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NCP1399 Series

High Performance Current Mode Resonant Controller with Integrated High-Voltage Drivers

The NCP1399 is a high performance current mode controller for half bridge resonant converters. This controller implements 600 V gate drivers, simplifying layout and reducing external component count. The built-in Brown-Out input function eases implementation of the controller in all applications. In applications where a PFC front stage is needed, the NCP1399 features a dedicated output to drive the PFC controller. This feature together with dedicated skip mode technique further improves light load efficiency of the whole application. The NCP1399 provides a suite of protection features allowing safe operation in any application. This includes: overload protection, over-current protection to prevent hard switching cycles, brown-out detection, open optocoupler detection, automatic dead-time adjust, overvoltage (OVP) and overtemperature (OTP) protections.

Features

- High-Frequency Operation from 20 kHz up to 750 kHz
- Current Mode Control Scheme
- Automatic Dead-time with Maximum Dead-time Clamp
- Dedicated Startup Sequence for Fast Resonant Tank Stabilization
- Skip Mode Operation for Improved Light Load Efficiency
- Off-mode Operation for Extremely Low No-load Consumption
- Latched or Auto-Recovery Overload Protection
- Latched or Auto-Recovery Output Short Circuit Protection
- Latched Input for Severe Fault Conditions, e.g. OVP or OTP
- Out of Resonance Switching Protection
- Open Feedback Loop Protection
- Precise Brown-Out Protection
- PFC Stage Operation Control According to Load Conditions
- Startup Current Source with Extremely Low Leakage Current
- Dynamic Self-Supply (DSS) Operation in Off-mode or Fault Modes
- Pin to Adjacent Pin / Open Pin Fail Safe
- These are Pb-Free Devices

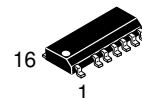
Typical Applications

- Adapters and Offline Battery Chargers
- Flat Panel Display Power Converters
- Computing Power Supplies
- Industrial and Medical Power Sources



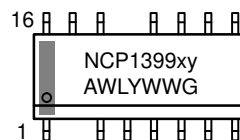
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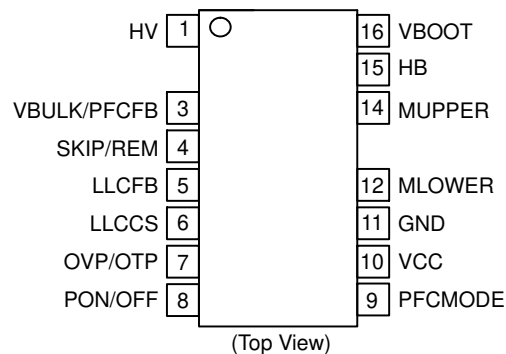
SOIC-16 NB
(LESS PINS 2 AND 13)
D SUFFIX
CASE 751DU

MARKING DIAGRAM



NCP1399 = Specific Device Code
x = A or B
y = A, B, C, F, G H, I, J, K, L, M
A = Assembly Location
WL = Wafer Lot
Y = Year
WW = Work Week
G = Pb-Free Package

PIN CONNECTIONS



ORDERING INFORMATION

See detailed ordering and shipping information on page 10 of this data sheet.

NCP1399 Series

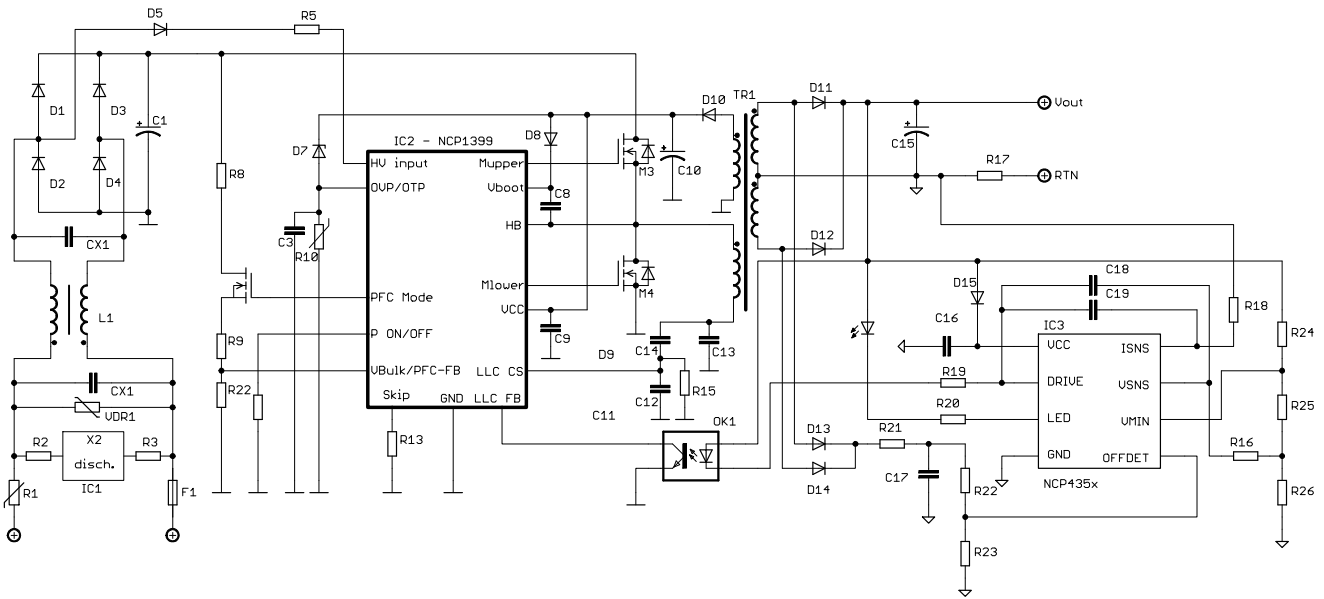


Figure 1. Typical Application Example without PFC Stage – WLLC Design (Active OFF off-mode)

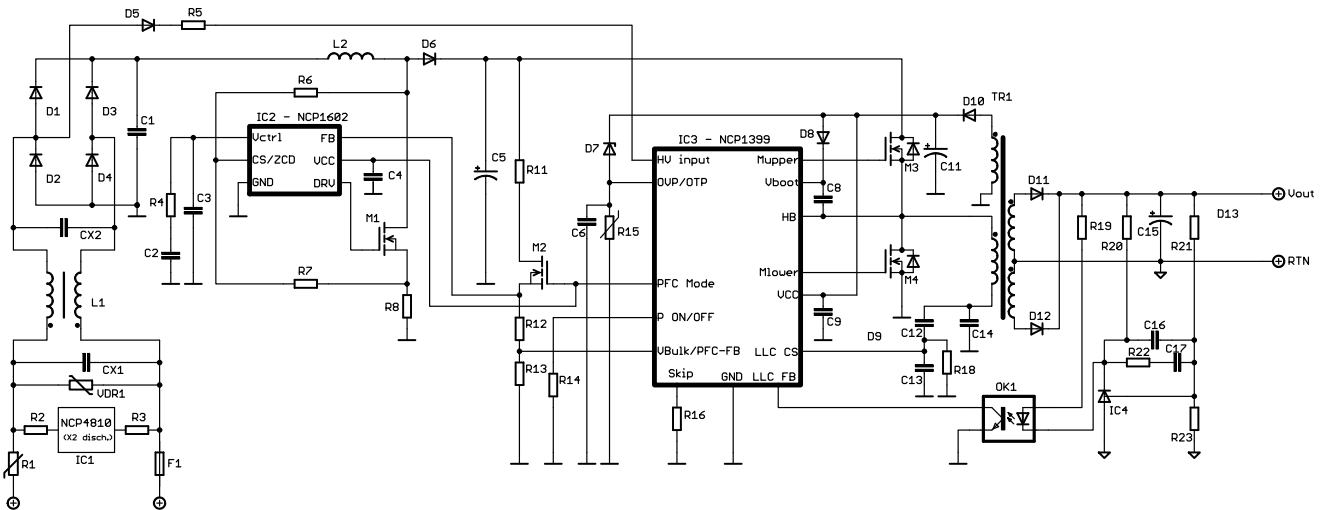


Figure 2. Typical Application Example with PFC Stage (Active OFF off-mode)

NCP1399 Series

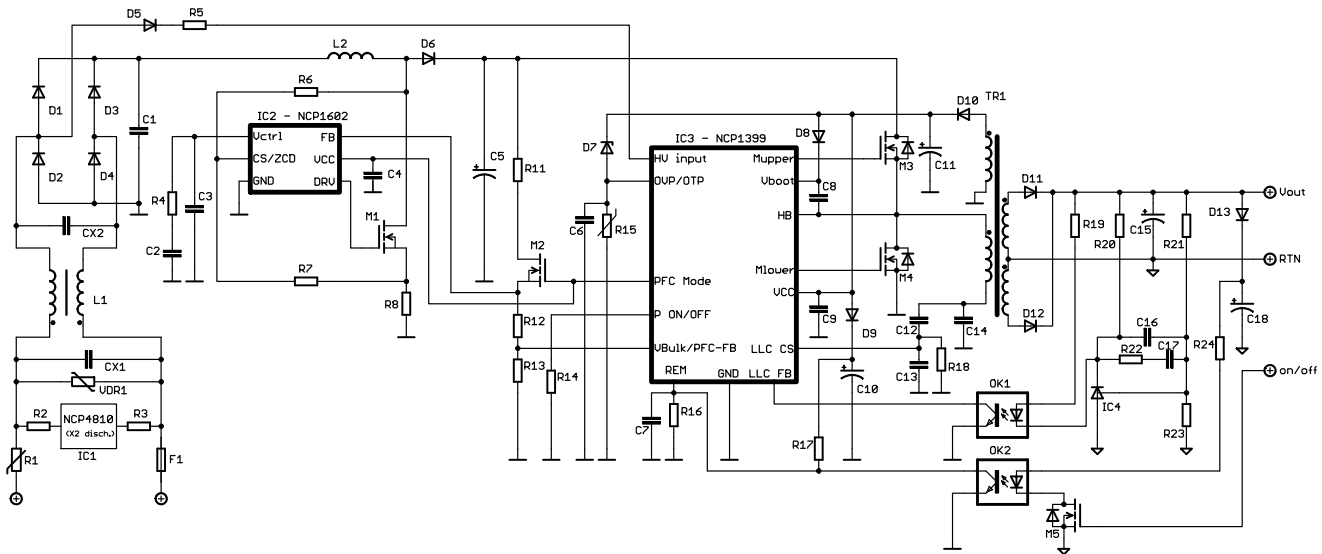


Figure 3. Typical Application Example with PFC Stage (Active ON off-mode)

PIN FUNCTION DESCRIPTION

Pin No.	Pin Name	Function	Pin Description
1	HV	High – voltage startup current source input	Connects to rectified AC line or to bulk capacitor to perform functions of Start – up Current Source and Dynamic Self – Supply
2	NC	Not connected	Increases the creepage distance
3	VBULK / PFC FB	Bulk voltage monitoring input	Receives divided bulk voltage to perform Brown–out protection.
4	SKIP/REM	Skip threshold adjust / Off–mode control input	Sets the skip in threshold via a resistor connected to ground – version NCP1399Ay. Activates off–mode (or Standby) when pulled–up by external auxiliary voltage source / deactivates off–mode when pull down by external off–mode control optocoupler – version NCP1399By.
5	LLC FB	LLC feedback input	Defines operating frequency based on given load conditions. Activates skip mode operation under light load conditions. Activates off–mode operation for NCP1399Ay version.
6	LLC CS	LLC current sense input	Senses divided resonant capacitor voltage to perform on–time modulation, out of resonant switching protection, over–current protection and secondary side short circuit protection.
7	OTP / OVP	Over–temperature and over–voltage protection input	Implements over–temperature and over–voltage protection on single pin.
8	P ON/OFF	PFC turn–off FB level adjust	Adjusts the FB pin to a level below which the PFC stage operation is disabled.
9	PFC MODE	PFC and external HV switch control output	Provides supply voltage for PFC front stage controller and/or enables Vbulk sensing network HV switch.
10	VCC	Supplies the controller	The controller accepts up to 20 V on VCC pin
11	GND	Analog ground	Common ground connection for adjust components, sensing networks and DRV outputs.
12	MLOWER	Low side driver output	Drives the lower side MOSFET
13	NC	Not connected	Increases the creepage distance
14	MUPPER	High side driver output	Drives the higher side MOSFET
15	HB	Half – bridge connection	Connects to the half – bridge output.
16	VBOOT	Bootstrap pin	The floating VCC supply for the upper stage

NCP1399 Series

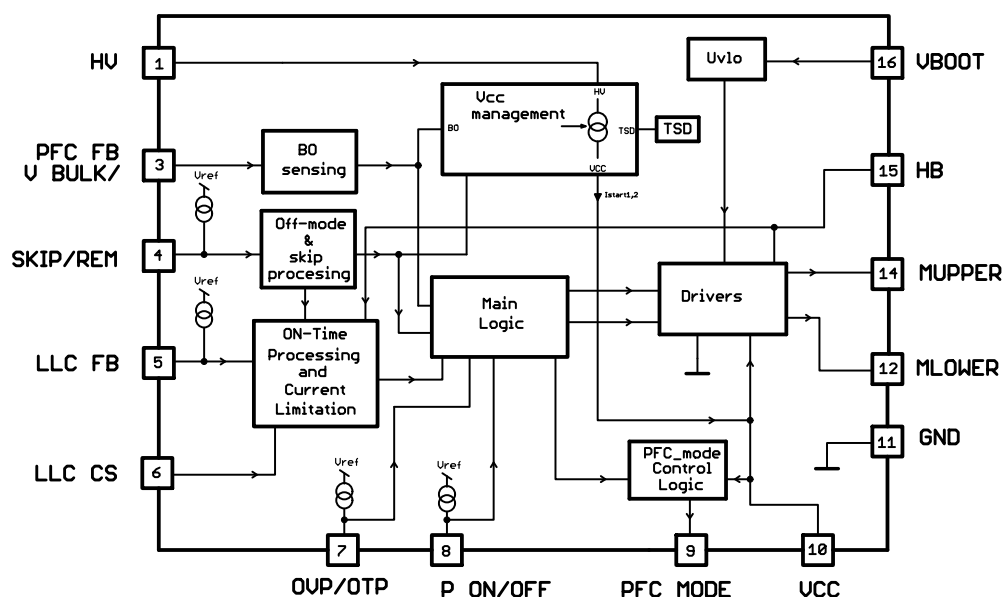


Figure 4. Internal Circuit Architecture

MAXIMUM RATINGS

Rating	Symbol	Value	Unit
HV Startup Current Source HV Pin Voltage (Pin 1)	V_{HV}	-0.3 to 600	V
VBULK/PFC FB Pin Voltage (Pin3)	$V_{BULK/PFC FB}$	-0.3 to 5.5	V
SKIP/REM Pin Voltage (Pin 4) NCP1399Ay Revision Only	$V_{SKIP/REM}$	-0.3 to 5.5	V
SKIP/REM Pin Voltage (Pin 4) NCP1399By Revision Only	$V_{SKIP/REM}$	-0.3 to 10	V
LLC FB Pin Voltage (Pin 5)	V_{FB}	-0.3 to 5.5	V
LLC CS Pin Voltage (Pin 6)	V_{CS}	-5 to 5	V
PFC MODE Pin Output Voltage (Pin 9)	$V_{PFC MODE}$	-0.3 to $V_{CC} + 0.3$	V
VCC Pin Voltage (Pin 10)	V_{CC}	-0.3 to 20	V
Low Side Driver Output Voltage (Pin 12)	V_{DRV_MLOWER}	-0.3 to $V_{CC} + 0.3$	V
High Side Driver Output Voltage (Pin 14)	V_{DRV_MUPPER}	$V_{HB} - 0.3$ to $V_{BOOT} + 0.3$	V
High Side Offset Voltage (Pin 15)	V_{HB}	$V_{Boot} - 20$ to $V_{Boot} + 0.3$	V
High Side Floating Supply Voltage (Pin 16)	V_{BOOT}	$T_J = -40^{\circ}C$ to $+125^{\circ}C$ $T_J = -55^{\circ}C$ to $-40^{\circ}C$	V
High Side Floating Supply Voltage (Pin 15 and 16)	$V_{Boot-VHB}$	-0.3 to 20.0	V
Allowable Output Slew Rate on HB Pin (Pin 15)	dV/dt_{max}	50	V/ns
OVP/OTP Pin Voltage (Pin 7)	$V_{OVP/OTP}$	-0.3 to 5.5	V
P ON/OFF Pin Voltage (Pin 8)	$V_{P ON/OFF}$	-0.3 to 5.5	V
Junction Temperature	T_J	-55 to 150	$^{\circ}C$
Storage Temperature	T_{STG}	-55 to 150	$^{\circ}C$
Thermal Resistance Junction-to-air	$R_{\theta JA}$	130	$^{\circ}C/W$
Human Body Model ESD Capability per JEDEC JESD22-A114F (except HV Pin - Pin 1)	-	4.5	kV
Charged-Device Model ESD Capability per JEDEC JESD22-C101E	-	1	kV

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

1. This device contains latch-up protection and exceeds 100 mA per JEDEC Standard JESD78.

NCP1399 Series

ELECTRICAL CHARACTERISTICS

(For typical values $T_J = 25^\circ\text{C}$, for min/max values $T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$, $V_{CC} = 12\text{ V}$ unless otherwise noted.)

Symbol	Rating	Pin	Min	Typ	Max	Unit
HV Startup Current Source						
V_{HV_MIN1}	Minimum voltage for current source operation ($V_{CC} = V_{CC_ON} - 0.5\text{ V}$, I_{START2} drops to 95 %)	1	–	–	60	V
V_{HV_MIN2}	Minimum voltage for current source operation ($V_{CC} = V_{CC_ON} - 0.5\text{ V}$, I_{START2} drops to 5 mA)	1	–	–	60	V
I_{START1}	Current flowing out of V_{CC} pin ($V_{CC} = 0\text{ V}$)	1, 10	0.2	0.5	0.8	mA
I_{START2}	Current flowing out of V_{CC} pin ($V_{CC} = V_{CC_ON} - 0.5\text{ V}$)	1, 10	6	9	13	mA
I_{START_OFF}	Off–state leakage current ($V_{HV} = 500\text{ V}$, $V_{CC} = 15\text{ V}$)	1	–	–	10	μA
$I_{HV_OFF_MODE}$	HV pin current when off–mode operation is active ($V_{HV} = 400\text{ V}$)	1	–	–	8	μA

Supply Section

V_{CC_ON}	Turn–on threshold level, V_{CC} going up	10	15.3	15.8	16.3	V
V_{CC_ON}	Turn–on threshold level, V_{CC} going up (NCP1399AL, NCP1399AM)	10	11.5	12.0	12.3	V
V_{CC_OFF}	Minimum operating voltage after turn–on	10	9.0	9.5	10	V
V_{CC_RESET}	V_{CC} level at which the internal logic gets reset	10	5.8	6.6	7.2	V
$V_{CC_INHIBIT}$	V_{CC} level for I_{START1} to I_{START2} transition	10	0.40	0.80	1.25	V
$V_{CC_ON_BLANK}$	Delay to generate DRV pulses after V_{CC_ON} is reached	10	100	125	150	μs
$I_{CC_OFF_MODE}$	Controller supply current in off–mode, $V_{CC} = V_{CC_ON} - 0.2\text{ V}$ (except NCP1399AG)	10, 11	10	27	40	μA
$I_{CC_SKIP_MODE}$	Controller supply current in skip–mode, $V_{CC} = 15\text{ V}$ (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AH, NCP1399AI, NCP1399AK, NCP1399AM) (NCP1399AF, NCP1399AG, NCP1399AJ) (NCP1399AL)	10, 11				μA
			580	750	900	
			500	670	820	
			500	710	890	
I_{CC_LATCH}	Controller supply current in latch–off mode, $V_{CC} = V_{CC_ON} - 0.2\text{ V}$ (except NCP1399AI)	10, 11	330	490	600	μA
$I_{CC_AUTOREC}$	Controller supply current in auto–recovery mode, $V_{CC} = V_{CC_ON} - 0.2\text{ V}$ (except NCP1399AF)	10, 11	300	490	600	μA
$I_{CC_OPERATION}$	Controller supply current in normal operation, $f_{sw} = 100\text{ kHz}$, $C_{load} = 1\text{ nF}$, $V_{CC} = 15\text{ V}$	10, 11	4.0	5.4	7.0	mA

Bootstrap Section

V_{BOOT_ON}	Startup voltage on the floating section (Note 5)	16, 15	8	9	10	V
V_{BOOT_OFF}	Cutoff voltage on the floating section	16, 15	7.2	8.2	9.0	V
I_{BOOT1}	Upper driver consumption, no DRV pulses	16, 15	30	75	130	μA
I_{BOOT2}	Upper driver consumption, $C_{load} = 1\text{ nF}$ between Pins 13 & 15 $f_{sw} = 100\text{ kHz}$, HB connected to GND	16, 15	1.30	1.65	2.00	mA

HB Discharger

$I_{DISCHARGE1}$	HB sink current capability $V_{HB} = 30\text{ V}$	15	5	–	–	mA
$I_{DISCHARGE2}$	HB sink current capability $V_{HB} = V_{HB_MIN}$	15	1	–	–	mA
V_{HB_MIN}	HB voltage @ $I_{DISCHARGE}$ changes from 2 to 0 mA	15	–	–	10	V

Remote Input – NCP1399By

V_{REM_ON}	Remote pin voltage below which off–mode is deactivated (V_{REM} going down)	4	1.0	1.5	2.0	V
V_{REM_OFF}	Remote pin voltage above which off–mode is activated (V_{REM} going up)	4	7.2	8.0	8.8	V

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

2. The NCP1399Ay version has skip adjustable externally.
3. Guaranteed by design.
4. Minimal impedance on P ON/OFF pin is 1 k Ω .
5. Minimal resistance connected in series with bootstrap diode is 3.3 Ω .

NCP1399 Series

ELECTRICAL CHARACTERISTICS

(For typical values $T_J = 25^\circ\text{C}$, for min/max values $T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$, $V_{CC} = 12\text{ V}$ unless otherwise noted.)

Symbol	Rating	Pin	Min	Typ	Max	Unit
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Remote Input – NCP1399By

$t_{\text{REM_TIMER}}$	Remote timer duration	4	80	100	120	ms
$I_{\text{REM_LEAK}}$	Remote input leakage current ($V_{\text{REM}} = 10\text{ V}$)	4	–	0.02	1.00	μA
$R_{\text{SW_REM}}$	Internal remote pull down switch resistance ($V_{\text{REM}} = 8\text{ V}$)	4	3	–	7	$\text{k}\Omega$

Remote Control – NCP1399Ay (i.e. Off-mode is Sensed via FB Pin, except NCP1399AG)

$V_{\text{FB_REM_ON}}$	FB pin voltage above which off-mode is deactivated (V_{FB} going up)	5	1.5	2.0	2.5	V
$V_{\text{FB_REM_OFF}}$	FB pin voltage below which off-mode is activated (V_{FB} going down)	5	0.36	0.40	0.44	V
$I_{\text{FB_REM_BIAS}}$	Pull-up FB pin bias current during off-mode	5	1.0	2.3	4.0	μA

Driver Outputs

t_r	Output voltage rise-time @ $C_L = 1\text{ nF}$, 10–90% of output signal	12, 14	20	45	80	ns
t_f	Output voltage fall-time @ $C_L = 1\text{ nF}$, 10–90% of output signal	12, 14	5	30	50	ns
R_{OH}	Source resistance	12, 14	4	16	32	Ω
R_{OL}	Sink resistance	12, 14	1	5	11	Ω
$I_{\text{DRVSOURCE}}$	Output high short circuit pulsed current $V_{\text{DRV}} = 0\text{ V}$, $\text{PW} \leq 10\ \mu\text{s}$	12, 14	–	0.5	–	A
I_{DRVSINK}	Output high short circuit pulsed current $V_{\text{DRV}} = V_{\text{CC}}$, $\text{PW} \leq 10\ \mu\text{s}$	12, 14	–	1	–	A
$I_{\text{HV_LEAK}}$	Leakage current on high voltage pins to GND	14, 15, 16	–	–	5	μA

Dead-time Generation

$t_{\text{DEAD_TIME_MAX}}$	Maximum Dead-time value if no dV/dt falling/rising edge is received	12, 14	720	800	880	ns
$N_{\text{DT_MAX}}$	Number of DT_MAX events to enters IC into fault (NCP1399AA, NCP1399BA, NCP1399AH, NCP1399AK, NCP1399AL)	12, 14, 16	–	8	–	–
	Number of DT_MAX events to enters IC into fault (NCP1399AC, NCP1399AF, NCP1399AG, NCP1399AI, NCP1399AJ, NCP1399AM)	12, 14, 16	–	16	–	–

dV/dt Detector

$P_{\text{dV/dt_th}}$	Positive slew rate on V_{BOOT} pin above which automatic dead-time end is generated	16	–	10	–	$\text{V}/\mu\text{s}$
$N_{\text{dV/dt_th}}$	Negative slew rate on V_{BOOT} pin above which automatic dead-time end is generated	16	–	10	–	$\text{V}/\mu\text{s}$

PFC MODE Output and P ON/OFF Adjust

$V_{\text{PFC_M_BO}}$	PFC MODE output voltage when $V_{\text{FB}} < V_{\text{P_ON/OFF}}$ (sink 1 mA current from PFC MODE output)	9	5.75	6.00	6.25	V
$V_{\text{PFC_M_ON}}$	PFC MODE output voltage when $V_{\text{FB}} > V_{\text{P_ON/OFF}}$ (sink 10 mA current from PFC MODE output)	9	$V_{\text{CC}} - 0.4$	–	–	V
$I_{\text{PFC_M_LIM}}$	PFC MODE output current limit ($V_{\text{PFC_MODE}} < 2\text{ V}$)	9	0.7	1.2	1.85	mA
$t_{\text{P_ON/OFF_TIMER}}$	Delay to transition PFC MODE from $V_{\text{PFC_M_ON}}$ to $V_{\text{PFC_M_BO}}$ after V_{FB} drops below $V_{\text{P_ON/OFF}}$	5, 8, 9	9.4	–	10.9	s
$I_{\text{P_ON/OFF}}$	Pull-up current source (Note 4)	8	18	20	22	μA

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

2. The NCP1399Ay version has skip adjustable externally.
3. Guaranteed by design.
4. Minimal impedance on P ON/OFF pin is 1 $\text{k}\Omega$.
5. Minimal resistance connected in series with bootstrap diode is 3.3 Ω .

NCP1399 Series

ELECTRICAL CHARACTERISTICS

(For typical values $T_J = 25^\circ\text{C}$, for min/max values $T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$, $V_{CC} = 12\text{ V}$ unless otherwise noted.)

Symbol	Rating	Pin	Min	Typ	Max	Unit
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PFC MODE Output and P ON/OFF Adjust

$P_{ON/OFF_{HYST}}$	P ON/OFF comparator hysteresis – percentage level of P ON/OFF pin voltage	5, 8, 9	80	100	120	%
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OVP/OTP

V_{OVP}	OVP threshold voltage ($V_{OVP/OTP}$ going up)	7	2.35	2.50	2.65	V
V_{OTP}	OTP threshold voltage ($V_{OVP/OTP}$ going down)	7	0.76	0.80	0.84	V
I_{OTP}	OTP/OVP pin source current for external NTC – during normal operation	7	90	95	100	μA
I_{OTP_BOOST}	OTP/OVP pin source current for external NTC – during startup	7	180	190	200	μA
t_{OVP_FILTER}	Internal filter for OVP comparator	7	32	37	44	μs
t_{OTP_FILTER}	Internal filter for OTP comparator	7	200	330	500	μs
t_{BLANK_OTP}	Blanking time for OTP input during startup (NCP1399AA, NCP1399BA, NCP1399AK)	7	7.3	8.0	8.7	ms
	Blanking time for OTP input during startup (NCP1399AC, NCP1399AF, NCP1399AG, NCP1399AH, NCP1399AI, NCP1399AJ, NCP1399AL, NCP1399AM)	7	14	16	18	ms
V_{CLAMP_OVP/OTP_1}	OVP/OTP pin clamping voltage @ $I_{OVP/OTP} = 0\text{ mA}$	7	1.0	1.2	1.4	V
V_{CLAMP_OVP/OTP_2}	OVP/OTP pin clamping voltage @ $I_{OVP/OTP} = 1\text{ mA}$	7	1.8	2.4	3.0	V

Start-up Sequence Parameters

t_{TON_MAX}	Maximum on-time clamp (NCP1399AA, NCP1399BA, NCP1399AK, NCP1399AL)	12, 14	7.3	7.7	8.4	μs
	Maximum on-time clamp (NCP1399AC, NCP1399AG, NCP1399AI, NCP1399AM)	12, 14	10.6	11.2	12.1	μs
	Maximum on-time clamp (NCP1399AF, NCP1399AJ)	12, 14	15.2	16.3	17.8	μs
	Maximum on-time clamp (NCP1399AH)	12, 14	8.8	9.5	10.5	μs
$t_{1st_MLOWER_TON}$	Initial Mlower DRV on-time duration (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AG, NCP1399AH, NCP1399AI, NCP1399AK, NCP1399AL, NCP1399AM)	12	4.7	4.9	5.4	μs
$t_{1st_MLOWER_TON}$	Initial Mlower DRV on-time duration (NCP1399AF, NCP1399AJ)	12	9.3	10	11	μs
$t_{1st_MUPPER_TON}$	Initial Mupper DRV on-time duration (NCP1399AM)	14	0.44	0.50	0.57	μs
$t_{1st_MUPPER_TON}$	Initial Mupper DRV on-time duration (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AG, NCP1399AH, NCP1399AI, NCP1399AK, NCP1399AL)	14	0.72	0.79	0.88	μs
$t_{1st_MUPPER_TON}$	Initial Mupper DRV on-time duration (NCP1399AF, NCP1399AJ)	14	0.99	1.10	1.21	μs
$t_{SS_INCREMENT}$	On-time period increment during soft-start (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AG, NCP1399AH, NCP1399AI, NCP1399AK, NCP1399AL, NCP1399AM)	12, 14	17	20	22	ns
	On-time period increment during soft-start (NCP1399AF, NCP1399AJ)	12, 14	75	80	88	ns
$K_{SS_INCREMENT}$	Soft-Start increment division ratio (NCP1399AA, NCP1399BA, NCP1399AK)	12, 14	–	4	–	–
	Soft-Start increment division ratio (NCP1399AL)	12, 14	–	2	–	–
	Soft-Start increment division ratio (NCP1399AC, NCP1399AF, NCP1399AG, NCP1399AH, NCP1399AI, NCP1399AJ, NCP1399AM)	12, 14	–	8	–	–

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

2. The NCP1399Ay version has skip adjustable externally.
3. Guaranteed by design.
4. Minimal impedance on P ON/OFF pin is 1 k Ω
5. Minimal resistance connected in series with bootstrap diode is 3.3 Ω

NCP1399 Series

ELECTRICAL CHARACTERISTICS

(For typical values $T_J = 25^\circ\text{C}$, for min/max values $T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$, $V_{CC} = 12\text{ V}$ unless otherwise noted.)

Symbol	Rating	Pin	Min	Typ	Max	Unit
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Start-up Sequence Parameters

t_{WATCHDOG}	Time duration to restart IC if start-up phase is not finished	12, 14	0.45	0.50	0.55	ms
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Feedback Section

R_{FB}	Internal pull-up resistor on FB pin	5	15	18	25	$\text{k}\Omega$
K_{FB}	V_{FB} to internal current set point division ratio	5	1.92	2.00	2.08	–
$V_{\text{FB_REF}}$	Internal voltage reference on the FB pin	5	4.60	4.95	5.30	V
$V_{\text{FB_CLAMP}}$	Internal clamp on FB input of On-time comparator referred to external FB pin voltage	5	4.4	4.6	4.8	V
$V_{\text{FB_SKIP_IN}}$	Feedback voltage thresholds to enters in skip mode for NCP1399By version (Note 2)	5	0.44	0.50	0.56	V
$V_{\text{FB_SKIP_HYST}}$	Skip comparator hysteresis (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AG, NCP1399AH, NCP1399AK, NCP1399AM)	5	130	160	200	mV
	Skip comparator hysteresis (NCP1399AF, NCP1399AJ, NCP1399AL)	5	105	140	175	
	Skip comparator hysteresis (NCP1399AI)	5	0	23	50	
$t_{1\text{st_MLOWER_SKIP}}$	On-time duration of 1 st Mlower pulse when FB cross $V_{\text{FB_SKIP_IN}} + V_{\text{FB_SKIP_HYST}}$ threshold (NCP1399AA, NCP1399BA, NCP1399AK, NCP1399AL)	5, 12	0.95	1.05	1.15	μs
	On-time duration of 1 st Mlower pulse when FB cross $V_{\text{FB_SKIP_IN}} + V_{\text{FB_SKIP_HYST}}$ threshold (NCP1399AC, NCP1399AG, NCP1399AI, NCP1399AM)	5, 12	1.8	1.9	2.1	μs
	On-time duration of 1 st Mlower pulse when FB cross $V_{\text{FB_SKIP_IN}} + V_{\text{FB_SKIP_HYST}}$ threshold (NCP1399AF, NCP1399AJ)	5, 12	1.08	1.20	1.32	μs
	On-time duration of 1 st Mlower pulse when FB cross $V_{\text{FB_SKIP_IN}} + V_{\text{FB_SKIP_HYST}}$ threshold (NCP1399AH)	5, 12	2.1	2.4	2.7	μs
$V_{1\text{st_MUPPER_SKIP}}$	Internal FB level reduction during 1 st Mupper pulse when FB cross $V_{\text{FB_SKIP_IN}} + V_{\text{FB_SKIP_HYST}}$ threshold (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AG, NCP1399AI, NCP1399AK, NCP1399AL, NCP1399AM) (Note 3)	5, 6, 14	–	150	–	mV
	Internal FB level reduction during 1 st Mupper pulse when FB cross $V_{\text{FB_SKIP_IN}} + V_{\text{FB_SKIP_HYST}}$ threshold (NCP1399AF, NCP1399AJ) (Note 3)	5, 6, 14	–	100	–	mV
	Internal FB level reduction during 1 st Mupper pulse when FB cross $V_{\text{FB_SKIP_IN}} + V_{\text{FB_SKIP_HYST}}$ threshold (NCP1399AH) (Note 3)	5, 6, 14	–	0	–	mV

Skip Input – NCP1399Ay version

I_{SKIP}	Internal Skip pin current source	4	48	50	52	μA
$C_{\text{SKIP_LOAD_MAX}}$	Maximum loading capacitance for skip pin voltage filtering (Note 3)	4	–	–	10	nF

Current Sense Input Section

$t_{\text{pd_CS}}$	On-time comparator delay to Mupper driver turn off $V_{\text{FB}} = 2.5\text{ V}$, V_{CS} goes up from -2.5 V to 2.5 V with rising edge of 100 ns	5, 6	–	–	250	ns
$I_{\text{CS_LEAKAGE}}$	Current sense input leakage current for $V_{\text{CS}} = \pm 3\text{ V}$	6	–	–	± 1	μA

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

2. The NCP1399Ay version has skip adjustable externally.
3. Guaranteed by design.
4. Minimal impedance on P ON/OFF pin is $1\text{ k}\Omega$
5. Minimal resistance connected in series with bootstrap diode is $3.3\ \Omega$

NCP1399 Series

ELECTRICAL CHARACTERISTICS

(For typical values $T_J = 25^\circ\text{C}$, for min/max values $T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$, $V_{CC} = 12\text{ V}$ unless otherwise noted.)

Symbol	Rating	Pin	Min	Typ	Max	Unit
--------	--------	-----	-----	-----	-----	------

Current Sense Input Section

V_{CS_OFFSET}	Current sense input offset voltage (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AG, NCP1399AH, NCP1399AI, NCP1399AK, NCP1399AL, NCP1399AM)	6	160	200	240	mV
	Current sense input offset voltage (NCP1399AF, NCP1399AJ)	6	110	150	190	mV
t_{LEB}	Leading edge blanking time of the on-time comparator output	5, 6, 14	360	440	540	ns

Faults and Auto-Recovery Timer

$t_{FB_FAULT_TIMER}$	FB fault timer duration (NCP1399AA, NCP1399BA, NCP1399AK, NCP1399AL)	–	160	200	240	ms
	FB fault timer duration (NCP1399AC, NCP1399AF, NCP1399AG, NCP1399AI, NCP1399AJ, NCP1399AM)	–	80	100	120	ms
	FB fault timer duration (NCP1399AH)	–	240	300	360	ms
$N_{FB_FAULT_COUNTER}$	Number of DRV pulses to confirm FB fault	–	–	1000	–	–
V_{FB_FAULT}	FB voltage when FB fault is detected	5	4.5	4.7	4.9	V
$N_{CS_FAULT_COUNTER}$	Number of CS_fault cmp. pulses to confirm CS fault	–	–	5	–	–
V_{CS_FAULT}	CS voltage when CS fault is detected (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AF, NCP1399AH, NCP1399AI, NCP1399AK, NCP1399AL, NCP1399AM) (NCP1399AG) (NCP1399AJ)	6				V
			2.5 3.2 1.85	2.7 3.4 2.00	2.9 3.6 2.15	
t_{A-REC_TIMER}	Auto-recovery duration, common timer for all fault condition (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AG, NCP1399AH, NCP1399AJ, NCP1399AK, NCP1399AL, NCP1399AM)	–	0.8	1	1.2	s
	Auto-recovery duration, common timer for all fault condition (NCP1399AI)	–	1.6	1.9	2.4	

Brown-Out Protection

V_{BO}	Brown-out turn-off threshold	3	0.965	1.000	1.035	V
I_{BO}	Brown-out hysteresis current, $V_{VBULK/PFC_FB} < V_{BO}$	3	4.3	5.0	5.4	μA
V_{BO_HYST}	Brown – Out comparator hysteresis	3	5	12	25	mV
I_{BO_BIAS}	Brown – Out input bias current	3	–	–	0.05	μA
t_{BO_FILTR}	BO filter duration	3	10	20	30	μs

Ramp Compensation

RC_{GAIN}	Ramp compensation gain (NCP1399AA, NCP1399BA, NCP1399AC, NCP1399AF, NCP1399AG, NCP1399AK, NCP1399AM)	–	58	82	108	mV/ μs
	Ramp compensation gain (NCP1399AI)		82	110	131	
	Ramp compensation gain (NCP1399AJ)		92	125	150	
	Ramp compensation gain (NCP1399AH)		107	149	168	
	Ramp compensation gain (NCP1399AL)		116	166	185	
t_{RC_SHIFT}	Ramp compensation time shift	–	–	0.6	–	μs

Temperature Shutdown Protection

T_{TSD}	Temperature shutdown T_J going up (NCP1399AA, NCP1399BA, NCP1399AH, NCP1399AK)	–	–	124	–	$^\circ\text{C}$
	Temperature shutdown T_J going up (NCP1399AC, NCP1399AF, NCP1399AG, NCP1399AI, NCP1399AJ, NCP1399AL, NCP1399AM)	–	–	137	–	$^\circ\text{C}$
T_{TSD_HYST}	Temperature shutdown hysteresis	–	–	30	–	$^\circ\text{C}$

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

2. The NCP1399Ay version has skip adjustable externally.
3. Guaranteed by design.
4. Minimal impedance on P ON/OFF pin is 1 k Ω
5. Minimal resistance connected in series with bootstrap diode is 3.3 Ω

NCP1399 Series

IC Options

Option	FB fault	FB fault source	Cumulative FB fault timer/counter	CS_FAULT	TON_MAX fault	OVP fault	OTP fault	Dedicated Soft_start_seq
NCP1399AA	Auto-recovery	Timer	NO	Auto-recovery	Auto-recovery	Latch	Auto-recovery	ON
NCP1399BA	Auto-recovery	Timer	NO	Auto-recovery	Auto-recovery	Latch	Auto-recovery	ON
NCP1399AC	Auto-recovery	Timer	NO	Auto-recovery	OFF	Latch	Latch	ON
NCP1399AF	Latch	Timer	NO	Latch	Latch	Latch	Latch	ON
NCP1399AG	Auto-recovery	Timer	NO	Auto-recovery	OFF	Latch	Auto-recovery	ON
NCP1399AH	Auto-recovery	Timer	NO	Auto-recovery	Auto-recovery	Latch	Auto-recovery	ON
NCP1399AI	Auto-recovery	Timer	NO	Auto-recovery	Auto-recovery	Auto-recovery	Auto-recovery	ON
NCP1399AJ	Auto-recovery	Timer	NO	Auto-recovery	Auto-recovery	Latch	Latch	ON
NCP1399AK	Auto-recovery	Timer	NO	Auto-recovery	Auto-recovery	Latch	Auto-recovery	ON
NCP1399AL	Auto-recovery	Timer	NO	Auto-recovery	Auto-recovery	Latch	Auto-recovery	ON
NCP1399AM	Auto-recovery	Timer	NO	Auto-recovery	OFF	Latch	Latch	ON

Option	PFC_MODE skip status	Dead time control	Dead time fault	OFF-mode version	OFF-mode status	BO status	Ramp comp status	P ON/OFF pull-up
NCP1399AA	ON	ZVS or DT_max	Auto-recovery	Active OFF	ON	ON	Without ramp shift	ON
NCP1399BA	ON		Auto-recovery	Active ON	ON	ON		ON
NCP1399AC	ON		Auto-recovery	Active OFF	ON	ON		ON
NCP1399AF	OFF		OFF	Active OFF	ON	ON		ON
NCP1399AG	OFF		Auto-recovery	-	OFF	ON		ON
NCP1399AH	ON		OFF	Active OFF	ON	ON		ON
NCP1399AI	ON		Auto-recovery	Active OFF	ON	ON		ON
NCP1399AJ	OFF		OFF	Active OFF	ON	ON		ON
NCP1399AK	OFF		Auto-recovery	Active OFF	ON	ON		ON
NCP1399AL	ON		OFF	Active OFF	ON	ON		ON
NCP1399AM	ON		OFF	Active OFF	ON	ON		ON

ORDERING INFORMATION

Part Number	Marking	Package	Shipping†
NCP1399AADR2G	NCP1399AA	SOIC-16 (Pb-Free)	2500 / Tape & Reel
NCP1399BADR2G	NCP1399BA		
NCP1399ACDR2G	NCP1399AC		
NCP1399AFDR2G	NCP1399AF		
NCP1399AGDR2G	NCP1399AG		
NCP1399AHDR2G	NCP1399AH		
NCP1399AIDR2G	NCP1399AI		
NCP1399AJDR2G	NCP1399AJ		
NCP1399AKDR2G	NCP1399AK		
NCP1399ALDR2G	NCP1399AL		
NCP1399AMDR2G	NCP1399AM		

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

NCP1399 Series

TYPICAL CHARACTERISTICS

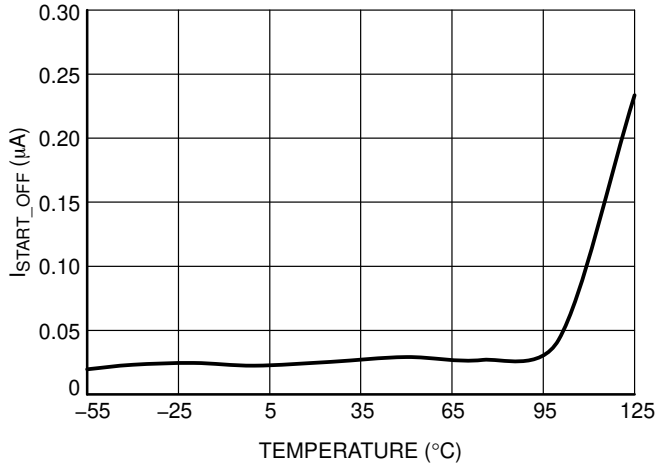


Figure 5. I_{START_OFF} vs. Temperature

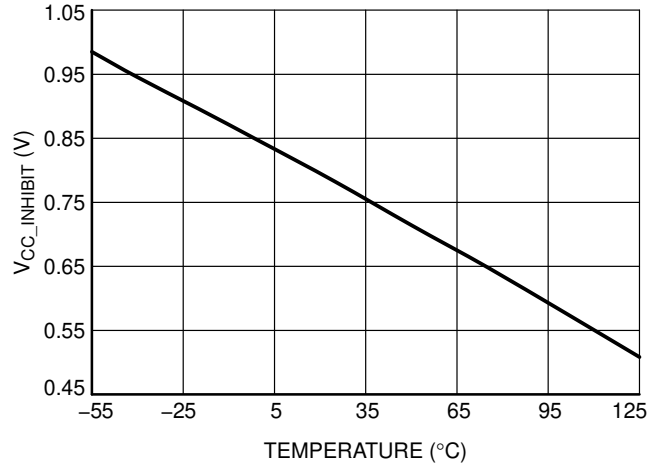


Figure 6. V_{CC_INHIBIT} vs. Temperature

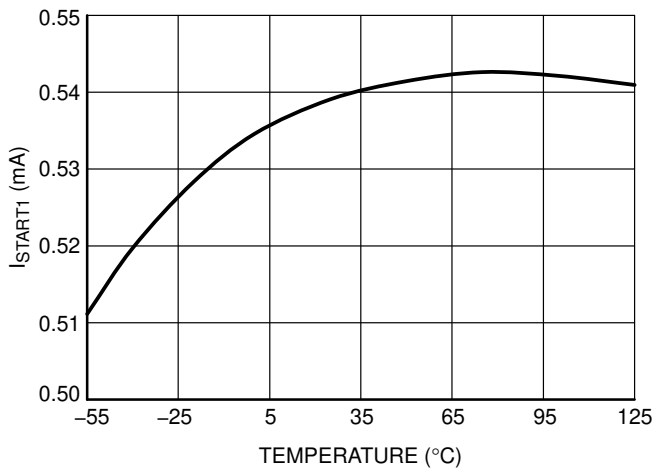


Figure 7. I_{START1} vs. Temperature

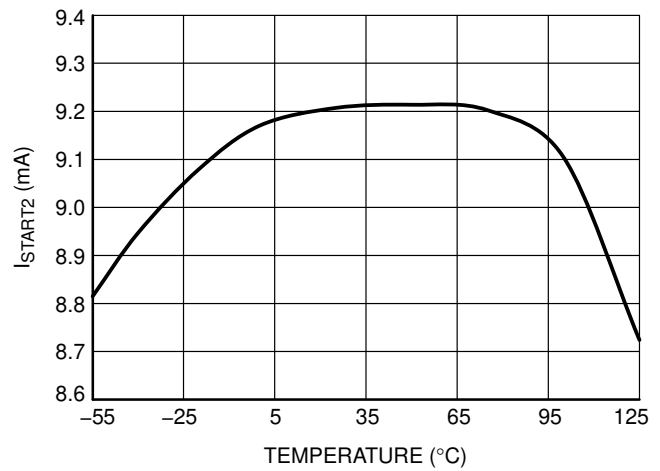


Figure 8. I_{START2} vs. Temperature

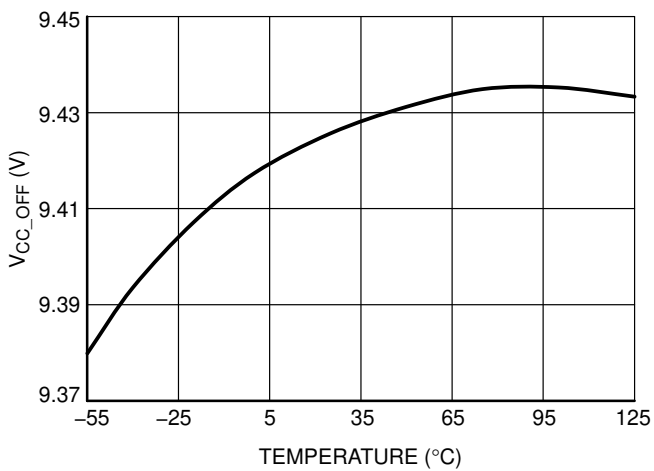


Figure 9. V_{CC_OFF} vs. Temperature

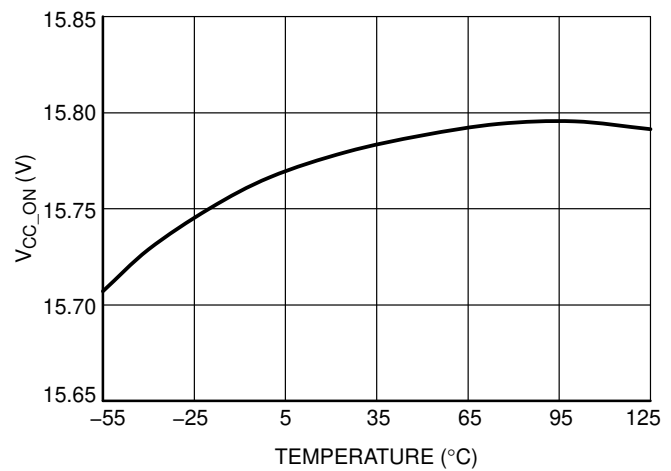


Figure 10. V_{CC_ON} vs. Temperature

NCP1399 Series

TYPICAL CHARACTERISTICS

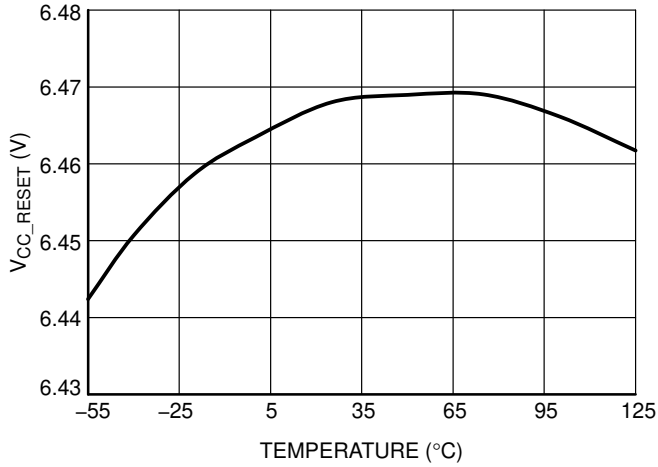


Figure 11. V_{CC_RESET} vs. Temperature

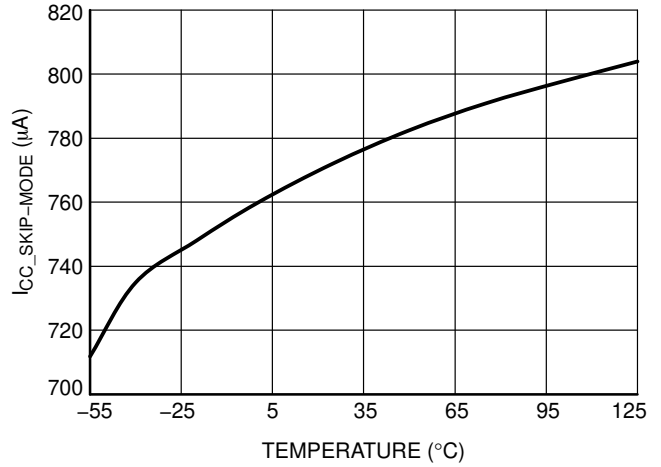


Figure 12. I_{CC_SKIP-MODE} vs. Temperature

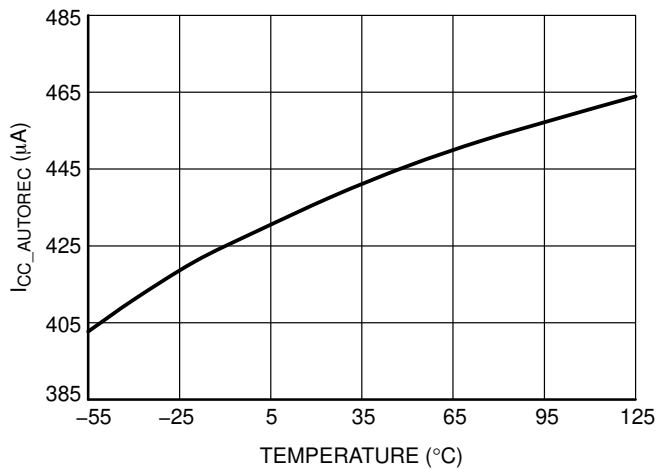


Figure 13. I_{CC_AUTOREC} vs. Temperature

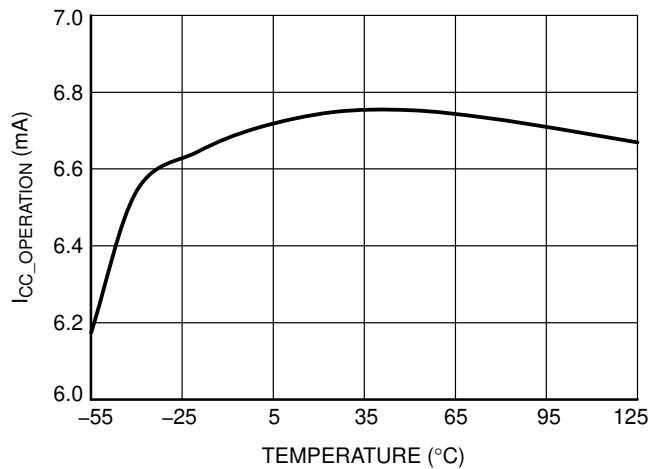


Figure 14. I_{CC_OPERATION} vs. Temperature

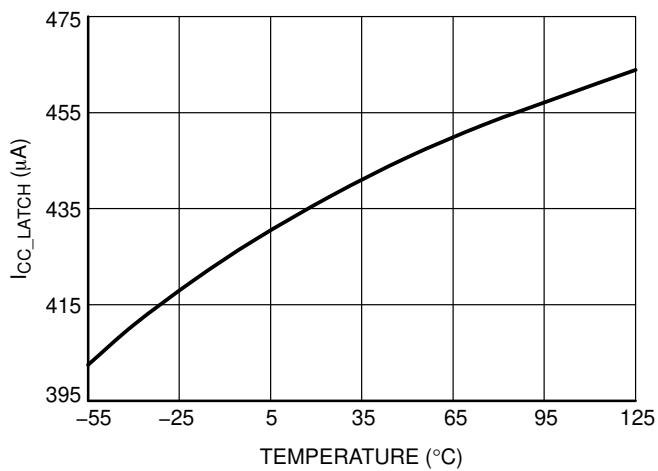


Figure 15. I_{CC_LATCH} vs. Temperature

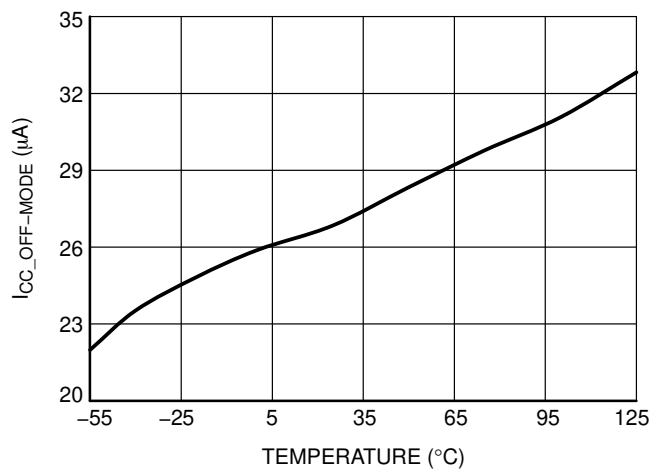


Figure 16. I_{CC_OFF-MODE} vs. Temperature

NCP1399 Series

TYPICAL CHARACTERISTICS

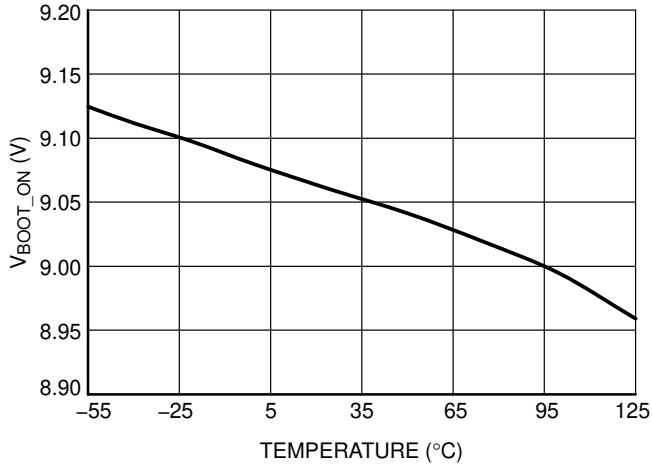


Figure 17. V_{BOOT_ON} vs. Temperature

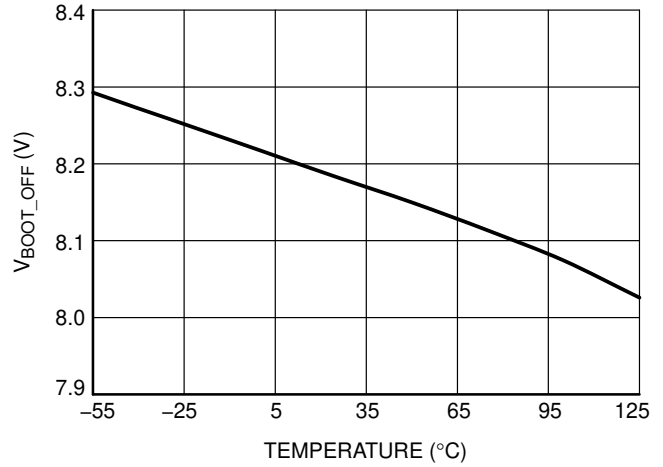


Figure 18. V_{BOOT_OFF} vs. Temperature

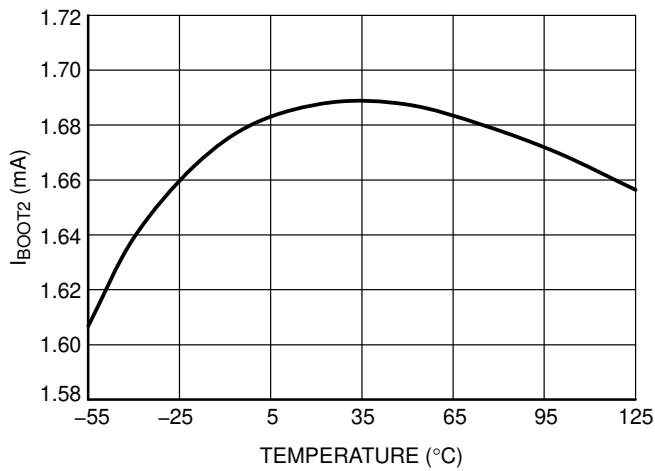


Figure 19. I_{BOOT2} vs. Temperature

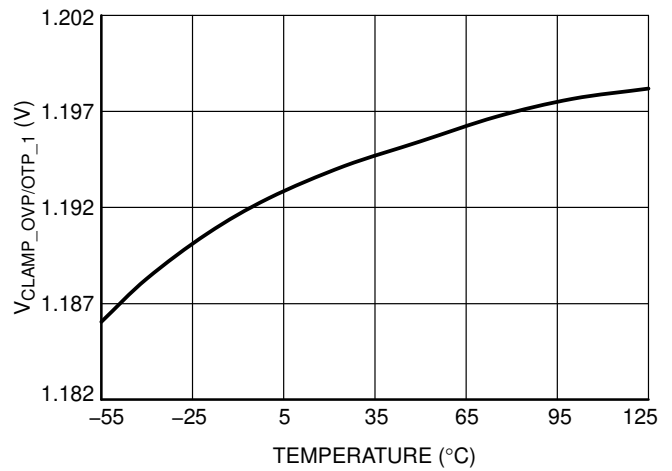


Figure 20. V_{CLAMP_OVP/OTP_1} vs. Temperature

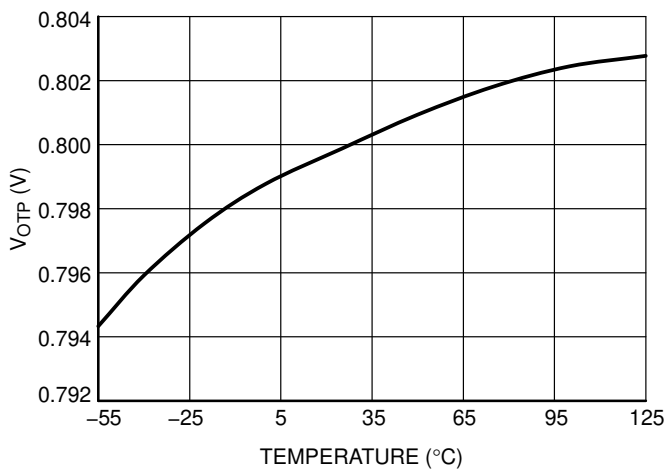


Figure 21. V_{OTP} vs. Temperature

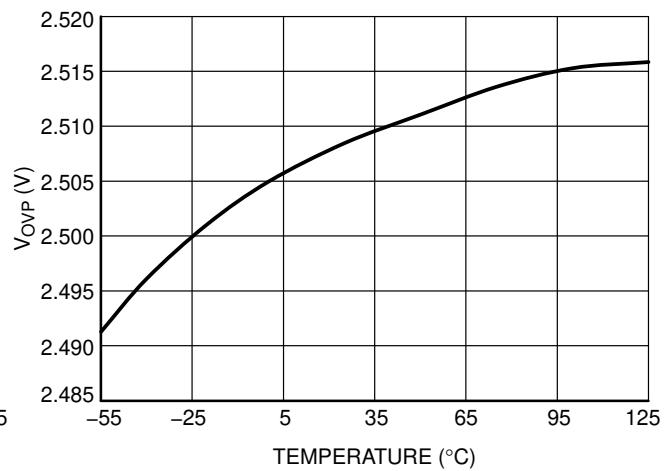


Figure 22. V_{OVP} vs. Temperature

NCP1399 Series

TYPICAL CHARACTERISTICS

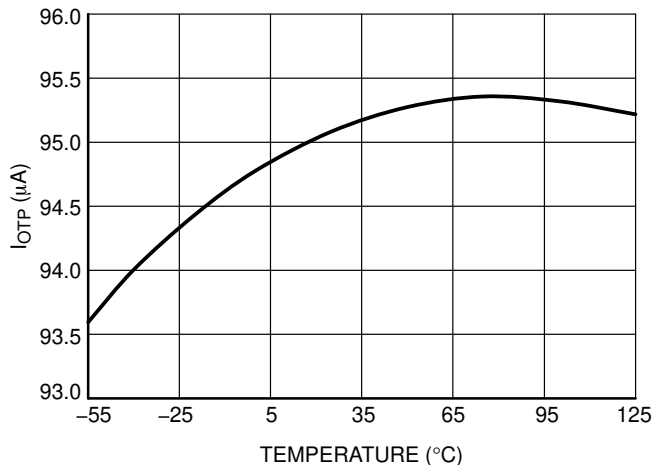


Figure 23. I_{OTP} vs. Temperature

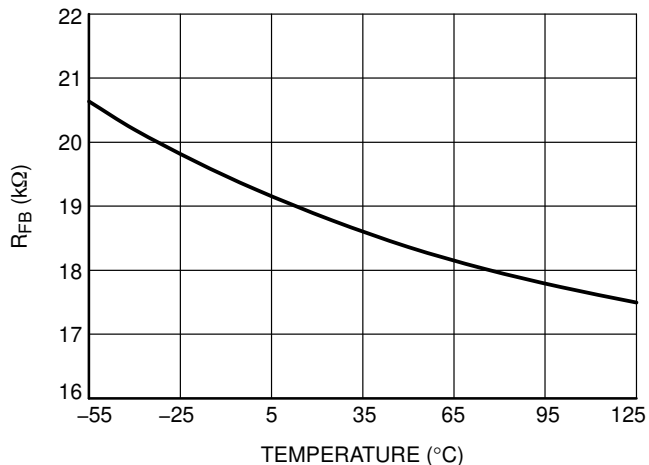


Figure 24. R_{FB} vs. Temperature

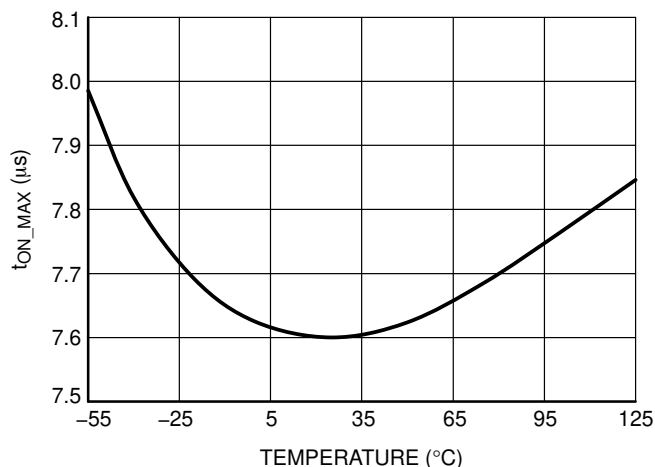


Figure 25. t_{ON_MAX} vs. Temperature

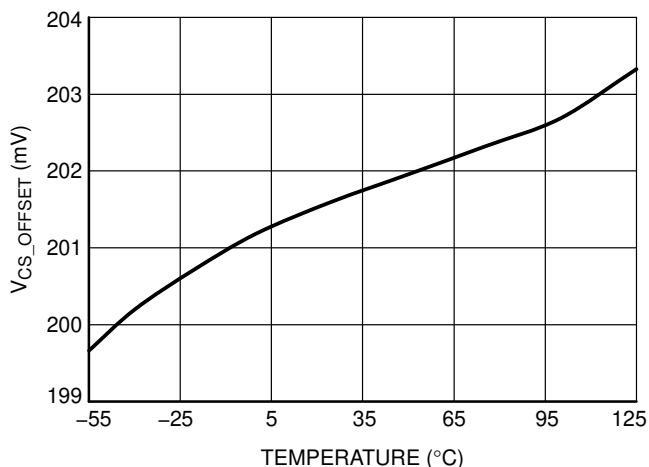


Figure 26. V_{CS_OFFSET} vs. Temperature

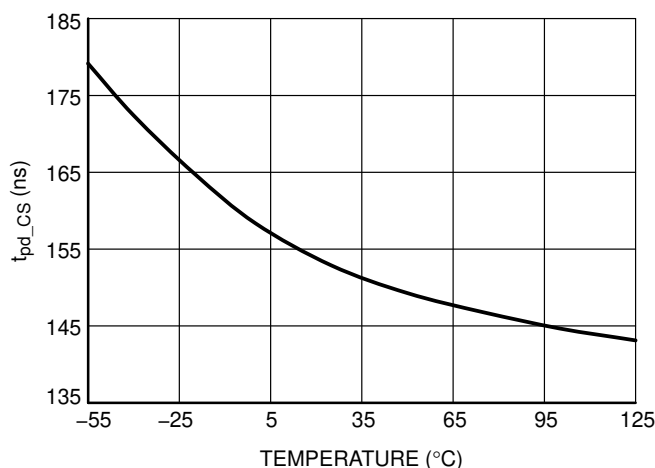


Figure 27. t_{pd_CS} vs. Temperature

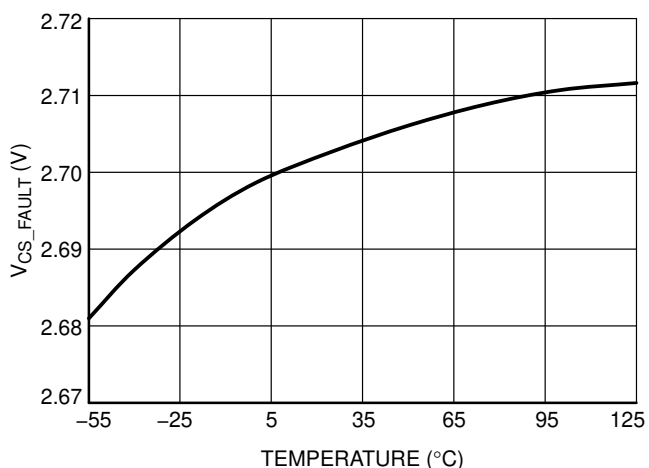


Figure 28. V_{CS_FAULT} vs. Temperature

NCP1399 Series

TYPICAL CHARACTERISTICS

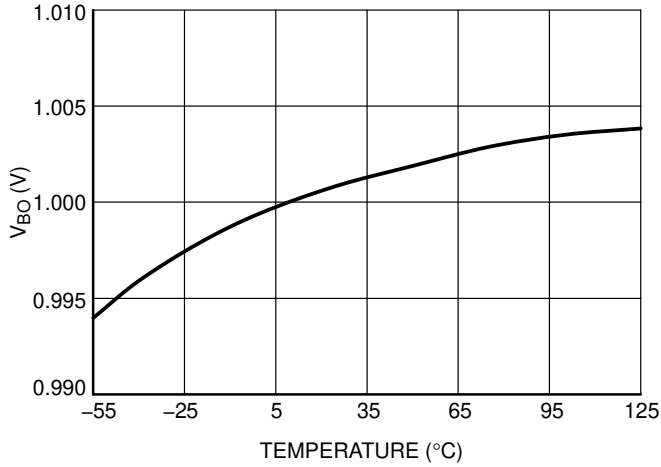


Figure 29. V_{BO} vs. Temperature

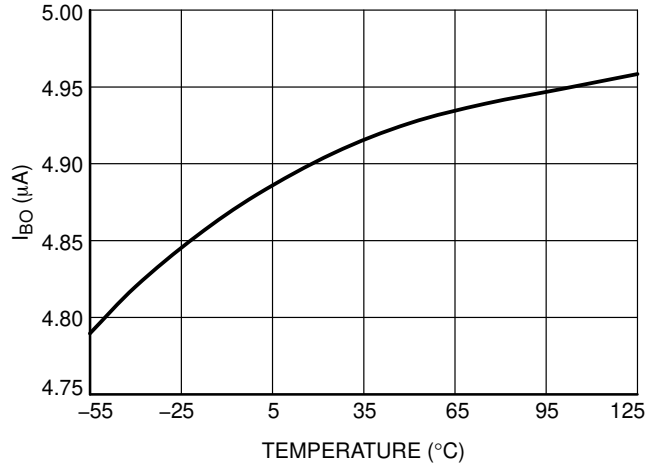


Figure 30. I_{BO} vs. Temperature

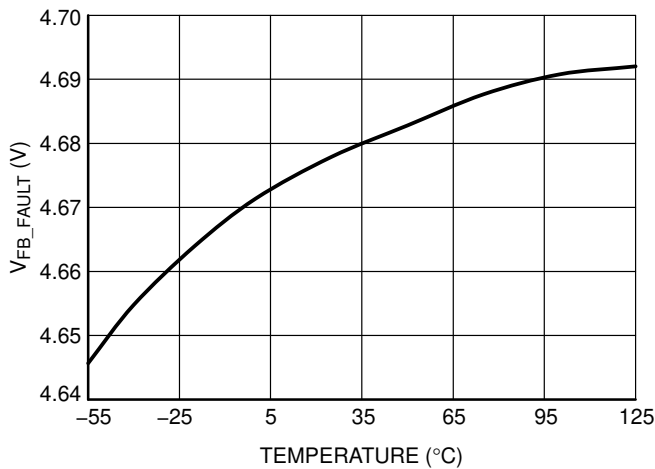


Figure 31. V_{FB_FAULT} vs. Temperature

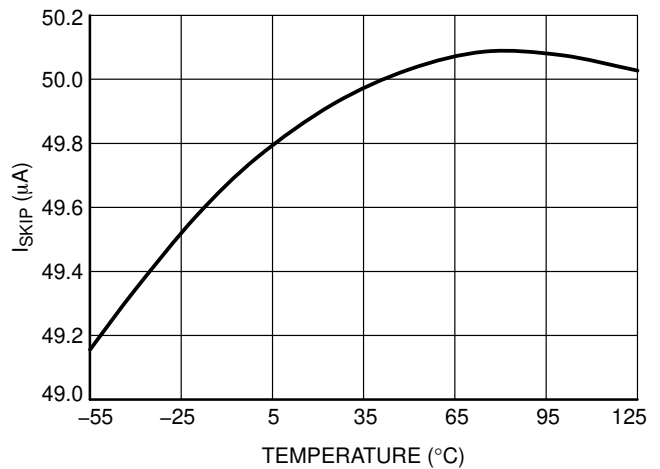


Figure 32. I_{SKIP} vs. Temperature

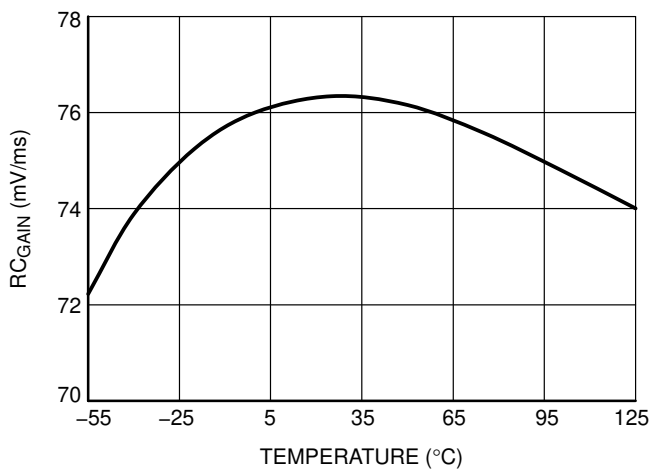


Figure 33. RC_{GAIN} vs. Temperature

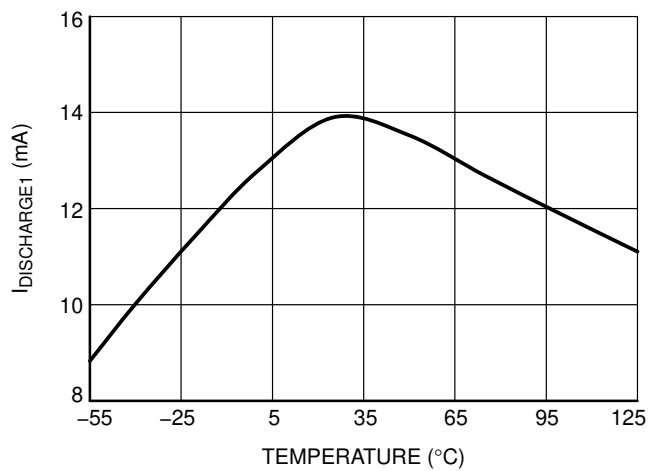


Figure 34. I_{DISCHARGE1} vs. Temperature

NCP1399 Series

TYPICAL CHARACTERISTICS

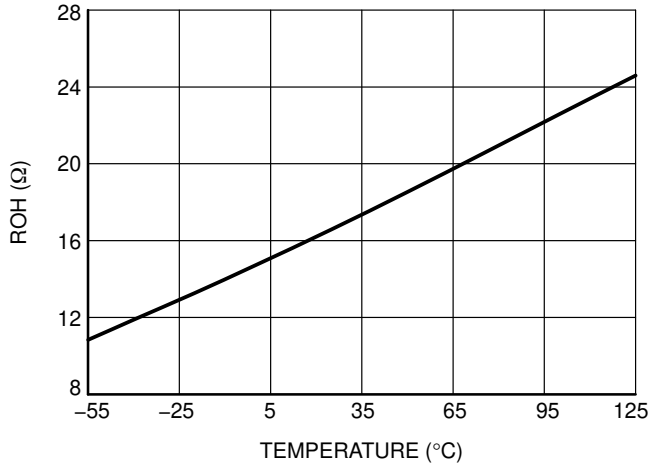


Figure 35. ROH vs. Temperature

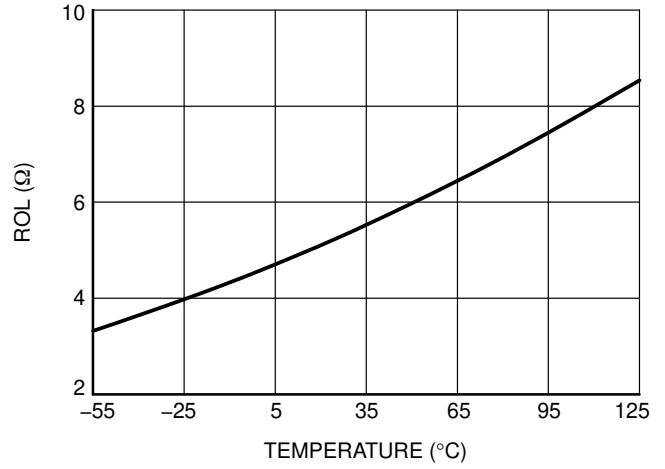


Figure 36. ROL vs. Temperature

VCC Management with High-voltage Startup Current Source

The NCP1399 controller features a HV startup current source that allows fast startup time and extremely low standby power consumption. Two startup current levels (I_{start1} and I_{start2}) are provided by the system for safety in case of short circuit between VCC and GND pins. In addition, the HV startup current source features a dedicated over-temperature protection to prevent IC damage for any

failure mode that may occur in the application. The HV startup current source is primarily enabled or disabled based on VCC level. The startup HV current source can be also enabled by BO_OK rising edge, auto-recovery timer end, REMote and TSD end event. The HV startup current source charges the VCC capacitor before IC start-up.

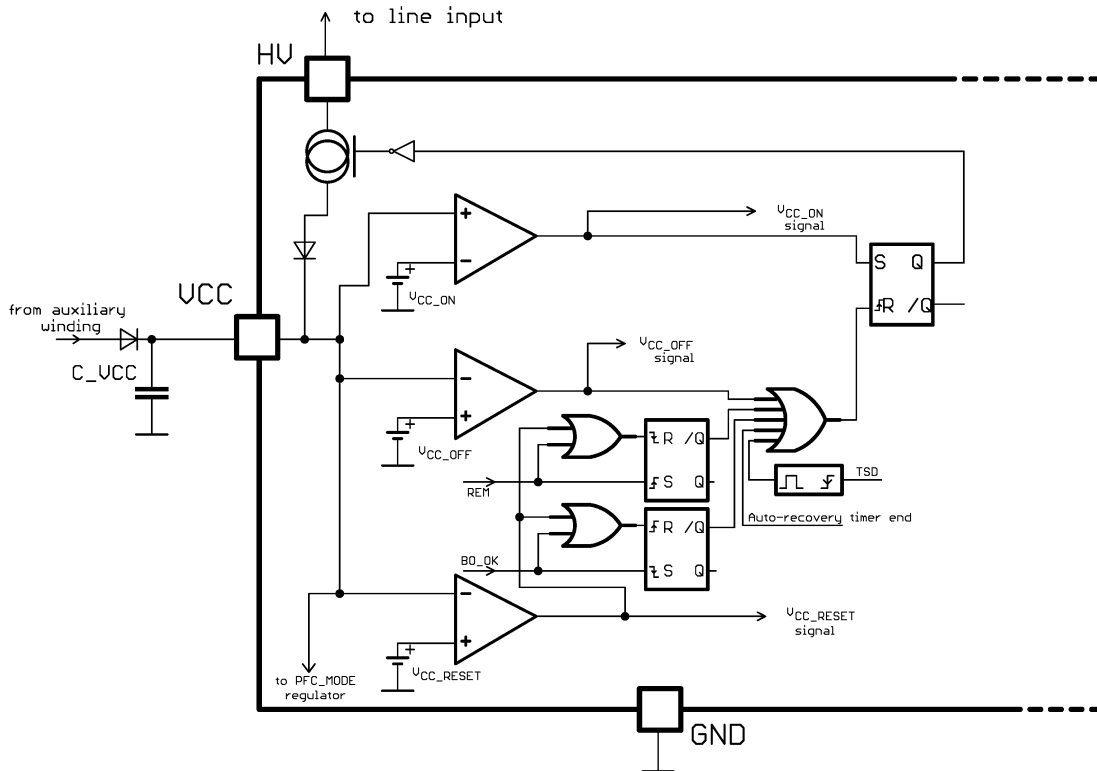


Figure 37. Internal Connection of the VCC Management Block

The NCP1399 controller disables the HV startup current source once the VCC pin voltage level reaches V_{CC_ON} threshold – refer to Figure 37. The application then starts operation and the auxiliary winding maintains the voltage bias for the controller during normal and skip-mode operating modes. The IC operates in so called Dynamic Self Supply (DSS) mode when the bias from auxiliary winding is not sufficient to keep the VCC voltage above V_{CC_OFF} threshold (i.e. VCC voltage is cycling between V_{CC_ON} and V_{CC_OFF} thresholds with no driver pulses on the output during positive VCC ramp). The HV source is also operated in DSS mode when the low voltage controller enters off-mode or fault-mode operation. In this case the VCC pin voltage will cycle between V_{CC_ON} and V_{CC_OFF} thresholds and the controller will not deliver any driver pulse – waiting for return from the off-mode or latch mode operation. Please refer to figures Figure 61 through

Figure 65 to find an illustration of the NCP1399 VCC management system under all operating conditions/modes.

The HV startup current source features an independent over-temperature protection system to limit I_{start2} current when the die temperature reaches 130°C. At this temperature, I_{start2} will be progressively to prevent the die temperature from rising above 130°C.

Brown-out Protection – VBULK/PFC FB Input

Resonant tank of an LLC converter is always designed to operate within a specific bulk voltage range. Operation below minimum bulk voltage level would result in current and temperature overstress of the converter power stage. The NCP1399 controller features a VBULK/PFC FB input in order to precisely adjust the bulk voltage turn-ON and turn-OFF levels. This Brown-Out protection (BO) greatly simplifies application level design.

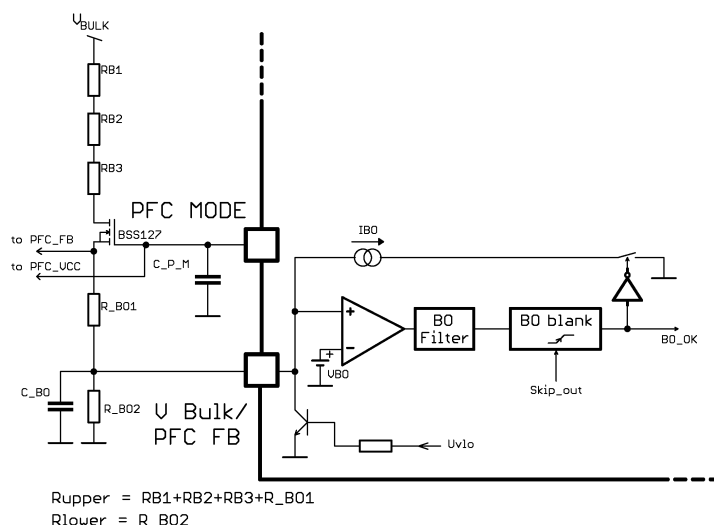


Figure 38. Internal Connection of the Brown-out Protection Block

The internal circuitry shown in Figure 38 allows monitoring the high-voltage input rail (V_{bulk}). A high-impedance resistive divider made of R_{upper} and R_{lower} resistors brings a portion of the V_{bulk} rail to the VBULK/PFC FB pin. The Current sink (I_{BO}) is active below the bulk voltage turn-on level (V_{bulk_ON}). Therefore, the bulk voltage turn-on level is higher than defined by the division ratio of the resistive divider. To the contrary, when the internal BO_OK signal is high, i.e. the application is running, the I_{BO} sink is disabled. The bulk voltage turn-off threshold (V_{bulk_OFF}) is then given by BO comparator reference voltage directly on the resistor divider. The advantage of this solution is that the V_{bulk_OFF} threshold precision is not affected by I_{BO} hysteresis current sink tolerance.

The V_{bulk_ON} and V_{bulk_OFF} levels can be calculated using equations below:

The I_{BO} is ON:

$$V_{BO} + V_{BOhyst} = V_{bulk_ON} \cdot \frac{R_{lower}}{R_{lower} + R_{upper}} - I_{BO} \cdot \left(\frac{R_{lower} \cdot R_{upper}}{R_{lower} + R_{upper}} \right) \quad (eq. 1)$$

The I_{BO} is OFF:

$$V_{BO} = V_{bulk_OFF} \cdot \frac{R_{lower}}{R_{lower} + R_{upper}} \quad (eq. 2)$$

One can extract R_{lower} term from equation 2 and use it in equation 1 to get needed R_{upper} value:

$$R_{lower} = \frac{\frac{V_{bulk_ON} \cdot V_{BO}}{V_{bulk_OFF}} - V_{BO} - V_{BOhyst}}{I_{BO} \cdot \left(1 - \frac{V_{BO}}{V_{bulk_OFF}} \right)} \quad (eq. 3)$$

$$R_{upper} = R_{lower} \cdot \frac{V_{bulk_OFF} - V_{BO}}{V_{BO}} \quad (eq. 4)$$

Note that the VBULK/PFC FB pin is pulled down by an internal switch when the controller is in startup phase – i.e. when the V_{CC} voltage ramps up from $V_{CC} < V_{CC_RESET}$ towards the V_{CC_ON} level on the VCC pin. This feature assures that the VBULK/PFC FB pin voltage will not ramp up before the IC operation starts. The I_{BO} hysteresis current sink is activated and BO discharge switch is disabled once the V_{CC} voltage crosses V_{CC_ON} threshold. The VBULK/PFC FB pin voltage then ramps up naturally according to the BO divider information. The BO comparator then authorizes or disables the LLC stage operation based on the actual V_{bulk} level.

The low I_{BO} hysteresis current of the NCP1399 brown out protection system allows increasing the bulk voltage divider resistance and thus reduces the application power consumption during light load operation. On the other hand, the high impedance divider can be noise sensitive due to capacitive coupling to HV switching traces in the application. This is why a filter (t_{BO_FILTR}) is added after the BO comparator in order to increase the system noise immunity. Despite the internal filtering, it is also recommended to keep a good layout for BO divider resistors and use a small external filtering capacitor on the VBULK/PFC pin if precise BO detection wants to be achieved.

The bulk voltage HV divider can be also used by a PFC front stage controller as a feedback sensing network (refer again to Figure 38). The shared bulk voltage resistor divider between PFC and LLC stage offers a way how to further reduce power losses during off-mode and no-load operation. The NCP1399 features a PFC MODE pin that disconnects bias of the PFC stage during light load, off-mode or fault mode operation. The signal from the PFC MODE pin can be also used to control an external HV switch in order to disconnect the bulk voltage divider from bulk during off-mode operation. This technique further reduces

the no-load power consumption down again since the power losses of voltage divider are not affected by the bulk voltage at all.

Please refer to Figure 61 through Figure 65 for an illustration of NCP1399 Brown-out protection system in all operating conditions/modes.

Over-voltage and Over-temperature Protection

The OVP/OTP pin is a dedicated input to allow for a simple and cost effective implementation of two key protection features that are needed in adapter applications: over-voltage (OVP) and over-temperature (OTP) protections. Both of these protections can be either latched or auto-recovery- depending on the version of NCP1399. The OVP/OTP pin has two voltage threshold levels of detection (V_{OVP} and V_{OTP}) that define a no-fault window. The controller is allowed to run when OVP/OTP input voltage is within this working window. The controller stops

the operation, after filter time delay, when the OVP/OTP input voltage is out of the no-fault window. The controller then either latches-off or starts an auto-recovery timer – depending on the IC version – and triggered the protection threshold (V_{OTP} or V_{OVP}).

The internal current source I_{OTP} allows a simple OTP implementation by using a single negative temperature coefficient (NTC) thermistor. An active soft clamp composed from V_{clamp} and R_{clamp} components prevents the OVP/OTP pin voltage from reaching the V_{OVP} threshold when the pin is pulled up by the I_{OTP} current. An external pull-up current, higher than the pull-down capability of the internal clamp ($V_{CLAMP_OVP/OTP}$), has to be applied to pull the OVP/OTP pin above V_{OVP} threshold to activate the OVP protection. The t_{OVP_FILTER} and t_{OTP_FILTER} filters are implemented in the system to avoid any false triggering of the protections due to application noise and/or poor layout.

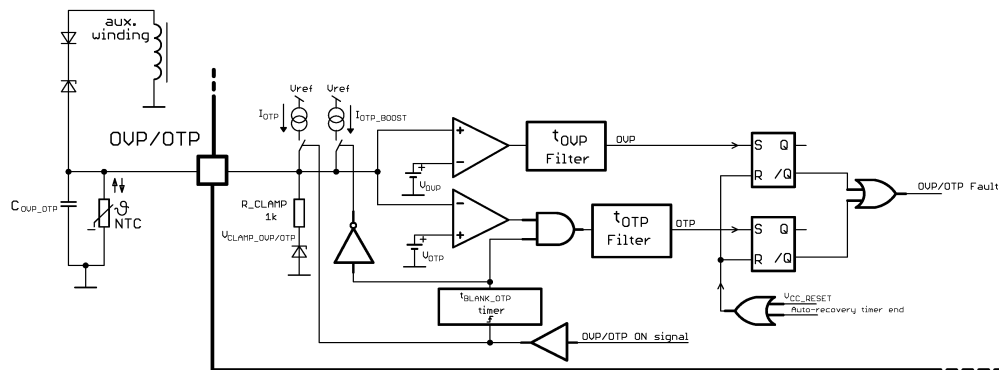


Figure 39. Internal Connection of OVP/OTP Input

The OTP protection could be falsely triggered during controller startup due to the external filtering capacitor charging current. Thus the t_{BLANK_OTP} period has been implemented in the system to overcome such behavior. The OTP comparator output is ignored during t_{BLANK_OTP} period. In order to speed up the charging of the external filtering capacitor C_{OVP_OTP} connected to OVP/OTP pin, the I_{OTP} current has been doubled to I_{OTP_BOOST} . The maximum value of filtering capacitor is 47 nF.

The OVP/OTP ON signal is set after the following events:

- the V_{CC} voltage exceeds the V_{CC_ON} threshold during first start-up phase (after V_{CC} pin voltage was below V_{CC_RESET} threshold)
- BO OK signal is received from BO block
- Auto-recovery timer elapsed and a new restart occurs

- IC returns to operation from skip-mode ($V_{FB_SKIP_IN} + V_{FB_SKIP_HYST}$ threshold was reached)
- IC returns to operation from off-mode (V_{REM_ON} or $V_{FB_REM_ON}$ signal is received by off-mode control block)

The I_{OTP} current source is disabled when:

- V_{CC} falls below V_{CC_OFF} threshold
- BO OK signal goes to low state (i.e. Brown-out condition occurs on the mains)
- Fault signal is activated (Auto-recovery timer starts counting or Latch fault is present)
- IC goes into the skip-mode operation ($V_{FB_SKIP_IN}$ threshold was reached)
- IC goes into the off-mode operation (V_{REM_OFF} or ($V_{FB_REM_OFF}$ & V_{CC_OFF}) signal was reached)

NCP1399 Series

The latched OVP or OTP versions of NCP1399 enters latched protection mode when V_{CC} voltage cycles between V_{CC_ON} and V_{CC_OFF} thresholds and no pulses are provided by drivers. The controller V_{CC} pin voltage has to be cycled down below V_{CC_RESET} threshold in order to restart operation. This would happen when the power supply is unplugged from the mains.

SKIP/REM Input and Off-mode Control

The NCP1399 implements an ultra-low power consumption mode of operation called off-mode. The application output voltage is cycled between the nominal and lower levels that are defined by the secondary side off-mode controller (like NCP435x secondary off-mode controller). The output voltage is thus not regulated to nominal level but is always kept at a high enough voltage level to provide bias for the necessary circuits in the target application – for example this could be the case of microcontroller with very low consumption that handles V_{CC} management in a notebook or TV. The no-load input power consumption could be significantly reduced when using described technique. The NCP1399 implements two different off-mode control system approaches:

- Active ON off-mode control – available on the NCP1399By device family

- Active OFF off-mode control – available on the NCP1399Ay device family

These two off-mode operation control techniques differ in the way the off-mode operation is started on the primary side controller. Both of these methods are described separately hereinafter.

Active ON Off-mode Control – NCP1399B Device Family

The NCP1399B device family uses a SKIP/REM pin only for off-mode operation control– i.e. the pin is internally connected to the Active ON off-mode control block and the skip mode threshold level is not adjustable externally. The skip mode comparator threshold can be adjusted only internally (by IC option) in this package option. The SKIP/REM pin when used for off-mode control allows the user to activate the ultra-low consumption mode during which the IC consumption is reduced to only very low HV pin leakage current ($I_{HV_OFF-MODE}$) and very low V_{CC} pin consumption ($I_{CC_OFF-MODE}$). The off-mode is activated when SKIP/REM pin voltage exceeds V_{REM_OFF} threshold. Normal operating mode is resumed when SKIP/REM pin voltage drops below V_{REM_ON} threshold – refer to Figure 40 for an illustration.

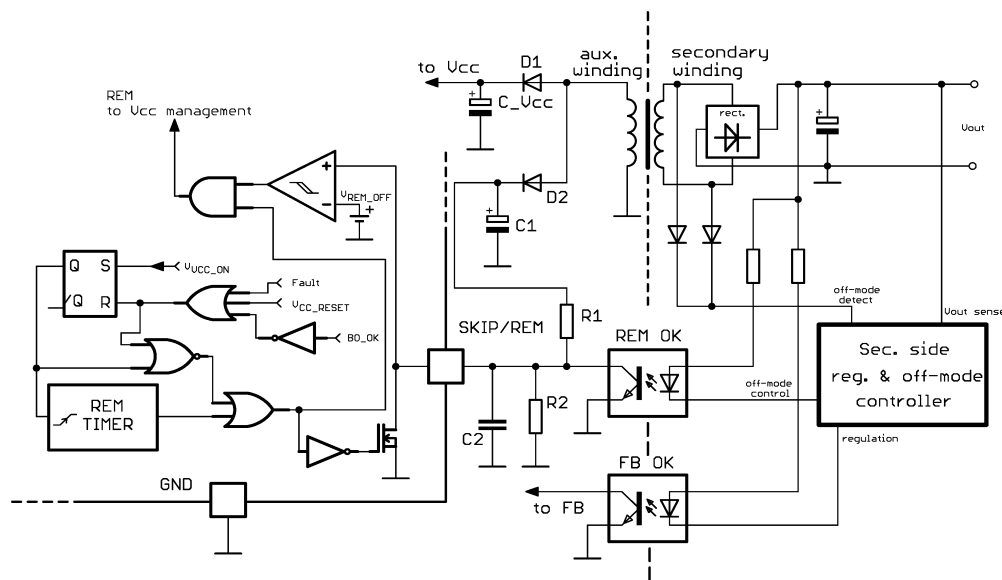


Figure 40. SKIP/REM Input Internal Connection – Active ON Version

The off-mode operation is activated by the secondary side off-mode controller. The auxiliary bias for primary side off-mode control is provided by a circuit composed of components D_2 , C_1 , R_1 , R_2 and C_2 . The SKIP/REM pin is pulled up by this auxiliary supply circuit once the REM optocoupler (REM OK) is released. The application then operates in off-mode until the secondary side off-mode controller activates the REM optocoupler or until the auxiliary bias on C_1 is lost. Normal operation mode is then recovered via power stage startup. The application is thus

switching between ON-mode and OFF-mode states when off-mode control is implemented. The OFF mode period last significantly longer time (tens of seconds or more) compared to the secondary capacitor refilling period (few tens of milliseconds) – this explains why the no-load input power consumption can be drastically reduced. The auxiliary off-mode supply capacitor C_1 can stay charged while the secondary bias is lost – this can happen during overload or other fault mode conditions. A REM TIMER is thus implemented in the system to allow fast application

restart in such cases. The controller blanks the SKIP/REM input information and pulls down the SKIP/REM input for t_{REM_TIMER} time during controller restart so that the secondary side bias can be restored and the secondary off-mode controller can activate the REM optocoupler. This REM TIMER blank sequence is activated each time the VCC pin voltage reaches V_{CC_ON} threshold – except in the situation when after IC left off-mode operation by standard way and V_{CC} is restored – i.e. when the REM optocoupler is activated by the secondary off-mode controller.

The SKIP/REM input blanking is activated in following cases:

- VCC pin voltage reaches V_{CC_ON} threshold during first start-up phase (i.e. when V_{CC} was below V_{CC_RESET} threshold before)
- Auto-recovery timer elapsed and new start is initiated

The REM TIMER helps to assure fast application re-start from fault conditions by forcing controller operation after t_{REM_TIMER} . However, the secondary controller drives the remote pin via REM optocoupler during normal operating conditions in order to switch between ON and OFF operating modes. The controller is active for very short time during no-load conditions – just during the time needed to re-fill the secondary side capacitors to the nominal output voltage level. In this case we do not use REM TIMER because it would increase the no-load power consumption by forcing the application to run for a longer time than necessary. The REM TIMER blank period is thus not activated in no-load conditions.

The bias on VCC pin needs to be assured when off-mode operation takes place. The auxiliary winding is no more able to provide any bias thus the HV startup current source is operated in DSS mode – i.e. the VCC pin voltage is cycling between V_{CC_ON} and V_{CC_OFF} thresholds. This approach keeps IC biasing in order to memorize the current operation state.

Please refer to Figure 64 for an illustration on how the NCP1399 Active ON off-mode system works under all operating conditions/modes.

Active OFF Off-mode Control – NCP1399A Device Family

The NCP1399A device family uses LLC FB pin voltage information for off-mode operation detection – refer to Figure 41. The SKIP/REM pin is internally connected to the skip mode block in this case and serves as a $V_{FB_SKIP_IN}$ threshold voltage adjust pin. The secondary off-mode controller reuses the LLC stage regulation optocoupler in order to reduce total system cost. The off-mode operation is initiated once the LLC FB pin is pulled down below V_{REM_ON} threshold and the VCC pin voltage drops below V_{CC_OFF} threshold in the same time. The optocoupler has to be active at all time the application is held in off-mode. No biased is then provided by the secondary off-mode controller during normal operation – this is why this approach is called Active OFF off-mode operation. The application no-load input power consumption is slightly higher compared to Active ON off-mode solution, previously described, because the optocoupler needs to be biased during off mode operation

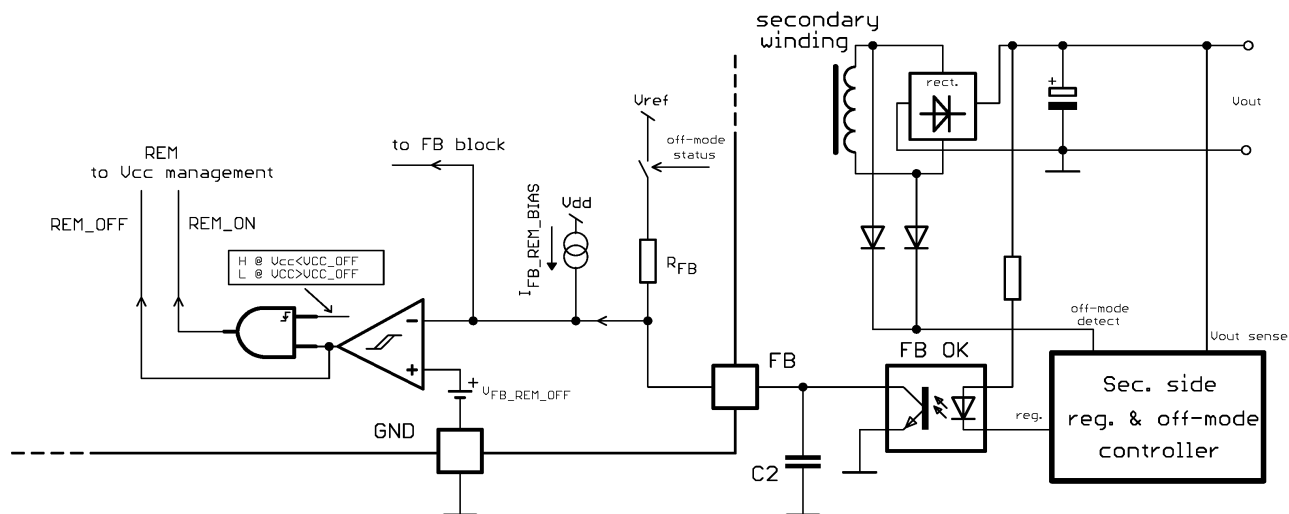


Figure 41. Active OFF Off-mode Internal Detection Based on the LLC FB Pin Voltage

The controller monitors the LLC FB pin voltage level and restarts via regular startup sequence (including VCC pin voltage ramp-up to V_{CC_ON} level and soft-start) once the FB pin is released by the secondary off-mode controller.

The HV startup current source is working in DSS mode during application off-mode operation – i.e. the VCC pin

voltage is cycling between V_{CC_ON} and V_{CC_OFF} thresholds. This approach keeps IC biased so that the actual operation state is memorized. The LLC FB pin pull-up resistor is disconnected when off-mode operation is activated in order to reduce IC power consumption and also needed current for optocoupler driving from secondary side.

Please refer to Figure 65 for an illustration on how the NCP1399 active ON off-mode system works under all operating conditions/modes.

PFC MODE Output and P ON/OFF Control Pin

The NCP1399 has two pins P ON/OFF and PFC MODE that can be used to disable or enable PFC stage operation based on actual application operating state – please refer to Figure 46. The PFC MODE pin voltage is changed ($V_{PFC_M_ON}$ or $V_{PFC_M_BO}$) based on the actual P ON/OFF input logic signal state. Minimum impedance connected to

P ON/OFF pin is 1 k Ω . The PFC stage operation can thus be disabled/enabled via external logic signal. This option should be used with the wide range input voltage LLC tank designed to assure correct operation of the LLC stage through whole bulk voltage range. The PFC MODE output pin can be used for two purposes:

1. to control the external small signal HV MOSFET switch that connects the bulk voltage divider to the VBULK/PFC FB input
2. to control the PFC front stage controller operation via PFC controller supply pin

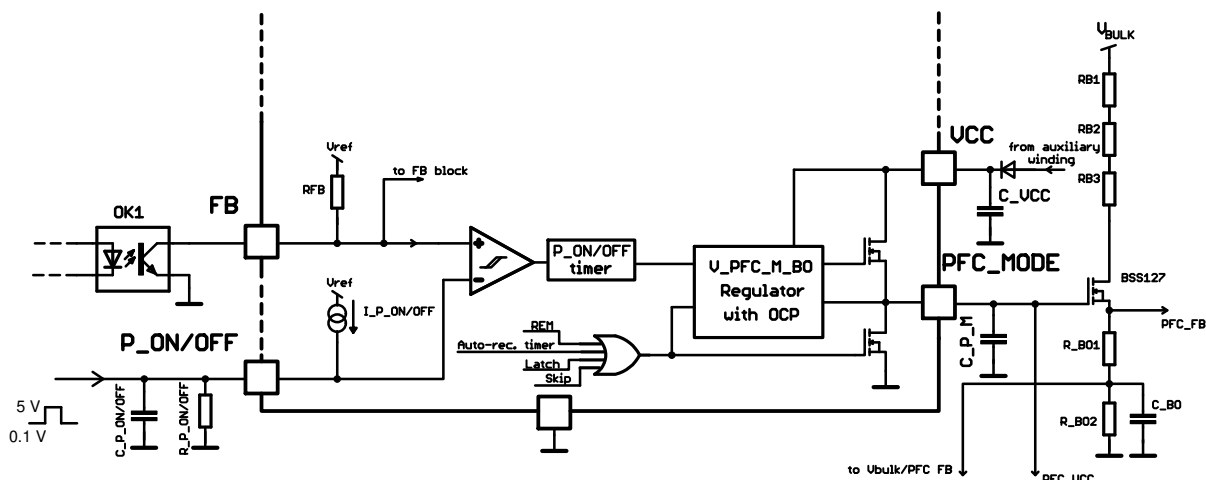


Figure 42. Internal Connection of the PFC MODE and P ON/OFF Blocks

There are three possible states of the PFC MODE output that can be placed by the controller based on the application operating conditions:

1. The PFC MODE output pin is pulled-down by an internal MOSFET switch before controller startup. This technique ensures minimum VCC pin current consumption in order to ramp V_{CC} voltage in a short time from the HV startup current source which speeds up the startup or restart process. The PFC MODE output pin is also pulled-down in off-mode or protection mode during which the HV startup current source is operated in DSS mode. This reduces the application power consumption in both cases.
2. The pull-down switch is disabled and the internal regulator enabled by the controller to provide V_{PFC_M_BO} reference when an external logic signal on the P ON/OFF pin is at “high” state. An internal regulator includes current limitation for the PFC MODE output that is set to I_{PFC_M_LIM} when V_{PFC_M_BO} reference is provided. The PFC MODE pin drives external small signal HV MOSFET switch to keep bulk voltage divider connected. The LLC power stage Brown-out protection system thus works when the LLC stage is switching while PFC stage disabled.
3. The pull-down switch is disabled and the internal regulator is switched to bypass mode in which it

connects VCC pin voltage to PFC MODE output with minimum dropout ($V_{PFC_M_ON}$). This state of the PFC MODE output appears in case an external signal on the P ON/OFF pin is at “low” state.

The output power level is derived internally from the actual FB pin voltage. This information could be compared on external comparator with the reference level and control the P ON/OFF input, thus the user has possibility to adjust power below which the PFC stage is disabled in order to increase efficiency in light load conditions. The P ON/OFF comparator features an hysteresis (P_ON/OFF_{HYST}) proportional to the set P ON/OFF level in order to overcome PFC power stage oscillations (periodical ON/OFF operation). The P ON/OFF timer (t_{P_ON/OFF_TIMER}) is implemented to ensure a long enough propagation delay from the PFC turn OFF detection to PFC MODE output deactivation. This timer is unidirectional so that it resets immediately after PFC ON condition is detected by the P ON/OFF comparator. This technique is used in order to avoid a PFC stage deactivation during load or line transients. The PFC MODE pin output current is limited when the VCC to PFC MODE bypass switch is activated. The current limitation avoids bypass switch damage during PFC VCC decoupling capacitor charging process or short circuit. A minimum value PFC VCC decoupling capacitance should be used in order to speed up PFC stage startup after it is enabled by the NCP1399 controller.

Please refer to Figure 61 through Figure 65 for an illustration of NCP1399 PFC operation control.

ON-time Modulation and Feedback Loop Block

Frequency modulation of today's commercially available resonant mode controllers is based on the output voltage regulator feedback only. The feedback voltage (or current) of output regulator drives voltage (or current) controlled oscillator (VCO or CCO) in the controller. This method presents three main disadvantages:

1. The 2nd order pole is present in small signal gain-phase characteristics \geq the lower cross over frequency and worse transient response is imposed by the system when voltage mode control is used. There is no direct link to the actual primary current – i.e. no line feed forward mechanism which results in poor line transient response.

2. Precise VCO (or CCO) is needed to assure frequency modulation with good reproducibility, f_{min} and f_{max} clamps need to be adjusted for each design \geq need for an adjustment pin(s).
3. Dedicated overload protection system, requiring an additional pin, is needed to assure application safety during overload and/or secondary short circuit events.

The NCP1399 resolves all disadvantages mentioned above by implementing a current mode control scheme that ensures best transient response performance and provides inherent cycle-by-cycle over-current protection feature in the same time. The current mode control principle used in this device can be seen in Figure 43.

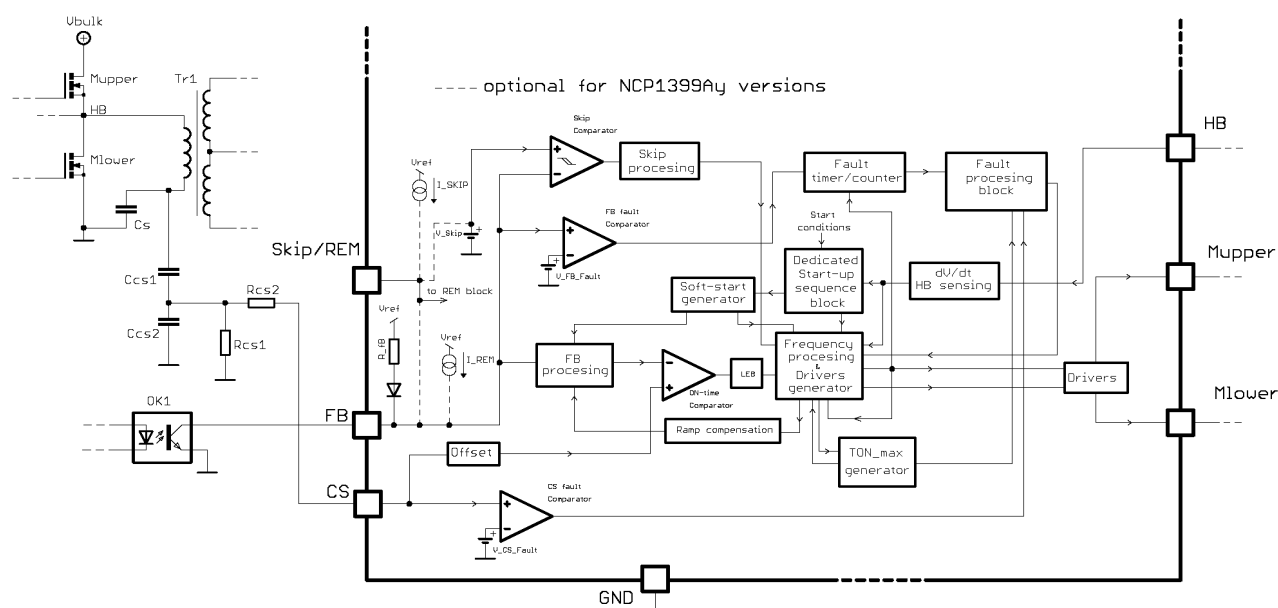


Figure 43. Internal Connection of the NCP1399 Current Mode Control Scheme

The basic principle of current mode control scheme implementation lies in the use of an ON-time comparator that defines upper switch on-time by comparing voltage ramp, derived from the current sense input voltage, to the divided feedback pin voltage. The upper switch on-time is then re-used for low side switch conduction period. The switching frequency is thus defined by the actual primary current and output load conditions. Digital processing with 10 ns minimum on-time resolution is implemented to ensure high noise immunity. The ON-time comparator output is blanked by the leading edge blanking (t_{LEB}) after the Mupper switch is turned-on. The ON-time comparator LEB period helps to avoid false triggering of the on-time modulation due to noise generated by the HB pin voltage transition.

The voltage signal for current sense input is prepared externally via natural primary current integration by the resonant tank capacitor Cs. The resonant capacitor voltage

is divided down by capacitive divider (Ccs1, Ccs2, Rcs1, Rcs2) before it is provided to the CS input. The capacitive divider division ratio, which is fully externally adjustable, defines the maximum primary current level that is reached in case of maximum feedback voltage – i.e. the capacitive divider division ratio defines the maximum output power of the converter for given bulk voltage. The CS is a bipolar input pin which an input voltage swing is restricted to ± 5 V. A fixed voltage offset is internally added to the CS pin signal in order to assure enough voltage margin for operation the feedback optocoupler – the FB optocoupler saturation voltage is ~ 0.15 V (depending on type). However, the CS pin useful signal for frequency modulation swings from 0 V, so current mode regulation would not work under light load conditions if no offset would be added to the CS pin before it is stabilized to the level of the on-time comparator input. The CS pin signal is also used for secondary side short circuit detection – please refer to chapter dedicated to short circuit protection.

The second input signal for the on-time comparator is derived from the FB pin voltage. This internal FB pin signal is also used for the following purposes: skip mode operation detection, PFC MODE control, off-mode detection (in NCP1399A device family) and overload / open FB pin fault detection. The detailed description of these functions can be found in each dedicated chapters. The internal pull-up resistor assures that the FB pin voltage increases when the optocoupler LED becomes less biased – i.e. when output load is increased. The higher FB pin voltage implies a higher reference level for on-time comparator i.e. longer Mupper switch on-time and thus also higher output power. The FB pin features a precise voltage clamp which limits the internal FB signal during overload and startup. The FB pin signal

passes through the FB processing block before it is brought to the ON-time comparator input. The FB processing block scales the FB signal down by a K_{FB} ratio in order to limit the CS input dynamic voltage range. The scaled FB signal is then further processed by subtraction of a ramp compensation generator signal in order to ensure stability of the current mode control scheme. The divided internal FB signal is overridden by a Soft-start generator output voltage during device starts-up.

The actual operation frequency of the converter is defined based on the CS pin and FB pin input signals. Please refer to Figure 44 and below description for better understanding of the NCP1399 frequency modulation system.

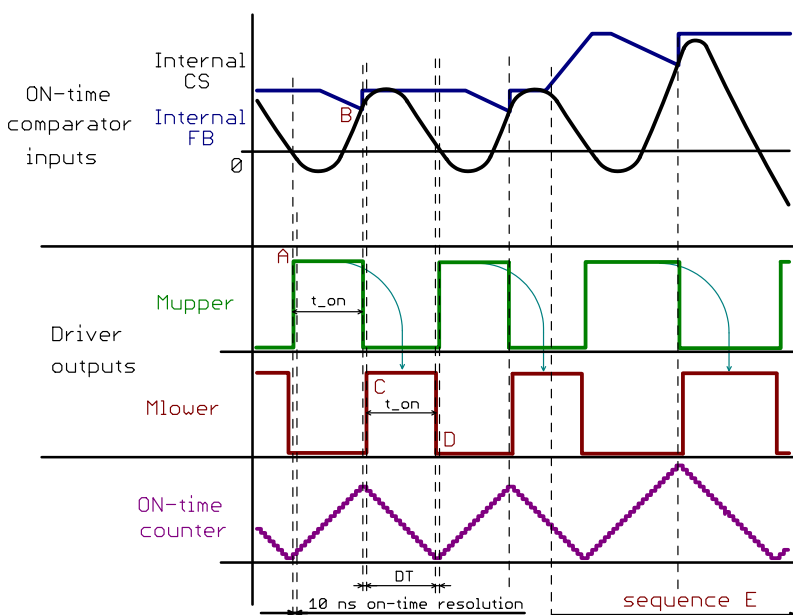


Figure 44. NCP1399 On-time Modulation Principle

The Mupper switch is activated by the controller after dead-time (DT) period lapses in point A. The frequency processing block increments the ON-time counter with 10 ns resolution until the internal CS signal crosses the internal FB set point for the ON-time comparator in point B. A DT period is then introduced by the controller to avoid any shoot-through current through the power stage switches. The DT period ends in point C and the controller activates the Mlower switch. The ON-time processing block decrements the ON_time counter down until it reaches zero. The Mlower switch is then turned-OFF at point D and the DT period is started. This approach results in perfect duty cycle symmetry for Mlower and Mupper switches. The Mupper switch on-time naturally increases and the operating frequency drops when the FB pin voltage is increased, i.e. when higher current is delivered by the converter output – sequence E.

The resonant capacitor voltage and thus also CS pin voltage can be out of balance in some cases – this is the case during transition from full load to no-load operation when

skip mode is not used or adjusted correctly. The current mode operation is not possible in such case because the ON-time comparator output stays active for several switching cycles. Thus a special logic has been implemented in NCP1399 in order to repeat the last valid on-time until the current mode operation recovers – i.e. until the CS pin signal balance is restored by the system.

Overload and Open FB Protections

The overload protection and open FB pin detection are implemented via FB pin voltage monitoring in this controller. The FB fault comparator is triggered once the FB pin voltage reaches its maximum level and the V_{FB_FAULT} threshold is exceeded. The fault timer or counter (depending on IC option) is then enabled – refer to Figure 43. The time period to the FB fault event confirmation is defined by the preselected $t_{FB_FAULT_TIMER}$ parameter when the fault timer option is used. The FB fault counter, once selected as a FB fault confirmation period source, defines the fault confirmation period via Mupper DRV pulses counting. The

FB fault confirmation time is thus dependent on switching frequency. The fault timer/counter is reset once the FB fault condition diminishes. A digital noise filter has been added after the FB fault comparator to overcome false triggering of the FB fault timer/counter due to possible noise on the FB input. The noise filter has a period of 2 μ s for FB fault timer/counter activation and 20 μ s for reset/deactivation to assure high noise immunity. A cumulative timer/counter IC

option is also available on request. The FB fault timer/counter is not reset when the FB fault condition diminishes in this case. The FB fault timer/counter is disabled and memorizes the fault period information. The cumulative FB fault timer/counter integrates all the FB fault events over the IC operation time. The Fault timer/counter can be reset via skip mode or VCC UVLO event.

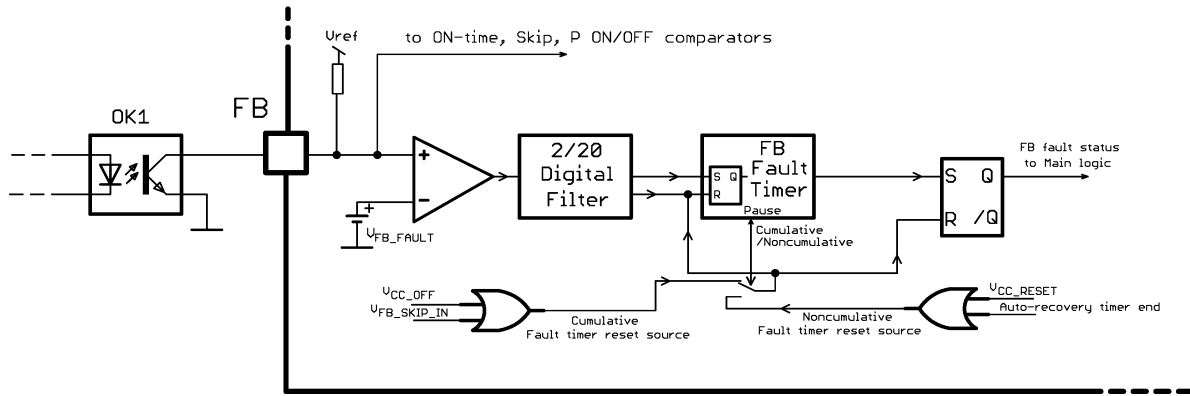


Figure 45. Internal FB Fault Management

The controller disables driver pulses and enters protection mode once the FB fault event is confirmed by the FB fault timer or counter. Latched or auto-recovery operation is then triggered – depends on selected IC option. The controller adds an auto-recovery off-time period (t_{A-REC_TIMER}) and restarts the operation via soft start in case of auto-recovery option. The application temperature runaway is thus avoided in case of overload while the automatic restart is still possible once the overload condition disappears. The IC with latched FB fault option stays latched-off, supplied by the HV startup current source working in DSS mode, until the V_{CC_RESET} threshold is reached on the VCC pin – i.e. until user re-connects power supply mains.

Please refer to Figure 61 and Figure 62 for an illustration of the NCP1399 FB fault detection block.

Secondary Short Circuit Detection

The protection system described previously, implemented via FB pin voltage level detection, prevents continuous overload operation and/or open FB pin conditions. The

primary current is naturally limited by the NCP1399 on-time modulation principle in this case. But the primary current increases when the output terminals are shorted. The NCP1399 controller will maintain zero voltage switching operation in such case, however high currents will flow through the power MOSFETS, transformer winding and secondary side rectification. The NCP1399 implements a dedicated secondary side short circuit protection system that will shut down the controller much faster than the regular FB fault event in order to limit the stress of the power stage components. The CS pin signal is monitored by the dedicated CS fault comparator – refer to Figure 43. The CS fault counter is incremented each time the CS fault comparator is triggered. The controller enters auto-recovery or latched protection mode (depending on IC option) in case the CS fault counter overflows refer to Figure 46. The CS fault counter is then reset once the CS fault comparator is inactive for at least 50 Mupper upcoming pulses. This digital filtering improves CS fault protection system noise immunity.