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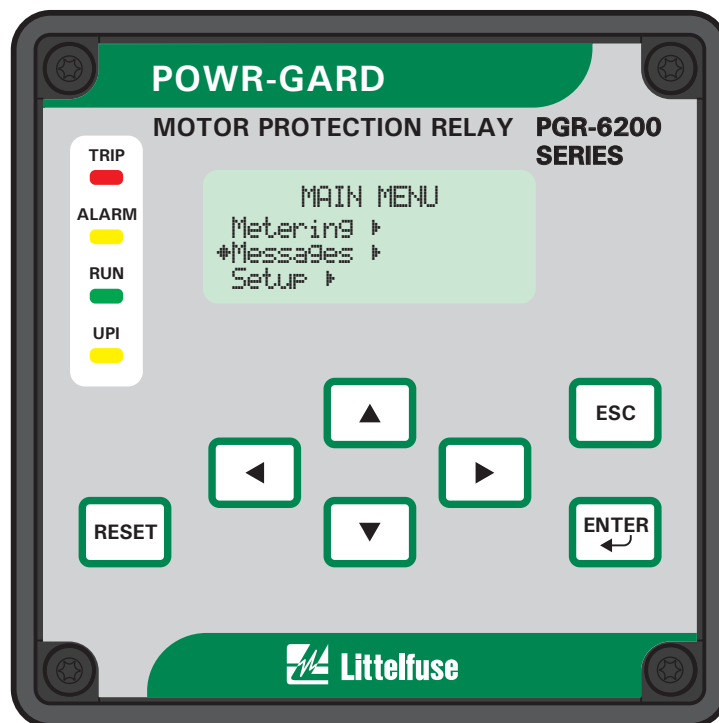
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**PGR-6200 MANUAL**  
**MOTOR PROTECTION RELAY**

June 1, 2009

Revision 2



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Factory default password is 1111

New Password  
See Section 4.5

Motor Identification

**TABLE OF CONTENTS**

	<i>Page</i>		<i>Page</i>
Table of Contents.....	i	4.2 Setup .....	4-2
List of Figures.....	ii	4.2.1 Phase-CT Inputs.....	4-2
List of Tables.....	ii	4.2.2 Earth-Fault-CT Input.....	4-2
<b>1. INTRODUCTION.....</b>	<b>1-1</b>	4.2.3 Motor Data .....	4-2
1.1 General .....	1-1	4.2.4 Output Relay Assignment .....	4-3
1.2 PGR-6200 Features .....	1-1	4.2.5 Digital Input .....	4-3
1.2.1 Protection .....	1-1	4.2.6 Analog Output.....	4-4
1.2.2 Metering.....	1-1	4.2.7 Miscellaneous Configuration.....	4-4
1.2.3 Data Logging.....	1-1	4.2.8 Communications.....	4-4
1.2.4 Inputs and Outputs.....	1-1	4.3 Metering.....	4-5
1.2.5 Operator Interface.....	1-1	4.4 Messages .....	4-5
1.2.6 PGA-0120 Temperature Input Module (Optional) .....	1-1	4.4.1 Trip Reset.....	4-5
1.2.7 PGA-0140 Differential Current Module (Optional).....	1-1	4.4.2 Data Logging.....	4-5
1.2.8 Communications .....	1-1	4.4.3 Statistical Data .....	4-6
1.3 Ordering Information .....	1-1	4.4.4 Emergency Thermal Reset .....	4-6
<b>2. INSTALLATION.....</b>	<b>2-1</b>	4.5 Password Entry and Programming .....	4-6
2.1 General .....	2-1	4.6 PGA-0120.....	4-7
2.2 PGR-6200 Motor Protection Relay.....	2-1	4.7 PGA-0140.....	4-7
2.3 PGA-0CIM Current Input Module .....	2-1	<b>5. PROTECTIVE FUNCTIONS.....</b>	<b>5-1</b>
2.4 Sensitive Earth-Fault CT's .....	2-1	5.1 General .....	5-1
2.5 PGA-0120 Temperature Input Module.....	2-1	5.2 Overload.....	5-1
2.6 PGA-0140 Differential Current Module .....	2-1	5.2.1 Thermal Model .....	5-1
<b>3. SYSTEM WIRING.....</b>	<b>3-1</b>	5.2.2 Locked-Rotor Times.....	5-4
3.1 General .....	3-1	5.2.3 Emergency Thermal Reset .....	5-4
3.2 Wiring Connections .....	3-2	5.3 Overcurrent .....	5-4
3.2.1 PGR-6200 Connections .....	3-2	5.4 Auxiliary Overcurrent.....	5-5
3.2.1.1 Supply Voltage .....	3-2	5.5 Reduced Overcurrent.....	5-5
3.2.1.2 CIM Input.....	3-2	5.6 Jam .....	5-5
3.2.1.3 Digital Input.....	3-2	5.7 Earth Fault.....	5-5
3.2.1.4 Analog Output .....	3-2	5.8 Current Unbalance.....	5-6
3.2.1.5 PTC or RTD Input (Local).....	3-2	5.9 Phase Loss .....	5-6
3.2.1.6 I/O Module Interface .....	3-2	5.10 Phase Reverse.....	5-6
3.2.1.7 RS/EIA/TIA-232 Communications .....	3-3	5.11 Undercurrent .....	5-6
3.2.2 PGA-0CIM Connections .....	3-3	5.12 Differential Current Protection.....	5-6
3.2.2.1 Standard.....	3-4	5.13 Starts per Hour/Time Between Starts .....	5-7
3.2.2.2 Residual Earth-Fault .....	3-4	5.14 PTC Temperature (Local) .....	5-7
3.2.2.3 Two-CT.....	3-4	5.15 RTD Temperature (Local) .....	5-7
3.2.3 PGA-0120 Connections and Address Selection.....	3-6	5.16 RTD Temperature (PGA-0120 Module).....	5-8
3.2.4 PGA-0140 Connections.....	3-6	5.17 Hot-Motor Compensation .....	5-8
3.2.4.1 Core Balance.....	3-6	<b>6. THEORY OF OPERATION.....</b>	<b>6-1</b>
3.2.4.2 PGR-6200 Summation .....	3-6	6.1 Signal-Processing Algorithms .....	6-1
3.2.4.3 DIF Summation .....	3-6	6.2 Temperature Input Module (PGA-0120) .....	6-1
3.2.5 Cable Restraint .....	3-6	6.3 Differential Current Module (PGA-0140).....	6-1
3.2.6 Dielectric-Strength Testing .....	3-6	<b>7. COMMUNICATIONS.....</b>	<b>7-1</b>
<b>4. OPERATION AND SETUP.....</b>	<b>4-1</b>	7.1 Personal-Computer Interface.....	7-1
4.1 Display and Indication .....	4-1	7.1.1 Firmware Upgrade.....	7-1
4.1.1 Front-Panel LED Indication .....	4-1	7.1.2 PGW-COMM .....	7-1
4.1.2 Rear-Panel LED Indication.....	4-2	7.2 Network Interface .....	7-1
4.1.3 Display Contrast and Test .....	4-2	7.2.1 TIA-485 Option .....	7-1
		7.2.2 DeviceNet Option .....	7-1
		7.2.3 Ethernet Option .....	7-1



	<i>Page</i>
<b>8. TECHNICAL SPECIFICATIONS</b> .....	8-1
8.1 PGR-6200.....	8-1
8.2 Current Input Module (PGR-0CIM).....	8-3
8.3 Temperature Input Module (PGA-0120).....	8-3
8.4 Differential Current Module (PGA-0140).....	8-4
Appendix A PGR-6200 Menu Map.....	A-1
Appendix B PGR-6200 Setup Record.....	B-1
Appendix C Not Used.....	C-1
Appendix D PGR-6200 TIA-232 Modbus Protocol.....	D-1
Appendix E Communications Database Table.....	E-1
Appendix F Register Formats.....	F-1
Appendix G Ground-Fault Performance Test.....	G-1

### **LIST OF FIGURES**

	<i>Page</i>
1.1 Motor Protection Relay Block Diagram.....	1-2
1.2 PGR-6200 Ordering Information.....	1-3
2.1 PGR-6200 Outline and Panel-Mounting Details.....	2-2
2.2 PGR-6200 Outline and Surface-Mounting Details.....	2-3
2.3 PGA-0CIM Outline and Mounting Details.....	2-4
2.4 PGC-3082 Outline and Mounting Details.....	2-5
2.5 PGC-3140 Outline and Mounting Details.....	2-6
2.6 PGC-3026 Outline and Mounting Details.....	2-7
2.7 PGA-0120 Outline and Mounting Details.....	2-8
2.8 PGA-0140 Outline and Mounting Details.....	2-9
3.1 Typical PGR-6200 Connection Diagram.....	3-1
3.2 Analog-Output Connections.....	3-2
3.3 Local Temperature-Sensor Connections.....	3-2
3.4 I/O Module Connection Diagram.....	3-2
3.5 PGA-0CIM Schematic.....	3-3
3.6 PGA-0CIM Standard Connections.....	3-4
3.7 Other PGA-0CIM Connections.....	3-5
3.8 PGA-0120 Connection Diagram.....	3-7
3.9 Core-Balance Connection.....	3-7
3.10 PGR-6200-Summation Connection.....	3-8
3.11 PGA-0140-Summation Connections.....	3-8
4.1 Menu Example.....	4-1
4.2 Menu Symbols.....	4-1
5.1 Class-20 Overload Curve.....	5-3
5.2 Asymmetrical-Current Multipliers.....	5-5
5.3 Used I <sup>2</sup> t Bias Curve.....	5-8

### **LIST OF TABLES**

	<i>Page</i>
3.1 PGA-0420 Adapter Pinout.....	3-3
3.2 PGA-0120 Address Selection.....	3-6
4.1 UPI LED Functions.....	4-1
4.2 Output-Relay Functions.....	4-3
4.3 Digital-Input Functions.....	4-3
4.4 Analog-Output Parameters.....	4-4
4.5 Metering Display.....	4-5
5.1 Fault Duration Required for Trip or Alarm.....	5-4

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This product has a variety of applications. Those responsible for its application must take the necessary steps to assure that each installation meets all performance and safety requirements including any applicable laws, regulations, codes, and standards.

Information provided by Littelfuse is for purposes of example only. Littelfuse does not assume responsibility for liability for use based upon the examples shown.

## 1. INTRODUCTION

### 1.1 General

The POWR-GARD® PGR-6200 is a motor-protection relay that provides integrated protection, metering, and data-logging functions for fixed- and variable-frequency applications. The PGR-6200 can be programmed using the front-panel operator interface, the TIA-232 port, or an optional communications network.

The PGR-6200 uses a PGA-0CIM current-input module for current-transformer connections as shown in Fig. 1.1. Each PGR-6200 includes a PGA-0CIM.

### 1.2 PGR-6200 Features

#### 1.2.1 Protection

- Overload (49, 51)
- Overcurrent (50, 51)
- Earth fault (50G/N, 51G/N)
- Unbalance (46)
- Phase loss (46)
- Phase reverse (46)
- Jam
- Undercurrent (37)
- Starts per hour (66)
- Differential (87)
- PTC overtemperature (49)
- RTD temperature (38, 49)

#### 1.2.2 Metering

- Line currents
- Current unbalance
- Positive-sequence current ( $I_1$ )
- Negative-sequence current ( $I_2$ )
- Zero-sequence current ( $3I_0$ , calculated)
- Earth-leakage current (CT input)
- Differential currents
- Used thermal capacity
- Thermal trend
- RTD temperatures
- Frequency

#### 1.2.3 Data Logging

- One-hundred records
  - Date and time of event
  - Event type
  - Cause of trip
  - Line currents
  - Current unbalance
  - Earth-leakage current
  - Differential currents
  - Used thermal capacity

- Thermal capacity used during starts
- Start time
- RTD temperatures
- Trip counters
- Running hours

#### 1.2.4 Inputs and Outputs

- Phase-current inputs
- Earth-leakage-current input
- Programmable digital input (24 Vdc)
- 24-Vdc source for digital input
- 4–20-mA analog output, programmable
- Temperature-sensor input, Pt100 RTD or PTC
- I/O module interface
- Three output relays, programmable
- TIA-232 communications
- Network communications

#### 1.2.5 Operator Interface

- 4 x 20 backlit LCD display
- Display-control and programming keys
- LED status indication

#### 1.2.6 PGA-0120 Temperature Input Module (Optional)

- Eight-RTD inputs per module
- Individually selectable RTD types
- Solid-state multiplexing
- Up to three modules per system
- Remote operation up to 1.2 km (4,000')
- Powered by PGR-6200

#### 1.2.7 PGA-0140 Differential Current Module (Optional)

- 3-CT core balance connection
- 6-CT summation connection
- Remote operation up to 1.2 km (4,000')
- Powered by PGR-6200

#### 1.2.8 Communications

The standard communications interface is a TIA-232 port using the Modbus® RTU protocol. In addition to the standard interface, network communications options include TIA-485 with both Modbus® RTU and A-B® DF1 protocols, DeviceNet™, and an IEEE 802.3 port with Modbus® TCP Ethernet protocol.

### 1.3 Ordering Information

See Fig. 1.2 for PGR-6200, PGA-0CIM, PGA-0120 and PGA-0140 model numbers.

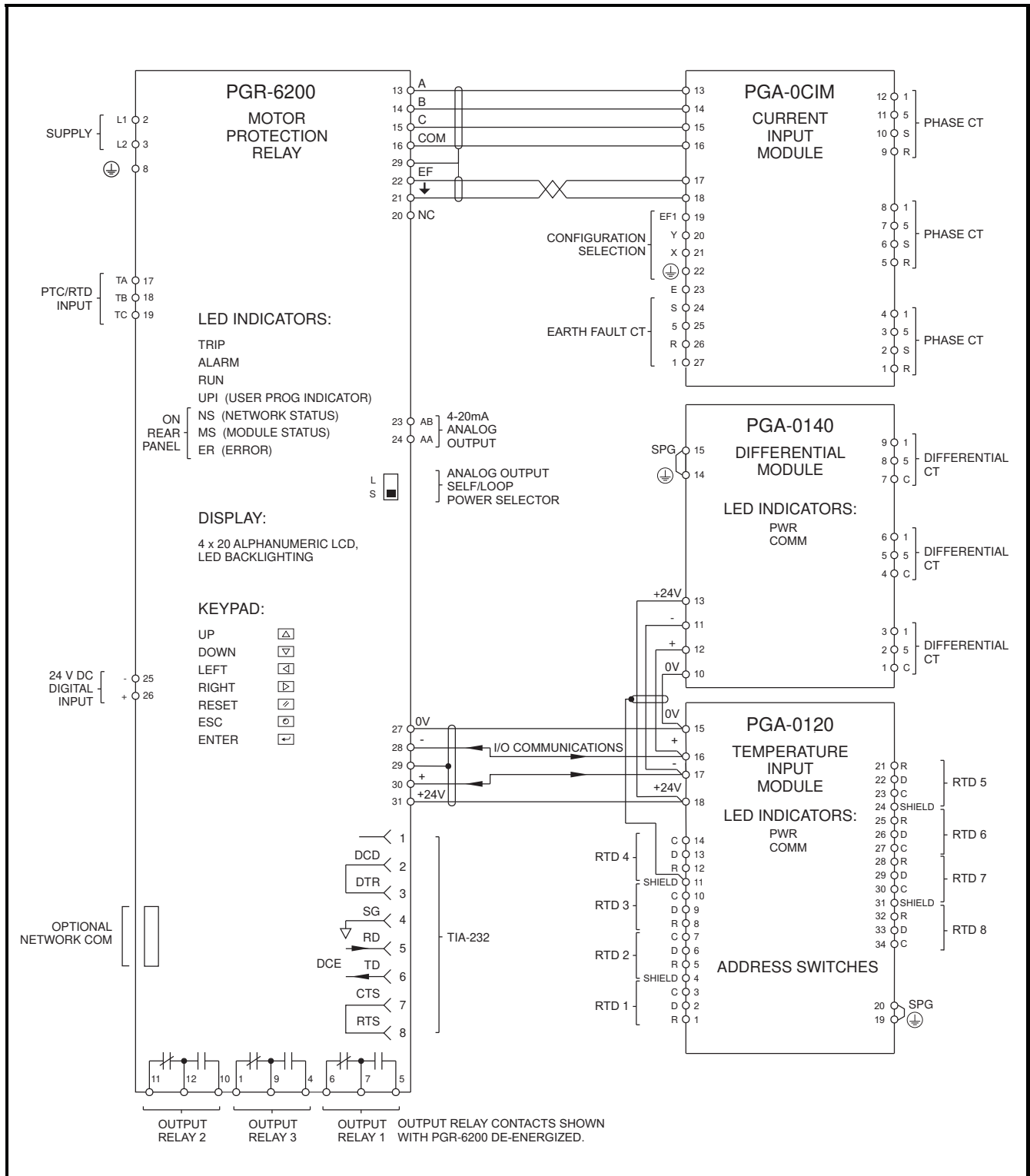
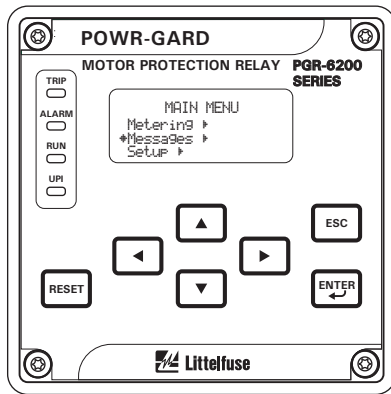
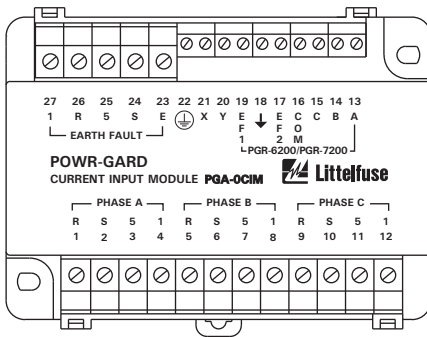


FIGURE 1.1 Motor Protection Relay Block Diagram.



PGR-6200- [ ] - [ ]

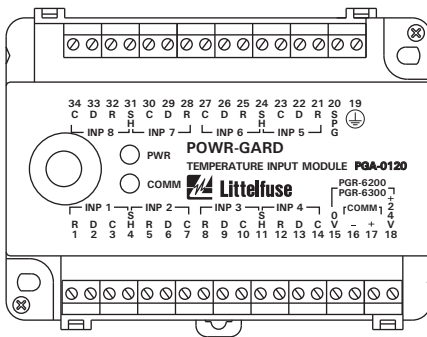
- Options:  
00 CIM Input
- Network Communications:  
0 None, TIA-232 only  
1 TIA-485 c/w A-B<sup>®</sup> DF1 & Modbus<sup>®</sup> RTU Protocols  
2 DeviceNet<sup>™</sup>  
4 IEEE 802.3 (Ethernet)
- Power Supply:  
0 Universal ac/dc (65 to 265 Vac and 80 to 275 Vdc)



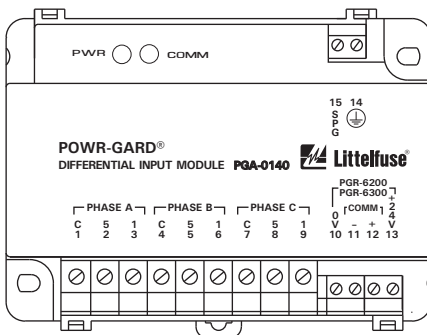
PGA-0CIM

**NOTE:**

The PGR-6200 consists of the Motor Protection Relay and the PGA-0CIM Current Input Module. To order the relay only, add (-MPU) to the part number listed above.



PGA-0120



PGA-0140

**Supplied Interconnect Cable:**

- P75-P300-20030 . . . PGA-0CIM to PGR-6200 Interconnect Cable, 6 m (19') Included with PGA-0CIM  
3124A . . . . . I/O Module to PGR-6200 Interconnect Cable, 4 m (13') Included with PGA-0120 and PGA-0140

FIGURE 1.2 PGR-6200 Ordering Information.





Current Transformers:

- PGC-3026 ..... Sensitive Earth-Fault CT,  
5-A-primary rating,  
26-mm (1") window
- PGC-3082 ..... Sensitive Earth-Fault CT,  
5-A-primary rating,  
82-mm (3.2") window
- PGC-31FC ..... Flux Conditioner for  
PGC-3082,  
70-mm (2.7") window
- PGC-3140 ..... Sensitive Earth-Fault CT  
with Flux Conditioner,  
5-primary rating,  
139-mm (5.5") window
- Other Earth-Fault CT's ..... Contact factory
- Phase CT's ..... Contact factory

Accessories:

- PGK-0SMK ..... Surface-mounting  
hardware kit
- PGA-016A ..... Watertight faceplate cover
- PGA-0420 ..... DB9 to RJ-45 Adaptor with  
1.5 m (5') cable
- PGA-0440 ..... USB to TIA-232 serial  
converter

Software:

- PGW-COMM ..... PC Interface <sup>(1)</sup>
- PGW-FLSH ..... Firmware Upgrade <sup>(1)</sup>

<sup>(1)</sup> Available at [www.littelfuse.com/protectionrelays](http://www.littelfuse.com/protectionrelays)

## 2. INSTALLATION

### 2.1 General

A basic system consists of a PGR-6200, a PGR-0CIM, and three 1-A- or 5-A-secondary line-current transformers. Earth-fault protection can be provided from a core-balance CT or from phase CT's. A core-balance CT (1-A, 5-A, or PGC-3000 series) is recommended. In addition to a single PTC/RTD input provided on the PGR-6200, up to three PGA-0120 modules (eight RTD inputs per module) and one PGA-0140 differential module can be connected to a PGR-6200.

The PGR-6200 switch-mode power supply is rated 65 to 265 Vac and 80 to 275 Vdc.

All modules can be mounted in any orientation.

### 2.2 PGR-6200 Motor Protection Relay

Outline and details for PGR-6200 panel-mounting are shown in Fig. 2.1. The PGR-6200 mounts in a 92 mm (3.62") ¼ DIN square cutout and is secured by a panel-mount clamp. Insert the PGR-6200 through the panel cutout and slip the panel-mount clamp over the PGR-6200 body. Slide the clamp forward until the latch tabs snap into the mating holes. Lock the unit in place by tightening the four clamp screws against the panel.

#### **Caution:**

Do not over tighten the clamp screws as this may deform the clamp and release the latch tabs.

Outline and details for PGR-6200 surface-mounting are shown in Fig. 2.2. Ensure that the L/S switch is set before installing surface-mounting brackets. See Section 3.2.1.4 for switch positions. A detailed installation instruction sheet is included with the PGK-OSMK, Surface-Mounting Hardware Kit.

### 2.3 PGA-0CIM Current Input Module

The PGA-0CIM can be surface or DIN-rail mounted. Outline and mounting details are shown in Fig. 2.3. To minimize CT-lead burden, a PGA-0CIM can be located close to the CT's. The PGA-0CIM terminates phase- and earth-fault-CT secondaries—shorting blocks are not required for PGA-0CIM outputs.

### 2.4 Sensitive Earth-Fault CT's

Outline and mounting details for the PGC-3026, PGC-3082, and PGC-3140 are shown in Figs. 2.4, 2.5, and 2.6.

### 2.5 PGA-0120 Temperature Input Module

Outline and mounting details for the PGA-0120 are shown in Fig. 2.7. The PGA-0120 will fit inside most motor RTD-termination junction boxes and it is certified for use in Class I, Zone 2 hazardous locations. The PGA-0120 can be surface or DIN-rail mounted.

### 2.6 PGA-0140 Differential Current Module

Outline and mounting details for the PGA-0140 are shown in Fig 2.8. The PGA-0140 can be surface or DIN-rail mounted.

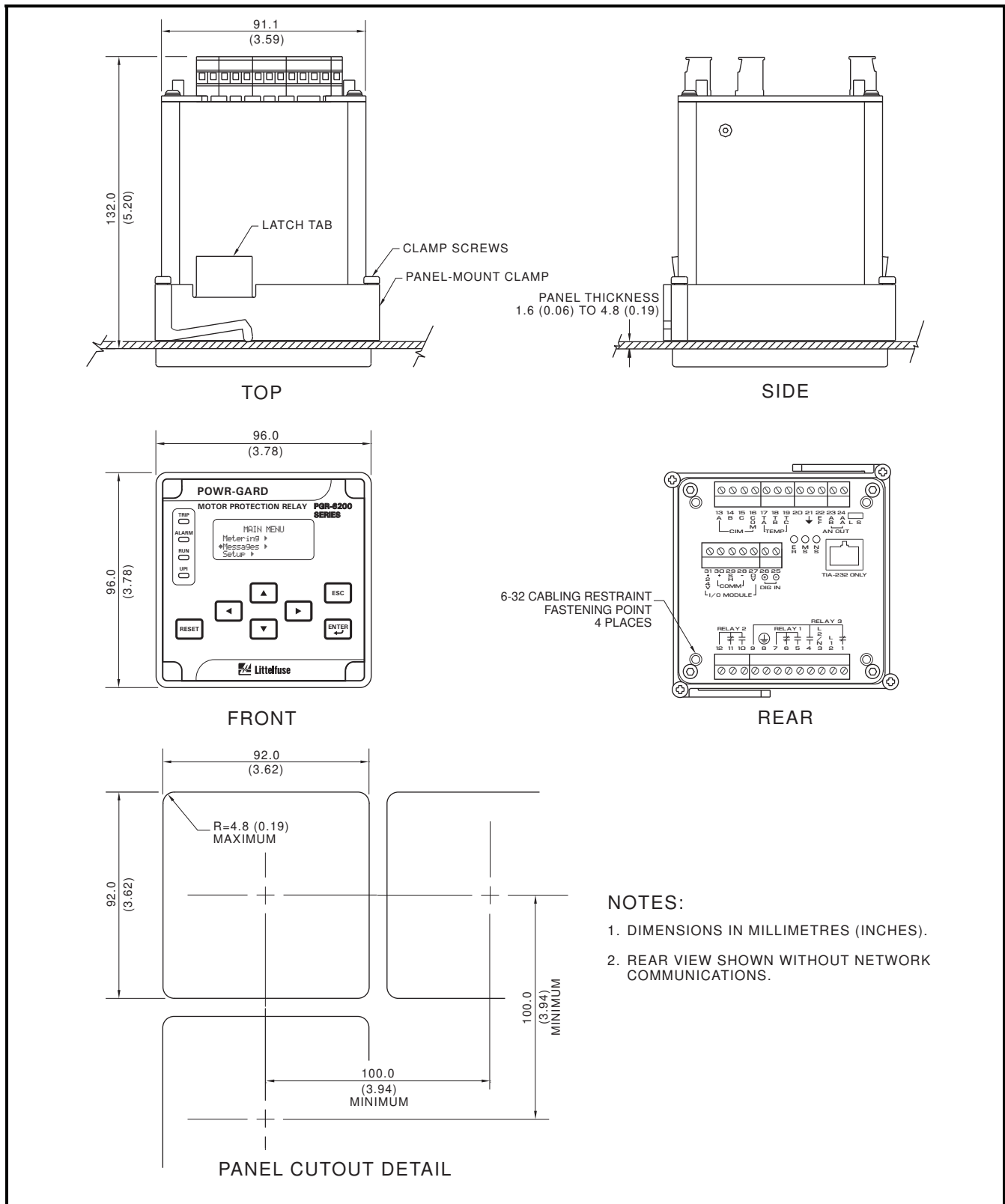


FIGURE 2.1 PGR-6200 Outline and Panel-Mounting Details.

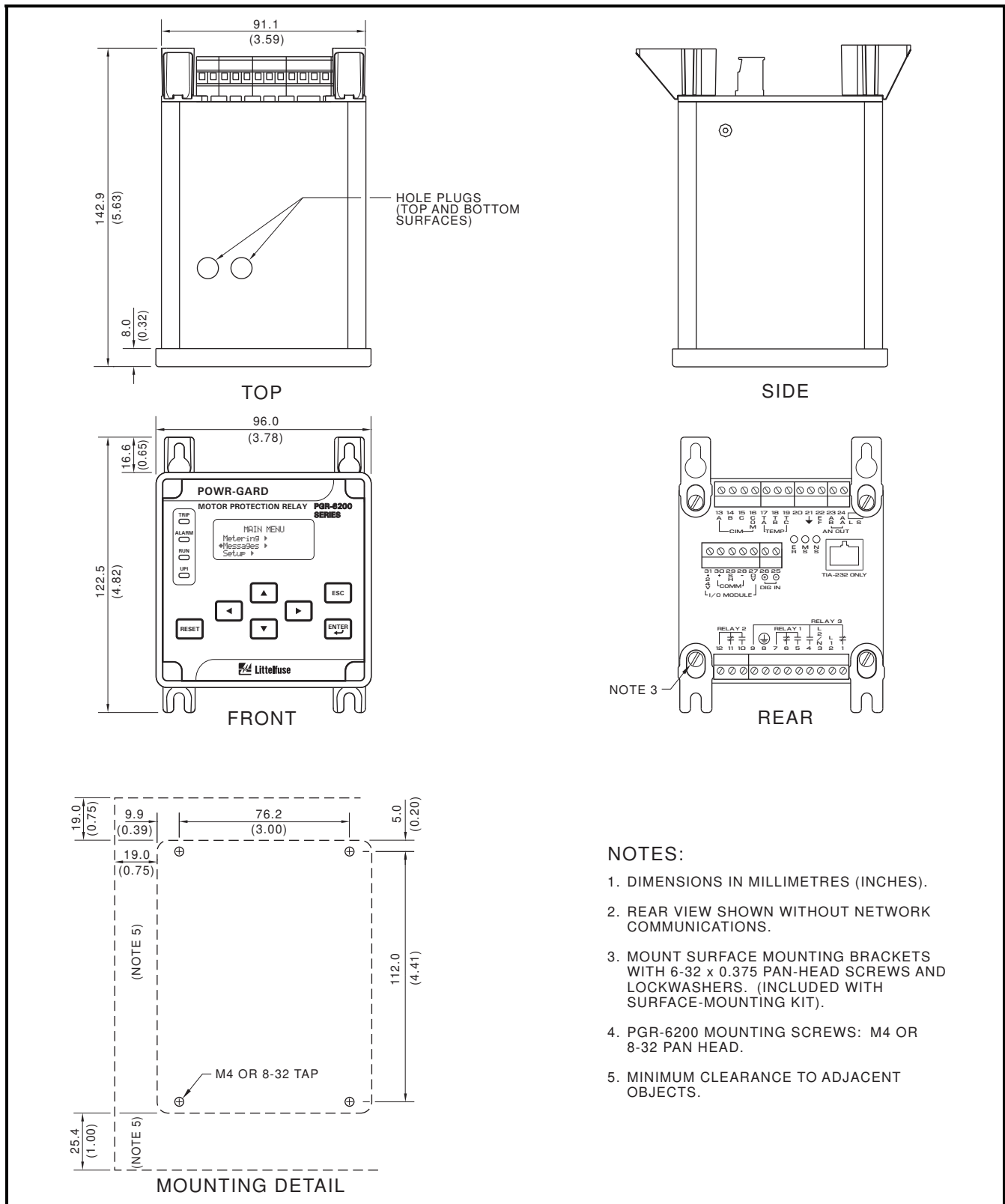


FIGURE 2.2 PGR-6200 Outline and Surface-Mounting Details.

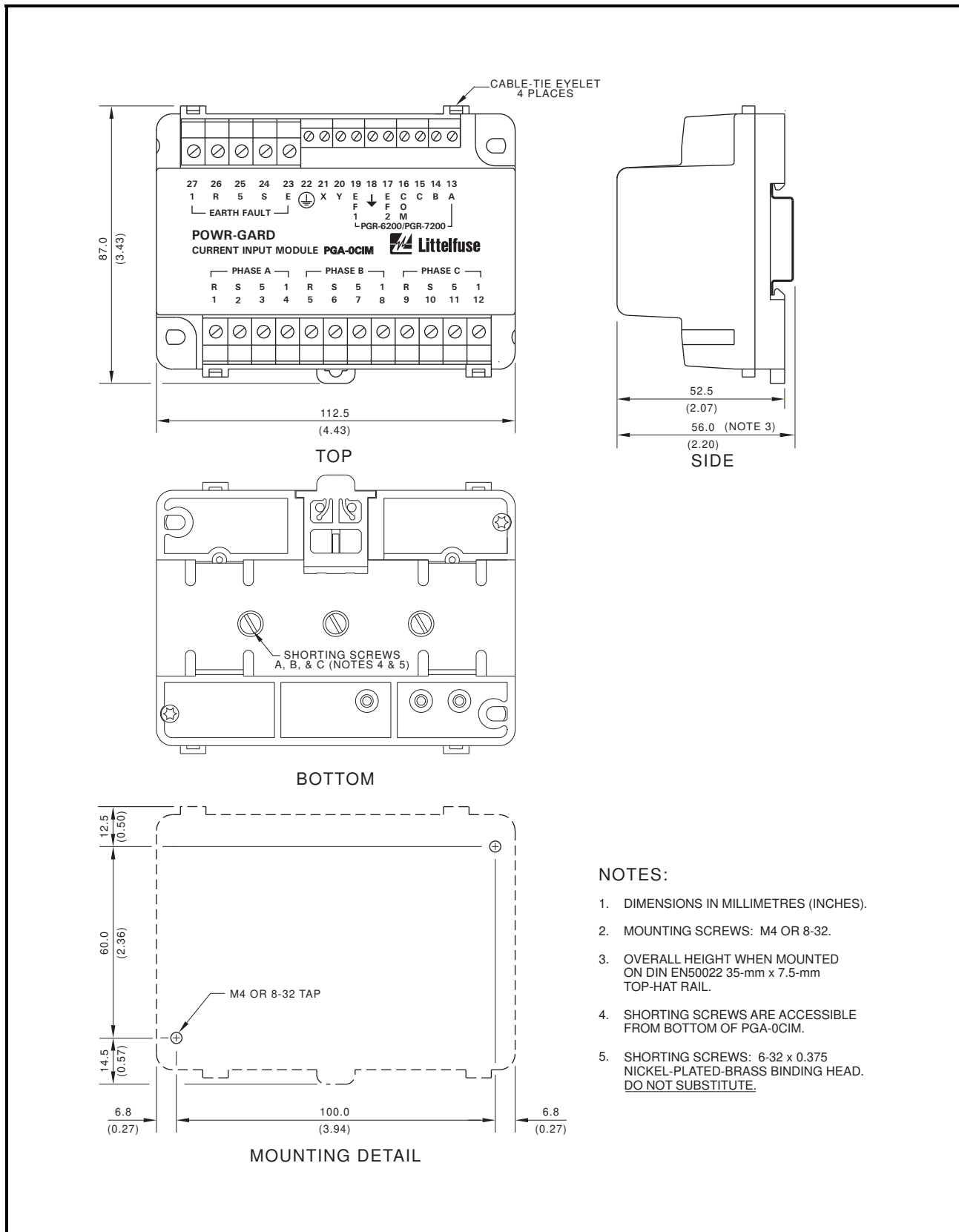


FIGURE 2.3 PGA-0CIM Outline and Mounting Details.



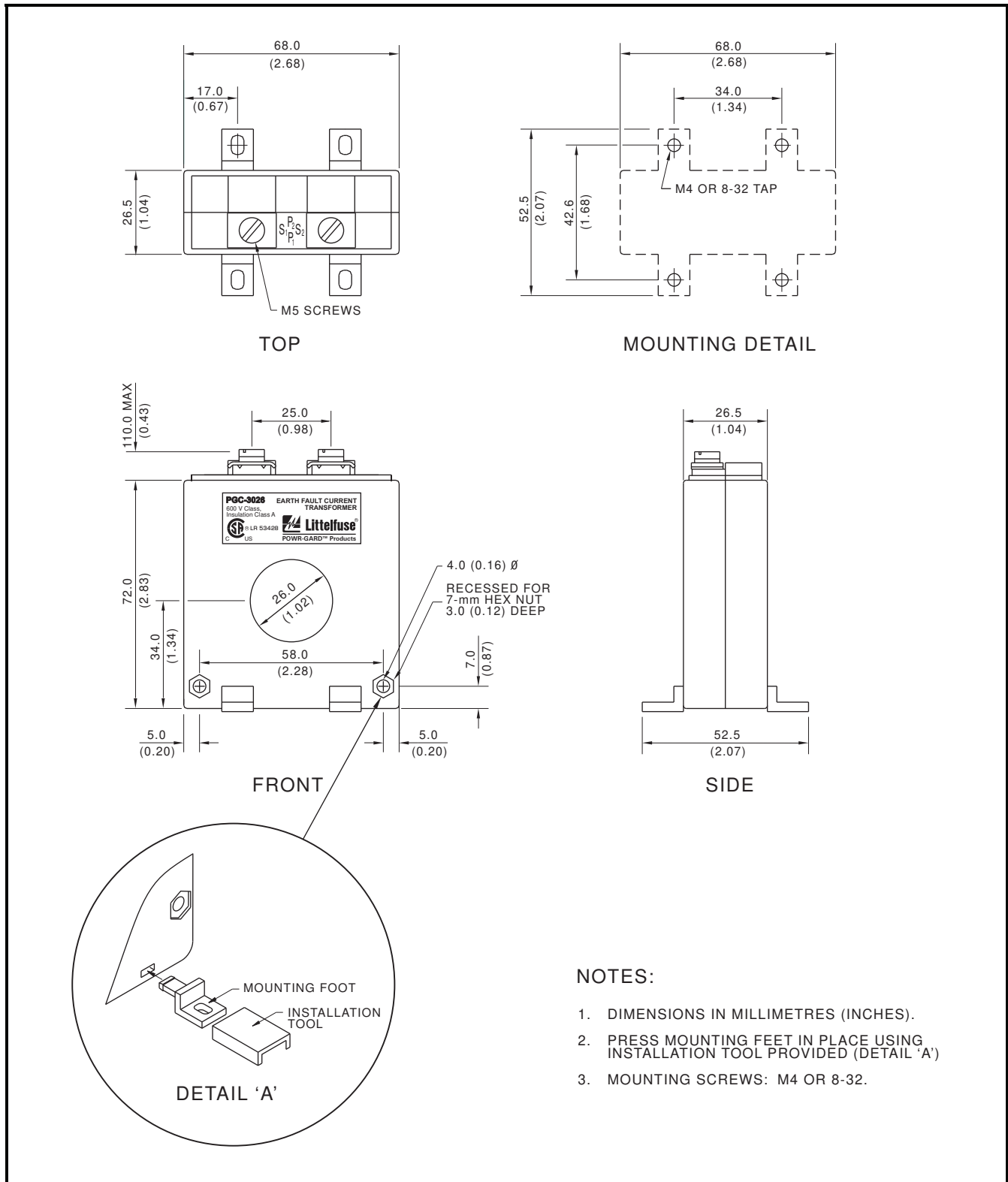


FIGURE 2.4 PGC-3026 Outline and Mounting Details.

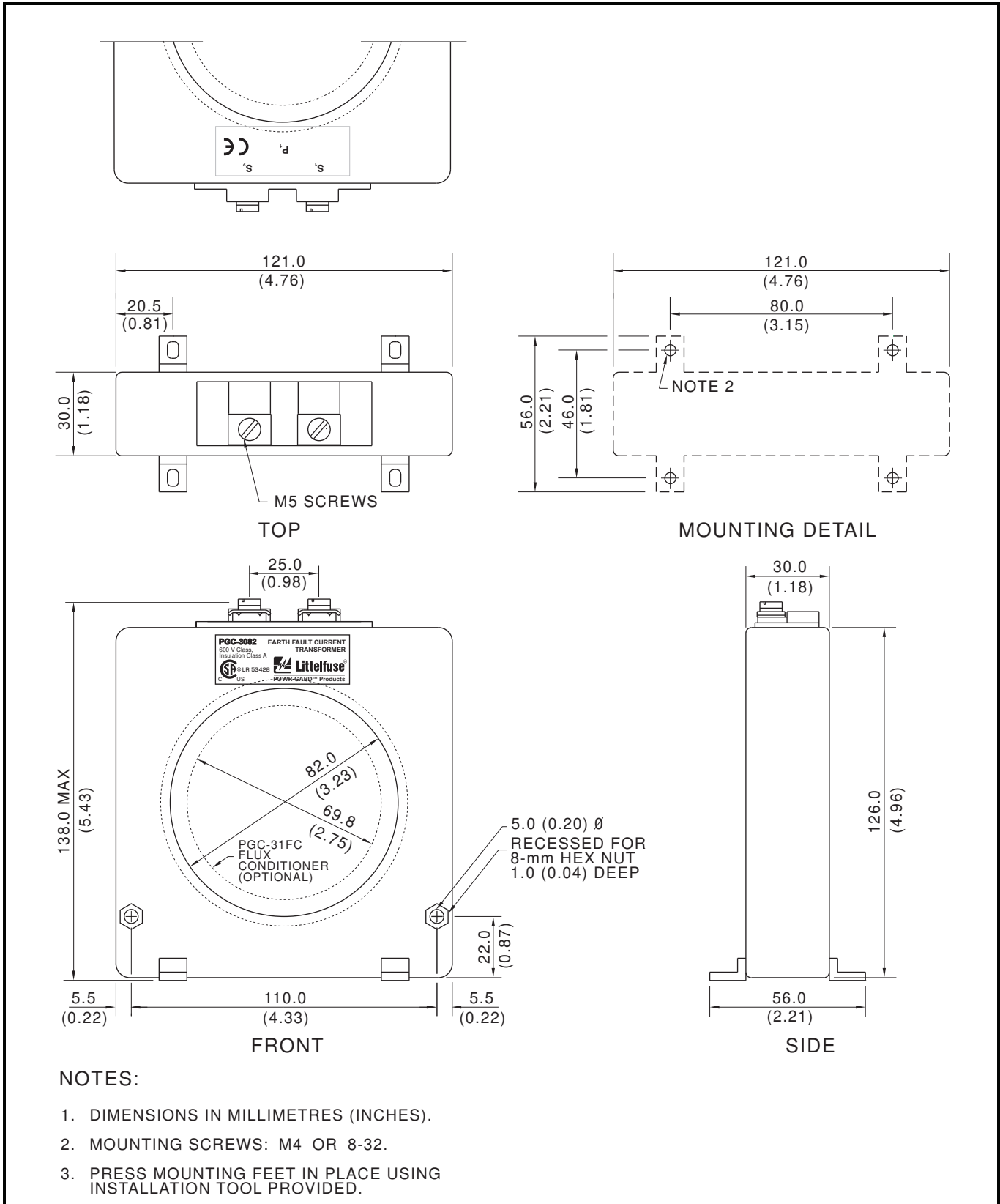


FIGURE 2.5 PGC-3082 Outline and Mounting Details.

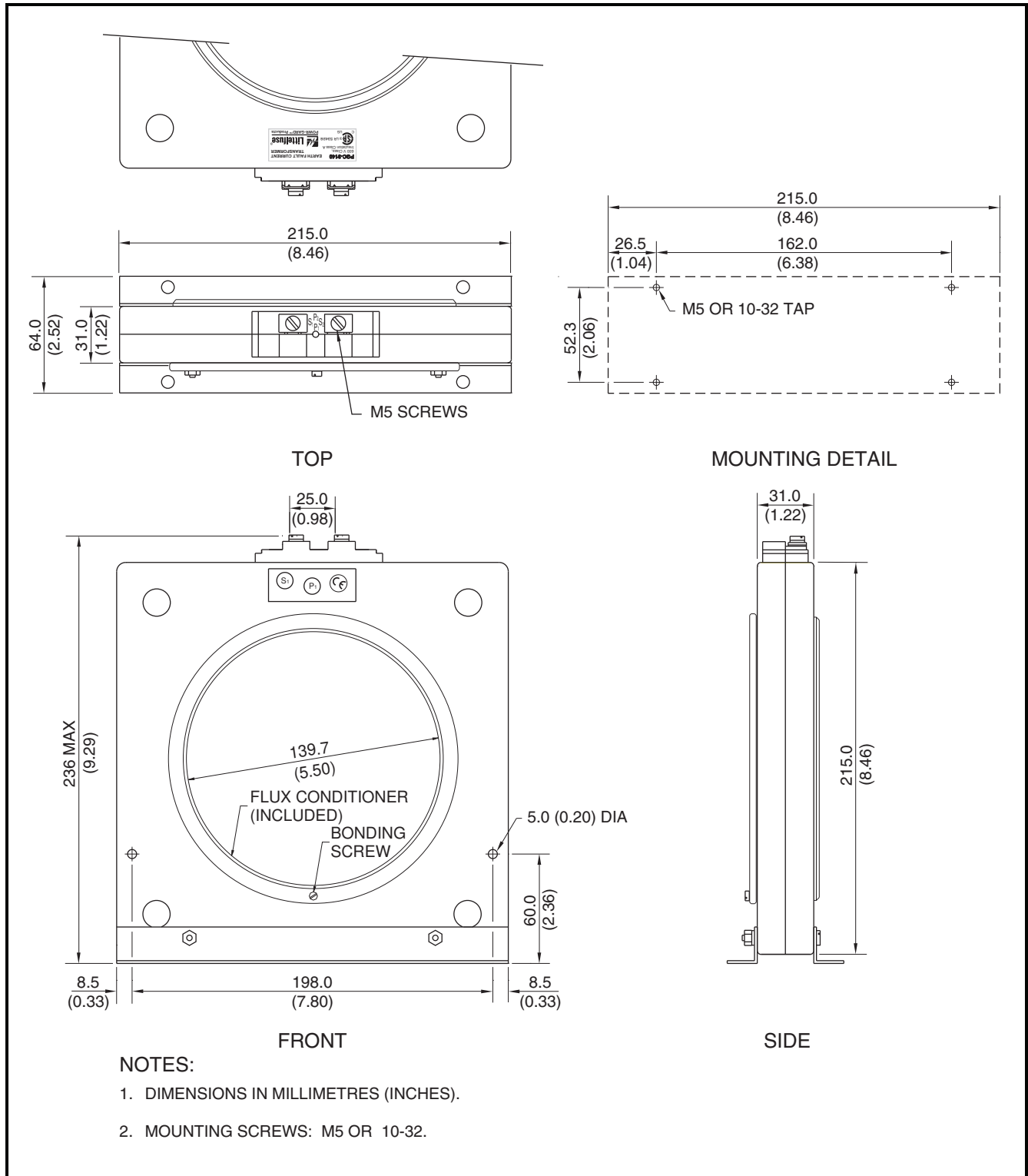


FIGURE 2.6 PGC-3140 Outline and Mounting Details.

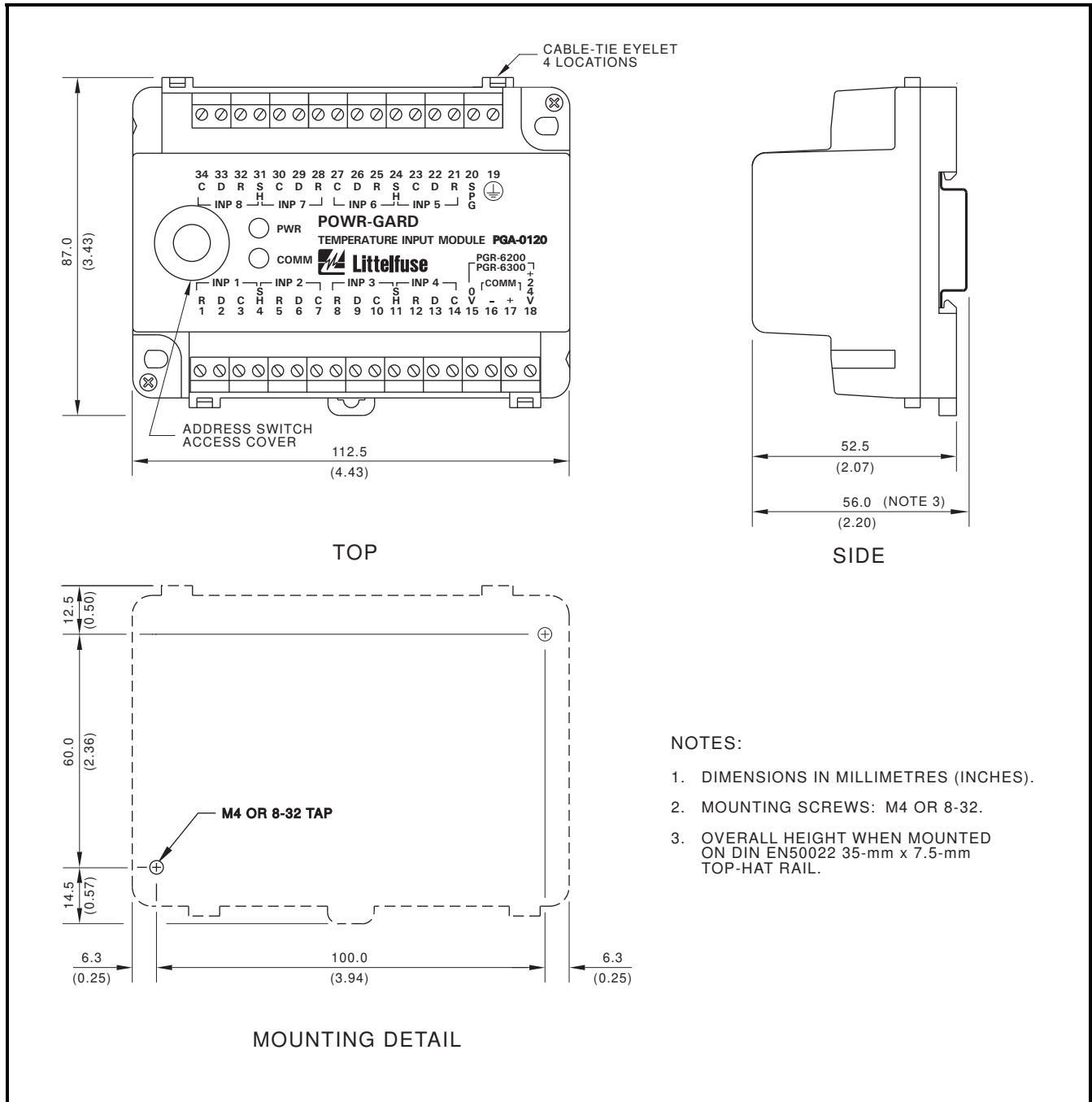


FIGURE 2.7 PGA-0120 Outline and Mounting Details.

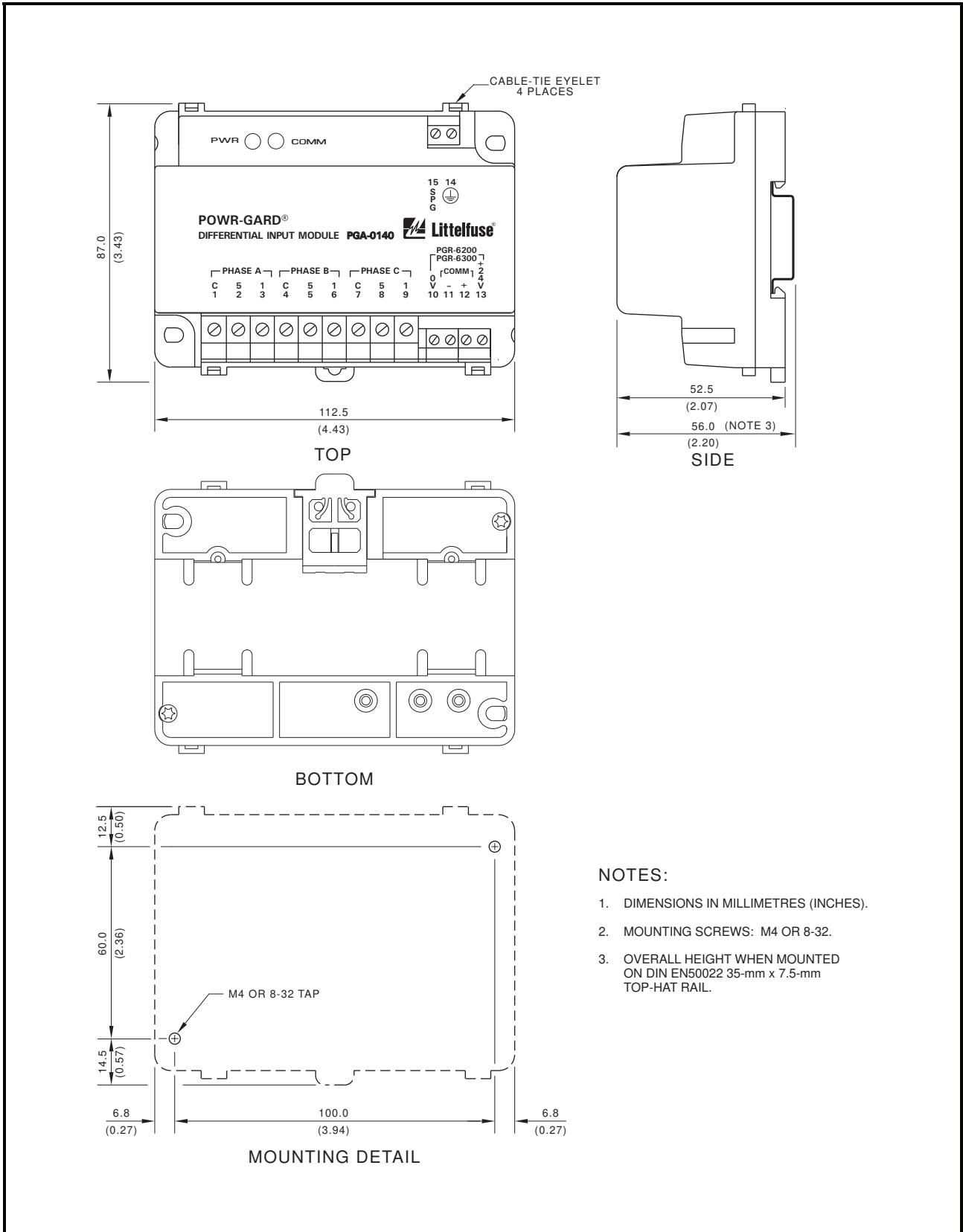


FIGURE 2.8 PGA-0140 Outline and Mounting Details.



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### 3. SYSTEM WIRING

#### 3.1 General

A typical connection diagram for a PGR-6200 and PGA-0CIM is shown in Fig. 3.1. See Sections 3.2.3 and 3.2.4 for PGA-0120 and PGA-0140 connections.

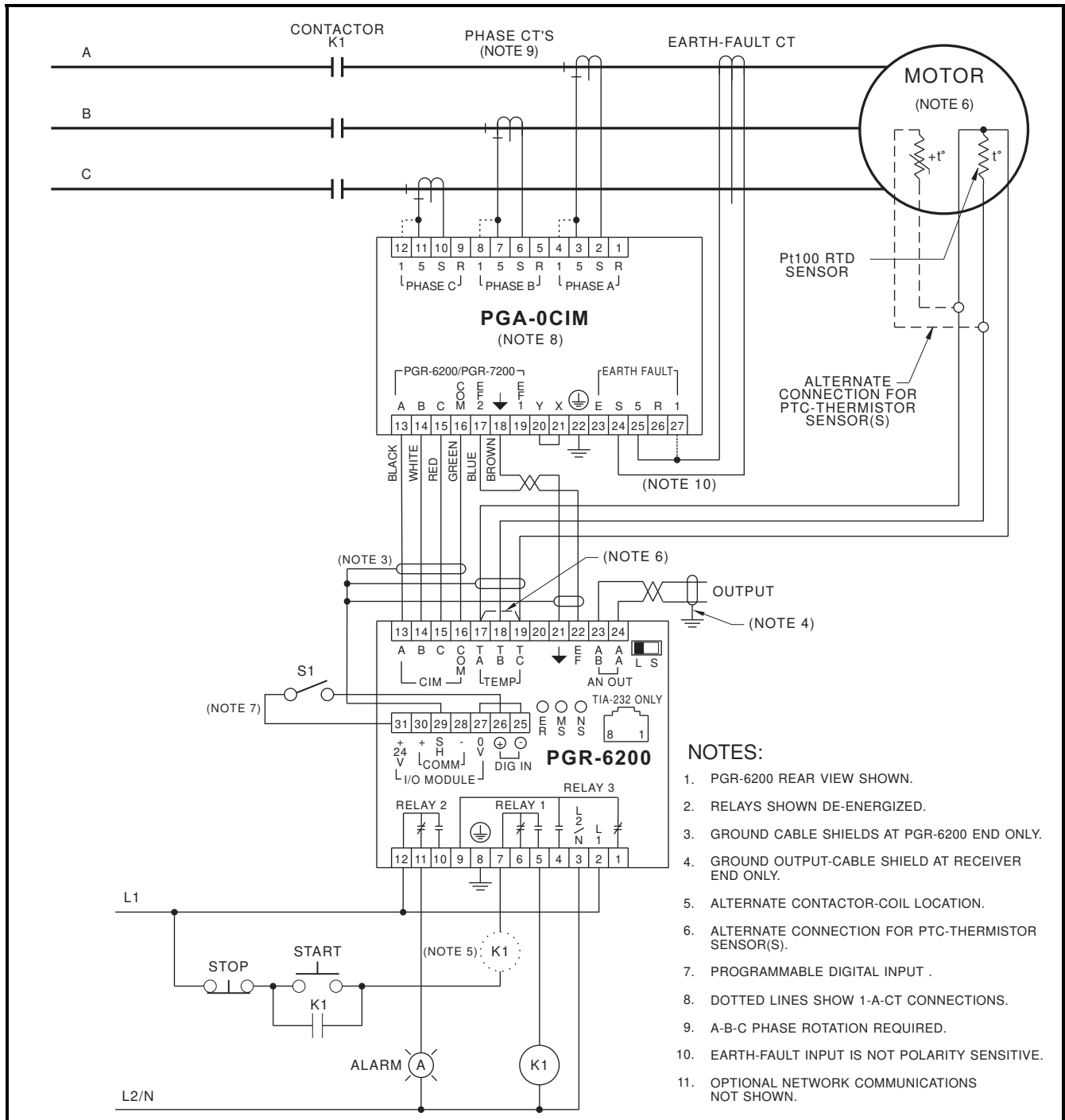


FIGURE 3.1 Typical PGR-6200 Connection Diagram.

### 3.2 Wiring Connections

#### 3.2.1 PGR-6200 Connections

The PGR-6200 wire-clamping terminal blocks accept 24 to 12 AWG (0.2 to 2.5 mm<sup>2</sup>) conductors. These terminal blocks unplug to allow the PGR-6200 to be easily removed.

##### 3.2.1.1 Supply Voltage

Derive supply voltage from the line side of the motor controller or from an independent source. Connect supply voltage to terminals 2 and 3 (L1 and L2/N) as shown in Fig. 3.1. In 120-Vac systems, L2/N is designated as the neutral conductor. For direct-current power supplies, use L1 for the positive terminal and L2/N as the negative terminal. Ground terminal 8 (⊕).

##### 3.2.1.2 CIM Input

Connect the PGR-6200 to the PGA-0CIM as shown in Figs. 3.6 and 3.7 using the cable provided.

##### 3.2.1.3 Digital Input

A 24-Vdc digital input is provided on terminals 25 and 26. This input is polarity sensitive. For a logical 1, terminal 26 must be positive with respect to terminal 25. See Section 4.2.5.

The current-limited 24-Vdc source (terminals 27 & 31) can be used to power the digital input.

##### 3.2.1.4 Analog Output

The analog output is switch selectable as self powered or loop powered.

For the self-powered connection, set the L/S switch to the S position. The self-powered connection is shown in Fig. 3.2 (a). The analog output is referenced to the I/O module supply, terminal 27.

For the loop-powered connection, set the L/S switch to the L position. The loop-powered connection is shown in Fig. 3.2 (b). In loop-powered operation, the analog-output is isolated from all other PGR-6200 terminals.

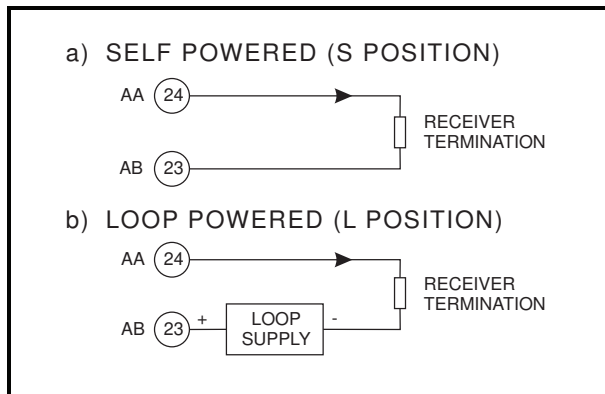


FIGURE 3.2 Analog-Output Connections.

##### 3.2.1.5 PTC or RTD Input (Local)

The temperature-sensor input on the PGR-6200 can be configured for either PTC or Pt100 RTD operation as shown in Fig. 3.3.

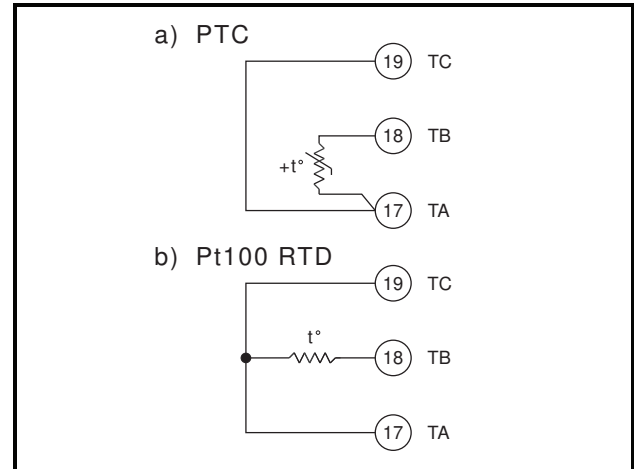


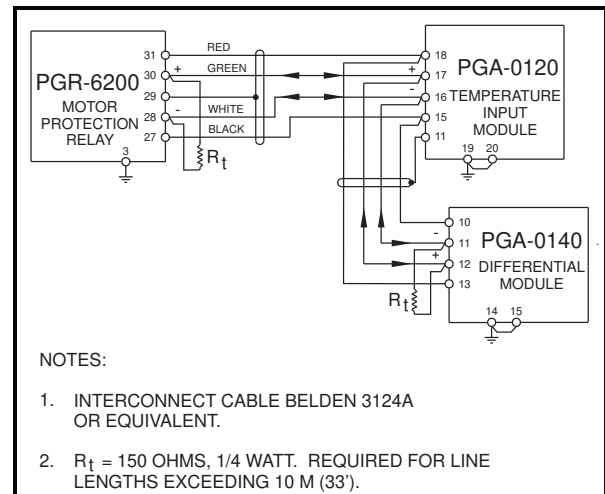
FIGURE 3.3 Local Temperature-Sensor Connections.

##### 3.2.1.6 I/O Module Interface

The I/O module interface supplies power and communications to optional I/O modules such as the PGA-0120 and PGA-0140.

I/O module communication is based on the two-wire multi-drop TIA-485 standard but uses a proprietary protocol. Overall line length must not exceed 1.2 km (4,000'). For line lengths exceeding 10 m (33'), 150-Ω terminations are required at the cable ends. I/O modules are supplied with 4 m (13') of interconnection cable. See Fig. 3.4.

**Note:** I/O communication is shared with the display. Incorrect wiring can cause the display and keypad to freeze.



NOTES:

1. INTERCONNECT CABLE BELDEN 3124A OR EQUIVALENT.
2.  $R_t = 150$  OHMS, 1/4 WATT. REQUIRED FOR LINE LENGTHS EXCEEDING 10 M (33').

FIGURE 3.4 I/O Module Connection Diagram.

### 3.2.1.7 RS/EIA/TIA-232 Communications

An RJ-45 TIA-232 connector is provided on the rear panel of the PGR-6200. This port uses Modbus® RTU protocol to communicate with PGW-COMM PC-interface software. For Modbus® RTU protocol, see Appendix D. The slave ID and communication baud rate are set in the *Setup | Hardware | Local Comms* menu.

Table 3.1 shows the pinout for the optional PGA-0420 adapter for operation with PGW-COMM.

See Fig 3.1 for RJ-45 pinout.

For a USB connection, use an PGA-0440 adapter.

TABLE 3.1 PGA-0420 Adapter Pinout

SYMBOLIC NAME	RJ-45	DB9
RI/DSR	1	9
CD	2	1
DTR	3	4
SG	4	5
RD	5	2
TD	6	3
CTS	7	8
RTS	8	7

### 3.2.2 PGA-0CIM Connections

The PGA-0CIM CT-input terminal blocks accept 22 to 10 AWG (0.3 to 4.0 mm<sup>2</sup>) conductors. The remaining PGA-0CIM clamping blocks accept 24 to 12 AWG (0.2 to 2.5 mm<sup>2</sup>) conductors.

The PGA-0CIM contains four signal-conditioning interface transformers which are interconnected as shown in Fig. 3.5. These transformers isolate the PGR-6200 from the phase and earth-fault CT's. The PGA-0CIM eliminates the need for CT shorting contacts when the PGR-6200 is disconnected. Phase-CT and earth-fault-CT secondaries can be simultaneously grounded through terminal 22 and a jumper to terminal 20. For applications where the CT secondaries must be grounded at another location, the CT secondaries can be isolated by removing shorting screws A, B, and C through holes in the bottom of the PGA-0CIM. See Figs. 2.3 and 3.5.

**Note:** A-B-C phase sequence and polarity must be observed when connecting phase CT's. See Section 4.2.1.

Connect the PGA-0CIM to the PGR-6200 as shown in Figs. 3.6 and 3.7 using the cable provided.

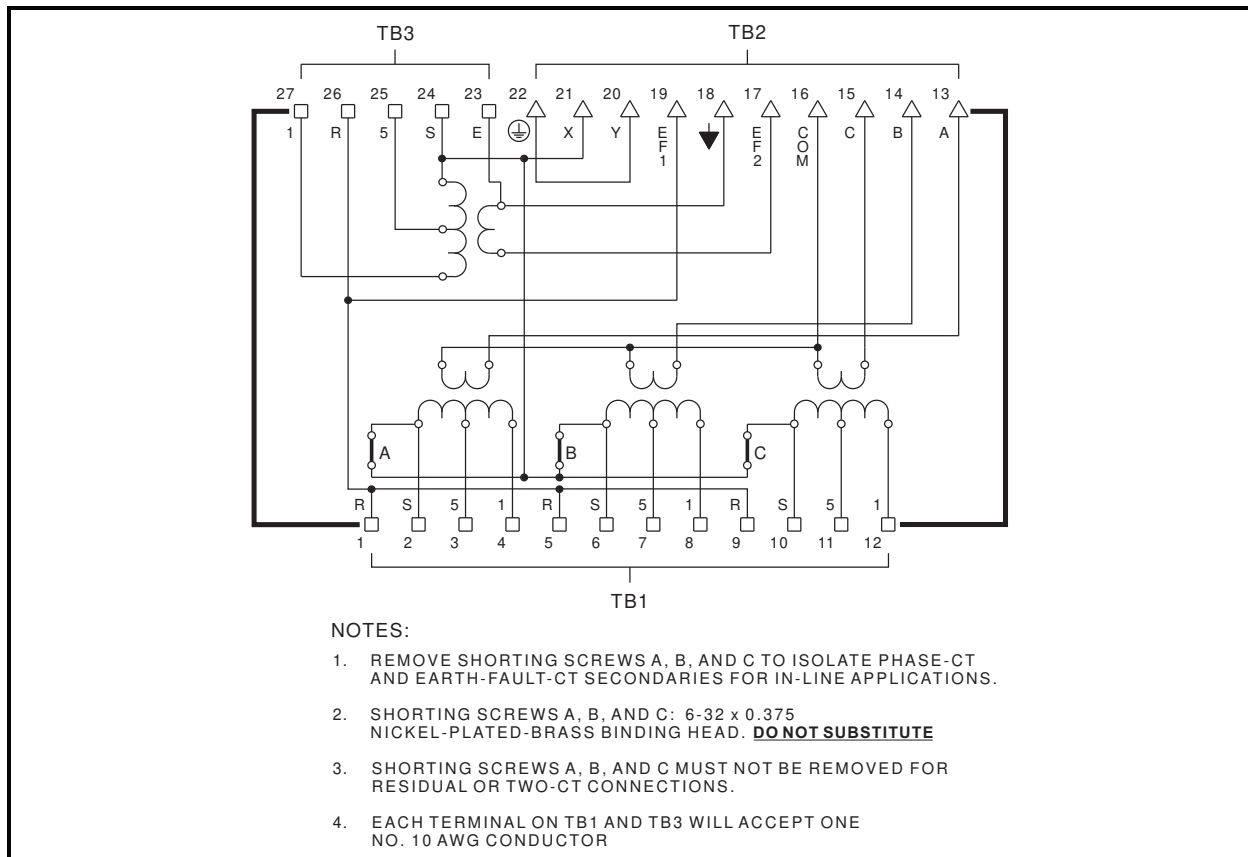


FIGURE 3.5 PGA-0CIM Schematic.

**3.2.2.1 Standard**

Standard connections with earth-fault CTs are shown in Fig. 3.6. Dotted lines indicate 1-A-CT connections. Use shielded cable for PGC-3000-series current-transformer connections. Ensure only current-carrying phase conductors pass through the earth-fault-CT window and that ground conductors do not.

**3.2.2.2 Residual Earth-Fault**

The wired residual earth-fault connection is shown in Fig. 3.7 (a). Dotted lines indicate 1-A-CT

connections. Use three identical CT's for this connection.

The PGR-6200 also calculates residual current. See Section 4.2.2.

**3.2.2.3 Two-CT**

The two-CT connection is shown in Figs. 3.7 (b) and 3.7 (c). Dotted lines indicate 1-A-CT connections. Since this connection derives the current in the unmonitored phase, it should be used only in retrofit applications where it is not possible to install a third CT.

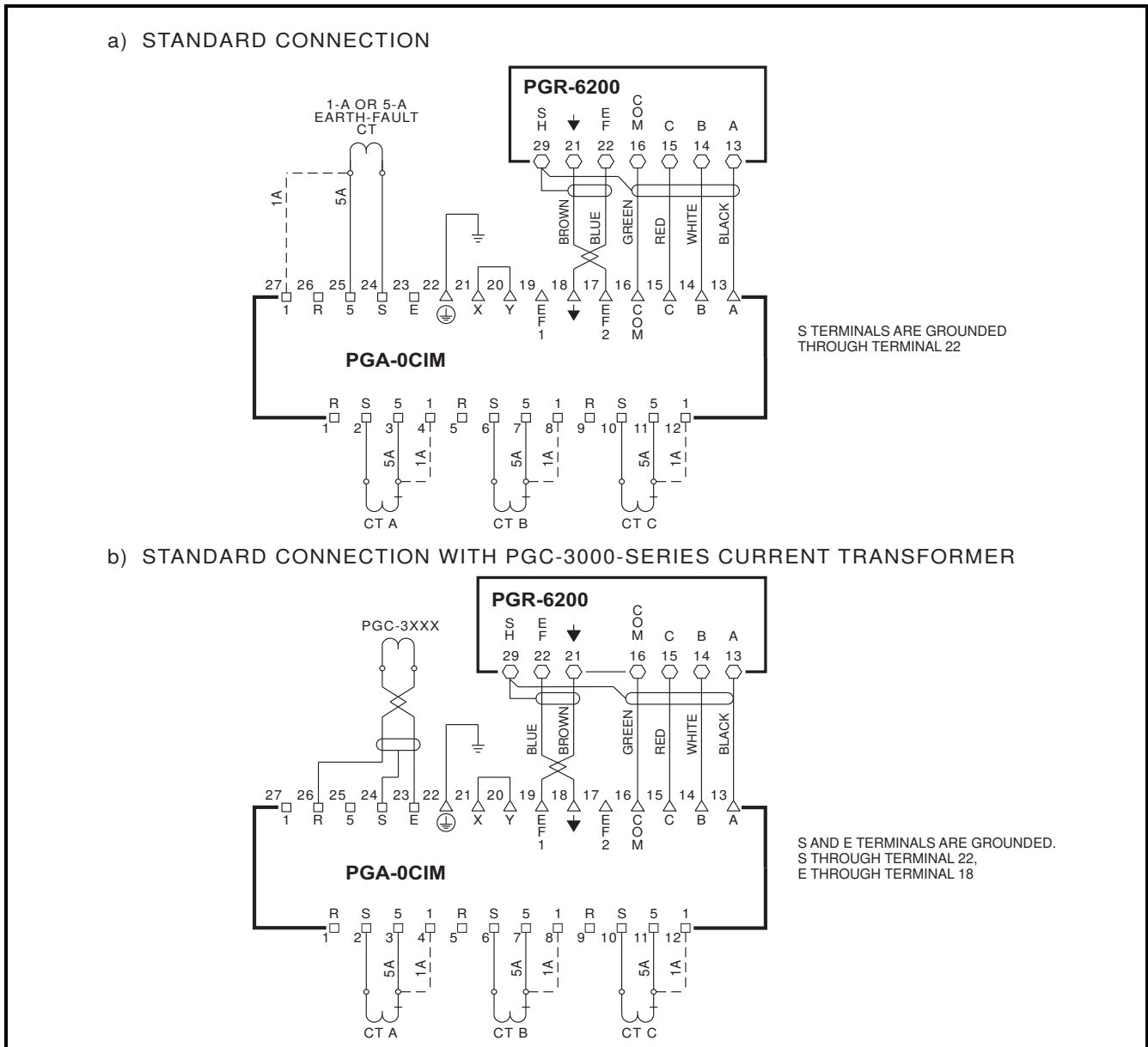
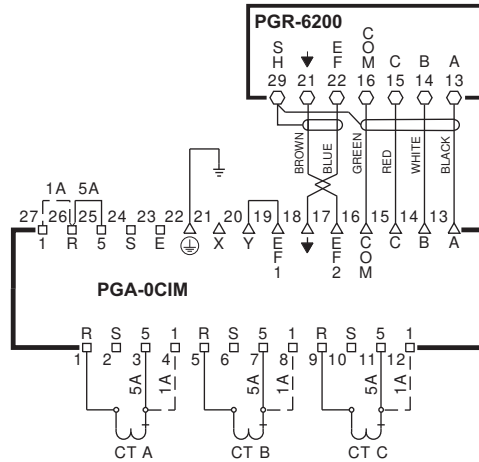


FIGURE 3.6 PGA-0CIM Standard Connections.

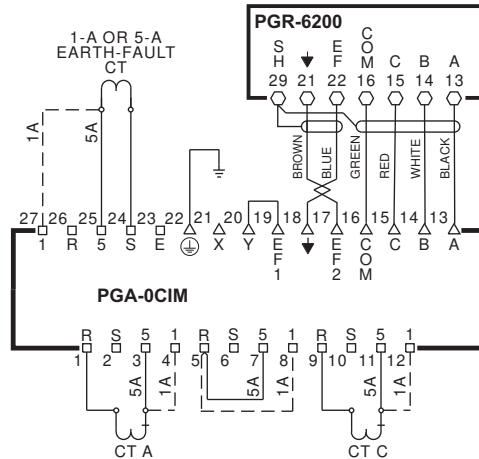


a) RESIDUAL CONNECTION



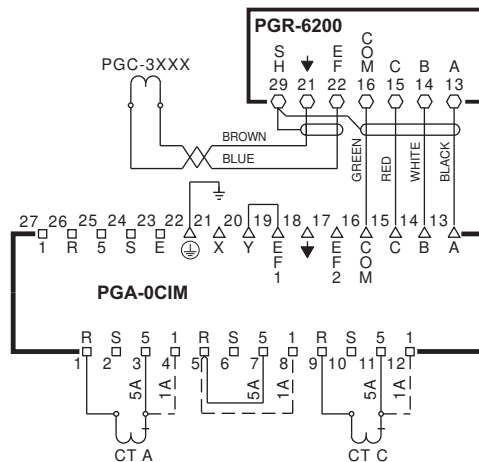
SHORTING SCREWS  
A, B, & C MUST  
NOT BE REMOVED.  
R TERMINALS ARE  
GROUNDED THROUGH  
TERMINAL 22.

b) TWO-CT CONNECTION



SHORTING SCREWS  
A, B, & C MUST  
NOT BE REMOVED.  
R TERMINALS ARE GROUNDED  
THROUGH TERMINAL 22.  
EARTH-FAULT CT MUST  
NOT BE GROUNDED.

c) TWO-CT CONNECTION WITH PGC-3000-SERIES CURRENT TRANSFORMER



SHORTING SCREWS  
A, B, & C MUST  
NOT BE REMOVED.  
R TERMINALS ARE GROUNDED  
THROUGH TERMINAL 22.

FIGURE 3.7 Other PGA-0CIM Connections.

### 3.2.3 PGA-0120 Connections and Address Selection

Connect the PGA-0120 Temperature Input Module to the PGR-6200 using the four-conductor shielded cable (Belden 3124A or equivalent) supplied with the PGA-0120 as shown in Fig. 3.8. The PGR-6200 24-Vdc supply can power up to three PGA-0120 modules.

Connect RTD's to the PGA-0120 as shown in Fig 3.8. When the RTD module is installed in a motor junction box, RTD-lead shielding is not required. PGA-0120 terminal blocks accept 24 to 12 AWG (0.2 to 2.5 mm<sup>2</sup>) conductors.

Connect surge-protection (SPG) terminal 20 to terminal 19 (⊕) and ground terminal 19.

The PGA-0120 has two switches to select its network address. See Fig. 3.8. Up to three PGA-0120 modules can be connected to the I/O MODULE bus, and each RTD-module address must be unique. If one module is used, address 1 must be used. If two RTD Modules are used, addresses 1 and 2 must be used. If three RTD Modules are used, addresses 1, 2, and 3 must be used.

Table 3.2 shows the address selection format.

TABLE 3.2 PGA-0120 Address Selection

ADDRESS	SWITCH 1	SWITCH 2
0 (Off line)	Open	Open
1 (First RTD module)	Closed	Open
2 (Second RTD module)	Open	Closed
3 (Third RTD module)	Closed	Closed

### 3.2.4 PGA-0140 Connections

Connect the PGA-0140 Differential Input Module to the PGR-6200 using four-conductor shielded cable (Belden 3124A or equivalent) as shown in Fig. 3.4.

Connect the surge-protection (SPG) terminal 15 to terminal 14 (⊕), and ground terminal 14.

The PGA-0140 CT-input terminal blocks accept 22 to 10 AWG (0.3 to 4.0 mm<sup>2</sup>) conductors. The remaining PGA-0140 clamping blocks accept 24 to 12 AWG (0.2 to 2.5 mm<sup>2</sup>) conductors.

#### 3.2.4.1 Core Balance

The core-balance connection uses three differential CT's as shown in Fig. 3.9. To minimize power-cable and CT secondary lead lengths, both the differential CT's and the PGA-0140 can be located near the motor. The primary rating of the differential CT does not have to match the phase-CT primary rating and is usually selected with a lower ratio resulting in more sensitive differential protection. The core-balance method avoids CT-matching issues and is the preferred connection.

#### 3.2.4.2 PGR-6200 Summation

The PGR-6200-summation connection uses three phase CT's and three differential CT's as shown in Fig. 3.10. Both CT-ratio and CT-saturation characteristics must be matched to avoid differential currents under motor starting and running conditions. The PGA-0140 module should be located near the PGA-0CIM to minimize CT-wire length. It is preferred to use three dedicated phase CT's and three core-balance differential CT's as described in Section 3.2.4.1.

For the delta connection, the *FLA Rating* is set equal to the motor's full-load current multiplied by  $\sqrt{3}$ .

#### 3.2.4.3 DIF Summation

The DIF-summation connection uses six differential CT's as shown in Fig. 3.11. Both CT-ratio and CT-saturation characteristics must be matched to avoid differential currents under motor starting and running conditions. It is preferred to use three core-balance CT's as described in Section 3.2.4.1. This six-CT connection allows the CT's and PGA-0140 to be placed near the motor to minimize power-cable and CT-lead length.

### 3.2.5 Cable Restraint

All conductors should be restrained within 100 mm (4") of the terminal blocks. Four cabling-restraint points are provided on the PGR-6200 rear panel. Secure cables to the PGA-0CIM, PGA-0120 and PGA-0140 using the cable-tie eyelets and the cable ties provided. See Figs. 2.1, 2.3, 2.7 and 2.8.

### 3.2.6 Dielectric-Strength Testing

Dielectric-strength testing can be performed only on CT inputs, supply-voltage input, and output relays. Unplug all other I/O and remove the PGA-0CIM ⊕ connection (terminal 22) during dielectric-strength testing.

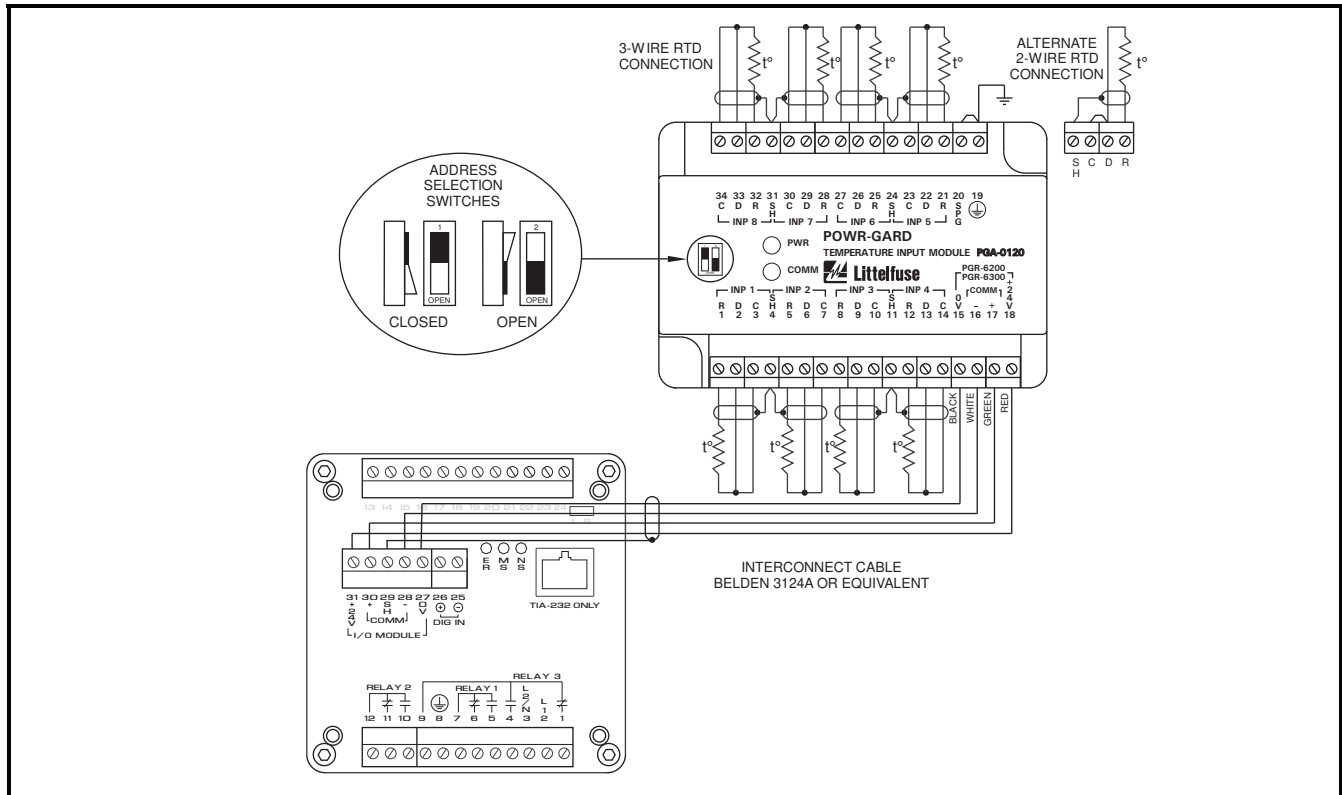


FIGURE 3.8 PGA-0120 Connection Diagram.

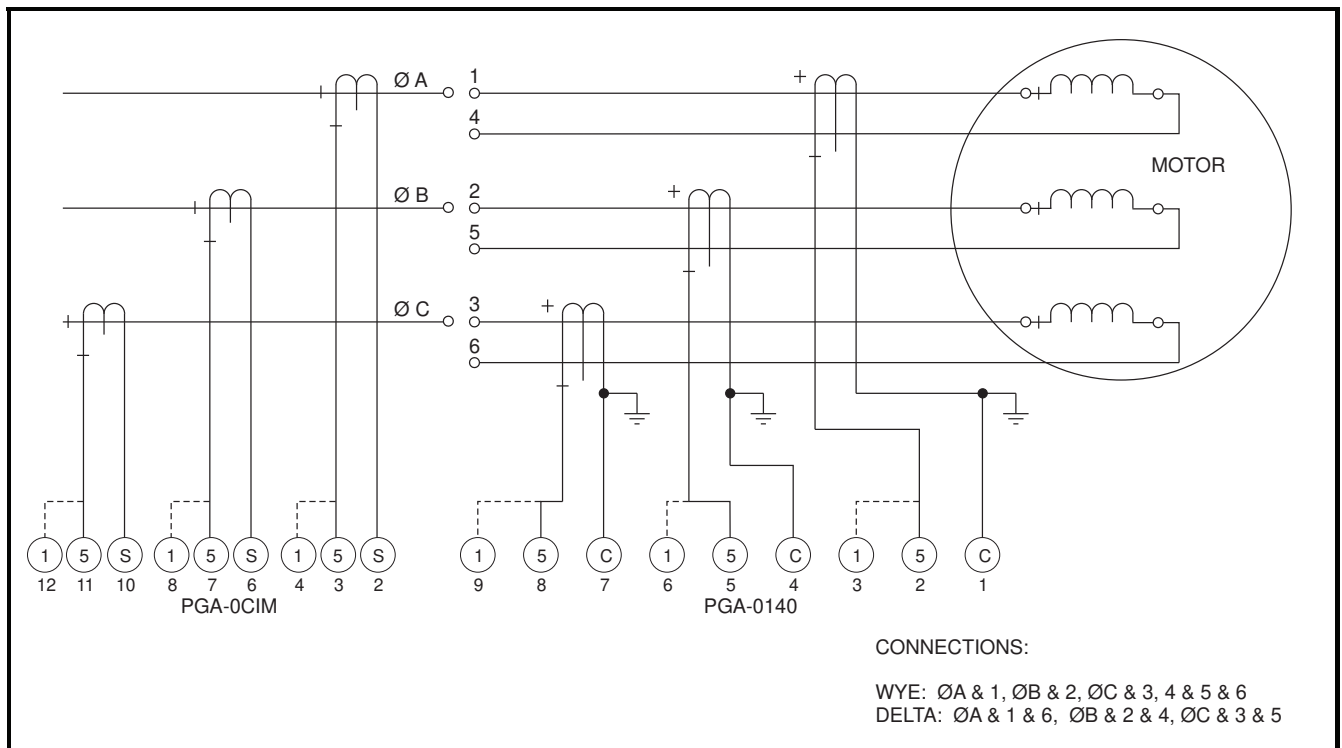


FIGURE 3.9 Core-Balance Connection.