



Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from,Europe,America and south Asia,supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of “Quality Parts,Customers Priority,Honest Operation,and Considerate Service”,our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip,ALPS,ROHM,Xilinx,Pulse,ON,Everlight and Freescale. Main products comprise IC,Modules,Potentiometer,IC Socket,Relay,Connector.Our parts cover such applications as commercial,industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



MC33887

5.0 A H-bridge with load current feedback

Rev. 17 — 17 September 2018

Data sheet: technical data

1 General description

The 33887 is a monolithic H-bridge power IC with a load current feedback feature making it ideal for closed-loop DC motor control. The IC incorporates internal control logic, charge pump, gate drive, and low $R_{DS(on)}$ MOSFET output circuitry. The 33887 is able to control inductive loads with continuous DC load currents up to 5.0 A, and with peak current active limiting between 5.2 A and 7.8 A. Output loads can be pulse width modulated at frequencies up to 10 kHz. The load current feedback feature provides a proportional (1/375th of the load current) constant-current output suitable for monitoring by a microcontroller's A/D input. This feature facilitates the design of closed-loop torque/speed control as well as open load detection. It meets the stringent requirements of automotive applications and is fully AEC-Q100 grade 1 qualified.

A fault status output pin reports undervoltage, short-circuit, and overtemperature conditions. Two independent inputs provide polarity control of two half-bridge totem-pole outputs. Two disable inputs force the H-bridge outputs to 3-state (exhibit high-impedance).

The 33887 is parametrically specified over a temperature range of $-40\text{ }^{\circ}\text{C} \leq T_A \leq 125\text{ }^{\circ}\text{C}$ and a voltage range of $5.0\text{ V} \leq V_+ \leq 28\text{ V}$. Operation with voltages up to 40 V with derating of the specifications.

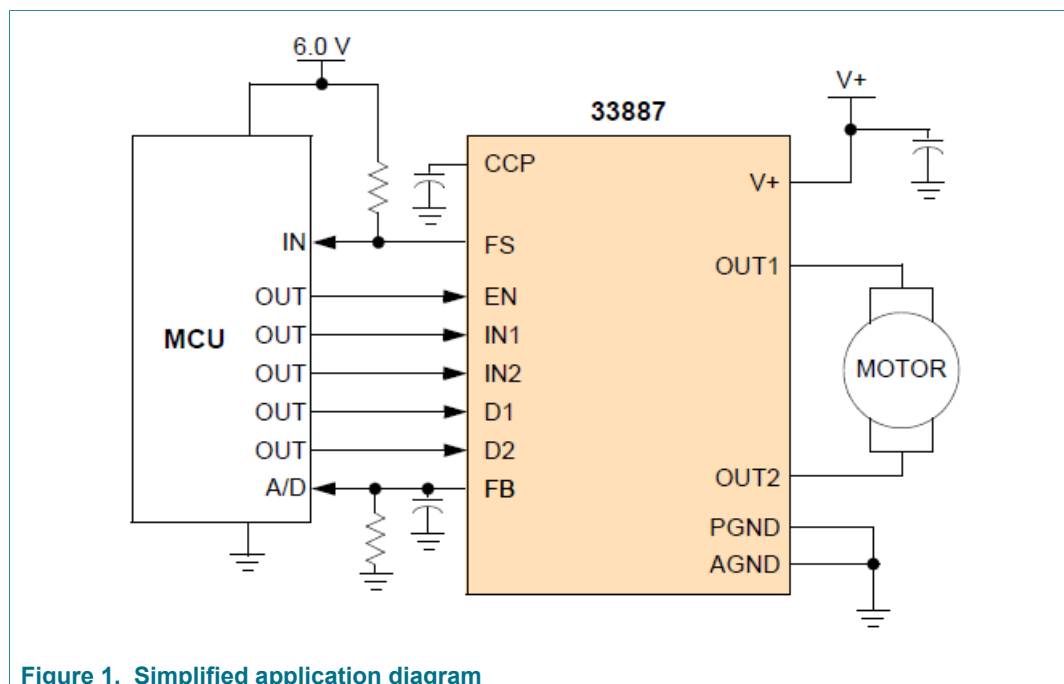


Figure 1. Simplified application diagram

2 Features and benefits

- Fully specified operation 5.0 V to 28 V
- Limited operation with reduced performance up to 40 V
- 120 mΩ R_{DS(on)} typical H-bridge MOSFETs
- TTL/CMOS compatible Inputs
- PWM frequencies up to 10 kHz
- Active current limiting (regulation)
- Fault status reporting
- Sleep mode with current draw ≤ 50 μA (inputs floating or set to match default logic states)
- AEC-Q100 grade 1 qualified

3 Applications

- Electronic throttle control (ETC)
- Exhaust gas recirculation (EGR)
- Turbo flap control
- Industrial and medical pumps and motor control

4 Ordering information

Table 1. Ordering information

Type number ^[1]	Package			
	Name	Description	Operating temperature	Version
MC33887APVW	HSOP20	HSOP20, plastic, heatsink small outline package; 20 terminals; 1.27 mm pitch; 11 mm x 15.9 mm x 3.2 mm body	T _A = -40 °C to 125 °C	SOT397-2
MC33887PFK	HQFN36	HQFN36, 36 terminals; 0.8 mm pitch; 9 mm x 9 mm x 2.1 mm body		SOT1663-1
MC33887PEK	HSOP54	HSOP54, plastic, heatsink small outline package; 54 terminals; 0.65 mm pitch; 17.9 mm x 7.5 mm x 2.45 mm body		SOT1747-3

[1] To order parts in tape and reel, add the R2 suffix to the part number.

5 Block diagram

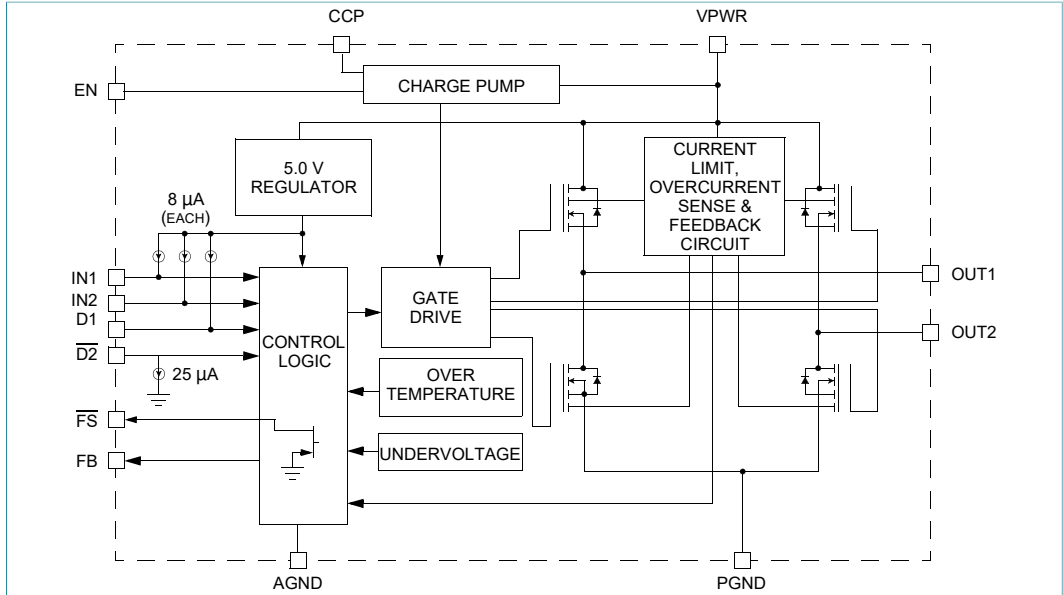


Figure 2. Block diagram

6 Pinning information

6.1 Pinning

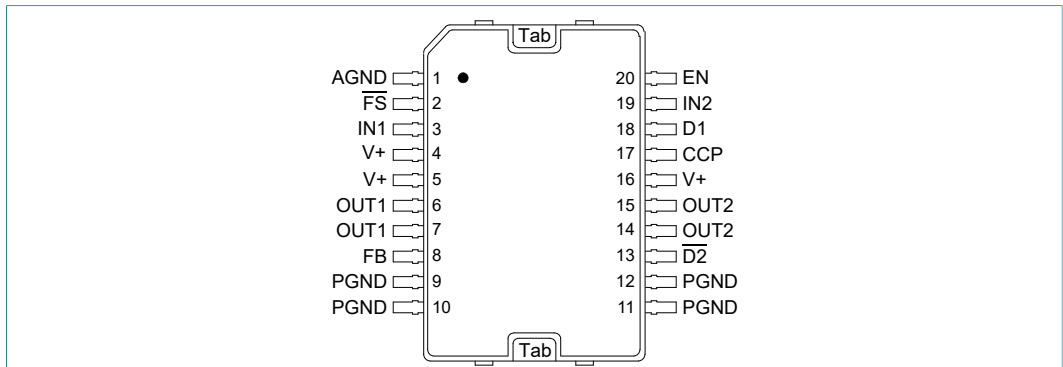


Figure 3. Pin configuration for HSOP20

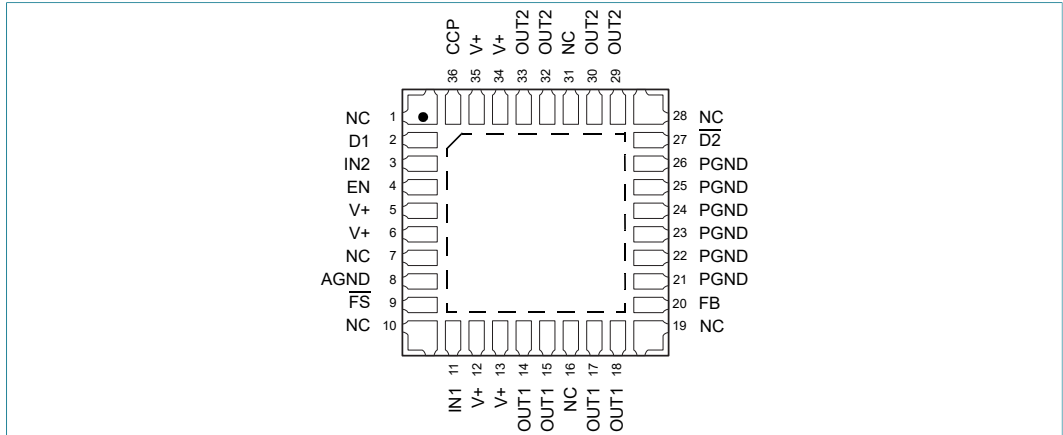


Figure 4. Pin configuration for HQFN36

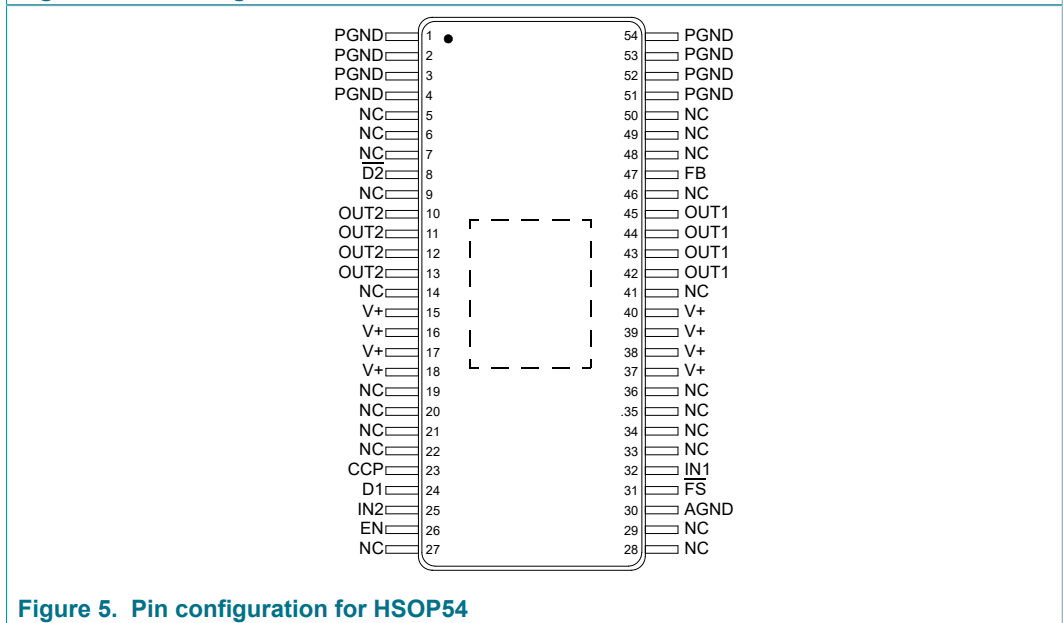


Figure 5. Pin configuration for HSOP54

6.2 Pin description

For functional description of each pin see [Section 14.2 "Functional pin description"](#).

Table 2. HSOP20 pin description

Symbol	Pin	Name	Description
AGND	1	Analog ground	Low-current analog signal ground
FS	2	Fault status for H-bridge	Open drain active low fault status output requiring a pull-up resistor to 5.0 V
IN1	3	Logic input control 1	Logic input control of OUT1 (i.e., IN1 logic high = OUT1 high)
V+	4, 5, 16	Positive power supply	Positive supply connections
OUT1	6, 7	H-bridge output 1	Output 1 of H-bridge
FB	8	Feedback for H-bridge	Current sensing feedback output providing ground referenced 1/375th (0.00266) of H-bridge high-side current
PGND	9, 10, 11, 12	Power ground	High-current power ground

5.0 A H-bridge with load current feedback

Symbol	Pin	Name	Description
D2	13	Disable 2	Active low input used to simultaneously 3-state disable both H-bridge outputs. When $\overline{D2}$ is logic low, both outputs are 3-stated.
OUT2	14, 15	H-bridge output 2	Output 2 of H-bridge
CCP	17	Charge pump capacitor	External reservoir capacitor connection for internal charge pump capacitor
D1	18	Disable 1	Active high input used to simultaneously 3-state disable both H-bridge outputs. When D1 is logic high, both outputs are 3-stated.
IN2	19	Logic input control 2	Logic input control of OUT2 (i.e., IN2 logic high = OUT2 high)
EN	20	Enable	Logic input enable control of device (i.e., EN logic high = full operation, EN logic low = Sleep mode)
Thermal interface	Tab/pad	Exposed pad thermal interface	Exposed pad thermal interface for sinking heat from the device ^[1]

[1] Must be DC-coupled to analog ground and power ground via very low impedance path to prevent injection of spurious signals into IC substrate.

Table 3. HQFN36 pin description

Symbol	Pin	Name	Description
n.c.	1, 7, 10, 16, 19, 28, 31	not connected	No internal connection to this pin
D1	2	Disable 1	Active high input used to simultaneously 3-state disable both H-bridge outputs. When D1 is logic high, both outputs are 3-stated.
IN2	3	Logic input control 2	Logic input control of OUT2 (i.e., IN2 logic high = OUT2 high)
EN	4	Enable	Logic input enable control of device (i.e., EN logic high = full operation, EN logic low = Sleep mode)
V+	5, 6, 12, 13, 34, 35	Positive power supply	Positive supply connections
AGND	8	Analog ground	Low-current analog signal ground
FS	9	Fault status for H-bridge	Open drain active low fault status output requiring a pull-up resistor to 5.0 V
IN1	11	Logic input control 1	Logic input control of OUT1 (i.e., IN1 logic high = OUT1 high)
OUT1	14, 15, 17, 18	H-bridge output 1	Output 1 of H-bridge
FB	20	Feedback for H-bridge	Current feedback output providing ground referenced 1/375th ratio of H-bridge high-side current
PGND	21, 22, 23, 24, 25, 26	Power ground	High-current power ground
$\overline{D2}$	27	Disable 2	Active low input used to simultaneously 3-state disable both H-bridge outputs. When $\overline{D2}$ is logic low, both outputs are 3-stated.
OUT2	29, 30, 32, 33	H-bridge output 2	Output 2 of H-bridge
CCP	36	Charge pump capacitor	External reservoir capacitor connection for internal charge pump capacitor
Thermal interface	Tab/pad	Exposed pad thermal interface	Exposed pad thermal interface for sinking heat from the device ^[1]

[1] Must be DC-coupled to analog ground and power ground via very low impedance path to prevent injection of spurious signals into IC substrate.

Table 4. HSOP54 pin description

Symbol	Pin	Name	Description
PGND	1, 2, 3, 4, 51, 52, 53, 54	Power ground	High-current power ground
n.c.	5, 6, 7, 9, 14, 19, 20, 21, 22, 27, 28, 29, 33, 34, 35, 36, 41, 46, 48, 49, 50	not connected	No internal connection to this pin
D2	8	Disable 2	Active low input used to simultaneously 3-state disable both H-bridge outputs. When D2 is logic low, both outputs are 3-stated.
OUT2	10, 11, 12, 13	H-bridge output 2	Output 2 of H-bridge
V+	15, 16, 17, 18, 37, 38, 39, 40	Positive power supply	Positive supply connections
CCP	23	Charge pump capacitor	External reservoir capacitor connection for internal charge pump capacitor
D1	24	Disable 1	Active high input used to simultaneously 3-state disable both H-bridge outputs. When D1 is logic high, both outputs are 3-stated.
IN2	25	Logic input control 2	Logic input control of OUT2 (i.e., IN2 logic high = OUT2 high)
EN	26	Enable	Logic input enable control of device (i.e., EN logic high = full operation, EN logic low = Sleep mode)
AGND	30	Analog ground	Low-current analog signal ground
FS	31	Fault status for H-bridge	Open drain active low fault status output requiring a pull-up resistor to 5.0 V
IN1	32	Logic input control 1	Logic input control of OUT1 (i.e., IN1 logic high = OUT1 high)
OUT1	42, 43, 44, 45	H-bridge output 1	Output 1 of H-bridge
FB	47	Feedback for H-bridge	Current feedback output providing ground referenced 1/375th ratio of H-bridge high-side current
Thermal interface	Pad	Exposed pad thermal interface	Exposed pad thermal interface for sinking heat from the device ^[1]

[1] Must be DC-coupled to analog ground and power ground via very low impedance path to prevent injection of spurious signals into IC substrate.

7 Maximum ratings

Table 5. Maximum ratings

All voltages are with respect to ground unless otherwise noted.

Symbol	Parameter	Value	Unit
Electrical ratings			
V+	Supply voltage	^[1] -0.3 to 40	V
V _{IN}	Input voltage	^[2] -0.3 to 7.0	V
V _{FS}	FS status output	^[3] -0.3 to 7.0	V
I _{OUT}	Continuous current	^[4] 5.0	A

Symbol	Parameter	Value	Unit
V_{ESD1} V_{ESD2}	ESD voltage <ul style="list-style-type: none"> Human body model Machine model 	^[5] ± 2000 ± 200	V

- [1] Performance at voltages greater than 28 V is degraded. See [Section 13](#) for typical performance. Extended operation at higher voltages has not been fully characterized and may reduce the operational lifetime.
- [2] Exceeding the input voltage on IN1, IN2, EN, D1, or $\overline{D2}$ may cause a malfunction or permanent damage to the device.
- [3] Exceeding the pull-up resistor voltage on the open drain \overline{FS} pin may cause permanent damage to the device.
- [4] Continuous current capability so long as junction temperature is ≤ 150 °C.
- [5] ESD1 testing is performed in accordance with the Human Body Model ($C_{ZAP} = 100$ pF, $R_{ZAP} = 1500$ Ω), ESD2 testing is performed in accordance with the Machine Model ($C_{ZAP} = 200$ pF, $R_{ZAP} = 0$ Ω).

8 Thermal characteristics

Table 6. Thermal characteristics

Symbol	Parameter	Value	Unit
T_{STG}	Storage temperature	-65 to 150	°C
T_A	Operational ambient temperature	^[1] -40 to 125	°C
T_J	Operation junction temperature	^[1] -40 to 150	°C
T_{PPRT}	Peak package reflow temperature during reflow	^[2] ^[3]	°C
Thermal resistance and package dissipation ^[4] ^[5] ^[6] ^[7]			
$R_{\theta JB}$	Junction-to-board (bottom exposed pad soldered to board) <ul style="list-style-type: none"> HSOP20 (6.0 W) HQFN36 (4.0 W) HSOP54 (2.0 W) 	~ 7.0 ~ 8.0 ~ 9.0	°C/W
$R_{\theta JA}$	Junction-to-ambient, natural convection, single-layer board (1s) <ul style="list-style-type: none"> HSOP20 (6.0 W) HQFN36 (4.0 W) HSOP54 (2.0 W) 	^[8] ~ 41 ~ 50 ~ 62	°C/W
$R_{\theta JMA}$	Junction-to-ambient, natural convection, four-layer board (2s2p) <ul style="list-style-type: none"> HSOP20 (6.0 W) HQFN36 (4.0 W) HSOP54 (2.0 W) 	^[9] ~ 18 ~ 21 ~ 23	°C/W
$R_{\theta JC}$	Junction-to-case (exposed pad) <ul style="list-style-type: none"> HSOP20 (6.0 W) HQFN36 (4.0 W) HSOP54 (2.0 W) 	^[10] ~ 0.8 ~ 1.2 ~ 2.0	°C/W

- [1] The limiting factor is junction temperature, taking into account the power dissipation, thermal resistance, and heat sinking provided. Brief non-repetitive excursions of junction temperature above 150 °C can be tolerated, provided the duration does not exceed 30 seconds maximum. Non-repetitive events are defined as not occurring more than once in 24 hours.
- [2] Pin soldering temperature limit is for 10 seconds maximum duration. Not designed for immersion soldering. Exceeding these limits may cause malfunction or permanent damage to the device.
- [3] NXP's Package Reflow capability meets Pb-free requirements for JEDEC standard J-STD-020C. For Peak Package Reflow Temperature and Moisture Sensitivity Levels (MSL), go to www.nxp.com, search by part number (remove prefixes/suffixes and enter the core ID) to view all orderable parts, and review parametrics.
- [4] The limiting factor is junction temperature, taking into account the power dissipation, thermal resistance, and heat sinking.
- [5] Exposed heatsink pad plus the power and ground pins comprise the main heat conduction paths. The actual $R_{\theta JB}$ (junction-to-PC board) values will vary depending on solder thickness and composition and copper trace thickness. Maximum current at maximum die temperature represents ~ 16 W of conduction loss heating in the diagonal pair of output MOSFETs. Therefore, the $R_{\theta JC}$ -total must be less than 5.0 °C/W for maximum load at 70°C ambient. Module thermal design must be planned accordingly.
- [6] Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
- [7] Junction temperature is a function of on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
- [8] Per SEMI G38-87 and JEDEC JESD51-2 with the single-layer board (JESD51-3) horizontal.
- [9] Per JEDEC JESD51-6 with the board horizontal.
- [10] Indicates the maximum thermal resistance between the die and the exposed pad surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1) with the cold plate temperature used for the case temperature.

9 Static characteristics

Table 7. Static characteristics

Characteristics noted under conditions $5.0\text{ V} \leq V_+ \leq 28\text{ V}$ and $-40\text{ }^\circ\text{C} \leq T_A \leq 125\text{ }^\circ\text{C}$, unless otherwise noted. Typical values noted reflect the approximate parameter means at $T_A = 25\text{ }^\circ\text{C}$ under nominal conditions, unless otherwise noted.

Symbol	Parameter	Min	Typ	Max	Unit
Power supply					
V+	Operating voltage range ^[1]	5.0	—	28	V
I _{Q(SLEEP)}	Sleep state supply current ^[2] • I _{OUT} = 0 A, V _{EN} = 0 V	—	25	50	μA
I _{Q(STANDBY)}	Standby supply current • I _{OUT} = 0 A, V _{EN} = 5.0 V	—	—	20	mA
V _{+(THRES-OFF)}	Threshold supply voltage • Switch OFF • Switch ON • Hysteresis	4.15	4.4	4.65	V
V _{+(THRES-ON)}		4.5	4.75	5.0	V
V _{+(HYS)}		150	—	—	mV
Charge pump					
V _{CP} - V+	Charge pump voltage • V ₊ = 5.0 V • 8.0 V ≤ V ₊ ≤ 28 V	3.35 —	— —	— 20	V
Control inputs					
V _{IH} V _{IL} V _{HYS}	Input voltage (IN1, IN2, D1, D2) • Threshold high • Threshold low • Hysteresis	3.5 — 0.7	— — 1.0	— 1.4 —	V
I _{INP}	Input current (IN1, IN2, D1) • V _{IN} = 0.0 V	-200	-80	—	μA
I _{INP}	Input current (D2, EN) • V _{D2} = 5.0 V	—	25	100	μA
Power outputs OUT1, OUT2					
R _{DS(on)}	Output ON resistance ^[3] • 5.0 V ≤ V ₊ ≤ 28 V, T _J = 25 °C • 8.0 V ≤ V ₊ ≤ 28 V, T _J = 150 °C • 5.0 V ≤ V ₊ ≤ 8.0 V, T _J = 150 °C	— — —	120 — —	— 225 300	mΩ
I _{LIM}	Active current limiting threshold (via internal constant OFF time PWM) on low-side MOSFETs ^[4]	5.2	6.5	7.8	A
I _{SCH}	High-side short-circuit detection threshold	11	—	—	A
I _{SCL}	Low-side short-circuit detection threshold	8.0	—	—	A
I _{OUT(LEAK)}	Leakage current ^[5] • V _{OUT} = V ₊ • V _{OUT} = Ground	— —	100 30	200 60	μA
V _F	Output MOSFET body diode forward voltage drop • I _{OUT} = 3.0 A	—	—	2.0	V
T _{LIM} T _{HYS}	Overtemperature shutdown • Thermal limit • Hysteresis	175 10	— —	225 30	°C
High-side current sense feedback					
I _{FB}	Feedback current • I _{OUT} = 0 mA • I _{OUT} = 500 mA • I _{OUT} = 1.5 A • I _{OUT} = 3.0 A • I _{OUT} = 6.0 A	— 1.07 3.6 7.2 14.4	— 1.33 4.0 8.0 16	600 1.68 4.62 9.24 18.48	μA mA mA mA mA

Symbol	Parameter	Min	Typ	Max	Unit
Fault status ^[6]					
I _{FS(LEAK)}	Fault status leakage current • V _{FS} = 5.0 V	—	—	10	µA
V _{FS(LOW)}	Fault status set voltage • I _{FS} = 300 µA	—	—	1.0	V

- [1] Specifications are characterized over the range of 5.0 V ≤ V+ ≤ 28 V. See [Section 13](#) and [Section 14](#) for information about operation outside of this range.
- [2] I_{Q(sleep)} is with sleep mode function enabled.
- [3] Output ON resistance as measured from output to V+ and ground.
- [4] Active current limitation applies only for the low-side MOSFETs.
- [5] Outputs switched OFF via D1 or D2.
- [6] Fault status output is an open drain output requiring a pull-up resistor to 5.0 V.
- [7] Fault status leakage current is measured with fault status high and not set.
- [8] Fault status set voltage is measured with fault status low and set with I_{FS} = 300 µA.

10 Dynamic characteristics

Table 8. Dynamic characteristics

Characteristics noted under conditions 5.0 V ≤ V+ ≤ 28 V and -40 °C ≤ T_A ≤ 125 °C, unless otherwise noted. Typical values noted reflect the approximate parameter means at T_A = 25 °C under nominal conditions, unless otherwise noted.

Symbol	Parameter	Min	Typ	Max	Unit
Timing characteristics					
f _{PWM}	PWM frequency ^[1]	—	10	—	kHz
f _{MAX}	Maximum switching frequency during active current limiting ^[2]	—	—	20	kHz
t _{D(ON)}	Output ON delay • V+ = 14 V ^[3]	—	—	18	µs
t _{D(OFF)}	Output OFF delay • V+ = 14 V ^[3]	—	—	18	µs
t _A	I _{LIM} output constant OFF time for low-side MOSFETs ^{[4] [5]}	15	20.5	26	µs
t _B	I _{LIM} blanking time for low-side MOSFETs ^{[5] [6]}	12	16.5	21	µs
t _F , t _R	Output rise and fall time • V+ = 14 V, I _{OUT} = 3.0 A ^[7]	2.0	5.0	8.0	µs
t _{D(DISABLE)}	Disable delay time ^[8]	—	—	8.0	µs
t _{POD}	Power ON delay time ^[9]	—	1.0	5.0	ms
t _{WUD}	Wake-up delay time ^[9]	—	1.0	5.0	ms
t _{RR}	Output MOSFET body diode reverse recovery time ^[10]	100	—	—	ns

- [1] The outputs can be PWM-controlled from an external source. This is typically done by holding one input high while applying a PWM pulse train to the other input. The maximum PWM frequency obtainable is a compromise between switching losses and switching frequency. See [Section 12](#).
- [2] The maximum switching frequency during active current limiting is internally implemented. The internal current limit circuitry produces a constant OFF time pulse-width modulation of the output current. The output load's inductance, capacitance, and resistance characteristics affect the total switching period (OFF time + ON time) and thus the PWM frequency during current limit.
- [3] Output delay is the time duration from the midpoint of the IN1 or IN2 input signal to the 10 % or 90 % point (dependent on the transition direction) of the OUT1 or OUT2 signal. If the output is transitioning high to low, the delay is from the midpoint of the input signal to the 90% point of the output response signal. If the output is transitioning low to high, the delay is from the midpoint of the input signal to the 10 % point of the output response signal. See [Figure 6](#).
- [4] I_{LIM} output constant OFF time is the time during which the internal constant OFF time PWM current regulation circuit has 3-stated the output bridge.
- [5] Load currents ramping up to the current regulation threshold become limited at the I_{LIM} value. The short-circuit current possess a di/dt that ramps up to the I_{SCH} or I_{SCL} threshold during the I_{LIM} blanking time, registering as a short-circuit event detection and causing the shutdown circuitry to force the output into an immediate 3-state latch OFF. See [Figure 10](#) and [Figure 11](#). Operation in current limit mode may cause junction temperatures to rise. Junction temperatures above ~160 °C causes the output current limit threshold to progressively foldback, or decrease with temperature, until ~175 °C is reached, after which the T_{LIM} thermal latch OFF occurs. Permissible operation within this foldback region is limited to nonrepetitive transient events of duration not to exceed 30 seconds. See [Figure 9](#).
- [6] I_{LIM} blanking time is the time during which the current regulation threshold is ignored so that the short-circuit detection threshold comparators may have time to act.
- [7] Rise time is from the 10 % to the 90 % level and fall time is from the 90 % to the 10 % level of the output signal. See [Figure 8](#).
- [8] Disable delay time measurement is defined in [Figure 7](#).

[9] Parameter has been characterized but not production tested.
 [10] Parameter is guaranteed by design but not production tested.

11 Timing diagrams

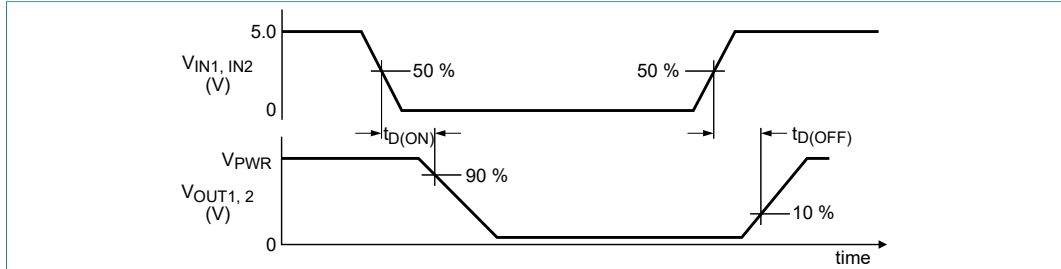


Figure 6. Output delay time

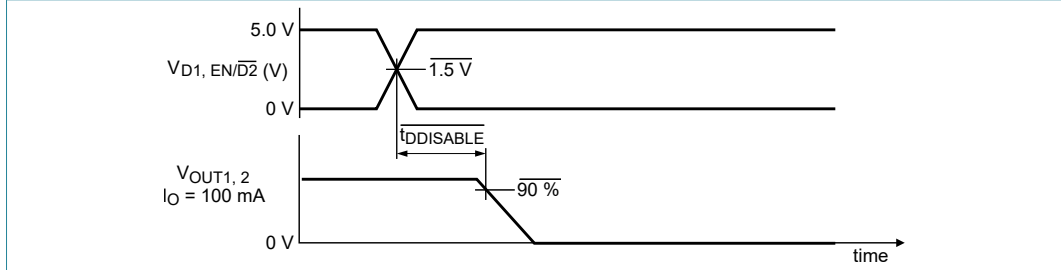


Figure 7. Disable delay time

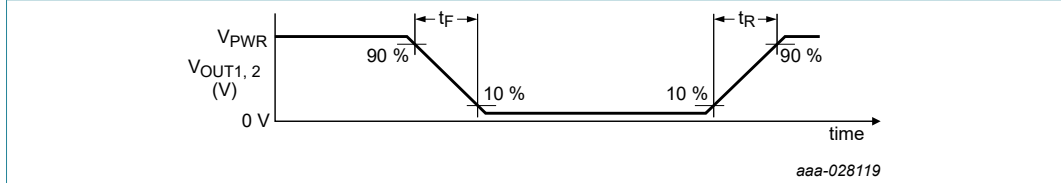


Figure 8. Output switching time

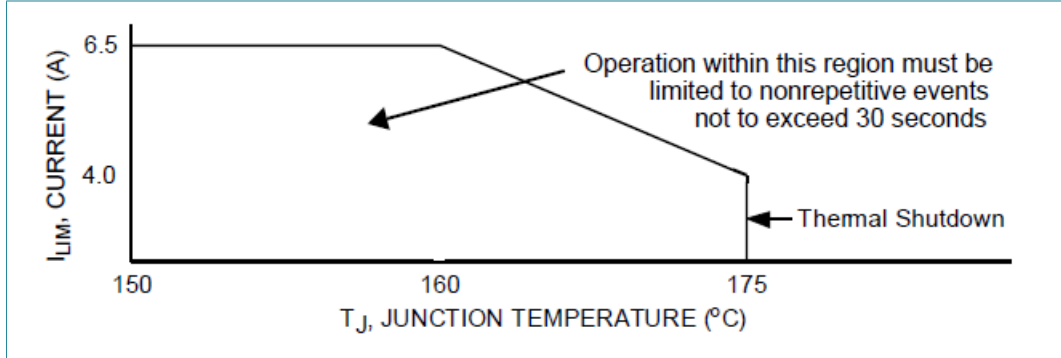


Figure 9. Active current limiting versus temperature (typical)

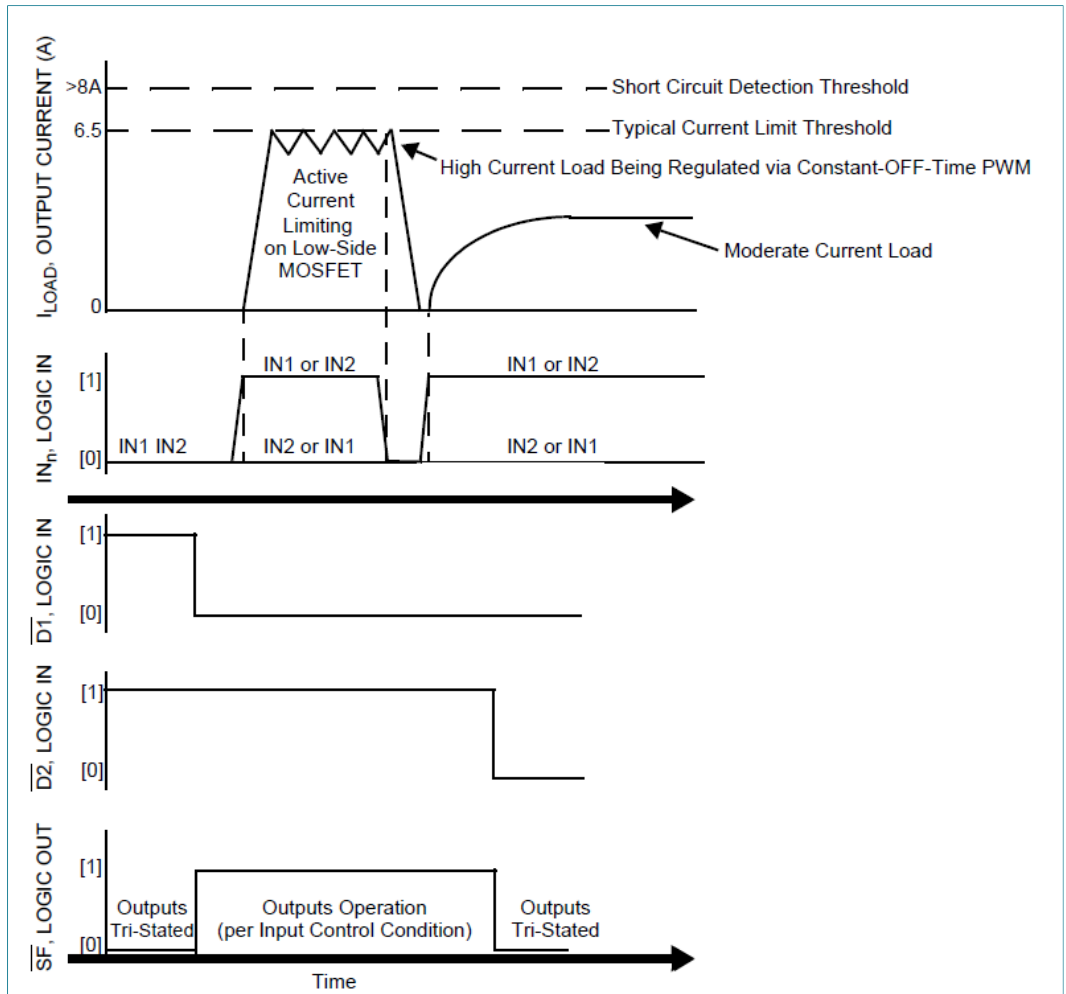


Figure 10. Operating states

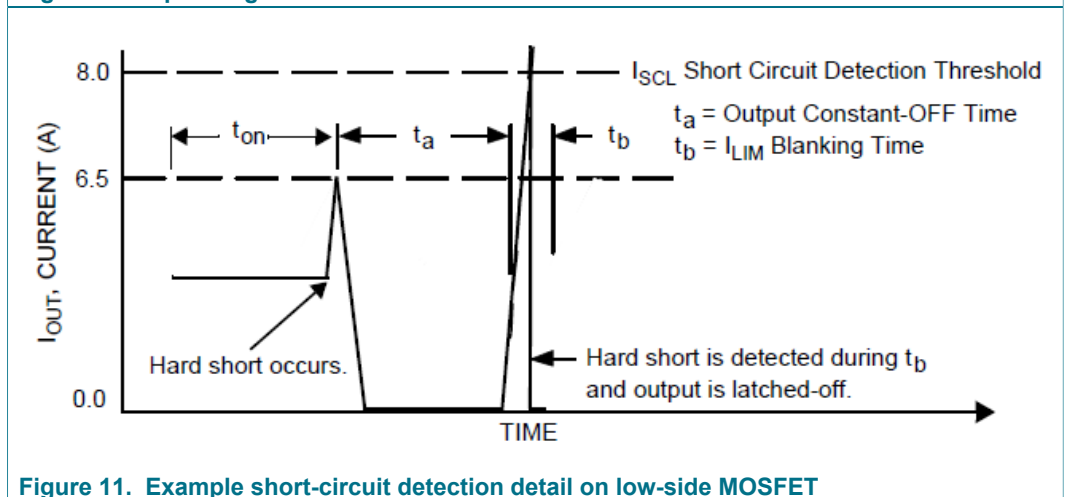


Figure 11. Example short-circuit detection detail on low-side MOSFET

12 Typical switching waveforms

Important: For all plots, the following applies:

5.0 A H-bridge with load current feedback

- $Ch2 = 2.0 \text{ A per division}$
- $L_{LOAD} = 533 \mu\text{H} @ 1.0 \text{ kHz}$
- $L_{LOAD} = 530 \mu\text{H} @ 10.0 \text{ kHz}$
- $R_{LOAD} = 4.0 \Omega$

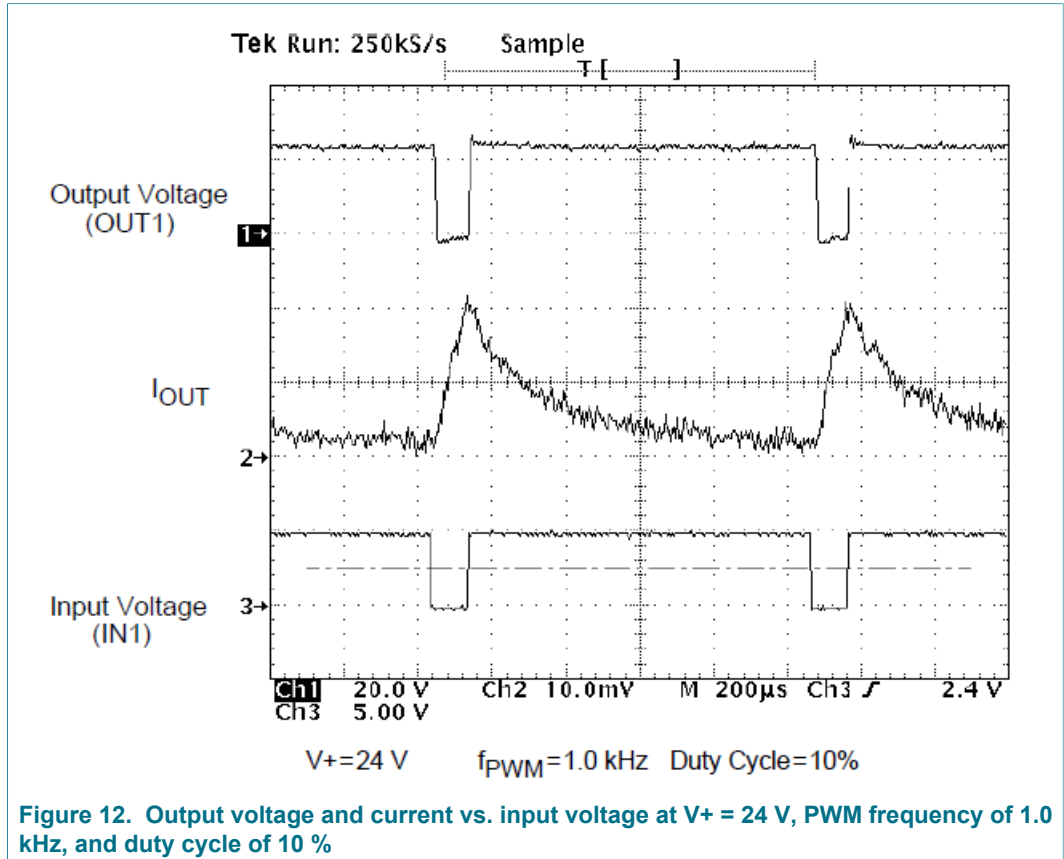


Figure 12. Output voltage and current vs. input voltage at $V+ = 24 \text{ V}$, PWM frequency of 1.0 kHz, and duty cycle of 10 %

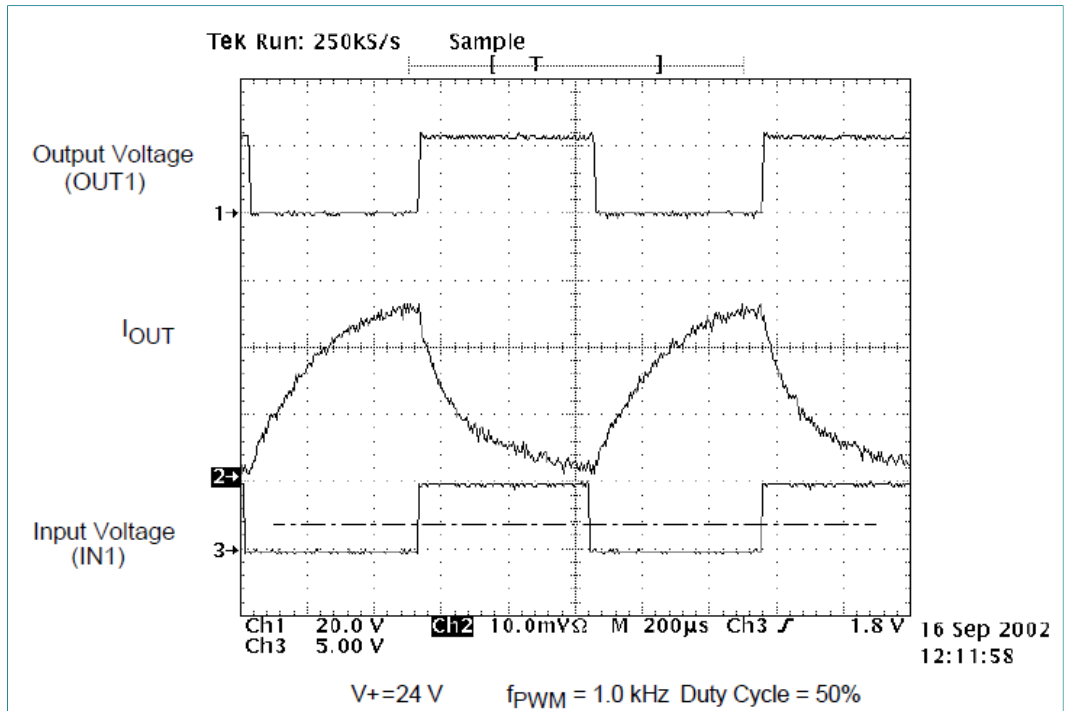


Figure 13. Output voltage and current vs. input voltage at $V^+ = 24\text{ V}$, PWM frequency of 1.0 kHz, and duty cycle of 50 %

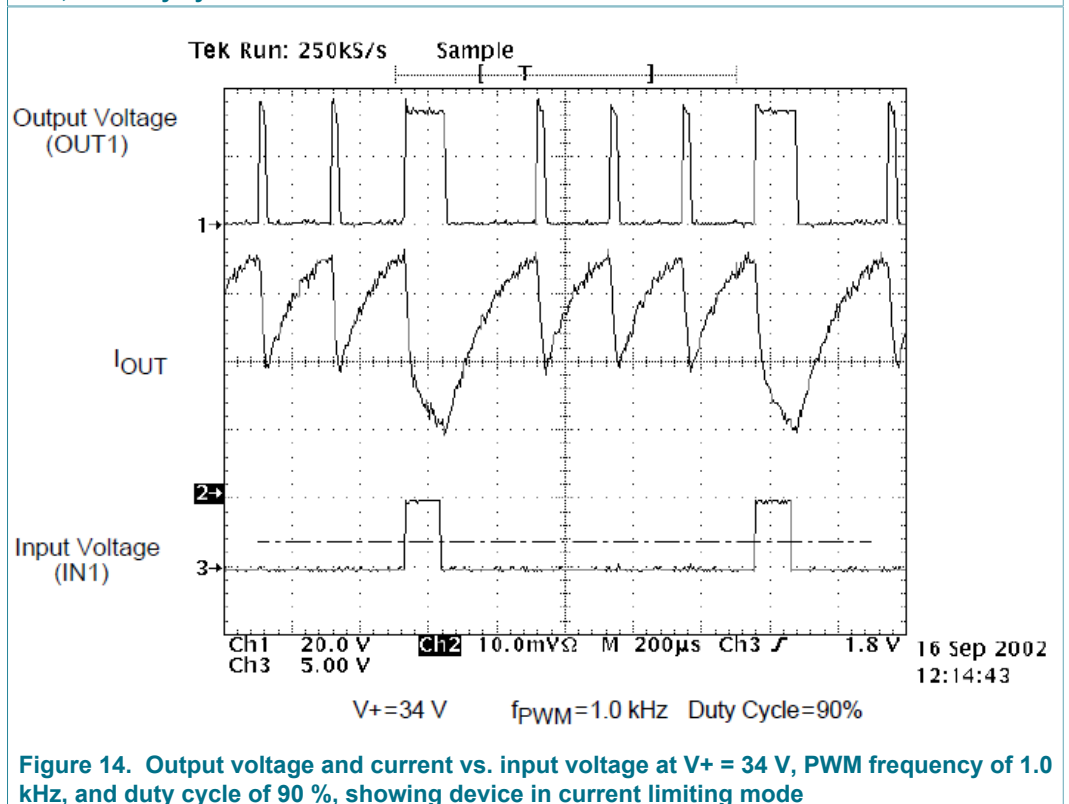


Figure 14. Output voltage and current vs. input voltage at $V^+ = 34\text{ V}$, PWM frequency of 1.0 kHz, and duty cycle of 90 %, showing device in current limiting mode

5.0 A H-bridge with load current feedback

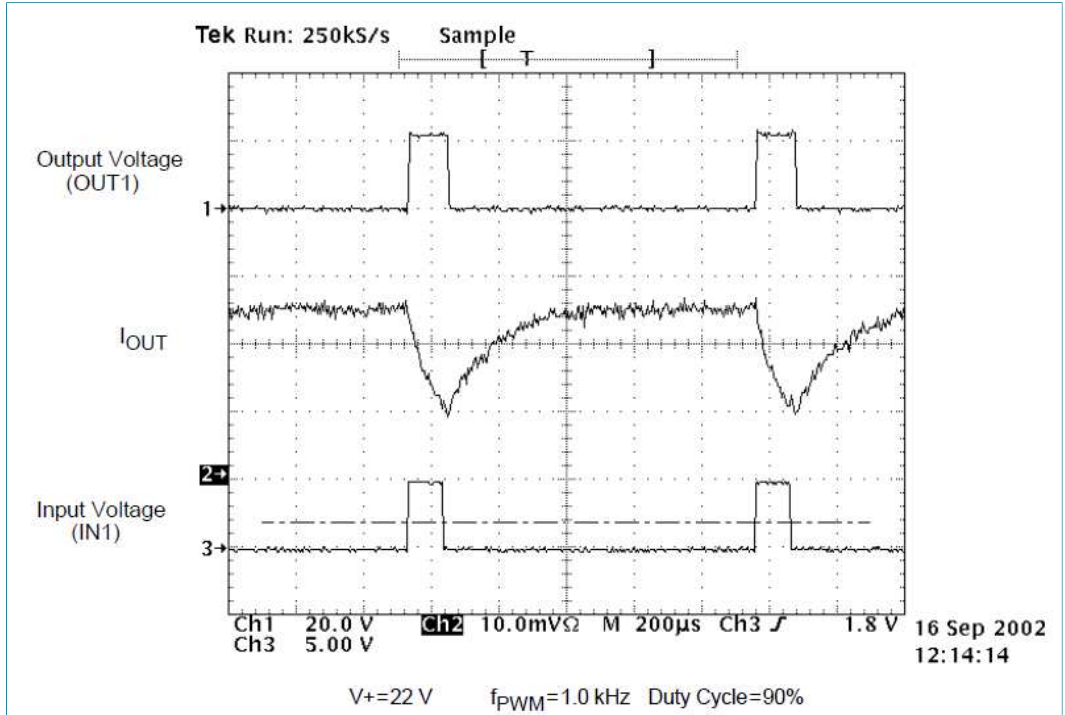


Figure 15. Output voltage and current vs. input voltage at $V+ = 22\text{ V}$, PWM frequency of 1.0 kHz, and duty cycle of 90 %

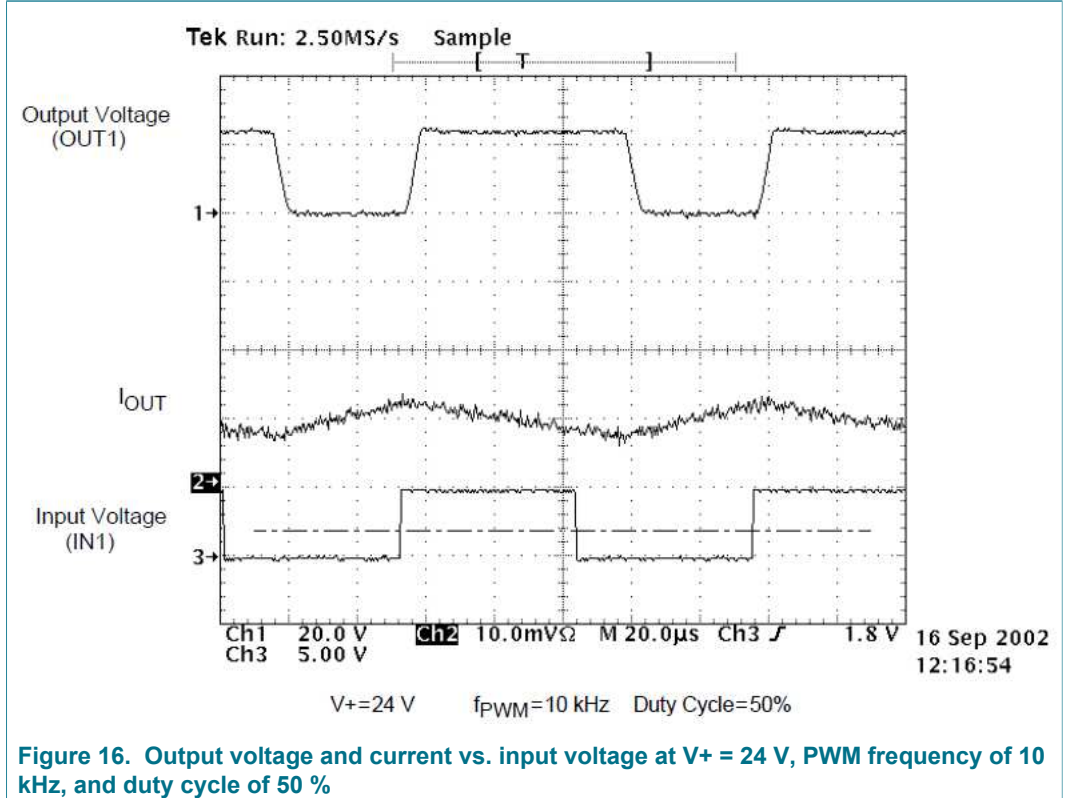


Figure 16. Output voltage and current vs. input voltage at $V+ = 24\text{ V}$, PWM frequency of 10 kHz, and duty cycle of 50 %

5.0 A H-bridge with load current feedback

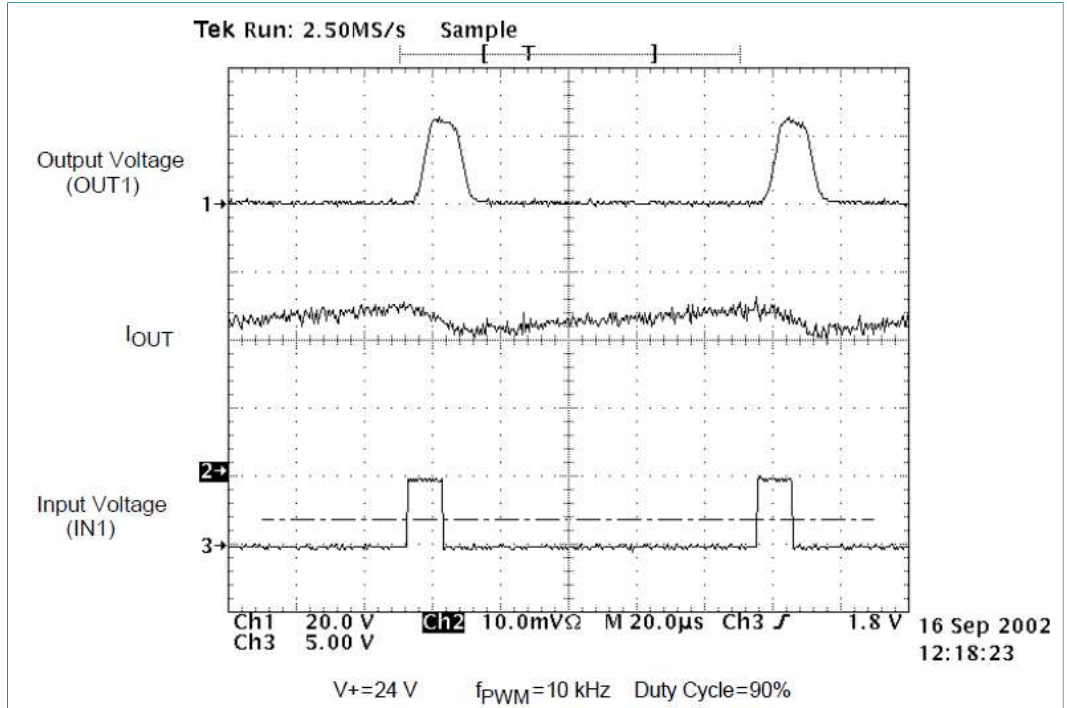


Figure 17. Output voltage and current vs. input voltage at $V^+ = 24\text{ V}$, PWM frequency of 10 kHz, and duty cycle of 90 %

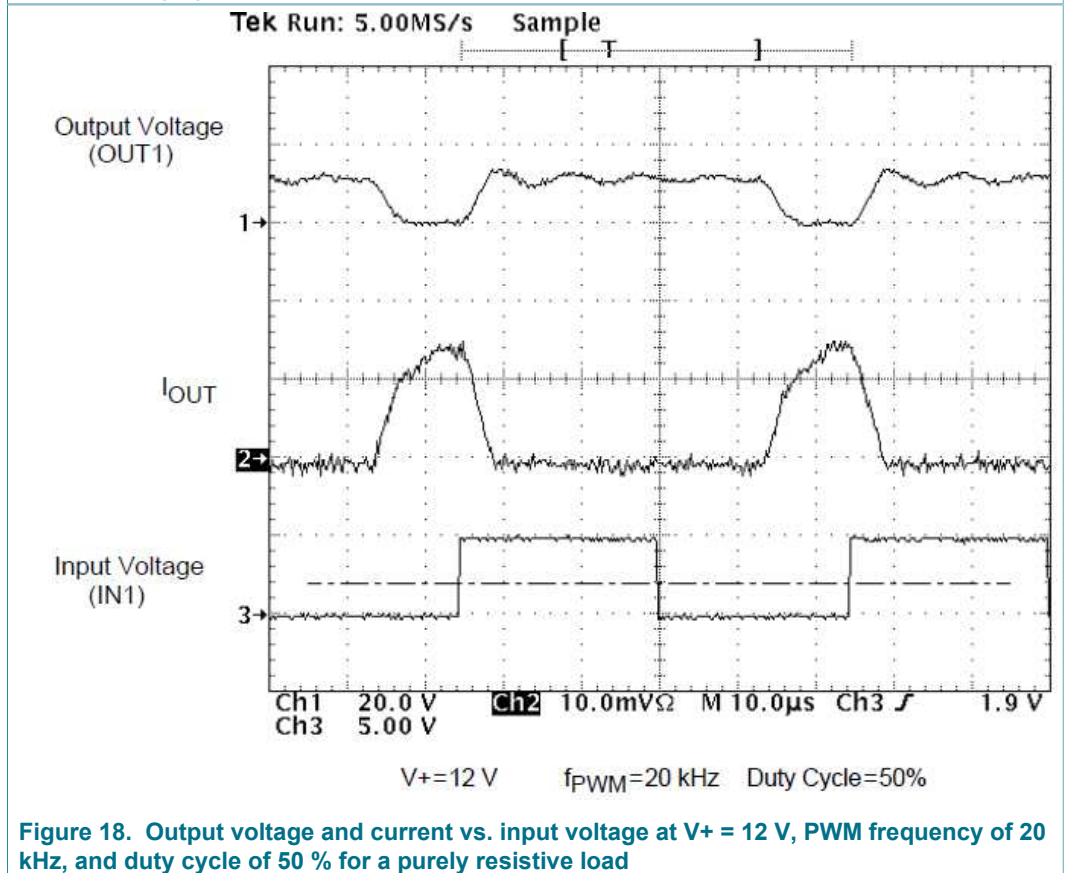
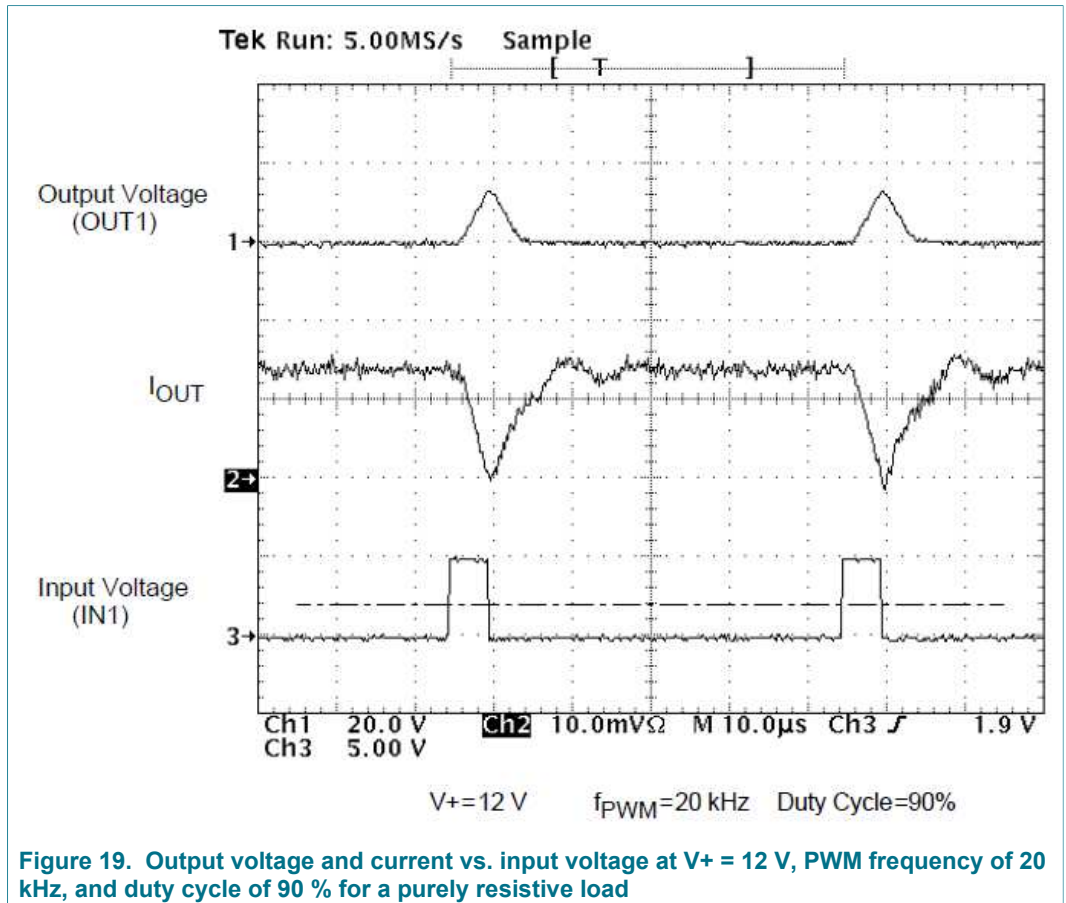
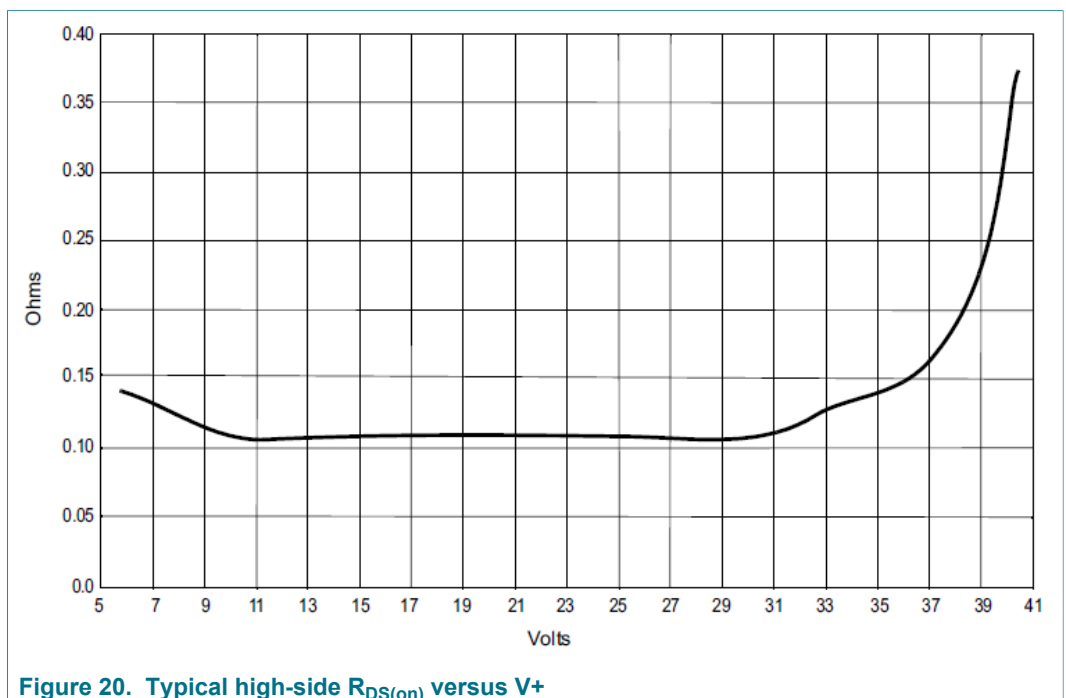


Figure 18. Output voltage and current vs. input voltage at $V^+ = 12\text{ V}$, PWM frequency of 20 kHz, and duty cycle of 50 % for a purely resistive load



13 Electrical performance curves



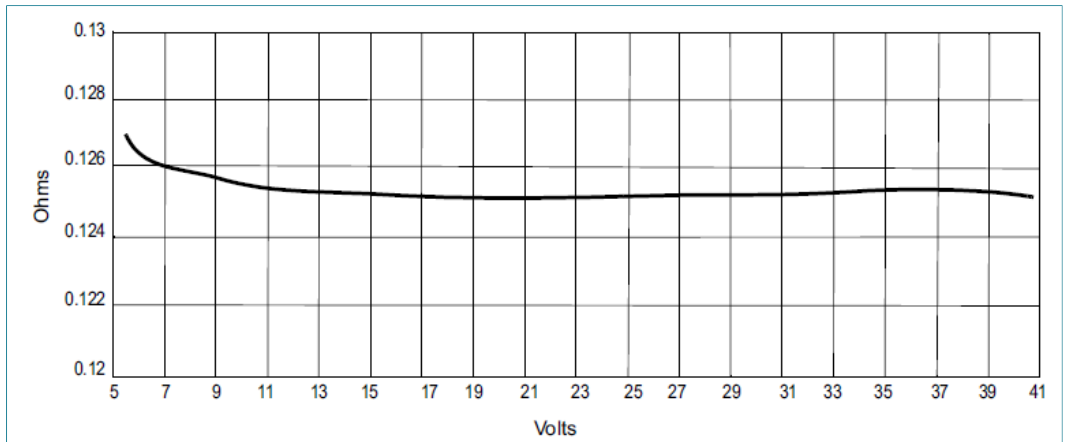


Figure 21. Typical low-side $R_{DS(on)}$ versus $V+$

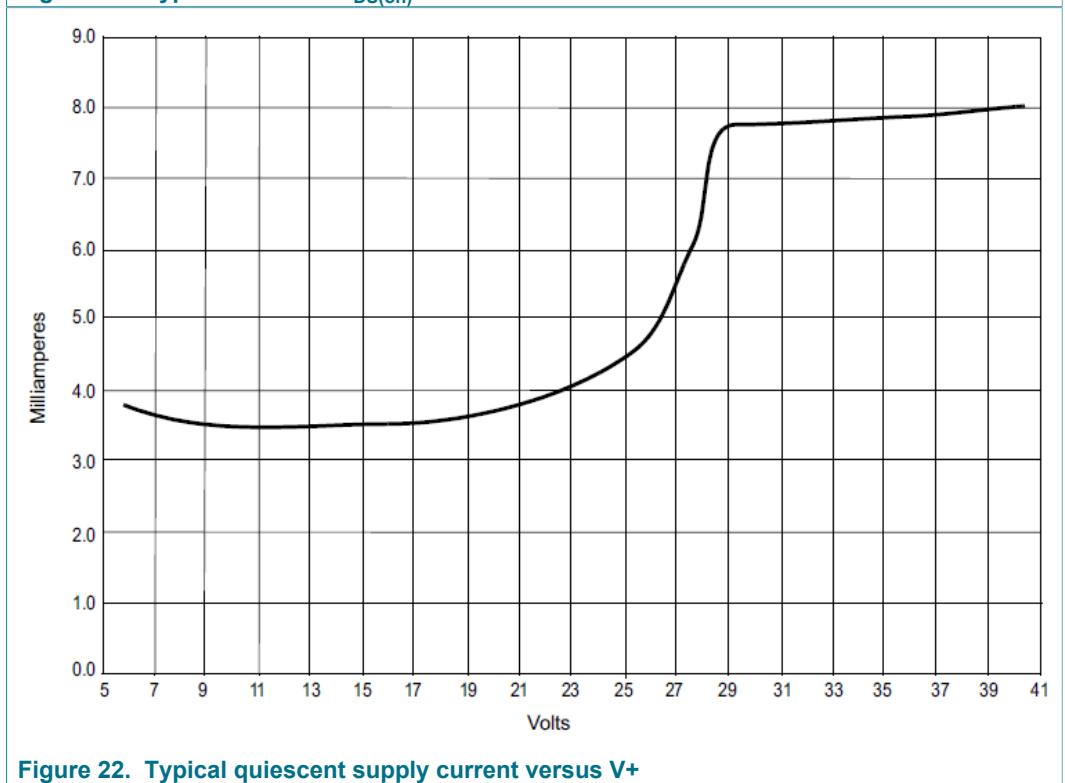


Figure 22. Typical quiescent supply current versus $V+$

Table 9. Truth table

The 3-state conditions and the status flag are reset using D1 or $\overline{D2}$. The truth table uses the following notations: L = low, H = high, X = high or low, and Z = high-impedance.

Device state	Input conditions					Fault status flag FS	Output state	
	EN	D1	$\overline{D2}$	IN1	IN2		OUT1	OUT2
Forward	H	L	H	H	L	H	H	L
Reverse	H	L	H	L	H	H	L	H
Freewheeling low	H	L	H	L	L	H	L	L
Freewheeling high	H	L	H	H	H	H	H	H
Disable 1 (D1)	H	H	X	X	X	L	Z	Z
Disable 2 ($\overline{D2}$)	H	X	L	X	X	L	Z	Z
IN1 disconnected	H	L	H	Z	X	H	H	X
IN2 disconnected	H	L	H	X	Z	H	X	H
D1 disconnected	H	Z	X	X	X	L	Z	Z
$\overline{D2}$ disconnected	H	X	Z	X	X	L	Z	Z
Undervoltage ^[1]	H	X	X	X	X	L	Z	Z
Overtemperature ^[2]	H	X	X	X	X	L	Z	Z
Short-circuit ^[2]	H	X	X	X	X	L	Z	Z
Sleep mode EN	L	X	X	X	X	H	Z	Z
EN disconnected	Z	X	X	X	X	H	Z	Z

[1] In the event of an undervoltage condition, the outputs 3-state and status flag are set to logic low. Upon undervoltage recovery, status flag is reset automatically or automatically cleared and the outputs are restored to their original operating condition.

[2] When a short-circuit or overtemperature condition is detected, the power outputs are 3-state latched OFF independent of the input signals and the fault status flag is set logic low.

14 Functional description

14.1 Introduction

Numerous protection and operational features (speed, torque, direction, dynamic braking, PWM control, and closed-loop control), in addition to the 5.0 A current capability, make the 33887 a very attractive, cost-effective solution for controlling a broad range of small DC motors. In addition, a pair of 33887 devices can be used to control bipolar stepper motors. The 33887 can also be used to excite transformer primary windings with a switched square wave to produce secondary winding AC currents.

14.2 Functional pin description

14.2.1 Power ground and analog ground (PGND and AGND)

The power and analog ground pins should be connected together with a very low-impedance connection.

14.2.2 Positive power supply (V+)

V+ pins are the power supply inputs to the device. All V+ pins must be connected together on the printed circuit board with as short as possible traces offering as low impedance as possible between pins.

V+ pins have an undervoltage threshold. If the supply voltage drops below a V+ undervoltage threshold, the output power stage switches to a 3-state condition and the fault status flag is set and the fault status pin voltage switches to a logic low. When the supply voltage returns to a level that is above the threshold, the power stage automatically resumes normal operation according to the established condition of the input pins and the fault status flag is automatically reset logic high.

As V+ increases in value above 28 V, the charge pump performance begins to degrade. At +40 V, the charge pump is effectively non-functional. Operation at this high voltage level results in the output FETs not being enhanced when turned on. This means that the voltage on the output will be $V_{OUT} = (V+) - V_{GS}$. This increased voltage drop under load produces a higher power dissipation.

14.2.3 Fault status (\overline{FS})

The \overline{FS} pin is the device fault status output. This output is an active low open drain structure requiring a pull-up resistor to 5.0 V. See [Table 9](#).

14.2.4 Logic input control and disable (IN1, IN2, D1, and $\overline{D2}$)

These pins are input control pins used to control the outputs. These pins are 5.0 V CMOS-compatible inputs with hysteresis. The IN1 and IN2 independently control OUT1 and OUT2, respectively. D1 and $\overline{D2}$ are complementary inputs used to 3-state disable the H-bridge outputs.

When either D1 or $\overline{D2}$ is set (D1 = logic high or D2 = logic low) in the disable state, outputs OUT1 and OUT2 are both 3-state disabled; however, the rest of the circuitry is fully operational and the supply $I_{Q(standby)}$ current is reduced to a few milliamperes. See [Table 9](#) and [Table 7](#).

14.2.5 H-bridge output (OUT1, OUT2)

These pins are the outputs of the H-bridge with integrated output MOSFET body diodes. The bridge output is controlled using the IN1, IN2, D1 and $\overline{D2}$ inputs. The low-side MOSFETs have active current limiting above the I_{LIM} threshold. The outputs also have thermal shutdown (3-state latch off) with hysteresis as well as short-circuit latch off protection.

A disable timer (time t_b) used to detect currents that are higher than current limit is activated at each output activation to facilitate hard short detection (see [Figure 11](#)).

14.2.6 Charge pump capacitor (CCP)

A filter capacitor (up to 33 nF) can be connected from the charge pump output pin and PGND. The device can operate without the external capacitor, although the C_{CP} capacitor helps to reduce noise and allows the device to perform at maximum speed, timing, and PWM frequency.

14.2.7 Enable (EN)

The EN pin is used to place the device in a Sleep mode so as to consume very low currents. When the EN pin voltage is a logic low state, the device is in the Sleep mode. The device is enabled and fully operational when the EN pin voltage is logic high.

An internal pull-down resistor maintains the device in Sleep mode in the event EN is driven through a high impedance I/O or an unpowered microcontroller, or the EN input becomes disconnected.

14.2.8 Feedback for H-bridge (FB)

The 33887 has a feedback output (FB) for real time monitoring of H-bridge high-side current to facilitate closed-loop operation for motor speed and torque control.

The FB pin provides current sensing feedback of the H-bridge high-side drivers. When running in forward or reverse direction, a ground referenced $1/375^{\text{th}}$ (0.00266) of load current is output to this pin. Through an external resistor to ground, the proportional feedback current can be converted to a proportional voltage equivalent and the controlling microcontroller can read the current proportional voltage with its analog-to-digital converter (ADC). This is intended to provide the user with motor current feedback for motor torque control. The resistance range for the linear operation of the FB pin is $100 < R_{\text{FB}} < 200 \Omega$.

If PWM-ing is implemented using the disable pin inputs (either D1 or $\overline{\text{D2}}$), a small filter capacitor (1.0 μF or less) may be required in parallel with the external resistor to ground for fast spike suppression.

15 Functional device operation

15.1 Operational modes

The 33887 (see [Figure 2](#)), is a fully protected monolithic H-bridge with enable, fault status reporting, and high-side current sense feedback to accommodate closed-loop PWM control.

For a DC motor to run, the input conditions need be as follows: Enable input logic high, D1 input logic low, $\overline{\text{D2}}$ input logic high, $\overline{\text{FS}}$ flag cleared (logic high), one IN logic low and the other IN logic high (to define output polarity). The 33887 can execute dynamic braking by simultaneously turning on either both high-side MOSFETs or both low-side MOSFETs in the output H-bridge; e.g., IN1 and IN2 logic high or IN1 and IN2 logic low.

The 33887 outputs are capable of providing a continuous DC load current of 5.0 A from a 28 V V+ source. An internal charge pump supports PWM frequencies to 10 kHz. An external pull-up resistor is required at the $\overline{\text{FS}}$ pin for fault status reporting. The 33887 has an analog feedback (current mirror) output pin (the FB pin) that provides a constant current source ratioed to the active high-side MOSFET. This can be used to provide real time monitoring of load current to facilitate closed-loop operation for motor speed/torque control.

Two independent inputs (IN1 and IN2) provide control of the two totem-pole half-bridge outputs. Two disable inputs (D1 and $\overline{\text{D2}}$) provide the means to force the H-bridge outputs to a high-impedance state (all H-bridges switch off). An EN pin controls an enable function that allows the 33887 to be placed in a power-conserving sleep mode.

The 33887 has undervoltage shutdown with automatic recovery, active current limiting, output short-circuit latch off, and overtemperature latch off. An undervoltage shutdown, output short-circuit latch off, or overtemperature latch off fault condition causes the outputs to turn off (i.e., become high impedance or 3-stated) and the fault output flag to be set low. Either of the disable inputs or V+ must be toggled to clear the fault flag.

Active current limiting is accomplished by a constant OFF time PWM method employing active current limiting threshold triggering. The active current limiting scheme is unique in that it incorporates a junction temperature dependent current limit threshold. This means the active current limiting threshold is ramped down as the junction temperature increases above 160 °C, until at 175 °C the current is decreased to about 4.0 A. Above 175 °C, the overtemperature shutdown (latch off) occurs. This combination of features allows the device to remain in operation for 30 seconds at junction temperatures above 150 °C for nonrepetitive unexpected loads.

15.2 Protection and diagnostic features

15.2.1 Short-circuit protection

If an output short-circuit condition is detected, the power outputs 3-state (latch off) independent of the input (IN1 and IN2) states, and the fault status output flag is set logic low. If the D1 input changes from logic high to logic low, or if the $\overline{D2}$ input changes from logic low to logic high, the output bridge becomes operational again and the fault status flag is reset (cleared) to a logic High state.

The output stage always switches into the mode defined by the input pins (IN1, IN2, D1, and $\overline{D2}$), provided the device junction temperature is within the specified operating temperature range.

15.2.2 Active current limiting

The maximum current flow under normal operating conditions is internally limited to I_{LIM} (5.2 A to 7.8 A). When the maximum current value is reached, the output stages are 3-stated for a fixed time (t_a) of 20 μ s typical. Depending on the time constant associated with the load characteristics, the current decreases during the 3-state duration until the next output ON cycle occurs (see [Figure 11](#) and [Figure 14](#)).

The current limiting threshold value is dependent upon the device junction temperature. When $-40\text{ °C} \leq T_J \leq 160\text{ °C}$, I_{LIM} is between 5.2 A to 7.8 A. When T_J exceeds 160 °C, the I_{LIM} current decreases linearly down to 4.0 A typical at 175 °C. Above 175 °C the device overtemperature circuit detects T_{LIM} and overtemperature shutdown occurs (see [Figure 9](#)). This feature allows the device to remain operational for a longer time but at a regressing output performance level at junction temperatures above 160 °C.

15.2.3 Output avalanche protection

An inductive flyback event, namely when the outputs are suddenly disabled and V+ is lost, could result in electrical overstress of the drivers. To prevent this, the V+ input to the 33887 should not exceed the maximum rating during a flyback condition. This may be done with either a zener clamp and/or an appropriately valued input capacitor with sufficiently low ESR.

15.2.4 Overtemperature shutdown and hysteresis

If an overtemperature condition occurs, the power outputs are 3-stated (latched off) and the fault status flag is set to logic low.

To reset from this condition, D1 must change from logic high to logic low, or $\overline{D2}$ must change from logic low to logic high. When reset, the output stage switches ON again,

provided that the junction temperature is now below the overtemperature threshold limit minus the hysteresis.

Important:

Resetting from the fault condition clears the fault status flag.

16 Typical applications

Figure 23 shows a typical application schematic. For precision high-current applications in harsh, noisy environments, the V+ bypass capacitor may need to be substantially larger.

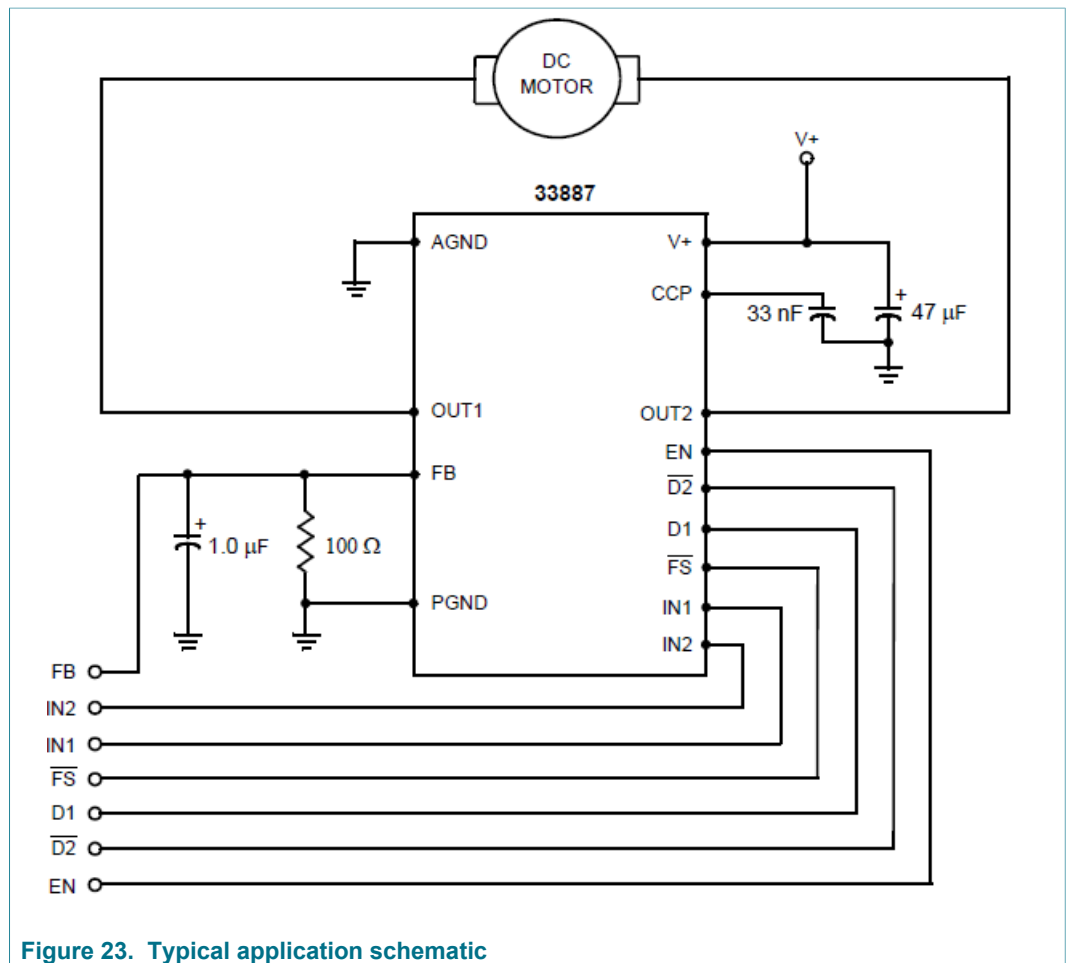


Figure 23. Typical application schematic

17 Packaging

17.1 Soldering information

The 33887 packages are designed for thermal performance. The significant feature of these packages is the exposed pad on which the power die is soldered. When soldered to a PCB, this pad provides a path for heat flow to the ambient environment. The more copper area and thickness on the PCB, the better the power dissipation and transient behavior.

Example characterization on a double-sided PCB: bottom side area of copper is 7.8 cm²; top surface is 2.7 cm² (see [Figure 24](#)); grid array of 24 vias 0.3 mm in diameter

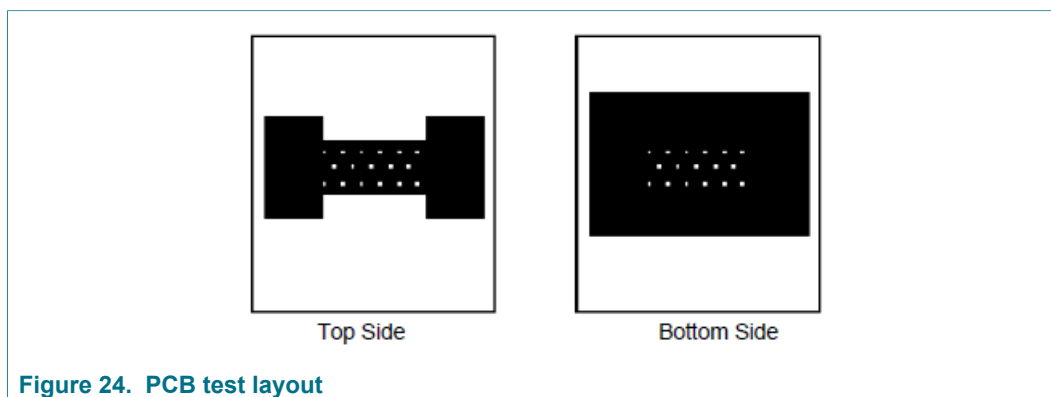


Figure 24. PCB test layout

17.2 Package outline

Important: The most current package outline is available at www.nxp.com.

