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## Thyristor Modules <br> Thyristor/Diode Modules

| $\mathrm{V}_{\text {RSM }}$ | $\mathrm{V}_{\text {RRM }}$ | Type |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {DSM }}$ | $\mathrm{V}_{\text {DRM }}$ |  |  |  |  |  |
| V | V | Version | 1 B | 8 B | Version | 1 B 8 B |
| 900 | 800 | MCC 72-08 | io1 B | 08 B | MCD 72-08 | io1 B/io8 B |
| 1300 | 1200 | MCC 72-12 | io1 B | 08 B | MCD 72-12 | io1 B /io8 B |
| 1500 | 1400 | MCC 72-14 | io1 B |  | MCD 72-1 | io1 B /io8 B |
| 1700 | 1600 | MCC 72-16 | io1 B | 08 B | MCD 72-16 | io1 B /io8 B |
| 1900 | 1800 | MCC 72-18 | io1 B | 08 B | MCD 72-1 | io1 B /io8 B |


| Symbol | Conditions |  | Maximum Ratings |  |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{\text {TRMS }}, \mathrm{I}_{\text {FRMS }}$ $\mathrm{I}_{\text {TAVM, }}, \mathrm{I}_{\text {FAVM }}$ | $\mathrm{T}_{\mathrm{vJ}}=\mathrm{T}_{\text {vjM }}$ |  | 180 A |  |
|  | $\mathrm{T}_{\mathrm{C}}=63^{\circ} \mathrm{C} ; 180^{\circ}$ sine |  | 115 | A |
|  | $\mathrm{T}_{\mathrm{C}}=85^{\circ} \mathrm{C} ; 180^{\circ}$ sine |  | 85 A |  |
| $\mathrm{I}_{\text {TSM }}, \mathrm{I}_{\text {FSM }}$ | $\mathrm{T}_{\text {vJ }}=45^{\circ} \mathrm{C}$ | $\mathrm{t}=10 \mathrm{~ms}(50 \mathrm{~Hz})$, sine | 1700 | A |
|  | $\mathrm{V}_{\mathrm{R}}=0$ | $\mathrm{t}=8.3 \mathrm{~ms}(60 \mathrm{~Hz})$, sine | 1800 | A |
|  | $\mathrm{T}_{\mathrm{VJ}}=\mathrm{T}_{\text {vıM }}$ | $\mathrm{t}=10 \mathrm{~ms}(50 \mathrm{~Hz})$, sine | 1540 | A |
|  | $\mathrm{V}_{\mathrm{R}}=0$ | $\mathrm{t}=8.3 \mathrm{~ms}(60 \mathrm{~Hz})$, sine | 1640 | A |
| $\int i^{2} d t$ | $\begin{aligned} & \mathrm{T}_{\mathrm{VJ}}=45^{\circ} \mathrm{C} \\ & \mathrm{~V}_{\mathrm{R}}=0 \end{aligned}$ | $t=10 \mathrm{~ms}(50 \mathrm{~Hz})$, sine $\mathrm{t}=8.3 \mathrm{~ms}(60 \mathrm{~Hz})$, sine | $\begin{aligned} & 14450 \\ & 13500 \end{aligned}$ | $\begin{aligned} & \mathrm{A}^{2} \mathrm{~S} \\ & \mathrm{~A}^{2} \mathrm{~S} \end{aligned}$ |
|  |  |  |  |  |
|  | $\mathrm{T}_{\mathrm{VJ}}=\mathrm{T}_{\text {vjM }}$ | $\mathrm{t}=10 \mathrm{~ms} \mathrm{(50} \mathrm{Hz)}$, | 11850 | $\mathrm{A}^{2} \mathrm{~S}$ |
|  | $\mathrm{V}_{\mathrm{R}}=0$ | $\mathrm{t}=8.3 \mathrm{~ms}(60 \mathrm{~Hz})$, sine | 11300 | $A^{2} \mathrm{~s}$ |
| (di/dt) ${ }_{\text {cr }}$ | $\begin{aligned} & \mathrm{T}_{\mathrm{VJ}}=\mathrm{T}_{\mathrm{VJM}} \\ & \mathrm{f}=50 \mathrm{~Hz} ; \mathrm{t}_{\mathrm{P}}=200 \mu \mathrm{~s} \end{aligned}$ | repetitive, $\mathrm{I}_{T}=250 \mathrm{~A}$ | 150 | A/ $/ \mathrm{s}$ |
|  | $\begin{aligned} & \mathrm{V}_{\mathrm{D}}=2 / 3 \mathrm{~V}_{\text {DRM }} \\ & \mathrm{I}_{\mathrm{G}}=0.45 \mathrm{~A} \\ & \mathrm{di}_{\mathrm{G}} / \mathrm{dt}=0.45 \mathrm{~A} / \mathrm{\mu s} \end{aligned}$ | non repetitive, $\mathrm{I}_{\mathrm{T}}=\mathrm{I}_{\text {TAVM }}$ | 500 | A/ $/$ s |
| (dv/dt) ${ }_{\text {cr }}$ | $\begin{array}{lc} \hline \mathrm{T}_{\mathrm{VJ}}=\mathrm{T}_{\mathrm{VJM}} ; & \mathrm{V}_{\mathrm{DR}}=2 / 3 \mathrm{~V}_{\mathrm{DRM}} \\ \mathrm{R}_{\mathrm{GK}}=\infty ; \text { method } 1 \text { (linear voltage rise) } \end{array}$ |  | 1000 | V/us |
| $\mathbf{P}_{\text {GM }}$ | $\begin{aligned} & \mathrm{T}_{\mathrm{VJ}}=\mathrm{T}_{\mathrm{VJMM}} ; \\ & \mathrm{I}_{\mathrm{T}}=\mathrm{I}_{\mathrm{TAVM} ;} ; \end{aligned}$ | $\begin{aligned} & \mathrm{t}_{\mathrm{p}}=30 \mu \mathrm{~s} \\ & \mathrm{t}_{\mathrm{p}}=300 \mu \mathrm{~s} \end{aligned}$ | $\begin{array}{r} 10 \\ 5 \end{array}$ | WW |
|  |  |  |  |  |
| $\mathbf{P}_{\text {GAV }}$ |  |  | 0.5 | W |
| $\mathrm{V}_{\text {RGM }}$ |  |  | 10 | V |
| $\mathrm{T}_{\mathrm{v}}$ |  |  | $-40 \ldots+125 \quad{ }^{\circ} \mathrm{C}$ |  |
| $\mathrm{T}_{\text {vJM }}$ |  |  | $125{ }^{\circ} \mathrm{C}$ |  |
| $\mathrm{T}_{\text {stg }}$ |  |  | -40...+125 ${ }^{\circ} \mathrm{C}$ |  |
| $\mathrm{V}_{\text {ISOL }}$ | 50/60 Hz, RMS;$\mathrm{I}_{\mathrm{ISOL}} \leq 1 \mathrm{~mA} \text {; }$ | $\begin{aligned} & t=1 \mathrm{~min} \\ & t=1 \mathrm{~s} \end{aligned}$ | $\begin{aligned} & 3000 \\ & 3600 \end{aligned}$ | VV |
|  |  |  |  |  |
| $\mathrm{M}_{\text {d }}$ | Mounting torque (M5) |  | 2.5-4.0/22-35 Nm/lb.in. |  |
|  | Terminal connection torque (M5) |  | 2.5-4.0/22-35 Nm/lb.in. |  |
| Weight | Typical including screws |  | 90 | g |

Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated.

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\(\mathrm{I}_{\text {trms }}=2 \times 180 \mathrm{~A}\)
\(\mathrm{I}_{\text {TAVM }}=2 \times 115 \mathrm{~A}\)
\(V_{\text {RRM }}=800-1800 \mathrm{~V}\)
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MCC
Version 1 B


MCC
Version 8 B


MCD
Version 8 B


## Features

- International standard package, JEDEC TO-240 AA
- Direct copper bonded $\mathrm{Al}_{2} \mathrm{O}_{3}$-ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- UL registered, E 72873
- Gate-cathode twin pins for version 1B


## Applications

- DC motor control
- Softstart AC motor controller
- Light, heat and temperature control


## Advantages

- Space and weight savings
- Simple mounting with two screws
- Improved temperature and power cycling
- Reduced protection circuits

Symbol


| $\mathrm{t}_{\mathrm{q}}$ | $\mathrm{T}_{\mathrm{VJ}}=\mathrm{T}_{\mathrm{V}, \mathrm{m} ;} ; \mathrm{I}_{\mathrm{T}}=150 \mathrm{~A}, \mathrm{t}_{\mathrm{P}}=200 \mu \mathrm{~s} ;-\mathrm{d} / \mathrm{dt}=10 \mathrm{~A} / \mu \mathrm{s}$ | typ. 185 | $\mu \mathrm{~s}$ |
| :--- | :--- | :--- | :--- | :--- |
| $\mathrm{~V}_{\mathrm{R}}=100 \mathrm{~V} ; \mathrm{dv} / \mathrm{dt}=20 \mathrm{~V} / \mu \mathrm{s} ; \mathrm{V}_{\mathrm{D}}=2 / 3 \mathrm{~V}_{\text {DRM }}$ |  |  |  |


| $\begin{aligned} & \mathbf{Q}_{\mathrm{S}} \\ & \mathbf{I}_{\mathrm{RM}} \end{aligned}$ | $\mathrm{T}_{\mathrm{VJ}}=\mathrm{T}_{\mathrm{V} \text { M }} ; \mathrm{I}_{\mathrm{T}} / \mathrm{I}_{\mathrm{F}}=50 \mathrm{~A},-\mathrm{di} / \mathrm{dt}=6 \mathrm{~A} / \mu \mathrm{s}$ | 170 45 | $\begin{gathered} \mu \mathrm{C} \\ \mathrm{~A} \end{gathered}$ |
| :---: | :---: | :---: | :---: |
| $\mathrm{R}_{\mathrm{thJc}}$ | per thyristor/diode; DC current <br> per module <br> other values | 0.3 0.15 | $\begin{aligned} & \text { K/W } \\ & \text { K/W } \end{aligned}$ |
| $\mathrm{R}_{\text {thJK }}$ | per thyristor/diode; DC current $\int$ see Fig. 8/9 per module | $\begin{array}{r} 0.5 \\ 0.25 \end{array}$ | $\begin{aligned} & \text { K/W } \\ & \text { K/W } \end{aligned}$ |
| $\mathrm{d}_{\text {s }}$ | Creepage distance on surface | 12.7 | mm |
| $\mathrm{d}_{\mathrm{A}}$ | Strike distance through air | 9.6 | mm |
| a | Maximum allowable acceleration | 50 | $\mathrm{m} / \mathrm{s}^{2}$ |

Optional accessories for module-type MCC 72 version 1 B
Keyed gate/cathode twin plugs with wire length $=350 \mathrm{~mm}$, gate $=$ yellow, cathode $=$ red
Type ZY 200L (L = Left for pin pair 4/5) UL 758, style 1385,
Type ZY 200R ( $\mathrm{R}=$ right for pin pair 6/7) $\}$ CSA class 5851, guide 460-1-1


Fig. 1 Gate trigger characteristics


Fig. 2 Gate trigger delay time


MCD Version 8 B



Fig. 3 Surge overload current




Fig. 4a Maximum forward current at case temperature

Fig. 5 Power dissipation versus onstate current and ambient temperature (per thyristor or diode)

Fig. 6 Three phase rectifier bridge: Power dissipation versus direct output current and ambient temperature

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Fig. 7 Three phase AC-controller: Power dissipation versus RMS output current and ambient temperature

Fig. 8 Transient thermal impedance junction to case (per thyristor or diode)
$R_{\text {thJc }}$ for various conduction angles d :

| d | $\mathrm{R}_{\text {thJc }}(\mathrm{K} / \mathrm{W})$ |
| :---: | :--- |
| DC | 0.3 |
| $180^{\circ}$ | 0.31 |
| $120^{\circ}$ | 0.33 |
| $60^{\circ}$ | 0.35 |
| $30^{\circ}$ | 0.37 |

Constants for $Z_{\text {thJc }}$ calculation:

| i | $\mathrm{R}_{\mathrm{tti}}(\mathrm{K} / \mathrm{W})$ | $\mathrm{t}_{\mathrm{i}}(\mathrm{s})$ |
| :--- | :--- | :--- |
| 1 | 0.008 | 0.0019 |
| 2 | 0.054 | 0.047 |
| 3 | 0.238 | 0.3 |

Fig. 9 Transient thermal impedance junction to heatsink (per thyristor or diode)
$\mathrm{R}_{\mathrm{t} \mathrm{JJK}}$ for various conduction angles d :

| d | $\mathrm{R}_{\mathrm{thJK}}(\mathrm{K} / \mathrm{W})$ |
| :---: | :--- |
| DC | 0.5 |
| $180^{\circ}$ | 0.51 |
| $120^{\circ}$ | 0.53 |
| $60^{\circ}$ | 0.55 |
| $30^{\circ}$ | 0.57 |

Constants for $Z_{\text {thJk }}$ calculation:

| i | $\mathrm{R}_{\mathrm{tti}}(\mathrm{K} / \mathrm{W})$ | $\mathrm{t}_{\mathrm{i}}(\mathrm{s})$ |
| :---: | :--- | :--- |
| 1 | 0.008 | 0.0019 |
| 2 | 0.054 | 0.047 |
| 3 | 0.238 | 0.3 |
| 4 | 0.2 | 1.25 |

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