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MICROCHIP MCP414X/416X/424X/426X

7/8-Bit Single/Dual SPI Digital POT with Non-Volatile Memory

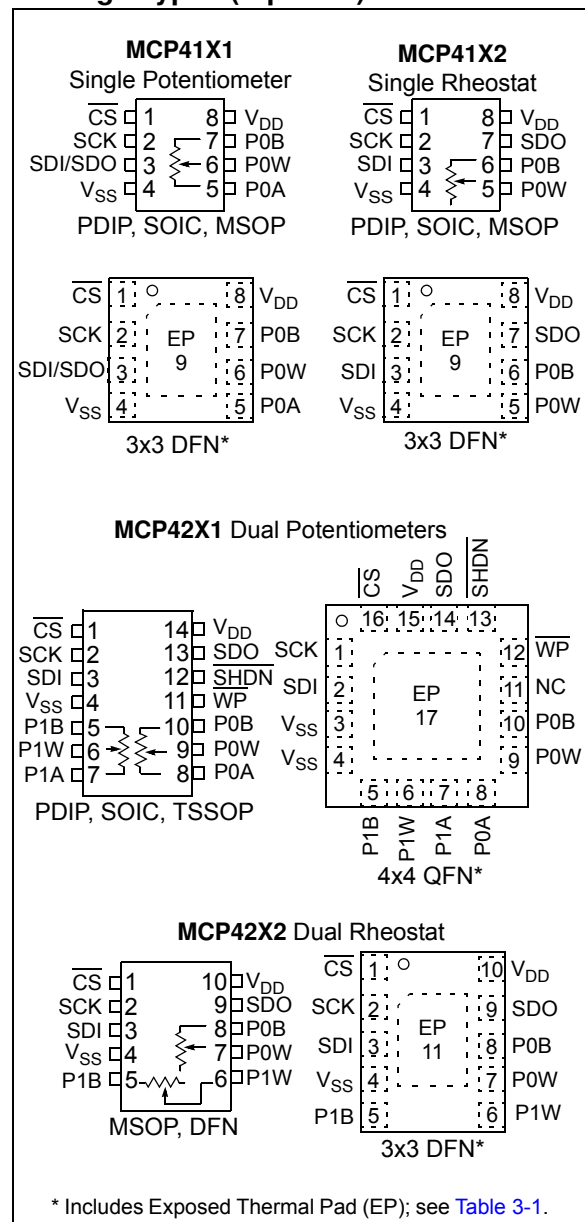
Features

- Single or Dual Resistor Network options
- Potentiometer or Rheostat configuration options
- Resistor Network Resolution
 - 7-bit: 128 Resistors (129 Steps)
 - 8-bit: 256 Resistors (257 Steps)
- R_{AB} Resistances options of:
 - 5 k Ω
 - 10 k Ω
 - 50 k Ω
 - 100 k Ω
- Zero-Scale to Full-Scale Wiper operation
- Low Wiper Resistance: 75 Ω (typical)
- Low Tempco:
 - Absolute (Rheostat): 50 ppm typical (0°C to 70°C)
 - Ratiometric (Potentiometer): 15 ppm typical
- Non-volatile Memory
 - Automatic Recall of Saved Wiper Setting
 - WiperLock™ Technology
- SPI serial interface (10 MHz, modes 0,0 & 1,1)
 - High-Speed Read/Writes to wiper registers
 - Read/Write to Data EEPROM registers
 - Serially enabled EEPROM write protect
 - SDI/SDO multiplexing (MCP41X1 only)
- Resistor Network Terminal Disconnect Feature via:
 - Shutdown pin ($\overline{\text{SHDN}}$)
 - Terminal Control (TCON) Register
- Write Protect Feature:
 - Hardware Write Protect ($\overline{\text{WP}}$) Control pin
 - Software Write Protect (WP) Configuration bit
- Brown-out reset protection (1.5V typical)
- Serial Interface Inactive current (2.5 μA typical)
- High-Voltage Tolerant Digital Inputs: Up to 12.5V
- Supports Split Rail Applications
- Internal weak pull-up on all digital inputs
- Wide Operating Voltage:
 - 2.7V to 5.5V - Device Characteristics Specified
 - 1.8V to 5.5V - Device Operation
- Wide Bandwidth (-3dB) Operation:
 - 2 MHz (typical) for 5.0 k Ω device
- Extended temperature range (-40°C to +125°C)

Description

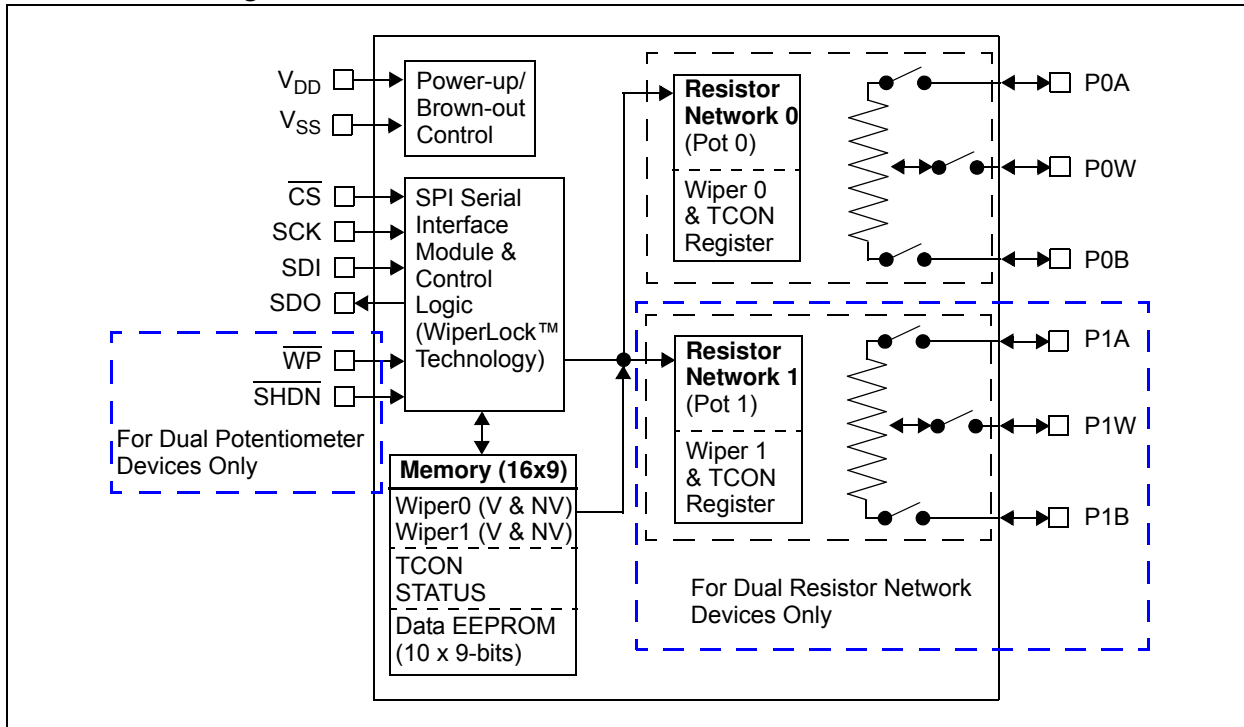
The MCP41XX and MCP42XX devices offer a wide range of product offerings using an SPI interface. WiperLock Technology allows application-specific calibration settings to be secured in the EEPROM.

Package Types (top view)



MCP414X/416X/424X/426X

Device Block Diagram



Device Features

| Device | # of POTs | Wiper Configuration | Control Interface | Memory Type | WiperLock Technology | POR Wiper Setting | Resistance (typical) | | # of Steps | V _{DD} Operating Range ⁽²⁾ |
|------------------------|-----------|------------------------------|-------------------|-------------|----------------------|-------------------|------------------------------|----------------------------|------------|--|
| | | | | | | | R _{AB} Options (kΩ) | Wiper - R _W (Ω) | | |
| MCP4131 ⁽³⁾ | 1 | Potentiometer ⁽¹⁾ | SPI | RAM | No | Mid-Scale | 5.0, 10.0, 50.0, 100.0 | 75 | 129 | 1.8V to 5.5V |
| MCP4132 ⁽³⁾ | 1 | Rheostat | SPI | RAM | No | Mid-Scale | 5.0, 10.0, 50.0, 100.0 | 75 | 129 | 1.8V to 5.5V |
| MCP4141 | 1 | Potentiometer ⁽¹⁾ | SPI | EE | Yes | NV Wiper | 5.0, 10.0, 50.0, 100.0 | 75 | 129 | 2.7V to 5.5V |
| MCP4142 | 1 | Rheostat | SPI | EE | Yes | NV Wiper | 5.0, 10.0, 50.0, 100.0 | 75 | 129 | 2.7V to 5.5V |
| MCP4151 ⁽³⁾ | 1 | Potentiometer ⁽¹⁾ | SPI | RAM | No | Mid-Scale | 5.0, 10.0, 50.0, 100.0 | 75 | 257 | 1.8V to 5.5V |
| MCP4152 ⁽³⁾ | 1 | Rheostat | SPI | RAM | No | Mid-Scale | 5.0, 10.0, 50.0, 100.0 | 75 | 257 | 1.8V to 5.5V |
| MCP4161 | 1 | Potentiometer ⁽¹⁾ | SPI | EE | Yes | NV Wiper | 5.0, 10.0, 50.0, 100.0 | 75 | 257 | 2.7V to 5.5V |
| MCP4162 | 1 | Rheostat | SPI | EE | Yes | NV Wiper | 5.0, 10.0, 50.0, 100.0 | 75 | 257 | 2.7V to 5.5V |
| MCP4231 ⁽³⁾ | 2 | Potentiometer ⁽¹⁾ | SPI | RAM | No | Mid-Scale | 5.0, 10.0, 50.0, 100.0 | 75 | 129 | 1.8V to 5.5V |
| MCP4232 ⁽³⁾ | 2 | Rheostat | SPI | RAM | No | Mid-Scale | 5.0, 10.0, 50.0, 100.0 | 75 | 129 | 1.8V to 5.5V |
| MCP4241 | 2 | Potentiometer ⁽¹⁾ | SPI | EE | Yes | NV Wiper | 5.0, 10.0, 50.0, 100.0 | 75 | 129 | 2.7V to 5.5V |
| MCP4242 | 2 | Rheostat | SPI | EE | Yes | NV Wiper | 5.0, 10.0, 50.0, 100.0 | 75 | 129 | 2.7V to 5.5V |
| MCP4251 ⁽³⁾ | 2 | Potentiometer ⁽¹⁾ | SPI | RAM | No | Mid-Scale | 5.0, 10.0, 50.0, 100.0 | 75 | 257 | 1.8V to 5.5V |
| MCP4252 ⁽³⁾ | 2 | Rheostat | SPI | RAM | No | Mid-Scale | 5.0, 10.0, 50.0, 100.0 | 75 | 257 | 1.8V to 5.5V |
| MCP4261 | 2 | Potentiometer ⁽¹⁾ | SPI | EE | Yes | NV Wiper | 5.0, 10.0, 50.0, 100.0 | 75 | 257 | 2.7V to 5.5V |
| MCP4262 | 2 | Rheostat | SPI | EE | Yes | NV Wiper | 5.0, 10.0, 50.0, 100.0 | 75 | 257 | 2.7V to 5.5V |

Note 1: Floating either terminal (A or B) allows the device to be used as a Rheostat (variable resistor).

2: Analog characteristics only tested from 2.7V to 5.5V unless otherwise noted.

3: Please check Microchip web site for device release and availability

1.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings †

| | |
|---|--|
| Voltage on V_{DD} with respect to V_{SS} | -0.6V to +7.0V |
| Voltage on \overline{CS} , SCK, SDI, SDI/SDO, \overline{WP} , and SHDN with respect to V_{SS} | -0.6V to 12.5V |
| Voltage on all other pins (PxA, PxW, PxB, and SDO) with respect to V_{SS} | -0.3V to $V_{DD} + 0.3V$ |
| Input clamp current, I_{IK} ($V_I < 0$, $V_I > V_{DD}$, $V_I > V_{PP}$ ON HV pins) | ± 20 mA |
| Output clamp current, I_{OK} ($V_O < 0$ or $V_O > V_{DD}$) | ± 20 mA |
| Maximum output current sunk by any Output pin | 25 mA |
| Maximum output current sourced by any Output pin | 25 mA |
| Maximum current out of V_{SS} pin | 100 mA |
| Maximum current into V_{DD} pin | 100 mA |
| Maximum current into PxA, PxW & PxB pins | ± 2.5 mA |
| Storage temperature | -65°C to +150°C |
| Ambient temperature with power applied | -40°C to +125°C |
| Total power dissipation (Note 1) | 400 mW |
| Soldering temperature of leads (10 seconds) | +300°C |
| ESD protection on all pins | ≥ 4 kV (HBM), $\geq 300V$ (MM) |
| Maximum Junction Temperature (T_J) | +150°C |

Note 1: Power dissipation is calculated as follows:

$$P_{dis} = V_{DD} \times \{I_{DD} - \sum I_{OH}\} + \sum \{(V_{DD} - V_{OH}) \times I_{OH}\} + \sum (V_{OI} \times I_{OL})$$

† **Notice:** Stresses above those listed under “Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

MCP414X/416X/424X/426X

AC/DC CHARACTERISTICS

| DC Characteristics | | Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ (extended) All parameters apply across the specified operating ranges unless noted. $V_{DD} = +2.7\text{V}$ to 5.5V , $5\text{ k}\Omega$, $10\text{ k}\Omega$, $50\text{ k}\Omega$, $100\text{ k}\Omega$ devices. Typical specifications represent values for $V_{DD} = 5.5\text{V}$, $T_A = +25^{\circ}\text{C}$. | | | | |
|---|------------|--|------|------------------------|---------------|---|
| Parameters | Sym | Min | Typ | Max | Units | Conditions |
| Supply Voltage | V_{DD} | 2.7 | — | 5.5 | V | |
| | | 1.8 | — | 2.7 | V | Serial Interface only. |
| CS, SDI, SDO, SCK, WP, SHDN pin Voltage Range | V_{HV} | V_{SS} | — | 12.5V | V | $V_{DD} \geq 4.5\text{V}$ The CS pin will be at one of three input levels (V_{IL} , V_{IH} or V_{IHH}). (Note 6) |
| | | V_{SS} | — | $V_{DD} + 8.0\text{V}$ | V | $V_{DD} < 4.5\text{V}$ |
| VDD Start Voltage to ensure Wiper Reset | V_{BOR} | — | — | 1.65 | V | RAM retention voltage (V_{RAM}) $< V_{BOR}$ |
| VDD Rise Rate to ensure Power-on Reset | V_{DDRR} | (Note 9) | | | V/ms | |
| Delay after device exits the reset state ($V_{DD} > V_{BOR}$) | T_{BORD} | — | 10 | 20 | μs | |
| Supply Current (Note 10) | I_{DD} | — | — | 450 | μA | Serial Interface Active, $V_{DD} = 5.5\text{V}$, $\overline{\text{CS}} = V_{IL}$, SCK @ 5 MHz, write all 0's to volatile Wiper 0 (address 0h) |
| | | — | — | 1 | mA | EE Write Current, $V_{DD} = 5.5\text{V}$, $\overline{\text{CS}} = V_{IL}$, SCK @ 5 MHz, write all 0's to non-volatile Wiper 0 (address 2h) |
| | | — | 2.5 | 5 | μA | Serial Interface Inactive, $\overline{\text{CS}} = V_{IH}$, $V_{DD} = 5.5\text{V}$ |
| | | — | 0.55 | 1 | mA | Serial Interface Active, $V_{DD} = 5.5\text{V}$, $\overline{\text{CS}} = V_{IHH}$, SCK @ 5 MHz, decrement non-volatile Wiper 0 (address 2h) |

- Note 1:** Resistance is defined as the resistance between terminal A to terminal B.
- 2:** INL and DNL are measured at V_W with $V_A = V_{DD}$ and $V_B = V_{SS}$.
- 3:** MCP4XX1 only.
- 4:** MCP4XX2 only, includes V_{WZSE} and V_{WFSE} .
- 5:** Resistor terminals A, W and B's polarity with respect to each other is not restricted.
- 6:** This specification by design.
- 7:** Non-linearity is affected by wiper resistance (R_W), which changes significantly over voltage and temperature.
- 8:** The MCP4XX1 is externally connected to match the configurations of the MCP41X2 and MCP42X2, and then tested.
- 9:** POR/BOR is not rate dependent.
- 10:** Supply current is independent of current through the resistor network

MCP414X/416X/424X/426X

AC/DC CHARACTERISTICS (CONTINUED)

| DC Characteristics | | Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ (extended) All parameters apply across the specified operating ranges unless noted. $V_{DD} = +2.7\text{V}$ to 5.5V , $5\text{ k}\Omega$, $10\text{ k}\Omega$, $50\text{ k}\Omega$, $100\text{ k}\Omega$ devices. Typical specifications represent values for $V_{DD} = 5.5\text{V}$, $T_A = +25^{\circ}\text{C}$. | | | | | |
|--|--------------------------------|--|------------------|----------|-------------------------|---|--|
| Parameters | Sym | Min | Typ | Max | Units | Conditions | |
| Resistance ($\pm 20\%$) | R_{AB} | 4.0 | 5 | 6.0 | k Ω | -502 devices (Note 1) | |
| | | 8.0 | 10 | 12.0 | k Ω | -103 devices (Note 1) | |
| | | 40.0 | 50 | 60.0 | k Ω | -503 devices (Note 1) | |
| | | 80.0 | 100 | 120.0 | k Ω | -104 devices (Note 1) | |
| Resolution | N | 257 | | | Taps | 8-bit No Missing Codes | |
| | | 129 | | | Taps | 7-bit No Missing Codes | |
| Step Resistance | R_S | — | $R_{AB} / (256)$ | — | Ω | 8-bit Note 6 | |
| | | — | $R_{AB} / (128)$ | — | Ω | 7-bit Note 6 | |
| Nominal Resistance Match | $ R_{AB0} - R_{AB1} / R_{AB}$ | — | 0.2 | 1.25 | % | MCP42X1 devices only | |
| | $ R_{BW0} - R_{BW1} / R_{BW}$ | — | 0.25 | 1.5 | % | MCP42X2 devices only, Code = Full-Scale | |
| Wiper Resistance (Note 3, Note 4) | R_W | — | 75 | 160 | Ω | $V_{DD} = 5.5\text{ V}$, $I_W = 2.0\text{ mA}$, code = 00h | |
| | | — | 75 | 300 | Ω | $V_{DD} = 2.7\text{ V}$, $I_W = 2.0\text{ mA}$, code = 00h | |
| Nominal Resistance Tempco | $\Delta R_{AB} / \Delta T$ | — | 50 | — | ppm/ $^{\circ}\text{C}$ | $T_A = -20^{\circ}\text{C}$ to $+70^{\circ}\text{C}$ | |
| | | — | 100 | — | ppm/ $^{\circ}\text{C}$ | $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ | |
| | | — | 150 | — | ppm/ $^{\circ}\text{C}$ | $T_A = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$ | |
| Ratiometric Tempco | $\Delta V_{WB} / \Delta T$ | — | 15 | — | ppm/ $^{\circ}\text{C}$ | Code = Midscale (80h or 40h) | |
| Resistor Terminal Input Voltage Range (Terminals A, B and W) | V_A, V_W, V_B | V_{SS} | — | V_{DD} | V | Note 5, Note 6 | |
| Maximum current through A, W or B | I_W | — | — | 2.5 | mA | Note 6 , Worst case current through wiper when wiper is either Full-Scale or Zero Scale. | |
| Leakage current into A, W or B | I_{WL} | — | 100 | — | nA | MCP4XX1 $PxA = PxB = V_{SS}$ | |
| | | — | 100 | — | nA | MCP4XX2 $PxB = PkW = V_{SS}$ | |

Note 1: Resistance is defined as the resistance between terminal A to terminal B.

2: INL and DNL are measured at V_W with $V_A = V_{DD}$ and $V_B = V_{SS}$.

3: **MCP4XX1** only.

4: **MCP4XX2** only, includes V_{WZSE} and V_{WFSE} .

5: Resistor terminals A, W and B's polarity with respect to each other is not restricted.

6: This specification by design.

7: Non-linearity is affected by wiper resistance (R_W), which changes significantly over voltage and temperature.

8: The **MCP4XX1** is externally connected to match the configurations of the **MCP41X2** and **MCP42X2**, and then tested.

9: POR/BOR is not rate dependent.

10: Supply current is independent of current through the resistor network

MCP414X/416X/424X/426X

AC/DC CHARACTERISTICS (CONTINUED)

| DC Characteristics | | Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ (extended) All parameters apply across the specified operating ranges unless noted. $V_{DD} = +2.7\text{V}$ to 5.5V , $5\text{ k}\Omega$, $10\text{ k}\Omega$, $50\text{ k}\Omega$, $100\text{ k}\Omega$ devices. Typical specifications represent values for $V_{DD} = 5.5\text{V}$, $T_A = +25^{\circ}\text{C}$. | | | | | | |
|--|------------|--|-------------|-------|-------|----------------|--|--|
| Parameters | Sym | Min | Typ | Max | Units | Conditions | | |
| Full-Scale Error (MCP4XX1 only) (8-bit code = 100h, 7-bit code = 80h) | V_{WFSE} | -6.0 | -0.1 | — | LSb | 5 k Ω | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | -4.0 | -0.1 | — | LSb | | 7-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | -3.5 | -0.1 | — | LSb | 10 k Ω | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | -2.0 | -0.1 | — | LSb | | 7-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | -0.8 | -0.1 | — | LSb | 50 k Ω | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | -0.5 | -0.1 | — | LSb | | 7-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | -0.5 | -0.1 | — | LSb | 100 k Ω | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | -0.5 | -0.1 | — | LSb | | 7-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| Zero-Scale Error (MCP4XX1 only) (8-bit code = 00h, 7-bit code = 00h) | V_{WZSE} | — | +0.1 | +6.0 | LSb | 5 k Ω | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | — | +0.1 | +3.0 | LSb | | 7-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | — | +0.1 | +3.5 | LSb | 10 k Ω | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | — | +0.1 | +2.0 | LSb | | 7-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | — | +0.1 | +0.8 | LSb | 50 k Ω | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | — | +0.1 | +0.5 | LSb | | 7-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | — | +0.1 | +0.5 | LSb | 100 k Ω | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| | | — | +0.1 | +0.5 | LSb | | 7-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ |
| Potentiometer Integral Non-linearity | INL | -1 | ± 0.5 | +1 | LSb | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ | |
| | | -0.5 | ± 0.25 | +0.5 | LSb | 7-bit | MCP4XX1 devices only (Note 2) | |
| Potentiometer Differential Non-linearity | DNL | -0.5 | ± 0.25 | +0.5 | LSb | 8-bit | $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$ | |
| | | -0.25 | ± 0.125 | +0.25 | LSb | 7-bit | MCP4XX1 devices only (Note 2) | |
| Bandwidth -3 dB (See Figure 2-58, load = 30 pF) | BW | — | 2 | — | MHz | 5 k Ω | 8-bit | Code = 80h |
| | | — | 2 | — | MHz | | 7-bit | Code = 40h |
| | | — | 1 | — | MHz | 10 k Ω | 8-bit | Code = 80h |
| | | — | 1 | — | MHz | | 7-bit | Code = 40h |
| | | — | 200 | — | kHz | 50 k Ω | 8-bit | Code = 80h |
| | | — | 200 | — | kHz | | 7-bit | Code = 40h |
| | | — | 100 | — | kHz | 100 k Ω | 8-bit | Code = 80h |
| | | — | 100 | — | kHz | | 7-bit | Code = 40h |

Note 1: Resistance is defined as the resistance between terminal A to terminal B.

2: INL and DNL are measured at V_W with $V_A = V_{DD}$ and $V_B = V_{SS}$.

3: MCP4XX1 only.

4: MCP4XX2 only, includes V_{WZSE} and V_{WFSE} .

5: Resistor terminals A, W and B's polarity with respect to each other is not restricted.

6: This specification by design.

7: Non-linearity is affected by wiper resistance (R_W), which changes significantly over voltage and temperature.

8: The MCP4XX1 is externally connected to match the configurations of the MCP41X2 and MCP42X2, and then tested.

9: POR/BOR is not rate dependent.

10: Supply current is independent of current through the resistor network

MCP414X/416X/424X/426X

AC/DC CHARACTERISTICS (CONTINUED)

| DC Characteristics | | Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ (extended) All parameters apply across the specified operating ranges unless noted. $V_{DD} = +2.7\text{V}$ to 5.5V , $5\text{ k}\Omega$, $10\text{ k}\Omega$, $50\text{ k}\Omega$, $100\text{ k}\Omega$ devices. Typical specifications represent values for $V_{DD} = 5.5\text{V}$, $T_A = +25^{\circ}\text{C}$. | | | | | | |
|---|-------|--|-----------|--------|-------|----------------|-------|--|
| Parameters | Sym | Min | Typ | Max | Units | Conditions | | |
| Rheostat Integral Non-linearity MCP41X1 (Note 4, Note 8) MCP4XX2 devices only (Note 4) | R-INL | -1.5 | ± 0.5 | +1.5 | LSb | 5 k Ω | 8-bit | 5.5V, $I_W = 900\ \mu\text{A}$ |
| | | -8.25 | +4.5 | +8.25 | LSb | | | 3.0V, $I_W = 480\ \mu\text{A}$ (Note 7) |
| | | -1.125 | ± 0.5 | +1.125 | LSb | 5 k Ω | 7-bit | 5.5V, $I_W = 900\ \mu\text{A}$ |
| | | -6.0 | +4.5 | +6.0 | LSb | | | 3.0V, $I_W = 480\ \mu\text{A}$ (Note 7) |
| | | -1.5 | ± 0.5 | +1.5 | LSb | 10 k Ω | 8-bit | 5.5V, $I_W = 450\ \mu\text{A}$ |
| | | -5.5 | +2.5 | +5.5 | LSb | | | 3.0V, $I_W = 240\ \mu\text{A}$ (Note 7) |
| | | -1.125 | ± 0.5 | +1.125 | LSb | 10 k Ω | 7-bit | 5.5V, $I_W = 450\ \mu\text{A}$ |
| | | -4.0 | +2.5 | +4.0 | LSb | | | 3.0V, $I_W = 240\ \mu\text{A}$ (Note 7) |
| | | -1.5 | ± 0.5 | +1.5 | LSb | 50 k Ω | 8-bit | 5.5V, $I_W = 90\ \mu\text{A}$ |
| | | -2.0 | +1 | +2.0 | LSb | | | 3.0V, $I_W = 48\ \mu\text{A}$ (Note 7) |
| | | -1.125 | ± 0.5 | +1.125 | LSb | 50 k Ω | 7-bit | 5.5V, $I_W = 90\ \mu\text{A}$ |
| | | -1.5 | +1 | +1.5 | LSb | | | 3.0V, $I_W = 48\ \mu\text{A}$ (Note 7) |
| | | -1.0 | ± 0.5 | +1.0 | LSb | 100 k Ω | 8-bit | 5.5V, $I_W = 45\ \mu\text{A}$ |
| | | -1.5 | +0.25 | +1.5 | LSb | | | 3.0V, $I_W = 24\ \mu\text{A}$ (Note 7) |
| | | -0.8 | ± 0.5 | +0.8 | LSb | 100 k Ω | 7-bit | 5.5V, $I_W = 45\ \mu\text{A}$ |
| | | -1.125 | +0.25 | +1.125 | LSb | | | 3.0V, $I_W = 24\ \mu\text{A}$ (Note 7) |

- Note 1:** Resistance is defined as the resistance between terminal A to terminal B.
- Note 2:** INL and DNL are measured at V_W with $V_A = V_{DD}$ and $V_B = V_{SS}$.
- Note 3:** **MCP4XX1** only.
- Note 4:** **MCP4XX2** only, includes V_{WZSE} and V_{WFSE} .
- Note 5:** Resistor terminals A, W and B's polarity with respect to each other is not restricted.
- Note 6:** This specification by design.
- Note 7:** Non-linearity is affected by wiper resistance (R_W), which changes significantly over voltage and temperature.
- Note 8:** The **MCP4XX1** is externally connected to match the configurations of the **MCP41X2** and **MCP42X2**, and then tested.
- Note 9:** POR/BOR is not rate dependent.
- Note 10:** Supply current is independent of current through the resistor network

MCP414X/416X/424X/426X

AC/DC CHARACTERISTICS (CONTINUED)

| DC Characteristics | | Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ (extended) All parameters apply across the specified operating ranges unless noted. $V_{DD} = +2.7\text{V}$ to 5.5V , $5\text{ k}\Omega$, $10\text{ k}\Omega$, $50\text{ k}\Omega$, $100\text{ k}\Omega$ devices. Typical specifications represent values for $V_{DD} = 5.5\text{V}$, $T_A = +25^{\circ}\text{C}$. | | | | | | |
|---|----------|--|------------|--------|-------|------------------------------|-------|--------------------------------|
| Parameters | Sym | Min | Typ | Max | Units | Conditions | | |
| Rheostat Differential Non-linearity MCP41X1 (Note 4, Note 8) MCP4XX2 devices only (Note 4) | R-DNL | -0.5 | ± 0.25 | +0.5 | LSb | 5 k Ω | 8-bit | 5.5V, $I_W = 900\ \mu\text{A}$ |
| | | -1.0 | +0.5 | +1.0 | LSb | | | 3.0V (Note 7) |
| | | -0.375 | ± 0.25 | +0.375 | LSb | | 7-bit | 5.5V, $I_W = 900\ \mu\text{A}$ |
| | | -0.75 | +0.5 | +0.75 | LSb | | | 3.0V (Note 7) |
| | | -0.5 | ± 0.25 | +0.5 | LSb | 10 k Ω | 8-bit | 5.5V, $I_W = 450\ \mu\text{A}$ |
| | | -1.0 | +0.25 | +1.0 | LSb | | | 3.0V (Note 7) |
| | | -0.375 | ± 0.25 | +0.375 | LSb | | 7-bit | 5.5V, $I_W = 450\ \mu\text{A}$ |
| | | -0.75 | +0.5 | +0.75 | LSb | | | 3.0V (Note 7) |
| | | -0.5 | ± 0.25 | +0.5 | LSb | 50 k Ω | 8-bit | 5.5V, $I_W = 90\ \mu\text{A}$ |
| | | -0.5 | ± 0.25 | +0.5 | LSb | | | 3.0V (Note 7) |
| | | -0.375 | ± 0.25 | +0.375 | LSb | | 7-bit | 5.5V, $I_W = 90\ \mu\text{A}$ |
| | | -0.375 | ± 0.25 | +0.375 | LSb | | | 3.0V (Note 7) |
| | | -0.5 | ± 0.25 | +0.5 | LSb | 100 k Ω | 8-bit | 5.5V, $I_W = 45\ \mu\text{A}$ |
| | | -0.5 | ± 0.25 | +0.5 | LSb | | | 3.0V (Note 7) |
| | | -0.375 | ± 0.25 | +0.375 | LSb | | 7-bit | 5.5V, $I_W = 45\ \mu\text{A}$ |
| | | -0.375 | ± 0.25 | +0.375 | LSb | | | 3.0V (Note 7) |
| Capacitance (P_A) | C_{AW} | — | 75 | — | pF | f = 1 MHz, Code = Full-Scale | | |
| Capacitance (P_W) | C_W | — | 120 | — | pF | f = 1 MHz, Code = Full-Scale | | |
| Capacitance (P_B) | C_{BW} | — | 75 | — | pF | f = 1 MHz, Code = Full-Scale | | |

- Note 1:** Resistance is defined as the resistance between terminal A to terminal B.
- 2:** INL and DNL are measured at V_W with $V_A = V_{DD}$ and $V_B = V_{SS}$.
- 3:** **MCP4XX1** only.
- 4:** **MCP4XX2** only, includes V_{WZSE} and V_{WFSE} .
- 5:** Resistor terminals A, W and B's polarity with respect to each other is not restricted.
- 6:** This specification by design.
- 7:** Non-linearity is affected by wiper resistance (R_W), which changes significantly over voltage and temperature.
- 8:** The **MCP4XX1** is externally connected to match the configurations of the **MCP41X2** and **MCP42X2**, and then tested.
- 9:** POR/BOR is not rate dependent.
- 10:** Supply current is independent of current through the resistor network

MCP414X/416X/424X/426X

AC/DC CHARACTERISTICS (CONTINUED)

| DC Characteristics | | Standard Operating Conditions (unless otherwise specified) | | | | |
|---|----------------------|---|-------------|------------------------------|------------------|---|
| | | Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ (extended) | | | | |
| | | All parameters apply across the specified operating ranges unless noted. | | | | |
| | | $V_{DD} = +2.7\text{V}$ to 5.5V , $5\text{ k}\Omega$, $10\text{ k}\Omega$, $50\text{ k}\Omega$, $100\text{ k}\Omega$ devices. | | | | |
| | | Typical specifications represent values for $V_{DD} = 5.5\text{V}$, $T_A = +25^{\circ}\text{C}$. | | | | |
| Parameters | Sym | Min | Typ | Max | Units | Conditions |
| Digital Inputs/Outputs (CS, SDI, SDO, SCK, WP, SHDN) | | | | | | |
| Schmitt Trigger High Input Threshold | V_{IH} | $0.45 V_{DD}$ | — | — | V | $2.7\text{V} \leq V_{DD} \leq 5.5\text{V}$ (Allows 2.7V Digital V_{DD} with 5V Analog V_{DD}) |
| | | $0.5 V_{DD}$ | — | — | V | $1.8\text{V} \leq V_{DD} \leq 2.7\text{V}$ |
| Schmitt Trigger Low Input Threshold | V_{IL} | — | — | $0.2V_{DD}$ | V | |
| Hysteresis of Schmitt Trigger Inputs | V_{HYS} | — | $0.1V_{DD}$ | — | V | |
| High Voltage Input Entry Voltage | V_{IHH} | 8.5 | — | $12.5^{(6)}$ | V | Threshold for WiperLock™ Technology |
| High Voltage Input Exit Voltage | V_{IHH} | — | — | $V_{DD} + 0.8\text{V}^{(6)}$ | V | |
| High Voltage Limit | V_{MAX} | — | — | $12.5^{(6)}$ | V | Pin can tolerate V_{MAX} or less. |
| Output Low Voltage (SDO) | V_{OL} | V_{SS} | — | $0.3V_{DD}$ | V | $I_{OL} = 5\text{ mA}$, $V_{DD} = 5.5\text{V}$ |
| | | V_{SS} | — | $0.3V_{DD}$ | V | $I_{OL} = 1\text{ mA}$, $V_{DD} = 1.8\text{V}$ |
| Output High Voltage (SDO) | V_{OH} | $0.7V_{DD}$ | — | V_{DD} | V | $I_{OH} = -2.5\text{ mA}$, $V_{DD} = 5.5\text{V}$ |
| | | $0.7V_{DD}$ | — | V_{DD} | V | $I_{OL} = -1\text{ mA}$, $V_{DD} = 1.8\text{V}$ |
| Weak Pull-up / Pull-down Current | I_{PU} | — | — | 1.75 | mA | Internal V_{DD} pull-up, V_{IHH} pull-down, $V_{DD} = 5.5\text{V}$, $V_{CS} = 12.5\text{V}$ |
| | | — | 170 | — | μA | $\overline{\text{CS}}$ pin, $V_{DD} = 5.5\text{V}$, $V_{CS} = 3\text{V}$ |
| $\overline{\text{CS}}$ Pull-up / Pull-down Resistance | R_{CS} | — | 16 | — | $\text{k}\Omega$ | $V_{DD} = 5.5\text{V}$, $V_{CS} = 3\text{V}$ |
| Input Leakage Current | I_{IL} | -1 | — | 1 | μA | $V_{IN} = V_{DD}$ and $V_{IN} = V_{SS}$ |
| Pin Capacitance | C_{IN} , C_{OUT} | — | 10 | — | pF | $f_C = 20\text{ MHz}$ |

- Note 1:** Resistance is defined as the resistance between terminal A to terminal B.
- 2:** INL and DNL are measured at V_W with $V_A = V_{DD}$ and $V_B = V_{SS}$.
- 3:** **MCP4XX1** only.
- 4:** **MCP4XX2** only, includes V_{WZSE} and V_{WFSE} .
- 5:** Resistor terminals A, W and B's polarity with respect to each other is not restricted.
- 6:** This specification by design.
- 7:** Non-linearity is affected by wiper resistance (R_W), which changes significantly over voltage and temperature.
- 8:** The **MCP4XX1** is externally connected to match the configurations of the **MCP41X2** and **MCP42X2**, and then tested.
- 9:** POR/BOR is not rate dependent.
- 10:** Supply current is independent of current through the resistor network

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AC/DC CHARACTERISTICS (CONTINUED)

| DC Characteristics | | Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ (extended) All parameters apply across the specified operating ranges unless noted. $V_{DD} = +2.7\text{V}$ to 5.5V , $5\text{ k}\Omega$, $10\text{ k}\Omega$, $50\text{ k}\Omega$, $100\text{ k}\Omega$ devices. Typical specifications represent values for $V_{DD} = 5.5\text{V}$, $T_A = +25^{\circ}\text{C}$. | | | | | |
|---|------------------------|--|--------|--------|--------|--------------|---|
| Parameters | Sym | Min | Typ | Max | Units | Conditions | |
| RAM (Wiper) Value | | | | | | | |
| Value Range | N | 0h | — | 1FFh | hex | 8-bit device | |
| | | 0h | — | 1FFh | hex | 7-bit device | |
| EEPROM | | | | | | | |
| Endurance | $E_{\text{endurance}}$ | — | 1M | — | Cycles | | |
| EEPROM Range | N | 0h | — | 1FFh | hex | | |
| Initial Factory Setting | N | 80h | | | hex | 8-bit | WiperLock Technology = Off |
| | | 40h | | | hex | 7-bit | WiperLock Technology = Off |
| EEPROM Programming Write Cycle Time | t_{WC} | — | 5 | 10 | ms | | |
| Power Requirements | | | | | | | |
| Power Supply Sensitivity (MCP41X2 and MCP42X2 only) | PSS | — | 0.0015 | 0.0035 | %/% | 8-bit | $V_{DD} = 2.7\text{V}$ to 5.5V , $V_A = 2.7\text{V}$, Code = 80h |
| | | — | 0.0015 | 0.0035 | %/% | 7-bit | $V_{DD} = 2.7\text{V}$ to 5.5V , $V_A = 2.7\text{V}$, Code = 40h |

- Note 1:** Resistance is defined as the resistance between terminal A to terminal B.
- 2:** INL and DNL are measured at V_W with $V_A = V_{DD}$ and $V_B = V_{SS}$.
- 3:** MCP4XX1 only.
- 4:** MCP4XX2 only, includes V_{WZSE} and V_{WFSE} .
- 5:** Resistor terminals A, W and B's polarity with respect to each other is not restricted.
- 6:** This specification by design.
- 7:** Non-linearity is affected by wiper resistance (R_W), which changes significantly over voltage and temperature.
- 8:** The MCP4XX1 is externally connected to match the configurations of the MCP41X2 and MCP42X2, and then tested.
- 9:** POR/BOR is not rate dependent.
- 10:** Supply current is independent of current through the resistor network

1.1 SPI Mode Timing Waveforms and Requirements

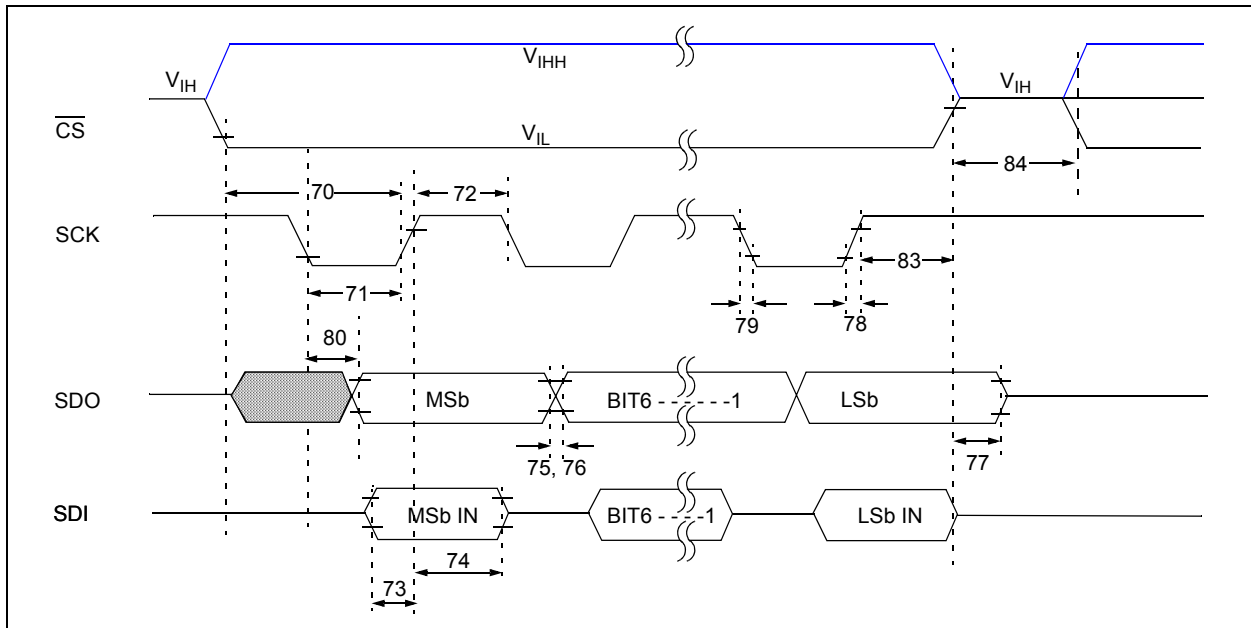


FIGURE 1-1: SPI Timing Waveform (Mode = 11).

TABLE 1-1: SPI REQUIREMENTS (MODE = 11)

| # | Characteristic | Symbol | Min | Max | Units | Conditions |
|----|--|---------------|-----|-----|-------|---------------------------|
| | SCK Input Frequency | F_{SCK} | — | 10 | MHz | $V_{DD} = 2.7V$ to $5.5V$ |
| | | | — | 1 | MHz | $V_{DD} = 1.8V$ to $2.7V$ |
| 70 | \overline{CS} Active (V_{IL} or V_{IHH}) to $SCK\uparrow$ input | $T_{csA2scH}$ | 60 | — | ns | |
| 71 | SCK input high time | T_{scH} | 45 | — | ns | $V_{DD} = 2.7V$ to $5.5V$ |
| | | | 500 | — | ns | $V_{DD} = 1.8V$ to $2.7V$ |
| 72 | SCK input low time | T_{scL} | 45 | — | ns | $V_{DD} = 2.7V$ to $5.5V$ |
| | | | 500 | — | ns | $V_{DD} = 1.8V$ to $2.7V$ |
| 73 | Setup time of SDI input to $SCK\uparrow$ edge | $T_{DlV2scH}$ | 10 | — | ns | |
| 74 | Hold time of SDI input from $SCK\uparrow$ edge | $T_{scH2dIL}$ | 20 | — | ns | |
| 77 | \overline{CS} Inactive (V_{IH}) to SDO output hi-impedance | $T_{csH2doZ}$ | — | 50 | ns | Note 1 |
| 80 | SDO data output valid after $SCK\downarrow$ edge | $T_{scL2doV}$ | — | 70 | ns | $V_{DD} = 2.7V$ to $5.5V$ |
| | | | — | 170 | ns | $V_{DD} = 1.8V$ to $2.7V$ |
| 83 | \overline{CS} Inactive (V_{IH}) after $SCK\uparrow$ edge | $T_{scH2csl}$ | 100 | — | ns | $V_{DD} = 2.7V$ to $5.5V$ |
| | | | 1 | — | ms | $V_{DD} = 1.8V$ to $2.7V$ |
| 84 | Hold time of \overline{CS} Inactive (V_{IH}) to \overline{CS} Active (V_{IL} or V_{IHH}) | $T_{csA2csl}$ | 50 | — | ns | |

Note 1: This specification by design.

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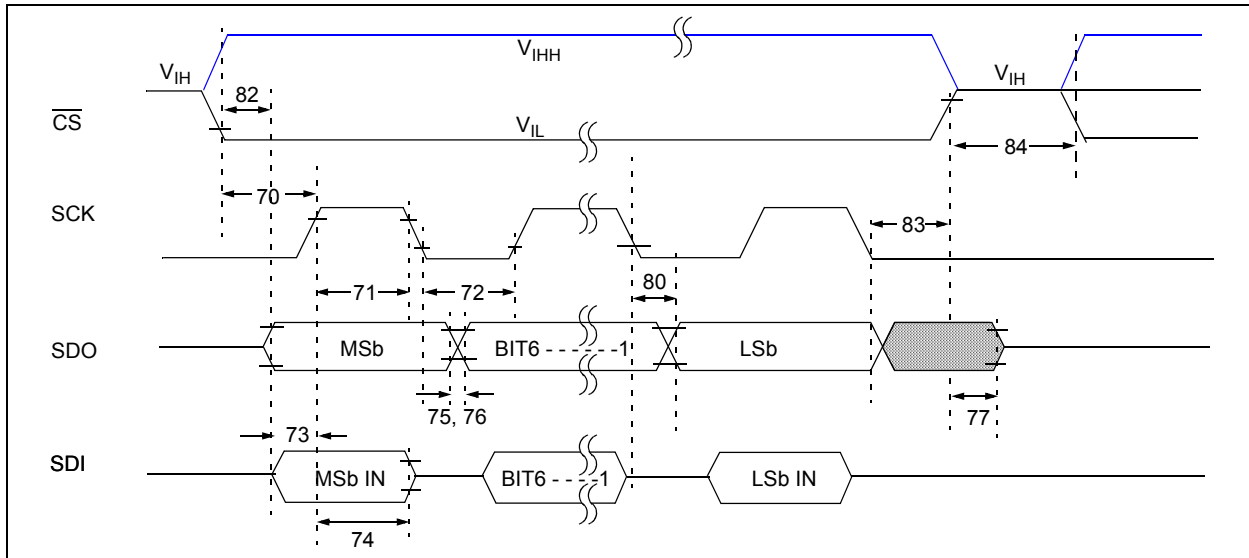


FIGURE 1-2: SPI Timing Waveform (Mode = 00).

TABLE 1-2: SPI REQUIREMENTS (MODE = 00)

| # | Characteristic | Symbol | Min | Max | Units | Conditions |
|----|--|---------------|-----|-----|-------|-------------------------|
| | SCK Input Frequency | F_{SCK} | — | 10 | MHz | $V_{DD} = 2.7V$ to 5.5V |
| | | | — | 1 | MHz | $V_{DD} = 1.8V$ to 2.7V |
| 70 | \overline{CS} Active (V_{IL} or V_{IHH}) to SCK \uparrow input | $T_{csA2sch}$ | 60 | — | ns | |
| 71 | SCK input high time | T_{sch} | 45 | — | ns | $V_{DD} = 2.7V$ to 5.5V |
| | | | 500 | — | ns | $V_{DD} = 1.8V$ to 2.7V |
| 72 | SCK input low time | T_{scl} | 45 | — | ns | $V_{DD} = 2.7V$ to 5.5V |
| | | | 500 | — | ns | $V_{DD} = 1.8V$ to 2.7V |
| 73 | Setup time of SDI input to SCK \uparrow edge | $T_{diV2sch}$ | 10 | — | ns | |
| 74 | Hold time of SDI input from SCK \uparrow edge | $T_{sch2diL}$ | 20 | — | ns | |
| 77 | \overline{CS} Inactive (V_{IH}) to SDO output hi-impedance | $T_{csH2doZ}$ | — | 50 | ns | Note 1 |
| 80 | SDO data output valid after SCK \downarrow edge | $T_{scl2doV}$ | — | 70 | ns | $V_{DD} = 2.7V$ to 5.5V |
| | | | — | 170 | ns | $V_{DD} = 1.8V$ to 2.7V |
| 82 | SDO data output valid after \overline{CS} Active (V_{IL} or V_{IHH}) | $T_{ssL2doV}$ | — | 70 | ns | |
| 83 | \overline{CS} Inactive (V_{IH}) after SCK \downarrow edge | $T_{sch2csl}$ | 100 | — | ns | $V_{DD} = 2.7V$ to 5.5V |
| | | | 1 | — | ms | $V_{DD} = 1.8V$ to 2.7V |
| 84 | Hold time of \overline{CS} Inactive (V_{IH}) to \overline{CS} Active (V_{IL} or V_{IHH}) | $T_{csA2csl}$ | 50 | — | ns | |

Note 1: This specification by design.

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TABLE 1-3: SPI REQUIREMENTS FOR SDI/SDO MULTIPLEXED (READ OPERATION ONLY)⁽²⁾

| Characteristic | Symbol | Min | Max | Units | Conditions |
|---|---------------|-----|-----|-------|---------------------------|
| SCK Input Frequency | F_{SCK} | — | 250 | kHz | $V_{DD} = 2.7V$ to $5.5V$ |
| \overline{CS} Active (V_{IL} or V_{IHH}) to SCK \uparrow input | $T_{csA2sch}$ | 60 | — | ns | |
| SCK input high time | T_{sch} | 1.8 | — | us | |
| SCK input low time | T_{scl} | 1.8 | — | ns | |
| Setup time of SDI input to SCK \uparrow edge | $T_{diV2sch}$ | 40 | — | ns | |
| Hold time of SDI input from SCK \uparrow edge | $T_{sch2diL}$ | 40 | — | ns | |
| \overline{CS} Inactive (V_{IH}) to SDO output hi-impedance | $T_{csH2doZ}$ | — | 50 | ns | Note 1 |
| SDO data output valid after SCK \downarrow edge | $T_{scl2doV}$ | — | 1.6 | us | |
| SDO data output valid after \overline{CS} Active (V_{IL} or V_{IHH}) | $T_{ssl2doV}$ | — | 50 | ns | |
| \overline{CS} Inactive (V_{IH}) after SCK \downarrow edge | $T_{sch2csl}$ | 100 | — | ns | |
| Hold time of \overline{CS} Inactive (V_{IH}) to \overline{CS} Active (V_{IL} or V_{IHH}) | $T_{csA2csl}$ | 50 | — | ns | |

Note 1: This specification by design

- 2:** This table is for the devices where the SPI's SDI and SDO pins are multiplexed (SDI/SDO) and a Read command is issued. This is NOT required for SDI/SDO operation with the Increment, Decrement, or Write commands. This data rate can be increased by having external pull-up resistors to increase the rising edges of each bit.

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TEMPERATURE CHARACTERISTICS

| Electrical Specifications: Unless otherwise indicated, $V_{DD} = +2.7V$ to $+5.5V$, $V_{SS} = GND$. | | | | | | |
|---|---------------|-----|-------|------|-------|------------|
| Parameters | Sym | Min | Typ | Max | Units | Conditions |
| Temperature Ranges | | | | | | |
| Specified Temperature Range | T_A | -40 | — | +125 | °C | |
| Operating Temperature Range | T_A | -40 | — | +125 | °C | |
| Storage Temperature Range | T_A | -65 | — | +150 | °C | |
| Thermal Package Resistances | | | | | | |
| Thermal Resistance, 8L-MSOP | θ_{JA} | — | 211 | — | °C/W | |
| Thermal Resistance, 8L-PDIP | θ_{JA} | — | 89.3 | — | °C/W | |
| Thermal Resistance, 8L-SOIC | θ_{JA} | — | 149.5 | — | °C/W | |
| Thermal Resistance, 8L-DFN (3x3) | θ_{JA} | — | 60 | — | °C/W | |
| Thermal Resistance, 10L-DFN (3x3) | θ_{JA} | — | 57 | — | °C/W | |
| Thermal Resistance, 10L-MSOP | θ_{JA} | — | 202 | — | °C/W | |
| Thermal Resistance, 14L-PDIP | θ_{JA} | — | 70 | — | °C/W | |
| Thermal Resistance, 14L-SOIC | θ_{JA} | — | 95.3 | — | °C/W | |
| Thermal Resistance, 14L-TSSOP | θ_{JA} | — | 100 | — | °C/W | |
| Thermal Resistance, 16L-QFN | θ_{JA} | — | 43 | — | °C/W | |

2.0 TYPICAL PERFORMANCE CURVES

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

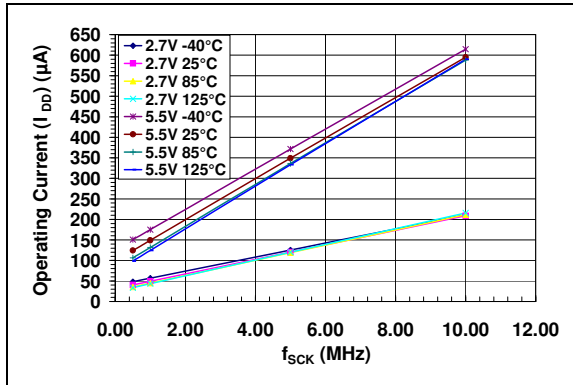


FIGURE 2-1: Device Current (I_{DD}) vs. SPI Frequency (f_{SCK}) and Ambient Temperature ($V_{DD} = 2.7\text{V}$ and 5.5V).

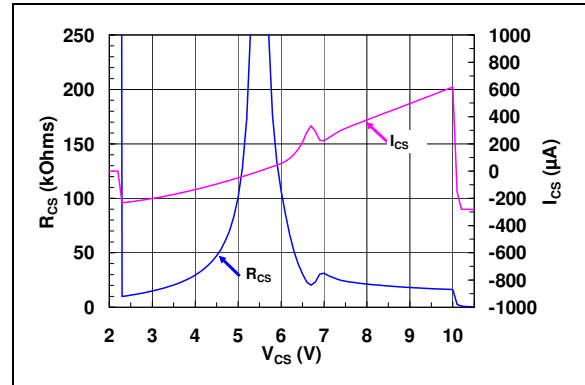


FIGURE 2-4: \overline{CS} Pull-up/Pull-down Resistance ($R_{\overline{CS}}$) and Current ($I_{\overline{CS}}$) vs. \overline{CS} Input Voltage ($V_{\overline{CS}}$) ($V_{DD} = 5.5\text{V}$).

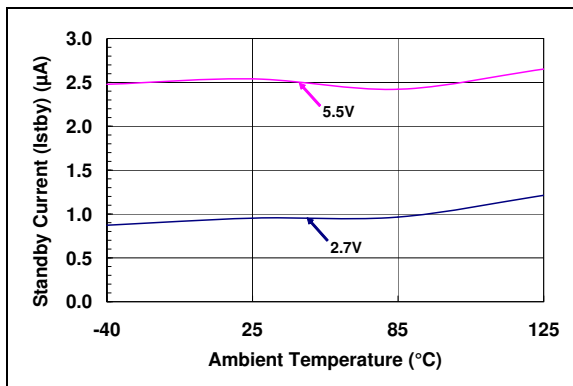


FIGURE 2-2: Device Current (I_{SHDN}) and V_{DD} . ($\overline{CS} = V_{DD}$) vs. Ambient Temperature.

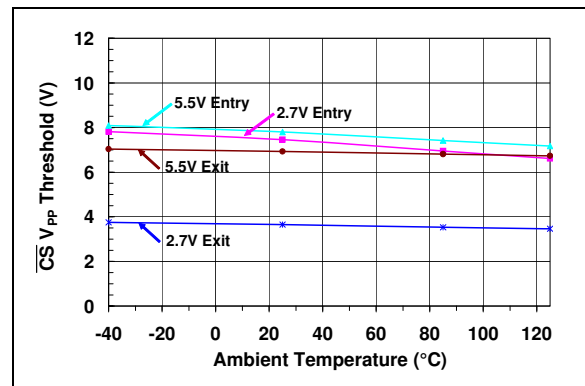


FIGURE 2-5: \overline{CS} High Input Entry/Exit Threshold vs. Ambient Temperature and V_{DD} .

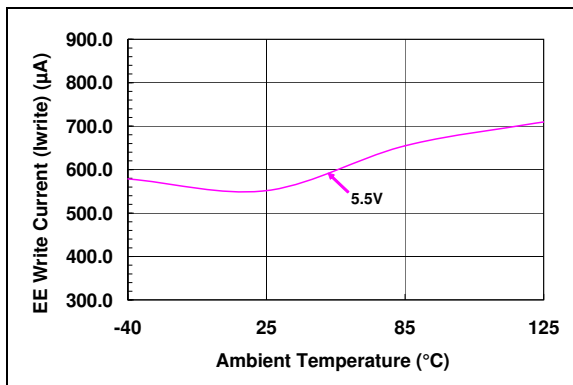


FIGURE 2-3: Write Current (I_{WRITE}) vs. Ambient Temperature and V_{DD} .

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Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

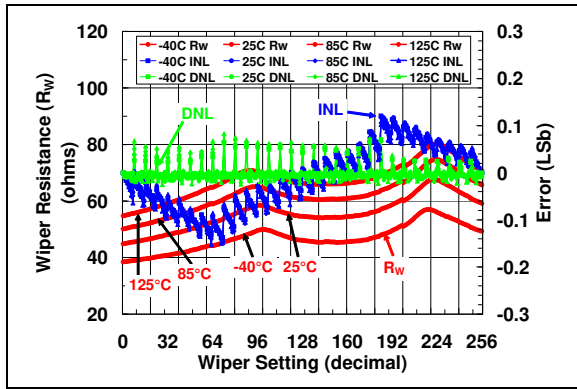


FIGURE 2-6: 5 kΩ Pot Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 5.5\text{V}$).

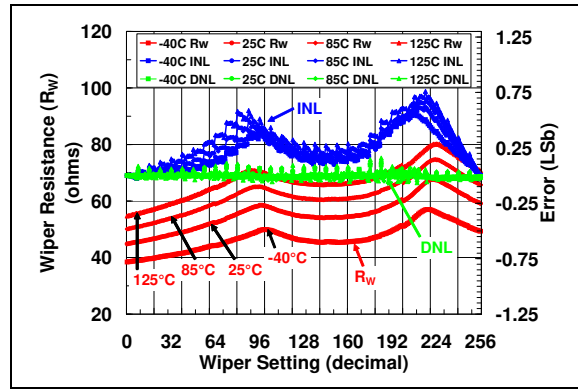


FIGURE 2-9: 5 kΩ Rheo Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 5.5\text{V}$).

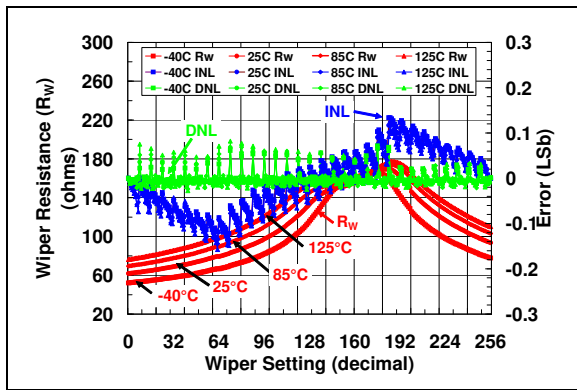


FIGURE 2-7: 5 kΩ Pot Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 3.0\text{V}$).

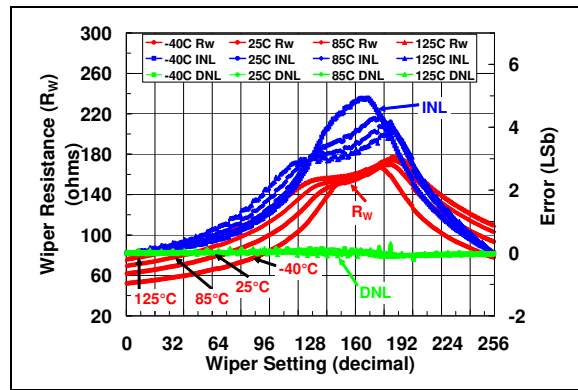


FIGURE 2-10: 5 kΩ Rheo Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 3.0\text{V}$).

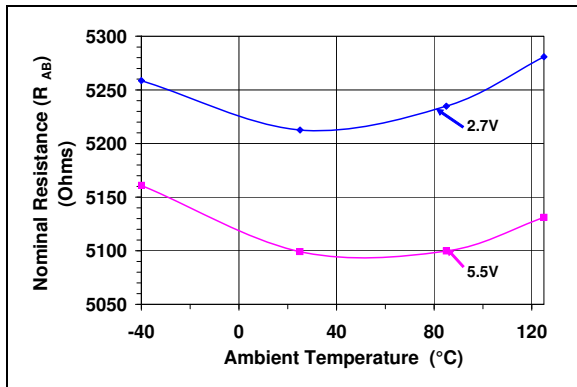


FIGURE 2-8: 5 kΩ – Nominal Resistance (Ω) vs. Ambient Temperature and V_{DD} .

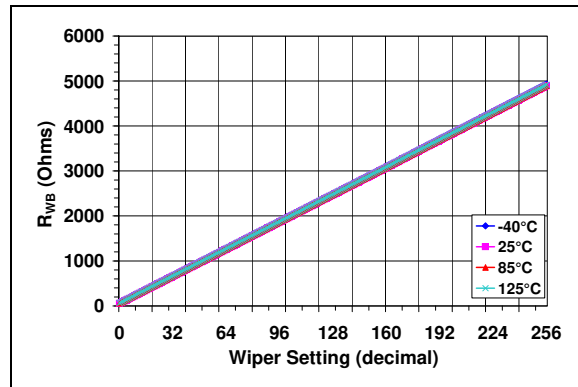


FIGURE 2-11: 5 kΩ – R_{WB} (Ω) vs. Wiper Setting and Ambient Temperature.

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Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

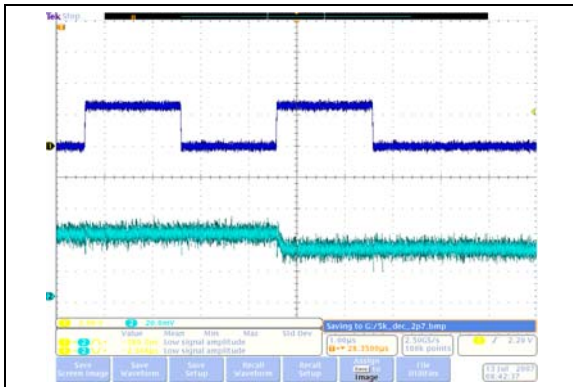


FIGURE 2-12: 5 k Ω – Low-Voltage Decrement Wiper Settling Time ($V_{DD} = 2.7\text{V}$) (1 $\mu\text{s}/\text{Div}$).

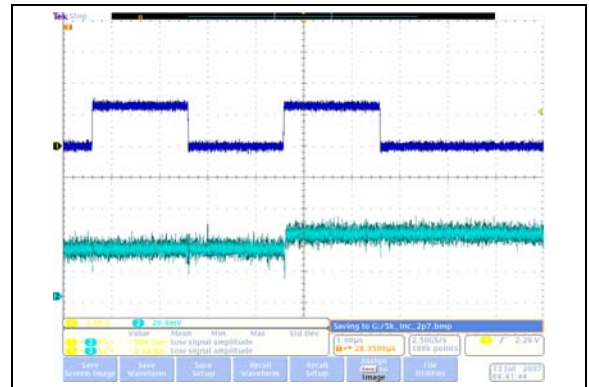


FIGURE 2-15: 5 k Ω – Low-Voltage Increment Wiper Settling Time ($V_{DD} = 2.7\text{V}$) (1 $\mu\text{s}/\text{Div}$).

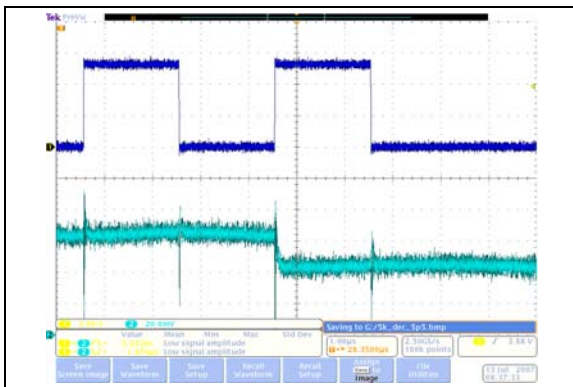


FIGURE 2-13: 5 k Ω – Low-Voltage Decrement Wiper Settling Time ($V_{DD} = 5.5\text{V}$) (1 $\mu\text{s}/\text{Div}$).

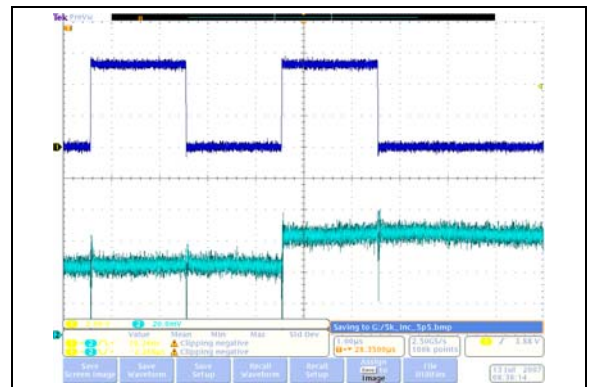


FIGURE 2-16: 5 k Ω – Low-Voltage Increment Wiper Settling Time ($V_{DD} = 5.5\text{V}$) (1 $\mu\text{s}/\text{Div}$).

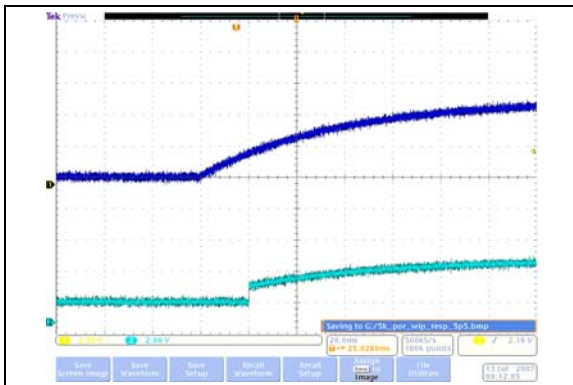


FIGURE 2-14: 5 k Ω – Power-Up Wiper Response Time (20 ms/Div).

MCP414X/416X/424X/426X

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

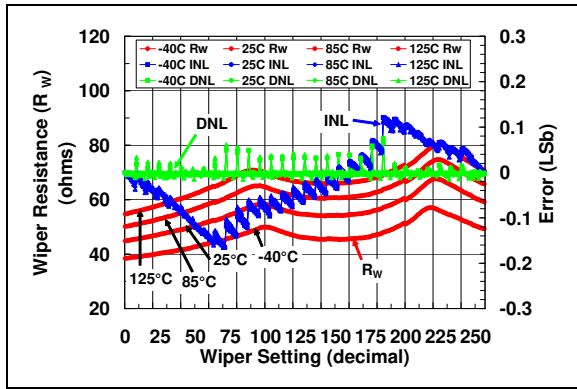


FIGURE 2-17: 10 kΩ Pot Mode – R_w (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 5.5\text{V}$).

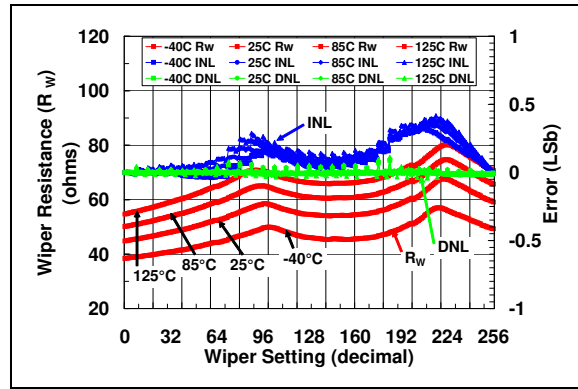


FIGURE 2-20: 10 kΩ Rheo Mode – R_w (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 5.5\text{V}$).

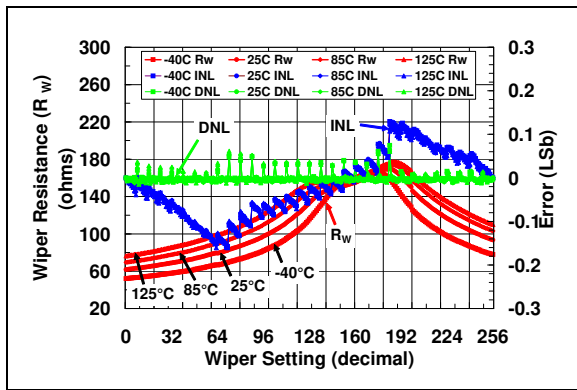


FIGURE 2-18: 10 kΩ Pot Mode – R_w (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 3.0\text{V}$).

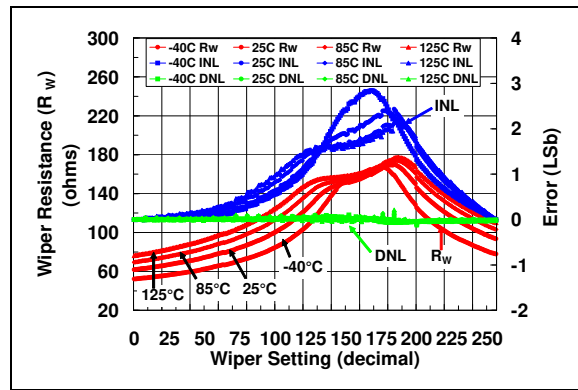


FIGURE 2-21: 10 kΩ Rheo Mode – R_w (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 3.0\text{V}$).

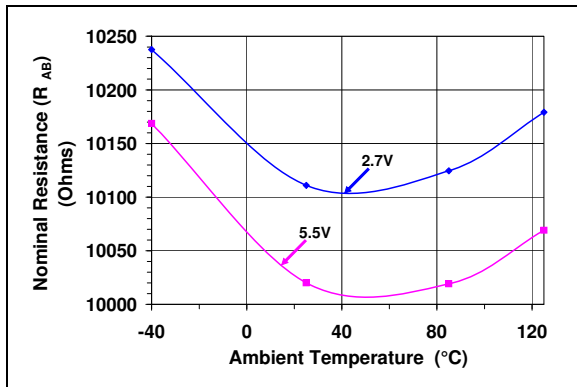


FIGURE 2-19: 10 kΩ – Nominal Resistance (Ω) vs. Ambient Temperature and V_{DD} .

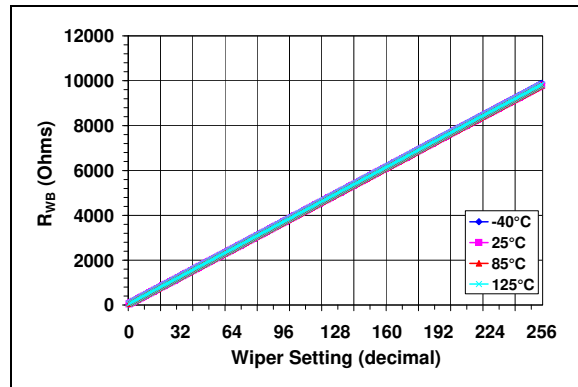


FIGURE 2-22: 10 kΩ – R_{WB} (Ω) vs. Wiper Setting and Ambient Temperature.

MCP414X/416X/424X/426X

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

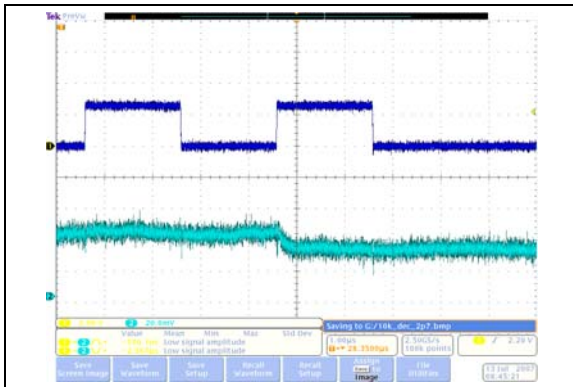


FIGURE 2-23: 10 k Ω – Low-Voltage
Decrement Wiper Settling Time ($V_{DD} = 2.7\text{V}$)
(1 $\mu\text{s}/\text{Div}$).

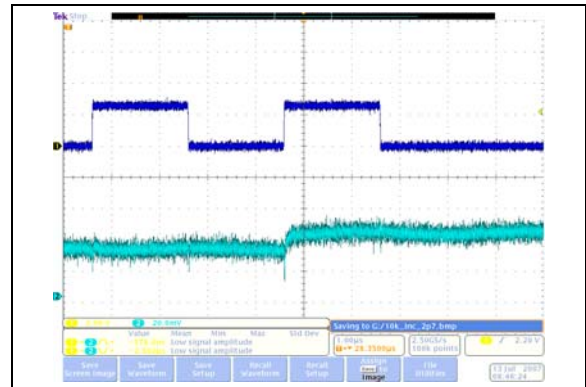


FIGURE 2-25: 10 k Ω – Low-Voltage
Increment Wiper Settling Time ($V_{DD} = 2.7\text{V}$)
(1 $\mu\text{s}/\text{Div}$).

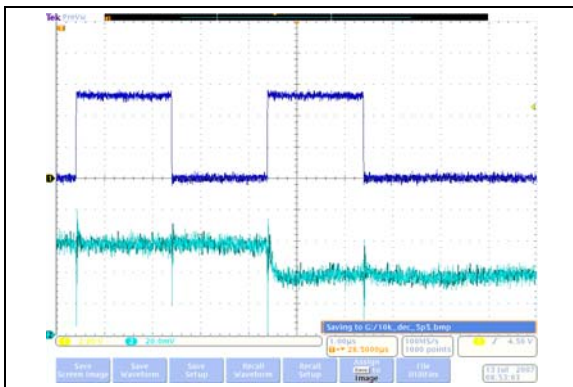


FIGURE 2-24: 10 k Ω – Low-Voltage
Decrement Wiper Settling Time ($V_{DD} = 5.5\text{V}$)
(1 $\mu\text{s}/\text{Div}$).

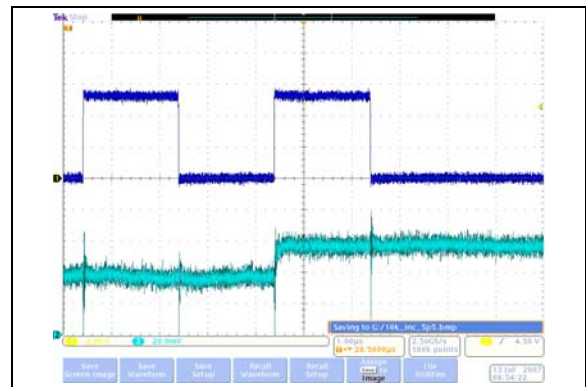


FIGURE 2-26: 10 k Ω – Low-Voltage
Increment Wiper Settling Time ($V_{DD} = 5.5\text{V}$)
(1 $\mu\text{s}/\text{Div}$).

MCP414X/416X/424X/426X

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

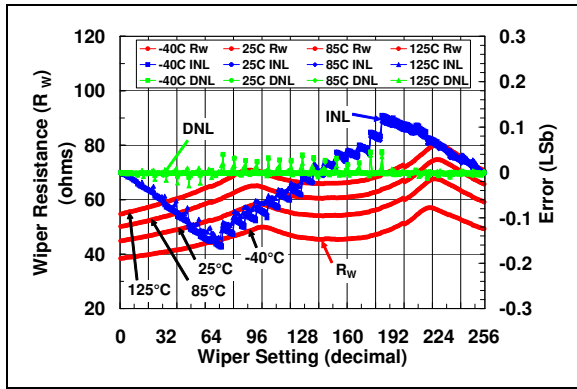


FIGURE 2-27: 50 kΩ Pot Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 5.5\text{V}$).

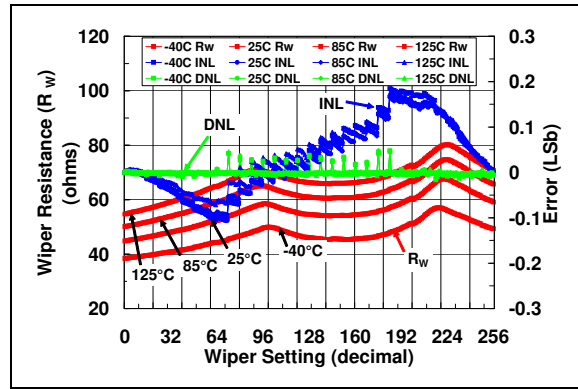


FIGURE 2-30: 50 kΩ Rheo Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 5.5\text{V}$).

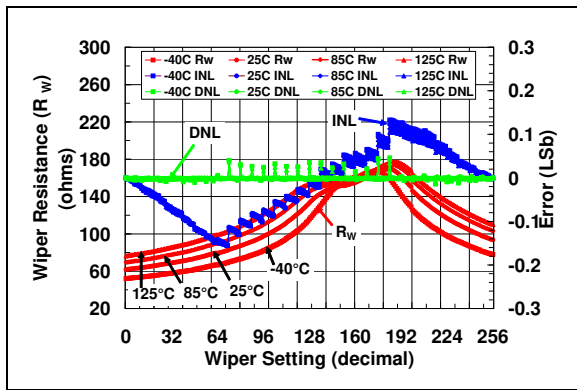


FIGURE 2-28: 50 kΩ Pot Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 3.0\text{V}$).

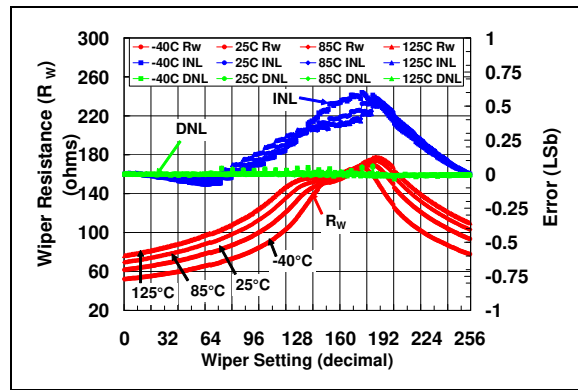


FIGURE 2-31: 50 kΩ Rheo Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 3.0\text{V}$).

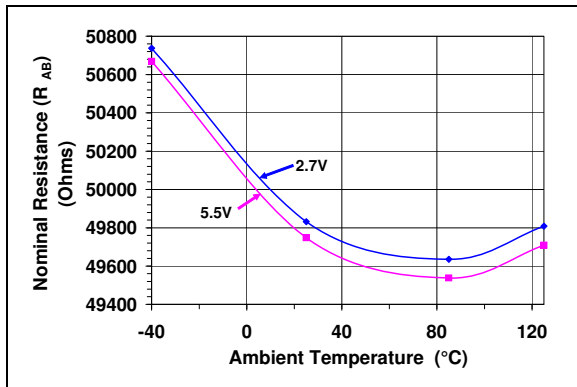


FIGURE 2-29: 50 kΩ – Nominal Resistance (Ω) vs. Ambient Temperature and V_{DD} .

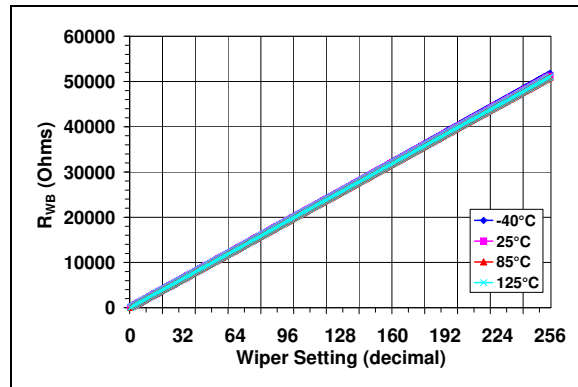


FIGURE 2-32: 50 kΩ – R_{WB} (Ω) vs. Wiper Setting and Ambient Temperature.

MCP414X/416X/424X/426X

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

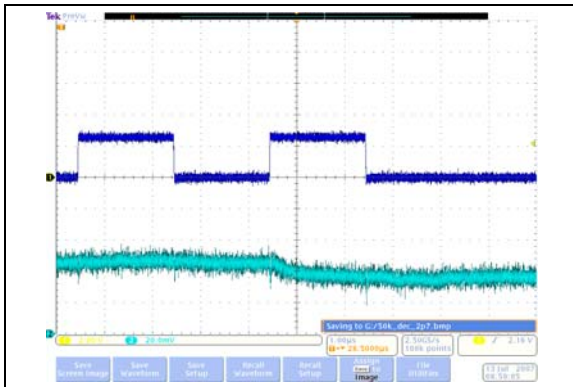


FIGURE 2-33: $50\text{ k}\Omega$ – Low-Voltage Decrement Wiper Settling Time ($V_{DD} = 2.7\text{V}$) ($1\ \mu\text{s}/\text{Div}$).

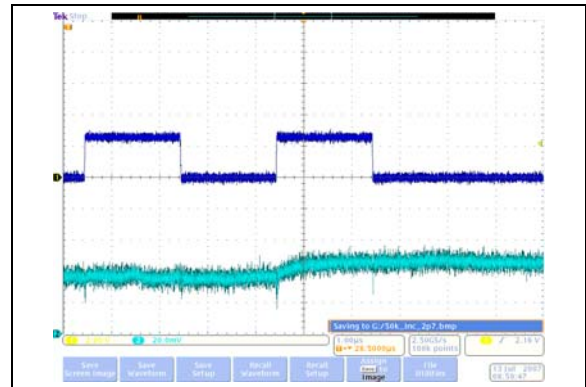


FIGURE 2-35: $50\text{ k}\Omega$ – Low-Voltage Increment Wiper Settling Time ($V_{DD} = 2.7\text{V}$) ($1\ \mu\text{s}/\text{Div}$).

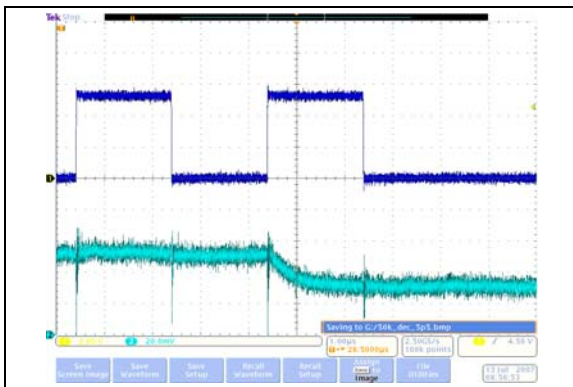


FIGURE 2-34: $50\text{ k}\Omega$ – Low-Voltage Decrement Wiper Settling Time ($V_{DD} = 5.5\text{V}$) ($1\ \mu\text{s}/\text{Div}$).

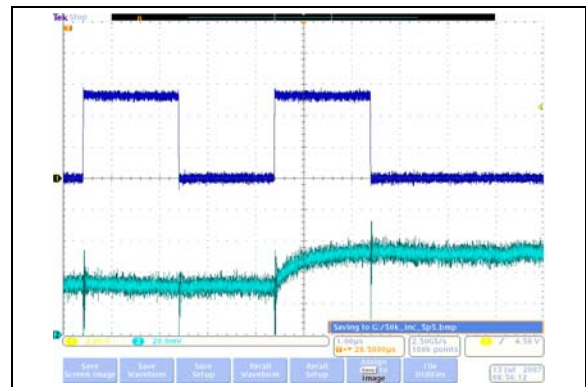


FIGURE 2-36: $50\text{ k}\Omega$ – Low-Voltage Increment Wiper Settling Time ($V_{DD} = 5.5\text{V}$) ($1\ \mu\text{s}/\text{Div}$).

MCP414X/416X/424X/426X

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

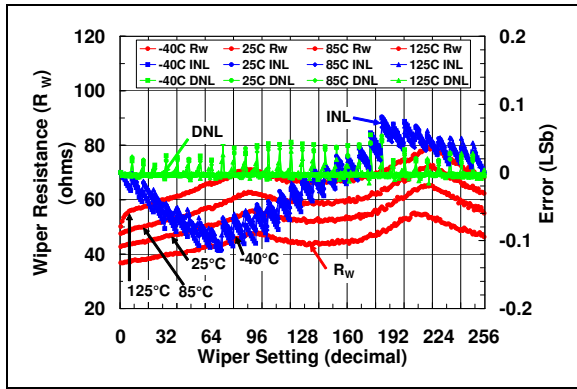


FIGURE 2-37: 100 k Ω Pot Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 5.5\text{V}$).

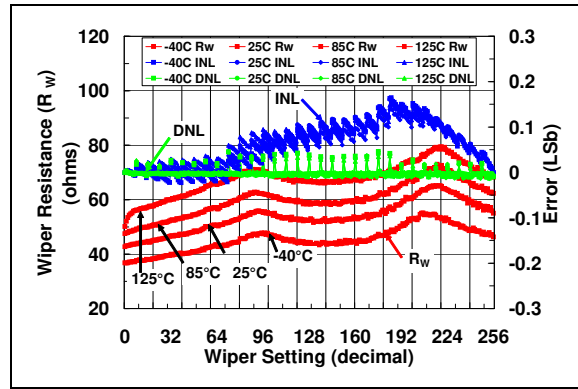


FIGURE 2-40: 100 k Ω Rheo Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 5.5\text{V}$).

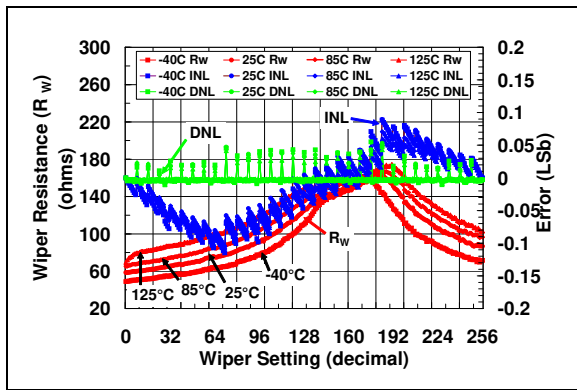


FIGURE 2-38: 100 k Ω Pot Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 3.0\text{V}$).

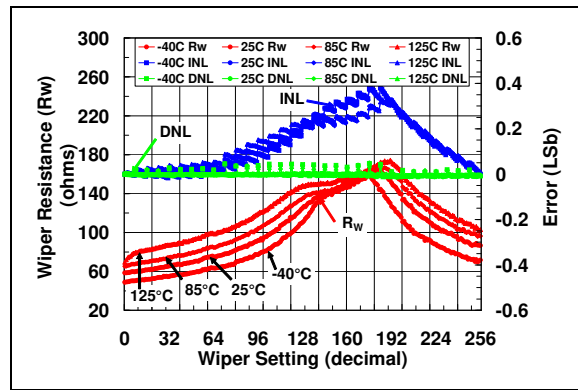


FIGURE 2-41: 100 k Ω Rheo Mode – R_W (Ω), INL (LSb), DNL (LSb) vs. Wiper Setting and Ambient Temperature ($V_{DD} = 3.0\text{V}$).

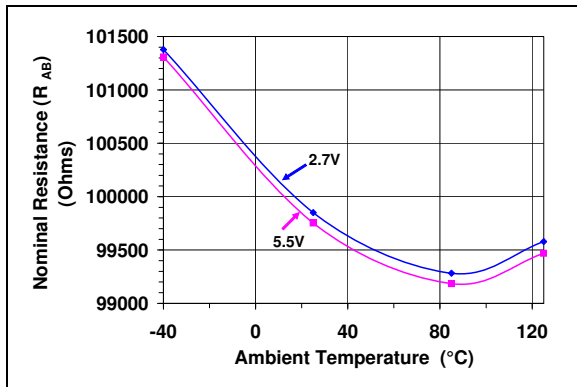


FIGURE 2-39: 100 k Ω – Nominal Resistance (Ω) vs. Ambient Temperature and V_{DD} .

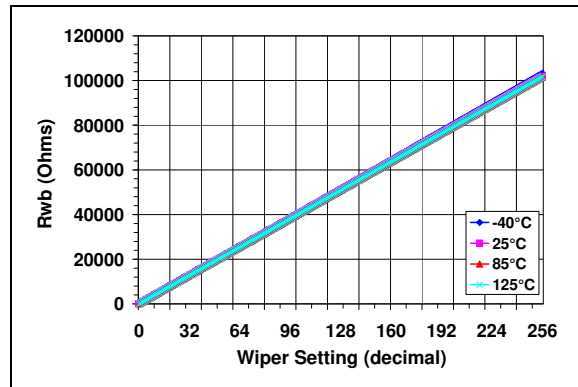


FIGURE 2-42: 100 k Ω – R_{WB} (Ω) vs. Wiper Setting and Ambient Temperature.

MCP414X/416X/424X/426X

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

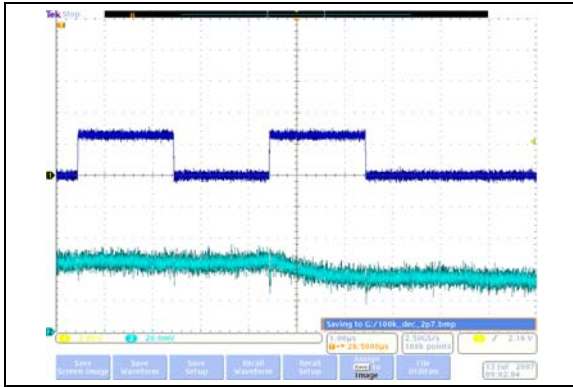


FIGURE 2-43: 100 k Ω – Low-Voltage Decrement Wiper Settling Time ($V_{DD} = 2.7\text{V}$) ($1\ \mu\text{s}/\text{Div}$).

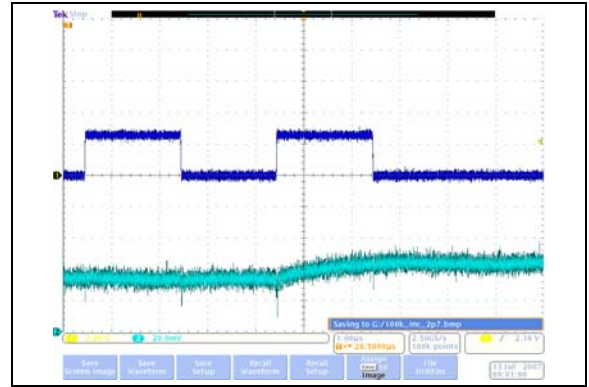


FIGURE 2-45: 100 k Ω – Power-Up Wiper Response Time ($1\ \mu\text{s}/\text{Div}$).

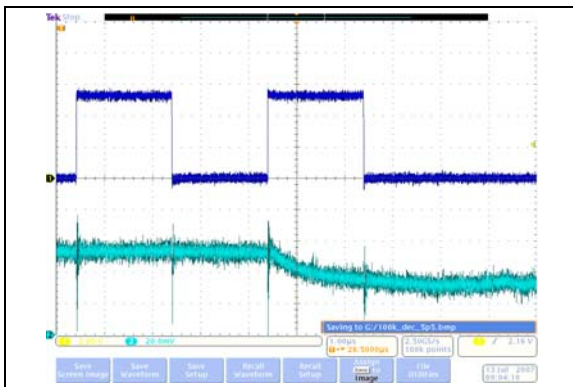


FIGURE 2-44: 100 k Ω – Low-Voltage Decrement Wiper Settling Time ($V_{DD} = 5.5\text{V}$) ($1\ \mu\text{s}/\text{Div}$).

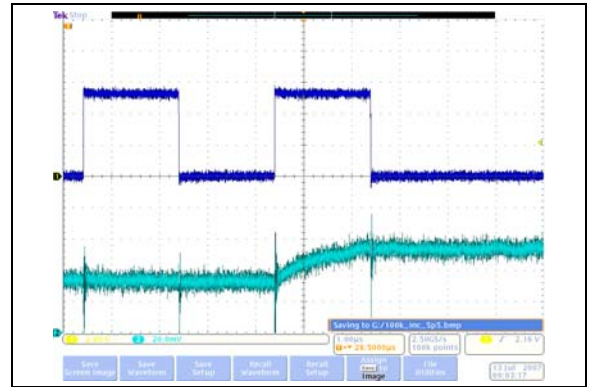


FIGURE 2-46: 100 k Ω – Low-Voltage Increment Wiper Settling Time ($V_{DD} = 2.7\text{V}$) ($1\ \mu\text{s}/\text{Div}$).

MCP414X/416X/424X/426X

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

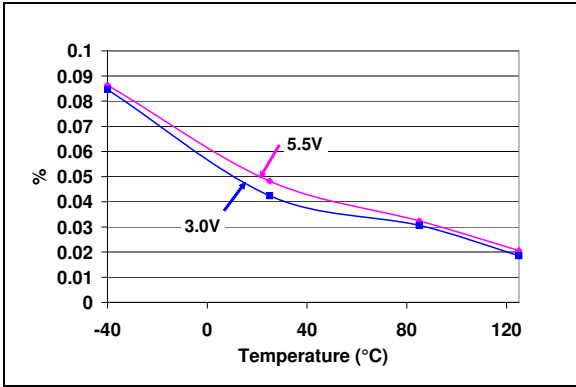


FIGURE 2-47: Resistor Network 0 to Resistor Network 1 R_{AB} ($5\text{ k}\Omega$) Mismatch vs. V_{DD} and Temperature.

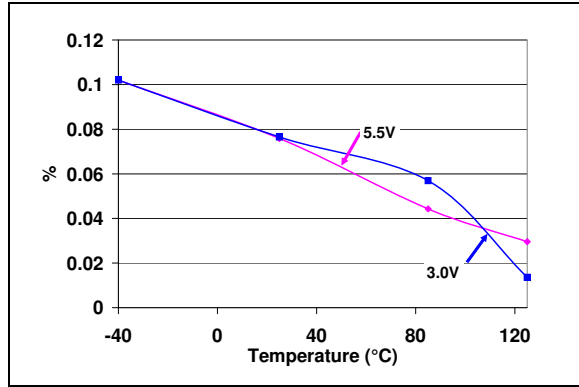


FIGURE 2-49: Resistor Network 0 to Resistor Network 1 R_{AB} ($50\text{ k}\Omega$) Mismatch vs. V_{DD} and Temperature.

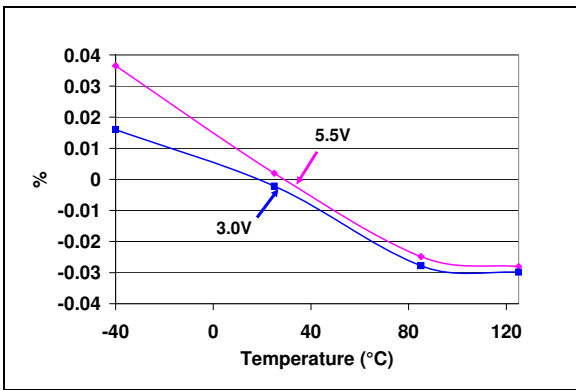


FIGURE 2-48: Resistor Network 0 to Resistor Network 1 R_{AB} ($10\text{ k}\Omega$) Mismatch vs. V_{DD} and Temperature.

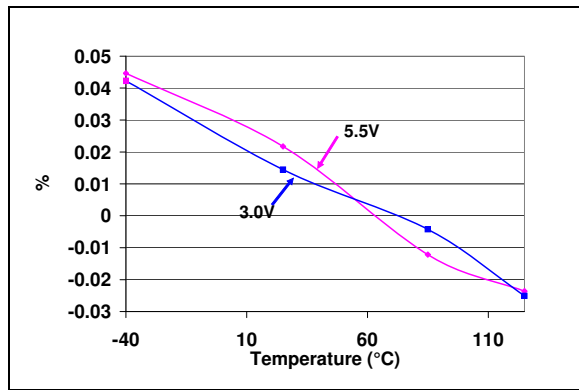


FIGURE 2-50: Resistor Network 0 to Resistor Network 1 R_{AB} ($100\text{ k}\Omega$) Mismatch vs. V_{DD} and Temperature.

MCP414X/416X/424X/426X

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$.

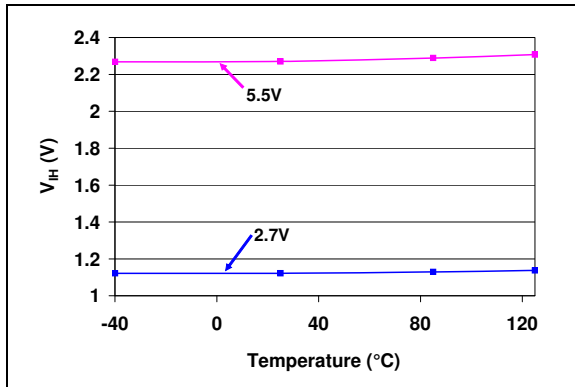


FIGURE 2-51: V_{IH} (SDI, SCK, $\overline{\text{CS}}$, $\overline{\text{WP}}$, and $\overline{\text{SHDN}}$) vs. V_{DD} and Temperature.

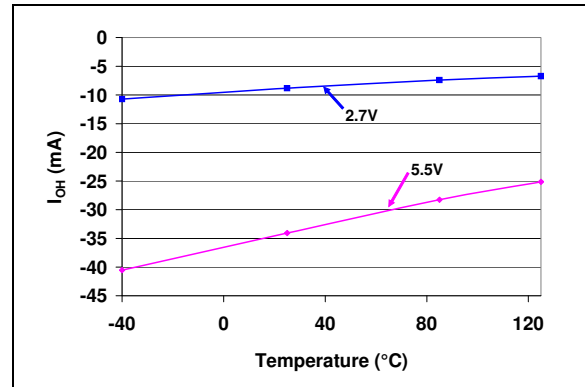


FIGURE 2-53: I_{OH} (SDO) vs. V_{DD} and Temperature.

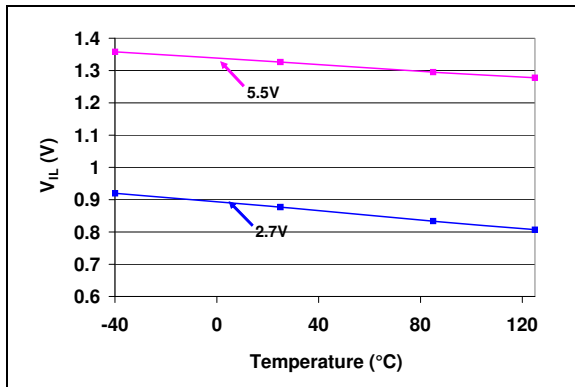


FIGURE 2-52: V_{IL} (SDI, SCK, $\overline{\text{CS}}$, $\overline{\text{WP}}$, and $\overline{\text{SHDN}}$) vs. V_{DD} and Temperature.

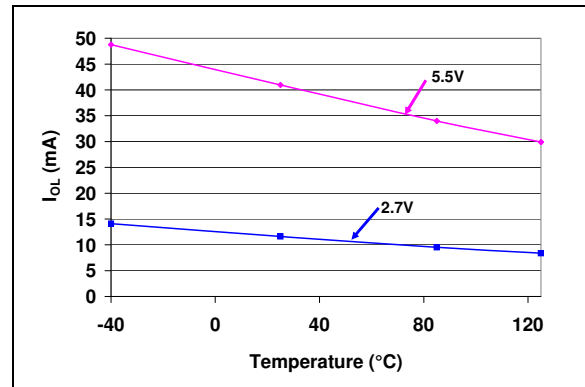


FIGURE 2-54: I_{OL} (SDO) vs. V_{DD} and Temperature.