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## SmartGLCD 240x128







### TO OUR VALUED CUSTOMERS

I want to express my thanks to you for being interested in our products and for having confidence in MikroElektronika.

The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.

Nebojsa Matic General Manager

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### What is the SmartGLCD 240x128?

The SmartGLCD 240x128 is a compact smart display, with many on-board peripherals. It's designed to become a control interface of your device. Main part of the board is a large 240x128 pixel graphical LCD with a 4-wire resistive touch screen. It features RGB backlight, which can greatly improve user experience, but can also be used as a signaling feature. The heart of the board is PIC18F87K22, an 8-bit microcontroller delivering 12MIPS of processing power. Other modules like USB UART, piezo buzzer, microSD slot and connection pads can be found on board as well. The board is preprogrammed with UART bootloader. We have also provided a nice example which will give you a great out-of-thebox experience.





### Package Contains



## 1. Key Features

01 GLCD 240x128 display

#### 02 RESET button



- Power supply pads
- 04 I/O pads
- 05 Pads for mikroProg programmer
- 06 USB connector



- Touch panel connector
- 08 PIC18F87K22 microcontroler
- 9 Contrast potentiometer
- 10 microSD card slot



12 Buzzer





## 2. Power supply

The SmartGLCD board can be powered in two different ways: via USB connector **(CN1)** using MINI-B USB cable provided with the board **(Figure 2-1)**, or via side headers **(CN2** or **CN4)** using external 5V power supply (**Figure 2-2** and **Figure 2-3**).



When the board is powered up the GLCD display will be automatically turned on. The USB connection can provide up to 500mA of current which is more than enough for the operation of all on-board modules and the microcontroller as well.



Figure 2-4: Power supply schematic

### 3. PIC18F87K22 microcontroller

The SmartGLCD development tool comes with the **PIC18F87K22** microcontroller. This 8-bit microcontroller is rich with on-chip peripherals and features 128KB of Flash and 4KB of RAM. It can easily handle demanding graphical applications.

#### **Key microcontroller features**

- Up to 12 MIPS Operation;
- 8-bit architecture;
- 128KB of Flash memory;
- 3,862 bytes of RAM;
- 1024 bytes of EEPROM;
- 80 pin TQFP;
- 24 ch, 12-bit ADC;
- UART, SPI, I<sup>2</sup>C; etc.



### 4. Programming the microcontroller



Figure 4-1: PIC18F87K22 microcontroller

The microcontroller can be programmed in two ways:



Using USB UART mikroBootloader

Using external mikroProg<sup>™</sup> for PIC, dsPIC, PIC32 programmer

### 5. Programming with bootloader

Microcontroller is preprogrammed with USB UART Bootloader, which can be used to upload new device firmware. To transfer firmware .HEX file from a PC to MCU you need to use mikro-Bootloader USB UART application, which can be downloaded from:



Upon download, unzip it to desired location and start the mikroBootloader application:



#### mikroBootloader software

	-	
1		 

Before starting mikroBootloader software, connect SmartGLCD to a PC using a USB cable provided with the package.



#### Figure 5-1: mikroBootloader window



When you start mikroBootloader software a window should appear, as shown in the image above.

### Identifying device COM port

### step 1 - Choosing COM port



Figure 5-2: Identifying COM port



MIKLORO	ottoade	Select MU	U PICI	8
1 Setur COM P Daud F	Cont: COM1 Rete: 19200	Change Setting	Conn	Rx T
2 Consect	Connect	Settings	СОМ 18	02
3 thoose HEX file	Browse for HEX	Baud rate Data bits	115200 8	•
4 Start	Regin uploading	Stop bits Pantu	1 None	•
Bootloading		Flow control	Software	•

Figure 5-3: Choosing COM port



Click the **Change Settings** button.

From the drop down list, select appropriate **Port** (in this case it is COM18) and **Baud rate** (115200).

B Click OK.

### step 2 - Establishing Connection

<b>MIKLOROOTIO</b>	ader	Select MCU		PIC	18	•
<b>1</b> Setup COM Port: <b>CO</b> port Baud Rate: <b>11</b>	M18 C 5200 S	hange ettings	Signals	Conn	Rx @	Tx @
2 Connect Connect	ect • - 01	story Windo	ow a.			~
3 Choose Brow HEX file for Hi	se EX					
4 Start Begi bootloader upload	n ling					÷
Bootloading				l s	how A	ctivity

Figure 5-4: Connecting with mikroBootloader



### step 3 - Browsing for .HEX file

1 Setup COM port Bau	I Port: COM18 d Rate: 115200	Change Settings	Signals	Conn	Rx O	Tx @
2 Connect to MCU 3 Choose HEX file	Disconnect Browse for HEX	History Win Setup: Port CO Setup: Port CO Waiting MCU re Onnected.	ndow M1. M18. sponse			
4 Start bootloader	Begin uploading					

Figure 5-5: Browse for HEX



Click the **Browse for HEX** button and from a pop-up window (Figure 5-6) choose a .HEX file to be uploaded in MCU memory.

#### step 4 - Selecting .hex file

Organize 👻 New fol	der			H • 🛄 🔞
* Favorites	Name	Date modified	Туре	Size
E Desktop	SmartGLCD.hex	28.3.2013 16:20	HEX File	16 KE
🔛 Recent Places	01			
<ul> <li>Libraries</li> <li>Documents</li> <li>Music</li> <li>Pictures</li> <li>Videos</li> </ul>		,		
<ul> <li>Libraries</li> <li>Documents</li> <li>Music</li> <li>Pictures</li> <li>Videos</li> <li>Homegroup</li> </ul>	, u	,		
Libraries Documents Music Pictures Videos Homegroup Computer	Ţ			
Libraries  Libraries  Documents  Music  Pictures Videos  Homegroup  Computer  Local Disk (C:)				

Figure 5-6: Locating and selecting .hex file



Select .HEX file from the **Open dialog** window.

Click the **Open** button.

#### step 5 - Uploading .hex file

<b>1</b> Setup COM Port: COM18 Baud Rate: 115200	Change Settings V Conn Rx T
Connect	History Window
3 Choose Browse for HEX	Setup: Port COM10. Wailing MCU response Connected. Opened: C: 'Project' SmartGLCD.hex
4 Start Begin uploading	-01

Figure 5-7: Begin uploading



In order to upload .HEX file click the **Begin** uploading button.

### step 6 - Progress bar

mikroBootloade	Select MCU PIC18	•
1 Setup COM Port: COM18 Baud Rate: 115200	Change Settings	×
<b>Connect</b>	History Window	
3 Choose Browse for HEX file For HEX	Setup: Port COM1. Setup: Port COM10. Walling MCU response Connected. Opened: C:\Project\SmartGLCD.hex Uploading	*
4 Start Stop uploading		Ŧ
Bootloading progress bar	Show Activ	ity

#### Figure 5-8: Progress bar



Progress bar enables you to monitor .HEX file uploading.

### step 7 - Finishing upload

Setup	Success		
2 Connec to MCU	Reset MCU. Uploading program	n has finished.	0
3 Choose HEX file	Show details		ОК
4 Start bootload	Begin ( er uploading	Completed successfully.	

#### Figure 5-9: Restarting MCU

finished.

OI Click **OK** button after the uploading process has been

02 Press Reset button on SmartGLCD board and wait for 5 seconds. Your program will run automatically.

### Tips and Tricks: Speed-up UART data transfer

🚔 Device Manager	USB Serial Port (COM18) Properties	Advanced Settings for COM18
Device Manager         File       Action         View Help         Monitors         Monitors         Network adapters         Other devices         Ports (COM & LPT)         Communications Port (COMI)         Printer Port (LPT1)         Public Driver Software         S         Disable         S         Uninstall	USS Serial Port (COM18) Properties	Advanced Settings for COM18  COM gort Number: COM18  USB Transfer Sizes Select lower settings to correct performance, Receive (bytes): 9096 Transmit (bytes): 9096 BM Options BM Options BM Options Latency Timer (msec): EM Conceller Set 20 BM Options Set 20 BM Options Conceller Set 2
Construction of the second secon	OK Cancel	Minimum Reed Timeout (insec):

**note** If .HEX file transfer from your PC to MCU is too slow, it's possible to speed up data transfer by setting latency time of COM port to 1 ms. This is done in Device Manager:

- 01 02 04
  - Right click on the USB Serial Port (COM18) item and then select Properties.
  - Select Port Settings tab.
  - Click the **Advanced...** button.
  - Set Latency Timer to 1 and click OK.

## 6. Programming with mikroProg<sup>™</sup> programmer

The microcontroller can be programmed with the external **mikroProg**<sup>™</sup> programmer which can be connected to the board via **CN3** connector. Before establishing this connection it is necessary to solder 1x5 male header to **CN3** connection pads. This can be done in both ways: on the bottom, or the top side, as shown in **Figures 6-1** and **6-2**.





**note** If bootloader program is accidently erased you can upload it again through mikroProg programmer. Program Bootloader18F87K22.hex can be found under Firmware folder (page 12).



Figure 6-3: mikroProg<sup>™</sup> connection schematic



Make sure to use only the front row of mikroProg's IDC10 connector (side with a knob and incision) when connecting it to 1x5 header on your SmartGLCD board.



### 7. mikroProg Suite<sup>™</sup> for PIC<sup>®</sup> Software



The **mikroProg**<sup>TD</sup> programmer requires special programming software called mikroProg Suite<sup>TT</sup> for PIC<sup>®</sup>. It can be used for programming all Microchip® microcontroller families, including PIC10<sup>®</sup>, PIC12°, PIC16°, PIC18°, dsPIC30/33°, PIC24<sup>®</sup> and PIC32<sup>®</sup>. The software has intuitive interface and SingleClick<sup>™</sup> programming technology. Just download the latest version of mikroProg Suite<sup>T</sup> and your programmer is ready to program new devices. mikroProg **Suite**<sup>Th</sup> is updated regularly, at least four times a year, so your programmer will be more and more powerful with each new release



Figure 7-1: Main window of mikroProg Suite<sup>™</sup> for PIC<sup>®</sup> programming software

#### Software Installation Wizard







Tr mikroProg Suite for PIC x2.29 Setup Installing Please wait while mikroProp Suite for PSC v2 29 is being installed Create folder: C: ProgramCata Wicrosoft Windows Start Menu Programs Wikroelektronika ink Show details < link next > Canor

#### Installation in progress









Finish installation





### 8. microSD Card Slot

Figure 8-1: microSD card slot

There is a built-in microSD card slot provided on-board. It enables the expansion of available memory space using microSD cards. Communication between the microcontroller and the card is done through Serial Peripheral Interface (**SPI**).



#### Figure 8-2: microSD Card Slot module connection schematic

### 9. Touch Screen



The development system features a **Graphical LCD in 240x128 pixel resolution**. Display is covered with a **4-wire resistive** touch panel. Together they form a functional unit called a touch screen, **Figure 9-1**. It enables data to be entered and displayed at the same time.

Figure 9-1: Touch Screen



Figure 9-2: Touch Screen connection schematic