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PCA8530

Automotive 102 x 4 Chip-On-Glass LCD segment driver

Rev. 2 — 25 September 2014

Product data sheet

1. General description

The PCA8530 is a fully featured Chip-On-Glass (COG)¹ Liquid Crystal Display (LCD) driver, designed for high-contrast Vertical Alignment (VA) LCD with multiplex rates up to 1:4. It generates the drive signals for a static or multiplexed LCD containing up to 4 backplane, 102 segment outputs, and up to 408 segments/elements. The PCA8530 features an internal charge pump with internal capacitors for on-chip generation of the LCD driving voltage. To ensure an optimal and stable contrast over the full temperature range, the PCA8530 offers a programmable temperature compensation of the LCD supply voltage. The PCA8530 can be easily controlled by a microcontroller through either the two-line l²C-bus or a four-line bidirectional SPI-bus.

For a selection of NXP LCD segment drivers, see Table 58 on page 93.

2. Features and benefits

- AEC Q100 grade 2 compliant for automotive applications
- Low power consumption
- Extended operating temperature range from -40 °C to +105 °C
- 102 segments and 4 backplanes allowing to drive:
 - up to 51 7-segment numeric characters
 - up to 25 14-segment alphanumeric characters
 - any graphics of up to 408 segments/elements
- 408-bit RAM for display data storage
- Two sets of backplane outputs providing higher flexibility for optimal COG layout configurations
- Up to 4 chips can be cascaded to drive larger displays with an internally generated or externally supplied V_{LCD}
- Selectable backplane drive configuration: static, 2, or 4 backplane multiplexing
- LCD supply voltage
 - ◆ Programmable internal charge pump for on-chip LCD voltage generation up to 5 × V_{DD2}
 - External LCD voltage supply possible as well
- Selectable 400 kHz I²C-bus or 3 MHz SPI-bus interface
- Selectable linear temperature compensation of V_{LCD}
- Selectable display bias configuration
- Wide range for digital and analog power supply: from 2.5 V to 5.5 V

^{1.} The definition of the abbreviations and acronyms used in this data sheet can be found in Section 21 on page 95.



Automotive 102 x 4 Chip-On-Glass LCD segment driver

- Wide LCD voltage range from 4.0 V for low threshold LCDs up to 12.0 V for high threshold twisted nematic and Vertical Alignment (VA) displays
- Display memory bank switching in static and 1:2 multiplex drive modes
- Programmable frame frequency in the range of 45 Hz to 300 Hz; factory calibrated with a tolerance of ±3 Hz (at 80 Hz)
- Selectable inversion scheme for LCD driving waveforms: frame or n-line inversion
- Diagnostic features for status monitoring
- Integrated temperature sensor with temperature readout
- On chip calibration of internal oscillator frequency and V_{LCD}
- Laser marking at the back-side of the die for traceability of the lot number, wafer number, and die position on the wafer

3. Applications

- Automotive
 - Instrument clusters
 - Climate control
 - Car entertainment
 - Car radio
- Industrial
 - Consumer
 - Medical and health care
 - Measuring equipment
 - Machine control systems
 - Information boards
 - White goods
 - General-purpose display modules

Automotive 102 x 4 Chip-On-Glass LCD segment driver

4. Ordering information

Table 1. Ordering information

| Type number | Package | | | | | |
|-------------|----------|-------------|------------|--|--|--|
| | Name | Description | Version | | | |
| PCA8530DUG | bare die | 247 bumps | PCA8530DUG | | | |

4.1 Ordering options

Table 2. Ordering options

| Product type number | Orderable part number | Sales item (12NC) | Delivery form | IC revision |
|---------------------|-----------------------|----------------------|-----------------------------|-------------|
| PCA8530DUG/DA | PCA8530DUG/DAZ | 935304675033 | chips with bumps[1] in tray | 1 |

^[1] Bump hardness, see Table 56 on page 90.

5. Marking

Table 3. Marking codes

| Product type number | Marking code |
|---------------------|--------------------------------|
| PCA8530DUG/DA | on the active side of the die |
| | PC8530-1 |
| | on the rear side of the die[1] |
| | LLLLLL WW XXXXXX |

[1] The rear side marking has the following meaning:

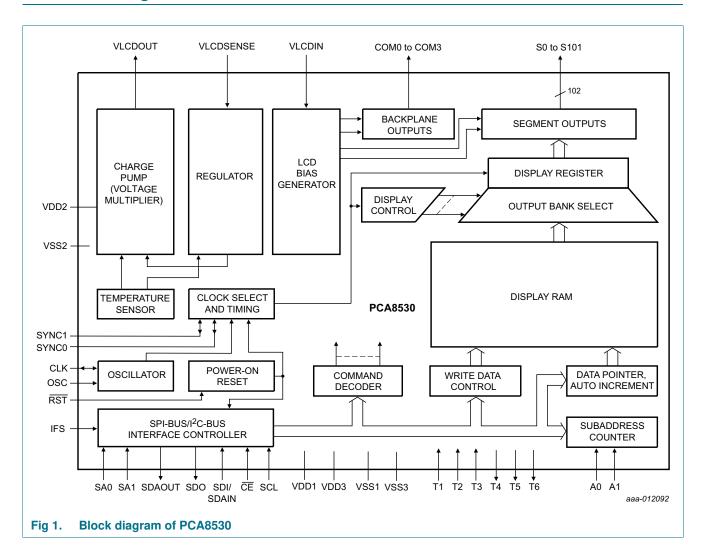
LLLLLL — wafer lot number

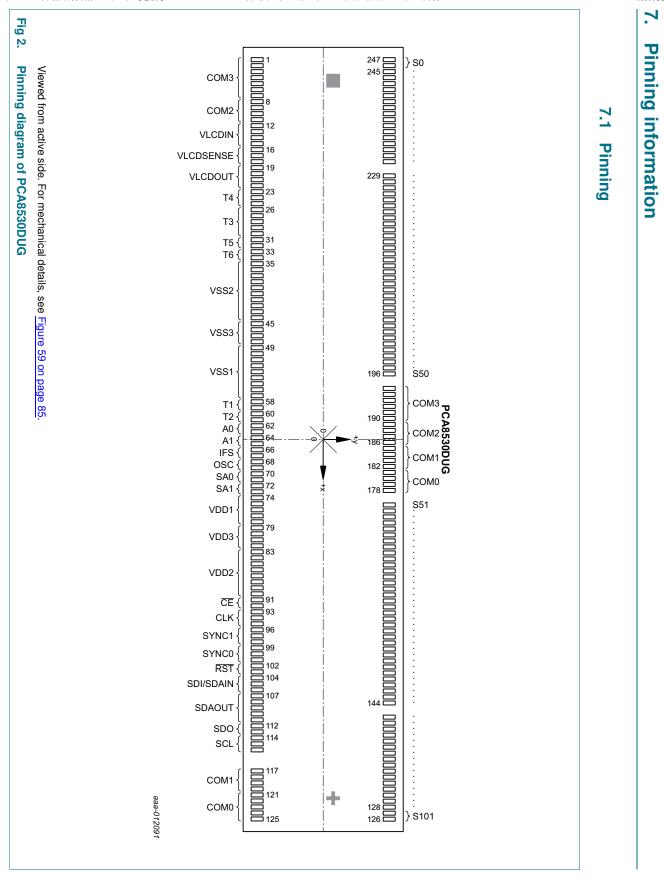
WW — wafer number

XXXXXX — die identification number

Automotive 102 x 4 Chip-On-Glass LCD segment driver

6. Block diagram





Automotive 102 x 4 Chip-On-Glass LCD segment driver

7.2 Pin description

Table 4. Pin description

Input or input/output pins must always be at a defined level (V_{SS} or V_{DD}) unless otherwise specified.

| Symbol | Pin | Туре | Description |
|-----------------------|------------------------|----------------|--|
| Backplane out | put pins | | |
| COM3 | 1 to 7, 190 to 195 | output | LCD backplane |
| COM2 | 8 to 11, 186 to 189 | | |
| COM1 | 117 to 120, 182 to 185 | | |
| COM0 | 121 to 125, 178 to 181 | | |
| Segment outpo | ut pins | | |
| S101 | 126, 127 | output | LCD segment |
| S100 to S51 | 128 to 177 | | |
| S50 to S1 | 196 to 245 | | |
| S0 | 246, 247 | | |
| V _{LCD} pins | | | |
| VLCDIN | 12 to 15 | supply | V _{LCD} input |
| VLCDSENSE | 16 to 18 | input | V _{LCD} regulation input |
| VLCDOUT | 19 to 22 | output | V _{LCD} output |
| Test pins | | | |
| T4 | 23 to 25 | output | not accessible; must be left open |
| Т3 | 26 to 30 | input | not accessible; must be connected to T5 |
| T5 | 31, 32 | output | not accessible; must be connected to T3 |
| Т6 | 33, 34 | output | not accessible; must be left open |
| T1 | 58, 59 | input | not accessible; must be connected to V _{SS1} |
| T2 | 60, 61 | | |
| Supply pins | | | |
| VSS2[1] | 35 to 44 | supply | ground supply |
| VSS3[1] | 45 to 48 | | |
| VSS1[1] | 49 to 57 | | |
| VDD1 | 74 to 78 | supply | supply voltage 1 (analog and digital) |
| VDD3 | 79 to 82 | supply | supply voltage 3 (analog) |
| VDD2 | 83 to 90 | supply | supply voltage 2 (charge pump) |
| Oscillator, syn | chronization, addressi | ing, and reset | t pins |
| CLK[2] | 93 to 95 | input/output | internal oscillator output, external oscillator input |
| OSC[2] | 68, 69 | input | clock (internal/external) selector |
| SYNC1 ³ | 96 to 98 | input/output | charge pump synchronization for cascaded devices; must not be connected if V_{LCD} is externally supplied |
| SYNC0[3] | 99 to 101 | input/output | display synchronization for cascaded devices |
| RST | 102, 103 | input | active LOW reset input |
| A0 | 62, 63 | input | hardware device address selection for cascading; |
| A1 | 64, 65 | input | connect to V _{SS1} for logic 0 |
| | | | connect to V _{DD1} for logic 1 |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

 Table 4.
 Pin description ...continued

Input or input/output pins must always be at a defined level (V_{SS} or V_{DD}) unless otherwise specified.

| Symbol | Pin | Туре | Description | | |
|--------------------|------------|--------|--|--|--|
| Bus-related | pins | | , | | |
| | | | SPI-bus | I ² C-bus | |
| IFS | 66, 67 | input | interface selector input | | |
| | | | connect to V_{SS1} | connect to V _{DD1} | |
| SA0 | 70, 71 | input | unused; | slave address selector; | |
| SA1 | 72, 73 | input | connect to V_{SS1} | connect to V_{SS1} for logic 0 | |
| | | | | connect to V_{DD1} for logic 1 | |
| CE | 91, 92 | input | chip enable input (active LOW) | unused; | |
| | | | | connect to V_{DD1} | |
| SDI/SDAIN | 104 to 106 | input | SPI-bus data input | I ² C-bus serial data input | |
| SDAOUT | 107 to 111 | output | unused; | serial data output | |
| | | | must be connected to V_{SS1} | | |
| SDO | 112, 113 | output | SPI serial data output | unused; | |
| | | | | must be left open | |
| SCL | 114 to 116 | input | serial clock input | serial clock input | |

^[1] The substrate (rear side of the die) is connected to V_{SS1} and should be electrically isolated.

^[2] If pin OSC is tied to V_{SS1}, CLK is the output pin of the internal oscillator. If pin OSC is tied to V_{DD1}, CLK is the input pin for the external oscillator.

^[3] If cascading is not used, pin must be left floating; for cascading see Section 15.2 on page 80.

NXP

Semiconductors

8. Functional description

8.1 Commands of PCA8530

The PCA8530 is controlled by the commands defined in Table 5.

Remark: Any other combinations of operation code bits that are not mentioned in this document may lead to undesired operation modes of PCA8530.

Table 5. Commands of PCA8530

| Command name | R/W[1] | | | Comm | Command bits | | | | | | | Reference |
|----------------------------|-------------|--------|----|---------|--------------|-----|--------|--------|------|--------|-----|---------------|
| | | select | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| General control commands | 3 | • | | | • | | | | | | | |
| Initialize | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 | Section 8.2.1 |
| OTP-refresh | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | Section 8.2.2 |
| Device-address | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | A[1:0] | | Section 8.2.3 |
| SYNC1_pin | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | OE | Section 8.2.4 |
| Clock-out-ctrl | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | COE | Section 8.2.5 |
| Read-select | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | SO | Section 8.2.6 |
| Status-readout temperature | 1 | 0 | 0 | TD[7:0] |] | | · | · | · | · | · | Section 8.2.7 |
| device status | 6 | | | SR7 | SR6 | SR5 | SR4 | SR[3:0 |] | | | |
| Clear-reset-flag | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | Section 8.2.8 |
| Charge pump and LCD bia | s control o | omman | ds | | , | | | | | | | |
| Charge-pump-ctrl | 0 | 0 | 0 | 1 | 1 | 0 | 0 | CPE | CPC[| 2:0] | | Section 8.3.1 |
| Set-V _{LCD} MSB | 0 | 0 | 0 | 0 | 1 | 0 | V[8:4] | · | · | | | Section 8.3.2 |
| LSB | 0 | 0 | 0 | 0 | 1 | 1 | 0 | V[3:0] | | | | |
| Set-bias-mode | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | B[1:0] | | Section 8.3.3 |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

| Tuble 3. Communas of Cadoodcommuca | | Table 5. | Command | s of | PCA8530 | continued |
|------------------------------------|--|----------|---------|------|---------|-----------|
|------------------------------------|--|----------|---------|------|---------|-----------|

| Command name | | R/W[1] | Regist | | Comn | nand bits | | | | | | | Reference |
|-----------------|------------|---------------|-------------------------|----|--------|-----------|-----|--------|-------|---------|---------|-----|---------------|
| | | | selection RS[1:0][2] | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| Temperature | compensat | ion control c | omman | ds | | | l l | | | | | | |
| Temperature-c | trl | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | TCE | TMF | TME | Section 8.4.1 |
| TC-slope | Α | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | TSA[2: | 0] | | Section 8.4.3 |
| | В | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 | TSB[2: | 0] | | |
| | С | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | TSC[2: | 0] | | |
| | D | 0 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | TSD[2: | 0] | | |
| | E | 0 | 1 | 0 | 0 | 0 | 1 | 0 | 1 | TSE[2: | 0] | | |
| | F | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 0 | TSF[2:0 | 0] | | |
| TC-set | 1 | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 1 | T1T[2:0 | 0] | | Section 8.4.2 |
| | 2 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 0 | T2T[2:0 | 0] | | |
| | 3 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | T3T[2:0 | 0] | | |
| | 4 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 0 | T4T[2:0 | 0] | | |
| Display contr | ol comman | ds | | ' | ' | | - | | | | | | |
| Set-MUX-mod | е | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | M[2:0] | | | Section 8.5.1 |
| Inversion-mod | е | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | INV[2:0 |)] | | Section 8.5.2 |
| Display-ctrl | | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 0 | DE | Section 8.5.3 |
| Clock and fra | me frequen | cy command | k | ' | ' | , | ' | | , | 1 | | | |
| Frame-frequer | псу | 0 | 0 | 0 | 1 | 1 | 1 | FF[4:0 |)] | | | | Section 8.6.4 |
| Display RAM | commands | | | ' | ' | , | ' | | | | | | |
| Write-display-o | data | 0 | 0 | 1 | DB[7:0 | 0] | | | | | | | Section 8.7.1 |
| Input-bank-sel | ect | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | IB[1:0] | | Section 8.7.2 |
| Output-bank-s | elect | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | OB[1:0 |] | |
| Data-pointer-ir | nit | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | Section 8.7.3 |
| Data-pointer | MSB | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | PX[6:4] | | ' | |
| | LSB | 0 | 0 | 0 | 1 | 0 | 0 | 1 | PX[3: | 0] | | | |

^[1] For further information about the R/\overline{W} -bit, see <u>Table 42 on page 56</u>.

^[2] For further information about the register selection bits, see <u>Table 42 on page 56</u>.

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.2 General control commands

8.2.1 Initialization

8.2.1.1 Command: Initialize

This command generates a chip-wide reset of the device without changing the content of the display RAM. For further information about start-up and shut-down, see <u>Section 8.8 on page 26</u>.

Table 6. Initialize command bit description

| Bit | Symbol | Value | Description |
|--------|---------|----------|-------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 0 | - | 00111010 | fixed value |

8.2.1.2 RST pin

The RST pin generates a chip-wide reset of the device without changing the content of the display RAM. For further information about start-up and shut-down, see Section 8.8 on page 26.

8.2.2 Command: OTP-refresh

Each IC is calibrated during production and testing of the device in order to achieve the specified accuracy of the V_{LCD} , the frame frequency, and the temperature measurement. This calibration is performed on EPROM cells called One Time Programmable (OTP) cells. These cells are read by the device after a reset and every time when the Initialize command or the OTP-refresh command is sent. The OTP-refresh command takes approximately 10 ms to finish.

Table 7. OTP-refresh - OTP-refresh command bit description

| Bit | Symbol | Value | Description |
|--------|---------|----------|-------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 0 | - | 11011000 | fixed value |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.2.3 Command: Device-address

The Device-address command allows setting the address of the device in a cascaded configuration and corresponds with pins A0 and A1 (see Section 15.2 on page 80).

Table 8. Device-address - device address command bit description

| Bit | Symbol | Value | Description |
|--------|---------|--------|-------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 2 | - | 000110 | fixed value |
| 1 to 0 | A[1:0] | | set address |
| | | 00 | master |
| | | 01 | slave 1 |
| | | 10 | slave 2 |
| | | 11 | slave 3 |

8.2.4 Command: SYNC1 pin

With the SYNC1_pin command, the SYNC1 pin can be configured for using the PCA8530 as a single chip or a master in a cascade. If the PCA8530 is a slave in a cascade, the command has no effect.

Table 9. SYNC1_pin - SYNC1 pin configuration command bit description *This command has no effect if the PCA8530 is a slave in a cascade.*

| Bit | Symbol | Value | Description |
|--------|---------|-------------------------|---|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 1 | - | 1011100 | fixed value |
| 0 OE | | SYNC1 pin configuration | |
| | | 0 | pin SYNC1 is an output; gated to 0 V; to be used when PCA8530 is a single chip |
| | | 1 | pin SYNC1 is an output; providing the synchronization signal; to be used when PCA8530 is a master in a cascade |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.2.5 Command: Clock-out-ctrl

When pin CLK is configured as an output pin, the Clock-out-ctrl command enables or disables the clock output on pin CLK (Section 8.6.1 on page 22).

Table 10. Clock-out-ctrl - CLK pin input/output switch command bit description

| Bit | Symbol | Value | Description |
|--------|---------|---------|--|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 1 | - | 1101010 | fixed value |
| 0 | COE | | control pin CLK |
| | | 0 | clock signal not available on pin CLK; pin CLK is in 3-state |
| | | 1 | clock signal available on pin CLK |

8.2.6 Command: Read-select

The Read-select command allows choosing to readout the temperature or the device status.

Table 11. Read-select - status read select command bit description

| Bit | Symbol | Value | Description |
|--------|---------|---------|--|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 1 | - | 0001110 | fixed value |
| 0 | SO | | readout |
| | | 0 | temperature; the Status-readout command allows to readout the temperature TD[7:0], see Table 12 |
| | | 1 | device status: the Status-readout command allows to readout some information about the status of the device, see <u>Table 12</u> |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.2.7 Command: Status-readout

The Status-readout command offers to readout some status bits of the PCA8530. These bits indicate the status of the device at the moment of reading.

Table 12. Status-readout - status and temperature read command bit description For this command, bit R/W has to be set logic 1.

| Bit | Symbol | Value | Description |
|--------|--------------------------|--------------------------|--|
| - | R/W | 1 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| Tempe | rature readout if SO = 0 | (see <u>Table 11</u>) | |
| 7 to 0 | TD[7:0] | 00000000 to 11111111 | temperature readout (see Section 8.10.4.1 on page 40) |
| Device | status readout if SO = 1 | 1 (see <u>Table 11</u>) | |
| 7 | SR7 | | display status (see Table 22 on page 21) |
| | | 0 | display is disabled |
| | | 1 | display is enabled |
| 6 | SR6 | | charge pump switching status (status of bit CPE, see <u>Table 14 on page 15</u>) |
| | | 0 | charge pump disabled |
| | | 1 | charge pump enabled |
| 5 | SR5 | | charge pump charge status |
| | | 0 | charge pump has not reached programmed value |
| | | 1 | charge pump has reached programmed value |
| 4 | SR4 | | reset status flag |
| | | 0 | no reset has occurred since the reset status flag was cleared last time |
| | | 1 | reset has occurred since the reset status flag was cleared last time[1] |
| 3 to 0 | SR[3:0] | | EMC detection |
| | | 01 SA1 SA0 | pre-defined code for EMC detection when I ² C interface is used |
| | | 0101 | pre-defined code for EMC detection when SPI interface is used |

^[1] The flag is set whenever a reset occurs, induced by $\overline{\text{RST}}$ pin, Power-On Reset (POR), or Initialize command. After power-on, the flag is set and should be cleared for reset monitoring.

Some bits of the Status-readout command have a certain probability of being changed by an EMC/ESD event. For example, an EMC/ESD event can cause a change of the hard-wired settings of SA1 or SA0. Therefore SR[3:0] can help to detect if an EMC/ESD event has occurred which has caused the change of a bit. In environments where EMC/ESD events may occur, it could be helpful to compare the result of the Status-readout command with the initial bit settings periodically.

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.2.8 Command: Clear-reset-flag

The Clear-reset-flag command clears the reset flag SR4, see Table 12.

Table 13. Clear-reset-flag - Clear-reset-flag command bit description

| Bit | Symbol | Value | Description |
|--------|---------|----------|-------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 0 | - | 00011111 | fixed value |

8.3 Charge pump and LCD bias control commands

8.3.1 Command: Charge-pump-ctrl

The Charge-pump-ctrl command enables or disables the internal V_{LCD} generation and controls the charge pump voltage multiplier settings.

Automotive 102 x 4 Chip-On-Glass LCD segment driver

Table 14. Charge-pump-ctrl - charge pump control command bit description

| Bit | Symbol | Value | Description |
|--------|----------|------------|--|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 4 | - | 1100 | fixed value |
| 3 | CPE | | charge pump status |
| | | 0 | charge pump disabled; no internal V _{LCD} generation; external supply of V _{LCD} |
| | | 1 | charge pump enabled; internal V_{LCD} generation; no external supply of V_{LCD} |
| 2 to 0 | CPC[2:0] | | charge pump voltage multiplier setting |
| | | 000 | $V_{LCD} = 2 \times V_{DD2}$ |
| | | 001 | $V_{LCD} = 3 \times V_{DD2}$ |
| | | 010 | $V_{LCD} = 4 \times V_{DD2}$ |
| | | 011 | $V_{LCD} = 5 \times V_{DD2}$ |
| | | 100 to 111 | V _{LCD} = V _{DD2} (direct mode) |

8.3.2 Command: Set-V_{LCD}

The Set-V_{LCD} command allows setting the LCD voltage.

Table 15. Set-V_{LCD} - Set-V_{LCD} command bit description

| Bit | Symbol | Value | Description | | |
|---------------------|---------------------------|--------------------------|--|--|--|
| Set-V _{LC} | Set-V _{LCD} -MSB | | | | |
| - | R/W | 0 | fixed value | | |
| - | RS[1:0] | 00 | fixed value | | |
| 7 to 5 | - | 010 | fixed value | | |
| 4 to 0 | V[8:4] | | set V _{LCD} MSB | | |
| | | 0 0 0 0 to 1 1 1 1 1 1 1 | the 5 most significant bits of V[8:0] | | |
| Set-V _{LC} | CD-LSB | | | | |
| - | R/W | 0 | fixed value | | |
| - | RS[1:0] | 00 | fixed value | | |
| 7 to 4 | - | 0110 | fixed value | | |
| 3 to 0 | V[3:0] | | set V _{LCD} LSB | | |
| | | 0000 to 1111 | the 4 least significant bits of V[8:0] | | |

A value of 0h corresponds to V_{LCD} = 4 V and values equal or higher than 10Ch correspond to V_{LCD} = 12 V without temperature compensation. Every LSB change corresponds to a V_{LCD} programming step of 0.03 V. For further information, see

Automotive 102 x 4 Chip-On-Glass LCD segment driver

Section 8.10.3 on page 34 and Equation 2 on page 35.

8.3.3 Command: Set-bias-mode

Table 16. Set-bias-mode - set bias mode command bit description

This command is not applicable for the static drive mode.

| Bit | Symbol | Value | Description |
|--------|---------|--------|--------------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 2 | - | 110100 | fixed value |
| 1 to 0 | B[1:0] | | set bias mode |
| | | 00, 01 | unused |
| | | 11 | $\frac{1}{3}$ bias |
| | | 10 | $\frac{1}{2}$ bias |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.4 Temperature compensation control commands

8.4.1 Command: Temperature-ctrl

The Temperature-ctrl command enables or disables the temperature measurement block and the temperature compensation of V_{LCD} (see Section 8.10.4 on page 40).

Table 17. Temperature-ctrl - temperature measurement control command bit description For this command, the register selection bits have to be set RS[1:0] = 10.

| Bit | Symbol | Value | Description |
|--------|---------|-------|---|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 10 | fixed value |
| 7 to 3 | - | 00000 | fixed value |
| 2 | TCE | | temperature compensation control |
| | | 0 | temperature compensation of V _{LCD} disabled |
| | | 1 | temperature compensation of V _{LCD} enabled |
| 1 | TMF | | temperature measurement filter |
| | | 0 | digital temperature filter disabled ^[1] |
| | | 1 | digital temperature filter enabled |
| 0 | TME | | temperature measurement control |
| | | 0 | temperature measurement disabled; |
| | | | no temperature readout possible |
| | | 1 | temperature measurement enabled; |
| | | | temperature readout possible |

^[1] The unfiltered digital value of TD[7:0] is immediately available for the readout and V_{LCD} compensation.

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.4.2 Command: TC-set

The TC-set command allows defining six temperature intervals in the operating temperature range from -40 °C to +105 °C. For each of the temperature intervals, the TC-slope command (see Section 8.4.3) allows setting the temperature coefficient of V_{LCD} .

Table 18. TC-set - V_{LCD} temperature compensation set command bit description For this command, the register selection bits have to be set RS[1:0] = 10.

| Bit | Symbol | Value | Description | | | |
|---------|----------|------------|-------------------------|--|--|--|
| TC-set- | TC-set-1 | | | | | |
| - | R/W | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 00111 | fixed value | | | |
| 2 to 0 | T1T[2:0] | 000 to 111 | see Table 32 on page 42 | | | |
| TC-set- | 2 | | | | | |
| - | R/W | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 01000 | fixed value | | | |
| 2 to 0 | T2T[2:0] | 000 to 111 | see Table 32 on page 42 | | | |
| TC-set- | 3 | | | | | |
| - | R/W | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 01001 | fixed value | | | |
| 2 to 0 | T3T[2:0] | 000 to 111 | see Table 32 on page 42 | | | |
| TC-set- | 4 | | | | | |
| - | R/W | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 01010 | fixed value | | | |
| 2 to 0 | T4T[2:0] | 000 to 111 | see Table 32 on page 42 | | | |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.4.3 Command: TC-slope

The TC-slope command allows setting the temperature coefficients of V_{LCD} corresponding to six temperature intervals defined by the TC-set command.

Table 19. TC-slope - V_{LCD} temperature compensation slope command bit description For this command, the register selection bits have to be set RS[1:0] = 10.

| Bit | Symbol | Value | Description | | | |
|--------|------------------|------------|-------------------------|--|--|--|
| TC-slo | TC-slope-A | | | | | |
| - | R/W | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 00001 | fixed value | | | |
| 2 to 0 | TSA[2:0] | 000 to 111 | see Table 33 on page 43 | | | |
| TC-slo | ре-В | | | | | |
| - | R/W | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 00010 | fixed value | | | |
| 2 to 0 | TSB[2:0] | 000 to 111 | see Table 33 on page 43 | | | |
| TC-slo | pe-C | | | | | |
| - | R/\overline{W} | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 00011 | fixed value | | | |
| 2 to 0 | TSC[2:0] | 000 to 111 | see Table 33 on page 43 | | | |
| TC-slo | pe-D | | | | | |
| - | R/\overline{W} | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 00100 | fixed value | | | |
| 2 to 0 | TSD[2:0] | 000 to 111 | see Table 33 on page 43 | | | |
| TC-slo | pe-E | | | | | |
| - | R/\overline{W} | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 00101 | fixed value | | | |
| 2 to 0 | TSE[2:0] | 000 to 111 | see Table 33 on page 43 | | | |
| TC-slo | pe-F | | | | | |
| - | R/W | 0 | fixed value | | | |
| - | RS[1:0] | 10 | fixed value | | | |
| 7 to 3 | - | 00110 | fixed value | | | |
| 2 to 0 | TSF[2:0] | 000 to 111 | see Table 33 on page 43 | | | |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.5 Display control commands

8.5.1 Command: Set-MUX-mode

The Set-MUX-mode command allows setting the multiplex drive mode.

Table 20. Set-MUX-mode - set multiplex drive mode command bit description

| Bit | Symbol | Value | Description |
|--------|---------|------------|--------------------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 3 | - | 00000 | fixed value |
| 2 to 0 | M[2:0] | | set multiplex drive mode |
| | | 000 to 100 | unused |
| | | 101 | 1:4 multiplex drive mode |
| | | 110 | 1:2 multiplex drive mode |
| | | 111 | static |

8.5.2 Command: Inversion-mode

The Inversion-mode command allows changing the drive scheme inversion mode.

The waveforms used to drive LCD displays (see Figure 25 on page 46 to Figure 28 on page 49) inherently produce a DC voltage across the display cell. The PCA8530 compensates for the DC voltage by inverting the waveforms on alternate frames or alternate lines. The choice of the compensation method is determined with INV[2:0] in Table 21.

Table 21. Inversion-mode - inversion mode command bit description

| Bit | Symbol | Value | Description |
|--------|----------|------------|-----------------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 3 | - | 10110 | fixed value |
| 2 to 0 | INV[2:0] | | set inversion mode |
| | | 000 | frame inversion mode |
| | | 001 | 1-line inversion mode |
| | | 010 | 2-line inversion mode |
| | | 011 | 3-line inversion mode |
| | | 100 to 111 | unused |

8.5.2.1 Line inversion mode (driving scheme A)

In line inversion mode, the DC value is compensated every nth line. Changing the inversion mode to line inversion mode reduces the possibility for flickering but increases the power consumption (see example waveforms in <u>Figure 25 on page 46</u> to <u>Figure 28 on page 49</u>)

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.5.2.2 Frame inversion mode (driving scheme B)

In frame inversion mode, the DC value is compensated across two frames and not within one frame. Changing the inversion mode to frame inversion reduces the power consumption, therefore it is useful when power consumption is a key point in the application.

Frame inversion may not be suitable for all applications. The RMS voltage across a segment is better defined, however since the switching frequency is reduced there is possibility for flicker to occur.

8.5.3 Command: Display-ctrl

The Display-ctrl command enables or disables the display.

Table 22. Display-ctrl - display on and off switch command bit description

| Bit | Symbol | Value | Description |
|--------|---------|---------|------------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 1 | - | 0011100 | fixed value |
| 0 | DE | | display control |
| | | 0 | display disabled |
| | | 1 | display enabled |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.6 Clock and frame frequency command

8.6.1 Oscillator

The internal logic and LCD drive signals of the PCA8530 are timed by the clock frequency f_{clk} , which is either internally generated by an on-chip oscillator circuit or externally supplied.

The clock frequency f_{clk} determines the internal data flow of the device that includes the transfer of display data from the display RAM to the display segment outputs and the generation of the LCD frame frequency.

8.6.2 External clock

When an external clock is used, the input pin OSC must be connected to V_{DD1} . The clock must be supplied to the CLK pin and must have an amplitude equal to the V_{DD1} voltage supplied to the chip and be referenced to V_{SS1} .

Remark: If an external clock is used, then this clock signal must always be supplied to the device. Removing the clock may freeze the LCD in a DC state, which is not suitable for the liquid crystal. Removal of the clock is possible when following the correct procedures as described in Section 8.8.3 on page 29.

8.6.3 Internal clock

In applications where the internal clock is used, the input pin OSC must be connected to V_{SS1} . It is possible to make the clock frequency available on pin CLK by setting bit COE logic 1 (see <u>Table 10 on page 12</u>). If pin CLK is not used, it should be left open. At power-on the signal at pin CLK is disabled and pin CLK is in 3-state.

8.6.4 Command: Frame-frequency

With this command, the clock and frame frequency can be programmed when using the internal clock.

Table 23. Frame-frequency - frame frequency select command bit description

| Bit | Symbol | Value | Description |
|--------|---------|---------------------|--------------------------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 00 | fixed value |
| 7 to 5 | - | 111 | fixed value |
| 4 to 0 | FF[4:0] | see <u>Table 24</u> | clock and frame frequency (Hz) |

The duty ratio of the clock output may change when choosing different values for the frame frequency (see <u>Table 24</u>).

The LCD frame frequency is derived from the clock frequency by a fixed division (see Equation 1).

$$f_{fr} = \frac{f_{clk}}{144} \tag{1}$$

Automotive 102 x 4 Chip-On-Glass LCD segment driver

The Frame-frequency command allows configuring the frame frequency in the range of $45\ Hz$ to $300\ Hz$ with steps of

- 5 Hz from 45 Hz to 100 Hz
- 10 Hz from 100 Hz to 300 Hz

The frame frequency of 80 Hz is factory calibrated with a tolerance of ± 3 Hz at 25 °C.

Table 24. Clock and frame frequency values

Duty cycle definition: % HIGH-level time : % LOW-level time.

| FF[4:0] | Frame frequency (Hz) | Clock frequency (Hz) | Typical duty cycle (%) |
|---------|----------------------|----------------------|------------------------|
| 00000 | 45 | 6472 | 29 : 71 |
| 00001 | 50 | 7200 | 20 : 80 |
| 00010 | 55 | 7945 | 12 : 88 |
| 00011 | 60 | 8662 | 4:96 |
| 00100 | 65 | 9366 | 48 : 52 |
| 00101 | 70 | 10105 | 44 : 56 |
| 00110 | 75 | 10766 | 41 : 59 |
| 00111 | 80 | 11520 | 36 : 64 |
| 01000 | 85 | 12255 | 32 : 68 |
| 01001 | 90 | 12944 | 29 : 71 |
| 01010 | 95 | 13714 | 24 : 76 |
| 01011 | 100 | 14400 | 20 : 80 |
| 01100 | 110 | 15781 | 13 : 87 |
| 01101 | 120 | 17194 | 5 : 95 |
| 01110 | 130 | 18581 | 49 : 51 |
| 01111 | 140 | 20211 | 44 : 56 |
| 10000 | 150 | 21736 | 40 : 60 |
| 10001 | 160 | 23040 | 36 : 64 |
| 10010 | 170 | 24511 | 32 : 68 |
| 10011 | 180 | 26182 | 28 : 72 |
| 10100 | 190 | 27429 | 24 : 76 |
| 10101 | 200 | 28800 | 20 : 80 |
| 10110 | 210 | 30316 | 16 : 84 |
| 10111 | 220 | 32000 | 12 : 88 |
| 11000 | 230 | 32914 | 9:91 |
| 11001 | 240 | 34909 | 4:96 |
| 11010 | 250 | 36000 | 50 : 50 |
| 11011 | 260 | 37161 | 49 : 51 |
| 11100 | 270 | 38400 | 47 : 53 |
| 11101 | 280 | 39724 | 45 : 55 |
| 11110 | 290 | 41143 43 : 57 | |
| 11111 | 300 | 42667 | 41 : 59 |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.7 Display RAM commands

8.7.1 Command: Write-display-data

The Write-display-data command writes data byte-wise to the RAM. After Power-On Reset (POR), the RAM content is random and should be brought to a defined status by clearing it (setting it logic 0).

Table 25. Write-display-data - write display data command bit description

For this command, the register selection bits have to be set RS[1:0] = 01.

| Bit | Symbol | Value | Description |
|--------|---------|-------------------------|-------------------------------|
| - | R/W | 0 | fixed value |
| - | RS[1:0] | 01 | fixed value |
| 7 to 0 | DB[7:0] | 00000000 to 11111111 | writing data byte-wise to RAM |

More information about the display RAM can be found in Section 8.14 on page 51.

8.7.2 Bank select commands

For multiplex drive modes 1:2, and static drive mode, it is possible to write data to one area of the RAM while displaying from another. These areas are named as RAM banks. Input and output banks can be set independently from one another with the Input-bank-select and the Output-bank-select command. More information about RAM bank switching can be found in Section 8.14.3 on page 53.

8.7.2.1 Command: Input-bank-select

Table 26. Input-bank-select - input bank select command bit description This command is not applicable for multiplex drive mode 1:4.

| Bit | Symbol | Value | Description | |
|--------------------------|---------|-----------------------|-----------------------------|--------------------------|
| - | R/W | 0 | fixed value | |
| - | RS[1:0] | 00 | fixed value | |
| 7 to 2 | - | 000010 | fixed value | |
| 1 to 0 IB[1:0] selects R | | selects RAM bank to v | elects RAM bank to write to | |
| | | | static drive mode | 1:2 drive mode |
| | | 00 | bank 0: RAM-row 0 | bank 0: RAM-rows 0 and 1 |
| | | 01 | bank 1: RAM-row 1 | |
| | | 10 | bank 2: RAM-row 2 | bank 2: RAM-rows 2 |
| | | 11 | bank 3: RAM-row 3 | and 3 |

Automotive 102 x 4 Chip-On-Glass LCD segment driver

8.7.2.2 Command: Output-bank-select

Table 27. Output-bank-select - output bank select command bit description This command is not applicable for multiplex drive mode 1:4.

| Bit | Symbol | Value | Description | |
|--------|---------|--------|--|-----------------------------|
| - | R/W | 0 | fixed value | |
| - | RS[1:0] | 00 | fixed value | |
| 7 to 2 | - | 000100 | fixed value | |
| 1 to 0 | OB[1:0] | | selects RAM bank to read from to the LCD | |
| | | | static drive mode | 1:2 drive mode |
| | | 00 | bank 0: RAM-row 0 | bank 0: RAM-rows 0 and 1 |
| | | 01 | bank 1: RAM-row 1 | |
| | | 10 | bank 2: RAM-row 2 | bank 2: RAM-rows 2 and 3 |
| | | 11 | bank 3: RAM-row 3 | |

8.7.3 Command: Data-pointer

The Data-pointer command defines the display RAM address where the following display data are sent to. For setting the data pointer always the three commands Data-pointer-init, Data-pointer-MSB and Data-pointer-LSB have to be sent.

Table 28. Data-pointer - set data pointer command bit description For further information about the RAM, see Section 8.14 on page 51.

| Bit | Symbol | Value | Description | | |
|---------|---------------------------|--------------|--------------------|--|--|
| Data-po | Data-pointer-init | | | | |
| - | R/W | 0 | fixed value | | |
| - | RS[1:0] | 00 | fixed value | | |
| 7 to 0 | - | 10100000 | fixed value | | |
| Data-po | inter-MSB: PX[6:4] | | | | |
| - | R/W | 0 | fixed value | | |
| - | RS[1:0] | 00 | fixed value | | |
| 7 to 3 | - | 10000 | fixed value | | |
| 2 to 0 | PX[6:4] | 000 to 111 | 3-bit binary value | | |
| Data-po | Data-pointer-LSB: PX[3:0] | | | | |
| - | R/W | 0 | fixed value | | |
| - | RS[1:0] | 00 | fixed value | | |
| 7 to 4 | - | 1001 | fixed value | | |
| 3 to 0 | PX[3:0] | 0000 to 1111 | 4-bit binary value | | |