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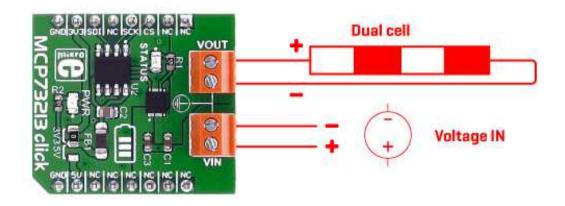
MCP73213 click

PID: MIKROE-2575



MCP73213 click carries the MCP73213 dual-cell Li-Ion/Li-Polymer battery charge management controller with input overvoltage protection from Microchip. The click is designed to run on either 3.3V or 5V power supply. It communicates with the target microcontroller over SPI.

Note: The click is designed to charge a dual-cell Li-lon/Li-Polymer battery. The input voltage needs to be higher that the voltage of a dual-cell Li-lon/Li-Polymer battery.



MCP73213 controller features

The MCP73213 is a highly integrated Li-Ion battery charge management controller.

The MCP73213 provides specific charge algorithms for dual-cell Li-Ion/Li-Polymer batteries to achieve optimal capacity and safety in the shortest charging time possible.

The absolute maximum voltage, up to 18V, allows the use of MCP73213 in harsh environments, such as low-cost wall wart or voltage spikes from plug/unplug.

An internal **overvoltage protection** (OVP) circuit monitors the input voltage and keeps the charger in shutdown mode when the input supply rises above the typical 13V OVP threshold. The OVP hysteresis is approximately 150 mV for the MCP73213 device.

How it works

First you need to connect the input voltage to the input screw terminal. Then to set the input voltage, because it needs to be larger than voltage of two series connected batteries for regular charging, (which means it needs to be >8V). We can change the charging current trough SPI interface.

Now just leave the batteries to charge, and when they are charged it will be signalized on the status LED.

Key features

- MCP73213 controller
 - o 13V Input Overvoltage Protection
 - o Resistor Programmable Fast Charge Current: 130 mA-1100 mA
 - o Elapse Safety Timer: 4 hr, 6 hr, 8 hr or Disable
- Two pairs of screw terminals
- Status indication LED
- SPI interface
- 3.3V or 5V power supply

Specification

Product Type	Buck
Applications	Portable Media players, digital camcorders, handheld devices, etc.
MCU	MCP73213
	13V Input Overvoltage Protection, Resistor Programmable Fast Charge Current: 130 mA-1100 mA, Elapse Safety Timer: 4 hr, 6 hr, 8 hr or Disable
Interface	SPI
Power Supply	3.3V or 5V

Compatibility	mikroBUS
Click board size	S (28.6 x 25.4 mm)

Pinout diagram

This table shows how the pinout on MCP73213 click corresponds to the pinout on the mikroBUSTM socket (the latter shown in the two middle columns).

Notes	Pin	mikroBUS tm				Pin	Notes	
Not connected	NC	1	AN	PWM	16	NC	Not connected	
Not connected	NC	2	RST	INT	15	NC	Not connected	
Chip Select	SPI_CS	3	CS	TX	14	NC	Not connected	
SPI Clock	SPI_SCK	4	SCK	RX	13	NC	Not connected	
Not connected	NC	5	MISO	SCL	12	NC	Not connected	
SPI Master output svale input	SPI_MOSI	6	MOSI	SDA	11	NC	Not connected	
Power supply	+3.3V	7	3.3V	5V	10	+5V	Power supply	
Ground	GND	8	GND	GND	9	GND	Ground	

Maximum ratings

Description	Min	Тур	Max	Unit
Input Voltage Range	4		16	V
Operating Supply Voltage	4.2		13	V
Fast Change Current Regulation	130		1100	А

Programming

Code examples for MCP73213 click, written for MikroElektronika hardware and compilers are available on <u>Libstock</u>.

Code snippet

The following code snippet shows how to initialize the SPI interface, and then use it to set output current to 250mA.

```
01 void main() {
02
        /*Sets chip select*/
03
        GPIO_Digital_Output (&GPIOD_BASE, _GPIO_PINMASK_13);
04
05
        GPIO_Alternate_Function_Enable(&_GPIO_MODULE_SPI3_PC10_11_12);
06
07
        /*Initializes SPI interface*/
        SPI3_Init_Advanced(_SPI_FPCLK_DIV256, _SPI_MASTER | _SPI_16_BIT |
80
          SPI CLK IDLE LOW | SPI FIRST CLK EDGE TRANSITION | SPI MSB FIRST
09
10
          _SPI_SS_DISABLE | _SPI_SSM_ENABLE | _SPI_SSI_1,
11
          &_GPIO_MODULE_SPI3_PC10_11_12);
12
13
        SPI_Set_Active(SPI3_Read, SPI3_Write);
14
        /*Sets chip select to inactive*/
15
        GPIOD\_ODR.B13 = 1;
16
17
        delay_ms(5000);
18
19
20
21
        //5 kOhm, 250mA
22
        GPIOD\_ODR.B13 = 0;
        Spi3_Write(0b00000000);
23
24
        Spi3_Write(0b10000010);
        GPIOD\_ODR.B13 = 1;
25
        delay_ms(5000);
26
27 }
```