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Multi-Channel Low-Temperature Remote Diode Sensor

Features

- Up to Three External Temperature Monitors
 - $\pm 1^{\circ}\text{C}$ maximum accuracy
 - MCP9902: -40°C to $+105^{\circ}\text{C}$
 - MCP9903/4: -40°C to $+125^{\circ}\text{C}$
 - $\pm 2^{\circ}\text{C}$ maximum accuracy ($+65^{\circ}\text{C} < T_{\text{DIODE}} < +125^{\circ}\text{C}$)
 - 0.125°C resolution
- Internal Temperature Monitor
 - $\pm 1^{\circ}\text{C}$ accuracy
 - (-40°C to $+65^{\circ}\text{C}$)
 - 0.125°C resolution
- Supports up to 2.2 nF diode filter capacitor
- Up to 400 kHz clock rate
 - Maskable with register control
- Programmable SMBus address
- Operating voltage: 3.0 to 3.6 (V)
- ESD protection: 2 kV HBM
- Temperature Range: -40°C to $+125^{\circ}\text{C}$
- Available in a small 8-Lead 2x2 mm WDFN and 10-lead 3x3 mm VDFN packages

Typical Applications

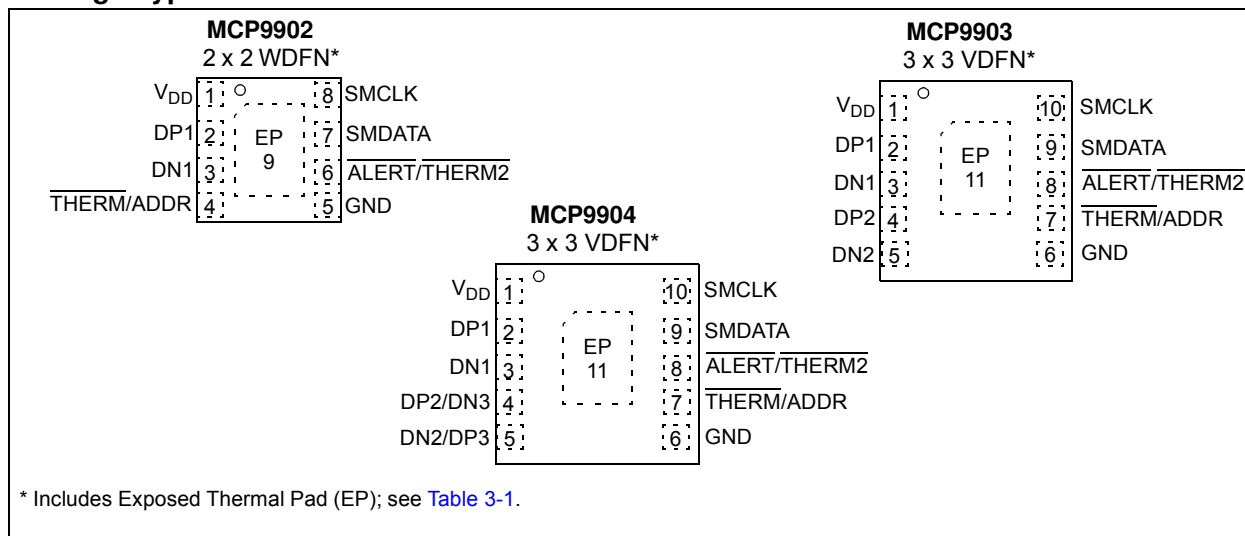
- General Purpose Temperature Sensing
- Industrial Freezers and Refrigerators
- Food Processing
- Base Stations
- Remote Radio Unit

Description

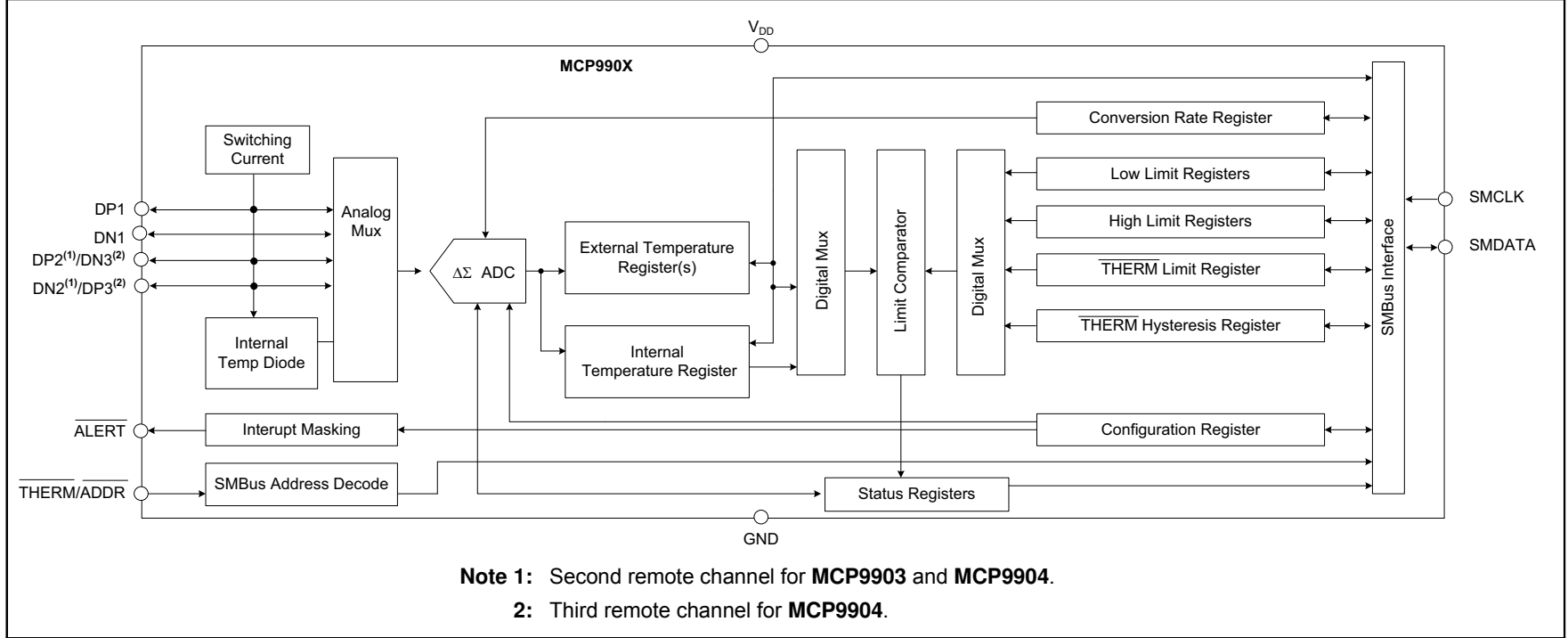
The MCP9902/3/4 is a high-accuracy, low-cost, System Management Bus (SMBus) temperature sensor. The MCP9902/3/4 monitors up to four temperature channels. Advanced features such as Resistance Error Correction (REC), Beta Compensation and automatic diode-type detection combine to provide a robust solution for complex environmental monitoring applications.

Resistance Error Correction automatically eliminates the temperature error caused by series resistance allowing greater flexibility in routing thermal diodes. Beta Compensation eliminates temperature errors caused by low, variable beta transistors common in today's fine geometry processors. The automatic beta detection feature monitors the external diode/transistor and determines the optimum sensor settings for accurate temperature measurements regardless of processor technology. This frees the user from providing unique sensor configurations for each temperature monitoring application. These advanced features plus $\pm 1^{\circ}\text{C}$ measurement accuracy for both external and internal diode temperatures provide a low-cost, highly flexible and accurate solution for critical temperature monitoring applications.

Package Types



MCP9902/3/4 Functional Block Diagram



1.0 ELECTRICAL CHARACTERISTICS

1.1 Electrical Specifications

Absolute Maximum Ratings^(†)

Ambient Temperature under Bias.....	-40°C to +125°C
Storage Temperature	-65°C to +150°C
Voltage on V _{DD} with respect to V _{SS}	-0.3V to +4.0V
Voltage on all other pins with respect to V _{SS}	-0.3V to (V _{DD} + 0.3V)
Total Power Dissipation ^(†)	500 mW
Maximum Current out of V _{SS} pin	20 mA
Maximum Current into V _{DD} pin	20 mA
Clamp Current, I _K (V _{PIN} < 0 or V _{PIN} > V _{DD}).....	± 20 mA
ESD Rating, All pins HBM.....	2000V
Input Current, any pin Except V _{DD}	± 10 mA

† **NOTICE:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure above maximum rating conditions for extended periods may affect device reliability.

Note 1: Power dissipation is calculated as follows: $P_{DIS} = V_{DD} \times \{I_{DD} - \sum I_{OH}\} + \sum \{(V_{DD} - V_{OH}) \times I_{OH}\} + \sum (V_{OL} \times I_{OL})$. Rating up to +85°C.

1.2 DC Characteristics

Electrical Characteristics: Unless otherwise specified, $3.0 \leq V_{DD} \leq 3.6V$ at $-40^\circ C \leq T_A \leq +125^\circ C$						
Characteristic	Sym.	Min.	Typ.	Max.	Units	Conditions
Power Supply						
Supply Voltage	V _{DD}	3.0	3.3	3.6	V	—
Supply Current	I _{DD}	—	200	450	µA	0.0625 conversion/second, dynamic averaging disabled
		—	225	600	µA	1 conversion/second, dynamic averaging enabled
		—	450	850	µA	4 conversions/second, dynamic averaging enabled
		—	1120	1500	µA	≥ 16 conversions/second, dynamic averaging enabled
One-Shot Supply Current	I _{DD_OS}	—	170	230	µA	Device in One-Shot state, no active SMBus communications, \overline{ALERT} and \overline{THERM} pins not asserted.
Standby Supply Current	I _{DD_SBY}	—	170	230	µA	Device in Standby state, no SMBus communications, \overline{ALERT} and \overline{THERM} pins not asserted.
Power-on Reset Voltage	POR_V	—	0.6	0.9	V	Pin states defined
Power-On Reset Release Voltage	PORR	—	1.45	—	V	Rising V _{DD}
Power-Up Timer	t _{PWRT}	—	10	—	ms	—
V _{DD} Rise Rate	V _{DD_RISE}	0.05	—	—	V/ms	0 to 3V in 60 ms
Supply Voltage	V _{DD}	3.0	3.3	3.6	V	—

MCP9902/3/4

1.2 DC Characteristics (Continued)

Electrical Characteristics: Unless otherwise specified, $3.0 \leq V_{DD} \leq 3.6V$ at $-40^{\circ}C \leq T_A \leq +125^{\circ}C$						
Characteristic	Sym.	Min.	Typ.	Max.	Units	Conditions
External Temperature Monitor						
Temperature Accuracy (MCP9902)	—	-1	± 0.25	+1	$^{\circ}C$	$-40^{\circ}C < T_{DIODE} < +105^{\circ}C$, $-40^{\circ}C < T_A < +65^{\circ}C$
		-2	± 0.25	+2	$^{\circ}C$	$-40^{\circ}C < T_{DIODE} < +125^{\circ}C$ $-40^{\circ}C < T_A < +125^{\circ}C$
Temperature Accuracy (MCP9903, MCP9904)	—	-1	± 0.25	+1	$^{\circ}C$	$-40^{\circ}C < T_{DIODE} < +125^{\circ}C$, $-40^{\circ}C < T_A < +65^{\circ}C$
		-2	± 0.25	+2	$^{\circ}C$	$+40^{\circ}C < T_{DIODE} < +125^{\circ}C$ $-40^{\circ}C < T_A < +125^{\circ}C$
Temperature Resolution	—	—	0.125	—	$^{\circ}C$	—
Internal Temperature Monitor						
Temperature Accuracy	—	-1	± 0.25	+1	$^{\circ}C$	$-40^{\circ}C < T_A < +65^{\circ}C$
		-2	± 0.5	+2	$^{\circ}C$	$-40^{\circ}C < T_A < +125^{\circ}C$
Temperature Resolution	—	—	0.125	—	$^{\circ}C$	—
Timing and Capacitive Filter						
Time to First Communications	t_{INT_T}	—	15	20	ms	Time after power up before ready to begin communications and measurement
Conversion Time All Channels (MCP9903, MCP9904)	t_{CONV}	—	190	—	ms	Default settings
Conversion Time All Channels (MCP9902)	t_{CONV}	—	150	—	ms	Default settings
Time to First Conversion from Standby	t_{CONV1}	—	220	—	ms	Default settings
Capacitive Filter	C_{FILTER}	—	2.2	2.7	nF	Connected across external diode
ALERT and THERM Pins						
Output Low Voltage	V_{OL}	0.4	—	—	V	$I_{SINK} = 8\text{ mA}$
Leakage Current	I_{LEAK}	—	—	± 5	μA	ALERT and THERM pins Device powered or unpowered $T_A < +85^{\circ}C$ pull-up voltage $\leq 3.6V$

1.3 Thermal Specifications

Electrical Characteristics: Unless otherwise specified, $3.0 \leq V_{DD} \leq 3.6V$ at $-40^{\circ}C \leq T_A \leq +125^{\circ}C$						
Parameters	Sym.	Min.	Typ.	Max.	Units	Test Conditions
Temperature Ranges						
Specified Temperature Range	T_A	-40	—	+125	$^{\circ}C$	
Operating Temperature Range	T_A	-40	—	+125	$^{\circ}C$	
Storage Temperature Range	T_A	-65	—	+125	$^{\circ}C$	
Thermal Package Resistances (Note 1)						
Thermal Resistance, 8L-WDFN, 2x2	θ_{JA}	—	141.3	—	$^{\circ}C/W$	

1.3 Thermal Specifications

Electrical Characteristics: Unless otherwise specified, $3.0 \leq V_{DD} \leq 3.6V$ at $-40^{\circ}C \leq T_A \leq +125^{\circ}C$

Parameters	Sym.	Min.	Typ.	Max.	Units	Test Conditions
Thermal Resistance, 10L-VDFN, 3x3	θ_{JA}	—	78	—	$^{\circ}C/W$	

Note 1: JEDEC 2s2p, board size 76.2 x 114.3 x 1.6 mm, 1 via, airflow = 0 m/s.

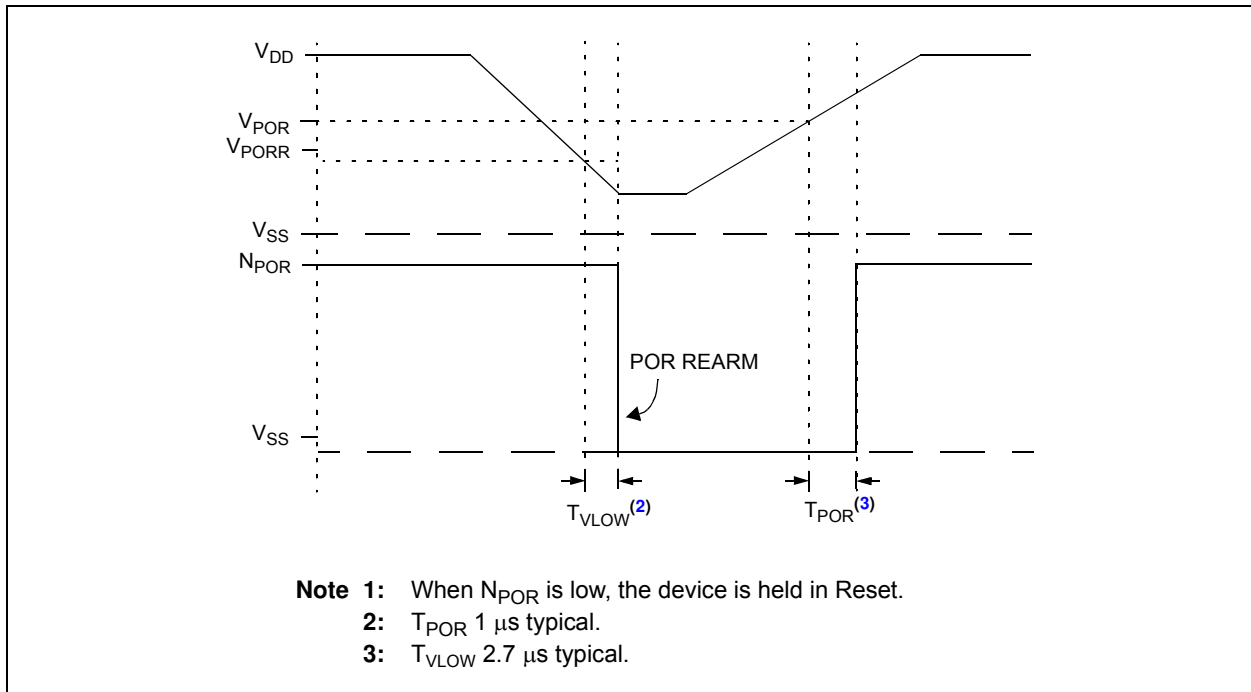


FIGURE 1-1: POR and POR Rearm With Slow Rising V_{DD} .

MCP9902/3/4

1.4 SMBUS Module Specifications

Operating Conditions (unless otherwise indicated): $3.0V \leq V_{DD} \leq 3.6V$ at $-40^{\circ}C \leq T_A \leq +85^{\circ}C$						
Characteristic	Sym.	Min.	Typ.	Max.	Units	Conditions
SMBus Interface						
Input High Voltage	V_{IH}	2.1	—	V_{DD}	V	—
Input Low Voltage	V_{IL}	-0.3	—	0.8	V	—
Leakage Current	I_{LEAK}	—	—	± 5	μA	Powered or unpowered $T_A < +85^{\circ}C$
Hysteresis		—	$0.1 * V_{DD}$	—	mV	—
Input Capacitance	C_{IN}	—	5	—	pF	—
Output Low Sink Current	I_{OL}	8.2	—	15	mA	SMDATA = 0.2V
SMBus Timing						
Clock Frequency	f_{SMB}	10	—	400	kHz	—
Spike Suppression	t_{SP}	—	—	50	ns	—
Bus Free Time Stop to Start	t_{BUF}	1.3	—	—	μs	—
Hold Time: Start	$t_{HD:STA}$	0.6	—	—	μs	—
Setup Time: Start	$t_{SU:STA}$	0.6	—	—	μs	—
Setup Time: Stop	$t_{SU:STO}$	0.6	—	—	μs	—
Data Hold Time	$t_{HD:DAT}$	0	—	—	μs	—
Data Hold Time	$t_{HD:DAT}$	0.3	—	—	μs	When transmitting to the master
Data Setup Time	$t_{SU:DAT}$	100	—	—	ns	When receiving from the master
Clock Low Period	t_{LOW}	1.3	—	—	μs	—
Clock High Period	t_{HIGH}	0.6	—	—	μs	—
Clock/Data Fall Time	t_{FALL}	—	—	300	ns	—
Clock/Data Rise Time	t_{RISE}	—	—	300	ns	Min = $20 + 0.1 C_{LOAD}$ ns
Capacitive Load	C_{LOAD}	—	—	400	pF	Min = $20 + 0.1 C_{LOAD}$ ns
Timeout	$t_{TIME-OUT}$	25	—	35	ms	Per bus line
Clock Frequency	f_{SMB}	10	—	400	kHz	Disabled by default

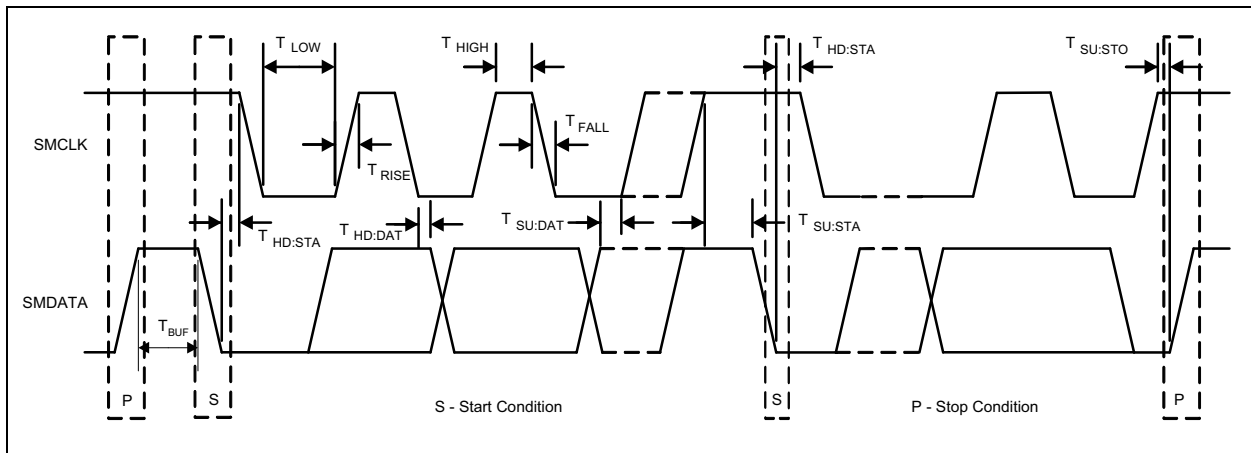


FIGURE 1-2: SMBus Timing Diagram.

2.0 TYPICAL OPERATING CURVES

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

Note: Unless otherwise indicated $3.0 \leq V_{DD} \leq 3.6V$ at $-40^{\circ}C \leq T_A \leq +125^{\circ}C$.

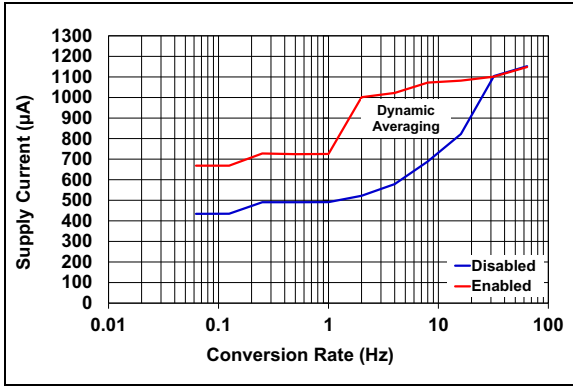


FIGURE 2-1: Supply Current vs. Conversion Rate ($T_A = +25^{\circ}C$, $V_{DD} = 3.3V$).

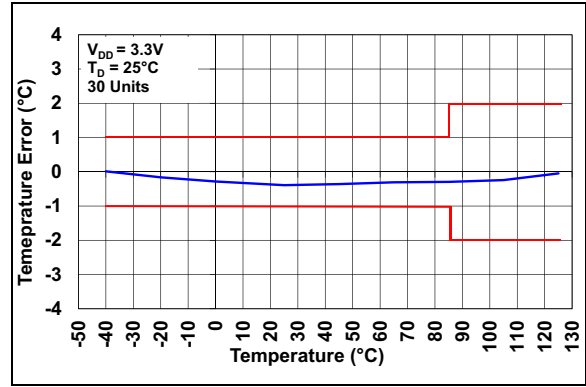


FIGURE 2-4: Temperature Error vs. Ambient Temperature ($V_{DD} = 3.3V$, $T_D = +25^{\circ}C$, 16 Units, 2N3904).

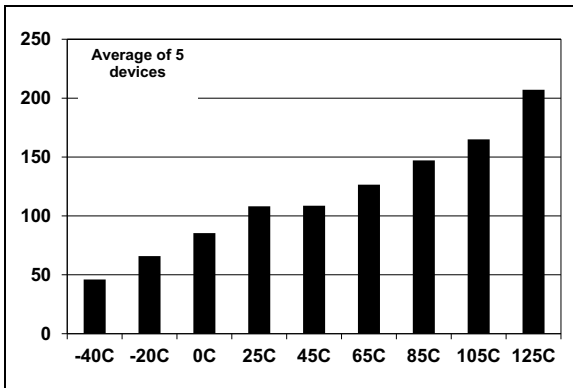


FIGURE 2-2: I_{DD} vs. Temperature.

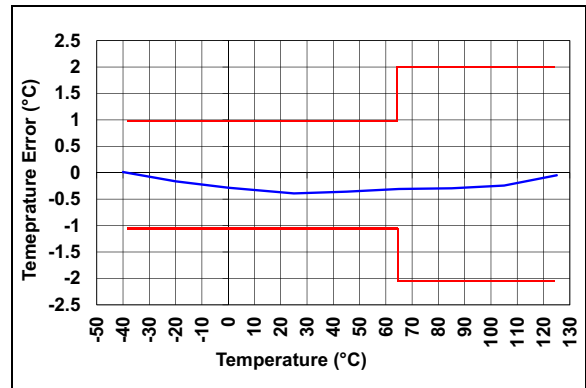


FIGURE 2-5: Temperature Error vs. Remote Temperature. ($V_{DD} = 3.3V$, $T_D = +25^{\circ}C$, 16 Units, 2N3904).

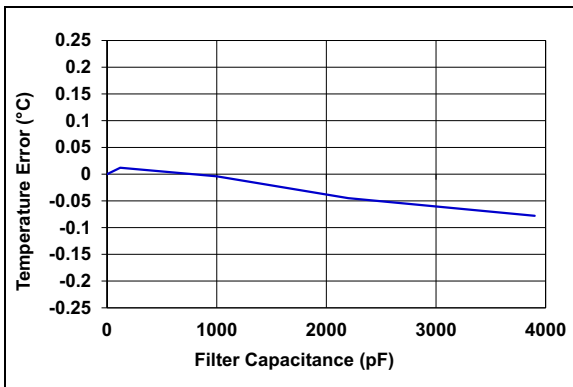


FIGURE 2-3: Temperature Error vs. Filter Capacitor ($V_{DD} = 3.3V$, $T_A = T_D = +25^{\circ}C$, 2N3904).

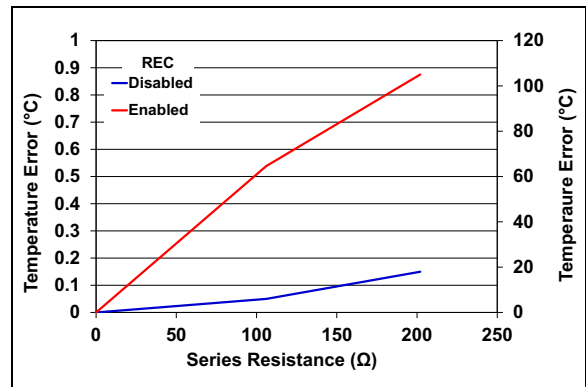


FIGURE 2-6: Temperature Error vs. Series Resistance ($T_A = +25^{\circ}C$, $V_{DD} = 3.3V$).

MCP9902/3/4

3.0 PIN DESCRIPTIONS

The MCP9902/3/4 has two variants that include features unique to each device. Refer to the table to determine applicability of the pin descriptions.

The description of the pins is listed in [Table 3-1](#).

TABLE 3-1: PIN FUNCTION TABLE

MCP9902 WDFN	MCP9903 VDFN	MCP9904 VDFN	Pin Name	Pin Type	Description
1	1	1	V _{DD}	P	Power
2	2	2	DP1	Analog	Diode 1/2 Connection
3	3	3	DN1	Analog	Diode 1/2 Connection
—	4	4	DP2 ⁽¹⁾ (/DN3) ⁽²⁾	Analog	Diode 1/2 Connection
—	5	5	DN2 ⁽¹⁾ (/DP3) ⁽²⁾	Analog	Diode 1/2 Connection
5	6	6	GND	P	Ground
4	7	7	$\overline{\text{THERM/ADDR}}$	OD	Non-Maskable $\overline{\text{THERM}}$
6	8	8	$\overline{\text{ALERT/THERM2}}$	OD	Maskable $\overline{\text{ALERT/THERM2}}$
7	9	9	SMDATA	OD	SMBus Clock
8	10	10	SMCLK	OD	SMBus Data
9	11	11	EP	—	Exposed Thermal pad

Note 1: MCP9903 only.

2: MCP9904 only.

3: See [Section 3.10 “Exposed Thermal Pad \(EP\)”](#) for grounding recommendations.

3.1 Power Supply (V_{DD})

This pin is used to supply power to the device.

3.2 Diode 1 Pair (DN1/DP1)

Remote Diode 1 anode (DP1) and cathode (DN1) pins for the MCP9902/3/4.

3.3 Diode 2 Pair (DN2/DP2)

Remote Diode 2 anode (DP2) and cathode (DN2) pins for the MCP9903.

3.4 Anti-Parallel Diode Pair (DN3/DP2 and DN2/DP3) (MCP9904 only)

- DP2/DN3: DP2 anode and DN3 cathode
- DN2/DP3: DN2 cathode and DP3 anode

3.5 THERM LIMIT ALERT (THERM/ADDR)

This pin asserts low when the hardware-set THERM limit threshold is exceeded by one of the temperature sensors. The assertion of this signal can't be controlled or masked by register setting. If enabled, the SMBus slave address is set by the pull-up resistor on this pin.

3.6 Ground (GND)

This pin is used for system ground for the device.

3.7 Maskable ALERT (ALERT/THERM2)

This pin asserts when a diode temperature exceeds the ALERT threshold. This pin may be masked by register settings.

3.8 SMBus Data (SMDATA)

This is the open drain, bidirectional data pin for SMBus communication.

3.9 SMBus Clock (SMCLK)

This is the SMBus input clock pin for SMBus communication.

3.10 Exposed Thermal Pad (EP)

Not internally connected, but recommend grounding for mechanical support.

4.0 FUNCTIONAL DESCRIPTION

Thermal management is performed in cooperation with a host device. This consists of the host reading the temperature data of both the external and internal temperature diodes of the MCP9902/3/4 and using that data to control the speed of one or more fans.

The MCP9902/3/4 has two levels of monitoring. The first provides a maskable ALERT signal to the host when the measured temperatures exceed user programmable limits. This allows the MCP9902/3/4 to be used as an independent thermal watchdog to warn the host of temperature hot spots without direct control by the host. The second level of monitoring provides a non-maskable interrupt on the THERM output if the measured temperatures meet or exceed a second programmable limit.

Figure 4-1 shows a system level block diagram of the MCP9902/3/4.

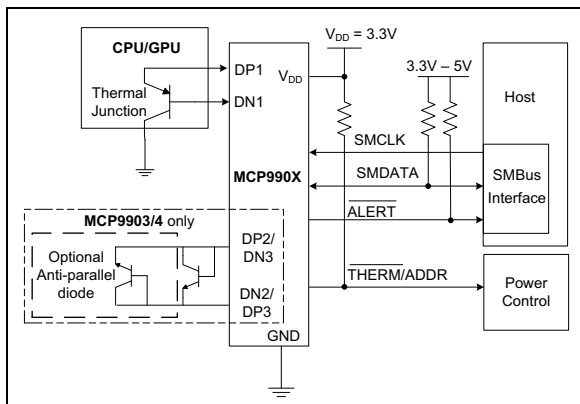


FIGURE 4-1: MCP9902/3/4 System Diagram.

4.1 Power States

The MCP9902/3/4 has two modes of operation:

- **Active (Run)** - In this mode of operation, the ADC is converting on all temperature channels at the programmed conversion rate. The temperature data is updated at the end of every conversion and the limits are checked. In Active mode, writing to the one-shot register will do nothing.
- **Standby (Stop)** - In this mode of operation, the majority of circuitry is powered down to reduce supply current. The temperature data is not updated and the limits are not checked. In this mode of operation, the SMBus is fully active and the part will return requested data. Writing to the one-shot register will enable the device to update all temperature channels. Once all the channels are updated, the device will return to the Standby mode.

4.2 Conversion Rates

The MCP9902/3/4 may be configured for different conversion rates based on the system requirements. The default conversion rate is 4 conversions per second. Other available conversion rates are shown in Table 4-1.

TABLE 4-1: CONVERSION RATE

HEX	CONV<3:0>				Conversions/Second
	3	2	1	0	
0h	0	0	0	0	1/16
1h	0	0	0	1	1/8
2h	0	0	1	0	1/4
3h	0	0	1	1	1/2
4h	0	1	0	0	1
5h	0	1	0	1	2
6h	0	1	1	0	4 (default)
7h	0	1	1	1	8
8h	1	0	0	0	16
9h	1	0	0	1	32
Ah	1	0	1	0	64
Bh - Fh	All others				1

4.3 Dynamic Averaging

Dynamic averaging allows the MCP9902/3/4 to measure the external diode channel for an extended time based on the selected conversion rate. This functionality can be disabled for increased power savings at the lower conversion rates (see Register 5-6). When dynamic averaging is enabled, the device will automatically adjust the sampling and measurement time for the external diode channels. This allows the device to average 2x or 16x longer than the normal 11 bit operation (nominally 21 ms per channel) while still maintaining the selected conversion rate. The benefits of dynamic averaging are improved noise rejection due to the longer integration time as well as less random variation of the temperature measurement.

When enabled, the dynamic averaging applies when a one-shot command is issued. The device will perform the desired averaging during the one-shot operation according to the selected conversion rate.

When enabled, the dynamic averaging will affect the typical supply current based on the chosen conversion rate as shown in the power supply characteristics in Table 1.2 "DC Characteristics".

MCP9902/3/4

4.4 $\overline{\text{THERM}}$ Output

The $\overline{\text{THERM}}$ output is asserted independently of the $\overline{\text{ALERT}}$ output and cannot be masked. Whenever any of the measured temperatures exceed the user programmed Therm Limit values for the programmed number of consecutive measurements, the $\overline{\text{THERM}}$ output is asserted. Once it has been asserted, it will remain asserted until all measured temperatures drop below the Therm Limit minus the Therm Hysteresis (also programmable).

When the $\overline{\text{THERM}}$ output is asserted, the THERM status bits will likewise be set. Reading these bits will not clear them until the $\overline{\text{THERM}}$ output is deasserted. Once the $\overline{\text{THERM}}$ output is deasserted, the THERM status bits will be automatically cleared.

4.5 $\overline{\text{THERM}}$ Pin Address Decoding

The Address decode is performed by pulling known currents from V_{DD} through the external resistor causing the pin voltage to drop based on the respective current/resistor relationship. This pin voltage is compared against a threshold that determines the value of the pull-up resistor.

The MCP9902/3/4-A SMBus slave address is determined by the pull-up resistor on the $\overline{\text{THERM/ADDR}}$ pin as shown in Table 4-2.

TABLE 4-2: $\text{I}^2\text{C/SMBUS ADDRESS DECODE}$

Pull Up Resistor on $\overline{\text{THERM}}$ pin ($\pm 5\%$)	SMBus Address
4.7 k Ω	1111_100 (r/\overline{w}) b
6.8 k Ω	1011_100 (r/\overline{w}) b
10 k Ω	1001_100 (r/\overline{w}) b
15 k Ω	1101_100 (r/\overline{w}) b
22 k Ω	0011_100 (r/\overline{w}) b
33 k Ω	0111_100 (r/\overline{w}) b

The MCP9902-1 $\text{I}^2\text{C/SMBus}$ address is hard coded to 1001_100 (r/\overline{w}).

The MCP9902-2 $\text{I}^2\text{C/SMBus}$ address is hard coded to 1001_101 (r/\overline{w}).

The MCP9903-1 $\text{I}^2\text{C/SMBus}$ address is hard coded to 1001_100 (r/\overline{w}).

The MCP9903-2 $\text{I}^2\text{C/SMBus}$ address is hard coded to 1001_101 (r/\overline{w}).

The MCP9904-1 $\text{I}^2\text{C/SMBus}$ address is hard coded to 1001_100 (r/\overline{w}).

The MCP9904-2 $\text{I}^2\text{C/SMBus}$ address is hard coded to 1001_101 (r/\overline{w}).

4.6 $\overline{\text{ALERT/THERM2}}$ Output

4.6.1 $\overline{\text{ALERT/THERM2}}$ PIN INTERRUPT MODE

When configured to operate in interrupt mode, the $\overline{\text{ALERT/THERM2}}$ pin asserts low when an out-of-limit measurement (\geq high limit or $<$ low limit) is detected on any diode or when an external diode fault is detected. The $\overline{\text{ALERT/THERM2}}$ pin will remain asserted as long as an out-of-limit condition remains. Once the out-of-limit condition has been removed, the $\overline{\text{ALERT/THERM2}}$ pin will remain asserted until the appropriate status bits are cleared.

The $\overline{\text{ALERT/THERM2}}$ pin can be masked by setting the MASK_ALL bit. Once the $\overline{\text{ALERT/THERM2}}$ pin has been masked, it will be deasserted and remain deasserted until the MASK_ALL bit is cleared by the user. Any interrupt conditions that occur while the $\overline{\text{ALERT/THERM2}}$ pin is masked will update the Status Register normally. There are also individual channel masks (see Register 5-20).

The $\overline{\text{ALERT/THERM2}}$ pin is used as an interrupt signal or as an SMBus Alert signal that allows an SMBus slave to communicate an error condition to the master. One or more $\overline{\text{ALERT/THERM2}}$ Outputs can be hard-wired together.

4.6.2 $\overline{\text{ALERT/THERM2}}$ PIN IN THERM MODE

When the $\overline{\text{ALERT/THERM2}}$ pin is configured to operate in THERM mode, it will be asserted if any of the measured temperatures exceeds the respective high limit. The $\overline{\text{ALERT/THERM2}}$ pin will remain asserted until all temperatures drop below the corresponding high limit minus the Therm Hysteresis value.

When the $\overline{\text{ALERT/THERM2}}$ pin is asserted in THERM mode, the corresponding high limit status bits will be set. Reading these bits will not clear them until the $\overline{\text{ALERT/THERM2}}$ pin is deasserted. Once the $\overline{\text{ALERT/THERM2}}$ pin is deasserted, the status bits will be automatically cleared.

The MASK_ALL bit will not block the $\overline{\text{ALERT/THERM2}}$ pin in this mode; however, the individual channel masks (see Register 5-20) will prevent the respective channel from asserting the $\overline{\text{ALERT/THERM2}}$ pin.

4.6.3 DEFAULT POWER UP CONDITIONS

On power-up, the $\overline{\text{ALERT/THERM2}}$ is disabled and the MASK ALL (MSKAL) bit in the CONFIG register (see Register 5-6) is set. Additionally, an artificial fault has been placed in the device, and is enabled at power up. The FAULT TEST (FT_TST) bit in the Fault Status register (see Register 5-20) will allow the assertion of the $\overline{\text{ALERT/THERM2}}$ pin when this test mode is enabled once MSKAL is cleared. To use the $\overline{\text{ALERT/THERM2}}$ functions described in this section, the MSKAL bit must be set to '0', and the FT_TST bit to '1' in order for the pin to function properly.

4.7 Temperature Measurement

The MCP9902/3/4 can monitor the temperature of up to three externally connected diodes.

The device contains programmable High, Low and Therm limits for all measured temperature channels. If the measured temperature goes below the Low limit or above the High limit, the `ALERT/THERM2` pin can be asserted (based on user settings). If the measured temperature meets or exceeds the Therm Limit, the `THERM` pin is asserted unconditionally, providing two tiers of temperature detection.

4.8 Beta Compensation

The MCP9902/3/4 is configured to monitor the temperature of basic diodes (e.g., 2N3904) or CPU thermal diodes. For the MCP9902/3/4, the External Diode 1 channel automatically detects the type of external diode and determines the optimal setting to reduce temperature errors introduced by beta variation. Compensating for this error is also known as implementing the transistor or BJT model for temperature measurement.

For discrete transistors configured with the collector and base shorted together, the beta is generally sufficiently high such that the percent change in beta variation is very small. For example, a 10% variation in beta for two forced emitter currents with a transistor whose ideal beta is 50 would contribute approximately +0.25°C error at +100°C. However, for substrate transistors where the base-emitter junction is used for temperature measurement and the collector is tied to the substrate, the proportional beta variation will cause large error. For example, a 10% variation in beta for two forced emitter currents with a transistor whose ideal beta is 0.5 would contribute approximately +8.25°C error at +100°C.

The MCP9904 does not support Beta Compensation on External Diode 2 and External Diode 3 channels due to the high beta of diode-connected transistors.

Care should be taken when setting the `BETA<2:0>` bits if the auto-detection circuitry is disabled. If the Beta Compensation factor is set at a beta value that is higher than the transistor beta, the circuit may introduce measurement errors. When measuring a discrete thermal diode (such as 2N3904) or a CPU diode that functions like a discrete thermal diode (such as an AMD processor diode), the `BETA<2:0>` bits should be set to '111b'.

4.9 Resistance Error Correction (REC)

Parasitic resistance in series with the external diodes will limit the accuracy obtainable from temperature measurement devices. The voltage developed across this resistance by the switching diode currents causes the temperature measurement to read higher than the true temperature. Contributors to series resistance are PCB trace resistance, on die (i.e., on the processor) metal resistance, bulk resistance in the base and emitter of the temperature transistor. Typically, the error caused by series resistance is +0.7°C per ohm. The MCP9902/3/4 automatically corrects up to 100 ohms of series resistance.

4.10 Programmable External Diode Ideality Factor

The MCP9902/3/4 is designed for external diodes with an ideality factor of 1.008. Not all external diodes, processor or discrete, will have this exact value. This variation of the ideality factor introduces temperature measurement errors which must be corrected. This correction is typically done using programmable offset registers. Since an ideality factor mismatch introduces an error that is a function of temperature, this correction is only accurate within a small range of temperatures. To provide maximum flexibility to the user, the MCP9902/3/4 provides a 6-bit register for each external diode where the ideality factor of the diode used is programmed to eliminate errors across all temperatures.

These registers store the ideality factors that are applied to the external diode. [Table 4-3](#) defines each setting and the corresponding ideality factor. Beta Compensation and Resistance Error Correction automatically correct for most diode ideality errors; therefore, it is not recommended that these settings be updated without consulting Microchip Technology Inc.

TABLE 4-3: IDEALITY FACTOR LOOK-UP TABLE (DIODE MODEL)

Setting	Factor	Setting	Factor	Setting	Factor
08h	0.9949	18h	1.0159	28h	1.0371
09h	0.9962	19h	1.0172	29h	1.0384
0Ah	0.9975	1Ah	1.0185	2Ah	1.0397
0Bh	0.9988	1Bh	1.0200	2Bh	1.0410
0Ch	1.0001	1Ch	1.0212	2Ch	1.0423
0Dh	1.0014	1Dh	1.0226	2Dh	1.0436
0Eh	1.0027	1Eh	1.0239	2Eh	1.0449
0Fh	1.0040	1Fh	1.0253	2Fh	1.0462
10h	1.0053	20h	1.0267	30h	1.0475
11h	1.0066	21h	1.0280	31h	1.0488
12h	1.0080	22h	1.0293	32h	1.0501
13h	1.0093	23h	1.0306	33h	1.0514
14h	1.0106	24h	1.0319	34h	1.0527
15h	1.0119	25h	1.0332	35h	1.0540
16h	1.0133	26h	1.0345	36h	1.0553
17h	1.0146	27h	1.0358	37h	1.0566

For CPU substrate transistors that require the BJT transistor model, the ideality factor behaves slightly differently than for discrete diode-connected transistors. Refer to [Table 4-4](#) when using a CPU substrate transistor.

TABLE 4-4: SUBSTRATE DIODE IDEALITY FACTOR LOOK-UP TABLE (BJT MODEL)

Setting	Factor	Setting	Factor	Setting	Factor
08h	0.9869	18h	1.0079	28h	1.0291
09h	0.9882	19h	1.0092	29h	1.0304
0Ah	0.9895	1Ah	1.0105	2Ah	1.0317
0Bh	0.9908	1Bh	1.0120	2Bh	1.0330
0Ch	0.9921	1Ch	1.0132	2Ch	1.0343
0Dh	0.9934	1Dh	1.0146	2Dh	1.0356
0Eh	0.9947	1Eh	1.0159	2Eh	1.0369
0Fh	0.9960	1Fh	1.0173	2Fh	1.0382
10h	0.9973	20h	1.0187	30h	1.0395
11h	0.9986	21h	1.0200	31h	1.0408
12h	1.0000	22h	1.0213	32h	1.0421
13h	1.0013	23h	1.0226	33h	1.0434
14h	1.0026	24h	1.0239	34h	1.0447
15h	1.0039	25h	1.0252	35h	1.0460
16h	1.0053	26h	1.0265	36h	1.0473
17h	1.0066	27h	1.0278	37h	1.0486

4.11 Diode Faults

The MCP9902/3/4 detects several “diode fault” mechanisms, defined as one of the following: an open between DP and DN, a short from V_{DD} to DP, or a short from V_{DD} to DN. When each temperature measurement is made, the device checks for a diode fault on the external diode channel(s). When a diode fault is detected, the ALERT/THERM2 pin asserts (unless masked, see [Register 5-20](#)) and the temperature data reads 00h in the MSB and LSB registers (note: the low limit will not be checked).

If a short occurs across DP and DN or a short occurs from DP to GND, the low limit status bit is set and the ALERT/THERM2 pin asserts (unless masked). This condition is indistinguishable from a temperature measurement of 0.000°C (-64°C in extended range) resulting in temperature data of 00h in the MSB and LSB registers.

If a short from DN to GND occurs (with a diode-connected transistor), temperature measurements will continue as normal with no alerts.

The External Diode Fault Register ([Register 5-19](#)) indicates which of the external diodes caused the FAULT bit in the Status Register to be set. This register is cleared when it is read.

4.12 Consecutive Alerts

The MCP9902/3/4 contains multiple consecutive alert counters. One set of counters applies to the ALERT/THERM2 pin and the second set of counters applies to the THERM pin. Each temperature measurement channel has a separate consecutive alert counter for each of the ALERT/THERM2 and THERM pins. All counters are user programmable and determine the number of consecutive measurements that a temperature channel(s) must be out-of-limit or reporting a diode fault before the corresponding pin is asserted.

The Consecutive Alert register determines how many times an out-of-limit error or diode fault must be detected in consecutive measurements before the ALERT/THERM2 or THERM pin is asserted. Additionally, the Consecutive Alert register controls the SMBus Time-out functionality.

An out-of-limit condition (i.e., HIGH, LOW or FAULT) occurring on the same temperature channel in consecutive measurements will increment the consecutive alert counter. The counters will also be reset if no out-of-limit condition or diode fault condition occurs in a consecutive reading.

When the ALERT/THERM2 pin is configured as an interrupt, when the consecutive alert counter reaches its programmed value, the following will occur: the STATUS bit(s) for that channel and the last error condition(s) (i.e., E1HIGH, or E2LOW and/or

E2FAULT) will be set to '1', the $\overline{\text{ALERT/THERM2}}$ pin will be asserted, the consecutive alert counter will be cleared and measurements will continue.

When the $\overline{\text{ALERT/THERM2}}$ pin is configured as a comparator, the consecutive alert counter will ignore diode fault and low limit errors and only increment if the measured temperature exceeds the High Limit. Additionally, once the consecutive alert counter reaches the programmed limit, the $\overline{\text{ALERT/THERM2}}$ pin will be asserted, but the counter will not be reset. It will remain set until the temperature drops below the High Limit minus the Therm Hysteresis value.

For example, if the CALRT<2:0> bits are set for four consecutive alerts on an MCP9902/3/4 device, the high limits are set at +70°C and none of the channels are masked, then the $\overline{\text{ALERT/THERM2}}$ pin will be asserted after the following five measurements:

- The Internal Diode reads +71°C and both the external diodes read +69°C. Consecutive alert counter for INT is incremented to 1.
- Both the Internal Diode and the External Diode 1 read +71°C and External Diode 2 reads +68°C. The consecutive alert counter for INT is incremented to 2 and the counter for EXT1 is set to 1.
- The External Diode 1 reads +71°C and both Internal Diode and External Diode 2 read +69°C. The consecutive alert counters for INT and EXT2 are cleared, and EXT1 is incremented to 2.
- The Internal Diode reads +71°C and both external diodes read +71°C. The consecutive alert counter for INT is set to 1, EXT2 is set to 1 and EXT1 is incremented to 3.
- The Internal Diode reads +71°C and both external diodes read +71°C. The consecutive alert counter for INT is incremented to 2, EXT2 is set to 2 and EXT1 is incremented to 4. The appropriate status bits are set for EXT1 and the $\overline{\text{ALERT/THERM2}}$ pin is asserted. The EXT1 counter is reset to 0 and all other counters hold the last value until the next temperature measurement.

All temperature channels use this value to set the respective counters. The consecutive Therm counter is incremented whenever any measurement exceeds the corresponding Therm Limit.

If the temperature drops below the Therm Limit, the counter is reset. If a number of consecutive measurements above the Therm Limit occurs, the $\overline{\text{THERM}}$ pin is asserted low.

Once the $\overline{\text{THERM}}$ pin has been asserted, the consecutive therm counter will not reset until the corresponding temperature drops below the Therm Limit minus the Therm Hysteresis value.

The default setting is one out-of-limit conversion and it is set in [Register 5-21](#).

TABLE 4-5: CONSECUTIVE ALERT/THERM SETTINGS

2	1	0	Number of consecutive out of limit measurements
0	0	0	1 (default for CALRT<2:0>)
0	0	1	2
0	1	1	3
1	1	1	4 (default for CTHRM<2:0>)

4.13 Limit Register Interaction

The various limit registers in the device interact based on both external conditions present on the diode pins as well as changes in register bits in the SMBus interface. The device contains both high and low limits for all temperature channels. If the measured temperature exceeds the high limit, then the corresponding status bit is set and the $\overline{\text{ALERT/THERM2}}$ pin is asserted. Likewise, if the measured temperature is less than or equal to the low limit, the corresponding status bit is set and the $\overline{\text{ALERT/THERM2}}$ pin is asserted.

The data format for the limits must match the selected data format for the temperature so that if the extended temperature range is used, the limits must be programmed in the extended data format.

The limit registers with multiple addresses are fully accessible at either address.

When the device is in Standby mode, updating the limit registers will have no effect until the next conversion cycle occurs. This can be initiated via a write to the One Shot register (see [Register 5-15](#)) or by clearing the RUN/STOP bit (see [Register 5-6](#)).

The $\overline{\text{THERM}}$ Limit Status register contains the status bits that are set when a temperature channel Therm Limit is exceeded. If any of these bits are set, the $\overline{\text{THERM}}$ status bit in the Status register is set. Reading from the $\overline{\text{THERM}}$ Limit Status register will not clear the status bits. Once the temperature drops below the $\overline{\text{THERM}}$ Limit minus the $\overline{\text{THERM}}$ Hysteresis, the corresponding status bits will be automatically cleared. The $\overline{\text{THERM}}$ bit in the Status register will be cleared when all individual channel $\overline{\text{THERM}}$ bits are cleared.

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4.13.1 HIGH LIMIT REGISTER

The High Limit Status register contains the status bits that are set when a temperature channel high limit is exceeded. If any of these bits are set, then the HIGH status bit in the Status register is set. Reading from the High Limit Status register will clear all bits. Reading from the register will also clear the HIGH status bit in the Status register.

The $\overline{\text{ALERT/THERM2}}$ pin will be set if the programmed number of consecutive alert counts have been met and any of these status bits are set.

The status bits will remain set until read unless the $\overline{\text{ALERT/THERM2}}$ pin is configured as a comparator output (see Section 4.6.2 “ $\overline{\text{ALERT/THERM2}}$ Pin In THERM Mode”).

4.13.2 LOW LIMIT REGISTER

The Low Limit Status register contains the status bits that are set when a temperature channel drops below the low limit. If any of these bits are set, then the LOW status bit in the Status register is set. Reading from the Low Limit Status register will clear all bits.

The $\overline{\text{ALERT/THERM2}}$ pin will be set if the programmed number of consecutive alert counts have been met and any of these status bits are set.

The status bits will remain set until read unless the $\overline{\text{ALERT/THERM2}}$ pin is configured as a comparator output (see Section 4.6.2 “ $\overline{\text{ALERT/THERM2}}$ Pin In THERM Mode”).

4.13.3 THERM LIMIT REGISTER

The Therm Limit registers are used to determine whether a critical thermal event has occurred. If the measured temperature exceeds the Therm Limit, the $\overline{\text{THERM}}$ pin is asserted. The limit setting must match the chosen data format of the temperature reading registers.

Unlike the $\overline{\text{ALERT/THERM2}}$ pin, the $\overline{\text{THERM}}$ pin cannot be masked. Additionally, the $\overline{\text{THERM}}$ pin will be released once the temperature drops below the corresponding threshold minus the Therm Hysteresis.

4.13.4 CHANNEL MASKING

The Channel Mask register (Register 5-20) controls individual channel masking. When a channel is masked, the $\overline{\text{ALERT/THERM2}}$ pin will not be asserted when the masked channel reads a diode fault or out of limit error. The channel mask does not mask the $\overline{\text{THERM}}$ pin.

4.14 Digital Filter

To reduce the effect of noise and temperature spikes on the reported temperature, the External Diode channel uses a programmable digital filter. This filter can be configured as Level 1, Level 2, or Disabled (default). The typical filter performance is shown in Figure 4-2 and Figure 4-3. The Filter Configuration register controls the digital filter on the External Diode 1 channel.

TABLE 4-6: FILTER SETTINGS

FILTER<1:0>		Averaging
1	0	
0	0	Disabled (default)
0	1	Level 1
1	0	Level 1
1	1	Level 2

Note 1: Filtering Level 1 corresponds to 4x attenuation of a temperature spike.

2: Filtering Level 2 corresponds to 8x attenuation of a temperature spike.

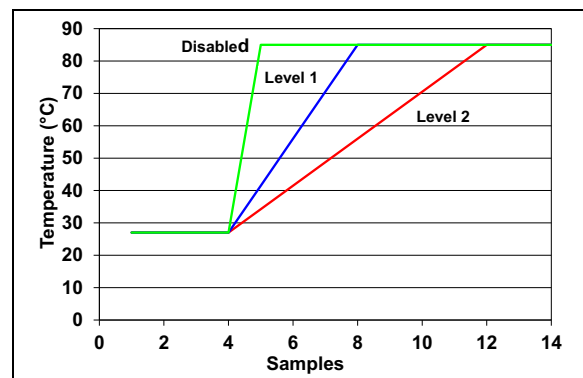


FIGURE 4-2: Temperature Filter Step Response.

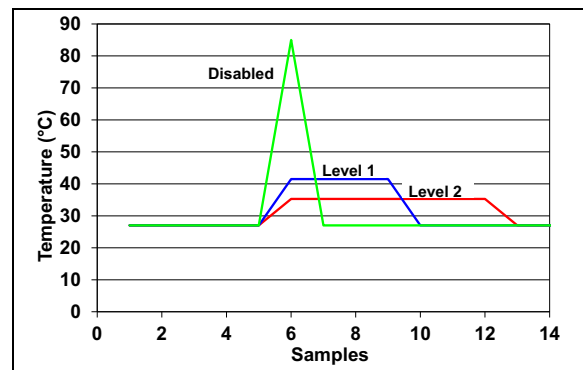


FIGURE 4-3: Temperature Filter Impulse Response.

4.15 Temperature Measurement Results and Data

The temperature measurement results are stored in the internal and external temperature registers. These are then compared with the values stored in the high and low limit registers. Both external and internal temperature measurements are stored in 11-bit format with the eight (8) most significant bits stored in a high byte register and the three (3) least significant bits stored in the three (3) MSB positions of the low byte register. All other bits of the low byte register are set to zero.

The MCP9902/3/4 has two selectable temperature ranges. The default range is from 0°C to +127°C and the temperature is represented as binary number able to report a temperature from 0°C to +127.875°C in 0.125°C steps.

The extended range is an extended temperature range from -64°C to +191°C. The data format is a binary number offset by +64°C. The extended range is used to measure temperature diodes with a large known offset (such as AMD processor diodes) where the diode temperature plus the offset would be equivalent to a temperature higher than +127°C.

Table 4-7 shows the default and extended range formats.

TABLE 4-7: TEMPERATURE DATA FORMAT

Temperature (°C)	Default Range 0°C to +127°C	Extended Range -64°C to +191°C
Diode Fault	000 0000 0000	000 0000 0000
-64	000 0000 0000	000 0000 0000 (Note 2)
-1	000 0000 0000	001 1111 1000
0	000 0000 0000 (Note 1)	010 0000 0000
0.125	000 0000 0001	010 0000 0001
1	000 0000 1000	010 0000 1000
64	010 0000 0000	100 0000 0000
65	010 0000 1000	100 0000 1000
127	011 1111 1000	101 1111 1000
127.875	011 1111 1111	101 1111 1111
128	011 1111 1111 (Note 3)	110 0000 0000
190	011 1111 1111	111 1111 0000
191	011 1111 1111	111 1111 1000
≥ 191.875	011 1111 1111	111 1111 1111 (Note 4)

- Note 1:** In default mode, all temperatures < 0°C will be reported as 0°C
- 2:** In the extended range, all temperatures less than -64°C will be reported as -64°C.
- 3:** For the default range, all temperatures greater than +127.875°C will be reported as +127.875°C.
- 4:** For the extended range, all temperatures greater than +191.875°C will be reported as +191.875°C.

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5.0 COMMUNICATIONS PROTOCOL

The MCP9902/3/4 communicates with a host controller, such as an PIC MCU, through the SMBus. The SMBus is a two-wire serial communication protocol between a computer host and its peripheral devices. A detailed timing diagram is shown in [Figure 4-1](#).

For the first 15 ms after power-up the device may not respond to SMBus communications.

5.1 SMBus Control Bits

The interaction between clock and data creates special function bits within the data stream.

5.1.1 SMBUS START BIT

The SMBus Start bit is defined as a transition of the SMBus Data line from a logic '1' state to a logic '0' state while the SMBus Clock line is in a logic '1' state.

5.1.2 SMBUS ADDRESS AND RD/WR BIT

The SMBus Address Byte consists of the 7-bit client address followed by the RD/WR indicator bit. If this RD/WR bit is a logic '0', the SMBus Host is writing data to the client device. If this RD/WR bit is a logic '1', the SMBus Host is reading data from the client device.

5.1.3 SMBUS DATA BYTES

All SMBus Data bytes are sent most significant bit first and composed of 8-bits of information.

5.1.4 SMBUS ACK AND NACK BITS

The SMBus client will acknowledge all data bytes that it receives. This is done by the client device pulling the SMBus data line low after the 8th bit of each byte that is transmitted. This applies to the Write Byte protocol.

The Host will NACK (not acknowledge) the last data byte to be received from the client by holding the SMBus data line high after the 8th data bit has been sent.

5.1.5 SMBUS STOP BIT

The SMBus Stop bit is defined as a transition of the SMBus Data line from a logic '0' state to a logic '1' state while the SMBus clock line is in a logic '1' state. When the device detects an SMBus Stop bit and it has been communicating with the SMBus protocol, it will reset its client interface and prepare to receive further communications.

5.2 SMBus Timeout

The MCP9902/3/4 supports SMBus Timeout. If the clock line is held low for longer than t_{TIMEOUT} , the device will reset its SMBus protocol. This function can be enabled by setting the TIMEOUT bit (see [Register 5-21](#)).

5.3 SMBus and I²C Compatibility

The MCP9902/3/4 is compatible with SMBus and I²C. The major differences between SMBus and I²C devices are highlighted here. For more information, refer to the SMBus 2.0 and I²C specifications. For information on using the MCP9902/3/4 in an I²C system, refer to AN14.0 "Microchip Dedicated Slave Devices in I²C Systems", DS00001853.

- MCP9902/3/4 supports I²C fast mode at 400 kHz. This covers the SMBus max time of 100 kHz.
- Minimum frequency for SMBus communications is 10 kHz.
- The SMBus client protocol will reset if the clock is held at a logic '0' for longer than 30 ms. This timeout functionality is disabled by default in the MCP9902/3/4 and can be enabled by writing to the TIMEOUT bit. I²C does not have a timeout.
- I²C devices do not support the Alert Response Address functionality (which is optional for SMBus).

Attempting to communicate with the MCP9902/3/4 SMBus interface with an invalid slave address or invalid protocol will result in no response from the device and will not affect its register contents. Stretching of the SMCLK signal is supported, provided other devices on the SMBus control the timing.

5.4 SMBus Protocols

The device supports Send Byte, Read Byte, Write Byte, Receive Byte and the Alert Response Address as valid protocols, as shown below.

All of the following protocols use the convention in [Table 5-1](#).

TABLE 5-1: PROTOCOL FORMAT

Data Sent To Device	Data Sent To The Host
# of bits sent	# of bits sent

5.4.1 WRITE BYTE

The Write Byte is used to write one byte of data to the registers, as shown in [Table 5-2](#).

TABLE 5-2: WRITE BYTE PROTOCOL

START	Slave Address	WR	ACK	Register Address	ACK	Register Data	ACK	STOP
1 → 0	YYYY_YYY	0	0	XXh	0	XXh	0	0 → 1

5.4.2 READ BYTE

The Read Byte protocol is used to read one byte of data from the registers as shown in [Table 5-3](#).

TABLE 5-3: READ BYTE PROTOCOL

START	Slave Address	WR	ACK	Register Address	ACK		
1 → 0	YYYY_YYY	0	0	XXh	0		
START	Slave Address	RD	ACK	Register Data	NACK	STOP	
1 → 0	YYYY_YYY	1	0	XXh	1	0 → 1	

5.4.3 SEND BYTE

The Send Byte protocol is used to set the internal address register pointer to the correct address location. No data is transferred during the Send Byte protocol as shown in [Table 5-4](#).

TABLE 5-4: SEND BYTE PROTOCOL

START	Slave Address	WR	ACK	Register Address	ACK	STOP
1 → 0	YYYY_YYY	0	0	XXh	0	0 → 1

5.4.4 RECEIVE BYTE

The Receive Byte protocol is used to read data from a register when the internal register address pointer is known to be at the right location (e.g. set via Send Byte). This is used for consecutive reads of the same register as shown in [Table 5-5](#).

TABLE 5-5: RECEIVE BYTE PROTOCOL

START	Slave Address	RD	ACK	Register Data	NACK	STOP
1 → 0	YYYY_YYY	1	0	XXh	1	0 → 1

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5.5 Alert Response Address

The $\overline{\text{ALERT/THERM2}}$ output can be used as a processor interrupt or as an SMBus Alert.

When it detects that the $\overline{\text{ALERT/THERM2}}$ pin is asserted, the host will send the Alert Response Address (ARA) to the general address of 0001_100xb. All devices with active interrupts will respond with their client address as shown in [Table 5-6](#).

TABLE 5-6: ALERT RESPONSE ADDRESS PROTOCOL

START	ALERT Response Address	RD	ACK	Device Address	NACK	STOP
1 → 0	0001_100	1	0	YYYY_YYY	1	0 → 1

The MCP9902/3/4 will respond to the ARA in the following way:

- Send Slave Address and verify that full slave address was sent (i.e. the SMBus communication from the device was not prematurely stopped due to a bus contention event).
- Set the $\overline{\text{MASK_ALL}}$ bit to clear the $\overline{\text{ALERT/THERM2}}$ pin.

The ARA does not clear the Status Register and if the $\overline{\text{MASK_ALL}}$ bit is cleared prior to the Status Register being cleared, the $\overline{\text{ALERT/THERM2}}$ pin will be reasserted.

5.6 Register Description

TABLE 5-7: REGISTER SET IN HEXADECIMAL ORDER

Register Address	Register Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Por Value
00h	INT TEMP HIGH BYTE	IHB7	IHB6	IHB5	IHB4	IHB3	IHB2	IHB1	IHB0	00h
01h	EXT1 TEMP HIGH BYTE	E1HB7	E1HB6	E1HB5	E1HB4	ETHB3	E1HB2	E1HB1	E1HB0	00h
02h	STATUS	BUSY	IHIGH	ILOW	EHIGH	ELOW	FAULT	ETHRM	ITHRM	00h
03h	CONFIG	MSKAL	R/S	AT/THM	RECD1	RECD2	RANGE	DA_DIS	APDD	00h
04h	CONVERT	SLEEP	—	—	—	CONV3	CONV2	CONV1	CONV0	06h (4/sec)
05h	INT DIODE HI LIMIT TEMP	IDHL7	IDHL6	IDHL5	IDHL4	IDHL3	IDHL2	IDHL1	IDHL0	55h (+85°C)
06h	INT DIODE LO LIMIT TEMP	IDLL7	IDLL6	IDLL5	IDLL4	IDLL3	IDLL2	IDLL1	IDLL0	00h (0°C)
07h	EXT1 HI LIMIT TEMP HI BYTE	E1HLH7	E1HLH6	E1HLH5	E1HLH4	E1HLH3	E1HLH2	E1HLH1	E1HLH0	55h (+85°C)
08h	EXT1 LO LIMIT TEMP HI BYTE	E1LLH7	E1LLH6	E1LLH5	E1LLH4	E1LLH3	E1LLH2	E1LLH1	E1LLH0	00h (0°C)
09h	CONFIG	MSKAL	R/S	AT/THM	RECD1	RECD2	RANGE	DA_DIS	APDD	00h
0Ah	CONVERT	STOP	—	—	—	CONV3	CONV2	CONV1	CONV0	06h (4/sec)
0Bh	INT DIODE HI LIMIT TEMP	IDHL7	IDHL6	IDHL5	IDHL4	IDHL3	IDHL2	IDHL1	IDHL0	55h (+85°C)
0Ch	INT DIODE LO LIMIT TEMP	IDLL7	IDLL6	IDLL5	IDLL4	IDLL3	IDLL2	IDLL1	IDLL0	00h (0°C)
0Dh	EXT1 HI LIMIT TEMP HI BYTE	E1HLH7	E1HLH6	E1HLH5	E1HLH4	E1HLH3	E1HLH2	E1HLH1	E1HLH0	55h (+85°C)
0Eh	EXT1 LO LIMIT TEMP HI BYTE	E1LLH7	E1LLH6	E1LLH5	E1LLH4	E1LLH3	E1LLH2	E1LLH1	E1LLH0	00h (0°C)
0Fh	ONE SHOT	ONSH7	ONSH6	ONSH5	ONSH4	ONSH3	ONSH2	ONSH1	ONSH0	00h
10h	EXT1 TEMP LO BYTE	E1LB2	E1LB1	E1LB0	—	—	—	—	—	00h
11h	SCRTCHPD1	SPD17	SPD16	SPD15	SPD14	SPD13	SPD12	SPD11	SPD10	00h
12h	SCRTCHPD2	SPD27	SPD26	SPD25	SPD24	SPD23	SPD22	SPD21	SPD20	00h
13h	EXT1 HI LIM TEMP LO BYTE	E1HLL2	E1HLL1	E1HLL0	—	—	—	—	—	00h
14h	EXT1 LO LIMIT TEMP LO BYTE	E1LLL2	E1LLL1	E1LLL0	—	—	—	—	—	00h
15h	EXT2 HI LIMIT TEMP HI BYTE	E2HLH7	E2HLH6	E2HLH5	E2HLH4	E2HLH3	E2HLH2	E2HLH1	E2HLH0	55h (+85°C)

TABLE 5-7: REGISTER SET IN HEXADECIMAL ORDER (CONTINUED)

Register Address	Register Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Por Value
16h	EXT2 LO LIMIT TEMP HI BYTE	E2LLH7	E2LLH6	E2LLH5	E2LLH4	E2LLH3	E2LLH2	E2LLH1	E2LLH0	00h (0°C)
17h	EXT2 HI LIMIT TEMP LO BYTE	E2HLL2	E2HLL1	E2HLL0	—	—	—	—	—	00h
18h	EXT2 LO LIMIT TEMP LO BYTE	E2LLL2	E2LLL1	E2LLL0	—	—	—	—	—	00h
19h	EXT1 THERM LIMIT	E1THL7	E1THL6	E1THL5	E1THL4	E1THL3	E1THL2	E1THL1	E1THL0	55h (+85°C)
1Ah	EXT2 THERM LIMIT	E2THL7	E2THL6	E2THL5	E2THL4	E2THL3	E2THL2	E2THL1	E2THL0	55h (+85°C)
1Bh	EXT DIODE FAULT STS	—	—	—	—	E3FLT	E2FLT	E1FLT	—	00h
1Fh	DIODE FAULT MASK	—	—	—	—	E3MSK	E2MSK	E1MSK	INTMSK	00h
20h	INT DIODE THERM LIMIT	IDTHL7	IDTHL6	IDTHL5	IDTHL4	IDTHL3	IDTHL2	IDTHL1	IDTHL0	55h (+85°C)
21h	THRM HYS	THMH7	THMH6	THMH5	THMH4	THMH3	THMH2	THMH1	THMH0	0Ah (+10°C)
22h	CONSEC ALRT	TMOUT	CTHM2	CTHM1	CTHM0	CALRT2	CALRT1	CALRT0	—	70h
23h	EXT2 TEMP HI BYTE	E2THB7	E2THB6	E2THB5	E2THB4	E2THB3	E2THB2	E2THB1	E2THB0	00h
24h	EXT2 TEMP LO BYTE	E2TLB2	E2TLB1	E2TLB0	—	—	—	—	—	00h
25h	EXT1 BETA CONFIG	—	—	—	—	ENBL1	BETA12	BETA11	BETA10	08h
26h	EXTD2 BETA CFG	—	—	—	—	ENBL2	BETA22	BETA21	BETA20	08h
27h	EXT1 IDEALITY FACTOR	—	—	IDEL15	IDEL14	IDEL13	IDEL12	IDEL11	IDEL10	12h (1.008)
28h	EXT2 IDEALITY FACTOR	—	—	IDEL25	IDEL24	IDEL23	IDEL22	IDEL21	IDEL20	12h (1.008)
29h	INT TEMP LO BYTE	ITLB2	ITLB1	ITLB0	—	—	—	—	—	00h
2Ah	EXT3 TEMP HI BYTE	E3THB7	E3THB6	E3THB5	E3THB4	E3THB3	E3THB2	E3THB1	E3THB0	00h
2Bh	EXT3 TEMP LO BYTE	E3TLB2	E3TLB1	E3TLB0	—	—	—	—	—	00h
2Ch	EXT3 HI LIMIT HI BYTE	E3HLH7	E3HLH6	E3HLH5	E3HLH4	E3HLH3	E3HLH2	E3HLH1	E3HLH0	55h (+85°C)
2Dh	EXT3 LO LIMIT HI BYTE	E3LLH7	E3LLH6	E3LLH5	E3LLH4	E3LLH3	E3LLH2	E3LLH1	E3LLH0	00h (0°C)
2Eh	EXT3 HI LIMIT LO BYTE	E3HLL2	E3HLL1	E3HLL0	—	—	—	—	—	00h
2Fh	EXTD3 LO LIMIT LO BYTE	E3LLL2	E3LLL1	E3LLL0	—	—	—	—	—	00h
30h	EXT3 THERM LIMIT	E3THL7	E3THL6	E3THL5	E3THL4	E3THL3	E3THL2	E3THL1	E3THL0	55h (+85°C)

TABLE 5-7: REGISTER SET IN HEXADECIMAL ORDER (CONTINUED)

Register Address	Register Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Por Value
31h	EXT3 IDEALITY FACTOR	—	—	IDEL35	IDEL34	IDEL23	IDEL32	IDEL31	IDEL30	12h (1.008)
35h	HI LIMIT STATUS	—	—	—	—	E3HIGH	E2HIGH	E1HIGH	IHIGH	00h
36h	LO LIMIT STATUS	—	—	—	—	E3LOW	E2LOW	E1LOW	ILOW	00h
37h	THRM LIMIT STATUS	—	—	—	—	E3THM	E2THM	E1THM	ITHM	00h
40h	FLTR SEL	—	—	—	—	—	—	FLTER1	FLTER0	00h
FDh	PRODUCT ID (DECODER)	0	0	1	0	0	EXT2_APD_EN	0	EXT2_EN	20h
	MCP9903									21h
	MCP9904									25h
FEh	MANUFACTURER ID									5Dh
FFh	REVISION									00h

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5.7 Data Read Interlock

When any temperature channel high byte register is read, the corresponding low byte is copied into an internal 'shadow' register. The user is free to read the low byte at any time and be guaranteed that it will correspond to the previously read high byte. Regardless if the low byte is read or not, reading from the same high byte register again will automatically refresh this stored low byte data.

REGISTER 5-1: INT TEMP HI BYTE: INTERNAL DIODE HIGH BYTE TEMPERATURE DATA REGISTER (ADDRESS 00H)

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
IHB<7:0>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as 0	
-n = Value at POR	'1' = bit is set	'0' = Bit is cleared	x = Bit in unknown

7-0 **IHB<7:0>**: 2's complement integer value of the internal diode temperature reading

REGISTER 5-2: INT TEMP LO BYTE: INTERNAL DIODE LOW BYTE TEMPERATURE DATA REGISTER (ADDRESS 29H)

R-0	R-0	R-0	U-0	U-0	U-0	U-0	U-0
ILB<2:0>			—	—	—	—	—
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as 0	
-n = Value at POR	'1' = bit is set	'0' = Bit is cleared	x = Bit in unknown

7-5 **ILB<2:0>**: Fractional portion of the Internal Diode Temperature to be added to the value at register 00h
111 = 0.875°C
110 = 0.750°C
101 = 0.625°C
100 = 0.500°C
011 = 0.375°C
010 = 0.250°C
001 = 0.125°C
000 = 0.000°C

4-0 **Unimplemented**: Read as '0'

REGISTER 5-3: EXT(N) TEMP HI BYTE: EXTERNAL DIODE HIGH BYTE TEMPERATURE DATA REGISTER (ADDRESSES 01H, 23H, 2AH)

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
EXT(N)_HB<7:0>							
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as 0
 -n = Value at POR '1' = bit is set '0' = Bit is cleared x = Bit in unknown

7-0 **EXT(N)_HB<7:0>**: 2's complement integer value of the External Diode n temperature reading, where n = 1 to 3, depending on the device

REGISTER 5-4: EXT(N) TEMP LO BYTE: EXTERNAL DIODE LOW BYTE TEMPERATURE DATA REGISTER (ADDRESSES 10H, 24H, 2BH)

R-0	R-0	R-0	U-0	U-0	U-0	U-0	U-0
EXT(N)_LB<2:0>			—	—	—	—	—
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as 0
 -n = Value at POR '1' = bit is set '0' = Bit is cleared x = Bit in unknown

7-5 **EXT(N)_LB<2:0>**: Fractional portion of the Internal Diode Temperature to be added to the value at register 00h
 111 = 0.875°C
 110 = 0.750°C
 101 = 0.625°C
 100 = 0.500°C
 011 = 0.375°C
 010 = 0.250°C
 001 = 0.125°C
 000 = 0.000°C

4-0 **Unimplemented**: Read as '0'

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REGISTER 5-5: STATUS: STATUS REGISTER REPORTING STATE OF INTERNAL AND EXTERNAL DIODES (ADDRESS 02H)

RC-0	RC-0	RC-0	RC-0	RC-0	RC-0	RC-0	RC-0
BUSY	IHIGH	ILOW	EHIGH	ELOW	FAULT	ETHRM	ITHRM
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as 0

-n = Value at POR

'1' = bit is set

'0' = Bit is cleared

x = Bit in unknown

- 7 **BUSY:** This bit indicates that the ADC is currently converting. This bit does not cause either the ALERT/THERM2 or THERM pin to be asserted.
1 = ADC is currently converting
0 = ADC is not converting
- 6 **IHIGH:** This bit indicates the Internal Diode channel exceeds its programmed high limit. When set, this bit will assert the ALERT/THERM2 pin.
1 = Reported temperature above the high limit
0 = Reported temperature is not above the high limit
- 5 **ILOW:** This bit indicates the Internal Diode channel drops below its programmed low limit. When set, this bit will assert the ALERT/THERM2 pin.
1 = Reported temperature below the low limit
0 = Reported temperature is not below the low limit
- 4 **EHIGH:** This bit indicates the External Diode channel exceeds its programmed high limit. When set, this bit will assert the ALERT/THERM2 pin.
1 = Reported temperature above the high limit
0 = Reported temperature is not above the high limit
- 3 **ELOW:** This bit indicates the External Diode channel drops below its programmed low limit. When set, this bit will assert the ALERT/THERM2 pin.
1 = Reported temperature below the low limit
0 = Reported temperature is not below the low limit
- 2 **FAULT:** This bit indicates when a diode fault is detected. When set, this bit will assert the ALERT/THERM2 pin.
1 = Open circuit or short of a diode
0 = No fault reported
- 1 **ETHRM:** This bit indicates the External Diode channel exceeds the programmed Therm Limit. When set, this bit will assert the THERM pin. This bit will remain set until the THERM pin is released at which point it will be automatically cleared.
1 = Reported temperature above the high limit
0 = Reported temperature is not above the high limit
- 0 **ITHRM:** This bit is set when the Internal Diode channel exceeds the programmed Therm Limit. When set, this bit will assert the THERM pin. This bit will remain set until the THERM pin is released at which point it will be automatically cleared.
1 = Reported temperature above the high limit
0 = Reported temperature is not above the high limit

REGISTER 5-6: CONFIG: CONFIGURATION REGISTER (ADDRESSES 03H AND 09H)

RW-0	RW-0	RW-0	RW-0	RW-0	RW-0	RW-0	RW-0
MSKAL	R/S	AT/THM	RECD1	RECD2	RANGE	DA_DIS	APDD
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as 0
-n = Value at POR	'1' = bit is set	'0' = Bit is cleared
		x = Bit in unknown

- 7 **MSKAL:** Masks the $\overline{\text{ALERT/THERM2}}$ pin from asserting when the $\overline{\text{ALERT/THERM2}}$ pin is in interrupt mode. This bit has no effect when the $\overline{\text{ALERT/THERM2}}$ pin is in comparator mode.
 1 = The $\overline{\text{ALERT/THERM2}}$ pin is masked and will not be asserted for any interrupt condition when the $\overline{\text{ALERT/THERM2}}$ pin is in interrupt mode. The Status Register will be updated normally.
 0 = The $\overline{\text{ALERT/THERM2}}$ pin is not masked. If any of the appropriate status bits are set, the $\overline{\text{ALERT/THERM2}}$ pin will be asserted.
- 6 **R/S:** Controls Active/Standby states
 1 = The device is in Standby state and not converting (unless a one-shot has been commanded)
 0 = The device is in Active state and converting on all channels
- 5 **AT/THM:** Controls the operation of the $\overline{\text{ALERT/THERM2}}$ pin
 1 = The $\overline{\text{ALERT/THERM2}}$ pin acts in comparator mode as described in [Section 4.6.2 “ALERT/THERM2 Pin In THERM Mode”](#). In this mode the MASK_ALL bit is ignored.
 0 = The $\overline{\text{ALERT/THERM2}}$ pin acts in interrupt mode as described in [Section 4.6.1 “ALERT/THERM2 Pin Interrupt Mode”](#).
- 4 **RECD1:** Disables the Resistance Error Correction (REC) for the External Diode 1
 1 = REC is disabled for the External Diode 1
 0 = REC is enabled for the External Diode 1
- 3 **RECD2:** Disables the Resistance Error Correction (REC) for External Diode 2 and External Diode 3
 1 = REC is disabled for External Diode 2 and External Diode 3
 0 = REC is enabled for External Diode 2 and External Diode 3
- 2 **RANGE:** Configures the measurement range and data format of the temperature channels
 1 = The temperature measurement range is -64°C to +191.875°C and the data format is offset binary (see [Table 4-7](#))
 0 = The temperature measurement range is 0°C to +127.875°C and the data format is binary
- 1 **DA_DIS:** Disables the dynamic averaging feature on all temperature channels
 1 = The dynamic averaging feature is disabled
 0 = The dynamic averaging feature is enabled. All temperature channels will be converted with an averaging factor that is based on the conversion rate as shown in [Table 4-1](#).
- 0 **APDD (MCP9904 only):** Disables the anti-parallel diode operation
 1 = Anti-parallel diode mode is disabled. Only one external diode will be measured on the DP2 and DN2 pins.
 0 = Anti-parallel diode mode is enabled. Two external diodes will be measured on the DP2 and DN2 pins.