3/4	$t_{DLYOFF}$	50 25	– –	120 65	$\mu s$

Notes

40. Not production tested.

**Table 5. Dynamic Electrical Characteristics**

Characteristics noted under conditions  $3.0V \leq V_{CC} \leq 5.5V$ ,  $7.0V \leq V_{BAT} \leq 20V$ ,  $-40^{\circ}C \leq T_A \leq 125^{\circ}C$ ,  $GND = 0V$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25^{\circ}C$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
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**POWER OUTPUTS TIMING (OUT1 TO OUT5) (CONTINUED)**

Driver Output Matching Time ( $t_{DLY(ON)} - t_{DLY(OFF)}$ ) @ Output = 50% $V_{BAT}$ with $V_{BAT} = 14V$ , $f_{PWM} = 240Hz$ , $\delta_{PWM} = 50\%$ , @ $25^{\circ}C$	$\Delta t_{RF}$				$\mu s$
SR bit = 0: $I_{OUT} = 2.8A$ for OUT1 and OUT5 and $I_{OUT} = 5.5A$ for OUT2/3/4		-30	–	30	
SR bit = 1: $I_{OUT} = 0.7A$ for OUT1 and OUT5 and $I_{OUT} = 1.4A$ for OUT2/3/4		-15	–	15	

**PWM MODULE**

Nominal PWM Frequency Range <sup>(41)</sup>	$f_{PWM}$	30.0	–	400	Hz
Clock Input Frequency Range	$f_{CLK}$	7.68	–	51.2	kHz
Output PWM Duty Cycle maximum range for $11V < V_{BAT} < 18V$ <sup>(41), (42)</sup>	PWM_MAX	4.0	–	96	%
Output PWM Duty Cycle linear range for $11V < V_{BAT} < 18V$ <sup>(43)</sup>	PWM_LIN	5.5	–	96	%
Output PWM Duty Cycle range for full diagnostic for $11V < V_{BAT} < 18V$ <sup>(44)</sup>	PWM_DIAG				%
200 Hz Output PWM frequency		5.5	–	96	
400 Hz Output PWM frequency		11	–	90	

Notes

41. Not production tested.
42. The PWM ratio is measured at  $V_{OUT} = 50\%$  of  $V_{BAT}$  in nominal range of PWM frequency. It is possible to put the device fully on (PWM duty cycle = 100%) and fully off (PWM duty cycle = 0%). Between 4%-96%, OCHI<sub>1,2</sub>, OCLO and open load are available in ON state. See [Figure 6. Output Slew Rate and Time Delays](#).
43. Linear range is defined by output duty cycle to SPI duty cycle configuration +/-1 LSB. For values outside linear duty cycle range, a calibration curve is available.
44. Full diagnostic corresponds to the availability of the following features: output current sensing, output status and open load detection. Not production tested.

**Table 5. Dynamic Electrical Characteristics**

Characteristics noted under conditions  $3.0V \leq V_{CC} \leq 5.5V$ ,  $7.0V \leq V_{BAT} \leq 20V$ ,  $-40^{\circ}C \leq T_A \leq 125^{\circ}C$ ,  $GND = 0V$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25^{\circ}C$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>WATCHDOG TIMING</b>					
Watchdog Timeout (SPI Failure)	$t_{WDTO}$	50	75	100	ms
<b>I/O PLAUSIBILITY CHECK TIMING</b>					
Fault Shutdown Delay Time (from Overtemperature or OCHI1 or OCHI2 or OCLO or UV Fault Detection to Output = 50% $V_{BAT}$ without round shaping feature for turn off)	$t_{SD}$	–	7.0	30	$\mu s$
Under-voltage Deglitch Time <sup>(45)</sup>	$t_{UV}$	0.8	1.25	2.0	$\mu s$
High Over-current Threshold Time 1 for OUT1 and OUT5 for OUT2, OUT3, and OUT4	$t_1$	7.0 14	10 20	13.5 26	ms
High Over-current Threshold Time 2 for OUT1 and OUT5 for OUT2, OUT3, and OUT4	$t_2$	52.5 105	75 150	97.5 195	ms
Autorestart Period for OUT1 and OUT5 for OUT2, OUT3, and OUT4	$t_{AUTORST}$	52.5 105	75 150	97.5 195	ms
Autorestart Over-current Shutdown Delay Time for OUT1 and OUT5 for OUT2, OUT3, and OUT4	$t_{OCHI\_AUTO}$	3.5 7.0	5.0 10.0	6.5 13.0	ms
Limp Home Input pin Deglitcher Time	$t_{LIMP}$	7.0	10.0	13.0	ms
Cyclic Open Load Detection Timing with LED <sup>(46)</sup>	$t_{OLLED}$	105	150	195	ms
Flasher Toggle Timeout	$t_{FLASHER}$	1.4	2.3	3.0	s
Fog Toggle Timeout	$t_{FOG}$	1.4	2.3	3.0	s
Ignition Toggle Timeout	$t_{IGNITION}$	1.4	2.3	3.0	s
Clock Input Low Frequency Detection Range	$f_{LCLK\ DET}$	1.0	2.0	4.0	kHz
Clock Input High Frequency Detection Range	$f_{HCLK\ DET}$	100	200	400	kHz

Notes

- 45. This time is measured from the  $V_{BAT(UV)}$  level to the fault reporting. Parameter guaranteed in testmode.
- 46. IOLLEDn bit (where “n” corresponds to respective outputs 1 through 5) in SI data is set to logic [1]. Refer to [Table 8, Serial Input Address and Configuration Bit Map](#), page 29.

**Table 5. Dynamic Electrical Characteristics**

Characteristics noted under conditions  $3.0V \leq V_{CC} \leq 5.5V$ ,  $7.0V \leq V_{BAT} \leq 20V$ ,  $-40^{\circ}C \leq T_A \leq 125^{\circ}C$ ,  $GND = 0V$ , unless otherwise noted. Typical values noted reflect the approximate parameter means at  $T_A = 25^{\circ}C$  under nominal conditions, unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>SPI INTERFACE CHARACTERISTICS</b>					
Maximum Frequency of SPI Operation	$f_{SPI}$	–	–	3.0	MHz
Rising Edge of $\overline{CS}$ to Falling Edge of $\overline{CS}$ (Required Setup Time) <sup>(47)</sup>	$t_{\overline{CS}}$	–	–	1.0	us
Falling Edge of $\overline{CS}$ to Rising Edge of SCLK (Required Setup Time) <sup>(47)</sup>	$t_{LEAD}$	–	–	500	ns
Required High State Duration of SCLK (Required Setup Time) <sup>(47)</sup>	$t_{WSCLKH}$	–	–	167	ns
Required Low State Duration of SCLK (Required Setup Time) <sup>(47)</sup>	$t_{WSCLKL}$	–	–	167	ns
Falling Edge of SCLK to Rising Edge of $\overline{CS}$ (Required Setup Time) <sup>(47)</sup>	$t_{LAG}$	–	50	167	ns
SI to Falling Edge of SCLK (Required Setup Time) <sup>(48)</sup>	$t_{SI(SU)}$	–	25	83	ns
Falling Edge of SCLK to SI (Required Setup Time) <sup>(48)</sup>	$t_{SIHOLD}$	–	25	83	ns
SO Rise Time $C_L = 80$ pF	$t_{RSO}$	–	25	50	ns
SO Fall Time $C_L = 80$ pF	$t_{FSO}$	–	25	50	ns
SI, $\overline{CS}$ , SCLK, Incoming Signal Rise Time <sup>(48)</sup>	$t_{RSI}$	–	–	50	ns
SI, $\overline{CS}$ , SCLK, Incoming Signal Fall Time <sup>(48)</sup>	$t_{FSI}$	–	–	50	ns
Time from Falling Edge of SCLK to SO Low-impedance <sup>(49)</sup>	$t_{SO(EN)}$	–	–	145	ns
Time from Rising Edge of SCLK to SO High-impedance <sup>(50)</sup>	$t_{SO(DIS)}$	–	65	145	ns

Notes

47. Maximum setup time required for the 10XS3535 is the minimum guaranteed time needed from the microcontroller.
48. Rise and Fall time of incoming SI,  $\overline{CS}$ , and SCLK signals suggested for design consideration to prevent the occurrence of double pulsing.
49. Time required for output status data to be available for use at SO. 1.0 k $\Omega$  on pull-up on  $\overline{CS}$ .
50. Time required for output status data to be terminated at SO. 1.0 k $\Omega$  on pull-up on  $\overline{CS}$ .



TIMING DIAGRAMS

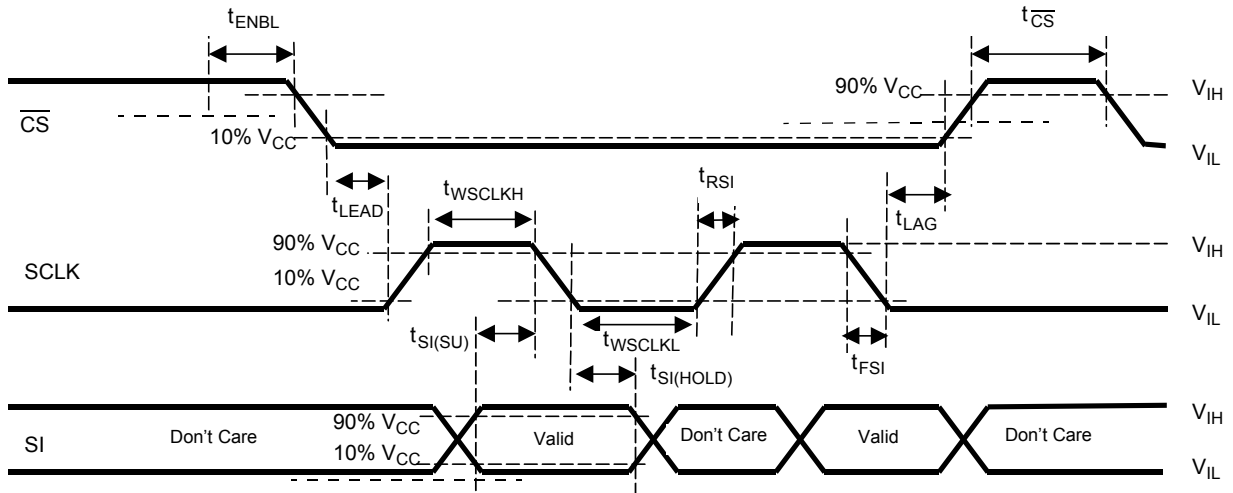


Figure 4. Input Timing Switching Characteristics

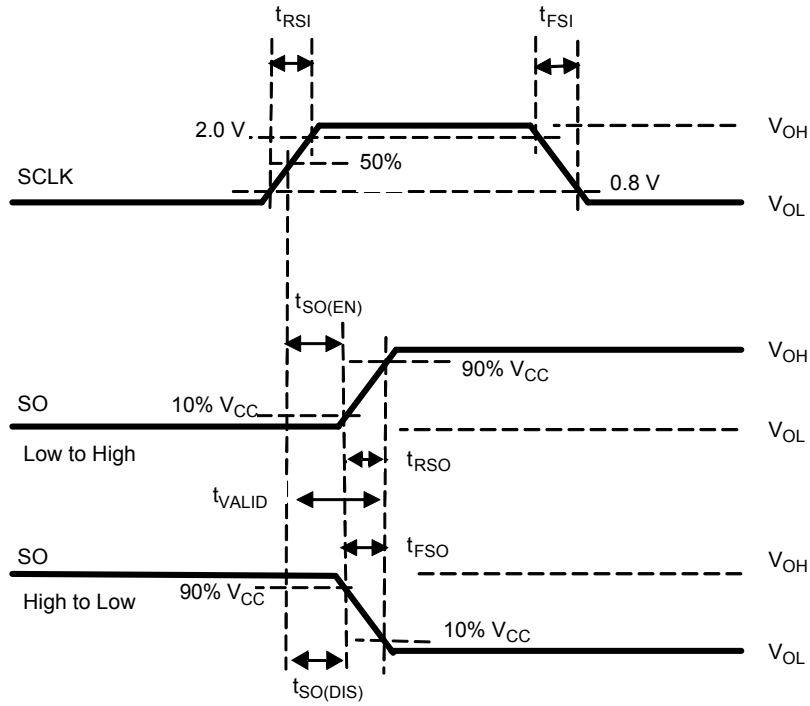


Figure 5. SCLK Waveform and Valid SO Data Delay Time

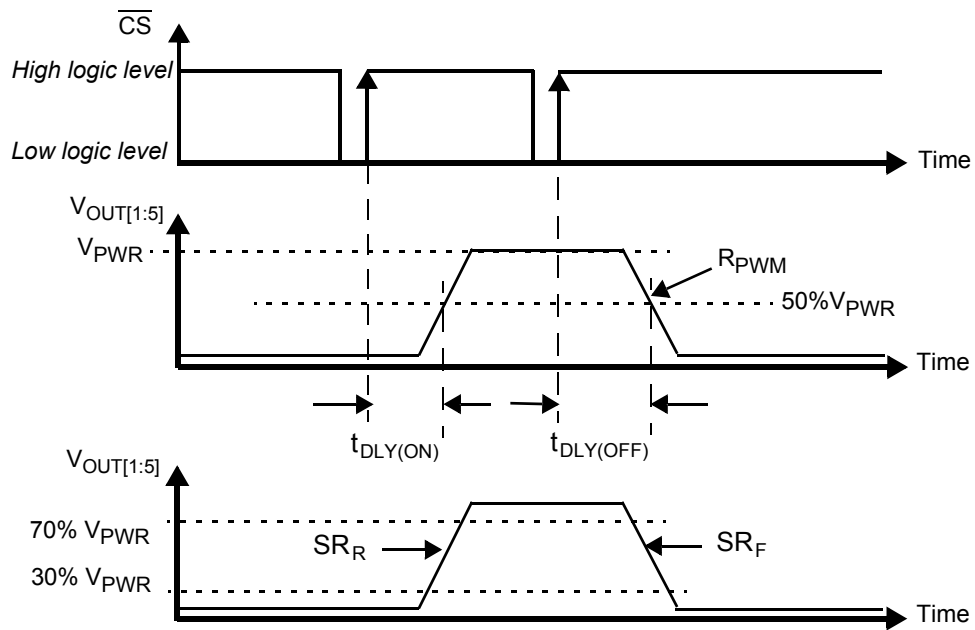


Figure 6. Output Slew Rate and Time Delays

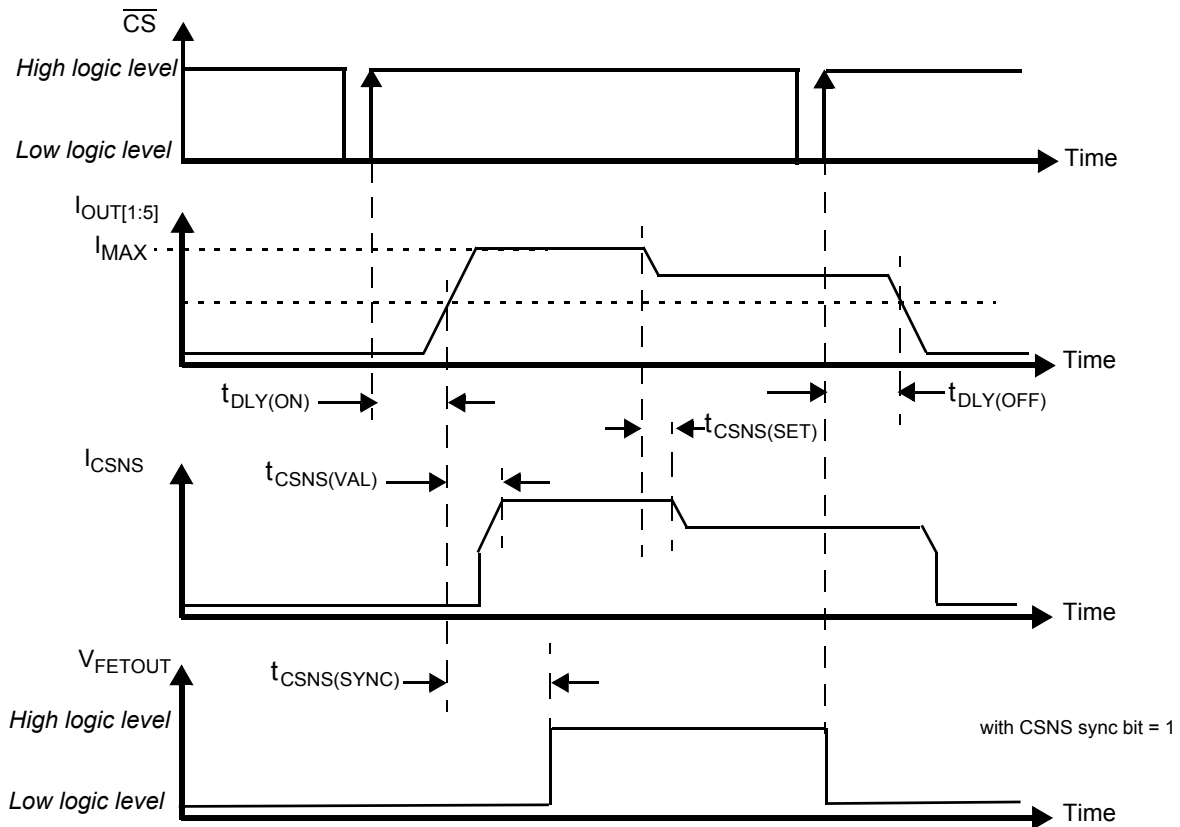


Figure 7. Current Sensing Time Delays

## FUNCTIONAL DESCRIPTION

### INTRODUCTION

The 10XS3535 is designed for low-voltage automotive and industrial lighting applications. Its five low  $R_{DS(ON)}$  MOSFETs (three 10 m $\Omega$  and two 35 m $\Omega$ ) can control the high sides of

five separate resistive loads (bulbs). Programming, control, and diagnostics are accomplished using a 16-bit SPI interface.

### FUNCTIONAL PIN DESCRIPTION

#### SUPPLY VOLTAGE (VBAT)

The VBAT pin of the 10XS3535 is the power supply of the device. In addition to its supply function, this tab contributes to the thermal behavior of the device by conducting the heat from the switching MOSFETs to the printed circuit board.

#### SUPPLY VOLTAGE (VCC)

This is an external voltage input pin used to supply the digital portion of the circuit and the gate driver of the external SMART MOSFET.

#### GROUND (GND)

This pin is the ground of the device.

#### CLOCK INPUT / WAKE-UP OUTPUT (CLOCK)

When the part is in Normal Mode ( $\overline{RST}=1$ ), the PWM frequency and timing are generated from the rising edge of clock input by the PWM module. The clock input frequency is the selectable factor  $2^7 = 128$  or  $2^8 = 256$  of the PWM frequency per output, depending PR bit value.

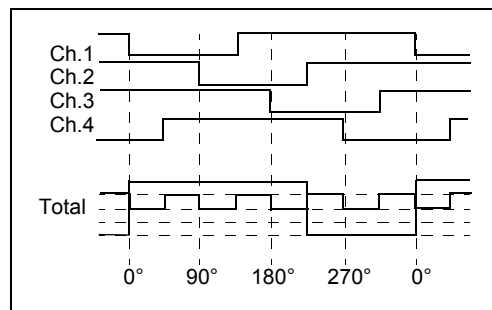
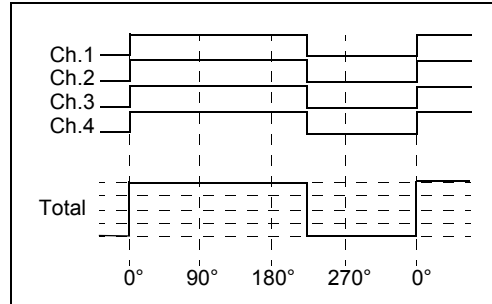
The OUT1:6 can be controlled in the range of 4% to 96% with a resolution of 7 bits of duty cycle (bits D[6:0]).

The following table describes the PWM resolution.

On/Off (Bit D7)	Duty cycle (7 bits resolution)	Output state
0	X	OFF
1	0000000	PWM (1/128 duty cycle)
1	0000001	PWM (2/128 duty cycle)
1	0000010	PWM (3/128 duty cycle)
1	1111111	fully ON

The timing includes four programmable PWM switching phases (0°, 90°, 180°, and 270°) to improve overall EMC behavior of the light module.

The amplitude of the input current is divided by four while the frequency is 4 times the original one. The two following pictures illustrate this behavior.



The synchronization of the switching phases between different IC is provided by an SPI command in combination with the  $\overline{CS}$  input. The bit in the SPI is called PWM sync (initialization register).

In Normal mode, no PWM feature (100% duty cycle) is provided in the following instances:

- with the following SPI configuration: D7:D0=FF.
- In case of clock input signal failure (out of  $f_{PWM}$ ), the outputs state depends of D7 bit value (D7=1=ON) in Normal mode.

In Fail mode, the outputs state depend on IGN, FLASHER, and FOG pins.

If  $\overline{RST}=0$ , this pin reports the wake-up event for wake=1 when VBAT and VCC are in operational voltage range.

#### LIMP HOME INPUT (LIMP)

The Fail mode of the component can be activated by this digital input port. The signal is "high active", meaning the Fail mode can be activated by a logic high signal at the input.

**IGNITION INPUT (IGN)**

The ignition input wakes the device. It also controls the Fail mode activation. The signal is “high active”, meaning the component is active in case of a logic high at the input.

**FLASHER INPUT (FLASHER)**

The flasher input wakes the device. It also controls the Fail Mode activation. The signal is “high active”, meaning the component is active in case of a logic high at the input.

**FOG INPUT (FOG)**

The fog input wakes the device. It also controls the Fail Mode activation. The signal is “high active”, meaning the component is active in case of a logic high at the input.

**RESET INPUT ( $\overline{\text{RST}}$ )**

This input wakes the device when the  $\overline{\text{RST}}$  pin is at logic [1]. It is also used to initialize the device configuration and the SPI faults registers when the signal is low. All SI/SO registers described [Table 8](#) and [Table 11](#) are reset. The fault management is not affected by  $\overline{\text{RST}}$ .

**CURRENT SENSE OUTPUT (CSNS)**

The current sense output pin is an analog current output or a voltage proportional to the temperature on the GND flag. The routing to the external resistor is SPI programmable.

This current sense monitoring may be synchronized in case of the OUT6 is not used. So, the current sense monitoring can be synchronized with a rising edge on the FETOUT pin ( $t_{\text{CSNS(SYNC)}}$ ) if CSNS sync SPI bit is set to logic [1]. Connection of the FETOUT-pin to a MCU input pin allows the MCU to sample the CSNS-pin during a valid time-slot. Since this falling edge is generated at the end of this time-slot, upon a switch-off command, this feature may be used to implement maximum current control.

**CHARGE PUMP (CP)**

An external capacitor is connected between this pin and the VBAT pin. It is used as a tank for the internal charge pump. Its value is 100 nF  $\pm$ 20%, 25 V maximum.

**FETOUT OUTPUT (FETOUT)**

This output pin is used to control an external MOSFET (OUT6).

The high level of the FETOUT Output is  $V_{\text{CC}}$ , if VBAT and  $V_{\text{CC}}$  are available, in case FETOUT is a controlled ON.

FETOUT is not protected if there is a short-circuit or under-voltage on VBAT.

In case of a reverse battery, OUT6 is OFF.

**FETIN INPUT (FETIN)**

This input pin gives the current recopy of the external MOSFET. It can be routed on CSNS output by a SPI command.

**SPI PROTOCOL DESCRIPTION**

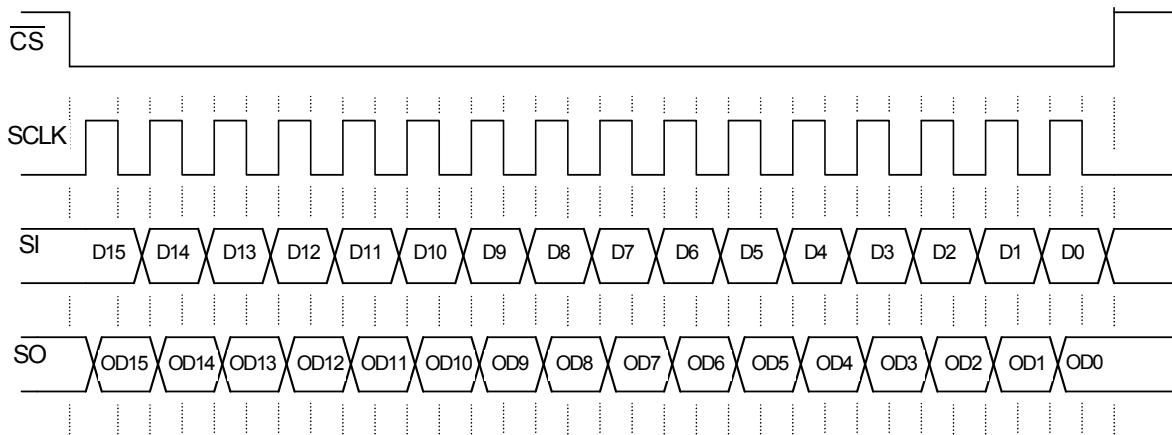
The SPI interface has a full-duplex, three-wire, synchronous data transfer with four I/O lines associated with it: Serial Clock (SCLK), Serial Input (SI), Serial Output (SO), and Chip Select ( $\overline{\text{CS}}$ ).

The SI/SO pins of the 10XS3535 device follow a first-in, first-out (D15 to D0) protocol, with both input and output words transferring the most significant bit (MSB) first. All inputs are compatible with 3.3 V and 5.0 V CMOS logic levels, supplied by  $V_{\text{CC}}$ .

The SPI lines perform the following functions:

**SERIAL CLOCK (SCLK)**

The SCLK pin clocks the internal shift registers of the 10XS3535 device. The SI pin accepts data into the input shift register on the falling edge of the SCLK signal, while the SO pin shifts data information out of the SO line driver on the rising edge of the SCLK signal. It is important that the SCLK pin be in a logic low state whenever  $\overline{\text{CS}}$  makes any transition. For this reason, it is recommended the SCLK pin be in a logic [0] whenever the device is not accessed ( $\overline{\text{CS}}$  logic [1] state). SCLK has a passive pull-down,  $R_{\text{DOWN}}$ . When  $\overline{\text{CS}}$  is logic [1], signals at the SCLK and SI pins are ignored and SO is tri-stated (high-impedance) (see [Figure 8](#)).



Notes

1. D15 : D0 relate to the most recent ordered entry of data into the device.
2. OD15 : OD0 relate to the first 16 bits of ordered fault and status data out of the device.

**Figure 8. Single 16-Bit Word SPI Communication**

**SERIAL INPUT (SI)**

The SI pin is a serial interface command data input pin. Each SI bit is read on the falling edge of SCLK. A 16-bit stream of serial data is required on the SI pin, starting with D15 to D0. SI has a passive pull-down,  $R_{DOWN}$ .

**SERIAL OUTPUT (SO)**

The SO data pin is a tri-stateable output from the shift register. The SO pin remains in a high-impedance state until the  $\overline{CS}$  pin is put into a logic [0] state. The SO data is capable of reporting the status of the output, the device configuration, and the state of the key inputs. The SO pin changes state on the rising edge of SCLK and reads out on the falling edge of SCLK.

**CHIP SELECT ( $\overline{CS}$ )**

The  $\overline{CS}$  pin enables communication with the master device. When this pin is in a logic [0] state, the device is capable of transferring information to, and receiving information from, the master device. The 10XS3535 device latches in data from the Input Shift registers to the addressed registers on the rising edge of  $\overline{CS}$ . The device transfers status information from the power output to the Shift register on the falling edge of  $\overline{CS}$ . The SO output driver is enabled when  $\overline{CS}$  is logic [0].  $\overline{CS}$  should transition from a logic [1] to a logic [0] state only when SCLK is a logic [0].  $\overline{CS}$  has a passive pull-up,  $R_{UP}$ .

## FUNCTIONAL DEVICE OPERATION

### OPERATIONAL MODES

#### SLEEP MODE

The Sleep mode is the default mode of the 10XS3535. This is the state of the device after first applying battery voltage ( $V_{BAT}$ ) and prior to any I/O transitions. This is also the state of the device when IGN, FOG, FLASHER, and  $\overline{RST}$  are logic [0] (wake=0). In the Sleep mode, the outputs and all internal circuitry are OFF to minimize current draw. In addition, all SPI-configurable features of the device are reset. The 10XS3535 will transit to two modes (Normal and Fail) depending on wake and fail signals (see Fig13).

The transition to the other modes is according following signals:

- Wake = IGN or IGN\_ON or FLASHER or FLASHER\_ON or  $\overline{RST}$  or FOG or FOG\_ON
- Fail = VCC fail or SPI fail or External limp

#### NORMAL MODE

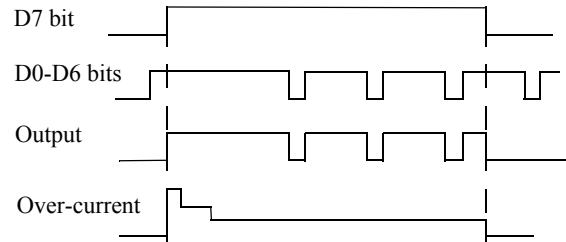
The 10XS3535 is in Normal mode when:

- Wake = 1
- Fail = 0

In Normal operating mode the power outputs are under full control of the SPI as follows:

- The outputs 1 to 6, including multiphase timing and selectable slew-rate, are controlled by the programmable PWM module.
- The outputs 1 to 5 are switched OFF in case of an under-voltage on VBAT.
- The outputs 1 to 5 are protected by the selectable over-current double window and over-temperature shutdown circuit.
- The digital diagnosis feature transfers status of the smart outputs via SPI.
- The analog current sense output (current recopy feature) can be routed by SPI.
- The outputs 1 and 5 can be configured to control LED loads:  $R_{DS(ON)}$  is increased by a factor of 2 and the current recopy ratio is scaled by a factor of 4.
- The SPI reports NM=1 in this mode.

The figure below describes the PWM, outputs and over-current behavior in Normal mode.



#### FAIL MODE

The 10XS3535 is in Fail mode when:

- Wake = 1
- Fail = 1

In Fail mode:

- The outputs are under control of external pins (see [Table 6](#))
- The outputs are fully protected in case of an overload, over-temperature and under-voltage (on VBAT or on VCC).
- The SPI reports continuously the content of address 11, disregard to previous requested output data word.
- Analog current sense is not available.
- Output 2 is configured in Xenon mode.
- In case of an overload (OCHI2 or OCLO) conditions or under-voltage on VBAT, the outputs are under control of autorestart feature.
- In case of serious overload condition (OCHI1 or OT) the corresponding output is latched OFF until a new wake-up event (wake=0 then 1).

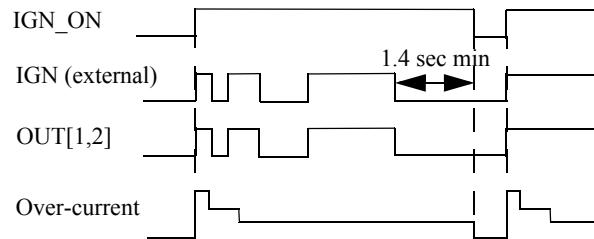


Table 6. Limp Home Output State

Output 1 Parking Light	Output 2 Low Beam	Output 3 High Beam	Output 4 Fog Light	Output 5 Flasher	External Switch Spare
IGN Pin	IGN Pin	OFF	FOG Pin	FLASHER Pin	OFF