Ehipsmall

Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from,Europe,America and south Asia,supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of "Quality Parts,Customers Priority,Honest Operation,and Considerate Service",our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip,ALPS,ROHM,Xilinx,Pulse,ON,Everlight and Freescale. Main products comprise IC,Modules,Potentiometer,IC Socket,Relay,Connector.Our parts cover such applications as commercial,industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!

Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China

Fixed Frequency Current Mode Controller for Flyback Converters

The NCP1240 is a new fixed−frequency current−mode controller featuring the Dynamic Self−Supply. This function greatly simplifies the design of the auxiliary supply and the V_{CC} capacitor by activating the internal startup current source to supply the controller during start−up, transients, latch, stand−by etc. This device contains a special HV detector which detect the application unplug from the AC input line and triggers the X2 discharge current. This HV structure allows the brown−out detection as well.

It features a timer−based fault detection that ensures the detection of overload and an adjustable compensation to help keep the maximum power independent of the input voltage.

Due to frequency foldback, the controller exhibits excellent efficiency in light load condition while still achieving very low standby power consumption. Internal frequency jittering, ramp compensation, and a versatile latch input make this controller an excellent candidate for the robust power supply designs.

A dedicated Off mode allows to reach the extremely low no load input power consumption via "sleeping" whole device and thus minimize the power consumption of the control circuitry.

Features

- Fixed−Frequency Current−Mode Operation (65 kHz and 100 kHz frequency options)
- Frequency Foldback then Skip Mode for Maximized Performance in Light Load and Standby Conditions
- Timer−Based Overload Protection with Latched (Options A and E) or Auto−Recovery (Options B and F) Operation
- High−voltage Current Source with Brown−Out Detection and Dynamic Self–Supply, Simplifying the Design of the V_{CC} Circuitry
- Frequency Modulation for Softened EMI Signature
- Adjustable Overpower Protection Dependant on the Bulk Voltage
- Latch−off Input Combined with the Overpower Protection Sensing Input
- V_{CC} Operation up to 28 V, With Overvoltage Detection
- 500/800 mA Source/Sink Drive Peak Current Capability
- 10 ms Soft−Start
- Internal Thermal Shutdown
- No−Load Standby Power < 30 mW
- X2 Capacitor in EMI Filter Discharging Feature
- These Devices are Pb−Free and Halogen Free/BFR Free

ON Semiconductor®

www.onsemi.com

1 | 8 5 3 4 (Top View) Latch CS HV **PIN CONNECTIONS** 6 FB 2 GND | 4 | | 5 | DRV V_{CC}

ORDERING INFORMATION

See detailed ordering and shipping information on page 44 of this data sheet.

Typical Applications

- AC−DC Adapters for Notebooks, LCD, and Printers
- Offline Battery Chargers
- Consumer Electronic Power Supplies
- Auxiliary/Housekeeping Power Supplies
- Offline Adapters for Notebooks

TYPICAL APPLICATION EXAMPLE

Figure 1. Flyback Converter Application Using the NCP1240

OPTIONS

PIN FUNCTION DESCRIPTION

SIMPLIFIED INTERNAL BLOCK SCHEMATIC

MAXIMUM RATINGS

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

1. This device contains latch-up protection and exceeds 100 mA per JEDEC Standard JESD78.
2. As mounted on a 80 x 100 x 1.5 mm FR4 substrate with a single layer of 50 mm² of 2 oz copper traces and heat spreading area. As for a JEDEC 51-1 conductivity test PCB. Test conditions were under natural convection or zero air flow.

3. As mounted on a 80 x 100 x 1.5 mm FR4 substrate with a single layer of 100 mm² of 2 oz copper traces and heat spreading area. As specified for a JEDEC 51-2 conductivity test PCB. Test conditions were under natural convection or zero air flow.

4. As mounted on a 80 x 100 x 1.5 mm FR4 substrate with a single layer of 650 mm² of 2 oz copper traces and heat spreading area. As specified for a JEDEC 51-3 conductivity test PCB. Test conditions were under natural convection or zero air flow.

Characteristics Test Condition Symbol Min Typ Max Unit

ELECTRICAL CHARACTERISTICS (For typical values $T_J = 25^\circ C$, for min/max values $T_J = -40^\circ C$ to +125 $\circ C$, V_{HV} = 125 V,

SUPPLY

5. $V_{CC(off)} < V_{CC(min)}$ with the minimum gap 0.5 V.

6. Internal supply current only, currents sourced via FB pin is not included (current is flowing in GND pin only).

7. Guaranteed by design.

8. CS pin source current is a sum of I_{bias} and I_{OPC} , thus at V_{HV} = 125 V is observed the I_{bias} only, because I_{OPC} is switched off.

5. V_{CC(off)} < V_{CC(min)} with the minimum gap 0.5 V.
6. Internal supply current only, currents sourced via FB pin is not included (current is flowing in GND pin only).

7. Guaranteed by design.

8. CS pin source current is a sum of I_{bias} and I_{OPC}, thus at V_{HV} = 125 V is observed the I_{bias} only, because I_{OPC} is switched off.

ELECTRICAL CHARACTERISTICS (For typical values T_J = 25°C, for min/max values T_J = −40°C to +125°C, V_{HV} = 125 V, V_{CC} = 11 V unless otherwise noted)

5. V_{CC(off)} < V_{CC(min)} with the minimum gap 0.5 V.
6. Internal supply current only, currents sourced via FB pin is not included (current is flowing in GND pin only).

7. Guaranteed by design.

8. CS pin source current is a sum of I_{bias} and I_{OPC}, thus at V_{HV} = 125 V is observed the I_{bias} only, because I_{OPC} is switched off.

ELECTRICAL CHARACTERISTICS (For typical values T_J = 25°C, for min/max values T_J = −40°C to +125°C, V_{HV} = 125 V, V_{CC} = 11 V unless otherwise noted)

TEMPERATURE SHUTDOWN

5. V_{CC(off)} < V_{CC(min)} with the minimum gap 0.5 V.
6. Internal supply current only, currents sourced via FB pin is not included (current is flowing in GND pin only).

7. Guaranteed by design.

8. CS pin source current is a sum of I_{bias} and I_{OPC} , thus at V_{HV} = 125 V is observed the I_{bias} only, because I_{OPC} is switched off.

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

APPLICATION INFORMATION

Functional Description

The NCP1240 includes all necessary features to build a safe and efficient power supply based on a fixed−frequency flyback converter. The NCP1240 is a multimode controller as illustrated in Figure 45. The mode of operation depends upon line and load condition. Under all modes of operation, the NCP1240 terminates the DRV signal based on the switch current. Thus, the NCP1240 always operates in current mode control so that the power MOSFET current is always limited.

Under normal operating conditions, the FB pin commands the operating mode of the NCP1240 at the voltage thresholds shown in Figure 45. At normal rated operating loads (from 100% to approximately 33% full rated power) the NCP1240 controls the converter in fixed frequency PWM mode. It can operate in the continuous conduction mode (CCM) or discontinuous conduction mode (DCM) depending upon the input voltage and loading conditions. If the controller is used in CCM with a wide input voltage

range, the duty−ratio may increase up to 50%. The build−in slope compensation prevents the appearance of sub−harmonic oscillations in this operating area.

The converter operates in frequency foldback mode (FFM) for loads that are between approximately 17% and 48% of full rated power.

Effectively, operation in FFM results in the application of constant volt−seconds to the flyback transformer each switching cycle. Voltage regulation in FFM is achieved by varying the switching frequency in the range from 65 kHz (or 100 kHz) to 27 kHz. For extremely light loads (below approximately 6% full rated power), the converter is controlled using bursts of 27 kHz pulses. This mode is called as skip mode. The FFM, keeping constant peak current and skip mode allows design of the power supplies with increased efficiency under the light loading conditions. Keep in mind that the aforementioned boundaries of steady−state operation are approximate because they are subject to converter design parameters.

There was implemented the low consumption off mode allowing to reach extremely low no load input power. This mode is controlled by the FB pin and allows the remote control (or secondary side control) of the power supply shut−down. Most of the device internal circuitry is unbiased in the low consumption off mode. Only the FB pin control circuitry and X2 cap discharging circuitry is operating in the low consumption off mode. If the voltage at feedback pin decreases below the 0.6 V the controller will enter the low consumption off mode. The controller can start if the FB pin voltage increases above the 2.2 V level.

See the detailed status diagrams for the versions fully latched A and the autorecovery B on the following figures. The basic status of the device after wake–up by the V_{CC} is the off mode and mode is used for the overheating protection mode if the thermal shutdown protection is activated.

www.onsemi.com www.onsemi.com
17

The information about the fault (permanent Latch or Autorecovery) is kept during the low consumption off mode due the safety reason. The reason is not to allow unlatch the device by the remote control being in off mode.

Start−up of the Controller

At start−up, the current source turns on when the voltage on the HV pin is higher than $V_{\text{HV}(min)}$, and turns off when V_{CC} reaches $V_{CC(on)}$, then turns on again when V_{CC} reaches $V_{CC(min)}$, until the input voltage is high enough to ensure a proper start–up, i.e. when V_{HV} reaches $V_{HV(stat)}$. The controller actually starts the next time V_{CC} reaches $V_{CC(on)}$. The controller then delivers pulses, starting with a soft−start period t_{SSTART} during which the peak current linearly increases before the current−mode control takes over.

Even though the Dynamic Self−Supply is able to maintain the V_{CC} voltage between V_{CC(on)} and V_{CC(min)} by turning the HV start−up current source on and off, it can only be used in light load condition, otherwise the power dissipation on the die would be too much. As a result, an auxiliary voltage source is needed to supply V_{CC} during normal operation.

The Dynamic Self−Supply is useful to keep the controller alive when no switching pulses are delivered, e.g. in brown−out condition, or to prevent the controller from stopping during load transients when the V_{CC} might drop. The NCP1240 accepts a supply voltage as high as 28 V, with an overvoltage threshold $V_{CC(ovp)}$ that latches the controller off.

Figure 48. VCC Start−up Timing Diagram

For safety reasons, the start−up current is lowered when V_{CC} is below $V_{CC(inhibit)}$, to reduce the power dissipation in case the V_{CC} pin is shorted to GND (in case of V_{CC} capacitor failure, or external pull-down on V_{CC} to disable the controller). There is only one condition for which the current source doesn't turn on when V_{CC} reaches $V_{CC (inhibit)}$: the voltage on HV pin is too low (below V_{HV(min)}).

HV Sensing of Rectified AC Voltage

The NCP1240 features on its HV pin a true ac line monitoring circuitry. It includes a minimum start−up threshold and an autorecovery brown−out protection; both of them independent of the ripple on the input voltage. It is allowed only to work with an unfiltered, rectified ac input to ensure the X2 capacitor discharge function as well, which is described in following. The brown−out protection thresholds are fixed, but they are designed to fit most of the standard ac−dc conversion applications.

When the input voltage goes below $V_{\text{HV}(stop)}$, a brown−out condition is detected, and the controller stops. The HV current source maintains V_{CC} at $V_{CC(min)}$ level until the input voltage is back above $V_{\text{HV}(\text{start})}$.

Figure 49. Ac Line Drop−out Timing Diagram

Figure 50. VCC Collapses After Overload and Its Recovery

Figure 51. Ac Line Drop−out Timing Diagram with Parasitic Spike

When V_{HV} crosses the $V_{\text{HV}(\text{start})}$ threshold, the controller can start immediately. When it crosses $V_{HV(\text{stop})}$, it triggers a timer of duration t _{HV}, this ensures that the controller doesn't stop in case of line cycle drop−out. The device restart after the ac line voltage drop-out is protected to the parasitic restart initiated e.g. the spikes induced at HV pin

immediately after the device is stopped by the residual energy in the EMI filter. The device restart is allowed only after the 1st watch dog signal event. The basic principle is shown at Figure 49 and detail of the device restart is shown at Figure 52.

Figure 52. Detailed Timing Diagram of the Device Restart After the Short ac Line Drop−out

X2 Cap Discharge Feature

The X2 capacitor discharging feature is offered by usage of the NCP1240. This feature saves approximately 16 mW − 25 mW input power depending on the EMI filter X2 capacitors volume and it saves the external components count as well. The discharge feature is ensured via the start−up current source with a dedicated control circuitry for this function. The X2 capacitors are being discharged by current defined as I_{start2} when this discharge event is detected.

There is used a dedicated structure called ac line unplug detector inside the X2 capacitor discharge control circuitry. See the Figure 53 for the block diagram for this structure and Figures 54, 55, 56 and 57 for the timing diagrams. The basic idea of ac line unplug detector lies in comparison of the direct sample of the high voltage obtained via the high voltage sensing structure with the delayed sample of the high voltage. The delayed signal is created by the sample & hold structure.

The comparator used for the comparison of these signals is without hysteresis inside. The resolution between the slopes of the ac signal and dc signal is defined by the sampling time T_{SAMPL} and additional internal offset N_{OS}. These parameters ensure the noise immunity as well. The additional offset is added to the picture of the sampled HV signal and its analog sum is stored in the C_1 storage capacitor. If the voltage level of the HV sensing structure output crosses this level the comparator CMP output signal resets the detection timer and no dc signal is detected. The additional offset N_{OS} can be measured as the $V_{HV(hvst)}$ on the HV pin. If the comparator output produces pulses it means that the slope of input signal is higher than set resolution level and the slope is positive. If the comparator output produces the low level it means that the slope of input signal is lower than set resolution level or the slope is negative. There is used the detection timer which is reset by any edge of the comparator output. It means if no edge comes before the timer elapses there is present only dc signal or signal with the small ac ripple at the HV pin. This type of the ac detector detects only the positive slope, which fulfils the requirements for the ac line presence detection.

In case of the dc signal presence on the high voltage input, the direct sample of the high voltage obtained via the high voltage sensing structure and the delayed sample of the high voltage are equivalent and the comparator produces the low level signal during the presence of this signal. No edges are present at the output of the comparator, that's why the detection timer is not reset and dc detect signal appears.

The minimum detectable slope by this ac detector is given by the ration between the maximum hysteresis observed at HV pin $V_{HV(hyst),max}$ and the sampling time:

$$
S_{min} = \frac{V_{HV(hyst),max}}{T_{sample}}
$$
 (eq. 1)

Than it can be derived the relationship between the minimum detectable slope and the amplitude and frequency of the sinusoidal input voltage:

$$
V_{\text{max}} = \frac{V_{\text{HV(hyst),max}}}{2 \cdot \pi \cdot f \cdot T_{\text{sample}}} = \frac{5}{2 \cdot \pi \cdot 35 \cdot 1 \cdot 10^{-3}} \text{ (eq. 2)}
$$

= 22.7 V

The minimum detectable AC RMS voltage is 16 V at frequency 35 Hz, if the maximum hysteresis is 5 V and sampling time is 1 ms.

The X2 capacitor discharge feature is available in any controller operation mode to ensure this safety feature. The detection timer is reused for the time limiting of the discharge phase, to protect the device against overheating. The discharging process is cyclic and continues until the ac line is detected again or the voltage across the X2 capacitor is lower than $V_{HV(min)}$. This feature ensures to discharge quite big X2 capacitors used in the input line filter to the safe level. **It is important to note that it is not allowed to connect HV pin to any dc voltage due this feature. e.g. directly to bulk capacitor.**

During the HV sensing or $X2$ cap discharging the V_{CC} net is kept above the V_{CC(off)} voltage by the Self-Supply in any mode of device operation to supply the control circuitry. During the discharge sequence is not allowed to start−up the device.

Figure 53. The ac Line Unplug Detector Structure Used for X2 Capacitor Discharge System

Figure 54. The ac Line Unplug Detector Timing Diagram