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### Low power RS-485/RS-422 transceiver

### Features

- Low quiescent current: 300 µA
- Designed for RS-485 interface application
- -7 V to 12 V common mode input voltage range
- Driver maintains high impedance in 3-state or with the power OFF
- 70 mV typical input hysteresis
- 30 ns propagation delay, 5 ns skew
- Operate from a single 5 V supply
- Current limiting and thermal shutdown for driver overload protection
- Allows up to 64 transceivers on the bus

### Description

The ST485 is al low power transceiver for RS-485 and RS-422 communication. Each part contains one driver and one receiver.

This transceiver draw 300  $\mu$ A (typ.) of supply current when unloaded or fully loaded with disabled drivers.

It operates from a single 5 V supply.

Driver is short-circuit current limited and is protected against excessive power dissipation by thermal shutdown circuitry that placed the driver outputs into a high-impedance state.

The ST485 is designed for bi-directional data communications on multipoint bus transmission line (half-duplex applications).

| R NN  | TUT  |
|-------|------|
| DIP-8 | SO-8 |

The ST485 is available in three temperature range: commercial (0 °C to 70 °C), industrial (- 40 °C to 85 °C) and automotive (- 55 °C to 125 °C).

| Order code | Temperature range | Package              | Packaging                           |
|------------|-------------------|----------------------|-------------------------------------|
| ST485CN    | 0 to 70 °C        | DIP-8                | 50 parts per tube / 40 tube per box |
| ST485BN    | - 40 to 85 °C     | DIP-8                | 50 parts per tube / 40 tube per box |
| ST485CDR   | 0 to 70 °C        | SO-8 (tape and reel) | 2500 parts per reel                 |
| ST485BDR   | - 40 to 85 °C     | SO-8 (tape and reel) | 2500 parts per reel                 |

#### Table 1. Device summary

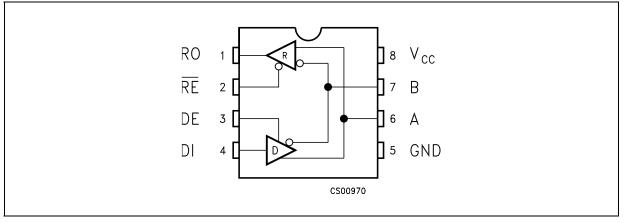
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## 1 Pin configuration

#### Figure 1. Pin connections



#### Table 2.Pin description

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| Pin n° | Symbol          | Name and function  |
|--------|-----------------|--|
| 1      | RO              | Receiver output  |
| 2      | RE              | Receiver output enable                                       |
| 3      | DE              | Driver output enable   |
| 4      | DI              | Driver input   |
| 5      | GND             | Ground   |
| 6      | A               | Non-inverting receiver input and non-inverting driver output |
| 7      | В               | Inverting receiver input and inverting driver output         |
| 8      | V <sub>CC</sub> | Supply voltage   |

## 2 Truth tables

#### Table 3. Truth table (driver)

|    | Inputs | Outputs |   |   |
|----|--------|---------|---|---|
| RE | DE     | DI      | В | А |
| Х  | Н      | Н       | L | Н |
| Х  | Н      | L       | Н | L |
| Х  | L      | Х       | Z | Z |

Note: X = Don't care; Z = High impedance

#### Table 4.Truth table (receiver)

|    | Inputs |             | Outputs |
|----|--------|-------------|---------|
| RE | DE     | A-B         | RO      |
| L  | L      | ≥ +0.2V     | н       |
| L  | L      | ≤ -0.2V     | L       |
| L  | L      | Inputs open | н       |
| Н  | L      | Х           | Z       |

Note: X = Don't care; Z = High impedance



## 3 Maximum ratings

| Table 5. Absolute maximum ratings | Table 5. | Absolute max | imum ratings |
|-----------------------------------|----------|--------------|--------------|
|-----------------------------------|----------|--------------|--------------|

| Symbol          | Parameter                      | Value                           | Unit |
|-----------------|--------------------------------|---------------------------------|------|
| V <sub>CC</sub> | Supply voltage                 | 7                               | V    |
| VI              | Control input voltage (RE, DE) | -0.5 to (V <sub>CC</sub> + 0.5) | V    |
| V <sub>DI</sub> | Driver input voltage (DI)      | -0.5 to (V <sub>CC</sub> + 0.5) | V    |
| V <sub>DO</sub> | Driver output voltage (A, B)   | ± 14                            | V    |
| V <sub>RI</sub> | Receiver input voltage (A, B)  | ± 14                            | V    |
| V <sub>RO</sub> | Receiver output voltage (RO)   | -0.5 to (V <sub>CC</sub> + 0.5) | V    |

*Note:* Absolute maximum ratings are those values beyond which damage to the device may occur. Functional operation under these condition is not implied.



## 4 Electrical characteristics

 $V_{CC}$  = 5 V ± 5 %,  $T_A$  =  $T_{MIN}$  to  $T_{MAX},$  unless otherwise specified. Typical values are referred to  $T_A$  = 25  $^\circ C$ 

| Table 6. | <b>DC</b> electrical | characteristics |
|----------|----------------------|-----------------|
| Table 6. | DC electrical        | cnaracteristics |

|                  |  |  | Value |                           |            |        |            |          |
|------------------|--|--|-------|---------------------------|------------|--------|------------|----------|
| Symbol           | Parameter  | Test conditions <sup>(1)</sup>   | -4    | -40 to 85 °C -55 to 125 ° |            | 125 °C | Unit       |          |
|                  |  |  | Min.  | Тур.                      | Max.       | Min.   | Max.       |          |
| V <sub>OD1</sub> | Differential driver output<br>(no load)  |  |       |                           | 5          |        | 5          | V        |
| V <sub>OD2</sub> | Differential driver output<br>(with load)  | $R_L = 27\Omega$ (RS-485) <i>Figure 2</i><br>$R_L = 50\Omega$ (RS-422) <i>Figure 2</i>                                     | 1.5   |                           | 5<br>5     | 1.4    | 5<br>5     | V<br>V   |
| ΔV <sub>OD</sub> | Change in magnitude of<br>driver differential output<br>voltage for complementary<br>output states   | $R_L = 27\Omega \text{ or } 50\Omega \text{ Figure } 2$  |       |                           | 0.2        |        | 0.2        | V        |
| V <sub>OC</sub>  | Driver common-mode<br>output voltage   | $R_L = 27\Omega \text{ or } 50\Omega \text{ Figure } 2$  |       |                           | 3          |        | 3          | v        |
| ΔV <sub>OC</sub> | Change in magnitude of<br>driver common-mode<br>output voltage for<br>complementary output<br>states | $R_L = 27\Omega \text{ or } 50\Omega \text{ Figure } 2$  |       |                           | 0.2        |        | 0.2        | V        |
| V <sub>IH</sub>  | Input high voltage   | RE, DE, DI   | 2.0   |                           |            | 2.0    |            | V        |
| V <sub>IL</sub>  | Input low voltage  | RE, DE, DI   |       |                           | 0.8        |        | 0.8        | V        |
| I <sub>IN1</sub> | Input current  | RE, DE, DI   |       |                           | ±2         |        | ±2         | μA       |
| I <sub>IN2</sub> | Input current (A, B)   | $\label{eq:VCM} \begin{array}{l} V_{CM} = 0V \text{ or } 5.25V, \ V_{DE} = 0V \\ V_{IN} = 12V \\ V_{IN} = -7V \end{array}$ |       |                           | 1<br>-0.8  |        | 1<br>-0.8  | mA<br>mA |
| V <sub>TH</sub>  | Receiver differential threshold voltage  | V <sub>CM</sub> = -7 to 12V  | -0.2  |                           | 0.2        | -0.2   | 0.2        | v        |
| $\Delta V_{TH}$  | Receiver input hysteresis  | $V_{CM} = 0V$  |       | 70                        |            |        |            | mV       |
| V <sub>OH</sub>  | Receiver output high voltage   | $I_{O} = -4mA, V_{ID} = 200mV$   | 3.5   |                           |            | 3.4    |            | V        |
| V <sub>OL</sub>  | Receiver output low voltage  | I <sub>O</sub> = 4mA, V <sub>ID</sub> = -200mV   |       |                           | 0.4        |        | 0.55       | v        |
| I <sub>OZR</sub> | 3-state (high impedance)<br>output current at receiver   | $V_{O} = 0.4 \text{ to } 2.4 \text{V}$   |       |                           | ± 1        |        | ± 1        | μA       |
| R <sub>IN</sub>  | Receiver input resistance  | V <sub>CM</sub> = -7 to 12V  | 24    |                           |            | 24     |            | kΩ       |
| I <sub>CC</sub>  | No load supply current <sup>(2)</sup>  | $V_{RE} = 0V \text{ or } V_{CC}$<br>$V_{DE} = V_{CC}$<br>$V_{DE} = 0V$   |       | 400<br>300                | 900<br>500 |        | 900<br>500 | μΑ<br>μΑ |

|                   |   |  |      |         | Value |        |        |      |
|-------------------|---|--|------|---------|-------|--------|--------|------|
| Symbol            | Parameter   | Test conditions <sup>(1)</sup>         | -4   | 0 to 85 | °C    | -55 to | 125 °C | Unit |
|                   |   |  | Min. | Тур.    | Max.  | Min.   | Max.   |      |
| I <sub>OSD1</sub> | Driver short-circuit<br>current, V <sub>O</sub> =High | $V_{\rm O} = -7$ to 12V <sup>(3)</sup> | 35   |         | 250   | 35     | 250    | mA   |
| I <sub>OSD2</sub> | Driver short-circuit<br>current, V <sub>O</sub> =Low  | $V_{\rm O}$ = -7 to 12V <sup>(3)</sup> | 35   |         | 250   | 35     | 250    | mA   |
| I <sub>OSR</sub>  | Receiver short-circuit current                        | $V_{O} = 0V$ to $V_{CC}$               | 7    |         | 95    | 7      | 95     | mA   |

#### Table 6. DC electrical characteristics (continued)

1. All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

2. Supply current specification is valid for loaded transmitters when  $V_{DE} = 0V$ 

3. Applies to peak current. See typical Operating Characteristics.

 $V_{CC}$  = 5 V  $\pm$  5 %,  $T_A$  =  $T_{MIN}$  to  $T_{MAX},$  unless otherwise specified. Typical values are referred to  $T_A$  = 25  $^\circ C$ 

|                                      |                                      |   |      |         | Value | !      |       |      |
|--------------------------------------|--------------------------------------|---|------|---------|-------|--------|-------|------|
| Symbol                               | Parameter                            | Test conditions <sup>(1)</sup>  | -4   | 0 to 85 | °C    | -55 to | 125°C | Unit |
|                                      |                                      |   | Min. | Тур.    | Max.  | Min.   | Max.  |      |
| t <sub>PLH</sub><br>t <sub>PHL</sub> | Propagation delay<br>input to output | $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$<br>(See <i>Figure 4</i> and <i>Figure 6</i> ) | 10   | 30      | 60    |        | 70    | ns   |
| t <sub>SK</sub>                      | Output skew to output                | $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$<br>(See <i>Figure 4</i> and <i>Figure 6</i> ) |      | 5       | 10    |        | 10    | ns   |
| t <sub>TLH</sub><br>t <sub>THL</sub> | Rise or fall time                    | $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$<br>(See <i>Figure 4</i> and <i>Figure 6</i> ) | 3    | 15      | 40    | 3      | 45    | ns   |
| t <sub>PZH</sub>                     | Output enable time                   | C <sub>L</sub> = 100pF, S2 = Closed<br>(See <i>Figure 5</i> and <i>Figure 7</i> )               |      | 70      | 90    |        | 90    | ns   |
| t <sub>PZL</sub>                     | Output enable time                   | C <sub>L</sub> = 100pF, S1 = Closed<br>(See <i>Figure 5</i> and <i>Figure 7</i> )               |      | 70      | 90    |        | 90    | ns   |
| t <sub>PLZ</sub>                     | Output disable time                  | C <sub>L</sub> = 15pF, S1 = Closed<br>(See <i>Figure 5</i> and <i>Figure 7</i> )                |      | 70      | 90    |        | 90    | ns   |
| t <sub>PHZ</sub>                     | Output disable time                  | C <sub>L</sub> = 15pF, S2 = Closed<br>(See <i>Figure 5</i> and <i>Figure 7</i> )                |      | 70      | 90    |        | 90    | ns   |

#### Table 7. Driver switching characteristics

1. All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

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 $V_{CC}$  = 5 V  $\pm$  5%,  $T_A$  =  $T_{MIN}$  to  $T_{MAX},$  unless otherwise specified. Typical values are referred to  $T_A$  = 25  $^\circ C$ 

|                                      |                                   |   | Value        |      |      |              |      |      |
|--------------------------------------|-----------------------------------|---|--------------|------|------|--------------|------|------|
| Symbol                               | Parameter                         | Test conditions <sup>(1)</sup>  | -40 to 85 °C |      |      | -55 to 125°C |      | Unit |
|                                      |                                   |   | Min.         | Тур. | Max. | Min.         | Max. |      |
| t <sub>PLH</sub><br>t <sub>PHL</sub> | Propagation delay input to output | $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF<br>(See <i>Figure 4</i> and <i>Figure 8</i> ) | 20           | 130  | 210  |              | 230  | ns   |
| t <sub>SKD</sub>                     | Differential receiver skew        | $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF<br>(See <i>Figure 4</i> and <i>Figure 8</i> ) |              | 13   |      |              |      | ns   |
| t <sub>PZH</sub>                     | Output enable time                | C <sub>RL</sub> = 15pF, S1 = Closed<br>(See Fig. 2 and <i>Figure 9</i> )                            |              | 20   | 50   |              | 56   | ns   |
| t <sub>PZL</sub>                     | Output enable time                | C <sub>RL</sub> = 15pF, S2 = Closed<br>(See Fig. 2 and <i>Figure 9</i> )                            |              | 20   | 50   |              | 56   | ns   |
| t <sub>PLZ</sub>                     | Output disable time               | C <sub>RL</sub> = 15pF, S1 = Closed<br>(See Fig. 2 and <i>Figure 9</i> )                            |              | 20   | 50   |              | 56   | ns   |
| t <sub>PHZ</sub>                     | Output disable time               | C <sub>RL</sub> = 15pF, S2 = Closed<br>(See Fig. 2 and <i>Figure 9</i> )                            |              | 20   | 50   |              | 56   | ns   |
| f <sub>MAX</sub>                     | Maximum data rate                 |   | 2.5          |      |      | 2.5          |      | Mbps |

| Table 8. | Receiver  | switching | characteristics |
|----------|-----------|-----------|-----------------|
|          | 110001001 | Switching | onunuotonotioo  |

1. All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified



## 5 Test circuit and typical characteristics

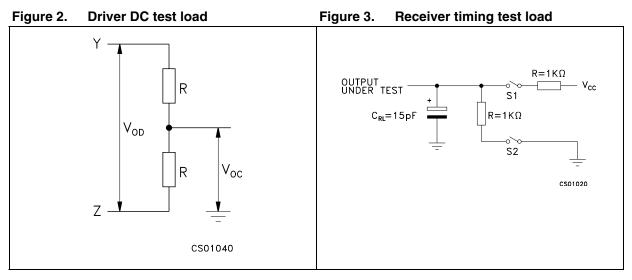
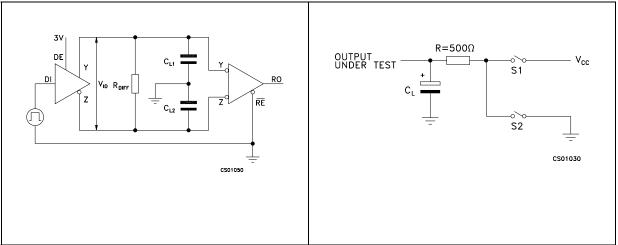
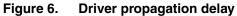




Figure 5. Driver timing test load





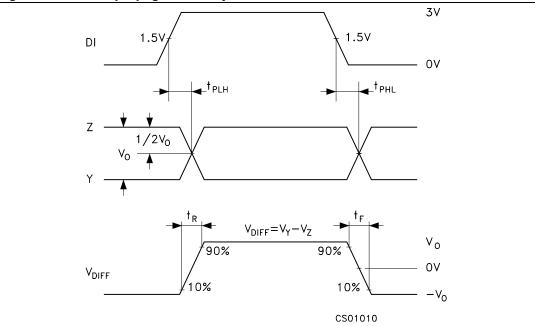
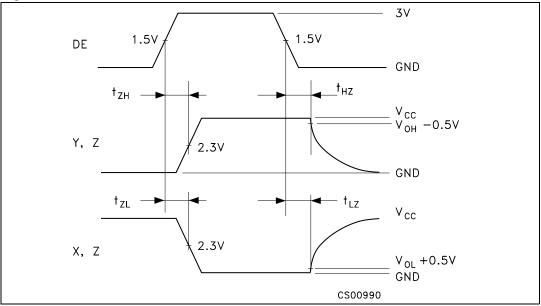
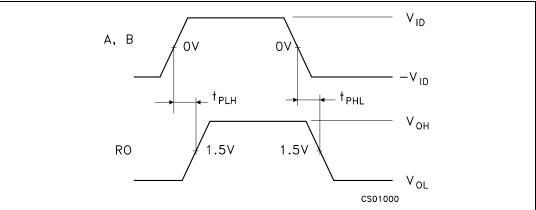


Figure 7. Driver enable and disable time









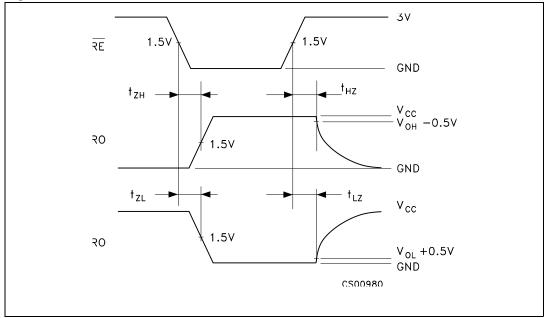


Figure 10. Receiver output current vs. output Figure 11. Receiver output current vs. output low voltage high voltage

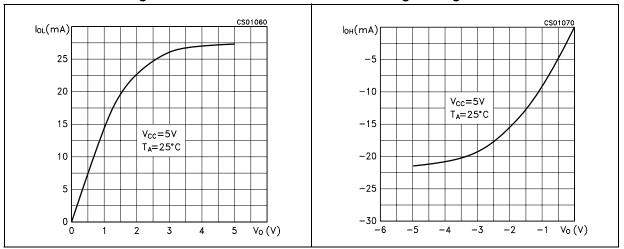
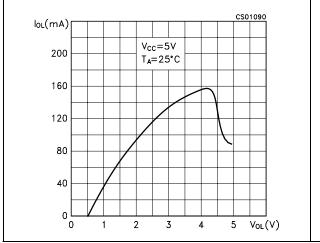


Figure 12. Driver output current vs. output low Figure 13. Driver output current vs. output voltage high voltage





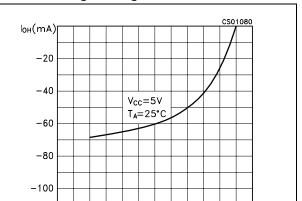


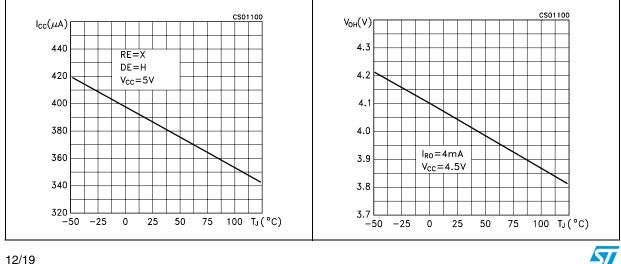
Figure 15. Receiver high level output voltage vs. temperature

-3

-2

 $-1 V_0(V)$ 

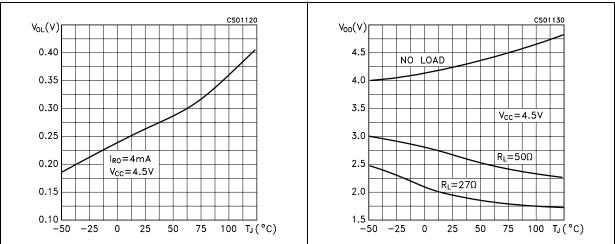
-4



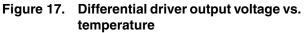
-120

-6

-5



## Figure 16. Receiver low level output voltage vs. temperature

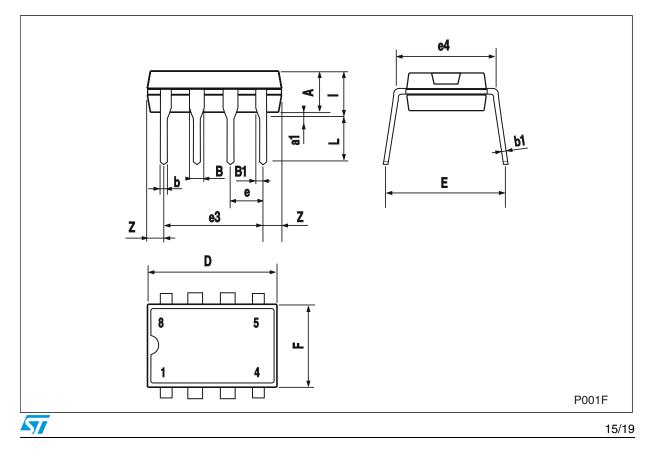


## 6 Package mechanical data

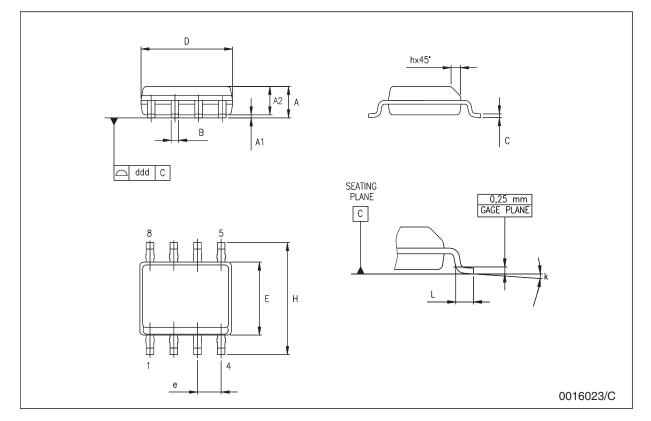
In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK<sup>®</sup> packages, depending on their level of environmental compliance. ECOPACK<sup>®</sup> specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark.

| Ρ | lastic | DIP-8 | mechanical | data |
|---|--------|-------|------------|------|
|   | lastio |       | meenamou   | aata |

| Dim. | mm.  |      |      | inch. |       |       |  |
|------|------|------|------|-------|-------|-------|--|
|      | Min. | Тур. | Max. | Min.  | Тур.  | Max.  |  |
| А    |      | 3.3  |      |       | 0.130 |       |  |
| a1   | 0.7  |      |      | 0.028 |       |       |  |
| В    | 1.39 |      | 1.65 | 0.055 |       | 0.065 |  |
| B1   | 0.91 |      | 1.04 | 0.036 |       | 0.041 |  |
| b    |      | 0.5  |      |       | 0.020 |       |  |
| b1   | 0.38 |      | 0.5  | 0.015 |       | 0.020 |  |
| D    |      |      | 9.8  |       |       | 0.386 |  |
| Е    |      | 8.8  |      |       | 0.346 |       |  |
| е    |      | 2.54 |      |       | 0.100 |       |  |
| e3   |      | 7.62 |      |       | 0.300 |       |  |
| e4   |      | 7.62 |      |       | 0.300 |       |  |
| F    |      |      | 7.1  |       |       | 0.280 |  |
| I    |      |      | 4.8  |       |       | 0.189 |  |
| L    |      | 3.3  |      |       | 0.130 |       |  |
| Z    | 0.44 |      | 1.6  | 0.017 |       | 0.063 |  |



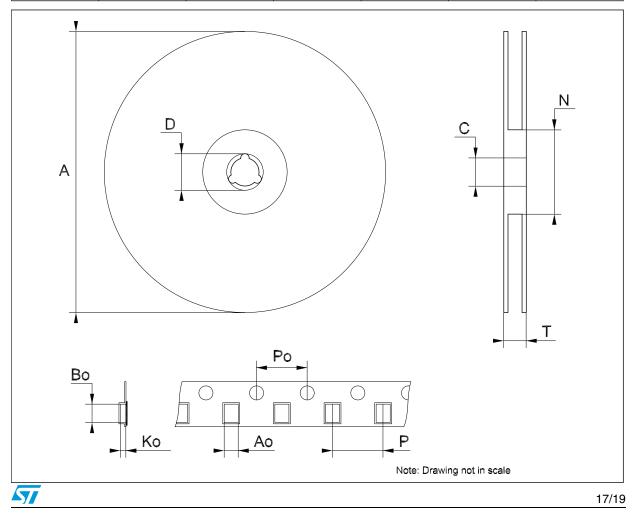
| Dim. |      | mm.  |       | inch. |       |       |  |
|------|------|------|-------|-------|-------|-------|--|
| Dim. | Min. | Тур. | Max.  | Min.  | Тур.  | Max.  |  |
| А    | 1.35 |      | 1.75  | 0.053 |       | 0.069 |  |
| A1   | 0.10 |      | 0.25  | 0.04  |       | 0.010 |  |
| A2   | 1.10 |      | 1.65  | 0.043 |       | 0.065 |  |
| В    | 0.33 |      | 0.51  | 0.013 |       | 0.020 |  |
| С    | 0.19 |      | 0.25  | 0.007 |       | 0.010 |  |
| D    | 4.80 |      | 5.00  | 0.189 |       | 0.197 |  |
| E    | 3.80 |      | 4.00  | 0.150 |       | 0.157 |  |
| е    |      | 1.27 |       |       | 0.050 |       |  |
| Н    | 5.80 |      | 6.20  | 0.228 |       | 0.244 |  |
| h    | 0.25 |      | 0.50  | 0.010 |       | 0.020 |  |
| L    | 0.40 |      | 1.27  | 0.016 |       | 0.050 |  |
| k    |      |      | 8° (r | nax.) |       |       |  |
| ddd  |      |      | 0.1   |       |       | 0.04  |  |



#### SO-8 mechanical data

| Dim  | mm.  |      |      | inch. |      |        |  |
|------|------|------|------|-------|------|--------|--|
| Dim. | Min. | Тур. | Max. | Min.  | Тур. | Max.   |  |
| А    |      |      | 330  |       |      | 12.992 |  |
| С    | 12.8 |      | 13.2 | 0.504 |      | 0.519  |  |
| D    | 20.2 |      |      | 0.795 |      |        |  |
| Ν    | 60   |      |      | 2.362 |      |        |  |
| Т    |      |      | 22.4 |       |      | 0.882  |  |
| Ao   | 8.1  |      | 8.5  | 0.319 |      | 0.335  |  |
| Во   | 5.5  |      | 5.9  | 0.216 |      | 0.232  |  |
| Ko   | 2.1  |      | 2.3  | 0.082 |      | 0.090  |  |
| Po   | 3.9  |      | 4.1  | 0.153 |      | 0.161  |  |
| Р    | 7.9  |      | 8.1  | 0.311 |      | 0.319  |  |





## 7 Revision history

| Date        | Revision | Changes   |  |  |
|-------------|----------|---|--|--|
| 21-Mar-2006 | 12       | Order codes has been updated and new template.  |  |  |
| 02-Aug-2006 | 13       | Mistake in cover page first row mA ==> $\mu$ A. |  |  |
| 08-Nov-2006 | 14       | Added: Table 1.                                 |  |  |
| 07-Feb-2008 | 15       | Modified: Table 1 on page 1.                    |  |  |
| 16-Feb-2009 | 16       | Modified Note: on page 5.                       |  |  |



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