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Freescale Semiconductor

Data Sheet: Technical Data

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MCF523x Integrated Microprocessor Hardware Specification

by: Microcontroller Solutions Group

The MCF523*x* is a family of highly-integrated 32-bit microcontrollers based on the V2 ColdFire microarchitecture. Featuring a 16 or 32 channel eTPU, 64 Kbytes of internal SRAM, a 2-bank SDRAM controller, four 32-bit timers with dedicated DMA, a 4 channel DMA controller, up to 2 CAN modules, 3 UARTs and a queued SPI, the MCF523*x* family has been designed for general purpose industrial control applications. It is also a high-performance upgrade for users of the MC68332. This document provides an overview of the MCF523*x* microcontroller family, as well as detailed descriptions of the mechanical and electrical characteristics of the devices.

The MCF523*x* family is based on the Version 2 ColdFire reduced instruction set computing (RISC) microarchitecture operating at a core frequency of up to 150 MHz and bus frequency up to 75 MHz.

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1 MCF523*x* Family Configurations

Table 1.	MCF523 <i>x</i>	Family	Config	gurations
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Module	MCF5232	MCF5233	MCF5234	MCF5235
ColdFire V2 Core with EMAC (Enhanced Multiply-Accumulate Unit)	х	Х	Х	Х
Enhanced Time Processor Unit with memory (eTPU)	16-ch 6K	32-ch 6K	16-ch 6K	32-ch 6K
System Clock		up to 1	50 MHz	
Performance (Dhrystone/2.1 MIPS)		up to	144	
Instruction/Data Cache		8 Kb	oytes	
Static RAM (SRAM)		64 K	oytes	
Interrupt Controllers (INTC)	2	2	2	2
Edge Port Module (EPORT)	х	х	х	х
External Interface Module (EIM)	х	х	х	х
4-channel Direct-Memory Access (DMA)	х	х	х	х
SDRAM Controller	х	х	х	х
Fast Ethernet Controller (FEC)	_	_	х	х
Cryptography - Security module for data packets processing	_	_	_	х
Watchdog Timer (WDT)	х	х	х	х
Four Periodic Interrupt Timers (PIT)	х	х	х	х
32-bit DMA Timers	4	4	4	4
QSPI	х	х	х	х
UART(s)	3	3	3	3
I ² C	х	х	х	х
FlexCAN 2.0B - Controller-Area Network communication module	1	2	1	2
General Purpose I/O Module (GPIO)	х	х	х	х
JTAG - IEEE 1149.1 Test Access Port	х	х	х	х
Package	160 QFP 196 MAPBGA	256 MAPBGA	256 MAPBGA	256 MAPBGA

2 Block Diagram

The superset device in the MCF523*x* family comes in a 256 mold array process ball grid array (MAPBGA) package. Figure shows a top-level block diagram of the MCF5235, the superset device.

Features



3 Features

For a detailed feature list see the MCF5235 Reference Manual (MCF5235RM).

4 Signal Descriptions

This section describes signals that connect off chip, including a table of signal properties. For a more detailed discussion of the MCF523*x* signals, consult the *MCF5235 Reference Manual* (MCF5235RM).

4.1 Signal Properties

Table 2 lists all of the signals grouped by function. The "Dir" column is the direction for the primary function of the pin. Refer to Section 6, "Mechanicals/Pinouts and Part Numbers," for package diagrams.

NOTE

In this table and throughout this document a single signal within a group is designated without square brackets (i.e., A24), while designations for multiple signals within a group use brackets (i.e., A[23:21]) and is meant to include all signals within the two bracketed numbers when these numbers are separated by a colon.

NOTE

The primary functionality of a pin is not necessarily its default functionality. Pins that are muxed with GPIO will default to their GPIO functionality.

Signal Name	GPIO	Alternate 1	Alternate 2	Dir. ¹	MCF5232 160 QFP	MCF5232 196 MAPBGA	MCF5233 256 MAPBGA	MCF5234 256 MAPBGA	MCF5235 256 MAPBGA
				R	eset				
RESET	_			I	83	N13	T15	T15	T15
RSTOUT	_	—	—	0	82	P13	T14	T14	T14
				С	lock				
EXTAL	_	_	_	I	86	M14	P16	P16	P16
XTAL	_			0	85	N14	R16	R16	R16
CLKOUT	_	_	_	0	89	K14	M16	M16	M16
			Ν	Node S	Selection				
CLKMOD[1:0]	_	_	_	I	19,20	G5, H5	J3, J2	J3, J2	J3, J2
RCON	_	—	—	I	79	K10	P13	P13	P13
			External Me	emory	Interface and	Ports			
A[23:21]	PADDR[7:5]	<u>CS</u> [6:4]	—	0	126, 125, 124	B11, C11, D11	B14, C14, A15	B14, C14, A15	B14, C14, A15

Table 2. MCF523x Signal Information and Muxing

Signal Name	GPIO	Alternate 1	Alternate 2	Dir. ¹	MCF5232 160 QFP	MCF5232 196 MAPBGA	MCF5233 256 MAPBGA	MCF5234 256 MAPBGA	MCF5235 256 MAPBGA
A[20:0]	_		_	0	123:115, 112:106, 102:98	A12, B12, C12, A13, B13, B14, C13, C14, D12, D13, D14, E11, E12, E13, E14, F12, F13, F14, G11, G12, G13	B15, B16, C15, C16, D16, D15, D14, E16, E15, E14, E13, F15, F14, F13, G15, G14, G13, H16, H15, H14, H13	B15, B16, C15, C16, D16, D15, D14, E16, E15, E14, E13, F15, F14, F13, G15, G14, G13, H16, H15, H14, H13	B15, B16, C15, C16, D16, D15, D14, E16, E15, E14, E13, F15, F14, F13, G15, G14, G13, H16, H15, H14, H13
D[31:16]	_	_	_	0	21:24,26:30, 33:39	G1, G2, H1, H2, H3, H4, J1, J2, J3, J4, K1, K2, K3, K4, L1, L2	K4, K3, K2, K1, L4, L3, L2, L1, M3, M2, M1, N2, N1, P2, P1, R1	K4, K3, K2, K1, L4, L3, L2, L1, M3, M2, M1, N2, N1, P2, P1, R1	K4, K3, K2, K1, L4, L3, L2, L1, M3, M2, M1, N2, N1, P2, P1, R1
D[15:8]	PDATAH[7:0]	_	—	0	42:49,	M1, N1, M2, N2, P2, L3, M3, N3,	R2, T2, N3, P3, R3, T3, N4, P4,	R2, T2, N3, P3, R3, T3, N4, P4,	R2, T2, N3, P3, R3, T3, N4, P4,
D[7:0]	PDATAL[7:0]	_	_	0	50:52, 56:60	P3, M4, N4, P4, L5, M5, N5, P5	R4, T4, P5, R5, N6, P6, R6, N7	R4, T4, P5, R5, N6, P6, R6, N7	R4, T4, P5, R5, N6, P6, R6, N7
BS[3:0]	PBS[7:4]	CAS[3:0]		0	143:140	B6, C6, D7, C7	C9, B9, A9, A10	C9, B9, A9, A10	C9, B9, A9, A10
ŌĒ	PBUSCTL7		—	0	63	N6	T7	T7	T7
TA	PBUSCTL6	—	—	I	97	H11	K14	K14	K14
TEA	PBUSCTL5	DREQ1	—	Ι	_	J14	K13	K13	K13
R/W	PBUSCTL4	—	—	0	96	J13	L16	L16	L16
TSIZ1	PBUSCTL3	DACK1	—	0	—	P6	N8	N8	N8
TSIZ0	PBUSCTL2	DACK0	—	0	_	P7	P8	P8	P8
TS	PBUSCTL1	DACK2	—	0	_	H13	K16	K16	K16
TIP	PBUSCTL0	DREQ0	—	0	_	H12	K15	K15	K15
	Chip Selects								
<u>CS</u> [7:4]	PCS[7:4]	_	_	0	_	B9, A10, C10, A11	C12, A13, C13, A14	C12, A13, C13, A14	C12, A13, C13, A14
<u>CS</u> [3:2]	PCS[3:2]	SD_CS[1:0]		0	134,133	A9, C9	B12, D12	B12, D12	B12, D12
CS1	PCS1			0	130	B10	B13	B13	B13
CS0		—	—	0	129	D10	D13	D13	D13
			SE	ORAM	Controller				

Table 2. MCF523x Signal Information and Muxing (continued)

Signal Name	GPIO	Alternate 1	Alternate 2	Dir. ¹	MCF5232 160 QFP	MCF5232 196 MAPBGA	MCF5233 256 MAPBGA	MCF5234 256 MAPBGA	MCF5235 256 MAPBGA
SD_WE	PSDRAM5	_		0	93	K13	L13	L13	L13
SD_SCAS	PSDRAM4	_	_	0	92	K12	M15	M15	M15
SD_SRAS	PSDRAM3	_		0	91	K11	M14	M14	M14
SD_CKE	PSDRAM2	_	_	0	_	E8	C10	C10	C10
SD_CS[1:0]	PSDRAM[1:0]	_	_	0	_	L12, L13	N15, M13	N15, M13	N15, M13
			Exte	rnal In	terrupts Port				
IRQ[7:3]	PIRQ[7:3]	_	—	I	IRQ7=64 IRQ4=65	N7, M7, L7, P8, N8	R8, T8, N9, P9, R9	R8, T8, N9, P9, R9	R8, T8, N9, P9, R9
IRQ2	PIRQ2	DREQ2	_	I	_	M8	Т9	Т9	Т9
IRQ1	PIRQ1	_		Ι	66	L8	N10	N10	N10
				e	ΓPU				
TPUCH31		ECOL	_		_	_	F3	_	F3
TPUCH30	—	ECRS			_	_	F4	—	F4
TPUCH29	—	ERXCLK	—		—	—	E3	—	E3
TPUCH28	—	ERXDV	_		_		E4	—	E4
TPUCH[27:24]	_	ERXD[3:0]	_		_	_	D3, D4, C3, C4	_	D3, D4, C3, C4
TPUCH23	—	ERXER	—		_	—	D5	—	D5
TPUCH22	—	ETXCLK	_			_	C5	—	C5
TPUCH21	—	ETXEN	—		_	—	D6	—	D6
TPUCH20	—	ETXER	—		—	—	C6	—	C6
TPUCH[19:16]	_	ETXD[3:0]	—		—	—	B6,B5, A5, B7	—	B6,B5, A5, B7
TPUCH[15:0]		_	_		11, 10, 7:2, 159:154, 152, 151	E2, E1, D1 D2, D3, C1, C2, B1, B2, A2, C3, B3, A3, A4, C4, BR	F2, E1, E2, D1, D2, C1, C2, B1, B2, A2, B3, A3, B4, A4, A6, A7	F2, E1, E2, D1, D2, C1, C2, B1, B2, A2, B3, A3, B4, A4, A6, A7	F2, E1, E2, D1, D2, C1, C2, B1, B2, A2, B3, A3, B4, A4, A6, A7
TCRCLK	PETPU2	—	—		12	E3	F1	F1	F1
UTPUODIS	PETPU1		—			H10	J13	J13	J13
LTPUODIS	PETPU0	_	—		—	G10	J14	J14	J14
				F	EC				
EMDIO	PFECI2C2	I2C_SDA	U2RXD	I/O	—	—	—	C7	C7
EMDC	PFECI2C3	I2C_SCL	U2TXD	0		—	—	D7	D7
ECOL	—		—	I		—		F3	F3

Signal Name	GPIO	Alternate 1	Alternate 2	Dir. ¹	MCF5232 160 QFP	MCF5232 196 MAPBGA	MCF5233 256 MAPBGA	MCF5234 256 MAPBGA	MCF5235 256 MAPBGA
ECRS	_	—	—	Ι	_		—	F4	F4
ERXCLK	_	—	—	I	_	_	—	E3	E3
ERXDV	_			Ι	_	_		E4	E4
ERXD[3:0]	_	—	—	I	_	_	—	D3, D4, C3, C4	D3, D4, C3, C4
ERXER	_	—	—	I	_	_	—	D5	D5
ETXCLK	_	_	_	I	_	_	_	C5	C5
ETXEN	_	—	—	0	_	_	—	D6	D6
ETXER	_	—	—	0	_	_	—	C6	C6
ETXD[3:0]	_	_	_	0			—	B6, B5, A5, B7	B6, B5, A5, B7
			F	eatur	e Control				
eTPU/EthENB	—	—	—	Ι	—	—	—	—	M4
				l	² C				
I2C_SDA	PFECI2C1	CAN0RX		I/O		J12	L15	L15	L15
I2C_SCL	PFECI2C0	CAN0TX	—	I/O	_	J11	L14	L14	L14
		L		D	MA		L	1	1
DACK[2:0] and Please TS and DT2OL TSIZ0 and DT0 TEA and DT1II	DREQ[2:0] do r e refer to the fol JT for DACK2, OUT for DACK N for DREQ1, a	not have a dec lowing pins fo TSIZ1and DT 0, IRQ2 and I and TIP and I	dicated bond or muxing: 10UT for DA 0T2IN for DR 0T0IN for DR	pads. .CK1, EQ2, EQ0.	_	_		_	_
				Q	SPI				
QSPI_CS1	PQSPI4	SD_CKE	_	0	139	B7	B10	B10	B10
QSPI_CS0	PQSPI3	—	—	0	147	A6	D9	D9	D9
QSPI_CLK	PQSPI2	I2C_SCL	—	0	148	C5	B8	B8	B8
QSPI_DIN	PQSPI1	I2C_SDA	_	Ι	149	B5	C8	C8	C8
QSPI_DOUT	PQSPI0	_		0	150	A5	D8	D8	D8
				UA	ARTs				
U2TXD	PUARTH1	CAN1TX	—	0	—	A8	D11	D11	D11
U2RXD	PUARTH0	CAN1RX	—	I	—	A7	D10	D10	D10
U1CTS	PUARTL7	U2CTS	—	I	—	B8	C11	C11	C11
U1RTS	PUARTL6	U2RTS		0	_	C8	B11	B11	B11
U1TXD	PUARTL5	CAN0TX	—	0	135	D9	A12	A12	A12

Table 2. MCF523x Signal Information and Muxing (continued)

Signal Name	GPIO	Alternate 1	Alternate 2	Dir. ¹	MCF5232 160 QFP	MCF5232 196 MAPBGA	MCF5233 256 MAPBGA	MCF5234 256 MAPBGA	MCF5235 256 MAPBGA
U1RXD	PUARTL4	CAN0RX	—	I	136	D8	A11	A11	A11
UOCTS	PUARTL3	—	—	I	—	F3	G1	G1	G1
UORTS	PUARTL2	_	—	0	_	G3	H3	H3	H3
U0TXD	PUARTL1	—	—	0	14	F1	H2	H2	H2
U0RXD	PUARTL0	—	—	I	13	F2	G2	G2	G2
				DMA	Timers				
DT3IN	PTIMER7	U2CTS	QSPI_CS2	Ι	—	H14	J15	J15	J15
DT3OUT	PTIMER6	U2RTS	QSPI_CS3	0	—	G14	J16	J16	J16
DT2IN	PTIMER5	DREQ2	DT2OUT	I	—	M9	P10	P10	P10
DT2OUT	PTIMER4	DACK2	—	0	—	L9	R10	R10	R10
DT1IN	PTIMER3	DREQ1	DT1OUT	I	—	L6	P7	P7	P7
DT1OUT	PTIMER2	DACK1	—	0	—	M6	R7	R7	R7
DT0IN	PTIMER1	DREQ0	—	I		E4	G4	G4	G4
DT0OUT	PTIMER0	DACK0	—	0	_	F4	G3	G3	G3
			·	BDM	JTAG ²				
DSCLK	_	TRST	—	Ι	70	N9	N11	N11	N11
PSTCLK	_	TCLK	—	0	68	P9	T10	T10	T10
BKPT	_	TMS	—	I	71	P10	P11	P11	P11
DSI	_	TDI	—	I	73	M10	T11	T11	T11
DSO	_	TDO	—	0	72	N10	R11	R11	R11
JTAG_EN		_	—	I	78	K9	N13	N13	N13
DDATA[3:0]	_	-	—	0	—	M12, N12, P12, L11	N14, P14, T13, R13	N14, P14, T13, R13	N14, P14, T13, R13
PST[3:0]	_	—	—	0	77:74	M11, N11, P11, L10	T12, R12, P12, N12	T12, R12, P12, N12	T12, R12, P12, N12

Table 2. MCF523x Signal Information and Muxing (continued)

Signal Name	GPIO	Alternate 1	Alternate 2	Dir. ¹	MCF5232 160 QFP	MCF5232 196 MAPBGA	MCF5233 256 MAPBGA	MCF5234 256 MAPBGA	MCF5235 256 MAPBGA
				٦	lest				
TEST	—	—	—	Ι	18	F5	J4	J4	J4
PLL_TEST	—	—	—	I	—		R14	R14	R14
			F	Power	Supplies				
VDDPLL	—	—	—	Ι	87	M13		P15	
VSSPLL	_	—	—	I	84	L14		R15	
OVDD	_	_	_	I	1, 9, 17, 32, 41, 55, 62, 69, 81, 90, 95, 105, 114, 128, 132, 138, 146	E5, E7, E10, F7, F9, G6, G8, H7, H8, H9, J6, J8, J10, K5, K6, K8	E6:11, F5, F G12, H5, H J12, K5, K	7:10, F12, G 6, H11, H12, 6, K11, K12, L12, M6:M11	5, G6, G11, J5, J6, J11, L5, L7:10,
VSS	_	_	_	I	8, 16, 25, 31, 40, 54, 61, 67, 80, 88, 94, 104, 113, 127, 131, 137, 145, 153, 160	A1, A14, E6, E9, F6, F8, F10, G7, G9, H6, J5, J7, J9, K7, P1, P14	A1, A16, G7:10, H7: L11, M5,	E5, E12, F6, 10, J1, J7:10 M12, N16, T ⁻	F11, F16, , K7:10, L6, 1, T6, T16
VDD	—	_	—	Ι	15, 53, 103, 144	D6, F11, G4, L4	A	8, G16, H1, 1	Γ5

 Table 2. MCF523x Signal Information and Muxing (continued)

Refers to pin's primary function. All pins which are configurable for GPIO have a pullup enabled in GPIO mode with the exception of PBUSCTL[7], PBUSCTL[4:0], PADDR, PBS, PSDRAM.

² If JTAG_EN is asserted, these pins default to Alternate 1 (JTAG) functionality. The GPIO module is not responsible for assigning these pins.

5 Design Recommendations

5.1 Layout

- Use a 4-layer printed circuit board with the VDD and GND pins connected directly to the power and ground planes for the MCF523x.
- See application note AN1259, System Design and Layout Techniques for Noise Reduction in Processor-Based Systems.
- Match the PC layout trace width and routing to match trace length to operating frequency and board impedance. Add termination (series or therein) to the traces to dampen reflections. Increase the PCB impedance (if possible) keeping the trace lengths balanced and short. Then do cross-talk analysis to separate traces with significant parallelism or are otherwise "noisy". Use 6 mils trace and separation. Clocks get extra separation and more precise balancing.

Design Recommendations

5.2 Power Supply

• 33 μ F, 0.1 μ F, and 0.01 μ F across each power supply

5.2.1 Supply Voltage Sequencing and Separation Cautions

Figure 1 shows situations in sequencing the I/O V_{DD} (OV_{DD}), PLL V_{DD} (V_{DDPLL}), and Core V_{DD} (V_{DD}). OV_{DD} is specified relative to V_{DD} .



Figure 1. Supply Voltage Sequencing and Separation Cautions

5.2.1.1 Power Up Sequence

If OV_{DD} is powered up with V_{DD} at 0 V, then the sense circuits in the I/O pads cause all pad output drivers connected to the OV_{DD} to be in a high impedance state. There is no limit on how long after OV_{DD} powers up before V_{DD} must power up. V_{DD} should not lead the OV_{DD} or V_{DDPLL} by more than 0.4 V during power ramp-up, or there will be high current in the internal ESD protection diodes. The rise times on the power supplies should be slower than 1 µs to avoid turning on the internal ESD protection clamp diodes.

The recommended power up sequence is as follows:

- 1. Use 1 ms or slower rise time for all supplies.
- 2. V_{DD} and OV_{DD}/V_{DDPLL} should track up to 0.9 V, then separate for the completion of ramps with OV_{DD} going to the higher external voltages. One way to accomplish this is to use a low drop-out voltage regulator.

5.2.1.2 Power Down Sequence

If V_{DD} is powered down first, then sense circuits in the I/O pads cause all output drivers to be in a high impedance state. There is no limit on how long after V_{DD} powers down before OV_{DD}/V_{DDPLL} must power down. V_{DD} should not lag OV_{DD} or V_{DDPLL} going low by more than 0.4 V during power down or there will be undesired high current in the ESD protection diodes. There are no requirements for the fall times of the power supplies.

The recommended power down sequence is as follows:

- 1. Drop V_{DD} to 0 V.
- 2. Drop OV_{DD}/V_{DDPLL} supplies.

5.3 Decoupling

- Place the decoupling caps as close to the pins as possible, but they can be outside the footprint of the package.
- $0.1 \ \mu F$ and $0.01 \ \mu F$ at each supply input

5.4 Buffering

• Use bus buffers on all data/address lines for all off-board accesses and for all on-board accesses when excessive loading is expected. See Section 7, "Electrical Characteristics."

5.5 Pull-up Recommendations

• Use external pull-up resistors on unused inputs. See pin table.

5.6 Clocking Recommendations

- Use a multi-layer board with a separate ground plane.
- Place the crystal and all other associated components as close to the EXTAL and XTAL (oscillator pins) as possible.
- Do not run a high frequency trace around crystal circuit.
- Ensure that the ground for the bypass capacitors is connected to a solid ground trace.
- Tie the ground trace to the ground pin nearest EXTAL and XTAL. This prevents large loop currents in the vicinity of the crystal.
- Tie the ground pin to the most solid ground in the system.
- Do not connect the trace that connects the oscillator and the ground plane to any other circuit element. This tends to make the oscillator unstable.
- Tie XTAL to ground when an external oscillator is clocking the device.

5.7 Interface Recommendations

5.7.1 SDRAM Controller

5.7.1.1 SDRAM Controller Signals in Synchronous Mode

Table 3 shows the behavior of SDRAM signals in synchronous mode.

Table 3. Synchronous DRAM Signal Connections

Signal	Description
SD_SRAS	Synchronous row address strobe. Indicates a valid SDRAM row address is present and can be latched by the SDRAM. \overline{SD} _SRAS should be connected to the corresponding SDRAM \overline{SD} _SRAS. Do not confuse \overline{SD} _SRAS with the DRAM controller's \overline{SD} _CS[1:0], which should not be interfaced to the SDRAM \overline{SD} _SRAS signals.
SD_SCAS	Synchronous column address strobe. Indicates a valid column address is present and can be latched by the SDRAM. SD_SCAS should be connected to the corresponding signal labeled SD_SCAS on the SDRAM.
DRAMW	DRAM read/write. Asserted for write operations and negated for read operations.
SD_CS[1:0]	Row address strobe. Select each memory block of SDRAMs connected to the MCF523 <i>x</i> . One \overline{SD}_{CS} signal selects one SDRAM block and connects to the corresponding \overline{CS} signals.
SD_CKE	Synchronous DRAM clock enable. Connected directly to the CKE (clock enable) signal of SDRAMs. Enables and disables the clock internal to SDRAM. When CKE is low, memory can enter a power-down mode where operations are suspended or they can enter self-refresh mode. SD_CKE functionality is controlled by DCR[COC]. For designs using external multiplexing, setting COC allows SD_CKE to provide command-bit functionality.
BS[3:0]	Column address strobe. For synchronous operation, $\overline{\text{BS}}$ [3:0] function as byte enables to the SDRAMs. They connect to the DQM signals (or mask qualifiers) of the SDRAMs.
CLKOUT	Bus clock output. Connects to the CLK input of SDRAMs.

5.7.1.2 Address Multiplexing

See the SDRAM controller module chapter in the *MCF5235 Reference Manual* for details on address multiplexing.

5.7.2 Ethernet PHY Transceiver Connection

The FEC supports both an MII interface for 10/100 Mbps Ethernet and a seven-wire serial interface for 10 Mbps Ethernet. The interface mode is selected by R_CNTRL[MII_MODE]. In MII mode, the 802.3 standard defines and the FEC module supports 18 signals. These are shown in Table 4.

Signal Description	MCF523 <i>x</i> Pin
Transmit clock	ETXCLK
Transmit enable	ETXEN
Transmit data	ETXD[3:0]

Table 4. MII Mode

Design Recommendations

Signal Description	MCF523 <i>x</i> Pin
Transmit error	ETXER
Collision	ECOL
Carrier sense	ECRS
Receive clock	ERXCLK
Receive enable	ERXDV
Receive data	ERXD[3:0]
Receive error	ERXER
Management channel clock	EMDC
Management channel serial data	EMDIO

Table	4.	MII	Mode	(continued)	
Table	-		Mouc	(continucu)	

The serial mode interface operates in what is generally referred to as AMD mode. The MCF523x configuration for seven-wire serial mode connections to the external transceiver are shown in Table 5.

Signal Description	MCF523 <i>x</i> Pin
Transmit clock	ETXCLK
Transmit enable	ETXEN
Transmit data	ETXD[0]
Collision	ECOL
Receive clock	ERXCLK
Receive enable	ERXDV
Receive data	ERXD[0]
Unused, configure as PB14	ERXER
Unused input, tie to ground	ECRS
Unused, configure as PB[13:11]	ERXD[3:1]
Unused output, ignore	ETXER
Unused, configure as PB[10:8]	ETXD[3:1]
Unused, configure as PB15	EMDC
Input after reset, connect to ground	EMDIO

Table 5. Seven-Wire Mode Configuration

Refer to the M523*x*EVB evaluation board user's manual for an example of how to connect an external PHY. Schematics for this board are accessible at the MCF5235 site by navigating to: http://www.freescale.com/coldfire.

5.7.3 FlexCAN

The FlexCAN module interface to the CAN bus is composed of 2 pins: CANTX and CANRX, which are the serial transmitted data and the serial received data. The use of an external CAN transceiver to interface to the CAN bus is generally required. The transceiver is capable of driving the large current needed for the CAN bus and has current protection, against a defective CAN bus or defective stations.

5.7.4 BDM

Use the BDM interface as shown in the M523*x*EVB evaluation board user's manual. The schematics for this board are accessible at the Freescale website at: http://www.freescale.com/coldfire.

6 Mechanicals/Pinouts and Part Numbers

This section contains drawings showing the pinout and the packaging and mechanical characteristics of the MCF523x devices. See Table 2 for a list the signal names and pin locations for each device.

6.1 Pinout—196 MAPBGA

The following figure shows a pinout of the MCF5232CVMxxx package.

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	_
A		TPUCH6	TPUCH3	TPUCH2	QSPI_ DOUT	QSPI_CS0	U2RXD	U2TXD	CS3	CS6	CS4	A20	A17		А
в	TPUCH8	TPUCH7	TPUCH4	TPUCH0	QSPI_ DIN	BS3	QSPI_CS1	U1CTS	CS7	CS1	A23	A19	A16	A15	в
С	TPUCH10	TPUCH9	TPUCH5	TPUCH1	QSPI_CLK	BS2	BS0	U1RTS	CS2	CS5	A22	A18	A14	A13	с
D	TPUCH13	TPUCH12	TPUCH11	NC	NC	VDD	BS1	U1RXD/ CAN0RX	U1TXD/ CAN0TX	CS0	A21	A12	A11	A10	D
E	TPUCH14	TPUCH15	TCRCLK	DT0IN	OVDD	VSS	OVDD	SD_CKE	VSS	OVDD	A9	A8	A7	A6	E
F	U0TXD	U0RXD	UOCTS	DT0OUT	TEST		OVDD	VSS	OVDD	VSS	VDD	A5	A4	A3	F
G	D31	D30	UORTS	VDD	CLKMOD1	OVDD	VSS	OVDD	VSS	LTPU ODIS	A2	A1	A0	DT3OUT	G
Н	D29	D28	D27	D26	CLKMOD0	VSS	OVDD	OVDD	OVDD	UTPU ODIS	TA	TIP	TS	DT3IN	н
J	D25	D24	D23	D22	VSS	OVDD	VSS	OVDD	VSS	OVDD	I2C_SCL	I2C_SDA	R/W	TEA	J
к	D21	D20	D19	D18	OVDD	OVDD		OVDD	JTAG_EN	RCON	SD_SRAS	SD_SCAS	SD_WE	CLKOUT	к
L	D17	D16	D10	VDD	D3	DT1IN	IRQ5	IRQ1	DT2OUT	PST0	DDATA0	SD_CS1	SD_CS0	VSSPLL	L
М	D15	D13	D9	D6	D2	DT1OUT	IRQ6	IRQ2	DT2IN	TDI/DSI	PST3	DDATA3	VDDPLL	EXTAL	м
N	D14	D12	D8	D5	D1	ŌĒ	IRQ7	IRQ3	TRST/ DSCLK	TDO/DSO	PST2	DDATA2	RESET	XTAL	N
Ρ	VSS	D11	D7	D4	D0	TSIZ1	TSIZ0	IRQ4	TCLK/ PSTCLK	TMS/ BKPT	PST1	DDATA1	RSTOUT	VSS	Ρ
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	

Figure 2. MCF5232CVMxxx Pinout (196 MAPBGA)

6.2 Package Dimensions—196 MAPBGA

Figure 3 shows MCF5232CVMxxx package dimensions.



Figure 3. 196 MAPBGA Package Dimensions (Case No. 1128A-01)

6.2.1 Pinout—256 MAPBGA

Figure 4 through Figure 6 show pinouts of the MCF5233CVMxxx, MCF5234CVMxxx, and MCF5235CVMxxx packages.

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	
A	VSS	TPUCH6	TPUCH4	TPUCH2	TPUCH17	TPUCH1	TPUCH0	VDD	BS1	BSO	U1RXD/ CAN0RX	U1TXD/ CAN0TX	CS6	CS4	A21	VSS	A
В	TPUCH8	TPUCH7	TPUCH5	TPUCH3	TPUCH18	TPUCH19	TPUCH16	QSPI_ CLK	BS2	QSPI_ CS1	U1RTS	CS3	CS1	A23	A20	A19	В
С	TPUCH10	TPUCH9	TPUCH25	TPUCH24	TPUCH22	TPUCH20	I2C_SDA/ U2RXD	QSPI_ DIN	BS3	SD_CKE	U1CTS	CS7	CS5	A22	A18	A17	С
D	TPUCH12	TPUCH11	TPUCH27	TPUCH26	TPUCH23	TPUCH21	I2C_SCL/ U2TXD	QSPI_ DOUT	QSPI_ CS0	U2RXD/ CAN1RX	U2TXD/ CAN1TX	CS2	CS0	A14	A15	A16	D
E	TPUCH14	TPUCH13	TPUCH29	TPUCH28	VSS	OVDD	OVDD	OVDD	OVDD	OVDD	OVDD	VSS	A10	A11	A12	A13	E
F	TCRCLK	TPUCH15	TPUCH31	TPUCH30	OVDD	VSS	OVDD	OVDD	OVDD	OVDD	VSS	OVDD	A7	A8	A9	VSS	F
G	UOCTS	UORXD	DT0OUT	DT0IN	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	A4	A5	A6	VDD	G
Η	VDD	U0TXD	UORTS	NC	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	A0	A1	A2	A3	н
J	VSS	CLK MOD0	CLK MOD1	TEST	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	UTPU ODIS	LTPU ODIS	DT3IN	DT3OUT	J
К	D28	D29	D30	D31	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	TEA	TA	TIP	TS	к
L	D24	D25	D26	D27	OVDD	VSS	OVDD	OVDD	OVDD	OVDD	VSS	OVDD	SD_WE	I2C_SCL/ CAN0TX	I2C_SDA/ CAN0RX	R/W	L
М	D21	D22	D23	NC	VSS	OVDD	OVDD	OVDD	OVDD	OVDD	OVDD	VSS	SD_ CS0	SD_ SRAS	SD_ SCAS	CLKOUT	М
N	D19	D20	D13	D9	NC	D3	D0	TSIZ1	IRQ5	IRQ1	TRST/ DSCLK	PST0	JTAG_ EN	DDATA3	SD_CS1	VSS	N
Ρ	D17	D18	D12	D8	D5	D2	DT1IN	TSIZ0	IRQ4	DT2IN	TMS/ BKPT	PST1	RCON	DDATA2	VDDPLL	EXTAL	Ρ
R	D16	D15	D11	D7	D4	D1	DT1OUT	IRQ7	IRQ3	DT2OUT	TDO/ DSO	PST2	DDATA0	PLL_ TEST	VSSPLL	XTAL	R
Т	VSS	D14	D10	D6	VDD	VSS	ŌĒ	IRQ6	IRQ2	TCLK/ PSTCLK	TDI/DSI	PST3	DDATA1	RSTOUT	RESET	VSS	т
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	

Figure 4. MCF5233CVMxxx Pinout (256 MAPBGA)

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	
A	VSS	TPUCH6	TPUCH4	TPUCH2	ETXD1	TPUCH1	TPUCH0	VDD	BS1	BSO	U1RXD/ CAN0RX	U1TXD/ CAN0TX	CS6	CS4	A21	VSS	A
В	TPUCH8	TPUCH7	TPUCH5	TPUCH3	ETXD2	ETXD3	ETXD0	QSPI_ CLK	BS2	QSPI_ CS1	U1RTS	CS3	CS1	A23	A20	A19	в
С	TPUCH10	TPUCH9	ERXD1	ERXD0	ETXCLK	ETXER	EMDIO	QSPI_ DIN	BS3	SD_CKE	U1CTS	CS7	CS5	A22	A18	A17	С
D	TPUCH12	TPUCH11	ERXD3	ERXD2	ERXER	ETXEN	EMDC	QSPI_ DOUT	QSPI_ CS0	U2RXD	U2TXD	CS2	CS0	A14	A15	A16	D
E	TPUCH14	TPUCH13	ERXCLK	ERXDV	VSS	OVDD	OVDD	OVDD	OVDD	OVDD	OVDD	VSS	A10	A11	A12	A13	E
F	TCRCLK	TPUCH15	ECOL	ECRS	OVDD	VSS	OVDD	OVDD	OVDD	OVDD	VSS	OVDD	A7	A8	A9	VSS	F
G	UOCTS	U0RXD	DT0OUT	DT0IN	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	A4	A5	A6	VDD	G
Н	VDD	U0TXD	UORTS	NC	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	A0	A1	A2	A3	н
J	VSS	CLK MOD0	CLK MOD1	TEST	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	UTPU ODIS	LTPU ODIS	DT3IN	DT3OUT	J
к	D28	D29	D30	D31	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	TEA	TA	TIP	TS	к
L	D24	D25	D26	D27	OVDD	VSS	OVDD	OVDD	OVDD	OVDD	VSS	OVDD	SD_WE	I2C_SCL/ CAN0TX	I2C_SDA/ CAN0RX	R/W	L
М	D21	D22	D23	NC	VSS	OVDD	OVDD	OVDD	OVDD	OVDD	OVDD	VSS	SD_CS0	SD_ SRAS	SD_ SCAS	CLKOUT	М
N	D19	D20	D13	D9	NC	D3	D0	TSIZ1	IRQ5	IRQ1	TRST/ DSCLK	PST0	JTAG_ EN	DDATA3	SD_CS1	VSS	N
Ρ	D17	D18	D12	D8	D5	D2	DT1IN	TSIZ0	IRQ4	DT2IN	TMS/ BKPT	PST1	RCON	DDATA2	VDDPLL	EXTAL	Ρ
R	D16	D15	D11	D7	D4	D1	DT1OUT	IRQ7	IRQ3	DT2OUT	TDO/ DSO	PST2	DDATA0	PLL_ TEST	VSSPLL	XTAL	R
Т	VSS	D14	D10	D6	VDD	VSS	ŌĒ	IRQ6	IRQ2	TCLK/ PSTCLK	TDI/DSI	PST3	DDATA1	RST OUT	RESET	VSS	т
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	

Figure 5. MCF5234CVMxxx Pinout (256 MAPBGA)

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	
A	VSS	TPUCH6	TPUCH4	TPUCH2	TPUCH17/ ETXD1	TPUCH1	TPUCH0	VDD	BS1	BSO	U1RXD/ CAN0RX	U1TXD/ CAN0TX	CS6	CS4	A21	VSS	A
В	TPUCH8	TPUCH7	TPUCH5	TPUCH3	TPUCH18/ ETXD2	TPUCH19/ ETXD3	TPUCH16/ ETXD0	QSPI_ CLK	BS2	QSPI_ CS1	U1RTS	CS3	CS1	A23	A20	A19	В
с	TPUCH10	TPUCH9	TPUCH25/ ERXD1	TPUCH24/ ERXD0	TPUCH22/ ETXCLK	TPUCH20/ ETXER	I2C_SDA/ U2RXD/ EMDIO	QSPI_ DIN	BS3	SD_CKE	U1CTS	CS7	CS5	A22	A18	A17	С
D	TPUCH12	TPUCH11	TPUCH27/ ERXD3	TPUCH26/ ERXD2	TPUCH23/ ERXER	TPUCH21/ ETXEN	I2C_SCL/ U2TXD/ EMDC	QSPI_ DOUT	QSPI_ CS0	U2RXD/ CAN1RX	U2TXD/ CAN1TX	CS2	CS0	A14	A15	A16	D
E	TPUCH14	TPUCH13	TPUCH29/ ERXCLK	TPUCH2/ ERXDV	VSS	OVDD	OVDD	OVDD	OVDD	OVDD	OVDD	VSS	A10	A11	A12	A13	E
F	TCRCLK	TPUCH15	TPUCH31/ ECOL	TPUCH30/ ECRS	OVDD	VSS	OVDD	OVDD	OVDD	OVDD	VSS	OVDD	A7	A8	A9	VSS	F
G	UOCTS	U0RXD	DT0OUT	DT0IN	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	A4	A5	A6	VDD	G
н	VDD	U0TXD	UORTS	NC	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	A0	A1	A2	A3	Н
J	VSS	CLK MOD0	CLK MOD1	TEST	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	UTPU ODIS	LTPU ODIS	DT3IN	DT3OUT	J
к	D28	D29	D30	D31	OVDD	OVDD	VSS	VSS	VSS	VSS	OVDD	OVDD	TEA	TA	TIP	TS	к
L	D24	D25	D26	D27	OVDD	VSS	OVDD	OVDD	OVDD	OVDD	VSS	OVDD	SD_WE	I2C_SCL/ CAN0TX	I2C_SDA/ CAN0RX	R/W	L
М	D21	D22	D23	eTPU/ EthENB	VSS	OVDD	OVDD	OVDD	OVDD	OVDD	OVDD	VSS	SD_CS0	SD_ SRAS	SD_ SCAS	CLKOUT	М
N	D19	D20	D13	D9	NC	D3	D0	TSIZ1	IRQ5	IRQ1	TRST/ DSCLK	PST0	JTAG_ EN	DDATA3	SD_CS1	VSS	N
Ρ	D17	D18	D12	D8	D5	D2	DT1IN	TSIZ0	IRQ4	DT2IN	TMS/ BKPT	PST1	RCON	DDATA2	VDDPLL	EXTAL	Ρ
R	D16	D15	D11	D7	D4	D1	DT1OUT	IRQ7	IRQ3	DT2OUT	TDO/ DSO	PST2	DDATA0	PLL_ TEST	VSSPLL	XTAL	R
т	VSS	D14	D10	D6	VDD	VSS	ŌĒ	IRQ6	IRQ2	TCLK/ PSTCLK	TDI/DSI	PST3	DDATA1	RSTOUT	RESET	VSS	Т
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	[

Figure 6. MCF5235CVMxxx Pinout (256 MAPBGA)

6.2.2 Package Dimensions—256 MAPBGA

Figure 7 shows MCF5235CVMxxx, MCF5234CVMxxx, and MCF5233CVMxx package dimensions.



Figure 7. 256 MAPBGA Package Outline

6.3 Pinout—160 QFP

Figure 8 shows a pinout of the MCF5232CABxxx package.



Figure 8. MCF5232CABxxx Pinout (160 QFP)

6.4 Package Dimensions—160 QFP

Figure 9 shows MCF5232CAB80 package dimensions.



Figure 9. 160 QFP Package Dimensions

6.5 Ordering Information

Table 6. Orderable Part Numbers

Freescale Part Number	Description	Package	Speed	Lead-Free?	Temperature
MCF5232CAB80	MCF5232 RISC Microprocessor	160 QFP	80MHz	Yes	-40° to $+85^{\circ}$ C
MCF5232CVM100	MCF5232 RISC Microprocessor	196 MAPBGA	100MHz	Yes	-40° to $+85^{\circ}$ C
MCF5232CVM150	MCF5232 RISC Microprocessor	196 MAPBGA	150MHz	Yes	-40° to $+85^{\circ}$ C
MCF5233CVM100	MCF5233 RISC Microprocessor	256 MAPBGA	100MHz	Yes	-40° to $+85^{\circ}$ C
MCF5233CVM150	MCF5233 RISC Microprocessor	256 MAPBGA	150MHz	Yes	-40° to $+85^{\circ}$ C
MCF5234CVM100	MCF5234 RISC Microprocessor	256 MAPBGA	100MHz	Yes	-40° to $+85^{\circ}$ C
MCF5234CVM150	MCF5234 RISC Microprocessor	256 MAPBGA	150MHz	Yes	-40° to $+85^{\circ}$ C
MCF5235CVM100	MCF5235 RISC Microprocessor	256 MAPBGA	100MHz	Yes	-40° to $+85^{\circ}$ C
MCF5235CVM150	MCF5235 RISC Microprocessor	256 MAPBGA	150MHz	Yes	-40° to $+85^{\circ}$ C
MCF5235CVF150	MCF5235 RISC Microprocessor,	256 MAPBGA	150MHz	No	-40° to $+85^{\circ}$ C

7 Electrical Characteristics

This chapter contains electrical specification tables and reference timing diagrams for the MCF5235 microcontroller unit. This section contains detailed information on power considerations, DC/AC electrical characteristics, and AC timing specifications of MCF5235.

NOTE

The parameters specified in this processor document supersede any values found in the module specifications.

7.1 Maximum Ratings

Table 7. Absolute Maximum Ratings^{1, 2}

Rating	Symbol	Value	Unit
Core Supply Voltage	V _{DD}	- 0.5 to +2.0	V
Pad Supply Voltage	OV _{DD}	- 0.3 to +4.0	V
PLL Supply Voltage	V _{DDPLL}	- 0.3 to +4.0	V
Digital Input Voltage ³	V _{IN}	- 0.3 to + 4.0	V
Instantaneous Maximum Current Single pin limit (applies to all pins) ^{3,4,5}	Ι _D	25	mA
Operating Temperature Range (Packaged)	T _A (T _L - T _H)	- 40 to 85	°C
Storage Temperature Range	T _{stg}	– 65 to 150	°C

Electrical Characteristics

- ¹ Functional operating conditions are given in DC Electrical Specifications. Absolute Maximum Ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Continued operation at these levels may affect device reliability or cause permanent damage to the device.
- ² This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (e.g., either V_{SS} or OV_{DD}).
- ³ Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.
- ⁴ All functional non-supply pins are internally clamped to V_{SS} and OV_{DD}.
- ⁵ Power supply must maintain regulation within operating OV_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{in} > OV_{DD}$) is greater than I_{DD} , the injection current may flow out of OV_{DD} and could result in external power supply going out of regulation. Insure external OV_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the processor is not consuming power (ex; no clock).Power supply must maintain regulation within operating OV_{DD} range during instantaneous and operating maximum current conditions.

7.2 Thermal Characteristics

The below table lists thermal resistance values.

Characteristic		Symbol	256 MAPBGA	196 MAPBGA	160 QFP	Unit
Junction to ambient, natural convection	Four layer board (2s2p)	θ_{JMA}	26 ^{1,2}	32 ^{1,2}	40 ^{1,2}	°C/W
Junction to ambient (@200 ft/min)	Four layer board (2s2p)	θ_{JMA}	23 ^{1,2}	29 ^{1,2}	36 ^{1,2}	°C/W
Junction to board		θ_{JB}	15 ³	20 ³	25 ³	°C/W
Junction to case		θ _{JC}	10 ⁴	10 ⁴	10 ⁴	°C/W
Junction to top of package		Ψ _{jt}	2 ^{1,5}	2 ^{1,5}	2 ^{1,5}	°C/W
Maximum operating junction temperature		Тj	102	104	105 ⁶	°C

Table 8. Thermal Characteristics

 θ_{JMA} and Ψ_{jt} parameters are simulated in conformance with EIA/JESD Standard 51-2 for natural convection. Freescale recommends the use of θ_{JmA} and power dissipation specifications in the system design to prevent device junction temperatures from exceeding the rated specification. System designers should be aware that device junction temperatures can be significantly influenced by board layout and surrounding devices. Conformance to the device junction temperature specification can be verified by physical measurement in the customer's system using the Ψ_{jt} parameter, the device power dissipation, and the method described in EIA/JESD Standard 51-2.

- ² Per JEDEC JESD51-6 with the board horizontal.
- ³ Thermal resistance between the die and the printed circuit board in conformance with JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
- ⁴ Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1).
- ⁵ Thermal characterization parameter indicating the temperature difference between package top and the junction temperature per JEDEC JESD51-2. When Greek letters are not available, the thermal characterization parameter is written in conformance with Psi-JT.
- ⁶ At 100MHz.

The average chip-junction temperature (T_J) in °C can be obtained from:

$$\Gamma_{\rm J} = T_{\rm A} + (P_{\rm D} \times \Theta_{\rm JMA}) \quad (1)$$

Where:

$$\begin{split} T_A &= \text{Ambient Temperature, }^\circ\text{C}\\ \Theta_{JMA} &= \text{Package Thermal Resistance, Junction-to-Ambient, }^\circ\text{C/W}\\ P_D &= P_{INT} + P_{I/O}\\ P_{INT} &= I_{DD} \times V_{DD}, \text{Watts - Chip Internal Power}\\ P_{I/O} &= \text{Power Dissipation on Input and Output Pins} - \text{User Determined} \end{split}$$

For most applications $P_{I/O} < P_{INT}$ and can be ignored. An approximate relationship between P_D and T_J (if $P_{I/O}$ is neglected) is:

$$P_{\rm D} = \mathbf{K} \div (\mathbf{T}_{\rm J} + 273^{\circ}C) \quad (2)$$

Solving equations 1 and 2 for K gives:

$$K = P_D \times (T_A + 273 \text{ °C}) + \Theta_{JMA} \times P_D^2 (3)$$

where K is a constant pertaining to the particular part. K can be determined from equation (3) by measuring P_D (at equilibrium) for a known T_A . Using this value of K, the values of P_D and T_J can be obtained by solving equations (1) and (2) iteratively for any value of T_A .

7.3 DC Electrical Specifications

Table 9. DC Electrical Specifications¹

Characteristic	Symbol	Min	Typical	Max	Unit
Core Supply Voltage	V _{DD}	1.4	—	1.6	V
Pad Supply Voltage	OV _{DD}	3.0		3.6	V
PLL Supply Voltage	V _{DDPLL}	3.0	_	3.6	V
Input High Voltage	V _{IH}	$0.7 \times \mathrm{OV}_\mathrm{DD}$	_	3.65	V
Input Low Voltage	V _{IL}	V _{SS} – 0.3	_	$0.35\times \text{OV}_{\text{DD}}$	V
Input Hysteresis	V _{HYS}	$0.06\times \text{OV}_{\text{DD}}$	_	—	mV
Input Leakage Current $V_{in} = V_{DD}$ or V_{SS} , Input-only pins	l _{in}	-1.0	_	1.0	μ A
High Impedance (Off-State) Leakage Current $V_{in} = V_{DD}$ or V_{SS} , All input/output and output pins	I _{OZ}	-1.0	_	1.0	μ A
Output High Voltage (All input/output and all output pins) $I_{OH} = -5.0 \text{ mA}$	V _{OH}	OV _{DD} - 0.5	—	_	V
Output Low Voltage (All input/output and all output pins) $I_{OL} = 5.0 \text{mA}$	V _{OL}	-	_	0.5	V
Weak Internal Pull Up Device Current, tested at V_{IL} Max. ²	I _{APU}	-10	_	- 130	μA