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Ready^m for PIC[®]

Best solution for fast and simple development of applications using 28-pin PIC MCUs. Due to the special white plastic casing the Ready for PIC^{*} board can be quickly turned into a final product.



DIP28



TO OUR VALUED CUSTOMERS

I want to express my thanks to you for being interested in our products and for having confidence in MikroElektronika.

The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.

Nebojsa Matic General Manager

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Introduction

Ready for PIC® Board is the best solution for fast and simple development of various microcontroller applications. The board is equipped with the PIC18F25K22 MCU that is placed in DIP 28 socket and contains male headers and connection pads for all available microcontroller ports. The pins are grouped according to their functions, which is clearly indicated on the silkscreen. The MCU comes pre programmed with mikroBootloader, but it can also be programmed with mikroProg[™] programmer. The board also contains USB-UART module. prototyping area and a power supply circuit. It is specially designed to fit into the special white plastic casing so that you can turn your PIC project into a final product.



Package Contains



Key Features

System Specification



power supply

Via AC/DC connector 7-23V AC or 9-32V DC



power consumption

7mA in idle state (when on-board modules are off)

_	- 1	
	- 2	
5		_

board dimensions

141 x 84mm (5.55 x 3.3 inch)



weight

~60g (0.13 lbs)

Power LED indicator UART communication LEDs (RX.TX) FTDI chip USB UART connector Power supply select Power adapter connector Power screw terminals Male headers Reset button mikroProg[™] connector PIC18F25K22 microcontroller

01

02

03

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- Crystal oscillator
- Connection pads
- Prototyping area



1. Power supply



Ready for PIC* board can be powered in three different ways: via USB connector (CN1), via adapter connector using external adapters (CN2) or via additional screw terminals (CN46). The USB connection can provide up to 500mA of current which is more than enough for the operation of every on-board module and the microcontroller as well. If you decide to use external power supply, voltage values must be within 7-23V AC or 9-32V DC range. Power LED ON (GREEN) indicates the presence of power supply. Use only one of suggested methods for powering the board. If you use MCU with a 5V power supply place jumper J1 in the 5V position. Otherwise, it should be placed in the 3.3V position.



Figure 1-4: Power supply schematic

2. Programming with mikroBootloader

You can program the microcontroller with bootloader which is pre programmed by default. To transfer .hex file from a PC to the MCU you need a bootloader software (**mikroBootloader**) which can be downloaded from:



http://www.mikroe.com/eng/downloads/get/1808/ ready_pic_mikrobootloader.zip

After the mikroBootloader software is downloaded, unrar it to a desired location, and start it.



mikroBootloader software

note	Before starting mikroBootloader software, connect Ready for
	PIC® to a PC using a USB cable provided with the package

1 Setup port Baud F	ort: COM1 late: 9600	Change Settings	Signals	Conn	Rx @	T:
2 Connect to MCU	Connect	History Wind	0W			
3 Choose HEX file	Browse for HEX					
4 Start bootloader	Begin uploading					2

Figure 2-1: mikroBootloader window



When you start mikroBootloader software, a window as shown in **Figure 2-1** should appear

Identifying device COM port

Device Manager	
File Action View Help	
(= -) 🖬 📓 🖬 📾 🖄 👘 🖏	
b 🕼 Human Interface Devices	
IDE ATA/ATAPI controllers	
>	
Mice and other pointing devices	
Monitors	
Network adapters	
>- D Other devices	
Ports (COM & LPT)	
Communications Port (COM1)	
Printer Port (LPT1)	
USB Serial Port (COM3)	
Processors	
5 📲 Sound, video and game controllers	
System devices	
👂 - 🏺 Universal Serial Bus controllers	

Figure 2-2: Identifying COM port

Open Device Manager window and expand Ports section to see which COM port is assigned to Ready for PIC* board (in this case it is COM3)

step 1 - Choosing COM port



Figure 2-3: Choosing COM port



- Click the Change Settings button
- Prom the drop down list, select appropriate COM port (in this case it is COM3)
- 03 Click OK

step 2 - Establishing Connection

1 Setup COM P port Baud F	ort: COM3 late: 115200	Change Settings	Signals	Conn	Rx @	Tx @
2 Connect to MCU	Connect •	LO1 ry Wind	low L			*
3 Choose HEX file	Browse for HEX					
4 Start bootloader	Begin uploading					÷

Figure 2-4: Connecting with mikroBootloader

Press the Reset button on Ready for PIC* board and click the Connect button within 5s, otherwise the existing microcontroller program will run. If connected, the button's caption will be changed to Disconnect

step 3 - Browsing for .HEX file



Figure 2-5: Browse for HEX

Click the Browse for HEX button and from a pop-up window (Figure 2-6) choose a .HEX file to be uploaded to MCU memory

step 4 - Selecting .HEX file



Figure 2-6: Locating and selecting .hex file



Select .HEX file using open dialog window.

O2 Click the **Open** button

step 5 - Uploading .HEX file

1 Setup COM Po port Baud R	ort: COM3 ate: 115200	Change Settings	slanals Coun	Rx T
7 Connect	Disconnect	History Windov	v	
3 Choose HEX file	Browse for HEX	Waiting MCU respons Connected. Opened: F:\LED Blink	ie, ing\LedBlinkir	ng.hex
4 Start bootloader	Begin uploading	01		

Figure 2-7: Begin uploading



step 6 - Progress bar



Figure 2-8: Progress bar



step 7 - Finishing upload



Figure 2-9: Restarting MCU



Click **OK** button after the uploading process is finished

(02) Press Reset button on Ready for PIC[®] board and wait for 5 seconds. Your program will run automatically

3. Programming with mikroProg^m programmer

The board is equipped with **mikroProg**[™] **connector pads**, which allow you to program the microcontroller using external mikroProg[™] programmer. Before attaching the programming connector, it is necessary to make a few adjustments (**Page 16**).

> Figure 3-1: mikroProg[™] programmer



First you need to cut copper between pads for the external programmer, **Figure 3-2**. By doing so pins RB6, RB7, MCLR and VCC on MCU will be separated from the rest of the board. After that it is time to place (**Figure 3-3**) and solder (**Figure 3-4**) a 2x5 male header on the pad **(CN5)**. Now ti is time to place the external mikroProg[™] programmer connector on the 2x5 male header, **Figure 3-5**. After the programming process is finished you can remove programmer connector and solder jumpers over pads in order to enable pins RB6, RB7 to be used as I/O pins and MCLR to be used as reset pin.



Figure 3-6: mikroProg[™] programmer connection schematic

4. USB-UART

Fast on-board **FTDI® chip** allows you to communicate with a PC or other UART devices using USB-UART connection. USB-B connector (**CN1**) is used for connecting the USB cable. RX (receive) and TX (transmit) LEDs will indicate communication status. Before connecting the board to a PC, make sure that you have the appropriate **FTDI drivers** installed on your operating system. Drivers can be found at the following URL:

Figure 4-1: connected USB-UART







6. Pin headers and connection pads



Each microcontroller pin is available for further connections through four on-board 2x5 connection headers and two 1x28 connection pads. Pins are grouped in four PORT groups (2x5 male headers) as well as per their functions (1x28 connection pads), which makes development and connections much easier. Everything is printed on the silkscreen, so that there will be no need of using microcontroller data sheet while developing. Before using the pins, it is necessary to solder **2x5 male headers** (1-4) on the board pads.



Figure 6-1: schematic of pin headers and connection pads

7. Reset button



Ready for PIC^{*} board has a specialized reset circuit with high-quality reset button which can be used to reset the program execution of the microcontroller. If you want to reset the circuit, press on-board RESET button. It will generate low voltage level on the microcontroller reset pin (input). In addition, a reset can be externally generated through **MCLR pin** on 1x28 connection pads.

8. Integrating with the casing



Figure 8-1: Place the board into the bottom part of the casing. Make sure that connectors are aligned with square openings



Figure 8-2: Wind screws into inner screw holes to fix the board with the bottom plastic casing



Figure 8-3: Place plastic casing cover and wind screws into outer screw holes to fix it with bottom plastics casing

Ready for PIC[®] can easily be integrated into the specialized white plastic casing. This feature is very convenient for turning the board into a final product. The white plastic casing contains inner and outer screw holes. Inner are used for fixing the board to the casing and outer are used for fixing the top part of the casing. Casing comes with holes for USB and power adapter connector, but you can customize it by drilling and cutting holes in specific areas, depending on the target application.



