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A product Line of Diodes Incorporated

### PI3EQX1204-C

### 12.5Gbps 4-channel, SAS3 ReDriver with Linear Equalization

### Features

- → 1-12.5Gbps serial link with linear equalizer
- → Support SATA Gen1/Gen2/Gen3, SAS2/3, and XAUI protocol
- → Supporting 4 differential channels
- ➔ Handle up to 34dB channel loss (42" FR4 trace or 10 meters or SAS3 cable)
- ➔ Independent channel configuration of receiver equalization, output swing and flat gain
- → Rate and Coding Agnostic
- → Transparent to link training, OOB, Idle
- → 260mW per channel power dissipation with 700 mVpp output swing
- → Pin strap and I<sup>2</sup>C selectable device programming
- → 4-bit selectable address bit for  $I^2C$
- → Supply Voltage: 3.3V±0.3V
- → Industrial Temperature Range: -40°C to 85°C
- → Packaging (Pb-free & Green):
  - 42-contact TQFN (9mm x3.5mm)

### Description

The PI3EQX1204-C is a SAS3, 4 differential channels ReDriver. The device provides programmable linear equalization, output swing and flat gain, by either pin strapping option or I<sup>2</sup>C Control, to optimize performance over a variety of physical mediums by reducing Inter-symbol interference.

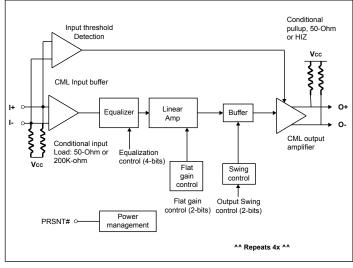
PI3EQX1204-C supports four 100-Ohm Differential CML data I/O's and extends the signals across other distant data pathways on the user's platform.

The integrated equalization circuitry provides flexibility with signal integrity of the signal before the ReDriver, whereas the integrated linear amplifier/buffer circuitry provides flexibility with signal integrity of the signal after the ReDriver.

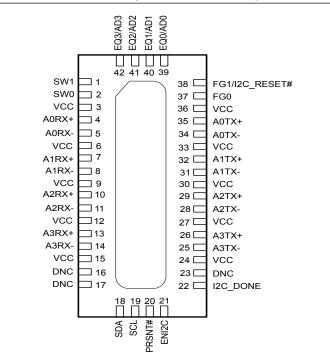
### Application

Rack Server, JBOD storage

### Block Diagram



### Pin Configuration (Top-Side View)







### **Pin Description**

Pin #	Pin Name	Туре	Description			
Data Signals						
4	A0RX+	Ι	CML inputs for Channel A0, with internal 50-Ohm pull-up and ~200K-Ohm			
5	A0RX-	Ι	pull-up otherwise.			
35	A0TX+	0	CML outputs for Channel A0, with internal 50-Ohm pull-up and high			
34	A0TX-	0	impedance otherwise.			
7	A1RX+	Ι	CML inputs for Channel A1, with internal 50-Ohm pull-up and ~200K-Ohm			
8	A1RX-	Ι	otherwise.			
32	A1TX+	0	CML outputs for Channel A1, with internal 50-Ohm pull-up and high			
31	A1TX-	0	impedance otherwise.			
10	A2RX+	Ι	CML inputs for Channel A2, with internal 50-Ohm pull-up and ~200K-Ohm			
11	A2RX-	Ι	otherwise.			
29	A2TX+	0	CML outputs for Channel A2, with internal 50-Ohm pull-up and high			
28	A2TX-	0	impedance otherwise.			
13	A3RX+	Ι	CML inputs for Channel A3, with internal 50-Ohm pull-up and ~200K-Ohm			
14	A3RX-	Ι	otherwise.			
26	A3TX+	0	CML outputs for Channel A3, with internal 50-Ohm pull-up and high			
25	A3TX-	0	impedance otherwise.			
Control Signals						
19	SCL	I/O	I <sup>2</sup> C SCL Clock. In Master mode (ENI2C floating), SCL is an output. Otherwise it is an input.			
18	SDA	I/O	I <sup>2</sup> C SDA data input/output.			
42, 41, 40, 39	AD[3:0]	Ι	I <sup>2</sup> C programmable address bits, with internal 100k-Ohm pull-up.			
20	PRSNT#	I	This pin is active in both PIN mode(ENI2C=LOW) and I <sup>2</sup> C mode (ENI2C=HIGH). Cable present detect input. This pin has internal 100K-ohm pull-up. When High, a cable is not present, and the device is put in lower power mode. When LOW, the device is enabled and in normal operation.			
21	ENI2C	Ι	When LOW, each channel is programmed by the external pin voltage. When HIGH, each channel is programmed by the data stored in the I <sup>2</sup> C bus. When floating, master mode (Read External EEPROM)			
42, 41, 40, 39	EQ[3:0]	Ι	Inputs with internal 100k-Ohm pull-up. This pins set the amount of Equalizer Boost in all channel when ENI2C is LOW.			
1, 2	SW[1:0]	Ι	Inputs with internal 100k-Ohm pull-up. This pin sets the output Voltage Level in all channel when ENI2C is LOW.			
38, 37	FG[1:0]	Ι	Inputs with internal $100K\Omega$ pull up resistor. Sets the output flat gain level on all channels when ENI2C is low.			
38	I <sup>2</sup> C_RESET#	Ι	Inputs with internal 100K $\Omega$ pull up resistor. Reset pin for I <sup>2</sup> C. When set low will reset the registers to default state.			





Pin #	Pin Name	Туре	Description
22	I <sup>2</sup> C_DONE	0	Valid register load status output, use for daisy chain master LOW = External EEPROM load failed HIGH = External EEPROM load passed
16, 17, 23	DNC		Do Not Connect
Power Pins			
3, 6, 9, 12, 15, 24, 27, 30, 33, 36	V <sub>CC</sub>	PWR	3.3V Supply Voltage
ЕР	GND	PWR	Exposed pad. Supply Ground





### **Description of Operation**

### **Power Enable function:**

One pin control or I<sup>2</sup>C control, when PRSNT# is set to HIGH, the IC goes into power down mode, both input and output termination set to 200K and High impedance respectively. Individual Channel Enabling is done through the I<sup>2</sup>C register programming.

### **Equalization Setting:**

EQ[3:0] are the selection pins for the equalization selection for each channel.

### **Table 1. Equalization Setting**

	Equalizer setting								
EQ3	EQ2	EQ1	EQ0	@ 3GHz	@ 4GHz	@ 5GHz	@ 6GHz		
0	0	0	0	3.6	4.5	5.5	6.8		
0	0	0	1	4	5.1	6.2	7.6		
0	0	1	0	4.4	5.6	6.9	8.4		
0	0	1	1	4.7	6.1	7.5	9.1		
0	1	0	0	5.1	6.6	8.1	9.8		
0	1	0	1	5.5	7.1	8.7	10.4		
0	1	1	0	5.9	7.6	9.2	11		
0	1	1	1	6.2	8	9.7	11.5		
1	0	0	0	6.6	8.5	10.2	12		
1	0	0	1	6.9	8.9	10.7	12.5		
1	0	1	0	7.3	9.3	11.1	12.9		
1	0	1	1	7.6	9.7	11.5	13.3		
1	1	0	0	8	10.1	11.9	13.7		
1	1	0	1	8.2	10.5	12.3	14.1		
1	1	1	0	8.6	10.8	12.7	14.4		
1	1	1	1	8.9	11.1	13	14.7		



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**PI3EQX1204-C** 

### Flat Gain Setting:

FG[1:0] are the selection bits for the DC value.

### Table 2. Flat Gain Setting

Flat Gain Setting					
FG1	FG0	dB			
0	0	-3.5			
0	1	-1.5			
1	0	0.5			
1	1	2.5			

### Swing Setting:

Swing Setting: SW[1:0] are the selection bits for the output swing value.

### Table 3. Swing Setting

SW1	SW0	mVp-p
0	0	700
0	1	800
1	0	900
1	1	1000





### I<sup>2</sup>C Programming

Address	assignmen	t							
A6	A5	A	4	A3	A2	A1	A0	R/W	
1	1	1		AD3	AD2	AD1	AD0	1=R, 0=W	
BYTE 0	Reserved								
BYTE 1	Reserved								
BYTE 2									
Bit	Туре	Power up	condition			С	ontrol affected	Comment	
7	R/W	0				A	3 Power down		
6	R/W	0				A	2 Power down		
5	R/W	0				A	1 Power down		
4	R/W	0				A	) Power down	1 Dergen der	
3	R/W	0						-1 = Power down	
2	R/W	0							
1	R/W	0							
0	R/W	0							
BYTE 3				·				·	
Bit	Туре	Power up	condition			C	ontrol affected	Comment	
7	R/W	0				E	Q3		
6	R/W	0				E	Q2	– Equalizer	
5	R/W	0				E	Q1		
4	R/W	0		C	annal A0 configur	E	Q0		
3	R/W	0			nannel A0 configura	F	G1		
2	R/W	0				F	G0	— Flat gain	
1	R/W	0				SV	W1	Suring	
0	R/W	0				SV	W0	— Swing	
BYTE 4				i					
Bit	Туре	Power up	o condition			C	ontrol affected	Comment	
7	R/W	0				E	Q3		
6	R/W	0				E	Q2	Equalizer	
5	R/W	0				E	Q1	Equanzer	
4	R/W	0			annal Al conferm	E	Q0		
3	R/W	0			nannel A1 configura	F	G1	Elat asi:	
2	R/W	0				F	G0	— Flat gain	
1	R/W	0				SV	W1	Servin -	
								Swing	





### I<sup>2</sup>C Programming cont.

Bit	Туре	Power up condition		Control affected	Comment
7	R/W	0		EQ3	
6	R/W	0	n Channel A2 configuration FG FG	EQ2	
5	R/W	0		EQ1	– Equalizer
4	R/W	0		EQ0	
3	R/W	0		FG1	
2	R/W	0		FG0	– Flat gain
1	R/W	0		SW1	Continue
0	R/W	0		SW0	- Swing
BYTE	5				
Bit	Туре	Power up condition		Control affected	Comment
7	R/W	0		EQ3	
/	10/ 11	-		LQJ	
6	R/W	0		EQ2	- -
					– – Equalizer
6	R/W	0		EQ2	– – Equalizer –
6 5	R/W R/W	0 0	Channel A3 configuration	EQ2 EQ1	_
6 5 4 3	R/W R/W R/W	0 0 0	Channel A3 configuration	EQ2 EQ1 EQ0	– Equalizer – Flat gain
6 5 4	R/W           R/W           R/W           R/W           R/W	0 0 0 0	Channel A3 configuration	EQ2 EQ1 EQ0 FG1	_

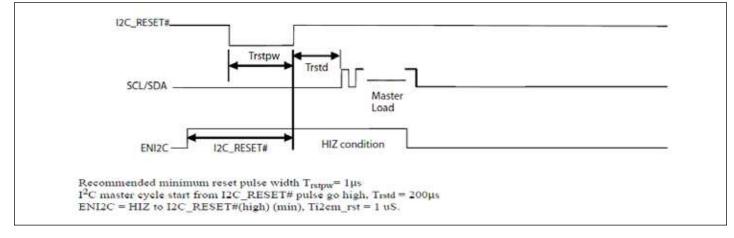


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PI3EQX1204-C

### **Reset and I<sup>2</sup>CM Timing Diagram**



### I<sup>2</sup>C Operation

The integrated I<sup>2</sup>C interface operates as a master or slave device depending on the pin ENI2C being HIZ or HIGH respectively. Standard mode (100Kbps) is supported with 7-bit addressing. The data byte format is 8-bit bytes, and supports the format of indexing to be compatible with other bus devices. In the Slave mode (ENI2C = HIGH), the device supports Read/Write. The bytes must be accessed in sequential order from the lowest to the highest byte with the ability to stop after any complete byte has been transferred. Address bits A3 to A0 are programmable to support multiple chips environment. The Data is loaded until a Stop sequence is issued.

In the master mode (ENI2C = HIZ), PI3EQX1204-C supports up to 16 masters connected in daisy chain through connecting  $I^2C_DONE$  pin to  $I^2C_RESET\#$  pin of the next part.

I <sup>2</sup> C address:	
AD3, AD2, AD1, AD0	Data starting location
0000	00H
0001	10H
0010	20H
0011	30H
0100	40H
0101	50H
0110	60H
0111	70H
1000	80H
1001	90H
1010	A0H
1011	B0H
1100	С0Н
1101	D0H
1110	E0H
1111	F0H

Master EEPROM data starting address for device address:





Transferring Data

Every byte put on the SDA line must be 8-bits long. Each byte has to be followed by an acknowledge bit. Data is transferred with the most significant bit (MSB) first (see the I<sup>2</sup>C Data Transfer diagram). The PI3EQX1204-C will never hold the clock line SCL LOW to force the master into a wait state.

### Acknowledge

Data transfer with acknowledge is required from the master. When the master releases the SDA line (HIGH) during the acknowledge clock pulse, the PI3EQX1204-C will pull down the SDA line during the acknowledge clock pulse so that it remains stable LOW during the HIGH period of this clock pulse as indicated in the I2C Data Transfer diagram. The PI3EQX1204-C will generate an acknowledge after each byte has been received.

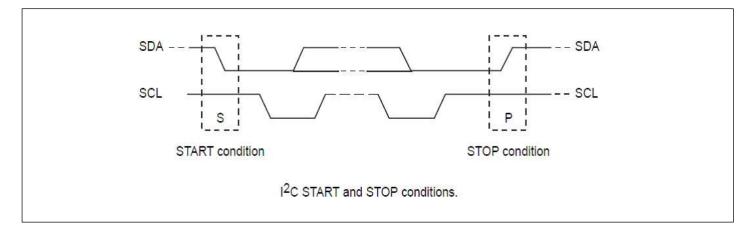
### Data Transfer

A data transfer cycle begins with the master issuing a start bit. After recognizing a start bit, the PI3EQX1204-C will watch the next byte of information for a match with its address setting. When a match is found it will respond with a read or write of data on the following clocks. Each byte must be followed by an acknowledge bit, except for the last byte of a read cycle which ends with a stop bit. For a write cycle, the first data byte following the address byte is an index byte that is used by the PI3EQX1204-C. Data is transferred with the most significant bit (MSB) first.

### **12C Data Transfer**

### Start & Stop Conditions

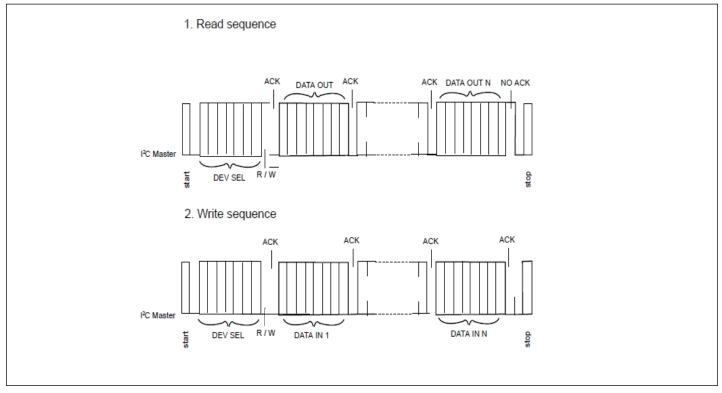
A HIGH to LOW transition on the SDA line while SCL is HIGH indicates a START condition. A LOW to HIGH transition on the SDA line while SCL is HIGH defines a STOP condition, as shown in the figure below







### I<sup>2</sup>C Data Transfer







### Maximum Ratings

(Above which useful life may be impaired. For user guidelines, not tested.)

Storage Temperature65°C to +150°C
Supply Voltage to Ground Potential0.5V to +4.6V
DC SIG Voltage $\ldots \ldots \ldots \ldots \ldots -0.5V$ to $V_{CC}\text{+}0.5V$
Output Current25mA to +25mA
Power Dissipation Continuous2.1W
Junction Temperature Tj 125°C
ESD, HBM2kV to +2kV

Note:

Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

### **Electrical characteristics:**

### LVCMOS I/O DC Specifications ( $V_{CC} = 3.3 \pm 0.3 V$ , $T_A = -40$ to $85^{\circ}$ C)

Symbol	Parameter	Conditions	Min.	Тур.	Max	Units
V <sub>IH</sub>	DC input logic high		$V_{\rm CC}/2+0.7$		$V_{\rm C}C + 0.3$	V
V <sub>IL</sub>	DC input logic low		-0.3		V <sub>CC</sub> /2 - 0.7	v
V <sub>OH</sub>	At IOH = -200μA		$V_{CC} + 0.2$			V
V <sub>OL</sub>	At IOL = $-200\mu$ A				0.2	v
V <sub>hys</sub>	Hysteresis of Schmitt trigger input		0.8			v

### SDA and SCL I/O for I2C-bus (V\_{CC} = 3.3 $\pm$ 0.3V, T\_A = -40 to 85°C)

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
V <sub>IH</sub>	DC input logic high		$V_{CC}/2 + 0.7$		V <sub>CC</sub> + 0.3	V
V <sub>IL</sub>	DC input logic low		-0.3		V <sub>CC</sub> /2 - 0.7	V
V <sub>OL</sub>	DC output logic low	$I_{OL} = 3mA$			0.4	V
V <sub>hys</sub>	Hysteresis of Schmitt trigger input		0.8			V
t <sub>of</sub>	Output fall time from VIHmin to VILmax with bus cap. 10-400pF				250	ns
f <sub>SCLK</sub>	SCLK clock frequency				100	kHz

### High speed I/O AC/DC Specifications ( $V_{CC} = 3.3 \pm 0.3 V$ , $T_A = -40$ to $85^{\circ}$ C)

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units	
C <sub>RX</sub>	RX AC coupling capacitance			220		nF	
0	T	10MHz to 6GHz differential		11.0		10	
S <sub>11</sub>	Input return loss	100 Hz to 6GHz differential       11.0         100 Hz to 6GHz common mode       5.0         100 Hz to 6GHz differential       11.5         110 Hz to 6GHz differential       11.5		dB			
0		10MHz to 6GHz differential		11.5		10	
S <sub>22</sub>	Output return loss	1GHz to 6GHz common mode		4.8	0	dB	
D	DC single-ended input impedance			50		0	
R <sub>IN</sub>	DC Differential Input Impedance			100		Ω	





### High speed I/O AC/DC Specifications cont.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units		
R <sub>OUT</sub>	DC single-ended output impedance		50					
	DC Differential output Impedance			100		Ω		
Z <sub>RX-HIZ</sub>	DC input CM input impedance during reset or power down			200		kΩ		
V <sub>RX-DIFF-PP</sub>	Differential Input Peak-to-peak Volt- age	Operational			1.2	Vppd		
	Input source common-mode noise	DC – 200MHz			150	mVpp		
T <sub>TX-IDLE-SET-TO-</sub> IDLE	Max time to electrical idle after send- ing an EIOS			4	8	ns		
T <sub>TX-IDLE-TO-DIFF-</sub> DATA	Max time to valid diff signal after leav- ing electrical idle			4	8	ns		
Vcc	Power supply voltage		3	3.3	3.6	V		
P <sub>max</sub>	Max Supply power	PRSNT#=0			1.3	W		
I <sub>max</sub>	Max Supply current				360	mA		
P <sub>idle</sub>	Supply power	PRSNT#=1			14.4	mW		
t <sub>pd</sub>	Latency	From input to output		0.5		ns		
Gp	Peaking gain (Compensation at 6GHz, relative to 100MHz, 100mVp-p sine wave input)	EQ<3:0> = 1111		15.4		dB		
		EQ<3:0> = 1000		12.5				
		EQ<3:0> = 0000		7.1				
		Variation around typical	-3		+3	dB		
	Flat gain (100MHz, EQ<3:0> = 1000, SW<1:0> = 10)	FG<1:0> = 11		2				
		FG<1:0> = 10		0		dB		
G <sub>F</sub>		FG<1:0> = 01		-2				
		FG<1:0> = 00		-4				
		Variation around typical	-3		+3	dB		
V1dB_100M	-1dB compression point of output swing (at 100MHz)	SW<1:0> = 11		1370				
		SW<1:0> = 10		1280		mVppd		
		SW<1:0> = 01		1040				
		SW<1:0> = 00		920				
V <sub>1dB_6G</sub>	-1dB compression point of output swing (at 6GHz)	SW<1:0> = 11		1000				
		SW<1:0> = 10		940				
		SW<1:0> = 01		700		mVppd		
		SW<1:0> = 00		600				
V <sub>Coup</sub>	Channel isolation	100MHz to 6GHz, Figure 1 (Note 1)25			dB			





### High speed I/O AC/DC Specifications cont.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
Vnoise_input	Input-referred noise	100MHz to 6GHz, FG<1:0> = 11, EQ<3:0> = 0000, Figure 2		0.5		mV <sub>RMS</sub>
		100MHz to 6GHz, FG<1:0> = 11, EQ<3:0> = 1010, Figure 2		0.4		
Vnoise_output		100MHz to 6GHz, FG<1:0> = 11, EQ<3:0> = 0000, Figure 2		0.7		
	Output-referred noise (Note 2)	100MHz to 6GHz, FG<1:0> = 11, EQ<3:0> = 1010, Figure 2		0.8	0.8 1.6	mV <sub>RMS</sub>

Note: (1) Measured using a vector-network analyzer (VNA) with -15dBm power level applied to the adjacent input. The VNA detects the signal at the output of the victim channel. All other inputs and outputs are terminated with  $50\Omega$ .

(2) Guaranteed by design and characterization.

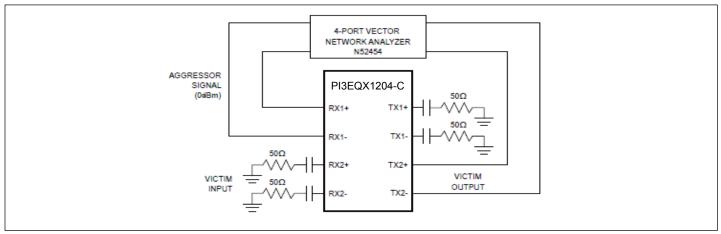
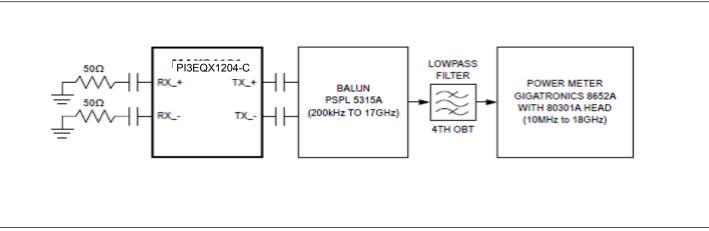


Figure 1. Channel-isolation test configuration







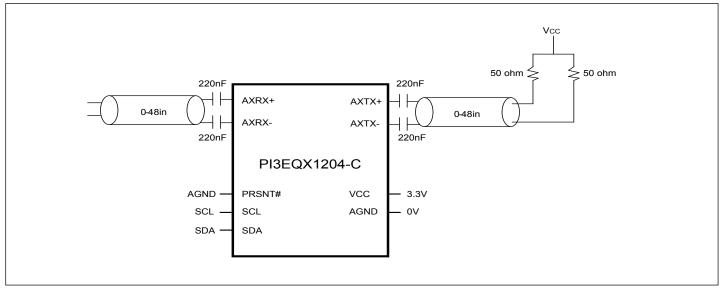
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PI3EQX1204-C

### **ESD Specification**

- 2000V HBM
- 500V CDM

### **Application Diagram**







### AC/DC Specifications - SCL/SDA for I<sup>2</sup>C BUS

Symbol	Parameter	Conditions	Min.	Тур.	Max	Units
V <sub>IH</sub>	DC input logic high		V <sub>CC</sub> /2 + 0.7		V <sub>CC</sub> + 0.3	V
V <sub>IL</sub>	DC input logic low		-0.3		V <sub>CC</sub> /2 - 0.7	V
V <sub>OL</sub>	DC output logic low	$I_{OL} = 3mA$			0.4	V
Ipullup	Current Through Pull-Up Resistor or Current Source	High Power specification	3.0		3.6	mA
VDD	Nominal Bus Voltage		3.0		3.6	V
Ileak-bus	Input leakage per bus segment		-200		200	uA
Ileak-pin	Input leakage per device pin			-15		uA
CI	Capacitance for SDA/SCL				10	pF
Freq	Bus Operation Frequency				100k	Hz
TBUF	"Bus Free Time Between Stop and Start condition"		1.3			us
THD:STA	Hold time after (Repeated) Start condition. After this period, the first clock is generated.	At Ipull-up, Max	0.6			us
TSU:STA	Repeated start conidtion setup time		0.6			us
TSU:STO	Stop condition setup time		0.6			us
THD:DAT	Data hold time		0			ns
TSU:DAT	Data setup time		100			ns
Tlow	Clock low period		1.3			us
Thigh	Clock high period		0.6		50	us
tF	Clock/Data fall time				300	ns
tR	Clock/Data rise time				300	ns
tpor	"Time in which a device must be operation after power-on reset"				500	ms

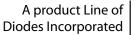
Note: (1) Recommended value.

(2) Recommended maximum capacitance load per bus segment is 400pF.

(3) Compliant to I2C physical layer specification.

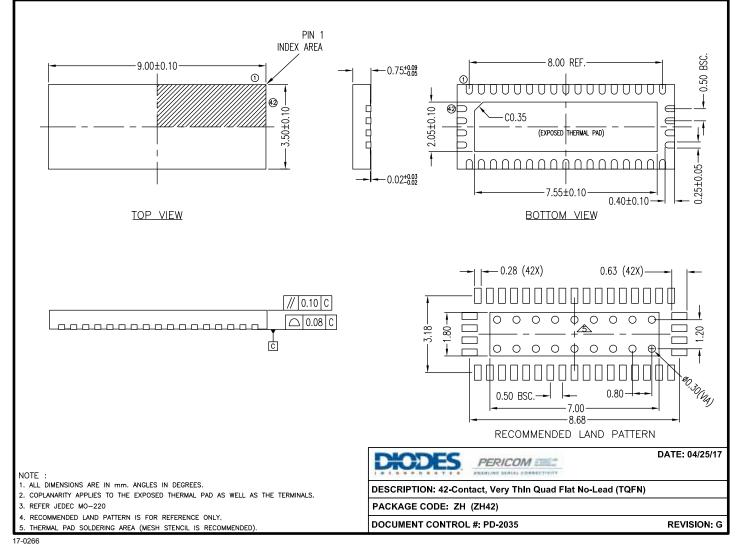
(4) Ensured by Design. Parameter not tested in production.







### Package Mechanical: 42-Contact TQFN (ZH)



Note: For latest package info, please check: https://www.diodes.com/design/support/packaging/pericom-packaging/

### **Ordering Information**

Ordering Number	Package Code	Package Description
PI3EQX1204-CZHE	ZH	42-Contact, Thin Fine Pitch Quad Flat No-Lead (TQFN)
PI3EQX1204-CZHEX	ZH	42-Contact, Thin Fine Pitch Quad Flat No-Lead (TQFN), Tape & Reel

Notes:

• Thermal characteristics can be found on the company web site at www.pericom.com/packaging/

• E = Pb-free and Green

• X suffix = Tape/Reel





### IMPORTANT NOTICE

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