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Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China





MCP4706/4716/4726

8-/10-/12-Bit Voltage Output Digital-to-Analog Converter with EEPROM and I²C™ Interface

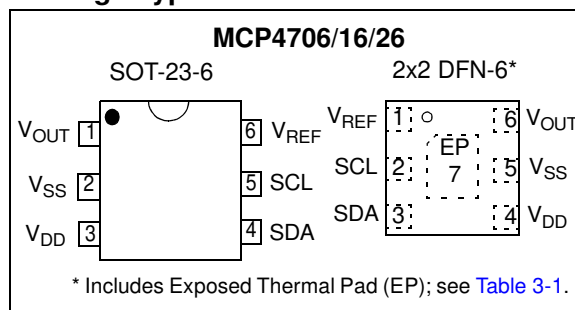
Features:

- Output Voltage Resolutions:
 - 12-bit: **MCP4726**
 - 10-bit: **MCP4716**
 - 8-bit: **MCP4706**
- Rail-to-Rail Output
- Fast Settling Time of 6 μ s (typical)
- DAC Voltage Reference Options:
 - V_{DD}
 - V_{REF} Pin
- Output Gain Options:
 - Unity (1x)
 - 2x, only when V_{REF} pin is used as voltage source
- Nonvolatile Memory (EEPROM):
 - Auto Recall of Saved DAC register setting
 - Auto Recall of Saved Device Configuration (Voltage Reference, Gain, Power-Down)
- Power-Down modes:
 - Disconnects output buffer
 - Selection of V_{OUT} pull-down resistors (640 k Ω , 125 k Ω , or 1 k Ω)
- Low-Power Consumption:
 - Normal Operation: 210 μ A typical
 - Power-Down Operation: 60 nA typical (PD1:PD0 = 11)
- Single-Supply Operation: 2.7V to 5.5V
- I²C™ Interface:
 - Eight Available Addresses
 - Standard (100 kbps), Fast (400 kbps), and High-Speed (3.4 Mbps) modes
- Small 6-lead SOT-23 and DFN (2x2) Packages
- Extended Temperature Range: -40°C to +125°C

Applications:

- Set Point or Offset Trimming
- Sensor Calibration
- Low-Power Portable Instrumentation
- PC Peripherals
- Data Acquisition Systems
- Motor Control

Package Types



Description:

The MCP4706/4716/4726 are single channel 8-bit, 10-bit, and 12-bit buffered voltage output Digital-to-Analog Converters (DAC) with nonvolatile memory and an I²C serial interface. This family will also be referred to as MCP47X6.

The V_{REF} pin or the device V_{DD} can be selected as the DAC's reference voltage. When V_{DD} is selected, V_{DD} is connected internally to the DAC reference circuit. When the V_{REF} pin is used, the user can select the output buffer's gain to 1 or 2. When the gain is 2, the V_{REF} pin voltage should be limited to a maximum of $V_{DD}/2$.

The DAC register value and Configuration bits can be programmed to nonvolatile memory (EEPROM). The nonvolatile memory holds the DAC register and Configuration bit values when the device is powered off. A device Reset (such as a Power-on Reset) latches these stored values into the volatile memory.

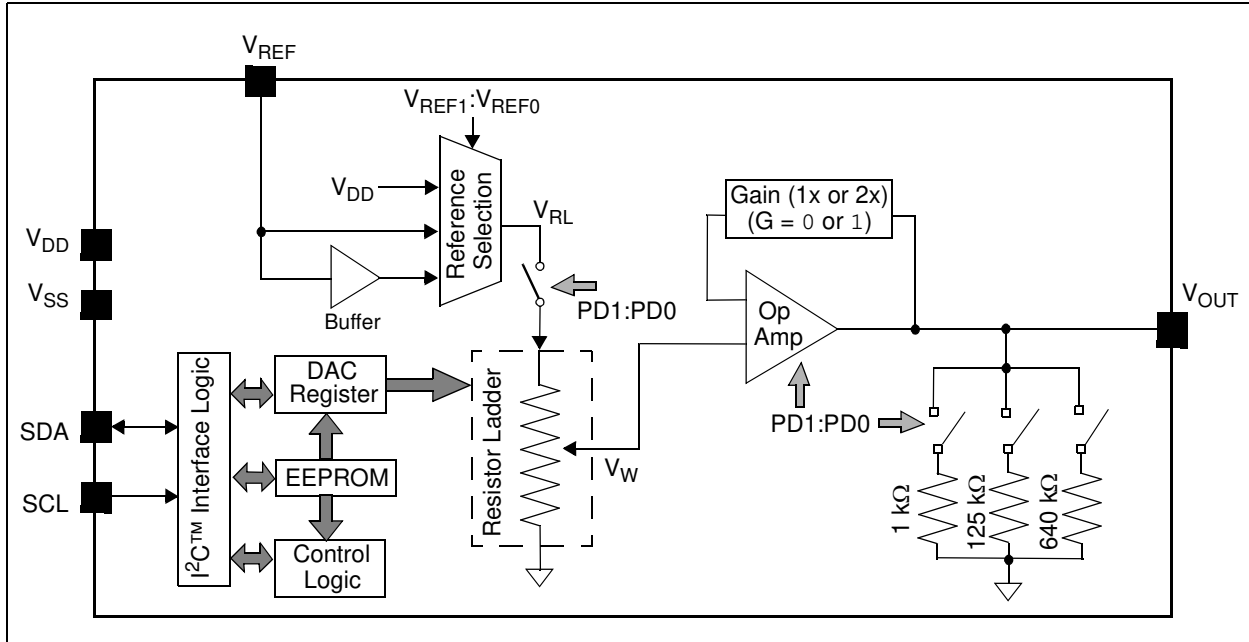
Power-Down modes enable system current reduction when the DAC output voltage is not required. The V_{OUT} pin can be configured to present a low, medium, or high resistance load.

These devices have a two-wire I²C™ compatible serial interface for standard (100 kHz), fast (400 kHz), or High-Speed (3.4 MHz) mode.

These devices are available in small 6-pin SOT-23 and DFN 2x2 mm packages.

MCP4706/4716/4726

Block Diagram



1.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings †

Voltage on V_{DD} with respect to V_{SS}	-0.6V to +6.5V
Voltage on all pins with respect to V_{SS}	-0.3V to $V_{DD} + 0.3V$
Input clamp current, I_{IK} ($V_I < 0$, $V_I > V_{DD}$)	± 20 mA
Output clamp current, I_{OK} ($V_O < 0$ or $V_O > V_{DD}$)	± 20 mA
Maximum input current source/sunk by SDA, SCL pins	2 mA
Maximum output current sunk by SDA Output pin	25 mA
Maximum current out of V_{SS} pin	50 mA
Maximum current into V_{DD} pin	50 mA
Maximum current sourced by the V_{OUT} pin	40 mA
Maximum current sunk by the V_{OUT} pin	40 mA
Maximum current sunk by the V_{REF} pin	40 μ A
Package power dissipation ($T_A = +50^\circ\text{C}$, $T_J = +150^\circ\text{C}$)	
SOT-23-6	452 mW
DFN-6	1098 mW
Storage temperature	-65°C to $+150^\circ\text{C}$
Ambient temperature with power applied	-55°C to $+125^\circ\text{C}$
ESD protection on all pins	≥ 6 kV (HBM)
.....	$\geq 400\text{V}$ (MM)
Maximum Junction Temperature (T_J)	$+150^\circ\text{C}$

† Notice: Stresses above those listed under “Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

MCP4706/4716/4726

ELECTRICAL CHARACTERISTICS

Electrical Specifications: Unless otherwise indicated, $V_{DD} = 2.7V$ to $5.5V$, $V_{SS} = 0V$, $R_L = 5\text{ k}\Omega$ from V_{OUT} to GND, $C_L = 100\text{ pF}$, $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$. Typical values at $+25^\circ\text{C}$.

Parameters	Symbol	Min	Typical	Max	Units	Conditions
Power Requirements						
Input Voltage	V_{DD}	2.7	—	5.5	V	
Input Current	I_{DD}	—	210	400	μA	$V_{REF1}:V_{REF0} = 00$, SCL = SDA = V_{SS} , V_{OUT} is unloaded, volatile DAC Register = $0x000$
		—	210	400	μA	$V_{REF1}:V_{REF0} = 11$, $V_{REF} = V_{DD}$, SCL = SDA = V_{SS} , V_{OUT} is unloaded, volatile DAC Register = $0x000$
Power-Down Current	I_{DDP}	—	0.09	2	μA	PD1:PD0 = 01 (Note 6), V_{OUT} not connected
Power-On Reset Threshold	V_{POR}	—	2.2	—	V	RAM retention voltage, (V_{RAM}) < V_{POR}
Power-Up Ramp Rate	V_{RAMP}	1	—	—	V/S	(Note 1 , Note 4)
DC Accuracy						
Offset Error	V_{OS}		± 0.02	0.75	% of FSR	Code = $0x000h$ $V_{REF1}:V_{REF0} = 00$, $G = 0$
Offset Error Temperature Coefficient	$V_{OS}/^\circ\text{C}$	—	± 1	—	ppm/ $^\circ\text{C}$	-40°C to $+25^\circ\text{C}$
		—	± 2	—	ppm/ $^\circ\text{C}$	$+25^\circ\text{C}$ to $+85^\circ\text{C}$
Zero-Scale Error	E_{ZS}	—	0.13	2.0	LSb	MCP4706 , Code = $0x00h$
		—	0.52	7.7	LSb	MCP4716 , Code = $0x000h$
		—	2.05	30.8	LSb	MCP4726 , Code = $0x000h$
Full-Scale Error	E_{FS}	—	0.3	5.2	LSb	MCP4706 , Code = $0xFFh$
		—	1.1	20.5	LSb	MCP4716 , Code = $0x3FFh$
		—	4.1	82.0	LSb	MCP4726 , Code = $0xFFFFh$
Gain Error (Note 2)	g_E	-2	-0.10	2	% of FSR	MCP4706 , Code = $0xFFh$ $V_{REF1}:V_{REF0} = 00$, $G = 0$
		-2	-0.10	2	% of FSR	MCP4716 , Code = $0x3FFh$ $V_{REF1}:V_{REF0} = 00$, $G = 0$
		-2	-0.10	2	% of FSR	MCP4726 , Code = $0xFFFFh$ $V_{REF1}:V_{REF0} = 00$, $G = 0$
Gain Error Drift	$\Delta G/^\circ\text{C}$	—	-3	—	ppm/ $^\circ\text{C}$	
Resolution	n	8			bits	MCP4706
		10			bits	MCP4716
		12			bits	MCP4726
INL Error (Note 7)	INL	-0.907	± 0.125	+0.907	LSb	MCP4706 (codes: 6 to 250)
		-3.625	± 0.5	+3.625	LSb	MCP4716 (codes: 25 to 1000)
		-14.5	± 2	+14.5	LSb	MCP4726 (codes: 100 to 4000)
DNL Error (Note 7)	DNL	-0.05	± 0.0125	+0.05	LSb	MCP4706 (codes: 6 to 250)
		-0.188	± 0.05	+0.188	LSb	MCP4716 (codes: 25 to 1000)
		-0.75	± 0.2	+0.75	LSb	MCP4726 (codes: 100 to 4000)

- Note 1:** This parameter is ensured by design and is not 100% tested.
Note 2: This Gain error does not include Offset error. See [Section 1.0 “Electrical Characteristics”](#) for more details in plots.
Note 3: Within 1/2 LSb of final value when code changes from 1/4 to 3/4 of FSR. (Example: 400h to C00h in 12-bit device).
Note 4: The power-up ramp rate affects on uploading the EEPROM contents to the DAC register. It measures the rise of V_{DD} over time.
Note 5: This parameter is ensured by characterization, and not 100% tested.
Note 6: The PD1:PD0 = 10 , and ‘11’ configurations should have the same current.
Note 7: $V_{DD} = V_{REF} = 5.5V$.

ELECTRICAL CHARACTERISTICS (CONTINUED)

Electrical Specifications: Unless otherwise indicated, $V_{DD} = 2.7V$ to $5.5V$, $V_{SS} = 0V$, $R_L = 5\text{ k}\Omega$ from V_{OUT} to GND, $C_L = 100\text{ pF}$, $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$. Typical values at $+25^\circ\text{C}$.

Parameters	Symbol	Min	Typical	Max	Units	Conditions
Output Amplifier						
Minimum Output Voltage	$V_{OUT(MIN)}$	—	0.01	—	V	Output Amplifier's minimum drive
Maximum Output Voltage	$V_{OUT(MAX)}$	—	$V_{DD} - 0.04$	—	V	Output Amplifier's maximum drive
Phase Margin	PM	—	66	—	Degree ($^\circ$)	$C_L = 400\text{ pF}$, $R_L = \infty$
Slew Rate	SR	—	0.55	—	$V/\mu\text{s}$	
Short Circuit Current	I_{SC}	7	15	24	mA	
Settling Time	$t_{SETTLING}$	—	6	—	μs	Note 3
Power-Down Output Disable Time Delay	T_{PDD}	—	1	—	μs	PD1:PD0 = 00 -> 11, '10', or '01' started from falling edge SCL at end of ACK bit. $V_{OUT} = V_{OUT} - 10\text{ mV}$. V_{OUT} not connected.
Power-Down Output Enable Time Delay	T_{PDE}	—	10.5	—	μs	PD1:PD0 = 11, '10', or '01' -> "00" started from falling edge SCL at end of ACK bit. Volatile DAC Register = FFh, $V_{OUT} = 10\text{ mV}$. V_{OUT} not connected.
External Reference (V_{REF}) (Note 1)						
Input Range	V_{REF}	0.04	—	$V_{DD} - 0.04$	V	Buffered mode
		0	—	V_{DD}	V	Unbuffered mode
Input Impedance	R_{VREF}	—	210	—	$\text{k}\Omega$	Unbuffered mode
Input Capacitance	C_{REF}	—	29	—	pF	Unbuffered mode
-3 dB Bandwidth		—	86.5	—	kHz	$V_{REF} = 2.048V \pm 0.1V$, $V_{REF1}:V_{REF0} = 10$, $G = 0$
		—	67.7	—	kHz	$V_{REF} = 2.048V \pm 0.1V$, $V_{REF1}:V_{REF0} = 10$, $G = 1$
Total Harmonic Distortion	THD	—	-73	—	dB	$V_{REF} = 2.048V \pm 0.1V$, $V_{REF1}:V_{REF0} = 10$, $G = 0$, Frequency = 1 kHz
Dynamic Performance (Note 1)						
Major Code Transition Glitch		—	45	—	nV-s	1 LSb change around major carry (800h to 7FFh)
Digital Feedthrough		—	<10	—	nV-s	

- Note 1:** This parameter is ensured by design and is not 100% tested.
Note 2: This Gain error does not include Offset error. See [Section 1.0 "Electrical Characteristics"](#) for more details in plots.
Note 3: Within 1/2 LSb of final value when code changes from 1/4 to 3/4 of FSR. (Example: 400h to C00h in 12-bit device).
Note 4: The power-up ramp rate affects on uploading the EEPROM contents to the DAC register. It measures the rise of V_{DD} over time.
Note 5: This parameter is ensured by characterization, and not 100% tested.
Note 6: The PD1:PD0 = 10, and '11' configurations should have the same current.
Note 7: $V_{DD} = V_{REF} = 5.5V$.

MCP4706/4716/4726

ELECTRICAL CHARACTERISTICS (CONTINUED)

Electrical Specifications: Unless otherwise indicated, $V_{DD} = 2.7V$ to $5.5V$, $V_{SS} = 0V$, $R_L = 5\text{ k}\Omega$ from V_{OUT} to GND, $C_L = 100\text{ pF}$, $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$. Typical values at $+25^\circ\text{C}$.

Parameters	Symbol	Min	Typical	Max	Units	Conditions
Digital Interface						
Output Low Voltage	V_{OL}	—	—	0.4	V	$I_{OL} = 3\text{ mA}$
Input High Voltage (SDA and SCL Pins)	V_{IH}	$0.7V_{DD}$	—	—	V	
Input Low Voltage (SDA and SCL Pins)	V_{IL}	—	—	$0.3V_{DD}$	V	
Input Leakage	I_{LI}	—	—	± 1	μA	SCL = SDA = V_{SS} or SCL = SDA = V_{DD}
Pin Capacitance	C_{PIN}	—	—	3	pF	(Note 5)
EEPROM						
EEPROM Write Time	T_{WRITE}	—	25	50	ms	
Data Retention		—	200	—	Years	At $+25^\circ\text{C}$, (Note 1)
Endurance		1	—	—	Million Cycles	At $+25^\circ\text{C}$, (Note 1)

- Note 1:** This parameter is ensured by design and is not 100% tested.
- Note 2:** This Gain error does not include Offset error. See [Section 1.0 “Electrical Characteristics”](#) for more details in plots.
- Note 3:** Within 1/2 LSB of final value when code changes from 1/4 to 3/4 of FSR. (Example: 400h to C00h in 12-bit device).
- Note 4:** The power-up ramp rate affects on uploading the EEPROM contents to the DAC register. It measures the rise of V_{DD} over time.
- Note 5:** This parameter is ensured by characterization, and not 100% tested.
- Note 6:** The PD1:PD0 = 10, and ‘11’ configurations should have the same current.
- Note 7:** $V_{DD} = V_{REF} = 5.5V$.

1.1 I²C Mode Timing Waveforms and Requirements

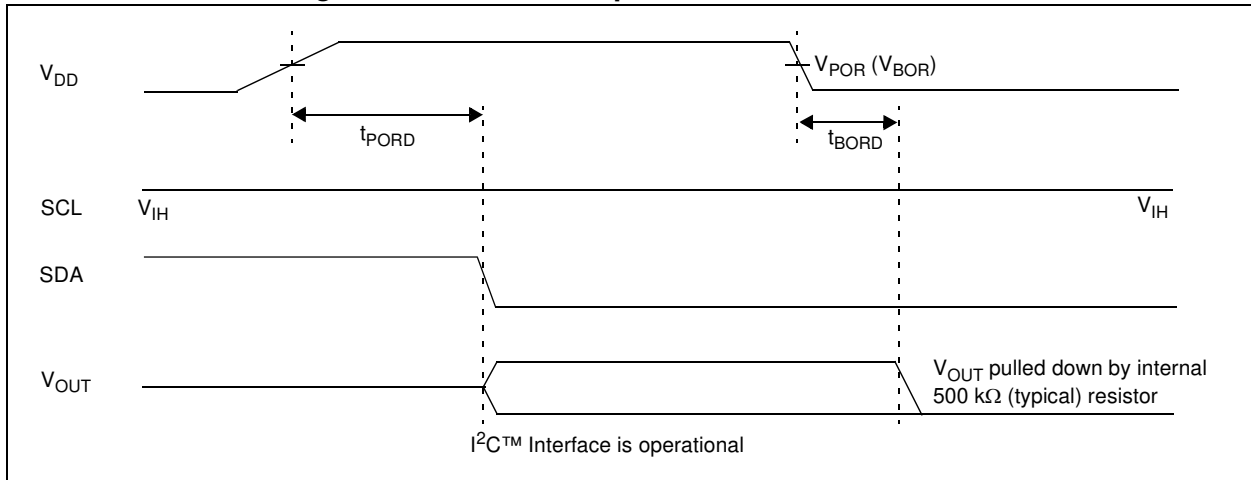


FIGURE 1-1: Power-On and Brown-Out Reset Waveforms.

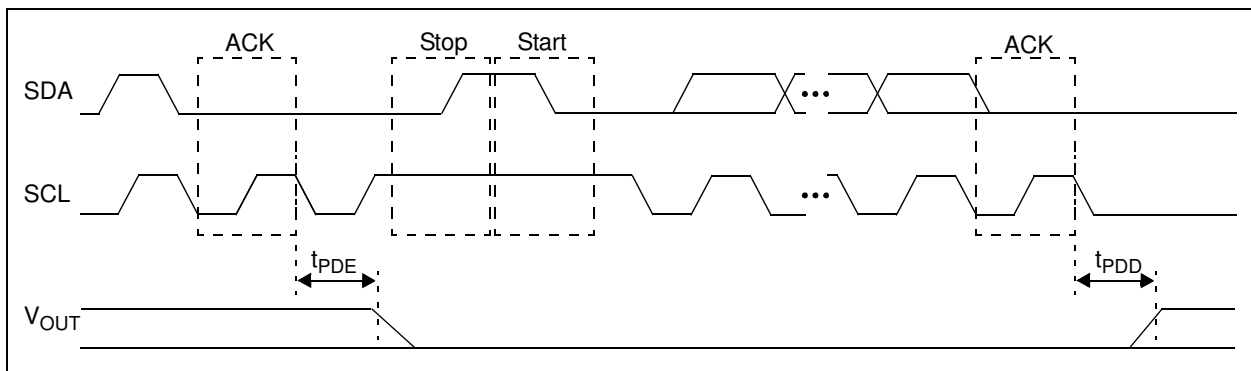


FIGURE 1-2: I²C Power-Down Command Timing.

TABLE 1-1: RESET TIMING

Timing Characteristics		Standard Operating Conditions (unless otherwise specified)				
		Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ (extended)				
		All parameters apply across the specified operating ranges unless noted.				
		$V_{DD} = +2.7\text{V to } 5.5\text{V}$, 5 k Ω , 10 k Ω , 50 k Ω , 100 k Ω devices.				
		Typical specifications represent values for $V_{DD} = 5.5\text{V}$, $T_A = +25^{\circ}\text{C}$.				
Parameters	Sym	Min	Typ	Max	Units	Conditions
Power-Up Reset Delay	t_{PORD}	—	60	—	μs	Monitor ACK bit response to ensure device responds to command.
Brown-Out Reset Delay	t_{BORD}	—	1	—	μs	V_{DD} transitions from $V_{DD(\text{MIN})} \rightarrow > V_{\text{POR}}$ V_{OUT} driven to V_{OUT} disabled
Power-Down Disable Time Delay	T_{PDD}	—	2.5	—	μs	$V_{DD} = 5\text{V}$ PD1:PD0 $\rightarrow 00$ (from '01', '10', or '11'), from falling edge SCL at end of ACK bit.
		—	5	—	μs	$V_{DD} = 3\text{V}$ PD1:PD0 $\rightarrow 00$ (from '01', '10', or '11'), from falling edge SCL at end of ACK bit.
Power-Down Enable Time Delay	T_{PDE}	—	10.5	—	μs	PD1:PD0 $\rightarrow 01, '10', \text{ or } '11'$ (from '00'), from falling edge SCL at end of ACK bit.

MCP4706/4716/4726

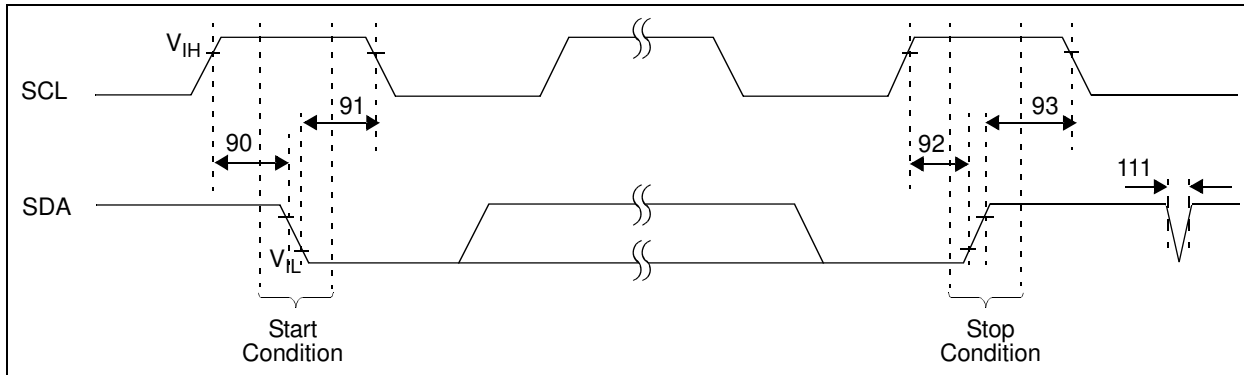


FIGURE 1-3: I²C Bus Start/Stop Bits Timing Waveforms.

TABLE 1-2: I²C BUS START/STOP BITS REQUIREMENTS

I ² C™ AC Characteristics		Standard Operating Conditions (unless otherwise specified)						
		Operating Temperature -40°C ≤ TA ≤ +125°C (Extended)						
		Operating Voltage VDD range is described in Electrical Characteristics						
Param. No.	Symbol	Characteristic	Min	Max	Units	Conditions		
	F _{SCL}	SCL pin Frequency	Standard mode	0	100	kHz	C _b = 400 pF, 2.7V - 5.5V	
			Fast mode	0	400	kHz		C _b = 400 pF, 2.7V - 5.5V
			High-Speed 1.7	0	1.7	MHz		C _b = 400 pF, 4.5V - 5.5V
			High-Speed 3.4	0	3.4	MHz		C _b = 100 pF, 4.5V - 5.5V
D102	C _b	Bus capacitive loading	100 kHz mode	—	400	pF		
			400 kHz mode	—	400	pF		
			1.7 MHz mode	—	400	pF		
			3.4 MHz mode	—	100	pF		
90	TSU:STA	Start condition Setup time	100 kHz mode	4700	—	ns	Only relevant for repeated Start condition	
			400 kHz mode	600	—	ns		
			1.7 MHz mode	160	—	ns		
			3.4 MHz mode	160	—	ns		
91	THD:STA	Start condition Hold time	100 kHz mode	4000	—	ns	After this period, the first clock pulse is generated	
			400 kHz mode	600	—	ns		
			1.7 MHz mode	160	—	ns		
			3.4 MHz mode	160	—	ns		
92	TSU:STO	Stop condition Setup time	100 kHz mode	4000	—	ns		
			400 kHz mode	600	—	ns		
			1.7 MHz mode	160	—	ns		
			3.4 MHz mode	160	—	ns		
93	THD:STO	Stop condition Hold time	100 kHz mode	4000	—	ns		
			400 kHz mode	600	—	ns		
			1.7 MHz mode	160	—	ns		
			3.4 MHz mode	160	—	ns		
94	T _{HVCSU}	HVC to SCL Setup time	25	—	uS	High Voltage Commands		
95	T _{HVCHD}	SCL to HVC Hold time	25	—	uS	High Voltage Commands		

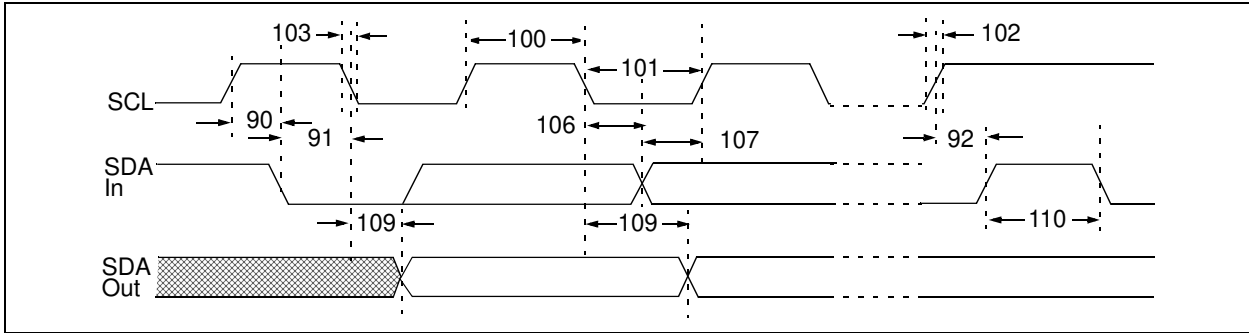


FIGURE 1-4: I²C Bus Data Timing.

TABLE 1-3: I²C BUS DATA REQUIREMENTS (SLAVE MODE)

I ² C™ AC Characteristics			Standard Operating Conditions (unless otherwise specified)				
			Operating Temperature -40°C ≤ T _A ≤ +125°C (Extended)				
			Operating Voltage V _{DD} range is described in Electrical Characteristics				
Param. No.	Sym	Characteristic	Min	Max	Units	Conditions	
100	T _{HIGH}	Clock high time	100 kHz mode	4000	—	ns	2.7V-5.5V
			400 kHz mode	600	—	ns	2.7V-5.5V
			1.7 MHz mode	120	—	ns	4.5V-5.5V
			3.4 MHz mode	60	—	ns	4.5V-5.5V
101	T _{LOW}	Clock low time	100 kHz mode	4700	—	ns	2.7V-5.5V
			400 kHz mode	1300	—	ns	2.7V-5.5V
			1.7 MHz mode	320	—	ns	4.5V-5.5V
			3.4 MHz mode	160	—	ns	4.5V-5.5V

- Note 1:** As a transmitter, the device must provide this internal minimum delay time to bridge the undefined region (minimum 300 ns) of the falling edge of SCL to avoid unintended generation of Start or Stop conditions.
- 2:** A Fast mode (400 kHz) I²C™ bus device can be used in a Standard mode (100 kHz) I²C bus system, but the requirement $t_{SU:DAT} \geq 250$ ns must then be met. This will automatically be the case if the device does not stretch the Low period of the SCL signal. If such a device does stretch the Low period of the SCL signal, it must output the next data bit to the SDA line.
 $T_R \text{ max.} + t_{SU:DAT} = 1000 + 250 = 1250$ ns (according to the Standard mode I²C bus specification) before the SCL line is released.
- 3:** The MCP47X6 device must provide a data hold time to bridge the undefined part between V_{IH} and V_{IL} of the falling edge of the SCL signal. This specification is not a part of the I²C specification, but must be tested in order to ensure that the output data will meet the setup and hold specifications for the receiving device.
- 4:** Use C_b in pF for the calculations.
- 5:** Not Tested. This parameter ensured by characterization.
- 6:** A Master Transmitter must provide a delay to ensure that difference between SDA and SCL fall times do not unintentionally create a Start or Stop condition.
 If this parameter is too short, it can create an unintentional Start or Stop condition to other devices on the I²C bus line. If this parameter is too long, the Data Input Setup (T_{SU:DAT}) or Clock Low time (T_{LOW}) can be affected.
Data Input: This parameter must be longer than t_{SP}.
Data Output: This parameter is characterized, and tested indirectly by testing T_{AA} parameter.
- 7:** Ensured by the T_{AA} 3.4 MHz specification test.
- 8:** The specification is not part of the I²C specification. $T_{AA} = T_{HD:DAT} + T_{FSDA}$ (or T_{RSDA}).

MCP4706/4716/4726

TABLE 1-3: I²C BUS DATA REQUIREMENTS (SLAVE MODE) (CONTINUED)

I ² C™ AC Characteristics		Standard Operating Conditions (unless otherwise specified) Operating Temperature -40°C ≤ T _A ≤ +125°C (Extended) Operating Voltage V _{DD} range is described in Electrical Characteristics							
Param. No.	Sym	Characteristic	Min	Max	Units	Conditions			
102A ⁽⁵⁾	T _{RSCL}	SCL rise time	100 kHz mode	—	1000	ns	C _b is specified to be from 10 to 400 pF (100 pF maximum for 3.4 MHz mode)		
			400 kHz mode	20 + 0.1C _b	300	ns			
			1.7 MHz mode	20	80	ns			
					1.7 MHz mode	20	160	ns	After a Repeated Start condition or an Acknowledge bit
					3.4 MHz mode	10	40	ns	
					3.4 MHz mode	10	80	ns	After a Repeated Start condition or an Acknowledge bit
102B ⁽⁵⁾	T _{RSDA}	SDA rise time	100 kHz mode	—	1000	ns	C _b is specified to be from 10 to 400 pF (100 pF max for 3.4 MHz mode)		
			400 kHz mode	20 + 0.1C _b	300	ns			
			1.7 MHz mode	20	160	ns			
			3.4 MHz mode	10	80	ns			
103A ⁽⁵⁾	T _{FSCL}	SCL fall time	100 kHz mode	—	300	ns	C _b is specified to be from 10 to 400 pF (100 pF max for 3.4 MHz mode)		
			400 kHz mode	20 + 0.1C _b	300	ns			
			1.7 MHz mode	20	80	ns			
			3.4 MHz mode	10	40	ns			
103B ⁽⁵⁾	T _{FSDA}	SDA fall time	100 kHz mode	—	300	ns	C _b is specified to be from 10 to 400 pF (100 pF max for 3.4 MHz mode)		
			400 kHz mode	20 + 0.1C _b ⁽⁴⁾	300	ns			
			1.7 MHz mode	20	160	ns			
			3.4 MHz mode	10	80	ns			

- Note 1:** As a transmitter, the device must provide this internal minimum delay time to bridge the undefined region (minimum 300 ns) of the falling edge of SCL to avoid unintended generation of Start or Stop conditions.
- 2:** A Fast mode (400 kHz) I²C™ bus device can be used in a Standard mode (100 kHz) I²C bus system, but the requirement t_{SU;DAT} ≥ 250 ns must then be met. This will automatically be the case if the device does not stretch the Low period of the SCL signal. If such a device does stretch the Low period of the SCL signal, it must output the next data bit to the SDA line.
T_R max. + t_{SU;DAT} = 1000 + 250 = 1250 ns (according to the Standard mode I²C bus specification) before the SCL line is released.
- 3:** The MCP47X6 device must provide a data hold time to bridge the undefined part between V_{IH} and V_{IL} of the falling edge of the SCL signal. This specification is not a part of the I²C specification, but must be tested in order to ensure that the output data will meet the setup and hold specifications for the receiving device.
- 4:** Use C_b in pF for the calculations.
- 5:** Not Tested. This parameter ensured by characterization.
- 6:** A Master Transmitter must provide a delay to ensure that difference between SDA and SCL fall times do not unintentionally create a Start or Stop condition.
If this parameter is too short, it can create an unintentional Start or Stop condition to other devices on the I²C bus line. If this parameter is too long, the Data Input Setup (T_{SU;DAT}) or Clock Low time (T_{LOW}) can be affected.
Data Input: This parameter must be longer than t_{SP}.
Data Output: This parameter is characterized, and tested indirectly by testing T_{AA} parameter.
- 7:** Ensured by the T_{AA} 3.4 MHz specification test.
- 8:** The specification is not part of the I²C specification. T_{AA} = T_{HD;DAT} + T_{FSDA} (or T_{RSDA}).

TABLE 1-3: I²C BUS DATA REQUIREMENTS (SLAVE MODE) (CONTINUED)

I ² C™ AC Characteristics		Standard Operating Conditions (unless otherwise specified) Operating Temperature -40°C ≤ T _A ≤ +125°C (Extended) Operating Voltage V _{DD} range is described in Electrical Characteristics					
Param. No.	Sym	Characteristic	Min	Max	Units	Conditions	
106	T _{HD:DAT}	Data input hold time	100 kHz mode	0	—	ns	2.7V-5.5V, Note 6
			400 kHz mode	0	—	ns	2.7V-5.5V, Note 6
			1.7 MHz mode	0	—	ns	4.5V-5.5V, Note 6
			3.4 MHz mode	0	—	ns	4.5V-5.5V, Note 6
107	T _{SU:DAT}	Data input setup time	100 kHz mode	250	—	ns	Note 2
			400 kHz mode	100	—	ns	
			1.7 MHz mode	10	—	ns	
			3.4 MHz mode	10	—	ns	
109	T _{AA}	Output valid from clock	100 kHz mode	—	3750	ns	Note 1, Note 8
			400 kHz mode	—	1200	ns	
			1.7 MHz mode	—	150	ns	C _b = 100 pF, Note 1, Note 7, Note 8
				—	310	ns	C _b = 400 pF, Note 1, Note 5, Note 8
			3.4 MHz mode	—	150	ns	C _b = 100 pF, Note 1, Note 8
110	T _{BUF}	Bus free time	100 kHz mode	4700	—	ns	Time the bus must be free before a new transmission can start
			400 kHz mode	1300	—	ns	
			1.7 MHz mode	N/A	—	ns	
			3.4 MHz mode	N/A	—	ns	

- Note 1:** As a transmitter, the device must provide this internal minimum delay time to bridge the undefined region (minimum 300 ns) of the falling edge of SCL to avoid unintended generation of Start or Stop conditions.
- 2:** A Fast mode (400 kHz) I²C™ bus device can be used in a Standard mode (100 kHz) I²C bus system, but the requirement t_{SU:DAT} ≥ 250 ns must then be met. This will automatically be the case if the device does not stretch the Low period of the SCL signal. If such a device does stretch the Low period of the SCL signal, it must output the next data bit to the SDA line.
T_{R max.}+t_{SU:DAT} = 1000 + 250 = 1250 ns (according to the Standard mode I²C bus specification) before the SCL line is released.
- 3:** The MCP47X6 device must provide a data hold time to bridge the undefined part between V_{IH} and V_{IL} of the falling edge of the SCL signal. This specification is not a part of the I²C specification, but must be tested in order to ensure that the output data will meet the setup and hold specifications for the receiving device.
- 4:** Use C_b in pF for the calculations.
- 5:** Not Tested. This parameter ensured by characterization.
- 6:** A Master Transmitter must provide a delay to ensure that difference between SDA and SCL fall times do not unintentionally create a Start or Stop condition.
If this parameter is too short, it can create an unintentional Start or Stop condition to other devices on the I²C bus line. If this parameter is too long, the Data Input Setup (T_{SU:DAT}) or Clock Low time (T_{LOW}) can be affected.
Data Input: This parameter must be longer than t_{SP}.
Data Output: This parameter is characterized, and tested indirectly by testing T_{AA} parameter.
- 7:** Ensured by the T_{AA} 3.4 MHz specification test.
- 8:** The specification is not part of the I²C specification. T_{AA} = T_{HD:DAT} + T_{FSDA} (or T_{RSDA}).

MCP4706/4716/4726

TABLE 1-3: I²C BUS DATA REQUIREMENTS (SLAVE MODE) (CONTINUED)

I ² C™ AC Characteristics		Standard Operating Conditions (unless otherwise specified)					
		Operating Temperature -40°C ≤ T _A ≤ +125°C (Extended)					
		Operating Voltage V _{DD} range is described in Electrical Characteristics					
Param. No.	Sym	Characteristic	Min	Max	Units	Conditions	
111	T _{SP}	Input filter spike suppression (SDA and SCL)	100 kHz mode	—	50	ns	NXP Spec states N/A
			400 kHz mode	—	50	ns	
			1.7 MHz mode	—	10	ns	Spike suppression
			3.4 MHz mode	—	10	ns	Spike suppression

- Note 1:** As a transmitter, the device must provide this internal minimum delay time to bridge the undefined region (minimum 300 ns) of the falling edge of SCL to avoid unintended generation of Start or Stop conditions.
- 2:** A Fast mode (400 kHz) I²C™ bus device can be used in a Standard mode (100 kHz) I²C bus system, but the requirement t_{SU;DAT} ≥ 250 ns must then be met. This will automatically be the case if the device does not stretch the Low period of the SCL signal. If such a device does stretch the Low period of the SCL signal, it must output the next data bit to the SDA line.
T_R max. + t_{SU;DAT} = 1000 + 250 = 1250 ns (according to the Standard mode I²C bus specification) before the SCL line is released.
- 3:** The MCP47X6 device must provide a data hold time to bridge the undefined part between V_{IH} and V_{IL} of the falling edge of the SCL signal. This specification is not a part of the I²C specification, but must be tested in order to ensure that the output data will meet the setup and hold specifications for the receiving device.
- 4:** Use C_b in pF for the calculations.
- 5:** Not Tested. This parameter ensured by characterization.
- 6:** A Master Transmitter must provide a delay to ensure that difference between SDA and SCL fall times do not unintentionally create a Start or Stop condition.
If this parameter is too short, it can create an unintentional Start or Stop condition to other devices on the I²C bus line. If this parameter is too long, the Data Input Setup (T_{SU;DAT}) or Clock Low time (T_{LOW}) can be affected.
Data Input: This parameter must be longer than t_{SP}.
Data Output: This parameter is characterized, and tested indirectly by testing T_{AA} parameter.
- 7:** Ensured by the T_{AA} 3.4 MHz specification test.
- 8:** The specification is not part of the I²C specification. T_{AA} = T_{HD;DAT} + T_{FSDA} (or T_{RSDA}).

TEMPERATURE CHARACTERISTICS

Electrical Specifications: Unless otherwise indicated, $V_{DD} = +2.7V$ to $+5.5V$, $V_{SS} = GND$.						
Parameters	Symbol	Min	Typical	Max	Units	Conditions
Temperature Ranges						
Specified Temperature Range	T_A	-40	—	+125	°C	
Operating Temperature Range	T_A	-40	—	+125	°C	Note 1
Storage Temperature Range	T_A	-65	—	+150	°C	
Thermal Package Resistances						
Thermal Resistance, 6L-SOT-23	θ_{JA}	—	190	—	°C/W	
Thermal Resistance, 6L-DFN (2 x 2)	θ_{JA}	—	91	—	°C/W	

Note 1: The MCP47X6 devices operate over this extended temperature range, but with reduced performance. Operation in this range must not cause T_J to exceed the Maximum Junction Temperature of $+150^\circ\text{C}$.

MCP4706/4716/4726

NOTES:

2.0 TYPICAL PERFORMANCE CURVES

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

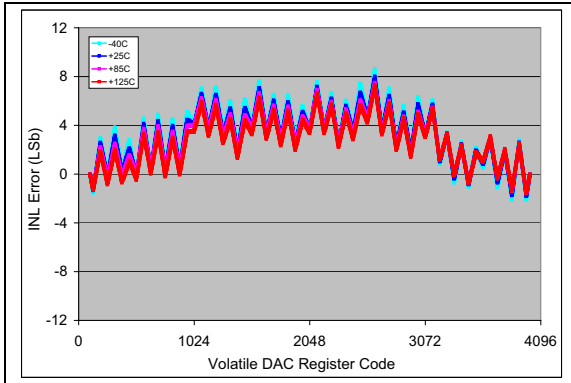


FIGURE 2-1: INL vs. Code (code = 100 to 4000) and Temperature (MCP4726).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 00$.

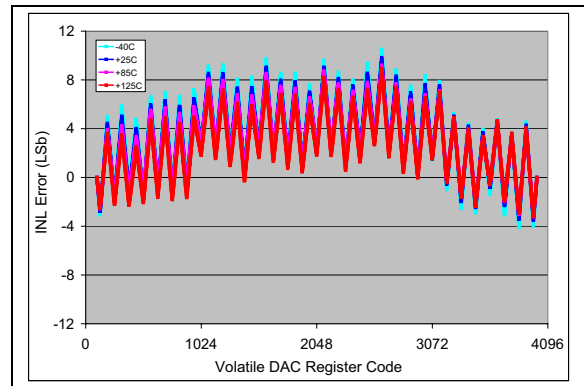


FIGURE 2-4: INL vs. Code (code = 100 to 4000) and Temperature (MCP4726).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 00$.

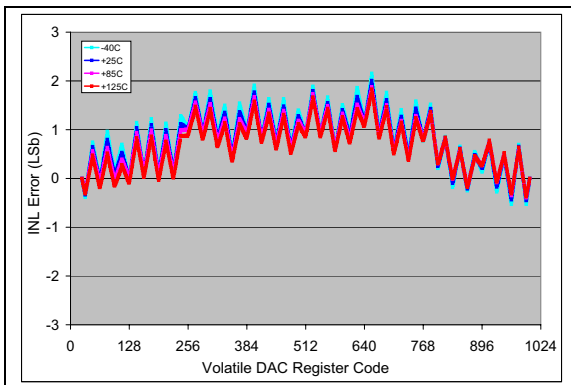


FIGURE 2-2: INL vs. Code (code = 25 to 1000) and Temperature (MCP4716).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 00$.

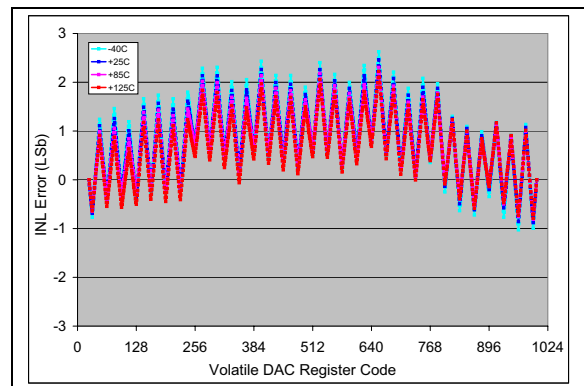


FIGURE 2-5: INL vs. Code (code = 25 to 1000) and Temperature (MCP4716).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 00$.

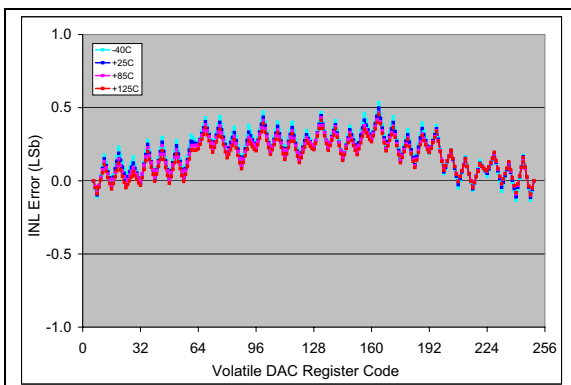


FIGURE 2-3: INL vs. Code (code = 6 to 250) and Temperature (MCP4706).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 00$.

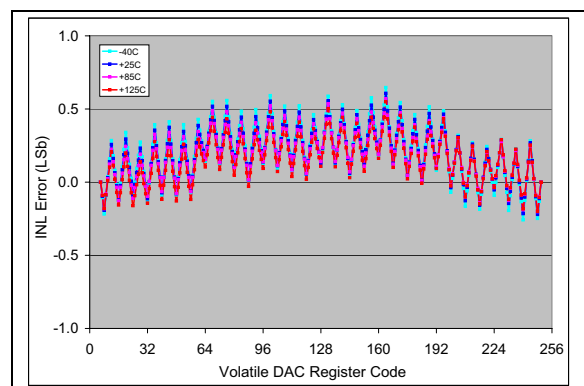


FIGURE 2-6: INL vs. Code (code = 6 to 250) and Temperature (MCP4706).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 00$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

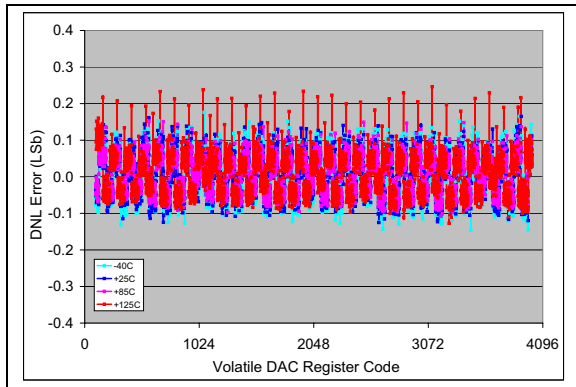


FIGURE 2-7: DNL vs. Code (code = 100 to 4000) and Temperature (MCP4726). $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 00$.

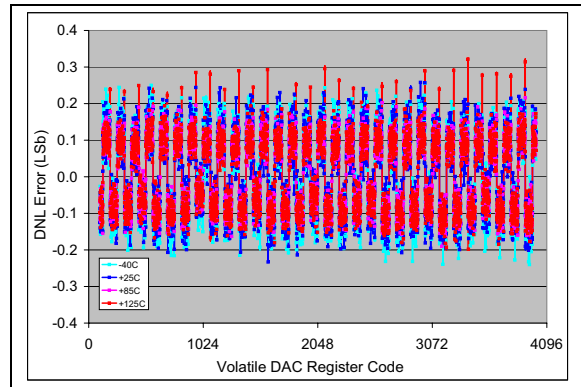


FIGURE 2-10: DNL vs. Code (code = 100 to 4000) and Temperature (MCP4726). $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 00$.

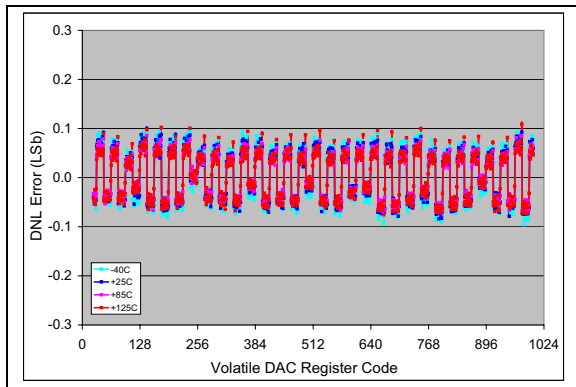


FIGURE 2-8: DNL vs. Code (code = 25 to 1000) and Temperature (MCP4716). $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 00$.

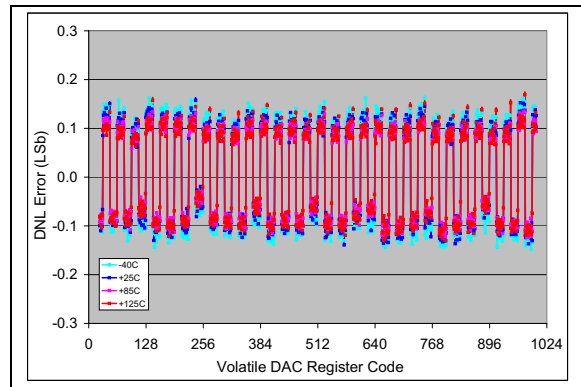


FIGURE 2-11: DNL vs. Code (code = 25 to 1000) and Temperature (MCP4716). $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 00$.

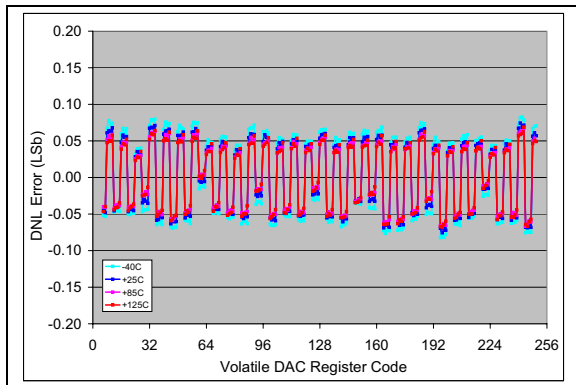


FIGURE 2-9: DNL vs. Code (code = 6 to 250) and Temperature (MCP4706). $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 00$.

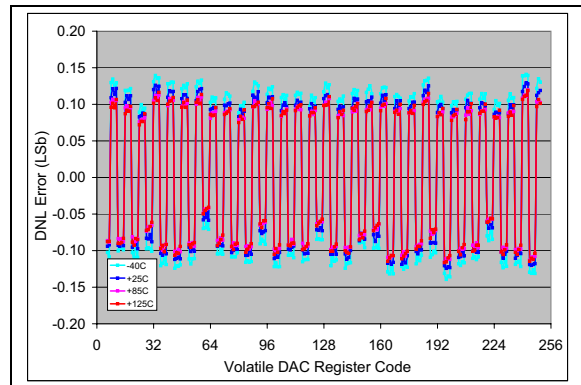


FIGURE 2-12: DNL vs. Code (code = 6 to 250) and Temperature (MCP4706). $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 00$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

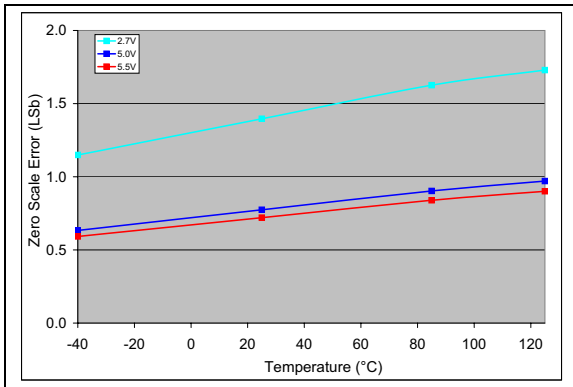


FIGURE 2-13: Zero-Scale Error (ZSE) vs. V_{DD} and Temperature (MCP4726).
 $V_{REF1}:V_{REF0} = 00$.

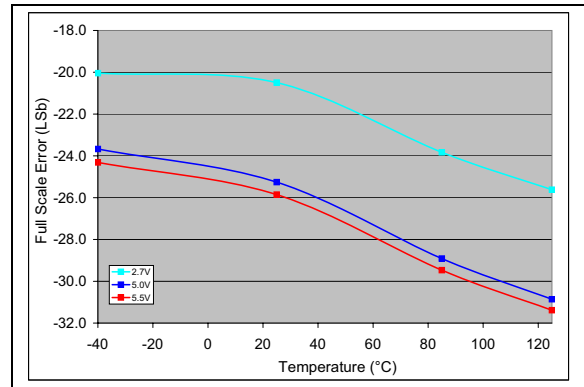


FIGURE 2-16: Full-Scale Error (FSE) vs. V_{DD} and Temperature (MCP4726).
 $V_{REF1}:V_{REF0} = 00$.

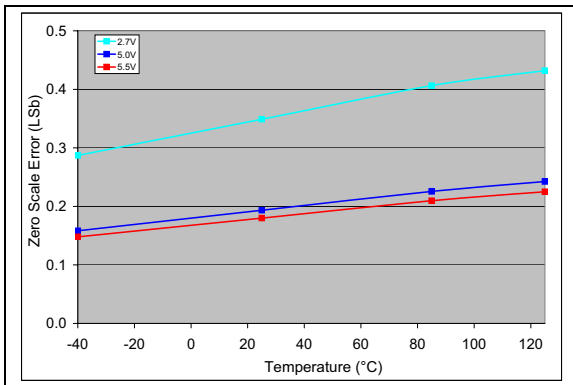


FIGURE 2-14: Zero-Scale Error (ZSE) vs. V_{DD} and Temperature (MCP4716).
 $V_{REF1}:V_{REF0} = 00$.

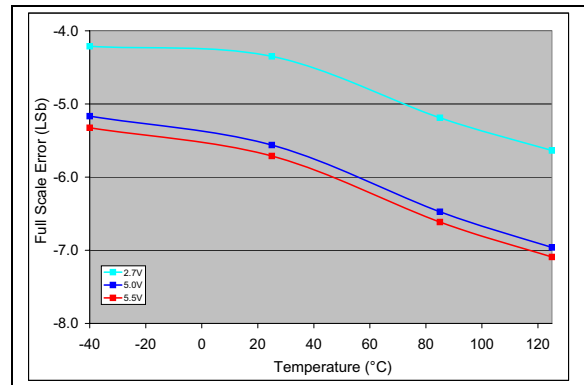


FIGURE 2-17: Full-Scale Error (FSE) vs. V_{DD} and Temperature (MCP4716).
 $V_{REF1}:V_{REF0} = 00$.

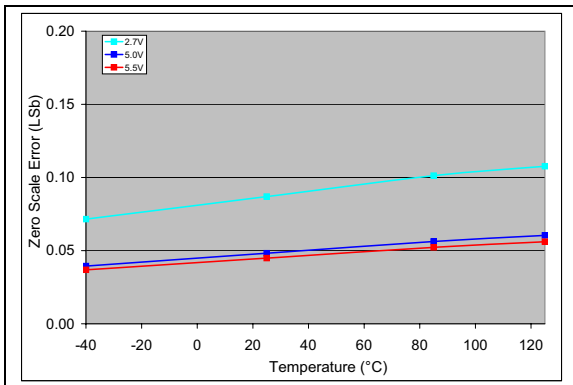


FIGURE 2-15: Zero-Scale Error (ZSE) vs. V_{DD} and Temperature (MCP4706).
 $V_{REF1}:V_{REF0} = 00$.

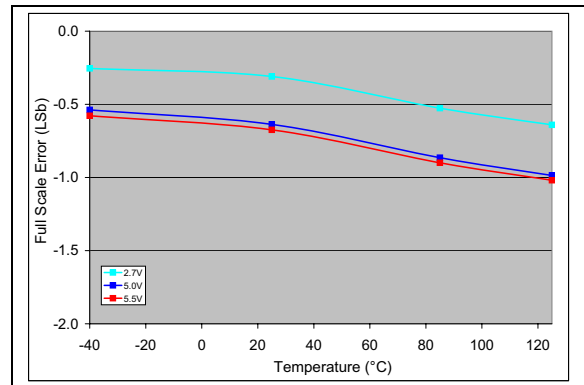


FIGURE 2-18: Full-Scale Error (FSE) vs. V_{DD} and Temperature (MCP4706).
 $V_{REF1}:V_{REF0} = 00$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

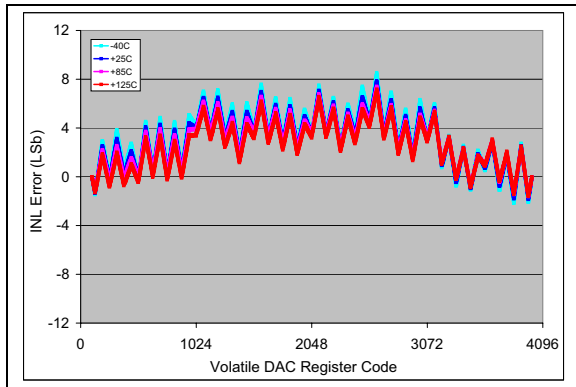


FIGURE 2-19: INL vs. Code (code = 100 to 4000) and Temperature (**MCP4726**).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

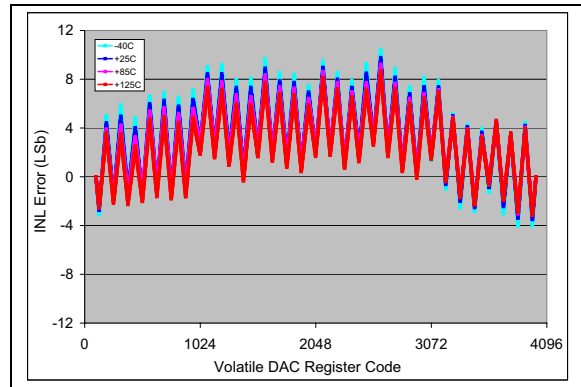


FIGURE 2-22: INL vs. Code (code = 100 to 4000) and Temperature (**MCP4726**).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

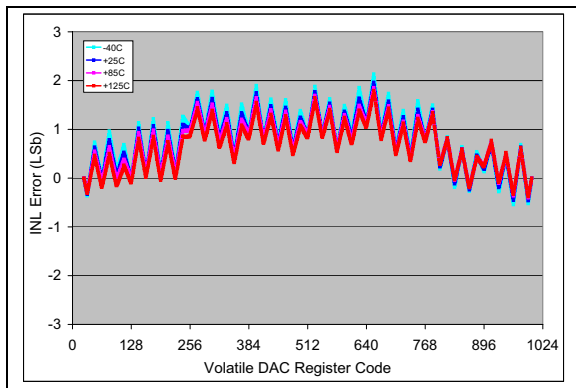


FIGURE 2-20: INL vs. Code (code = 25 to 1000) and Temperature (**MCP4716**).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

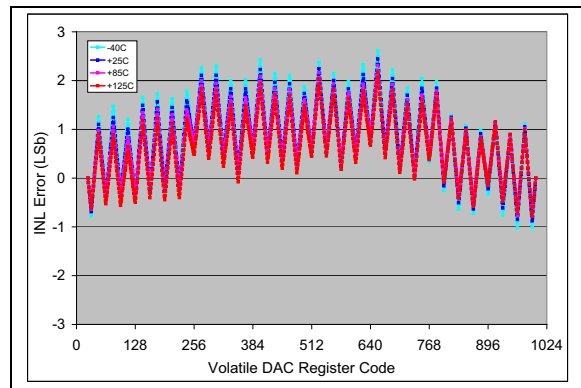


FIGURE 2-23: INL vs. Code (code = 25 to 1000) and Temperature (**MCP4716**).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

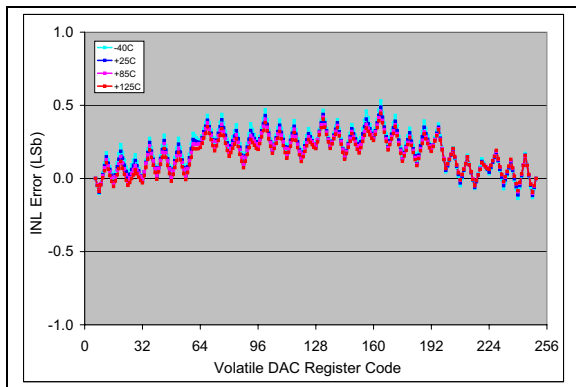


FIGURE 2-21: INL vs. Code (code = 6 to 250) and Temperature (**MCP4706**).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

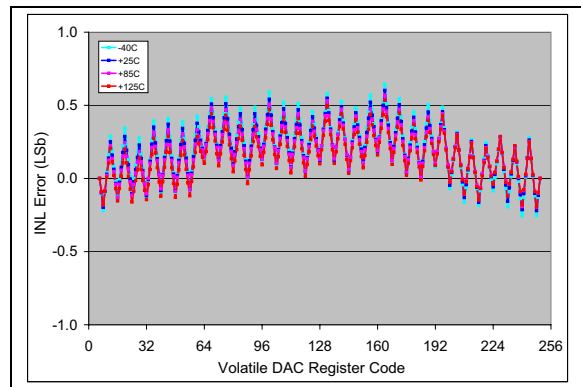


FIGURE 2-24: INL vs. Code (code = 6 to 250) and Temperature (**MCP4706**).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

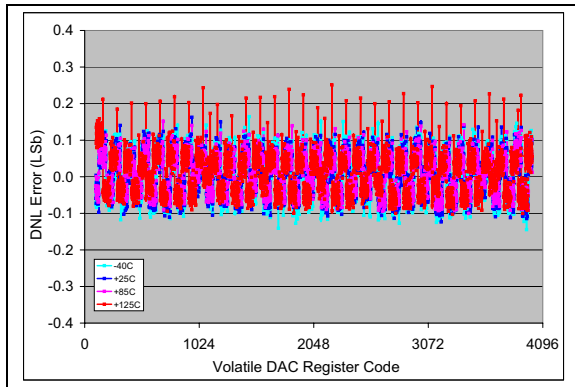


FIGURE 2-25: DNL vs. Code (code = 100 to 4000) and Temperature (MCP4726).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

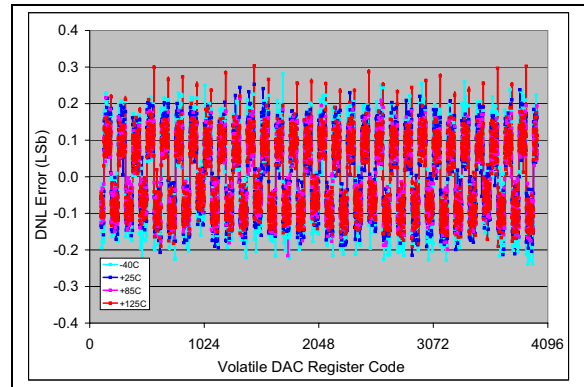


FIGURE 2-28: DNL vs. Code (code = 100 to 4000) and Temperature (MCP4726).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

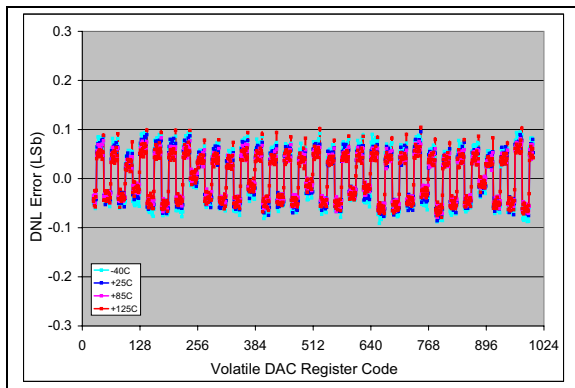


FIGURE 2-26: DNL vs. Code (code = 25 to 1000) and Temperature (MCP4716).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

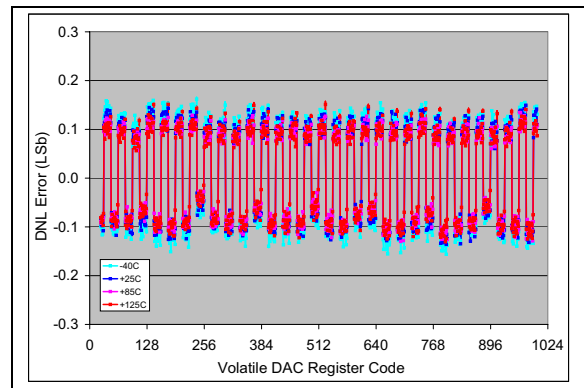


FIGURE 2-29: DNL vs. Code (code = 25 to 1000) and Temperature (MCP4716).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

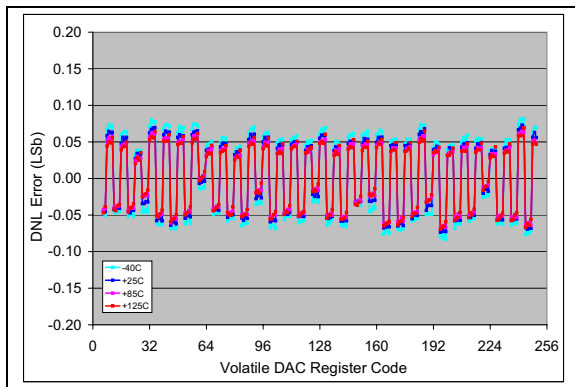


FIGURE 2-27: DNL vs. Code (code = 6 to 250) and Temperature (MCP4706).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

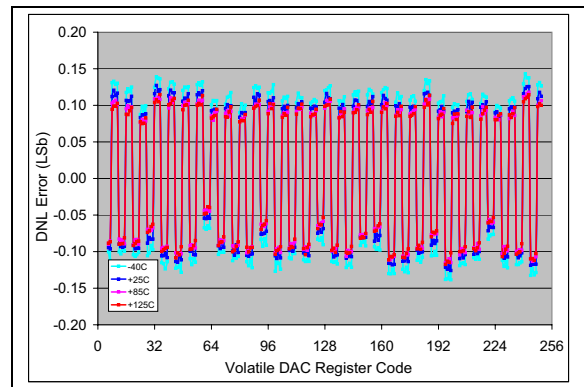


FIGURE 2-30: DNL vs. Code (code = 6 to 250) and Temperature (MCP4706).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

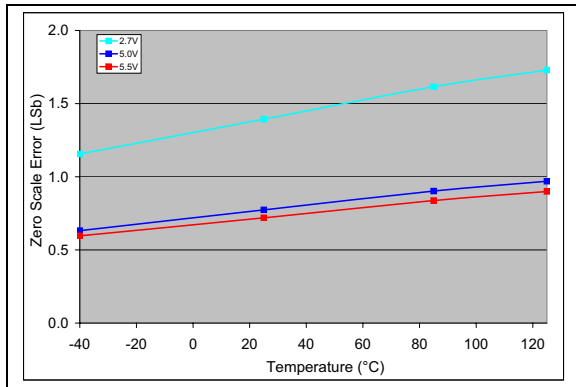


FIGURE 2-31: Zero-Scale Error (ZSE) vs. Temperature (MCP4726).

$V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

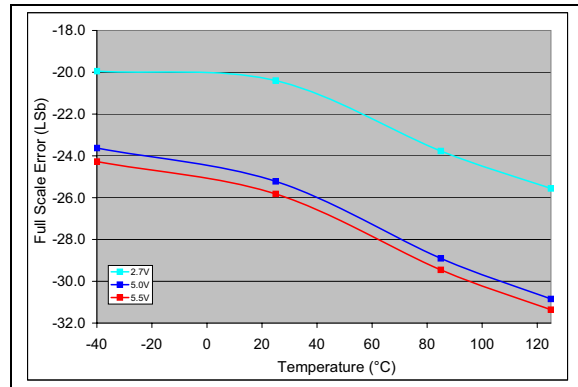


FIGURE 2-34: Full-Scale Error (FSE) vs. Temperature (MCP4726).

$V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

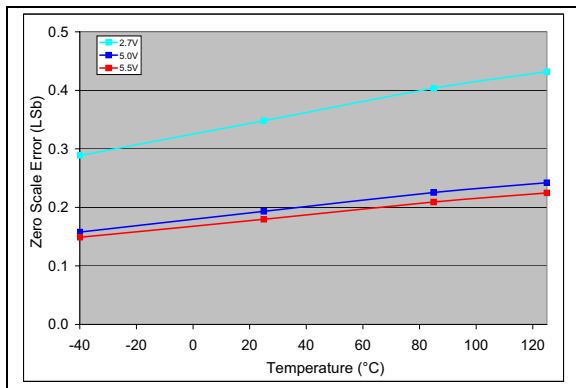


FIGURE 2-32: Zero-Scale Error (ZSE) vs. Temperature (MCP4716).

$V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

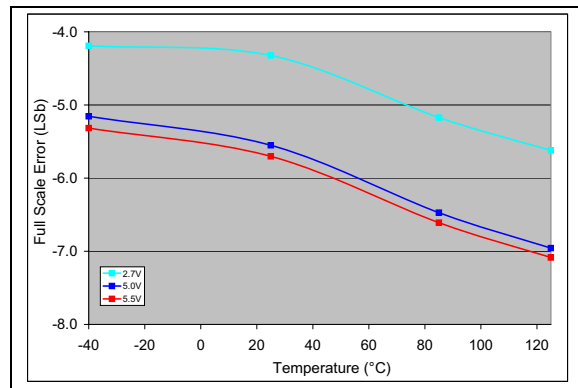


FIGURE 2-35: Full-Scale Error (FSE) vs. Temperature (MCP4716).

$V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

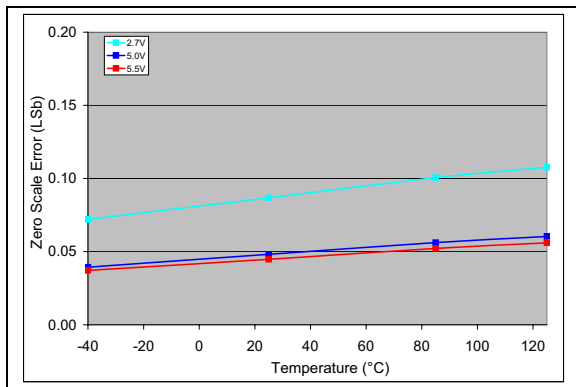


FIGURE 2-33: Zero-Scale Error (ZSE) vs. Temperature (MCP4706).

$V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

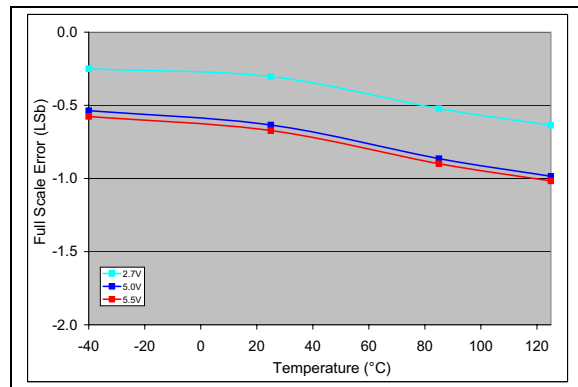


FIGURE 2-36: Full-Scale Error (FSE) vs. Temperature (MCP4706).

$V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 10$, $G = 0$,
 $V_{REF} = V_{DD}$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

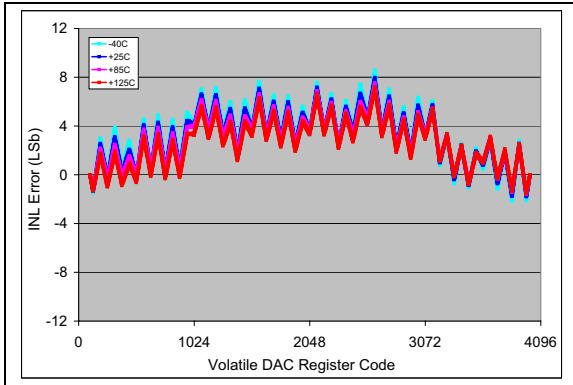


FIGURE 2-37: INL vs. Code (code = 100 to 4000) and Temperature (MCP4726).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

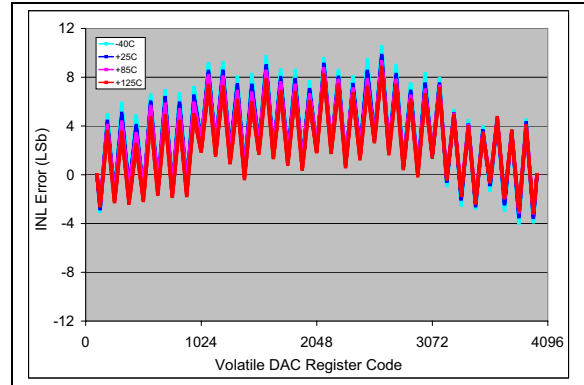


FIGURE 2-40: INL vs. Code (code = 100 to 4000) and Temperature (MCP4726).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

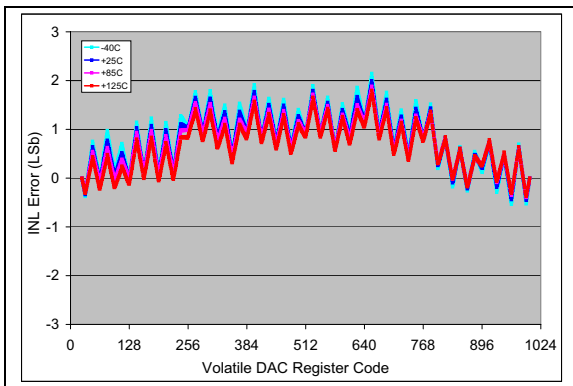


FIGURE 2-38: INL vs. Code (code = 25 to 1000) and Temperature (MCP4716).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

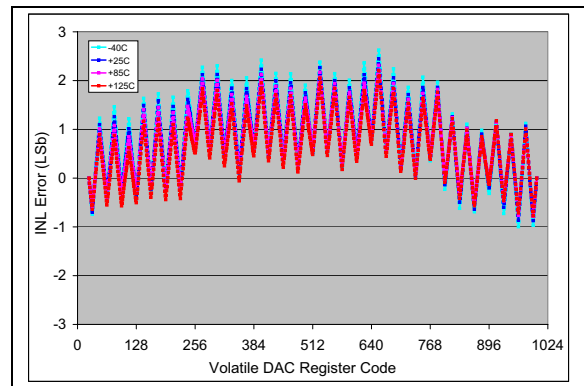


FIGURE 2-41: INL vs. Code (code = 25 to 1000) and Temperature (MCP4716).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

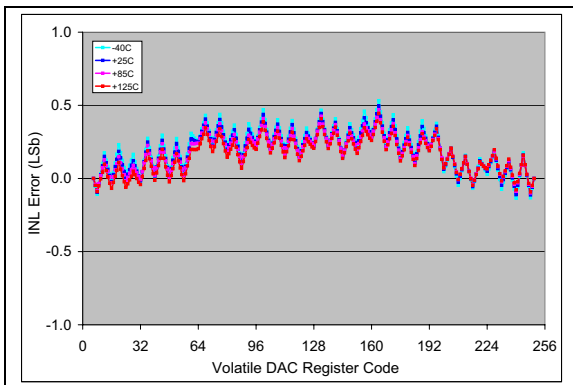


FIGURE 2-39: INL vs. Code (code = 6 to 250) and Temperature (MCP4706).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

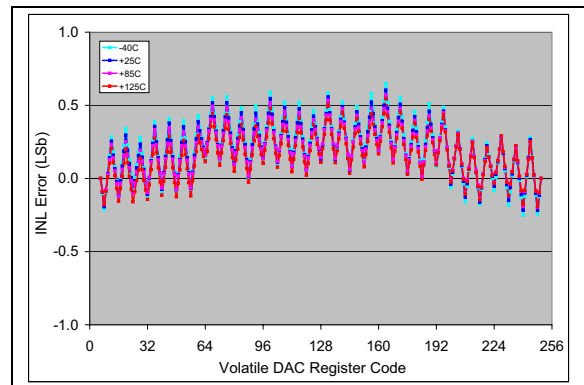


FIGURE 2-42: INL vs. Code (code = 6 to 250) and Temperature (MCP4706).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \text{x1}$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

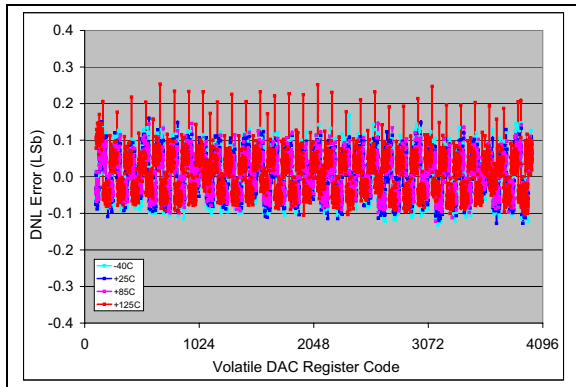


FIGURE 2-43: DNL vs. Code (code = 100 to 4000) and Temperature (MCP4726).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

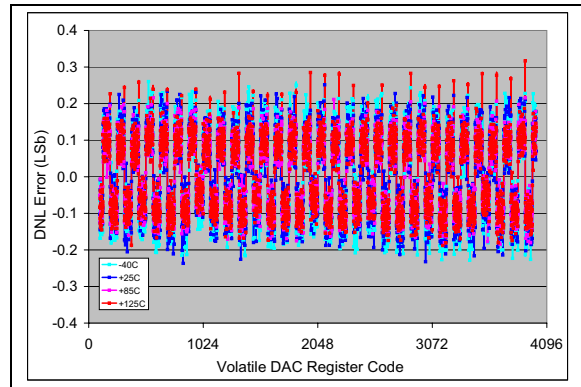


FIGURE 2-46: DNL vs. Code (code = 100 to 4000) and Temperature (MCP4726).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

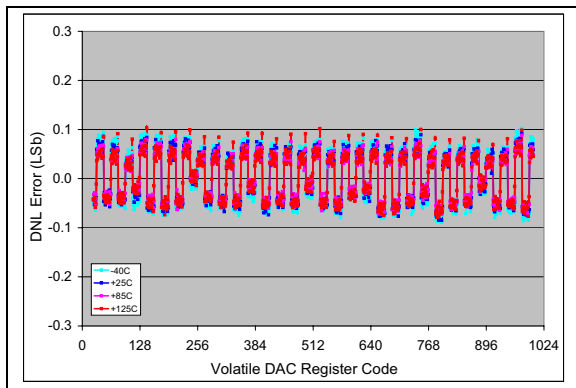


FIGURE 2-44: DNL vs. Code (code = 25 to 1000) and Temperature (MCP4716).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

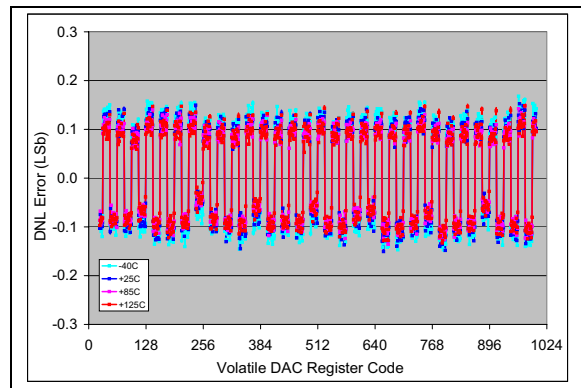


FIGURE 2-47: DNL vs. Code (code = 25 to 1000) and Temperature (MCP4716).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

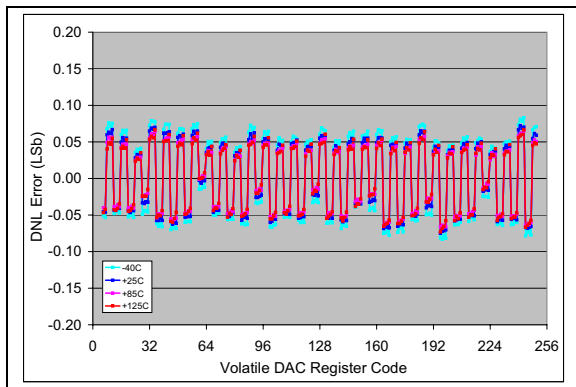


FIGURE 2-45: DNL vs. Code (code = 6 to 250) and Temperature (MCP4706).
 $V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

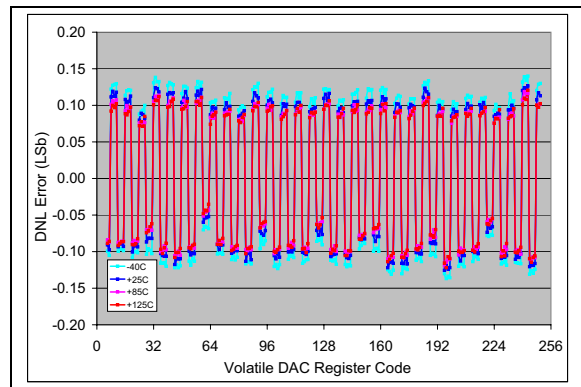


FIGURE 2-48: DNL vs. Code (code = 6 to 250) and Temperature (MCP4706).
 $V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

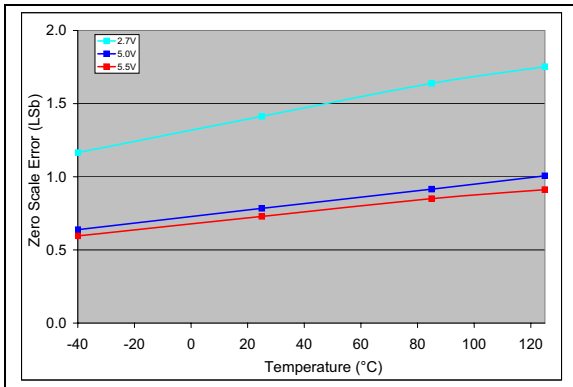


FIGURE 2-49: Zero-Scale Error (ZSE) vs. Temperature (MCP4726).

$V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

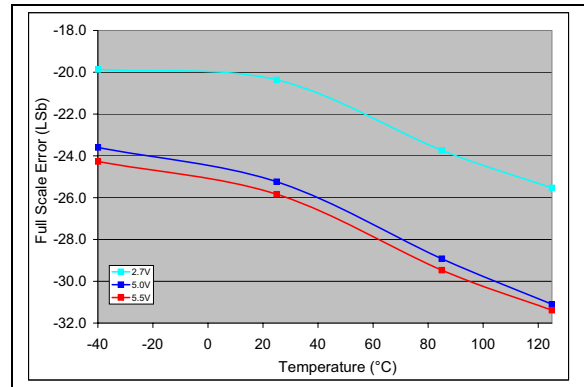


FIGURE 2-52: Full-Scale Error (FSE) vs. Temperature (MCP4726).

$V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

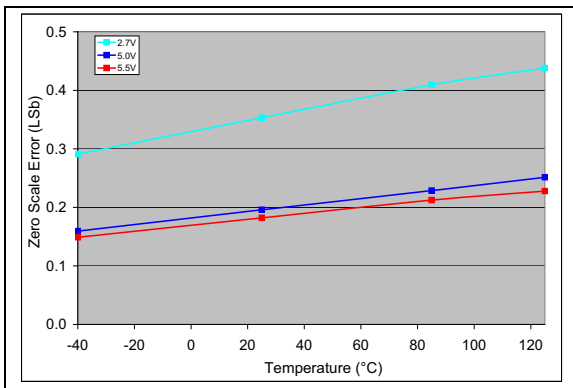


FIGURE 2-50: Zero-Scale Error (ZSE) vs. Temperature (MCP4716).

$V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

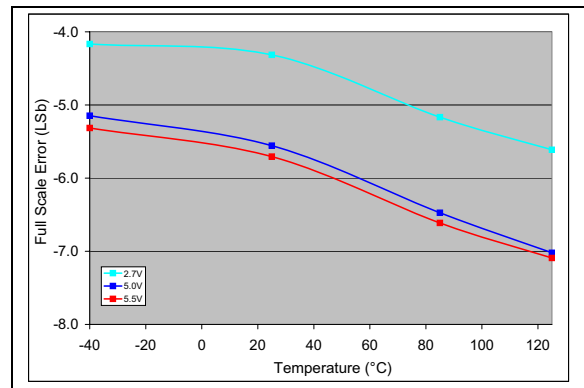


FIGURE 2-53: Full-Scale Error (FSE) vs. Temperature (MCP4716).

$V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

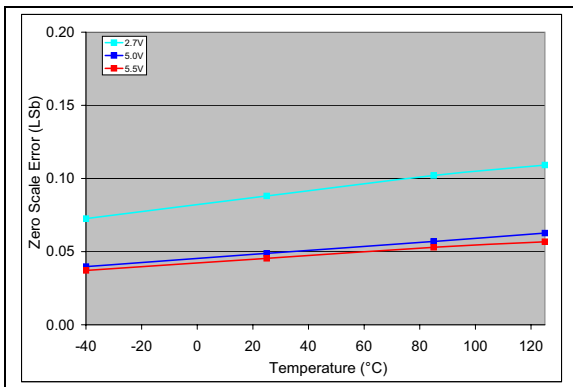


FIGURE 2-51: Zero-Scale Error (ZSE) vs. Temperature (MCP4706).

$V_{DD} = 5\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

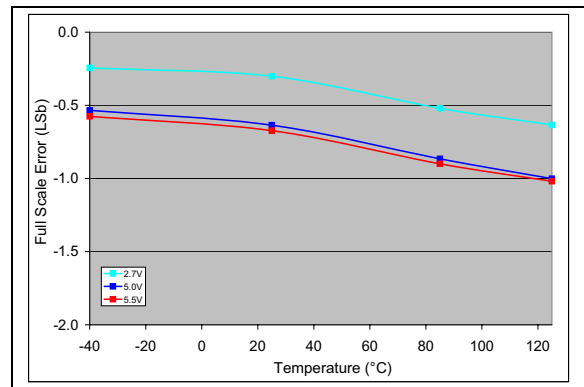


FIGURE 2-54: Full-Scale Error (FSE) vs. Temperature (MCP4706).

$V_{DD} = 2.7\text{V}$, $V_{REF1}:V_{REF0} = 11$, $G = 0$,
 $V_{REF} = V_{DD}$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

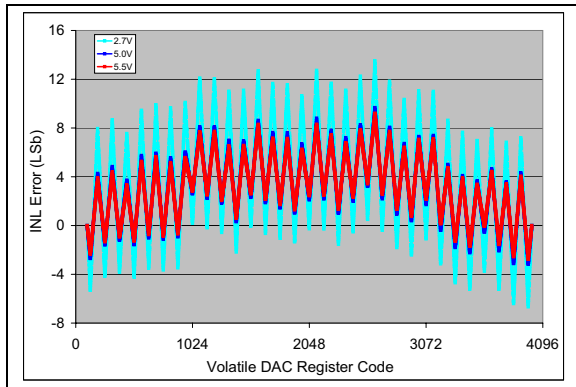


FIGURE 2-55: INL vs. Code (code = 100 to 4000) and V_{DD} (2.7V, 5V, 5.5V) (MCP4726).
 $V_{REF1}:V_{REF0} = 10$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

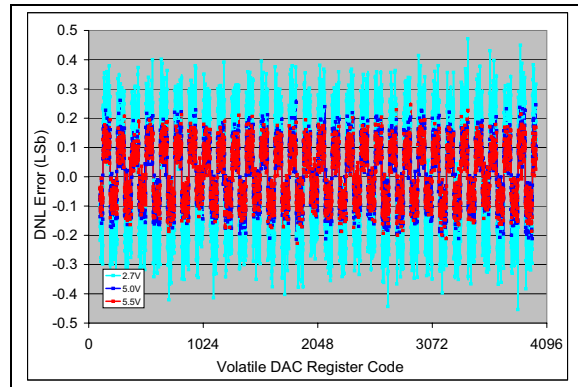


FIGURE 2-58: DNL vs. Code (code = 100 to 4000) and V_{DD} (2.7V, 5V, 5.5V) (MCP4726).
 $V_{REF1}:V_{REF0} = 10$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

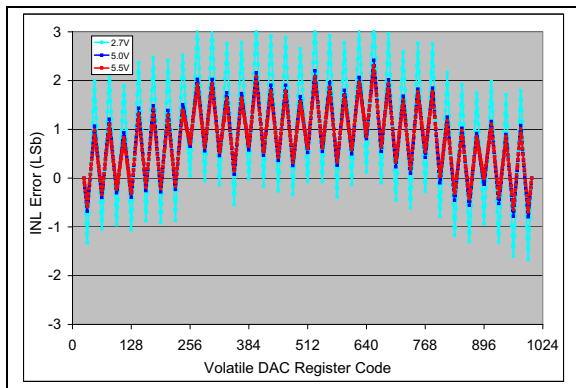


FIGURE 2-56: INL vs. Code (code = 25 to 1000) and V_{DD} (2.7V, 5V, 5.5V) (MCP4716).
 $V_{REF1}:V_{REF0} = 10$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

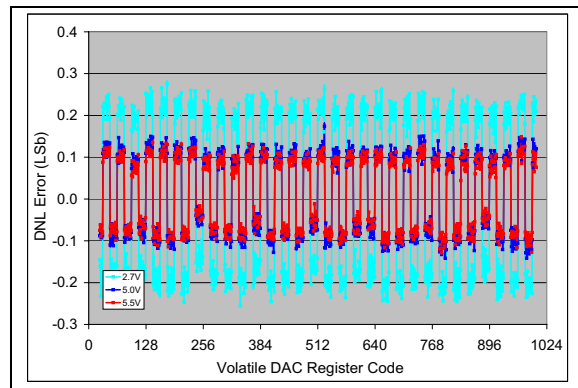


FIGURE 2-59: DNL vs. Code (code = 25 to 1000) and V_{DD} (2.7V, 5V, 5.5V) (MCP4716).
 $V_{REF1}:V_{REF0} = 10$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

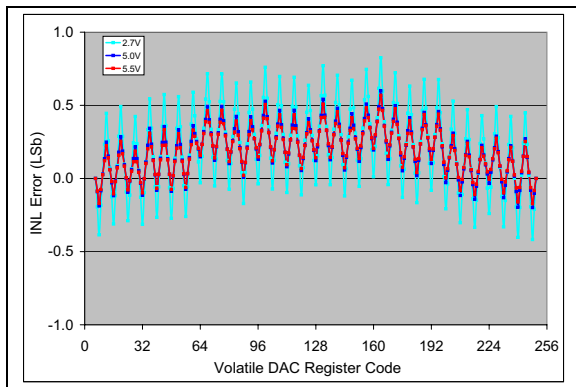


FIGURE 2-57: INL vs. Code (code = 6 to 250) and V_{DD} (2.7V, 5V, 5.5V) (MCP4706).
 $V_{REF1}:V_{REF0} = 10$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

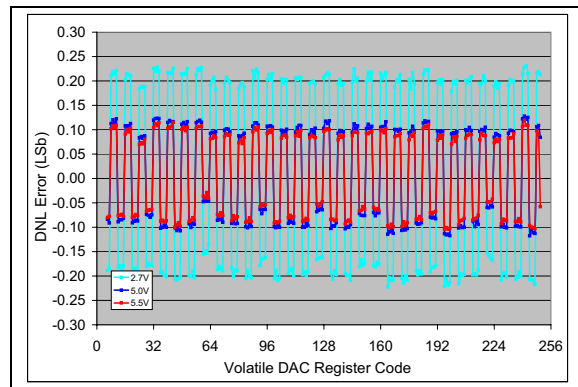


FIGURE 2-60: DNL vs. Code (code = 6 to 250) and V_{DD} (2.7V, 5V, 5.5V) (MCP4706).
 $V_{REF1}:V_{REF0} = 10$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

MCP4706/4716/4726

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = 5\text{V}$, $V_{SS} = 0\text{V}$, $V_{RL} = \text{Internal}$, $\text{Gain} = \times 1$, $R_L = 5\text{ k}\Omega$, $C_L = 100\text{ pF}$.

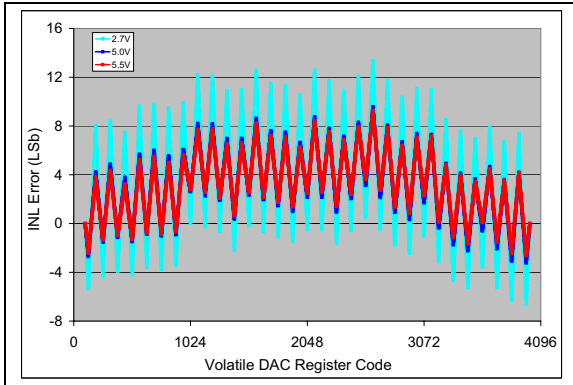


FIGURE 2-61: INL vs. Code (code = 100 to 4000) and V_{DD} (2.7V, 5V, 5.5V) (MCP4726).
 $V_{REF1}:V_{REF0} = 11$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

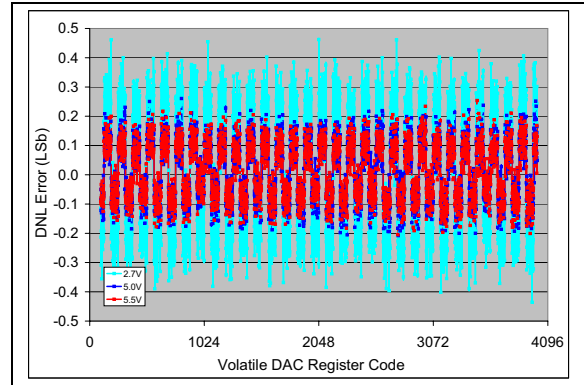


FIGURE 2-64: DNL vs. Code (code = 100 to 4000) and V_{DD} (2.7V, 5V, 5.5V) (MCP4726).
 $V_{REF1}:V_{REF0} = 11$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

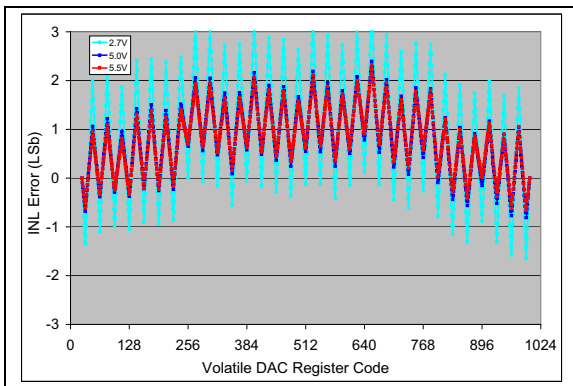


FIGURE 2-62: INL vs. Code (code = 25 to 1000) and V_{DD} (2.7V, 5V, 5.5V) (MCP4716).
 $V_{REF1}:V_{REF0} = 11$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

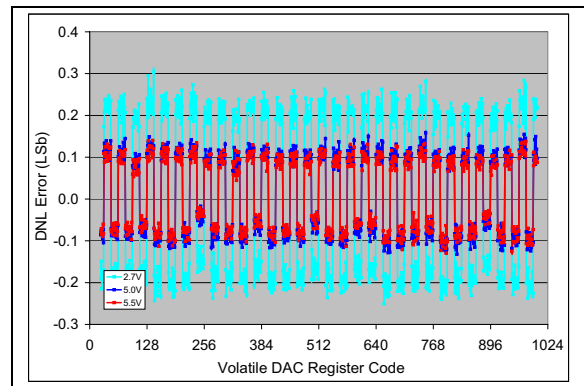


FIGURE 2-65: DNL vs. Code (code = 25 to 1000) and V_{DD} (2.7V, 5V, 5.5V) (MCP4716).
 $V_{REF1}:V_{REF0} = 11$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

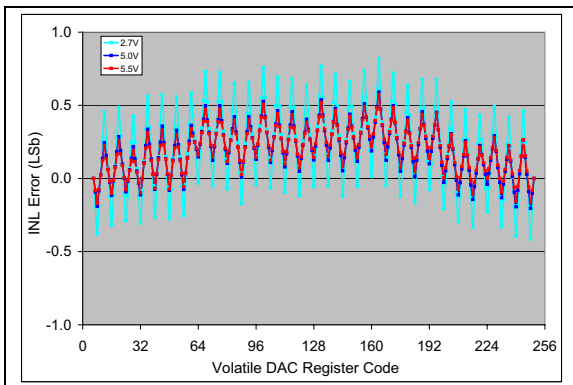


FIGURE 2-63: INL vs. Code (code = 6 to 250) and V_{DD} (2.7V, 5V, 5.5V) (MCP4706).
 $V_{REF1}:V_{REF0} = 11$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.

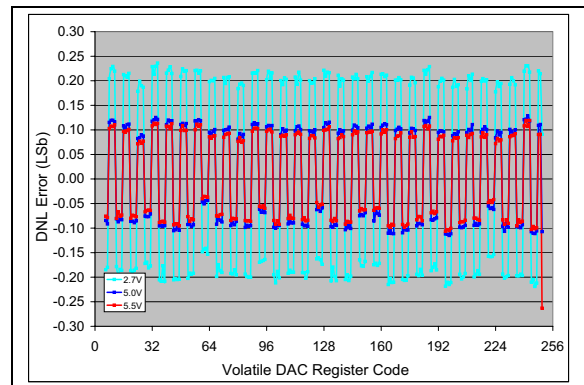


FIGURE 2-66: DNL vs. Code (code = 6 to 250) and V_{DD} (2.7V, 5V, 5.5V) (MCP4706).
 $V_{REF1}:V_{REF0} = 11$, $G = 1$, $V_{REF} = V_{DD}/2$,
 $\text{Temp} = +25^\circ\text{C}$.