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### Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China







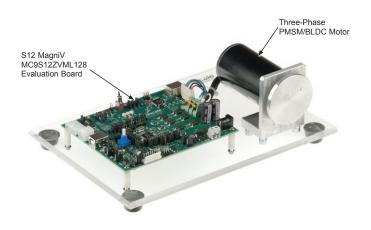


### MagniV® MC9S12ZVML128 MCU

Three-phase Sensorless PMSM Motor Control Development Kit



# THREE-PHASE SENSORLESS PMSM KIT WITH MagniV MC9S12ZVML128 MCU



### THREE-PHASE SENSORLESS PMSM KIT WITH MagniV MC9S12ZVML128 MCU

#### Hardware

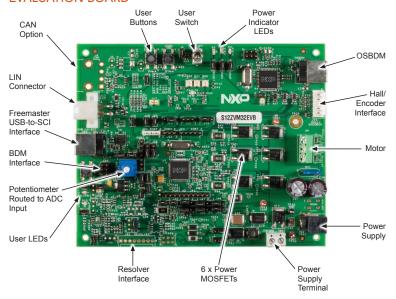
- MagniV MC9S12ZVML128 evaluation board with integrated 3-phase 12 V/10 A power stage
- Three-phase PMSM/BLDC motor with HALL sensor, 24 VDC, 9350 RPM, 90 W, 45ZWN2490B
- USB cable
- 12 VDC power supply

#### Resources

- Sensorless field-oriented control of PMSM using Back-EMF observer
- Automotive math and motor control library set for MC9S12ZVM installation package

- FreeMASTER installation package
- FreeMASTER project including Motor Control Application Tuning tool
- Three-Phase Sensorless PMSM Kit with MagniV MC9S12ZVML128 MCU Fact Sheet
- Three-phase Sensorless PMSM Kit with MagniV MC9S12ZVML128 MCU Quick Start Guide
- 3-Phase Sensorless PMSM Kit with MagniV MC9S12ZVML128 MCU Application Note
- MagniV MC9S12ZVML128 Evaluation Board User Guide

### GET TO KNOW THE MagniV MC9S12ZVML128 EVALUATION BOARD



Front side of MagniV MC9S12ZVML128

#### SOFTWARE TOOLS INSTALLATION

Install the FreeMASTER debugging tool. For FreeMASTER application download, please visit

#### www.nxp.com/freemaster.

Install the CP210x virtual COM port driver. For the CP210x virtual COM port driver installation file, please visit Downloads section at www.nxp.com/automcdevkits.

- Run "Device Manager" on your system. Check which COM port was assigned to the CP210x COM port driver.
- Connect the USB cable to the MagniV MC9S12ZVML128 evaluation board and the host PC.
- 5 Connect the power supply to the MagniV MC9S12ZVML128 evaluation board.

- 6 Start the FreeMASTER project MC9S12ZVML128\_PMSM\_Sensorles s.pmp located in MTRCKTSPNZVM128\SW\ MC9S12ZVML128\_PMSM\_Sensorless project directory.
- Tenable communication by pressing the "STOP" button in the FreeMASTER, or by pressing "CTRL+K."
- Successful communication is signalized in the status bar. If the communication is not established, check the USB connection between the PC and MagniV MC9S12ZVML128 evaluation board, communication port and speed. The communication port and speed can be set in the Project\Options menu (or pressing "CTRL+T"). The communication speed must be set at 19200 Bd.

#### APPLICATION CONTROL

- When the power supply is connected to the evaluation board the PMSM motor is in stop mode. To start the motor use the user switch. Blue LED1 (D14) connected to port PS4) of the MC9S12ZVML128 evaluation board has the following functionality:
- OFF if the application is in the READY, INIT states
- Slow flashing if the application is in the
  - CALIB state (flashing with a period of 2 Hz)
  - ALIGN state (flashing with a period of 4 Hz)
- ON if the application is in the RUN state
- · Fast flashing if the application is in the
  - FAULT state (flashing with a period of 8 Hz)

- If no actual faults are present in the system, all the LED-like indicators on the FreeMASTER MCAT Control Page will be dark red. If there is a fault present, identify the source of the fault and remove it. Successful removal is signalized by the switching off of the respective LED-like indicator on the FreeMASTER MCAT Control Page.
- Press the UP and DOWN (SW1 + SW2) buttons on the MC9S12ZVML128 evaluation board simultaneously to clear the fault status register once in the FAULT state. The application can be restarted by positioning the ON/OFF switch (SW3) on the MC9S12ZVML128 evaluation board to the RUN position (transition from STOP to RUN in case the switch was in the RUN state when the fault event occurred).

#### APPLICATION CONTROL (CONT.)

If all the LED-like indicators on the FreeMASTER MCAT Control Page are off, clear pending faults by pressing the fault button "FAULT CLEAR" on the FreeMASTER MCAT Control Page, or alternatively by pressing the UP+DOWN buttons (SW2+SW1) on the MC9S12ZVML128 Evaluation Board simultaneously. The ON/OFF switch (SW3) on the MC9S12ZVML128 Evaluation Board must be in OFF position.

Start the application by pressing "RUN" on the (ON/OFF) button on the FreeMASTER MCAT Control Page or by positioning the ON/OFF switch (SW3) on the MC9S12ZVML128 evaluation board to the ON position (transition from OFF to ON in case the switch was in the ON state when a fault event occurred).

Enter the required speed by assigning this value to the "Speed Required" variable in the variables watch window or by clicking on the speed gauge on the FreeMASTER MCAT Control Page. The value is in revolutions per minute. Alternatively, the rotor speed can be increased/decreased by pressing the UP/DOWN switches on the MC9S12ZVML128 evaluation board.

This is the application by pressing "STOP" on the (ON/OFF) switch on the FreeMASTER MCAT Control Page, or by positioning the ON/OFF switch (SW3) on the MC9S12ZVML128 Evaluation Board to the OFF position.

JUMPER	OPTION	SETTING	DESCRIPTION
J2	CAN transceiver 5 V supply	OPEN	$V_{\tiny DDC}$ ballast transistor is not supplied from $V_{\tiny SUP}$
	option	*CLOSE*	$V_{\tiny DDC}$ ballast transistor is supplied from $V_{\tiny SUP}$
J3	V <sub>DDC</sub> supplied from USB option	*OPEN*	$\mathbf{V}_{\mathtt{DDC}}$ node is not supplied from the USB-to-SCI interface
		CLOSE	$\mathbf{V}_{\mathtt{DDC}}$ node is supplied from the USB-to-SCI interface
J4	RESET LED indicator option	OPEN	RESET LED indicator disabled
		*CLOSE*	RESET LED indicator enabled
J5	V <sub>DDX</sub> LED indicator option	OPEN	V <sub>DD</sub> LED indicator disabled
	·	*CLOSE*	V <sub>DD</sub> LED indicator enabled
J6	OSJTAG bootloader	OPEN	V <sub>SUP</sub> LED indicator disabled
	selection	*CLOSE*	V <sub>SUP</sub> LED indicator enabled

JUMPER	OPTION	SETTING	DESCRIPTION
J9	ON/OFF switch option	OPEN	ON/OFF switch disabled
		*CLOSE*	ON/OFF switch enabled
J10	OSDBM bootloader	*OPEN*	OSBDM boot-loader disabled
	option	CLOSE	OSBDM boot-loader enabled
J12	Resolver circuit 5 V supply option	OPEN	Resolver Inputs circuitry (+5VDC) supply disabled
		*CLOSE*	Resolver Inputs circuitry (+5VDC) supply enabled
J14	EVDD or FAULT selector	1–2	FAULT input is connected to port PP0
		*2-3*	Port PP0 is connected to EVDD at Hall sensor interface
J15	Resolver or Hall/ Encoder Phase A selector	*1-2*	Phase A from Resolver is connected to port PT1
		2–3	Phase A from Hall / Encoder interface is connected to port PT1

JUMPER	OPTION	SETTING	DESCRIPTION
J16	Resolver or Hall/ Encoder Phase	*1-2*	Phase B from Hall/Encoder interface is connected to port PT2
	B Selector	2–3	Phase B from Resolver is connected to port PT2
J18	USB-to-SCI interface supply	OPEN	USB-to-SCI isolator supply disable
	option	*CLOSE*	USB-to-SCI isolator supply enabled
J19	"UP" pushbutton option	OPEN	"UP" push button disabled
		*CLOSE*	"UP" push button enabled
J20	"DOWN" pushbutton option	OPEN	"DOWN" push button disabled
		*CLOSE*	"DOWN" push button enabled
J27	SCI RXD selector	1–2	RXD from OSBDM is connected to port PS2
		*2-3*	RXD from USB-to-SCI is connected to port PS2

JUMPER	OPTION	SETTING	DESCRIPTION
J28	SCI TXD selector	1–2	TXD from OSBDM is connected to port PS3
		*2-3*	TXD from USB-to-SCI is connected to port PS3
J29	BDM interface supply option	OPEN	BDM supply disabled
	Supply Sphon	*CLOSE*	BDM supply enabled
J30	ADC potentiometer pull-up option	OPEN	POT 1 (ADC potentiometer) supply disabled
		*CLOSE*	POT 1 (ADC potentiometer) supply enabled
J33	Microcontroller supply option	OPEN	MCU supply disabled
		*CLOSE*	MCU supply enabled
J35	ADC mapping– PAD0	*1-2*	Connects PAD0 to AMP0 external gain-setting resistors
		2–3	Connects PAD0 to POS_SIN resolver output

JUMPER	OPTION	SETTING	DESCRIPTION
J36	V <sub>REF</sub> generation supply option	OPEN	Disconnects $V_{\text{SUP}}$ to supply a regulated voltage at $V_{\text{REF2}}$
		*CLOSE*	Connects $V_{\text{SUP}}$ to supply a regulated voltage at $V_{\text{REF2}}$
J37	USER LED1 option	OPEN	"User LED1" disabled
		*CLOSE*	"User LED1" enabled
J38	PDO-PDOCLK	*OPEN*	PDO-PDOCLK not shorted
		CLOSE	PDO-PDOCLK shorted
J39	Resolver phase B selector	*1-2*	Pins 1-2 closed—SINCOS I/O connector Phase B connected to Resolver Phase B input
		2–3	Pins 2-3 closed—POS_COS connected to Resolver Phase B input
J40	V <sub>DDX</sub> ballast supply option	OPEN	V <sub>DDX</sub> ballast is disconnected
		*CLOSE*	V <sub>DDX</sub> ballast is connected

JUMPER	OPTION	SETTING	DESCRIPTION
J43	Resolver circuit 12 V supply option	OPEN	Resolver generator circuit supply disconnected
		*CLOSE*	Resolver generator circuit supply connected
J44	ADC mapping – PAD1	OPEN	PAD1 is disconnected from the AMPM0 external gain-setting resistors
		*CLOSE*	PAD1 is connected to the AMPM0 external gain-setting resistors
J45	ADC mapping – PAD2	OPEN	PAD2 is disconnected from the AMPP0 external gain-setting resistors
		*CLOSE*	PAD2 is connected to the AMPP0 external gain- setting resistors
J46	ADC mapping – PAD3	*1–2*	Connects PAD3 to ADC_IA (phase A current sense from external op-amp)
		2–3	Connects PAD3 to POS_SIN resolver output

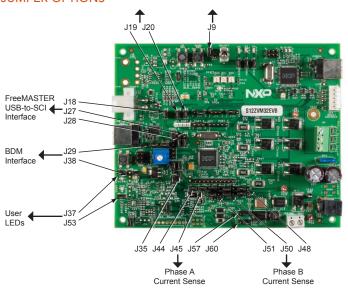
JUMPER	OPTION	SETTING	DESCRIPTION
J47	ADC mapping— PAD4	*1–2*	Connects PAD4 to ADC_IB (phase B current sense from external op-amp)
		2–3	Connects PAD4 to ADC potentiometer POT1
J48	ADC mapping— PAD5	*1-2*	Connects PAD5 to AMP1 external gain setting resistors
		2–3	Connects PAD5 to ADC_IB (phase B current sense from external op-amp)
J49	Resolver phase A selector	*1-2*	Resolver phase A connected to SINCOS I/O connector Phase A input
		2–3	Resolver phase A connected to Resolver POS_ SIN Schmitt-Trigger
J50	ADC mapping— PAD6	*1-2*	Connects PAD6 to AMPM1 external gain-setting resistors
		2–3	Connects PAD6 to POS_COS resolver output

JUMPER	OPTION	SETTING	DESCRIPTION
J51/42	ADC mapping— PAD7	*J51 (1–2)*	Connects PAD7 to AMPP1 external gain-setting resistors
		J51 (2–3)	Connects PAD7 to POS_SIN resolver output
		J42 (1) – J51 (2)	Connects PAD7 to ADC potentiometer POT1
J52	ADC mapping— PAD8	*1–2*	Connects PAD8 to ADC_IC (phase C current sense from external op-amp)
		2–3	Connects PAD8 to POS_COS resolver output
J53	USER LED2 option	OPEN	"User LED 2" disabled
	•	*CLOSE*	"User LED 2" enabled
J55	V <sub>REF</sub> selector	*1–2*	$V_{\rm REF}$ supplied from $V_{\rm DDX}$
		2–3	$V_{\text{REF}}$ supplied from the $V_{\text{REF2}}$ regulator

JUMPER	OPTION	SETTING	DESCRIPTION
J56	Resolver COS reference	*1-2*	Input to POS_COS circuit is from OFFSET1
		2–3	Input to POS_COS circuit is from RES_COS_REF
J57	Internal AMP0 input selector (inverting)	*1-2*	Connects DC Bus to the internal AMP0 inverting input (Phase A current sense)
		2–3	Connects Ground to the internal AMP0 inverting input (DC Bus current sense)
J59	Resolver SIN reference	*1-2*	Input to POS_SIN circuit is from RES_SIN_REF
		2–3	Input to POS_SIN circuit is from OFFSET1
J60	Internal AMP0 input selector (non-inverting)	*1-2*	Connects Phase A to the internal AMP0 noninverting input (Phase A Current sense)
		2–3	Connects DC Bus as non-inverting input for internal AMP0 (DC Bus current sense)

JUMPER	OPTION	SETTING	DESCRIPTION
J63	FAULT comparators 5 V	OPEN	FAULT circuit supply disconnected
	supply option	*CLOSE*	FAULT circuit supply connected

### MagniV MC9S12ZVML128 EVALUATION BOARD JUMPER OPTIONS



Front side of MagniV MC9S12ZVML128

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#### WARRANTY

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