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MCP2515 CAN Bus Monitor Demo Board User's Guide

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MCP2515 CAN BUS MONITOR DEMO BOARD USER'S GUIDE

Table of Contents

Preface 1

Introduction 1

Document Layout 1

Conventions Used in this Guide 2

Recommended Reading 3

The Microchip Web Site 3

Customer Support 3

Document Revision History 4

Chapter 1. Product Overview

1.1 Introduction 5

1.2 What is the MCP2515 CAN Bus Monitor Demo Board? 5

1.3 What the MCP2515 CAN Bus Monitor Demo Board Kit includes 5

Chapter 2. Installation and Operation

2.1 Introduction 7

2.2 Features 7

2.3 Getting Started 8

2.4 Functional Operation 10

2.5 Software Operation 11

Appendix A. Schematic and Layouts

A.1 Introduction 15

A.2 Board Schematic - Page 1 16

A.3 Board Schematic - Page 2 17

A.4 Board - Top Silk-screen Layer 18

A.5 Board - Top Layer 18

A.6 Board - Bottom Silk-screen Layer 19

A.7 Board - Bottom Layer 19

Appendix B. Bill Of Materials (BOM)

Worldwide Sales and Service 24

NOTES:

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MCP2515 CAN BUS MONITOR DEMO BOARD USER'S GUIDE

Preface

NOTICE TO CUSTOMERS

All documentation becomes dated, and this manual is no exception. Microchip tools and documentation are constantly evolving to meet customer needs, so some actual dialogs and/or tool descriptions may differ from those in this document. Please refer to our web site (www.microchip.com) to obtain the latest documentation available.

Documents are identified with a "DS" number. This number is located on the bottom of each page, in front of the page number. The numbering convention for the DS number is "DSXXXXXA", where "XXXXX" is the document number and "A" is the revision level of the document.

For the most up-to-date information on development tools, see the MPLAB® IDE on-line help. Select the Help menu, and then Topics to open a list of available on-line help files.

INTRODUCTION

This chapter contains general information that will be useful to know before using the MCP2515 CAN Bus Monitor Demo Board. Items discussed in this chapter include:

- Document Layout
- Conventions Used in this Guide
- Recommended Reading
- The Microchip Web Site
- Customer Support
- Document Revision History

DOCUMENT LAYOUT

This document describes how to use the MCP2515 CAN Bus Monitor Demo Board as a development tool to emulate and debug firmware on a target board. The manual layout is as follows:

- **Chapter 1. "Product Overview"** – Important information about the MCP2515 CAN Bus Monitor Demo Board.
- **Chapter 2. "Installation and Operation"** – This chapter includes a detailed description of each function of the demo board and instructions for how to begin using the board.
- **Appendix A. "Schematic and Layouts"** – Shows the schematic and layout diagrams for the MCP2515 CAN Bus Monitor Demo Board.
- **Appendix B. "Bill Of Materials (BOM)"** – Lists the parts used to build the MCP2515 CAN Bus Monitor Demo Board.

CONVENTIONS USED IN THIS GUIDE

This manual uses the following documentation conventions:

DOCUMENTATION CONVENTIONS

Description	Represents	Examples
Arial font:		
Italic characters	Referenced books	*MPLAB® IDE User's Guide*
	Emphasized text	...is the *only* compiler...
Initial caps	A window	the Output window
	A dialog	the Settings dialog
	A menu selection	select Enable Programmer
Quotes	A field name in a window or dialog	"Save project before build"
Underlined, italic text with right angle bracket	A menu path	*File>Save*
Bold characters	A dialog button	Click **OK**
	A tab	Click the **Power** tab
N'Rnnnn	A number in verilog format, where N is the total number of digits, R is the radix and n is a digit.	4'b0010, 2'hF1
Text in angle brackets < >	A key on the keyboard	Press <Enter>, <F1>
Courier New font:		
Plain Courier New	Sample source code	`#define START`
	Filenames	`autoexec.bat`
	File paths	`c:\mcc18\h`
	Keywords	`_asm, _endasm, static`
	Command-line options	`-Opa+, -Opa-`
	Bit values	`0, 1`
	Constants	`0xFF, 'A'`
Italic Courier New	A variable argument	*`file`*`.o`, where *`file`* can be any valid filename
Square brackets [ ]	Optional arguments	`mcc18 [options]` *`file`* `[options]`
Curly brackets and pipe character: { | }	Choice of mutually exclusive arguments; an OR selection	`errorlevel {0|1}`
Ellipses...	Replaces repeated text	`var_name [, var_name...]`
	Represents code supplied by user	`void main (void) { ... }`

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RECOMMENDED READING

This user's guide describes how to use MCP2515 CAN Bus Monitor Demo Board. The following Microchip documents are available and recommended as supplemental reference resources.

MCP2515 Data Sheet, *"Stand-Alone CAN Controller With SPI Interface"*, (DS21801)

This data sheet provides detailed information regarding the MCP2515 product family.

MCP2551 Data Sheet, *"High Speed CAN Transceiver"*, (DS21667)

This data sheet provides detailed information regarding the MCP2551 product family.

PIC18F2455/2550/4455/4550 Data Sheet, (DS39632)

This data sheet provides detailed information regarding the PIC18F4550 product family.

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- **General Technical Support** – Frequently Asked Questions (FAQs), technical support requests, online discussion groups, Microchip consultant program member listing
- **Business of Microchip** – Product selector and ordering guides, latest Microchip press releases, listing of seminars and events, listings of Microchip sales offices, distributors and factory representatives

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- Distributor or Representative
- Local Sales Office
- Field Application Engineer (FAE)
- Technical Support

Customers should contact their distributor, representative or field application engineer (FAE) for support. Local sales offices are also available to help customers. A listing of sales offices and locations is included in the back of this document.

Technical support is available through the web site at: http://support.microchip.com

DOCUMENT REVISION HISTORY

Revision A (August 2008)

- Initial Release of this Document.

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Chapter 1. Product Overview

1.1 INTRODUCTION

This chapter provides an overview of the MCP2515 CAN Bus Monitor Demo Board and covers the following topics:

- What is the MCP2515 CAN Bus Monitor Demo Board?
- What the MCP2515 CAN Bus Monitor Demo Board kit includes

1.2 WHAT IS THE MCP2515 CAN BUS MONITOR DEMO BOARD?

The MCP2515 CAN Bus Monitor Demo Board kit contains two identical boards which can be connected together to create a simple two node Controller Area Network (CAN) bus, which can be controlled and/or monitored via the included PC interface. The board(s) can also be connected to an existing CAN bus.

Using the PC interface, users can configure the MCP2515 registers, send CAN messages, and receive CAN messages. CAN traffic can be generated using a button on the board not connected to the PC.

There are also several headers (test points) so the MCP2515 pins can be monitored.

1.3 WHAT THE MCP2515 CAN BUS MONITOR DEMO BOARD KIT INCLUDES

The MCP2515 CAN Bus Monitor Demo Board Kit includes:

- Two MCP2515 CAN Bus Monitor Demo Board boards, 102-00108
- PIC18F4550 Firmware
- Connector cable to connect the two boards together
- Analog and Interface Products Demonstration Boards CD-ROM (DS21912)
  - MCP2515 CAN Bus Monitor Demo Board User's Guide, DS51757)
  - PC software for interfacing with the bus and the MCP2515

NOTES:

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Chapter 2. Installation and Operation

2.1 INTRODUCTION

The MCP2515 CAN Bus Monitor Demo Board kit demonstrates the MCP2515 Stand-Alone CAN Controller interfacing to a CAN bus. The MCP2515 CAN Bus Monitor Demo Board kit consists of two identical boards which, when connected together, create a small, 2-node CAN bus. This bus can be interfaced to a PC by connecting one of the two boards to the PC (USB) and running the custom software.

The two nodes are identical in form, however, the function is determined by the connection to each other and the PC. One node (connected to the PC) will become the monitor and the other one will become the Traffic Generator. The boards are reversible (i.e., they can take either role, depending on the connection scheme).

Additionally, the board(s) can be connected to an existing CAN bus where the software can monitor the traffic and the user can interact with the bus as needed. The software allows some of the MCP2515 registers to be modified, as well as allows messages to be received and transmitted.

The user can gain an understanding of the capabilities of the MCP2515.

2.2 FEATURES

The MCP2515 CAN Bus Monitor Demo Board kit has the following features:

- Two identical boards and a CAN cable for creating a small CAN bus
- USB interface and PC software to interface to the CAN bus
- CAN bus PC software
- Button for changing the bus load on the Traffic Generator node
- Headers (test points) for monitoring the MCP2515 pins (CAN, SPI, and status/interrupt pins)
- PIC18F4550 PIC® Microcontroller (MCU) with ICD2 interface/header for in-circuit programming.

2.3 GETTING STARTED

The MCP2515 CAN Bus Monitor Demo Board is a fully functional, assembled, and tested kit used to demonstrate the MCP2515 in a CAN bus environment. The following describes the basic setup and operation. See Figure 2-1 and Figure 2-2 for a simplified functional diagram and block diagram. Basic Setup:

1. Connect the two boards together using the supplied ribbon cable
2. Connect the USB cable to PC
3. Start the bus monitor software. Both boards will be configured to 125 kb/s CAN rate by default. Select **"Device > Connect"** to connect the board to the GUI.
4. Can now generate traffic (press the "LOAD" button on traffic generator board).

FIGURE 2-1: BLOCK DIAGRAM

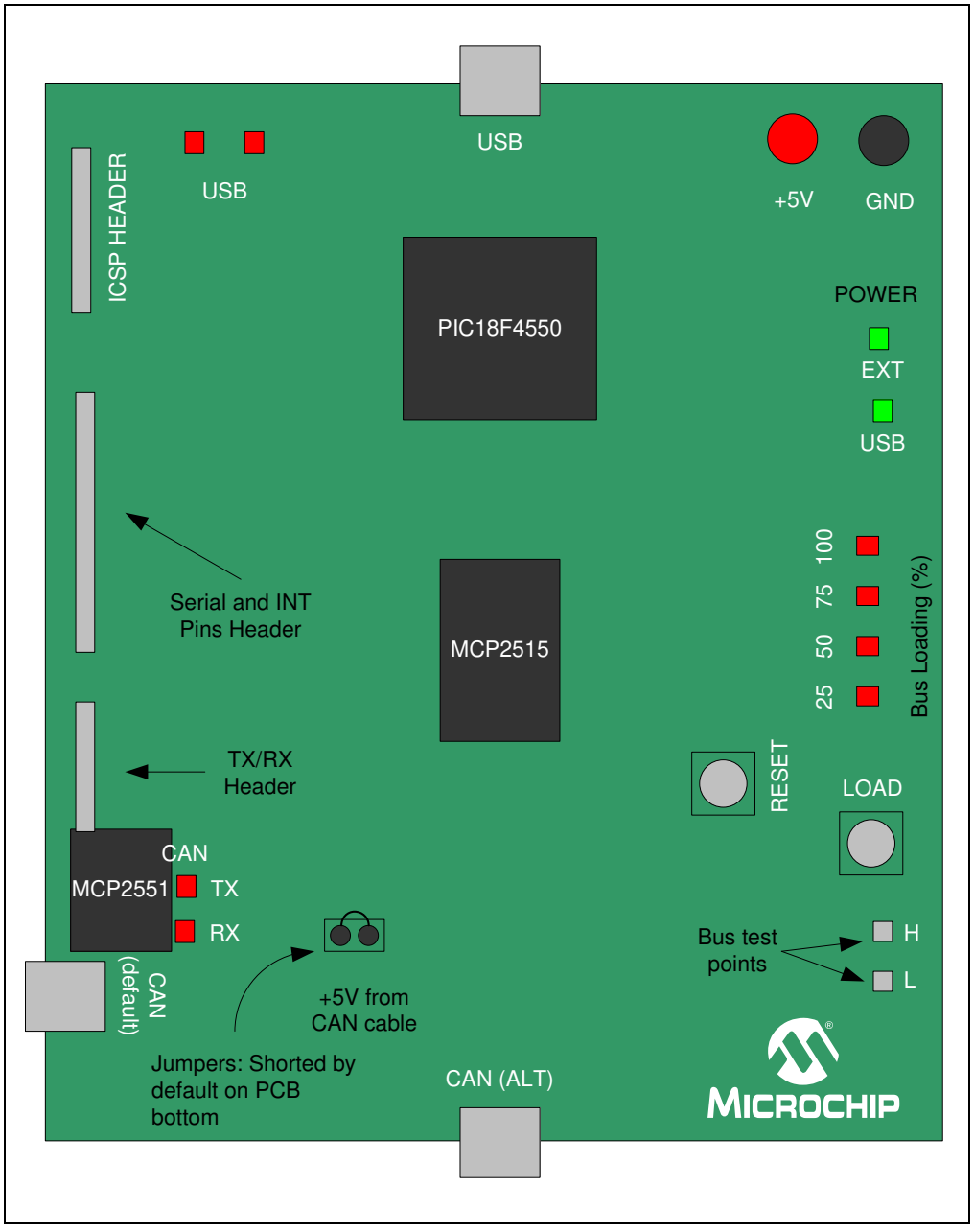

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FIGURE 2-2: FUNCTIONAL DIAGRAM

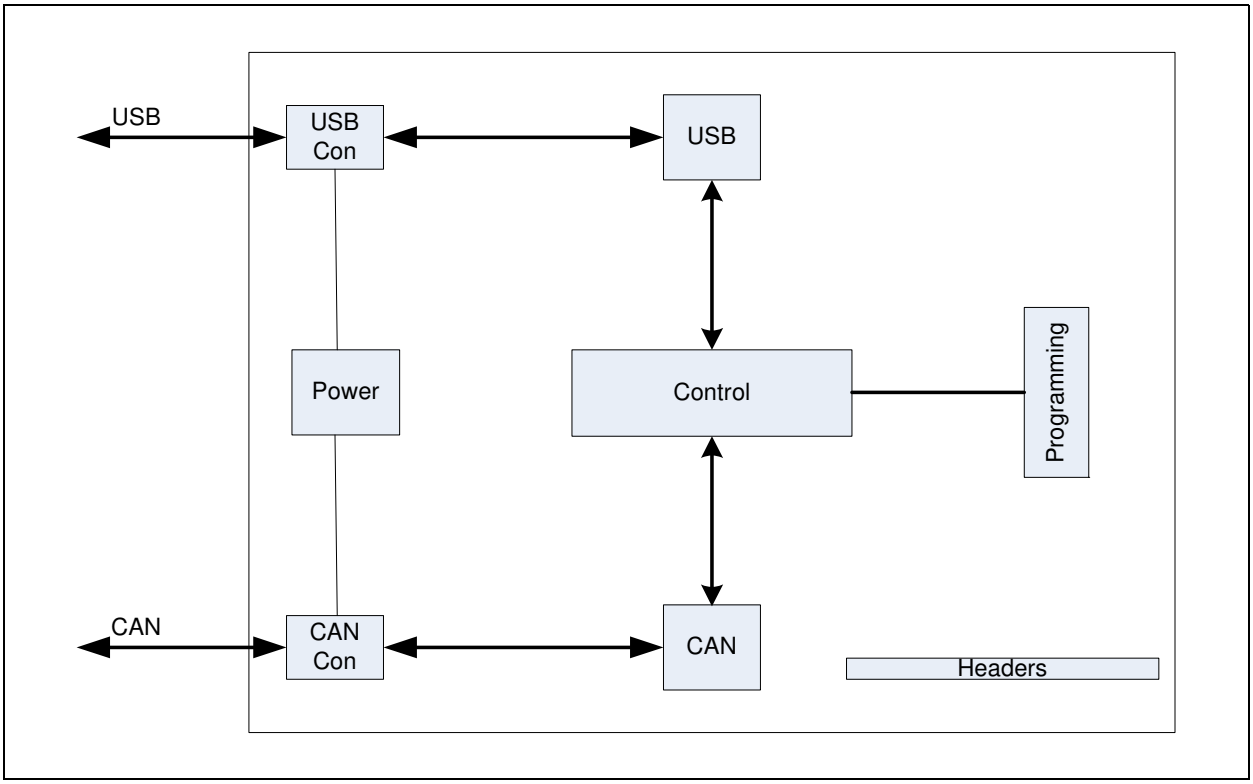
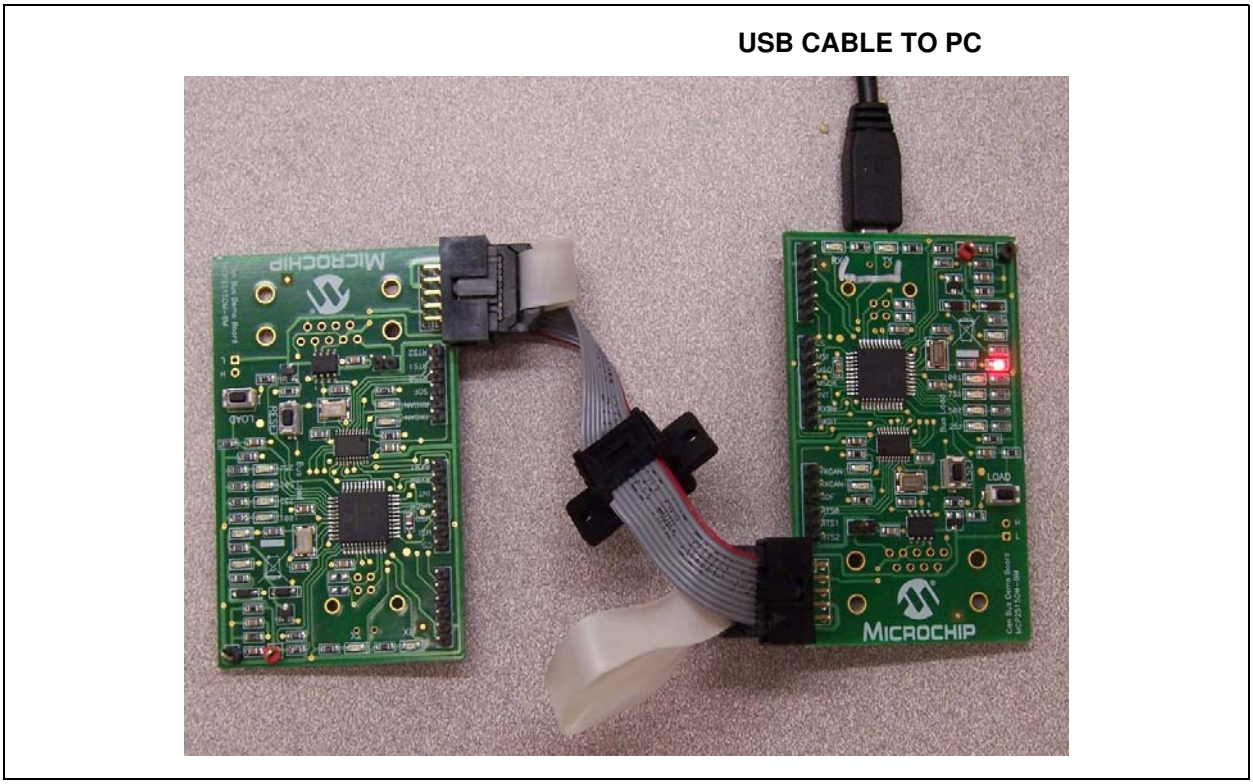


FIGURE 2-3: BOARD SET-UP CONFIGURATION



2.4 FUNCTIONAL OPERATION

The MCP2515 CAN Bus Monitor Demo Board is basically a USB-to-CAN board which provides visual feedback of Controller Area Network operation. The two boards included in the kit can be used together to create a 2-node CAN bus.

The function of the board is determined by how it is powered.

2.4.1 Bus Monitor (Sniffer) Configuration

The board is a designated as a Bus Monitor when the board detects a connection to the USB power (and enumerates to USB).

By default, this node is configured for 125 kb/s and the receive buffers are wide open (i.e., will receive all messages on the bus). The PC software communicates with this node.

2.4.2 Traffic Generator Configuration

The board is designated as a Traffic Generator when it is powered by a source other than USB (In this case, the other board is being powered by the CAN cable). In this configuration, the node responds to pressing the traffic generator button. Each depression of the button increments the bus load to the next step until it rolls arount to zero again, at which time, the load will increment again for every depression.

Note: The silkscreen on the board indicates that the bus loading ranges from 25% to 100% when pressing the "LOAD" button. While the node can handle these loads, the display in the Output window becomes meaningless at loads above 5% - 8%. Therefore, the bus loading is reduced for demonstration purposes. The firmware can be modified to increase the traffic as needed.

2.4.3 Headers/Test Points

Two of the headers are connected to the MCP2515 pins so the pins can be monitored. The SPI and CAN serial interfaces, interrupt pin(s), and SOF pin are routed to headers/test points.

The ICSP signals from the PIC18F4550 are routed to a header.

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2.5 SOFTWARE OPERATION

The software consists of five (5) main windows that are selected by tabs:

1. **Bus Statistics Window:** Shows the status of the bus, including on/off the bus, bus loading, number of transmitted and receive messages, and bit timing settings status. See Figure 2-4
2. **Bus Parameters Window:** Is used to set basic bit timing. The bus speeds are limited to the values in the pull-down box. To set custom bit timing, refer to the MCP2515 Configuration Window. See Figure 2-5
3. **Transmit Window:** This screen is used to configure and transmit CAN messages. See Figure 2-6
4. **Output Window:** This window displays the messages transmitted and received by the MCP2515. The right mouse button can be used to display the time in free running or delta. See Figure 2-7
5. **MCP2515 Configuration Window:** This window allows access to the MCP2515 registers. SPI commands can be issued. See Figure 2-8

FIGURE 2-4: BUS STATISTICS WINDOW

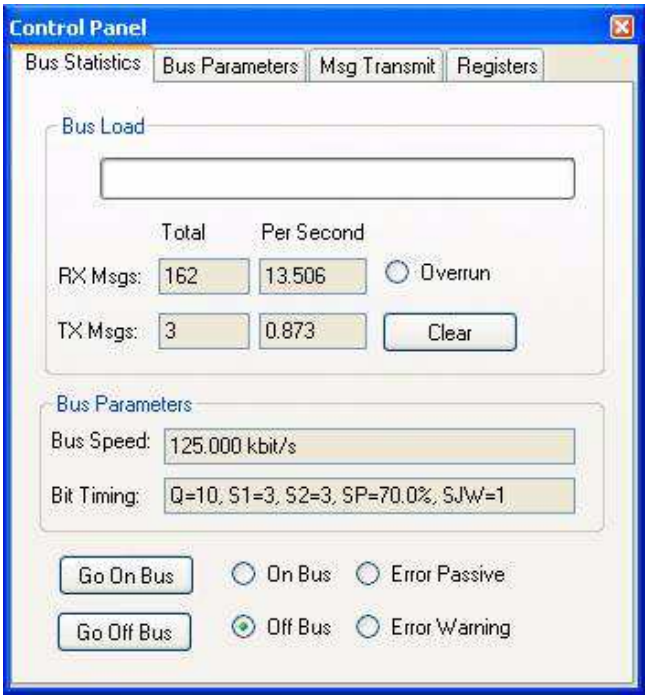

FIGURE 2-5: BUS PARAMETERS WINDOW

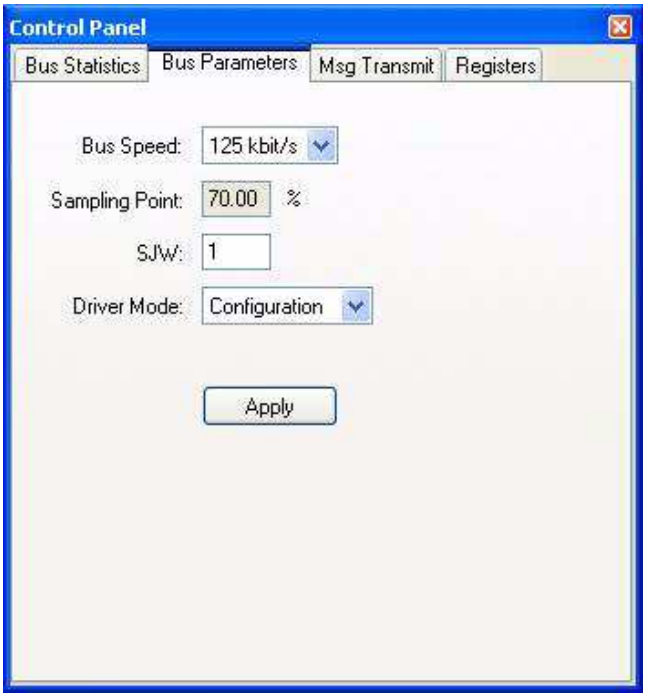

FIGURE 2-6: TRANSMIT WINDOW

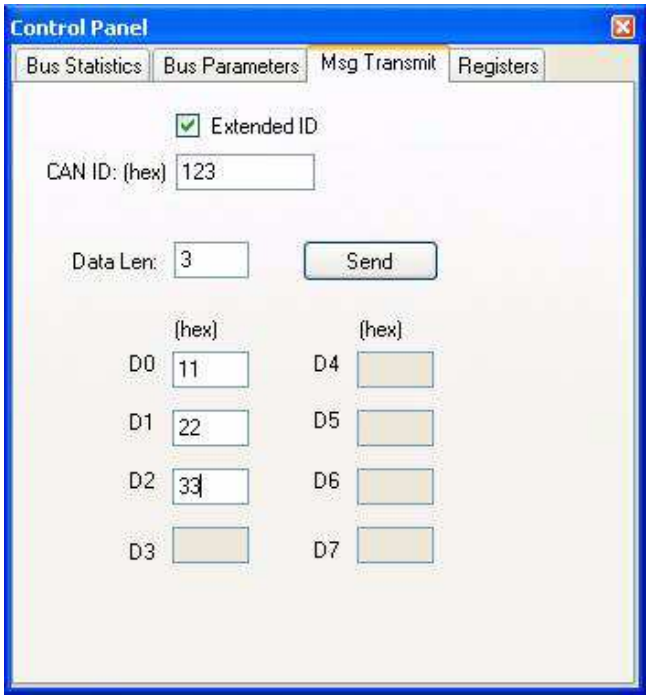

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FIGURE 2-7: OUTPUT WINDOW

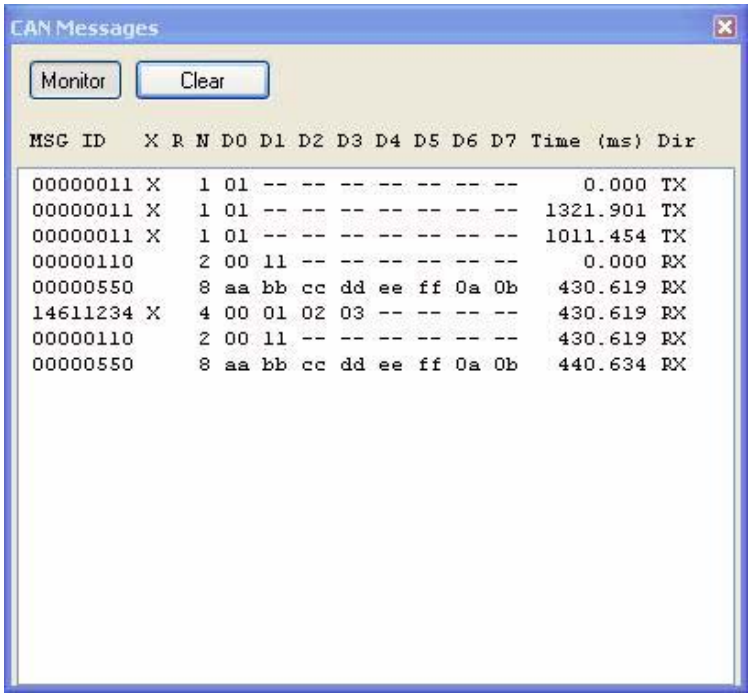
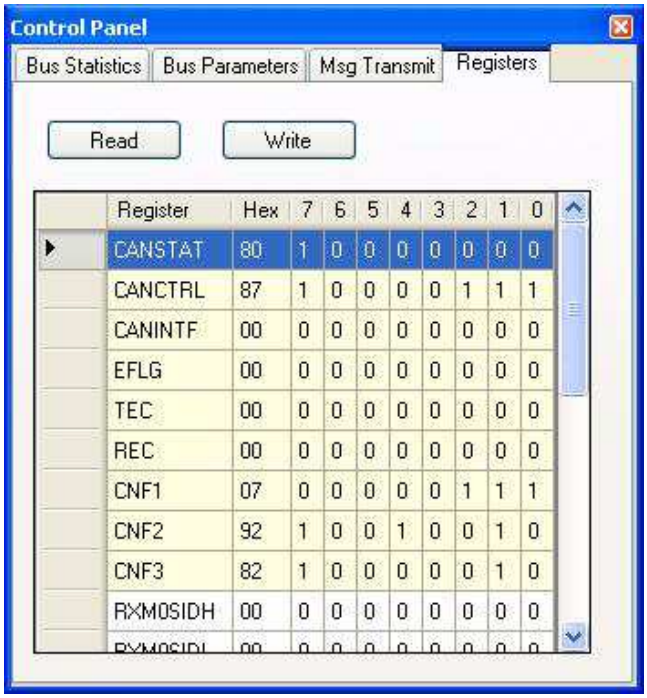


FIGURE 2-8: MCP2515 REGISTERS WINDOW



NOTES:

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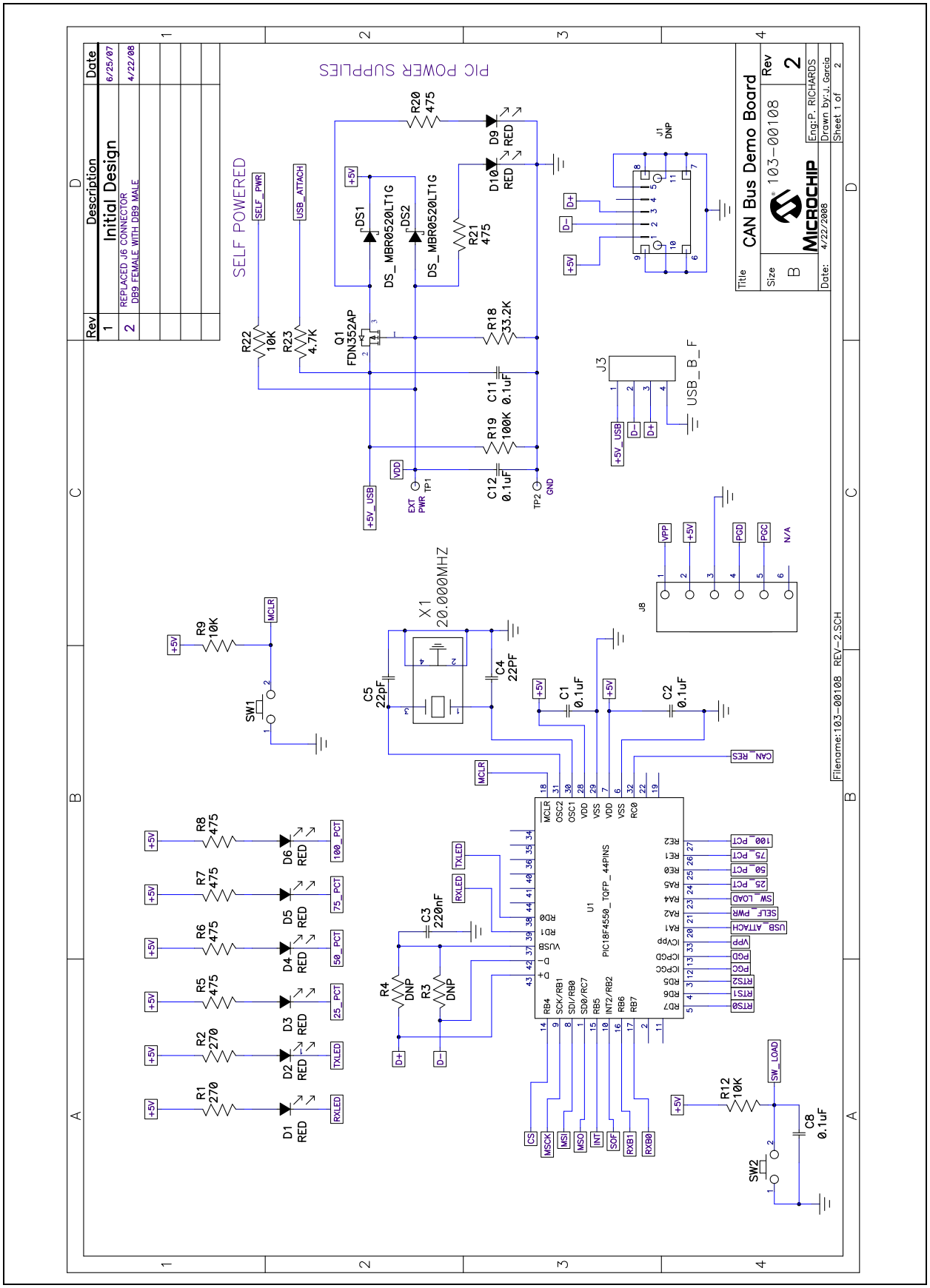
Appendix A. Schematic and Layouts

A.1 INTRODUCTION

This appendix contains the following schematics and layouts for the MCP2515 CAN Bus Monitor Demo Board:

- Board Schematic - Page 1
- Board Schematic - Page 2
- Board - Top Silk-screen Layer
- Board - Top Layer
- Board - Bottom Silk-screen Layer
- Board - Bottom Layer

A.2 BOARD SCHEMATIC - PAGE 1



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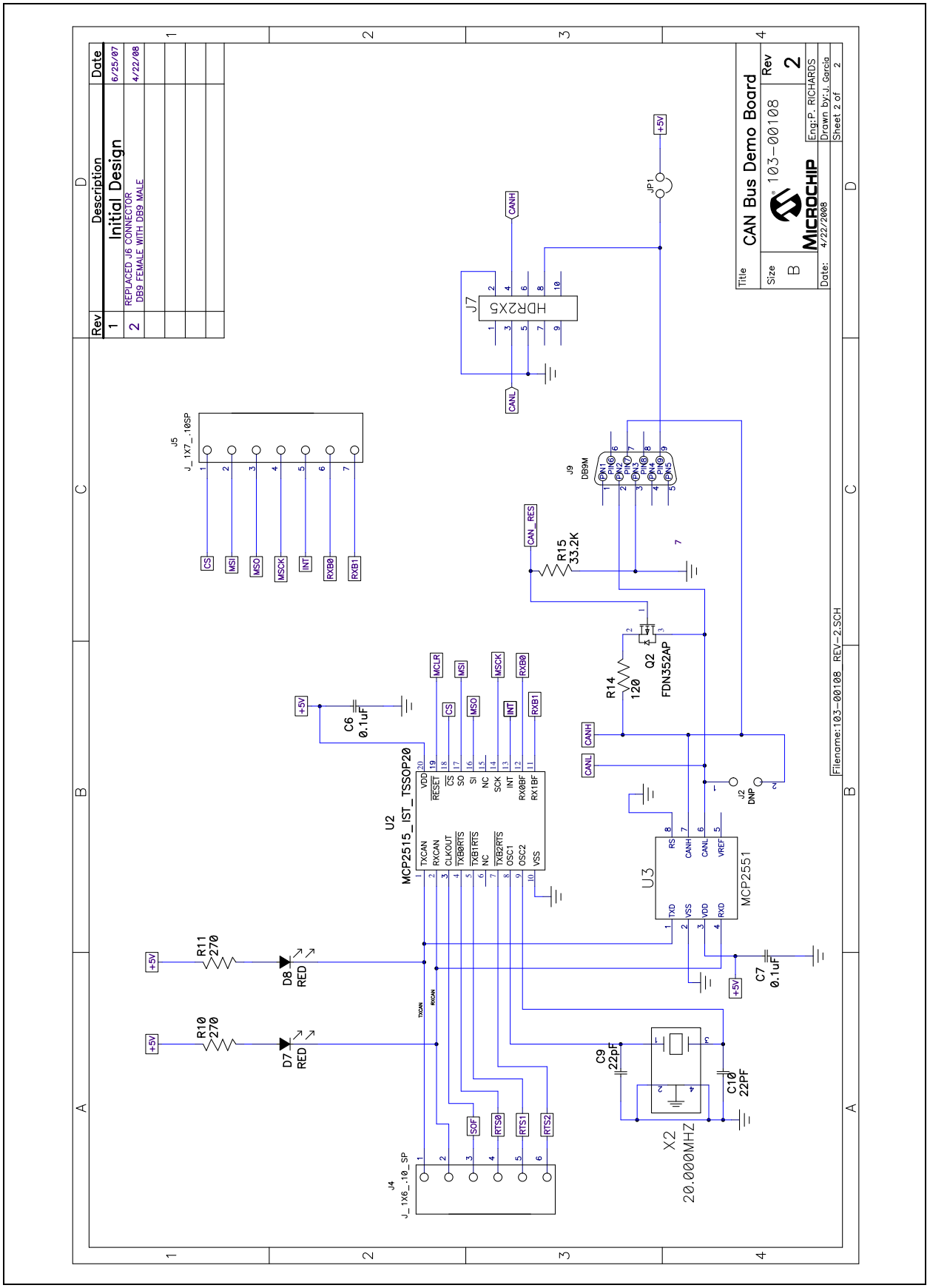
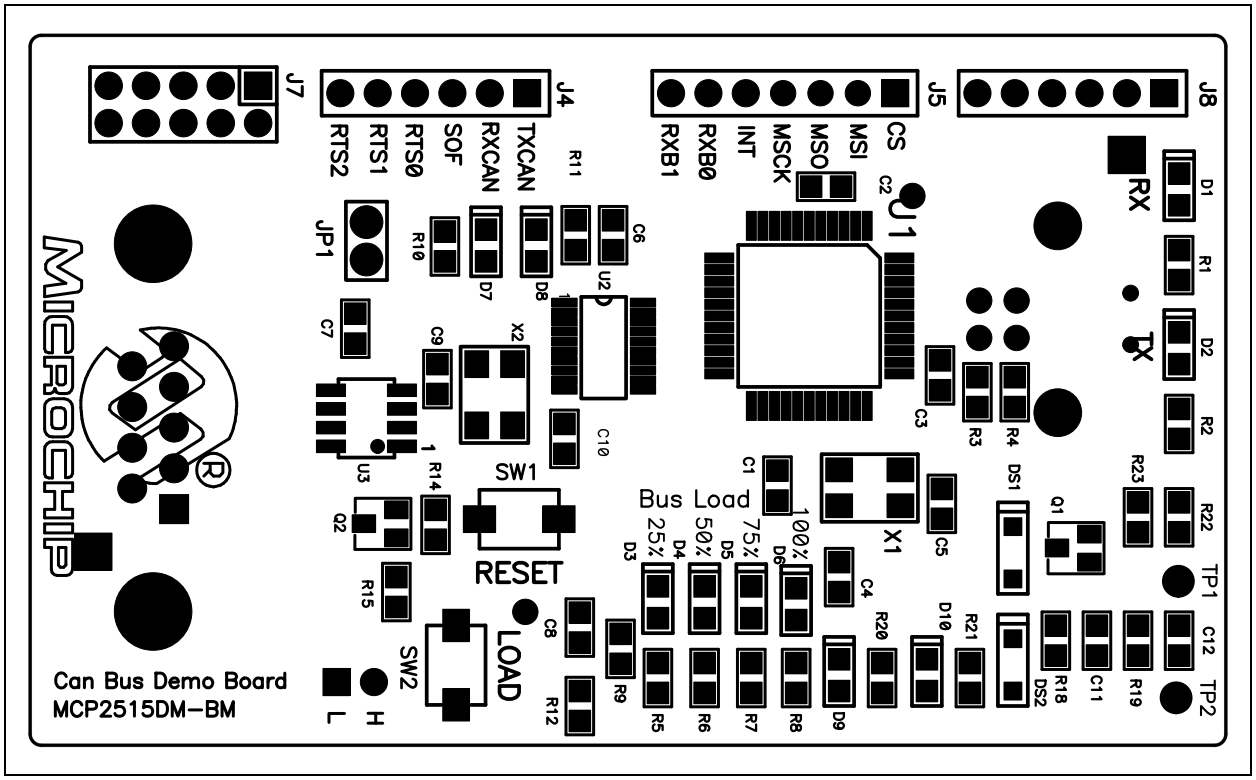
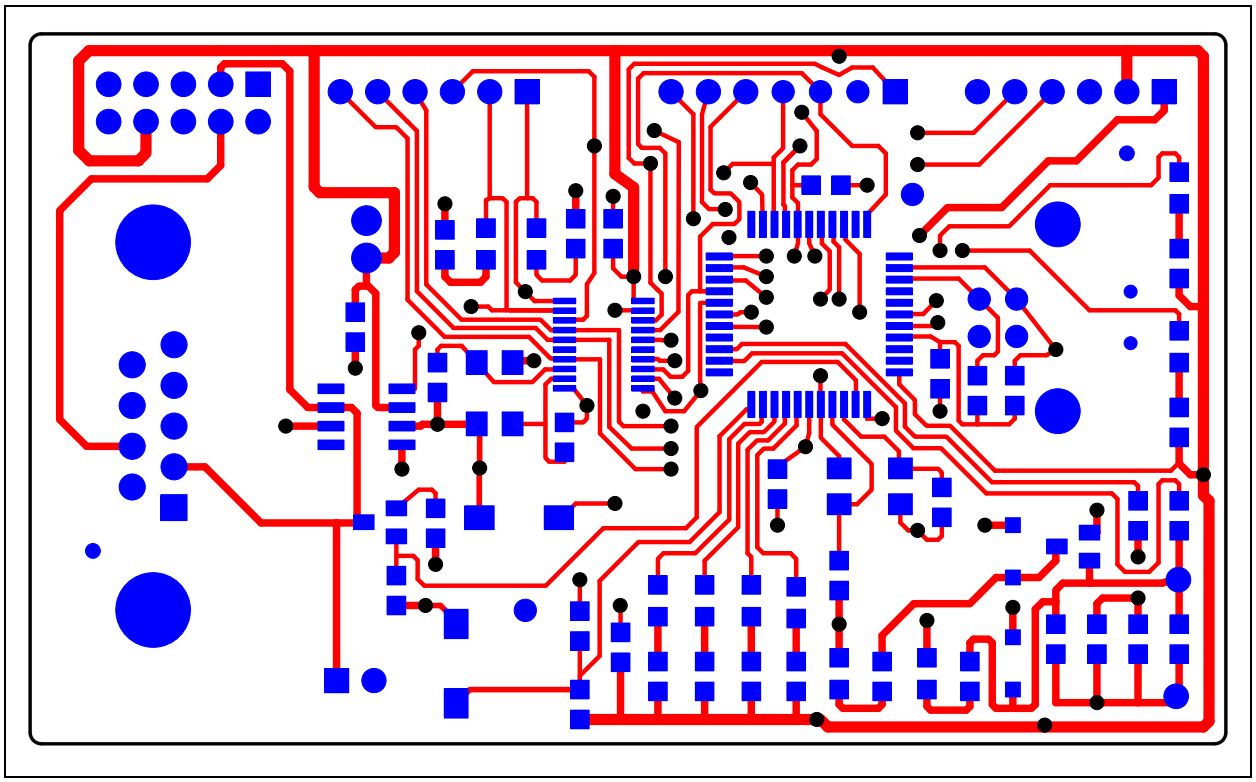
A.3 BOARD SCHEMATIC - PAGE 2



A.4 BOARD - TOP SILK-SCREEN LAYER



A.5 BOARD - TOP LAYER



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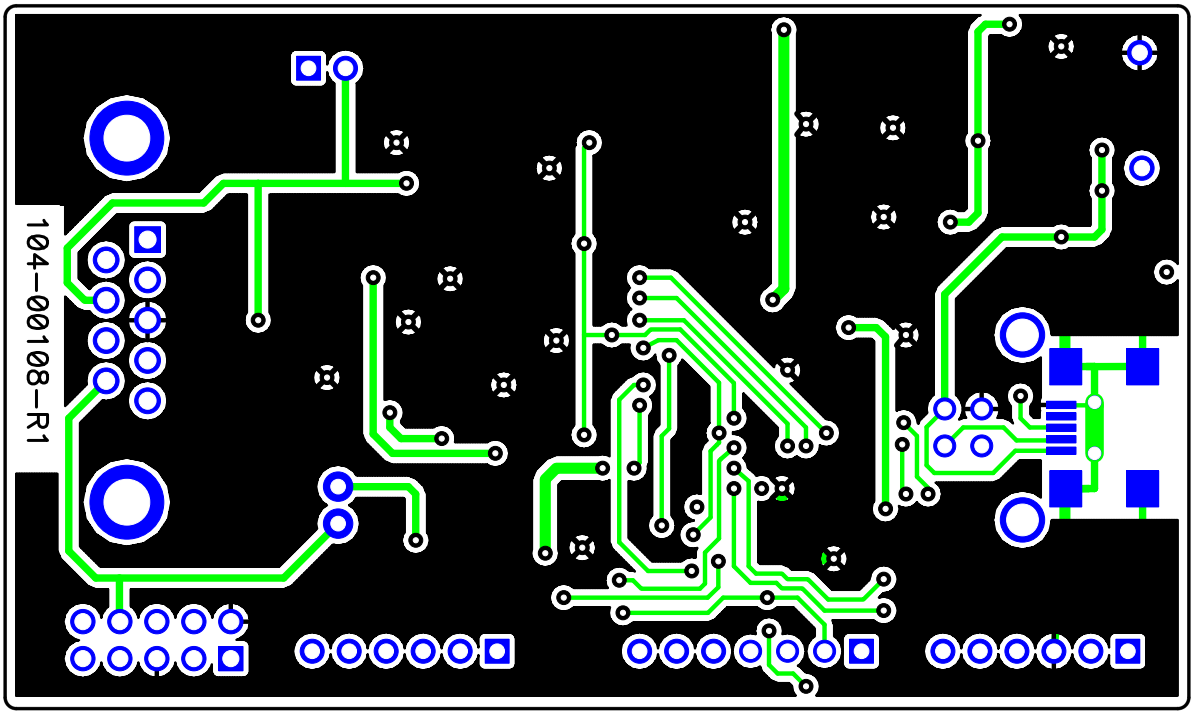
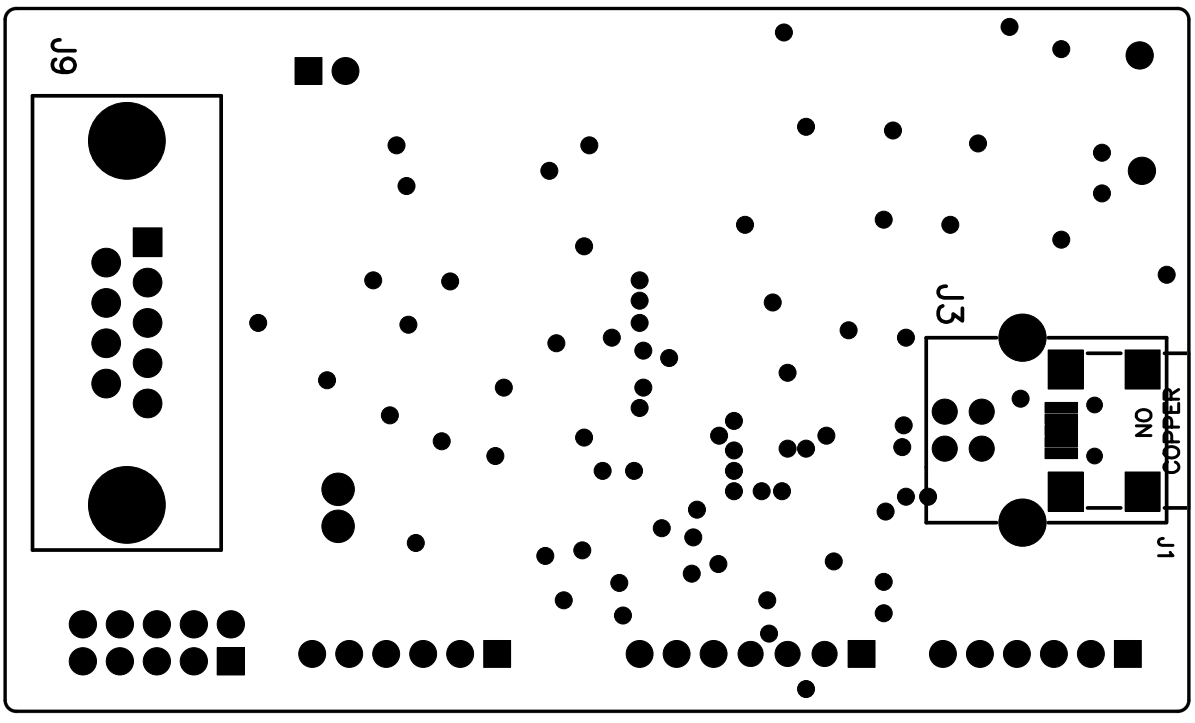
A.6 BOARD - BOTTOM SILK-SCREEN LAYER



A.7 BOARD - BOTTOM LAYER



NOTES:

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Appendix B. Bill Of Materials (BOM)

TABLE B-1: BILL OF MATERIALS (BOM)

Qty	Reference	Description	Manufacturer	Part Number
7	C1, C2, C6, C7, C8, C11, C12	CAP .10UF 50V CERAMIC X7R 0805	Kemet Electronics®	C0805C104K5RACTU
1	C3	CAP .22UF 16V CERAMIC X7R 0805	Panasonic	ECJ-2VB1C224K
4	C4, C5, C9, C10	CAP CERAMIC 22PF 50V NP0 0805	Yageo®	CC0805JRNP09BN220
10	D1<->D10	LED THIN 635NM RED DIFF 0805 SMD	Lumex® Inc.	SML-LXT0805IW-TR
2	DS1, DS2	DIODE SCHOTTKY 20V 0.5A SOD123	ON Semiconductor®	MBR0520LT1G
1	J1	CONN RECEPT MINI USB2.0 5POS (mini USB)	Hirose Electronic Co Ltd	UX60-MB-5ST
0	J2	DO NOT POPULATE	—	—
0	J3	DO NOT POPULATE	—	—
2	J4, J8	CONN HEADER VERT 6POS .100 TIN	Tyco® Electronics/Amp	3-644695-6
1	J5	CONN HEADER VERT 7POS .100 TIN	Tyco Electronics/Amp	3-644695-7
0	J6	DO NOT POPULATE	—	—
1	J7	CONN HEADER LOPRO R/A 10POS 15AU	Tyco Electronics/Amp	103310-1
1	JP1	CONN HEADER VERT 2POS .100 TIN	Tyco Electronics/Amp	3-644695-2
1	PCB	RoHS Compliant Bare PCB, CAN Bus Monitor Demonstration Board	Microchip Technology Inc.	104-000108
2	Q1, Q2	(NDS352P) MPSFET P-CH -20V .5 OHM SSOT3	Fairchild Semiconductor®	NDS352P
4	R1, R2, R10, R11	RES 270 OHM 1/8W 5% 0805 SMD	Panasonic	ERJ-6GEYJ271V
0	R3, R4	DO NOT POPULATE	—	—
6	R5, R6, R7, R8, R20, R21	RES 470 OHM 1/8W 5% 0805 SMD	Panasonic	ERJ-6GEYJ471V
3	R9, R12, R22	RES 10K OHM 1/8W 5% 0805 SMD	Panasonic	ERJ-6GEYJ103V
1	R14	RES 120 OHM 1/8W 5% 0805 SMD	Panasonic	ERJ-6GEYJ121V
2	R15, R18	RES 33.2K OHM 1/8W 1% 0805 SMD	Panasonic	ERJ-6ENF3322V
1	R19	RES 100K OHM 1/8W 1% 0805 SMD	Panasonic	ERJ-6ENF1003V
1	R23	RES 4.7K OHM 1/8W 5% 0805 SMD	Panasonic	ERJ-6GEYJ472V
2	SW1, SW2	SWITCH LT TOUCH 6X3.5 100GF SMD	Panasonic - ECG	EVQ-PJS04K

Note: The components listed in this Bill of Materials are representative of the PCB assembly. The released BOM used in manufacturing uses all RoHS-compliant components.