



Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from,Europe,America and south Asia,supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of “Quality Parts,Customers Priority,Honest Operation,and Considerate Service”,our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip,ALPS,ROHM,Xilinx,Pulse,ON,Everlight and Freescale. Main products comprise IC,Modules,Potentiometer,IC Socket,Relay,Connector.Our parts cover such applications as commercial,industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



**MC9S12H256**  
**Device User Guide**  
**V01.20**  
**Covers also MC9S12H128**

**Original Release Date: 29 SEP 2000**  
**Revised: 28 JUL 2008**

**Freescale Semiconductor Inc.**



# Revision History

Version Number	Revision Date	Effective Date	Author	Description of Changes
V01.00	07 MAR 2001	03 APR 2001		Initial version.
V01.01	10 MAI 2001	10 MAY 2001		- Minor formal corrections - Changed ATD coupling ratio to $10^{-2}$ - Changed $V_{DD5}$ to 4.5V
V01.02	14 MAY 2001	14 MAY 2001		- Removed 112-pin package references - Changed ATD Electrical Characteristics separate coupling ratio for positive and negative bulk current injection
V01.03	30 MAY 2001	30 MAY 2001		- Reinserted 112-pin package information.
V01.04	11 JUN 2001	11 JUN 2001		- Removed SRSv2 comment from preface - Corrected RESET pin to active low in table 2-1
V01.05	18 JUN 2001	18 JUN 2001		- Adapted style and wording to 9DP256 device user guide - Minor format and wording improvements - Added SRAM data retention disclaimer
V01.06	28 JUN 2001	28 JUN 2001		- Changed Oscillator Characteristics $t_{CQOUT}$ max 2.5s and replaced Clock Monitor Time-out by Clock Monitor Failure Assert Frequency - Changed Self Clock Mode Frequency min 1MHz and max 5.5MHz - Changed $I_{DDPS}$ (RTI and COP disabled) to 400 $\mu$ A - Corrected typo in Figure 2-1 pin 76: PK3 -> PK2
V01.07	12 JUL 2001	12 JUL 2001		- Added $t_{EXTR}$ and $t_{EXTF}$ to Oscillator Characteristics - Added typ value for $t_{UOSC}$ - Corrected $t_{EXTL}$ and $t_{EXTH}$ values - Updated thermal resistances as per Thermal Simulation Report, July 10, 2001
V01.08	16 JUL 2001	16 JUL 2001		- updated EEPROM size - added DC cutoff capacitor into layout proposals
V01.09	03 AUG 2001	03 AUG 2001		- minor updates
V01.10	29 AUG 2001	29 AUG 2001		- updated electrical spec

Freescale reserves the right to make changes without further notice to any products herein to improve reliability, function or design. Freescale does not assume any liability arising out of the application or use of any product or circuit described herein; neither does it convey any license under its patent rights nor the rights of others. Freescale products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Freescale product could create a situation where personal injury or death may occur. Should Buyer purchase or use Freescale products for any such unintended or unauthorized application, Buyer shall indemnify and hold Freescale and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Freescale was negligent regarding the design or manufacture of the part.

Version Number	Revision Date	Effective Date	Author	Description of Changes
V01.11	11 OCT 2001	11 OCT 2001		- Replaced references w.r.t. new family name HCS12. - Corrected XCLKS reference in CRG electrical spec.
V01.12	07 NOV 2001	07 NOV 2001		- added 'powered by' column in pin list table
V01.13	08 MAR 2002	08 MAR 2002		- new document numbering - removed document order number except from cover sheet - updated min VDD, VDDPLL - updated currents on $V_{OH}$ , $V_{OL}$ for standard pins - updated $C_{IN}$ , $I_{DD5}$ , $I_{REF}$ , $C_{INS}$ , $T_{EXTL}$ , $T_{EXTH}$ - included missing lcd electrical spec - updated NVM spec
V01.14	16 DEC 2002	16 DEC 2002		- updated input leakage - updated slew rate spec on PU,PV, PW - updated supply currents - included 1K78X - added detailed register map
V01.15	31 MAR 2003	31 MAR 2003		- added $K_1$ max value - added chragepump current min/max values
V01.16	05 NOV 2003	05 NOV 2003		- corrected pinout problem in LQFP112 layout proposal
V01.17	04 AUG 2004	04 AUG 2004		- added MC9S12H128
V01.18	13 AUG 2004	13 AUG 2004		- added Internal Pull Resistor columns to signal properties table
V01.19	05 NOV 2004	05 NOV 2004		- changed SPI0 to SPI, ATD0 to ATD
V01.20	28 JUL 2008	28 JUL 2008		- changed PU,PV,PW rise/fall times in EPP package at cold.



## Section 1 Introduction

1.1	Overview	17
1.2	Features	17
1.3	Modes of Operation	19
1.4	Block Diagram	20
1.5	Device Memory Map	24
1.5.1	Detailed Register Map	30
1.6	Part ID Assignments	53

## Section 2 Signal Description

2.1	Device Pinout	55
2.2	Signal Properties Summary	58
2.3	Detailed Signal Descriptions	60
2.3.1	EXTAL, XTAL — Oscillator Pins	60
2.3.2	RESET — External Reset Pin	60
2.3.3	TEST — Test Pin	60
2.3.4	XFC — PLL Loop Filter Pin	60
2.3.5	BKGD / TAGHI / MODC — Background Debug, Tag High, and Mode Pin	60
2.3.6	PAD[15:8] / AN[15:8] — Port AD Input Pins [15:8]	60
2.3.7	PAD[7:0] / AN[7:0] — Port AD Input Pins [7:0]	60
2.3.8	PA[7:0] / FP[15:8] / ADDR[15:8] / DATA[15:8] — Port A I/O Pins	60
2.3.9	PB[7:0] / FP[7:0] / ADDR[7:0] / DATA[7:0] — Port B I/O Pins	61
2.3.10	PE7 / FP22 / XCLKS / NOACC — Port E I/O Pin 7	61
2.3.11	PE6 / MODB / IPIPE1 — Port E I/O Pin 6	61
2.3.12	PE5 / MODA / IPIPE0 — Port E I/O Pin 5	61
2.3.13	PE4 / ECLK — Port E I/O Pin 4	61
2.3.14	PE3 / FP21 / LSTRB / TAGLO — Port E I/O Pin 3	61
2.3.15	PE2 / FP20 / R/W — Port E I/O Pin 2	62
2.3.16	PE1 / IRQ — Port E Input Pin 1	62
2.3.17	PE0 / XIRQ — Port E Input Pin 0	62
2.3.18	PH[7:0] / KWH[7:0] — Port H I/O Pins [7:0]	62
2.3.19	PJ[3:0] / KWJ[3:0] — Port J I/O Pins [3:0]	62
2.3.20	PK7 / FP23 / ECS / ROMONE — Port K I/O Pin 7	62
2.3.21	PK[3:0] / BP[3:0] / XADDR[17:14] — Port K I/O Pins [3:0]	62
2.3.22	PL[7:4] / FP[31:28] — Port L I/O Pins [7:4]	63
2.3.23	PL[3:0] / FP[19:16] — Port L I/O Pins [3:0]	63

2.3.24	PM5 / TXCAN1 — Port M I/O Pin 5	63
2.3.25	PM4 / RXCAN1 — Port M I/O Pin 4	63
2.3.26	PM3 / TXCAN0 — Port M I/O Pin 3	63
2.3.27	PM2 / RXCAN0 — Port M I/O Pin 2	63
2.3.28	PM1 / SCL — Port M I/O Pin 1	63
2.3.29	PM0 / SDA — Port M I/O Pin 0	63
2.3.30	PP[5:2] / PWM[5:2] — Port P I/O Pins [5:2]	64
2.3.31	PP[1:0] / PWM[1:0] — Port P I/O Pins [1:0]	64
2.3.32	PS7 / SS — Port S I/O Pin 7	64
2.3.33	PS6 / SCK — Port S I/O Pin 6	64
2.3.34	PS5 / MOSI — Port S I/O Pin 5	64
2.3.35	PS4 / MISO — Port S I/O Pin 4	64
2.3.36	PS3 / TXD1 — Port S I/O Pin 3	64
2.3.37	PS2 / RXD1 — Port S I/O Pin 2	64
2.3.38	PS1 / TXD0 — Port S I/O Pin 1	65
2.3.39	PS0 / RXD0 — Port S I/O Pin 0	65
2.3.40	PT[7:4] / IOC[7:4] — Port T I/O Pins [7:4]	65
2.3.41	PT[3:0] / IOC[3:0] / FP[27:24] — Port T I/O Pins [3:0]	65
2.3.42	PU[7:4] / M1C1P, M1C1M, M1C0P, M1C0M — Port U I/O Pins [7:4]	65
2.3.43	PU[3:0] / M0C1P, M0C1M, M0C0P, M0C0M — Port U I/O Pins [3:0]	65
2.3.44	PV[7:4] / M3C1P, M3C1M, M3C0P, M3C0M — Port V I/O Pins [7:4]	65
2.3.45	PV[3:0] / M2C1P, M2C1M, M2C0P, M2C0M — Port V I/O Pins [3:0]	66
2.3.46	PW[7:4] / M5C1P, M5C1M, M5C0P, M5C0M — Port W I/O Pins [7:4]	66
2.3.47	PW[3:0] / M4C1P, M4C1M, M4C0P, M4C0M — Port W I/O Pins [3:0]	66
2.4	Power Supply Pins	66
2.4.1	VDDR — External Power Pin	66
2.4.2	VDDX1, VDDX2, VSSX1, VSSX2 — External Power and Ground Pins	66
2.4.3	VDD1, VSS1, VSS2 — Core Power Pins	67
2.4.4	VDDA, VSSA — Power Supply Pins for ATD and VREG	67
2.4.5	VDDM1, VDDM2, VDDM3 — Power Supply Pins for Motor 0 to 5	67
2.4.6	VSSM1, VSSM2, VSSM3 — Ground Pins for Motor 0 to 5	67
2.4.7	VLCD — Power Supply Reference Pin for LCD driver	67
2.4.8	VRH, VRL — ATD Reference Voltage Input Pins	67
2.4.9	VDDPLL, VSSPLL — Power Supply Pins for PLL	67

## Section 3 System Clock Description

3.1	Overview.....	69
<b>Section 4 Modes of Operation</b>		
4.1	Overview.....	71
4.2	Modes of Operation .....	71
4.2.1	Normal Operating Modes.....	72
4.2.2	Special Operating Modes.....	74
4.2.3	Test Operating Mode (Freescale Use Only) .....	75
4.3	Security.....	76
4.3.1	Securing the Microcontroller.....	76
4.3.2	Operation of the Secured Microcontroller.....	76
4.3.3	Unsecuring the Microcontroller.....	76
4.4	Low Power Modes .....	77
<b>Section 5 Resets and Interrupts</b>		
5.1	Overview.....	79
5.2	Vectors .....	79
5.2.1	Vector Table.....	79
5.3	Effects of Reset.....	80
5.3.1	I/O pins.....	80
5.3.2	Memory .....	81
<b>Section 6 HCS12 Core Block Description</b>		
<b>Section 7 Clock and Reset Generator (CRG) Block Description</b>		
7.1	Device-specific information .....	83
7.1.1	XCLKS.....	83
<b>Section 8 Timer (TIM) Block Description</b>		
<b>Section 9 Analog to Digital Converter (ATD) Block Description</b>		
<b>Section 10 Inter-IC Bus (IIC) Block Description</b>		
<b>Section 11 Serial Communications Interface (SCI) Block Description</b>		
<b>Section 12 Serial Peripheral Interface (SPI) Block Description</b>		



Section 13 Pulse Width Modulator (PWM) Block Description

Section 14 Flash EEPROM 256K Block Description

Section 15 EEPROM 4K Block Description

Section 16 RAM Block Description

Section 17 Liquid Crystal Display Driver (LCD) Block Description

Section 18 MSCAN Block Description

Section 19 PWM Motor Control (MC) Block Description

Section 20 Port Integration Module (PIM) Block Description

Section 21 Voltage Regulator (VREG) Block Description

21.1	Device-specific information	85
21.1.1	VREGEN	85
21.1.2	Modes of Operation	85
21.2	Recommended PCB layout	86

Appendix A Electrical Characteristics

A.1	General	89
A.1.1	Parameter Classification	89
A.1.2	Power Supply	89
A.1.3	Pins	90
A.1.4	Current Injection	90
A.1.5	Absolute Maximum Ratings	91
A.1.6	ESD Protection and Latch-up Immunity	92
A.1.7	Operating Conditions	93
A.1.8	Power Dissipation and Thermal Characteristics	93
A.1.9	I/O Characteristics	94
A.1.10	Supply Currents	97
A.2	ATD Characteristics	99
A.2.1	ATD Operating Characteristics	99
A.2.2	Factors influencing accuracy	99

A.2.3	ATD accuracy .....	101
A.3	NVM, Flash and EEPROM .....	103
A.3.1	NVM timing .....	103
A.3.2	NVM Reliability .....	104
A.4	Reset, Oscillator and PLL .....	107
A.4.1	Startup .....	107
A.4.2	Oscillator .....	108
A.4.3	Phase Locked Loop .....	109
A.5	MSCAN .....	113
A.6	SPI .....	115
A.6.1	Master Mode .....	115
A.6.2	Slave Mode .....	117
A.7	LCD_32F4B .....	119
A.8	External Bus Timing .....	121
A.8.1	General Muxed Bus Timing .....	121

## Appendix B Package Information

B.1	General .....	125
B.2	112-pin LQFP package .....	126
B.3	144-pin LQFP package .....	127



Figure 1-1	MC9S12H256 Block Diagram. . . . .	21
Figure 1-2	MC9S12H128 Block Diagram. . . . .	23
Figure 1-3	MC9S12H256 Memory Map. . . . .	27
Figure 1-4	MC9S12H128 Memory Map. . . . .	29
Figure 2-1	Pin Assignments in 112-pin LQFP for MC9S12H256 and MC9S12H128. . . . .	56
Figure 2-2	Pin Assignments in 144-pin LQFP for MC9S12H256 . . . . .	57
Figure 3-1	Clock Connections. . . . .	69
Figure 21-1	LQFP112 recommended PCB layout. . . . .	86
Figure 21-2	LQFP144 recommended PCB layout. . . . .	87
Figure A-1	ATD Accuracy Definitions . . . . .	102
Figure A-2	Basic PLL functional diagram. . . . .	109
Figure A-3	Jitter Definitions. . . . .	111
Figure A-4	Maximum bus clock jitter approximation . . . . .	111
Figure A-5	SPI Master Timing (CPHA = 0) . . . . .	115
Figure A-6	SPI Master Timing (CPHA =1) . . . . .	116
Figure A-7	SPI Slave Timing (CPHA = 0) . . . . .	117
Figure A-8	SPI Slave Timing (CPHA =1) . . . . .	117
Figure A-9	General External Bus Timing . . . . .	122
Figure B-1	112-pin LQFP mechanical dimensions (case no. 987) . . . . .	126
Figure B-2	144-pin LQFP mechanical dimensions (case no. 918-03). . . . .	127



Table 0-1	Document References . . . . .	15
Table 1-1	Device Memory Map MC9S12H256 . . . . .	26
Table 1-2	Device Memory Map MC9S12H128 . . . . .	27
Table 1-3	Detailed MSCAN Foreground Receive and Transmit Buffer Layout. . . . .	44
Table 1-4	Detailed MSCAN Foreground Receive and Transmit Buffer Layout. . . . .	46
Table 1-5	Assigned Part ID Numbers . . . . .	53
Table 1-6	Memory size registers . . . . .	54
Table 2-1	Signal Properties . . . . .	58
Table 4-1	Mode Selection . . . . .	71
Table 5-1	Reset and Interrupt Vector Table . . . . .	79
Table 21-1	Recommended Components . . . . .	88
Table A-1	Absolute Maximum Ratings . . . . .	91
Table A-2	ESD and Latch-up Test Conditions. . . . .	92
Table A-3	ESD and Latch-Up Protection Characteristics . . . . .	92
Table A-4	Operating Conditions . . . . .	93
Table A-5	Thermal Package Characteristics . . . . .	94
Table A-6	5V I/O Characteristics. . . . .	96
Table A-7	Supply Current Characteristics . . . . .	98
Table A-8	ATD Operating Characteristics. . . . .	99
Table A-9	ATD Electrical Characteristics . . . . .	100
Table A-10	ATD Conversion Performance. . . . .	101
Table A-11	NVM Timing Characteristics. . . . .	104
Table A-12	NVM Reliability Characteristics. . . . .	105
Table A-13	Startup Characteristics. . . . .	107
Table A-14	Oscillator Characteristics . . . . .	108
Table A-15	PLL Characteristics . . . . .	112
Table A-16	MSCAN Wake-up Pulse Characteristics . . . . .	113
Table A-17	SPI Master Mode Timing Characteristics. . . . .	116
Table A-18	SPI Slave Mode Timing Characteristics . . . . .	118
LCD_32F4B	Driver Electrical Characteristics	119
Table A-20	Expanded Bus Timing Characteristics. . . . .	123



## Preface

The Device User Guide provides information about the MC9S12H256 and MC9S12H128 device made up of standard HCS12 blocks and the HCS12 processor core.

This document is part of the customer documentation. A complete set of device manuals also includes the HCS12 Core User Guide and all the individual Block User Guides of the implemented modules. In an effort to reduce redundancy all module specific information is located only in the respective Block User Guide. If applicable, special implementation details of the module are given in the block description sections of this document.

See **Table 0-1** for names and versions of the referenced documents throughout the Device User Guide.

**Table 0-1 Document References**

User Guide	Version	Document Order Number
HCS12 V1.5 Core User Guide	1.2	HCS12COREUG
CRG Block User Guide	V02	S12CRGV2/D
TIM_16B8C Block User Guide	V01	S12TIM16B8CV1/D
ATD_10B16C Block User Guide	V02	S12ATD10B16CV2/D
IIC Block User Guide	V02	S12IICV2/D
SCI Block User Guide	V02	S12SCIV2/D
SPI Block User Guide	V02	S12SPIV2/D
PWM_8B6C Block User Guide	V01	S12PWM8B6CV1/D
FTS256K Block User Guide	V02	S12FTS256KV2/D
EETS4K Block User Guide	V02	S12EETS4KV2/D
LCD_32F4B Block User Guide	V01	S12LCD32F4BV1/D
MSCAN Block User Guide	V02	S12MSCANV2/D
MC_10B12C Block User Guide	V02	S12MC10B12CV2/D
PIM_9H256 Block User Guide	V01	S12PIMH256V1/D
VREG Block User Guide	V01	S12VREGV1/D





# Section 1 Introduction

## 1.1 Overview

The MC9S12H256 microcontroller unit (MCU) is a 16-bit device composed of standard on-chip peripherals including a 16-bit central processing unit (HCS12 CPU), 256K bytes of Flash EEPROM, 12K bytes of RAM, 4K bytes of EEPROM, two asynchronous serial communications interfaces (SCI), a serial peripheral interface (SPI), an IIC-bus interface (IIC), an 8-channel 16-bit timer (TIM), a 16-channel, 10-bit analog-to-digital converter (ATD), a six-channel pulse width modulator (PWM), and two CAN 2.0 A, B software compatible modules (MSCAN).

The MC9S12H128 microcontroller unit (MCU) is a 16-bit device composed of standard on-chip peripherals including a 16-bit central processing unit (HCS12 CPU), 128K bytes of Flash EEPROM, 6K bytes of RAM, 2K bytes of EEPROM, one asynchronous serial communications interface (SCI), a serial peripheral interface (SPI), an IIC-bus interface (IIC), an 8-channel 16-bit timer (TIM), a 8-channel, 10-bit analog-to-digital converter (ATD), a two-channel pulse width modulator (PWM), and two CAN 2.0 A, B software compatible modules (MSCAN).

In addition, it features a 32x4 liquid crystal display (LCD) controller/driver and a motor pulse width modulator (MC) consisting of 24 high current outputs suited to drive up to 6 stepper motors. System resource mapping, clock generation, interrupt control, and bus interfacing are managed by the HCS12 Core.

The MC9S12H256 has full 16-bit data paths throughout. The inclusion of a PLL circuit allows power consumption and performance to be adjusted to suit operational requirements. In addition to the I/O ports available in each module, 12 general purpose I/O pins are available with interrupt and wake-up capability from STOP or WAIT mode.

## 1.2 Features

- HCS12 Core
  - 16-bit HCS12 CPU
    - i. Upward compatible with M68HC11 instruction set
    - ii. Interrupt stacking and programmer's model identical to M68HC11
    - iii. 20-bit ALU
    - iv. Instruction queue
    - v. Enhanced indexed addressing
  - MEBI (Multiplexed External Bus Interface)
  - MMC (Module Mapping Control)
  - INT (Interrupt control)
  - BKP (Breakpoints)

- BDM (Background Debug Mode)
- CRG (low current oscillator, PLL, reset, clocks, COP watchdog, real time interrupt, clock monitor)
- 8-bit and 4-bit ports with interrupt functionality
  - Digital filtering
  - Programmable rising or falling edge trigger
- Memory
  - 128K, 256K Flash EEPROM
  - 2K, 4K byte EEPROM
  - 6K, 12K byte RAM
- Analog-to-Digital Converter
  - 8, 16 channels, 10-bit resolution
  - External conversion trigger capability
- Two 1M bit per second, CAN 2.0 A, B software compatible modules
  - Five receive and three transmit buffers
  - Flexible identifier filter programmable as 2 x 32 bit, 4 x 16 bit or 8 x 8 bit
  - Four separate interrupt channels for Rx, Tx, error and wake-up
  - Low-pass filter wake-up function
  - Loop-back for self test operation
- Timer
  - 16-bit main counter with 7-bit prescaler
  - 8 programmable input capture or output compare channels
  - Two 8-bit or one 16-bit pulse accumulators
- 2, 6 PWM channels
  - Programmable period and duty cycle
  - 8-bit 2, 6-channel or 16-bit 1, 3-channel
  - Separate control for each pulse width and duty cycle
  - Center-aligned or left-aligned outputs
  - Programmable clock select logic with a wide range of frequencies
  - Fast emergency shutdown input
- Serial interfaces
  - Two asynchronous Serial Communications Interfaces (SCI)
  - Synchronous Serial Peripheral Interface (SPI)

- Inter-Integrated Circuit interface (IIC)
- Liquid Crystal Display driver with variable input voltage
  - Configurable for up to 32 frontplanes and 4 backplanes or general purpose input or output
  - 5 modes of operation allow for different display sizes to meet application requirements
  - Unused frontplane and backplane pins can be used as general purpose I/O
- 16, 24 high current drivers suited for PWM motor control
  - Each PWM channel switchable between two drivers in an H-bridge configuration
  - Left, right and center aligned outputs
  - Support for sine and cosine drive
  - Dithering
  - Output slew rate control
- 144-Pin or 112-Pin LQFP package
  - I/O lines with 5V input and drive capability
  - 5V A/D converter inputs
  - Operation at 32MHz equivalent to 16MHz Bus Speed
  - Development support
  - Single-wire background debug™ mode (BDM)
  - On-chip hardware breakpoints

## 1.3 Modes of Operation

### User modes

- Normal and Emulation Operating Modes
  - Normal Single-Chip Mode
  - Normal Expanded Wide Mode
  - Normal Expanded Narrow Mode
  - Emulation Expanded Wide Mode
  - Emulation Expanded Narrow Mode
- Special Operating Modes
  - Special Single-Chip Mode with active Background Debug Mode
  - Special Test Mode (**Freescale Use Only**)
  - Special Peripheral Mode (**Freescale Use Only**)

### Low power modes

- Stop Mode
- Pseudo Stop Mode
- Wait Mode

## 1.4 Block Diagram

**Figure 1-1** is a block diagram of the MC9S12H256 device.

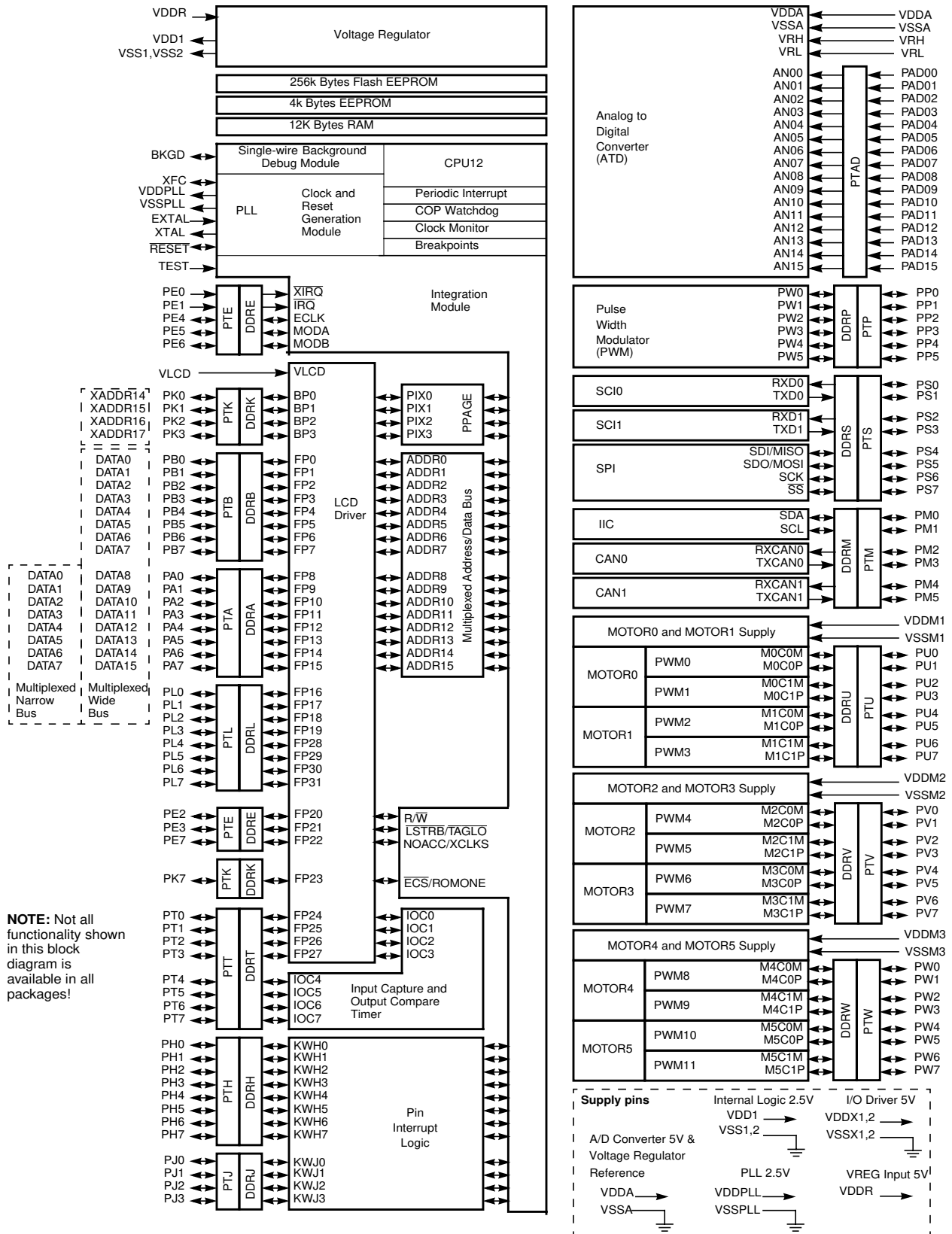


Figure 1-1 MC9S12H256 Block Diagram

**Figure 1-2** is a block diagram of the MC9S12H128 device.

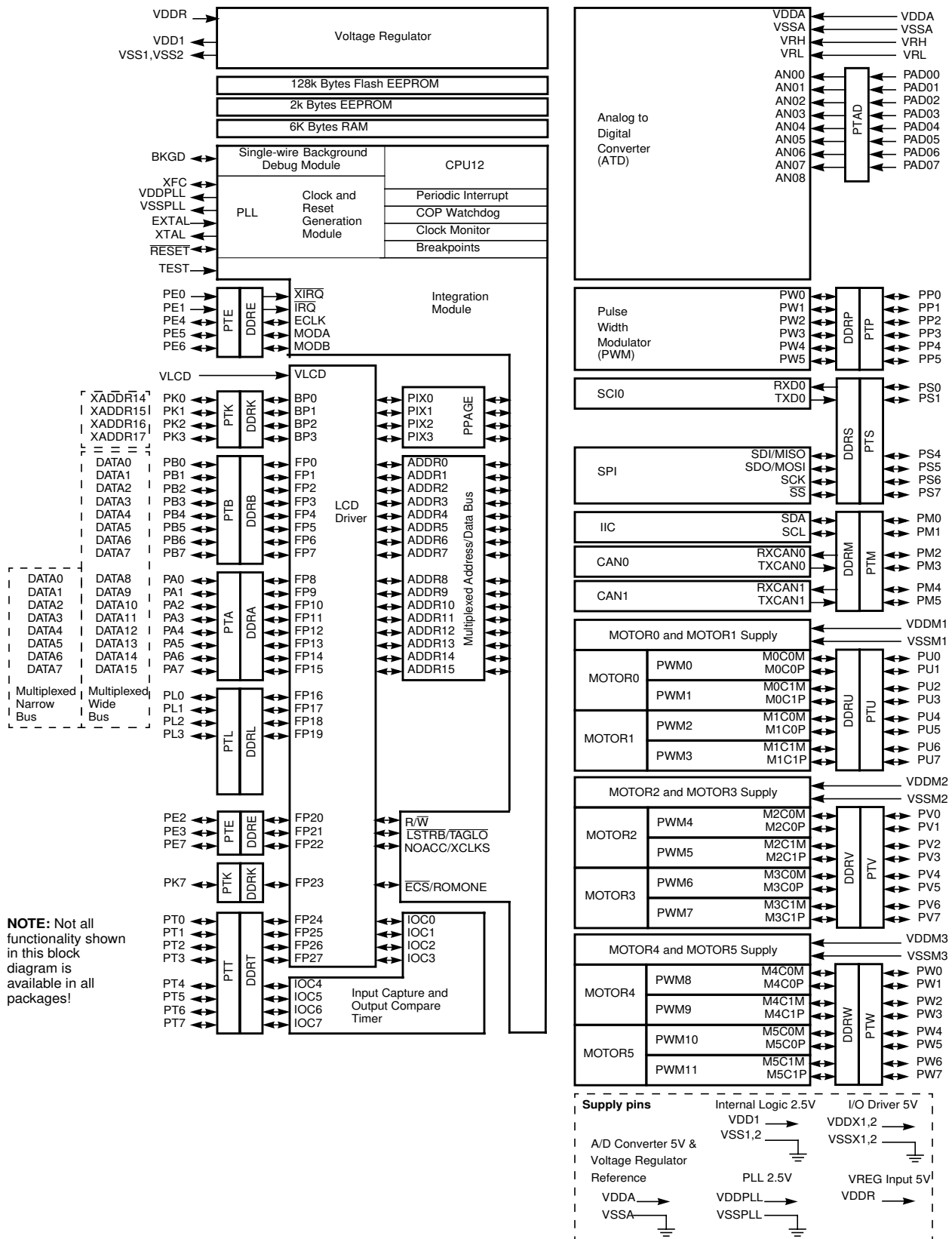


Figure 1-2 MC9S12H128 Block Diagram



## 1.5 Device Memory Map

