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40/44-Pin Flash Microcontrollers with XLP and mTouch[®] Technology

Devices included in this data sheet

- PIC16F707
- PIC16LF707

High-Performance RISC CPU

- Only 35 Single-Word Instructions to Learn:
 - All single-cycle instructions except branches
- Operating Speed:
 - DC – 20 MHz clock input
 - DC – 200 ns instruction cycle
- Interrupt Capability
- 8-Level Deep Hardware Stack
- Direct, Indirect and Relative Addressing modes
- Processor Read Access to Program Memory
- Pinout Compatible to other 40-Pin PIC16CXXX and PIC16FXXX Microcontrollers

Memory

- 8K x 14 Words of Flash Program Memory
- 363 Bytes of Data Memory (SRAM)

Special Microcontroller Features

- Precision Internal Oscillator:
 - 16 MHz or 500 kHz operation
 - Factory calibrated to $\pm 1\%$, typical
 - Software selectable $\div 1$, $\div 2$, $\div 4$ or $\div 8$ divider
- 31 kHz Low-Power Internal Oscillator
- External Oscillator Block with:
 - Three crystal/resonator modes up to 20 MHz
 - Three external clock modes up to 20 MHz
- Power-on Reset (POR)
- Power-up Timer (PWRT)
- Oscillator Start-Up Timer (OST)
- Brown-out Reset (BOR):
 - Selectable between two trip points
 - Disabled in Sleep option
- Watchdog Timer (WDT)
- Programmable Code Protection
- In-Circuit Serial Programming[™] (ICSP[™]) via Two Pins
- In-Circuit Debug (ICD) via Two Pins
- Multiplexed Master Clear with Pull-up/Input Pin
- Industrial and Extended Temperature Range

- Operating Voltage Range:
 - 1.8V to 3.6V (PIC16LF707)
 - 1.8V to 5.5V (PIC16F707)

Extreme Low-Power Management PIC16LF707 with XLP

- Sleep mode: 20 nA @ 1.8V, typical
- Watchdog Timer: 500 nA @ 1.8V, typical
- Timer1 Oscillator: 600 nA @ 1.8V, typical @ 32 kHz

mTouch[®] Technology Features

- Up to 32 Channels
- Two Capacitive Sensing modules:
 - Acquire two samples simultaneously
- Multiple Power modes:
 - Operation during Sleep
 - Proximity sensing with ultra low μA current
- Adjustable Waveform Min. and Max. for Optimal Noise Performance
- 1.8V to 5.5V Operation (3.6V max. for PIC16LF707)

Analog Features

- A/D Converter:
 - 8-bit resolution and up to 14 channels
 - Conversion available during Sleep
 - Selectable 1.024V/2.048V/4.096V voltage reference
- On-chip 3.2V Regulator (PIC16F707 device only)

Peripheral Highlights

- Up to 35 I/O Pins and One Input-only Pin:
 - High current source/sink for direct LED drive
 - Interrupt-on-pin change
 - Individually programmable weak pull-ups
- Timer0/A/B: 8-Bit Timer/Counter with 8-Bit Prescaler
- Enhanced Timer1/3:
 - Dedicated low-power 32 kHz oscillator driver
 - 16-bit timer/counter with prescaler
 - External Gate Input mode with toggle and single shot modes
 - Interrupt-on-gate completion
- Timer2: 8-Bit Timer/Counter with 8-Bit Period Register, Prescaler and Postscaler

PIC16(L)F707

- Two Capture, Compare, PWM modules (CCP):
 - 16-bit Capture, max. resolution 12.5 ns
 - 16-bit Compare, max. resolution 200 ns
 - 10-bit PWM, max. frequency 20 kHz
- Addressable Universal Synchronous Asynchronous Receiver Transmitter (AUSART)
- Synchronous Serial Port (SSP):
 - SPI (Master/Slave)
 - I²C (Slave) with Address Mask
- Voltage Reference module:
 - Fixed Voltage Reference (FVR) with 1.024V, 2.048V and 4.096V output levels
 - 5-bit rail-to-rail resistive DAC with positive reference selection

Device	Program Memory Flash (words)	SRAM (bytes)	High Endurance Flash (bytes)	I/Os	Capacitive Touch Channels	8-bit A/D (ch)	AUSART	CCP	Timers 8/16-bit
PIC16(L)F707	8192	363	128	36	32	14	Yes	2	4/2

PIN DIAGRAMS

FIGURE 1: 40-PIN PDIP

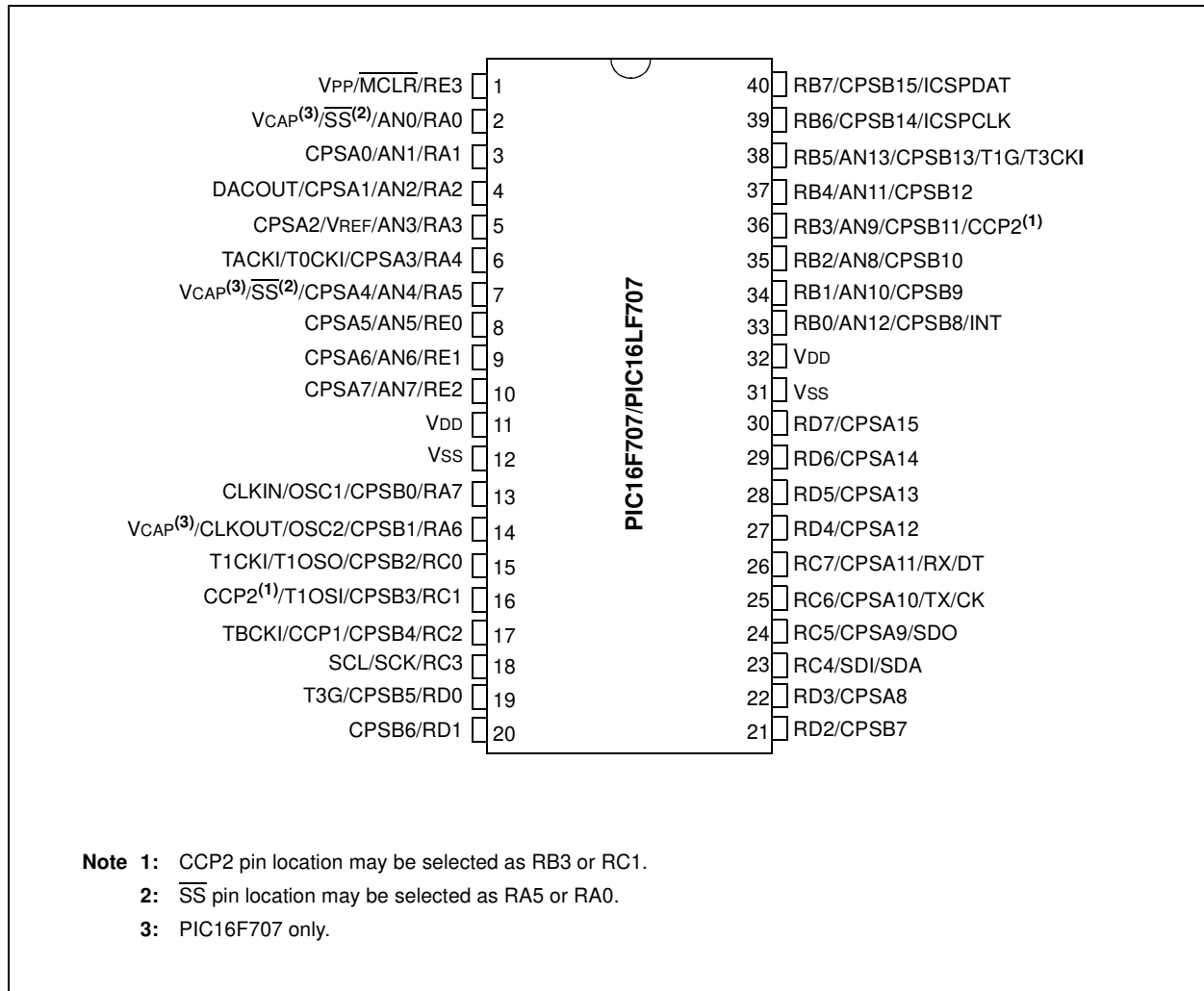
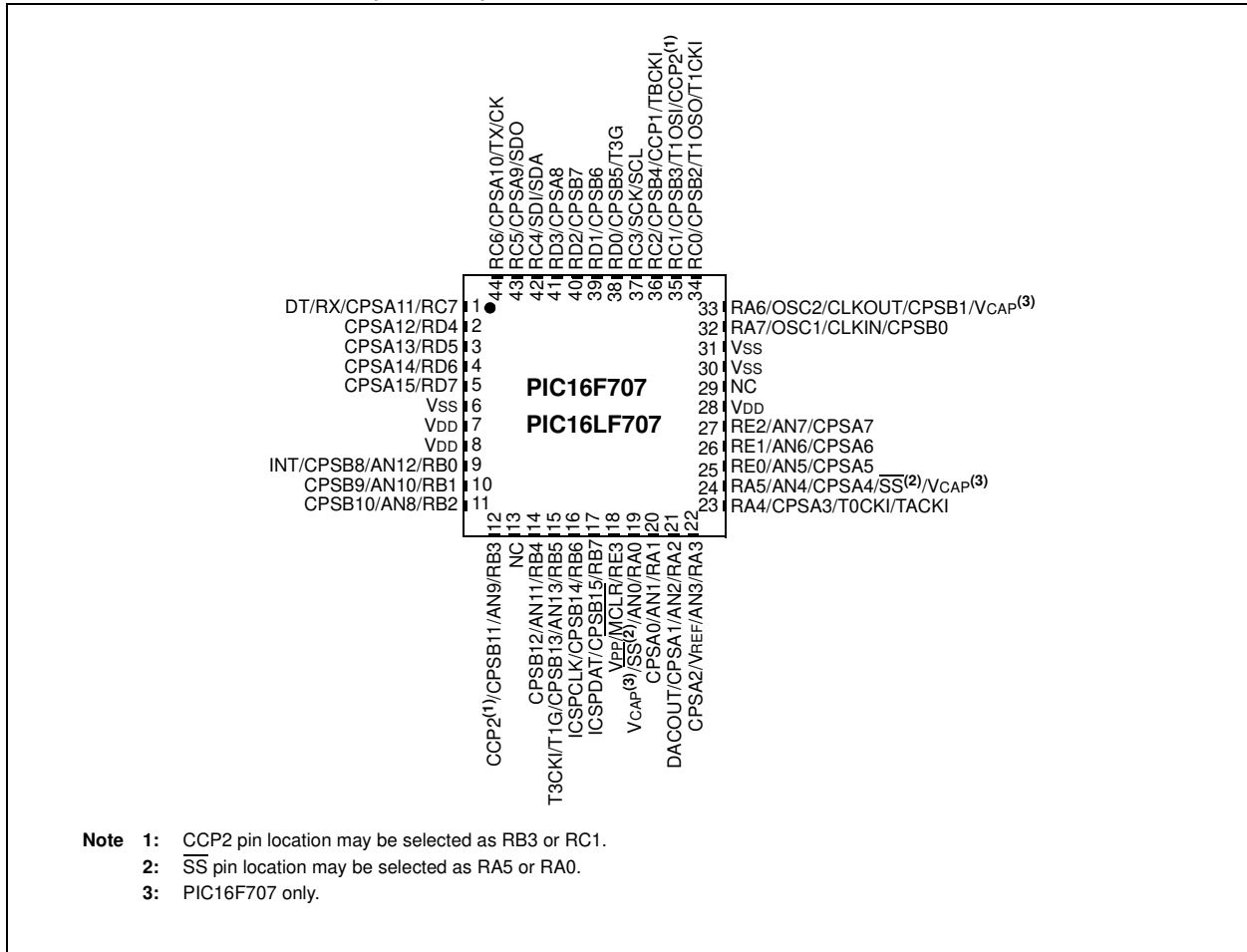


FIGURE 2: 44-PIN QFN (8X8X0.9)



- Note**
- 1: CCP2 pin location may be selected as RB3 or RC1.
 - 2: SS pin location may be selected as RA5 or RA0.
 - 3: PIC16F707 only.

PIC16(L)F707

FIGURE 3: 44-PIN TQFP

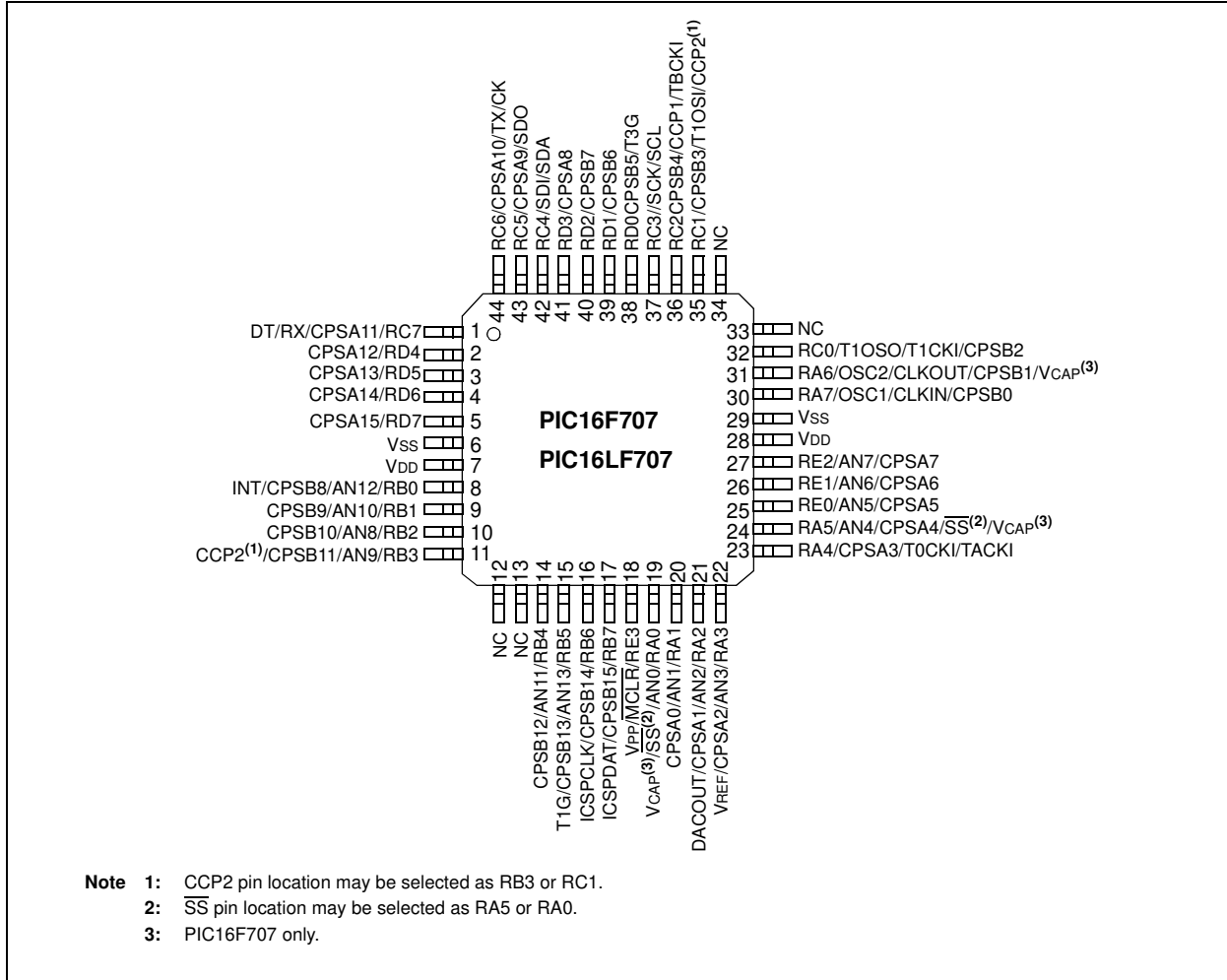
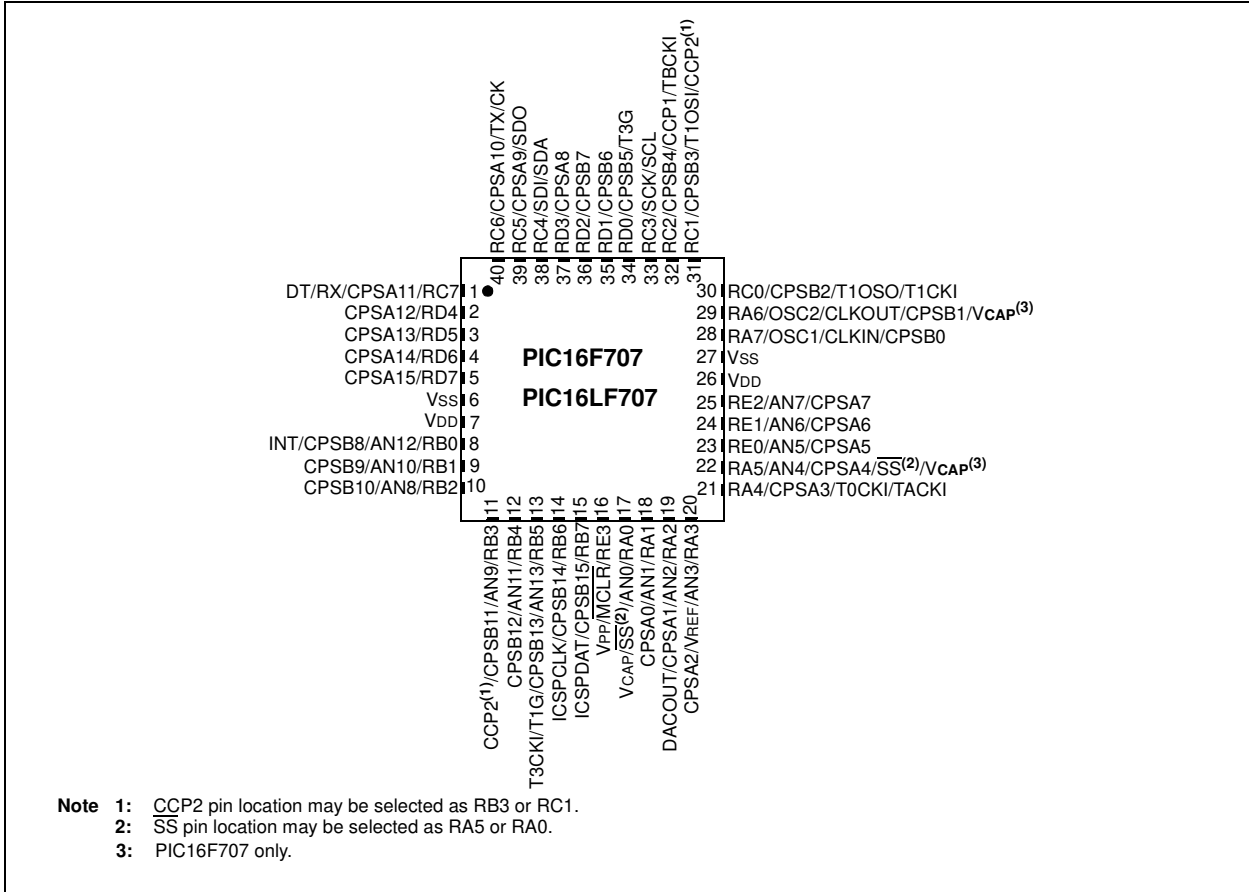


FIGURE 4: 40-PIN UQFN (5X5X0.5)



PIC16(L)F707

PIN ALLOCATION TABLE

TABLE 1: 40/44-PIN ALLOCATION TABLE FOR PIC16F707/PIC16LF707

I/O	40-Pin PDIP	40-Pin UQFN	44-Pin TQFP	44-Pin QFN	ANSEL	A/D	DAC	Cap Sensor	Timers	CCP	AUSART	SSP	Interrupt	Pull-up	Basic
RA0	2	17	19	19	Y	AN0	—	—	—	—	—	SS ⁽³⁾	—	—	VCAP ⁽⁴⁾
RA1	3	18	20	20	Y	AN1	—	CPSA0	—	—	—	—	—	—	—
RA2	4	19	21	21	Y	AN2	DACOUT	CPSA1	—	—	—	—	—	—	—
RA3	5	20	22	22	Y	AN3/ VREF	VREF	CPSA2	—	—	—	—	—	—	—
RA4	6	21	23	23	Y	—	—	CPSA3	T0CKI/ TACKI	—	—	—	—	—	—
RA5	7	22	24	24	Y	AN4	—	CPSA4	—	—	—	SS ⁽³⁾	—	—	VCAP ⁽⁴⁾
RA6	14	29	31	33	Y	—	—	CPSB1	—	—	—	—	—	—	OSC2/ CLKOUT/ VCAP ⁽⁴⁾
RA7	13	28	30	32	Y	—	—	CPSB0	—	—	—	—	—	—	OSC1/ CLKIN
RB0	33	8	8	9	Y	AN12	—	CPSB8	—	—	—	—	IOC/INT	Y	—
RB1	34	9	9	10	Y	AN10	—	CPSB9	—	—	—	—	IOC	Y	—
RB2	35	10	10	11	Y	AN8	—	CPSB10	—	—	—	—	IOC	Y	—
RB3	36	11	11	12	Y	AN9	—	CPSB11	—	CCP2 ⁽²⁾	—	—	IOC	Y	—
RB4	37	12	14	14	Y	AN11	—	CPSB12	—	—	—	—	IOC	Y	—
RB5	38	13	15	15	Y	AN13	—	CPSB13	T1G/ T3CKI	—	—	—	IOC	Y	—
RB6	39	14	16	16	Y	—	—	CPSB14	—	—	—	—	IOC	Y	ICSPCLK/ ICDCLK
RB7	40	15	17	17	Y	—	—	CPSB15	—	—	—	—	IOC	Y	ICSPDAT/ ICDDAT
RC0	15	30	32	34	Y	—	—	CPSB2	T1OSO/ T1CKI	—	—	—	—	—	—
RC1	16	31	35	35	Y	—	—	CPSB3	T1OSI	CCP2 ⁽²⁾	—	—	—	—	—
RC2	17	32	36	36	Y	—	—	CPSB4	TBCKI	CCP1	—	—	—	—	—
RC3	18	33	37	37	—	—	—	—	—	—	—	SCK/ SCL	—	—	—
RC4	23	38	42	42	—	—	—	—	—	—	—	SDI/ SDA	—	—	—
RC5	24	39	43	43	Y	—	—	CPSA9	—	—	—	SDO	—	—	—
RC6	25	40	44	44	Y	—	—	CPSA10	—	—	TX/CK	—	—	—	—
RC7	26	1	1	1	Y	—	—	CPSA11	—	—	RX/DT	—	—	—	—
RD0	19	34	38	38	Y	—	—	CPSB5	T3G	—	—	—	—	—	—
RD1	20	35	39	39	Y	—	—	CPSB6	—	—	—	—	—	—	—
RD2	21	36	40	40	Y	—	—	CPSB7	—	—	—	—	—	—	—
RD3	22	37	41	41	Y	—	—	CPSA8	—	—	—	—	—	—	—
RD4	27	2	2	2	Y	—	—	CPSA12	—	—	—	—	—	—	—
RD5	28	3	3	3	Y	—	—	CPSA13	—	—	—	—	—	—	—
RD6	29	4	4	4	Y	—	—	CPSA14	—	—	—	—	—	—	—
RD7	30	5	5	5	Y	—	—	CPSA15	—	—	—	—	—	—	—
RE0	8	23	25	25	Y	AN5	—	CPSA5	—	—	—	—	—	—	—
RE1	9	24	26	26	Y	AN6	—	CPSA6	—	—	—	—	—	—	—
RE2	10	25	27	27	Y	AN7	—	CPSA7	—	—	—	—	—	—	—
RE3	1	16	18	18	—	—	—	—	—	—	—	—	—	Y ⁽¹⁾	MCLR/ VPP

Note 1: Pull-up activated only with external MCLR configuration.

2: RC1 is the default pin location for CCP2. RB3 may be selected by changing the CCP2SEL bit in the APFCON register.

3: RA5 is the default pin location for SS. RA0 may be selected by changing the SSSEL bit in the APFCON register.

4: PIC16F707 only. VCAP functionality is selectable by the VCAPEN bits in Configuration Word 2.

PIC16(L)F707

TABLE 1: 40/44-PIN ALLOCATION TABLE FOR PIC16F707/PIC16LF707

I/O	40-Pin PDIP	40-Pin UQFN	44-Pin TQFP	44-Pin QFN	ANSEL	A/D	DAC	Cap Sensor	Timers	CCP	AUSART	SSP	Interrupt	Pull-up	Basic
VDD	11, 32	7, 26	7, 28	7, 8, 28		—	—	—	—	—	—	—	—	—	VDD
Vss	12, 31	6, 27	6, 29	6, 30, 31		—	—	—	—	—	—	—	—	—	Vss

- Note**
- 1: Pull-up activated only with external MCLR configuration.
 - 2: RC1 is the default pin location for CCP2. RB3 may be selected by changing the CCP2SEL bit in the APFCON register.
 - 3: RA5 is the default pin location for SS. RA0 may be selected by changing the SSSEL bit in the APFCON register.
 - 4: PIC16F707 only. VCAP functionality is selectable by the VCAPEN bits in Configuration Word 2.

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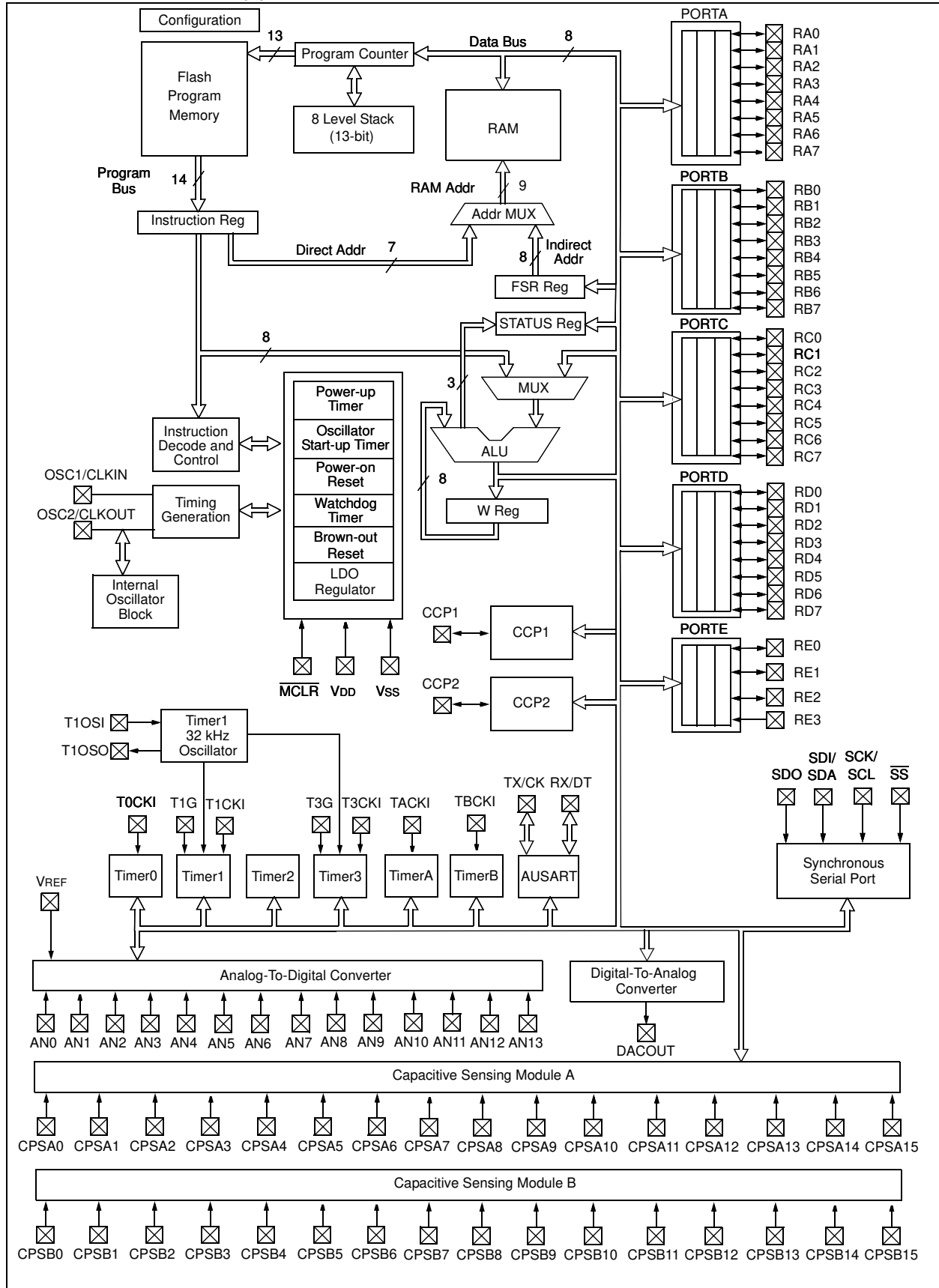
PIC16(L)F707

1.0 DEVICE OVERVIEW

The PIC16(L)F707 devices are covered by this data sheet. They are available in 40/44-pin packages. [Figure 1-1](#) shows a block diagram of the PIC16(L)F707 devices. [Table 1-1](#) shows the pinout descriptions.

PIC16(L)F707

FIGURE 1-1: PIC16(L)F707 BLOCK DIAGRAM



PIC16(L)F707

TABLE 1-1: PIC16(L)F707 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
RA0/AN0/ \overline{SS} /VCAP	RA0	TTL	CMOS	General purpose I/O.
	AN0	AN	—	A/D Channel 0 input.
	\overline{SS}	ST	—	Slave Select input.
	VCAP	Power	Power	Filter capacitor for Voltage Regulator (PIC16F only).
RA1/AN1/CPSA0	RA1	TTL	CMOS	General purpose I/O.
	AN1	AN	—	A/D Channel 1 input.
	CPSA0	AN	—	Capacitive sensing A input 0.
RA2/AN2/CPSA1/DACOUT	RA2	TTL	CMOS	General purpose I/O.
	AN2	AN	—	A/D Channel 2 input.
	CPSA1	AN	—	Capacitive sensing A input 1.
	DACOUT	—	AN	Voltage Reference Output.
RA3/AN3/VREF/CPSA2	RA3	TTL	CMOS	General purpose I/O.
	AN3	AN	—	A/D Channel 3 input.
	VREF	AN	—	A/D Voltage Reference input.
	CPSA2	AN	—	Capacitive sensing A input 2.
RA4/CPSA3/T0CKI/TACKI	RA4	TTL	CMOS	General purpose I/O.
	CPSA3	AN	—	Capacitive sensing A input 3.
	T0CKI	ST	—	Timer0 clock input.
	TACKI	ST	—	TimerA clock input.
RA5/AN4/CPSA4/ \overline{SS} /VCAP	RA5	TTL	CMOS	General purpose I/O.
	AN4	AN	—	A/D Channel 4 input.
	CPSA4	AN	—	Capacitive sensing A input 4.
	\overline{SS}	ST	—	Slave Select input.
	VCAP	Power	Power	Filter capacitor for Voltage Regulator (PIC16F only).
RA6/OSC2/CLKOUT/VCAP/CPSB1	RA6	TTL	CMOS	General purpose I/O.
	OSC2	—	XTAL	Crystal/Resonator (LP, XT, HS modes).
	CLKOUT	—	CMOS	Fosc/4 output.
	VCAP	Power	Power	Filter capacitor for Voltage Regulator (PIC16F only).
	CPSB1	AN	—	Capacitive sensing B input 1.
RA7/OSC1/CLKIN/CPSB0	RA7	TTL	CMOS	General purpose I/O.
	OSC1	XTAL	—	Crystal/Resonator (LP, XT, HS modes).
	CLKIN	CMOS	—	External clock input (EC mode).
	CLKIN	ST	—	RC oscillator connection (RC mode).
	CPSB0	AN	—	Capacitive sensing B input 0.
RB0/AN12/CPSB8/INT	RB0	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN12	AN	—	A/D Channel 12 input.
	CPSB8	AN	—	Capacitive sensing B input 8.
	INT	ST	—	External interrupt.
RB1/AN10/CPSB9	RB1	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN10	AN	—	A/D Channel 10 input.
	CPSB9	AN	—	Capacitive sensing B input 9.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I²C = Schmitt Trigger input with I²C levels
HV = High Voltage XTAL = Crystal

TABLE 1-1: PIC16(L)F707 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
RB2/AN8/CPSB10	RB2	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN8	AN	—	A/D Channel 8 input.
	CPSB10	AN	—	Capacitive sensing B input 10.
RB3/AN9/CPSB11/CCP2	RB3	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN9	AN	—	A/D Channel 9 input.
	CPSB11	AN	—	Capacitive sensing B input 11.
	CCP2	ST	CMOS	Capture/Compare/PWM2.
RB4/AN11/CPSB12	RB4	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN11	AN	—	A/D Channel 11 input.
	CPSB12	AN	—	Capacitive sensing B input 12.
RB5/AN13/CPSB13/T1G/T3CKI	RB5	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN13	AN	—	A/D Channel 13 input.
	CPSB13	AN	—	Capacitive sensing B input 13.
	T1G	ST	—	Timer1 gate input.
	T3CKI	ST	—	Timer3 clock input.
RB6/ICSPCLK/ICDCLK/CPSB14	RB6	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	ICSPCLK	ST	—	Serial Programming Clock.
	ICDCLK	ST	—	In-Circuit Debug Clock.
	CPSB14	AN	—	Capacitive sensing B input 14.
RB7/ICSPDAT/ICDDAT/CPSB15	RB7	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	ICSPDAT	ST	CMOS	ICSP™ Data I/O.
	ICDDAT	ST	—	In-Circuit Data I/O.
	CPSB15	AN	—	Capacitive sensing B input 15.
RC0/T1OSO/T1CKI/CPSB2	RC0	ST	CMOS	General purpose I/O.
	T1OSO	XTAL	XTAL	Timer1 oscillator connection.
	T1CKI	ST	—	Timer1 clock input.
	CPSB2	AN	—	Capacitive sensing B input 2.
RC1/T1OSI/CCP2/CPSB3	RC1	ST	CMOS	General purpose I/O.
	T1OSI	XTAL	XTAL	Timer1 oscillator connection.
	CCP2	ST	CMOS	Capture/Compare/PWM2.
	CPSB3	AN	—	Capacitive sensing B input 3.
RC2/CCP1/CPSB4/TBCKI	RC2	ST	CMOS	General purpose I/O.
	CCP1	ST	CMOS	Capture/Compare/PWM1.
	CPSB4	AN	—	Capacitive sensing B input 4.
	TBCKI	ST	—	TimerB clock input.
RC3/SCK/SCL	RC3	ST	CMOS	General purpose I/O.
	SCK	ST	CMOS	SPI clock.
	SCL	I ² C	OD	I ² C clock.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I²C = Schmitt Trigger input with I²C levels
HV = High Voltage XTAL = Crystal

PIC16(L)F707

TABLE 1-1: PIC16(L)F707 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
RC4/SDI/SDA	RC4	ST	CMOS	General purpose I/O.
	SDI	ST	—	SPI data input.
	SDA	I ² C	OD	I ² C data input/output.
RC5/SDO/CPSA9	RC5	ST	CMOS	General purpose I/O.
	SDO	—	CMOS	SPI data output.
	CPSA9	AN	—	Capacitive sensing A input 9.
RC6/TX/CK/CPSA10	RC6	ST	CMOS	General purpose I/O.
	TX	—	CMOS	USART asynchronous transmit.
	CK	ST	CMOS	USART synchronous clock.
	CPSA10	AN	—	Capacitive sensing A input 10.
RC7/RX/DT/CPSA11	RC7	ST	CMOS	General purpose I/O.
	RX	ST	—	USART asynchronous input.
	DT	ST	CMOS	USART synchronous data.
	CPSA11	AN	—	Capacitive sensing A input 11.
RD0/CPSB5/T3G	RD0	ST	CMOS	General purpose I/O.
	CPSB5	AN	—	Capacitive sensing B input 5.
	T3G	ST	—	Timer3 Gate input.
RD1/CPSB6	RD1	ST	CMOS	General purpose I/O.
	CPSB6	AN	—	Capacitive sensing B input 6.
RD2/CPSB7	RD2	ST	CMOS	General purpose I/O.
	CPSB7	AN	—	Capacitive sensing B input 7.
RD3/CPSA8	RD3	ST	CMOS	General purpose I/O.
	CPSA8	AN	—	Capacitive sensing A input 8.
RD4/CPSA12	RD4	ST	CMOS	General purpose I/O.
	CPSA12	AN	—	Capacitive sensing A input 12.
RD5/CPSA13	RD5	ST	CMOS	General purpose I/O.
	CPSA13	AN	—	Capacitive sensing A input 13.
RD6/CPSA14	RD6	ST	CMOS	General purpose I/O.
	CPSA14	AN	—	Capacitive sensing A input 14.
RD7/CPSA15	RD7	ST	CMOS	General purpose I/O.
	CPSA15	AN	—	Capacitive sensing A input 15.
RE0/AN5/CPSA5	RE0	ST	CMOS	General purpose I/O.
	AN5	AN	—	A/D Channel 5 input.
	CPSA5	AN	—	Capacitive sensing A input 5.
RE1/AN6/CPSA6	RE1	ST	CMOS	General purpose I/O.
	AN6	AN	—	A/D Channel 6 input.
	CPSA6	AN	—	Capacitive sensing A input 6.
RE2/AN7/CPSA7	RE2	ST	CMOS	General purpose I/O.
	AN7	AN	—	A/D Channel 7 input.
	CPSA7	AN	—	Capacitive sensing A input 7.
RE3/MCLR/VPP	RE3	TTL	—	General purpose input.
	MCLR	ST	—	Master Clear with internal pull-up.
	VPP	HV	—	Programming voltage.
VDD	VDD	Power	—	Positive supply.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I²C = Schmitt Trigger input with I²C levels
HV = High Voltage XTAL = Crystal

TABLE 1-1: PIC16(L)F707 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
Vss	Vss	Power	—	Ground reference.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I²C = Schmitt Trigger input with I²C levels
HV = High Voltage XTAL = Crystal

Note: The PIC16F707 devices have an internal low dropout voltage regulator. An external capacitor must be connected to one of the available VCAP pins to stabilize the regulator. For more information, see **Section 5.0 “Low Dropout (LDO) Voltage Regulator”**. The PIC16LF707 devices do not have the voltage regulator and therefore no external capacitor is required.

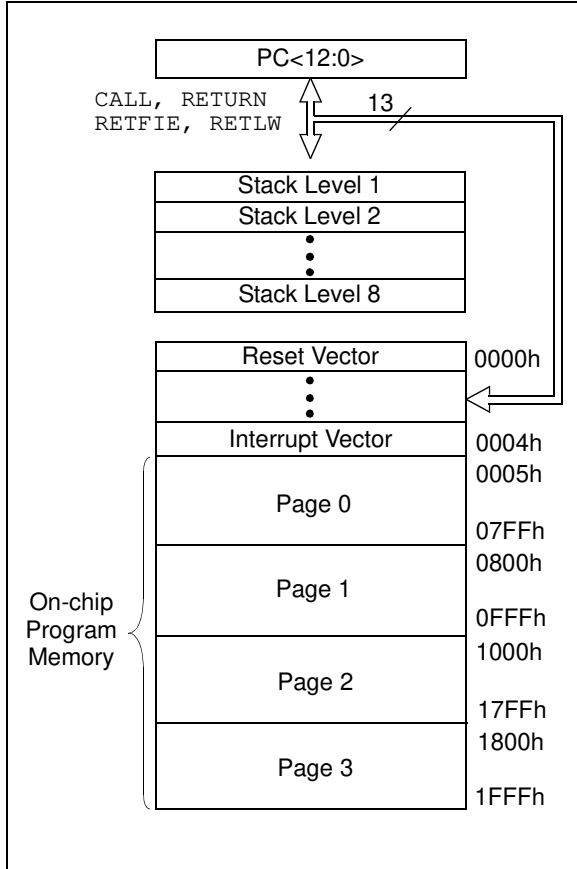
PIC16(L)F707

2.0 MEMORY ORGANIZATION

2.1 Program Memory Organization

The PIC16(L)F707 has a 13-bit program counter capable of addressing an 8K x 14 program memory space. The Reset vector is at 0000h and the interrupt vector is at 0004h.

FIGURE 2-1: PROGRAM MEMORY MAP AND STACK FOR THE PIC16(L)F707



2.2 Data Memory Organization

The data memory is partitioned into multiple banks which contain the General Purpose Registers (GPRs) and the Special Function Registers (SFRs). Bits RP0 and RP1 are bank select bits.

RP1	RP0	
0	0	→ Bank 0 is selected
0	1	→ Bank 1 is selected
1	0	→ Bank 2 is selected
1	1	→ Bank 3 is selected

Each bank extends up to 7Fh (128 bytes). The lower locations of each bank are reserved for the Special Function Registers. Above the Special Function Registers are the General Purpose Registers, implemented as static RAM. All implemented banks contain Special Function Registers. Some frequently used Special Function Registers from one bank are mirrored in another bank for code reduction and quicker access.

2.2.1 GENERAL PURPOSE REGISTER FILE

The register file is organized as 363 x 8 bits. Each register is accessed either directly or indirectly through the File Select Register (FSR), (Refer to [Section 2.5 "Indirect Addressing, INDF and FSR Registers"](#)).

2.2.2 SPECIAL FUNCTION REGISTERS

The Special Function Registers are registers used by the CPU and peripheral functions for controlling the desired operation of the device (refer to [Table 2-2](#)). These registers are static RAM.

The Special Function Registers can be classified into two sets: core and peripheral. The Special Function Registers associated with the "core" are described in this section. Those related to the operation of the peripheral features are described in the section of that peripheral feature.

TABLE 2-1: DATA MEMORY MAP FOR PIC16(L)F707

				File Address			
Indirect addr. ^(*)	00h	Indirect addr. ^(*)	80h	Indirect addr. ^(*)	100h	Indirect addr. ^(*)	180h
TMR0	01h	OPTION	81h	TMR0	101h	OPTION	181h
PCL	02h	PCL	82h	PCL	102h	PCL	182h
STATUS	03h	STATUS	83h	STATUS	103h	STATUS	183h
FSR	04h	FSR	84h	FSR	104h	FSR	184h
PORTA	05h	TRISA	85h	TACON	105h	ANSELA	185h
PORTB	06h	TRISB	86h	CPSBCON0	106h	ANSELB	186h
PORTC	07h	TRISC	87h	CPSBCON1	107h	ANSELC	187h
PORTD	08h	TRISD	88h	CPSACON0	108h	ANSELD	188h
PORTE	09h	TRISE	89h	CPSACON1	109h	ANSELE	189h
PCLATH	0Ah	PCLATH	8Ah	PCLATH	10Ah	PCLATH	18Ah
INTCON	0Bh	INTCON	8Bh	INTCON	10Bh	INTCON	18Bh
PIR1	0Ch	PIE1	8Ch	PMDATL	10Ch	PMCON1	18Ch
PIR2	0Dh	PIE2	8Dh	PMADRL	10Dh	Reserved	18Dh
TMR1L	0Eh	PCON	8Eh	PMDATH	10Eh	Reserved	18Eh
TMR1H	0Fh	T1GCON	8Fh	PMADRH	10Fh	Reserved	18Fh
T1CON	10h	OSCCON	90h	TMRA	110h	General Purpose Register 16 Bytes	190h
TMR2	11h	OSCTUNE	91h	TBCON	111h		191h
T2CON	12h	PR2	92h	TMRB	112h		192h
SSPBUF	13h	SSPADD/SSPMSK	93h	DACCON0	113h		193h
SSPCON	14h	SSPSTAT	94h	DACCON1	114h		194h
CCPR1L	15h	WPUB	95h	General Purpose Register 11 Bytes	115h		195h
CCPR1H	16h	IOCB	96h		116h		196h
CCP1CON	17h	T3CON	97h		117h		197h
RCSTA	18h	TXSTA	98h		118h		198h
TXREG	19h	SPBRG	99h		119h		199h
RCREG	1Ah	TMR3L	9Ah		11Ah		19Ah
CCPR2L	1Bh	TMR3H	9Bh		11Bh	19Bh	
CCPR2H	1Ch	APFCON	9Ch	11Ch	19Ch		
CCP2CON	1Dh	FVRCON	9Dh	11Dh	19Dh		
ADRES	1Eh	T3GCON	9Eh	11Eh	19Eh		
ADCON0	1Fh	ADCON1	9Fh	11Fh	19Fh		
General Purpose Register 96 Bytes	20h	General Purpose Register 80 Bytes	A0h	General Purpose Register 80 Bytes	120h	General Purpose Register 80 Bytes	1A0h
	Accesses 70h – 7Fh		EFh		16Fh		1EFh
			Accesses 70h – 7Fh		F0h		170h
	7Fh		FFh		17Fh		1FFh
BANK 0		BANK 1		BANK 2		BANK 3	

Legend: = Unimplemented data memory locations, read as '0',
 * = Not a physical register

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TABLE 2-2: SPECIAL FUNCTION REGISTER SUMMARY

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
Bank 0											
00h ⁽²⁾	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx
01h	TMR0	Timer0 Module Register								0000 0000	0000 0000
02h ⁽²⁾	PCL	Program Counter (PC) Least Significant Byte								0000 0000	0000 0000
03h ⁽²⁾	STATUS	IRP	RP1	RP0	\overline{TO}	\overline{PD}	Z	DC	C	0001 1xxx	000q quuu
04h ⁽²⁾	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	uuuu uuuu
05h	PORTA	PORTA Data Latch when written: PORTA pins when read								xxxx xxxx	uuuu uuuu
06h	PORTB	PORTB Data Latch when written: PORTB pins when read								xxxx xxxx	uuuu uuuu
07h	PORTC	PORTC Data Latch when written: PORTC pins when read								xxxx xxxx	uuuu uuuu
08h	PORTD	PORTD Data Latch when written: PORTD pins when read								xxxx xxxx	uuuu uuuu
09h	PORTE	—	—	—	—	RE3	RE2	RE1	RE0	---- xxxx	---- uuuu
0Ah ^{(1),(2)}	PCLATH	—	—	—	Write Buffer for the upper 5 bits of the Program Counter					---0 0000	---0 0000
0Bh ⁽²⁾	INTCON	GIE	PEIE	TMR0IE	INTE	RBIE	TMR0IF	INTF	RBIF	0000 000x	0000 000u
0Ch	PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	0000 0000	0000 0000
0Dh	PIR2	TMR3GIF	TMR3IF	TMRBIF	TMRAIF	—	—	—	CCP2IF	0000 ---0	0000 ---0
0Eh	TMR1L	Holding Register for the Least Significant Byte of the 16-bit TMR1 Register								xxxx xxxx	uuuu uuuu
0Fh	TMR1H	Holding Register for the Most Significant Byte of the 16-bit TMR1 Register								xxxx xxxx	uuuu uuuu
10h	T1CON	TMR1CS1	TMR1CS0	T1CKPS1	T1CKPS0	T1OSCEN	$\overline{T1SYNC}$	—	TMR1ON	0000 00-0	uuuu uu-u
11h	TMR2	Timer2 Module Register								0000 0000	0000 0000
12h	T2CON	—	TOUTPS3	TOUTPS2	TOUTPS1	TOUTPS0	TMR2ON	T2CKPS1	T2CKPS0	-000 0000	-000 0000
13h	SSPBUF	Synchronous Serial Port Receive Buffer/Transmit Register								xxxx xxxx	uuuu uuuu
14h	SSPCON	WCOL	SSPOV	SSPEN	CKP	SSPM3	SSPM2	SSPM1	SSPM0	0000 0000	0000 0000
15h	CCPR1L	Capture/Compare/PWM Register 1 (LSB)								xxxx xxxx	uuuu uuuu
16h	CCPR1H	Capture/Compare/PWM Register 1 (MSB)								xxxx xxxx	uuuu uuuu
17h	CCP1CON	—	—	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0	--00 0000	--00 0000
18h	RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
19h	TXREG	USART Transmit Data Register								0000 0000	0000 0000
1Ah	RCREG	USART Receive Data Register								0000 0000	0000 0000
1Bh	CCPR2L	Capture/Compare/PWM Register 2 (LSB)								xxxx xxxx	uuuu uuuu
1Ch	CCPR2H	Capture/Compare/PWM Register 2 (MSB)								xxxx xxxx	uuuu uuuu
1Dh	CCP2CON	—	—	DC2B1	DC2B0	CCP2M3	CCP2M2	CCP2M1	CCP2M0	--00 0000	--00 0000
1Eh	ADRES	A/D Result Register								xxxx xxxx	uuuu uuuu
1Fh	ADCON0	—	—	CHS3	CHS2	CHS1	CHS0	$\overline{GO/DONE}$	ADON	--00 0000	--00 0000

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, read as '0', r = reserved.
Shaded locations are unimplemented, read as '0'.

- Note** 1: The upper byte of the program counter is not directly accessible. PCLATH is a holding register for the PC<12:8>, whose contents are transferred to the upper byte of the program counter.
2: These registers can be addressed from any bank.
3: Accessible only when SSPM<3:0> = 1001.

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TABLE 2-2: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
Bank 1											
80h ⁽²⁾	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx
81h	OPTION_REG	RBP \bar{U}	INTEDG	TMR0CS	TMR0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
82h ⁽²⁾	PCL	Program Counter (PC) Least Significant Byte								0000 0000	0000 0000
83h ⁽²⁾	STATUS	IRP	RP1	RP0	$\bar{T}O$	$\bar{P}D$	Z	DC	C	0001 1xxx	000q quuu
84h ⁽²⁾	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	uuuu uuuu
85h	TRISA	PORTA Data Direction Register								1111 1111	1111 1111
86h	TRISB	PORTB Data Direction Register								1111 1111	1111 1111
87h	TRISC	PORTC Data Direction Register								1111 1111	1111 1111
88h	TRISD	PORTD Data Direction Register								1111 1111	1111 1111
89h	TRISE	—	—	—	—	'1'	TRISE2	TRISE1	TRISE0	---- 1111	---- 1111
8Ah ^{(1),(2)}	PCLATH	—	—	—	Write Buffer for the upper 5 bits of the Program Counter					---0 0000	---0 0000
8Bh ⁽²⁾	INTCON	GIE	PEIE	TMR0IE	INTE	RBIE	TMR0IF	INTF	RBIF	0000 000x	0000 000u
8Ch	PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	0000 0000	0000 0000
8Dh	PIE2	TMR3GIE	TMR3IE	TMRBIE	TMRAIE	—	—	—	CCP2IE	0000 ---0	0000 ---0
8Eh	PCON	—	—	—	—	—	—	$\bar{P}OR$	$\bar{B}OR$	---- --qq	---- --uu
8Fh	T1GCON	TMR1GE	T1GPOL	T1GTM	T1GSPM	T1GGO/DONE	T1GVAL	T1GSS1	T1GSS0	0000 0x00	uuuu uxuu
90h	OSCCON	—	—	IRCF1	IRCF0	ICSL	ICSS	—	—	--10 00--	--10 uu--
91h	OSCTUNE	—	—	TUN5	TUN4	TUN3	TUN2	TUN1	TUN0	--00 0000	--00 0000
92h	PR2	Timer2 Period Register								1111 1111	1111 1111
93h	SSPADD	Synchronous Serial Port (I ² C mode) Address Register								0000 0000	0000 0000
93h ⁽³⁾	SSPMSK	Synchronous Serial Port (I ² C mode) Address Mask Register								1111 1111	1111 1111
94h	SSPSTAT	SMP	CKE	D \bar{A}	P	S	R \bar{W}	UA	BF	0000 0000	0000 0000
95h	WPUB	WPUB7	WPUB6	WPUB5	WPUB4	WPUB3	WPUB2	WPUB1	WPUB0	1111 1111	1111 1111
96h	IOCB	IOCB7	IOCB6	IOCB5	IOCB4	IOCB3	IOCB2	IOCB1	IOCB0	0000 0000	0000 0000
97h	T3CON	TMR3CS1	TMR3CS0	T3CKPS1	T3CKPS0	—	T3SYNC	—	TMR3ON	0000 -0-0	uuuu -u-u
98h	TXSTA	CSRC	TX9	TXEN	SYNC	—	BRGH	TRMT	TX9D	0000 -010	0000 -010
99h	SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
9Ah	TMR3L	Holding Register for the Least Significant Byte of the 16-bit TMR3 Register								xxxx xxxx	uuuu uuuu
9Bh	TMR3H	Holding Register for the Most Significant Byte of the 16-bit TMR3 Register								xxxx xxxx	uuuu uuuu
9Ch	APFCON	—	—	—	—	—	—	SSSEL	CCP2SEL	---- --00	---- --00
9Dh	FVRCON	FVRRDY	FVREN	—	—	CDAFVR1	CDAFVR0	ADFVR1	ADFVR0	x000 0000	x000 0000
9Eh	T3GCON	TMR3GE	T3GPOL	T3GTM	T3GSPM	T3GGO/DONE	T3GVAL	T3GSS1	T3GSS0	0000 0x00	uuuu uxuu
9Fh	ADCON1	—	ADCS2	ADCS1	ADCS0	—	—	ADREF1	ADREF0	-000 --00	-000 --00

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, read as '0', r = reserved.
Shaded locations are unimplemented, read as '0'.

- Note 1:** The upper byte of the program counter is not directly accessible. PCLATH is a holding register for the PC<12:8>, whose contents are transferred to the upper byte of the program counter.
- Note 2:** These registers can be addressed from any bank.
- Note 3:** Accessible only when SSPM<3:0> = 1001.

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TABLE 2-2: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
Bank 2											
100h ⁽²⁾	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx
101h	TMR0	Timer0 Module Register								0000 0000	0000 0000
102h ⁽²⁾	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	0000 0000
103h ⁽²⁾	STATUS	IRP	RP1	RP0	\overline{TO}	\overline{PD}	Z	DC	C	0001 1xxx	000q quuu
104h ⁽¹⁾	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	uuuu uuuu
105h	TACON	TMRAON	—	TACS	TASE	TAPSA	TAPS2	TAPS1	TAPS0	0-00 0000	0-00 0000
106h	CPSBCON0	CPSBON	CPSBRM	—	—	CPSBRNG1	CPSBRNG0	CPSBOUT	TBXCS	00-- 0000	00-- 0000
107h	CPSBCON1	—	—	—	—	CPSBCH3	CPSBCH2	CPSBCH1	CPSBCH0	---- 0000	---- 0000
108h	CPSACON0	CPSAON	CPSARM	—	—	CPSARNG1	CPSARNG0	CPSAOUT	TAXCS	0--- 0000	0--- 0000
109h	CPSACON1	—	—	—	—	CPSACH3	CPSACH2	CPSACH1	CPSACH0	---- 0000	---- 0000
10Ah ^{(1),(2)}	PCLATH	—	—	—	Write Buffer for the upper 5 bits of the Program Counter				---0 0000	---0 0000	
10Bh ⁽²⁾	INTCON	GIE	PEIE	TMR0IE	INTE	RBIE	TMR0IF	INTF	RBIF	0000 000x	0000 000u
10Ch	PMDATL	Program Memory Read Data Register Low Byte								xxxx xxxx	uuuu uuuu
10Dh	PMADRL	Program Memory Read Address Register Low Byte								xxxx xxxx	uuuu uuuu
10Eh	PMDATH	—	—	Program Memory Read Data Register High Byte				--xx xxxx	--uu uuuu		
10Fh	PMADRH	—	—	—	Program Memory Read Address Register High Byte				---x xxxx	---u uuuu	
110h	TMRA	TimerA Module Register								0000 0000	0000 0000
111h	TBCON	TMRBON	—	TBCS	TBSE	TBPSA	TBPS2	TBPS1	TBPS0	0-00 0000	0-00 0000
112h	TMRB	TimerB Module Register								0000 0000	0000 0000
113h	DACCON0	DACEN	DACLPS	DACOE	—	DACPSS1	DACPSS0	—	—	000- 00--	000- 00--
114h	DACCON1	—	—	—	DACR4	DACR3	DACR2	DACR1	DACR0	---0 0000	---0 0000

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, read as '0', r = reserved.
Shaded locations are unimplemented, read as '0'.

- Note 1:** The upper byte of the program counter is not directly accessible. PCLATH is a holding register for the PC<12:8>, whose contents are transferred to the upper byte of the program counter.
- 2:** These registers can be addressed from any bank.
- 3:** Accessible only when SSPM<3:0> = 1001.

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TABLE 2-2: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
Bank 3											
180h ⁽²⁾	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx
181h	OPTION_REG	$\overline{\text{RBPU}}$	INTEDG	TMR0CS	TMR0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
182h ⁽²⁾	PCL	Program Counter (PC) Least Significant Byte								0000 0000	0000 0000
183h ⁽²⁾	STATUS	IRP	RP1	RP0	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC	C	0001 1xxx	000q quuu
184h ⁽²⁾	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	uuuu uuuu
185h	ANSELA	ANSA7	ANSA6	ANSA5	ANSA4	ANSA3	ANSA2	ANSA1	ANSA0	1111 1111	1111 1111
186h	ANSELB	ANSB7	ANSB6	ANSB5	ANSB4	ANSB3	ANSB2	ANSB1	ANSB0	1111 1111	1111 1111
187h	ANSELC	ANSC7	ANSC6	ANSC5	—	—	ANSC2	ANSC1	ANSC0	111- -111	111- -111
188h	ANSELD	ANSD7	ANSD6	ANSD5	ANSD4	ANSD3	ANSD2	ANSD1	ANSD0	1111 1111	1111 1111
189h	ANSELE	—	—	—	—	—	ANSE2	ANSE1	ANSE0	---- -111	---- -111
18Ah ^{(1),(2)}	PCLATH	—	—	—	Write Buffer for the upper 5 bits of the Program Counter				---0 0000	---0 0000	
18Bh ⁽²⁾	INTCON	GIE	PEIE	TMR0IE	INTE	RBIE	TMR0IF	INTF	RBIF	0000 000x	0000 000u
18Ch	PMCON1	—	—	—	—	—	—	—	RD	1---- ---0	1---- ---0
18Dh	—	Reserved								—	—
18Eh	—	Reserved								—	—
18Fh	—	Reserved								—	—

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, read as '0', r = reserved.
Shaded locations are unimplemented, read as '0'.

- Note 1:** The upper byte of the program counter is not directly accessible. PCLATH is a holding register for the PC<12:8>, whose contents are transferred to the upper byte of the program counter.
2: These registers can be addressed from any bank.
3: Accessible only when SSPM<3:0> = 1001.

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2.2.2.1 STATUS Register

The STATUS register, shown in [Register 2-1](#), contains:

- the arithmetic status of the ALU
- the Reset status
- the bank select bits for data memory (SRAM)

The STATUS register can be the destination for any instruction, like any other register. If the STATUS register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. These bits are set or cleared according to the device logic. Furthermore, the TO and PD bits are not writable. Therefore, the result of an instruction with the STATUS register as destination may be different than intended.

For example, `CLRF STATUS` will clear the upper three bits and set the Z bit. This leaves the STATUS register as '000u u1uu' (where u = unchanged).

It is recommended, therefore, that only `BCF`, `BSF`, `SWAPF` and `MOVWF` instructions are used to alter the STATUS register, because these instructions do not affect any Status bits. For other instructions not affecting any Status bits (Refer to [Section 23.0 "Instruction Set Summary"](#)).

Note 1: The C and DC bits operate as Borrow and Digit Borrow out bits, respectively, in subtraction.

REGISTER 2-1: STATUS: STATUS REGISTER

R/W-0	R/W-0	R/W-0	R-1	R-1	R/W-x	R/W-x	R/W-x
IRP	RP1	RP0	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC ⁽¹⁾	C ⁽¹⁾
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 7 **IRP:** Register Bank Select bit (used for indirect addressing)
 1 = Bank 2, 3 (100h-1FFh)
 0 = Bank 0, 1 (00h-FFh)
- bit 6-5 **RP<1:0>:** Register Bank Select bits (used for direct addressing)
 00 = Bank 0 (00h-7Fh)
 01 = Bank 1 (80h-FFh)
 10 = Bank 2 (100h-17Fh)
 11 = Bank 3 (180h-1FFh)
- bit 4 **$\overline{\text{TO}}$:** Time-out bit
 1 = After power-up, `CLRWDT` instruction or `SLEEP` instruction
 0 = A WDT time-out occurred
- bit 3 **$\overline{\text{PD}}$:** Power-down bit
 1 = After power-up or by the `CLRWDT` instruction
 0 = By execution of the `SLEEP` instruction
- bit 2 **Z:** Zero bit
 1 = The result of an arithmetic or logic operation is zero
 0 = The result of an arithmetic or logic operation is not zero
- bit 1 **DC:** Digit Carry/Digit Borrow bit (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions)⁽¹⁾
 1 = A carry-out from the 4th low-order bit of the result occurred
 0 = No carry-out from the 4th low-order bit of the result
- bit 0 **C:** Carry/Borrow bit⁽¹⁾ (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions)⁽¹⁾
 1 = A carry-out from the Most Significant bit of the result occurred
 0 = No carry-out from the Most Significant bit of the result occurred

Note 1: For Borrow, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand. For rotate (`RRF`, `RLF`) instructions, this bit is loaded with either the high-order or low-order bit of the source register.

2.2.2.2 OPTION Register

The OPTION register, shown in [Register 2-2](#), is a readable and writable register, which contains various control bits to configure:

- Timer0/WDT prescaler
- External RB0/INT interrupt
- Timer0
- Weak pull-ups on PORTB

Note: To achieve a 1:1 prescaler assignment for Timer0, assign the prescaler to the WDT by setting PSA bit of the OPTION register to '1'. Refer to [Section 13.3 “Timer1/3 Prescaler”](#).

REGISTER 2-2: OPTION_REG: OPTION REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
$\overline{\text{RBP}}\text{U}$	INTEDG	TMR0CS	TMR0SE	PSA	PS2	PS1	PS0
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 7 **$\overline{\text{RBP}}\text{U}$:** PORTB Pull-up Enable bit
 1 = PORTB pull-ups are disabled
 0 = PORTB pull-ups are enabled by individual bits in the WPUB register
- bit 6 **INTEDG:** Interrupt Edge Select bit
 1 = Interrupt on rising edge of RB0/INT pin
 0 = Interrupt on falling edge of RB0/INT pin
- bit 5 **TMR0CS:** Timer0 Clock Source Select bit
 1 = Transition on RA4/T0CKI pin
 0 = Internal instruction cycle clock (FOSC/4)
- bit 4 **TMR0SE:** Timer0 Source Edge Select bit
 1 = Increment on high-to-low transition on RA4/T0CKI pin
 0 = Increment on low-to-high transition on RA4/T0CKI pin
- bit 3 **PSA:** Prescaler Assignment bit
 1 = Prescaler is assigned to the WDT
 0 = Prescaler is assigned to the Timer0 module
- bit 2-0 **PS<2:0>:** Prescaler Rate Select bits

Bit Value	Timer0 Rate	WDT Rate
000	1 : 2	1 : 1
001	1 : 4	1 : 2
010	1 : 8	1 : 4
011	1 : 16	1 : 8
100	1 : 32	1 : 16
101	1 : 64	1 : 32
110	1 : 128	1 : 64
111	1 : 256	1 : 128

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2.2.2.3 PCON Register

The Power Control (PCON) register contains flag bits (refer to [Table 3-4](#)) to differentiate between a:

- Power-on Reset ($\overline{\text{POR}}$)
- Brown-out Reset ($\overline{\text{BOR}}$)

The PCON register bits are shown in [Register 2-3](#).

REGISTER 2-3: PCON: POWER CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/W-q	R/W-q
—	—	—	—	—	—	$\overline{\text{POR}}$	$\overline{\text{BOR}}$
bit 7						bit 0	

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

q = Value depends on condition

bit 7-2 **Unimplemented:** Read as '0'

bit 1 **POR:** Power-on Reset Status bit

1 = No Power-on Reset occurred

0 = A Power-on Reset occurred (must be set in software after a Power-on Reset occurs)

bit 0 **BOR:** Brown-out Reset Status bit

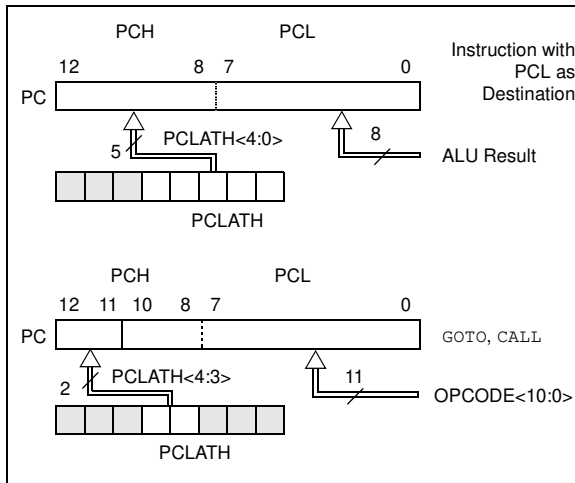
1 = No Brown-out Reset occurred

0 = A Brown-out Reset occurred (must be set in software after a Power-on Reset or Brown-out Reset occurs)

2.3 PCL and PCLATH

The Program Counter (PC) is 13 bits wide. The low byte comes from the PCL register, which is a readable and writable register. The high byte (PC<12:8>) is not directly readable or writable and comes from PCLATH. On any Reset, the PC is cleared. Figure 2-2 shows the two situations for the loading of the PC. The upper example in Figure 2-2 shows how the PC is loaded on a write to PCL (PCLATH<4:0> → PCH). The lower example in Figure 2-2 shows how the PC is loaded during a CALL or GOTO instruction (PCLATH<4:3> → PCH).

FIGURE 2-2: LOADING OF PC IN DIFFERENT SITUATIONS



2.3.1 COMPUTED GOTO

A computed GOTO is accomplished by adding an offset to the program counter (ADDWF PCL). When performing a table read using a computed GOTO method, care should be exercised if the table location crosses a PCL memory boundary (each 256-byte block). Refer to Application Note AN556, "Implementing a Table Read" (DS00556).

2.3.2 STACK

All devices have an 8-level x 13-bit wide hardware stack (refer to Figure 2-1). The stack space is not part of either program or data space and the Stack Pointer is not readable or writable. The PC is PUSHed onto the stack when a CALL instruction is executed or an interrupt causes a branch. The stack is POPed in the event of a RETURN, RETLW or a RETFIE instruction execution. PCLATH is not affected by a PUSH or POP operation.

The stack operates as a circular buffer. This means that after the stack has been PUSHed eight times, the ninth PUSH overwrites the value that was stored from the first PUSH. The tenth PUSH overwrites the second PUSH (and so on).

Note 1: There are no Status bits to indicate Stack Overflow or Stack Underflow conditions.

2: There are no instructions/mnemonics called PUSH or POP. These are actions that occur from the execution of the CALL, RETURN, RETLW and RETFIE instructions or the vectoring to an interrupt address.

2.4 Program Memory Paging

All devices are capable of addressing a continuous 8K word block of program memory. The CALL and GOTO instructions provide only 11 bits of address to allow branching within any 2K program memory page. When doing a CALL or GOTO instruction, the upper two bits of the address are provided by PCLATH<4:3>. When doing a CALL or GOTO instruction, the user must ensure that the page select bits are programmed so that the desired program memory page is addressed. If a return from a CALL instruction (or interrupt) is executed, the entire 13-bit PC is POPed off the stack. Therefore, manipulation of the PCLATH<4:3> bits is not required for the RETURN instructions (which POPs the address from the stack).

Note: The contents of the PCLATH register are unchanged after a RETURN or RETFIE instruction is executed. The user must rewrite the contents of the PCLATH register for any subsequent subroutine calls or GOTO instructions.

Example 2-1 shows the calling of a subroutine in page 1 of the program memory. This example assumes that PCLATH is saved and restored by the Interrupt Service Routine (if interrupts are used).

EXAMPLE 2-1: CALL OF A SUBROUTINE IN PAGE 1 FROM PAGE 0

```

ORG 500h
PAGESEL SUB_P1 ;Select page 1
                ; (800h-FFFh)
CALL SUB1_P1 ;Call subroutine in
:            ;page 1 (800h-FFFh)
:
ORG 900h ;page 1 (800h-FFFh)
SUB1_P1
:            ;called subroutine
                ;page 1 (800h-FFFh)
:
RETURN ;return to
                ;Call subroutine
                ;in page 0
                ; (000h-7FFh)
    
```