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4-Bit I2C-Bus and SMBus Low Power I/O Port

# Features

- → Operation power supply voltage from 2.3V to 5.5V
- → 4-bit I<sup>2</sup>C-bus GPIO with 5V tolerant I/Os
- ➔ Polarity inversion register
- → Low current consumption
- $\rightarrow$  0Hz to 1MHz clock frequency
- → Noise filter on SCL/SDA inputs
- → Power-on reset
- → 4 I/O pin which default to 4 inputs with 100kΩ pull-up resistor
- → ESD protection (4KV HBM and 1KV CDM)
- ➔ Offered in three different packages:SOIC-8,MSOP-8 and TDFN2x3-8

# **Pin Configuration**

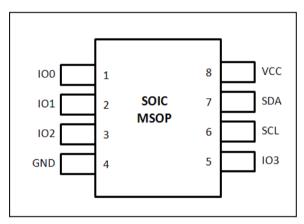


Figure1 : SOIC-8 & MSOP-8

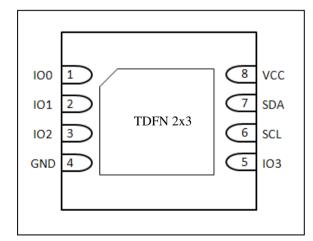


Figure2 : TDFN 2x3-8

# Description

The PI4IOE5V9536 provides 4 bits of General Purpose parallel Input/Output (GPIO) expansion for I<sup>2</sup>C-bus/ SMBus applications. It includes the features such as higher driving capability, 5V tolerance, lower power supply, individual I/O configuration, and smaller packaging. It provides a simple solution when additional I/O is needed for ACPI power switches, sensors, push buttons, LEDs, fans, etc.

The PI4IOE5V9536 consists of a 4-bit registers to configure the I/Os as either inputs or outputs, and a 4-bit polarity registers to change the polarity of the input port register data The data for each input or output is kept in the corresponding Input port or Output port register. All registers can be read by the system master.

# **Pin Description**

\* I = Input; O = Output; P = Power; G = Ground

Pin	Name	Туре	Description
1	IO0	I/O	input/output 0
2	IO1	I/O	input/output 1
3	IO2	I/O	input/output 2
4	GND	G	Supply Ground
5	IO3	I/O	input/output 3
6	SCL	Ι	Serial clock line
7	SDA	I/O	Serial data line
8	VCC	Р	Power supply





# **Maximum Ratings**

Power supply	-0.5V to +6.0V
Voltage on an I/O pin	
Input current	±20mA
Output current on an I/O pin	
Supply current	
Ground supply current	
Total power dissipation	
Operation temperature	40~85°C
Storage temperature	65~150℃
Maximum Junction temperature ,T j(max)	125°C
1	

Note:

Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

# **Static Characteristics**

VCC = 2.3 V to 5.5 V; GND = 0 V; Tamb= -40 °C to +85 °C; unless otherwise specified. Table 2: Static characteristic

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
Power supp	ly					
VCC	Supply voltage		2.3	-	5.5	V
т	Supply automt	Operating mode; VCC = 5.5 V; no load; fscL= 1MHz,	-	100	150	μΑ
I <sub>CC</sub>	Supply current	Operating mode; VCC = 2.3V; no load; fscL= 1MHz		20	40	μA
I <sub>stb</sub>	Stondby aumont	Standby mode; VCC = 5.5 V; no load; VI = GND; fSCL= 0 kHz; I/O = inputs	-	225	350	uA
I <sub>stb</sub>	Standby current	Standby mode; VCC = 5.5 V; no load; VI = VCC; fSCL= 0 kHz; I/O = inputs	-	0.25	1	μΑ
V <sub>POR</sub>	Power-on reset voltage <sup>[1]</sup>		-	1.16	1.41	V
Input SCL,	input/output SDA					
V <sub>IL</sub>	Low level input voltage		-0.5	-	+0.3VCC	V
V <sub>IH</sub>	High level input voltage		0.7VCC	-	5.5	V
I <sub>OL</sub>	Low level output current	V <sub>OL</sub> =0.4V	3	6	-	mA
$I_L$	Leakage current	V <sub>I</sub> =VCC=GND	-1	-	1	μΑ
Ci	Input capacitance	V <sub>1</sub> =GND	-	6	10	pF





**PI4IOE5V9536** 

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
/Os	•					
VIL	Low level input voltage		-0.5	-	+0.81	V
VIH	High level input voltage		+1.8	-	5.5	V
		$VCC = 2.3 \text{ V}; \text{ V}_{OL} = 0.5 \text{ V}^{[2]}$	8	10	-	mA
		$VCC = 2.3 \text{ V}; \text{ V}_{OL} = 0.7 \text{ V}^{[2]}$	10	13	-	mA
T		$VCC = 3.0 \text{ V}; \text{ V}_{OL} = 0.5 \text{ V}^{[2]}$	8	14	-	mA
I <sub>OL</sub> Low level output current	$VCC = 3.0 \text{ V}; \text{ V}_{OL} = 0.7 \text{ V}^{[2]}$	10	19	-	mA	
		$VCC = 4.5 \text{ V}; \text{ V}_{OL} = 0.5 \text{ V}^{[2]}$	8	17	-	mA
		VCC =4.5 V; $V_{OL}$ = 0.7 V <sup>[2]</sup>	10	24	-	mA
		$I_{OH}$ =-8mA;VCC=2.3V <sup>[3]</sup>	1.8	-	-	V
		I <sub>OH</sub> =-10mA;VCC=2.3V <sup>[3]</sup>	1.7	-	-	V
<b>N</b> 7		I <sub>OH</sub> =-8mA;VCC=3.0V <sup>[3]</sup>	2.6	-	-	V
V <sub>OH</sub>	High level output voltage	I <sub>OH</sub> =-10mA;VCC=3.0V <sup>[3]</sup>	2.5	-	-	V
		I <sub>OH</sub> =-8mA;VCC=4.75V <sup>[3]</sup>	4.1	-	-	V
		I <sub>OH</sub> =-10mA;VCC=4.75V <sup>[3]</sup>	4.0	-	-	V
I <sub>LIH</sub>	High level input leakage current	VCC=3.6V; V <sub>I</sub> =VCC	-	-	1	μΑ
I <sub>LIL</sub>	Low level input leakage current	VCC=5.5V; V <sub>I</sub> =GND	-	-	-100	μΑ
$C_i$	Input capacitance		-	3.7	10	pF
Co	Output capacitance		-	3.7	10	pF

Note: [1]: VCC must be lowered to 0.2 V for at least 5 us in order to reset part. [2]: Each I/O must be externally limited to a maximum of 25 mA and the device must be limited to a maximum current of 100 mA [3]: The total current sourced by all I/Os must be limited to 85mA.





**PI4IOE5V9536** 

# **Dynamic Characteristics**

Table 3: Dynamic characteristics

Symbol	Parameter	Test	Stan mode			mode <sup>2</sup> C	Fast mode Plus I <sup>2</sup> C		Unit
Symbol	T ut unicici	Conditions	Min	Max	Min	Max	Min	Max	
$\mathbf{f}_{\mathrm{SCL}}$	SCL clock frequency		0	100	0	400	0	1000	kHz
t <sub>BUF</sub>	bus free time between a STOP and START condition		4.7	-	1.3	-	0.5	-	μs
t <sub>HD;STA</sub>	hold time (repeated) START condition		4.0	-	0.6	-	0.26	-	μs
t <sub>SU;STA</sub>	set-up time for a repeated START condition		4.7	-	0.6	-	0.26	-	μs
t <sub>SU;STO</sub>	set-up time for STOP condition		4.0	-	0.6	-	0.26	-	μs
t <sub>VD;ACK</sub> <sup>[1]</sup>	data valid acknowledge time		-	3.45	-	0.9	-	0.45	μs
t <sub>HD;DAT</sub> <sup>[2]</sup>	data hold time		0	-	0	-	0	-	ns
t <sub>VD;DAT</sub>	data valid time		-	3.45	-	0.9	-	0.45	us
t <sub>SU;DAT</sub>	data set-up time		250	-	100	-	50	-	ns
t <sub>LOW</sub>	LOW period of the SCL clock		4.7	-	1.3	-	0.5	-	μs
t <sub>HIGH</sub>	HIGH period of the SCL clock		4.0	-	0.6	-	0.26	-	μs
$t_{\rm f}$	fall time of both SDA and SCL signals		-	300	-	300	-	120	ns
t <sub>r</sub>	rise time of both SDA and SCL signals		-	1000	-	300	-	120	ns
t <sub>SP</sub>	pulse width of spikes that must be suppressed by the input filter		-	50	-	50		50	ns
Port timing									
$t_{v(Q)}$	Data output valid time <sup>[3]</sup>		-	200	-	200	-	200	ns
t <sub>su(D)</sub>	Data input set-up time		100	-	100	-	100	-	ns
$T_{h\left(D\right)}$	Data input hold time		1	-	1	-	1	-	μs

Note:

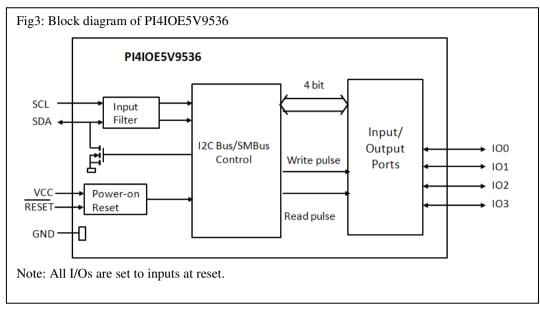
[1]:  $t_{VD;ACK}$  = time for acknowledgement signal from SCL LOW to SDA (out) LOW. [2]:  $t_{VD;DAT}$  = minimum time for SDA data out to be valid following SCL LOW.

[3]:  $t_{v(Q)}$  measured from 0.7VCC on SCL to 50% I/O output.





# PI4IOE5V9536 Block Diagram



# **Details Description**

## a. Device address

Table 4: Device address

	b7(MSB)	b6	b5	b4	b3	b2	b1	b0
Address Byte	1	0	0	0	0	0	1	R/W

Note: Read "1", Write "0"

# **b.** Registers

### i. Command byte

The command byte is the first byte to follow the address byte during a write transmission. It is used as a pointer to determine which of the following registers will be written or read.

Table 5: Command byte

Command	Register
0	Input port register
1	Output port register
2	Polarity inversion register
3	Configuration register





#### ii.Register 0: input port registers

This register is a read-only port. It reflects the incoming logic levels of the pins, regardless of whether the pin is defined as an input or an output by Register 2. Writes to this register have no effect.

The default value 'X' is determined by the externally applied logic level.

Table 6: Input port 0 register

Bit	7	6	5	4	3	2	1	0
Symbol	I7	I6	I5	I4	I3	I2	I1	IO
Default	1	1	1	1	Х	Х	Х	Х

#### iii. Register 1:Output port register

This register is an output-only port. It reflects the outgoing logic levels of the pins defined as outputs by Registers 3. Bit values in this register have no effect on pins defined as inputs. In turn, reads from this register reflect the value that is in the flip-flop controlling the output selection, not the actual pin value.

Table 8: Output port 0 register

Bit	7	6	5	4	3	2	1	0
Symbol	07	O6	05	O4	03	O2	01	00
Default	1	1	1	1	1	1	1	1

#### iv. Register 2: Polarity inversion register

This register allows the user to invert the polarity of the Input port register data. If a bit in this register is set (written with '1'), the Input port data polarity is inverted. If a bit in this register is cleared (written with a '0'), the Input port data polarity is retained. Table 10: Polarity Inversion port 0 register

Bit	7	6	5	4	3	2	1	0
Symbol	N7	N6	N5	N4	N3	N2	N1	N0
Default	0	0	0	0	0	0	0	0

#### v. Register 3: Configuration registers

This register configures the directions of the I/O pins. If a bit in this register is set (written with '1'), the corresponding port pin is enabled as an input with high-impedance output driver. If a bit in this register is cleared (written with '0'), the corresponding port pin is enabled as an output. At reset, the I/Os are configured as inputs with a weak pull-up to VCC

Table 12: Configuration port 0 register

Bit	7	6	5	4	3	2	1	0
Symbol	C7	C6	C5	C4	C3	C2	C1	C0
Default	1	1	1	1	1	1	1	1





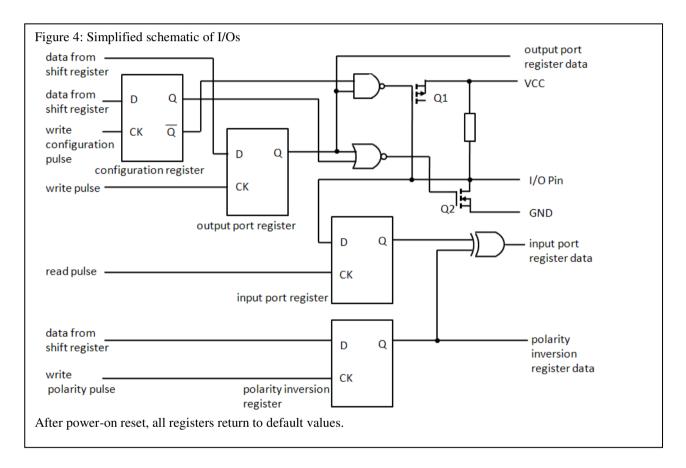
#### c. Power-on reset

When power is applied to VCC, an internal power-on reset holds the PI4IOE5V9536 in a reset condition until VCC has reached  $V_{POR}$ . At that point, the reset condition is released and the PI4IOE5V9536 registers and SMBus state machine will initialize to their default states. Thereafter, VCC must be lowered below 0.2 V to reset the device. For a power reset cycle, VCC must be lowered below 0.2 V and then restored to the operating voltage.

# d. I/O port

When an I/O is configured as an input, FETs Q1 and Q2 are off, creating a high-impedance input. The input voltage may be raised above VCC to a maximum of 5.5 V.

If the I/O is configured as an output, then either Q1 or Q2 is on, depending on the state of the Output Port register. Care should be exercised if an external voltage is applied to an I/O configured as an output because of the low-impedance path that exists between the pin and either VCC or GND.

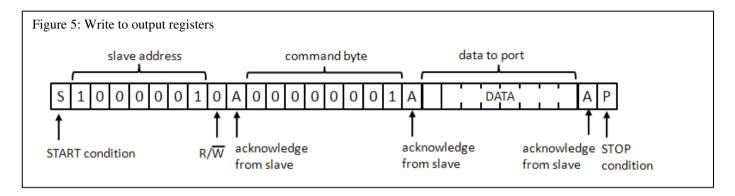


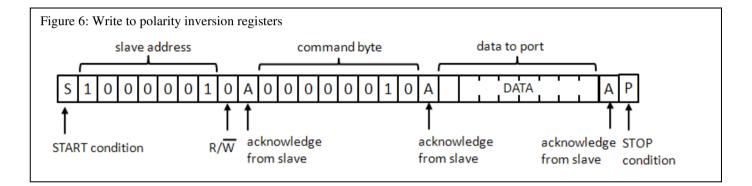


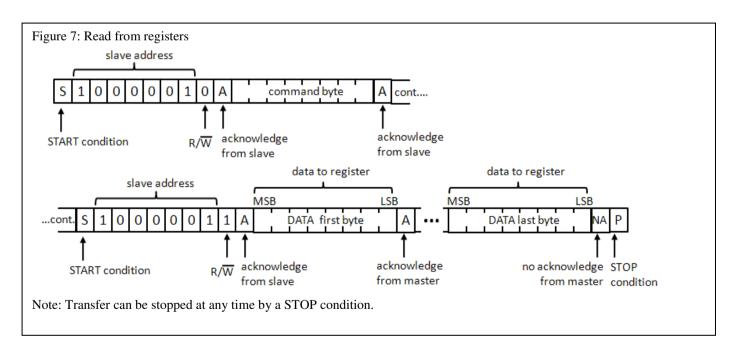


#### e. Bus Transaction

Data is transmitted to the PI4IOE5V9536 using the Write mode as shown in Figure 5.Data is read from the PI4IOE5V9536 using the read mode as shown in Figure 7.These devices do not implement an auto-increment function, so once a command byte has been sent, the register which was addressed will continue to be accessed by reads until a new command byte has been sent.



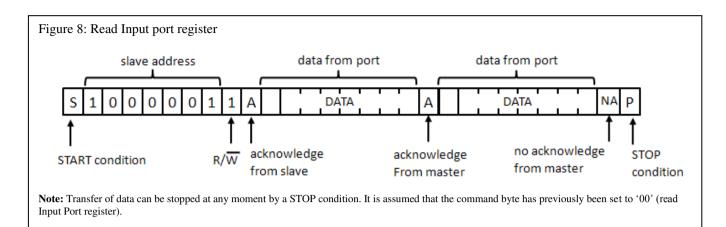




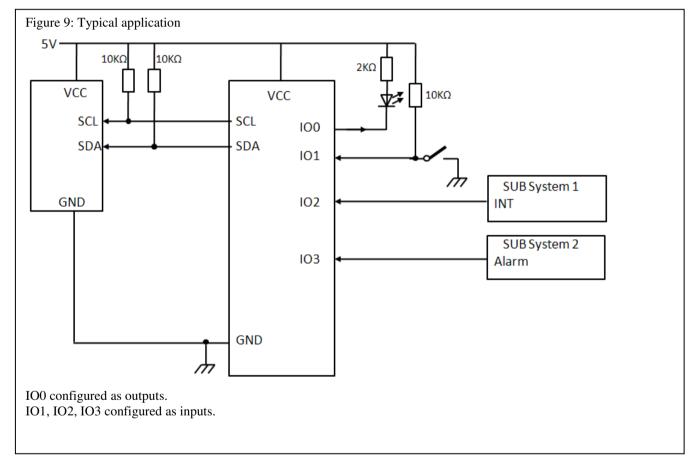




PI4IOE5V9536



# **Application Design-In Information**







# **Part Marking**

U Package

IOE5V9 536UE ABKG

AB: Date Code (Year & Workweek) K: Assembly Site Code G: Wafer Fab Site Code Bar above "G" means Cu wire

W Package and ZE Package

Top mark not available at this time. To obtain advance information regarding the top mark, please contact your local sales representative.

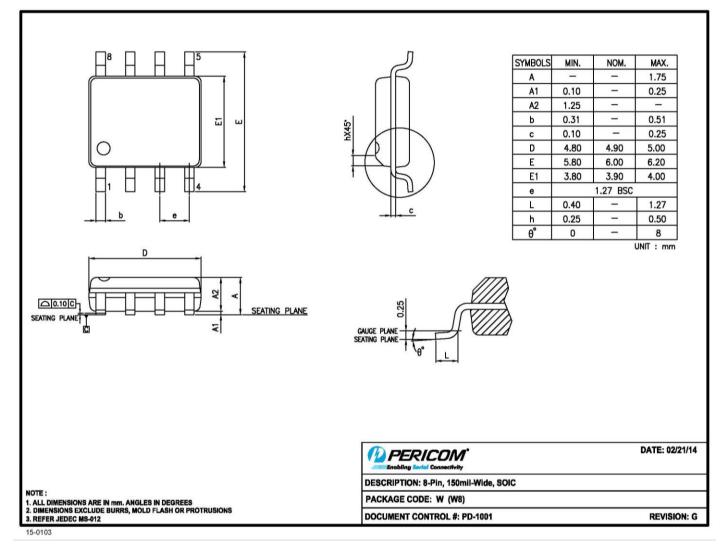




**PI4IOE5V9536** 

# **Packaging Mechanical**

SOIC-8 (W)

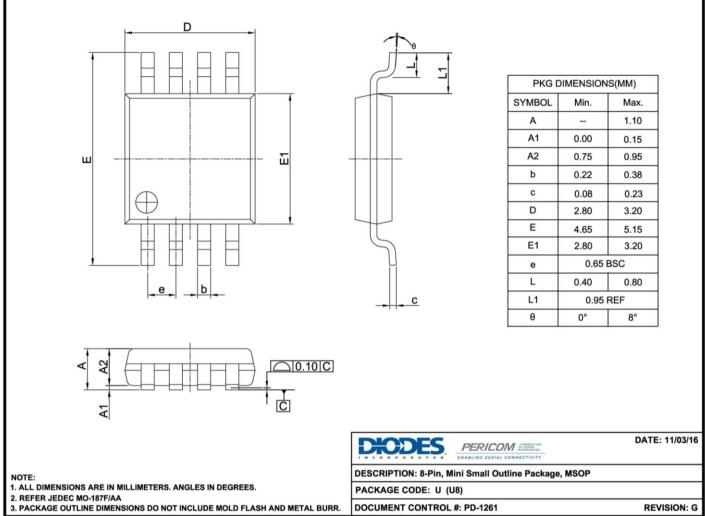






PI4IOE5V9536

### MSOP-8 (U)



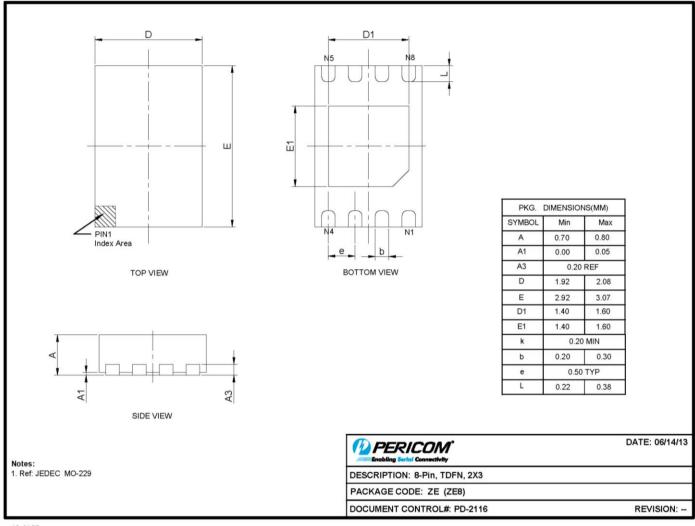
16-0242





**PI4IOE5V9536** 

TDFN-8 (ZE)



13-0155

#### For latest package info.

please check: http://www.diodes.com/design/support/packaging/pericom-packaging/packaging-mechanicals-and-thermal-characteristics/

# **Ordering Information**

Part Number	Package Code	Package Description
PI4IOE5V9536WEX	W	8-Pin,150mil-Wide (SOIC)
PI4IOE5V9536UEX	U	8-Pin, Mini Small Outline Package (MSOP)
PI4IOE5V9536ZEEX	ZE	8-Pin, 2x3 (TDFN)

Notes:

• No purposely added lead. Fully EU Directive 2002/95/EC (RoHS), 2011/65/EU (RoHS 2) & 2015/863/EU (RoHS 3).compliant.

• See http://www.diodes.com/quality/lead-free/ for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.

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• E = Pb-free and Green

• X suffix = Tape/Reel





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