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# SLDN-06D1Ax

## Non-Isolated DC-DC Converter

The SLDN-06D1Ax modules are non-isolated dc-dc converters that deliver up to 6A of output current. These modules operate over a wide range of input voltage ( $V_{IN} = 3 \text{ Vdc}-14.4 \text{ Vdc}$ ) and provide a precisely regulated output voltage from 0.45 Vdc to 5.5 Vdc, programmable via an external resistor and further adjustable through PMBus.

Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, over current and overtemperature protection. The PMBus interface supports a range of commands to control and monitor the module.

The Tunable Loop™ feature allows the user to optimize the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.



### Key Features & Benefits

- 3-14.4 VDC Input / 0.45 VDC @ 6 A Output
- Wide Input Voltage Range
- Fixed Switching Frequency
- Power Good Signal
- Remote On/Off
- Digital interface through the PMBus™ protocol
- Ability to Sink and Source Current
- Cost Efficient Open Frame Design
- Over Temperature Protection
- Tunable Loop™ (a registered trademark of Lineage Power Systems) to Optimize Dynamic output voltage response
- Flexible output voltage sequencing EZ-SEQUENCE
- Output overcurrent protection (non-latching)
- Wide operating temperature range [-40°C to 85°C]
- Class 2, Category 2, Non-Isolated DC/DC Converter (refer to IPC-9592A)
- Compliant to RoHS EU Directive 2002/95/EC
- Compatible in a Pb-free or SnPb reflow environment
- Certificated to UL60950-1/CSA C22.2 No.60950-1, 2rd

### Applications

- Distributed power architectures
- Intermediate bus voltage applications
- Telecommunications equipment
- Servers and storage applications
- Networking equipment
- Industrial equipment



## 1. MODEL SELECTION

MODEL NUMBER	OUTPUT VOLTAGE	INPUT VOLTAGE	MAX. OUTPUT CURRENT	MAX. OUTPUT POWER	TYPICAL EFFICIENCY
SLDN-06D1A0	0.45-5.5 VDC	3-14 VDC	6A	33 W	93.8%
SLDN-06D1AL	0.45-5.5 VDC	3-14 VDC	6A	33 W	93.8%

**NOTE:** 1. Add "R" suffix at the end of the model number to indicate tape and reel packaging (Standard).  
2. Add "G" suffix at the end of the model number to indicate tray packaging (Option).

### PART NUMBER EXPLANATION

S	LDN	-	06	D	1A	x	Y
Mounting Type	RoHS Status		Output Current	Wide input voltage range	Output Voltage	Enable	Package Type
Surface mount	Series code		6 A	3-14V	With sequencing	L – active Low 0 – active High	G – Tray package R –tape and reel packaging

## 2. ABSOLUTE MAXIMUM RATINGS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNITS
Continuous non-operating Input Voltage		-0.3	-	15	V
Voltage on SEQ SYNC VS+		-	-	7	V
Voltage on CLK DATA SMBALERT terminal		-	-	3.6	V
Ambient temperature	See Thermal Considerations section	-40	-	85	°C
Storage Temperature		-55	-	125	°C
Altitude		-	-	2000	m

**NOTE:** Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

## 3. INPUT SPECIFICATIONS

All specifications are typical at 25°C unless otherwise stated.

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Operating Input Voltage		3	-	14.4	V
Input Current (full load)	V <sub>IN</sub> =3V to 14.4V	-	-	5	A
Input Current (no load)	V <sub>O</sub> =0.6V V <sub>O</sub> =5V	-	30 90	-	mA mA
Input Stand-by Current	V <sub>IN</sub> = 12.0Vdc, module disabled	-	6	-	mA
Input Reflected Ripple Current (pk-pk)	1. 5Hz to 20MHz, 1μH source impedance; V <sub>IN</sub> = 0 to 14V, I <sub>O</sub> = I <sub>Omax</sub> 2. See Test Configurations	-	11.2	-	mA
I <sub>pt</sub> Inrush Current Transient		-	-	1	A2s
Input Ripple Rejection (120Hz)		-	-55	-	dB

**CAUTION:** This converter is not internally fused. An input line fuse must be used in application.

This power module can be used in a wide variety of applications, ranging from simple standalone operation to an integrated part of sophisticated power architecture. To preserve maximum flexibility, internal fusing is not included; however, to achieve maximum safety and system protection, always use an input line fuse. The safety agencies require a fast-acting fuse with a maximum rating of 6A. Based on the information provided in this data sheet on inrush energy and maximum dc input current, the same type of fuse with a lower rating can be used. Refer to the fuse manufacturer's data sheet for further information.

**Note:** Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

#### 4. OUTPUT SPECIFICATIONS

All specifications are typical at nominal input, full load at 25°C unless otherwise stated.

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Output Voltage Set Point	with 0.1% tolerance for external resistor used to set output voltage	-1.0	-	1.0	%Vo,set
Output Voltage	Over all operating input voltage, resistive load, and temperature conditions until end of life	-0.3	-	0.3	%Vo,set
PMBus Adjustable Output Voltage Range		-25	0	25	%Vo,set
PMBus Output Voltage Adjustment Step Size		-	0.4	-	%Vo,set
Adjustment Range	1. Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section 2. Selected by an external resistor.	0.6	-	5.5	V
Remote Sense Range		-	-	0.5	V
Load Regulation	$V_O \geq 2.5V$	-	-	10	mV
	$V_O < 2.5V$	-	-	10	mV
Line Regulation	$V_O \geq 2.5V$	-	-	0.4	%Vo,set
	$V_O < 2.5V$	-	-	5	mV
Temperature Regulation	$T_{ref}=T_{A, min}$ to $T_{A, max}$	-	-	0.4	%Vo,set
Ripple and Noise(Pk-Pk)	5Hz to 20MHz BW, $V_{IN}=V_{IN, nom}$ and $I_O=I_{O, min}$ to $I_{O, max}$ $C_O = 0.1\mu F$ // 22 $\mu F$ ceramic capacitors)	-	50	100	mV
Ripple and Noise(RMS)		-	20	38	mV
Output Current Range	in either sink or source mode	0	-	6	A
Output Current Limit Inception	Current limit does not operate in sink mode	-	200	-	%Io,max
Output Short-Circuit Current	$V_O \leq 250mV$ , Hiccup Mode	-	367	-	mA <sub>rms</sub>
Output Capacitance	$ESR \geq 1 m\Omega$	22	-	47	$\mu F$
	$ESR \geq 0.15 m\Omega$	22	-	1000	$\mu F$
	$ESR \geq 10 m\Omega$	22	-	3000	$\mu F$
Turn-On Delay Times ( $V_{IN}=V_{IN, nom}$ , $I_O=I_{O, max}$ , $V_O$ to within $\pm 1\%$ of steady state)	Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN, min}$ until $V_O = 10\%$ of $V_{O, set}$ )	-	0.4	-	ms
	Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until $V_O = 10\%$ of $V_{O, set}$ )	-	0.8	-	ms
Output voltage Rise time	time for $V_O$ to rise from 10% of $V_{O, set}$ to 90% of $V_{O, set}$	-	2.2	-	ms

- Notes:**
1. Some output voltages may not be possible depending on the input voltage.
  2. External capacitors may require using the new Tunable Loop™ feature to ensure that the module is stable as well as getting the best transient response (See the Tunable Loop™ section for details).
  3. Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

## 5. GENERAL SPECIFICATIONS

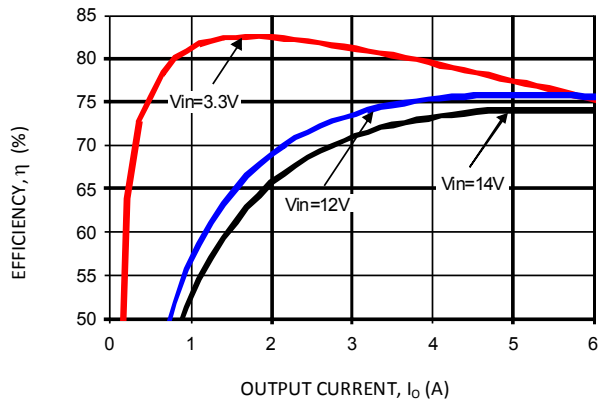
PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Efficiency	Vo=0.6V Vo=1.2V Vo=1.8V Vo=2.5V Vo=3.3V Vo=5.0V Vin= 12Vdc, Ta=25°C Io=Io, max , Vo= Vo,set	-	75.6 85.0 88.6 90.6 92.1 93.8	-	%
Switching Frequency		-	600	-	kHz
Synchronization Frequency Range		510	-	720	kHz
High-Level Input Voltage		2.0	-	-	V
Low-Level Input Voltage		-	-	0.4	V
Input Current, SYNC		-	-	100	nA
Minimum Pulse Width, SYNC		100	-	-	ns
Maximum SYNC rise time		100	-	-	ns
Over Temperature Protection		-	150	-	°C
PMBus Over Temperature Warning Threshold		-	130	-	°C
PMBus Adjustable Input Under Voltage Lockout Thresholds		2.5	-	14	V
Resolution of Adjustable Input Under Voltage Threshold		-	-	500	mV
Input Undervoltage Lockout Turn-on Threshold		-	2.79	-	V
Turn-off Threshold		-	2.58	-	V
Hysteresis		-	0.2	-	V
Tracking Accuracy		-	-	100	mV
Power-Up: 2V/ms	Vin, min to Vin, max; Io, min to Io, max, Vseq < Vo	-	-	100	mV
Power-Down: 2V/ms		-	-	100	mV
PGOOD (Power Good)		-	-	-	-
Overvoltage threshold for PGOOD ON		-	108	-	%Vo,set
Overvoltage threshold for PGOOD OFF		-	110	-	%Vo,set
Undervoltage threshold for PGOOD ON	Signal Interface Open Drain, Vsupply ≤ 5Vdc	-	92	-	%Vo,set
Undervoltage threshold for PGOOD OFF		-	90	-	%Vo,set
Pulldown resistance of PGOOD pin		-	-	50	Ω
Sink current capability into PGOOD pin		-	-	5	mA
Weight		-	1.65	-	g
MTBF	Calculated MTBF (IO=0.8Io, max, TA=40°C) Telecordia Issue 2 Method 1 Case 3		18,595,797		hours
Dimensions					
Inches (L × W × H)			0.48 x 0.48 x 0.29		Inches
Millimeters (L × W × H)			12.2 x 12.2 x 7.25		Millimeters

**Note:** Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

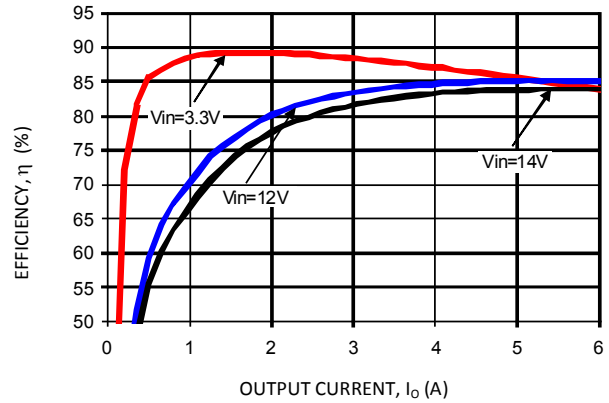
## 6. DIGITAL INTERFACE SPECIFICATIONS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
PMBus Signal Interface Characteristics					
Input High Voltage (CLK, DATA)		2.1	-	3.6	V
Input Low Voltage (CLK, DATA)		-	-	0.8	V
Input high level current (CLK, DATA)		-10	-	10	uA
Input low level current (CLK, DATA)		-10	-	10	uA
Output Low Voltage (CLK, DATA, SMBALERT#)	Iout =2mA	-	-	0.4	V
Output high level open drain leakage current (DATA, SMBALERT#)	Vout =3.6V	0	-	10	uA
Pin capacitance		-	0.7	-	pF
PMBus Operating frequency range		10	-	400	KHZ
Data setup time		250	-	-	ns
Data hold time	Receive Mode	0	-	-	ns
	Transmit Mode	300			
Measurement System Characteristics					
Read delay time		153	192	231	us
Output current measurement range		0	-	18	A
Output current measurement resolution		62.5	-	-	mA
Output current measurement gain accuracy		-	-	± 5	%
Output current measurement offset		-	-	0.1	A
VOUT measurement range		0	-	5.5	V
VOUT measurement resolution		-	15.625	-	mA
VOUT measurement gain accuracy		-15	-	15	%
VOUT measurement offset		-3	-	3	%
VIN measurement range		3	-	14.4	V
VIN measurement resolution		-	32.5	-	mV
VIN measurement gain accuracy		-15	-	15	%
VIN measurement offset		-5.5	-	1.4	LSB

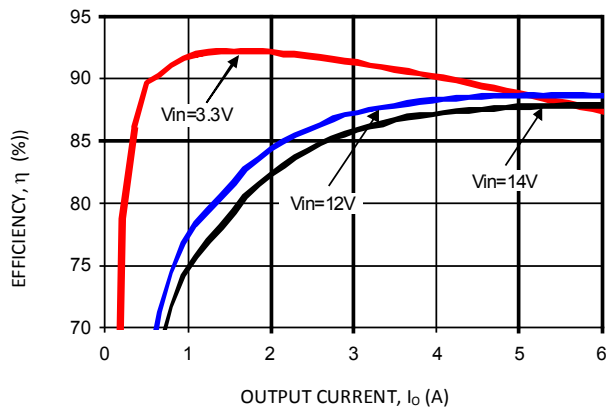
## 7. EFFICIENCY DATA



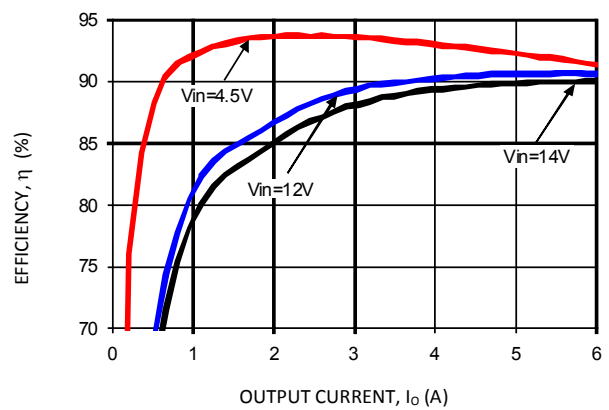
$V_o = 0.6V$



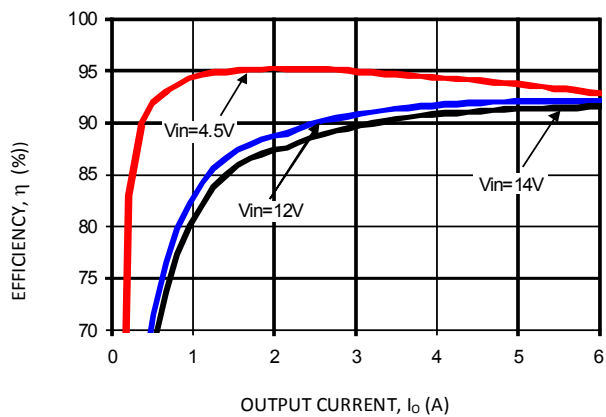
$V_o = 1.2V$



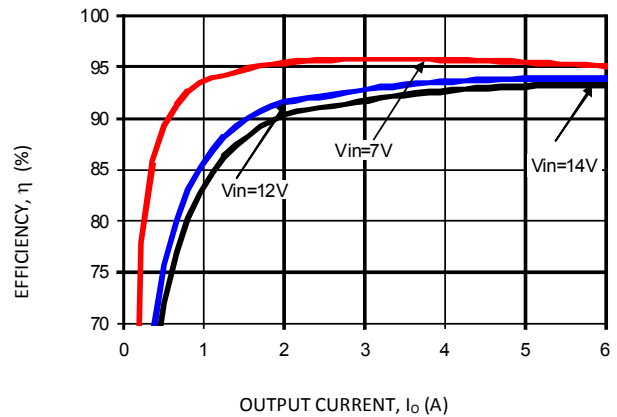
$V_o = 1.8V$



$V_o = 2.5V$

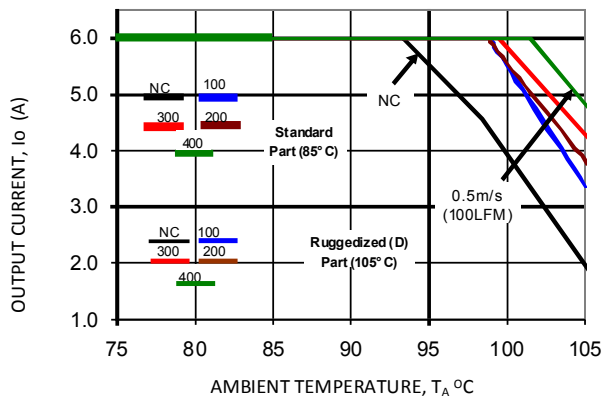
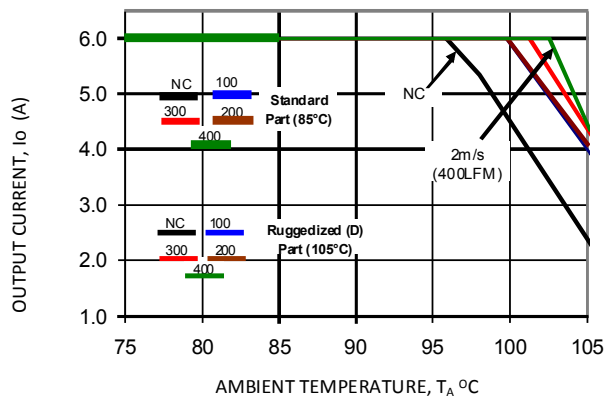
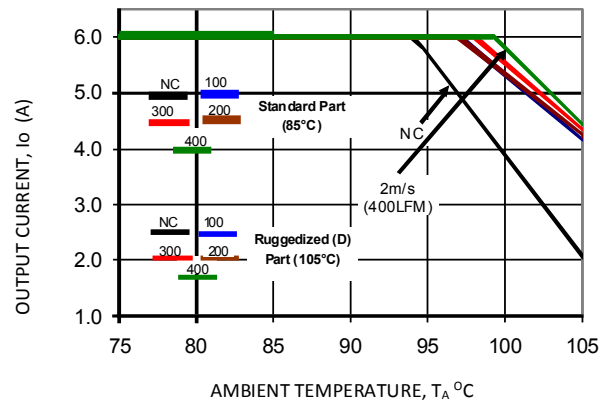
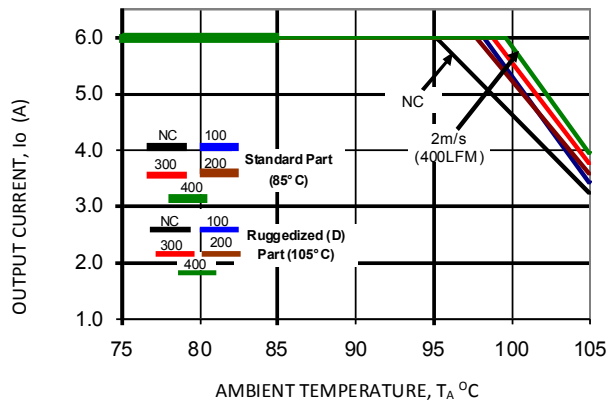
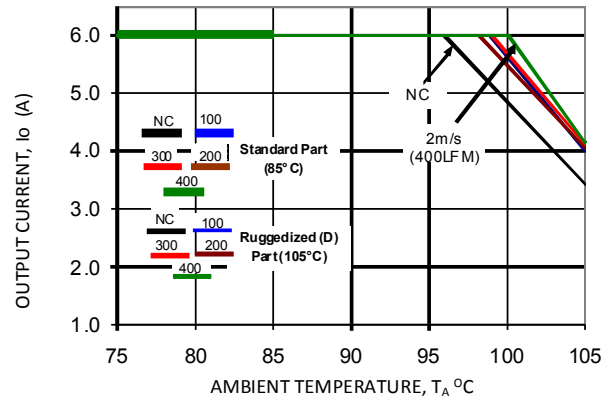
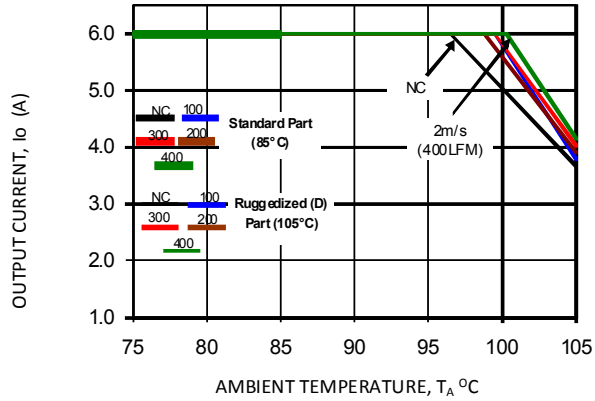


$V_o = 3.3V$



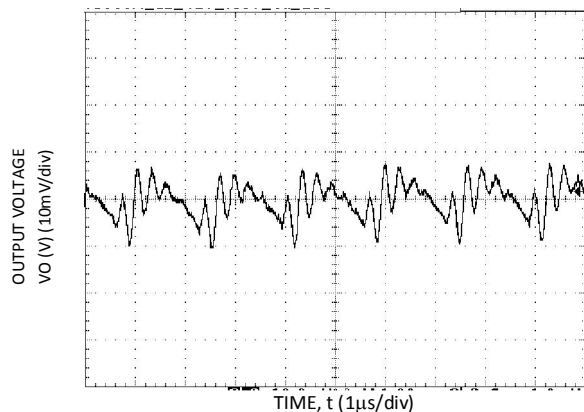
$V_o = 5.0V$

## 8. THERMAL DERATING CURVE

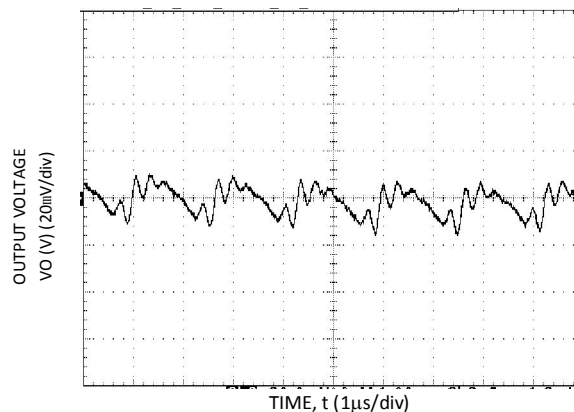




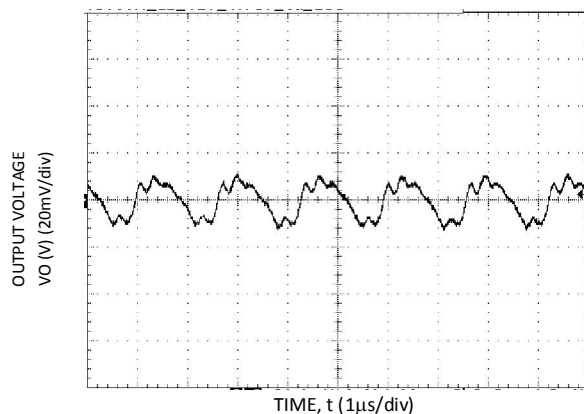
## 9. RIPPLE AND NOISE WAVEFORMS



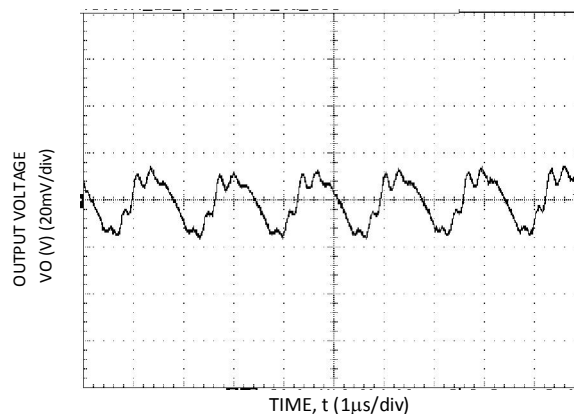
$V_o=0.6V, I_o = I_{o,max}$



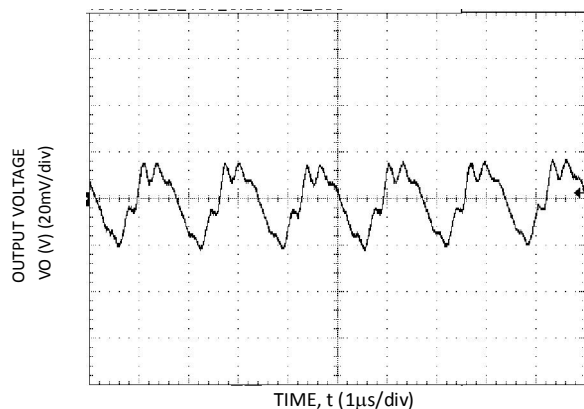
$V_o=1.2V, I_o = I_{o,max}$



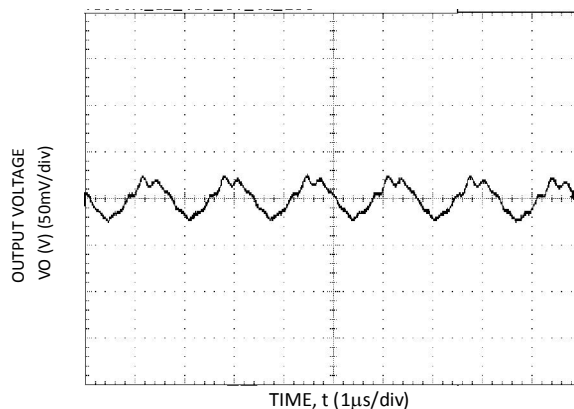
$V_o=1.8V, I_o = I_{o,max}$



$V_o=2.5V, I_o = I_{o,max}$



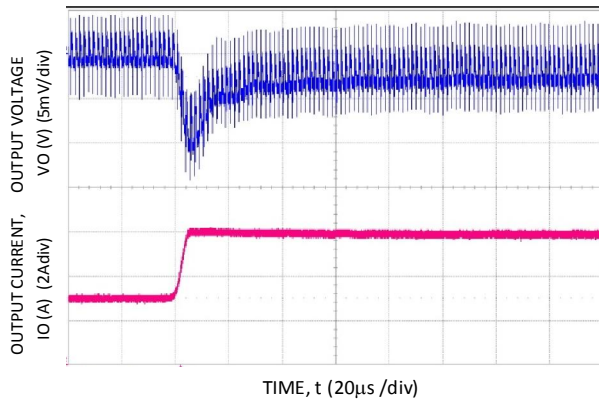
$V_o=3.3V, I_o = I_{o,max}$



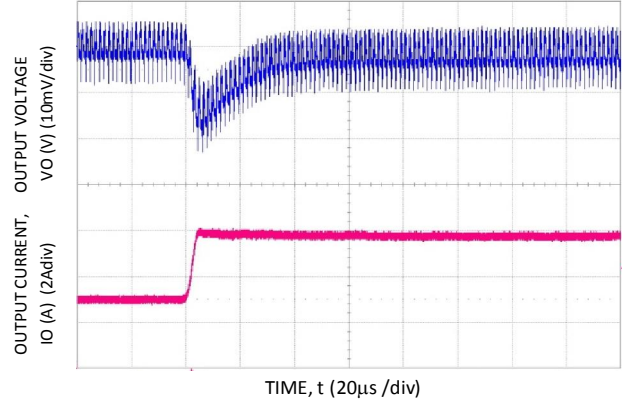
$V_o=5.0V, I_o = I_{o,max}$

Notes: CO=22μF ceramic, VIN = 12V

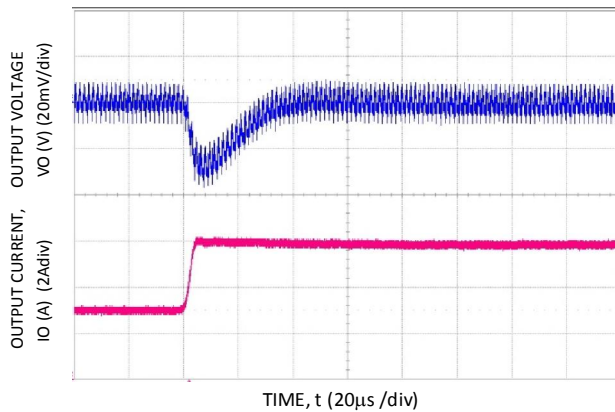
## 10. TRANSIENT RESPONSE WAVEFORMS



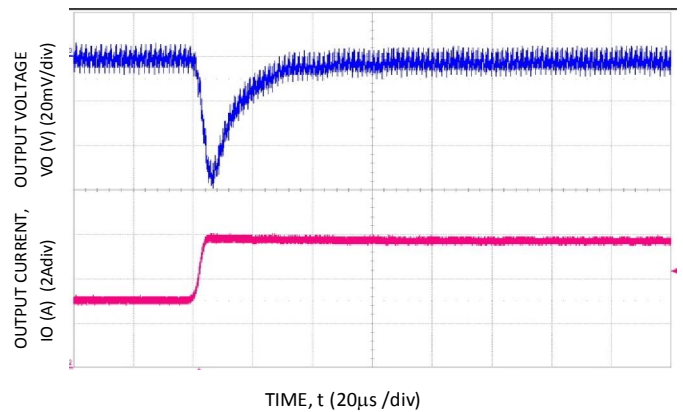
Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout=1x47uF + 4x330uF, CTune=33nF, RTune=178. Vo=0.6V



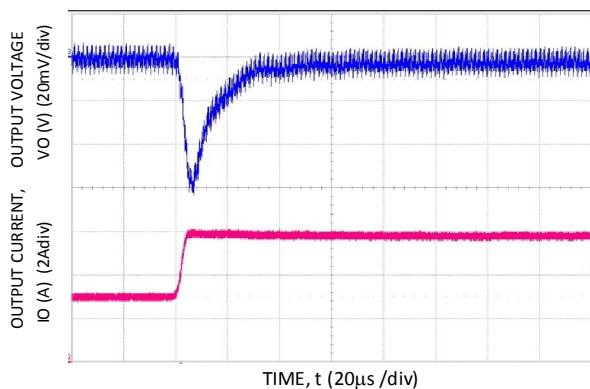
Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout=1x47uF + 2x330uF, CTune=12nF, RTune=178. Vo=1.2V



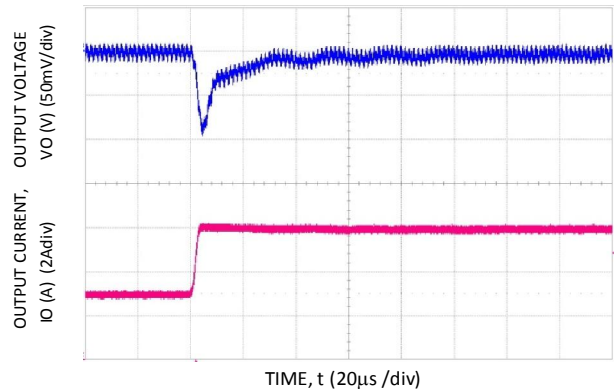
Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 1x47uF + 1x330uF, CTune=4700pF, RTune=178. Vo=1.8V



Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout=3x47uF, CTune=3300pF, RTune=178. Vo=2.5V

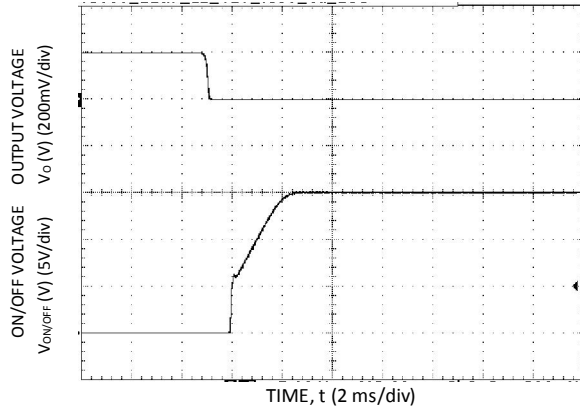


Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 3x47uF, CTune=3300pF, RTune=178. Vo=3.3V

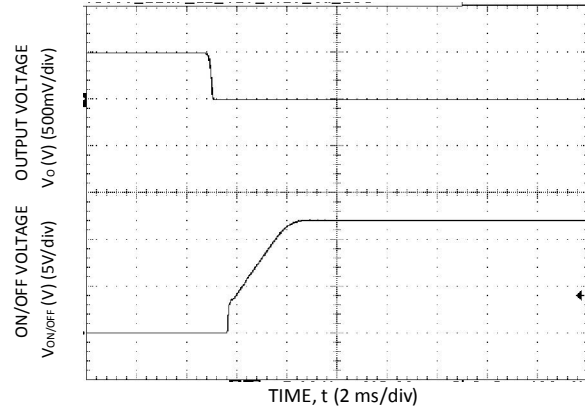


Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout=2x47uF, CTune=2200pF, RTune=261. Vo=5.0V

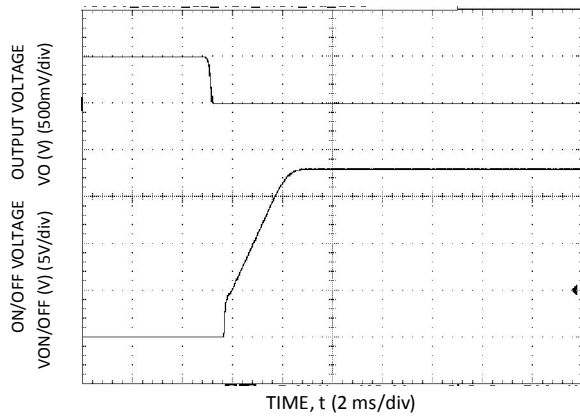
## 11. STARTUP TIME



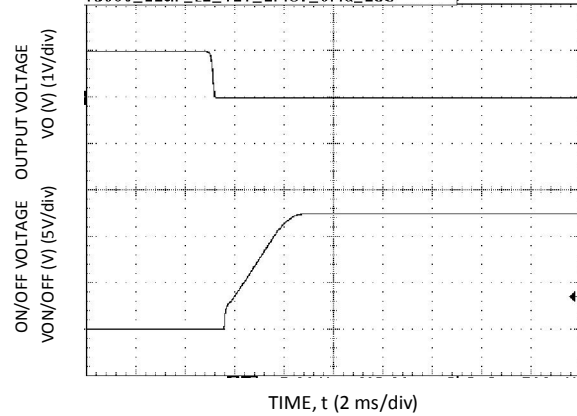
Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ),  $V_o = 0.6V$



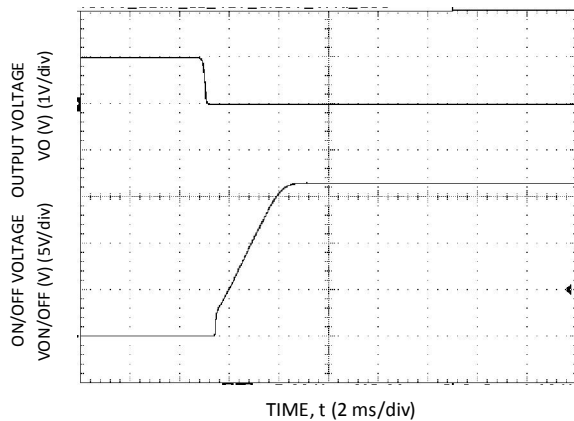
Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ),  $V_o = 1.2V$



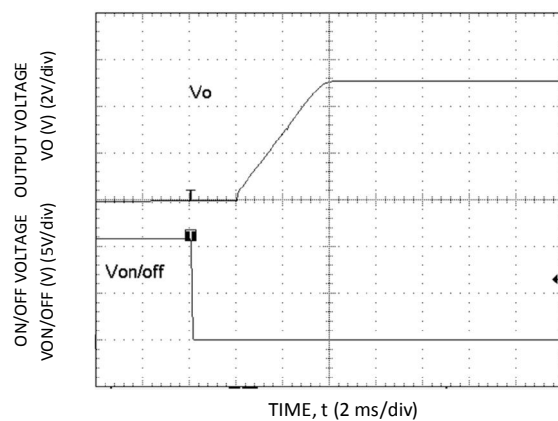
Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ),  $V_o = 1.8V$



Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ),  $V_o = 2.5V$

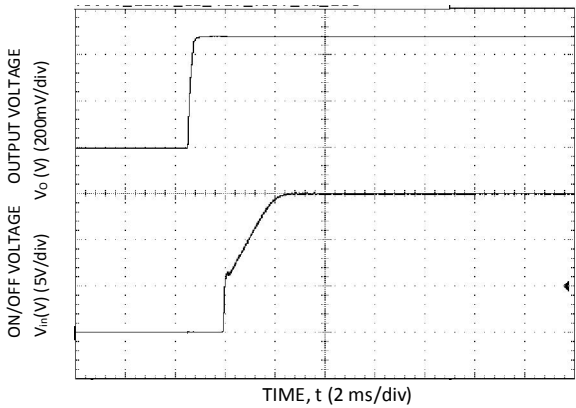


Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ),  $V_o = 3.3V$

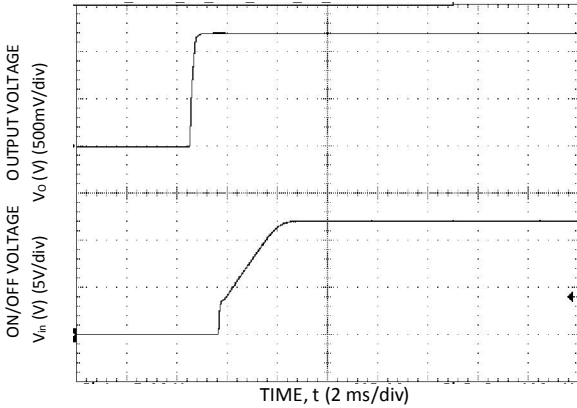


Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ),  $V_o = 5.0V$

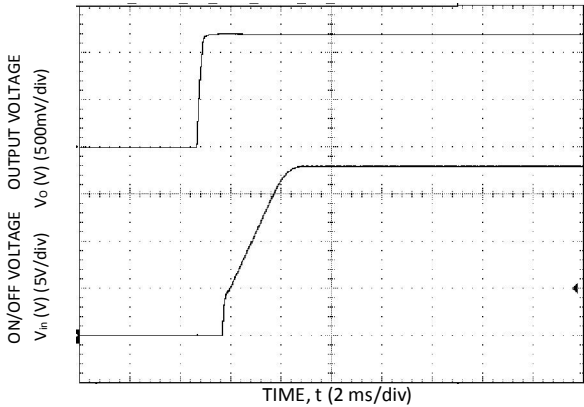
STARTUP TIME(CONTINUED)



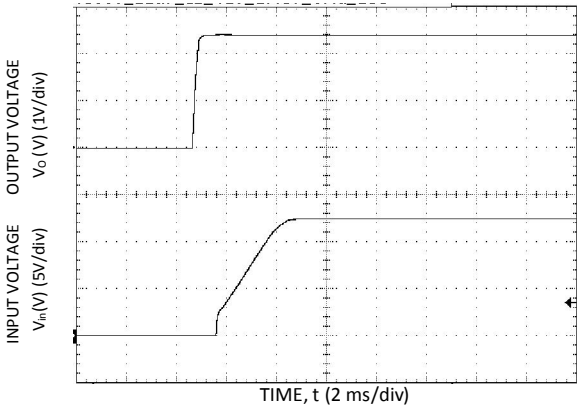
Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ),  
 $V_o = 0.6V$



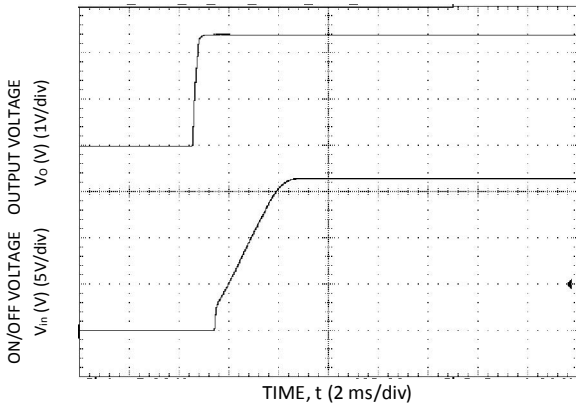
Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ),  
 $V_o = 1.2V$



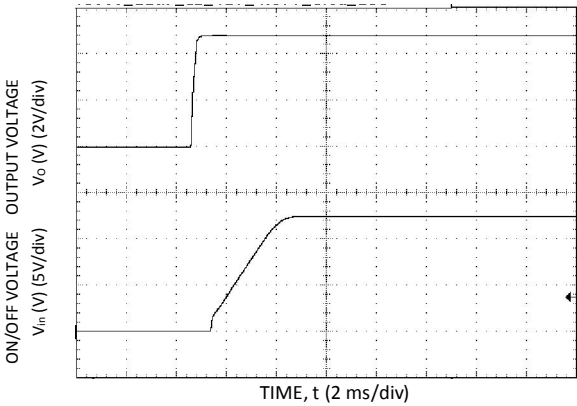
Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ),  
 $V_o = 1.8V$



Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ),  
 $V_o = 2.5V$



Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ),  
 $V_o = 3.3V$



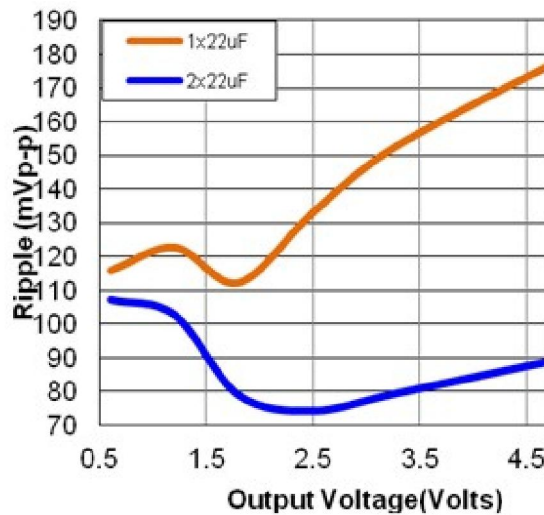
Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ),  
 $V_o = 5.0V$

## 12. INPUT FILTERING

The SLDN-06D1Ax module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 37 shows the input ripple voltage for various output voltages at 6A of load current with 1x22  $\mu$ F or 2x22  $\mu$ F ceramic capacitors and an input of 12V.

Figure 37



**Note:** Input ripple voltage for various output voltages with 1x22  $\mu$ F or 2x22  $\mu$ F ceramic capacitors at the input (6A load). Input voltage is 12V.

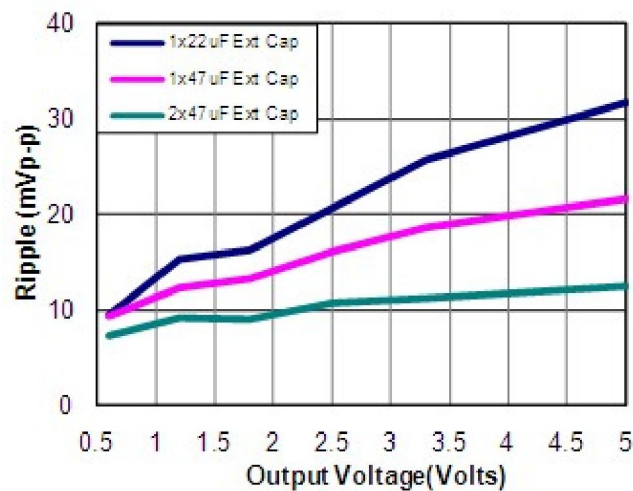


### 13. OUTPUT FILTERING

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with 0.1  $\mu\text{F}$  ceramic and 22  $\mu\text{F}$  ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 38 provides output ripple information for different external capacitance values at various  $V_o$  and a full load current of 6A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable Loop™ feature described later in this data sheet.

Figure 38



**Note:** Output ripple voltage for various output voltages with external 1x22  $\mu\text{F}$ , 1x47  $\mu\text{F}$ , or 2x47  $\mu\text{F}$  ceramic capacitors at the output (6A load). Input voltage is 12V.

### 14. SAFETY CONSIDERATIONS

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL 60950-1 2nd, CSA C22.2 No. 60950-1-07, DIN EN 60950-1:2006 + A11 (VDE0805 Teil 1 + A11):2009-11; EN 60950-1:2006 + A11:2009-03.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a fuse with a maximum rating of 10A in the positive input lead.

## 15. REMOTE ON/OFF

PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
Signal Low (Unit On)	Active Low	The remote on/off pin open, Unit on.	-0.2	-	0.6	V
Signal High (Unit Off)			2.0	-	V <sub>in,max</sub>	V
Signal Low (Unit Off)	Active High	The remote on/off pin open, Unit on.	-0.2	-	0.6	V
Signal High (Unit On)			2.0	-	V <sub>in,max</sub>	V

The SLDN-06D1Ax module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the two ON/OFF inputs:

Module ON/OFF can be controlled only through the analog interface (digital interface ON/OFF commands are ignored).

Module ON/OFF can be controlled only through the PMBus interface (analog interface is ignored).

Module ON/OFF can be controlled by either the analog or digital interface.

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

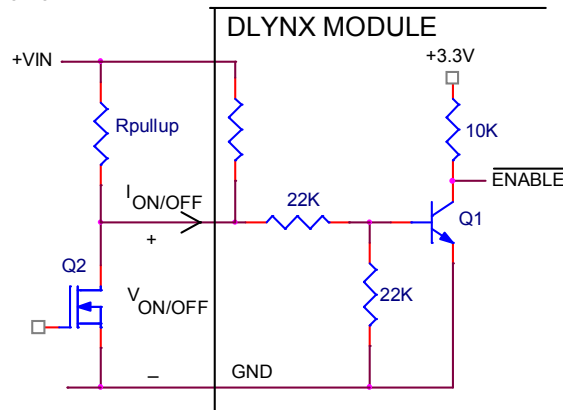
## 16. ANALOG ON/OFF

The SLDN-06D1Ax modules feature an On/Off pin for remote On/Off operation. Two On/Off logic options are available. In the Positive Logic On/Off option, (device code suffix "0" – see Ordering Information), the module turns ON during a logic High on the On/Off pin and turns OFF during a logic Low. With the Negative Logic On/Off option, (device code suffix "L" – see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. For either On/Off logic option, leaving the On/Off pin disconnected will turn the module ON when input voltage is present.

For positive logic modules, the circuit configuration for using the On/Off pin is shown in Figure 39. When the external transistor Q2 is in the OFF state, the internal transistor Q1 is turned ON, and the internal PWM #Enable signal is pulled low causing the module to be ON. When transistor Q2 is turned ON, the On/Off pin is pulled low and the module is OFF. A suggested value for  $R_{pullup}$  is  $20k\Omega$ .

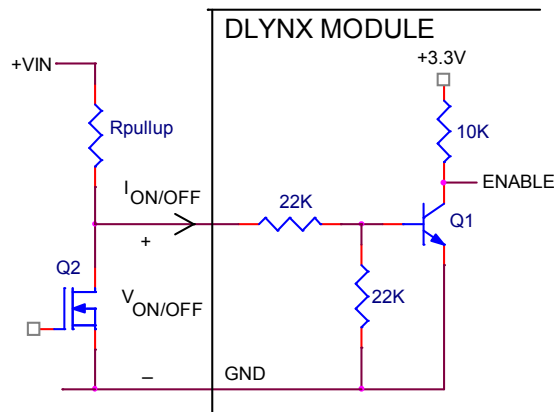
For negative logic On/Off modules, the circuit configuration is shown in Fig. 40. The On/Off pin should be pulled high with an external pull-up resistor (suggested value for the 3V to 14V input range is  $20k\Omega$ ). When transistor Q2 is in the OFF state, the On/Off pin is pulled high, transistor Q1 is turned ON and the module is OFF. To turn the module ON, Q2 is turned ON pulling the On/Off pin low, turning transistor Q1 OFF resulting in the PWM Enable pin going high.

Figure 39



Circuit configuration for using positive On/Off logic

Figure 40



Circuit configuration for using negative On/Off logic

## 17. DIGITAL ON/OFF

Please see the Digital Feature Descriptions section.

## 18. MONOTONIC START-UP AND SHUTDOWN

The SLDN-06D1Ax module has monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

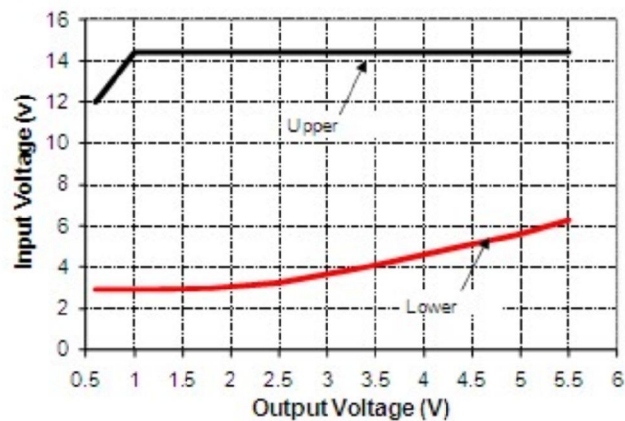
## 19. STARTUP INTO PRE-BIASED OUTPUT

The SLDN-06D1Ax module can start into a prebiased output as long as the prebias voltage is 0.5V less than the set output voltage.

## 20. OUTPUT VOLTAGE PROGRAMMING

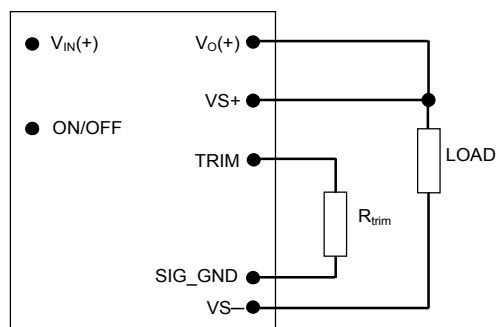
The output voltage of the module is programmable to any voltage from 0.6Vdc to 5.5Vdc by connecting a resistor between the Trim and SIG\_GND pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 41. The Upper Limit curve shows that for output voltages lower than 1V, the input voltage must be lower than the maximum of 14.4V. The Lower Limit curve shows that for output voltages higher than 0.6V, the input voltage needs to be larger than the minimum of 3V.

Figure 41



Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.

Figure 42



**Caution :** Do not connect SIG\_GND to GND elsewhere in the layout  
Circuit configuration for programming output voltage using an external resistor.

## 21. OUTPUT TRIM EQUATIONS

Without an external resistor between Trim and SIG\_GND pins, the output of the module will be 0.6Vdc. To calculate the value of the trim resistor, Rtrim for a desired output voltage, should be as per the following equation:

$$R_{trim} = \left[ \frac{12}{(V_o - 0.6)} \right] k\Omega$$

Rtrim is the external resistor in KΩ  
Vo is the desired output voltage.

Table 1 provides Rtrim values required for some common output voltages.

Table 1

VO, set (V)	Rtrim (KΩ)
0.6	Open
0.9	40
1.0	30
1.2	20
1.5	13.33
1.8	10
2.5	6.316
3.3	4.444
5.0	2.727

*By using a ±0.5% tolerance trim resistor with a TC of ±100ppm, a set point tolerance of ±1.5% can be achieved as specified in the electrical specification.*

## 22. DIGITAL OUTPUT VOLTAGE ADJUSTMENT

Please see the Digital Feature Descriptions section.

## 23. REMOTE SENSE

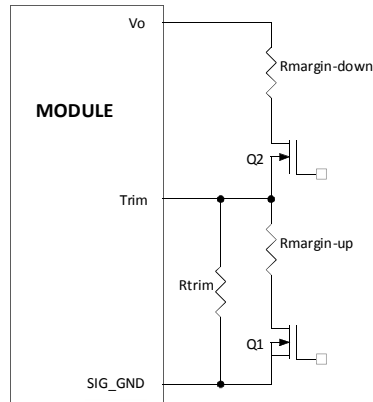
The SLDN-06D1Ax power module has a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.5V.



## 24. VOLTAGE MARGINING

Output voltage margining can be implemented in the module by connecting a resistor,  $R_{\text{margin-up}}$ , from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor,  $R_{\text{margin-down}}$ , from the Trim pin to output pin for margining-down. Figure 43 shows the circuit configuration for output voltage margining. Please consult your local Bel Power technical representative for additional details.

Figure 43



*Circuit Configuration for margining Output voltage*

## 25. DIGITAL OUTPUT VOLTAGE MARGINING

Please see the Digital Feature Descriptions section.

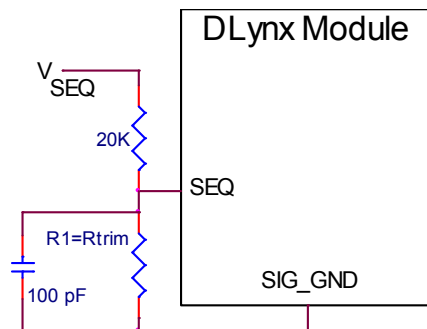
## 26. OUTPUT VOLTAGE SEQUENCING

The SLDN-06D1Ax module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

The voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown in Fig. 44. In addition, a small capacitor (suggested value 100pF) should be connected across the lower resistor R1.

For SLDN-06D1x modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is 10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.

Figure 44



Circuit showing connection of the sequencing signal to the SEQ pin

When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their set-point voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Note that in all digital Bel series of modules, the PMBus Output Undervoltage Fault will be tripped when sequencing is employed. This will be detected using the STATUS\_WORD and STATUS\_VOUT PMBus commands. In addition, the SMBALERT# signal will be asserted low as occurs for all faults and warnings. To avoid the module shutting down due to the Output Undervoltage Fault, the module must be set to continue operation without interruption as the response to this fault (see the description of the PMBus command VOUT\_UV\_FAULT\_RESPONSE for additional information)

## 27. OVERCURRENT PROTECTION

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range.

## 28. DIGITAL ADJUSTABLE OVERCURRENT WARNING

Please see the Digital Feature Descriptions section.

## 29. OVERTEMPERATURE PROTECTION

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 150°C (typ) is exceeded at the thermal reference point Tref. Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

### 30. DIGITAL TEMPERATURE STATUS VIA PMBUS

Please see the Digital Feature Descriptions section.

### 31. DIGITAL ADJUSTABLE OUTPUT OVER AND UNDER VOLTAGE PROTECTION

Please see the Digital Feature Descriptions section

### 32. INPUT UNDERVOLTAGE LOCKOUT

At input voltages below the input undervoltage lockout limit, the module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

### 33. DIGITAL ADJUSTABLE INPUT UNDERVOLTAGE LOCKOUT

Please see the Digital Feature Descriptions section

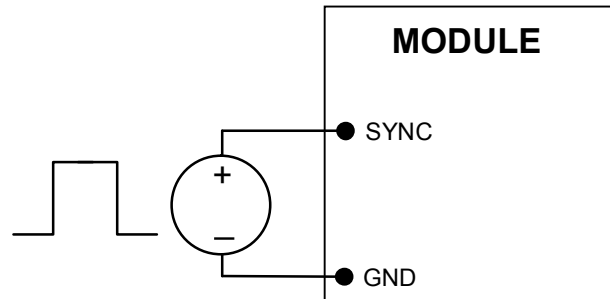
### 34. DIGITAL ADJUSTABLE POWER GOOD THRESHOLDS

Please see the Digital Feature Descriptions section

### 35. SYNCHRONIZATION

The SLDN-06D1Ax module switching frequency can be synchronized to a signal with an external frequency within a specified range. Synchronization can be done by using the external signal applied to the SYNC pin of the module as shown in Fig. 45, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. **If the SYNC pin is not used, the module should free run at the default switching frequency.**

Figure 45



External source connections to synchronize switching frequency of the module.

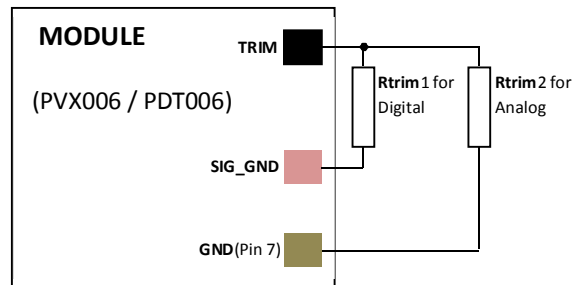
### 36. MEASURING OUTPUT CURRENT, OUTPUT VOLTAGE AND INPUT VOLTAGE

Please see the Digital Feature Descriptions section.

### 37. DUAL LAYOUT

Identical dimensions and pin layout of Analog and Digital modules permit migration from one to the other without needing to change the layout. To support this, 2 separate Trim Resistor locations have to be provided in the layout. As shown in Fig. 46, for the digital modules, the resistor is connected between the TRIM pad and SGND and in the case of the analog module it is connected between TRIM and GND.

Figure 46



**Caution :** For digital modules, do not connect SIG\_GND to GND elsewhere in the layout Layout to support either Analog or Digital on the same pad .

### 38. TUNABLE LOOP™

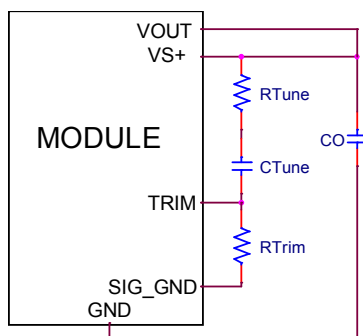
The SLDN-06D1Ax has a feature that optimizes transient response of the module called Tunable Loop™.



External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 38) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable Loop™ allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop™ is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 47. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

Figure 47



Circuit diagram showing connection of  $R_{TUNE}$  and  $C_{TUNE}$  to tune the control loop of the module

Recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  for different output capacitor combinations are given in Tables 2 and 3. Table 3 shows the recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  for different values of ceramic output capacitors up to 1000 $\mu$ F that might be needed for an application to meet output ripple and noise requirements. Selecting  $R_{TUNE}$  and  $C_{TUNE}$  according to Table 3 will ensure stable operation of the module.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 6A to 6A step change (50% of full load), with an input voltage of 12V.

Please contact your Bel Power technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

Co	1x47 $\mu$ F	2x47 $\mu$ F	4x47 $\mu$ F	6x47 $\mu$ F	10x47 $\mu$ F
$R_{TUNE}$	330	270	220	180	180
$C_{TUNE}$	680pF	1800pF	3300pF	4700pF	5600pF

Table 3. Recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  to obtain transient deviation of  $\leq 2\%$  of  $V_{out}$  for a 3A step load with  $V_{in}=12V$ .

Vo	5V	3.3V	2.5V	1.8V	1.2V	0.6V
Co	2x47 $\mu$ F	3x47 $\mu$ F	3x47 $\mu$ F	1x330 $\mu$ F	2x330 $\mu$ F Polymer	4x330 $\mu$ F Polymer
$R_{TUNE}$	270	180	180	180	180	180
$C_{TUNE}$	2200pF	3300pF	3300pF	4700pF	12nF	33nF
$\Delta V$	76mV	48mV	47mV	33mV	18mV	10mV

Recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  to obtain transient deviation of 2% of  $V_{out}$  for a 3A step load with  $V_{in}=12V$

**Note:** The capacitors used in the Tunable Loop tables are 47  $\mu$ F/3 m $\Omega$  ESR ceramic and 330  $\mu$ F/12 m $\Omega$  ESR polymer capacitors



39. PMBUS INTERFACE CAPABILITY

The SLDN-06D1Ax modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from [www.pmbus.org](http://www.pmbus.org). The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

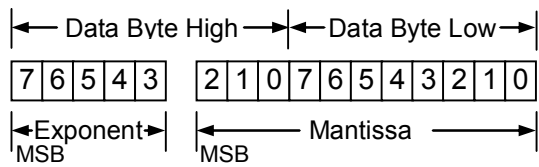
All communication over the module PMBus interface must support the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

40. PMBUS DATA FORMAT

For commands that set thresholds, voltages or report such quantities, the module supports the “Linear” data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two’s complement mantissa and a 5-bit, two’s complement exponent. The format of the two data bytes is shown below:



The value of the number is then given by  
 $Value = Mantissa \times 2^{Exponent}$

#### 41. PMBUS ADDRESSING

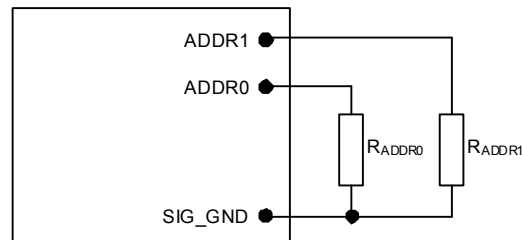
The SLDN-06D1Ax module can be addressed through the PMBus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG\_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 12, 40 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (1% tolerance resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

Table 4

Digit	Resistor Value (K $\Omega$ )
0	10
1	15.4
2	23.7
3	36.5
4	54.9
5	84.5
6	130
7	200

The user must know which I2C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, [smbus.org](http://smbus.org).

Figure 48



Circuit showing connection of resistors used to set the PMBus address of the module.

## 42. PMBUS ENABLE ON/OFF

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON\_OFF\_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

0 : Output is disabled  
1 : Output is enabled

This module uses the lower five bits of the ON\_OFF\_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r/w	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

*CMD: The CMD bit controls how the device responds to the OPERATION command.*

Bit Value	Action
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

*CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.*

Bit Value	Action
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit