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Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



1.5A Switch-Mode Power Supply with Linear Regulator

The 34701 provides the means to efficiently supply the Freescale Power QUICC™ I, II, and other families of Freescale microprocessors and DSPs. The 34701 incorporates a high performance switching regulator, providing the direct supply for the microprocessor's core, and a low dropout (LDO) linear regulator control circuit provides the microprocessor I/O and bus voltage.

The switching regulator is a high-efficiency synchronous buck regulator with integrated N-channel power MOSFETs to provide protection features and to allow space-efficient, compact design.

The 34701 incorporates many advanced features; e.g., precisely maintained up/down power sequencing, ensuring the proper operation and protection of the CPU and power system.

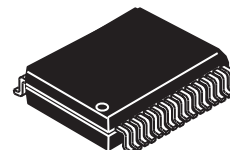
Features

- Operating voltage from 2.8V to 6.0V
- High-accuracy output voltages
- Fast transient response
- Switcher output current up to 1.5A
- Under-voltage lockout and overcurrent protection
- Enable inputs and programmable watchdog timer
- Voltage margining via I²C™ bus
- Reset with programmable power-ON delay
- Pb-free packaging designated by suffix code EW

I²C is a trademark of Philips Corporation.

34701

POWER SUPPLY



EW (Pb-FREE) SUFFIX
98AARH99137A
32-PIN SOICW

ORDERING INFORMATION

Device	Temperature Range (T _A)	Package
MCZ34701EW/R2	-40 to 85°C	32 SOICW

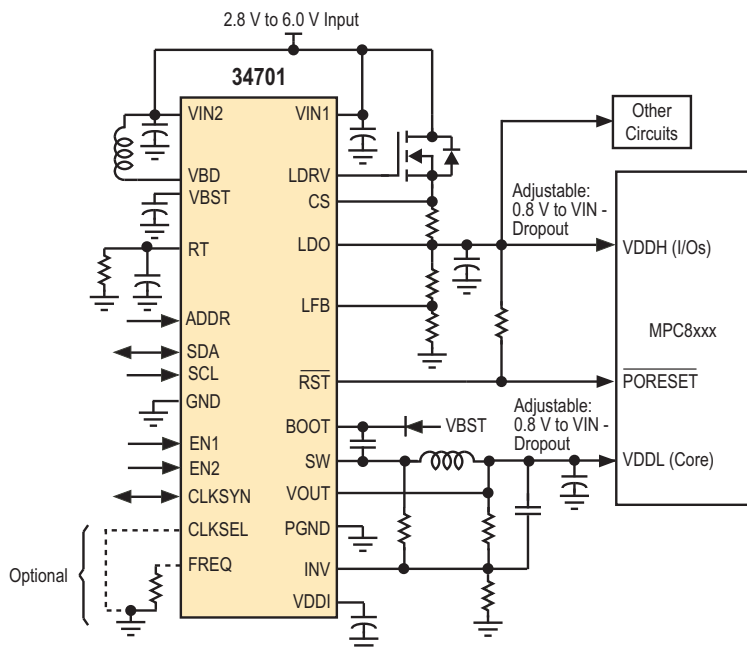


Figure 1. 34701 Simplified Application Diagram

INTERNAL BLOCK DIAGRAM

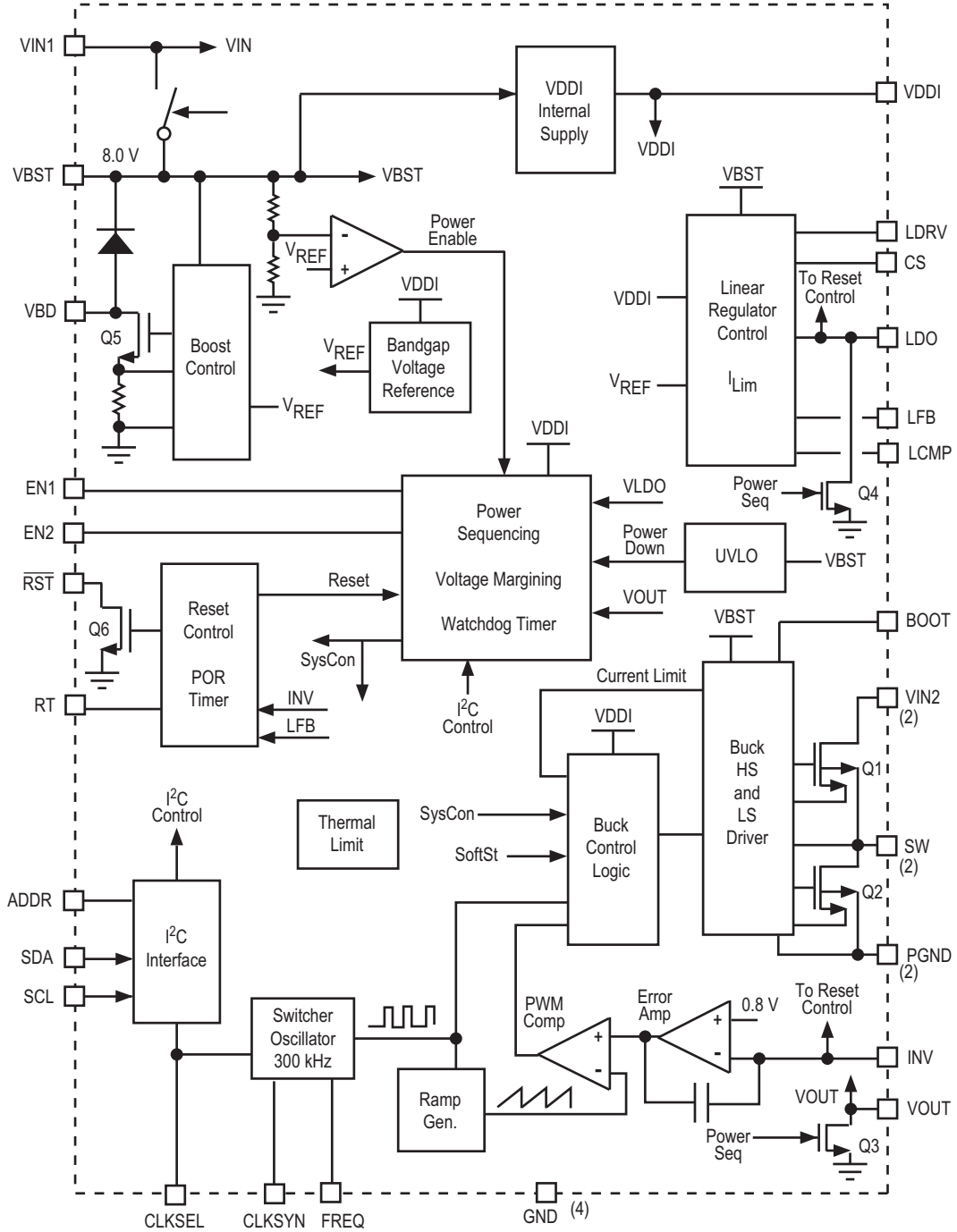


Figure 2. 34701 Simplified Internal Block Diagram

ARCHIVE INFORMATION

ARCHIVE INFORMATION

PIN CONNECTIONS

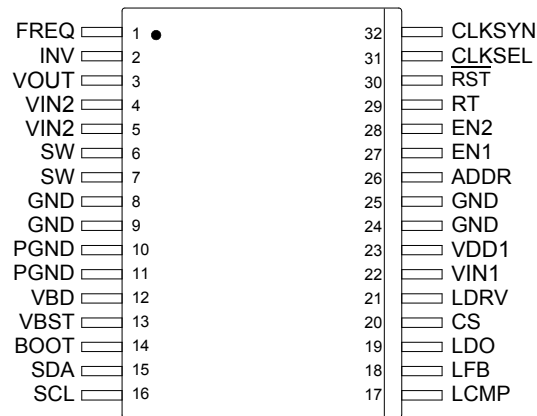


Figure 3. Pin Connections

Table 1. Pin Function Description

A functional description of each pin can be found in the [FUNCTIONAL PIN DESCRIPTION](#) section beginning on [page 16](#).

Pin	Pin Name	Formal Name	Definition
1	FREQ	Oscillator Frequency	This switcher frequency selection pin can be adjusted by connecting external resistor RF to the FREQ pin. The default switching frequency (FREQ pin left open or tied to VDD1) is set to 300kHz.
2	INV	Inverting Input	Buck controller error amplifier inverting input.
3	VOUT	Output Voltage	Output voltage of the buck converter. Input pin of the switching regulator power sequence control circuit.
4, 5	VIN2	Input Voltage 2	Buck regulator power input. Drain of the high side power MOSFET.
6, 7	SW	Switch	Buck regulator switching node. This pin is connected to the inductor.
8, 9 24, 25	GND	Ground	Analog ground of the IC, thermal heatsinking.
10, 11	PGND	Power Ground	Buck regulator power ground.
12	VBD	Boost Drain	Drain of the internal boost regulator power MOSFET.
13	VBST	Boost Voltage	Internal boost regulator output voltage. The internal boost regulator provides a 20mA output current to supply the drive circuits for the integrated power MOSFETs and the external N-channel power MOSFET of the linear regulator. The voltage at the VBST pin is 7.75V (nominal).
14	BOOT	Bootstrap	Bootstrap capacitor input.
15	SDA	Serial Data	I ² C bus pin. Serial data.
16	SCL	Serial Clock	I ² C bus pin. Serial clock.
17	LCMP	Linear Compensation	Linear regulator compensation pin.
18	LFB	Linear Feedback	Linear regulator feedback pin.
19	LDO	Linear Regulator	Input pin of the linear regulator power sequence control circuit.

Table 1. Pin Function Description (continued)

A functional description of each pin can be found in the [FUNCTIONAL PIN DESCRIPTION](#) section beginning on [page 16](#).

Pin	Pin Name	Formal Name	Definition
20	CS	Current Sense	Current sense pin of the LDO. Over-current protection of the linear regulator external power MOSFET. The voltage drop over the LDO current sense resistor RS is sensed between the CS and LDO pins. The LDO current limit can be adjusted by selecting the proper value of the current sensing resistor RS.
21	LDRV	Linear Drive	LDO gate drive of the external pass N-channel MOSFET.
22	VIN1	Input Voltage 1	The input supply pin for the integrated circuit. The internal circuits of the IC are supplied through this pin.
23	VDDI	Power Supply	Internal supply voltage. A ceramic low ESR 1uF 6V X5R or X7R capacitor is recommended.
26	ADDR	Address	I ² C address selection. This pin can either be left open, tied to VDDI, or grounded through a 10kΩ resistor.
27	EN1	Enable 1	Enable 1 Input. The combination of the logic state of the Enable 1 and Enable 2 inputs determines operation mode and type of power sequencing of the IC.
28	EN2	Enable 2	Enable 2 Input. The combination of the logic state of the Enable 1 and Enable 2 inputs determines operation mode and type of power sequencing of the IC.
29	RT	Reset Timer	This pin allows programming of the power-ON reset delay by means of an external RC network.
30	$\overline{\text{RST}}$	Reset Output (Active LOW)	The reset control circuit monitors both the switching regulator and the LDO feedback voltages. It is an open drain output and has to be pulled up to some supply voltage (e.g., the output of the LDO) by an external resistor.
31	CLKSEL	Clock Selection	This pin sets the CLKSYN pin as either an oscillator output or a synchronization input pin. The CLKSEL pin is also used for the I ² C address selection.
32	CLKSYN	Clock Synchronization	Oscillator output/synchronization input pin.

ELECTRICAL CHARACTERISTICS

MAXIMUM RATINGS

Table 2. Maximum Ratings

All voltages are with respect to ground unless otherwise noted. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Rating	Symbol	Value	Unit
ELECTRICAL RATINGS			
Supply Voltage	V_{IN1}, V_{IN2}	-0.3 to 7.0	V
Switching Node Voltage	V_{SW}	-1.0 to 7.0	V
Buck Regulator Bootstrap Input Voltage (BOOT - SW)	$V_{IN(BOOT)}$	-0.3 to 8.5	V
Boost Regulator Output Voltage	V_{BST}	-0.3 to 8.5	V
Boost Regulator Drain Voltage	V_{BD}	-0.3 to 9.5	V
\overline{RST} Drain Voltage	$V_{\overline{RST}}$	-0.3 to 7.0	V
Enable Pin Voltage at EN1, EN2	V_{EN}	-0.3 to 7.0	V
Logic Pin Voltage at SDA, SCL	V_{LOG}	-0.3 to 7.0	V
Analog Pin Voltage LDO, VOUT, \overline{RST} LDRV, LCMP, CS	V_{OUT} V_{LIN}	-0.3 to 7.0 -0.3 to 8.5	V
Pin Voltage at CLKSEL, ADDR, RT, FREQ, VDDI, CLKSYN, INV, LFB	V_{LOGIC}	-0.3 to 3.6	V
ESD Voltage ⁽¹⁾ Human Body Model Machine Model	V_{ESD}	±2000 ±200	V

Notes

- ESD1 testing is performed in accordance with the Human Body Model (CZAP=100 pF, RZAP=1500 Ω), ESD2 testing is performed in accordance with the Machine Model (CZAP=200 pF, RZAP=0 Ω), and the Charge Device Model.

Table 2. Maximum Ratings (continued)

All voltages are with respect to ground unless otherwise noted. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Rating	Symbol	Value	Unit
THERMAL RATINGS			
Storage Temperature	T_{STG}	-65 to 150	°C
Peak Package Reflow Temperature During Reflow ^{(2), (3)}	T_{PPRT}	Note 3	°C
Maximum Junction Temperature	T_{JMAX}	125	°C
Thermal Resistance	$R_{\theta JA}$		°C/W
Junction to Ambient (Single Layer) ^{(4), (5)}		70	
Junction to Ambient (Four Layers) ^{(4), (5)}		55	
Thermal Resistance, Junction to Base ⁽⁶⁾	$R_{\theta JB}$	18	°C/W
Operational Package Temperature (Ambient Temperature)	T_A	-40 to 85	°C

Notes

- Pin soldering temperature limit is for 10 seconds maximum duration. Not designed for immersion soldering. Exceeding these limits may cause malfunction or permanent damage to the device.
- Freescale's package reflow capability meets Pb-free requirements for JEDEC standard J-STD-020C. For Peak Package Reflow Temperature and Moisture Sensitivity Levels (MSL), Go to www.freescale.com, search by part number [e.g. remove prefixes/suffixes and enter the core ID to view all orderable parts. (i.e. MC33xxxD enter 33xxx), and review parametrics.
- Junction temperature is a function of on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board and board thermal resistance.
- Per JEDEC JESD51-6 with the board horizontal
- Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.

STATIC ELECTRICAL CHARACTERISTICS

Table 3. Static Electrical Characteristics

Characteristics noted under conditions $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ unless otherwise noted. Input voltages $V_{IN1} = V_{IN2} = 3.3\text{V}$ using the typical application circuit (see [Figure 33](#)), unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
GENERAL					
Operating Voltage Range (V_{IN1} , V_{IN2})	V_{IN}	2.8	–	6.0	V
Start-up Voltage Threshold (Boost Switching)	V_{ST}	–	1.6	1.8	V
VBST Under-voltage Lockout (VBST rising)	V_{BST_UVLO}	5.5	–	6.5	V
VBST Under-voltage Lockout Hysteresis	$V_{BST_UVLO_HYS}$	0.5	–	1.5	V
Input DC Supply Current (Normal Operation Mode, Enabled), Unloaded Outputs	I_{IN}	–	60	–	mA
VIN1 Pin Input Supply Current ($EN1 = EN2 = 0$)	I_{IN1}	–	10	–	mA
VIN2 Pin Input Leakage Current ($EN1 = EN2 = 0$)	I_{IN2}	–	100	–	μA
VDDI Internal Supply Voltage	V_{DDI}	2.9	–	3.3	V
VDDI Maximum Output Current (Externally Loaded)	I_{DDI}	–	–	-10	mA
BUCK CONVERTER					
Buck Converter Feedback Voltage ^{(7), (8)} IVOUT = 15mA to 1.5A. Includes Load Regulation Error	V_{INV}	0.784	0.800	0.816	V
Buck Converter Voltage Margining Step Size	V_{MVO}	–	1.0	–	%
Buck Converter Voltage Margining Highest Positive Value	V_{MP}	5.9	–	7.9	%
Buck Converter Voltage Margining Lowest Negative Value	V_{MN}	-7.9	–	-5.9	%
Buck Converter Line Regulation ^{(7), (8)} $V_{IN1} = V_{IN2} = 2.8\text{V}$ to 6.0V , IVOUT = 15mA to 1.5A	REG_{LNVO}	-1.0	–	1.0	%
Buck Converter Load Regulation ^{(7), (8)} $V_{IN1} = V_{IN2} = 2.8\text{V}$ to 6.0V , IVOUT = 15mA to 1.5A	REG_{LDVO}	-1.0	–	1.0	%
VOUT Input Leakage Current VOUT = 5.25V	I_{INVOUT}	–	3.5	–	mA
INV Input Leakage Current INV = 0.8V	I_{ININV}	-1.0	–	1.0	μA

Notes

7. Design information only. This parameter is not production tested.
8. IVOUT refers to load current on output switcher.

Table 3. Static Electrical Characteristics (continued)

Characteristics noted under conditions $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ unless otherwise noted. Input voltages $V_{IN1} = V_{IN2} = 3.3\text{V}$ using the typical application circuit (see [Figure 33](#)), unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
BUCK CONVERTER (CONTINUED)					
High Side Power MOSFET Q1 $R_{DS(ON)}$ ^{(9), (10)} ID = 500mA, $T_A = 25^{\circ}\text{C}$, $V_{BST} = 8.0\text{V}$	$R_{DS(ON)Q1}$	–	60	–	m Ω
Low Side Power MOSFET Q2 $R_{DS(ON)}$ ^{(9), (10)} ID = 500mA, $T_A = 25^{\circ}\text{C}$, $V_{BST} = 8.0\text{V}$	$R_{DS(ON)Q2}$	–	65	–	m Ω
Buck Converter Peak Current Limit (High Level)	I_{LIMH}	-4.0	-2.7	-1.5	A
VOUT Pull-down MOSFET Q3 Current Limit $T_A = 25^{\circ}\text{C}$, $V_{BST} = 8.0\text{V}$	I_{LIMPQ3}	0.75	–	2.0	A
VOUT Pull-down MOSFET Q3 $R_{DS(ON)}$ ⁽¹⁰⁾ ID = 1.0A, $V_{BST} = 8.0\text{V}$	$R_{DS(ON)PQ3}$	–	–	1.9	Ω
Thermal Shutdown (VOUT Pull-down MOSFET Q3) ⁽⁹⁾	T_{SD}	150	170	190	$^{\circ}\text{C}$
Thermal Shutdown Hysteresis ⁽⁹⁾	T_{HYS}	–	10	–	$^{\circ}\text{C}$

Notes

- 9. Design information only. This parameter is not production tested.
- 10. ID is the MOSFET drain current.

Table 3. Static Electrical Characteristics (continued)

Characteristics noted under conditions $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ unless otherwise noted. Input voltages $V_{IN1} = V_{IN2} = 3.3\text{V}$ using the typical application circuit (see [Figure 33](#)), unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
ERROR AMPLIFIER (BUCK CONVERTER)					
Input Impedance ⁽¹¹⁾	R_{IN}	–	500	–	$\text{k}\Omega$
Output Impedance ⁽¹¹⁾	R_{OUT}	–	150	–	Ω
DC Open Loop Gain ⁽¹¹⁾	A_{VOL}	–	80	–	dB
Gain Bandwidth Product ⁽¹¹⁾	G_{BW}	–	35	–	MHz
Slew Rate ⁽¹¹⁾	v_{SR}	–	200	–	$\text{V}/\mu\text{s}$
Output Voltage – High Level $V_{IN1} > 3.3\text{V}$, $I_{OEA} = -1.0\text{mA}$ ^{(11), (12)}	V_{EA_OH}	–	2.0	–	V
Output Voltage – Low Level $I_{OEA} = -1.0\text{mA}$ ^{(11), (12)}	V_{EA_OL}	–	0.4	–	V
Oscillator Ramp ⁽¹¹⁾	V_{SCRAMP}	–	0.5	–	V
OSCILLATOR					
CLKSYN Pin (open) Low Level Output Voltage $I_{OL} = +1.0\text{mA}$ ⁽¹³⁾	V_{OSC_OL}	–	–	0.4	V
CLKSYN Pin (open) High Level Output Voltage $I_{OH} = -1.0\text{mA}$ ⁽¹⁴⁾	V_{OSC_OH}	V_{DDI} -0.4V	–	–	V
CLKSYN Pin (grounded) Input Voltage Threshold	V_{OSC_IH}	1.2	–	2.0	V
CLKSYN Pin Pull-up Resistance	R_{PU}	60	–	240	$\text{k}\Omega$
Frequency Adjusting Reference Voltage	V_{FREQ}	–	1.26	–	V
BOOST REGULATOR					
Regulator Output Voltage $I_{BST} = 20\text{mA}$, $V_{IN1} = V_{IN2} = 2.8\text{V}$ to 6.0V	V_{BST}	7.3	7.7	8.3	V
Power MOSFET Q5 $R_{DS(ON)}$ ⁽¹¹⁾ $I_{BD} = 500\text{mA}$, $T_A = 25^{\circ}\text{C}$	$R_{DS(ON)Q5}$	–	650	1000	$\text{m}\Omega$
Regulator Recommended Output Capacitor	C_{BST}	–	10	–	μF
Regulator Recommended Output Capacitor Maximum ESR	$ESRC_{BST}$	–	100	–	$\text{m}\Omega$

Notes

11. Design information only. This parameter is not production tested.
12. IOEA Refers to Error Amplifier Output Current.
13. IOL Refers to I/O Low Level
14. IOH Refers to I/O High Level

Table 3. Static Electrical Characteristics (continued)

Characteristics noted under conditions $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ unless otherwise noted. Input voltages $V_{IN1} = V_{IN2} = 3.3\text{V}$ using the typical application circuit (see [Figure 33](#)), unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
LINEAR REGULATOR (LDO)					
LDO Feedback Voltage ⁽¹⁶⁾ VIN1 = VIN2 = 2.8V to 6.0V, ILDO = 10mA to 1000mA. Includes Load Regulation Error	V_{LFB}	0.784	0.800	0.816	V
LDO Voltage Margining Step Size	V_{MLDO}	–	1.0	–	%
LDO Voltage Margining Highest Positive Value	V_{MP}	5.9	–	7.9	%
LDO Voltage Margining Lowest Negative Value	V_{MN}	-7.9	–	-5.9	%
LDO Line Regulation ⁽¹⁶⁾ VIN1 = VIN2 = 2.8V to 6.0V, ILDO = 1000mA	REG_{LNVLDO}	-1.0	–	1.0	%
LDO Load Regulation ⁽¹⁶⁾ ILDO = 10mA to 1000mA	REG_{LDVLD0}	-1.0	–	1.0	%
LDO Ripple Rejection, Dropout Voltage ⁽¹⁶⁾ VDO = 1.0V, VRIIPPLE = +1.0V p-p Sinusoidal, f = 300kHz, ILDO = 500mA ⁽¹⁵⁾	V_{LDO_RR}	–	40	–	dB
LDO Maximum Dropout Voltage (VIN - VLDO), using IRL2703 ⁽¹⁶⁾ VLDO = 2.5V, ILDO = 1000mA	V_{DO}	–	50	75	mV
LDO Current Sense Comparator Threshold Voltage (VCS - VLDO)	V_{CSTH}	35	50	65	mV
LDO Pin Input Current, VLDO = 5.25V	I_{LDO}	1.0	1.9	4.0	mA
LDO Feedback Input Current (LFB Pin), VLFB = 0.8V	I_{LFB}	-1.0	–	1.0	μA
LDO Drive Output Current (LDRV Pin), VLDRV = 0V	I_{LDRV}	-5.0	-3.3	-2.0	mA
CS Pin Input Leakage Current VCS = 5.25V	I_{CSLK}	50	–	200	μA
LDO Pull-down MOSFET Q4 Current Limit $T_A = 25^{\circ}\text{C}$, VBST = 8.0V (LDO Pin)	I_{LIMQ4}	0.75	–	2.0	A
LDO Pull-down MOSFET Q4 RDS(ON) ID = 1.0A, VBST = 8.0V	$R_{DS(ON)Q4}$	–	–	1.9	Ω
LDO Recommended Output Capacitance	C_{LDO}	–	10	–	μF
LDO Recommended Output Capacitor ESR	R_{LDO}	–	5.0	–	m Ω
Thermal Shutdown (LDO Pull-down MOSFET Q4) ⁽¹⁵⁾	T_{SD}	150	170	190	$^{\circ}\text{C}$
Thermal Shutdown Hysteresis ⁽¹⁵⁾	T_{SDHYS}	–	10	–	$^{\circ}\text{C}$

Notes

- 15. Design information only. This parameter is not production tested.
- 16. IDO refers to Load Current on External LDOFET - IRL2703 is the Intersil MOSFET.

Table 3. Static Electrical Characteristics (continued)

Characteristics noted under conditions $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ unless otherwise noted. Input voltages $V_{IN1} = V_{IN2} = 3.3\text{V}$ using the typical application circuit (see [Figure 33](#)), unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
CONTROL AND SUPERVISORY CIRCUITS					
Enable (EN1, EN2) Input Voltage Threshold	V_{EN-TH}	1.0	1.5	2.0	V
Enable (EN1, EN2) Pull-down Resistance	R_{EN-PD}	30	55	90	$k\Omega$
\overline{RST} Low-level Output Voltage, IOL = 5.0mA	V_{OL}	–	–	0.4	V
\overline{RST} Leakage Current, OFF State, Pulled Up to 5.25V	$I_{LKG-\overline{RST}}$	–	–	10	μA
\overline{RST} Under-voltage Threshold on VOUT ($\Delta V_{OUT}/V_{OUT}$) ⁽¹⁷⁾	$V_{OUTTITH}$	-14	–	-0.5	%
\overline{RST} Over-voltage Threshold on VOUT ($\Delta V_{OUT}/V_{OUT}$) ⁽¹⁷⁾	$V_{OUTTITH}$	0.5	–	14	%
\overline{RST} Under-voltage Threshold on VLDO ($\Delta V_{LDO}/V_{LDO}$) ⁽¹⁷⁾	V_{LDOITH}	-12	–	-4.0	%
\overline{RST} Over-voltage Threshold on VLDO ($\Delta V_{LDO}/V_{LDO}$) ⁽¹⁷⁾	V_{LDOITH}	4.0	–	12	%
\overline{RST} Timer Voltage Threshold	V_{TH-RT}	1.0	1.2	1.5	V
\overline{RST} Timer Source Current (RT pin at 0V)	I_{S-RT}	-17	–	-34	mA
\overline{RST} Timer Leakage Current	I_{LKG-RT}	-1.0	–	1.0	μA
\overline{RST} Timer Saturation Voltage, Reset Timer Current = 300 μA	V_{SAT-RT}	–	35	100	mV
Maximum Recommended Value of the Reset Timer Capacitor	C_t	–	–	47	μF
CLKSEL Threshold Voltage	V_{THCLKS}	1.2	1.6	2.0	V
CLKSEL Pull-up Resistance	$R_{PU-CLKS}$	60	120	240	$k\Omega$
ADDR Threshold Voltage ⁽¹⁷⁾	V_{THADDR}	1.2	1.6	2.0	V
ADDR Pull-up Resistance	$R_{PU-ADDR}$	60	120	240	$k\Omega$
Thermal Shut-down (IC sensor) ⁽¹⁷⁾	T_{LIM}	150	170	190	$^{\circ}\text{C}$
Thermal Shut-down Hysteresis ⁽¹⁷⁾	T_{LIMHYS}	–	10	–	$^{\circ}\text{C}$

SDA, SCL PINS I²C BUS (STANDARD)

Input Threshold Voltage (Pin SCL), Rising Edge ⁽¹⁷⁾	V_{LTH}	1.3	–	1.7	V
Input Threshold Voltage (Pin SDA)	V_{LTH}	1.3	–	1.7	V
SDA, SCL Input Current, Input Voltage = 5.25V (VIN1)	I_{IN}	–	1.0	10	μA
SDA Low-level Output Voltage, 3.0mA Sink Current	V_{OL}	–	–	0.4	V
SDA, SCL Capacitance ⁽¹⁷⁾	C_{INPUT}	–	7.0	10	pF

Notes

17. Design information only. This parameter is not production tested.

DYNAMIC ELECTRICAL CHARACTERISTICS

Table 4. DYNAMIC ELECTRICAL CHARACTERISTICS

Characteristics noted under conditions $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ unless otherwise noted. Input voltages $V_{IN1} = V_{IN2} = 3.3\text{V}$ using the typical application circuit (see [Figures 33](#)), unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
BUCK CONVERTER					
Duty Cycle Range (Normal Operation) ⁽¹⁸⁾	t_D	0.0	–	95	%
Switching Node SW Rise Time ⁽¹⁸⁾ VIN = 5.0V, ILOAD = 1.0A	t_{RISE}	–	7.0	–	ns
Switching Node SW Fall Time ⁽¹⁸⁾ VIN = 5.0V, ILOAD = 1.0A	t_{FALL}	–	17	–	ns
Maximum Deadtime ⁽¹⁸⁾	t_D	–	35	–	ns
Buck Control Loop Propagation Delay ⁽¹⁸⁾ VINV < 0.8V to VSW > 90% of High Level or VINV > 0.8V to VSW < 10% of Low Level	t_{PD}	–	50	–	ns
Soft Start Duration (Power Sequencing Disabled, EN1 = 1, EN2 = 1) ⁽¹⁸⁾	t_{SS}	200	350	800	μs
Fault Condition Timeout ⁽¹⁸⁾	t_{FAULT}	7.0	10	15	ms
Retry Timer Cycle ⁽¹⁸⁾	t_{RET}	70	100	150	ms
OSCILLATOR					
Oscillator Center Frequency ⁽²⁰⁾ RF = 11.3k Ω	f_{OSC}	270	300	330	kHz
Oscillator Frequency Range	f_{OSC}	200	–	400	kHz
Oscillator Frequency Adjusting Resistor Range	R_{FREQ}	7.0	–	22	k Ω
Oscillator Frequency Adjustment ^{(19), (20)} RF = 7.0k Ω	f_{OSC}	400	–	–	kHz
Oscillator Frequency Adjustment ^{(19), (20)} RF = 22k Ω	f_{OSC}	–	–	200	kHz
Oscillator Default Frequency (Switching Frequency), FREQ Pin Open	f_{OSC}	–	300	–	kHz
Oscillator Output Signal Duty Cycle (Square Wave, 180° Out-of-Phase with the Internal Suitable Oscillator)	D_{OSC}	40	50	60	%
Synchronization Pulse Minimum Duration ⁽¹⁸⁾	t_{SYNC}	1.0	–	–	μs

Notes

- 18. Design information only. This parameter is not production tested.
- 19. see Figure 4 for more details
- 20. RF is RFREQ

Table 4. DYNAMIC ELECTRICAL CHARACTERISTICS (continued)

Characteristics noted under conditions $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ unless otherwise noted. Input voltages $V_{IN1} = V_{IN2} = 3.3\text{V}$ using the typical application circuit (see [Figures 33](#)), unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
BOOST REGULATOR					
Boost Regulator MOSFET Maximum ON Time ⁽²¹⁾	t_{ON}	–	24	–	μs
Boost Regulator Control Loop Propagation Delay ⁽²¹⁾	t_{BST_PD}	–	50	–	ns
Boost Switching Node VBD Rise Time ⁽²¹⁾ IBST = 20mA	t_{B_RISE}	–	5.0	–	ns
Boost Switching Node VBD Fall Time ⁽²¹⁾ IBST = 20mA	t_{B_FALL}	–	3.0	–	ns
LINEAR REGULATOR (LDO)					
Fault Condition Timeout	t_{FAULT}	7.0	10	15	ms
Retry Timer Cycle	t_{RET}	70	100	150	ms
RESET MONITOR ($\overline{\text{RST}}$)					
Monitoring LFB Pin Delay	$t_{D_RST_LFB}$	12	–	28	μs
Monitoring INV Pin Delay	$t_{D_RST_INV}$	12	–	28	μs
SCA, SCL PIN, I²C BUS (STANDARD)					
SCL Clock Frequency ⁽²¹⁾	f_{SCL}	–	–	100	kHz
Bus Free Time Between a STOP and a START Condition ⁽²¹⁾	t_{BUF}	4.7	–	–	μs
Hold Time (Repeated) START Condition (After this period, the first clock pulse is generated.) ⁽²¹⁾	t_{HD_STA}	4.0	–	–	μs
Low Period of the SCL Clock ⁽²¹⁾	t_{LOW}	4.7	–	–	μs
High Period of the SCL Clock ⁽²¹⁾	t_{HIGH}	4.0	–	–	μs
SDA Fall Time from V_{IH_MAX} to V_{IL_MIN} , Bus Capacitance 10pF to 400pF, 3.0mA Sink Current ^{(21), (23)}	t_F	–	–	250	ns
Setup Time for a Repeated START Condition ⁽²¹⁾	t_{SU_STA}	4.7	–	–	μs
Data Hold Time for I ² C Bus Devices ^{(21), (22)}	t_{HD_DAT}	0.0	–	–	μs
Data Setup Time ⁽²¹⁾	t_{SU_DAT}	250	–	–	ns
Setup Time for STOP Condition ⁽²¹⁾	t_{SU_STO}	4.0	–	–	μs
Capacitive Load for Each Bus Line ⁽²¹⁾	C_B	–	–	400	pF

Notes

21. Design information only. This parameter is not production tested.
22. The device provides an internal hold time of at least 300ns for the SDA signal (refer to the V_{IH_MIN} of the SCL signal) to bridge the undefined region of the falling edge of SCL.
23. V_{IH} is high level voltage on I²C bus lines and V_{IL} is low level voltage on I²C bus lines

TIMING DIAGRAM

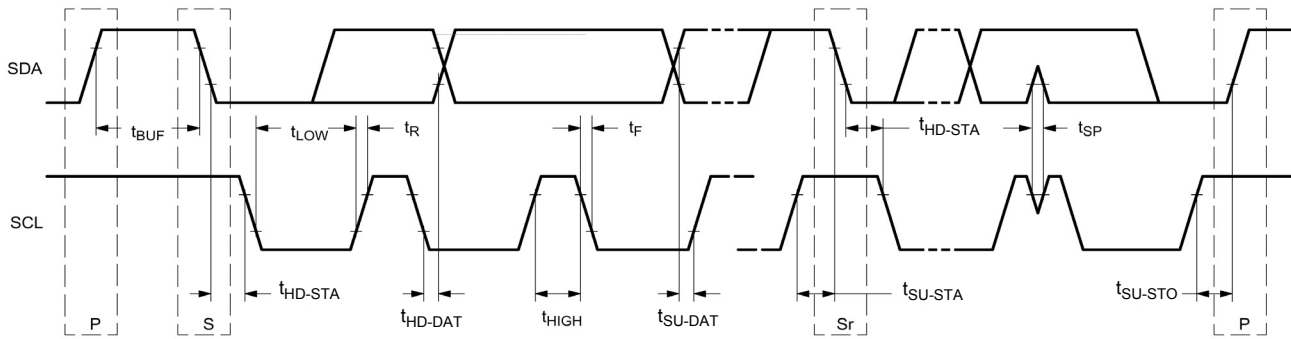


Figure 4. Definition of Time on the I²C Bus

ELECTRICAL PERFORMANCE CURVES

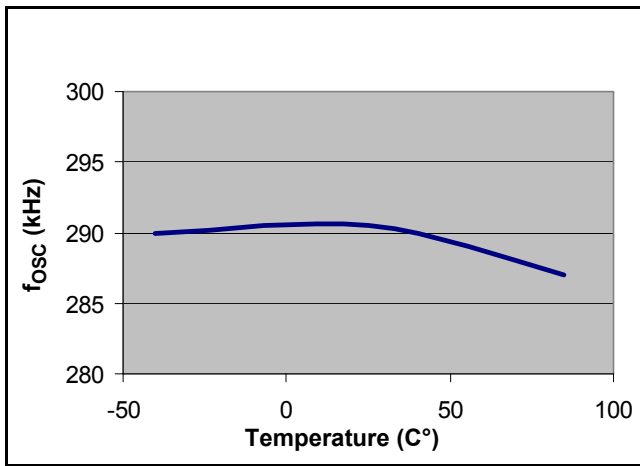


Figure 5. f_{osc} vs. Temperature

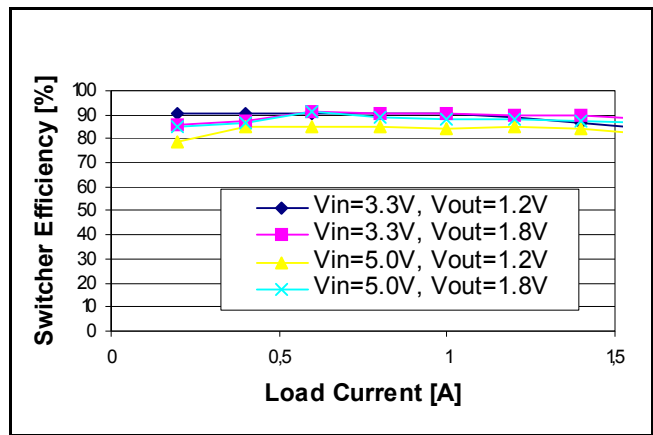


Figure 7. Switcher Efficiency vs. Load Current

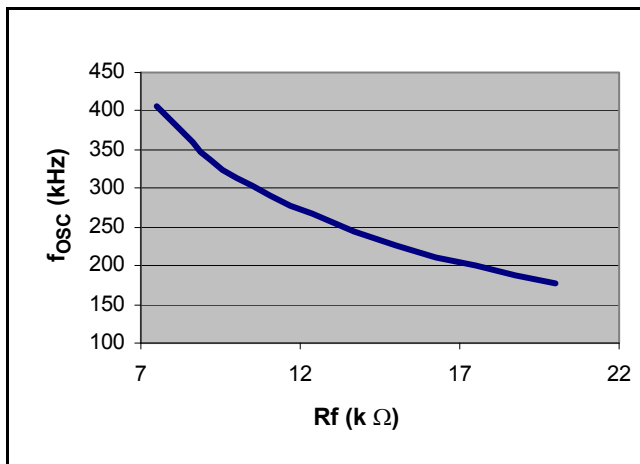


Figure 6. f_{osc} vs. R_f

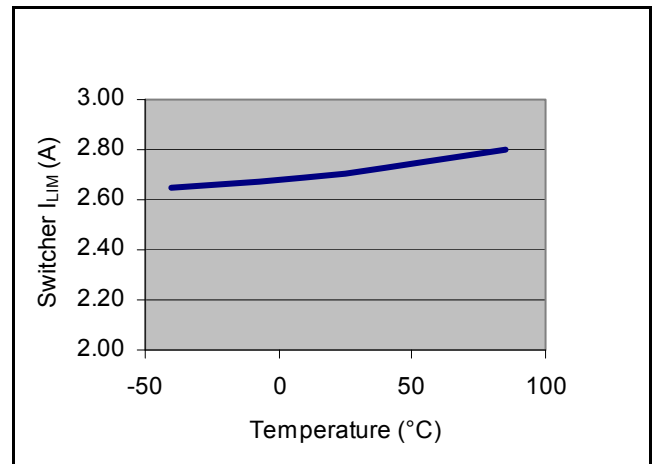


Figure 8. Switcher I_{Lim} vs. Temperature

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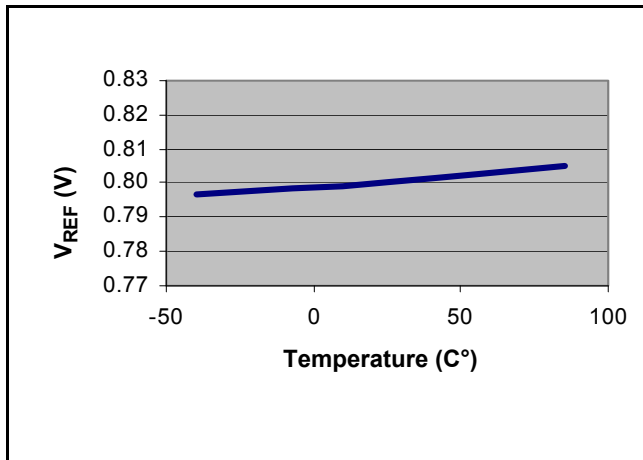


Figure 9. V_{REF} vs. Temperature

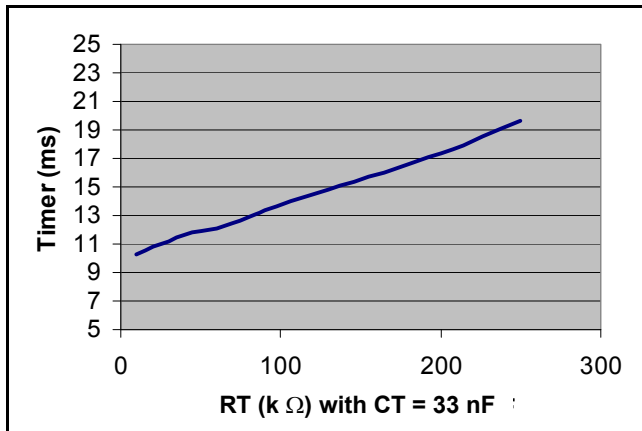


Figure 10. Timer (ms) vs. RT

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FUNCTIONAL DESCRIPTION

INTRODUCTION

The 34701 power supply integrated circuit provides the means to efficiently supply the Freescale Power QUICC and other families of Freescale microprocessors. It incorporates a high performance synchronous buck regulator, supplying the microprocessor's core, and a low dropout (LDO) linear regulator providing the microprocessor I/O and bus voltages.

This device incorporates many advanced features; e.g., precisely maintained up/down power sequencing, ensuring the proper operation and protection of the CPU and power system. At the same time, it provides high flexibility of configuration, allowing the maximum optimization of the power supply system.

FUNCTIONAL PIN DESCRIPTION

OSCILLATOR FREQUENCY PIN (FREQ)

This switcher frequency selection pin can be adjusted by connecting external resistor RF to the FREQ pin. The default switching frequency (FREQ pin left open or tied to VDDI) is set to 300kHz.

INVERTING INPUT PIN (INV)

Buck Controller Error Amplifier inverting input.

OUTPUT VOLTAGE PIN (VOUT)

Output voltage of the buck converter. Input pin of the switching regulator power sequence control circuit.

INPUT VOLTAGE 2 PINS (VIN2)

Buck regulator power input. Drain of the high side power MOSFET.

SWITCH PINS (SW)

Buck regulator switching node. This pin is connected to the inductor.

GROUND PINS (GND)

Analog ground of the IC, thermal heatsinking.

POWER GROUND PINS (PGND)

Buck regulator power ground.

BOOST DRAIN PIN (VBD)

Drain of the internal boost regulator power MOSFET.

BOOST VOLTAGE PIN (VBST)

Internal boost regulator output voltage. The internal boost regulator provides a 20mA output current to supply the drive circuits for the integrated power MOSFETs and the external N-channel power MOSFET of the linear regulator. The voltage at the VBST pin is 7.75V nominal.

BOOTSTRAP PIN (BOOT)

Bootstrap capacitor input.

SERIAL DATA PIN (SDA)

I²C bus pin. Serial data.

SERIAL CLOCK PIN (SCL)

I²C bus pin. Serial clock.

LINEAR COMPENSATION PIN (LCMP)

Linear regulator compensation pin.

LINEAR FEEDBACK PIN (LFB)

Linear regulator feedback pin.

LINEAR REGULATOR PIN (LDO)

Input pin of the linear regulator power sequence control circuit.

CURRENT SENSE PIN (CS)

Current sense pin of the LDO. Over-current protection of the linear regulator external power MOSFET. The voltage drop over the LDO current sense resistor RS is sensed between the CS and LDO pins. The LDO current limit can be adjusted by selecting the proper value of the current sensing resistor RS.

LINEAR DRIVE PIN (LDRV)

LDO gate drive of the external pass N-channel MOSFET.

INPUT VOLTAGE 1 PIN (VIN1)

The input supply pin for the integrated circuit. The internal circuits of the IC are supplied through this pin.

POWER SUPPLY PIN (VDDI)

Internal supply voltage. A ceramic low ESR 1uF 6V X5R or X7R capacitor is recommended.

ADDRESS PIN (ADDR)

The ADDR pin is used to set the address of the device when used in an I²C communication. This pin can either be tied to VDDI or grounded through a 10kΩ resistor. Refer to [I²C Bus Operation on page 26](#) for more information on this pin.

ENABLE 1 AND 2 PINS (EN1 AND EN2)

These two pins permit positive logic control of the Enable function and selection of the Power Sequencing mode concurrently. [Table 5](#) depicts the EN1 and EN2 function and Power Sequencing mode selection.

Both EN1 and EN2 pins have internal pull-down resistors and both can withstand a short circuit to the supply voltage, 6.0V.

Table 5. Operating Mode Selection

EN1	EN2	Operating Mode
0	0	Regulators Disabled
0	1	Standard Power Sequencing
1	0	Inverted Power Sequencing
1	1	No Power Sequencing, Regulators Enabled

RESET TIMER PIN (RT)

The Reset Timer power-up delay (RT) pin is used to set the delay between the time when the LDO and switcher outputs are active and stable and the $\overline{\text{RST}}$ output is released. An external resistor and capacitor are used to program the timer. The power-up delay can be obtained by using the following formula:

$$t_D = 10\text{ms} + R_t C_t$$

Where R_t is the Reset Timer programming resistor and C_t is the Reset Timer programming capacitor, both connected in parallel from RT to ground.

Note Observe the maximum C_t value and expect reduced accuracy if R_t is less than 10kΩ.

RESET OUTPUT PIN ($\overline{\text{RST}}$)

The Reset Control circuit monitors both the switching regulator and the LDO feedback voltages. It is an open drain output and has to be pulled up to some supply voltage (e.g., the output of the LDO) by an external resistor.

The Reset Control circuit supervises both output voltages—the linear regulator output VLDO and the switching regulator output VOUT. When either of these two regulators is out of regulation (high or low), the $\overline{\text{RST}}$ pin is pulled low. There is a 20μs delay filter preventing erroneous resets. During power-up sequencing, $\overline{\text{RST}}$ is held low until the Reset Timer times out.

CLOCK SELECTION PIN (CLKSEL)

This pin sets the CLKSYN pin as either an oscillator output or a synchronization input pin. The CLKSEL pin is also used for the I²C address selection.

CLOCK SYNCHRONIZATION PIN (CLKSYN)

Oscillator output/synchronization input pin.

FUNCTIONAL INTERNAL BLOCK DESCRIPTION

INTRODUCTION

The 34701 incorporates a high performance synchronous buck regulator, supplying the microprocessor's core, and a low dropout (LDO) linear regulator providing the microprocessor I/O and bus voltages. This device

incorporates many advanced features; e.g., precisely maintained up/down power sequencing, ensuring the proper operation and protection of the CPU and power system.

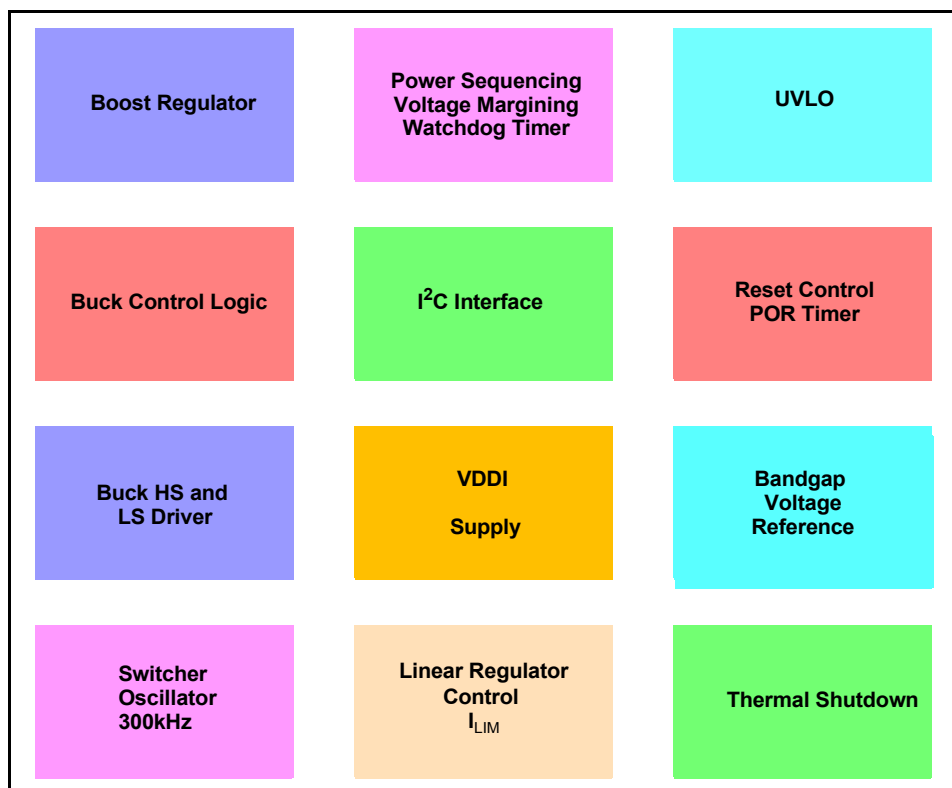


Figure 11. 34701 Functional Internal Block Diagram

BOOST REGULATOR

A boost regulator provides a high-voltage necessary to properly drive the buck regulator power MOSFETs, especially during the low input voltage condition. The LDO regulator external N-channel MOSFET gate is also powered from the boost regulator. In order to properly enhance the high side MOSFETs when only a +3.3V supply rail powers the integrated circuit, the boost regulator provides an output voltage of 7.75V nominal value.

The 34701 boost regulator uses a simple hysteretic current control technique, which allows fast power-up and does not require any compensation. When the boost regulator main power switch (low side) is turned on, the current in the inductor starts to ramp up. After the inductor current reaches the upper current limit (nominally set at 1.0A), the low-side switch is turned off and the current charges the output capacitor through the internal rectifier.

When the inductor current falls below the valley current limit value (nominally 600mA), the low side switch is turned on again, starting the next switching cycle. After the boost regulator output capacitor reaches approximately 6.0 volts, the peak and valley current limit levels are proportionally scaled down to approximately one fifth of their original values. When the boost regulator reaches its regulation limit (7.75V typical), the low side switch is turned off until the output voltage falls below the regulation limit again.

The higher current limit values in the beginning of the boost regulator start-up sequence allow fast power up of the whole IC, while the normal operation with reduced current limit greatly reduces the switching noise and therefore improves the overall EMC performance. See [Figure 12](#) for the boost regulator output voltage and inductor current waveforms (picture not to scale).

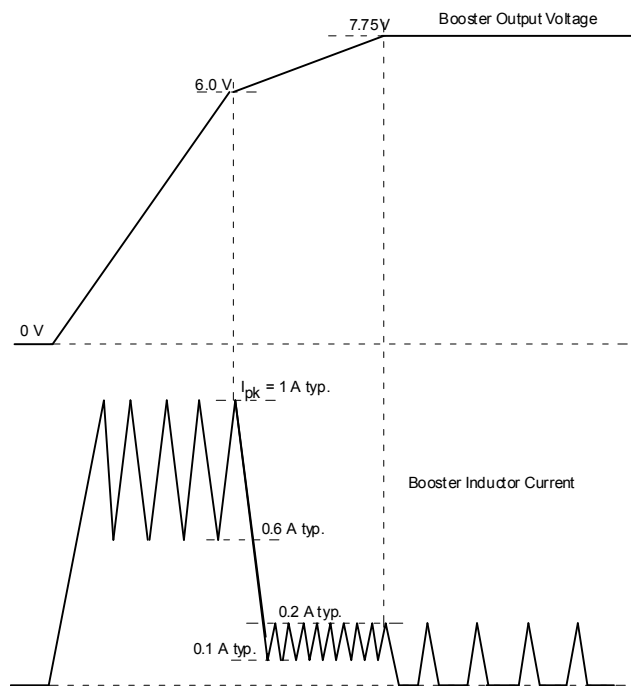


Figure 12. Boost Regulator Startup (Not To Scale)

SWITCHING REGULATOR

The switching regulator is a high frequency (300kHz default, adjustable in the range from 200kHz to 400kHz), synchronous buck converter driving integrated high side and low side N-channel power MOSFETs. The switching regulator output voltage is adjustable by means of an external resistor divider to provide the required output voltage within $\pm 2.0\%$ accuracy, and is intended to directly power the core of the microprocessor. The buck controller uses a PWM voltage mode control topology with feed-forward to achieve excellent line and load regulation.

The 34702 integrated boost regulator provides a 7.75V rail which is used to properly bias the switcher's MOSFET. In addition, the boost structure has a very low start-up voltage (Typically 1.6V), hence ensuring very low input voltage functionality. A typical bootstrap technique is used to provide voltage necessary to properly enhance the high side MOSFET gate. When the regulator is supplied only from low input voltage (e.g., single +3.3V supply rail), the bootstrap capacitor is charged from the internal boost regulator output VBST through an external diode. This arrangement allows the 34701 to operate from very low input voltage and also comply with the power sequencing requirements of the supplied microcontroller.

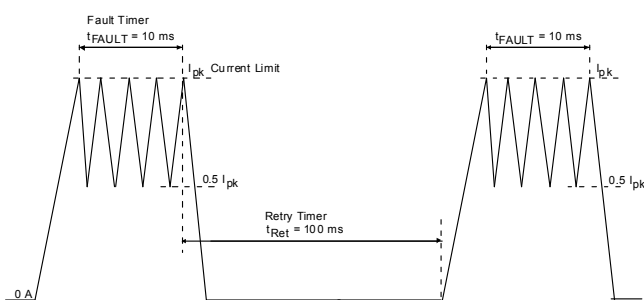


Figure 13. Switching Regulator Current Limit (Not To Scale)

To avoid destruction of the supplied circuits, the switching regulator has a current limit with retry capability. When an over-current condition occurs and the switch current reaches the peak current limit value, the main (high side) switch is turned off until the inductor current decays to the valley value, which is one half of the peak current limit. If an over-current condition exists for 10ms, the buck regulator control circuit shuts the switcher OFF and the switcher retry timer starts to time out. When the timer expires after 100ms, the switcher engages the start-up sequence and runs for 10ms, repeatedly checking for the over-current condition. Figure 13 describes the switching regulator over-current condition and current limit. During the current limited operation (e.g., in case of short-circuit on the switching regulator output), the switching regulator operation is not synchronized to the oscillator frequency. Figure 14 (respectively Figure 15) depicts the current limit with a retry capability feature of the switcher (respectively LDO).

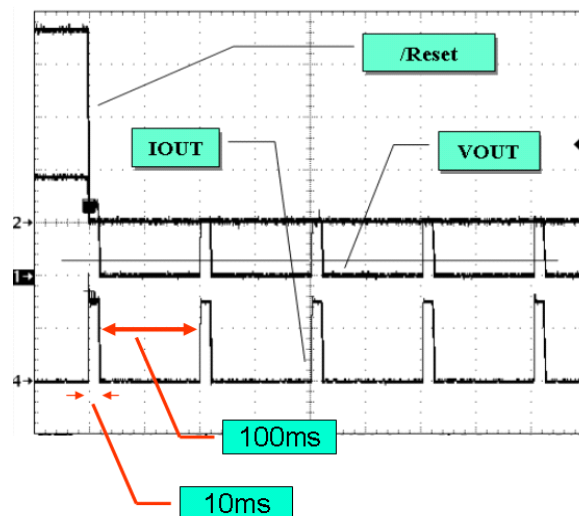


Figure 14. Switching Converter Over-current Protection

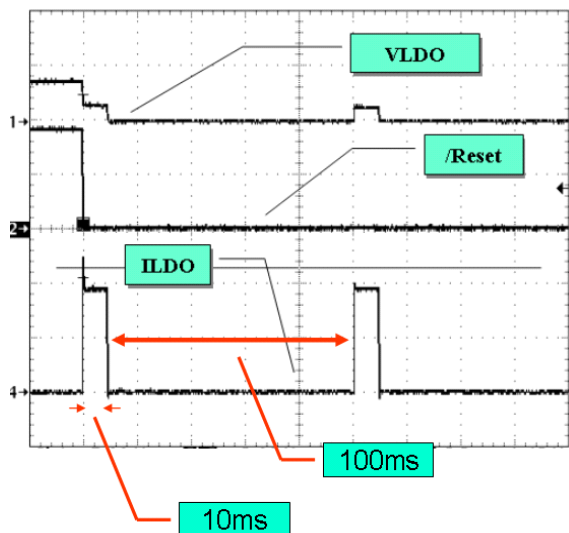


Figure 15. LDO Converter Over-current Protection

The output voltage VOUT can be adjusted by means of an external resistor divider connected to the feedback control pin INV. The switching regulator output voltage can be adjusted in the range of 0.8V to VIN - buck dropout voltage. Power-up, power-down, and fault management are coordinated with the linear regulator.

SWITCHER OSCILLATOR

A 300kHz (default) oscillator sets the switching frequency of the buck regulator. The frequency of the oscillator can be adjusted between 200kHz and 400kHz by an optional external resistor RF connected from the FREQ pin of the integrated circuit to ground. See [Figure 6](#) on page 14 for frequency resistor selection.

The CLKSYN pin can be configured as either an oscillator output when the CLKSEL pin is left open or as a synchronization input when the CLKSEL pin is grounded. The oscillator output signal is a square wave logic signal with 50% duty cycle, 180 degrees out-of-phase with the internal clock signal. This allows opposite phase synchronization of two 34702 devices.

When the CLKSYN pin is used as a synchronization input (CLKSEL pin grounded), the external resistor RF chosen from the chart in [Figure 6](#) should be used to synchronize the internal slope compensation ramp to the external clock. Operation is only recommended between 200kHz and 400kHz. The supplied synchronization signal does not need to be 50% duty cycle. Minimum pulse width is 1.0µs.

LOW DROPOUT LINEAR REGULATOR (LDO)

The adjustable low dropout linear regulator (LDO) is capable of supplying a 1.0A output current. It has a current limit with retry capability. When the voltage measured across the current sense resistor reaches the 50mV threshold, the control circuit limits the current for 10ms. If the over-current condition still exists, the linear regulator is turned off and the retry timer starts to time out. When the timer expires after

100ms, the LDO tries to power-up again for 10ms, repeatedly checking for the over-current condition. The current limit of the LDO can be set by using the following formula:

$$I_{LIM} = 50mV/RS$$

Where RS is the LDO current sense resistor, connected between the CS pin and the LDO pin output (see [Figure 33](#) on page 34), and 50mV is the typical value of the LDO current sense comparator threshold voltage.

When no current sense resistor is used, it is still possible to detect the over-current condition by tying the current sense pin CS to the VBST voltage. In this case, the over-current condition is sensed by saturation of the linear regulator driver buffer.

The output voltage of the LDO can be adjusted by means of an external resistor divider connected to the feedback control pin LFB. The linear regulator output voltage can be adjusted in the range of 0.8V to VIN - LDO dropout voltage. Power-up, power-down, and fault management are coordinated with the switching regulator.

POWER SEQUENCING VOLTAGE MARGINING WATCHDOG TIMER

A watchdog function is available via I²C bus communication. It is possible to select either window watchdog or timeout watchdog operation, as illustrated in [Figure 16](#).

Watchdog timeout starts when the watchdog function is activated via I²C bus sending a watchdog programming command byte, thus determining watchdog operation (window or timeout) and period duration (refer to [Table 8](#), page 27). If the watchdog is cleared by receiving a new watchdog programming command through the I²C bus, the watchdog timer is reset and the new timeout period begins. If the watchdog time expires, the RST will become active (LOW) for a time determined by the RC components of the RT timer plus 10ms. After a watchdog timeout, the function is no longer active.

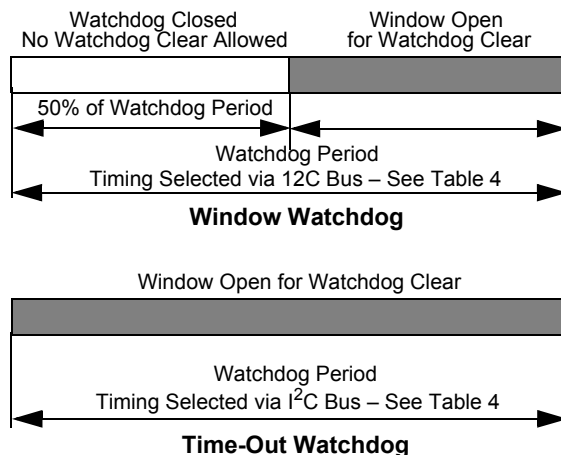


Figure 16. Watchdog Operation

When the window watchdog function is selected, the timer cannot be cleared during the closed window time, which is 50% of the total watchdog period. When the watchdog is cleared, the timer is reset and starts a new tim-out period. If

the watchdog is not cleared during the open window time, the $\overline{\text{RST}}$ will become active (LOW) for a time determined by the RC components of the RT timer plus 10ms.

ARCHIVE INFORMATION

ARCHIVE INFORMATION

FUNCTIONAL DEVICE OPERATION

OPERATIONAL MODES

THERMAL SHUTDOWN

To increase the overall safety of the system designed with the 34701, an internal thermal shutdown function has been incorporated into the switching regulator circuit. The 34701 senses the temperature of the buck regulator main switching MOSFET (high side MOSFET M1; see [Figure 2](#) on page 2), the low side (synchronous MOSFET M2), and control circuit. If the temperature of any of the monitored components exceeds the limit of safe operation (Thermal Shutdown), the switching regulator and the LDO shut down. After the temperature falls below the value given by the thermal shutdown hysteresis window, the switcher tries again to operate.

The VOUT pull-down MOSFET M3 has an independent thermal shutdown control. If the M3 temperature exceeds the thermal shutdown, the M3 is turned off without affecting the switcher operation.

The LDO pull-down MOSFET M4 has an independent thermal shutdown control. If the M4 temperature exceeds the thermal shutdown, the M4 will be turned off without affecting the LDO operation.

SOFT START

A switching regulator soft start feature is incorporated in the 34701. The soft start is active each time the IC is enabled, VIN is reapplied, or after a fault retry. Other transient events do not activate the soft start.

VOLTAGE MARGINING

The 34701 includes a voltage margining feature accessed through the I²C bus. Voltage margining allows for independent adjustment of the switcher VOUT voltage and the linear output VLDO. Each can be adjusted up and down in 1.0% steps to a range of $\pm 7.0\%$. This feature allows for worst case system validation; i.e., determining the design margin. Margining details are described in the section entitled I²C Bus Operation, beginning on page 26 of this datasheet.

POWER SEQUENCING MODES

The power sequencing of the two outputs of this power supply IC is in compliance with the Freescale Power QUICC and other 32-bit microprocessor requirements. When the input voltage is applied, the switcher and linear regulator outputs follow the supply rail voltage during power-up and power-down in the limits given by the microcontroller power sequencing specification, illustrated in [Figures 17](#) through [19](#). There are two possible power sequencing modes, Standard and Inverted, as explained in more detail below. The third mode of operation is Power Sequencing Disabled.

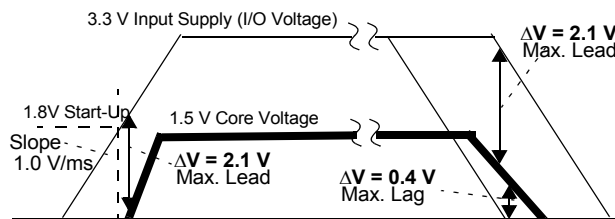
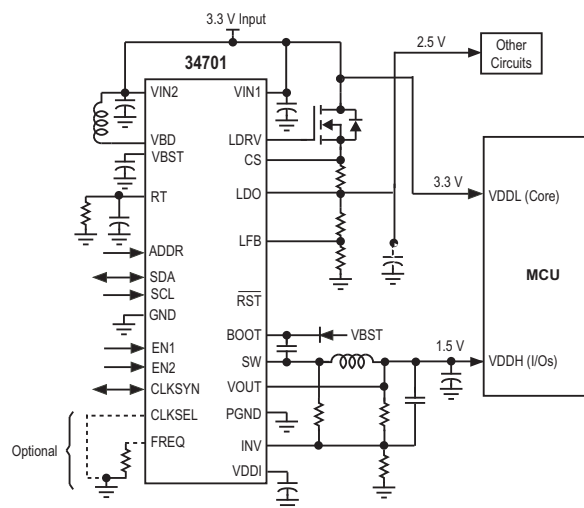


Figure 17. Standard Power-up/Down Sequence in +3.3V Supply System

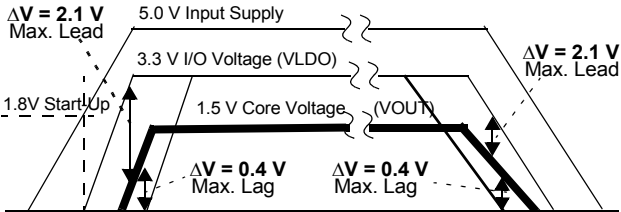
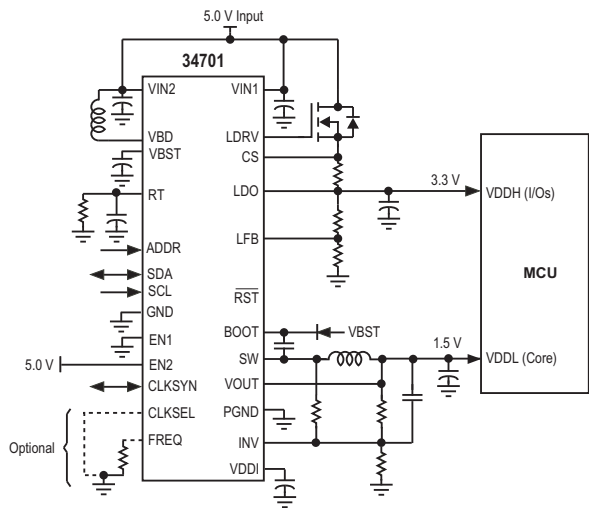


Figure 18. Standard Power-up/Down Sequence in +5.0V Supply System

STANDARD POWER SEQUENCING

When the power supply IC operates in the Standard Power Sequencing Mode, the switcher output provides the core voltage for the microprocessor. This situation and operating conditions are illustrated in Figures 17 and 18. Table 5, page 17, shows the Power Sequencing Mode selection.

INVERTED POWER SEQUENCING

When the power supply IC is operating in the Inverted Power Sequencing Mode, the linear regulator (LDO) output provides the core voltage for the microprocessor, as illustrated in Figure 19. Table 5 shows the Power Sequencing Mode selection.

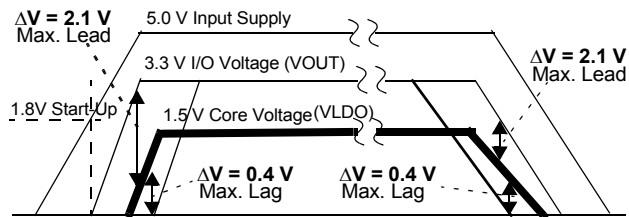
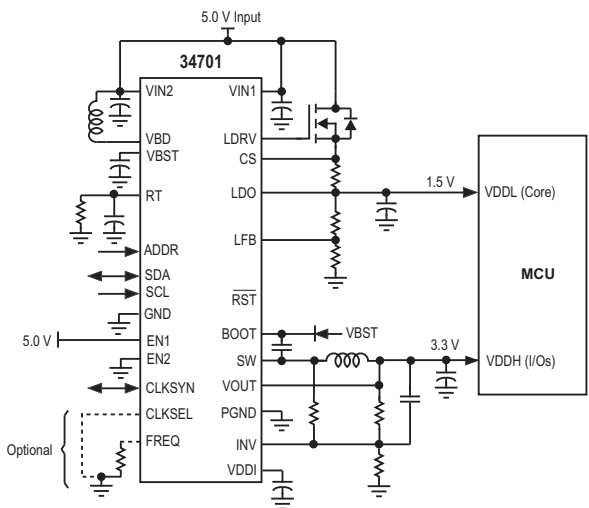


Figure 19. Inverted Power-up/Down Sequence in +5.0V Supply System

ASSUMED REQUIREMENTS

1. I/O supply voltage not to exceed core voltage by more than 2.0V.
2. Core supply voltage not to exceed I/O voltage by more than 0.4V.

Methods of Control

The 34701 has several methods of monitoring and controlling the regulator output voltages, as described in the paragraphs below. Power sequencing control is also achieved through the intrinsic operation of the regulators. The EN1 and EN2 pins can be used to select the proper Power Sequencing Mode required by the powered system or to disable the power sequencing (refer to Table 5).

Intrinsic Operation

For both the LDO and switcher, whenever the output voltage is below the regulation point, the LDO external Pass MOSFET is on, or the buck high side MOSFET is on at a duty cycle controlled by the switcher. Because these devices are MOSFETs, current can flow in either direction, balancing the voltages via the common supply pin. The ability to maintain the MOSFETs on is dependent on the available gate voltage, and thus the size of the boost regulator storage capacitor.

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Standard Power Sequencing Control

Comparators monitor voltage differences between the LDO (LDO pin) and the switcher (VOUT pin) outputs as follows:

1. $LDO > VOUT + 1.9V$, *turn off LDO*. The LDO can be forced off. This occurs whenever the LDO output voltage exceeds the switcher output voltage by more than 1.9V.
2. $LDO > VOUT + 2.0V$, *shunt LDO to ground*. If turning off the LDO is insufficient and the LDO output voltage exceeds the switcher output voltage by more than 2.0V, a 1.5Ω shunt MOSFET is turned on that discharges the LDO load capacitor to ground. The shunt MOSFET is used for switcher output shorts to ground and for power down in case of $VIN1 \neq VIN2$ with the switcher output falling faster than the LDO.
3. $LDO < VOUT + 1.9V$ cancel (2).
4. $LDO < VOUT + 1.8V$, *cancel (1) above, re-enable LDO*. Normal operation resumes when the LDO output voltage is less than 1.8V above the switcher output voltage.
5. $LDO < VOUT - 0.1V$, *turn off switcher*. The switcher can be forced off. This occurs whenever the LDO is less than $VOUT - 0.1V$.
6. $LDO < VOUT - 0.3V$, *turn on Sync (LS) MOSFET and 1.5Ω VOUT sink MOSFET*. The buck high side MOSFET is forced off and the sync MOSFET is forced on. This occurs when the switcher output voltage exceeds the LDO output by more than 300mV.
7. $LDO > VOUT - 0.3V$, *cancel (6)*.
8. $LDO > VOUT - 0.1V$, *cancel (5)*. Normal operation resumes when $LDO < VOUT - 0.1V$.

Inverted Power Sequencing Control

Comparators monitor voltage differences between the switcher (VOUT pin) and LDO (LDO pin) outputs as follows:

1. $VOUT > LDO + 1.8V$, *turn off VOUT*. The switcher VOUT can be forced off. This occurs whenever the VOUT output voltage exceeds the LDO output voltage by more than 1.8V.
2. $VOUT > LDO + 2.0V$, *shunt VOUT to ground*. If turning off the switcher VOUT is insufficient and the VOUT output voltage exceeds the LDO output voltage by more than 2.0V, a 1.5Ω shunt MOSFET and the switcher synchronous MOSFET are turned on to discharge the VOUT load capacitor to ground. The shunt MOSFET and synchronous MOSFET are used for LDO output shorts to ground and for power down in case of $VIN1 \neq VIN2$ with LDO output falling faster than the VOUT.
3. $VOUT < LDO + 1.8V$, *cancel (1) and (2) above, re-enable VOUT*. Normal operation resumes when the

VOUT output voltage is less than 1.8V above the LDO output voltage.

4. $VOUT < LDO + 2.0V$, *cancel (2)*
5. $VOUT < LDO - 0.2V$, *turn off LDO*. The LDO can be forced off. This occurs whenever the VOUT is less than $VLDO - 0.2V$.
6. $VOUT < LDO - 0.3V$, *turn on the 1.5Ω LDO sink MOSFET*. This occurs when the LDO output voltage exceeds the VOUT output by more than 300mV.
7. $VOUT < LDO - 0.2V$, *cancel (6)*.
8. $VOUT < LDO - 0.1V$, *cancel (5)*. Normal operation resumes when $VOUT > LDO - 0.1V$.

STANDARD OPERATING MODE

Single 3.3V Supply, $VIN = VIN1 = VIN2 = 3.3V$

The 3.3V supplies the microprocessor I/O voltage, the switcher supplies core voltage (e.g., 1.5V nominal), and the LDO operates independently (see [Figure 17](#), page 22). Power sequencing depends only on the normal switcher intrinsic operation to control the buck high side MOSFET.

Power-up

When VIN is rising, initially VOUT is below the regulation point and the Buck High-Side MOSFET is on. In order not to exceed the 2.1 V differential requirement between the I/O (VIN) and the core (VOUT), the switcher must start up at 2.1 V or less and be able to maintain the 2.1 V or less differential. The maximum slew rate for VIN is 1.0 V/ms.

Power-Down

When VIN is falling, VOUT falls below the regulation point; therefore, the buck high side MOSFET is on. In the case where VOUT is falling faster than VIN , the buck high side MOSFET attempts to maintain VOUT. In the case where VIN is falling faster than VOUT, the buck high side MOSFET is also on, and the VOUT load capacitor is discharged through the buck high side MOSFET to VIN . Thus, provided VIN does not fall too fast, the core voltage (VOUT) does not exceed the I/O voltage (VIN) by more than a maximum of 0.4V.

Shorted Load

1. *VOUT shorted to ground*. This causes the I/O voltage to exceed the core voltage by more than 2.1V. No load protection.
2. *VIN shorted to ground*. Until the switcher load capacitance is discharged, the core voltage exceeds the I/O voltage by more than 0.4V. By the intrinsic operation of the switcher, the load capacitor is discharged rapidly through the buck high side MOSFET to VIN .
3. *VOUT shorted to supply*. No load protection. 34701 is protected by current limit and thermal shutdown.

Single 5.0V Supply, VIN1 = VIN2, or Dual Supply VIN1 ≠ VIN2

The LDO supplies the microprocessor I/O voltage. The switcher supplies the core (e.g., 1.5V nominal) (see [Figure 18](#), page 23).

Power-up

This condition depends upon the regulator current limit, load current and capacitance, and the relative rise times of the VIN1 and VIN2 supplies. There are two cases:

1. *LDO rises faster than VOUT*. The LDO uses control methods (1) and (2) described in the section [Methods of Control on page 23](#).
2. *VOUT rises faster than LDO*. The switcher uses control methods (5) and (6) described in the section [Methods of Control on page 23](#).

Power-down

This condition depends upon the regulator load current and capacitance and the relative fall times of the VIN1 and VIN2 supplies. There are two cases:

1. *VOUT falls faster than LDO*. The LDO uses control methods (1) and (2) described in the section [Methods of Control on page 23](#).
In the case VIN1 = VIN2, the intrinsic operation turns on both the buck high side MOSFET and the LDO external Pass MOSFET, and discharges the LDO load capacitor into the VIN supply.
2. *LDO falls faster than VOUT*. The switcher uses control methods (5) and (6) described in the section [Methods of Control on page 23](#).

Shorted Load

1. *VOUT shorted to ground*. The LDO uses method (1) and (2) described in the section [Methods of Control on page 23](#).
2. *LDO shorted to ground*. The switcher uses control methods (5) and (6) described in the section [Methods of Control on page 23](#).
3. *VIN1 shorted to ground*. Device is not working.
4. *VIN2 shorted to ground with VIN1 and VIN2 different*. This is equivalent to the switcher output shorted to ground.
5. *VOUT shorted to supply*. No load protection. 34701 is protected by current limit and thermal shutdown.
6. *LDO shorted to supply*. No load protection. 34701 is protected by current limit and thermal shutdown.

INVERTED OPERATING MODE

Single 3.3V Supply, VIN = VIN1 = VIN2 = 3.3V

The 3.3V supplies the microprocessor I/O voltage, the LDO supplies core voltage (e.g., 1.5V nominal), and the switcher VOUT operates independently. Power sequencing

depends only on the normal LDO intrinsic operation to control the Pass MOSFET.

Power-up

When VIN is rising, initially LDO is below the regulation point and the Pass MOSFET is on. In order not to exceed the 2.1V differential requirement between the I/O (VIN) and the core (LDO), the LDO must start up at 2.1V or less and be able to maintain the 2.1V or less differential. The maximum slew rate for VIN is 1.0V/ms.

Power-down

When VIN is falling, LDO falls below the regulation point; therefore, the Pass MOSFET is on. In the case where LDO is falling faster than VIN, the pass MOSFET attempts to maintain LDO. In the case where VIN is falling faster than LDO, the pass MOSFET is also on, and the LDO load capacitor is discharged through the pass MOSFET to VIN. Thus, provided VIN does not fall too fast, the core voltage (LDO) does not exceed the I/O voltage (VIN) by more than maximum of 0.4V.

Shorted Load

1. *LDO shorted to ground*. This will cause the I/O voltage to exceed the core voltage by more than 2.1V. No load protection.
2. *VIN shorted to ground*. Until the LDO load capacitance is discharged, the core voltage exceeds the I/O voltage by more than 0.4V. By the intrinsic operation of the LDO, the load capacitor is discharged rapidly through the Pass MOSFET to VIN.
3. *LDO shorted to supply*. No load protection.

Single 5.0V Supply, VIN1 = VIN2, or Dual Supply VIN1 ≠ VIN2

The switcher VOUT supplies the microprocessor I/O voltage. The LDO supplies the core (e.g., 1.5V nominal) (see [Figure 19](#), page 23).

Power-up

This condition depends upon the regulator current limit, load current and capacitance, and the relative rise times of the VIN1 and VIN2 supplies. There are two cases:

1. *VOUT rises faster than LDO*. The switcher VOUT uses control methods (1) and (2) described in the section [Methods of Control on page 23](#).
2. *LDO rises faster than VOUT*. The LDO uses control methods (5) and (6) described in the section [Methods of Control on page 23](#).

Power-down

This condition depends upon the regulator load current and capacitance and the relative fall times of the VIN1 and VIN2 supplies. There are two cases: