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R7M-A□, R7M-AP□

# SmartStep servo motors

## The smart alternative to stepper motors

- SmartStep motors can be controlled by SmartStep drive and XtraDrive
- Cylindrical and flat servo motor types are available
- Easy to setup, easy to operate. SmartStep is as easy to use as a stepper motor
- Front-panel switches in the SmartStep drive make settings easy and eliminate the need for time-consuming parameter settings
- Extended features and embedded in drive control can be provided using intelligent XtraDrive
- Models with brake available
- Easy to connect to the drive using prebuilt cables

## Ratings

- 230 VAC from 30 W to 750 W  
(0.095 Nm to 2.39 Nm)

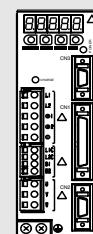


## System configuration

(Refer to servo drive chapter)

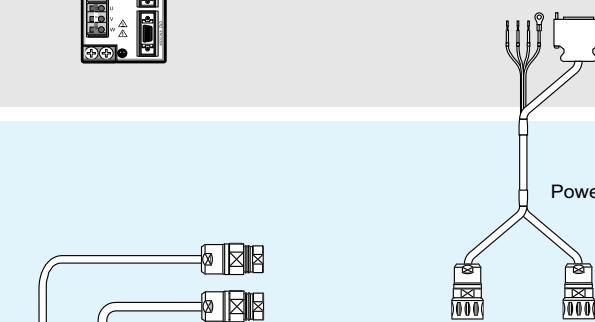


Servo Drive controlled by pulses  
SmartStep Servo Drive

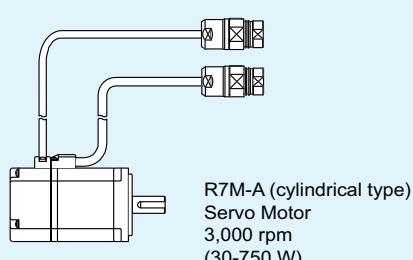


Intelligent Servo Drive  
XtraDrive

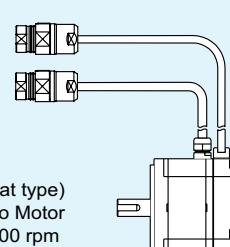
Drive options



Power and encoder cables



R7M-A (cylindrical type)  
Servo Motor  
3,000 rpm  
(30-750 W)



R7M-AP (flat type)  
Servo Motor  
3,000 rpm  
(100-750 W)

## Servo motor / servo drive combination

SmarStep servo motor					SmartStep servo drive	XtraDrive servo drive
	Voltage	Rated torque	Capacity	Model	230 V (1-phase)	230 V (1-phase)
	230 V	0.095 Nm	30 W	R7M-A03030-□	R7D-APA3H	XD-P3-MN01
		0.159 Nm	50 W	R7M-A05030-□	R7D-APA5H	XD-P5-MN01
		0.318 Nm	100 W	R7M-A10030-□	R7D-AP01H	XD-01-MN01
		0.637 Nm	200 W	R7M-A20030-□	R7D-AP02H	XD-02-MN01
		1.27 Nm	400 W	R7M-A40030-□	R7D-AP04H	XD-04-MN01
		2.39 Nm	750 W	R7M-A75030-□	R7D-AP08H	XD-08-MN
	230 V	0.318 Nm	100 W	R7M-AP10030-□	R7D-AP01H	XD-01-MN01
		0.637 Nm	200 W	R7M-AP20030-□	R7D-AP02H	XD-02-MN01
		1.27 Nm	400 W	R7M-AP40030-□	R7D-AP04H	XD-04-MN01
		2.39 Nm	750 W	R7M-AP75030-□	R7D-AP08H	XD-08-MN

**Note:** 1. For servo motor and cable part numbers, refer to ordering information at the end of this chapter.

2. Refer to the servo drive chapter for drive options selection and detailed specifications.

## Servo motor specifications

### General specifications

Item	Specification
Ambient operating temperature	0 to 40 °C
Ambient operating humidity	20% to 80% (with no condensation)
Ambient storage temperature	-20 to 60 °C
Ambient storage humidity	20% to 80% (with no condensation)
Storage/operating atmosphere	No corrosive gases.
Vibration resistance	10 to 2,500 Hz in X, Y, and Z directions with 0.2 mm double amplitude or acceleration of 24.5 m/s <sup>2</sup> max., whichever is smaller
Impact resistance	Acceleration 98 m/s <sup>2</sup> max., in a vertical direction, two times
Insulation resistance	Between power line terminals and FG: 10 MΩ min. (at 500 VDC)
Dielectric strength	Between power line terminals and FG: 1,500 VAC for 1 min at 50/60 Hz
Run position	Any direction
Insulation grade	Type B
Structure	Totally-enclosed self-cooling
Protective structure	IP55 for both the cylindrical and flat servo motors
Vibration grade	V-15
Mounting method	Flange-mounting
International standards	Approval obtained for UL, cUL, and EN (EMC directive and low-voltage directive)

### Performance specifications

#### Flat servo motors

Item	R7M-AP10030-□	R7M-AP20030-□	R7M-AP40030-□	R7M-AP75030-□	
Rated output	100 W	200 W	400 W	750 W	
Rated torque	0.318 N·m	0.637 N·m	1.27 N·m	2.39 N·m	
Rated rotation speed	3,000 r/min	3,000 r/min	3,000 r/min	3,000 r/min	
Momentary maximum rotation speed	4,500 r/min	4,500 r/min	4,500 r/min	4,500 r/min	
Momentary maximum torque	0.96 N·m	1.91 N·m	3.82 N·m	7.1 N·m	
Rated current	0.89 A (rms)	2.0 A (rms)	2.6 A (rms)	4.1 A (rms)	
Momentary maximum current	2.8 A (rms)	6.0 A (rms)	8.0 A (rms)	13.9 A (rms)	
Rotor inertia	$6.5 \times 10^{-6}$ kg·m <sup>2</sup>	$2.09 \times 10^{-5}$ kg·m <sup>2</sup>	$3.47 \times 10^{-5}$ kg·m <sup>2</sup>	$2.11 \times 10^{-4}$ kg·m <sup>2</sup>	
Power rate	15.7 kW/s	19.4 kW/s	46.8 kW/s	26.9 kW/s	
Allowable radial load	78 N	245 N	245 N	392 N	
Allowable thrust load	49 N	68 N	68 N	147 N	
Weight	Without brake With brake	0.7 kg 0.9 kg	1.4 kg 1.9 kg	2.1 kg 2.6 kg	4.2 kg 5.7 kg
Encoder resolution	2,000 pulses/revolution for phase-A and phase-B, 1 pulse/revolution for phase-Z				
Radiation shield dimensions	t6 × 250 mm square				t12 × 300 mm square
Brake specifications	Brake inertia	$3.1 \times 10^{-6}$ kg·m <sup>2</sup>	$1.52 \times 10^{-5}$ kg·m <sup>2</sup>	$1.52 \times 10^{-5}$ kg·m <sup>2</sup>	$8.75 \times 10^{-5}$ kg·m <sup>2</sup>
	Excitation voltage	24 VDC ±10%			
	Power consumption (at 20 °C)	7.5 W	7.6 W	8.2 W	7.5 W
	Current consumption (at 20 °C)	0.31 A	0.32 A	0.34 A	0.31 A
	Static friction torque	0.4 N·m min.	0.9 N·m min.	1.9 N·m min.	3.5 N·m min.
	Attraction time	60 ms max.	40 ms max.	60 ms max.	20 ms max.
	Release time	20 ms max.	20 ms max.	20 ms max.	40 ms max.
	Backlash	1°	1°	1°	1°
	Rating	Continuous	Continuous	Continuous	Continuous
Applicable servo driver (R7D-)	AP01H	AP02H	AP04H	AP08H	

## Cylindrical servo motors

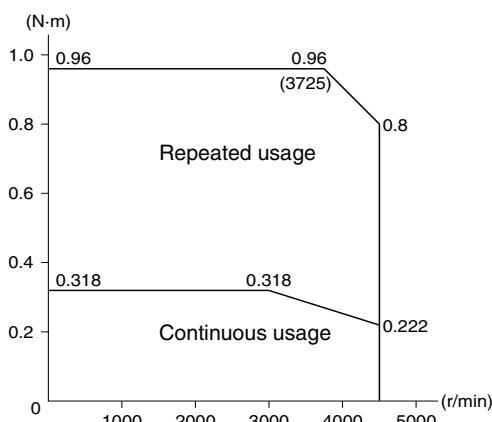
Item	R7M-A03030-□	R7M-A05030-□	R7M-A10030-□	R7M-A20030-□	R7M-A40030-□	R7M-A75030-□
Rated output	30 W	50 W	100 W	200 W	400 W	750 W
Rated torque	0.095 N·m	0.159 N·m	0.318 N·m	0.637 N·m	1.27 N·m	2.39 N·m
Rated rotation speed	3,000 r/min	3,000 r/min	3,000 r/min	3,000 r/min	3,000 r/min	3,000 r/min
Momentary maximum rotation speed	4,500 r/min	4,500 r/min	4,500 r/min	4,500 r/min	4,500 r/min	4,500 r/min
Momentary maximum torque	0.29 N·m	0.48 N·m	0.96 N·m	1.91 N·m	3.82 N·m	7.1 N·m
Rated current	0.42 A (rms)	0.6 A (rms)	0.87 A (rms)	2.0 A (rms)	2.6 A (rms)	4.4 A (rms)
Momentary maximum current	1.3 A (rms)	1.9 A (rms)	2.8 A (rms)	6.0 A (rms)	8.0 A (rms)	13.9 A (rms)
Rotor inertia	$1.7 \times 10^{-6}$ kg·m <sup>2</sup>	$2.2 \times 10^{-6}$ kg·m <sup>2</sup>	$3.6 \times 10^{-6}$ kg·m <sup>2</sup>	$1.19 \times 10^{-5}$ kg·m <sup>2</sup>	$1.87 \times 10^{-5}$ kg·m <sup>2</sup>	$6.67 \times 10^{-5}$ kg·m <sup>2</sup>
Power rate	5.31 kW/s	11.5 kW/s	28.1 kW/s	34.1 kW/s	86.3 kW/s	85.6 kW/s
Allowable radial load	68 N	68 N	78 N	245 N	245 N	392 N
Allowable thrust load	54 N	54 N	54 N	74 N	74 N	147 N
Weight	Without brake 0.3 kg With brake 0.6 kg	0.4 kg	0.5 kg	1.1 kg	1.7 kg	3.4 kg
Encoder resolution	2,000 pulses/revolution for phase-A and phase-B, 1 pulse/revolution for phase-Z					
Radiation shield dimensions	t6 × 250 mm square					
Brake specifications	Brake inertia $0.85 \times 10^{-6}$ kg·m <sup>2</sup> Excitation voltage 24 VDC ±10% V	$0.85 \times 10^{-6}$ kg·m <sup>2</sup>	$0.85 \times 10^{-6}$ kg·m <sup>2</sup>	$0.85 \times 10^{-6}$ kg·m <sup>2</sup>	$6.4 \times 10^{-6}$ kg·m <sup>2</sup>	$6.4 \times 10^{-6}$ kg·m <sup>2</sup>
	Power consumption (at 20 °C) 0.25 A	6 W	6 W	7 W	7 W	7.7 W
	Current consumption (at 20 °C) 0.2 N·m min.	0.25 A	0.25 A	0.29 A	0.29 A	0.32 A
	Attraction time 30 ms max.	0.2 N·m min.	0.34 N·m min.	1.47 N·m min.	1.47 N·m min.	2.45 N·m min.
	Release time 60 ms max.	30 ms max.	30 ms max.	60 ms max.	60 ms max.	60 ms max.
	Backlash 1°	60 ms max.	60 ms max.	20 ms max.	20 ms max.	20 ms max.
	Rating Continuous	Continuous	Continuous	Continuous	Continuous	Continuous
	Insulation grade Type F	Type F	Type F	Type F	Type F	Type F
Applicable servo driver (R7D-)	APA3H	APA5H	AP01H	AP02H	AP04H	AP08H

## Torque and rotation speed characteristics

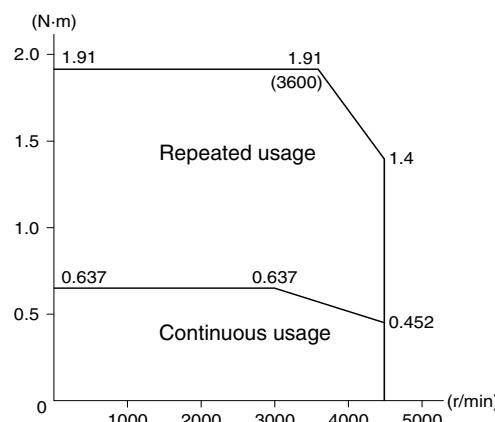
### Flat servo motors

The following graphs show the characteristics with a 3 m standard cable and R7D-AP□H servo driver (200 VAC input)

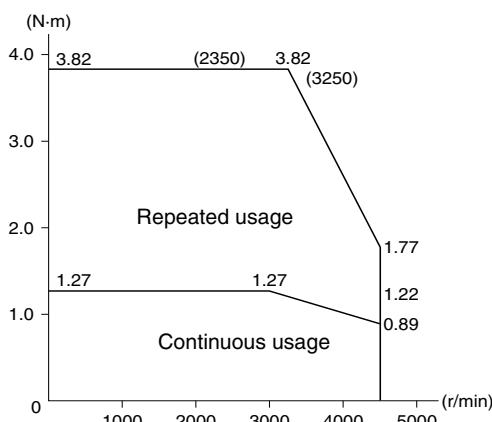
**R7M-AP10030 (100 W)**



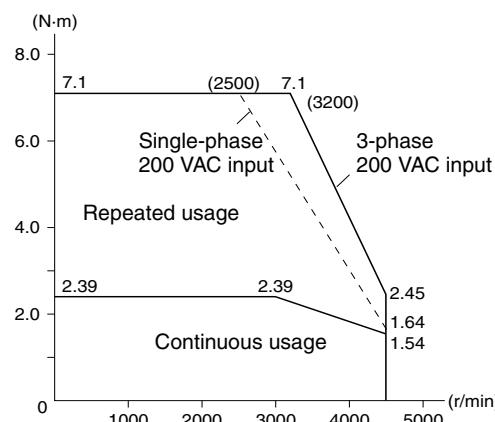
**R7M-AP20030 (200 W)**



**R7M-AP40030 (400 W)**

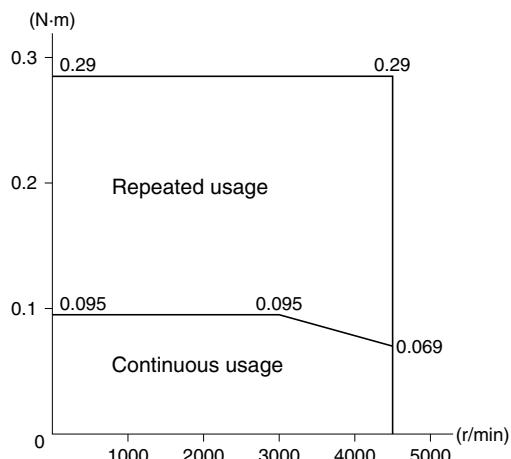
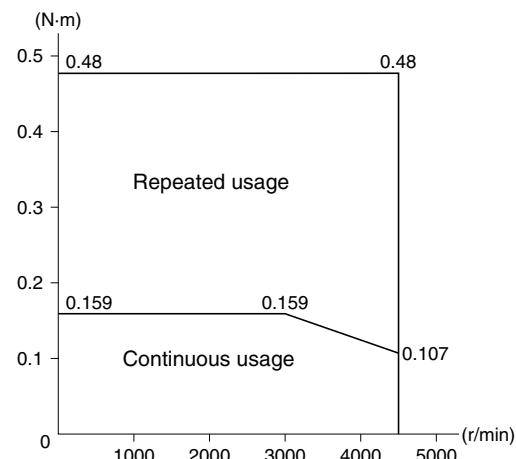
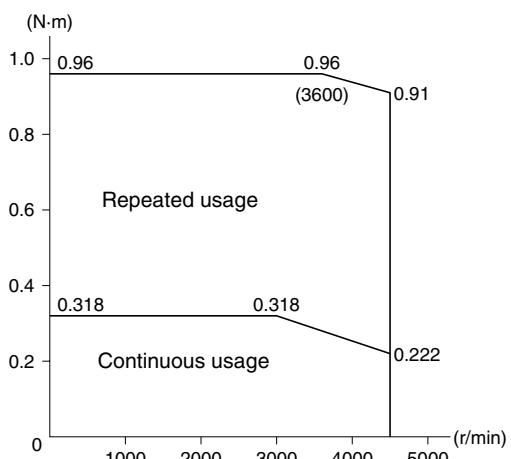
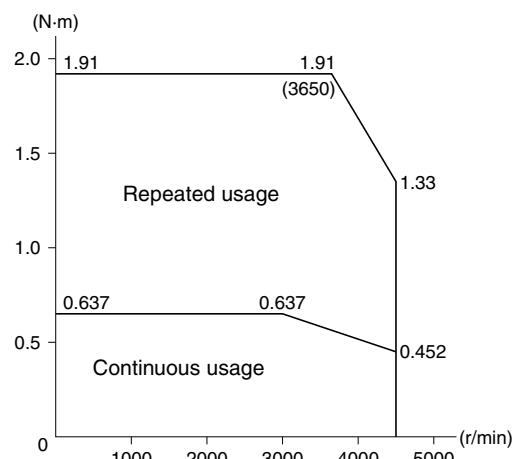
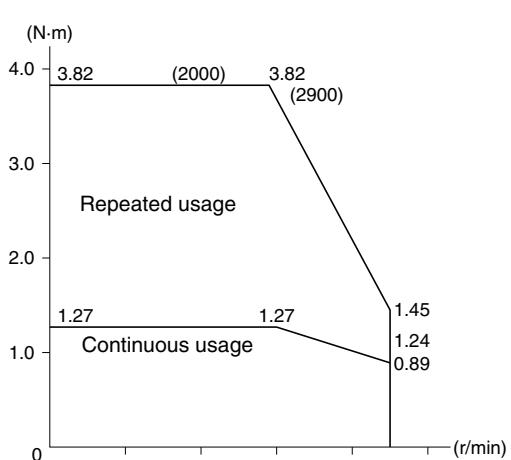
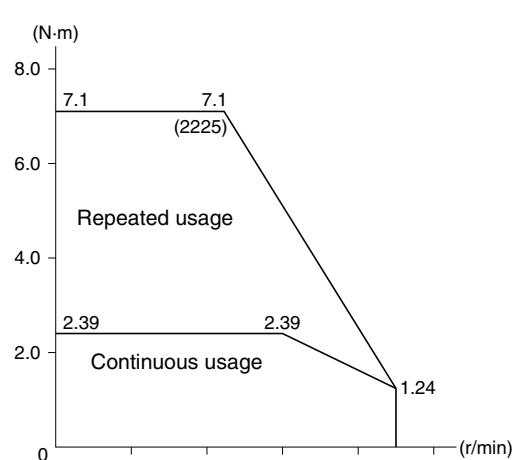


**R7M-AP75030 (750 W)**



**Torque and rotation speed characteristics****Cylindrical servo motors**

The following graphs show the characteristics with a 3 m standard cable and an R7D-AP□H servo driver (200 VAC input.)

**R7M-A03030 (30 W)****R7M-A05030 (50 W)****R7M-A10030 (100 W)****R7M-A20030 (200 W)****R7M-A40030 (400 W)****R7M-A75030 (750 W)**

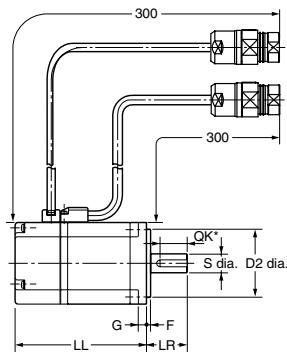
## Dimensions

**Cylindrical servo motors (3,000 r/min)**  
200 VAC: 30W/50W/100W/200W/400W/750W

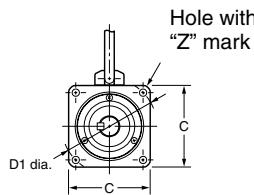
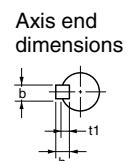
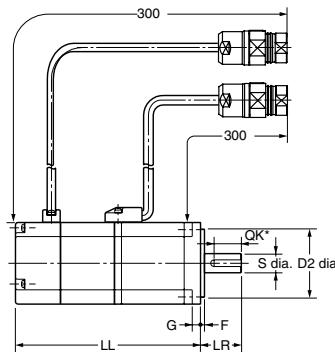
Without brake: R7M-A03030-S1-D/A05030-S1-D/A10030-S1-D/A20030-S1-D/A40030-S1-D/A75030-S1-D  
With brake: R7M-A03030-BS1-D/A05030-BS1-D/A10030-BS1-D/A20030-BS1-D/A40030-BS1-D/A75030-BS1-D

Model	Dimensions (mm)													
	LL		LR	Flange surface						Axis end				
	Without brake	With brake		C	D1	D2	F	G	Z	S	QK	b	h	t1
R7M-A03030□	69.5	101	25	40	46	30h7	2.5	5	Two, 4.3 dia.	6h6	14	2	2	1.2
R7M-A05030□	77	108.5							8h6			3	3	1.8
R7M-A10030□	94.5	135												
R7M-A20030□	96.5	136	30	60	70	50h7	3	6	Four, 5.5 dia.	14h6	20	5	5	3
R7M-A40030□	124.5	164												
R7M-A75030□	145	189.5	40	80	90	70h7	3	8	Four, 7 dia.	16h6	30			

R7M-A□□□30-S1-D (Without brake)



R7M-A□□□30-BS1-D (With brake)

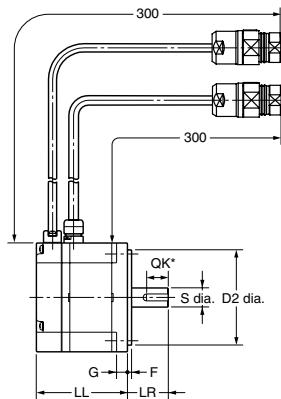


**Flat servo motors (3,000 r/min)**  
200 VAC: 100W/200W/400W/750W

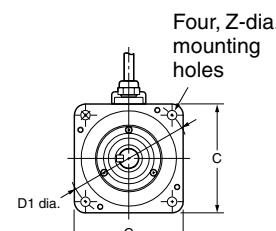
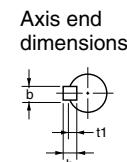
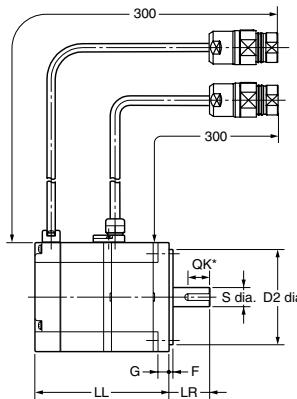
Without brake: R7M-AP10030-S1-D/AP20030-S1-D/AP40030-S1-D/AP75030-S1-D  
With brake: R7M-AP10030-BS1-D/AP20030-BS1-D/AP40030-BS1-D/AP75030-BS1-D

Model	Dimensions (mm)													
	LL		LR	Flange surface						Axis End				
	Without brake	With brake		C	D1	D2	F	G	Z	S	QK	b	h	t1
R7M-AP10030□	62	91	25	60	70	50h7	3	6	5.5	8h6	14	3	3	1.8
R7M-AP20030□	67	98.5	30	80	90	70h7	3	8	7	14h6	16	5	5	3
R7M-AP40030□	87	118.5												
R7M-AP75030□	86.5	120	40	120	145	110h7	3.5	10	10	16h6	22			

R7M-AP□□□30-S1-D (Without brake)



R7M-AP□□□30-BS1-D (With brake)



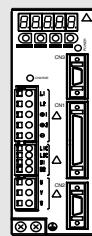
## Ordering information

(Refer to servo drive chapter)



Servo Drive controlled by pulses

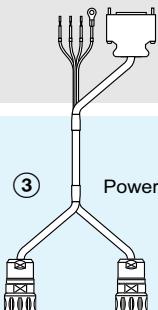
② SmartStep Servo Drive



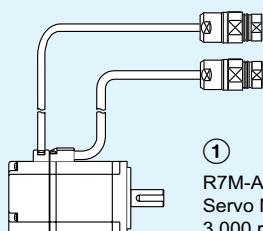
Intelligent Servo Drive

② XtraDrive

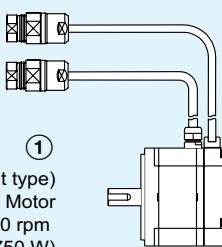
Drive options



Power and encoder cables



① R7M-A (cylindrical type)  
Servo Motor  
3,000 rpm  
(30-750 W)



① R7M-AP (flat type)  
Servo Motor  
3,000 rpm  
(100-750 W)

**Note:** The symbols ①②③... show the recommended sequence to select the servo motor and cables.

### Servo motor

#### Cylindrical servo motors (3,000-r/min)

Symbol	Specifications			Servo motor model	Compatible servo drives ②		
	Design	Rated torque	Capacity		SmartStep	XtraDrive	
①	Cylindrical servo motors (3,000-r/min)	Without brake	0.095 Nm	30 W	R7M-A03030-S1-D	R7D-APA3H	XD-P3-MN01
			0.159 Nm	50 W	R7M-A05030-S1-D	R7D-APA5H	XD-P5-MN01
			0.318 Nm	100 W	R7M-A10030-S1-D	R7D-AP01H	XD-01-MN01
			0.637 Nm	200 W	R7M-A20030-S1-D	R7D-AP02H	XD-02-MN01
			1.27 Nm	400 W	R7M-A40030-S1-D	R7D-AP04H	XD-04-MN01
			2.39 Nm	750 W	R7M-A75030-S1-D	R7D-AP08H	XD-08-MN
	Straight shaft with key	With brake	0.095 Nm	30 W	R7M-A03030-BS1-D	R7D-APA3H	XD-P3-MN01
			0.159 Nm	50 W	R7M-A05030-BS1-D	R7D-APA5H	XD-P5-MN01
			0.318 Nm	100 W	R7M-A10030-BS1-D	R7D-AP01H	XD-01-MN01
			0.637 Nm	200 W	R7M-A20030-BS1-D	R7D-AP02H	XD-02-MN01
			1.27 Nm	400 W	R7M-A40030-BS1-D	R7D-AP04H	XD-04-MN01
			2.39 Nm	750 W	R7M-A75030-BS1-D	R7D-AP08H	XD-08-MN

#### Flat servo motors (3,000-r/min)

Symbol	Specifications			Servo motor model	Compatible servo drives ②		
	Design	Rated torque	Capacity		SmartStep	XtraDrive	
①	Flat servo motors (3,000-r/min)	Without brake	0.318 Nm	100 W	R7M-AP10030-S1-D	R7D-AP01H	XD-01-MN01
			0.637 Nm	200 W	R7M-AP20030-S1-D	R7D-AP02H	XD-02-MN01
			1.27 Nm	400 W	R7M-AP40030-S1-D	R7D-AP04H	XD-04-MN01
			2.39 Nm	750 W	R7M-AP75030-S1-D	R7D-AP08H	XD-08-MN
			0.318 Nm	100 W	R7M-AP10030-BS1-D	R7D-AP01H	XD-01-MN01
			0.637 Nm	200 W	R7M-AP20030-BS1-D	R7D-AP02H	XD-02-MN01
	Straight shaft with key	With brake	1.27 Nm	400 W	R7M-AP40030-BS1-D	R7D-AP04H	XD-04-MN01
			2.39 Nm	750 W	R7M-AP75030-BS1-D	R7D-AP08H	XD-08-MN
			0.318 Nm	100 W	R7M-AP10030-BS1-D	R7D-AP01H	XD-01-MN01
			0.637 Nm	200 W	R7M-AP20030-BS1-D	R7D-AP02H	XD-02-MN01
			1.27 Nm	400 W	R7M-AP40030-BS1-D	R7D-AP04H	XD-04-MN01
			2.39 Nm	750 W	R7M-AP75030-BS1-D	R7D-AP08H	XD-08-MN

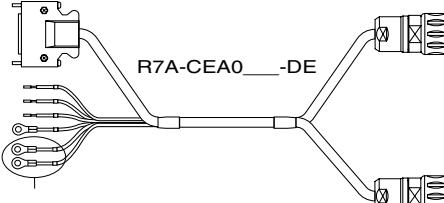
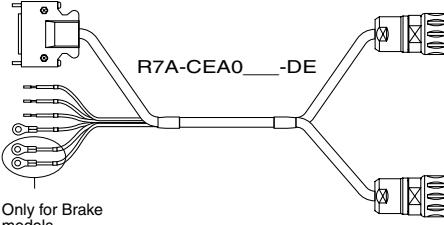
### Servo drive

**Note:** Choosing SmartStep drive or XtraDrive affects to the encoder cable needed.

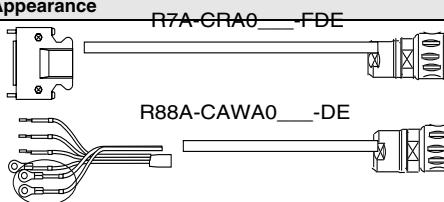
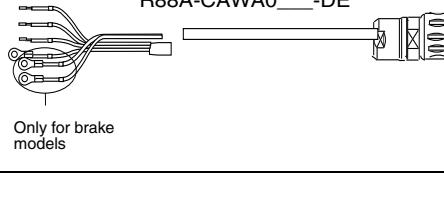
② Refer to SmartStep servo drive or XtraDrive chapter for detailed drive specifications and selection of drive accessories.

## Servo motor cables for SmartStep drive

### Standard cable (power + encoder)

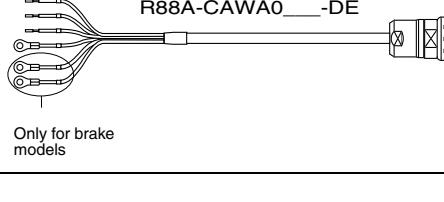
Symbol	Drive	Specifications	Power cable model	Encoder cable model	Appearance
(3)	SmartStep	For servo motors without brake R7M-A(P)□□□30-S1-D	3 m	R7A-CEA003S-DE	
			5 m	R7A-CEA005S-DE	
			10 m	R7A-CEA010S-DE	
			15 m	R7A-CEA015S-DE	
			20 m	R7A-CEA020S-DE	
		For servo motors with brake R7M-A(P)□□□30-BS1-D	3 m	R7A-CEA003B-DE	
			5 m	R7A-CEA005B-DE	
			10 m	R7A-CEA010B-DE	
			15 m	R7A-CEA015B-DE	
			20 m	R7A-CEA020B-DE	

### Flexible cables (power + encoder)

Symbol	Drive	Specifications	Power cable model	Encoder cable model	Appearance
(3)	SmartStep	For servo motors without brake R7M-A(P)□□□30-S1-D	3 m	R88A-CAWA003S-DE	
			5 m	R88A-CAWA005S-DE	
			10 m	R88A-CAWA010S-DE	
			15 m	R88A-CAWA015S-DE	
			20 m	R88A-CAWA020S-DE	
		For servo motors with brake R7M-A(P)□□□30-BS1-D	3 m	R88A-CAWA003B-DE	
			5 m	R88A-CAWA005B-DE	
			10 m	R88A-CAWA010B-DE	
			15 m	R88A-CAWA015B-DE	
			20 m	R88A-CAWA020B-DE	

## Servo motor cables for XtraDrive Drive

### Flexible cables (power + encoder)

Symbol	Drive	Specifications	Power cable model	Encoder cable model	Appearance
(3)	XtraDrive	For servo motors without brake R7M-A(P)□□□30-S1-D	3 m	R88A-CAWA003S-DE	
			5 m	R88A-CAWA005S-DE	
			10 m	R88A-CAWA010S-DE	
			15 m	R88A-CAWA015S-DE	
			20 m	R88A-CAWA020S-DE	
		For servo motors with brake R7M-A(P)□□□30-BS1-D	3 m	R88A-CAWA003B-DE	
			5 m	R88A-CAWA005B-DE	
			10 m	R88A-CAWA010B-DE	
			15 m	R88A-CAWA015B-DE	
			20 m	R88A-CAWA020B-DE	

## Connectors

Specifications	Model
SmartStep connectors kit	R7A-CNA00K-DE
SmartStep encoder connector (for CN2)	
Hypertac power connector female	
Hypertac encoder connector female	
Hypertac power connector male (used in the motor)	SRUC-06J-MSCN236
Hypertac encoder connector male (used in the motor)	SRUC-17G-MRWN087

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.  
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.