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## 60 MHz, 32 V/ $\mu$ s Rail-to-Rail Output (RRO) Op Amps

### Features:

- Gain-Bandwidth Product: 60 MHz (typical)
- Slew Rate: 32 V/ $\mu$ s (typical)
- Noise: 6.8 nV/ $\sqrt$ Hz (typical, at 1 MHz)
- Short Circuit Current: 90 mA (typical)
- Low Input Bias Current: 4 pA (typical)
- Ease of Use:
  - Unity-Gain Stable
  - Rail-to-Rail Output
  - Input Range including Negative Rail
  - No Phase Reversal
- Supply Voltage Range: +2.5V to +5.5V
- High Output Current:  $\pm$ 70 mA
- Supply Current: 6.0 mA/ch (typical)
- Low-Power Mode: 1  $\mu$ A/ch
- Small Packages: SOT23-5, DFN
- Extended Temperature Range: -40°C to +125°C

### Typical Applications:

- Multi-Pole Active Filter
- Driving A/D Converters
- Power Amplifier Control Loops
- Line Driver
- Video Amplifier
- Barcode Scanners
- Optical Detector Amplifier

### Design Aids:

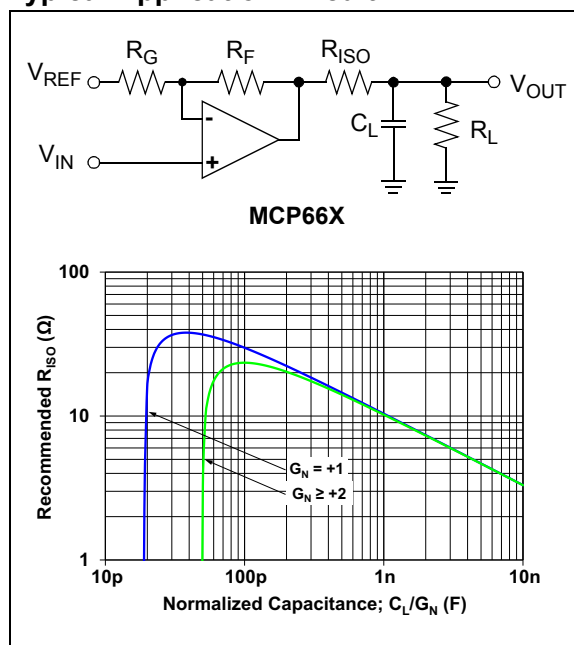
- SPICE Macro Models
- FilterLab<sup>®</sup> Software
- Microchip Advanced Part Selector (MAPS)
- Analog Demonstration and Evaluation Boards
  - MCP661DM-LD
- Application Notes

### Description:

The Microchip Technology Inc. MCP660/1/2/3/4/5/9 family of operational amplifiers (op amps) features high gain-bandwidth product and high slew rate. Some also provide a Chip Select pin ( $\overline{CS}$ ) that supports a low-power mode of operation. These amplifiers are optimized for high speed, low noise and distortion, single-supply operation with rail-to-rail output and an input that includes the negative rail.

This family is offered in single (MCP661), single with  $\overline{CS}$  pin (MCP663), dual (MCP662) and dual with two  $\overline{CS}$  pins (MCP665), triple (MCP660), quad (MCP664) and quad with two  $\overline{CS}$  pins (MCP669). All devices are fully specified from -40°C to +125°C.

### Typical Application Circuit

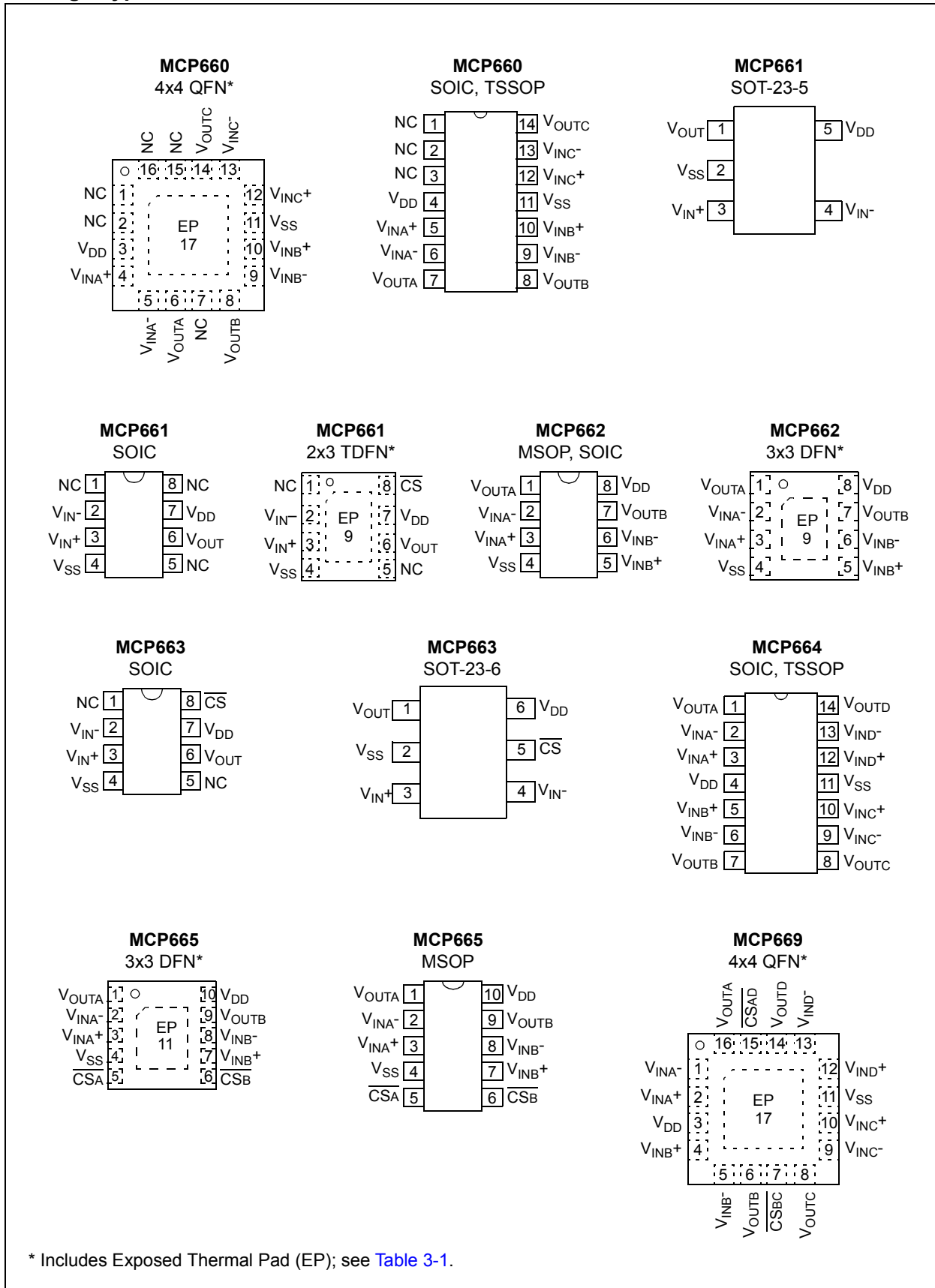


### High Gain-Bandwidth Op Amp Portfolio

Model Family	Channels/Package	Gain-Bandwidth	V <sub>OS</sub> (max.)	I <sub>Q</sub> /Ch (typ.)
<a href="#">MCP621/1S/2/3/4/5/9</a>	1, 2, 4	20 MHz	0.2 mV	2.5 mA
<a href="#">MCP631/2/3/4/5/9</a>	1, 2, 4	24 MHz	8.0 mV	2.5 mA
<a href="#">MCP651/1S/2/3/4/5/9</a>	1, 2, 4	50 MHz	0.2 mV	6.0 mA
<a href="#">MCP660/1/2/3/4/5/9</a>	1, 2, 3, 4	60 MHz	8.0 mV	6.0 mA

# MCP660/1/2/3/4/5/9

## Package Types



## 1.0 ELECTRICAL CHARACTERISTICS

### 1.1 Absolute Maximum Ratings †

$V_{DD} - V_{SS}$ .....	6.5V
Current at Input Pins .....	±2 mA
Analog Inputs ( $V_{IN+}$ and $V_{IN-}$ ) †† . $V_{SS} - 1.0V$ to $V_{DD} + 1.0V$	
All Other Inputs and Outputs .....	$V_{SS} - 0.3V$ to $V_{DD} + 0.3V$
Output Short Circuit Current .....	Continuous
Current at Output and Supply Pins .....	±150 mA
Storage Temperature .....	-65°C to +150°C
Maximum Junction Temperature .....	+150°C
ESD protection on all pins (HBM, MM) .....	≥ 1 kV, 200V

† **Notice:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

†† See **Section 4.1.2 “Input Voltage and Current Limits”**.

### 1.2 Specifications

#### DC ELECTRICAL SPECIFICATIONS

**Electrical Characteristics:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5V$  to  $+5.5V$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} \approx V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$  and  $\overline{CS} = V_{SS}$  (refer to [Figure 1-2](#)).

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Input Offset</b>						
Input Offset Voltage	$V_{OS}$	-8	±1.8	+8	mV	
Input Offset Voltage Drift	$\Delta V_{OS}/\Delta T_A$	—	±2.0	—	$\mu\text{V}/^\circ\text{C}$	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$
Power Supply Rejection Ratio	PSRR	61	76	—	dB	
<b>Input Current and Impedance</b>						
Input Bias Current	$I_B$	—	6	—	pA	
Across Temperature	$I_B$	—	130	—		$T_A = +85^\circ\text{C}$
Across Temperature	$I_B$	—	1700	5000		$T_A = +125^\circ\text{C}$
Input Offset Current	$I_{OS}$	—	±10	—	pA	
Common-Mode Input Impedance	$Z_{CM}$	—	$10^{13}  9$	—	$\Omega  \text{pF}$	
Differential Input Impedance	$Z_{DIFF}$	—	$10^{13}  2$	—	$\Omega  \text{pF}$	
<b>Common Mode</b>						
Common-Mode Input Voltage Range	$V_{CMR}$	$V_{SS} - 0.3$	—	$V_{DD} - 1.3$	V	<a href="#">Note 1</a>
Common-Mode Rejection Ratio	CMRR	64	79	—	dB	$V_{DD} = 2.5V$ , $V_{CM} = -0.3V$ to $1.2V$
		66	81	—	dB	$V_{DD} = 5.5V$ , $V_{CM} = -0.3V$ to $4.2V$
<b>Open-Loop Gain</b>						
DC Open-Loop Gain (large signal)	$A_{OL}$	88	117	—	dB	$V_{DD} = 2.5V$ , $V_{OUT} = 0.3V$ to $2.2V$
		94	126	—	dB	$V_{DD} = 5.5V$ , $V_{OUT} = 0.3V$ to $5.2V$
<b>Output</b>						
Maximum Output Voltage Swing	$V_{OL}$ , $V_{OH}$	$V_{SS} + 25$	—	$V_{DD} - 25$	mV	$V_{DD} = 2.5V$ , $G = +2$ , $0.5V$ Input Overdrive
		$V_{SS} + 50$	—	$V_{DD} - 50$		$V_{DD} = 5.5V$ , $G = +2$ , $0.5V$ Input Overdrive
Output Short-Circuit Current	$I_{SC}$	±45	±90	±145	mA	$V_{DD} = 2.5V$ ( <a href="#">Note 2</a> )
		±40	±80	±150		$V_{DD} = 5.5V$ ( <a href="#">Note 2</a> )

**Note 1:** See [Figure 2-5](#) for temperature effects.

**2:** The  $I_{SC}$  specifications are for design guidance only; they are not tested.

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## DC ELECTRICAL SPECIFICATIONS (CONTINUED)

**Electrical Characteristics:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $+5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} \approx V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$  and  $\overline{\text{CS}} = V_{SS}$  (refer to Figure 1-2).

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Power Supply</b>						
Supply Voltage	$V_{DD}$	2.5	—	5.5	V	
Quiescent Current per Amplifier	$I_Q$	3	6	9	mA	No Load Current

**Note 1:** See Figure 2-5 for temperature effects.

**2:** The  $I_{SC}$  specifications are for design guidance only; they are not tested.

## AC ELECTRICAL SPECIFICATIONS

**Electrical Characteristics:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $+5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/2$ ,  $V_{OUT} \approx V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{\text{CS}} = V_{SS}$  (refer to Figure 1-2).

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>AC Response</b>						
Gain-Bandwidth Product	GBWP	—	60	—	MHz	
Phase Margin	PM	—	65	—	$^\circ$	$G = +1$
Open-Loop Output Impedance	$R_{OUT}$	—	10	—	$\Omega$	
<b>AC Distortion</b>						
Total Harmonic Distortion plus Noise	THD + N	—	0.003	—	%	$G = +1$ , $V_{OUT} = 2V_{P-P}$ , $f = 1\text{ kHz}$ , $V_{DD} = 5.5\text{V}$ , $\text{BW} = 80\text{ kHz}$
Differential Gain, Positive Video (Note 1)	DG	—	0.3	—	%	NTSC, $V_{DD} = +2.5\text{V}$ , $V_{SS} = -2.5\text{V}$ , $G = +2$ , $V_L = 0\text{V}$ , DC $V_{IN} = 0\text{V}$ to $0.7\text{V}$
Differential Gain, Negative Video (Note 1)	DG	—	0.3	—	%	NTSC, $V_{DD} = +2.5\text{V}$ , $V_{SS} = -2.5\text{V}$ , $G = +2$ , $V_L = 0\text{V}$ , DC $V_{IN} = 0\text{V}$ to $-0.7\text{V}$
Differential Phase, Positive Video (Note 1)	DP	—	0.3	—	$^\circ$	NTSC, $V_{DD} = +2.5\text{V}$ , $V_{SS} = -2.5\text{V}$ , $G = +2$ , $V_L = 0\text{V}$ , DC $V_{IN} = 0\text{V}$ to $0.7\text{V}$
Differential Phase, Negative Video (Note 1)	DP	—	0.9	—	$^\circ$	NTSC, $V_{DD} = +2.5\text{V}$ , $V_{SS} = -2.5\text{V}$ , $G = +2$ , $V_L = 0\text{V}$ , DC $V_{IN} = 0\text{V}$ to $-0.7\text{V}$
<b>Step Response</b>						
Rise Time, 10% to 90%	$t_r$	—	5	—	ns	$G = +1$ , $V_{OUT} = 100\text{ mV}_{P-P}$
Slew Rate	SR	—	32	—	V/ $\mu\text{s}$	$G = +1$
<b>Noise</b>						
Input Noise Voltage	$E_{ni}$	—	14	—	$\mu\text{V}_{P-P}$	$f = 0.1\text{ Hz}$ to $10\text{ Hz}$
Input Noise Voltage Density	$e_{ni}$	—	6.8	—	nV/ $\sqrt{\text{Hz}}$	$f = 1\text{ MHz}$
Input Noise Current Density	$i_{ni}$	—	4	—	fA/ $\sqrt{\text{Hz}}$	$f = 1\text{ kHz}$

**Note 1:** These specifications are described in detail in Section 4.3 “Distortion”. (NTSC refers to a National Television Standards Committee signal.)

## DIGITAL ELECTRICAL SPECIFICATIONS

**Electrical Characteristics:** Unless indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V to } +5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/2$ ,  $V_{OUT} \approx V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{\text{CS}} = V_{SS}$  (refer to [Figures 1-1](#) and [2-1](#)).

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b><math>\overline{\text{CS}}</math> Low Specifications</b>						
$\overline{\text{CS}}$ Logic Threshold, Low	$V_{IL}$	$V_{SS}$	—	$0.2V_{DD}$	V	
$\overline{\text{CS}}$ Input Current, Low	$I_{CSL}$	—	-0.1	—	nA	$\overline{\text{CS}} = 0\text{V}$
<b><math>\overline{\text{CS}}</math> High Specifications</b>						
$\overline{\text{CS}}$ Logic Threshold, High	$V_{IH}$	$0.8V_{DD}$	—	$V_{DD}$	V	
$\overline{\text{CS}}$ Input Current, High	$I_{CSH}$	—	-0.7	—	$\mu\text{A}$	$\overline{\text{CS}} = V_{DD}$
GND Current	$I_{SS}$	-2	-1	—	$\mu\text{A}$	
$\overline{\text{CS}}$ Internal Pull-Down Resistor	$R_{PD}$	—	5	—	$\text{M}\Omega$	
Amplifier Output Leakage	$I_{O(\text{LEAK})}$	—	40	—	nA	$\overline{\text{CS}} = V_{DD}$ , $T_A = +125^\circ\text{C}$
<b><math>\overline{\text{CS}}</math> Dynamic Specifications</b>						
$\overline{\text{CS}}$ Input Hysteresis	$V_{HYST}$	—	0.25	—	V	
$\overline{\text{CS}}$ High to Amplifier Off Time (output goes High Z)	$t_{OFF}$	—	200	—	ns	$G = +1\text{ V/V}$ , $V_L = V_{SS}$ $\overline{\text{CS}} = 0.8V_{DD}$ to $V_{OUT} = 0.1(V_{DD}/2)$
$\overline{\text{CS}}$ Low to Amplifier On Time	$t_{ON}$	—	2	10	$\mu\text{s}$	$G = +1\text{ V/V}$ , $V_L = V_{SS}$ $\overline{\text{CS}} = 0.2V_{DD}$ to $V_{OUT} = 0.9(V_{DD}/2)$

## TEMPERATURE SPECIFICATIONS

**Electrical Characteristics:** Unless otherwise indicated, all limits are specified for  $V_{DD} = +2.5\text{V to } +5.5\text{V}$ ,  $V_{SS} = \text{GND}$ .

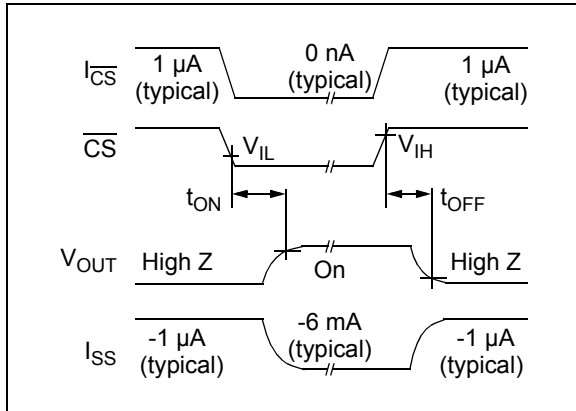
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Temperature Ranges</b>						
Specified Temperature Range	$T_A$	-40	—	+125	$^\circ\text{C}$	
Operating Temperature Range	$T_A$	-40	—	+125	$^\circ\text{C}$	<a href="#">Note 1</a>
Storage Temperature Range	$T_A$	-65	—	+150	$^\circ\text{C}$	
<b>Thermal Package Resistances</b>						
Thermal Resistance, 5L-SOT-23	$\theta_{JA}$	—	201.0	—	$^\circ\text{C/W}$	
Thermal Resistance, 6L-SOT-23	$\theta_{JA}$	—	190.5	—	$^\circ\text{C/W}$	
Thermal Resistance, 8L-3x3 DFN	$\theta_{JA}$	—	56.7	—	$^\circ\text{C/W}$	<a href="#">Note 2</a>
Thermal Resistance, 8L-MSOP	$\theta_{JA}$	—	211	—	$^\circ\text{C/W}$	
Thermal Resistance, 8L-SOIC	$\theta_{JA}$	—	149.5	—	$^\circ\text{C/W}$	
Thermal Resistance, 8L-2x3 TDFN	$\theta_{JA}$	—	52.5	—	$^\circ\text{C/W}$	
Thermal Resistance, 10L-3x3 DFN	$\theta_{JA}$	—	54.0	—	$^\circ\text{C/W}$	<a href="#">Note 2</a>
Thermal Resistance, 10L-MSOP	$\theta_{JA}$	—	202	—	$^\circ\text{C/W}$	
Thermal Resistance, 14L-SOIC	$\theta_{JA}$	—	90.8	—	$^\circ\text{C/W}$	
Thermal Resistance, 14L-TSSOP	$\theta_{JA}$	—	100	—	$^\circ\text{C/W}$	
Thermal Resistance, 16L-QFN	$\theta_{JA}$	—	52.1	—	$^\circ\text{C/W}$	

**Note 1:** Operation must not cause  $T_J$  to exceed the Maximum Junction Temperature specification ( $+150^\circ\text{C}$ ).

**2:** Measured on a standard JC51-7, four-layer printed circuit board with ground plane and vias.

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## 1.3 Timing Diagram



**FIGURE 1-1:** Timing Diagram.

## 1.4 Test Circuits

The circuit used for most DC and AC tests is shown in [Figure 1-2](#). This circuit can independently set  $V_{CM}$  and  $V_{OUT}$ ; see [Equation 1-1](#). Note that  $V_{CM}$  is not the circuit's common-mode voltage ( $(V_P + V_M)/2$ ) and that  $V_{OST}$  includes  $V_{OS}$  plus the effects (on the input offset error,  $V_{OST}$ ) of temperature, CMRR, PSRR and  $A_{OL}$ .

### EQUATION 1-1:

$$G_{DM} = \frac{R_F}{R_G}$$

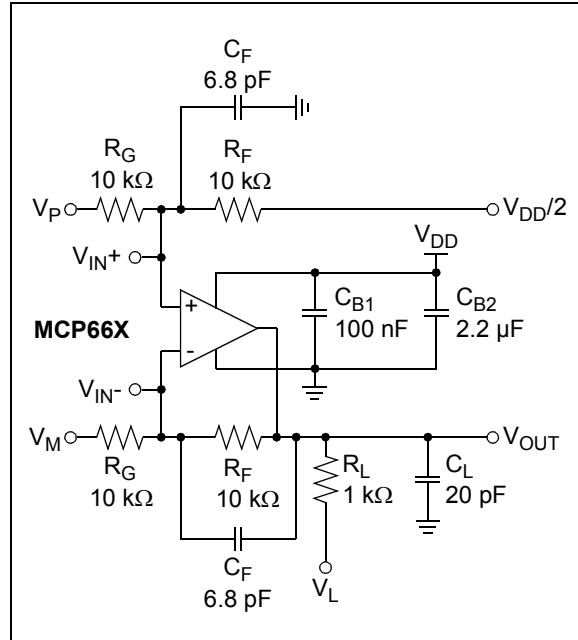
$$V_{CM} = \frac{V_P + \frac{V_{DD}}{2}}{2}$$

$$V_{OST} = V_{IN-} - V_{IN+}$$

$$V_{OUT} = \frac{V_{DD}}{2} + (V_P - V_M) + V_{OST}(1 + G_{DM})$$

Where:

- $G_{DM}$  = Differential Mode Gain (V/V)
- $V_{CM}$  = Op Amp's Common-Mode Input Voltage (V)
- $V_{OST}$  = Op Amp's Total Input Offset Voltage (mV)



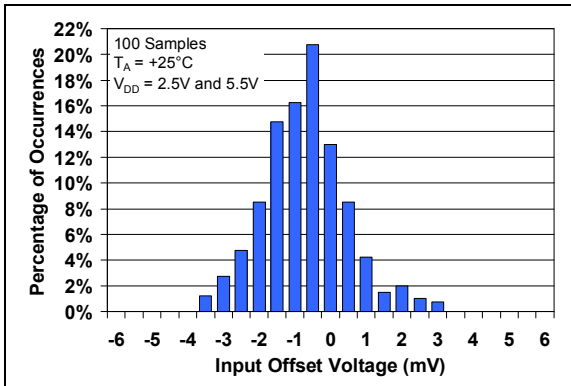
**FIGURE 1-2:** AC and DC Test Circuit for Most Specifications.

## 2.0 TYPICAL PERFORMANCE CURVES

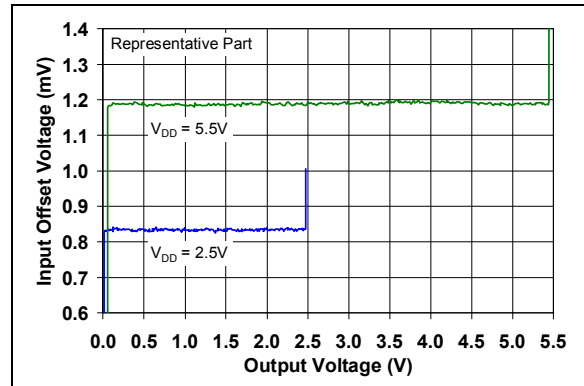
**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{CS} = V_{SS}$ .

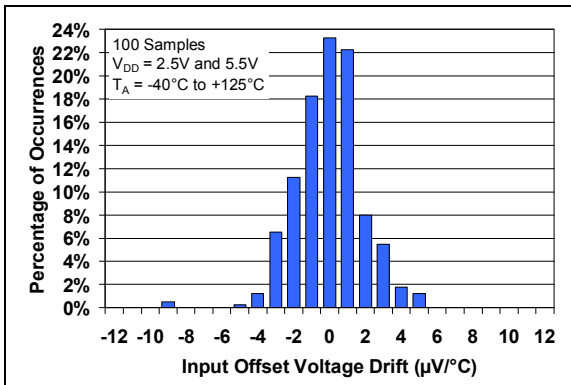
### 2.1 DC Signal Inputs



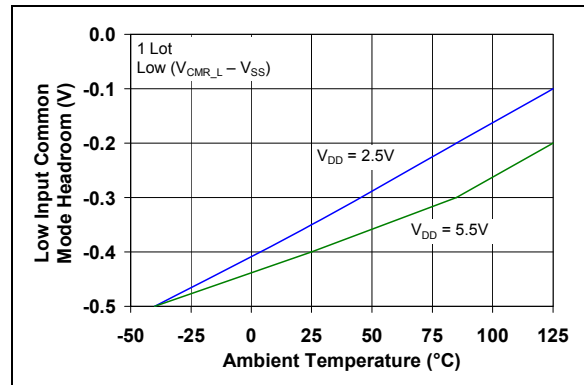
**FIGURE 2-1:** Input Offset Voltage.



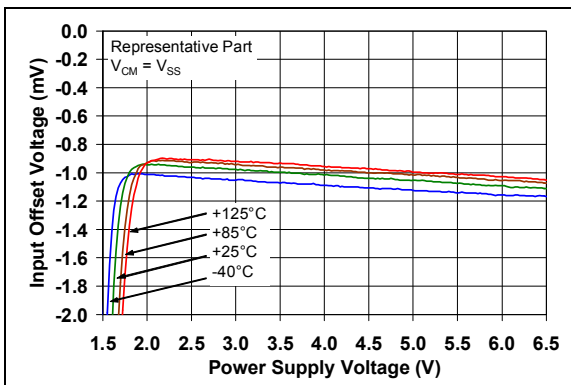
**FIGURE 2-4:** Input Offset Voltage vs. Output Voltage.



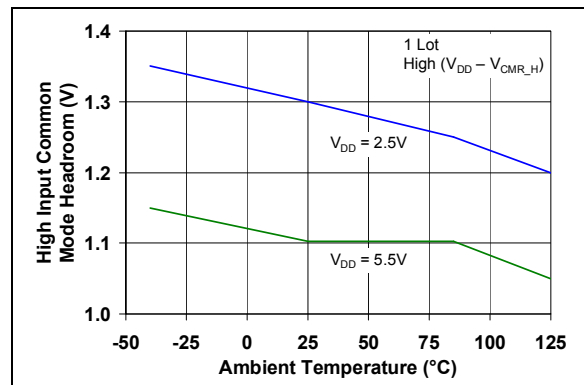
**FIGURE 2-2:** Input Offset Voltage Drift.



**FIGURE 2-5:** Low-Input Common-Mode Voltage Headroom vs. Ambient Temperature.



**FIGURE 2-3:** Input Offset Voltage vs. Power Supply Voltage with  $V_{CM} = 0\text{V}$ .

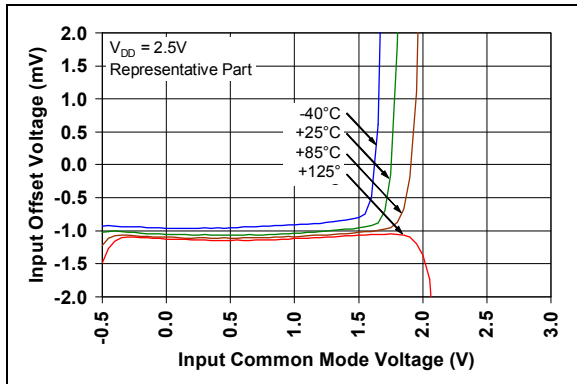


**FIGURE 2-6:** High-Input Common-Mode Voltage Headroom vs. Ambient Temperature.

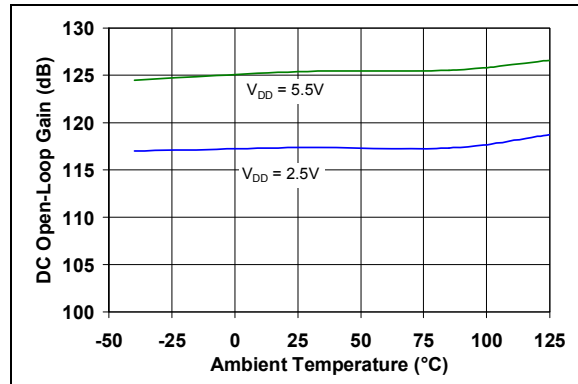


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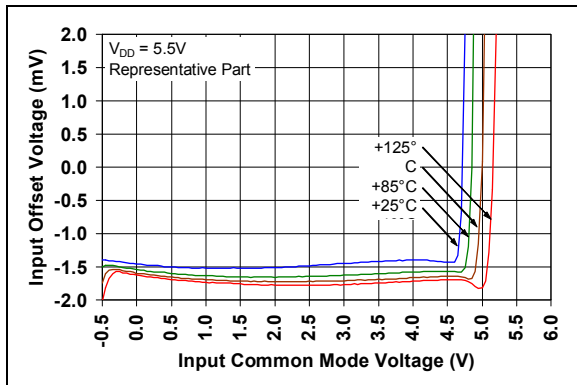
**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $CS = V_{SS}$ .



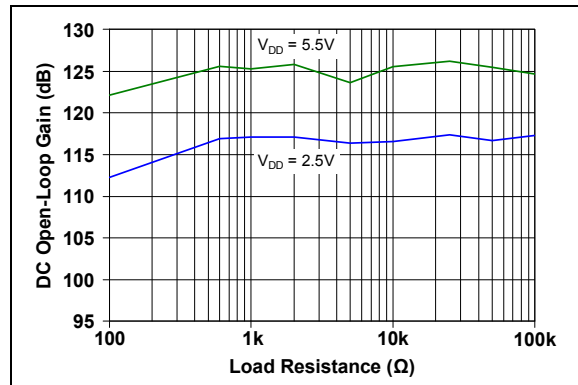
**FIGURE 2-7:** Input Offset Voltage vs. Common-Mode Voltage with  $V_{DD} = 2.5\text{V}$ .



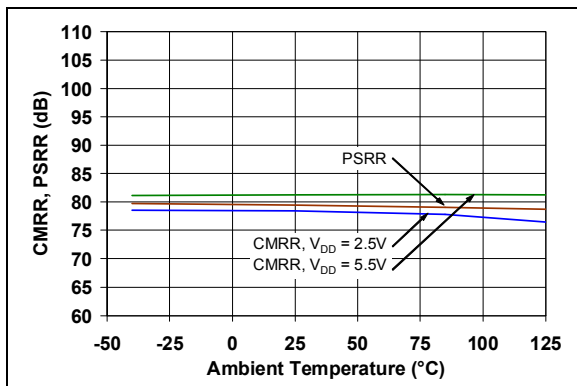
**FIGURE 2-10:** DC Open-Loop Gain vs. Ambient Temperature.



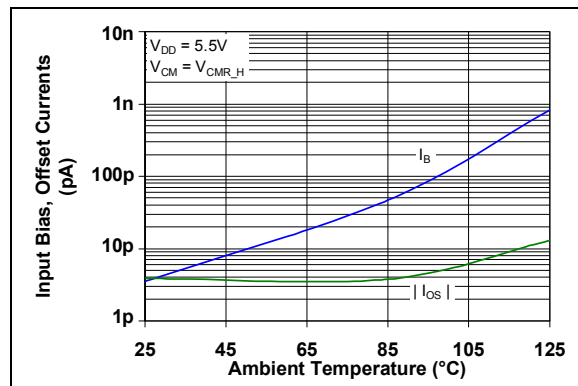
**FIGURE 2-8:** Input Offset Voltage vs. Common-Mode Voltage with  $V_{DD} = 5.5\text{V}$ .



**FIGURE 2-11:** DC Open-Loop Gain vs. Load Resistance.

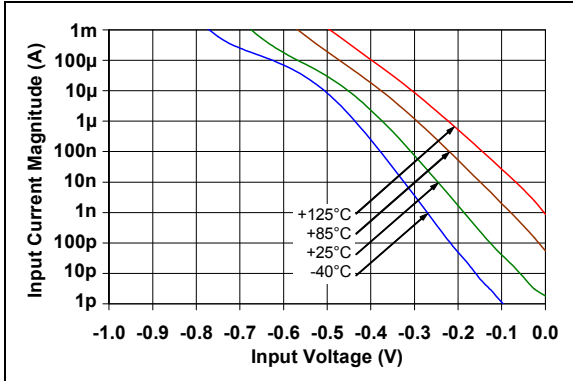


**FIGURE 2-9:** CMRR and PSRR vs. Ambient Temperature.

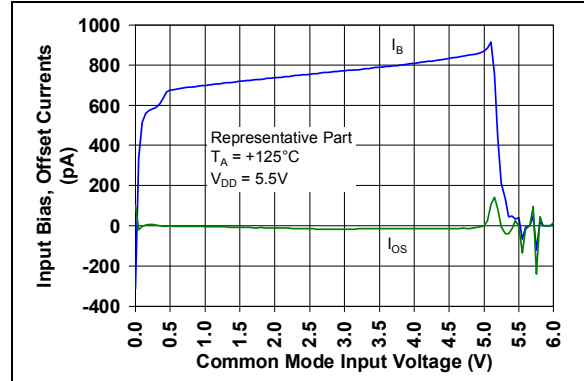


**FIGURE 2-12:** Input Bias and Offset Currents vs. Ambient Temperature with  $V_{DD} = 5.5\text{V}$ .

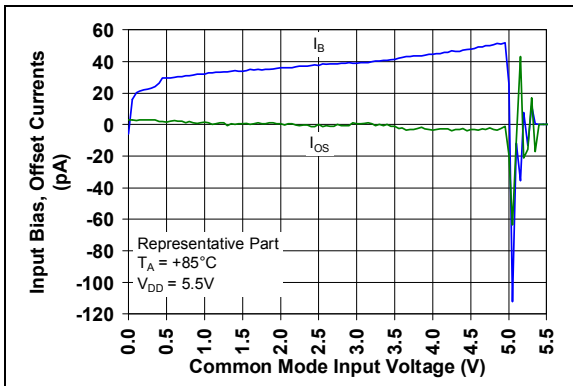
**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{CS} = V_{SS}$ .



**FIGURE 2-13:** Input Bias Current vs. Input Voltage (below  $V_{SS}$ ).



**FIGURE 2-15:** Input Bias and Offset Currents vs. Common-Mode Input Voltage with  $T_A = +125^\circ\text{C}$ .

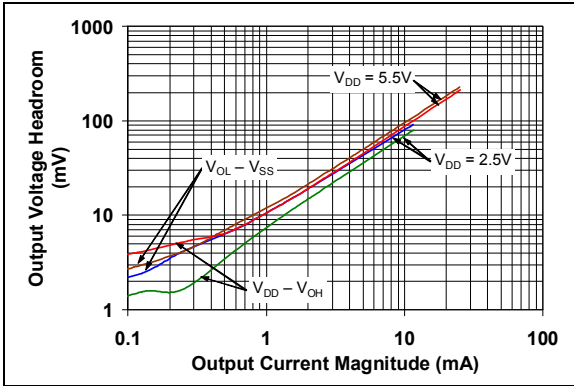


**FIGURE 2-14:** Input Bias and Offset Currents vs. Common-Mode Input Voltage with  $T_A = +85^\circ\text{C}$ .

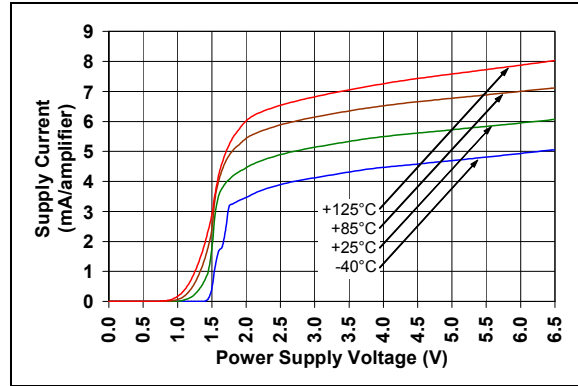
# MCP660/1/2/3/4/5/9

Note: Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{\text{CS}} = V_{SS}$ .

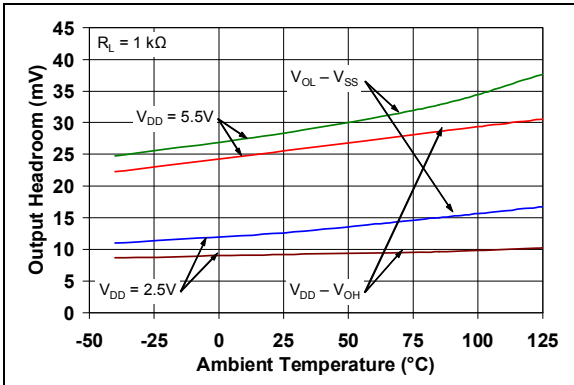
## 2.2 Other DC Voltages and Currents



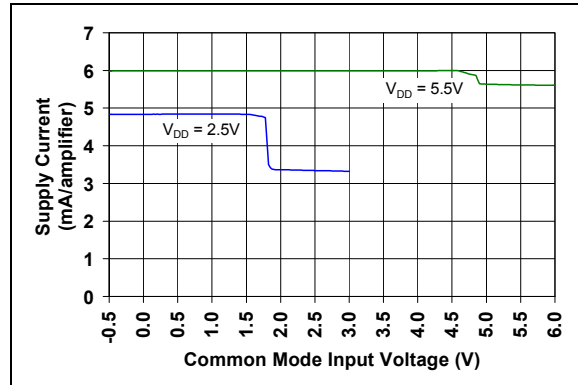
**FIGURE 2-16:** Output Voltage Headroom vs. Output Current.



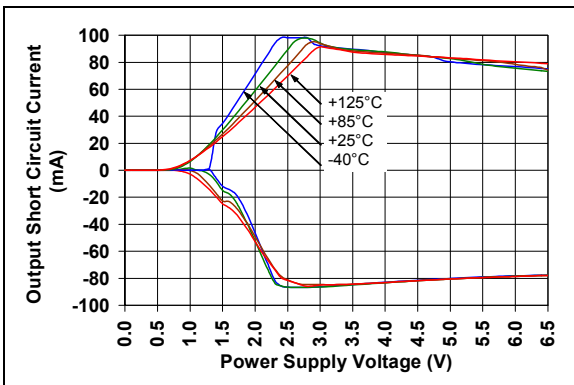
**FIGURE 2-19:** Supply Current vs. Power Supply Voltage.



**FIGURE 2-17:** Output Voltage Headroom vs. Ambient Temperature.



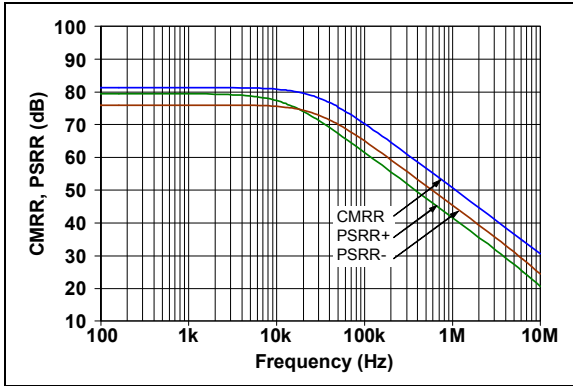
**FIGURE 2-20:** Supply Current vs. Common-Mode Input Voltage.



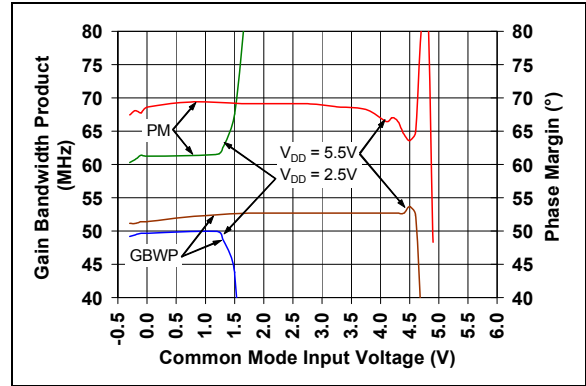
**FIGURE 2-18:** Output Short Circuit Current vs. Power Supply Voltage.

**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{CS} = V_{SS}$ .

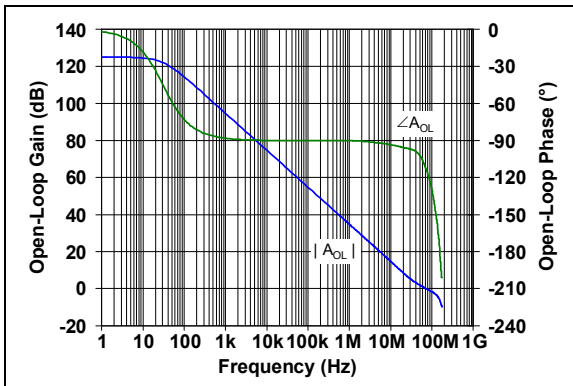
## 2.3 Frequency Response



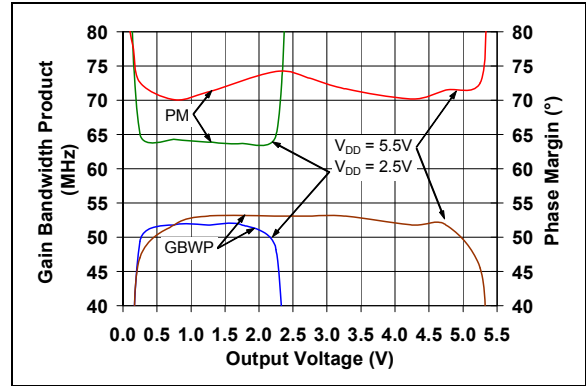
**FIGURE 2-21:** CMRR and PSRR vs. Frequency.



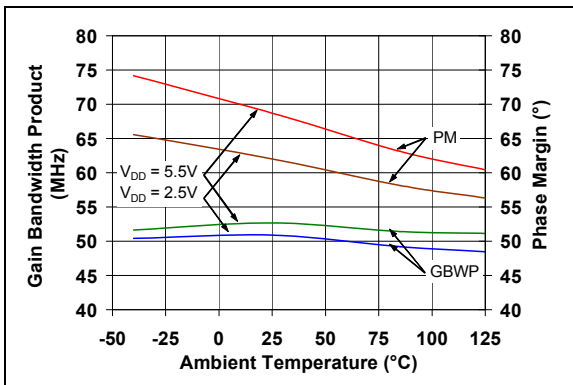
**FIGURE 2-24:** Gain-Bandwidth Product and Phase Margin vs. Common-Mode Input Voltage.



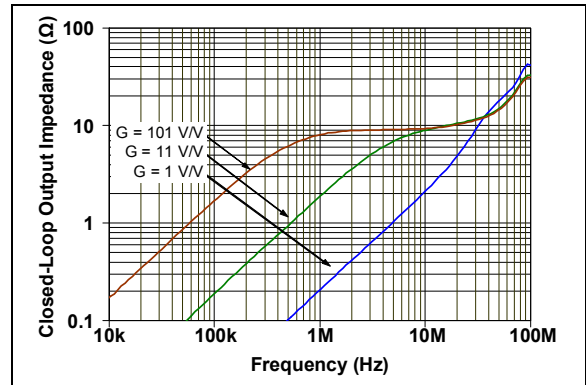
**FIGURE 2-22:** Open-Loop Gain vs. Frequency.



**FIGURE 2-25:** Gain-Bandwidth Product and Phase Margin vs. Output Voltage.



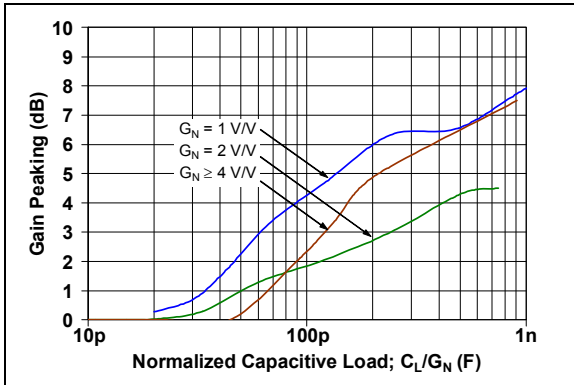
**FIGURE 2-23:** Gain-Bandwidth Product and Phase Margin vs. Ambient Temperature.



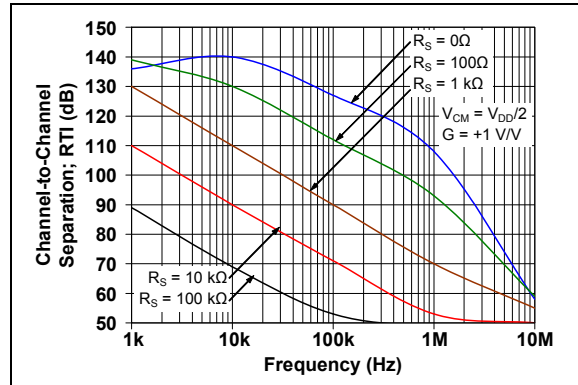
**FIGURE 2-26:** Closed-Loop Output Impedance vs. Frequency.

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**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{CS} = V_{SS}$ .



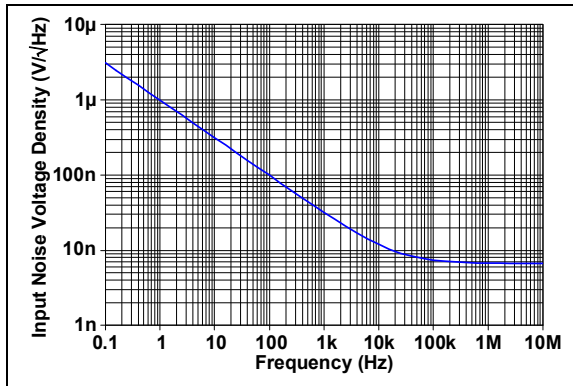
**FIGURE 2-27:** Gain Peaking vs. Normalized Capacitive Load.



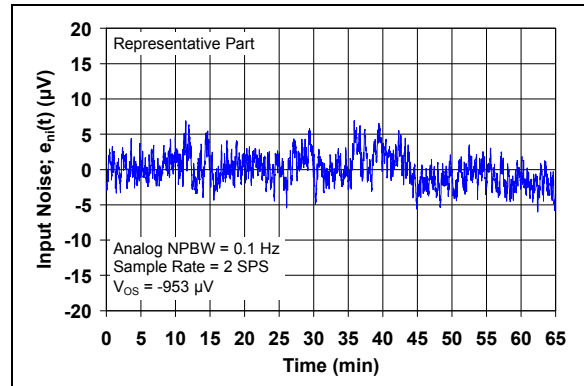
**FIGURE 2-28:** Channel-to-Channel Separation vs. Frequency.

**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $CS = V_{SS}$ .

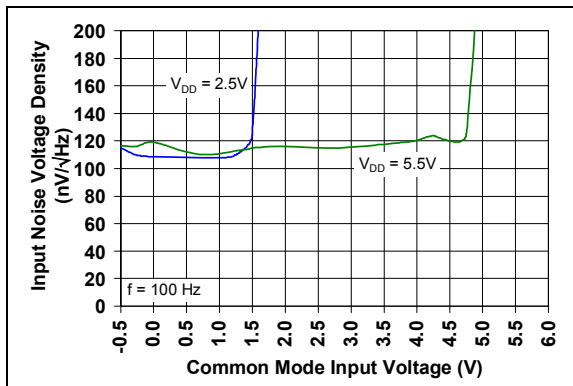
## 2.4 Noise and Distortion



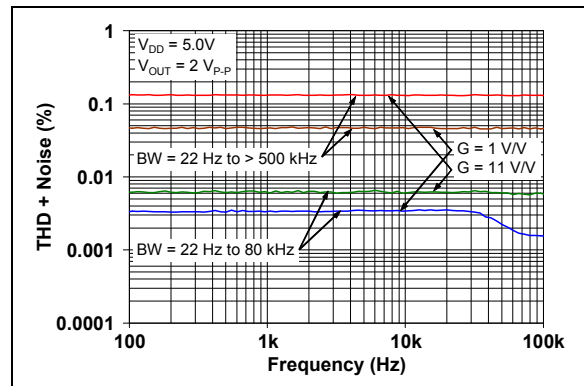
**FIGURE 2-29:** Input Noise Voltage Density vs. Frequency.



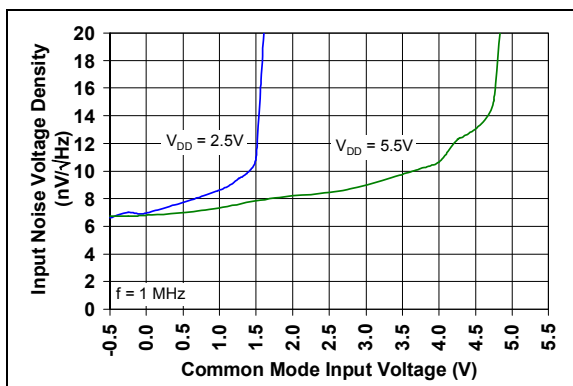
**FIGURE 2-32:** Input Noise vs. Time with 0.1 Hz Filter.



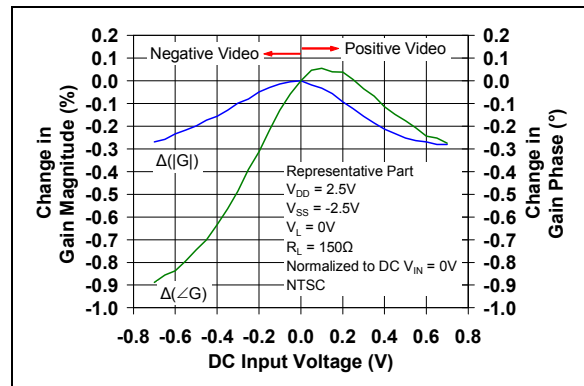
**FIGURE 2-30:** Input Noise Voltage Density vs. Input Common-Mode Voltage with  $f = 100\text{ Hz}$ .



**FIGURE 2-33:** THD+N vs. Frequency.



**FIGURE 2-31:** Input Noise Voltage Density vs. Input Common-Mode Voltage with  $f = 1\text{ MHz}$ .

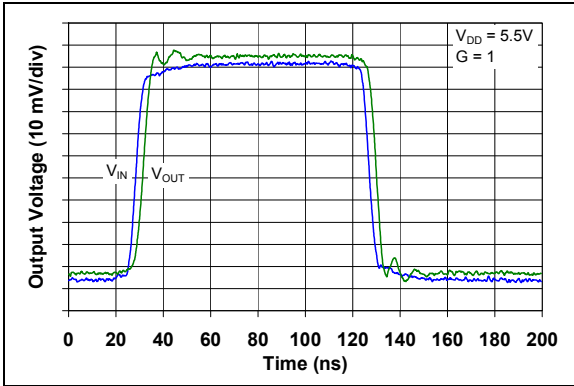


**FIGURE 2-34:** Change in Gain Magnitude and Phase vs. DC Input Voltage.

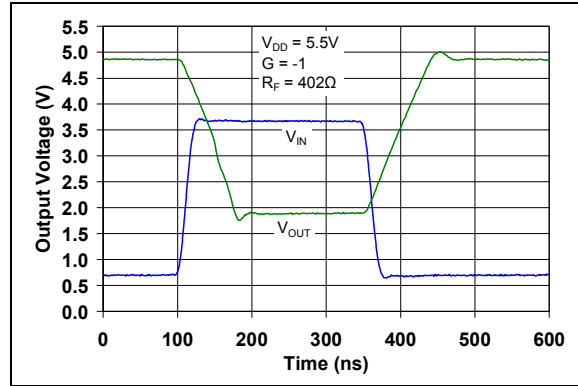
# MCP660/1/2/3/4/5/9

Note: Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{\text{CS}} = V_{SS}$ .

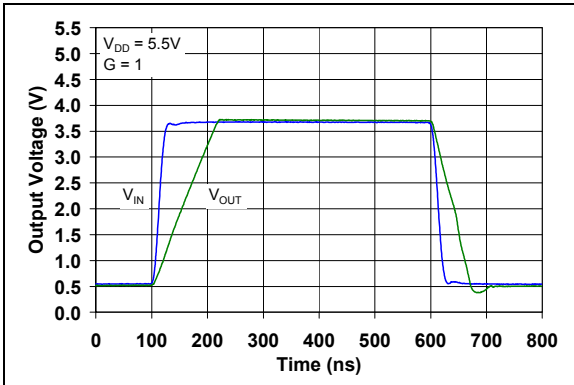
## 2.5 Time Response



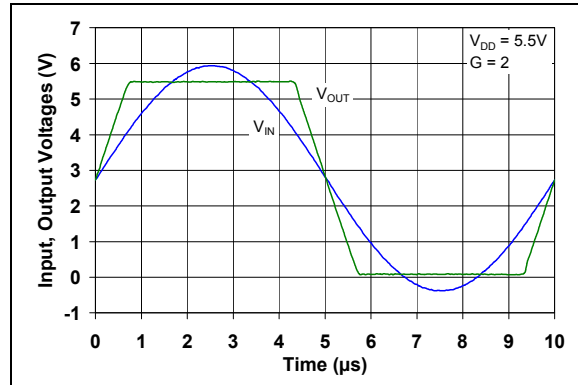
**FIGURE 2-35:** Non-Inverting Small Signal Step Response.



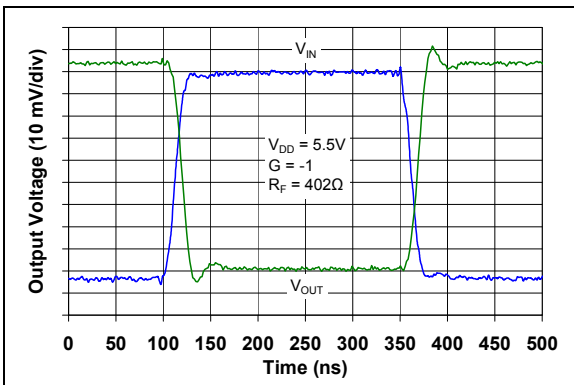
**FIGURE 2-38:** Inverting Large Signal Step Response.



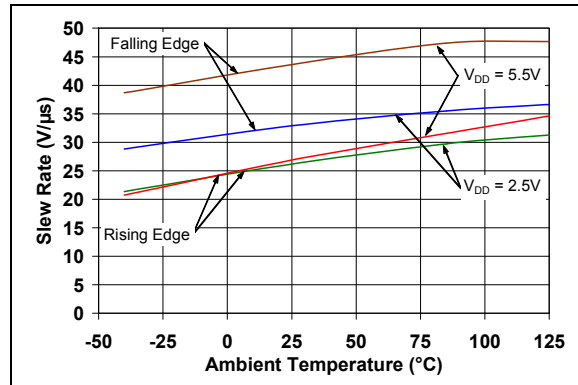
**FIGURE 2-36:** Non-Inverting Large Signal Step Response.



**FIGURE 2-39:** The MCP660/1/2/3/4/5/9 Family Shows No Input Phase Reversal with Overdrive.

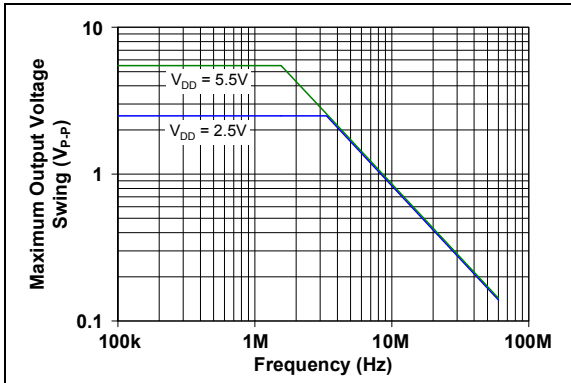


**FIGURE 2-37:** Inverting Small Signal Step Response.



**FIGURE 2-40:** Slew Rate vs. Ambient Temperature.

**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{CS} = V_{SS}$ .



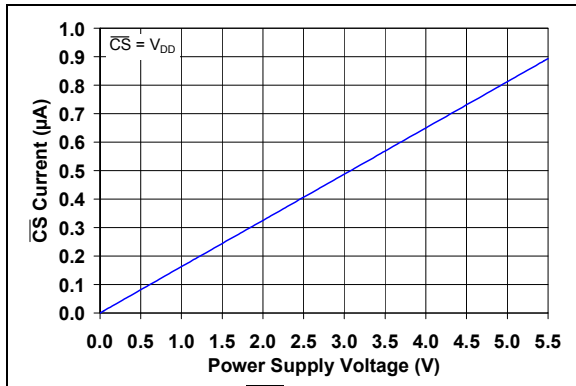
**FIGURE 2-41:** Maximum Output Voltage Swing vs. Frequency.



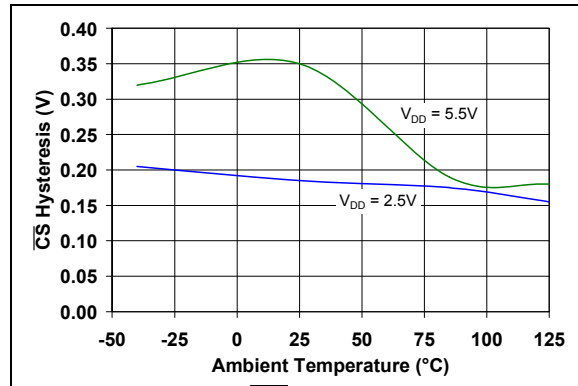
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**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{\text{CS}} = V_{SS}$ .

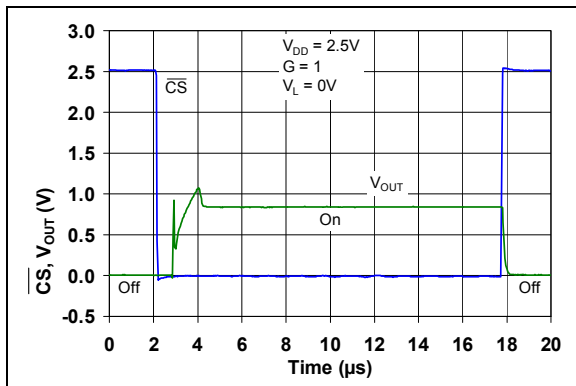
## 2.6 Chip Select Response



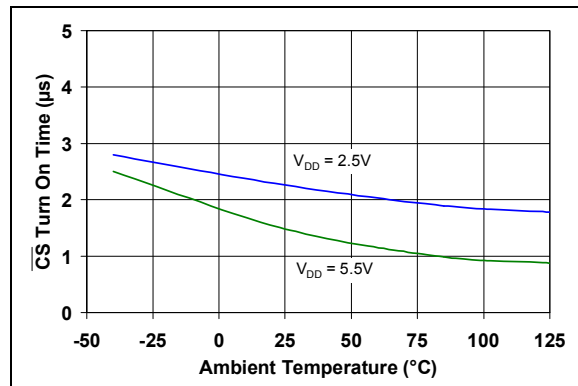
**FIGURE 2-42:** CS Current vs. Power Supply Voltage.



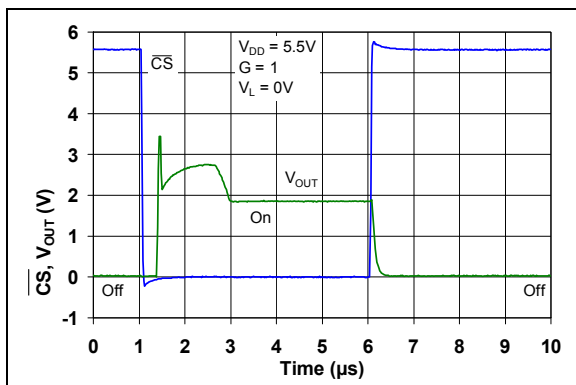
**FIGURE 2-45:** CS Hysteresis vs. Ambient Temperature.



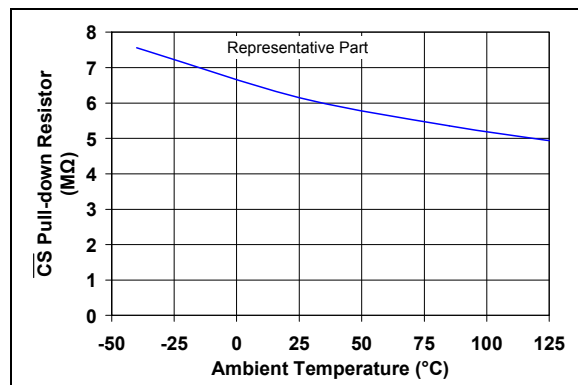
**FIGURE 2-43:** CS and Output Voltages vs. Time with  $V_{DD} = 2.5\text{V}$ .



**FIGURE 2-46:** CS Turn-On Time vs. Ambient Temperature.

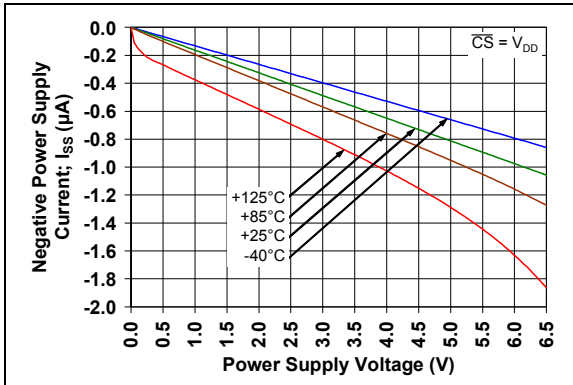


**FIGURE 2-44:** CS and Output Voltages vs. Time with  $V_{DD} = 5.5\text{V}$ .

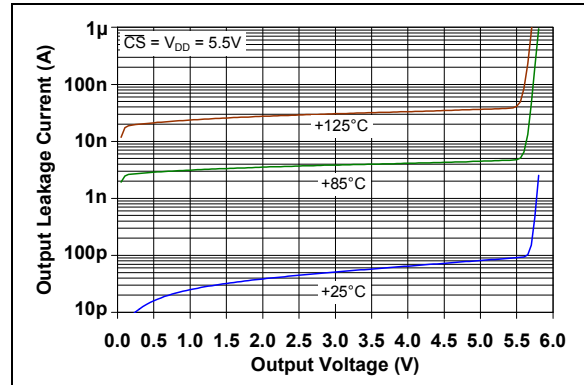


**FIGURE 2-47:** CS's Pull-Down Resistor ( $R_{PD}$ ) vs. Ambient Temperature.

**Note:** Unless otherwise indicated,  $T_A = +25^\circ\text{C}$ ,  $V_{DD} = +2.5\text{V}$  to  $5.5\text{V}$ ,  $V_{SS} = \text{GND}$ ,  $V_{CM} = V_{DD}/3$ ,  $V_{OUT} = V_{DD}/2$ ,  $V_L = V_{DD}/2$ ,  $R_L = 1\text{ k}\Omega$  to  $V_L$ ,  $C_L = 20\text{ pF}$  and  $\overline{CS} = V_{SS}$ .



**FIGURE 2-48:** Quiescent Current in Shutdown vs. Power Supply Voltage.



**FIGURE 2-49:** Output Leakage Current vs. Output Voltage.

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NOTES:

### 3.0 PIN DESCRIPTIONS

Descriptions of the pins are listed in [Table 3-1](#).

**TABLE 3-1: PIN FUNCTION TABLE**

MCP660		MCP661			MCP662		MCP663		MCP664		MCP665		MCP669	Symbol	Description
4x4 QFN	SOIC, TSSOP	SOIC	2x3 TDFN	SOT-23	MSOP, SOIC	DFN	SOIC	SOT-23	SOIC, TSSOP	MSOP	DFN	4x4 QFN			
5	6	2	2	4	2	2	2	4	2	2	2	1	$V_{IN-}, V_{INA-}$	Inverting Input (op amp A)	
4	5	3	3	3	3	3	3	3	3	3	3	2	$V_{IN+}, V_{INA+}$	Non-inverting Input (op amp A)	
3	4	7	7	5	8	8	7	6	4	10	10	3	$V_{DD}$	Positive Power Supply	
10	10	—	—	—	5	5	—	—	5	7	7	4	$V_{INB+}$	Non-inverting Input (op amp B)	
9	9	—	—	—	6	6	—	—	6	8	8	5	$V_{INB-}$	Inverting Input (op amp B)	
8	8	—	—	—	7	7	—	—	7	9	9	6	$V_{OUTB}$	Output (op amp B)	
—	—	—	—	—	—	—	—	—	—	—	—	7	$\overline{CSBC}$	Chip Select Digital Input (op amps B and C)	
14	14	—	—	—	—	—	—	—	8	—	—	8	$V_{OUTC}$	Output (op amp C)	
13	13	—	—	—	—	—	—	—	9	—	—	9	$V_{INC-}$	Inverting Input (op amp C)	
12	12	—	—	—	—	—	—	—	10	—	—	10	$V_{INC+}$	Non-inverting Input (op amp C)	
11	11	4	4	2	4	4	4	2	11	4	4	11	$V_{SS}$	Negative Power Supply	
—	—	—	—	—	—	—	—	—	12	—	—	12	$V_{IND+}$	Inverting Input (op amp D)	
—	—	—	—	—	—	—	—	—	13	—	—	13	$V_{IND-}$	Inverting Input (op amp D)	
—	—	—	—	—	—	—	—	—	14	—	—	14	$V_{OUTD}$	Output (op amp D)	
—	—	—	—	—	—	—	—	—	—	—	—	15	$\overline{CSAD}$	Chip Select Digital Input (op amps A and D)	
6	7	6	6	1	1	1	6	1	1	1	1	16	$V_{OUT}, V_{OUTA}$	Output (op amp A)	
17	—	—	9	—	—	9	—	—	—	—	11	17	EP	Exposed Thermal Pad (EP); must be connected to $V_{SS}$	
—	—	—	8	—	—	—	8	5	—	5	5	—	$\overline{CS}, \overline{CSA}$	Chip Select Digital Input (op amp A)	
—	—	—	—	—	—	—	—	—	—	6	6	—	$\overline{CSB}$	Chip Select Digital Input (op amp B)	
1, 2, 7, 15, 16	1, 2, 3	1, 5, 8	1, 5	—	—	—	1, 5	—	—	—	—	—	NC	No Internal Connection	

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## 3.1 Analog Outputs

The analog output pins ( $V_{OUT}$ ) are low-impedance voltage sources.

## 3.2 Analog Inputs

The non-inverting and inverting inputs ( $V_{IN+}$ ,  $V_{IN-}$ , ...) are high-impedance CMOS inputs with low bias currents.

## 3.3 Power Supply Pins

The positive power supply ( $V_{DD}$ ) is 2.5V to 5.5V higher than the negative power supply ( $V_{SS}$ ). For normal operation, the other pins are between  $V_{SS}$  and  $V_{DD}$ .

Typically, these parts are used in a single (positive) supply configuration. In that case,  $V_{SS}$  is connected to Ground and  $V_{DD}$  is connected to the supply.  $V_{DD}$  will need bypass capacitors.

## 3.4 Chip Select Digital Input ( $\overline{CS}$ )

The input ( $\overline{CS}$ ) is a CMOS, Schmitt-triggered input that places the part into a low-power mode of operation.

## 3.5 Exposed Thermal Pad (EP)

There is an internal connection between the exposed thermal pad (EP) and the  $V_{SS}$  pin; they must be connected to the same potential on the printed circuit board (PCB).

This pad can be connected to a PCB ground plane to provide a larger heat sink. This improves the package thermal resistance ( $\theta_{JA}$ ).

## 4.0 APPLICATIONS

The MCP660/1/2/3/4/5/9 family is manufactured using the Microchip state-of-the-art CMOS process. It is designed for low-cost, low-power and high-speed applications. Its low supply voltage, low quiescent current and wide bandwidth make the MCP660/1/2/3/4/5/9 ideal for battery-powered applications.

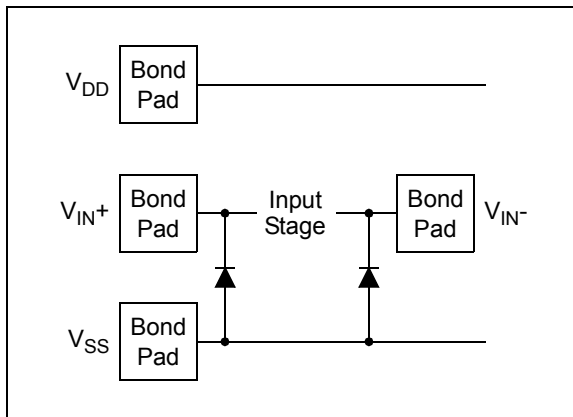
### 4.1 Input

#### 4.1.1 PHASE REVERSAL

The input devices are designed to not exhibit phase inversion when the input pins exceed the supply voltages. [Figure 2-39](#) shows an input voltage exceeding both supplies with no phase inversion.

#### 4.1.2 INPUT VOLTAGE AND CURRENT LIMITS

The electrostatic discharge (ESD) protection on the inputs can be depicted as shown in [Figure 4-1](#). This structure was chosen to protect the input transistors and to minimize input bias current ( $I_B$ ). The input ESD diodes clamp the inputs when they try to go more than one diode drop below  $V_{SS}$ . They also clamp any voltages that go too far above  $V_{DD}$ ; their breakdown voltage is high enough to allow normal operation and low enough to bypass quick ESD events within the specified limits.

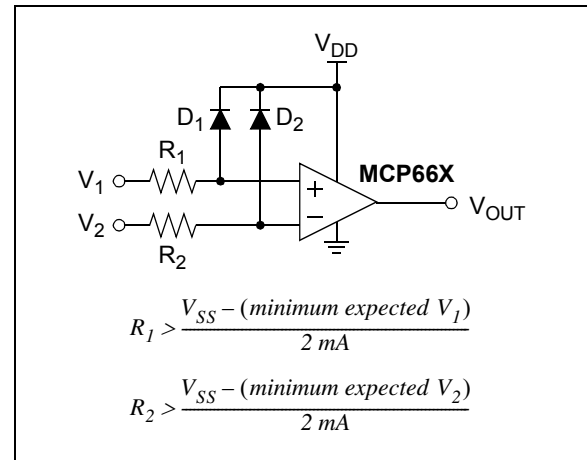


**FIGURE 4-1:** Simplified Analog Input ESD Structures.

In order to prevent damage and/or improper operation of these amplifiers, the circuit must limit the currents (and voltages) at the input pins (see **Section 1.1 "Absolute Maximum Ratings +"**). [Figure 4-2](#) shows the recommended approach to protecting these inputs.

The internal ESD diodes prevent the input pins ( $V_{IN+}$  and  $V_{IN-}$ ) from going too far below ground, while the resistors  $R_1$  and  $R_2$  limit the possible current drawn out of the input pins. Diodes  $D_1$  and  $D_2$  prevent the input pins ( $V_{IN+}$  and  $V_{IN-}$ ) from going too far above  $V_{DD}$  and dump any currents onto  $V_{DD}$ .

When implemented as shown, resistors  $R_1$  and  $R_2$  also limit the current through  $D_1$  and  $D_2$ .



**FIGURE 4-2:** Protecting the Analog Inputs.

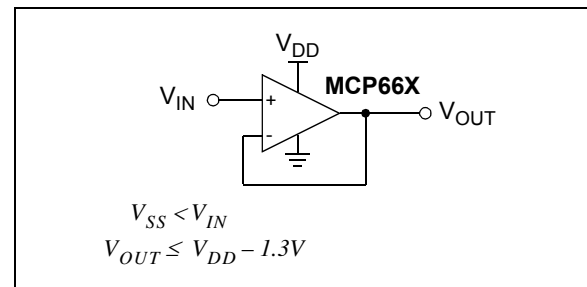
It is also possible to connect the diodes to the left of the resistors  $R_1$  and  $R_2$ . If so, the currents through the diodes  $D_1$  and  $D_2$  need to be limited by some other mechanism. The resistors then serve as in-rush current limiters; the DC current into the input pins ( $V_{IN+}$  and  $V_{IN-}$ ) should be very small.

A significant amount of current can flow out of the inputs (through the ESD diodes) when the common-mode voltage ( $V_{CM}$ ) is below ground ( $V_{SS}$ ); see [Figure 2-13](#). Applications that are high-impedance may need to limit the usable voltage range.

#### 4.1.3 NORMAL OPERATION

The input stage of the MCP660/1/2/3/4/5/9 op amps uses a differential PMOS input stage. It operates at low common-mode input voltages ( $V_{CM}$ ), with  $V_{CM}$  between  $V_{SS} - 0.3V$  and  $V_{DD} - 1.3V$ . To ensure proper operation, the input offset voltage ( $V_{OS}$ ) is measured at both  $V_{CM} = V_{SS} - 0.3V$  and  $V_{CM} = V_{DD} - 1.3V$ . See [Figures 2-5](#) and [2-6](#) for temperature effects.

When operating at very low non-inverting gains, the output voltage is limited at the top by the  $V_{CM}$  range ( $< V_{DD} - 1.3V$ ); see [Figure 4-3](#).



**FIGURE 4-3:** Unity-Gain Voltage Limitations for Linear Operation.

# MCP660/1/2/3/4/5/9

## 4.2 Rail-to-Rail Output

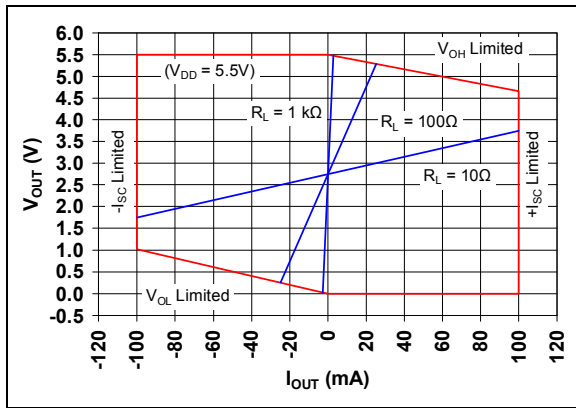
### 4.2.1 MAXIMUM OUTPUT VOLTAGE

The Maximum Output Voltage (see [Figures 2-16](#) and [2-17](#)) describes the output range for a given load. For example, the output voltage swings to within 50 mV of the negative rail with a 1 kΩ load tied to V<sub>DD</sub>/2.

### 4.2.2 OUTPUT CURRENT

[Figure 4-4](#) shows the possible combinations of output voltage (V<sub>OUT</sub>) and output current (I<sub>OUT</sub>), when V<sub>DD</sub> = 5.5V.

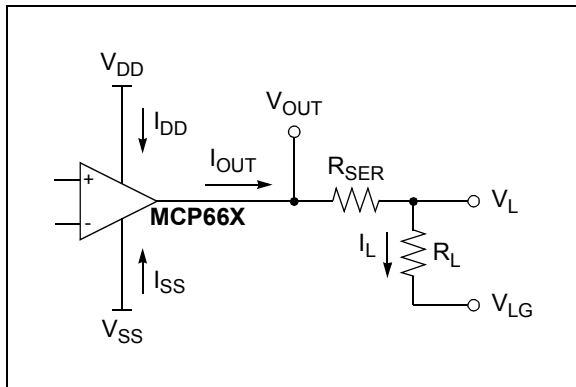
I<sub>OUT</sub> is positive when it flows out of the op amp into the external circuit.



**FIGURE 4-4:** Output Current.

### 4.2.3 POWER DISSIPATION

Since the output short circuit current (I<sub>SC</sub>) is specified at ±90 mA (typical), these op amps are capable of both delivering and dissipating significant power.



**FIGURE 4-5:** Diagram for Power Calculations.

[Figure 4-5](#) shows the power calculations used for a single op amp:

- R<sub>SER</sub> is 0Ω in most applications and can be used to limit I<sub>OUT</sub>.
- V<sub>OUT</sub> is the op amp's output voltage.
- V<sub>L</sub> is the voltage at the load.
- V<sub>LG</sub> is the load's ground point.
- V<sub>SS</sub> is usually ground (0V).

The input currents are assumed to be negligible. The currents shown in [Figure 4-5](#) can be approximated using [Equation 4-1](#):

#### EQUATION 4-1:

$$I_{OUT} = I_L = \frac{V_{OUT} - V_{LG}}{R_{SER} + R_L}$$

$$I_{DD} \approx I_Q + \max(0, I_{OUT})$$

$$I_{SS} \approx -I_Q + \min(0, I_{OUT})$$

Where:  
I<sub>Q</sub> = Quiescent supply current

The instantaneous op amp power (P<sub>OA(t)</sub>), R<sub>SER</sub> power (P<sub>RSER(t)</sub>) and load power (P<sub>L(t)</sub>) are calculated in [Equation 4-2](#):

#### EQUATION 4-2:

$$P_{OA(t)} = I_{DD}(V_{DD} - V_{OUT}) + I_{SS}(V_{SS} - V_{OUT})$$

$$P_{RSER(t)} = I_{OUT}^2 R_{SER}$$

$$P_L(t) = I_L^2 R_L$$

The maximum op amp power, for resistive loads, occurs when V<sub>OUT</sub> is halfway between V<sub>DD</sub> and V<sub>LG</sub> or halfway between V<sub>SS</sub> and V<sub>LG</sub>.

#### EQUATION 4-3:

$$P_{OAm} \leq \frac{\max^2(V_{DD} - V_{LG} - V_{SS})}{4(R_{SER} + R_L)}$$

The maximum ambient to junction temperature rise (ΔT<sub>JA</sub>) and junction temperature (T<sub>J</sub>) can be calculated using P<sub>OAm</sub>, the ambient temperature (T<sub>A</sub>), the package thermal resistance (θ<sub>JA</sub>, found in the [Temperature Specifications](#) table) and the number of op amps in the package (assuming equal power dissipations), as shown in [Equation 4-4](#):

#### EQUATION 4-4:

$$\Delta T_{JA} = P_{OA(t)} \theta_{JA} \leq n P_{OAm} \theta_{JA}$$

$$T_J = T_A + \Delta T_{JA}$$

Where:  
n = Number of op amps in the package (1, 2)

The power derating across temperature for an op amp in a particular package can be easily calculated (assuming equal power dissipations):

**EQUATION 4-5:**

$$P_{OAm_{ax}} \leq \frac{T_{Jmax} - T_A}{n \theta_{JA}}$$

Where:  
 $T_{Jmax}$  = Absolute maximum junction temperature

Several techniques are available to reduce  $\Delta T_{JA}$  for a given  $P_{OAm_{ax}}$ :

- Lower  $\theta_{JA}$ 
  - Use another package
  - PCB layout (ground plane, etc.)
  - Heat sinks and air flow
- Reduce  $P_{OAm_{ax}}$ 
  - Increase  $R_L$
  - Limit  $I_{OUT}$  (using  $R_{SER}$ )
  - Decrease  $V_{DD}$

### 4.3 Distortion

Differential gain (DG) and differential phase (DP) refer to the nonlinear distortion produced by an NTSC or a phase-alternating line (PAL) video component. The [AC Electrical Specifications](#) table and [Figure 2-34](#) show the typical performance of the MCP661, configured as a gain of +2 amplifier (see [Figure 4-10](#)), when driving one back-matched video load ( $150\Omega$ , for  $75\Omega$  cable). Microchip tests use a sine wave at NTSC's color sub-carrier frequency of 3.58 MHz, with a  $0.286V_{P-P}$  magnitude. The DC input voltage is changed over a +0.7V range (positive video) or a -0.7V range (negative video).

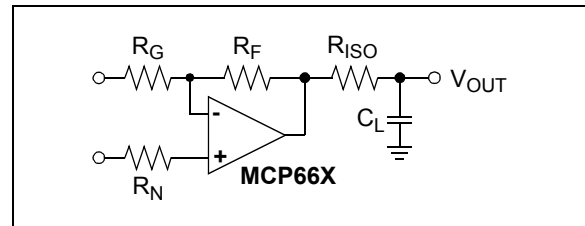
DG is the peak-to-peak change in the AC gain magnitude (color hue), as the DC level (luminance) is changed, in percentile units (%). DP is the peak-to-peak change in the AC gain phase (color saturation), as the DC level (luminance) is changed, in degree ( $^{\circ}$ ) units.

### 4.4 Improving Stability

#### 4.4.1 CAPACITIVE LOADS

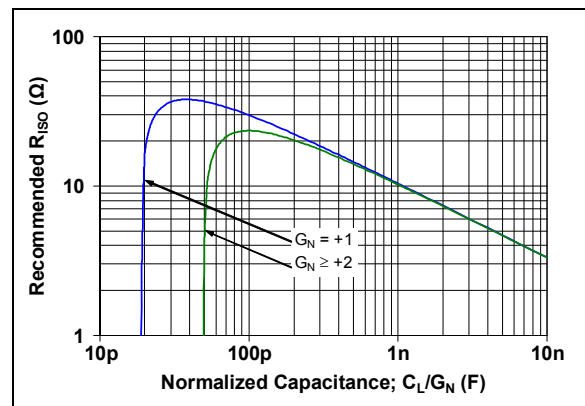
Driving large capacitive loads can cause stability problems for voltage feedback op amps. As the load capacitance increases, the phase margin (stability) of the feedback loop decreases and the closed-loop bandwidth is reduced. This produces gain peaking in the frequency response, with overshoot and ringing in the step response. A unity-gain buffer ( $G = +1$ ) is the most sensitive to capacitive loads, though all gains show the same general behavior.

When driving large capacitive loads with these op amps (e.g.,  $> 20$  pF when  $G = +1$ ), a small series resistor at the output ( $R_{ISO}$  in [Figure 4-6](#)) improves the phase margin of the feedback loop by making the output load resistive at higher frequencies. The bandwidth will generally be lower than bandwidth without the capacitive load.



**FIGURE 4-6:** Output Resistor,  $R_{ISO}$ , Stabilizes Large Capacitive Loads.

[Figure 4-7](#) gives recommended  $R_{ISO}$  values for different capacitive loads and gains. The x-axis is the normalized load capacitance ( $C_L/G_N$ ), where  $G_N$  is the circuit's noise gain. For non-inverting gains,  $G_N$  and the Signal Gain are equal. For inverting gains,  $G_N$  is  $1 + |\text{Signal Gain}|$  (e.g., -1 V/V gives  $G_N = +2$  V/V).



**FIGURE 4-7:** Recommended  $R_{ISO}$  Values for Capacitive Loads.

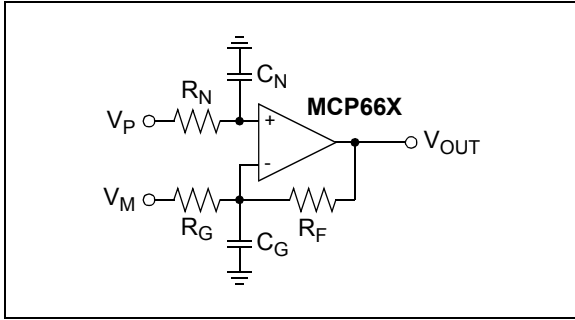
After selecting  $R_{ISO}$  for the circuit, double-check the resulting frequency response peaking and step response overshoot. Modify the value of  $R_{ISO}$  until the response is reasonable. Bench evaluation and simulations with the MCP660/1/2/3/4/5/9 SPICE macro model are helpful.



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## 4.4.2 GAIN PEAKING

Figure 4-8 shows an op amp circuit that represents non-inverting amplifiers ( $V_M$  is a DC voltage and  $V_P$  is the input) or inverting amplifiers ( $V_P$  is a DC voltage and  $V_M$  is the input). The capacitances  $C_N$  and  $C_G$  represent the total capacitance at the input pins; they include the op amp's common-mode input capacitance ( $C_{CM}$ ), board parasitic capacitance and any capacitor placed in parallel.

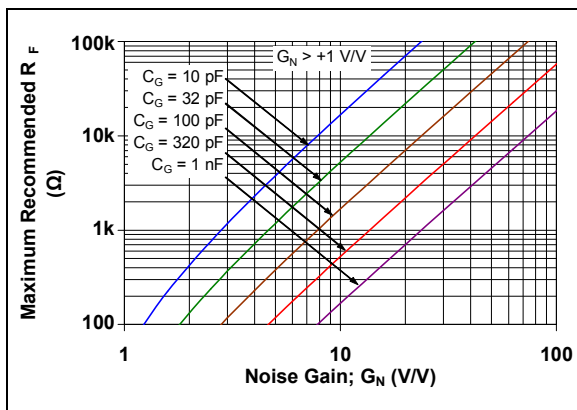


**FIGURE 4-8:** Amplifier with Parasitic Capacitance.

$C_G$  acts in parallel with  $R_G$  (except for a gain of +1 V/V), which causes an increase in gain at high frequencies.  $C_G$  also reduces the phase margin of the feedback loop, which becomes less stable. This effect can be reduced by either reducing  $C_G$  or  $R_F$ .

$C_N$  and  $R_N$  form a low-pass filter that affects the signal at  $V_P$ . This filter has a single real pole at  $1/(2\pi R_N C_N)$ .

The largest value of  $R_F$  that should be used depends on the noise gain (see  $G_N$  in Section 4.4.1 “Capacitive Loads”),  $C_G$  and the open-loop gain's phase shift. Figure 4-9 shows the maximum recommended  $R_F$  for several  $C_G$  values. Some applications may modify these values to reduce either output loading or gain peaking (step response overshoot).



**FIGURE 4-9:** Maximum Recommended  $R_F$  vs. Gain.

Figures 2-35 and 2-36 show the small signal and large signal step responses at  $G = +1$  V/V. The unity-gain buffer usually has  $R_F = 0\Omega$  and  $R_G$  open.

Figures 2-37 and 2-38 show the small signal and large signal step responses at  $G = -1$  V/V. Since the noise gain is 2 V/V and  $C_G \approx 10$  pF, the resistors were chosen to be  $R_F = R_G = 401\Omega$  and  $R_N = 200\Omega$ .

It is also possible to add a capacitor ( $C_F$ ) in parallel with  $R_F$  to compensate for the destabilizing effect of  $C_G$ . This makes it possible to use larger values of  $R_F$ . The conditions for stability are summarized in Equation 4-6.

### EQUATION 4-6:

Given:

$$G_{N1} = 1 + \frac{R_F}{R_G}$$

$$G_{N2} = 1 + \frac{C_G}{C_F}$$

$$f_F = \frac{1}{2\pi R_F C_F}$$

$$f_Z = f_F \left( \frac{G_{N1}}{G_{N2}} \right)$$

We need:

$$f_F \leq \frac{f_{GBWP}}{2G_{N2}}, G_{N1} < G_{N2}$$

$$f_F \leq \frac{f_{GBWP}}{4G_{N1}}, G_{N1} > G_{N2}$$

## 4.5 MCP663 and MCP665 Chip Select

The MCP663 is a single amplifier with Chip Select ( $\overline{CS}$ ). When  $\overline{CS}$  is pulled high, the supply current drops to 1  $\mu$ A (typical) and flows through the  $\overline{CS}$  pin to  $V_{SS}$ . When this happens, the amplifier output is put into a high-impedance state. By pulling  $\overline{CS}$  low, the amplifier is enabled. The  $\overline{CS}$  pin has an internal 5  $M\Omega$  (typical) pulldown resistor connected to  $V_{SS}$ , so it will go low if the  $\overline{CS}$  pin is left floating. Figures 1-1, 2-43 and 2-44 show the output voltage and supply current response to a  $\overline{CS}$  pulse.

The MCP665 is a dual amplifier with two  $\overline{CS}$  pins;  $\overline{CSA}$  controls op amp A and  $\overline{CSB}$  controls op amp B. These op amps are controlled independently, with an enabled quiescent current ( $I_Q$ ) of 6 mA/amplifier (typical) and a disabled  $I_Q$  of 1  $\mu$ A/amplifier (typical). The  $I_Q$  seen at the supply pins is the sum of the two op amps'  $I_Q$ ; the typical value for the  $I_Q$  of the MCP665 will be 2  $\mu$ A, 6 mA or 12 mA when there are 0, 1 or 2 amplifiers enabled, respectively.

## 4.6 Power Supply

With this family of operational amplifiers, the power supply pin ( $V_{DD}$  for single supply) should have a local bypass capacitor (i.e., 0.01  $\mu$ F to 0.1  $\mu$ F) within 2 mm for good high-frequency performance. Surface mount, multilayer ceramic capacitors, or their equivalent, should be used.

These op amps require a bulk capacitor (i.e., 2.2  $\mu$ F or larger) within 50 mm to provide large, slow currents. Tantalum capacitors, or their equivalent, may be a good choice. This bulk capacitor can be shared with other nearby analog parts as long as crosstalk through the power supplies does not prove to be a problem.

## 4.7 High Speed PCB Layout

These op amps are fast enough that a little extra care in the printed circuit board (PCB) layout can make a significant difference in performance. Good PCB layout techniques will help you achieve the performance shown in the specifications and typical performance curves; it will also help minimize electromagnetic compatibility (EMC) issues.

Use a solid ground plane. Connect the bypass local capacitor(s) to this plane with minimal length traces. This cuts down inductive and capacitive crosstalk.

Separate digital from analog, low-speed from high-speed and low-power from high-power. This will reduce interference.

Keep sensitive traces short and straight. Separate them from interfering components and traces. This is especially important for high-frequency (low rise time) signals.

Sometimes, it helps to place guard traces next to victim traces. They should be on both sides of the victim trace and as close as possible. Connect guard traces to ground plane at both ends and in the middle for long traces.

Use coax cables, or low inductance wiring, to route signal and power to and from the PCB. Mutual and self inductance of power wires is often a cause of crosstalk and unusual behavior.