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Fixed Frequency Current Mode Controller for Flyback Converters

The NCP1244 is a new fixed–frequency current–mode controller featuring the Dynamic Self–Supply. This function greatly simplifies the design of the auxiliary supply and the V_{CC} capacitor by activating the internal startup current source to supply the controller during start–up, transients, latch, stand–by etc. This device contains a special HV detector which detect the application unplug from the AC input line and triggers the X2 discharge current.

It features a timer-based fault detection that ensures the detection of overload and an adjustable compensation to help keep the maximum power independent of the input voltage.

Due to frequency foldback, the controller exhibits excellent efficiency in light load condition while still achieving very low standby power consumption. Internal frequency jittering, ramp compensation, and a versatile latch input make this controller an excellent candidate for the robust power supply designs.

A dedicated Off mode allows to reach the extremely low no load input power consumption via "sleeping" whole device and thus minimize the power consumption of the control circuitry.

Features

- Fixed–Frequency Current–Mode Operation (65 kHz and 100 kHz frequency options)
- Frequency Foldback then Skip Mode for Maximized Performance in Light Load and Standby Conditions
- Timer-Based Overload Protection with Latched (Option A) or Auto-Recovery (Option B) Operation
- High-voltage Current Source with Dynamic Self-Supply, Simplifying the Design of the V_{CC} Circuitry
- Frequency Modulation for Softened EMI Signature
- Adjustable Overpower Protection Dependant on the Bulk Voltage
- Latch-off Input Combined with the Overpower Protection Sensing Input
- V_{CC} Operation up to 28 V, With Overvoltage Detection
- 500/800 mA Source/Sink Drive Peak Current Capability
- 10 ms Soft-Start
- Internal Thermal Shutdown
- No-Load Standby Power < 30 mW
- X2 Capacitor in EMI Filter Discharging Feature
- These Devices are Pb-Free and Halogen Free/BFR Free



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MARKING DIAGRAM



SOIC-7 CASE 751U



44Xfff = Specific Device Code

X = A or B

fff = 065 or 100

A = Assembly Location

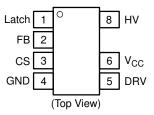
= Wafer Lot

′ = Year

W = Work Week

■ = Pb-Free Package

PIN CONNECTIONS



ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 39 of this data sheet.

Typical Applications

- AC-DC Adapters for Notebooks, LCD, and Printers
- Offline Battery Chargers
- Consumer Electronic Power Supplies
- Auxiliary/Housekeeping Power Supplies
- Offline Adapters for Notebooks

TYPICAL APPLICATION EXAMPLE

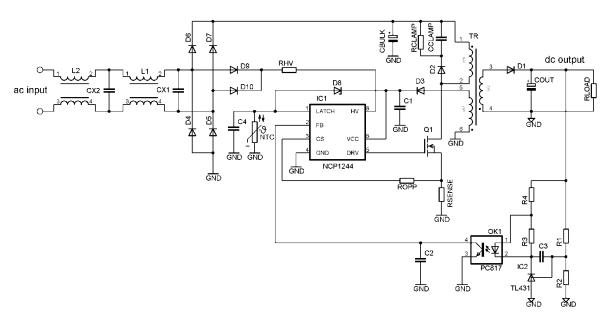


Figure 1. Flyback Converter Application Using the NCP1244

PIN FUNCTION DESCRIPTION

Pin No	Pin Name	Function	Pin Description
1	LATCH	Latch-Off Input	Pull the pin up or down to latch-off the controller. An internal current source allows the direct connection of an NTC for over temperature detection.
2	FB	Feedback + Shutdown pin	An optocoupler collector to ground controls the output regulation. The part goes to the low consumption Off mode if the FB input pin is pulled to GND.
3	CS	Current Sense	This Input senses the Primary Current for current–mode operation, and offers an overpower compensation adjustment.
4	GND	-	The controller ground
5	DRV	Drive output	Drives external MOSFET
6	VCC	VCC input	This supply pin accepts up to 28 Vdc, with overvoltage detection. The pin is connected to an external auxiliary voltage. It is not allowed to connect another circuit to this pin to keep low input power consumption.
8	HV	High-voltage pin	Connects to the rectified AC line to perform the functions of Start–up Current Source, Self–Supply and X2 capacitor discharge function and the HV sensing for the overpower protection purposes. It is not allowed to connect this pin to DC voltage.

SIMPLIFIED INTERNAL BLOCK SCHEMATIC

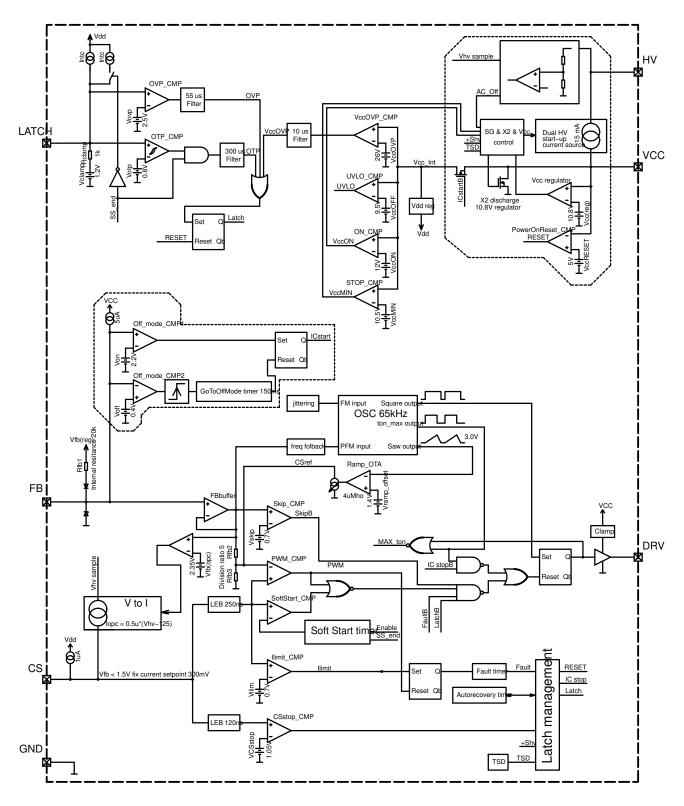


Figure 2. Simplified Internal Block Schematic

MAXIMUM RATINGS

Rating	Symbol	Value	Unit
DRV (pin 5)	Maximum voltage on DRV pin (Dc-Current self-limited if operated within the allowed range) (Note 1)	-0.3 to 20 ±1000 (peak)	V mA
V _{CC} (pin 6)	V _{CC} Power Supply voltage, V _{CC} pin, continuous voltage Power Supply voltage, V _{CC} pin, continuous voltage (Note 1)	-0.3 to 28 ±30 (peak)	V mA
HV (pin 8)	Maximum voltage on HV pin (Dc-Current self-limited if operated within the allowed range)	−0.3 to 500 ±20	V mA
V _{max}	Maximum voltage on low power pins (except pin 5, pin 6 and pin 8) (Dc-Current self-limited if operated within the allowed range) (Note 1)	-0.3 to 10 ±10 (peak)	V mA
$R_{\theta J-A}$	Thermal Resistance SOIC-7 Junction-to-Air, low conductivity PCB (Note 2) Junction-to-Air, medium conductivity PCB (Note 3) Junction-to-Air, high conductivity PCB (Note 4)	162 147 115	°C/W
$R_{\theta J-C}$	Thermal Resistance Junction-to-Case	73	°C/W
T _{JMAX}	Operating Junction Temperature	-40 to +150	°C
T _{STRGMAX}	Storage Temperature Range	-60 to +150	°C
	ESD Capability, HBM model (All pins except HV) per JEDEC Standard JESD22, Method A114E	> 2000	V
	ESD Capability, Machine Model per JEDEC Standard JESD22, Method A115A	> 200	V
	ESD Capability, Charged Device Model per JEDEC Standard JESD22, Method C101E	> 1000	V

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

- 1. This device contains latch-up protection and exceeds 100 mA per JEDEC Standard JESD78.
- 2. As mounted on a 80 x 100 x 1.5 mm FR4 substrate with a single layer of 50 mm² of 2 oz copper traces and heat spreading area. As specified for a JEDEC 51-1 conductivity test PCB. Test conditions were under natural convection or zero air flow.
- 3. As mounted on a 80 x 100 x 1.5 mm FR4 substrate with a single layer of 100 mm² of 2 oz copper traces and heat spreading area. As specified for a JEDEC 51-2 conductivity test PCB. Test conditions were under natural convection or zero air flow.
- As mounted on a 80 x 100 x 1.5 mm FR4 substrate with a single layer of 650 mm² of 2 oz copper traces and heat spreading area. As specified for a JEDEC 51-3 conductivity test PCB. Test conditions were under natural convection or zero air flow.

ELECTRICAL CHARACTERISTICS (For typical values $T_J = 25$ °C, for min/max values $T_J = -40$ °C to +125°C, $V_{HV} = 125$ V, $V_{CC} = 11 \text{ V unless otherwise noted}$

Characteristics	Test Condition	Symbol	Min	Тур	Max	Unit
HIGH VOLTAGE CURRENT SOURCE	•					
Minimum voltage for current source operation		V _{HV(min)}	-	30	40	V
Current flowing out of V _{CC} pin	$V_{CC} = 0 \text{ V}$ $V_{CC} = V_{CC(on)} - 0.5 \text{ V}$	I _{start1} I _{start2}	0.2 5	0.5 8	0.8 11	mA
Off-state leakage current	V _{HV} = 500 V, V _{CC} = 15 V	I _{start(off)}	10	25	50	μΑ
Off-mode HV supply current	V_{HV} = 141 V, V_{HV} = 325 V, V_{CC} loaded by 4.7 μ F cap	l _{HV(off)}	1 1	45 50	60 70	μΑ
SUPPLY						
HV current source regulation threshold		V _{CC(reg)}	8	11	-	V
Turn-on threshold level, V _{CC} going up HV current source stop threshold		V _{CC(on)}	11.0	12.0	13.0	V
HV current source restart threshold		$V_{CC(min)}$	9.5	10.5	11.5	V
Turn-off threshold		$V_{CC(off)}$	8.5	8.9	9.3	V
Overvoltage threshold		$V_{CC(ovp)}$	25	26.5	28	V
Blanking duration on $V_{CC(off)}$ and $V_{CC(ovp)}$ detection		t _{VCC(blank)}	-	10	-	μS
V _{CC} decreasing level at which the internal logic resets		V _{CC(reset)}	4.8	7.0	7.7	V
V _{CC} level for I _{START1} to I _{START2} transition		V _{CC(inhibit)}	0.2	0.8	1.25	V
Internal current consumption (Note 5)	DRV open, $V_{FB} = 3 \text{ V}$, 65 kHz DRV open, $V_{FB} = 3 \text{ V}$, 100 kHz	I _{CC1} I _{CC1}	1.3 1.3	1.85 1.85	2.2 2.2	mA
	Cdrv = 1 nF, V_{FB} = 3 V, 65 kHz Cdrv = 1 nF, V_{FB} = 3 V, 100 kHz	I _{CC2} I _{CC2}	1.8 2.3	2.6 2.9	3.0 3.5	
	Off manda (alice on bafaire about inn)	I _{CC3}	0.67	0.9	1.13	
	Off mode (skip or before start-up) Fault mode (fault or latch)	I _{CC4}	0.3	0.6	0.9	
X2 DISCHARGE				•	•	•
Comparator hysteresis observed at HV pin		V _{HV(hyst)}	1.5	3.5	5	V
HV signal sampling period		T _{sample}	-	1.0	-	ms
Timer duration for no line detection		t _{DET}	21	32	43	ms
Discharge timer duration		t _{DIS}	21	32	43	ms
OSCILLATOR						
Oscillator frequency		fosc	58 87	65 100	72 109	kHz
Maximum on time for $T_J = 25^{\circ}C$ to $+125^{\circ}C$ only	f _{OSC} = 65 kHz f _{OSC} = 100 kHz	t _{ONmax} (65kHz) t _{ONmax} (100kHz)	11.5 7.5	12.3 8.0	13.1 8.5	μS
Maximum on time	$f_{OSC} = 65 \text{ kHz}$ $f_{OSC} = 100 \text{ kHz}$	t _{ONmax} (65kHz) t _{ONmax} (100kHz)	11.3 7.4	12.3 8.0	13.1 8.5	μS
Maximum duty cycle (corresponding to maximum on time at maximum switching frequency)	f _{OSC} = 65 kHz f _{OSC} = 100 kHz	D _{MAX}	ı	80	-	%

Internal supply current only, currents sourced via FB pin is not included (current is flowing in GND pin only).
 Guaranteed by design.
 CS pin source current is a sum of I_{bias} and I_{OPC}, thus at V_{HV} = 125 V is observed the I_{bias} only, because I_{OPC} is switched off.

ELECTRICAL CHARACTERISTICS (For typical values $T_J = 25^{\circ}C$, for min/max values $T_J = -40^{\circ}C$ to $+125^{\circ}C$, $V_{HV} = 125$ V, $V_{CC} = 11$ V unless otherwise noted)

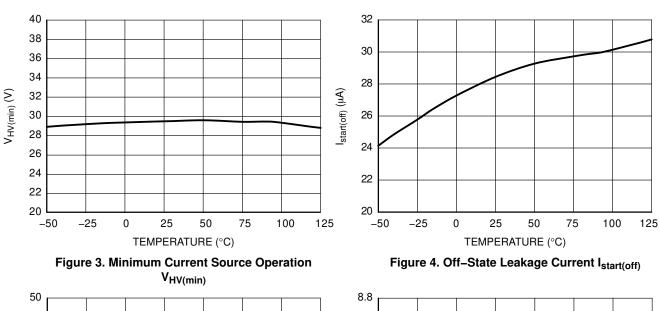
Characteristics	Test Condition	Symbol	Min	Тур	Max	Unit
OSCILLATOR						
Frequency jittering amplitude, in percentage of F_{OSC}		A _{jitter}	±4	±6	±8	%
Frequency jittering modulation frequency		F _{jitter}	85	125	165	Hz
FREQUENCY FOLDBACK						
Feedback voltage threshold below which frequency foldback starts		V _{FB(foldS)}	1.8	2.0	2.2	V
Feedback voltage threshold below which frequency foldback is complete		V _{FB(foldE)}	0.8	0.9	1.0	٧
Minimum switching frequency	$V_{FB} = V_{skip(in)} + 0.1$	f _{OSC(min)}	23	27	32	kHz
OUTPUT DRIVER						
Rise time, 10 to 90% of V _{CC}	$V_{CC} = V_{CC(min)} + 0.2 \text{ V},$ $C_{DRV} = 1 \text{ nF}$	t _{rise}	-	40	70	ns
Fall time, 90 to 10% of V_{CC}	$V_{CC} = V_{CC(min)} + 0.2 \text{ V},$ $C_{DRV} = 1 \text{ nF}$	t _{fall}	-	40	70	ns
Current capability	$\begin{aligned} V_{CC} &= V_{CC(min)} + 0.2 \text{ V,} \\ C_{DRV} &= 1 \text{ nF} \\ DRV \text{ high, } V_{DRV} &= 0 \text{ V} \\ DRV \text{ low, } V_{DRV} &= V_{CC} \end{aligned}$	I _{DRV} (source) I _{DRV} (sink)	- -	500 800	_ _	mA
Clamping voltage (maximum gate voltage)	$V_{CC} = V_{CCmax} - 0.2 \text{ V, DRV high,}$ $R_{DRV} = 33 \text{ k}\Omega, C_{load} = 220 \text{ pF}$	V _{DRV(clamp)}	11	13.5	16	٧
High-state voltage drop	$\begin{aligned} &V_{CC} = V_{CC(min)} + 0.2 \text{ V}, \\ &R_{DRV} = 33 \text{ k}\Omega, \text{ DRV high} \end{aligned}$	V _{DRV(drop)}	-	_	1	V
CURRENT SENSE						
Input Pull-up Current	V _{CS} = 0.7 V	I _{bias}	-	1	-	μΑ
Maximum internal current setpoint	V _{FB} > 3.5 V	V _{ILIM}	0.66	0.70	0.74	V
Propagation delay from $V_{\mbox{\scriptsize llimit}}$ detection to DRV off	$V_{CS} = V_{ILIM}$	t _{delay}	-	80	110	ns
Leading Edge Blanking Duration for V_{ILIM}		t _{LEB}	200	250	320	ns
Threshold for immediate fault protection activation		V _{CS(stop)}	0.95	1.05	1.15	V
Leading Edge Blanking Duration for $V_{\mbox{CS(stop)}}$ (Note 6)		t _{BCS}	90	120	150	ns
Soft-start duration	From 1 st pulse to V _{CS} = V _{ILIM}	t _{SSTART}	8	11	14	ms
Frozen current setpoint		V _{I(freeze)}	275	300	325	mV
INTERNAL SLOPE COMPENSATION						
Slope of the compensation ramp		S _{comp(65kHz)} S _{comp(100kHz)}		-32.5 -50	- -	mV / μs
FEEDBACK						
Internal pull-up resistor	$T_J = 25^{\circ}C$	R _{FB(up)}	15	20	25	kΩ
V _{FB} to internal current setpoint division ratio		K _{FB}	4.7	5	5.3	_
Internal pull-up voltage on the FB pin (Note 6)		V _{FB(ref)}	4.5	5	5.5	V
Feedback voltage below which the peak current is frozen		V _{FB(freeze)}	1.35	1.5	1.65	V

- Internal supply current only, currents sourced via FB pin is not included (current is flowing in GND pin only).
 Guaranteed by design.
 CS pin source current is a sum of I_{bias} and I_{OPC}, thus at V_{HV} = 125 V is observed the I_{bias} only, because I_{OPC} is switched off.

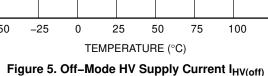
 $\textbf{ELECTRICAL CHARACTERISTICS} \text{ (For typical values } T_J = 25^{\circ}\text{C}, \text{ for min/max values } T_J = -40^{\circ}\text{C to } + 125^{\circ}\text{C}, \text{ V}_{HV} = 125 \text{ V}, \text{ } 125^{\circ}\text{C}, \text{ } 125^{\circ}\text{$ $V_{CC} = 11 \text{ V unless otherwise noted}$

Characteristics	Test Condition	Symbol	Min	Тур	Max	Unit
SKIP CYCLE MODE		•		•	-	-
Feedback voltage thresholds for skip mode	$ m V_{FB}$ going down $ m V_{FB}$ going up	$V_{skip(in)} \ V_{skip(out)}$	0.63 0.72	0.70 0.80	0.77 0.88	V
REMOTE CONTROL ON FB PIN						
The voltage above which the part enters the on mode	$V_{CC} > V_{CC(off)}, V_{HV} = 60 \text{ V}$	V _{ON}	_	2.2	_	V
The voltage below which the part enters the off mode	$V_{CC} > V_{CC(off)}$	V _{OFF}	0.35	0.40	0.45	V
Minimum hysteresis between the V _{ON} and V _{OFF}	$V_{CC} > V_{CC(off)}, V_{HV} = 60 \text{ V}$	V _{HYST}	500	_	_	mV
Pull-up current in off mode	$V_{CC} > V_{CC(off)}$	I _{OFF}	-	5	-	μΑ
Go To Off mode timer	$V_{CC} > V_{CC(off)}$	t _{GTОМ}	500	600	700	ms
OVERLOAD PROTECTION						
Fault timer duration		t _{fault}	108	128	178	ms
Autorecovery mode latch-off time duration		t _{autorec}	0.85	1.00	1.35	S
OVERPOWER PROTECTION						
V _{HV} to I _{OPC} conversion ratio		K _{OPC}	-	0.54	-	$\mu A / V$
Current flowing out of CS pin (Note 7)	V _{HV} = 125 V V _{HV} = 162 V V _{HV} = 325 V V _{HV} = 365 V	IOPC(125) IOPC(162) IOPC(325) IOPC(365)	- - - 105	0 20 110 130	- - - 150	μΑ
FB voltage above which I _{OPC} is applied	V _{HV} = 365 V	V _{FB(OPCF)}	2.12	2.35	2.58	V
FB voltage below which is no I _{OPC} applied	V _{HV} = 365 V	V _{FB(OPCE)}	-	2.15	_	٧
LATCH-OFF INPUT		, ,				
High threshold	V _{Latch} going up	V _{OVP}	2.35	2.5	2.65	٧
Low threshold	V _{Latch} going down	V _{OTP}	0.76	0.8	0.84	٧
Current source for direct NTC connection During normal operation During soft–start	$V_{Latch} = 0 V$	I _{NTC}	65 130	95 190	105 210	μΑ
Blanking duration on high latch detection	65 kHz version 100 kHz version	t _{Latch(OVP)}	35 20	50 35	70 50	μS
Blanking duration on low latch detection		t _{Latch(OTP)}	-	350	-	μS
Clamping voltage	$I_{Latch} = 0 \text{ mA}$ $I_{Latch} = 1 \text{ mA}$	V _{clamp0(Latch)} V _{clamp1(Latch)}	1.0 1.8	1.2 2.4	1.4 3.0	V
TEMPERATURE SHUTDOWN						
Temperature shutdown	T _J going up	T _{TSD}	_	150	-	°C
Temperature shutdown hysteresis	T _J going down	T _{TSD(HYS)}	-	30	-	°C

Internal supply current only, currents sourced via FB pin is not included (current is flowing in GND pin only).
 Guaranteed by design.
 CS pin source current is a sum of I_{bias} and I_{OPC}, thus at V_{HV} = 125 V is observed the I_{bias} only, because I_{OPC} is switched off.



45 I_{HV(off)} @ V_{HV} = 325 V 40 I_{start2} (mA) IHV(off) (µA) 35 $I_{HV(off)}$ @ $V_{HV} = 141 V$ 30 25 20 50 75 -50 -25 0 25 100 125



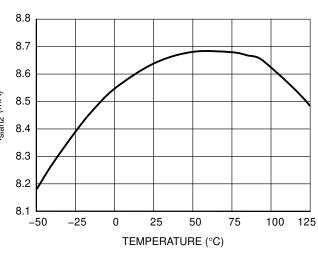


Figure 6. High Voltage Startup Current Flowing Out of V_{CC} Pin I_{start2}

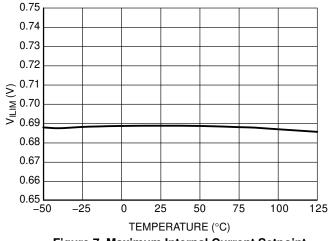


Figure 7. Maximum Internal Current Setpoint V_{ILIM}

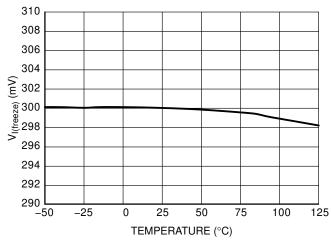


Figure 8. Frozen Current Setpoint $V_{I(freeze)}$ for the Light Load Operation

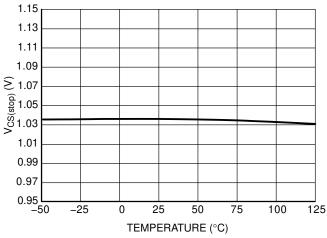


Figure 9. Threshold for Immediate Fault Protection Activation V_{CS(stop)}

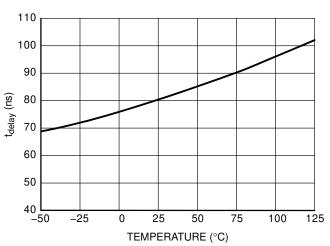


Figure 10. Propagation Delay t_{delay}

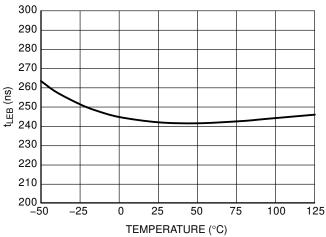


Figure 11. Leading Edge Blanking Duaration t_{LEB}

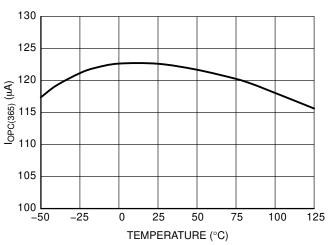


Figure 12. Maximum Overpower Compensating Current I_{OPC(365)} Flowing Out of CS Pin

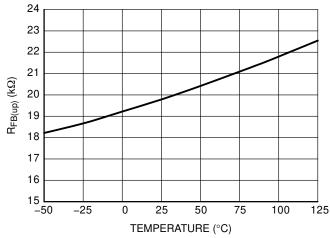


Figure 13. FB Pin Internal Pull-up Resistor $R_{FB(up)}$

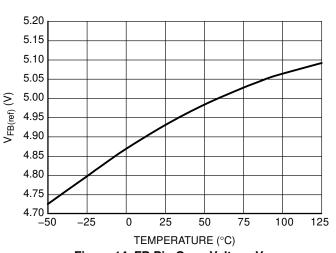


Figure 14. FB Pin Open Voltage V_{FB(ref)}

TYPICAL CHARACTERISTIC

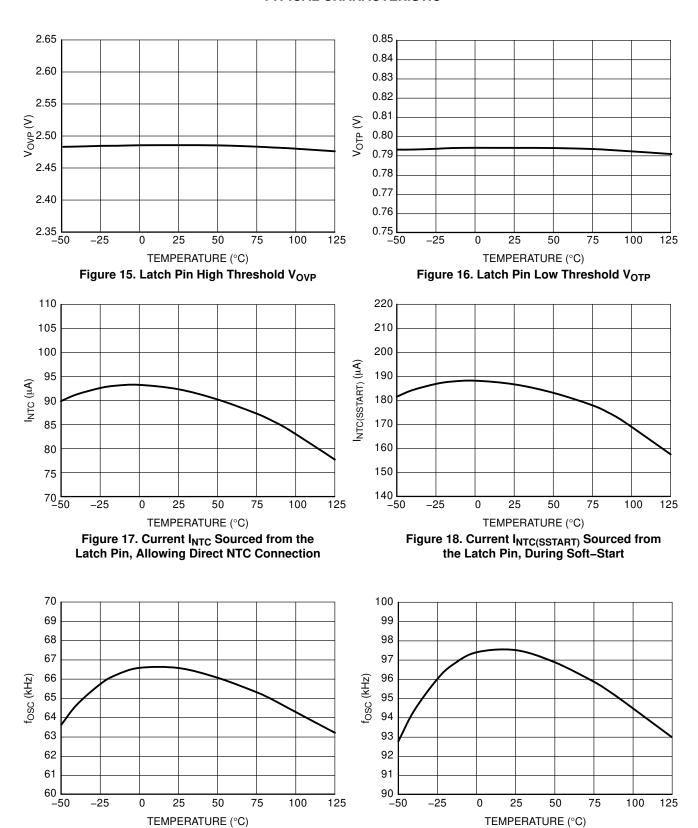


Figure 20. Oscillator fosc for the 100 kHz

Version

Figure 19. Oscillator fosc for the 65 kHz

Version

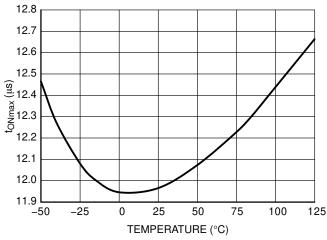


Figure 21. Maximum ON Time t_{ONmax} for the 65 kHz Version

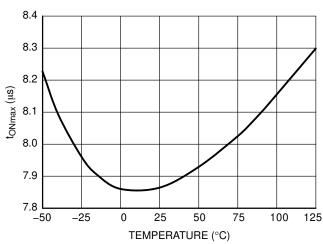


Figure 22. Maximum ON Time t_{ONmax} for the 100 kHz Version

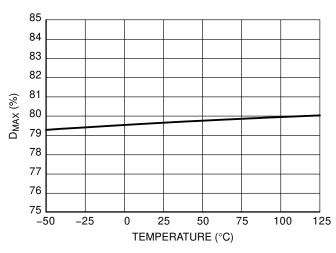


Figure 23. Maximum Duty Ratio D_{MAX}

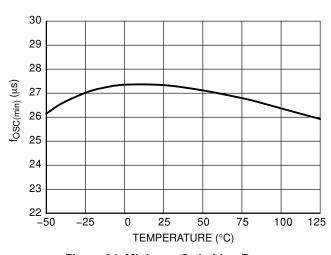


Figure 24. Minimum Switching Frequency f_{OSC(min)}

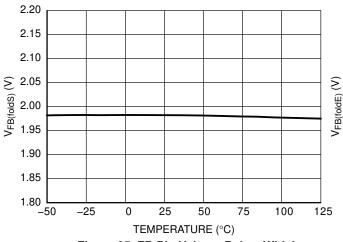


Figure 25. FB Pin Voltage Below Which Frequency Foldback Starts V_{FB(foldS)}

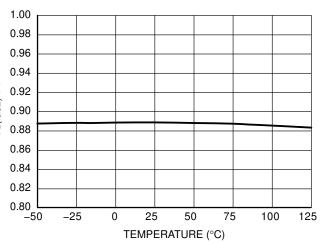
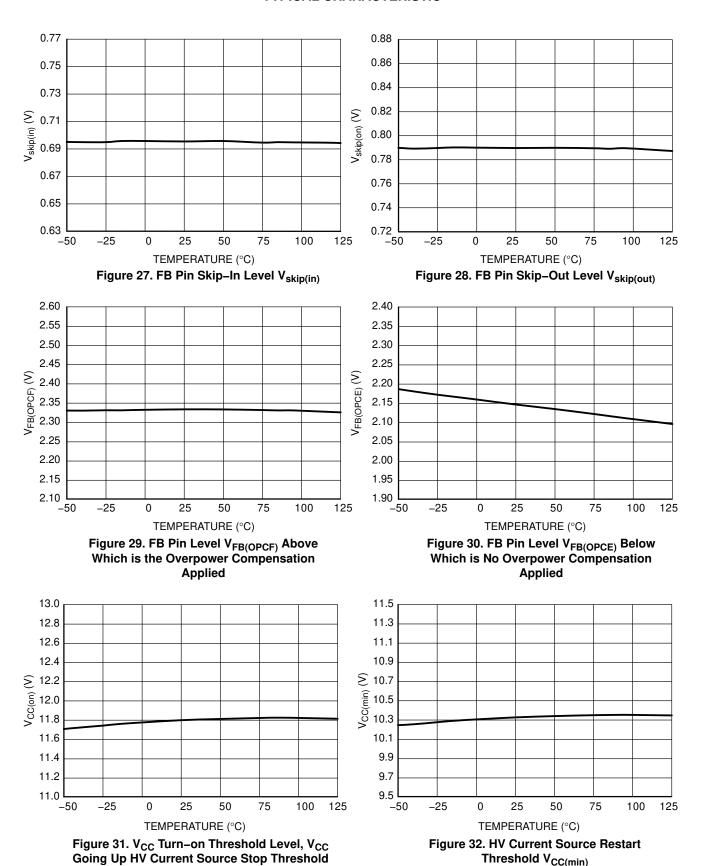
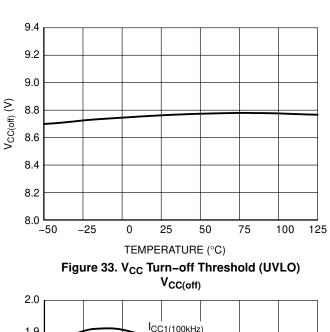


Figure 26. FB Pin Voltage Below Which Frequency Foldback Complete V_{FB(foldE)}

TYPICAL CHARACTERISTIC



V_{CC(on)}



7.3 7.2 7.1 7.0 Vcc(reset) (V) 6.9 6.8 6.7 6.6 6.5 6.4 . –50 -25 0 25 50 75 125 100 TEMPERATURE (°C)

ICC1(100kHz) 1.9 1.9 I_{CC1} (mA) I_{CC1(65kHz)} 1.8 1.8 1.7 -50 -25 25 50 75 100 125 TEMPERATURE (°C)

Figure 34. V_{CC} Decreasing Level at Which the Internal Logic Resets $V_{CC(reset)}$

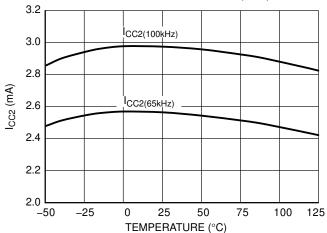
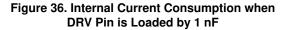
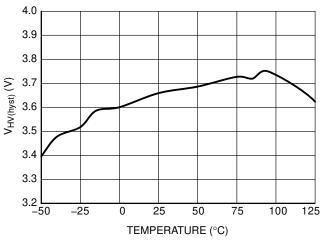


Figure 35. Internal Current Consumption when DRV Pin is Unloaded





1.10 1.08 1.06 1.04 T_{sample} (ms) 1.02 1.00 0.98 0.96 0.94 0.92 0.90 -50 -25 25 50 75 100 125 TEMPERATURE (°C)

Figure 37. X2 Discharge Comparator Hysteresis Observed at HV Pin $V_{HV(hyst)}$

Figure 38. HV Signal Sampling Period T_{sample}

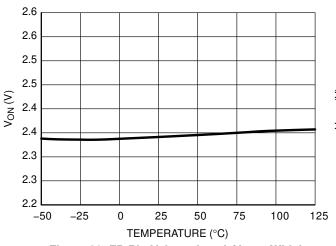


Figure 39. FB Pin Voltage Level Above Which is Entered On Mode V_{ON}

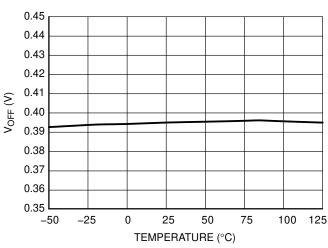


Figure 40. FB Pin Voltage Level Below Which is Entered Off Mode V_{OFF}

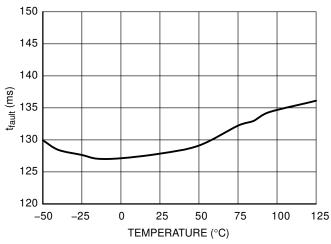


Figure 41. Fault Timer Duration t_{fault}

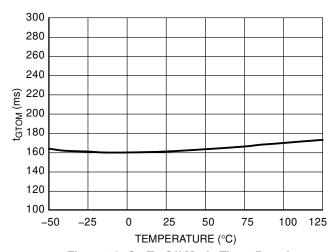


Figure 42. Go To Off Mode Timer Duration $$t_{\mbox{\scriptsize GTOM}}$$

APPLICATION INFORMATION

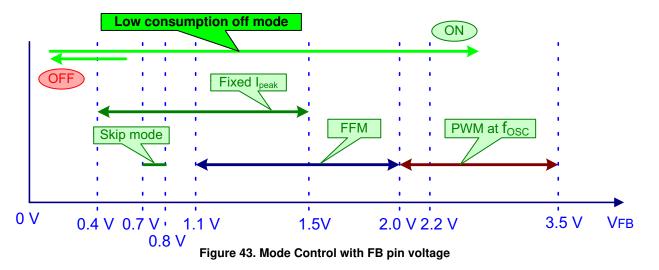
Functional Description

The NCP1244 includes all necessary features to build a safe and efficient power supply based on a fixed–frequency flyback converter. The NCP1244 is a multimode controller as illustrated in Figure 43. The mode of operation depends upon line and load condition. Under all modes of operation, the NCP1244 terminates the DRV signal based on the switch current. Thus, the NCP1244 always operates in current mode control so that the power MOSFET current is always limited.

Under normal operating conditions, the FB pin commands the operating mode of the NCP1244 at the voltage thresholds shown in Figure 43. At normal rated operating loads (from 100% to approximately 33% full rated power) the NCP1244 controls the converter in fixed frequency PWM mode. It can operate in the continuous conduction mode (CCM) or discontinuous conduction mode (DCM) depending upon the input voltage and loading conditions. If the controller is used in CCM with a wide input voltage range, the duty—ratio may increase up to 50%. The build—in slope compensation prevents the appearance of sub—harmonic oscillations in this operating area.

For loads that are between approximately 32% and 10% of full rated power, the converter operates in frequency foldback mode (FFM). If the feedback pin voltage is lower than 1.5 V the peak switch current is kept constant and the output voltage is regulated by modulating the switching frequency for a given and fixed input voltage V_{HV}.

Effectively, operation in FFM results in the application of constant volt–seconds to the flyback transformer each switching cycle. Voltage regulation in FFM is achieved by varying the switching frequency in the range from 65 kHz (or 100 kHz) to 27 kHz. For extremely light loads (below approximately 6% full rated power), the converter is controlled using bursts of 27 kHz pulses. This mode is called as skip mode. The FFM, keeping constant peak current and skip mode allows design of the power supplies with increased efficiency under the light loading conditions. Keep in mind that the aforementioned boundaries of steady–state operation are approximate because they are subject to converter design parameters.



There was implemented the low consumption off mode allowing to reach extremely low no load input power. This mode is controlled by the FB pin and allows the remote control (or secondary side control) of the power supply shut–down. Most of the device internal circuitry is unbiased in the low consumption off mode. Only the FB pin control circuitry and X2 cap discharging circuitry is operating in the low consumption off mode. If the voltage at feedback pin

decreases below the 0.4 V the controller will enter the low consumption off mode. The controller can start if the FB pin voltage increases above the 2.2 V level.

See the detailed status diagrams for the both versions fully latched A and the autorecovery B on the following figures. The basic status of the device after wake–up by the V_{CC} is the off mode and mode is used for the overheating protection mode if the thermal shutdown protection is activated.

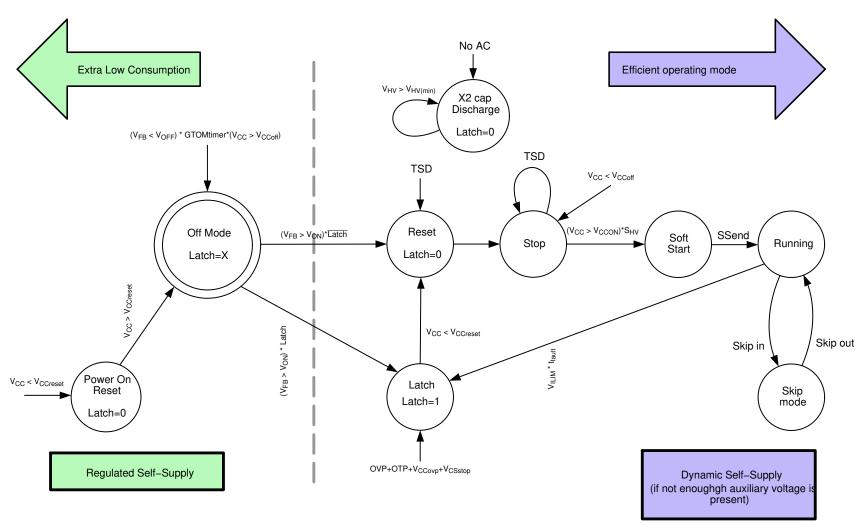


Figure 44. Operating Status Diagram for the Fully Latched Version A of the Device

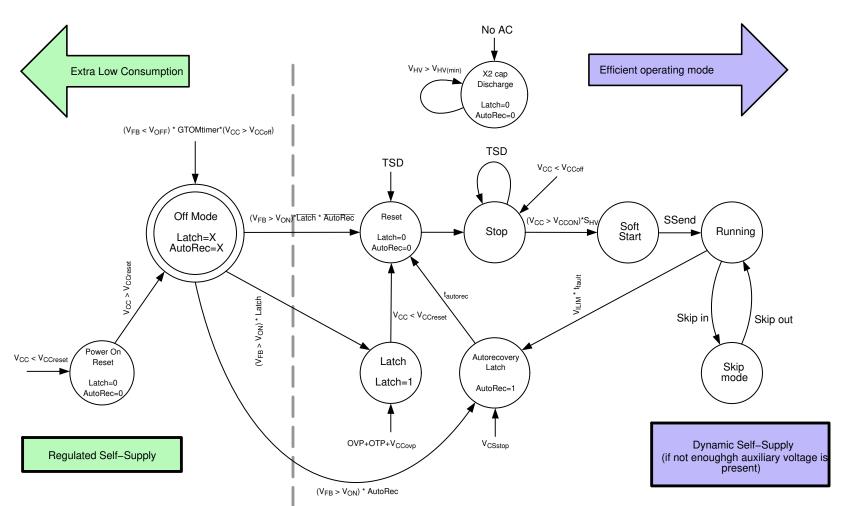


Figure 45. Operating Status Diagram for the Autorecovery Version B of the Device

The information about the fault (permanent Latch or Autorecovery) is kept during the low consumption off mode due the safety reason. The reason is not to allow unlatch the device by the remote control being in off mode.

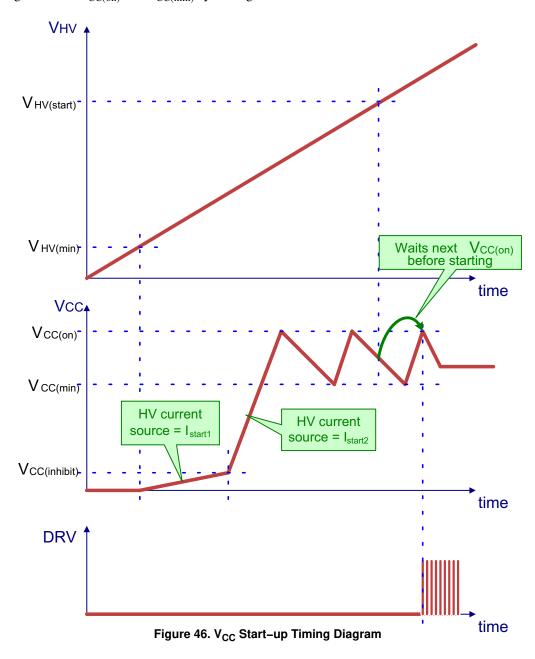
Start-up of the Controller

At start–up, the current source turns on when the voltage on the HV pin is higher than $V_{HV(min)}$, and turns off when V_{CC} reaches $V_{CC(on)}$, then turns on again when V_{CC} reaches $V_{CC(min)}$, until V_{CC} is supplied by an external source. The controller actually starts the first time V_{CC} reaches $V_{CC(on)}$ when the slope on HV pin is positive.

Even though the Dynamic Self–Supply is able to maintain the V_{CC} voltage between $V_{CC(on)}$ and $V_{CC(min)}$ by turning

the HV start–up current source on and off, it can only be used in light load condition, otherwise the power dissipation on the die would be too much. As a result, an auxiliary voltage source is needed to supply V_{CC} during normal operation.

The Dynamic Self–Supply is useful to keep the controller alive when no switching pulses are delivered, e.g. in latch or fault condition, or to prevent the controller from stopping during load transients when the V_{CC} might drop. The NCP1244 accepts a supply voltage as high as 28 V, with an overvoltage threshold $V_{CC(ovp)}$ that latches the controller off.



For safety reasons, the start—up current is lowered when V_{CC} is below $V_{CC(inhibit)}$, to reduce the power dissipation in case the V_{CC} pin is shorted to GND (in case of V_{CC} capacitor failure, or external pull—down on V_{CC} to disable the controller). There is only one condition for which the current source doesn't turn on when V_{CC} reaches $V_{CC(inhibit)}$: the voltage on HV pin is too low (below $V_{HV(min)}$). The controller can restart only when VCC reaches VCC(on) and

when the slope on HV pin is positive during the short ac line drop-outs. This feature differentiates between the short ac line drop-outs and application plug off. The minimum positive slope is defined by the Equation 1 in following chapter.

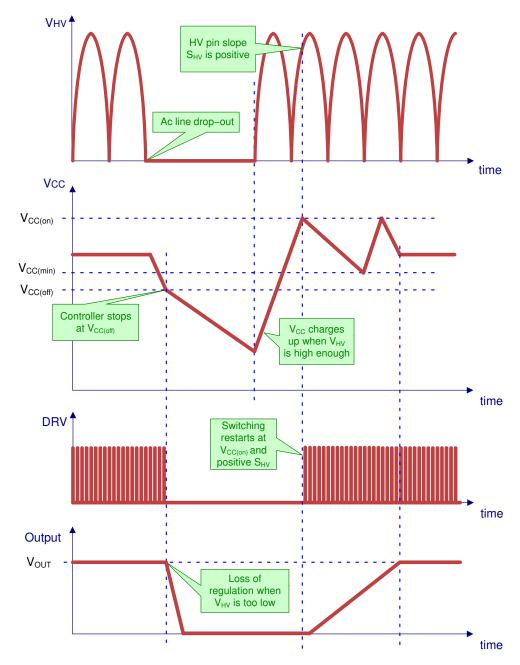


Figure 47. Ac Line Drop-out Timing Diagram

X2 Cap Discharge Feature

The X2 capacitor discharging feature is offered by usage of the NCP1244. This feature save approx. 16 mW - 25 mW input power depending on the EMI filter X2 capacitors volume and it saves the external components count as well. The discharge feature is ensured via the start–up current source with a dedicated control circuitry for this function. The X2 capacitors are being discharged by current defined as I_{start2} when this need is detected.

There is used a dedicated structure called ac line unplug detector inside the X2 capacitor discharge control circuitry. See the Figure 48 for the block diagram for this structure and Figures 49, 50 and 52 for the timing diagrams. The basic idea of ac line unplug detector lies in comparison of the direct sample of the high voltage obtained via the high voltage sensing structure with the delayed sample of the high voltage. The delayed signal is created by the sample & hold structure.

The comparator used for the comparison of these signals is without hysteresis inside. The resolution between the slopes of the ac signal and dc signal is defined by the sampling time T_{SAMPLE} and additional internal offset N_{OS}. These parameters ensure the noise immunity as well. The additional offset is added to the picture of the sampled HV signal and its analog sum is stored in the C₁ storage capacitor. If the voltage level of the HV sensing structure output crosses this level the comparator CMP output signal resets the detection timer and no dc signal is detected. The additional offset N_{OS} can be measured as the $V_{HV(hyst)}$ on the HV pin. If the comparator output produces pulses it means that the slope of input signal is higher than set resolution level and the slope is positive. If the comparator output produces the low level it means that the slope of input signal is lower than set resolution level or the slope is negative. There is used the detection timer which is reset by any edge of the comparator output. It means if no edge comes before the timer elapses there is present only dc signal or signal with the small ac ripple at the HV pin. This type of the ac detector detects only the positive slope, which fulfils the requirements for the ac line presence detection.

In case of the dc signal presence on the high voltage input, the direct sample of the high voltage obtained via the high voltage sensing structure and the delayed sample of the high voltage are equivalent and the comparator produces the low level signal during the presence of this signal. No edges are present at the output of the comparator, that's why the detection timer is not reset and dc detect signal appears.

The minimum detectable slope by this ac detector is given by the ration between the maximum hysteresis observed at $HV pin V_{HV(hyst),max}$ and the sampling time:

$$S_{min} = \frac{V_{HV(hyst),max}}{T_{sample}}$$
 (eq. 1)

Than it can be derived the relationship between the minimum detectable slope and the amplitude and frequency of the sinusoidal input voltage:

$$V_{\text{max}} = \frac{V_{\text{HV(hyst),max}}}{2 \cdot \pi \cdot f \cdot T_{\text{sample}}} = \frac{5}{2 \cdot \pi \cdot 35 \cdot 1 \cdot 10^{-3}} \text{ (eq. 2)}$$

The minimum detectable AC RMS voltage is 16 V at frequency 35 Hz, if the maximum hysteresis is 5 V and sampling time is 1 ms.

The X2 capacitor discharge feature is available in any controller operation mode to ensure this safety feature. The detection timer is reused for the time limiting of the discharge phase, to protect the device against overheating. The discharging process is cyclic and continues until the ac line is detected again or the voltage across the X2 capacitor is lower than $V_{HV(min)}$. This feature ensures to discharge quite big X2 capacitors used in the input line filter to the safe level. It is important to note that it is not allowed to connect HV pin to any dc voltage due this feature. e.g. directly to bulk capacitor.

During the HV sensing or X2 cap discharging the V_{CC} net is kept above the $V_{CC(off)}$ voltage by the Self–Supply in any mode of device operation to supply the control circuitry. During the discharge sequence device runs normally.

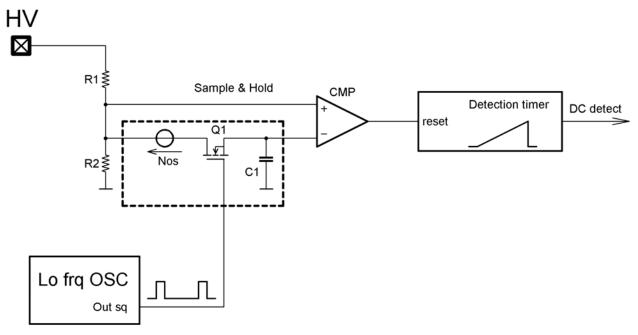


Figure 48. The ac Line Unplug Detector Structure Used for X2 Capacitor Discharge System

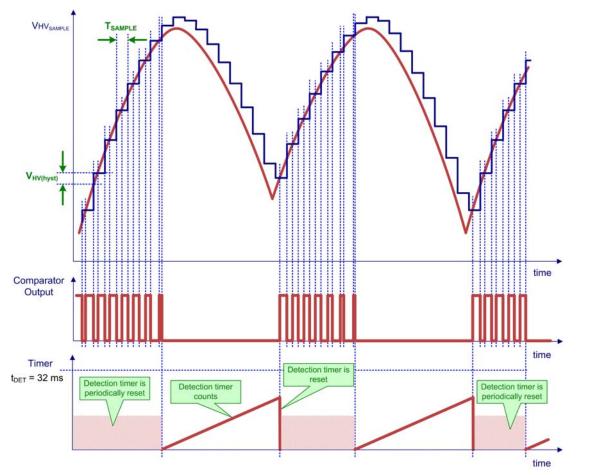


Figure 49. The ac Line Unplug Detector Timing Diagram

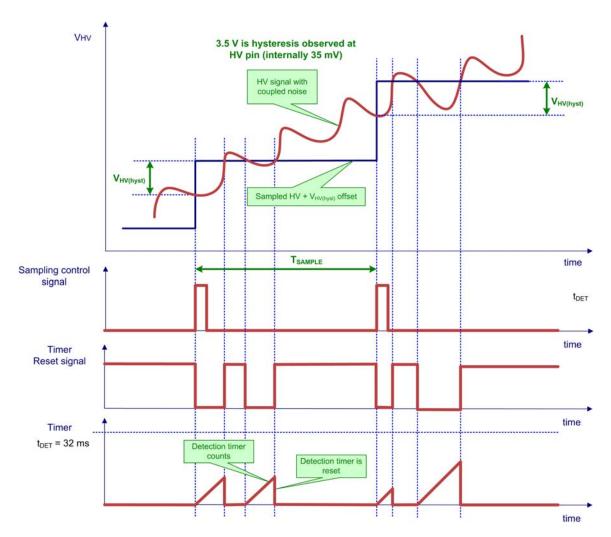


Figure 50. The ac Line Unplug Detector Timing Diagram Detail with Noise Effects

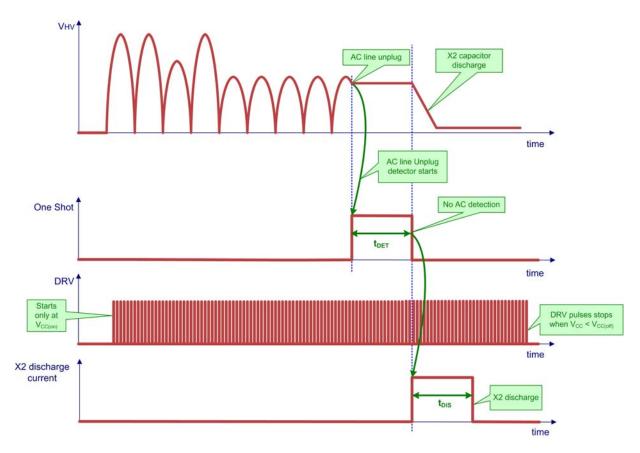


Figure 51. HV Pin ac Input Timing Diagram with X2 Capacitor Discharge Sequence when the Application is Unplugged Under Extremely Low Line Condition

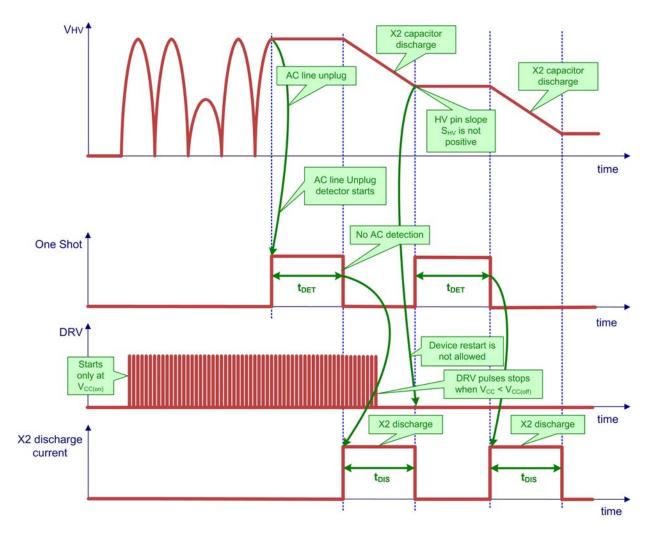


Figure 52. HV Pin ac Input Timing Diagram with X2 Capacitor Discharge Sequence When the Application is Unplugged Under High Line and Heavy Load Condition

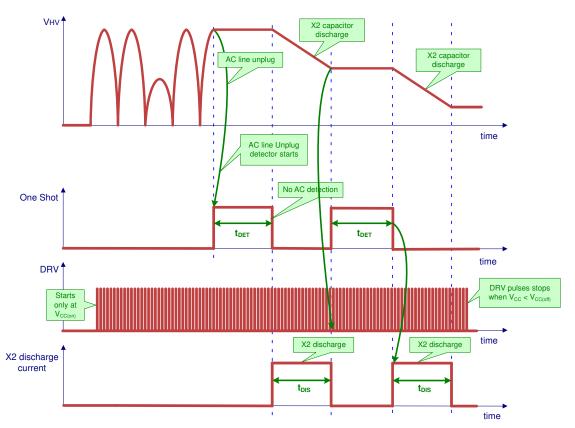


Figure 53. HV Pin ac Input Timing Diagram with X2 Capacitor Discharge Sequence When the Application is Unplugged Under High Line and Light Load Condition

The Low Consumption Off Mode

There was implemented the low consumption off mode allowing to reach extremely low no load input power as described in previous chapters. If the voltage at feedback pin decreases below the 0.4 V the controller enters the off mode. The internal V_{CC} is turned–off, the IC consumes extremely low V_{CC} current and only the voltage at external V_{CC} capacitor is maintained by the Self–Supply circuit. The Self–Supply circuit keeps the V_{CC} voltage at the $V_{CC(reg)}$ level. The supply for the FB pin watch dog circuitry and FB pin bias is provided via the low consumption current sources from the external V_{CC} capacitor. The controller can only start, if the FB pin voltage increases above the 2.2 V level. See Figure 54 for timing diagrams.

Only the X2 cap discharge and Self–Supply features is enabled in the low consumption off mode. The X2 cap discharging feature is enable due the safety reasons and the Self–Supply is enabled to keep the V_{CC} supply, but only very low V_{CC} consumption appears in this mode. Any other features are disabled in this mode.

The information about the latch status of the device is kept in the low consumption off mode and this mode is used for the TSD protection as well. The protection timer GoToOffMode t_{GTOM} is used to protect the application against the false activation of the low consumption off mode by the fast drop outs of the FB pin voltage below the 0.4 V level. E.g. in case when is present high FB pin voltage ripple during the skip mode.