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80 μ A, 1 MHz Zero-Drift Op Amps

Features

- High DC Precision:
 - V_{OS} Drift: ± 15 nV/ $^{\circ}$ C (maximum, $V_{DD} = 5.5$ V)
 - V_{OS} : ± 8 μ V (maximum)
 - A_{OL} : 125 dB (minimum, $V_{DD} = 5.5$ V)
 - PSRR: 117 dB (minimum, $V_{DD} = 5.5$ V)
 - CMRR: 120 dB (minimum, $V_{DD} = 5.5$ V)
 - E_{ni} : 0.54 μ V_{P-P} (typical), $f = 0.1$ Hz to 10 Hz
 - E_{ni} : 0.17 μ V_{P-P} (typical), $f = 0.01$ Hz to 1 Hz
- Enhanced EMI Protection:
 - Electromagnetic Interference Rejection Ratio (EMIRR) at 1.8 GHz: 101 dB
- Low Power and Supply Voltages:
 - I_Q : 80 μ A/amplifier (typical)
 - Wide Supply Voltage Range: 1.8V to 5.5V
- Small Packages:
 - Singles in SC70, SOT-23
 - Duals in MSOP-8, 2x3 TDFN
 - Quads in TSSOP-14
- Easy to Use:
 - Rail-to-Rail Input/Output
 - Gain Bandwidth Product: 1 MHz (typical)
 - Unity Gain Stable
- Extended Temperature Range: -40° C to $+125^{\circ}$ C

Typical Applications

- Portable Instrumentation
- Sensor Conditioning
- Temperature Measurement
- DC Offset Correction
- Medical Instrumentation

Design Aids

- SPICE Macro Models
- FilterLab[®] Software
- Microchip Advanced Part Selector (MAPS)
- Analog Demonstration and Evaluation Boards
- Application Notes

Related Parts

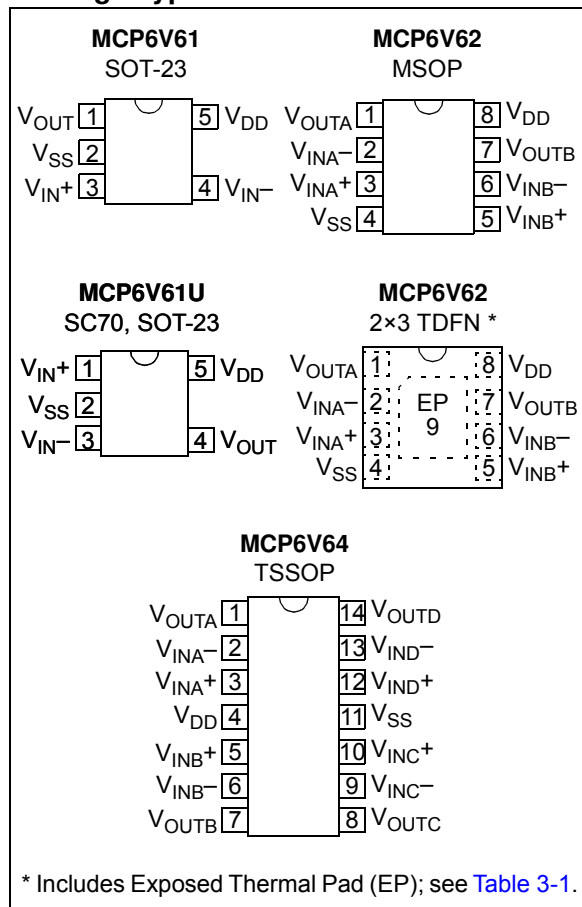
- [MCP6V11/1U/2/4: Zero-Drift, Low Power](#)
- [MCP6V31/1U/2/4: Zero-Drift, Low Power](#)
- [MCP6V71/1U/2/4: Zero-Drift, 2 MHz](#)
- [MCP6V81/1U: Zero-Drift, 5 MHz](#)
- [MCP6V91/1U: Zero-Drift, 10 MHz](#)

General Description

The Microchip Technology Inc. MCP6V61/1U/2/4 family of operational amplifiers provides input offset voltage correction for very low offset and offset drift. These devices have a gain bandwidth product of 1 MHz (typical). They are unity-gain stable, have virtually no 1/f noise and have good Power Supply Rejection Ratio (PSRR) and Common Mode Rejection Ratio (CMRR). These products operate with a single supply voltage as low as 1.8V, while drawing 80 μ A/amplifier (typical) of quiescent current.

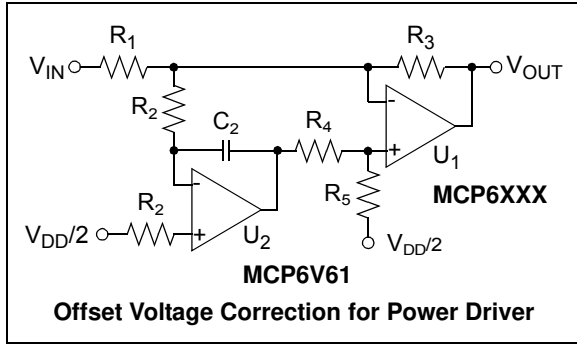
The Microchip Technology Inc. MCP6V61/1U/2/4 op amps are offered in single (MCP6V61 and MCP6V61U), dual (MCP6V62) and quad (MCP6V64) packages. They were designed using an advanced CMOS process.

Package Types



MCP6V61/1U/2/4

Typical Application Circuit



Figures 1 and 2 show input offset voltage versus ambient temperature for different power supply voltages.

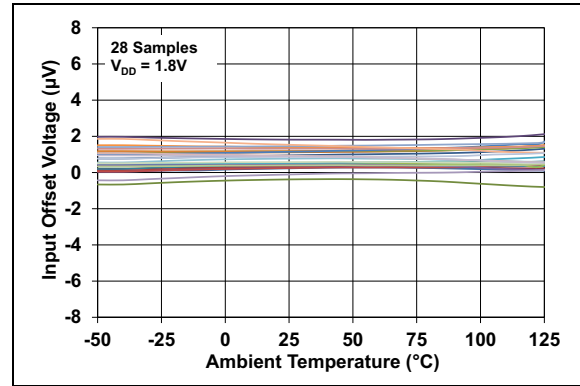


FIGURE 1: Input Offset Voltage vs. Ambient Temperature with $V_{DD} = 1.8V$.

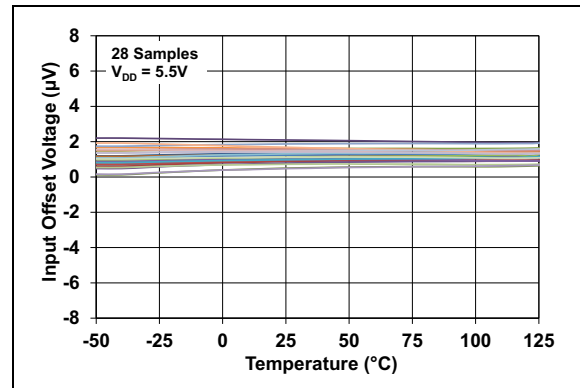


FIGURE 2: Input Offset Voltage vs. Ambient Temperature with $V_{DD} = 5.5V$.

As seen in Figures 1 and 2, the MCP6V61/1U/2/4 op amps have excellent performance across temperature. The input offset voltage temperature drift (TC_1) shown is well within the specified maximum values of $15 \text{ nV}/^\circ\text{C}$ at $V_{DD} = 5.5V$ and $30 \text{ nV}/^\circ\text{C}$ at $V_{DD} = 1.8V$.

This performance supports applications with stringent DC precision requirements. In many cases, it will not be necessary to correct for temperature effects (i.e., calibrate) in a design. In the other cases, the correction will be small.

1.0 ELECTRICAL CHARACTERISTICS

1.1 Absolute Maximum Ratings †

$V_{DD} - V_{SS}$	6.5V
Current at Input Pins	±2 mA
Analog Inputs (V_{IN+} and V_{IN-}) (Note 1).....	$V_{SS} - 1.0V$ to $V_{DD} + 1.0V$
All Other Inputs and Outputs	$V_{SS} - 0.3V$ to $V_{DD} + 0.3V$
Difference Input Voltage	$ V_{DD} - V_{SS} $
Output Short Circuit Current	Continuous
Current at Output and Supply Pins	±30 mA
Storage Temperature	-65°C to +150°C
Maximum Junction Temperature	+150°C
ESD protection on all pins (HBM, CDM, MM)	
MCP6V61/1U	≥ 4 kV, 1.5 kV, 400V
MCP6V62/4	≥ 4 kV, 1.5 kV, 300V

† **Note:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Note 1: See [Section 4.2.1 “Rail-to-Rail Inputs”](#).

1.2 Specifications

TABLE 1-1: DC ELECTRICAL SPECIFICATIONS

Electrical Characteristics: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8V$ to $+5.5V$, $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$ (refer to Figures 1-4 and 1-5).						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
Input Offset						
Input Offset Voltage	V_{OS}	-8	—	+8	μV	$T_A = +25^\circ\text{C}$
Input Offset Voltage Drift with Temperature (Linear Temp. Co.)	TC_1	-30	—	+30	$\text{nV}/^\circ\text{C}$	$T_A = -40$ to $+125^\circ\text{C}$, $V_{DD} = 1.8V$ (Note 1)
	TC_1	-15	—	+15	$\text{nV}/^\circ\text{C}$	$T_A = -40$ to $+125^\circ\text{C}$, $V_{DD} = 5.5V$ (Note 1)
Input Offset Voltage Quadratic Temp. Co.	TC_2	—	-30	—	$\text{pV}/^\circ\text{C}^2$	$T_A = -40$ to $+125^\circ\text{C}$, $V_{DD} = 1.8V$
	TC_2	—	-6	—	$\text{pV}/^\circ\text{C}^2$	$T_A = -40$ to $+125^\circ\text{C}$, $V_{DD} = 5.5V$
Input Offset Voltage Aging	ΔV_{OS}	—	±0.45	—	μV	408 hours Life Test at $+150^\circ$, measured at $+25^\circ\text{C}$.
Power Supply Rejection Ratio	PSRR	117	134	—	dB	

Note 1: For design guidance only; not tested.

2: [Figure 2-19](#) shows how V_{CML} and V_{CMH} changed across temperature for the first production lot.

3: Parts with date codes prior to September 2015 (week code 27) were screened to a +5 nA maximum limit.

4: Parts with date codes prior to September 2015 (week code 27) were screened to ±2 nA minimum/maximum limits.

MCP6V61/1U/2/4

TABLE 1-1: DC ELECTRICAL SPECIFICATIONS (CONTINUED)

Electrical Characteristics: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to $+5.5\text{V}$, $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$ (refer to Figures 1-4 and 1-5).						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
Input Bias Current and Impedance						
Input Bias Current	I_B	-50	± 1	+50	pA	
Input Bias Current across Temperature	I_B	—	+20	—	pA	$T_A = +85^\circ\text{C}$
	I_B	0	+0.2	+1.5	nA	$T_A = +125^\circ\text{C}$ (Note 3)
Input Offset Current	I_{OS}	-200	± 60	+200	pA	
Input Offset Current across Temperature	I_{OS}	—	± 50	—	pA	$T_A = +85^\circ\text{C}$
	I_{OS}	-800	± 50	+800	pA	$T_A = +125^\circ\text{C}$ (Note 4)
Common Mode Input Impedance	Z_{CM}	—	$10^{13} 8$	—	ΩpF	
Differential Input Impedance	Z_{DIFF}	—	$10^{13} 8$	—	ΩpF	
Common Mode						
Common Mode Input Voltage Range Low	V_{CML}	—	—	$V_{SS}-0.2$	V	Note 2
Common Mode Input Voltage Range High	V_{CMH}	$V_{DD}+0.3$	—	—	V	Note 2
Common Mode Rejection Ratio	CMRR	111	128	—	dB	$V_{DD} = 1.8\text{V}$, $V_{CM} = -0.2\text{V}$ to 2.1V (Note 2)
	CMRR	120	134	—	dB	$V_{DD} = 5.5\text{V}$, $V_{CM} = -0.2\text{V}$ to 5.8V (Note 2)
Open-Loop Gain						
DC Open-Loop Gain (Large Signal)	A_{OL}	114	146	—	dB	$V_{DD} = 1.8\text{V}$, $V_{OUT} = 0.3\text{V}$ to 1.6V
	A_{OL}	125	158	—	dB	$V_{DD} = 5.5\text{V}$, $V_{OUT} = 0.3\text{V}$ to 5.3V
Output						
Minimum Output Voltage Swing	V_{OL}	V_{SS}	$V_{SS}+35$	$V_{SS}+121$	mV	$R_L = 2\text{ k}\Omega$, $G = +2$, 0.5V input overdrive
	V_{OL}	—	$V_{SS}+3.5$	—	mV	$R_L = 20\text{ k}\Omega$, $G = +2$, 0.5V input overdrive
Maximum Output Voltage Swing	V_{OH}	$V_{DD}-121$	$V_{DD}-35$	V_{DD}	mV	$R_L = 2\text{ k}\Omega$, $G = +2$, 0.5V input overdrive
	V_{OH}	—	$V_{DD}-3.5$	—	mV	$R_L = 20\text{ k}\Omega$, $G = +2$, 0.5V input overdrive
Output Short Circuit Current	I_{SC}	—	± 7	—	mA	$V_{DD} = 1.8\text{V}$
	I_{SC}	—	± 23	—	mA	$V_{DD} = 5.5\text{V}$
Power Supply						
Supply Voltage	V_{DD}	1.8	—	5.5	V	
Quiescent Current per Amplifier	I_Q	40	80	130	μA	$I_O = 0$
Power-on Reset (POR) Trip Voltage	V_{POR}	0.9	—	1.6	V	

Note 1: For design guidance only; not tested.

- 2:** [Figure 2-19](#) shows how V_{CML} and V_{CMH} changed across temperature for the first production lot.
- 3:** Parts with date codes prior to September 2015 (week code 27) were screened to a +5 nA maximum limit.
- 4:** Parts with date codes prior to September 2015 (week code 27) were screened to ± 2 nA minimum/maximum limits.

TABLE 1-2: AC ELECTRICAL SPECIFICATIONS

Electrical Characteristics: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to $+5.5\text{V}$, $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$ (refer to [Figures 1-4](#) and [1-5](#)).

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
Amplifier AC Response						
Gain Bandwidth Product	GBWP	—	1	—	MHz	
Slew Rate	SR	—	0.45	—	V/ μs	
Phase Margin	PM	—	60	—	$^\circ\text{C}$	G = +1
Amplifier Noise Response						
Input Noise Voltage	E_{ni}	—	0.17	—	μV_{P-P}	f = 0.01 Hz to 1 Hz
	E_{ni}	—	0.54	—	μV_{P-P}	f = 0.1 Hz to 10 Hz
Input Noise Voltage Density	e_{ni}	—	26	—	nV/ $\sqrt{\text{Hz}}$	f < 2 kHz
Input Noise Current Density	i_{ni}	—	5	—	fA/ $\sqrt{\text{Hz}}$	
Amplifier Distortion (Note 1)						
Intermodulation Distortion (AC)	IMD	—	48	—	μV_{PK}	V_{CM} tone = 50 mV $_{PK}$ at 1 kHz, $G_N = 11$, RTI
Amplifier Step Response						
Start-Up Time	t_{STR}	—	250	—	μs	G = +1, 0.1% V_{OUT} settling (Note 2)
Offset Correction Settling Time	t_{STL}	—	30	—	μs	G = +1, V_{IN} step of 2V, V_{OS} within 100 μV of its final value
Output Overdrive Recovery Time	t_{ODR}	—	60	—	μs	G = -10, $\pm 0.5\text{V}$ input overdrive to $V_{DD}/2$, V_{IN} 50% point to V_{OUT} 90% point (Note 3)
EMI Protection						
EMI Rejection Ratio	EMIRR	—	80	—	dB	$V_{IN} = 0.1 V_{PK}$, f = 400 MHz
		—	96	—		$V_{IN} = 0.1 V_{PK}$, f = 900 MHz
		—	101	—		$V_{IN} = 0.1 V_{PK}$, f = 1800 MHz
		—	102	—		$V_{IN} = 0.1 V_{PK}$, f = 2400 MHz

- Note 1:** These parameters were characterized using the circuit in [Figure 1-6](#). In [Figures 2-40](#) and [2-41](#), there is an IMD tone at DC, a residual tone at 1 kHz and other IMD tones and clock tones. IMD is Referred to Input (RTI).
- 2:** High gains behave differently; see [Section 4.3.3 “Offset at Power-Up”](#).
- 3:** t_{STL} and t_{ODR} include some uncertainty due to clock edge timing.

TABLE 1-3: TEMPERATURE SPECIFICATIONS

Electrical Characteristics: Unless otherwise indicated, all limits are specified for: $V_{DD} = +1.8\text{V}$ to $+5.5\text{V}$, $V_{SS} = \text{GND}$

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
Temperature Ranges						
Specified Temperature Range	T_A	-40	—	+125	$^\circ\text{C}$	
Operating Temperature Range	T_A	-40	—	+125	$^\circ\text{C}$	Note 1
Storage Temperature Range	T_A	-65	—	+150	$^\circ\text{C}$	
Thermal Package Resistances						
Thermal Resistance, 5LD-SC70	θ_{JA}	—	209	—	$^\circ\text{C/W}$	
Thermal Resistance, 5LD-SOT-23	θ_{JA}	—	201	—	$^\circ\text{C/W}$	
Thermal Resistance, 8L-2x3 TDFN	θ_{JA}	—	53	—	$^\circ\text{C/W}$	
Thermal Resistance, 8L-MSOP	θ_{JA}	—	211	—	$^\circ\text{C/W}$	
Thermal Resistance, 14L-TSSOP	θ_{JA}	—	100	—	$^\circ\text{C/W}$	

- Note 1:** Operation must not cause T_J to exceed the Maximum Junction Temperature specification (+150 $^\circ\text{C}$).

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1.3 Timing Diagrams

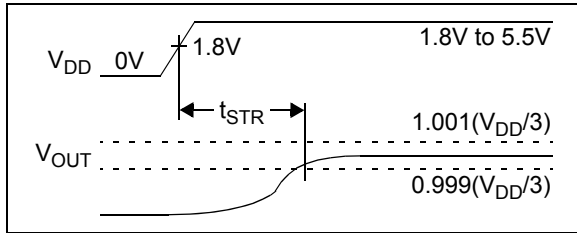


FIGURE 1-1: Amplifier Start-Up.

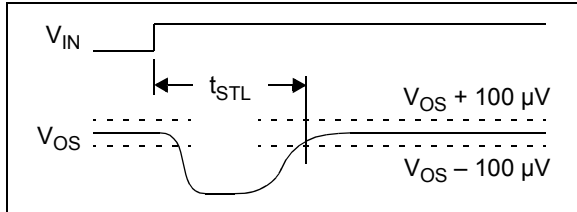


FIGURE 1-2: Offset Correction Settling Time.

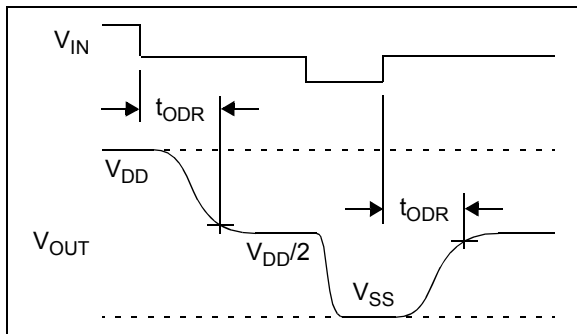


FIGURE 1-3: Output Overdrive Recovery.

1.4 Test Circuits

The circuits used for most DC and AC tests are shown in [Figures 1-4](#) and [1-5](#). Lay the bypass capacitors out as discussed in [Section 4.3.10 “Supply Bypassing and Filtering”](#). R_N is equal to the parallel combination of R_F and R_G to minimize bias current effects.

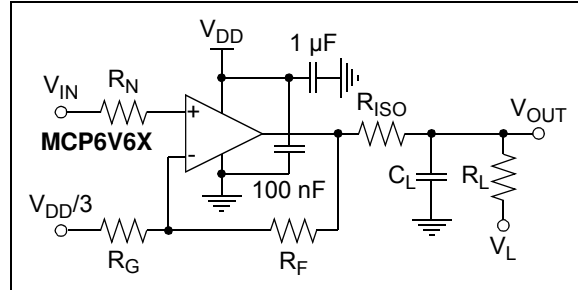


FIGURE 1-4: AC and DC Test Circuit for Most Non-Inverting Gain Conditions.

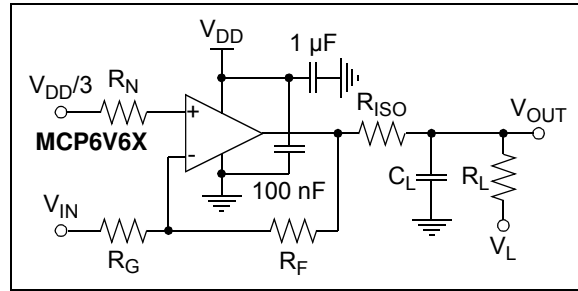


FIGURE 1-5: AC and DC Test Circuit for Most Inverting Gain Conditions.

The circuit in [Figure 1-6](#) tests the input's dynamic behavior (i.e., IMD, t_{STR} , t_{STL} and t_{ODR}). The potentiometer balances the resistor network (V_{OUT} should equal V_{REF} at DC). The op amp's Common Mode Input Voltage is $V_{CM} = V_{IN}/2$. The error at the input (V_{ERR}) appears at V_{OUT} with a noise gain of 10 V/V.

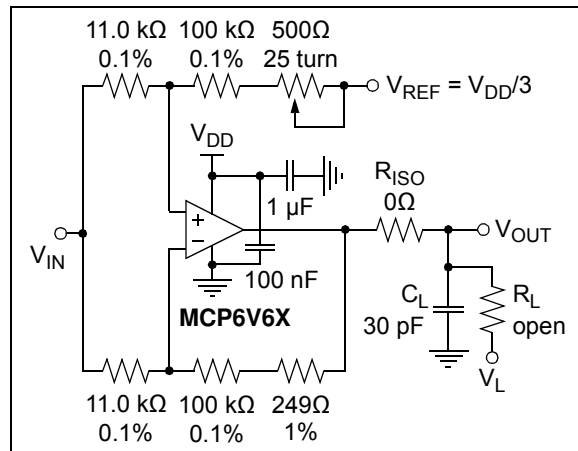


FIGURE 1-6: Test Circuit for Dynamic Input Behavior.

2.0 TYPICAL PERFORMANCE CURVES

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

2.1 DC Input Precision

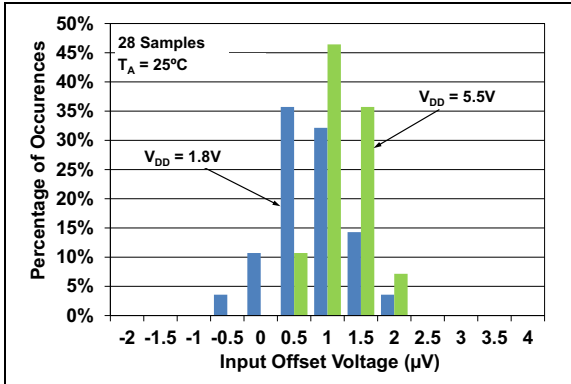


FIGURE 2-1: Input Offset Voltage.

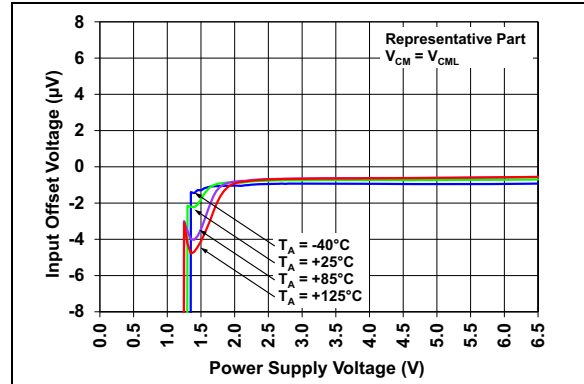


FIGURE 2-4: Input Offset Voltage vs. Power Supply Voltage with $V_{CM} = V_{CML}$.

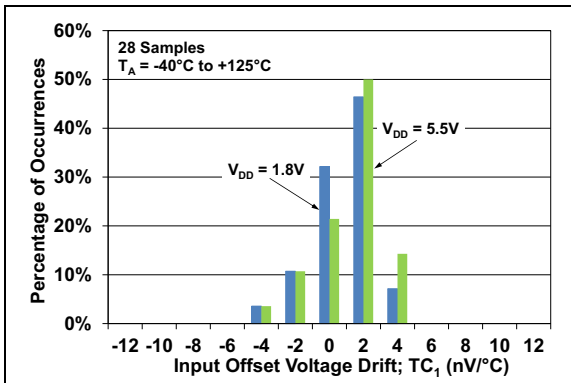


FIGURE 2-2: Input Offset Voltage Drift.

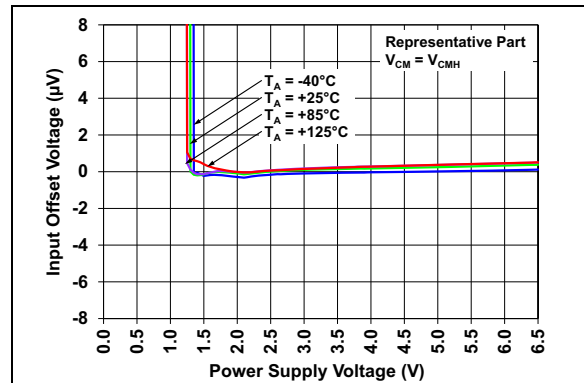


FIGURE 2-5: Input Offset Voltage vs. Power Supply Voltage with $V_{CM} = V_{CMH}$.

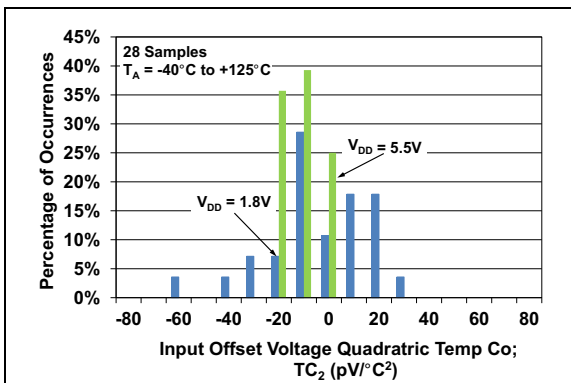


FIGURE 2-3: Input Offset Voltage Quadratic Temp. Co.

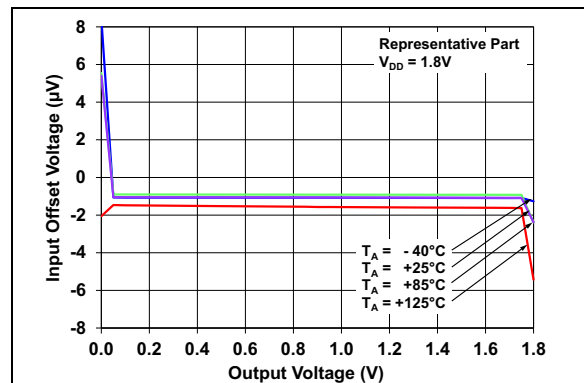


FIGURE 2-6: Input Offset Voltage vs. Output Voltage with $V_{DD} = 1.8\text{V}$.

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Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

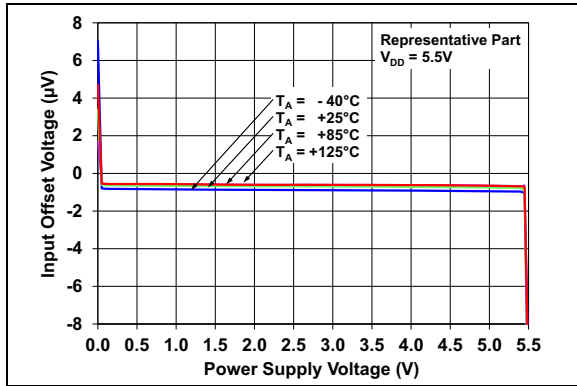


FIGURE 2-7: Input Offset Voltage vs. Output Voltage with $V_{DD} = 5.5\text{V}$.

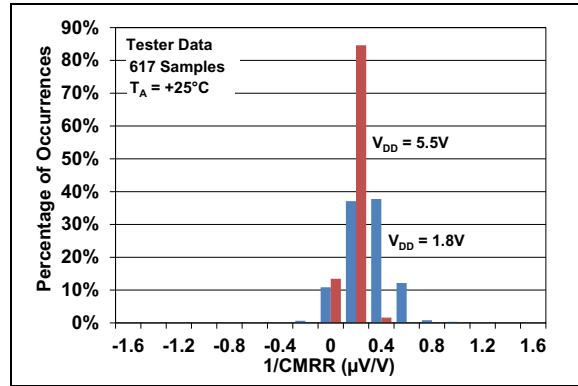


FIGURE 2-10: Common Mode Rejection Ratio.

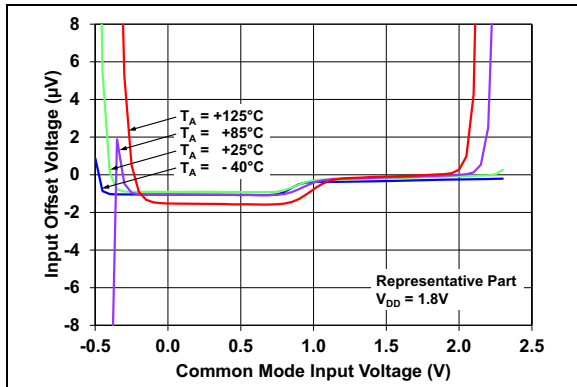


FIGURE 2-8: Input Offset Voltage vs. Common Mode Voltage with $V_{DD} = 1.8\text{V}$.

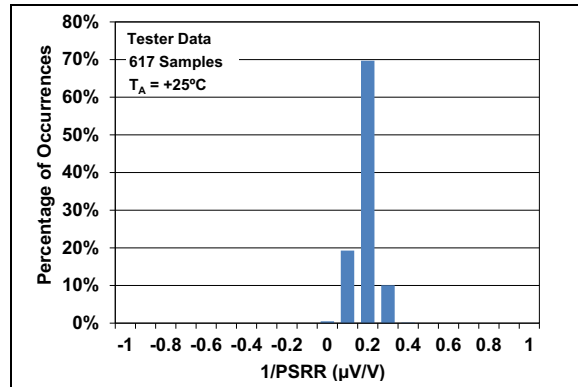


FIGURE 2-11: Power Supply Rejection Ratio.

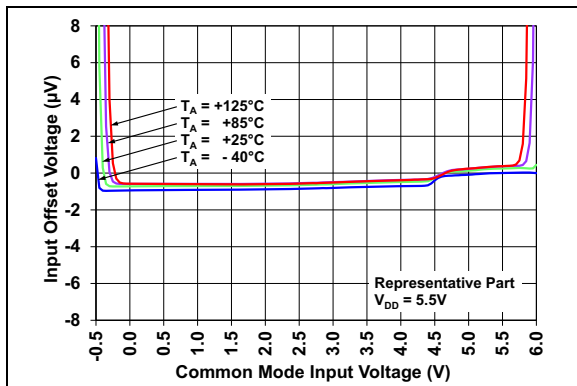


FIGURE 2-9: Input Offset Voltage vs. Common Mode Voltage with $V_{DD} = 5.5\text{V}$.

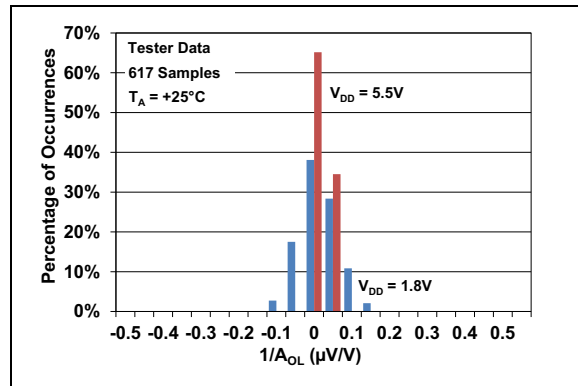


FIGURE 2-12: DC Open-Loop Gain.

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

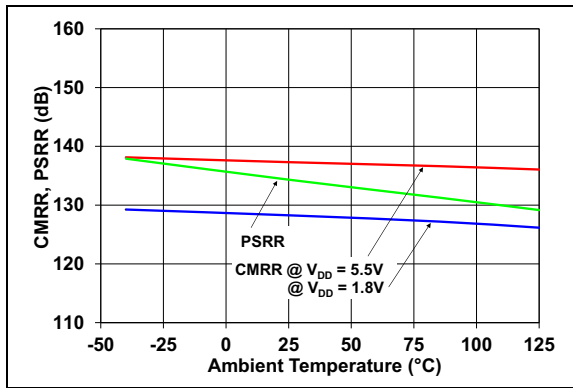


FIGURE 2-13: CMRR and PSRR vs. Ambient Temperature.

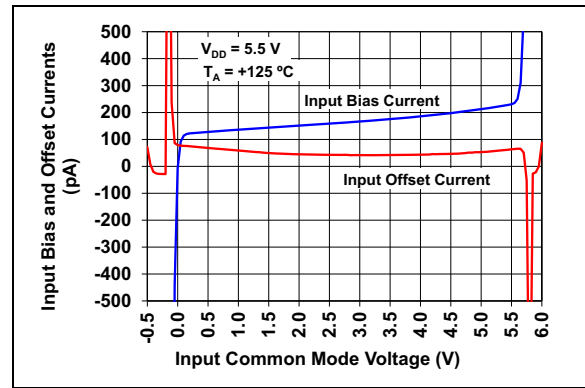


FIGURE 2-16: Input Bias and Offset Currents vs. Common Mode Input Voltage with $T_A = +125^\circ\text{C}$.

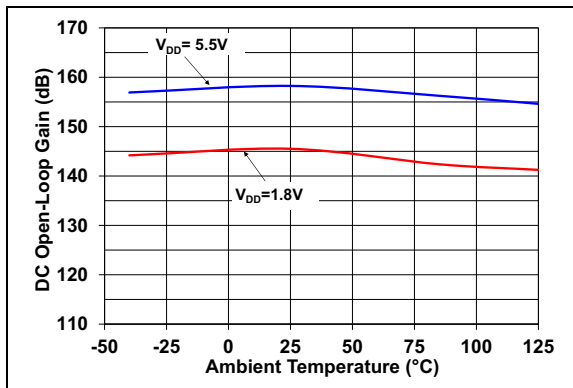


FIGURE 2-14: DC Open-Loop Gain vs. Ambient Temperature.

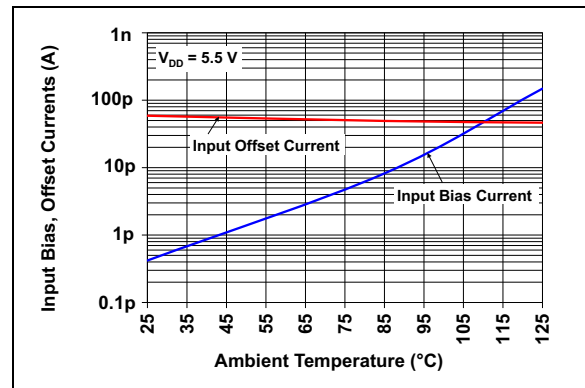


FIGURE 2-17: Input Bias and Offset Currents vs. Ambient Temperature with $V_{DD} = 5.5\text{V}$.

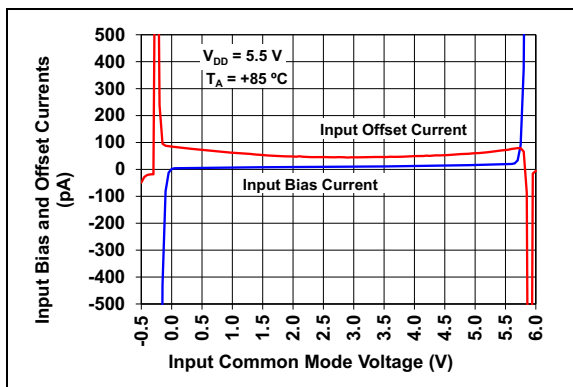


FIGURE 2-15: Input Bias and Offset Currents vs. Common Mode Input Voltage with $T_A = +85^\circ\text{C}$.

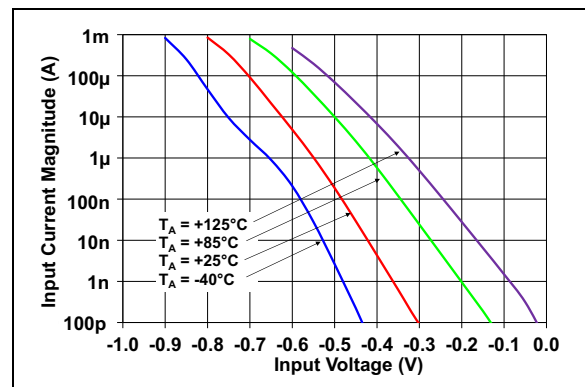


FIGURE 2-18: Input Bias Current vs. Input Voltage (Below V_{SS}).

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Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

2.2 Other DC Voltages and Currents

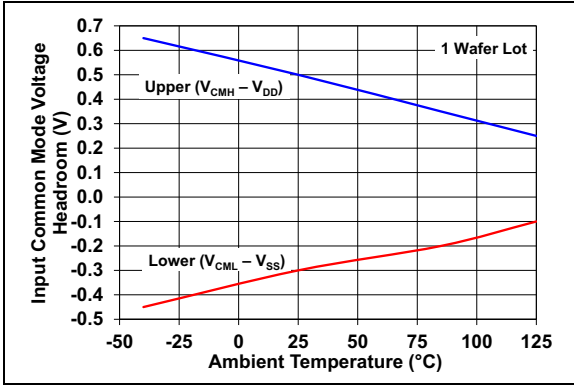


FIGURE 2-19: Input Common Mode Voltage Headroom (Range) vs. Ambient Temperature.

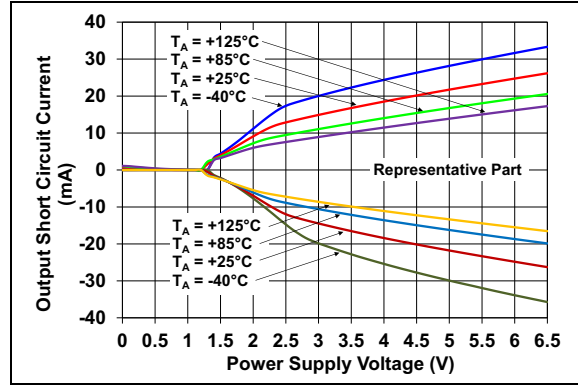


FIGURE 2-22: Output Short Circuit Current vs. Power Supply Voltage.

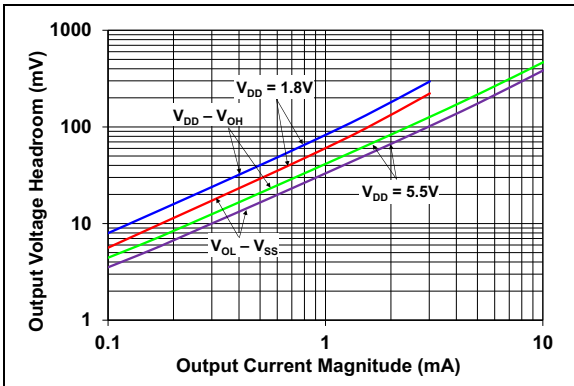


FIGURE 2-20: Output Voltage Headroom vs. Output Current.

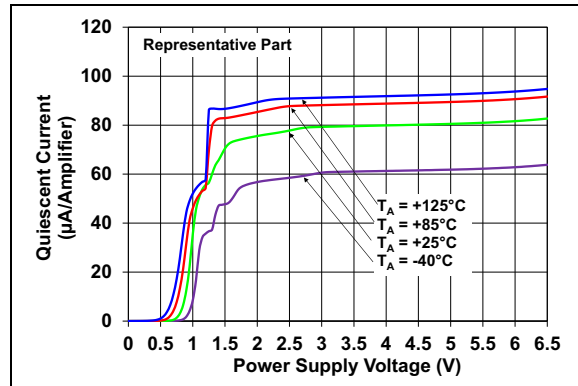


FIGURE 2-23: Supply Current vs. Power Supply Voltage.

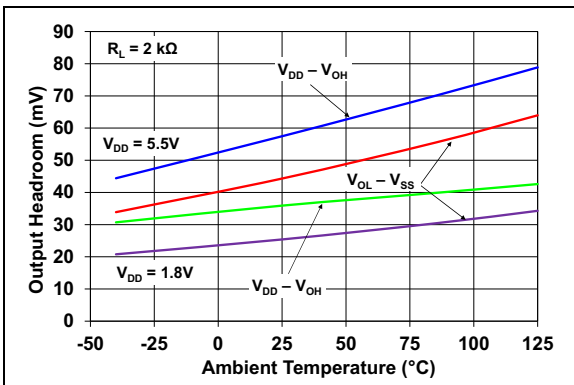


FIGURE 2-21: Output Voltage Headroom vs. Ambient Temperature.

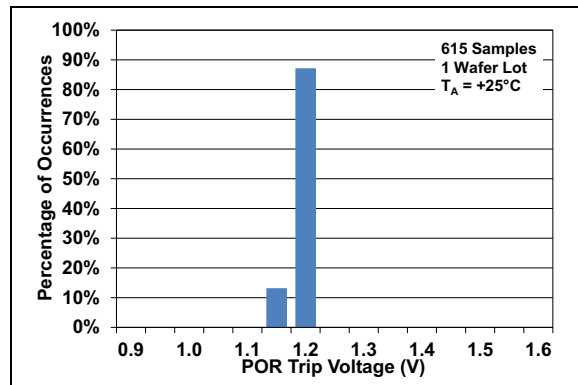


FIGURE 2-24: Power-On Reset Trip Voltage.

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

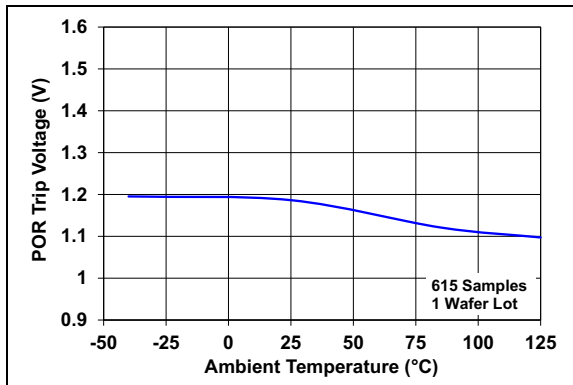


FIGURE 2-25: Power-On Reset Voltage vs. Ambient Temperature.

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Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

2.3 Frequency Response

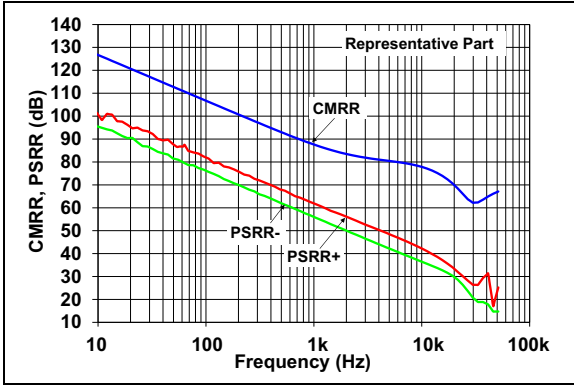


FIGURE 2-26: CMRR and PSRR vs. Frequency.

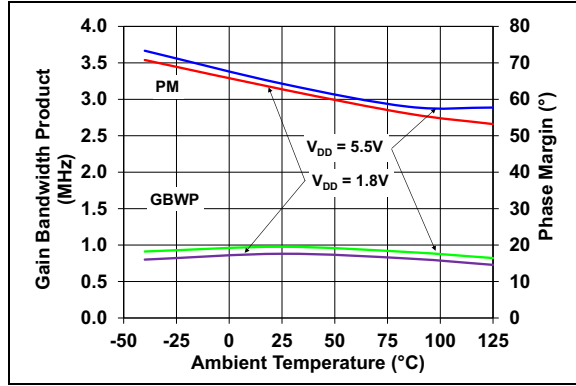


FIGURE 2-29: Gain Bandwidth Product and Phase Margin vs. Ambient Temperature.

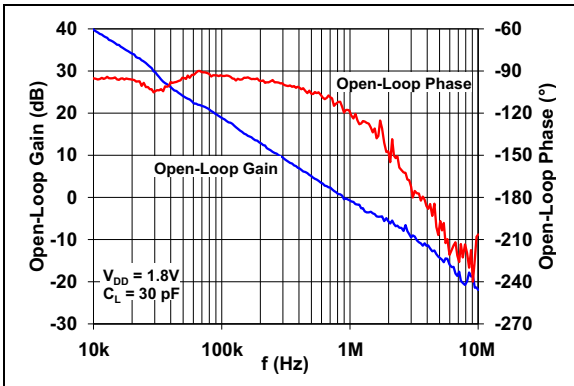


FIGURE 2-27: Open-Loop Gain vs. Frequency with $V_{DD} = 1.8\text{V}$.

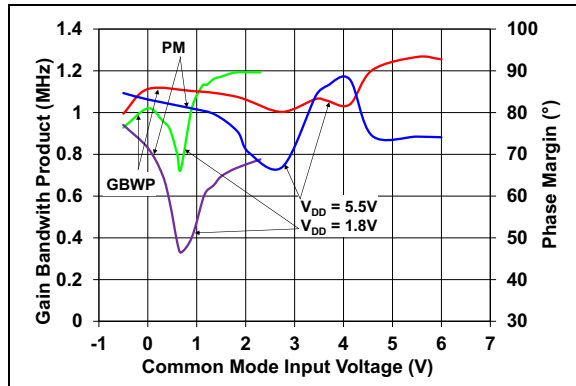


FIGURE 2-30: Gain Bandwidth Product and Phase Margin vs. Common Mode Input Voltage.

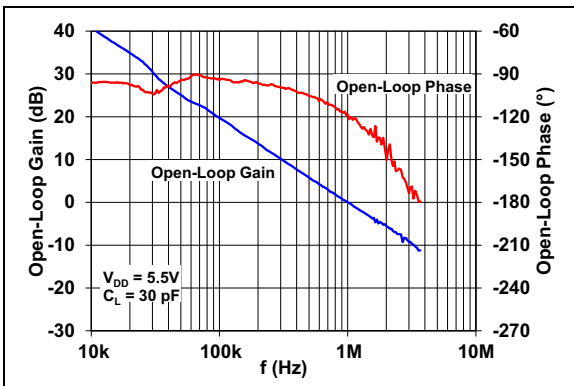


FIGURE 2-28: Open-Loop Gain vs. Frequency with $V_{DD} = 5.5\text{V}$.

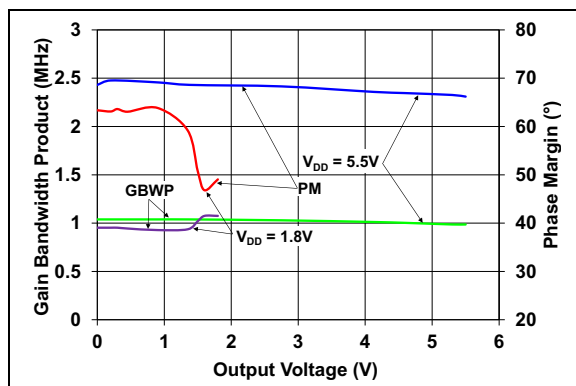


FIGURE 2-31: Gain Bandwidth Product and Phase Margin vs. Output Voltage.

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

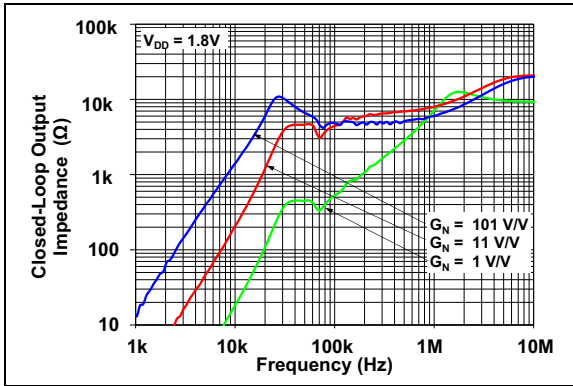


FIGURE 2-32: Closed-Loop Output Impedance vs. Frequency with $V_{DD} = 1.8\text{V}$.

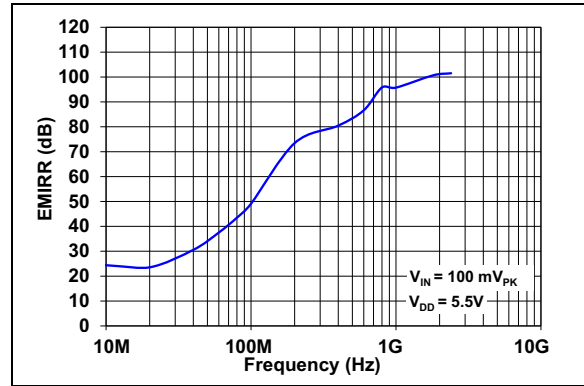


FIGURE 2-35: EMIRR vs. Frequency.

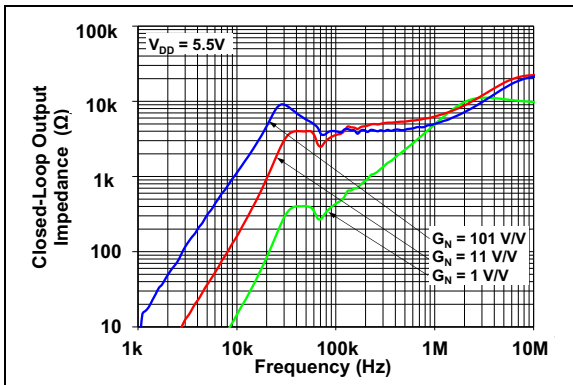


FIGURE 2-33: Closed-Loop Output Impedance vs. Frequency with $V_{DD} = 5.5\text{V}$.

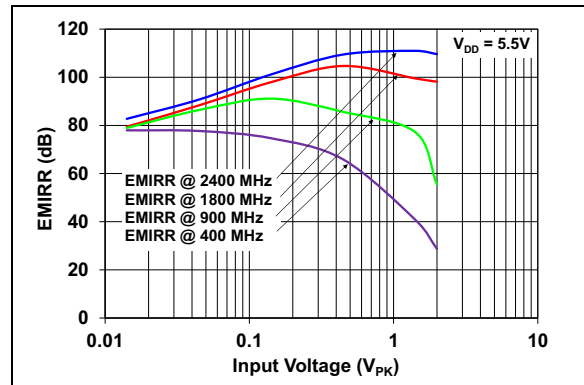


FIGURE 2-36: EMIRR vs. Input Voltage.

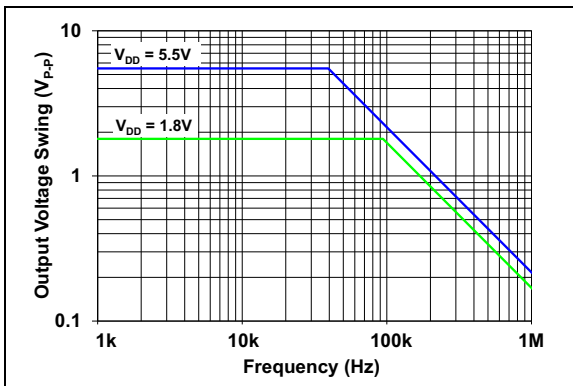


FIGURE 2-34: Maximum Output Voltage Swing vs. Frequency.

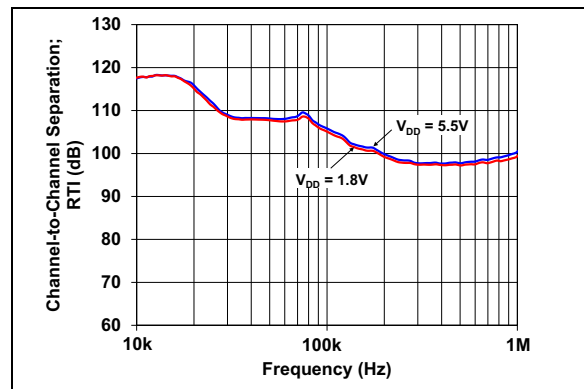


FIGURE 2-37: Channel-to-Channel Separation vs. Frequency.

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Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

2.4 Input Noise and Distortion

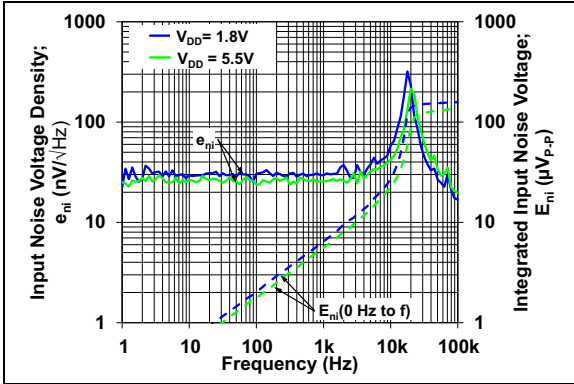


FIGURE 2-38: Input Noise Voltage Density and Integrated Input Noise Voltage vs. Frequency.

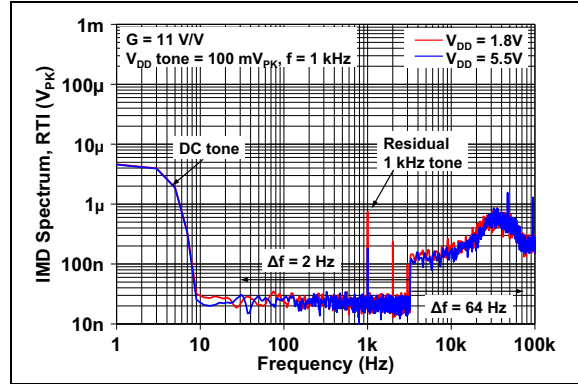


FIGURE 2-41: Inter-Modulation Distortion vs. Frequency with V_{DD} Disturbance (see Figure 1-6).

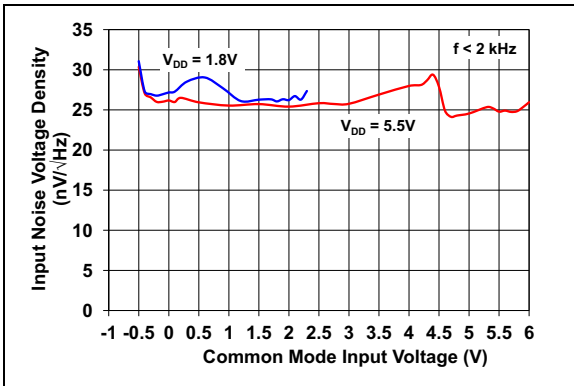


FIGURE 2-39: Input Noise Voltage Density vs. Input Common Mode Voltage.

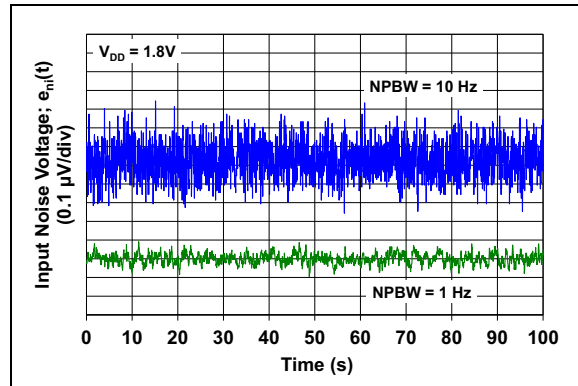


FIGURE 2-42: Input Noise vs. Time with 1 Hz and 10 Hz Filters and $V_{DD} = 1.8\text{V}$.

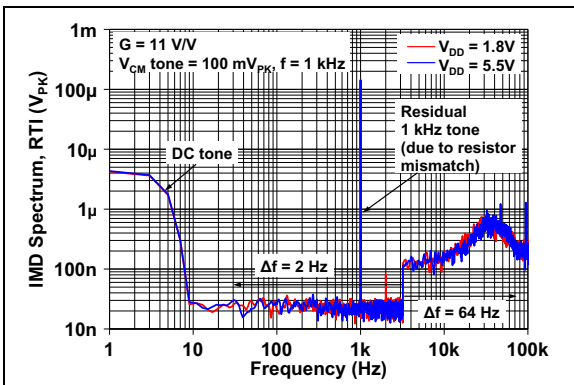


FIGURE 2-40: Intermodulation Distortion vs. Frequency with V_{CM} Disturbance (see Figure 1-6).

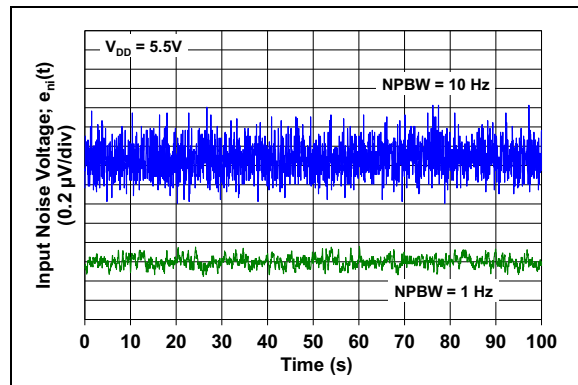


FIGURE 2-43: Input Noise vs. Time with 1 Hz and 10 Hz Filters and $V_{DD} = 5.5\text{V}$.

Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

2.5 Time Response

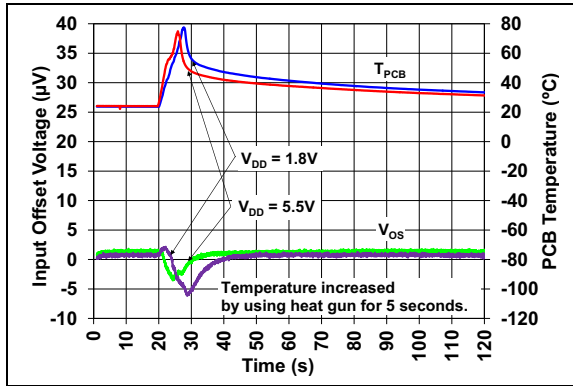


FIGURE 2-44: Input Offset Voltage vs. Time with Temperature Change.

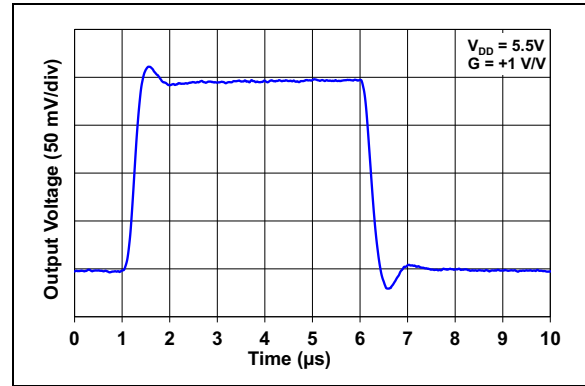


FIGURE 2-47: Non-Inverting Small Signal Step Response.

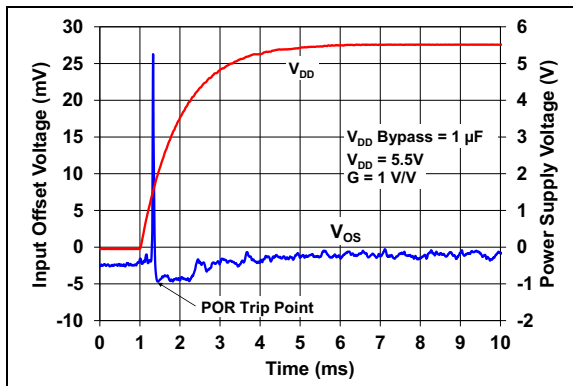


FIGURE 2-45: Input Offset Voltage vs. Time at Power-Up.

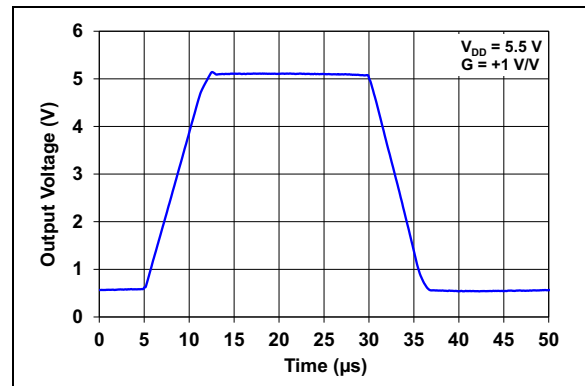


FIGURE 2-48: Non-Inverting Large Signal Step Response.

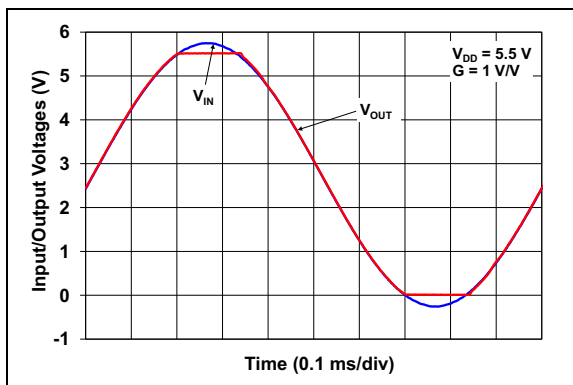


FIGURE 2-46: The MCP6V61/1U/2/4 Family Shows No Input Phase Reversal with Overdrive.

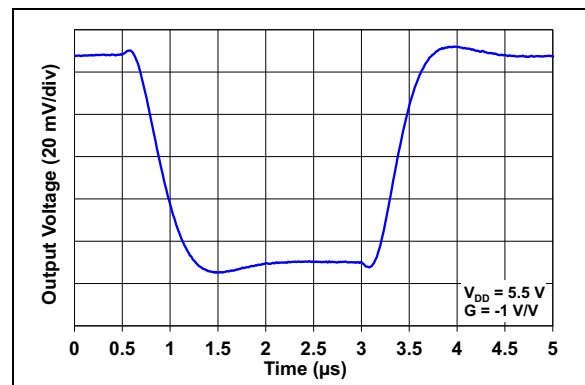


FIGURE 2-49: Inverting Small Signal Step Response.

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Note: Unless otherwise indicated, $T_A = +25^\circ\text{C}$, $V_{DD} = +1.8\text{V}$ to 5.5V , $V_{SS} = \text{GND}$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 20\text{ k}\Omega$ to V_L and $C_L = 30\text{ pF}$.

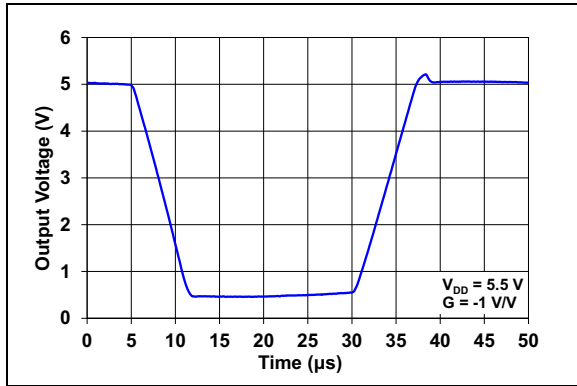


FIGURE 2-50: Inverting Large Signal Step Response.

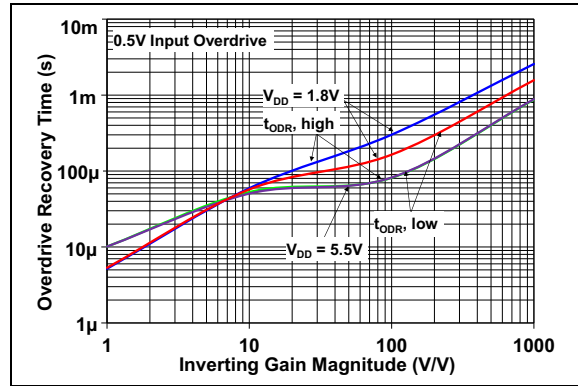


FIGURE 2-53: Output Overdrive Recovery Time vs. Inverting Gain.

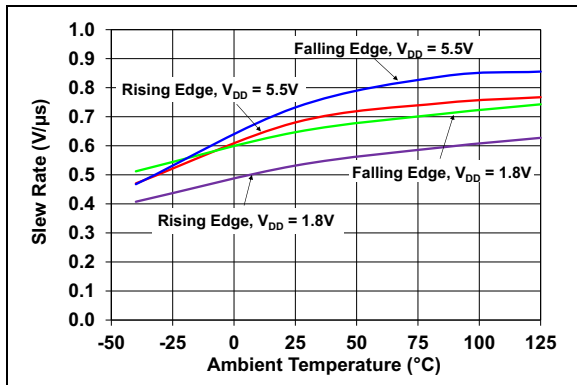


FIGURE 2-51: Slew Rate vs. Ambient Temperature.

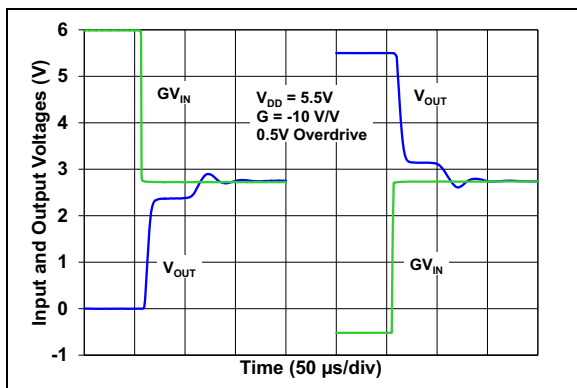


FIGURE 2-52: Output Overdrive Recovery vs. Time with $G = -10\text{ V/V}$.

3.0 PIN DESCRIPTIONS

Descriptions of the pins are listed in [Table 3-1](#).

TABLE 3-1: PIN FUNCTION TABLE

MCP6V61	MCP6V61U	MCP6V62		MCP6V64	Symbol	Description
SOT-23	SOT-23, SC-70	2×3 TDFN	MSOP	TSSOP		
1	4	1	1	1	V_{OUT}, V_{OUTA}	Output (Op Amp A)
2	2	4	4	11	V_{SS}	Negative Power Supply
3	1	3	3	3	V_{IN+}, V_{INA+}	Non-inverting Input (Op Amp A)
4	3	2	2	2	V_{IN-}, V_{INA-}	Inverting Input (Op Amp A)
5	5	8	8	4	V_{DD}	Positive Power Supply
—	—	5	5	5	V_{INB+}	Non-inverting Input (Op Amp B)
—	—	6	6	6	V_{INB-}	Inverting Input (Op Amp B)
—	—	7	7	7	V_{OUTB}	Output (Op Amp B)
—	—	—	—	8	V_{OUTC}	Output (Op Amp C)
—	—	—	—	9	V_{INC-}	Inverting Input (Op Amp C)
—	—	—	—	10	V_{INC+}	Non-inverting Input (Op Amp C)
—	—	—	—	12	V_{IND+}	Non-inverting Input (Op Amp D)
—	—	—	—	13	V_{IND-}	Inverting Input (Op Amp D)
—	—	—	—	14	V_{OUTD}	Output (Op Amp D)
—	—	9	—	—	EP	Exposed Thermal Pad (EP); must be connected to V_{SS}

3.1 Analog Outputs

The analog output pins (V_{OUT}) are low-impedance voltage sources.

3.2 Analog Inputs

The non-inverting and inverting inputs (V_{IN+} , V_{IN-} , ...) are high-impedance CMOS inputs with low bias currents.

3.3 Power Supply Pins

The positive power supply (V_{DD}) is 1.8V to 5.5V higher than the negative power supply (V_{SS}). For normal operation, the other pins are between V_{SS} and V_{DD} .

Typically, these parts are used in a single (positive) supply configuration. In this case, V_{SS} is connected to ground and V_{DD} is connected to the supply. V_{DD} will need bypass capacitors.

3.4 Exposed Thermal Pad (EP)

There is an internal connection between the exposed thermal pad (EP) and the V_{SS} pin; they must be connected to the same potential on the printed circuit board (PCB).

This pad can be connected to a PCB ground plane to provide a larger heat sink. This improves the package thermal resistance (θ_{JA}).

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4.0 APPLICATIONS

The MCP6V61/1U/2/4 family of zero-drift op amps is manufactured using Microchip's state-of-the-art CMOS process. It is designed for precision applications with requirements for small packages and low power. Its low supply voltage and low quiescent current make the MCP6V61/1U/2/4 devices ideal for battery-powered applications.

4.1 Overview of Zero-Drift Operation

Figure 4-1 shows a simplified diagram of the MCP6V61/1U/2/4 zero-drift op amps. This diagram will be used to explain how slow voltage errors are reduced in this architecture (much better V_{OS} , $\Delta V_{OS}/\Delta T_A$ (TC_1), CMRR, PSRR, A_{OL} and $1/f$ noise).

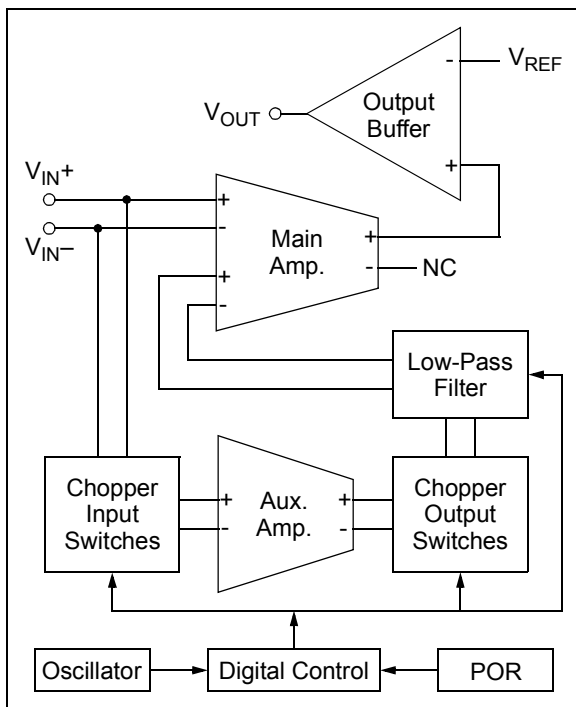


FIGURE 4-1: Simplified Zero-Drift Op Amp Functional Diagram.

4.1.1 BUILDING BLOCKS

The Main Amplifier is designed for high gain and bandwidth, with a differential topology. Its main input pair (+ and - pins at the top left) is used for the higher frequency portion of the input signal. Its auxiliary input pair (+ and - pins at the bottom left) is used for the low-frequency portion of the input signal, and corrects the op amp's input offset voltage. Both inputs are added together internally.

The Auxiliary Amplifier, Chopper Input Switches and Chopper Output Switches provide a high DC gain to the input signal. DC errors are modulated to higher frequencies, while white noise is modulated to low frequency.

The Low-Pass Filter reduces high-frequency content, including harmonics of the chopping clock.

The Output Buffer drives external loads at the V_{OUT} pin (V_{REF} is an internal reference voltage).

The Oscillator runs at $f_{OSC1} = 200$ kHz. Its output is divided by two to produce the chopping clock rate of $f_{CHOP} = 100$ kHz.

The internal Power-on Reset (POR) starts the part in a known good state, protecting against power supply brown-outs.

The Digital Control block controls switching and POR events.

4.1.2 CHOPPING ACTION

Figure 4-2 shows the amplifier connections for the first phase of the chopping clock, and Figure 4-3 shows the connections for the second phase. Its slow voltage errors alternate in polarity, making the average error small.

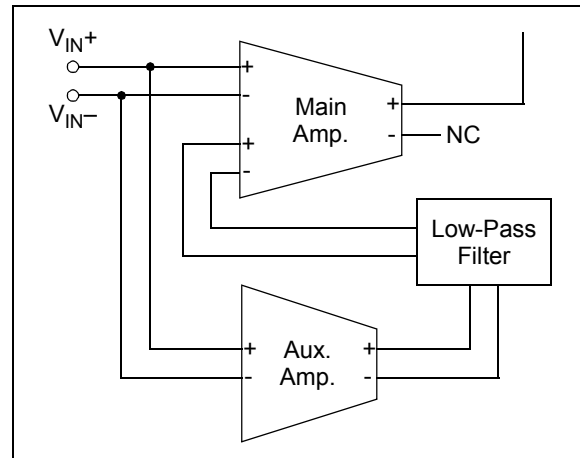


FIGURE 4-2: First Chopping Clock Phase; Equivalent Amplifier Diagram.

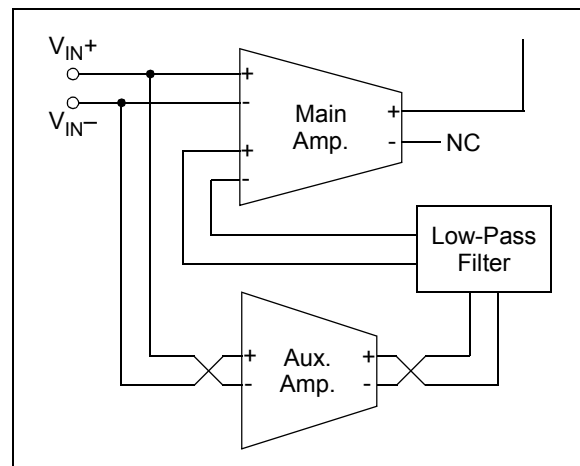


FIGURE 4-3: Second Chopping Clock Phase; Equivalent Amplifier Diagram.

4.1.3 INTERMODULATION DISTORTION (IMD)

These op amps will show intermodulation distortion (IMD) products when an AC signal is present.

The signal and clock can be decomposed into sine wave tones (Fourier series components). These tones interact with the zero-drift circuitry's nonlinear response to produce IMD tones at sum and difference frequencies. Each of the square wave clock's harmonics has a series of IMD tones centered on it. See [Figures 2-40](#) and [2-41](#).

4.2 Other Functional Blocks

4.2.1 RAIL-TO-RAIL INPUTS

The input stage of the MCP6V61/1U/2/4 op amps uses two differential CMOS input stages in parallel. One operates at low Common Mode Input Voltage (V_{CM} , which is approximately equal to V_{IN+} and V_{IN-} in normal operation) and the other at high V_{CM} . With this topology, the input operates with V_{CM} up to $V_{DD} + 0.3V$ and down to $V_{SS} - 0.2V$, at $+25^{\circ}C$ (see [Figure 2-19](#)). The input offset voltage (V_{OS}) is measured at $V_{CM} = V_{SS} - 0.2V$ and $V_{DD} + 0.3V$ to ensure proper operation.

4.2.1.1 Phase Reversal

The input devices are designed to not exhibit phase inversion when the input pins exceed the supply voltages. [Figure 2-46](#) shows an input voltage exceeding both supplies with no phase inversion.

4.2.1.2 Input Voltage Limits

In order to prevent damage and/or improper operation of these amplifiers, the circuit must limit the voltages at the input pins (see [Section 1.1 "Absolute Maximum Ratings †"](#)). This requirement is independent of the current limits discussed later on.

The ESD protection on the inputs can be depicted as shown in [Figure 4-4](#). This structure was chosen to protect the input transistors against many (but not all) overvoltage conditions and to minimize input bias current (I_B).

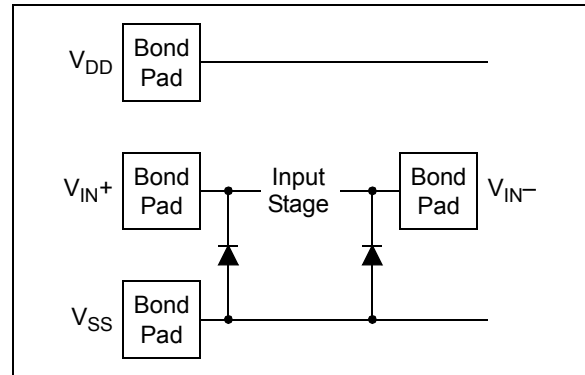


FIGURE 4-4: Simplified Analog Input ESD Structures.

The input ESD diodes clamp the inputs when they try to go more than one diode drop below V_{SS} . They also clamp any voltages well above V_{DD} ; their breakdown voltage is high enough to allow normal operation but not low enough to protect against slow overvoltage (beyond V_{DD}) events. Very fast ESD events (that meet the specification) are limited so that damage does not occur.

In some applications, it may be necessary to prevent excessive voltages from reaching the op amp inputs; [Figure 4-5](#) shows one approach to protecting these inputs. D_1 and D_2 may be small signal silicon diodes, Schottky diodes for lower clamping voltages or diode-connected FETs for low leakage.

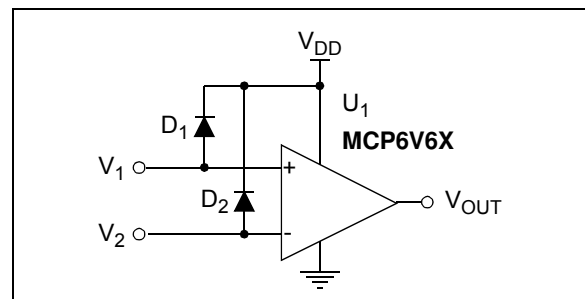


FIGURE 4-5: Protecting the Analog Inputs Against High Voltages.

MCP6V61/1U/2/4

4.2.1.3 Input Current Limits

In order to prevent damage and/or improper operation of these amplifiers, the circuit must limit the currents into the input pins (see [Section 1.1 “Absolute Maximum Ratings †”](#)). This requirement is independent of the voltage limits discussed previously.

[Figure 4-6](#) shows one approach to protecting these inputs. The R_1 and R_2 resistors limit the possible current in or out of the input pins (and into D_1 and D_2). The diode currents will dump onto V_{DD} .

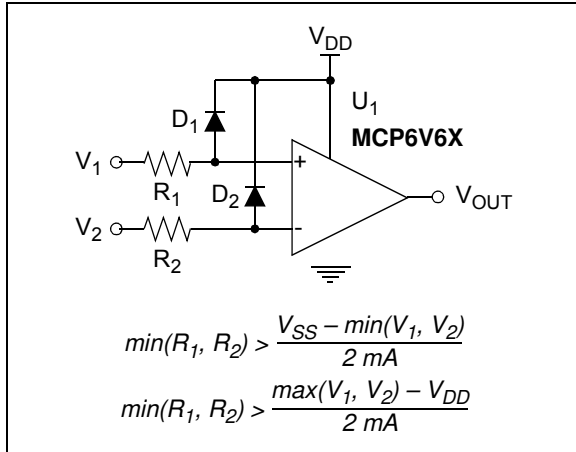


FIGURE 4-6: Protecting the Analog Inputs Against High Currents.

It is also possible to connect the diodes to the left of the R_1 and R_2 resistors. In this case, the currents through the D_1 and D_2 diodes need to be limited by some other mechanism. The resistors then serve as in-rush current limiters; the DC current into the input pins (V_{IN+} and V_{IN-}) should be very small.

A significant amount of current can flow out of the inputs (through the ESD diodes) when the Common Mode Voltage (V_{CM}) is below ground (V_{SS}) (see [Figure 2-18](#)).

4.2.2 RAIL-TO-RAIL OUTPUT

The Output Voltage Range of the MCP6V61/1U/2/4 zero-drift op amps is $V_{DD} - 5.9 \text{ mV}$ (typical) and $V_{SS} + 4.7 \text{ mV}$ (typical) when $R_L = 20 \text{ k}\Omega$ is connected to $V_{DD}/2$ and $V_{DD} = 5.5\text{V}$. Refer to [Figures 2-20](#) and [2-21](#) for more information.

This op amp is designed to drive light loads; use another amplifier to buffer the output from heavy loads.

4.3 Application Tips

4.3.1 INPUT OFFSET VOLTAGE OVER TEMPERATURE

[Table 1-1](#) gives both the linear and quadratic temperature coefficients (TC_1 and TC_2) of input offset voltage. The input offset voltage, at any temperature in the specified range, can be calculated as follows:

EQUATION 4-1:

$$V_{OS}(T_A) = V_{OS} + TC_1 \Delta T + TC_2 \Delta T^2$$

Where:

$$\Delta T = T_A - 25^\circ\text{C}$$

$$V_{OS}(T_A) = \text{Input offset voltage at } T_A$$

$$V_{OS} = \text{Input offset voltage at } +25^\circ\text{C}$$

$$TC_1 = \text{Linear temperature coefficient}$$

$$TC_2 = \text{Quadratic temperature coefficient}$$

4.3.2 DC GAIN PLOTS

[Figures 2-10](#) to [2-12](#) are histograms of the reciprocals (in units of $\mu\text{V/V}$) of CMRR, PSRR and A_{OL} , respectively. They represent the change in Input Offset Voltage (V_{OS}) with a change in Common Mode Input Voltage (V_{CM}), Power Supply Voltage (V_{DD}) and Output Voltage (V_{OUT}). The histograms are based on data taken with the production test equipment and the results reflect the trade-off between accuracy and test time. The actual performance of the devices is typically higher than shown in [Figures 2-10](#) to [2-12](#).

The $1/A_{OL}$ histogram is centered near $0 \mu\text{V/V}$ because the measurements are dominated by the op amp's input noise. The negative values shown represent noise and tester limitations, *not* unstable behavior. Production tests make multiple V_{OS} measurements, which validates an op amp's stability; an unstable part would show greater V_{OS} variability or the output would stick at one of the supply rails.

4.3.3 OFFSET AT POWER-UP

When these parts power up, the input offset (V_{OS}) starts at its uncorrected value (usually less than $\pm 5 \text{ mV}$). Circuits with high DC gain can cause the output to reach one of the two rails. In this case, the time to a valid output is delayed by an output overdrive time (like t_{ODR}) in addition to the start-up time (like t_{STR}).

It can be simple to avoid this extra start-up time. Reducing the gain is one method. Adding a capacitor across the feedback resistor (R_F) is another method.

4.3.4 SOURCE RESISTANCES

The input bias currents have two significant components: switching glitches that dominate at room temperature and below and input ESD diode leakage currents that dominate at +85°C and above.

Make the resistances seen by the inputs small and equal. This minimizes the output offset caused by the input bias currents.

The inputs should see a resistance on the order of 10Ω to 1 kΩ at high frequencies (i.e., above 1 MHz). This helps minimize the impact of switching glitches, which are very fast, on overall performance. In some cases it may be necessary to add resistors in series with the inputs to achieve this improvement in performance.

Small input resistances may be needed for high gains. Without them, parasitic capacitances might cause positive feedback and instability.

4.3.5 SOURCE CAPACITANCE

The capacitances seen by the two inputs should be small. Large input capacitances and source resistances, together with high gain, can lead to positive feedback and instability.

4.3.6 CAPACITIVE LOADS

Driving large capacitive loads can cause stability problems for voltage feedback op amps. As the load capacitance increases, the feedback loop's phase margin decreases and the closed-loop bandwidth is reduced. This produces gain peaking in the frequency response, with overshoot and ringing in the step response. These zero-drift op amps have a different output impedance than most op amps, due to their unique topology.

When driving a capacitive load with these op amps, a series resistor at the output (R_{ISO} in Figure 4-7) improves the feedback loop's phase margin (stability) by making the output load resistive at higher frequencies. The bandwidth will be generally lower than the bandwidth with no capacitive load.

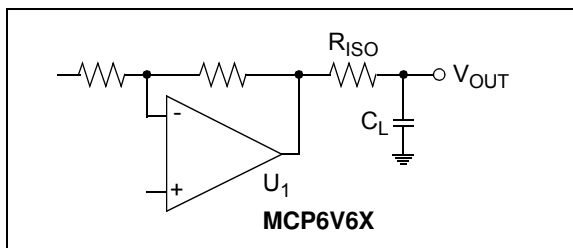


FIGURE 4-7: Output Resistor, R_{ISO} , Stabilizes Capacitive Loads.

Figure 4-8 gives recommended R_{ISO} values for different capacitive loads and gains. The x-axis is the load capacitance (C_L). The y-axis is the resistance (R_{ISO}).

G_N is the circuit's noise gain. For non-inverting gains, G_N and the Signal Gain are equal. For inverting gains, G_N is $1+|\text{Signal Gain}|$ (e.g., -1 V/V gives $G_N = +2$ V/V).

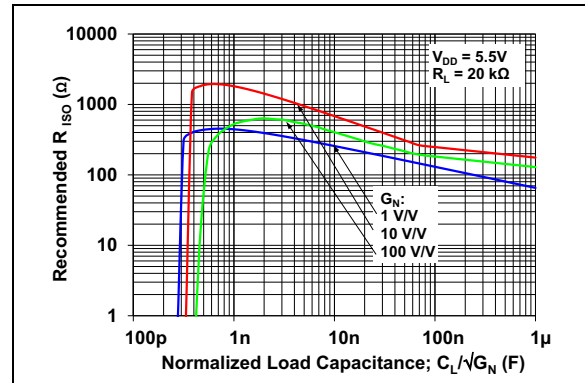


FIGURE 4-8: Recommended R_{ISO} values for Capacitive Loads.

After selecting R_{ISO} for your circuit, double check the resulting frequency response peaking and step response overshoot. Modify the R_{ISO} value until the response is reasonable. Bench evaluation is helpful.

4.3.7 STABILIZING OUTPUT LOADS

This family of zero-drift op amps has an output impedance (Figures 2-32 and 2-33) that has a double zero when the gain is low. This can cause a large phase shift in feedback networks that have low-impedance near the part's bandwidth. This large phase shift can cause stability problems.

Figure 4-9 shows that the load on the output is $(R_L + R_{ISO}) || (R_F + R_G)$, where R_{ISO} is before the load (like Figure 4-7). This load needs to be large enough to maintain stability; it should be at least 10 kΩ.

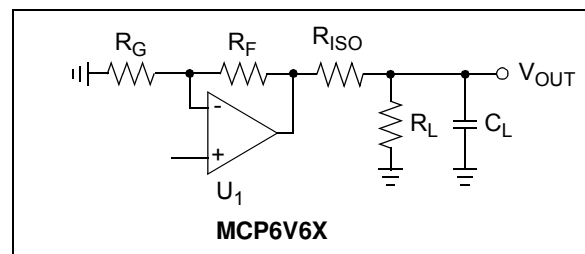


FIGURE 4-9: Output Load.

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4.3.8 GAIN PEAKING

Figure 4-10 shows an op amp circuit that represents non-inverting amplifiers (V_M is a DC voltage and V_P is the input) or inverting amplifiers (V_P is a DC voltage and V_M is the input). The C_N and C_G capacitances represent the total capacitance at the input pins; they include the op amp's Common Mode Input Capacitance (C_{CM}), board parasitic capacitance and any capacitor placed in parallel. The C_{FP} capacitance represents the parasitic capacitance coupling the output and non-inverting input pins.

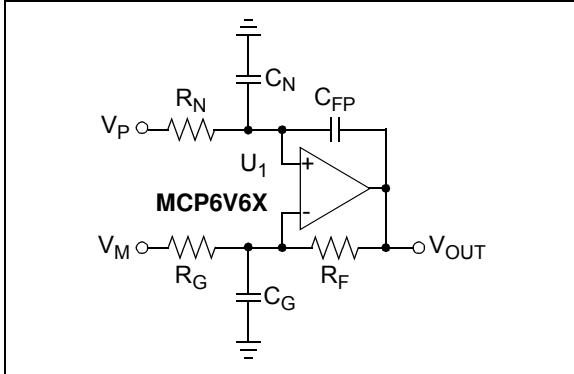


FIGURE 4-10: Amplifier with Parasitic Capacitance.

C_G acts in parallel with R_G (except for a gain of $+1 V/V$), which causes an increase in gain at high frequencies. C_G also reduces the phase margin of the feedback loop, which becomes less stable. This effect can be reduced by either reducing C_G or $R_F || R_G$.

C_N and R_N form a low-pass filter that affects the signal at V_P . This filter has a single real pole at $1/(2\pi R_N C_N)$.

The largest value of R_F that should be used depends on noise gain (see G_N in [Section 4.3.6 "Capacitive Loads"](#)), C_G and the open-loop gain's phase shift. An approximate limit for R_F is:

EQUATION 4-2:

$$R_F \leq 10 \text{ k}\Omega \times \frac{3.5 \text{ pF}}{C_G} \times G_N^2$$

Some applications may modify these values to reduce either output loading or gain peaking (step-response overshoot).

At high gains, R_N needs to be small in order to prevent positive feedback and oscillations. Large C_N values can also help.

4.3.9 REDUCING UNDESIRE NOISE AND SIGNALS

Reduce undesired noise and signals with:

- Low bandwidth signal filters:
 - Minimize random analog noise
 - Reduce interfering signals
- Good PCB layout techniques:
 - Minimize crosstalk
 - Minimize parasitic capacitances and inductances that interact with fast switching edges
- Good power supply design:
 - Isolation from other parts
 - Filtering of interference on supply line(s)

4.3.10 SUPPLY BYPASSING AND FILTERING

With this family of operational amplifiers, the power supply pin (V_{DD} for single supply) should have a local bypass capacitor (i.e., $0.01 \mu\text{F}$ to $0.1 \mu\text{F}$) within 2 mm of the pin for good high-frequency performance.

These parts also need a bulk capacitor (i.e., $1 \mu\text{F}$ or larger) within 100 mm to provide large, slow currents. This bulk capacitor can be shared with other low-noise analog parts.

In some cases, high-frequency power supply noise (e.g., switched mode power supplies) may cause undue intermodulation distortion with a DC offset shift; this noise needs to be filtered. Adding a small resistor into the supply connection can be helpful.

4.3.11 PCB DESIGN FOR DC PRECISION

In order to achieve DC precision on the order of $\pm 1 \mu\text{V}$, many physical errors need to be minimized. The design of the Printed Circuit Board (PCB), the wiring and the thermal environment have a strong impact on the precision achieved. A poor PCB design can easily be more than 100 times worse than the MCP6V61/1U/2/4 op amps' minimum and maximum specifications.

4.3.11.1 PCB Layout

Any time two dissimilar metals are joined together, a temperature-dependent voltage appears across the junction (the Seebeck or thermojunction effect). This effect is used in thermocouples to measure temperature. The following are examples of thermojunctions on a PCB:

- Components (resistors, op amps, ...) soldered to a copper pad
- Wires mechanically attached to the PCB
- Jumpers
- Solder joints
- PCB vias

Typical thermojunctions have temperature-to-voltage conversion coefficients of 1 to 100 $\mu\text{V}/^\circ\text{C}$ (sometimes higher).

Microchip's AN1258 ("Op Amp Precision Design: PCB Layout Techniques") contains in-depth information on PCB layout techniques that minimize thermojunction effects. It also discusses other effects, such as crosstalk, impedances, mechanical stresses and humidity.

4.3.11.2 Crosstalk

DC crosstalk causes offsets that appear as a larger input offset voltage. Common causes include:

- Common mode noise (remote sensors)
- Ground loops (current return paths)
- Power supply coupling

Interference from the mains (usually 50 Hz or 60 Hz) and other AC sources can also affect the DC performance. Nonlinear distortion can convert these signals to multiple tones, including a DC shift in voltage. When the signal is sampled by an ADC, these AC signals can also be aliased to DC, causing an apparent shift in offset.

To reduce interference:

- Keep traces and wires as short as possible
- Use shielding
- Use ground plane (at least a star ground)
- Place the input signal source near the DUT
- Use good PCB layout techniques
- Use a separate power supply filter (bypass capacitors) for these zero-drift op amps

4.3.11.3 Miscellaneous Effects

Keep the resistances seen by the input pins as small and as near to equal as possible to minimize bias current-related offsets.

Make the (trace) capacitances seen by the input pins small and equal. This is helpful in minimizing switching glitch-induced offset voltages.

Bending a coax cable with a radius that is too small causes a small voltage drop to appear on the center conductor (the triboelectric effect). Make sure the bending radius is large enough to keep the conductors and insulation in full contact.

Mechanical stresses can make some capacitor types (such as some ceramics) output small voltages. Use more appropriate capacitor types in the signal path and minimize mechanical stresses and vibration.

Humidity can cause electrochemical potential voltages to appear in a circuit. Proper PCB cleaning helps, as does the use of encapsulants.

4.4 Typical Applications

4.4.1 WHEATSTONE BRIDGE

Many sensors are configured as Wheatstone bridges. Strain gauges and pressure sensors are two common examples. These signals can be small and the Common mode noise large. Amplifier designs with high differential gain are desirable.

Figure 4-11 shows how to interface to a Wheatstone bridge with a minimum of components. Because the circuit is not symmetric, the ADC input is single-ended and there is a minimum of filtering; the CMRR is good enough for moderate Common mode noise.

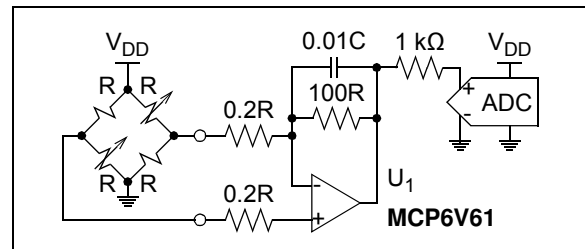


FIGURE 4-11: Simple Design.

4.4.2 RTD SENSOR

The ratiometric circuit in Figure 4-12 conditions a two-wire RTD for applications with a limited temperature range. U_1 acts as a difference amplifier with a low-frequency pole. The sensor's wiring resistance (R_W) is corrected in firmware. Failure (open) of the RTD is detected by an out-of-range voltage.

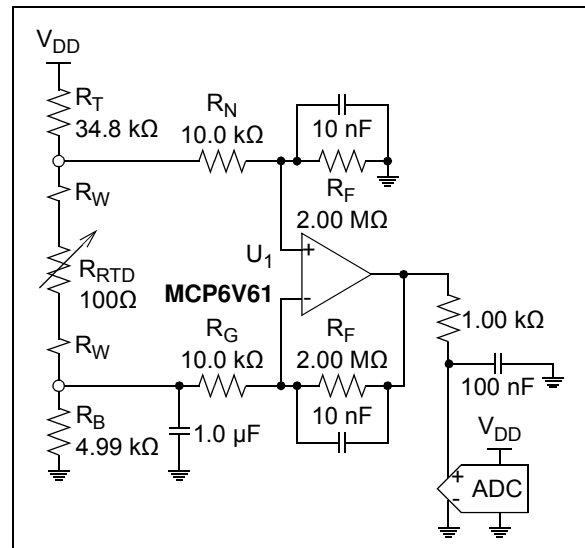


FIGURE 4-12: RTD Sensor.

MCP6V61/1U/2/4

4.4.3 OFFSET VOLTAGE CORRECTION

Figure 4-13 shows MCP6V61 (U_2) correcting the input offset voltage of another op amp (U_1). R_2 and C_2 integrate the offset error seen at U_1 's input; the integration needs to be slow enough to be stable (with the feedback provided by R_1 and R_3). R_4 and R_5 attenuate the integrator's output; this shifts the integrator pole down in frequency.

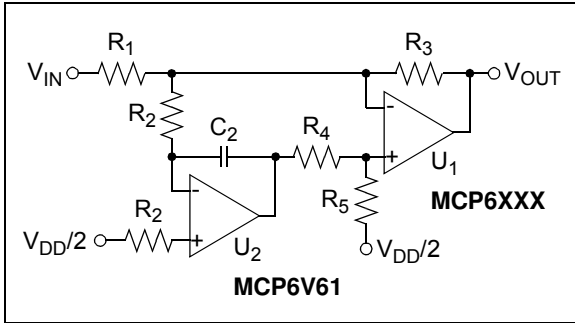


FIGURE 4-13: Offset Correction.

4.4.4 PRECISION COMPARATOR

Use high gain before a comparator to improve the latter's performance. Do not use MCP6V61/1U/2/4 as a comparator by itself; the V_{OS} correction circuitry does not operate properly without a feedback loop.

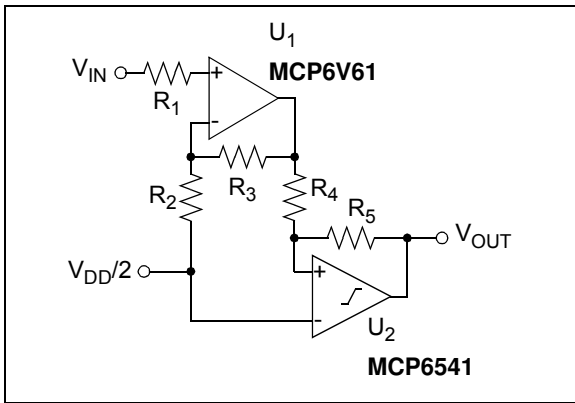


FIGURE 4-14: Precision Comparator.

5.0 DESIGN AIDS

Microchip provides the basic design aids needed for the MCP6V61/1U/2/4 family of op amps.

5.1 SPICE Macro Model

The latest SPICE macro model for the MCP6V61/1U/2/4 op amps is available on the Microchip web site at www.microchip.com. This model is intended to be an initial design tool that works well in the op amp's linear region of operation over the temperature range. See the model file for information on its capabilities.

Bench testing is a very important part of any design and cannot be replaced with simulations. Also, simulation results using this macro model need to be validated by comparing them to the data sheet specifications and characteristics curves.

5.2 FilterLab[®] Software

Microchip's FilterLab[®] software is an innovative software tool that simplifies analog active filter (using op amps) design. Available at no cost from the Microchip web site at www.microchip.com/filterlab, the FilterLab design tool provides full schematic diagrams of the filter circuit with component values. It also outputs the filter circuit in SPICE format, which can be used with the macro model to simulate actual filter performance.

5.3 Microchip Advanced Part Selector (MAPS)

MAPS is a software tool that helps efficiently identify Microchip devices that fit a particular design requirement. Available at no cost from the Microchip web site at www.microchip.com/maps, MAPS is an overall selection tool for Microchip's product portfolio that includes Analog, Memory, MCUs and DSCs. Using this tool, a customer can define a filter to sort features for a parametric search of devices and export side-by-side technical comparison reports. Helpful links are also provided for data sheets, purchase and sampling of Microchip parts.

5.4 Analog Demonstration and Evaluation Boards

Microchip offers a broad spectrum of Analog Demonstration and Evaluation Boards that are designed to help customers achieve faster time to market. For a complete listing of these boards and their corresponding user's guides and technical information, visit the Microchip web site at www.microchip.com/analog_tools.

Some boards that are especially useful are:

- MCP6V01 Thermocouple Auto-Zeroed Reference Design (P/N MCP6V01RD-TCPL)
- MCP6XXX Amplifier Evaluation Board 1 (P/N DS51667)
- MCP6XXX Amplifier Evaluation Board 2 (P/N DS51668)
- MCP6XXX Amplifier Evaluation Board 3 (P/N DS51673)
- MCP6XXX Amplifier Evaluation Board 4 (P/N DS51681)
- Active Filter Demo Board Kit (P/N DS51614)
- 8-Pin SOIC/MSOP/TSSOP/DIP Evaluation Board (P/N SOIC8EV)
- 14-Pin SOIC/TSSOP/DIP Evaluation Board (P/N SOIC14EV)

5.5 Application Notes

The following Microchip Application Notes are available on the Microchip web site at www.microchip.com/appnotes and are recommended as supplemental reference resources.

ADN003: "Select the Right Operational Amplifier for your Filtering Circuits", DS21821

AN722: "Operational Amplifier Topologies and DC Specifications", DS00722

AN723: "Operational Amplifier AC Specifications and Applications", DS00723

AN884: "Driving Capacitive Loads With Op Amps", DS00884

AN990: "Analog Sensor Conditioning Circuits – An Overview", DS00990

AN1177: "Op Amp Precision Design: DC Errors", DS01177

AN1228: "Op Amp Precision Design: Random Noise", DS01228

AN1258: "Op Amp Precision Design: PCB Layout Techniques", DS01258

These Application Notes and others are listed in the design guide:

"Signal Chain Design Guide", DS21825