



Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from,Europe,America and south Asia,supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of “Quality Parts,Customers Priority,Honest Operation,and Considerate Service”,our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip,ALPS,ROHM,Xilinx,Pulse,ON,Everlight and Freescale. Main products comprise IC,Modules,Potentiometer,IC Socket,Relay,Connector.Our parts cover such applications as commercial,industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China





# **PIC16F688**

## **Data Sheet**

14-Pin Flash-Based, 8-Bit  
CMOS Microcontrollers with  
nanoWatt Technology

---

**Note the following details of the code protection feature on Microchip devices:**

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as "unbreakable."

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip's code protection feature may be a violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

---

Information contained in this publication regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION, QUALITY, PERFORMANCE, MERCHANTABILITY OR FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights.

**Trademarks**

The Microchip name and logo, the Microchip logo, dsPIC, KEELOQ, KEELOQ logo, MPLAB, PIC, PICmicro, PICSTART, rfPIC and UNI/O are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.


FilterLab, Hampshire, HI-TECH C, Linear Active Thermistor, MXDEV, MXLAB, SEEVAL and The Embedded Control Solutions Company are registered trademarks of Microchip Technology Incorporated in the U.S.A.

Analog-for-the-Digital Age, Application Maestro, CodeGuard, dsPICDEM, dsPICDEM.net, dsPICworks, dsSPEAK, ECAN, ECONOMONITOR, FanSense, HI-TIDE, In-Circuit Serial Programming, ICSP, Mindi, MiWi, MPASM, MPLAB Certified logo, MPLIB, MPLINK, mTouch, Octopus, Omniscient Code Generation, PICC, PICC-18, PICDEM, PICDEM.net, PICKit, PICtail, PIC<sup>32</sup> logo, REAL ICE, rfLAB, Select Mode, Total Endurance, TSHARC, UniWinDriver, WiperLock and ZENA are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

SQTP is a service mark of Microchip Technology Incorporated in the U.S.A.

All other trademarks mentioned herein are property of their respective companies.

© 2009, Microchip Technology Incorporated, Printed in the U.S.A., All Rights Reserved.

 Printed on recycled paper.

**QUALITY MANAGEMENT SYSTEM**  
**CERTIFIED BY DNV**  
**== ISO/TS 16949:2002 ==**

*Microchip received ISO/TS-16949:2002 certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona; Gresham, Oregon and design centers in California and India. The Company's quality system processes and procedures are for its PIC<sup>®</sup> MCUs and dsPIC<sup>®</sup> DSCs, KEELOQ<sup>®</sup> code hopping devices, Serial EEPROMs, microperipherals, nonvolatile memory and analog products. In addition, Microchip's quality system for the design and manufacture of development systems is ISO 9001:2000 certified.*

---

---

## 14-Pin Flash-Based, 8-Bit CMOS Microcontrollers with nanoWatt Technology

---

---

### High-Performance RISC CPU:

- Only 35 Instructions to Learn:
  - All single-cycle instructions except branches
- Operating Speed:
  - DC – 20 MHz oscillator/clock input
  - DC – 200 ns instruction cycle
- Interrupt Capability
- 8-level Deep Hardware Stack
- Direct, Indirect and Relative Addressing modes

### Special Microcontroller Features:

- Precision Internal Oscillator:
  - Factory calibrated to  $\pm 1\%$
  - Software selectable frequency range of 8 MHz to 125 kHz
  - Software tunable
  - Two-Speed Start-Up mode
  - Crystal fail detect for critical applications
  - Clock mode switching during operation for power savings
- Power-Saving Sleep mode
- Wide Operating Voltage Range (2.0V-5.5V)
- Industrial and Extended Temperature Range
- Power-on Reset (POR)
- Power-up Timer (PWRT) and Oscillator Start-up Timer (OST)
- Brown-out Reset (BOR) with Software Control Option
- Enhanced Low-Current Watchdog Timer (WDT) with on-chip oscillator (software selectable nominal 268 seconds with full prescaler) with software enable
- Multiplexed Master Clear with Weak Pull-up or Input Only Pin
- Programmable Code Protection
- High-Endurance Flash/EEPROM Cell:
  - 100,000 write Flash endurance
  - 1,000,000 write EEPROM endurance
  - Flash/Data EEPROM retention: > 40 years

### Low-Power Features:

- Standby Current:
  - 50 nA @ 2.0V, typical
- Operating Current:
  - 11  $\mu$ A @ 32 kHz, 2.0V, typical
  - 220  $\mu$ A @ 4 MHz, 2.0V, typical
- Watchdog Timer Current:
  - 1  $\mu$ A @ 2.0V, typical

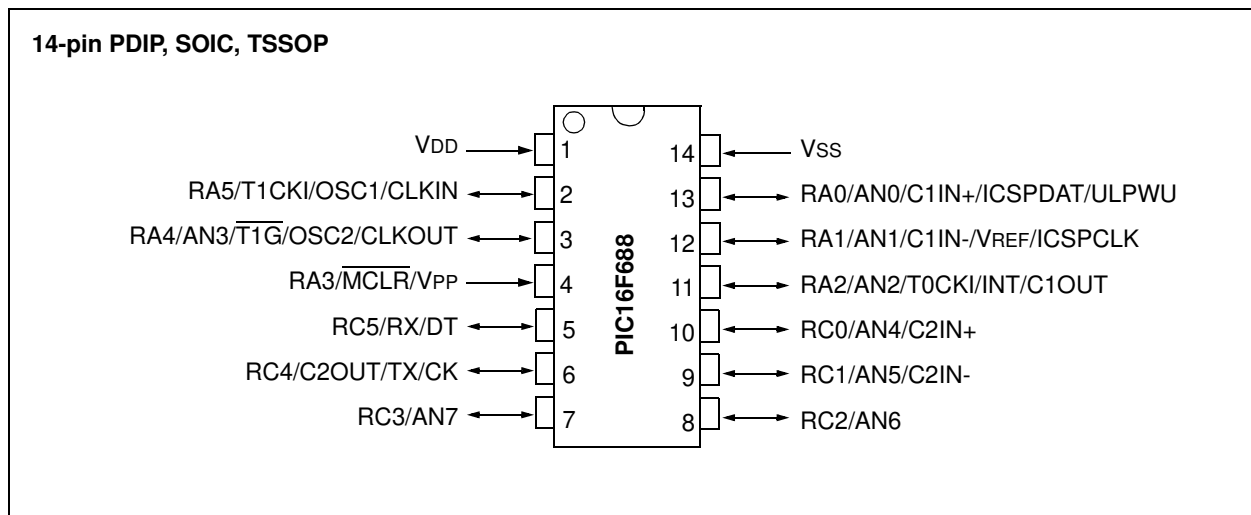
### Peripheral Features:

- 12 I/O Pins with Individual Direction Control:
  - High-current source/sink for direct LED drive
  - Interrupt-on-change pin
  - Individually programmable weak pull-ups
  - Ultra Low-Power Wake-up
- Analog Comparator module with:
  - Two analog comparators
  - Programmable On-chip Voltage Reference (CVREF) module (% of VDD)
  - Comparator inputs and outputs externally accessible
- A/D Converter:
  - 10-bit resolution and 8 channels
- Timer0: 8-bit Timer/Counter with 8-bit Programmable Prescaler
- Enhanced Timer1:
  - 16-bit timer/counter with prescaler
  - External Timer1 Gate (count enable)
  - Option to use OSC1 and OSC2 in LP mode as Timer1 oscillator if INTOSC mode selected
- Enhanced USART Module:
  - Supports RS-485, RS-232, LIN 2.0/2.1 and J2602
  - Auto-Baud Detect
  - Auto-wake-up on Start bit
- In-Circuit Serial Programming™ (ICSP™) via two pins

# PIC16F688

Device	Program Memory	Data Memory		I/O	10-bit A/D (ch)	Comparators	Timers 8/16-bit
	Flash (words)	SRAM (bytes)	EEPROM (bytes)				
PIC16F688	4096	256	256	12	8	2	1/1

## Pin Diagram (PDIP, SOIC, TSSOP)

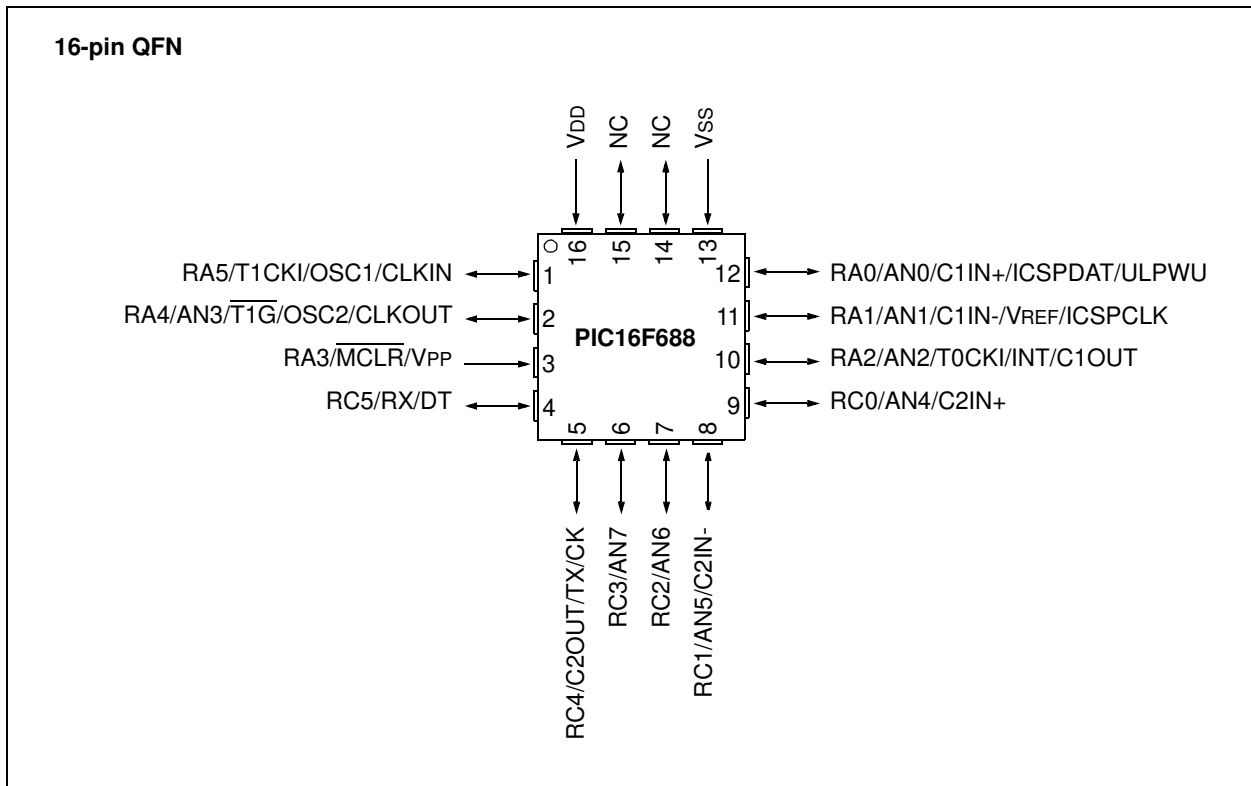


**TABLE 1: PIC16F688 14-PIN SUMMARY (PDIP, SOIC, TSSOP)**

I/O	Pin	Analog	Comparators	Timers	EUSART	Interrupt	Pull-up	Basic
RA0	13	AN0/ULPWU	C1IN+	—	—	IOC	Y	ICSPDAT
RA1	12	AN1	C1IN-	—	—	IOC	Y	VREF/ICSPCLK
RA2	11	AN2	C1OUT	T0CKI	—	IOC/INT	Y	—
RA3	4	—	—	—	—	IOC	Y <sup>(1)</sup>	MCLR/VPP
RA4	3	AN3	—	T1G	—	IOC	Y	OSC2/CLKOUT
RA5	2	—	—	T1CKI	—	IOC	Y	OSC1/CLKIN
RC0	10	AN4	C2IN+	—	—	—	—	—
RC1	9	AN5	C2IN-	—	—	—	—	—
RC2	8	AN6	—	—	—	—	—	—
RC3	7	AN7	—	—	—	—	—	—
RC4	6	—	C2OUT	—	TX/CK	—	—	—
RC5	5	—	—	—	RX/DT	—	—	—
—	1	—	—	—	—	—	—	VDD
—	14	—	—	—	—	—	—	VSS

**Note 1:** Pull-up activated only with external MCLR configuration.

## Pin Diagram (QFN)



**TABLE 2: PIC16F688 16-PIN SUMMARY (QFN)**

I/O	Pin	Analog	Comparators	Timers	EUSART	Interrupt	Pull-up	Basic
RA0	12	AN0/ULPWU	C1IN+	—	—	IOC	Y	ICSPDAT
RA1	11	AN1	C1IN-	—	—	IOC	Y	VREF/ICSPCLK
RA2	10	AN2	C1OUT	T0CKI	—	IOC/INT	Y	—
RA3	3	—	—	—	—	IOC	Y <sup>(1)</sup>	MCLR/VPP
RA4	2	AN3	—	T1G	—	IOC	Y	OSC2/CLKOUT
RA5	1	—	—	T1CKI	—	IOC	Y	OSC1/CLKIN
RC0	9	AN4	C2IN+	—	—	—	—	—
RC1	8	AN5	C2IN-	—	—	—	—	—
RC2	7	AN6	—	—	—	—	—	—
RC3	6	AN7	—	—	—	—	—	—
RC4	5	—	C2OUT	—	TX/CK	—	—	—
RC5	4	—	—	—	RX/DT	—	—	—
—	16	—	—	—	—	—	—	VDD
—	13	—	—	—	—	—	—	VSS
—	14	—	—	—	—	—	—	NC
—	15	—	—	—	—	—	—	NC

**Note 1:** Pull-up activated only with external MCLR configuration.

# PIC16F688

## Table of Contents

1.0	Device Overview .....	5
2.0	Memory Organization .....	7
3.0	Clock Sources .....	21
4.0	I/O Ports .....	33
5.0	Timer0 Module .....	45
6.0	Timer1 Module with Gate Control.....	49
7.0	Comparator Module.....	55
8.0	Analog-to-Digital Converter (A/D) Module.....	65
9.0	Data EEPROM and Flash Program Memory Control .....	77
10.0	Enhanced Universal Asynchronous Receiver Transmitter (EUSART) .....	83
11.0	Special Features of the CPU.....	109
12.0	Instruction Set Summary .....	129
13.0	Development Support .....	139
14.0	Electrical Specifications.....	143
15.0	DC and AC Characteristics Graphs and Tables.....	163
16.0	Packaging Information.....	185
	Appendix A: Data Sheet Revision History.....	193
	Appendix B: Migrating from other PIC® Devices.....	193
	Index .....	195
	On-line Support .....	199
	Systems Information and Upgrade Hot Line .....	199
	Reader Response .....	200
	Product Identification System.....	201

## TO OUR VALUED CUSTOMERS

It is our intention to provide our valued customers with the best documentation possible to ensure successful use of your Microchip products. To this end, we will continue to improve our publications to better suit your needs. Our publications will be refined and enhanced as new volumes and updates are introduced.

If you have any questions or comments regarding this publication, please contact the Marketing Communications Department via E-mail at [docerrors@microchip.com](mailto:docerrors@microchip.com) or fax the **Reader Response Form** in the back of this data sheet to (480) 792-4150. We welcome your feedback.

### Most Current Data Sheet

To obtain the most up-to-date version of this data sheet, please register at our Worldwide Web site at:

<http://www.microchip.com>

You can determine the version of a data sheet by examining its literature number found on the bottom outside corner of any page. The last character of the literature number is the version number, (e.g., DS30000A is version A of document DS30000).

### Errata

An errata sheet, describing minor operational differences from the data sheet and recommended workarounds, may exist for current devices. As device/documentation issues become known to us, we will publish an errata sheet. The errata will specify the revision of silicon and revision of document to which it applies.

To determine if an errata sheet exists for a particular device, please check with one of the following:

- Microchip's Worldwide Web site; <http://www.microchip.com>
- Your local Microchip sales office (see last page)

When contacting a sales office, please specify which device, revision of silicon and data sheet (include literature number) you are using.

### Customer Notification System

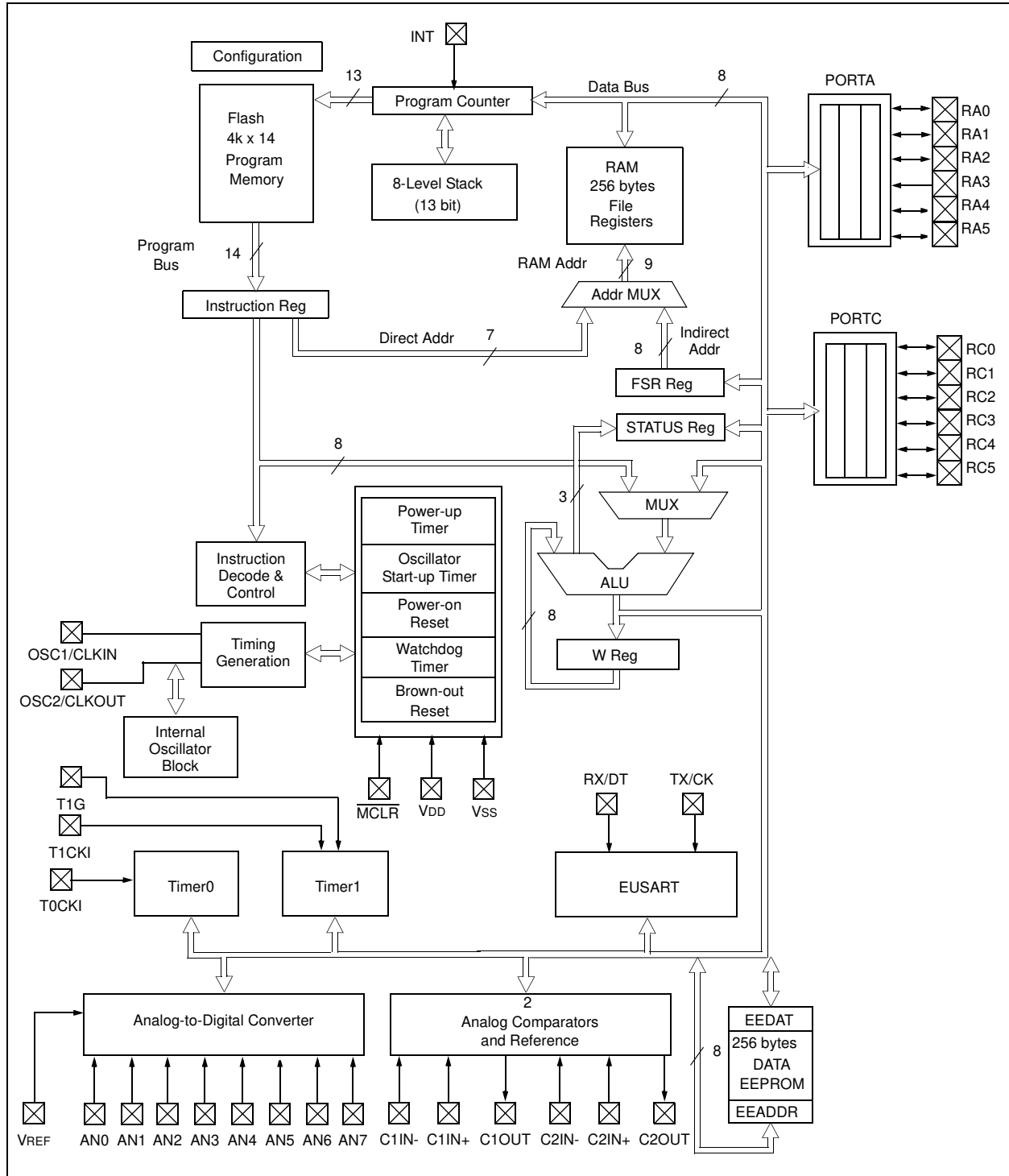
Register on our web site at [www.microchip.com](http://www.microchip.com) to receive the most current information on all of our products.



## 1.0 DEVICE OVERVIEW

The PIC16F688 is covered by this data sheet. It is available in 14-pin PDIP, SOIC, TSSOP and QFN packages. Figure 1-1 shows a block diagram of the PIC16F688 device. Table 1-1 shows the pinout description.

**FIGURE 1-1: PIC16F688 BLOCK DIAGRAM**





# PIC16F688

**TABLE 1-1: PIC16F688 PINOUT DESCRIPTION**

Name	Function	Input Type	Output Type	Description
RA0/AN0/C1IN+/ICSPDAT/ULPWU	RA0	TTL	CMOS	PORTA I/O w/prog pull-up and interrupt-on-change
	AN0	AN	—	A/D Channel 0 input
	C1IN+	AN	—	Comparator 1 input
	ICSPDAT	TTL	CMOS	Serial Programming Data I/O
	ULPWU	AN	—	Ultra Low-Power Wake-up input
RA1/AN1/C1IN-/VREF/ICSPCLK	RA1	TTL	CMOS	PORTA I/O w/prog pull-up and interrupt-on-change
	AN1	AN	—	A/D Channel 1 input
	C1IN-	AN	—	Comparator 1 input
	VREF	AN	—	External Voltage Reference for A/D
	ICSPCLK	ST	—	Serial Programming Clock
RA2/AN2/T0CKI/INT/C1OUT	RA2	ST	CMOS	PORTA I/O w/prog pull-up and interrupt-on-change
	AN2	AN	—	A/D Channel 2 input
	T0CKI	ST	—	Timer0 clock input
	INT	ST	—	External Interrupt
	C1OUT	—	CMOS	Comparator 1 output
RA3/MCLR/VPP	RA3	TTL	—	PORTA input with interrupt-on-change
	MCLR	ST	—	Master Clear w/internal pull-up
	VPP	HV	—	Programming voltage
RA4/AN3/T1G/OSC2/CLKOUT	RA4	TTL	CMOS	PORTA I/O w/prog pull-up and interrupt-on-change
	AN3	AN	—	A/D Channel 3 input
	T1G	ST	—	Timer1 gate
	OSC2	—	XTAL	Crystal/Resonator
	CLKOUT	—	CMOS	Fosc/4 output
RA5/T1CKI/OSC1/CLKIN	RA5	TTL	CMOS	PORTA I/O w/prog pull-up and interrupt-on-change
	T1CKI	ST	—	Timer1 clock
	OSC1	XTAL	—	Crystal/Resonator
	CLKIN	ST	—	External clock input/RC oscillator connection
RC0/AN4/C2IN+	RC0	TTL	CMOS	PORTC I/O
	AN4	AN	—	A/D Channel 4 input
	C2IN+	AN	—	Comparator 2 input
RC1/AN5/C2IN-	RC1	TTL	CMOS	PORTC I/O
	AN5	AN	—	A/D Channel 5 input
	C2IN-	AN	—	Comparator 2 input
RC2/AN6	RC2	TTL	CMOS	PORTC I/O
	AN6	AN	—	A/D Channel 6 input
RC3/AN7	RC3	TTL	CMOS	PORTC I/O
	AN7	AN	—	A/D Channel 7 input
RC4/C2OUT/TX/CK	RC4	TTL	CMOS	PORTC I/O
	C2OUT	—	CMOS	Comparator 2 output
	TX	—	CMOS	USART asynchronous output
	CK	ST	CMOS	USART asynchronous clock
RC5/RX/DT	RC5	TTL	CMOS	Port C I/O
	RX	ST	CMOS	USART asynchronous input
	DT	ST	CMOS	USART asynchronous data
Vss	Vss	Power	—	Ground reference
VDD	VDD	Power	—	Positive supply

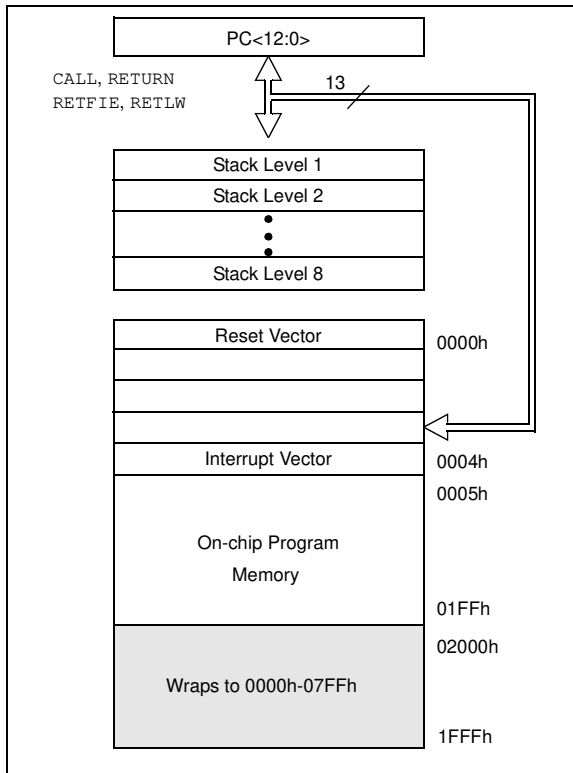
**Legend:** AN = Analog input or output      CMOS = CMOS compatible input or output      OC = Open collector output  
TTL = TTL compatible input      ST = Schmitt Trigger input with CMOS levels  
HV = High Voltage      XTAL = Crystal

## 2.0 MEMORY ORGANIZATION

### 2.1 Program Memory Organization

The PIC16F688 has a 13-bit program counter capable of addressing a 4K x 14 program memory space. Only the first 4K x 14 (0000h-01FFF) for the PIC16F688 is physically implemented. Accessing a location above these boundaries will cause a wrap-around within the first 4K x 14 space. The Reset vector is at 0000h and the interrupt vector is at 0004h (see Figure 2-1).

**FIGURE 2-1: PROGRAM MEMORY MAP AND STACK FOR THE PIC16F688**



### 2.2 Data Memory Organization

The data memory is partitioned into multiple banks, which contain the General Purpose Registers (GPR) and the Special Function Registers (SFR). Bits RP0 and RP1 are bank select bits.

RP1	RP0	
0	0	→ Bank 0 is selected
0	1	→ Bank 1 is selected
1	0	→ Bank 2 is selected
1	1	→ Bank 3 is selected

Each bank extends up to 7Fh (128 bytes). The lower locations of each bank are reserved for the Special Function Registers. Above the Special Function Registers are the General Purpose Registers, implemented as static RAM. All implemented banks contain Special Function Registers. Some frequently used Special Function Registers from one bank are mirrored in another bank for code reduction and quicker access.

#### 2.2.1 GENERAL PURPOSE REGISTER FILE

The register file is organized as 256 x 8 in the PIC16F688. Each register is accessed, either directly or indirectly, through the File Select Register (FSR) (see **Section 2.4 "Indirect Addressing, INDF and FSR Registers"**).

#### 2.2.2 SPECIAL FUNCTION REGISTERS

The Special Function Registers are registers used by the CPU and peripheral functions for controlling the desired operation of the device (see Tables 2-1, 2-2, 2-3 and 2-4). These registers are static RAM.

The special registers can be classified into two sets: core and peripheral. The Special Function Registers associated with the "core" are described in this section. Those related to the operation of the peripheral features are described in the section of that peripheral feature.

# PIC16F688

**FIGURE 2-2: PIC16F688 SPECIAL FUNCTION REGISTERS**

File Address	File Address	File Address	File Address
Indirect addr. <sup>(1)</sup> 00h	Indirect addr. <sup>(1)</sup> 80h	Indirect addr. <sup>(1)</sup> 100h	Indirect addr. <sup>(1)</sup> 180h
TMR0 01h	OPTION_REG 81h	TMR0 101h	OPTION_REG 181h
PCL 02h	PCL 82h	PCL 102h	PCL 182h
STATUS 03h	STATUS 83h	STATUS 103h	STATUS 183h
FSR 04h	FSR 84h	FSR 104h	FSR 184h
PORTA 05h	TRISA 85h	PORTA 105h	TRISA 185h
06h	86h	106h	186h
PORTC 07h	TRISC 87h	PORTC 107h	TRISC 187h
08h	88h	108h	188h
09h	89h	109h	189h
PCLATH 0Ah	PCLATH 8Ah	PCLATH 10Ah	PCLATH 18Ah
INTCON 0Bh	INTCON 8Bh	INTCON 10Bh	INTCON 18Bh
PIR1 0Ch	PIE1 8Ch	10Ch	18Ch
0Dh	8Dh	10Dh	18Dh
TMR1L 0Eh	PCON 8Eh	10Eh	18Eh
TMR1H 0Fh	OSCCON 8Fh	10Fh	18Fh
T1CON 10h	OSCTUNE 90h	110h	190h
BAUDCTL 11h	ANSEL 91h	111h	191h
SPBRGH 12h	92h	112h	192h
SPBRG 13h	93h	113h	193h
RCREG 14h	94h	114h	194h
TXREG 15h	WPUA 95h	115h	195h
TXSTA 16h	IOCA 96h	116h	196h
RCSTA 17h	EEDATH 97h	117h	197h
WDTCON 18h	EEADRH 98h	118h	198h
CMCON0 19h	VRCON 99h	119h	199h
CMCON1 1Ah	EEDAT 9Ah	11Ah	19Ah
1Bh	EEADR 9Bh	11Bh	19Bh
1Ch	EECON1 9Ch	11Ch	19Ch
1Dh	EECON2 <sup>(1)</sup> 9Dh	11Dh	19Dh
ADRESH 1Eh	ADRESL 9Eh	11Eh	19Eh
ADCON0 1Fh	ADCON1 9Fh	11Fh	19Fh
20h	A0h	120h	1A0h
General Purpose Register	General Purpose Register	General Purpose Register	
96 Bytes	80 Bytes	80 Bytes	
7Fh	EFh	16Fh	1EFh
Bank 0	accesses Bank 0	accesses Bank 0	accesses Bank 0
	F0h	170h	1F0h
	FFh	17Fh	1FFh
	Bank 1	Bank 2	Bank 3

Unimplemented data memory locations, read as '0'.  
**Note 1:** Not a physical register.

**TABLE 2-1: PIC16F688 SPECIAL REGISTERS SUMMARY BANK 0**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR/BOR	Page
Bank 0											
00h	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	20, 117
01h	TMR0	Timer0 Module's register								xxxx xxxx	45, 117
02h	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	19, 117
03h	STATUS	IRP	RP1	RP0	$\overline{TO}$	$\overline{PD}$	Z	DC	C	0001 1xxx	13, 117
04h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	20, 117
05h	PORTA	—	—	RA5	RA4	RA3	RA2	RA1	RA0	--x0 x000	33, 117
06h	—	Unimplemented								—	—
07h	PORTC	—	—	RC5	RC4	RC3	RC2	RC1	RC0	--xx 0000	42, 117
08h	—	Unimplemented								—	—
09h	—	Unimplemented								—	—
0Ah	PCLATH	—	—	—	Write Buffer for upper 5 bits of Program Counter				---	0 0000	19, 117
0Bh	INTCON	GIE	PEIE	TOIE	INTE	RAIE	TOIF	INTF	RAIF <sup>(2)</sup>	0000 000x	15, 117
0Ch	PIR1	EEIF	ADIF	RCIF	C2IF	C1IF	OSFIF	TXIF	TMR1IF	0000 0000	17, 117
0Dh	—	Unimplemented								—	—
0Eh	TMR1L	Holding Register for the Least Significant Byte of the 16-bit TMR1								xxxx xxxx	48, 117
0Fh	TMR1H	Holding Register for the Most Significant Byte of the 16-bit TMR1								xxxx xxxx	48, 117
10h	T1CON	T1GINV	TMR1GE	T1CKPS1	T1CKPS0	T1OSCEN	$\overline{T1SYNC}$	TMR1CS	TMR1ON	0000 0000	51, 117
11h	BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	94, 117
12h	SPBRGH	USART Baud Rate High Generator								0000 0000	95, 117
13h	SPBRG	USART Baud Rate Generator								0000 0000	95, 117
14h	RCREG	USART Receive Register								0000 0000	87, 117
15h	TXREG	USART Transmit Register								0000 0000	87, 117
16h	TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	0000 0010	92, 117
17h	RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	93, 117
18h	WDTCON	—	—	—	WDTPS3	WDTPS2	WDTPS1	WDTPS0	SWDTEN	---0 1000	124, 117
19h	CMCON0	C2OUT	C1OUT	C2INV	C1INV	CIS	CM2	CM1	CM0	0000 0000	61, 117
1Ah	CMCON1	—	—	—	—	—	—	T1GSS	C2SYNC	---- --10	62, 117
1Bh	—	Unimplemented								—	—
1Ch	—	Unimplemented								—	—
1Dh	—	Unimplemented								—	—
1Eh	ADRESH	Most Significant 8 bits of the left shifted A/D result or 2 bits of right shifted result								xxxx xxxx	72, 117
1Fh	ADCON0	ADFM	VCFG	—	CHS2	CHS1	CHS0	GO/DONE	ADON	00-0 0000	71, 117

**Legend:** — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

**Note 1:** Other (non Power-up) Resets include MCLR Reset and Watchdog Timer Reset during normal operation.

**2:** MCLR and WDT Reset does not affect the previous value data latch. The RAIF bit will be cleared upon Reset but will set again if the mismatched exists.

# PIC16F688

**TABLE 2-2: PIC16F688 SPECIAL FUNCTION REGISTERS SUMMARY BANK 1**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR/BOR	Page
Bank 1											
80h	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	20, 117
81h	OPTION_REG	RAPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	14, 117
82h	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	19, 117
83h	STATUS	IRP	RP1	RP0	TO	PD	Z	DC	C	0001 1xxx	13, 117
84h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	20, 117
85h	TRISA	—	—	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	--11 1111	33, 117
86h	—	Unimplemented								—	—
87h	TRISC	—	—	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	--11 1111	42, 117
88h	—	Unimplemented								—	—
89h	—	Unimplemented								—	—
8Ah	PCLATH	—	—	—	Write Buffer for upper 5 bits of Program Counter					---0 0000	19, 117
8Bh	INTCON	GIE	PEIE	T0IE	INTE	RAIE	T0IF	INTF	RAIF <sup>(3)</sup>	0000 000x	15, 117
8Ch	PIE1	EEIE	ADIE	RCIE	C2IE	C1IE	OSFIE	TXIE	TMR1IE	0000 0000	16, 117
8Dh	—	Unimplemented								—	—
8Eh	PCON	—	—	ULPWUE	SBOREN	—	—	POR	BOR	--01 --q <sub>q</sub>	18, 117
8Fh	OSCCON	—	IRCF2	IRCF1	IRCF0	OSTS	HTS	LTS	SCS	-110 x000	22, 118
90h	OSCTUNE	—	—	—	TUN4	TUN3	TUN2	TUN1	TUN0	---0 0000	26, 118
91h	ANSEL	ANS7	ANS6	ANS5	ANS4	ANS3	ANS2	ANS1	ANS0	1111 1111	34, 118
92h	—	Unimplemented								—	—
93h	—	Unimplemented								—	—
94h	—	Unimplemented								—	—
95h	WPUA <sup>(2)</sup>	—	—	WPUA5	WPUA4	—	WPUA2	WPUA1	WPUA0	--11 -111	35, 118
96h	IOCA	—	—	IOCA5	IOCA4	IOCA3	IOCA2	IOCA1	IOCA0	--00 0000	35, 118
97h	EEDATH	—	—	EEDATH5	EEDATH4	EEDATH3	EEDATH2	EEDATH1	EEDATH0	--00 0000	78, 118
98h	EEADRH	—	—	—	—	EEADRH3	EEADRH2	EEADRH1	EEADRH0	---- 0000	78, 118
99h	VRCON	VREN	—	VRR	—	VR3	VR2	VR1	VR0	0-0- 0000	63, 118
9Ah	EEDAT	EEDAT7	EEDAT6	EEDAT5	EEDAT4	EEDAT3	EEDAT2	EEDAT1	EEDAT0	0000 0000	78, 118
9Bh	EEADR	EEADR7	EEADR6	EEADR5	EEADR4	EEADR3	EEADR2	EEADR1	EEADR0	0000 0000	78, 118
9Ch	EECON1	EPPGD	—	—	—	WRERR	WREN	WR	RD	x--- x000	79, 118
9Dh	EECON2	EEPROM Control 2 Register (not a physical register)								---- ----	77, 118
9Eh	ADRESL	Least Significant 2 bits of the left shifted result or 8 bits of the right shifted result								xxxx xxxx	72, 118
9Fh	ADCON1	—	ADCS2	ADCS1	ADCS0	—	—	—	—	-000 ----	71, 118

**Legend:** — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

**Note 1:** Other (non Power-up) Resets include MCLR Reset and Watchdog Timer Reset during normal operation.

**Note 2:** RA3 pull-up is enabled when pin is configured as MCLR in the Configuration Word register.

**Note 3:** MCLR and WDT Reset does not affect the previous value data latch. The RAIF bit will be cleared upon Reset but will set again if the mismatched exists.

**TABLE 2-3: PIC16F688 SPECIAL REGISTERS SUMMARY BANK 2**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR/BOR	Page
Bank 2											
100h	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	20, 117
101h	TMR0	Timer0 Module's register								xxxx xxxx	45, 117
102h	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	19, 117
103h	STATUS	IRP	RP1	RP0	$\overline{TO}$	$\overline{PD}$	Z	DC	C	0001 1xxx	13, 117
104h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	20, 117
105h	PORTA	—	—	RA5	RA4	RA3	RA2	RA1	RA0	--x0 x000	33, 117
106h	—	Unimplemented								—	—
107h	PORTC	—	—	RC5	RC4	RC3	RC2	RC1	RC0	--xx 0000	42, 117
108h	—	Unimplemented								—	—
109h	—	Unimplemented								—	—
10Ah	PCLATH	—	—	—	Write Buffer for upper 5 bits of Program Counter				---0 0000	19, 117	
10Bh	INTCON	GIE	PEIE	TOIE	INTE	RAIE	TOIF	INTF	RAIF <sup>(2)</sup>	0000 000x	15, 117
10Ch	—	Unimplemented								—	—
10Dh	—	Unimplemented								—	—
10Eh	—	Unimplemented								—	—
10Fh	—	Unimplemented								—	—
110h	—	Unimplemented								—	—
111h	—	Unimplemented								—	—
112h	—	Unimplemented								—	—
113h	—	Unimplemented								—	—
114h	—	Unimplemented								—	—
115h	—	Unimplemented								—	—
116h	—	Unimplemented								—	—
117h	—	Unimplemented								—	—
118h	—	Unimplemented								—	—
119h	—	Unimplemented								—	—
11Ah	—	Unimplemented								—	—
11Bh	—	Unimplemented								—	—
11Ch	—	Unimplemented								—	—
11Dh	—	Unimplemented								—	—
11Eh	—	Unimplemented								—	—
11Fh	—	Unimplemented								—	—

**Legend:** — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

**Note 1:** Other (non Power-up) Resets include MCLR Reset and Watchdog Timer Reset during normal operation.

**2:** MCLR and WDT Reset does not affect the previous value data latch. The RAIF bit will be cleared upon Reset but will set again if the mismatched exists.

# PIC16F688

**TABLE 2-4: PIC16F688 SPECIAL FUNCTION REGISTERS SUMMARY BANK 3**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR/BOR	Page
Bank 3											
180h	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	20, 117
181h	OPTION_REG	RAPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	14, 117
182h	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	19, 117
183h	STATUS	IRP	RP1	RP0	$\overline{TO}$	$\overline{PD}$	Z	DC	C	0001 1xxx	13, 117
184h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	20, 117
185h	TRISA	—	—	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	--11 1111	33, 117
186h	—	Unimplemented								—	—
187h	TRISC	—	—	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	--11 1111	42, 117
188h	—	Unimplemented								—	—
189h	—	Unimplemented								—	—
18Ah	PCLATH	—	—	—	Write Buffer for upper 5 bits of Program Counter				---0 0000	19, 117	
18Bh	INTCON	GIE	PEIE	T0IE	INTE	RAIE	T0IF	INTF	RAIF <sup>(2)</sup>	0000 000x	15, 117
18Ch	—	Unimplemented								—	—
18Dh	—	Unimplemented								—	—
190h	—	Unimplemented								—	—
191h	—	Unimplemented								—	—
192h	—	Unimplemented								—	—
193h	—	Unimplemented								—	—
194h	—	Unimplemented								—	—
195h	—	Unimplemented								—	—
196h	—	Unimplemented								—	—
19Ah	—	Unimplemented								—	—
19Bh	—	Unimplemented								—	—
199h	—	Unimplemented								—	—
19Ah	—	Unimplemented								—	—
19Bh	—	Unimplemented								—	—
19Ch	—	Unimplemented								—	—
19Dh	—	Unimplemented								—	—
19Eh	—	Unimplemented								—	—
19Fh	—	Unimplemented								—	—

- Legend:** — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented
- Note 1:** Other (non Power-up) Resets include  $\overline{MCLR}$  Reset and Watchdog Timer Reset during normal operation.
- Note 2:**  $\overline{MCLR}$  and WDT Reset does not affect the previous value data latch. The RAIF bit will be cleared upon Reset but will set again if the mismatched exists.



## 2.2.2.1 STATUS Register

The STATUS register, shown in Register 2-1, contains:

- the arithmetic status of the ALU
- the Reset status
- the bank select bits for data memory (SRAM)

The STATUS register can be the destination for any instruction, like any other register. If the STATUS register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. These bits are set or cleared according to the device logic. Furthermore, the TO and PD bits are not writable. Therefore, the result of an instruction with the STATUS register as destination may be different than intended.

For example, CLRF STATUS will clear the upper three bits and set the Z bit. This leaves the STATUS register as '000u u1uu' (where u = unchanged).

It is recommended, therefore, that only BCF, BSF, SWAPF and MOVWF instructions are used to alter the STATUS register, because these instructions do not affect any Status bits. For other instructions not affecting any Status bits (see Section 12.0 "Instruction Set Summary").

**Note 1:** The C and DC bits operate as a Borrow and Digit Borrow out bit, respectively, in subtraction.

### REGISTER 2-1: STATUS: STATUS REGISTER

R/W-0	R/W-0	R/W-0	R-1	R-1	R/W-x	R/W-x	R/W-x
IRP	RP1	RP0	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC <sup>(1)</sup>	C <sup>(1)</sup>
bit 7							bit 0

#### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 7                      **IRP:** Register Bank Select bit (used for indirect addressing)  
                             1 = Bank 2, 3 (100h-1FFh)  
                             0 = Bank 0, 1 (00h-FFh)
- bit 6-5                      **RP<1:0>:** Register Bank Select bits (used for direct addressing)  
                             00 = Bank 0 (00h-7Fh)  
                             01 = Bank 1 (80h-FFh)  
                             10 = Bank 2 (100h-17Fh)  
                             11 = Bank 3 (180h-1FFh)
- bit 4                       **$\overline{\text{TO}}$ :** Time-out bit  
                             1 = After power-up, CLRWDI instruction or SLEEP instruction  
                             0 = A WDT time-out occurred
- bit 3                       **$\overline{\text{PD}}$ :** Power-down bit  
                             1 = After power-up or by the CLRWDI instruction  
                             0 = By execution of the SLEEP instruction
- bit 2                      **Z:** Zero bit  
                             1 = The result of an arithmetic or logic operation is zero  
                             0 = The result of an arithmetic or logic operation is not zero
- bit 1                      **DC:** Digit Carry/Borrow bit (ADDWF, ADDLW, SUBLW, SUBWF instructions)<sup>(1)</sup>  
                             1 = A carry-out from the 4th low-order bit of the result occurred  
                             0 = No carry-out from the 4th low-order bit of the result
- bit 0                      **C:** Carry/Borrow bit<sup>(1)</sup> (ADDWF, ADDLW, SUBLW, SUBWF instructions)<sup>(1)</sup>  
                             1 = A carry-out from the Most Significant bit of the result occurred  
                             0 = No carry-out from the Most Significant bit of the result occurred

**Note 1:** For Borrow, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand. For rotate (RRF, RLF) instructions, this bit is loaded with either the high-order or low-order bit of the source register.

# PIC16F688

## 2.2.2.2 OPTION Register

The OPTION register is a readable and writable register, which contains various control bits to configure:

- Timer0/WDT prescaler
- External RA2/INT interrupt
- Timer0
- Weak pull-ups on PORTA

**Note:** To achieve a 1:1 prescaler assignment for Timer0, assign the prescaler to the WDT by setting PSA bit of the OPTION register to '1'. See **Section 5.1.3 “Software Programmable Prescaler”**.

### REGISTER 2-2: OPTION\_REG: OPTION REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
$\overline{\text{RAPU}}$	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- bit 7       **$\overline{\text{RAPU}}$** : PORTA Pull-up Enable bit  
 1 = PORTA pull-ups are disabled  
 0 = PORTA pull-ups are enabled by individual PORT latch values
- bit 6      **INTEDG**: Interrupt Edge Select bit  
 1 = Interrupt on rising edge of RA2/INT pin  
 0 = Interrupt on falling edge of RA2/INT pin
- bit 5      **T0CS**: Timer0 Clock Source Select bit  
 1 = Transition on RA2/T0CKI pin  
 0 = Internal instruction cycle clock ( $F_{\text{OSC}}/4$ )
- bit 4      **T0SE**: Timer0 Source Edge Select bit  
 1 = Increment on high-to-low transition on RA2/T0CKI pin  
 0 = Increment on low-to-high transition on RA2/T0CKI pin
- bit 3      **PSA**: Prescaler Assignment bit  
 1 = Prescaler is assigned to the WDT  
 0 = Prescaler is assigned to the Timer0 module
- bit 2-0    **PS<2:0>**: Prescaler Rate Select bits

Bit Value	Timer0 Rate	WDT Rate
000	1 : 2	1 : 1
001	1 : 4	1 : 2
010	1 : 8	1 : 4
011	1 : 16	1 : 8
100	1 : 32	1 : 16
101	1 : 64	1 : 32
110	1 : 128	1 : 64
111	1 : 256	1 : 128

## 2.2.2.3 INTCON Register

The INTCON register is a readable and writable register, which contains the various enable and flag bits for TMR0 register overflow, PORTA change and external RA2/INT pin interrupts.

**Note:** Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the global enable bit, GIE of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

### REGISTER 2-3: INTCON: INTERRUPT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-x
GIE	PEIE	TOIE	INTE	RAIE	T0IF	INTF	RAIF
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 7      **GIE:** Global Interrupt Enable bit  
1 = Enables all unmasked interrupts  
0 = Disables all interrupts
- bit 6      **PEIE:** Peripheral Interrupt Enable bit  
1 = Enables all unmasked peripheral interrupts  
0 = Disables all peripheral interrupts
- bit 5      **TOIE:** Timer0 Overflow Interrupt Enable bit  
1 = Enables the Timer0 interrupt  
0 = Disables the Timer0 interrupt
- bit 4      **INTE:** RA2/INT External Interrupt Enable bit  
1 = Enables the RA2/INT external interrupt  
0 = Disables the RA2/INT external interrupt
- bit 3      **RAIE:** PORTA Change Interrupt Enable bit<sup>(1)</sup>  
1 = Enables the PORTA change interrupt  
0 = Disables the PORTA change interrupt
- bit 2      **T0IF:** Timer0 Overflow Interrupt Flag bit<sup>(2)</sup>  
1 = Timer0 register has overflowed (must be cleared in software)  
0 = Timer0 register did not overflow
- bit 1      **INTF:** RA2/INT External Interrupt Flag bit  
1 = The RA2/INT external interrupt occurred (must be cleared in software)  
0 = The RA2/INT external interrupt did not occur
- bit 0      **RAIF:** PORTA Change Interrupt Flag bit  
1 = When at least one of the PORTA <5:0> pins changed state (must be cleared in software)  
0 = None of the PORTA <5:0> pins have changed state

- Note 1:** IOCA register must also be enabled.
- 2:** T0IF bit is set when TMR0 rolls over. TMR0 is unchanged on Reset and should be initialized before clearing T0IF bit.

# PIC16F688

## 2.2.2.4 PIE1 Register

The PIE1 register contains the interrupt enable bits, as shown in Register 2-4.

**Note:** Bit PEIE of the INTCON register must be set to enable any peripheral interrupt.

### REGISTER 2-4: PIE1: PERIPHERAL INTERRUPT ENABLE REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
EEIE	ADIE	RCIE	C2IE	C1IE	OSFIE	TXIE	TMR1IE
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 7      **EEIE:** EE Write Complete Interrupt Enable bit  
1 = Enables the EE write complete interrupt  
0 = Disables the EE write complete interrupt
- bit 6      **ADIE:** A/D Converter (ADC) Interrupt Enable bit  
1 = Enables the ADC interrupt  
0 = Disables the ADC interrupt
- bit 5      **RCIE:** EUSART Receive Interrupt Enable bit  
1 = Enables the EUSART receive interrupt  
0 = Disables the EUSART receive interrupt
- bit 4      **C2IE:** Comparator 2 Interrupt Enable bit  
1 = Enables the Comparator C2 interrupt  
0 = Disables the Comparator C2 interrupt
- bit 3      **C1IE:** Comparator 1 Interrupt Enable bit  
1 = Enables the Comparator C1 interrupt  
0 = Disables the Comparator C1 interrupt
- bit 2      **OSFIE:** Oscillator Fail Interrupt Enable bit  
1 = Enables the oscillator fail interrupt  
0 = Disables the oscillator fail interrupt
- bit 1      **TXIE:** EUSART Transmit Interrupt Enable bit  
1 = Enables the EUSART transmit interrupt  
0 = Disables the EUSART transmit interrupt
- bit 0      **TMR1IE:** Timer1 Overflow Interrupt Enable bit  
1 = Enables the Timer1 overflow interrupt  
0 = Disables the Timer1 overflow interrupt

## 2.2.2.5 PIR1 Register

The PIR1 register contains the interrupt flag bits, as shown in Register 2-5.

**Note:** Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the global enable bit, GIE bit of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

### REGISTER 2-5: PIR1: PERIPHERAL INTERRUPT REQUEST REGISTER 1

R/W-0	R/W-0	R-0	R/W-0	R/W-0	R/W-0	R-0	R/W-0
EEIF	ADIF	RCIF	C2IF	C1IF	OSFIF	TXIF	TMR1IF
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 7            **EEIF:** EEPROM Write Operation Interrupt Flag bit  
                  1 = The write operation completed (must be cleared in software)  
                  0 = The write operation has not completed or has not been started
- bit 6            **ADIF:** A/D Converter Interrupt Flag bit  
                  1 = A/D conversion complete (must be cleared in software)  
                  0 = A/D conversion has not completed or has not been started
- bit 5            **RCIF:** EUSART Receive Interrupt Flag bit  
                  1 = The EUSART receive buffer is full (cleared by reading RCREG)  
                  0 = The EUSART receive buffer is not full
- bit 4            **C2IF:** Comparator C2 Interrupt Flag bit  
                  1 = Comparator output (C2OUT bit) has changed (must be cleared in software)  
                  0 = Comparator output (C2OUT bit) has not changed
- bit 3            **C1IF:** Comparator C1 Interrupt Flag bit  
                  1 = Comparator output (C1OUT bit) has changed (must be cleared in software)  
                  0 = Comparator output (C1OUT bit) has not changed
- bit 2            **OSFIF:** Oscillator Fail Interrupt Flag bit  
                  1 = System oscillator failed, clock input has changed to INTOSC (must be cleared in software)  
                  0 = System clock operating
- bit 1            **TXIF:** EUSART Transmit Interrupt Flag bit  
                  1 = The EUSART transmit buffer is empty (cleared by writing to TXREG)  
                  0 = The EUSART transmit buffer is full
- bit 0            **TMR1IF:** Timer1 Overflow Interrupt Flag bit  
                  1 = The TMR1 register overflowed (must be cleared in software)  
                  0 = The TMR1 register did not overflow

# PIC16F688

## 2.2.2.6 PCON Register

The Power Control (PCON) register (see Register 2-6) contains flag bits to differentiate between a:

- Power-on Reset ( $\overline{\text{POR}}$ )
- Brown-out Reset ( $\overline{\text{BOR}}$ )
- Watchdog Timer Reset (WDT)
- External MCLR Reset

The PCON register also controls the Ultra Low-Power Wake-up and software enable of the  $\overline{\text{BOR}}$ .

### REGISTER 2-6: PCON: POWER CONTROL REGISTER

U-0	U-0	R/W-0	R/W-1	U-0	U-0	R/W-0	R/W-x
—	—	ULPWUE	SBOREN <sup>(1)</sup>	—	—	$\overline{\text{POR}}$	$\overline{\text{BOR}}$
bit 7							bit 0

#### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **ULPWUE:** Ultra Low-Power Wake-up Enable bit  
 1 = Ultra low-power wake-up enabled  
 0 = Ultra low-power wake-up disabled

bit 4 **SBOREN:** Software BOR Enable bit<sup>(1)</sup>  
 1 = BOR enabled  
 0 = BOR disabled

bit 3-2 **Unimplemented:** Read as '0'

bit 1  **$\overline{\text{POR}}$ :** Power-on Reset Status bit  
 1 = No Power-on Reset occurred  
 0 = A Power-on Reset occurred (must be set in software after a Power-on Reset occurs)

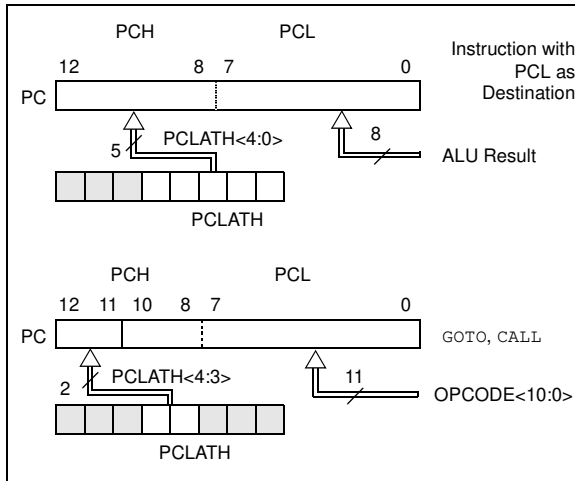
bit 0  **$\overline{\text{BOR}}$ :** Brown-out Reset Status bit  
 1 = No Brown-out Reset occurred  
 0 = A Brown-out Reset occurred (must be set in software after a Brown-out Reset occurs)

**Note 1:** BOREN<1:0> = 01 in the Configuration Word register for this bit to control the  $\overline{\text{BOR}}$ .

## 2.3 PCL and PCLATH

The Program Counter (PC) is 13 bits wide. The low byte comes from the PCL register, which is a readable and writable register. The high byte ( $PC<12:8>$ ) is not directly readable or writable and comes from PCLATH. On any Reset, the PC is cleared. Figure 2-3 shows the two situations for the loading of the PC. The upper example in Figure 2-3 shows how the PC is loaded on a write to PCL ( $PCLATH<4:0> \rightarrow PCH$ ). The lower example in Figure 2-3 shows how the PC is loaded during a CALL or GOTO instruction ( $PCLATH<4:3> \rightarrow PCH$ ).

**FIGURE 2-3: LOADING OF PC IN DIFFERENT SITUATIONS**



### 2.3.1 COMPUTED GOTO

A computed GOTO is accomplished by adding an offset to the program counter (`ADDWF PCL`). When performing a table read using a computed GOTO method, care should be exercised if the table location crosses a PCL memory boundary (each 256-byte block). Refer to the Application Note AN556, "Implementing a Table Read" (DS00556).

### 2.3.2 STACK

The PIC16F688 family has an 8-level x 13-bit wide hardware stack (see Figure 2-1). The stack space is not part of either program or data space and the Stack Pointer is not readable or writable. The PC is PUSHed onto the stack when a CALL instruction is executed or an interrupt causes a branch. The stack is POPed in the event of a RETURN, RETLW or a RETFIE instruction execution. PCLATH is not affected by a PUSH or POP operation.

The stack operates as a circular buffer. This means that after the stack has been PUSHed eight times, the ninth push overwrites the value that was stored from the first push. The tenth push overwrites the second push (and so on).

- Note 1:** There are no Status bits to indicate Stack Overflow or Stack Underflow conditions.
- 2:** There are no instructions/mnemonics called PUSH or POP. These are actions that occur from the execution of the CALL, RETURN, RETLW and RETFIE instructions or the vectoring to an interrupt address.



# PIC16F688

## 2.4 Indirect Addressing, INDF and FSR Registers

The INDF register is not a physical register. Addressing the INDF register will cause indirect addressing.

Indirect addressing is possible by using the INDF register. Any instruction using the INDF register actually accesses data pointed to by the File Select Register (FSR). Reading INDF itself indirectly will produce 00h. Writing to the INDF register indirectly results in a no operation (although Status bits may be affected). An effective 9-bit address is obtained by concatenating the 8-bit FSR register and the IRP bit of the STATUS register, as shown in Figure 2-4.

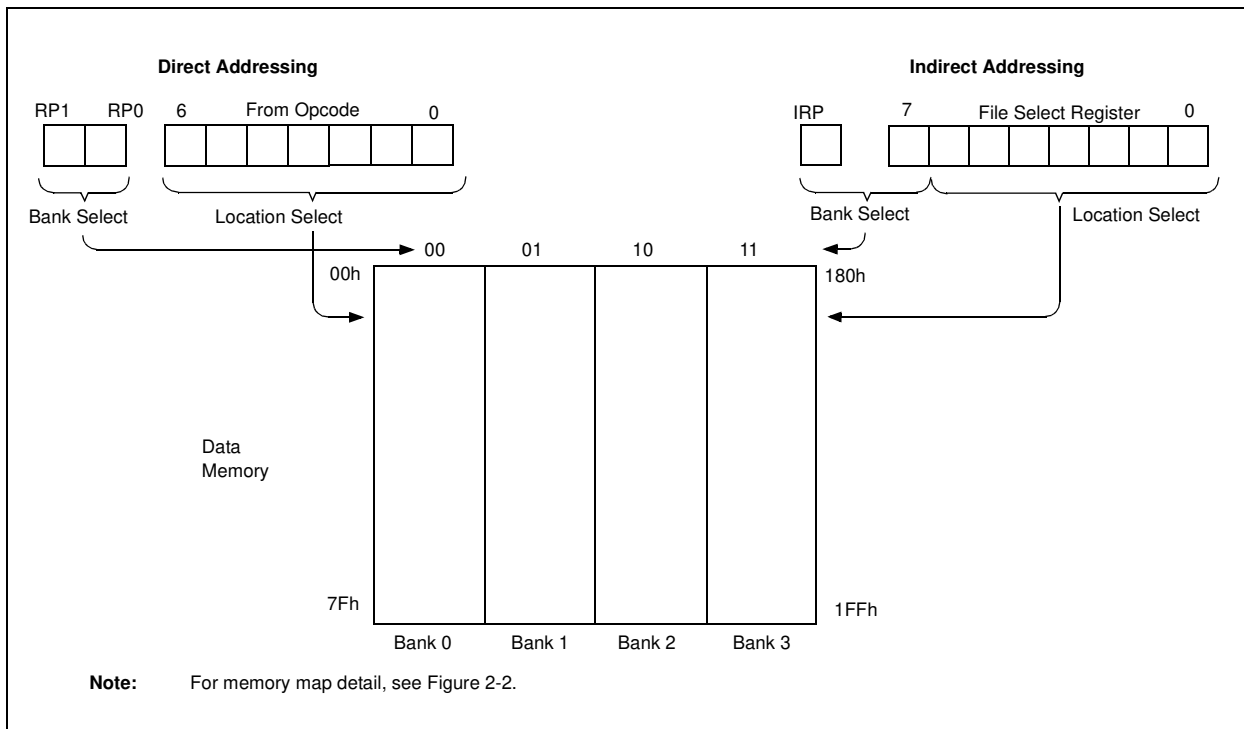
A simple program to clear RAM location 20h-2Fh using indirect addressing is shown in Example 2-1.

### EXAMPLE 2-1: INDIRECT ADDRESSING

```

MOVLW 0x20    ;initialize pointer
MOVWF FSR     ;to RAM
NEXT CLRF INDF ;clear INDF register
INCF FSR      ;inc pointer
BTFSF FSR,4   ;all done?
GOTO NEXT     ;no clear next
CONTINUE      ;yes continue
    
```

FIGURE 2-4: DIRECT/INDIRECT ADDRESSING PIC16F688



## 3.0 OSCILLATOR MODULE (WITH FAIL-SAFE CLOCK MONITOR)

### 3.1 Overview

The oscillator module has a wide variety of clock sources and selection features that allow it to be used in a wide range of applications while maximizing performance and minimizing power consumption. Figure 3-1 illustrates a block diagram of the oscillator module.

Clock sources can be configured from external oscillators, quartz crystal resonators, ceramic resonators and Resistor-Capacitor (RC) circuits. In addition, the system clock source can be configured from one of two internal oscillators, with a choice of speeds selectable via software. Additional clock features include:

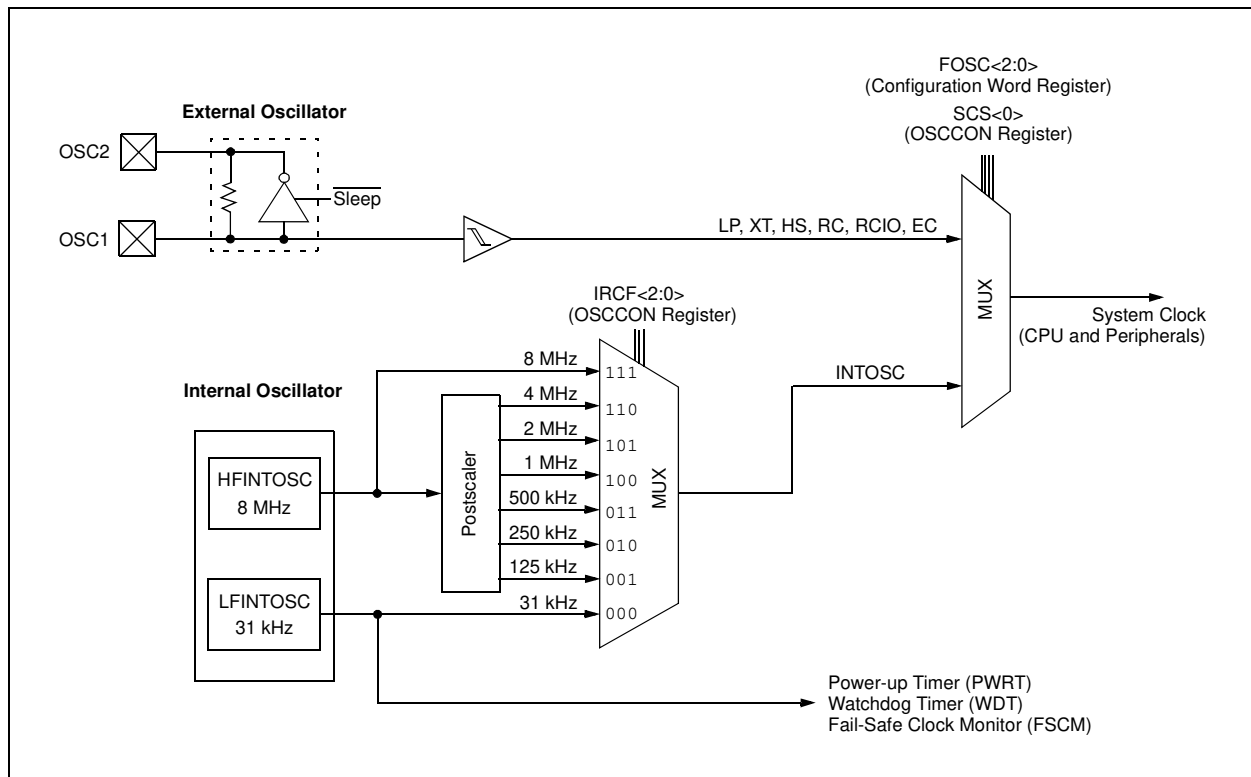
- Selectable system clock source between external or internal via software.
- Two-Speed Start-Up mode, which minimizes latency between external oscillator start-up and code execution.
- Fail-Safe Clock Monitor (FSCM) designed to detect a failure of the external clock source (LP, XT, HS, EC or RC modes) and switch automatically to the internal oscillator.

The oscillator module can be configured in one of eight clock modes.

1. EC – External clock with I/O on OSC2/CLKOUT.
2. LP – 32 kHz Low-Power Crystal mode.
3. XT – Medium Gain Crystal or Ceramic Resonator Oscillator mode.
4. HS – High Gain Crystal or Ceramic Resonator mode.
5. RC – External Resistor-Capacitor (RC) with Fosc/4 output on OSC2/CLKOUT.
6. RCIO – External Resistor-Capacitor (RC) with I/O on OSC2/CLKOUT.
7. INTOSC – Internal oscillator with Fosc/4 output on OSC2 and I/O on OSC1/CLKIN.
8. INTOSCIO – Internal oscillator with I/O on OSC1/CLKIN and OSC2/CLKOUT.

Clock source modes are configured by the FOSC<2:0> bits in the Configuration Word register (CONFIG). The internal clock can be generated from two internal oscillators. The HFINTOSC is a calibrated high-frequency oscillator. The LFINTOSC is an uncalibrated low-frequency oscillator.

**FIGURE 3-1: PIC® MCU CLOCK SOURCE BLOCK DIAGRAM**



# PIC16F688

## 3.2 Oscillator Control

The Oscillator Control (OSCCON) register (Figure 3-1) controls the system clock and frequency selection options. The OSCCON register contains the following bits:

- Frequency selection bits (IRCF)
- Frequency Status bits (HTS, LTS)
- System clock control bits (OSTS, SCS)

**REGISTER 3-1: OSCCON: OSCILLATOR CONTROL REGISTER**

U-0	R/W-1	R/W-1	R/W-0	R-1	R-0	R-0	R/W-0
—	IRCF2	IRCF1	IRCF0	OSTS <sup>(1)</sup>	HTS	LTS	SCS
bit 7							bit 0

<b>Legend:</b>			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 7           **Unimplemented:** Read as '0'
- bit 6-4       **IRCF<2:0>:** Internal Oscillator Frequency Select bits
  - 111 = 8 MHz
  - 110 = 4 MHz (default)
  - 101 = 2 MHz
  - 100 = 1 MHz
  - 011 = 500 kHz
  - 010 = 250 kHz
  - 001 = 125 kHz
  - 000 = 31 kHz (LFINTOSC)
- bit 3           **OSTS:** Oscillator Start-up Time-out Status bit<sup>(1)</sup>
  - 1 = Device is running from the external clock defined by FOSC<2:0> of the Configuration Word
  - 0 = Device is running from the internal oscillator (HFINTOSC or LFINTOSC)
- bit 2           **HTS:** HFINTOSC Status bit (High Frequency – 8 MHz to 125 kHz)
  - 1 = HFINTOSC is stable
  - 0 = HFINTOSC is not stable
- bit 1           **LTS:** LFINTOSC Stable bit (Low Frequency – 31 kHz)
  - 1 = LFINTOSC is stable
  - 0 = LFINTOSC is not stable
- bit 0           **SCS:** System Clock Select bit
  - 1 = Internal oscillator is used for system clock
  - 0 = Clock source defined by FOSC<2:0> of the Configuration Word

**Note 1:** Bit resets to '0' with Two-Speed Start-up and LP, XT or HS selected as the Oscillator mode or Fail-Safe mode is enabled.

## 3.3 Clock Source Modes

Clock source modes can be classified as external or internal.

- External Clock modes rely on external circuitry for the clock source. Examples are: oscillator modules (EC mode), quartz crystal resonators or ceramic resonators (LP, XT and HS modes) and Resistor-Capacitor (RC) mode circuits.
- Internal clock sources are contained internally within the oscillator module. The oscillator module has two internal oscillators: the 8 MHz High-Frequency Internal Oscillator (HFINTOSC) and the 31 kHz Low-Frequency Internal Oscillator (LFINTOSC).

The system clock can be selected between external or internal clock sources via the System Clock Select (SCS) bit of the OSCCON register. See **Section 3.6 “Clock Switching”** for additional information.

## 3.4 External Clock Modes

### 3.4.1 OSCILLATOR START-UP TIMER (OST)

If the oscillator module is configured for LP, XT or HS modes, the Oscillator Start-up Timer (OST) counts 1024 oscillations from OSC1. This occurs following a Power-on Reset (POR) and when the Power-up Timer (PWRT) has expired (if configured), or a wake-up from Sleep. During this time, the program counter does not increment and program execution is suspended. The OST ensures that the oscillator circuit, using a quartz crystal resonator or ceramic resonator, has started and is providing a stable system clock to the oscillator module. When switching between clock sources, a delay is required to allow the new clock to stabilize. These oscillator delays are shown in Table 3-1.

In order to minimize latency between external oscillator start-up and code execution, the Two-Speed Clock Start-up mode can be selected (see **Section 3.7 “Two-Speed Clock Start-up Mode”**).

**TABLE 3-1: OSCILLATOR DELAY EXAMPLES**

Switch From	Switch To	Frequency	Oscillator Delay
Sleep/POR	LFINTOSC HFINTOSC	31 kHz 125 kHz to 8 MHz	Oscillator Warm-Up Delay (TWARM)
Sleep/POR	EC, RC	DC – 20 MHz	2 instruction cycles
LFINTOSC (31 kHz)	EC, RC	DC – 20 MHz	1 cycle of each
Sleep/POR	LP, XT, HS	32 kHz to 20 MHz	1024 Clock Cycles (OST)
LFINTOSC (31 kHz)	HFINTOSC	125 kHz to 8 MHz	1 $\mu$ s (approx.)

### 3.4.2 EC MODE

The External Clock (EC) mode allows an externally generated logic level as the system clock source. When operating in this mode, an external clock source is connected to the OSC1 input and the OSC2 is available for general purpose I/O. Figure 3-2 shows the pin connections for EC mode.

The Oscillator Start-up Timer (OST) is disabled when EC mode is selected. Therefore, there is no delay in operation after a Power-on Reset (POR) or wake-up from Sleep. Because the PIC<sup>®</sup> MCU design is fully static, stopping the external clock input will have the effect of halting the device while leaving all data intact. Upon restarting the external clock, the device will resume operation as if no time had elapsed.

**FIGURE 3-2: EXTERNAL CLOCK (EC) MODE OPERATION**

