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SC1186

## Programmable Synchronous DC/DC

Converter, Dual LDO Controller

## POWER MANAGEMENT

## Description

The SC1186 combines a synchronous voltage mode controller with two low-dropout linear regulators providing most of the circuitry necessary to implement three DC/DC converters for powering advanced microprocessors such as Pentium ${ }^{\circledR}$ II \& III.

The SC1186 switching section features an integrated 5 bit D/A converter, latched drive output for enhanced noise immunity, pulse by pulse current limiting and logic compatible shutdown. The SC1186 switching section operates at a fixed frequency of 140 kHz , providing an optimum compromise between size, efficiency and cost in the intended application areas. The integrated D/A converter provides programmability of output voltage from 2.0 V to 3.5 V in 100 mV increments and 1.30 V to 2.05 V in 50 mV increments with no external components.

The SC1186 linear sections are low dropout regulators with short circuit protection, supplying 1.5 V for GTL bus and 2.5 V for non-GTL I/O. The Reference voltage is made available for external linear regulators.

## Features

- Synchronous design, enables no heatsink solution
- $95 \%$ efficiency (switching section)
- 5 bit DAC for output programmability
- Designed for Intel Pentium ${ }^{\circledR}$ II \& III requirements
- $1.5 \mathrm{~V}, 2.5 \mathrm{~V}$ short circuit protected linear controllers
- $1.265 \mathrm{~V} \pm 1.5 \%$ Reference available


## Applications

- Pentium ${ }^{\circledR}$ II \& III microprocessor supplies
- Flexible motherboards
- 1.3 V to 3.5 V microprocessor supplies
- Programmable triple power supplies


## Typical Application Circuit



## POWER MANAGEMENT

Absolute Maximum Ratings
Exceeding the specifications below may result in permanent damage to the device, or device malfunction. Operation outside of the parameters specified in the Electrical Characteristics section is not implied. Exposure to Absolute Maximum rated conditions for extended periods of time may affect device reliability.

| Parameter | Symbol | Maximum | Units |
| :--- | :---: | :---: | :---: |
| VCC to AGND | $\mathrm{V}_{\text {IN }}$ | -0.3 to +7 | V |
| PGNDH, PGNDL to AGND |  | $\pm 1$ | V |
| BSTH to PGNDH, BSTL to PGNDL |  | -0.3 to +15 | V |
| DH to PGNDH, DL to PGNDL (Note2) |  | -1 to +15 | V |
| Operating Temperature Range | $\mathrm{T}_{\mathrm{A}}$ | 0 to +70 | ${ }^{\circ} \mathrm{C}$ |
| Junction Temperature Range | $\mathrm{T}_{\mathrm{J}}$ | 0 to +125 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $\mathrm{T}_{\text {STG }}$ | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering) 10 Sec. | $\mathrm{T}_{\text {LEAD }}$ | 300 | ${ }^{\circ} \mathrm{C}$ |
| Thermal Resistance Junction to Ambient | $\theta_{\text {JA }}$ | 80 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Thermal Impedance Junction to Case | $\theta_{\mathrm{JC}}$ | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |  |

## Electrical Characteristics

Unless specified: VCC $=4.75 \mathrm{~V}$ to 5.25 V ; GND $=\mathrm{PGND}=0 \mathrm{~V}$; VOSENSE $=\mathrm{V}_{\mathrm{O}} ; 0 \mathrm{mV}<(\mathrm{CS}+-\mathrm{CS}-)<60 \mathrm{mV}$; LDOV $=\mathrm{BST}=11.4 \mathrm{~V}$ to 12.6 V ; $\mathrm{T}_{\mathrm{A}}=0$ to $70^{\circ} \mathrm{C}$

| Parameter | Conditions | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Switching Section |  |  |  |  |  |
| Output Voltage | $\mathrm{I}_{0}=2 \mathrm{~A}$ in Application Circuit | See Output Voltage Table |  |  |  |
| Supply Voltage | VCC | 4.5 |  | 7 | V |
| Supply Current | $\mathrm{VCC}=5.0 \mathrm{~V}$ |  | 8 | 15 | mA |
| Load Regulation | $\mathrm{I}_{0}=0.8 \mathrm{~A}$ to 15 A |  | 1 |  | \% |
| Line Regulation |  |  | $\pm 0.5$ |  | \% |
| Current Limit Voltage |  | 60 | 70 | 85 | mV |
| Oscillator Frequency |  | 120 | 140 | 160 | kHz |
| Oscillator Max Duty Cycle |  | 90 | 95 |  | \% |
| Peak DH Sink/Source Current | $\begin{array}{r} \mathrm{BSTH}-\mathrm{DH}=4.5 \mathrm{~V}, \mathrm{DH}-\mathrm{PGNDH}=3.3 \mathrm{~V} \\ \mathrm{DH}-\mathrm{PGNDH}=1.5 \mathrm{~V} \end{array}$ | $\begin{gathered} 1 \\ 100 \end{gathered}$ |  |  | $\begin{gathered} \mathrm{A} \\ \mathrm{~mA} \end{gathered}$ |
| Peak DL Sink/Source Current | $\begin{array}{rr} \text { BSTL }-\mathrm{DL}=4.5 \mathrm{~V}, & \mathrm{DL}-\mathrm{PGNDL}=3.3 \mathrm{~V} \\ \mathrm{DL}-\mathrm{PGNDH}=1.5 \mathrm{~V} \end{array}$ | $\begin{gathered} 1 \\ 100 \end{gathered}$ |  |  | $\begin{gathered} \mathrm{A} \\ \mathrm{~mA} \end{gathered}$ |
| Gain ( $\mathrm{A}_{\mathrm{OL}}$ ) | VOSENSE to $\mathrm{V}_{\text {。 }}$ |  | 35 |  | dB |
| VID Source Current | VIDx $<2.4 \mathrm{~V}$ | 1 | 10 |  | uA |
| VID Leakage | $\mathrm{VIDx}=5 \mathrm{~V}$ |  |  | 10 | uA |
| Power good threshold voltage |  | 88 |  | 112 | \% |
| Dead Time |  | 40 | 100 |  | ns |

POWER MANAGEMENT
Electrical Characteristics (Cont.)
Unless specified: $\mathrm{VCC}=4.75 \mathrm{~V}$ to $5.25 \mathrm{~V} ; \mathrm{GND}=\mathrm{PGND}=0 \mathrm{~V}$; VOSENSE $=\mathrm{V}_{\mathrm{O}} ; 0 \mathrm{mV}<(\mathrm{CS}+-\mathrm{CS}-)<60 \mathrm{mV} ; \mathrm{LDOV}=\mathrm{BST}=11.4 \mathrm{~V}$ to $12.6 \mathrm{~V} ; \mathrm{T}_{\mathrm{A}}=0$ to $70^{\circ} \mathrm{C}$

| Parameter | Conditions | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Linear Sections |  |  |  |  |  |
| Quiescent Current | LDOV $=12 \mathrm{~V}$ |  |  | 5 | mA |
| Output Voltage LDO1 |  | 2.493 | 2.525 | 2.556 | V |
| Output Voltage LDO2 |  | 1.496 | 1.515 | 1.534 | V |
| Reference Voltage | Iref $<100 \mathrm{uA}$ | 1.246 | 1.265 | 1.284 | V |
| Gain ( $\mathrm{A}_{\mathrm{oL}}$ ) | $\operatorname{LDOS}(1,2)$ to GATE $(1,2)$ |  | 90 |  | dB |
| Load Regulation | $\mathrm{I}_{0}=0$ to 8 A |  |  | 0.3 | \% |
| Line Regulation |  |  |  | 0.3 | \% |
| Output Impedance | VGATE $=6.5 \mathrm{~V}$ |  | 1 | 1.5 | k $\Omega$ |
| LDOV Undervoltage Lockout |  | 6.5 | 8.0 | 10 | V |
| LDOEN Threshold |  | 1.3 |  | 1.9 | $\checkmark$ |
| LDOEN Sink Current | $\begin{gathered} \text { LDOEN }=3.3 \mathrm{~V} \\ \text { LDOEN }=0 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 0.01 \\ -200 \end{gathered}$ | $\begin{gathered} 1.0 \\ -300 \end{gathered}$ | $\begin{aligned} & \mu \mathrm{A} \\ & \mu \mathrm{~A} \end{aligned}$ |
| Overcurrent Trip Voltage | \% of Vo set point | 20 | 40 | 60 | \% |
| Power-up Output Short Circuit Immunity |  | 1 | 5 | 60 | ms |
| Output Short Circuit Glitch Immunity |  | 0.5 | 4 | 20 | ms |
| Gate Pulldown Impedance | GATE $(1,2)$-AGND; $\mathrm{VCC}+\mathrm{BST}=0 \mathrm{~V}$ | 80 | 300 | 750 | k $\Omega$ |
| VOSENSE Impedance |  | 10 |  |  | k $\Omega$ |

## Note:

(1) This device is ESD sensitive. Use of standard ESD handling precautions is required.
(2) See Gate Resistor Selection recomendations.

POWER MANAGEMENT
Pin Configuration

|  | TOP VIEW |  |
| :---: | :---: | :---: |
| AGND $\square$ | 24 | $\square$ GATE2 |
| GATE1 $\square$ | 23 | $\square$ LDOV |
| LDOS1 $\square$ | 22 | $\square$ VIDO |
| LDOS2 $\square$ | 421 | $\square$ VID1 |
| VCC $\square$ | 20 | $\square$ VID2 |
| REF $\square$ | 19 | $\square$ VID3 |
| LDOEN $\square$ | 18 | $\square$ VID4 |
| CS- $\square$ | $8 \quad 17$ | $\square$ VOSENSE |
| CS+ $\square$ | 16 | $\square \mathrm{EN}$ |
| PGNDH $\square$ | $10 \quad 15$ | $\square$ BSTH |
| DH $\square$ | $11 \quad 14$ | $\square \mathrm{BSTL}$ |
| PGNDL $\square$ | 1213 | $\square \mathrm{DL}$ |
|  | (24 Pin SOIC) |  |

## Ordering Information

| Device ${ }^{(1)}$ | Package $^{(1)}$ | Linear <br> Voltage | Temp <br> Range $\left(T_{J}\right)$ |
| :---: | :---: | :---: | :---: |
| SC1186CSW.TR | SO-24 | $1.5 \mathrm{~V} / 2.5 \mathrm{~V}$ | $0^{\circ}$ to $125^{\circ} \mathrm{C}$ |
| SC1186CSWTRT ${ }^{(2)}$ |  |  |  |

Notes:
(1) Only available in tape and reel packaging. A reel contains 1000 devices.
(2) Lead free product. This product is fully WEEE and RoHS compliant.

## Pin Descriptions

| Pin \# | Pin Name |  |
| :---: | :---: | :--- |
| 1 | AGND | Small Signal Analog and Digital Ground |
| 2 | GATE1 | Gate Drive Output LDO1 |
| 3 | LDOS1 | Sense Input for LDO1 |
| 4 | LDOS2 | Sense Input for LDO2 |
| 5 | VCC | Input Voltage |
| 6 | REF | Buffered Reference Voltage output |
| 7 | LDOEN | LDO Supply Monitor. |
| 8 | CS- | Current Sense Input (negative) |
| 9 | CS+ | Current Sense Input (positive) |
| 10 | PGNDH | Power Ground for High Side Switch |
| 11 | DH | High Side Driver Output |
| 12 | PGNDL | Power Ground for Low Side Switch |
| 13 | DL | Low Side Driver Output |
| 14 | BSTL | Supply for Low Side Driver |
| 15 | BSTH | Supply for High Side Driver |
| 16 | EN ${ }^{(1)}$ | Logic low shuts down the converter, High or open for normal operation |
| 17 | VOSENSE | Top end of internal feedback chain. |
| 18 | VID4 ${ }^{(1)}$ | Programming Input (MSB) |
| 19 | VID3 ${ }^{(1)}$ | Programming Input |
| 20 | VID2 ${ }^{(1)}$ | Programming Input |
| 21 | VID1 ${ }^{(1)}$ | Programming Input |
| 22 | VID0 ${ }^{(1)}$ | Programming Input (LSB) |
| 23 | LDOV | +12V for LDO section |
| 24 | GATE2 | Gate Drive Output LDO2 |

Note:
(1) All logic level inputs and outputs are open collector TTL compatible.


POWER MANAGEMENT
Applications Information - Output Voltage Table
Unless specified: $4.75 \mathrm{~V}<\mathrm{VCC}<5.25 \mathrm{~V}$; GND $=$ PGND $=0 \mathrm{~V}$; VOSENSE $=\mathrm{V}_{\mathrm{o}} ; 0 \mathrm{mV}<(\mathrm{CS}+-\mathrm{CS}-)<60 \mathrm{mV} ;=0^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{j}}<85^{\circ} \mathrm{C}$

| Parameter | Conditions | $\begin{gathered} \text { Vid } \\ 43210 \end{gathered}$ | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Output Voltage ${ }^{(1)}$ | $\mathrm{I}_{\mathrm{O}}=2 \mathrm{~A}$ in Application circuit (Figure 1) | 01111 | 1.277 | 1.300 | 1.323 | V |
|  |  | 01110 | 1.326 | 1.350 | 1.374 |  |
|  |  | 01101 | 1.375 | 1.400 | 1.425 |  |
|  |  | 01100 | 1.424 | 1.450 | 1.476 |  |
|  |  | 01011 | 1.478 | 1.500 | 1.523 |  |
|  |  | 01010 | 1.527 | 1.550 | 1.573 |  |
|  |  | 01001 | 1.576 | 1.600 | 1.624 |  |
|  |  | 01000 | 1.625 | 1.650 | 1.675 |  |
|  |  | 00111 | 1.675 | 1.700 | 1.726 |  |
|  |  | 00110 | 1.724 | 1.750 | 1.776 |  |
|  |  | 00101 | 1.782 | 1.800 | 1.818 |  |
|  |  | 00100 | 1.832 | 1.850 | 1.869 |  |
|  |  | 00011 | 1.881 | 1.900 | 1.919 |  |
|  |  | 00010 | 1.931 | 1.950 | 1.970 |  |
|  |  | 00001 | 1.980 | 2.000 | 2.020 |  |
|  |  | 00000 | 2.030 | 2.050 | 2.071 |  |
|  |  | 11111 | 1.970 | 2.000 | 2.030 |  |
|  |  | 11110 | 2.069 | 2.100 | 2.132 |  |
|  |  | 11101 | 2.167 | 2.200 | 2.233 |  |
|  |  | 11100 | 2.266 | 2.300 | 2.335 |  |
|  |  | 11011 | 2.364 | 2.400 | 2.436 |  |
|  |  | 11010 | 2.463 | 2.500 | 2.538 |  |
|  |  | 11001 | 2.561 | 2.600 | 2.639 |  |
|  |  | 11000 | 2.660 | 2.700 | 2.741 |  |
|  |  | 10111 | 2.758 | 2.800 | 2.842 |  |
|  |  | 10110 | 2.842 | 2.900 | 2.958 |  |
|  |  | 10101 | 2.940 | 3.000 | 3.060 |  |
|  |  | 10100 | 3.038 | 3.100 | 3.162 |  |
|  |  | 10011 | 3.136 | 3.200 | 3.264 |  |
|  |  | 10010 | 3.234 | 3.300 | 3.366 |  |
|  |  | 10001 | 3.332 | 3.400 | 3.468 |  |
|  |  | 10000 | 3.430 | 3.500 | 3.570 |  |

## Layout Guidelines

Careful attention to layout requirements are necessary for successful implementation of the SC1186 PWM controller. High currents switching at 140 kHz are present in the application and their effect on ground plane voltage differentials must be understood and minimized.
1). The high power parts of the circuit should be laid out first. A ground plane should be used, the number and position of ground plane interruptions should be such as to not unnecessarily compromise ground plane integrity. Isolated or semi-isolated areas of the ground plane may be deliberately introduced to constrain ground currents to particular areas, for example the input capacitor and bottom FET ground.
2). The loop formed by the Input Capacitor(s) (Cin), the Top FET (Q1) and the Bottom FET (Q2) must be kept as small as possible. This loop contains all the high current, fast
transition switching. Connections should be as wide and as short as possible to minimize loop inductance. Minimizing this loop area will a) reduce EMI, b) lower ground injection currents, resulting in electrically "cleaner" grounds for the rest of the system and c) minimize source ringing, resulting in more reliable gate switching signals.
3). The connection between the junction of Q1, Q2 and the output inductor should be a wide trace or copper region. It should be as short as practical. Since this connection has fast voltage transitions, keeping this connection short will minimize EMI. The connection between the output inductor and the sense resistor should be a wide trace or copper area, there are no fast voltage or current transitions in this connection and length is not so important, however adding unnecessary impedance will reduce efficiency.
 high current paths.

Layout Diagram SC1186

## POWER MANAGEMENT

## Layout Guidelines (Cont.)

4) The Output Capacitor(s) (Cout) should be located as close to the load as possible, fast transient load currents are supplied by Cout only, and connections between Cout and the load must be short, wide copper areas to minimize inductance and resistance.
5) The SC1186 is best placed over a quiet ground plane area, avoid pulse currents in the Cin, Q1, Q2 loop flowing in this area. PGNDH and PGNDL should be returned to the ground plane close to the package. The AGND pin should be connected to the ground side of (one of) the output capacitor(s). If this is not possible, the AGND pin may be connected to the ground path between the Output Capacitor(s) and the Cin, Q1, Q2 loop. Under no circumstances should AGND be returned to a ground inside the Cin, Q1, Q2 loop.
6) Vcc for the SC1186 should be supplied from the 5 V supply through a $10 \Omega$ resistor, the Vcc pin should be decoupled directly to AGND by a $0.1 \mu \mathrm{~F}$ ceramic capacitor, trace lengths should be as short as possible.
7) The Current Sense resistor and the divider across it should form as small a loop as possible, the traces running back to CS+ and CS- on the SC1186 should run parallel and close to each other. The $0.1 \mu \mathrm{~F}$ capacitor should be mounted as close to the CS+ and CS- pins as possible. 8) Ideally, the grounds for the two LDO sections should be returned to the ground side of (one of) the output capacitor(s).


## Component Selection

## SWITCHING SECTION

OUTPUT CAPACITORS - Selection begins with the most critical component. Because of fast transient load current requirements in modern microprocessor core supplies, the output capacitors must supply all transient load current requirements until the current in the output inductor ramps up to the new level. Output capacitor ESR is therefore one of the most important criteria. The maximum ESR can be simply calculated from:

$$
R_{E S R} \leq \frac{V_{t}}{I_{t}}
$$

Where
$V_{t}=$ Maximum transient voltage excursion
$\mathrm{I}_{\mathrm{t}}=$ Transient current step
For example, to meet a 100 mV transient limit with a 10A load step, the output capacitor ESR must be less than $10 \mathrm{~m} \Omega$. To meet this kind of ESR level, there are three available capacitor technologies.

| Technology | Each Cap. |  | Total |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: |
|  | $\begin{array}{l}\text { Qty. } \\ (\mu \mathrm{F})\end{array}$ | $\begin{array}{l}\text { ESR } \\ (\mathrm{m} \Omega)\end{array}$ | $\begin{array}{l}\text { Rqd. }\end{array}$ |  | $\begin{array}{l}\text { C } \\ (\mu \mathrm{F})\end{array}$ | \(\left.\begin{array}{l}ESR <br>

(\mathrm{m} \Omega)\end{array}\right]\).

The choice of which to use is simply a cost/performance issue, with Low ESR Aluminum being the cheapest, but taking up the most space.

INDUCTOR - Having decided on a suitable type and value of output capacitor, the maximum allowable value of inductor can be calculated. Too large an inductor will produce a slow current ramp rate and will cause the output capacitor to supply more of the transient load current for longer - leading to an output voltage sag below the ESR excursion calculated above.
The maximum inductor value may be calculated from:

where $V_{A}$ is the lesser of $V_{O}$ or $\left(V_{\mathbb{I N}}-V_{O}\right)$

The calculated maximum inductor value assumes $100 \%$ and $0 \%$ duty cycle capability, so some allowance must be made. Choosing an inductor value of 50 to $75 \%$ of the calculated maximum will guarantee that the inductor current will ramp fast enough to reduce the voltage dropped across the ESR at a faster rate than the capacitor sags, hence ensuring a good recovery from transient with no additional excursions.
We must also be concerned with ripple current in the output inductor and a general rule of thumb has been to allow $10 \%$ of maximum output current as ripple current. Note that most of the output voltage ripple is produced by the inductor ripple current flowing in the output capacitor ESR. Ripple current can be calculated from:
$\mathrm{I}_{\text {LRPPLE }}=\frac{\mathrm{V}_{\text {IN }}}{4 \cdot \mathrm{~L} \cdot \mathrm{f}_{\text {OSC }}}$
Ripple current allowance will define the minimum permitted inductor value.

POWER FETS - The FETs are chosen based on several criteria, with probably the most important being power dissipation and power handling capability.
TOP FET - The power dissipation in the top FET is a combination of conduction losses, switching losses and bottom FET body diode recovery losses.
a) Conduction losses are simply calculated as:
$P_{\text {COND }}=I_{0}^{2} \cdot R_{\text {DS(on) }} \cdot \delta$
where
$\delta=$ duty cycle $\approx \frac{\mathrm{V}_{0}}{\mathrm{~V}_{\mathrm{IN}}}$
b) Switching losses can be estimated by assuming a switching time, if we assume 100ns then:
$P_{\text {sw }}=I_{0} \cdot V_{\text {IN }} \cdot 10^{-2}$
or more generally,
$P_{\text {SW }}=\frac{\mathrm{I}_{\mathrm{O}} \cdot \mathrm{V}_{\text {IN }} \cdot\left(\mathrm{t}_{\mathrm{r}}+\mathrm{t}_{\mathrm{f}}\right) \cdot \mathrm{f}_{\mathrm{OSC}}}{4}$
c) Body diode recovery losses are more difficult to estimate, but to a first approximation, it is reasonable to assume that the stored charge on the bottom FET body diode will be moved through the top FET as it starts to turn on. The resulting power dissipation in the top FET will be:
$P_{R R}=Q_{R R} \cdot V_{I N} \cdot f_{\text {OSC }}$

## POWER MANAGEMENT

## Component Selection (Cont.)

To a first order approximation, it is convenient to only consider conduction losses to determine FET suitability. For a 5 V in; 2.8 V out at 14.2 A requirement, typical FET losses would be:
Using 1.5X Room temp $\mathrm{R}_{\mathrm{DS(ON)}}$ to allow for temperature rise.

| FET type | $R_{\text {DS(on) }}(\mathrm{m} \Omega)$ | $P_{\mathrm{D}}(\mathrm{W})$ | Package |
| :--- | :--- | :--- | :--- |
| IRL34025 | 15 | 1.69 | D $^{2}$ Pak |
| IRL2203 | 10.5 | 1.19 | D $^{2}$ Pak |
| Si4410 | 20 | 2.26 | S0-8 |

BOTTOM FET - Bottom FET losses are almost entirely due to conduction. The body diode is forced into conduction at the beginning and end of the bottom switch conduction period, so when the FET turns on and off, there is very little voltage across it, resulting in low switching losses. Conduction losses for the FET can be determined by:

$$
\mathrm{P}_{\mathrm{COND}}=I_{0}^{2} \cdot R_{\mathrm{DS}(o n)} \cdot(1-\delta)
$$

For the example above:

| FET type | $R_{\text {DS(on) }}(\mathrm{m} \Omega)$ | $P_{\mathrm{D}}(\mathrm{W})$ | Package |
| :--- | :--- | :--- | :--- |
| IRL34025 | 15 | 1.33 | D $^{2}$ Pak |
| IRL2203 | 10.5 | 0.93 | D$^{2}$ Pak |
| Si4410 | 20 | 1.77 | S0-8 |

Each of the package types has a characteristic thermal impedance. For the surface mount packages on double sided FR4, 2 oz printed circuit board material, thermal impedances of $40^{\circ} \mathrm{C} / \mathrm{W}$ for the $\mathrm{D}^{2} \mathrm{PAK}$ and $80^{\circ} \mathrm{C} / \mathrm{W}$ for the SO-8 are readily achievable. The corresponding temperature rise is detailed below:

|  | Temperature Rise $\left({ }^{\circ} \mathrm{C}\right)$ |  |
| :--- | :--- | :--- |
| FET type | Top FET | Bottom FET |
| IRL34025 | 67.6 | 53.2 |
| IRL2203 | 47.6 | 37.2 |
| Si4410 | 180.8 | 141.6 |

It is apparent that single $\mathrm{SO}-8 \mathrm{Si} 4410$ are not adequate for this application, but by using parallel pairs in each position, power dissipation will be approximately halved and temperature rise reduced by a factor of 4.

## POWER MANAGEMENT

## Theory of Operation (Linear OCP)

The Linear controllers in the SC1186 have built in Overcurrent Protection (OCP). An overcurrent is assumed to have occured when the external FET is turned fully on and the output currrent is $\mathrm{R}_{\text {DS(ON) }}$ limited, this is detected by the gate voltage going very high while the output voltage is below approximately $40 \%$ of it's setpoint. To allow for capacitor charging and very short overcurrent durations, the gate voltage is ramped very slowly upwards whenever the output voltage is below the OCP threshold. To guarantee that the LDO output voltage is capable of reaching it's setpoint, the gate drive is disabled until both LDOV Undervoltage Lockout (UVLO) and LDOEN Threshold values are exceeded, ensuring that there is sufficient gate drive capability and sufficient LDO input voltage capability. A block diagram of one LDO controller is shown below.


During a normal start-up, once LDOV and LDOEN have reached their thresholds, the GATEx pin is released and $\mathrm{C}_{\text {RAMP }}$ is charged by 10 nA causing the GATEx voltage to ramp at $10 \mathrm{nA} / 10 \mathrm{pF}=1 \mathrm{~V} / \mathrm{ms}$. Once the GATEx output has ramped to the external FET threshold, Vout starts to ramp up, following GATEx. When Vout reaches the OCP threshold, approximately $40 \%$ of setpoint, switch S1 is closed and GATEx ramps up at a much faster rate, followed by Vout, until Vout reaches setpoint and the loop settles into steady state regulation.


If at some later time, a short circuit is applied to the output, the GATEx voltage will ramp up quickly as Vout falls to try and maintain regulation. Once Vout has fallen to the OCP threshold, switch S1 will open and the gate will continue ramping at the $1 \mathrm{~V} / \mathrm{ms}$ rate. If the short is not removed before the GATEx output reaches approximately LDOV - 0.7 V , the GATEx pin will be latched low, disabling the LDO


If the LDO tries to start into a short, the gate ramps at the $1 \mathrm{~V} / \mathrm{ms}$ rate to LDOV - 0.7 V , where the GATEx pin will be latched low.


POWER MANAGEMENT
Typical Characteristics



Transient Response Vo=2.4V, $10=300 \mathrm{~mA}$ to 15 A

2.5V Linear Short circuit output response



POWER MANAGEMENT
Evaluation Board Bill of Materials

| Item | Qty. | Reference | Value | Notes |
| :--- | :--- | :--- | :--- | :--- |
| 1 | 6 | C1, C4, C5, C10, C13, C28 | 0.1 uF |  |
| 2 | 12 | C2, C3, C6, C7, C8, C9, C18, C19, C20, C21, <br> C22, C23 | 1500 uF | Low ESR Sanyo MV-GX or <br> equivalent |
| 3 | 8 | C11, C12, C14, C15, C16, C17, C24, C25 | 330 uF |  |
| 4 | 1 | C27 | 47 uF |  |
| 5 | 1 | L1 | 1.9 uH |  |
| 6 | 3 | Q1, Q2, Q3, Q4 | IRLR3103N |  |
| 7 | 3 | Q5, Q6, Q7 | IRLR024N |  |
| 8 | 1 | R1 | 10 |  |
| 9 | 1 | R3 | EMPTY |  |
| 10 | 1 | R4 | 1.00 k | $1 \%$ |
| 11 | 1 | R5 | 2.32 k | $1 \%$ |
| 12 | 4 | R6, R7, R9, R10 | $2 R 2$ |  |
| 13 | 1 | R8 | $5 m O h m$ | IRC OAR1 |
| 14 | 2 | R15, R11 | See Table 2 |  |
| 15 | 1 | R12 | 1 k |  |
| 16 | 1 | R16 | 0 |  |
| 17 | 2 | R17, R18 | See Table |  |
| 18 | 1 | U1 | SC1186CS | SEMTECH |
| 19 | 1 | U2 | LM358 |  |

POWER MANAGEMENT

## Outline Drawing - SO-24



NOTES:

1. CONTROLLING DIMENSIONS ARE IN MILLIMETERS (ANGLES IN DEGREES)
2. DATUMS -A- AND -B- TO BE DETERMINED AT DATUM PLANE-H-
3. DIMENSIONS "E1" AND "D" DO NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS.
4. REFERENCE JEDEC STD MS-013, VARIATION AD.

## Outline Drawing - SO-24



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